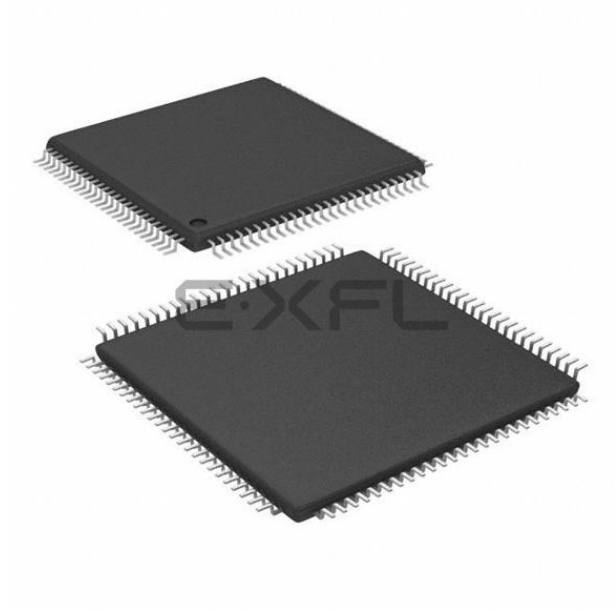
Microchip Technology - PIC32MZ1024EFG100-E/PF Datasheet



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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® M-Class
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	EBI/EMI, Ethernet, I²C, PMP, SPI, SQI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	78
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	2.1V ~ 3.6V
Data Converters	A/D 40x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mz1024efg100-e-pf

TABLE 5: PIN NAMES FOR 144-PIN DEVICES

144-PIN LQFP AND TQFP (TOP VIEW)

PIC32MZ0512EF(E/F/K)144
PIC32MZ1024EF(G/H/M)144
PIC32MZ1024EF(E/F/K)144
PIC32MZ2048EF(G/H/M)144

144

1

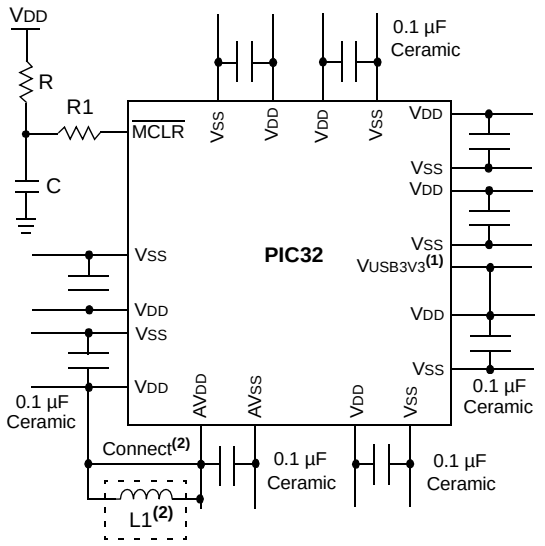
Pin Number	Full Pin Name	Pin Number	Full Pin Name
1	AN23/RG15	37	PGEC2/AN46/RPB6/RB6
2	EBIA5/AN34/PMA5/RA5	38	PGED2/AN47/RPB7/RB7
3	EBID5/AN17/RPE5/PMD5/RE5	39	VREF-/CVREF-/AN27/RA9
4	EBID6/AN16/PMD6/RE6	40	VREF+/CVREF+/AN28/RA10
5	EBID7/AN15/PMD7/RE7	41	AVDD
6	EBIA6/AN22/RPC1/PMA6/RC1	42	AVSS
7	AN35/ETXD0/RJ8	43	AN38/ETXD2/RH0
8	AN36/ETXD1/RJ9	44	AN39/ETXD3/RH1
9	EBIBS0/RJ12	45	EBIRP/RH2
10	EBIBS1/RJ10	46	RH3
11	EBIA12/AN21/RPC2/PMA12/RC2	47	EBIA10/AN48/RPB8/PMA10/RB8
12	EBIWE/AN20/RPC3/PMWR/RC3	48	EBIA7/AN49/RPB9/PMA7/RB9
13	EBIOE/AN19/RPC4/PMRD/RC4	49	CVREFOUT/AN5/RPB10/RB10
14	AN14/C1IND/RPG6/SCK2/RG6	50	AN6/RB11
15	AN13/C1INC/RPG7/SDA4/RG7	51	EBIA1/PMA1/RK1
16	AN12/C2IND/RPG8/SCL4/RG8	52	EBIA3/PMA3/RK2
17	VSS	53	EBIA17/RK3
18	VDD	54	VSS
19	EBIA16/RK0	55	VDD
20	MCLR	56	TCK/AN29/RA1
21	EBIA2/AN11/C2INC/RPG9/PMA2/RG9	57	TDI/AN30/RPF13/SCK5/RF13
22	TMS/AN24/RA0	58	TDO/AN31/RPF12/RF12
23	AN25/RPE8/RE8	59	AN7/RB12
24	AN26/RPE9/RE9	60	AN8/RB13
25	AN45/C1INA/RPB5/RB5	61	AN9/RPB14/SCK3/RB14
26	AN4/C1INB/RB4	62	AN10/RPB15/OCFB/RB15
27	AN37/ERXCLK/EREFCLK/RJ11	63	VSS
28	EBIA13/PMA13/RJ13	64	VDD
29	EBIA11/PMA11/RJ14	65	AN40/ERXERR/RH4
30	EBIA0/PMA0/RJ15	66	AN41/ERXD1/RH5
31	AN3/C2INA/RPB3/RB3	67	AN42/ERXD2/RH6
32	VSS	68	EBIA4/PMA4/RH7
33	VDD	69	AN32/RPD14/RD14
34	AN2/C2INB/RPB2/RB2	70	AN33/RPD15/SCK6/RD15
35	PGEC1/AN1/RPB1/RB1	71	OSC1/CLKI/RC12
36	PGED1/AN0/RPB0/RB0	72	OSC2/CLKO/RC15

Note 1: The RPn pins can be used by remappable peripherals. See Table 1 for the available peripherals and **Section 12.4 "Peripheral Pin Select (PPS)"** for restrictions.

