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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	MIPS32® M-Class
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	CANbus, Ethernet, I <sup>2</sup> C, PMP, SPI, SQI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	46
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	2.1V ~ 3.6V
Data Converters	A/D 24x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic32mz1024efh064-e-mr">https://www.e-xfl.com/product-detail/microchip-technology/pic32mz1024efh064-e-mr</a>

## 2.4 ICSP Pins

The PGECx and PGEDx pins are used for ICSP and debugging purposes. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of Ohms, not to exceed 100 Ohms.

Pull-up resistors, series diodes and capacitors on the PGECx and PGEDx pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high (V<sub>IH</sub>) and input low (V<sub>IL</sub>) requirements.

Ensure that the "Communication Channel Select" (i.e., PGECx/PGEDx pins) programmed into the device matches the physical connections for the ICSP to MPLAB® ICD 3 or MPLAB REAL ICE™.

For more information on ICD 3 and REAL ICE connection requirements, refer to the following documents that are available from the Microchip web site.

- "Using MPLAB® ICD 3" (poster) (DS50001765)
- "MPLAB® ICD 3 Design Advisory" (DS50001764)
- "MPLAB® REAL ICE™ In-Circuit Debugger User's Guide" (DS50001616)
- "Using MPLAB® REAL ICE™ Emulator" (poster) (DS50001749)

## 2.5 JTAG

The TMS, TDO, TDI and TCK pins are used for testing and debugging according to the Joint Test Action Group (JTAG) standard. It is recommended to keep the trace length between the JTAG connector and the JTAG pins on the device as short as possible. If the JTAG connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of Ohms, not to exceed 100 Ohms.

Pull-up resistors, series diodes and capacitors on the TMS, TDO, TDI and TCK pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high (V<sub>IH</sub>) and input voltage low (V<sub>IL</sub>) requirements.

## 2.6 Trace

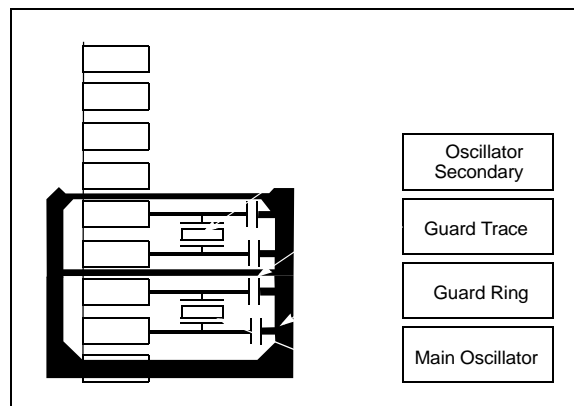
The trace pins can be connected to a hardware trace-enabled programmer to provide a compressed real-time instruction trace. When used for trace, the TRD3, TRD2, TRD1, TRD0 and TRCLK pins should be dedicated for this use. The trace hardware requires a 22 Ohm series resistor between the trace pins and the trace connector.

## 2.7 External Oscillator Pins

Many MCUs have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator (refer to **Section 8.0 "Oscillator Configuration"** for details).

The oscillator circuit should be placed on the same side of the board as the device. Also, place the oscillator circuit close to the respective oscillator pins, not exceeding one-half inch (12 mm) distance between them. The load capacitors should be placed next to the oscillator itself, on the same side of the board. Use a grounded copper pour around the oscillator circuit to isolate them from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed. A suggested layout is illustrated in Figure 2-3.

**FIGURE 2-3: SUGGESTED OSCILLATOR CIRCUIT PLACEMENT**



## 2.8 Unused I/Os

Unused I/O pins should not be allowed to float as inputs. They can be configured as outputs and driven to a logic-low state.

Alternatively, inputs can be reserved by connecting the pin to V<sub>SS</sub> through a 1k to 10k resistor and configuring the pin as an input.

# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

The MIPS architecture defines that the result of a multiply or divide operation be placed in one of four pairs of HI and LO registers. Using the Move-From-HI (MFHI) and Move-From-LO (MFLO) instructions, these values can be transferred to the General Purpose Register file.

In addition to the HI/LO targeted operations, the MIPS32 architecture also defines a multiply instruction, MUL, which places the least significant results in the primary register file instead of the HI/LO register pair. By avoiding the explicit MFLO instruction required when using the LO register, and by supporting multiple destination registers, the throughput of multiply-intensive operations is increased.

Two other instructions, Multiply-Add (MADD) and Multiply-Subtract (MSUB), are used to perform the multiply-accumulate and multiply-subtract operations. The MADD instruction multiplies two numbers and then adds the product to the current contents of the HI and LO registers. Similarly, the MSUB instruction multiplies two operands and then subtracts the product from the HI and LO registers. The MADD and MSUB operations are commonly used in DSP algorithms.

The MDU also implements various shift instructions operating on the HI/LO register and multiply instructions as defined in the DSP ASE. The MDU supports all of the data types required for this purpose and includes three extra HI/LO registers as defined by the ASE.

Table 3-2 lists the latencies and repeat rates for the DSP multiply and dot-product operations. The approximate latencies and repeat rates are listed in terms of pipeline clocks.

