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### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	53
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24fj256ga106t-i-pt">https://www.e-xfl.com/product-detail/microchip-technology/pic24fj256ga106t-i-pt</a>

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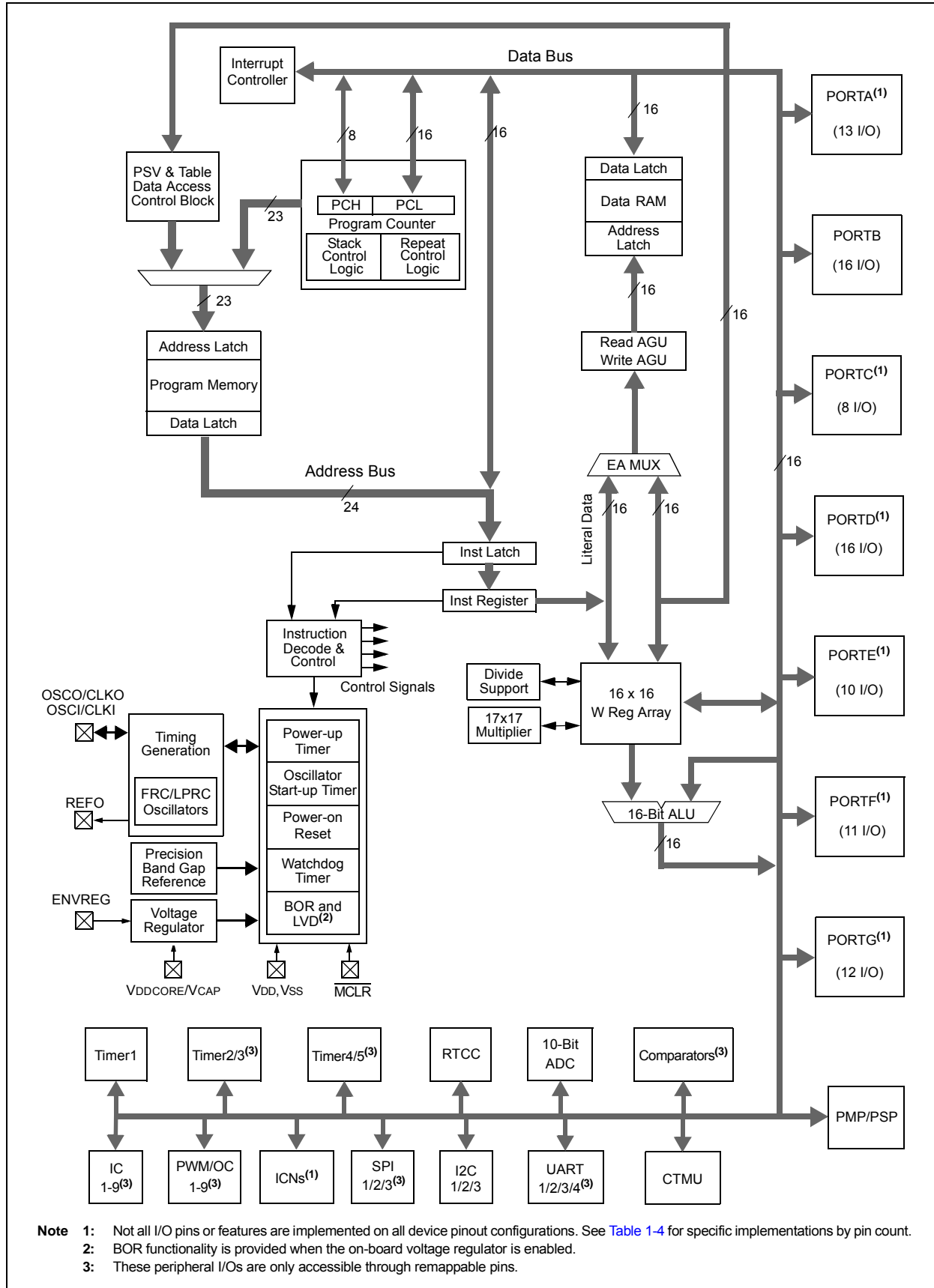
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# PIC24FJ256GA110 FAMILY

**FIGURE 1-1: PIC24FJ256GA110 FAMILY GENERAL BLOCK DIAGRAM**



# PIC24FJ256GA110 FAMILY

## REGISTER 3-2: CORCON: CPU CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15				bit 8			

U-0	U-0	U-0	U-0	R/C-0	R/W-0	U-0	U-0
—	—	—	—	IPL3 <sup>(1)</sup>	PSV	—	—
bit 7				bit 0			

<b>Legend:</b>	C = Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-4      **Unimplemented:** Read as '0'

bit 3      **IPL3:** CPU Interrupt Priority Level Status bit<sup>(1)</sup>  
             1 = CPU interrupt priority level is greater than 7  
             0 = CPU interrupt priority level is 7 or less

bit 2      **PSV:** Program Space Visibility in Data Space Enable bit  
             1 = Program space visible in data space  
             0 = Program space not visible in data space

bit 1-0      **Unimplemented:** Read as '0'

**Note 1:** User interrupts are disabled when IPL3 = 1.

# PIC24FJ256GA110 FAMILY

## 3.3 Arithmetic Logic Unit (ALU)

The PIC24F ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are 2's complement in nature. Depending on the operation, the ALU may affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array, or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

The PIC24F CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

### 3.3.1 MULTIPLIER

The ALU contains a high-speed, 17-bit x 17-bit multiplier. It supports unsigned, signed or mixed sign operation in several multiplication modes:

1. 16-bit x 16-bit signed
2. 16-bit x 16-bit unsigned
3. 16-bit signed x 5-bit (literal) unsigned
4. 16-bit unsigned x 16-bit unsigned
5. 16-bit unsigned x 5-bit (literal) unsigned
6. 16-bit unsigned x 16-bit signed
7. 8-bit unsigned x 8-bit unsigned

### 3.3.2 DIVIDER

The divide block supports signed and unsigned integer divide operations with the following data sizes:

1. 32-bit signed/16-bit signed divide
2. 32-bit unsigned/16-bit unsigned divide
3. 16-bit signed/16-bit signed divide
4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. Sixteen-bit signed and unsigned `DIV` instructions can specify any W register for both the 16-bit divisor (Wn), and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

### 3.3.3 MULTI-BIT SHIFT SUPPORT

The PIC24F ALU supports both single bit and single-cycle, multi-bit arithmetic and logic shifts. Multi-bit shifts are implemented using a shifter block, capable of performing up to a 15-bit arithmetic right shift, or up to a 15-bit left shift, in a single cycle. All multi-bit shift instructions only support Register Direct Addressing for both the operand source and result destination.