2: Every I/O port pin (RAx-RKx) can be used as a change notification pin (CNAx-CNKx). See **Section 12.0 "I/O Ports"** for more information.

3: Shaded pins are 5V tolerant.

FIGURE 2-1: RECOMMENDED MINIMUM CONNECTION



Note 1: If the USB module is not used, this pin must be connected to VSS.

2: As an option, instead of a hard-wired connection, an inductor (L1) can be substituted between VDD and AVDD to improve ADC noise rejection. The inductor impedance should be less than 1Ω and the inductor capacity greater than 10 mA.

Where:

$$f = \frac{FCNV}{2} \quad \text{(i.e., ADC conversion rate/2)}$$

$$f = \frac{1}{(2\pi\sqrt{LC})}$$

$$L = \left(\frac{1}{(2\pi f\sqrt{C})}\right)^2$$

2.2.1 BULK CAPACITORS

The use of a bulk capacitor is recommended to improve power supply stability. Typical values range from 4.7 µF to 47 µF. This capacitor should be located as close to the device as possible.

2.3 Master Clear (MCLR) Pin

The MCLR pin provides for two specific device functions:

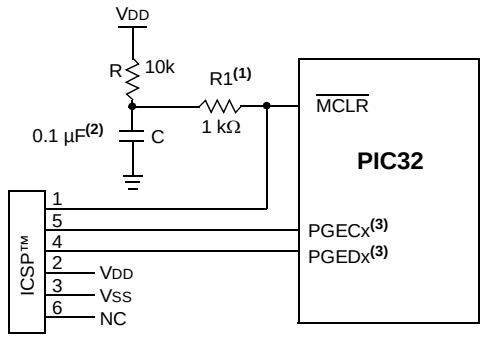
- Device Reset
- Device programming and debugging

Pulling The MCLR pin low generates either a device Reset or a POR, depending on the setting of the SMCLR bit (DEVCFG0<15>). Figure 2-2 illustrates a typical MCLR circuit. During device programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the MCLR pin. Consequently, specific voltage levels (VIH and VIL) and fast signal transitions must not be adversely affected. Therefore, specific values of R and C will need to be adjusted based on the application and PCB requirements.

For example, as illustrated in Figure 2-2, it is recommended that the capacitor C be isolated from the MCLR pin during programming and debugging operations.

Place the components illustrated in Figure 2-2 within one-quarter inch (6 mm) from the MCLR pin.

FIGURE 2-2: EXAMPLE OF MCLR PIN CONNECTIONS



Note 1: 470Ω ≤ R1 ≤ 1kΩ will limit any current flowing into MCLR from the external capacitor C, in the event of MCLR pin breakdown, due to Electrostatic Discharge (ESD) or Electrical Overstress (EOS). Ensure that the MCLR pin VIH and VIL specifications are met without interfering with the Debug/Programmer tools.

2: The capacitor can be sized to prevent unintentional Resets from brief glitches or to extend the device Reset period during POR.

3: No pull-ups or bypass capacitors are allowed on active debug/program PGECx/PGEDx pins.

3.1.4 FLOATING POINT UNIT (FPU)

The Floating Point Unit (FPU), Coprocessor (CP1), implements the MIPS Instruction Set Architecture for floating point computation. The implementation supports the ANSI/IEEE Standard 754 (IEEE for Binary Floating Point Arithmetic) for 32-bit and 64-bit floating point data formats. The FPU can be programmed to have thirty-two 32-bit or 64-bit floating point registers used for floating point operations.

The performance is optimized for 32-bit formats. Most instructions have one FPU cycle throughput and four FPU cycle latency. The FPU implements the multiply-add (MADD) and multiply-sub (MSUB) instructions with intermediate rounding after the multiply function. The result is guaranteed to be the same as executing a MUL and an ADD instruction separately, but the instruction latency, instruction fetch, dispatch bandwidth, and the total number of register accesses are improved.

IEEE denormalized input operands and results are supported by hardware for some instructions. IEEE denormalized results are not supported by hardware in general, but a fast flush-to-zero mode is provided to optimize performance. The fast flush-to-zero mode is enabled through the FCCR register, and use of this mode is recommended for best performance when denormalized results are generated.

The FPU has a separate pipeline for floating point instruction execution. This pipeline operates in parallel with the integer core pipeline and does not stall when the integer pipeline stalls. This allows long-running FPU operations, such as divide or square root, to be partially masked by system stalls and/or other integer unit instructions. Arithmetic instructions are always dispatched and completed in order, but loads and stores can complete out of order. The exception model is “precise” at all times.

Table 3-4 contains the floating point instruction latencies and repeat rates for the processor core. In this table, 'Latency' refers to the number of FPU cycles necessary for the first instruction to produce the result needed by the second instruction. The “Repeat Rate” refers to the maximum rate at which an instruction can be executed per FPU cycle.

TABLE 3-4: FPU INSTRUCTION LATENCIES AND REPEAT RATES

Op code	Latency (FPU Cycles)	Repeat Rate (FPU Cycles)
ABS.[S,D], NEG.[S,D], ADD.[S,D], SUB.[S,D], C.cond.[S,D], MUL.S	4	1
MADD.S, MSUB.S, NMADD.S, NMSUB.S, CABS.cond.[S,D]	4	1
CVT.D.S, CVT.PS.PW, CVT.[S,D].[W,L]	4	1
CVT.S.D, CVT.[W,L].[S,D], CEIL.[W,L].[S,D], FLOOR.[W,L].[S,D], ROUND.[W,L].[S,D], TRUNC.[W,L].[S,D]	4	1
MOV.[S,D], MOVF.[S,D], MOVN.[S,D], MOVT.[S,D], MOVZ.[S,D]	4	1
MUL.D	5	2
MADD.D, MSUB.D, NMADD.D, NMSUB.D	5	2
RECIP.S	13	10
RECIP.D	26	21
RSQRT.S	17	14
RSQRT.D	36	31
DIV.S, SQRT.S	17	14
DIV.D, SQRT.D	32	29
MTC1, DMTC1, LWC1, LDC1, LDXC1, LUXC1, LWXC1	4	1
MFC1, DMFC1, SWC1, SDC1, SDXC1, SUXC1, SWXC1	1	1