**TABLE 3-2: DSP-RELATED LATENCIES AND REPEAT RATES**

Op code	Latency	Repeat Rate
Multiply and dot-product without saturation after accumulation	5	1
Multiply and dot-product with saturation after accumulation	5	1
Multiply without accumulation	5	1

## 3.1.3 SYSTEM CONTROL COPROCESSOR (CP0)

In the MIPS architecture, CP0 is responsible for the virtual-to-physical address translation and cache protocols, the exception control system, the processor's diagnostics capability, the operating modes (Kernel, User and Debug) and whether interrupts are enabled or disabled. Configuration information, such as cache size and set associativity, and the presence of options like microMIPS is also available by accessing the CP0 registers, listed in Table 3-3.

**TABLE 3-3: COPROCESSOR 0 REGISTERS**

Register Number	Register Name	Function
0	Index	Index into the TLB array (MPU only).
1	Random	Randomly generated index into the TLB array (MPU only).
2	EntryLo0	Low-order portion of the TLB entry for even-numbered virtual pages (MPU only).
3	EntryLo1	Low-order portion of the TLB entry for odd-numbered virtual pages (MPU only).
4	Context/ UserLocal	Pointer to the page table entry in memory (MPU only). User information that can be written by privileged software and read via the RDHWR instruction.
5	PageMask/ PageGrain	PageMask controls the variable page sizes in TLB entries. PageGrain enables support of 1 KB pages in the TLB (MPU only).
6	Wired	Controls the number of fixed (i.e., wired) TLB entries (MPU only).
7	HWREna	Enables access via the RDHWR instruction to selected hardware registers in Non-privileged mode.
8	BadVAddr	Reports the address for the most recent address-related exception.
	BadInstr	Reports the instruction that caused the most recent exception.
	BadInstrP	Reports the branch instruction if a delay slot caused the most recent exception.
9	Count	Processor cycle count.
10	EntryHi	High-order portion of the TLB entry (MPU only).
11	Compare	Core timer interrupt control.

# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

**REGISTER 4-4: SBTxELOG2: SYSTEM BUS TARGET 'x' ERROR LOG REGISTER 2 ('x' = 0-13)**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	R-0	R-0
	—	—	—	—	—	—	GROUP<1:0>	

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared

bit 31-3 **Unimplemented:** Read as '0'

bit 1-0 **GROUP<1:0>:** Requested Permissions Group bits

11 = Group 3  
10 = Group 2  
01 = Group 1  
00 = Group 0

**Note:** Refer to Table 4-6 for the list of available targets and their descriptions.

**REGISTER 4-5: SBTxECON: SYSTEM BUS TARGET 'x' ERROR CONTROL REGISTER ('x' = 0-13)**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
	—	—	—	—	—	—	—	ERRP
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared

bit 31-25 **Unimplemented:** Read as '0'

bit 24 **ERRP:** Error Control bit

1 = Report protection group violation errors  
0 = Do not report protection group violation errors

bit 23-0 **Unimplemented:** Read as '0'

**Note:** Refer to Table 4-6 for the list of available targets and their descriptions.

## 5.1 Flash Control Registers

**TABLE 5-1: FLASH CONTROLLER REGISTER MAP**

Virtual Address (BF80_#)	Register Name	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
0600	NVMCON <sup>(1)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	WR	WREN	WRERR	LVDERR	—	—	—	—	PFSWAP	BFSWAP	—	—	NVMOP<3:0>				00x0
0610	NVMKEY	31:16	NVMKEY<31:0>																0000
		15:0																	0000
0620	NVMADDR <sup>(1)</sup>	31:16	NVMADDR<31:0>																0000
		15:0																	0000
0630	NVMDATA0	31:16	NVMDATA0<31:0>																0000
		15:0																	0000
0640	NVMDATA1	31:16	NVMDATA1<31:0>																0000
		15:0																	0000
0650	NVMDATA2	31:16	NVMDATA2<31:0>																0000
		15:0																	0000
0660	NVMDATA3	31:16	NVMDATA3<31:0>																0000
		15:0																	0000
0670	NVMSRC ADDR	31:16	NVMSRCADDR<31:0>																0000
		15:0																	0000
0680	NVMPWP <sup>(1)</sup>	31:16	PWPLOCK	—	—	—	—	—	—	—	PWP<23:16>								8000
		15:0	PWP<15:0>																0000
0690	NVMBWP <sup>(1)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	LBWPLOCK	—	—	LBWP4	LBWP3	LBWP2	LBWP1	LBWP0	UBWPLOCK	—	—	UBWP4	UBWP3	UBWP2	UBWP1	UBWP0	9FDF
06A0	NVMCON2 <sup>(1)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	001F
		15:0	—	—	—	—	—	—	—	—	SWAPLOCK<1:0>		—	—	—	—	—	—	0000

**Legend:** x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** This register has corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.3 “CLR, SET, and INV Registers”** for more information.

