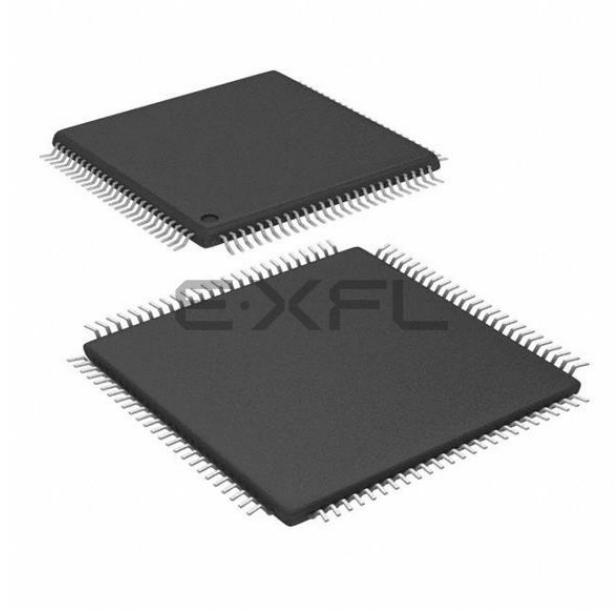
Microchip Technology - PIC32MZ1024EFE100-E/PT Datasheet



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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® M-Class
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	EBI/EMI, Ethernet, I²C, PMP, SPI, SQI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	78
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	2.1V ~ 3.6V
Data Converters	A/D 40x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mz1024efe100-e-pt

3.1.4 FLOATING POINT UNIT (FPU)

The Floating Point Unit (FPU), Coprocessor (CP1), implements the MIPS Instruction Set Architecture for floating point computation. The implementation supports the ANSI/IEEE Standard 754 (IEEE for Binary Floating Point Arithmetic) for 32-bit and 64-bit floating point data formats. The FPU can be programmed to have thirty-two 32-bit or 64-bit floating point registers used for floating point operations.

The performance is optimized for 32-bit formats. Most instructions have one FPU cycle throughput and four FPU cycle latency. The FPU implements the multiply-add (MADD) and multiply-sub (MSUB) instructions with intermediate rounding after the multiply function. The result is guaranteed to be the same as executing a MUL and an ADD instruction separately, but the instruction latency, instruction fetch, dispatch bandwidth, and the total number of register accesses are improved.

IEEE denormalized input operands and results are supported by hardware for some instructions. IEEE denormalized results are not supported by hardware in general, but a fast flush-to-zero mode is provided to optimize performance. The fast flush-to-zero mode is enabled through the FCCR register, and use of this mode is recommended for best performance when denormalized results are generated.

The FPU has a separate pipeline for floating point instruction execution. This pipeline operates in parallel with the integer core pipeline and does not stall when the integer pipeline stalls. This allows long-running FPU operations, such as divide or square root, to be partially masked by system stalls and/or other integer unit instructions. Arithmetic instructions are always dispatched and completed in order, but loads and stores can complete out of order. The exception model is “precise” at all times.

Table 3-4 contains the floating point instruction latencies and repeat rates for the processor core. In this table, 'Latency' refers to the number of FPU cycles necessary for the first instruction to produce the result needed by the second instruction. The “Repeat Rate” refers to the maximum rate at which an instruction can be executed per FPU cycle.

TABLE 3-4: FPU INSTRUCTION LATENCIES AND REPEAT RATES

Op code	Latency (FPU Cycles)	Repeat Rate (FPU Cycles)
ABS.[S,D], NEG.[S,D], ADD.[S,D], SUB.[S,D], C.cond.[S,D], MUL.S	4	1
MADD.S, MSUB.S, NMADD.S, NMSUB.S, CABS.cond.[S,D]	4	1
CVT.D.S, CVT.PS.PW, CVT.[S,D].[W,L]	4	1
CVT.S.D, CVT.[W,L].[S,D], CEIL.[W,L].[S,D], FLOOR.[W,L].[S,D], ROUND.[W,L].[S,D], TRUNC.[W,L].[S,D]	4	1
MOV.[S,D], MOVF.[S,D], MOVN.[S,D], MOVT.[S,D], MOVZ.[S,D]	4	1
MUL.D	5	2
MADD.D, MSUB.D, NMADD.D, NMSUB.D	5	2
RECIP.S	13	10
RECIP.D	26	21
RSQRT.S	17	14
RSQRT.D	36	31
DIV.S, SQRT.S	17	14
DIV.D, SQRT.D	32	29
MTC1, DMTC1, LWC1, LDC1, LDXC1, LUXC1, LWXC1	4	1
MFC1, DMFC1, SWC1, SDC1, SDXC1, SUXC1, SWXC1	1	1

Legend: S = Single (32-bit) D = Double (64-bit) W = Word (32-bit) L = Long word (64-bit)

TABLE 4-15: SYSTEM BUS TARGET 7 REGISTER MAP

Virtual Address (BF8F_#)	Register Name	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
9C20	SBT7ELOG1	31:16	MULTI	—	—	—	CODE<3:0>				—	—	—	—	—	—	—	—	0000
		15:0	INITID<7:0>								REGION<3:0>				—	CMD<2:0>			0000
9C24	SBT7ELOG2	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	GROUP<1:0>		0000
9C28	SBT7ECON	31:16	—	—	—	—	—	—	—	ERRP	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
9C30	SBT7ECLRS	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	CLEAR	0000
9C38	SBT7ECLRM	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	CLEAR	0000
9C40	SBT7REG0	31:16	BASE<21:6>																xxxx
		15:0	BASE<5:0>						PRI	—	SIZE<4:0>					—	—	—	xxxx
9C50	SBT7RD0	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	xxxx
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	GROUP3	GROUP2	GROUP1	GROUP0	xxxx
9C58	SBT7WR0	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	xxxx
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	GROUP3	GROUP2	GROUP1	GROUP0	xxxx
9C60	SBT7REG1	31:16	BASE<21:6>																xxxx
		15:0	BASE<5:0>						PRI	—	SIZE<4:0>					—	—	—	xxxx
9C70	SBT7RD1	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	xxxx
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	GROUP3	GROUP2	GROUP1	GROUP0	xxxx
9C78	SBT7WR1	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	xxxx
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	GROUP3	GROUP2	GROUP1	GROUP0	xxxx

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
Note: For reset values listed as 'xxxx', please refer to Table 4-6 for the actual reset values.

