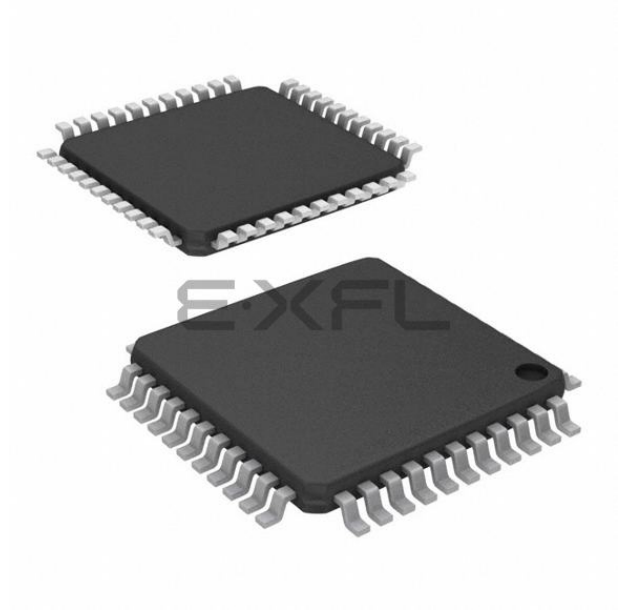

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	20MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	LVD, PWM, WDT
Number of I/O	37
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x12b; D/A 2x6b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mke02z16vld2

Table of Contents

1 Ordering parts

1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to **nxp.com** and perform a part number search for the following device numbers: KE02Z.

2 Part identification

2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

2.2 Format

Part numbers for this device have the following format:

Q KE## A FFF R T PP CC N

2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	• M = Fully qualified, general market flow • P = Prequalification
KE##	Kinetis family	• KE02
A	Key attribute	• Z = M0+ core
FFF	Program flash memory size	• 16 = 16 KB • 32 = 32 KB • 64 = 64 KB
R	Silicon revision	• (Blank) = Main • A = Revision after main

Table continues on the next page...

Table 3. DC characteristics (continued)

Symbol	C	Descriptions			Min	Typical[1]	Max	Unit
V_{OH}	P	Output high voltage	All I/O pins, except PTA2 and PTA3, standard-drive strength	5 V, I_{load} = –5 mA	V_{DD} – 0.8	—	—	V
	C			3 V, I_{load} = –2.5 mA	V_{DD} – 0.8	—	—	V
	P		High current drive pins, high-drive strength[2]	5 V, I_{load} = –20 mA	V_{DD} – 0.8	—	—	V
	C			3 V, I_{load} = –10 mA	V_{DD} – 0.8	—	—	V
I_{OHT}	D	Output high current	Max total I_{OH} for all ports	5 V	—	—	–100	mA
				3 V	—	—	–60	
V_{OL}	P	Output low voltage	All I/O pins, standard-drive strength	5 V, I_{load} = 5 mA	—	—	0.8	V
	C			3 V, I_{load} = 2.5 mA	—	—	0.8	V
	P		High current drive pins, high-drive strength[2]	5 V, I_{load} =20 mA	—	—	0.8	V
	C			3 V, I_{load} = 10 mA	—	—	0.8	V
I_{OLT}	D	Output low current	Max total I_{OL} for all ports	5 V	—	—	100	mA
				3 V	—	—	60	
V_{IH}	P	Input high voltage	All digital inputs	4.5≤V_{DD}<5.5 V	0.65 × V_{DD}	—	—	V
				2.7≤V_{DD}<4.5 V	0.70 × V_{DD}	—	—	
V_{IL}	P	Input low voltage	All digital inputs	4.5≤V_{DD}<5.5 V	—	—	0.35 × V_{DD}	V
				2.7≤V_{DD}<4.5 V	—	—	0.30 × V_{DD}	
V_{hys}	C	Input hysteresis	All digital inputs	—	0.06 × V_{DD}	—	—	mV
$\lvert I_{In} \rvert$	P	Input leakage current	Per pin (pins in high impedance input mode)	V_{IN} = V_{DD} or V_{SS}	—	0.1	1	µA
$\lvert I_{INTOT} \rvert$	C	Total leakage combined for all port pins	Pins in high impedance input mode	V_{IN} = V_{DD} or V_{SS}	—	—	2	µA
R_{PU}	P	Pullup resistors	All digital inputs, when enabled (all I/O pins other than PTA2 and PTA3)	—	30.0	—	50.0	kΩ
R_{PU}[3]	P	Pullup resistors	PTA2 and PTA3 pins	—	30.0	—	60.0	kΩ
I_{IC}	D	DC injection current[4, 5, 6]	Single pin limit	V_{IN} < V_{SS}, V_{IN} > V_{DD}	-2	—	2	mA
			Total MCU limit, includes sum of all stressed pins		-5	—	25	
C_{In}	C	Input capacitance, all pins		—	—	—	7	pF
V_{RAM}	C	RAM retention voltage		—	2.0	—	—	V

1. Typical values are measured at 25 °C. Characterized, not tested.
2. Only PTB4, PTB5, PTD0, PTD1, PTE0, PTE1, PTH0, and PTH1 support high current output.