## 6.0 RESETS

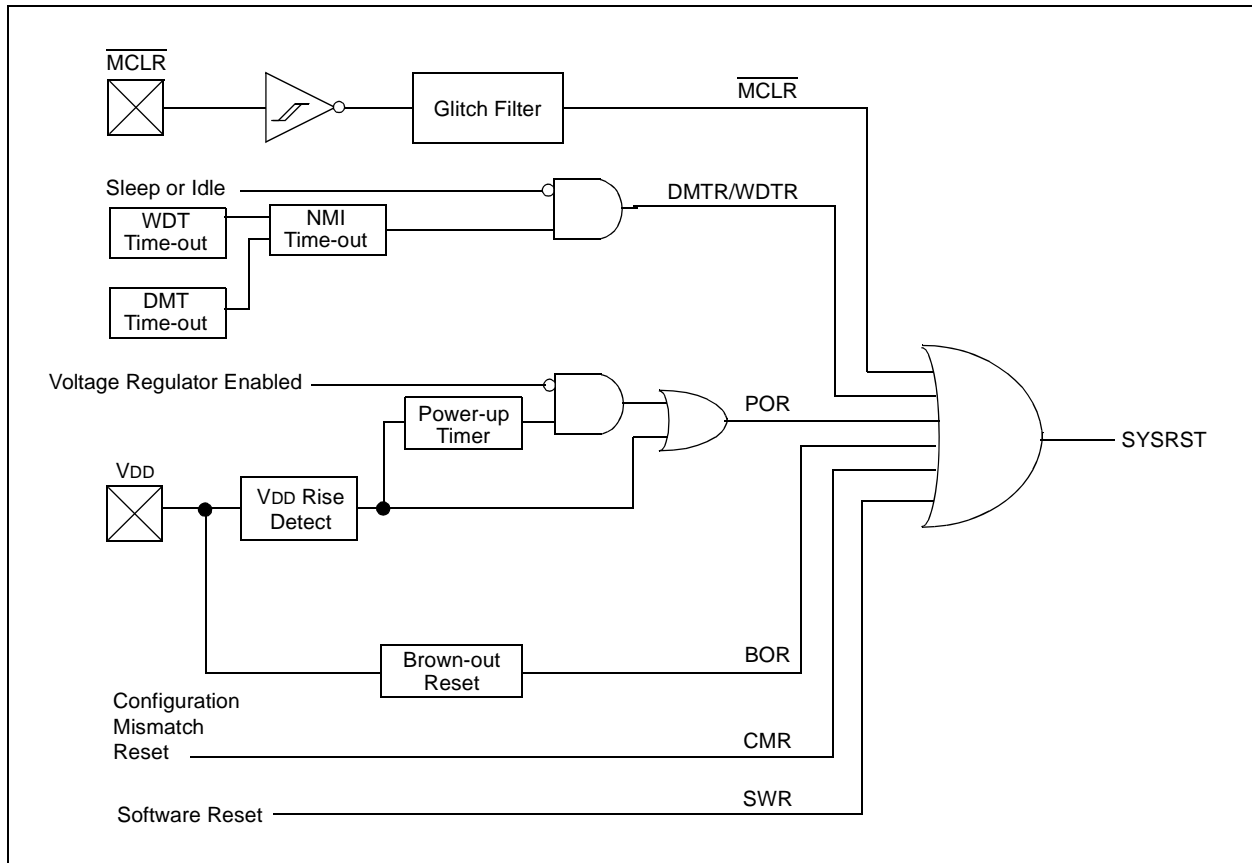
**Note:** This data sheet summarizes the features of the PIC32MZ EF family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 7. “Resets”** (DS60001118) in the *“PIC32 Family Reference Manual”*, which is available from the Microchip web site ([www.microchip.com/PIC32](http://www.microchip.com/PIC32)).

The Reset module combines all Reset sources and controls the device Master Reset signal, SYSRST. The device Reset sources are as follows:

- Power-on Reset (POR)
- Master Clear Reset pin ( $\overline{\text{MCLR}}$ )
- Software Reset (SWR)
- Watchdog Timer Reset (WDTR)
- Brown-out Reset (BOR)
- Configuration Mismatch Reset (CMR)
- Deadman Timer Reset (DMTR)

A simplified block diagram of the Reset module is illustrated in Figure 6-1.

**FIGURE 6-1: SYSTEM RESET BLOCK DIAGRAM**



# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

**REGISTER 6-1: RCON: RESET CONTROL REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	R/W-0, HS	R/W-0, HS	U-0	U-0
	—	—	—	—	BCFGERR	BCFGFAIL	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0, HS	U-0
	—	—	—	—	—	—	CMR	—
7:0	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-1, HS	R/W-1, HS
	EXTR	SWR	DMTO	WDTO	SLEEP	IDLE	BOR <sup>(1)</sup>	POR <sup>(1)</sup>