Legend: S = Single (32-bit) D = Double (64-bit) W = Word (32-bit) L = Long word (64-bit)

REGISTER 3-10: FCSR: FLOATING POINT CONTROL AND STATUS REGISTER; CP1 REGISTER 31

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	FCC<7:1>							FS
23:16	R/W-x	R/W-x	R/W-x	R-0	R-1	R-1	R/W-x	R/W-x
	FCC<0>	FO	FN	MAC2008	ABS2008	NAN2008	CAUSE<5:4>	
15:8	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	CAUSE<3:0>				ENABLES<4:1>			
					V	Z	O	U
7:0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	ENABLES<0>	FLAGS<4:0>					RM<1:0>	
	I	V	Z	O	U	I		

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-25 **FCC<7:1>:** Floating Point Condition Code bits
These bits record the results of floating point compares and are tested for floating point conditional branches and conditional moves.

bit 24 **FS:** Flush to Zero control bit
1 = Denormal input operands are flushed to zero. Tiny results are flushed to either zero or the applied format's smallest normalized number (MinNorm) depending on the rounding mode settings.
0 = Denormal input operands result in an Unimplemented Operation exception.

bit 23 **FCC<0>:** Floating Point Condition Code bits
These bits record the results of floating point compares and are tested for floating point conditional branches and conditional moves.

bit 22 **FO:** Flush Override Control bit
1 = The intermediate result is kept in an internal format, which can be perceived as having the usual mantissa precision but with unlimited exponent precision and without forcing to a specific value or taking an exception.
0 = Handling of Tiny Result values depends on setting of the FS bit.

bit 21 **FN:** Flush to Nearest Control bit
1 = Final result is rounded to either zero or 2E_min (MinNorm), whichever is closest when in Round to Nearest (RN) rounding mode. For other rounding modes, a final result is given as if FS was set to 1.
0 = Handling of Tiny Result values depends on setting of the FS bit.

bit 20 **MAC2008:** Fused Multiply Add mode control bit
0 = Unfused multiply-add. Intermediary multiplication results are rounded to the destination format.

bit 19 **ABS2008:** Absolute value format control bit
1 = ABS.fmt and NEG.fmt instructions compliant with IEEE Standard 754-2008. The ABS and NEG functions accept QNAN inputs without trapping.

bit 18 **NAN2008:** NaN Encoding control bit
1 = Quiet and signaling NaN encodings recommended by the IEEE Standard 754-2008. A quiet NaN is encoded with the first bit of the fraction being 1 and a signaling NaN is encoded with the first bit of the fraction being 0.

bit 17-12 **CAUSE<5:0>:** FPU Exception Cause bits
These bits indicated the exception conditions that arise during execution of an FPU arithmetic instruction.

bit 17 **E:** Unimplemented Operation bit

REGISTER 10-8: DCHxECON: DMA CHANNEL x EVENT CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
	CHAIRQ<7:0>(1)							
15:8	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
	CHSIRQ<7:0>(1)							
7:0	S-0	S-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
	CFORCE	CABORT	PATEN	SIRQEN	AIRQEN	—	—	—

Legend:	S = Settable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-24 **Unimplemented:** Read as '0'

bit 23-16 **CHAIRQ<7:0>:** Channel Transfer Abort IRQ bits(1)

11111111 = Interrupt 255 will abort any transfers in progress and set CHAIF flag
•
•
•
00000001 = Interrupt 1 will abort any transfers in progress and set CHAIF flag
00000000 = Interrupt 0 will abort any transfers in progress and set CHAIF flag

bit 15-8 **CHSIRQ<7:0>:** Channel Transfer Start IRQ bits(1)

11111111 = Interrupt 255 will initiate a DMA transfer
•
•
•
00000001 = Interrupt 1 will initiate a DMA transfer
00000000 = Interrupt 0 will initiate a DMA transfer

bit 7 **CFORCE:** DMA Forced Transfer bit

1 = A DMA transfer is forced to begin when this bit is written to a '1'
0 = This bit always reads '0'

bit 6 **CABORT:** DMA Abort Transfer bit

1 = A DMA transfer is aborted when this bit is written to a '1'
0 = This bit always reads '0'

bit 5 **PATEN:** Channel Pattern Match Abort Enable bit

1 = Abort transfer and clear CHEN on pattern match
0 = Pattern match is disabled

bit 4 **SIRQEN:** Channel Start IRQ Enable bit

1 = Start channel cell transfer if an interrupt matching CHSIRQ occurs
0 = Interrupt number CHSIRQ is ignored and does not start a transfer

bit 3 **AIRQEN:** Channel Abort IRQ Enable bit

1 = Channel transfer is aborted if an interrupt matching CHAIRQ occurs
0 = Interrupt number CHAIRQ is ignored and does not terminate a transfer

bit 2-0 **Unimplemented:** Read as '0'

Note 1: See **Table 7-2: "Interrupt IRQ, Vector, and Bit Location"** for the list of available interrupt IRQ sources.

REGISTER 11-10: USBIENCSR2: USB INDEXED ENDPOINT CONTROL STATUS REGISTER 2 (ENDPOINT 1-7)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TXINTERV<7:0>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	SPEED<1:0>		PROTOCOL<1:0>		TEP<3:0>			
15:8	U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
	—	—	RXCNT<13:8>					
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	RXCNT<7:0>							

Legend:	HC = Hardware Cleared	HS = Hardware Set	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-24 **TXINTERV<7:0>:** Endpoint TX Polling Interval/NAK Limit bits (*Host mode*)

For Interrupt and Isochronous transfers, this field defines the polling interval for the endpoint. For Bulk endpoints, this field sets the number of frames/microframes after which the endpoint should time out on receiving a stream of NAK responses.