7.0 CPU EXCEPTIONS AND INTERRUPT CONTROLLER

Note: This data sheet summarizes the features of the PIC32MZ EF family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 8. "Interrupt Controller"** (DS60001108) and **Section 50. "CPU for Devices with MIPS32® microAptiv™ and M-Class Cores"** (DS60001192) of the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

PIC32MZ EF devices generate interrupt requests in response to interrupt events from peripheral modules. The Interrupt Controller module exists outside of the CPU and prioritizes the interrupt events before presenting them to the CPU.

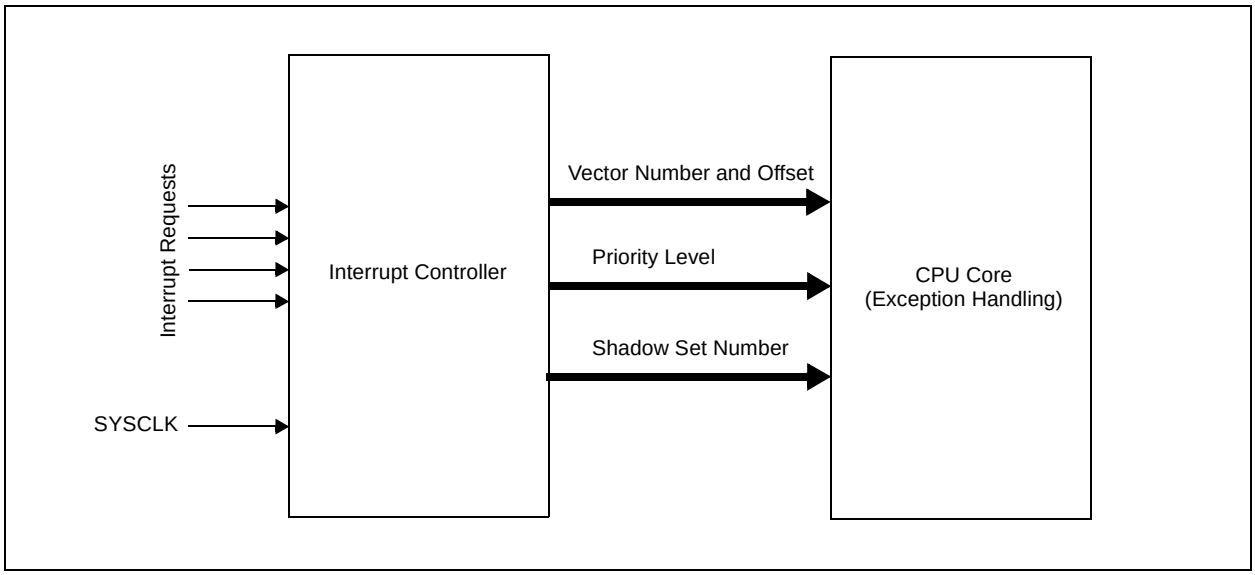
The CPU handles interrupt events as part of the exception handling mechanism, which is described in **Section 7.1 "CPU Exceptions"**.

The Interrupt Controller module includes the following features:

- Up to 213 interrupt sources and vectors with dedicated programmable offsets, eliminating the need for redirection
- Single and multi-vector mode operations
- Five external interrupts with edge polarity control
- Interrupt proximity timer
- Seven user-selectable priority levels for each vector
- Four user-selectable subpriority levels within each priority
- Seven shadow register sets that can be used for any priority level, eliminating software context switch and reducing interrupt latency
- Software can generate any interrupt

Figure 7-1 shows the block diagram for the Interrupt Controller and CPU exceptions.

FIGURE 7-1: CPU EXCEPTIONS AND INTERRUPT CONTROLLER MODULE BLOCK DIAGRAM



REGISTER 11-1: USBCSR0: USB CONTROL STATUS REGISTER 0 (CONTINUED)

bit 10 **RESUME:** Resume from Suspend control bit
1 = Generate Resume signaling when the device is in Suspend mode
0 = Stop Resume signaling

In *Device mode*, the software should clear this bit after 10 ms (a maximum of 15 ms) to end Resume signaling. In *Host mode*, the software should clear this bit after 20 ms.

bit 9 **SUSPMODE:** Suspend Mode status bit
1 = The USB module is in Suspend mode
0 = The USB module is in Normal operations

This bit is read-only in Device mode. In Host mode, it can be set by software, and is cleared by hardware.

bit 8 **SUSPEN:** Suspend Mode Enable bit
1 = Suspend mode is enabled
0 = Suspend mode is not enabled

bit 7 **Unimplemented:** Read as '0'

bit 6-0 **FUNC<6:0>:** Device Function Address bits

These bits are only available in *Device mode*. This field is written with the address received through a SET_ADDRESS command, which will then be used for decoding the function address in subsequent token packets.