<b>Legend:</b>	HS = Hardware Set	HC = Hardware Cleared
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

bit 31-28 **Unimplemented:** Read as '0'

bit 27 **BCFGERR:** Primary Configuration Registers Error Flag bit  
 1 = An error occurred during a read of the primary configuration registers  
 0 = No error occurred during a read of the primary configuration registers

bit 26 **BCFGFAIL:** Primary/Secondary Configuration Registers Error Flag bit  
 1 = An error occurred during a read of the primary and alternate configuration registers  
 0 = No error occurred during a read of the primary and alternate configuration registers

bit 25-10 **Unimplemented:** Read as '0'

bit 9 **CMR:** Configuration Mismatch Reset Flag bit  
 1 = A Configuration Mismatch Reset has occurred  
 0 = A Configuration Mismatch Reset has not occurred

bit 8 **Unimplemented:** Read as '0'

bit 7 **EXTR:** External Reset ( $\overline{\text{MCLR}}$ ) Pin Flag bit  
 1 = Master Clear (pin) Reset has occurred  
 0 = Master Clear (pin) Reset has not occurred

bit 6 **SWR:** Software Reset Flag bit  
 1 = Software Reset was executed  
 0 = Software Reset was not executed

bit 5 **DMTO:** Deadman Timer Time-out Flag bit  
 1 = A DMT time-out has occurred  
 0 = A DMT time-out has not occurred

bit 4 **WDTO:** Watchdog Timer Time-out Flag bit  
 1 = WDT Time-out has occurred  
 0 = WDT Time-out has not occurred

bit 3 **SLEEP:** Wake From Sleep Flag bit  
 1 = Device was in Sleep mode  
 0 = Device was not in Sleep mode

bit 2 **IDLE:** Wake From Idle Flag bit  
 1 = Device was in Idle mode  
 0 = Device was not in Idle mode

bit 1 **BOR:** Brown-out Reset Flag bit<sup>(1)</sup>  
 1 = Brown-out Reset has occurred  
 0 = Brown-out Reset has not occurred

bit 0 **POR:** Power-on Reset Flag bit<sup>(1)</sup>  
 1 = Power-on Reset has occurred  
 0 = Power-on Reset has not occurred

**Note 1:** User software must clear this bit to view the next detection.

**TABLE 7-3: INTERRUPT REGISTER MAP (CONTINUED)**

Virtual Address (BF81_#)	Register Name <sup>(1)</sup>	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
0548	OFF002	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
054C	OFF003	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0550	OFF004	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0554	OFF005	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0558	OFF006	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
055C	OFF007	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0560	OFF008	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0564	OFF009	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0568	OFF010	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
056C	OFF011	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0570	OFF012	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0574	OFF013	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0578	OFF014	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
057C	OFF015	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000
0580	OFF016	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	VOFF<17:16>		0000
		15:0	VOFF<15:1>															—	0000

**Legend:** x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

- Note**
- 1: All registers in this table with the exception of the OFFx registers, have corresponding CLR, SET, and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.3 “CLR, SET, and INV Registers”** for more information.
  - 2: This bit or register is not available on 64-pin devices.
  - 3: This bit or register is not available on devices without a CAN module.
  - 4: This bit or register is not available on 100-pin devices.
  - 5: Bits 31 and 30 are not available on 64-pin and 100-pin devices; bits 29 through 14 are not available on 64-pin devices.
  - 6: Bits 31, 30, 29, and bits 5 through 0 are not available on 64-pin and 100-pin devices; bit 31 is not available on 124-pin devices; bit 22 is not available on 64-pin devices.
  - 7: This bit or register is not available on devices without a Crypto module.
  - 8: This bit or register is not available on 124-pin devices.



**TABLE 10-3: DMA CHANNEL 0 THROUGH CHANNEL 7 REGISTER MAP (CONTINUED)**

Virtual Address (BF81_#)	Register Name <sup>(1)</sup>	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
1280	DCH2CPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHCPTR<15:0>																0000
1290	DCH2DAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHPDAT<15:0>																0000
12A0	DCH3CON	31:16	CHPIGN<7:0>								—	—	—	—	—	—	—	—	0000
		15:0	CHBUSY	—	CHPIGNEN	—	CHPATLEN	—	—	—	CHCHNS	CHEN	CHAE	CHCHN	CHAE	—	CHEDET	CHPRI<1:0>	0000
12B0	DCH3ECON	31:16	—	—	—	—	—	—	—	—	CHAIRQ<7:0>								00FF
		15:0	CHSIRQ<7:0>								CFORCE	CABORT	PATEN	SIRQEN	AIRQEN	—	—	—	FF00
12C0	DCH3INT	31:16	—	—	—	—	—	—	—	—	CHSDIE	CHSHIE	CHDDIE	CHDHIE	CHBCIE	CHCCIE	CHTAIE	CHERIE	0000
		15:0	—	—	—	—	—	—	—	—	CHSDIF	CHSHIF	CHDDIF	CHDHIF	CHBCIF	CHCCIF	CHTAIF	CHERIF	0000
12D0	DCH3SSA	31:16	CHSSA<31:0>																0000
		15:0																	0000
12E0	DCH3DSA	31:16	CHDSA<31:0>																0000
		15:0																	0000
12F0	DCH3SSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHSSIZ<15:0>																0000
1300	DCH3DSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHDSIZ<15:0>																0000
1310	DCH3SPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHSPTR<15:0>																0000
1320	DCH3DPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHDPTR<15:0>																0000
1330	DCH3CSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHCSIZ<15:0>																0000
1340	DCH3CPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHCPTR<15:0>																0000
1350	DCH3DAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHPDAT<15:0>																0000
1360	DCH4CON	31:16	CHPIGN<7:0>								—	—	—	—	—	—	—	—	0000
		15:0	CHBUSY	—	CHPIGNEN	—	CHPATLEN	—	—	—	CHCHNS	CHEN	CHAE	CHCHN	CHAE	—	CHEDET	CHPRI<1:0>	0000
1370	DCH4ECON	31:16	—	—	—	—	—	—	—	—	CHAIRQ<7:0>								00FF
		15:0	CHSIRQ<7:0>								CFORCE	CABORT	PATEN	SIRQEN	AIRQEN	—	—	—	FF00
1380	DCH4INT	31:16	—	—	—	—	—	—	—	—	CHSDIE	CHSHIE	CHDDIE	CHDHIE	CHBCIE	CHCCIE	CHTAIE	CHERIE	0000
		15:0	—	—	—	—	—	—	—	—	CHSDIF	CHSHIF	CHDDIF	CHDHIF	CHBCIF	CHCCIF	CHTAIF	CHERIF	0000