The following table describes the valid values and interpretation for these bits:

Transfer Type	Speed	Valid Values (m)	Interpretation
Interrupt	Low/Full	0x01 to 0xFF	Polling interval is 'm' frames.
	High	0x01 to 0x10	Polling interval is $2^{(m-1)}$ frames.
Isochronous	Full or High	0x01 to 0x10	Polling interval is $2^{(m-1)}$ frames/microframes.
Bulk	Full or High	0x02 to 0x10	NAK limit is $2^{(m-1)}$ frames/microframes. A value of '0' or '1' disables the NAK time-out function.

bit 23-22 **SPEED<1:0>:** TX Endpoint Operating Speed Control bits (*Host mode*)
11 = Low-Speed
10 = Full-Speed
01 = Hi-Speed
00 = Reserved

bit 21-20 **PROTOCOL<1:0>:** TX Endpoint Protocol Control bits
11 = Interrupt
10 = Bulk
01 = Isochronous
00 = Control

bit 19-16 **TEP<3:0>:** TX Target Endpoint Number bits

This value is the endpoint number contained in the TX endpoint descriptor returned to the USB module during device enumeration.

bit 15-14 **Unimplemented:** Read as '0'

bit 13-0 **RXCNT<13:0>:** Receive Count bits

The number of received data bytes in the endpoint RX FIFO. The value returned changes as the contents of the FIFO change and is only valid while RXPKTRDY is set.

REGISTER 11-30: USBCRCON: USB CLOCK/RESET CONTROL REGISTER (CONTINUED)

bit 3 **SENDMONEN:** Session End VBUS Monitoring for OTG Enable bit
1 = Enable monitoring for VBUS in Session End range (between 0.2V and 0.8V)
0 = Disable monitoring for VBUS in Session End range

bit 2 **USBIE:** USB General Interrupt Enable bit
1 = Enables general interrupt from USB module
0 = Disables general interrupt from USB module

bit 1 **USBRIE:** USB Resume Interrupt Enable bit
1 = Enable remote resume from suspend Interrupt
0 = Disable interrupt to a Remote Devices USB resume signaling

bit 0 **USBWKUPEN:** USB Activity Detection Interrupt Enable bit
1 = Enable interrupt for detection of activity on USB bus in Sleep mode
0 = Disable interrupt for detection of activity on USB bus in Sleep mode

TABLE 12-22: PERIPHERAL PIN SELECT INPUT REGISTER MAP (CONTINUED)

Virtual Address (BF80_#)	Register Name	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
1444	IC4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	IC4R<3:0>				0000
1448	IC5R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	IC5R<3:0>				0000
144C	IC6R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	IC6R<3:0>				0000
1450	IC7R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	IC7R<3:0>				0000
1454	IC8R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	IC8R<3:0>				0000
1458	IC9R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	IC9R<3:0>				0000
1460	OCFAR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	OCFAR<3:0>				0000
1468	U1RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U1RXR<3:0>				0000
146C	U1CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U1CTSR<3:0>				0000
1470	U2RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U2RXR<3:0>				0000
1474	U2CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U2CTSR<3:0>				0000
1478	U3RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U3RXR<3:0>				0000
147C	U3CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U3CTSR<3:0>				0000
1480	U4RXR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U4RXR<3:0>				0000
1484	U4CTSR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	U4CTSR<3:0>				0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: This register is not available on 64-pin devices.

2: This register is not available on devices without a CAN module.

TABLE 12-23: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP (CONTINUED)

Virtual Address (BF80_#)	Register Name	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
15B4	RPC13R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPC13R<3:0>				0000
15B8	RPC14R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPC14R<3:0>				0000
15C0	RPD0R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD0R<3:0>				0000
15C4	RPD1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD1R<3:0>				0000
15C8	RPD2R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD2R<3:0>				0000
15CC	RPD3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD3R<3:0>				0000
15D0	RPD4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD4R<3:0>				0000
15D4	RPD5R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD5R<3:0>				0000
15D8	RPD6R(2)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD6R<3:0>				0000
15DC	RPD7R(2)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD7R<3:0>				0000
15E4	RPD9R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD9R<3:0>				0000
15E8	RPD10R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD10R<3:0>				0000
15EC	RPD11R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD11R<3:0>				0000
15F0	RPD12R(1)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD12R<3:0>				0000
15F8	RPD14R(1)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD14R<3:0>				0000
15FC	RPD15R(1)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD15R<3:0>				0000
160C	RPE3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPE3R<3:0>				0000
1614	RPE5R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPE5R<3:0>				0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: This register is not available on 64-pin devices.

2: This register is not available on 64-pin and 100-pin devices.

REGISTER 19-1: SPIxCON: SPI CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FRMEN	FRMSYNC	FRMPOL	MSSEN	FRMSYPW	FRMCNT<2:0>		
23:16	R/W-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
	MCLKSEL(1)	—	—	—	—	—	SPIFE	ENHBUF(1)
15:8	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ON	—	SIDL	DISSDO(4)	MODE32	MODE16	SMP	CKE(2)
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	SSEN	CKP(3)	MSTEN	DISSDI(4)	STXISEL<1:0>		SRXISEL<1:0>	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **FRMEN:** Framed SPI Support bit
1 = Framed SPI support is enabled ($\overline{SSx}$ pin used as FSYNC input/output)
0 = Framed SPI support is disabled

bit 30 **FRMSYNC:** Frame Sync Pulse Direction Control on $\overline{SSx}$ pin bit (Framed SPI mode only)
1 = Frame sync pulse input (Slave mode)
0 = Frame sync pulse output (Master mode)

bit 29 **FRMPOL:** Frame Sync Polarity bit (Framed SPI mode only)
1 = Frame pulse is active-high
0 = Frame pulse is active-low

bit 28 **MSSEN:** Master Mode Slave Select Enable bit
1 = Slave select SPI support is enabled. The $\overline{SS}$ pin is automatically driven during transmission in Master mode. Polarity is determined by the FRMPOL bit.
0 = Slave select SPI support is disabled.