REGISTER 11-8: USBIENCSR0: USB INDEXED ENDPOINT CONTROL STATUS REGISTER 0 (ENDPOINT 1-7)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	AUTOSET	ISO	MODE	DMAREQEN	FRCDATTG	DMAREQMD	—	—
		—					DATAWEN	DATATGGL
23:16	R/W-0, HS	R/W-0, HC	R/W-0, HS	R/W-0	R/W-0	R/W-0, HS	R/W-0	R/W-0, HC
	INCOMPTX	CLRDT	SENTSTALL	SENDSTALL	FLUSH	UNDERRUN	FIFONE	TXPKTRDY
	NAKTMOUT		RXSTALL	SETUPPKT		ERROR		
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	MULT<4:0>					TXMAXP<10:8>		
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TXMAXP<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **AUTOSET:** Auto Set Control bit

1 = TXPKTRDY will be automatically set when data of the maximum packet size (value in TXMAXP) is loaded into the TX FIFO. If a packet of less than the maximum packet size is loaded, then TXPKTRDY will have to be set manually.
0 = TXPKTRDY must be set manually for all packet sizes

bit 30 **ISO:** Isochronous TX Endpoint Enable bit (Device mode)

1 = Enables the endpoint for Isochronous transfers
0 = Disables the endpoint for Isochronous transfers and enables it for Bulk or Interrupt transfers.
This bit only has an effect in Device mode. In Host mode, it always returns zero.

bit 29 **MODE:** Endpoint Direction Control bit

1 = Endpoint is TX
0 = Endpoint is RX

This bit only has any effect where the same endpoint FIFO is used for both TX and RX transactions.

bit 28 **DMAREQEN:** Endpoint DMA Request Enable bit

1 = DMA requests are enabled for this endpoint
0 = DMA requests are disabled for this endpoint

bit 27 **FRCDATTG:** Force Endpoint Data Toggle Control bit

1 = Forces the endpoint data toggle to switch and the data packet to be cleared from the FIFO, regardless of whether an ACK was received.
0 = No forced behavior

bit 26 **DMAREQMD:** Endpoint DMA Request Mode Control bit

1 = DMA Request Mode 1
0 = DMA Request Mode 0

This bit must not be cleared either before or in the same cycle as the above DMAREQEN bit is cleared.

bit 25 **DATAWEN:** Data Toggle Write Enable bit (Host mode)

1 = Enable the current state of the TX Endpoint data toggle (DATATGGL) to be written
0 = Disables writing the DATATGGL bit

bit 24 **DATATGGL:** Data Toggle Control bit (Host mode)

When read, this bit indicates the current state of the TX Endpoint data toggle. If DATAWEN = 1, this bit may be written with the required setting of the data toggle. If DATAWEN = 0, any value written to this bit is ignored.

REGISTER 11-13: USBOTG: USB OTG CONTROL/STATUS REGISTER (CONTINUED)

bit 19-16 **TXFIFOSZ<3:0>:** TX Endpoint FIFO packet size bits

The maximum packet size to allowed for (before any splitting within the FIFO of Bulk/High-Bandwidth packets prior to transmission)

1111 = Reserved
•
•
•
1010 = Reserved
1001 = 4096 bytes
1000 = 2048 bytes
0111 = 1024 bytes
0110 = 512 bytes
0101 = 256 bytes
0100 = 128 bytes
0011 = 64 bytes
0010 = 32 bytes
0001 = 16 bytes
0000 = 8 bytes

bit 15-10 **Unimplemented:** Read as '0'

bit 9 **TXEDMA:** TX Endpoint DMA Assertion Control bit
1 = DMA_REQ signal for all IN endpoints will be deasserted when MAXP-8 bytes have been written to an endpoint. This is Early mode.
0 = DMA_REQ signal for all IN endpoints will be deasserted when MAXP bytes have been written to an endpoint. This is Late mode.

bit 8 **RXEDMA:** RX Endpoint DMA Assertion Control bit
1 = DMA_REQ signal for all OUT endpoints will be deasserted when MAXP-8 bytes have been written to an endpoint. This is Early mode.
0 = DMA_REQ signal for all OUT endpoints will be deasserted when MAXP bytes have been written to an endpoint. This is Late mode.

bit 7 **BDEV:** USB Device Type bit
1 = USB is operating as a 'B' device
0 = USB is operating as an 'A' device

bit 6 **FSDEV:** Full-Speed/Hi-Speed device detection bit (*Host mode*)
1 = A Full-Speed or Hi-Speed device has been detected being connected to the port
0 = No Full-Speed or Hi-Speed device detected

bit 5 **LSDEV:** Low-Speed Device Detection bit (*Host mode*)
1 = A Low-Speed device has been detected being connected to the port
0 = No Low-Speed device detected

bit 4-3 **VBUS<1:0>:** VBUS Level Detection bits
11 = Above VBUS Valid
10 = Above AValid, below VBUS Valid
01 = Above Session End, below AValid
00 = Below Session End

bit 2 **HOSTMODE:** Host Mode bit
1 = USB module is acting as a Host
0 = USB module is not acting as a Host

bit 1 **HOSTREQ:** Host Request Control bit
'B' device only:
1 = USB module initiates the Host Negotiation when Suspend mode is entered. This bit is cleared when Host Negotiation is completed.
0 = Host Negotiation is not taking place

12.2 Registers for Slew Rate Control

Some I/O pins can be configured for various types of slew rate control on its associated port. This is controlled by the Slew Rate Control bits in the SRCON1x and SRCON0x registers that are associated with each I/O port. The slew rate control is configured using the corresponding bit in each register, as shown in Table 12-1.