**Legend:** x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.3 “CLR, SET, and INV Registers”** for more information.

# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

**REGISTER 10-4: DCRCCON: DMA CRC CONTROL REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0
	—	—	BYTO<1:0>		WBO <sup>(1)</sup>	—	—	BITO
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	PLEN<4:0>				
7:0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	CRCEN	CRCAPP <sup>(1)</sup>	CRCTYP	—	—	CRCCH<2:0>		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-30 **Unimplemented:** Read as '0'

bit 29-28 **BYTO<1:0>:** CRC Byte Order Selection bits

11 = Endian byte swap on half-word boundaries (i.e., source half-word order with reverse source byte order per half-word)

10 = Swap half-words on word boundaries (i.e., reverse source half-word order with source byte order per half-word)

01 = Endian byte swap on word boundaries (i.e., reverse source byte order)

00 = No swapping (i.e., source byte order)

bit 27 **WBO:** CRC Write Byte Order Selection bit<sup>(1)</sup>

1 = Source data is written to the destination re-ordered as defined by BYTO<1:0>

0 = Source data is written to the destination unaltered

bit 26-25 **Unimplemented:** Read as '0'

bit 24 **BITO:** CRC Bit Order Selection bit

When CRCTYP (DCRCCON<15>) = 1 (CRC module is in IP Header mode):

1 = The IP header checksum is calculated Least Significant bit (LSb) first (i.e., reflected)

0 = The IP header checksum is calculated Most Significant bit (MSb) first (i.e., not reflected)

When CRCTYP (DCRCCON<15>) = 0 (CRC module is in LFSR mode):

1 = The LFSR CRC is calculated Least Significant bit first (i.e., reflected)

0 = The LFSR CRC is calculated Most Significant bit first (i.e., not reflected)

bit 23-13 **Unimplemented:** Read as '0'

bit 12-8 **PLEN<4:0>:** Polynomial Length bits<sup>(1)</sup>

When CRCTYP (DCRCCON<15>) = 1 (CRC module is in IP Header mode):

These bits are unused.

When CRCTYP (DCRCCON<15>) = 0 (CRC module is in LFSR mode):

Denotes the length of the polynomial – 1.

bit 7 **CRCEN:** CRC Enable bit

1 = CRC module is enabled and channel transfers are routed through the CRC module

0 = CRC module is disabled and channel transfers proceed normally

**Note 1:** When WBO = 1, unaligned transfers are not supported and the CRCAPP bit cannot be set.

**TABLE 12-23: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP (CONTINUED)**

Virtual Address (BF80_#)	Register Name	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
15B4	RPC13R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPC13R<3:0>				0000
15B8	RPC14R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPC14R<3:0>				0000
15C0	RPD0R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD0R<3:0>				0000
15C4	RPD1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD1R<3:0>				0000
15C8	RPD2R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD2R<3:0>				0000
15CC	RPD3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD3R<3:0>				0000
15D0	RPD4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD4R<3:0>				0000
15D4	RPD5R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD5R<3:0>				0000
15D8	RPD6R <sup>(2)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD6R<3:0>				0000
15DC	RPD7R <sup>(2)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD7R<3:0>				0000
15E4	RPD9R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD9R<3:0>				0000
15E8	RPD10R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD10R<3:0>				0000
15EC	RPD11R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD11R<3:0>				0000
15F0	RPD12R <sup>(1)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD12R<3:0>				0000
15F8	RPD14R <sup>(1)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD14R<3:0>				0000
15FC	RPD15R <sup>(1)</sup>	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPD15R<3:0>				0000
160C	RPE3R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPE3R<3:0>				0000
1614	RPE5R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	RPE5R<3:0>				0000

**Legend:** x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

- Note** 1: This register is not available on 64-pin devices.  
 2: This register is not available on 64-pin and 100-pin devices.

# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

**REGISTER 17-1: ICxCON: INPUT CAPTURE x CONTROL REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
23:16	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
15:8	R/W-0 ON	U-0 —	R/W-0 SIDL	U-0 —	U-0 —	U-0 —	R/W-0 FEDGE	R/W-0 C32
7:0	R/W-0 ICTMR <sup>(1)</sup>	R/W-0 ICI<1:0>	R/W-0	R-0 ICOV	R-0 ICBNE	R/W-0	R/W-0	R/W-0 ICM<2:0>

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit

-n = Bit Value at POR: ('0', '1', x = unknown)

P = Programmable bit r = Reserved bit

- bit 31-16 **Unimplemented:** Read as '0'
- bit 15 **ON:** Input Capture Module Enable bit  
1 = Module is enabled  
0 = Disable and reset module, disable clocks, disable interrupt generation and allow SFR modifications
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **SIDL:** Stop in Idle Control bit  
1 = Halt in CPU Idle mode  
0 = Continue to operate in CPU Idle mode
- bit 12-10 **Unimplemented:** Read as '0'
- bit 9 **FEDGE:** First Capture Edge Select bit (only used in mode 6, ICM<2:0> = 110)  
1 = Capture rising edge first  
0 = Capture falling edge first
- bit 8 **C32:** 32-bit Capture Select bit  
1 = 32-bit timer resource capture  
0 = 16-bit timer resource capture
- bit 7 **ICTMR:** Timer Select bit (Does not affect timer selection when C32 (ICxCON<8>) is '1')<sup>(1)</sup>  
0 = Timery is the counter source for capture  
1 = Timerx is the counter source for capture
- bit 6-5 **ICI<1:0>:** Interrupt Control bits  
11 = Interrupt on every fourth capture event  
10 = Interrupt on every third capture event  
01 = Interrupt on every second capture event  
00 = Interrupt on every capture event
- bit 4 **ICOV:** Input Capture Overflow Status Flag bit (read-only)  
1 = Input capture overflow is occurred  
0 = No input capture overflow is occurred
- bit 3 **ICBNE:** Input Capture Buffer Not Empty Status bit (read-only)  
1 = Input capture buffer is not empty; at least one more capture value can be read  
0 = Input capture buffer is empty
- bit 2-0 **ICM<2:0>:** Input Capture Mode Select bits  
111 = Interrupt-Only mode (only supported while in Sleep mode or Idle mode)  
110 = Simple Capture Event mode – every edge, specified edge first and every edge thereafter  
101 = Prescaled Capture Event mode – every sixteenth rising edge  
100 = Prescaled Capture Event mode – every fourth rising edge  
011 = Simple Capture Event mode – every rising edge  
010 = Simple Capture Event mode – every falling edge  
001 = Edge Detect mode – every edge (rising and falling)  
000 = Input Capture module is disabled

**Note 1:** Refer to Table 17-1 for Timerx and Timery selections.

# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

## REGISTER 23-6: PMAEN: PARALLEL PORT PIN ENABLE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	PTEN<15:14>		PTEN<13:8>					
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	PTEN<7:0>							

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-15 **Unimplemented:** Read as '0'

bit 15-14 **PTEN<15:14>:** PMCS1 Strobe Enable bits

1 = PMA15 and PMA14 function as either PMA<15:14> or PMCS1 and PMCS2<sup>(1)</sup>

0 = PMA15 and PMA14 function as port I/O

bit 13-2 **PTEN<13:2>:** PMP Address Port Enable bits

1 = PMA<13:2> function as PMP address lines

0 = PMA<13:2> function as port I/O

bit 1-0 **PTEN<1:0>:** PMALH/PMALL Strobe Enable bits

1 = PMA1 and PMA0 function as either PMA<1:0> or PMALH and PMALL<sup>(2)</sup>

0 = PMA1 and PMA0 pads function as port I/O

**Note 1:** The use of these pins as PMA15 and PMA14 or CS1 and CS2 is selected by the CSF<1:0> bits in the PMCON register.

**2:** The use of these pins as PMA1/PMA0 or PMALH/PMALL depends on the Address/Data Multiplex mode selected by bits ADRMUX<1:0> in the PMCON register.

NOTES:

## PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

**REGISTER 24-4: EBIFTRPD: EXTERNAL BUS INTERFACE FLASH TIMING REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	TRPD<11:8>			
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TRPD<7:0>							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