bit 27 **FRMSYPW:** Frame Sync Pulse Width bit
1 = Frame sync pulse is one character wide
0 = Frame sync pulse is one clock wide

bit 26-24 **FRMCNT<2:0>:** Frame Sync Pulse Counter bits. Controls the number of data characters transmitted per pulse. This bit is only valid in Framed mode.
111 = Reserved
110 = Reserved
101 = Generate a frame sync pulse on every 32 data characters
100 = Generate a frame sync pulse on every 16 data characters
011 = Generate a frame sync pulse on every 8 data characters
010 = Generate a frame sync pulse on every 4 data characters
001 = Generate a frame sync pulse on every 2 data characters
000 = Generate a frame sync pulse on every data character

bit 23 **MCLKSEL:** Master Clock Enable bit(1)
1 = REFCLKO1 is used by the Baud Rate Generator
0 = PBCLK2 is used by the Baud Rate Generator

bit 22-18 **Unimplemented:** Read as '0'

Note 1: This bit can only be written when the ON bit = 0. Refer to **Section 37.0 "Electrical Characteristics"** for maximum clock frequency requirements.

2: This bit is not used in the Framed SPI mode. The user should program this bit to '0' for the Framed SPI mode (FRMEN = 1).

3: When AUDEN = 1, the SPI/I^2S module functions as if the CKP bit is equal to '1', regardless of the actual value of the CKP bit.

4: This bit present for legacy compatibility and is superseded by PPS functionality on these devices (see **Section 12.4 "Peripheral Pin Select (PPS)"** for more information).

REGISTER 21-2: I2CxSTAT: I^{2}C STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R-0, HS, HC	R-0, HS, HC	R/C-0, HS, HC	U-0	U-0	R/C-0, HS	R-0, HS, HC	R-0, HS, HC
	ACKSTAT	TRSTAT	ACKTIM	—	—	BCL	GCSTAT	ADD10
7:0	R/C-0, HS, SC	R/C-0, HS, SC	R-0, HS, HC	R/C-0, HS, HC	R/C-0, HS, HC	R-0, HS, HC	R-0, HS, HC	R-0, HS, HC
	IWCOL	I2COV	D_A	P	S	R_W	RBF	TBF

Legend:	HS = Hardware Set	HC = Hardware Cleared	SC = Software Cleared
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	C = Clearable bit

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ACKSTAT:** Acknowledge Status bit
(when operating as I^{2}C master, applicable to master transmit operation)
1 = NACK received from slave
0 = ACK received from slave
Hardware set or clear at end of slave Acknowledge.

bit 14 **TRSTAT:** Transmit Status bit (when operating as I^{2}C master, applicable to master transmit operation)
1 = Master transmit is in progress (8 bits + ACK)
0 = Master transmit is not in progress
Hardware set at beginning of master transmission. Hardware clear at end of slave Acknowledge.

bit 13 **ACKTIM:** Acknowledge Time Status bit (Valid in I^{2}C Slave mode only)
1 = I^{2}C bus is in an Acknowledge sequence, set on the eight falling edge of SCL clock
0 = Not an Acknowledge sequence, cleared on 9th rising edge of SCL clock

bit 12-11 **Unimplemented:** Read as '0'

bit 10 **BCL:** Master Bus Collision Detect bit
1 = A bus collision has been detected during a master operation
0 = No collision
Hardware set at detection of bus collision.

bit 9 **GCSTAT:** General Call Status bit
1 = General call address was received
0 = General call address was not received
Hardware set when address matches general call address. Hardware clear at Stop detection.

bit 8 **ADD10:** 10-bit Address Status bit
1 = 10-bit address was matched
0 = 10-bit address was not matched
Hardware set at match of 2nd byte of matched 10-bit address. Hardware clear at Stop detection.

bit 7 **IWCOL:** Write Collision Detect bit
1 = An attempt to write the I2CxTRN register failed because the I^{2}C module is busy
0 = No collision
Hardware set at occurrence of write to I2CxTRN while busy (cleared by software).

bit 6 **I2COV:** Receive Overflow Flag bit
1 = A byte was received while the I2CxRCV register is still holding the previous byte
0 = No overflow
Hardware set at attempt to transfer I2CxRSR to I2CxRCV (cleared by software).

REGISTER 25-3: RTCTIME: REAL-TIME CLOCK TIME VALUE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	HR10<3:0>				HR01<3:0>			
23:16	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	MIN10<3:0>				MIN01<3:0>			
15:8	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	SEC10<3:0>				SEC01<3:0>			
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-28 **HR10<3:0>:** Binary-Coded Decimal Value of Hours bits, 10 digits; contains a value from 0 to 2

bit 27-24 **HR01<3:0>:** Binary-Coded Decimal Value of Hours bits, 1 digit; contains a value from 0 to 9

bit 23-20 **MIN10<3:0>:** Binary-Coded Decimal Value of Minutes bits, 10 digits; contains a value from 0 to 5

bit 19-16 **MIN01<3:0>:** Binary-Coded Decimal Value of Minutes bits, 1 digit; contains a value from 0 to 9

bit 15-12 **SEC10<3:0>:** Binary-Coded Decimal Value of Seconds bits, 10 digits; contains a value from 0 to 5

bit 11-8 **SEC01<3:0>:** Binary-Coded Decimal Value of Seconds bits, 1 digit; contains a value from 0 to 9

bit 7-0 **Unimplemented:** Read as '0'

Note: This register is only writable when RTCWREN = 1 (RTCCON<3>).