As an example, writing 0x0001, 0x0000 to SRCON1A and SRCON0A, respectively, will enable slew rate control on the RA0 pin and sets the slew rate to the slow edge rate.

TABLE 12-1: SLEW RATE CONTROL BIT SETTINGS

SRCON1x	SRCON0x	Description
1	1	Slew rate control is enabled and is set to the slowest edge rate.
1	0	Slew rate control is enabled and is set to the slow edge rate.
0	1	Slew rate control is enabled and is set to the medium edge rate.
0	0	Slew rate control is disabled and is set to the fastest edge rate.

Note: By default, all of the Port pins are set to the fastest edge rate.

12.3 CLR, SET, and INV Registers

Every I/O module register has a corresponding CLR (clear), SET (set) and INV (invert) register designed to provide fast atomic bit manipulations. As the name of the register implies, a value written to a SET, CLR or INV register effectively performs the implied operation, but only on the corresponding base register and only bits specified as '1' are modified. Bits specified as '0' are not modified.

Reading SET, CLR and INV registers returns undefined values. To see the affects of a write operation to a SET, CLR or INV register, the base register must be read.

12.4 Peripheral Pin Select (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. The challenge is even greater on low pin-count devices. In an application where more than one peripheral needs to be assigned to a single pin, inconvenient workarounds in application code or a complete redesign may be the only option.

PPS configuration provides an alternative to these choices by enabling peripheral set selection and their placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the device to their entire application, rather than trimming the application to fit the device.

The PPS configuration feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of most digital peripherals to these I/O pins. PPS is performed in software and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

12.4.1 AVAILABLE PINS

The number of available pins is dependent on the particular device and its pin count. Pins that support the PPS feature include the designation "RPn" in their full pin designation, where "RP" designates a remappable peripheral and "n" is the remappable port number.

12.4.2 AVAILABLE PERIPHERALS

The peripherals managed by the PPS are all digital-only peripherals. These include general serial communications (UART, SPI, and CAN), general purpose timer clock inputs, timer-related peripherals (input capture and output compare), interrupt-on-change inputs, and reference clocks (input and output).

In comparison, some digital-only peripheral modules are never included in the PPS feature. This is because the peripheral's function requires special I/O circuitry on a specific port and cannot be easily connected to multiple pins. These modules include I^2C among others. A similar requirement excludes all modules with analog inputs, such as the Analog-to-Digital Converter (ADC).

A key difference between remappable and non-remappable peripherals is that remappable peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-remappable peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

When a remappable peripheral is active on a given I/O pin, it takes priority over all other digital I/O and digital communication peripherals associated with the pin. Priority is given regardless of the type of peripheral that is mapped. Remappable peripherals never take priority over any analog functions associated with the pin.

REGISTER 16-1: WDTCON: WATCHDOG TIMER CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
	WDTCLRKEY<15:8>							
23:16	W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
	WDTCLRKEY<7:0>							
15:8	R/W-y	U-0	U-0	R-y	R-y	R-y	R-y	R-y
	ON(1)	—	—	RUNDIV<4:0>				
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
	—	—	—	—	—	—	—	WDTWINEN

Legend:	y = Values set from Configuration bits on POR		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **WDTCLRKEY:** Watchdog Timer Clear Key bits
To clear the Watchdog Timer to prevent a time-out, software must write the value 0x5743 to this location using a single 16-bit write.

bit 15 **ON:** Watchdog Timer Enable bit(1)
1 = The WDT is enabled
0 = The WDT is disabled

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **RUNDIV<4:0>:** Watchdog Timer Postscaler Value bits
On reset, these bits are set to the values of the WDTPS<4:0> Configuration bits in DEVCFG1.

bit 7-1 **Unimplemented:** Read as '0'

bit 0 **WDTWINEN:** Watchdog Timer Window Enable bit
1 = Enable windowed Watchdog Timer
0 = Disable windowed Watchdog Timer

Note 1: This bit only has control when the FWDTEN bit (DEVCFG1<23>) = 0.

REGISTER 20-5: SQI1CLKCON: SQI CLOCK CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	—	CLKDIV<10:8>(1)		
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CLKDIV<7:0>(1)							
7:0	U-0	U-0	U-0	U-0	U-0	U-0	R-0	R/W-0
	—	—	—	—	—	—	STABLE	EN

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-19 **Unimplemented:** Read as '0'

bit 18-8 **CLKDIV<10:0>:** SQI Clock TSQI Frequency Select bit(1)

10000000000 = Base clock TBC is divided by 2048
01000000000 = Base clock TBC is divided by 1024
00100000000 = Base clock TBC is divided by 512
00010000000 = Base clock TBC is divided by 256
00001000000 = Base clock TBC is divided by 128
00000100000 = Base clock TBC is divided by 64
00000010000 = Base clock TBC is divided by 32
00000001000 = Base clock TBC is divided by 16
00000000100 = Base clock TBC is divided by 8
00000000010 = Base clock TBC is divided by 4
00000000001 = Base clock TBC is divided by 2
00000000000 = Base clock TBC

Setting these bits to '00000000000' specifies the highest frequency of the SQI clock.

bit 7-2 **Unimplemented:** Read as '0'

bit 1 **STABLE:** TSQI Clock Stable Select bit

This bit is set to '1' when the SQI clock, TSQI, is stable after writing a '1' to the EN bit.
1 = TSQI clock is stable
0 = TSQI clock is not stable

bit 0 **EN:** TSQI Clock Enable Select bit

When clock oscillation is stable, the SQI module will set the STABLE bit to '1'.
1 = Enable the SQI clock (TSQI) (when clock oscillation is stable, the SQI module sets the STABLE bit to '1')
0 = Disable the SQI clock (TSQI) (the SQI module should stop its clock to enter a low power state); SFRs can still be accessed, as they use PBCLK5

Note 1: Refer to Table 37-34 in **37.0 "Electrical Characteristics"** for the maximum clock frequency specifications.