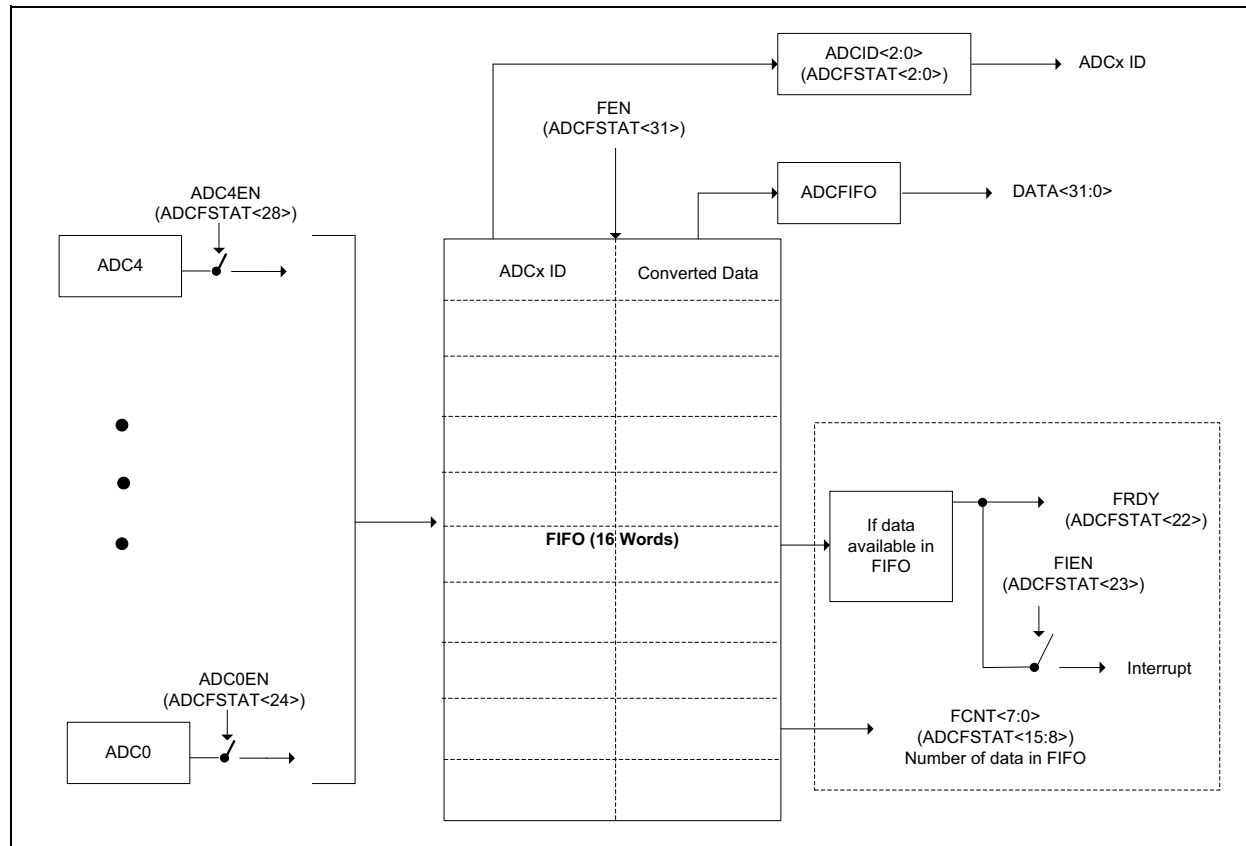
x = Bit is unknown

bit 31-12 **Unimplemented:** Read as '0'

bit 11-0 **TRPD<11:0>:** Flash Timing bits

These bits define the number of clock cycles to wait after resetting the external Flash memory before any read/write access.

**FIGURE 28-3: FIFO BLOCK DIAGRAM**





## REGISTER 29-14: CiFLTCON4: CAN FILTER CONTROL REGISTER 4 (CONTINUED)

- bit 15      **FLTEN17**: Filter 13 Enable bit  
1 = Filter is enabled  
0 = Filter is disabled
- bit 14-13   **MSEL17<1:0>**: Filter 17 Mask Select bits  
11 = Acceptance Mask 3 selected  
10 = Acceptance Mask 2 selected  
01 = Acceptance Mask 1 selected  
00 = Acceptance Mask 0 selected
- bit 12-8   **FSEL17<4:0>**: FIFO Selection bits  
11111 = Message matching filter is stored in FIFO buffer 31  
11110 = Message matching filter is stored in FIFO buffer 30  
•  
•  
•  
00001 = Message matching filter is stored in FIFO buffer 1  
00000 = Message matching filter is stored in FIFO buffer 0
- bit 7      **FLTEN16**: Filter 16 Enable bit  
1 = Filter is enabled  
0 = Filter is disabled
- bit 6-5    **MSEL16<1:0>**: Filter 16 Mask Select bits  
11 = Acceptance Mask 3 selected  
10 = Acceptance Mask 2 selected  
01 = Acceptance Mask 1 selected  
00 = Acceptance Mask 0 selected
- bit 4-0    **FSEL16<4:0>**: FIFO Selection bits  
11111 = Message matching filter is stored in FIFO buffer 31  
11110 = Message matching filter is stored in FIFO buffer 30  
•  
•  
•  
00001 = Message matching filter is stored in FIFO buffer 1  
00000 = Message matching filter is stored in FIFO buffer 0

<b>Note:</b> The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.
---

## 36.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16, and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

## 36.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

## 36.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/librarian features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