REGISTER 28-22: ADCFSTAT: ADC FIFO STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FEN	—	—	ADC4EN	ADC3EN	ADC2EN	ADC1EN	ADC0EN
23:16	R/W-0	R-0, HS, HC	R-0, HS, HC	U-0	U-0	U-0	U-0	U-0
	FIEN	FRDY	FWROVERR	—	—	—	—	—
15:8	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	FCNT<7:0>							
7:0	R-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
	FSIGN	—	—	—	—	ADCID<2:0>		

Legend:	HS = Hardware Set	HC = Hardware Cleared	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **FEN:** FIFO Enable bit
1 = FIFO is enabled
0 = FIFO is disabled; no data is being saved into the FIFO

bit 30-29 **Unimplemented:** Read as '0'

bit 28-24 **ADC4EN:ADC0EN:** ADCx Enable bits ('x' = 0 through 4)
1 = Converted output data of ADCx is stored in the FIFO
0 = Converted output data of ADCx is not stored in the FIFO

Note: While using FIFO, the output data is additionally stored in the respective output data register (ADCDATAx).

bit 23 **FIEN:** FIFO Interrupt Enable bit
1 = FIFO interrupts are enabled; an interrupt is generated once the FRDY bit is set
0 = FIFO interrupts are disabled

bit 22 **FRDY:** FIFO Data Ready Interrupt Status bit
1 = FIFO has data to be read
0 = No data is available in the FIFO

Note: This bit is cleared when the FIFO output data in ADCFIFO has been read and there is no additional data ready in the FIFO (that is, the FIFO is empty).

bit 21 **FWROVERR:** FIFO Write Overflow Error Status bit
1 = A write overflow error in the FIFO has occurred (circular FIFO)
0 = A write overflow error in the FIFO has not occurred

Note: This bit is cleared after ADCFSTAT<23:16> are read by software.

bit 15-8 **FCNT<7:0>:** FIFO Data Entry Count Status bit
The value in these bits indicates the number of data entries in the FIFO.

bit 7 **FSIGN:** FIFO Sign Setting bit
This bit reflects the sign of data stored in the ADCFIFO register.

bit 6-3 **Unimplemented:** Read as '0'

bit 2-0 **ADCID<2:0>:** ADCx Identifier bits ('x' = 0 through 4)
These bits specify the ADC module whose data is stored in the FIFO.
111 = Reserved
110 = Reserved
101 = Reserved
100 = Converted data of ADC4 is stored in FIFO
•
•
•
000 = Converted data of ADC0 is stored in FIFO

REGISTER 30-5: ETHHT0: ETHERNET CONTROLLER HASH TABLE 0 REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **HT<31:0>:** Hash Table Bytes 0-3 bits

Note 1: This register is only used for RX operations.
2: The bits in this register may only be changed while the RXEN bit (ETHCON1<8>) = 0 or the HTEN bit (ETHRXFC<15>) = 0.

REGISTER 30-6: ETHHT1: ETHERNET CONTROLLER HASH TABLE 1 REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<63:56>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<55:48>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<47:40>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	HT<39:32>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **HT<63:32>:** Hash Table Bytes 4-7 bits

Note 1: This register is only used for RX operations.
2: The bits in this register may only be changed while the RXEN bit (ETHCON1<8>) = 0 or the HTEN bit (ETHRXFC<15>) = 0.

32.0 COMPARATOR VOLTAGE REFERENCE (CVREF)

Note: This data sheet summarizes the features of the PIC32MZ EF family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 20. "Comparator Voltage Reference (CVREF)"** (DS60001109) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

The CVREF module is a 16-tap, resistor ladder network that provides a selectable reference voltage. Although its primary purpose is to provide a reference for the analog comparators, it also may be used independently of them.

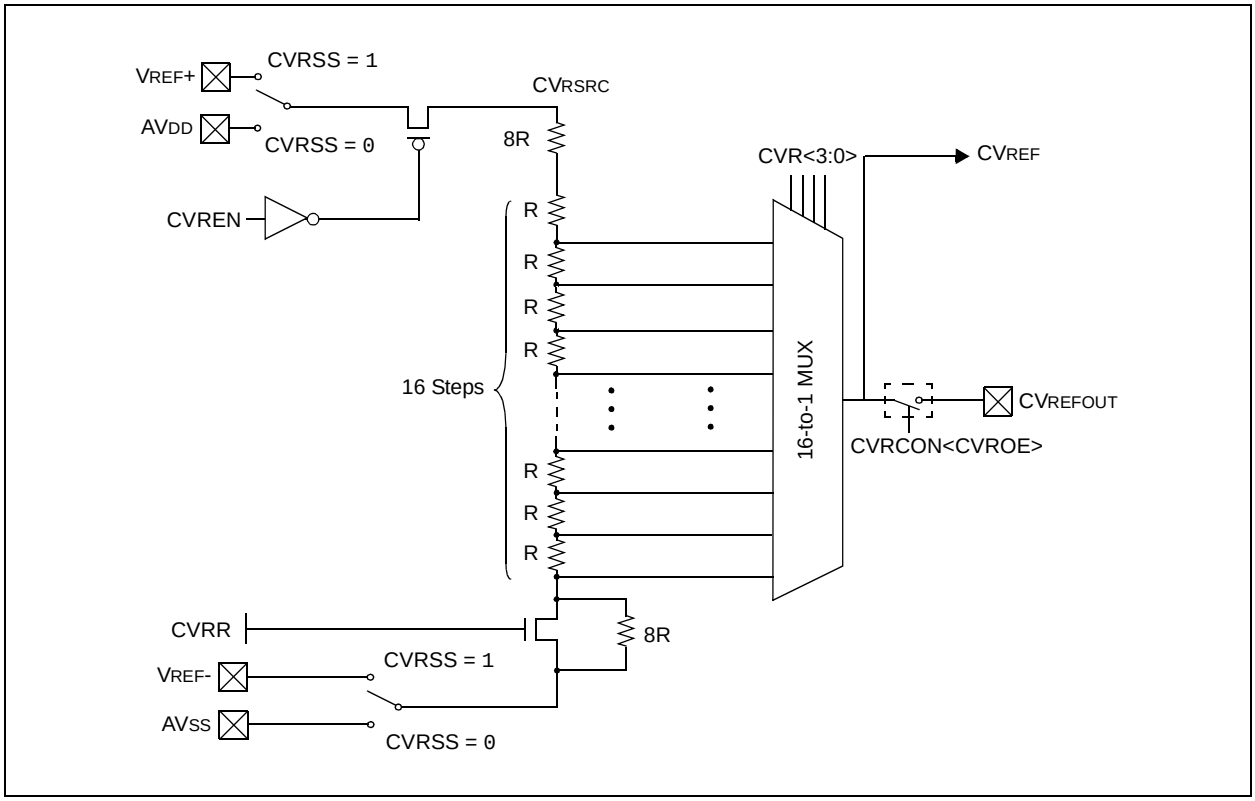
The resistor ladder is segmented to provide two ranges of voltage reference values and has a power-down function to conserve power when the reference is not being used. The module's supply reference can be provided from either device VDD/VSS or an external voltage reference. The CVREF output is available for the comparators and typically available for pin output.