REGISTER 23-4: PMDOUT: PARALLEL PORT OUTPUT DATA REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATAOUT<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATAOUT<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **DATAOUT<15:0>:** Port Data Output bits

This register is used for Read operations in the Enhanced Parallel Slave mode and Write operations for Dual Buffer Master mode.

In Dual Buffer Master mode, the DUALBUF bit (PMPCON<17>) = 1, a write to the MSB triggers the transaction on the PMP port. When MODE16 = 1, MSB = DATAOUT<15:8>. When MODE16 = 0, MSB = DATAOUT<7:0>.

Note: In Master mode, a read will return the last value written to the register. In Slave mode, a read will return indeterminate results.

REGISTER 23-5: PMDIN: PARALLEL PORT INPUT DATA REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATAIN<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATAIN<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **DATAIN<15:0>:** Port Data Input bits

This register is used for both Parallel Master Port mode and Enhanced Parallel Slave mode.

In Parallel Master mode, a write to the MSB triggers the write transaction on the PMP port. Similarly, a read to the MSB triggers the read transaction on the PMP port.

When MODE16 = 1, MSB = DATAIN<15:8>. When MODE16 = 0, MSB = DATAIN<7:0>.

Note: This register is not used in Dual Buffer Master mode (i.e., DUALBUF bit (PMPCON<17>) = 1).

REGISTER 30-3: ETHTXST: ETHERNET CONTROLLER TX PACKET DESCRIPTOR START ADDRESS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TXSTADDR<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TXSTADDR<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TXSTADDR<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
	TXSTADDR<7:2>						—	—

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-2 **TXSTADDR<31:2>:** Starting Address of First Transmit Descriptor bits
This register should not be written while any transmit, receive or DMA operations are in progress.
This address must be 4-byte aligned (bits 1-0 must be '00').

bit 1-0 **Unimplemented:** Read as '0'

Note 1: This register is only used for TX operations.
2: This register will be updated by hardware with the last descriptor used by the last successfully transmitted packet.

REGISTER 30-4: ETHRXST: ETHERNET CONTROLLER RX PACKET DESCRIPTOR START ADDRESS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RXSTADDR<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RXSTADDR<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RXSTADDR<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
	RXSTADDR<7:2>						—	—

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-2 **RXSTADDR<31:2>:** Starting Address of First Receive Descriptor bits
This register should not be written while any transmit, receive or DMA operations are in progress.
This address must be 4-byte aligned (bits 1-0 must be '00').

bit 1-0 **Unimplemented:** Read as '0'

Note 1: This register is only used for RX operations.
2: This register will be updated by hardware with the last descriptor used by the last successfully transmitted packet.

REGISTER 31-1: CMxCON: COMPARATOR CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	R-0
	ON	COE	CPOL(1)	—	—	—	—	COUT
7:0	R/W-1	R/W-1	U-0	R/W-0	U-0	U-0	R/W-1	R/W-1
	EVPOL<1:0>		—	CREF	—	—	CCH<1:0>	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** Comparator ON bit
- 1 = Module is enabled. Setting this bit does not affect the other bits in this register
- 0 = Module is disabled and does not consume current. Clearing this bit does not affect the other bits in this register

bit 14 **COE:** Comparator Output Enable bit
- 1 = Comparator output is driven on the output CxOUT pin
- 0 = Comparator output is not driven on the output CxOUT pin

bit 13 **CPOL:** Comparator Output Inversion bit(1)
- 1 = Output is inverted
- 0 = Output is not inverted

bit 12-9 **Unimplemented:** Read as '0'

bit 8 **COUT:** Comparator Output bit
- 1 = Output of the Comparator is a '1'
- 0 = Output of the Comparator is a '0'

bit 7-6 **EVPOL<1:0>:** Interrupt Event Polarity Select bits
- 11 = Comparator interrupt is generated on a low-to-high or high-to-low transition of the comparator output
- 10 = Comparator interrupt is generated on a high-to-low transition of the comparator output
- 01 = Comparator interrupt is generated on a low-to-high transition of the comparator output
- 00 = Comparator interrupt generation is disabled

bit 5 **Unimplemented:** Read as '0'

bit 4 **CREF:** Comparator Positive Input Configure bit
- 1 = Comparator non-inverting input is connected to the internal CVREF
- 0 = Comparator non-inverting input is connected to the CXINA pin

bit 3-2 **Unimplemented:** Read as '0'

bit 1-0 **CCH<1:0>:** Comparator Negative Input Select bits for Comparator
- 11 = Comparator inverting input is connected to the IVREF
- 10 = Comparator inverting input is connected to the CxIND pin
- 01 = Comparator inverting input is connected to the CxINC pin
- 00 = Comparator inverting input is connected to the CxINB pin

Note 1: Setting this bit will invert the signal to the comparator interrupt generator as well. This will result in an interrupt being generated on the opposite edge from the one selected by EVPOL<1:0>.