## 36.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

**TABLE 37-18: SYSTEM TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.1V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial				
Param. No.	Symbol	Characteristics	Minimum	Typical	Maximum	Units	Conditions
OS51	FSYS	System Frequency	DC	—	200	MHz	USB module disabled
			60	—	200	MHz	USB module enabled
OS55a	FPB	Peripheral Bus Frequency	DC	—	100	MHz	For PBCLKx, 'x' ≠ 4, 7
OS55b			DC	—	200	MHz	For PBCLK4, PBCLK7
OS56	FREF	Reference Clock Frequency	—	—	50	MHz	For REFCLKI1, 3, 4 and REFCLKO1, 3, 4 pins

**TABLE 37-19: PLL CLOCK TIMING SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.1V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	Symbol	Characteristics <sup>(1)</sup>	Min.	Typical	Max.	Units	Conditions
OS50	FIN	PLL Input Frequency Range	5	—	64	MHz	ECPLL, HSPLL, FRCPLL modes
OS52	TLOCK	PLL Start-up Time (Lock Time)	—	—	100	μs	—
OS53	DCLK	CLKO Stability <sup>(2)</sup> (Period Jitter or Cumulative)	-0.25	—	+0.25	%	Measured over 100 ms period
OS54	FVCO	PLL VCO Frequency Range	350	—	700	MHz	—
OS54a	FPLL	PLL Output Frequency Range	10	—	200	MHz	—

**Note 1:** These parameters are characterized, but not tested in manufacturing.

**2:** This jitter specification is based on clock-cycle by clock-cycle measurements. To get the effective jitter for individual time-bases on communication clocks, use the following formula:

$$EffectiveJitter = \frac{D_{CLK}}{\sqrt{\frac{PBCLK2}{CommunicationClock}}}$$

For example, if PBCLK2 = 100 MHz and SPI bit rate = 50 MHz, the effective jitter is as follows:

$$EffectiveJitter = \frac{D_{CLK}}{\sqrt{\frac{100}{50}}} = \frac{D_{CLK}}{1.41}$$

The diagram shows two signal groups. The top group, labeled 'TX Clock', consists of two horizontal lines: the upper line is labeled 'VIHMIN' and the lower line is labeled 'VILMAX'. A purple waveform oscillates between these two levels. The bottom group, labeled 'ETXD<3:0>, ETEN, ETXERR', consists of two horizontal lines: the upper line is labeled 'VIHMIN' and the lower line is labeled 'VILMAX'. A blue waveform is shown between these lines, with cross-hatched areas indicating specific timing regions. Vertical dashed lines mark the boundaries of these regions. A right-pointing arrow is located below the first boundary, and a left-pointing arrow labeled 'ET7' is located below the second boundary.

The diagram shows the timing relationship between the RX Clock and the ERXD signals (ERXD<3:0>, ERXD<0>, ERXD<1>, ERXD<2>, ERXD<3>). The RX Clock is a square wave. The ERXD signals are shown as a single line with a dashed line indicating the setup time (ET10) before the clock edge and the hold time (ET10 (Hold)) after the clock edge. The signals are labeled with VIHMIN and VILMAX levels.

# PIC32MZ Embedded Connectivity with Floating Point Unit (EF) Family

## B.6 Resets

On PIC32MZ EF devices, the Reset module adds eight bits to the NMICNT field to make the time-out period before device Reset longer, as described in Table B-5.

**TABLE B-5: RESETS DIFFERENCES**

PIC32MZ EC Feature	PIC32MZ EF Feature
<b>Countdown to Reset During NMIs</b>	
On PIC32MZ EC devices, the NMICNT<7:0> field is eight bits long, giving a maximum of 256 instructions before the device Reset.	On PIC32MZ EF devices, the NMICNT<15:0> field is now 16 bits long, giving a longer period of time (up to 65,536 instructions) prior to a device Reset.

## B.7 USB

On PIC32MZ EF devices, a new USBRCRCON register has been added to assist in controlling the reset of the USB module, and triggering interrupts based on VBUS voltage levels. This register also overcomes an errata on PIC32MZ EC devices that requires a three second start-up on the USB module.

## B.8 I/O Ports

On PIC32MZ EF devices, many of the I/O pins now feature slew rate control bits to control how fast the pin makes a low-to-high or high-to-low transition. The Change Notification feature has also been enhanced to allow detection of level events in addition to edge detection. However, the SIDL bit is not present in the CNCONx registers on PIC32MZ EF devices, as it is on PIC32MZ EC devices.

## B.9 Watchdog Timer

PIC32MZ EF devices use a new Watchdog Timer, although the overall control through the DEVCFGx words remains identical to that of PIC32MZ EC devices. Table B-6 lists two more changes, as well.

**TABLE B-6: WATCHDOG TIMER DIFFERENCES**

PIC32MZ EC Feature	PIC32MZ EF Feature
<b>Watchdog Timer Postscaler</b>	
On PIC32MZ EC devices, the SWDTPS<4:0> bits (WDTCON<6:2>) reflect the postscaler setting for the Watchdog Timer.	On PIC32MZ EF devices, the field has been changed to the RUNDIV<4:0> bits (WDTCON<12:8>).
<b>Watchdog Windowed Mode</b>	
On PIC32MZ EC devices, WDTWINEN is at bit position 1 (WDTCON<1>).	On PIC32MZ EF devices, WDTWINEN is now at bit position 0 (WDTCON<0>).