The comparator voltage reference has the following features:

- High and low range selection
- Sixteen output levels available for each range
- Internally connected to comparators to conserve device pins
- Output can be connected to a pin

A block diagram of the CVREF module is illustrated in Figure 32-1.

FIGURE 32-1: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM



REGISTER 32-1: CVRCON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	ON	—	—	—	—	—	—	—
7:0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	CVROE	CVRR	CVRSS	CVR<3:0>			

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** Comparator Voltage Reference On bit
- 1 = Module is enabled
  Setting this bit does not affect other bits in the register.
- 0 = Module is disabled and does not consume current.
  Clearing this bit does not affect the other bits in the register.

bit 14-7 **Unimplemented:** Read as '0'

bit 6 **CVROE:** CV_{REFOUT} Enable bit
- 1 = Voltage level is output on CV_{REFOUT} pin
- 0 = Voltage level is disconnected from CV_{REFOUT} pin

bit 5 **CVRR:** CV_{REF} Range Selection bit
- 1 = 0 to 0.67 CV_{RSRC}, with $CV_{RSRC}/24$ step size
- 0 = 0.25 CV_{RSRC} to 0.75 CV_{RSRC}, with $CV_{RSRC}/32$ step size

bit 4 **CVRSS:** CV_{REF} Source Selection bit
- 1 = Comparator voltage reference source, $CV_{RSRC} = (V_{REF}+) – (V_{REF}-)$
- 0 = Comparator voltage reference source, $CV_{RSRC} = AV_{DD} – AV_{SS}$

bit 3-0 **CVR<3:0>:** CV_{REF} Value Selection $0 \le CVR<3:0> \le 15$ bits

When CVRR = 1:
$CV_{REF} = (CVR<3:0>/24) \bullet (CV_{RSRC})$

When CVRR = 0:
$CV_{REF} = 1/4 \bullet (CV_{RSRC}) + (CVR<3:0>/32) \bullet (CV_{RSRC})$

33.0 POWER-SAVING FEATURES

Note: This data sheet summarizes the features of the PIC32MZ EF family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 10. "Power-Saving Features"** (DS60001130) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

This section describes power-saving features for the PIC32MZ EF devices. These devices offer various methods and modes that allow the user to balance power consumption with device performance. In all of the methods and modes described in this section, power-saving is controlled by software.

33.1 Power Saving with CPU Running

When the CPU is running, power consumption can be controlled by reducing the CPU clock frequency, lowering the speed of PBCLK7, or selecting a lower power clock source (i.e., LPRC or SOSC).

In addition, the Peripheral Bus Scaling mode is available for each peripheral bus where peripherals are clocked at reduced speed by selecting a higher divider for the associated PBCLKx, or by disabling the clock completely.

33.2 Power-Saving with CPU Halted

Peripherals and the CPU can be Halted or disabled to further reduce power consumption.

33.2.1 SLEEP MODE

Sleep mode has the lowest power consumption of the device power-saving operating modes. The CPU and most peripherals are Halted and the associated clocks are disabled. Select peripherals can continue to operate in Sleep mode and can be used to wake the device from Sleep. See the individual peripheral module sections for descriptions of behavior in Sleep.

Sleep mode includes the following characteristics:

- There can be a wake-up delay based on the oscillator selection
- The Fail-Safe Clock Monitor (FSCM) does not operate during Sleep mode
- The BOR circuit remains operative during Sleep mode
- The WDT, if enabled, is not automatically cleared prior to entering Sleep mode
- Some peripherals can continue to operate at limited functionality in Sleep mode. These peripherals include I/O pins that detect a change in the input signal, WDT, ADC, UART and peripherals that use an external clock input or the internal LPRC oscillator (e.g., RTCC, Timer1 and Input Capture).
- I/O pins continue to sink or source current in the same manner as they do when the device is not in Sleep

The processor will exit, or 'wake-up', from Sleep on one of the following events:

- On any interrupt from an enabled source that is operating in Sleep. The interrupt priority must be greater than the current CPU priority.
- On any form of device Reset
- On a WDT time-out

If the interrupt priority is lower than or equal to the current priority, the CPU will remain Halted, but the peripheral bus clocks will start running and the device will enter into Idle mode.

33.2.2 IDLE MODE

In Idle mode, the CPU is Halted; however, all clocks are still enabled. This allows peripherals to continue to operate. Peripherals can be individually configured to Halt when entering Idle by setting their respective SIDL bit. Latency, when exiting Idle mode, is very low due to the CPU oscillator source remaining active.

The device enters Idle mode when the SLPEN bit (OSCCON<4>) is clear and a `WAIT` instruction is executed.