A full summary of instructions that use the shift operation is provided below in [Table 3-2](#).

**TABLE 3-2: INSTRUCTIONS THAT USE THE SINGLE AND MULTI-BIT SHIFT OPERATION**

Instruction	Description
ASR	Arithmetic shift right source register by one or more bits.
SL	Shift left source register by one or more bits.
LSR	Logical shift right source register by one or more bits.

**TABLE 4-8: OUTPUT COMPARE REGISTER MAP (CONTINUED)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
OC8CON1	01D6	—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	—	ENFLT0	—	—	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC8CON2	01D8	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC8RS	01DA	Output Compare 8 Secondary Register																0000
OC8R	01DC	Output Compare 8 Register																0000
OC8TMR	01DE	Timer Value 8 Register																xxxx
OC9CON1	01E0	—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	—	ENFLT0	—	—	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC9CON2	01E2	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC9RS	01E4	Output Compare 9 Secondary Register																0000
OC9R	01E6	Output Compare 9 Register																0000
OC9TMR	01E8	Timer Value 9 Register																xxxx

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-9: I<sup>2</sup>C<sup>™</sup> REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
I2C1RCV	0200	—	—	—	—	—	—	—	—	Receive Register								0000
I2C1TRN	0202	—	—	—	—	—	—	—	—	Transmit Register								00FF
I2C1BRG	0204	—	—	—	—	—	—	—	—	Baud Rate Generator Register								0000
I2C1CON	0206	I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C1STAT	0208	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/Ā	P	S	R/Ā	RBF	TBF	0000
I2C1ADD	020A	—	—	—	—	—	—	Address Register										0000
I2C1MSK	020C	—	—	—	—	—	—	Address Mask Register										0000
I2C2RCV	0210	—	—	—	—	—	—	—	—	Receive Register								0000
I2C2TRN	0212	—	—	—	—	—	—	—	—	Transmit Register								00FF
I2C2BRG	0214	—	—	—	—	—	—	—	—	Baud Rate Generator Register								0000
I2C2CON	0216	I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C2STAT	0218	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/Ā	P	S	R/Ā	RBF	TBF	0000
I2C2ADD	021A	—	—	—	—	—	—	Address Register										0000
I2C2MSK	021C	—	—	—	—	—	—	Address Mask Register										0000
I2C3RCV	0270	—	—	—	—	—	—	—	—	Receive Register								0000
I2C3TRN	0272	—	—	—	—	—	—	—	—	Transmit Register								00FF
I2C3BRG	0274	—	—	—	—	—	—	—	—	Baud Rate Generator Register								0000
I2C3CON	0276	I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C3STAT	0278	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/Ā	P	S	R/Ā	RBF	TBF	0000
I2C3ADD	027A	—	—	—	—	—	—	Address Register										0000
I2C3MSK	027C	—	—	—	—	—	—	Address Mask Register										0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

# PIC24FJ256GA110 FAMILY

**REGISTER 5-1: NVMCON: FLASH MEMORY CONTROL REGISTER**

R/SO-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	U-0	U-0	U-0	U-0	U-0
WR	WREN	WRERR	—	—	—	—	—
bit 15			bit 8				

U-0	R/W-0 <sup>(1)</sup>	U-0	U-0	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>
—	ERASE	—	—	NVMOP3 <sup>(2)</sup>	NVMOP2 <sup>(2)</sup>	NVMOP1 <sup>(2)</sup>	NVMOP0 <sup>(2)</sup>
bit 7			bit 0				

<b>Legend:</b>	SO = Set Only bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15      **WR:** Write Control bit<sup>(1)</sup>  
1 = Initiates a Flash memory program or erase operation. The operation is self-timed and the bit is cleared by hardware once the operation is complete.  
0 = Program or erase operation is complete and inactive
- bit 14      **WREN:** Write Enable bit<sup>(1)</sup>  
1 = Enable Flash program/erase operations  
0 = Inhibit Flash program/erase operations
- bit 13      **WRERR:** Write Sequence Error Flag bit<sup>(1)</sup>  
1 = An improper program or erase sequence attempt or termination has occurred (bit is set automatically on any set attempt of the WR bit)  
0 = The program or erase operation completed normally
- bit 12-7    **Unimplemented:** Read as '0'
- bit 6        **ERASE:** Erase/Program Enable bit<sup>(1)</sup>  
1 = Perform the erase operation specified by NVMOP<3:0> on the next WR command  
0 = Perform the program operation specified by NVMOP<3:0> on the next WR command
- bit 5-4     **Unimplemented:** Read as '0'
- bit 3-0     **NVMOP<3:0>:** NVM Operation Select bits<sup>(1,2)</sup>  
1111 = Memory bulk erase operation (ERASE = 1) or no operation (ERASE = 0)<sup>(3)</sup>  
0011 = Memory word program operation (ERASE = 0) or no operation (ERASE = 1)  
0010 = Memory page erase operation (ERASE = 1) or no operation (ERASE = 0)  
0001 = Memory row program operation (ERASE = 0) or no operation (ERASE = 1)

- Note 1:** These bits can only be reset on POR.  
**2:** All other combinations of NVMOP<3:0> are unimplemented.  
**3:** Available in ICSP™ mode only. Refer to the device programming specification.

# PIC24FJ256GA110 FAMILY

## REGISTER 7-4: INTCON2: INTERRUPT CONTROL REGISTER 2

R/W-0	R-0	U-0	U-0	U-0	U-0	U-0	U-0
ALTIVT	DISI	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	INT4EP	INT3EP	INT2EP	INT1EP	INT0EP
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **ALTIVT:** Enable Alternate Interrupt Vector Table bit  
                  1 = Use Alternate Interrupt Vector Table  
                  0 = Use standard (default) vector table
- bit 14      **DISI:** DISI Instruction Status bit  
                  1 = DISI instruction is active  
                  0 = DISI instruction is not active
- bit 13-5    **Unimplemented:** Read as '0'
- bit 4        **INT4EP:** External Interrupt 4 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge
- bit 3        **INT3EP:** External Interrupt 3 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge
- bit 2        **INT2EP:** External Interrupt 2 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge
- bit 1        **INT1EP:** External Interrupt 1 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge
- bit 0        **INT0EP:** External Interrupt 0 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge



# PIC24FJ256GA110 FAMILY

## 10.4.6 PERIPHERAL PIN SELECT REGISTERS

The PIC24FJ256GA110 family of devices implements a total of 37 registers for remappable peripheral configuration:

- Input Remappable Peripheral Registers (21)
- Output Remappable Peripheral Registers (16)

**Note:** Input and output register values can only be changed if IOLOCK (OSCCON<6>) = 0. See [Section 10.4.4.1 “Control Register Lock”](#) for a specific command sequence.