NOTES:

TABLE 37-30: SPIx MASTER MODE (CKE = 0) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 2.1V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	**Symbol**	**Characteristics(1)**	**Min.**	**Typ.(2)**	**Max.**	**Units**	**Conditions**
SP10	TscL	SCKx Output Low Time **(Note 3)**	Tsck/2	—	—	ns	—
SP11	TscH	SCKx Output High Time **(Note 3)**	Tsck/2	—	—	ns	—
SP15	TscK	SPI Clock Speed **(Note 5)**	—	—	25	MHz	SPI1, SPI4 through SPI6
			—	—	50	MHz	SPI2 on RPB3, RPB5
			—	—	25	MHz	SPI2 on other I/O
			—	—	50	MHz	SPI3 on RPB10, RPB9, RPF0
			—	—	25	MHz	SPI3 on other I/O
SP20	TscF	SCKx Output Fall Time **(Note 4)**	—	—	—	ns	See parameter DO32
SP21	TscR	SCKx Output Rise Time **(Note 4)**	—	—	—	ns	See parameter DO31
SP30	TdoF	SDOx Data Output Fall Time **(Note 4)**	—	—	—	ns	See parameter DO32
SP31	TdoR	SDOx Data Output Rise Time **(Note 4)**	—	—	—	ns	See parameter DO31
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	—	7	ns	VDD > 2.7V
			—	—	10	ns	VDD < 2.7V
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	5	—	—	ns	—
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	5	—	—	ns	—

Note 1: These parameters are characterized, but not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

3: The minimum clock period for SCKx is 20 ns. Therefore, the clock generated in Master mode must not violate this specification.

4: Assumes 30 pF load on all SPIx pins.

5: To achieve maximum data rate, VDD must be ≥ 3.3V, the SMP bit (SPIxCON<9>) must be equal to '1', and the operating temperature must be within the range of -40°C to +105°C.

TABLE 38-3: DC CHARACTERISTICS: IDLE CURRENT (IIDLE)

DC CHARACTERISTICS			Standard Operating Conditions: 2.1V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +125°C for Extended	
Parameter No.	**Typical(2)**	**Maximum(4)**	**Units**	**Conditions**
Idle Current (IIDLE): Core Off, Clock on Base Current (Note 1)				
EDC30a	7	52	mA	4 MHz **(Note 3)**
EDC31a	8	56	mA	10 MHz
EDC32a	13	66	mA	60 MHz **(Note 3)**
EDC33a	21	86	mA	130 MHz **(Note 3)**
EDC34	26	96	mA	180 MHz **(Note 3)**

Note 1: The test conditions for IIDLE current measurements are as follows:

- Oscillator mode is EC+PLL with OSC1 driven by external square wave from rail-to-rail, (OSC1 input clock input over/undershoot < 100 mV required)
- OSC2/CLKO is configured as an I/O input pin
- USB PLL is disabled (USBPMD = 1), VUSB3V3 is connected to VSS, PBCLKx divisor = 1:128 ('x' ≠ 7)
- CPU is in Idle mode (CPU core Halted)
- L1 Cache and Prefetch modules are disabled
- No peripheral modules are operating, (ON bit = 0), but the associated PMD bit is cleared (except USBPMD)
- WDT, DMT, Clock Switching, Fail-Safe Clock Monitor, and Secondary Oscillator are disabled
- All I/O pins are configured as inputs and pulled to VSS
- $\overline{\text{MCLR}}$ = VDD
- RTCC and JTAG are disabled

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

3: This parameter is characterized, but not tested in manufacturing.

4: Data in the "Maximum" column is at 3.3V, +125ºC at specified operating frequency. Parameters are for design guidance only and are not tested.

TABLE 39-3: DC CHARACTERISTICS: IDLE CURRENT (I_{IDLE})

DC CHARACTERISTICS			Standard Operating Conditions: 2.1V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial	
Parameter No.	**Typical(2)**	**Maximum(4)**	**Units**	**Conditions**
Idle Current (I_{IDLE}): Core Off, Clock on Base Current (Note 1)				
MDC35	41	60	mA	252 MHz

Note 1: The test conditions for IIDLE current measurements are as follows:

- Oscillator mode is EC+PLL with OSC1 driven by external square wave from rail-to-rail, (OSC1 input clock input over/undershoot < 100 mV required)
- OSC2/CLKO is configured as an I/O input pin
- USB PLL is disabled (USBPMD = 1), VUSB3V3 is connected to VSS, PBCLKx divisor = 1:128 ('x' ≠ 7)
- CPU is in Idle mode (CPU core Halted)
- L1 Cache and Prefetch modules are disabled
- No peripheral modules are operating, (ON bit = 0), but the associated PMD bit is cleared (except USBPMD)
- WDT, DMT, Clock Switching, Fail-Safe Clock Monitor, and Secondary Oscillator are disabled
- All I/O pins are configured as inputs and pulled to VSS
- $\overline{MCLR}$ = VDD
- RTCC and JTAG are disabled

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

3: This parameter is characterized, but not tested in manufacturing.

4: Data in the "Maximum" column is at 3.3V, +85ºC at specified operating frequency, unless otherwise stated. Parameters are for design guidance only and are not tested.