The processor will wake or exit from Idle mode on the following events:

- On any interrupt event for which the interrupt source is enabled. The priority of the interrupt event must be greater than the current priority of the CPU. If the priority of the interrupt event is lower than or equal to current priority of the CPU, the CPU will remain Halted and the device will remain in Idle mode.
- On any form of device Reset
- On a WDT time-out interrupt

TABLE 37-12: DC CHARACTERISTICS: PROGRAM MEMORY(3)

DC CHARACTERISTICS			Standard Operating Conditions: 2.1V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	**Sym.**	**Characteristics**	**Min.**	**Typ.(1)**	**Max.**	**Units**	**Conditions**
D130a	EP	Cell Endurance	10,000	—	—	E/W	Without ECC
D130b			20,000	—	—	E/W	With ECC
D131	VPR	VDD for Read	VDDMIN	—	VDDMAX	V	—
D132	VPEW	VDD for Erase or Write	VDDMIN	—	VDDMAX	V	—
D134a	TRETD	Characteristic Retention	10	—	—	Year	Without ECC
D134b			20	—	—	Year	With ECC
D135	IDDP	Supply Current during Programming	—	—	30	mA	—
D136	TRW	Row Write Cycle Time **(Notes 2, 4)**	—	66813	—	FRC Cycles	—
D137	TQWW	Quad Word Write Cycle Time **(Note 4)**	—	773	—	FRC Cycles	—
D138	TWW	Word Write Cycle Time **(Note 4)**	—	383	—	FRC Cycles	—
D139	TCE	Chip Erase Cycle Time **(Note 4)**	—	515373	—	FRC Cycles	—
D140	TPFE	All Program Flash (Upper and Lower regions) Erase Cycle Time **(Note 4)**	—	256909	—	FRC Cycles	—
D141	TPBE	Program Flash (Upper or Lower regions) Erase Cycle Time **(Note 4)**	—	128453	—	FRC Cycles	—
D142	TPGE	Page Erase Cycle Time **(Note 4)**	—	128453	—	FRC Cycles	—

Note 1: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

2: The minimum PBCLK5 for row programming is 4 MHz.

3: Refer to the *"PIC32 Flash Programming Specification"* (DS60001145) for operating conditions during programming and erase cycles.

4: This parameter depends on FRC accuracy (see Table 37-20) and FRC tuning values (see the OSCTUN register: Register 8-2).

TABLE 37-13: DC CHARACTERISTICS: PROGRAM FLASH MEMORY WAIT STATES

DC CHARACTERISTICS	Standard Operating Conditions: 2.1V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended		
Required Flash Wait States(1)	**SYSCLK**	**Units**	**Conditions**
With ECC:			
0 Wait states	0 < SYSCLK ≤ 60	MHz	—
1 Wait state	60 < SYSCLK ≤ 120		
2 Wait states	120 < SYSCLK ≤ 200		
Without ECC:			
0 Wait states	0 < SYSCLK ≤ 74	MHz	—
1 Wait state	74 < SYSCLK ≤ 140		
2 Wait states	140 < SYSCLK ≤ 200		

Note 1: To use Wait states, the Prefetch module must be enabled (PREFEN<1:0> ≠ 00) and the PFMWS<2:0> bits must be written with the desired Wait state value.

38.0 EXTENDED TEMPERATURE ELECTRICAL CHARACTERISTICS

This section provides an overview of the PIC32MZ EF electrical characteristics for devices running up to 125ºC. Additional information will be provided in future revisions of this document as it becomes available.

The specifications for Extended Temperature are identical to those shown in **37.0 "Electrical Characteristics"**, with the exception of the parameters listed in this chapter.

Parameters in this chapter begin with the letter "E", which denotes Extended Temperature operation. For example, parameter DC28 in **37.0 "Electrical Characteristics"**, is the Extended Temperature operation equivalent for EDC28.

Absolute maximum ratings for the PIC32MZ EF devices are listed below. Exposure to these maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at these or any other conditions, above the parameters indicated in the operation listings of this specification, is not implied.

Absolute Maximum Ratings

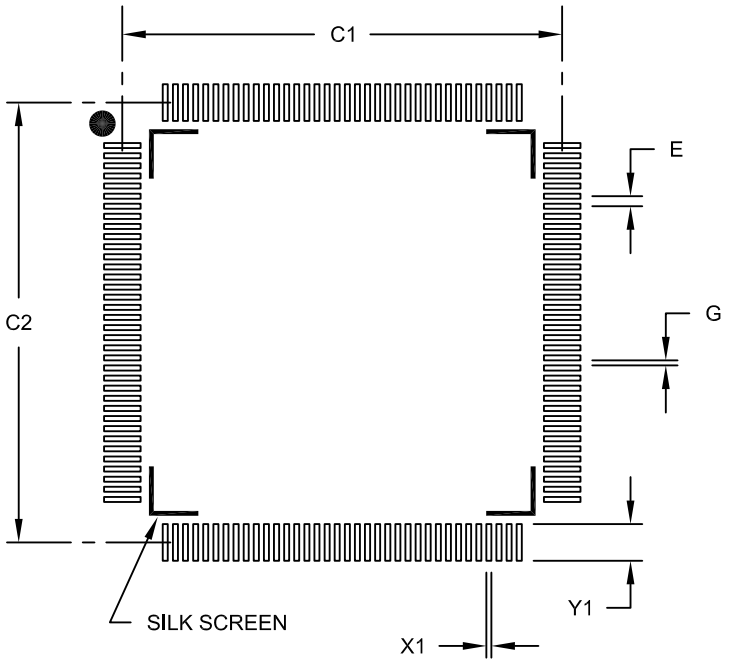
(See Note 1)

Ambient temperature under bias.....-40°C to +125°C

Note	**1:**	Stresses above those listed under **"Absolute Maximum Ratings"** may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions, above those indicated in the operation listings of this specification, is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

144-Lead Plastic Thin Quad Flat Pack (PH) - 16x16 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Contact Pad Spacing	C1		17.40	
Contact Pad Spacing	C2		17.40	
Contact Pad Width (X144)	X1			0.20
Contact Pad Length (X144)	Y1			1.45
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2155B