### REGISTER 10-1: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT1R5	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **INT1R<5:0>:** Assign External Interrupt 1 (INT1) to Corresponding RPN or RPN Pin bits

bit 7-0 **Unimplemented:** Read as '0'

### REGISTER 10-2: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT3R5	INT3R4	INT3R3	INT3R2	INT3R1	INT3R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT2R5	INT2R4	INT2R3	INT2R2	INT2R1	INT2R0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **INT3R<5:0>:** Assign External Interrupt 3 (INT3) to Corresponding RPN or RPN Pin bits

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **INT2R<5:0>:** Assign External Interrupt 2 (INT2) to Corresponding RPN or RPN Pin bits

# PIC24FJ256GA110 FAMILY

## REGISTER 10-13: RPINR18: PERIPHERAL PIN SELECT INPUT REGISTER 18

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U1CTSR5	U1CTSR4	U1CTSR3	U1CTSR2	U1CTSR1	U1CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U1RXR5	U1RXR4	U1RXR3	U1RXR2	U1RXR1	U1RXR0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **U1CTSR<5:0>:** Assign UART1 Clear to Send ( $\overline{\text{U1CTS}}$ ) to Corresponding RPn or RPIIn Pin bits

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **U1RXR<5:0>:** Assign UART1 Receive (U1RX) to Corresponding RPn or RPIIn Pin bits

## REGISTER 10-14: RPINR19: PERIPHERAL PIN SELECT INPUT REGISTER 19

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U2CTSR5	U2CTSR4	U2CTSR3	U2CTSR2	U2CTSR1	U2CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U2RXR5	U2RXR4	U2RXR3	U2RXR2	U2RXR1	U2RXR0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **U2CTSR<5:0>:** Assign UART2 Clear to Send ( $\overline{\text{U2CTS}}$ ) to Corresponding RPn or RPIIn Pin bits

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **U2RXR<5:0>:** Assign UART2 Receive (U2RX) to Corresponding RPn or RPIIn Pin bits

# PIC24FJ256GA110 FAMILY

## REGISTER 10-34: RPOR12: PERIPHERAL PIN SELECT OUTPUT REGISTER 12

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP25R5	RP25R4	RP25R3	RP25R2	RP25R1	RP25R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP24R5	RP24R4	RP24R3	RP24R2	RP24R1	RP24R0
bit 7							bit 0

### Legend:

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 15-14     **Unimplemented:** Read as '0'
- bit 13-8     **RP25R<5:0>:** RP25 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP25 (see [Table 10-3](#) for peripheral function numbers).
- bit 7-6       **Unimplemented:** Read as '0'
- bit 5-0       **RP24R<5:0>:** RP24 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP24 (see [Table 10-3](#) for peripheral function numbers).

## REGISTER 10-35: RPOR13: PERIPHERAL PIN SELECT OUTPUT REGISTER 13

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP27R5	RP27R4	RP27R3	RP27R2	RP27R1	RP27R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP26R5	RP26R4	RP26R3	RP26R2	RP26R1	RP26R0
bit 7							bit 0

### Legend:

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 15-14     **Unimplemented:** Read as '0'
- bit 13-8     **RP27R<5:0>:** RP27 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP27 (see [Table 10-3](#) for peripheral function numbers).
- bit 7-6       **Unimplemented:** Read as '0'
- bit 5-0       **RP26R<5:0>:** RP26 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP26 (see [Table 10-3](#) for peripheral function numbers).

## 12.0 TIMER2/3 AND TIMER4/5

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, **Section 14. “Timers”** (DS39704).

The Timer2/3 and Timer4/5 modules are 32-bit timers, which can also be configured as four independent 16-bit timers with selectable operating modes.

As 32-bit timers, Timer2/3 and Timer4/5 can each operate in three modes:

- Two independent 16-bit timers with all 16-bit operating modes (except Asynchronous Counter mode)
- Single 32-bit timer
- Single 32-bit synchronous counter

They also support these features:

- Timer Gate Operation
- Selectable Prescaler Settings
- Timer Operation during Idle and Sleep modes
- Interrupt on a 32-Bit Period Register Match
- ADC Event Trigger (Timer2/3 only)

Individually, all four of the 16-bit timers can function as synchronous timers or counters. They also offer the features listed above, except for the ADC event trigger; this is implemented only with Timer3. The operating modes and enabled features are determined by setting the appropriate bit(s) in the T2CON, T3CON, T4CON and T5CON registers. T2CON and T4CON are shown in generic form in [Register 12-1](#); T3CON and T5CON are shown in [Register 12-2](#).

For 32-bit timer/counter operation, Timer2 and Timer4 are the least significant word; Timer3 and Timer4 are the most significant word of the 32-bit timers.

**Note:** For 32-bit operation, T3CON and T5CON control bits are ignored. Only T2CON and T4CON control bits are used for setup and control. Timer2 and Timer4 clock and gate inputs are utilized for the 32-bit timer modules, but an interrupt is generated with the Timer3 or Timer5 interrupt flags.

To configure Timer2/3 or Timer4/5 for 32-bit operation:

1. Set the T32 bit (T2CON<3> or T4CON<3> = 1).
2. Select the prescaler ratio for Timer2 or Timer4 using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits. If TCS is set to external clock, RPINRx (TxCK) must be configured to an available RPN pin. See **Section 10.4 “Peripheral Pin Select”** for more information.
4. Load the timer period value. PR3 (or PR5) will contain the most significant word of the value while PR2 (or PR4) contains the least significant word.
5. If interrupts are required, set the interrupt enable bit, T3IE or T5IE; use the priority bits, T3IP<2:0> or T5IP<2:0>, to set the interrupt priority. Note that while Timer2 or Timer4 controls the timer, the interrupt appears as a Timer3 or Timer5 interrupt.
6. Set the TON bit (= 1).

The timer value, at any point, is stored in the register pair: TMR3:TMR2 (or TMR5:TMR4). TMR3 (TMR5) always contains the most significant word of the count, while TMR2 (TMR4) contains the least significant word.

To configure any of the timers for individual 16-bit operation:

1. Clear the T32 bit corresponding to that timer (T2CON<3> for Timer2 and Timer3 or T4CON<3> for Timer4 and Timer5).
2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits. See **Section 10.4 “Peripheral Pin Select”** for more information.
4. Load the timer period value into the PRx register.
5. If interrupts are required, set the interrupt enable bit, TxIE; use the priority bits, TxIP<2:0>, to set the interrupt priority.
6. Set the TON bit (TxCON<15> = 1).