FIGURE 40-5: VOH – 12x DRIVER PINS

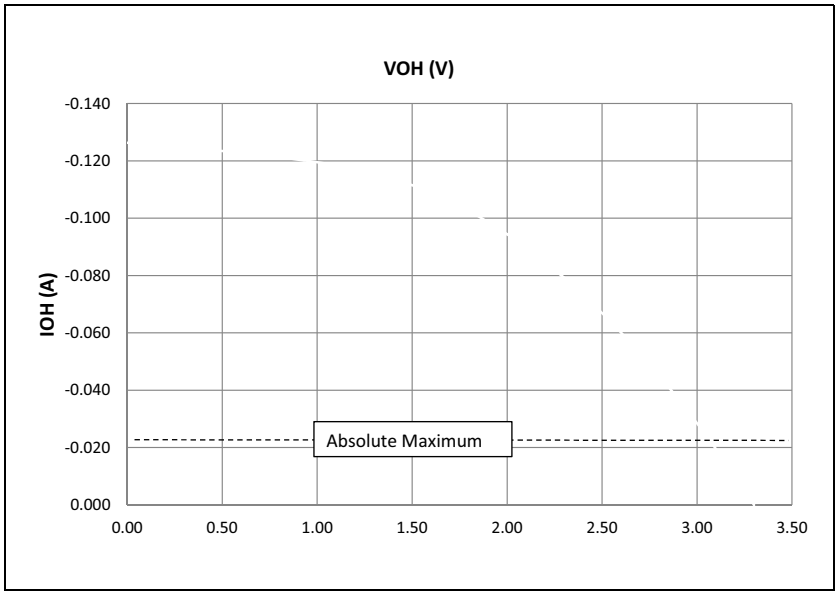


FIGURE 40-6: VOL – 12x DRIVER PINS

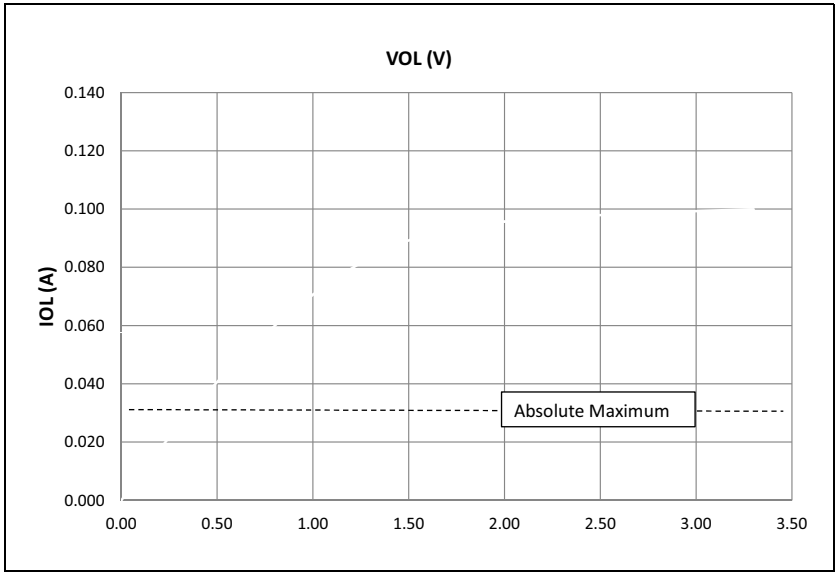
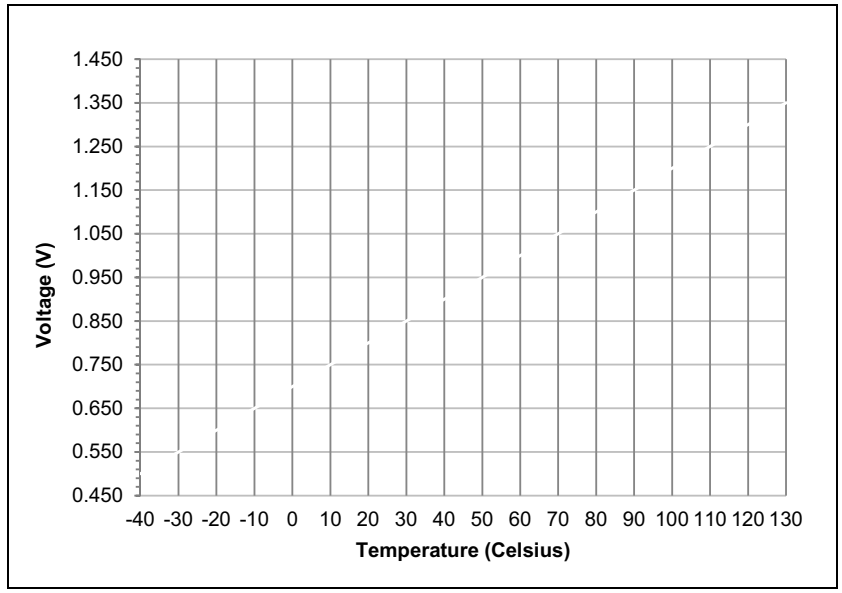
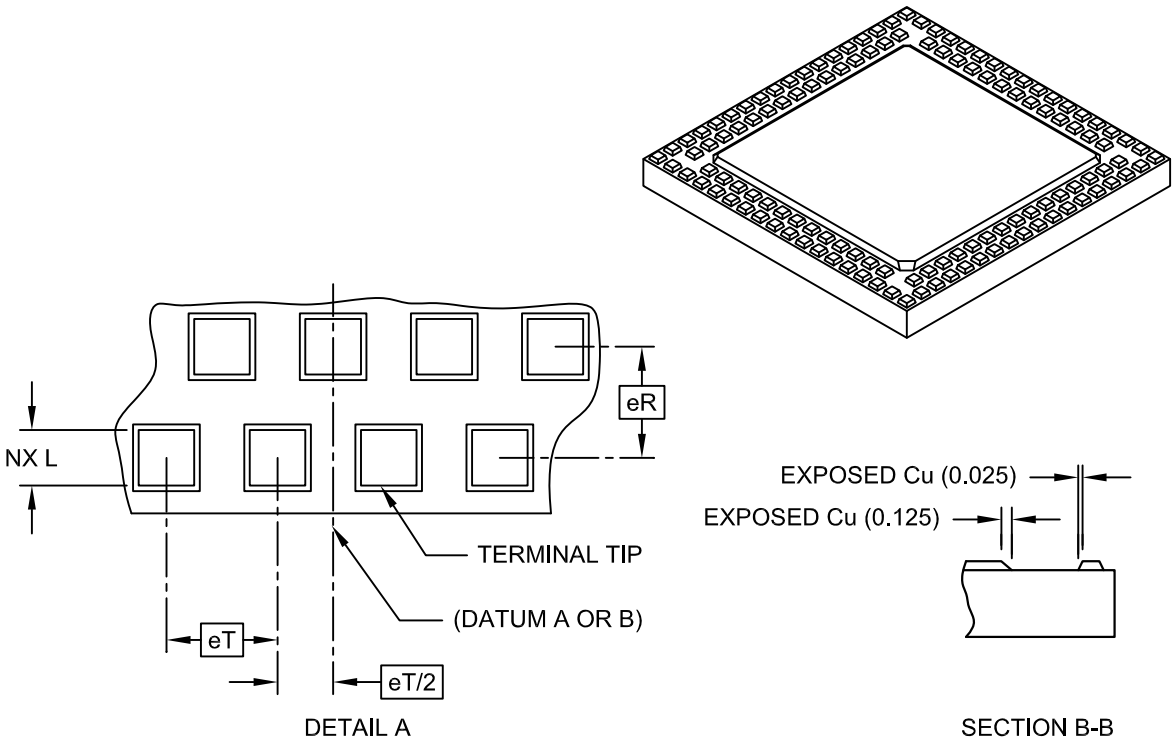