## 13.0 INPUT CAPTURE WITH DEDICATED TIMER

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, **Section 34. “Input Capture with Dedicated Timer”** (DS39722)

Devices in the PIC24FJ256GA110 family all feature 9 independent enhanced input capture modules. Each of the modules offers a wide range of configuration and operating options for capturing external pulse events and generating interrupts.

Key features of the enhanced output module include:

- Hardware-configurable for 32-bit operation in all modes by cascading two adjacent modules
- Synchronous and Trigger modes of output compare operation, with up to 30 user-selectable trigger/sync sources available
- A 4-level FIFO buffer for capturing and holding timer values for several events
- Configurable interrupt generation
- Up to 6 clock sources available for each module, driving a separate internal 16-bit counter

The module is controlled through two registers: ICxCON1 ([Register 13-1](#)) and ICxCON2 ([Register 13-2](#)). A general block diagram of the module is shown in [Figure 13-1](#).

## 13.1 General Operating Modes

### 13.1.1 SYNCHRONOUS AND TRIGGER MODES

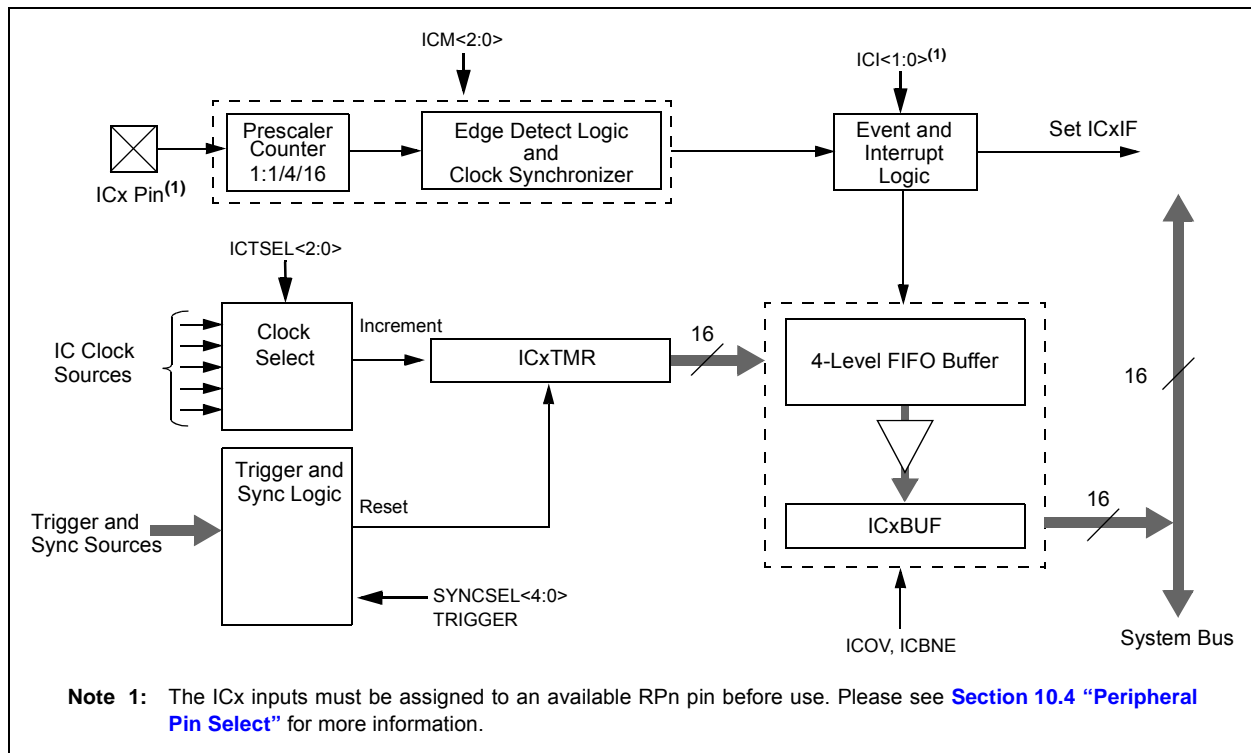
By default, the enhanced input capture module operates in a free-running mode. The internal 16-bit counter ICxTMR counts up continuously, wrapping around from FFFFh to 0000h on each overflow, with its period synchronized to the selected external clock source. When a capture event occurs, the current 16-bit value of the internal counter is written to the FIFO buffer.

In Synchronous mode, the module begins capturing events on the ICx pin as soon as its selected clock source is enabled. Whenever an event occurs on the selected sync source, the internal counter is reset. In Trigger mode, the module waits for a Sync event from another internal module to occur before allowing the internal counter to run.

Standard, free-running operation is selected by setting the SYNCSEL bits to ‘00000’ and clearing the ICTRIG bit (ICxCON2<7>). Synchronous and Trigger modes are selected any time the SYNCSEL bits are set to any value except ‘00000’. The ICTRIG bit selects either Synchronous or Trigger mode; setting the bit selects Trigger mode operation. In both modes, the SYNCSEL bits determine the sync/trigger source.

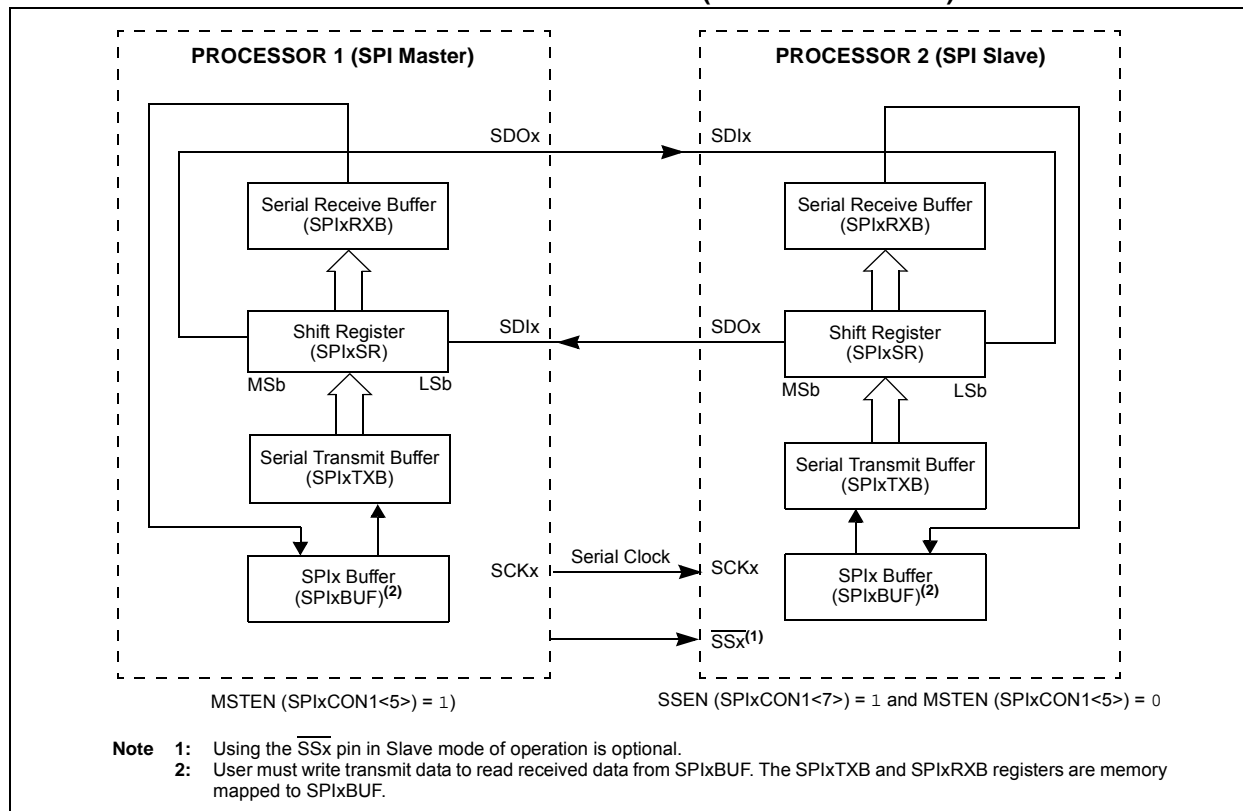
When the SYNCSEL bits are set to ‘00000’ and ICTRIG is set, the module operates in Software Trigger mode. In this case, capture operations are started by manually setting the TRIGSTAT bit (ICxCON2<6>).

**FIGURE 13-1: INPUT CAPTURE BLOCK DIAGRAM**

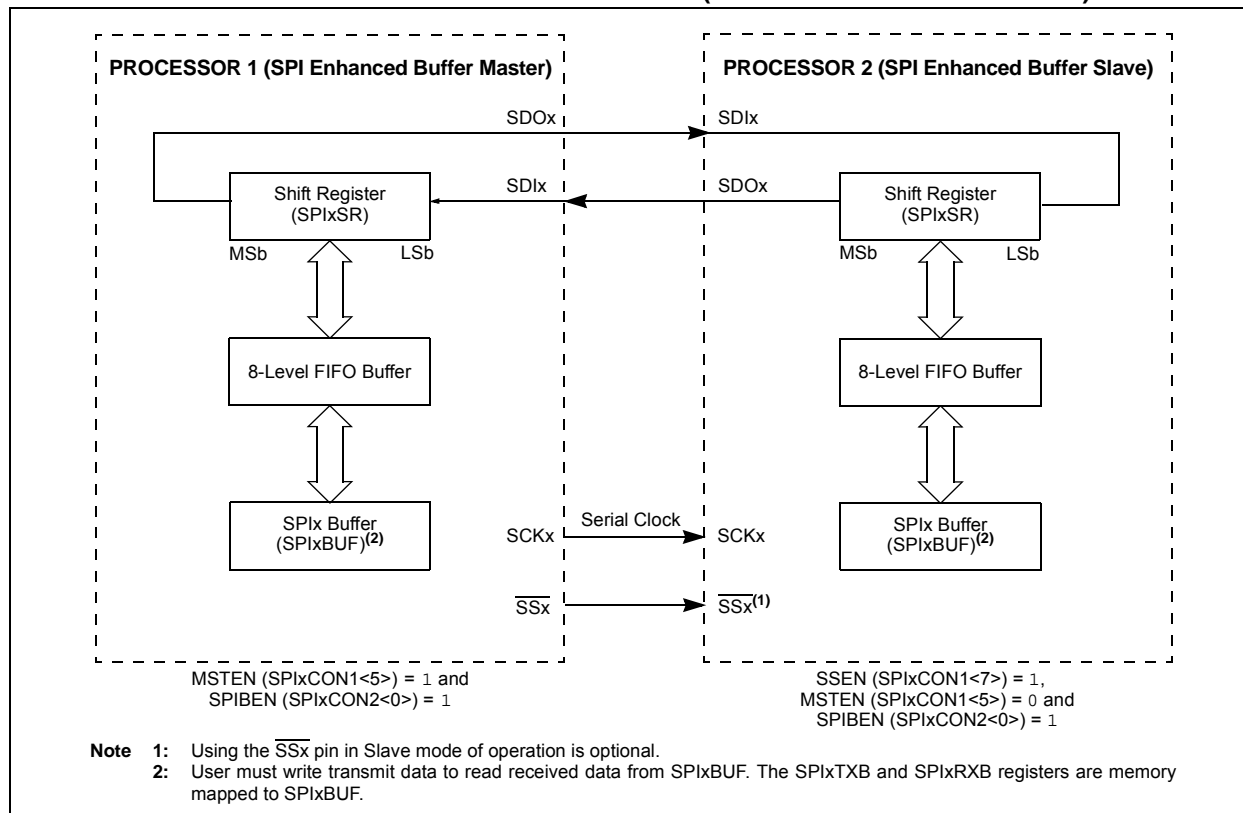


# PIC24FJ256GA110 FAMILY

**FIGURE 15-3: SPI MASTER/SLAVE CONNECTION (STANDARD MODE)**



**FIGURE 15-4: SPI MASTER/SLAVE CONNECTION (ENHANCED BUFFER MODES)**



## 17.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, Section 21. “UART” (DS39708).

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the PIC24F device family. The UART is a full-duplex asynchronous system that can communicate with peripheral devices, such as personal computers, LIN, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the  $\overline{\text{UxCTS}}$  and  $\overline{\text{UxRTS}}$  pins, and also includes an IrDA® encoder and decoder.