FIGURE 40-7: TYPICAL TEMPERATURE SENSOR VOLTAGE



124-Terminal Very Thin Leadless Array Package (TL) – 9x9x0.9 mm Body [VTLA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N		124	
Pitch	eT		0.50 BSC	
Pitch (Inner to outer terminal ring)	eR		0.50 BSC	
Overall Height	A	0.80	0.85	0.90
Standoff	A1	0.00	-	0.05
Overall Width	E		9.00 BSC	
Exposed Pad Width	E2	6.40	6.55	6.70
Overall Length	D		9.00 BSC	
Exposed Pad Length	D2	6.40	6.55	6.70
Contact Width	b	0.20	0.25	0.30
Contact Length	L	0.20	0.25	0.30
Contact-to-Exposed Pad	K	0.20	-	-

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated.
3. Dimensioning and tolerancing per ASME Y14.5M.
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.
   REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-193A Sheet 2 of 2

NOTES:

TABLE A-3: ADC DIFFERENCES (CONTINUED)

PIC32MX5XX/6XX/7XX Feature	PIC32MZ EF Feature
Scan Trigger Source	
On PIC32MX devices, there are four sources that can trigger a scan conversion in the ADC module: Auto, Timer3, INT0, and clearing the SAMP bit. SSRC<2:0> (AD1CON1<7:5>) 111 = Auto convert 110 = Reserved 101 = Reserved 100 = Reserved 011 = Reserved 010 = Timer3 period match 001 = Active transition on INT0 pin 000 = Clearing SAMP bit	On PIC32MZ EF devices, the list of sources for triggering a scan conversion has been expanded to include the comparators, Output Compare, and two additional Timers. In addition, trigger sources can be simulated by setting the RQCNVRT (ADCCON3<8>) bit. STRGSRC<4:0> (ADCCON1<20:16>) 11111 = Reserved • • • 01101 = Reserved 01100 = Comparator 2 COUT 01011 = Comparator 1 COUT 01010 = OCMP5 01001 = OCMP3 01000 = OCMP1 00111 = TMR5 match 00110 = TMR3 match 00101 = TMR1 match 00100 = INT0 00011 = Reserved 00010 = Global level software trigger (GLSWTRG) 00001 = Global software trigger (GSWTRG) 00000 = No trigger
Output Format	
On PIC32MX devices, the output format was decided for all ADC channels based on the setting of the FORM<2:0> bits. FORM<2:0> (AD1CON1<10:8>) 011 = Signed Fractional 16-bit 010 = Fractional 16-bit 001 = Signed Integer 16-bit 000 = Integer 16-bit 111 = Signed Fractional 32-bit 110 = Fractional 32-bit 101 = Signed Integer 32-bit 100 = Integer 32-bit	On PIC32MZ EF devices, the FRACT bit determines whether fractional or integer format is used. Then, each input can have its own setting for input (differential or single-ended) and sign (signed or unsigned) using the DIFFx and SIGNx bits in the ADCIMODx registers. FRACT (ADCCON1<23>) 1 = Fractional 0 = Integer DIFFx (ADCIMODy) 1 = Channel x is using Differential mode 0 = Channel x is using Single-ended mode SIGNx (ADCMODy) 1 = Channel x is using Signed Data mode 0 = Channel x is using Unsigned Data mode
Interrupts	
On PIC32MX devices, an interrupt is triggered from the ADC module when a certain number of conversions have taken place, irrespective of which channel was converted. SMPI<3:0> (AD1CON2<5:2>) 1111 = Interrupt for each 16th sample/convert sequence 1110 = Interrupt for each 15th sample/convert sequence • • • 0001 = Interrupt for each 2nd sample/convert sequence 0000 = Interrupt for each sample/convert sequence	On PIC32MZ EF devices, the ADC module can trigger an interrupt for each channel when it is converted. Use the Interrupt Controller bits, IEC1<31:27>, IEC2<31:0>, and IEC3<7:0>, to enable/disable them. In addition, the ADC support one global interrupt to indicate conversion on any number of channels. AGIENxx (ADCGIRQENx<y>) 1 = Data ready event will generate a Global ADC interrupt 0 = No global interrupt In addition, interrupts can be generated for filter and comparator events.