The primary features of the UART module are:

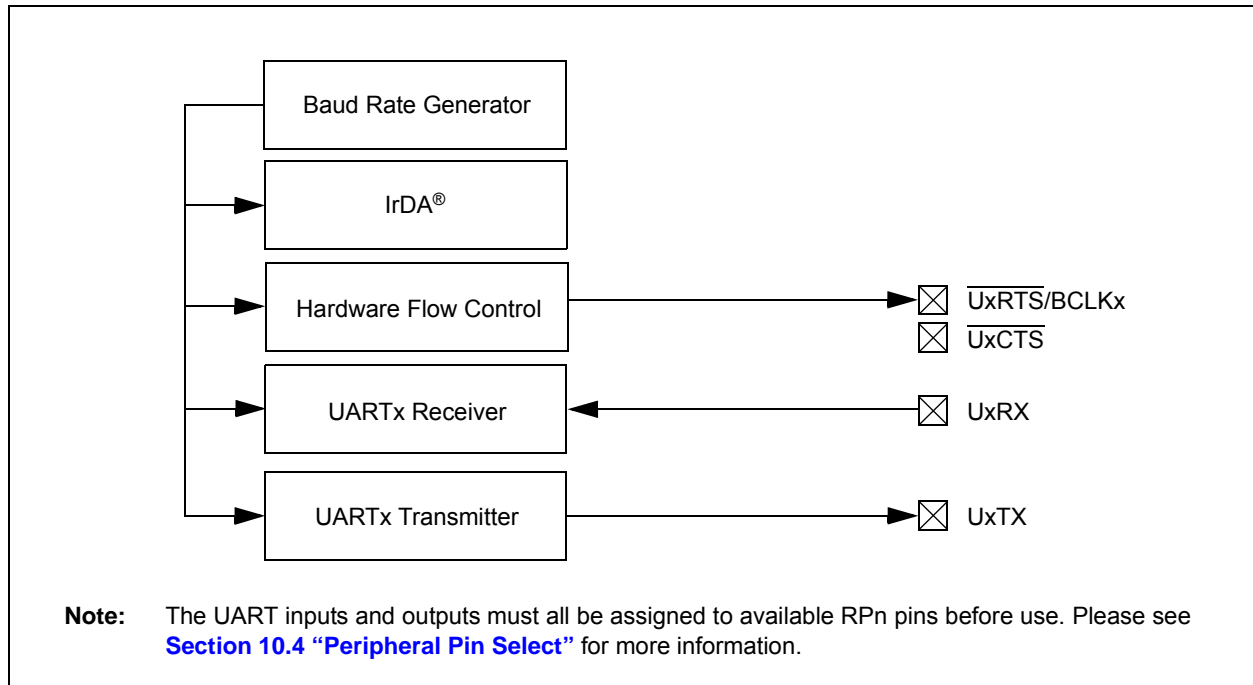
- Full-Duplex, 8 or 9-Bit Data Transmission through the  $\text{UxTX}$  and  $\text{UxRX}$  Pins
- Even, Odd or No Parity Options (for 8-bit data)
- One or Two Stop bits
- Hardware Flow Control Option with  $\overline{\text{UxCTS}}$  and  $\overline{\text{UxRTS}}$  Pins

- Fully Integrated Baud Rate Generator with 16-Bit Prescaler
- Baud Rates Ranging from 1 Mbps to 15 bps at 16 MIPS
- 4-Deep, First-In-First-Out (FIFO) Transmit Data Buffer
- 4-Deep FIFO Receive Data Buffer
- Parity, Framing and Buffer Overrun Error Detection
- Support for 9-Bit mode with Address Detect (9th bit = 1)
- Transmit and Receive Interrupts
- Loopback mode for Diagnostic Support
- Support for Sync and Break Characters
- Supports Automatic Baud Rate Detection
- IrDA Encoder and Decoder Logic
- 16x Baud Clock Output for IrDA Support

A simplified block diagram of the UART is shown in Figure 17-1. The UART module consists of these key important hardware elements:

- Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

**FIGURE 17-1: UART SIMPLIFIED BLOCK DIAGRAM**



# PIC24FJ256GA110 FAMILY

## REGISTER 21-2: AD1CON2: A/D CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	r-0	U-0	R/W-0	U-0	U-0
VCFG2	VCFG1	VCFG0	r	—	CSCNA	—	—
bit 15						bit 8	

R-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUFS	—	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS
bit 7							bit 0

**Legend:** r = Reserved bit  
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'  
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-13 **VCFG<2:0>:** Voltage Reference Configuration bits

VCFG<2:0>	Vr+	Vr-
000	AVDD	AVSS
001	External VREF+ pin	AVSS
010	AVDD	External VREF- pin
011	External VREF+ pin	External VREF- pin
1xx	AVDD	AVSS

bit 12 **Reserved:** Maintain as '0'

bit 11 **Unimplemented:** Read as '0'

bit 10 **CSCNA:** Scan Input Selections for S/H Positive Input for MUX A Input Multiplexer Setting bit  
1 = Scan inputs  
0 = Do not scan inputs

bit 9-8 **Unimplemented:** Read as '0'

bit 7 **BUFS:** Buffer Fill Status bit (valid only when BUFM = 1)  
1 = A/D is currently filling buffer 08-0F, user should access data in 00-07  
0 = A/D is currently filling buffer 00-07, user should access data in 08-0F

bit 6 **Unimplemented:** Read as '0'

bit 5-2 **SMPI<3:0>:** Sample/Convert Sequences Per Interrupt Selection bits  
1111 = Interrupts at the completion of conversion for each 16th sample/convert sequence  
1110 = Interrupts at the completion of conversion for each 15th sample/convert sequence  
.....  
0001 = Interrupts at the completion of conversion for each 2nd sample/convert sequence  
0000 = Interrupts at the completion of conversion for each sample/convert sequence

bit 1 **BUFM:** Buffer Mode Select bit  
1 = Buffer configured as two 8-word buffers (ADC1BUFn<15:8> and ADC1BUFn<7:0>)  
0 = Buffer configured as one 16-word buffer (ADC1BUFn<15:0>)

bit 0 **ALTS:** Alternate Input Sample Mode Select bit  
1 = Uses MUX A input multiplexer settings for first sample, then alternates between MUX B and MUX A input multiplexer settings for all subsequent samples  
0 = Always uses MUX A input multiplexer settings



# PIC24FJ256GA110 FAMILY

## REGISTER 21-4: AD1CHS: A/D INPUT SELECT REGISTER

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NB	—	—	CH0SB4 <sup>(1)</sup>	CH0SB3 <sup>(1)</sup>	CH0SB2 <sup>(1)</sup>	CH0SB1 <sup>(1)</sup>	CH0SB0 <sup>(1)</sup>
bit 15							bit 8

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NA	—	—	CH0SA4	CH0SA3	CH0SA2	CH0SA1	CH0SA0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **CH0NB:** Channel 0 Negative Input Select for MUX B Multiplexer Setting bit

1 = Channel 0 negative input is AN1

0 = Channel 0 negative input is VR-

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **CH0SB<4:0>:** Channel 0 Positive Input Select for MUX B Multiplexer Setting bits<sup>(1)</sup>

10001 = Channel 0 positive input is internal band gap reference (VBG)

10000 = Channel 0 positive input is VBG/2

01111 = Channel 0 positive input is AN15

01110 = Channel 0 positive input is AN14

01101 = Channel 0 positive input is AN13

01100 = Channel 0 positive input is AN12

01011 = Channel 0 positive input is AN11

01010 = Channel 0 positive input is AN10

01001 = Channel 0 positive input is AN9

01000 = Channel 0 positive input is AN8

00111 = Channel 0 positive input is AN7

00110 = Channel 0 positive input is AN6

00101 = Channel 0 positive input is AN5

00100 = Channel 0 positive input is AN4

00011 = Channel 0 positive input is AN3

00010 = Channel 0 positive input is AN2

00001 = Channel 0 positive input is AN1

00000 = Channel 0 positive input is AN0

bit 7 **CH0NA:** Channel 0 Negative Input Select for MUX A Multiplexer Setting bit

1 = Channel 0 negative input is AN1

0 = Channel 0 negative input is VR-

bit 6-5 **Unimplemented:** Read as '0'

bit 4-0 **CH0SA<4:0>:** Channel 0 Positive Input Select for MUX A Multiplexer Setting bits

Implemented combinations are identical to those for CH0SB<4:0> (above).

**Note 1:** Combinations, '10010' through '11111', are unimplemented; do not use.

# PIC24FJ256GA110 FAMILY

## REGISTER 24-1: CTMUCON: CTMU CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CTMUEN	—	CTMUSIDL	TGEN	EDGEN	EDGSEQEN	IDISSEN	CTTRIG
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
EDG2POL	EDG2SEL1	EDG2SEL0	EDG1POL	EDG1SEL1	EDG1SEL0	EDG2STAT	EDG1STAT
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15      **CTMUEN:** CTMU Enable bit  
             1 = Module is enabled  
             0 = Module is disabled
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **CTMUSIDL:** Stop in Idle Mode bit  
             1 = Discontinue module operation when device enters Idle mode  
             0 = Continue module operation in Idle mode
- bit 12      **TGEN:** Time Generation Enable bit<sup>(1)</sup>  
             1 = Enables edge delay generation  
             0 = Disables edge delay generation
- bit 11      **EDGEN:** Edge Enable bit  
             1 = Edges are not blocked  
             0 = Edges are blocked
- bit 10      **EDGSEQEN:** Edge Sequence Enable bit  
             1 = Edge 1 event must occur before Edge 2 event can occur  
             0 = No edge sequence is needed
- bit 9      **IDISSEN:** Analog Current Source Control bit  
             1 = Analog current source output is grounded  
             0 = Analog current source output is not grounded
- bit 8      **CTTRIG:** Trigger Control bit  
             1 = Trigger output is enabled  
             0 = Trigger output is disabled
- bit 7      **EDG2POL:** Edge 2 Polarity Select bit  
             1 = Edge 2 programmed for a positive edge response  
             0 = Edge 2 programmed for a negative edge response
- bit 6-5      **EDG2SEL<1:0>:** Edge 2 Source Select bits  
             11 = CTED1 pin  
             10 = CTED2 pin  
             01 = OC1 module  
             00 = Timer1 module
- bit 4      **EDG1POL:** Edge 1 Polarity Select bit  
             1 = Edge 1 programmed for a positive edge response  
             0 = Edge 1 programmed for a negative edge response

**Note 1:** If TGEN = 1, the CTEDGx inputs and CTPLS outputs must be assigned to available RPN pins before use. See [Section 10.4 “Peripheral Pin Select”](#) for more information.

# PIC24FJ256GA110 FAMILY

**TABLE 28-14: PLL CLOCK TIMING SPECIFICATIONS (V<sub>DD</sub> = 2.0V TO 3.6V)**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature -40°C ≤ T <sub>A</sub> ≤ +85°C for Industrial -40°C ≤ T <sub>A</sub> ≤ +125°C for Extended				
Param No.	Sym	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
OS50	FPLLI	PLL Input Frequency Range <sup>(2)</sup>	4	—	8	MHz	ECPLL, HSPLL, XTPLL modes
OS51	FSYS	PLL Output Frequency Range	16	—	32	MHz	
OS52	TLOCK	PLL Start-up Time (Lock Time)	—	—	2	ms	
OS53	DCLK	CLKO Stability (Jitter)	-2	1	+2	%	

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**TABLE 28-15: INTERNAL RC OSCILLATOR SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature -40°C ≤ T <sub>A</sub> ≤ +85°C for Industrial -40°C ≤ T <sub>A</sub> ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ	Max	Units	Conditions
	TFRC	FRC Start-up Time	—	15	—	μs	
	TLPRC	LPRC Start-up Time	—	40	—	μs	

**TABLE 28-16: INTERNAL RC OSCILLATOR ACCURACY**

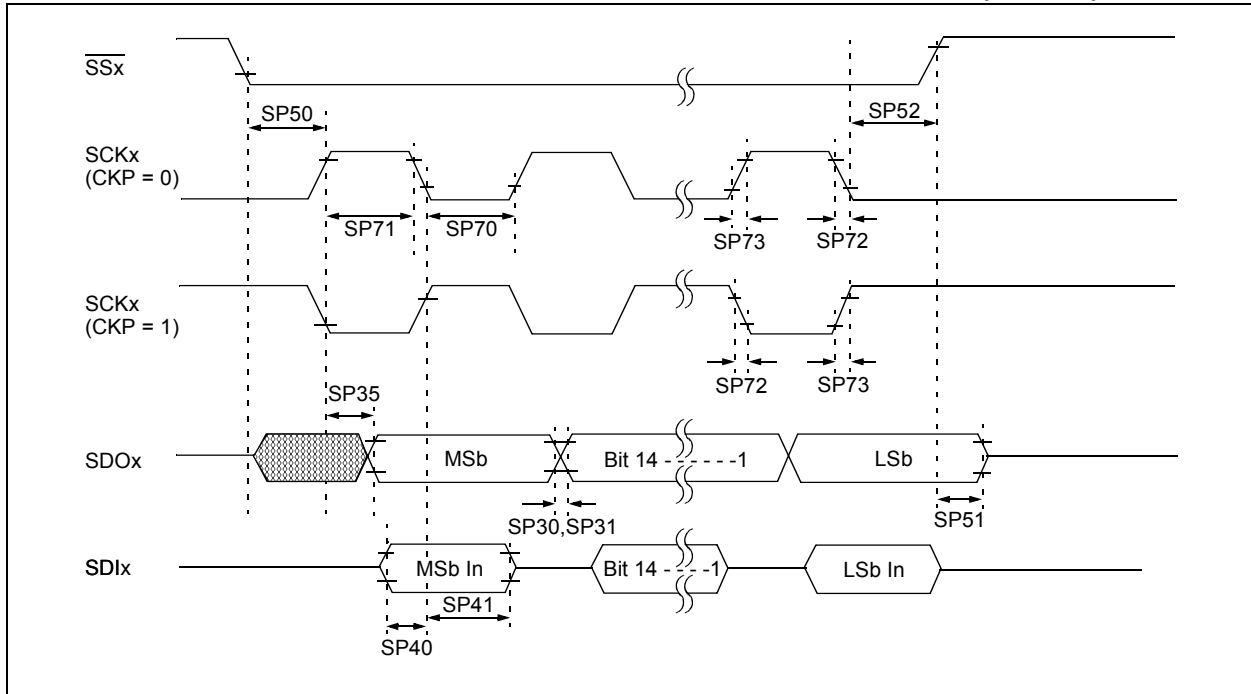
AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature -40°C ≤ T <sub>A</sub> ≤ +85°C for Industrial -40°C ≤ T <sub>A</sub> ≤ +125°C for Extended				
Param No.	Characteristic		Min	Typ	Max	Units	Conditions
F20	FRC Accuracy @ 8 MHz <sup>(1)</sup>		-2	—	2	%	+25°C, 3.0V ≤ V <sub>DD</sub> ≤ 3.6V
			-5	—	5	%	-40°C ≤ T <sub>A</sub> ≤ +85°C, 3.0V ≤ V <sub>DD</sub> ≤ 3.6V
F21	LPRC Accuracy @ 31 kHz <sup>(2)</sup>		-20	—	20	%	-40°C ≤ T <sub>A</sub> ≤ +85°C, 3.0V ≤ V <sub>DD</sub> ≤ 3.6V

**Note 1:** Frequency calibrated at 25°C and 3.3V. OSCTUN bits can be used to compensate for temperature drift.

**2:** Change of LPRC frequency as V<sub>DD</sub> changes.

# PIC24FJ256GA110 FAMILY

**FIGURE 28-13: SPIx MODULE SLAVE MODE TIMING CHARACTERISTICS (CKE = 0)**



**TABLE 28-26: SPIx MODULE SLAVE MODE TIMING REQUIREMENTS (CKE = 0)**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
SP70	TscL	SCKx Input Low Time	30	—	—	ns	
SP71	Tsch	SCKx Input High Time	30	—	—	ns	
SP72	TscF	SCKx Input Fall Time <sup>(2)</sup>	—	10	25	ns	
SP73	TscR	SCKx Input Rise Time <sup>(2)</sup>	—	10	25	ns	
SP30	TdoF	SDOx Data Output Fall Time <sup>(2)</sup>	—	10	25	ns	
SP31	TdoR	SDOx Data Output Rise Time <sup>(2)</sup>	—	10	25	ns	
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	—	30	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	20	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	20	—	—	ns	
SP50	TssL2scH, TssL2scL	SSx to SCKx ↑ or SCKx Input	120	—	—	ns	
SP51	TssH2doZ	SSx ↑ to SDOx Output High-Impedance <sup>(3)</sup>	10	—	50	ns	
SP52	Tsch2ssH, TscL2ssH	SSx after SCKx Edge	1.5 Tcy + 40	—	—	ns	

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** Assumes 50 pF load on all SPIx pins.

## APPENDIX A: REVISION HISTORY

### Revision A (December 2007)

Original data sheet for the PIC24FJ256GA110 family of devices.

### Revision B (February 2008)

Updates to [Section 28.0 “Electrical Characteristics”](#) and minor edits to text throughout document.

### Revision C (April 2009)

Updates to all Pin Diagrams to reflect the correct order of priority for multiplexed peripherals and adds the ASCK1 pin function.

Adds packaging information for the new 64-pin QFN package to [Section 29.0 “Packaging Information”](#) and the Product Information System.

Updates [Section 5.0 “Flash Program Memory”](#) with revised code examples in assembler and new code examples in C.

Updates [Section 6.2 “Device Reset Times”](#) with revised information, particularly [Table 6-3](#).

Adds the INTTREG register to [Section 4.0 “Memory Organization”](#) and [Section 7.0 “Interrupt Controller”](#).

Makes several additions and changes to [Section 10.0 “I/O Ports”](#), including:

- revision of [Section 10.4.2.1 “Peripheral Pin Select Function Priority”](#)
- addition of [Section 10.4.3.3 “Alternate Fixed Pin Mapping”](#)
- revisions to [Table 10-3](#), “Selectable Output Sources”
- addition of the ALTRP register (and in [Section 4.0 “Memory Organization”](#))

Updates [Section 15.0 “Serial Peripheral Interface \(SPI\)”](#) to include references to the ASCK1 pin function.

Updates [Section 20.0 “Programmable Cyclic Redundancy Check \(CRC\) Generator”](#) with new illustrations and a revised [Section 20.1 “User Interface”](#).

Updates [Section 21.0 “10-Bit High-Speed A/D Converter”](#) by changing all references to AD1CHS0 to AD1CHS (as well as other locations in the document). Also revises bit field descriptions in registers: AD1CON3 (bits 7:0) and AD1CHS (bits 12:8).

Makes minor text edits to bit descriptions in [Section 22.0 “Triple Comparator Module”](#) (Register 22-1) and [Section 24.0 “Charge Time Measurement Unit \(CTMU\)”](#) (Register 24-1).

Updates [Section 25.2 “On-Chip Voltage Regulator”](#) with revised text on the operation of the regulator during POR and Standby mode.

Updates [Section 25.5 “JTAG Interface”](#) to remove references to programming via the interface.

Makes multiple additions and changes to [Section 28.0 “Electrical Characteristics”](#), including:

- DC current characteristics for extended temperature operation (125°C)
- New DC characteristics of VBOR, VBG, TBG and ICNPD
- Addition of new VPEW specification for VDDCORE
- New AC characteristics for internal oscillator start-up time (TLPRC)
- Combination of all Internal RC Accuracy information into a single table

Makes other minor typographic corrections throughout the text.

### Revision D (December 2009)

Updates [Section 2.0 “Guidelines for Getting Started with 16-bit Microcontrollers”](#) with the most current version.

Corrects annotations to the CN70 pin function in [Table 4-4](#) of [Section 4.2.4 “SFR Space”](#).

Corrects annotations to remappable output function 30 in [Register 10-37](#) of [Section 10.4 “Peripheral Pin Select”](#).

Corrects the definitions for the WPEND and WFPF<7:0> Configuration bits in [Register 25-3](#) of [Section 25.1 “Configuration Bits”](#).

Updates [Section 28.0 “Electrical Characteristics”](#) with additional data for IDD at 60°C. Also corrects occurrences of “DISVREG” throughout the chapter, replacing them with “ENVREG” and the proper VDD/VSS connection information.

Makes other minor typographic corrections throughout the text.

### Revision E (November 2010)

Updated [Section 2.0 “Guidelines for Getting Started with 16-bit Microcontrollers”](#) with the most current version.

Updates to [Section 28.0 “Electrical Characteristics”](#) with tables being added and replaced from the FRM chapters.