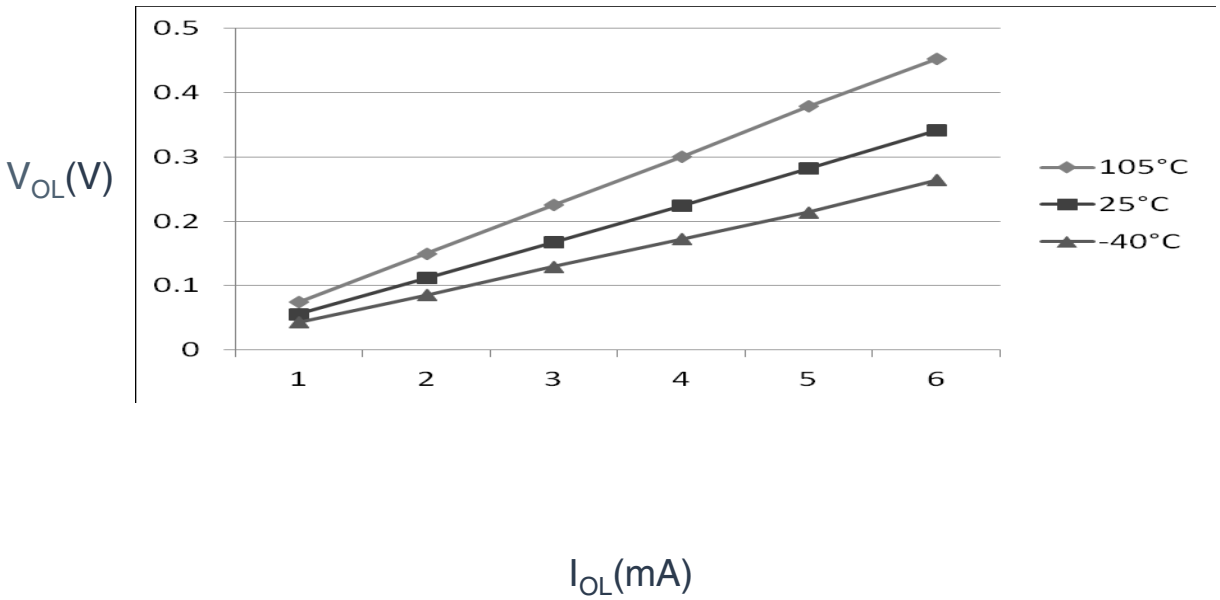


Figure 5. Typical V_{OL} Vs. I_{OL} (standard drive strength) (V_{DD} = 5 V)

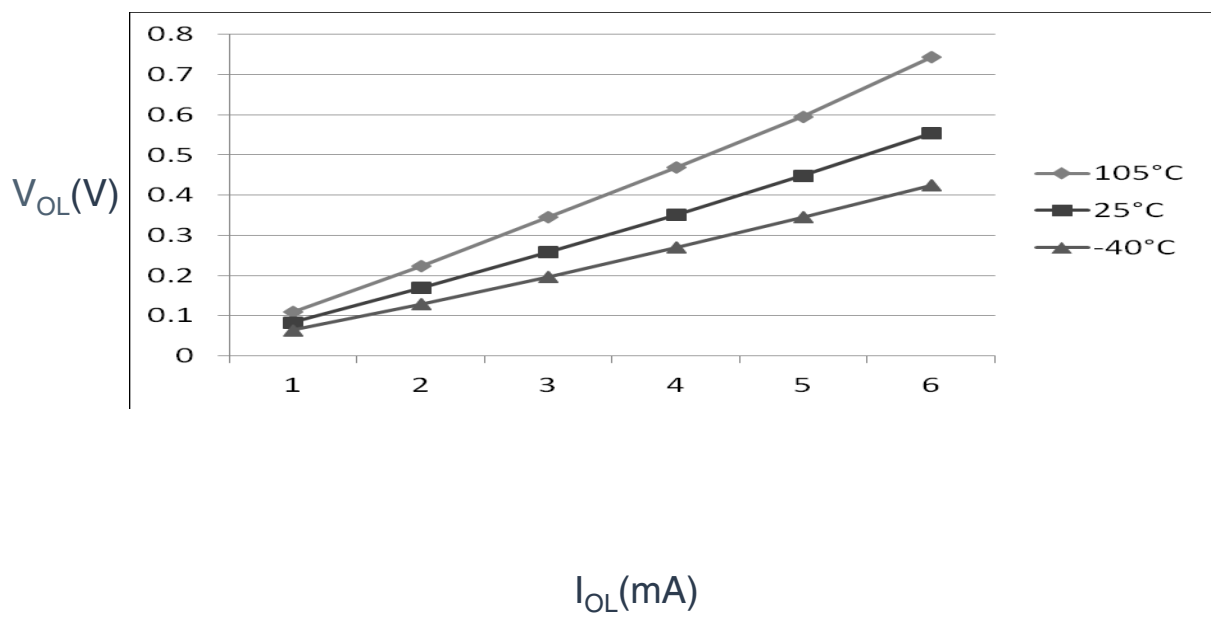


Figure 6. Typical V_{OL} Vs. I_{OL} (standard drive strength) (V_{DD} = 3 V)

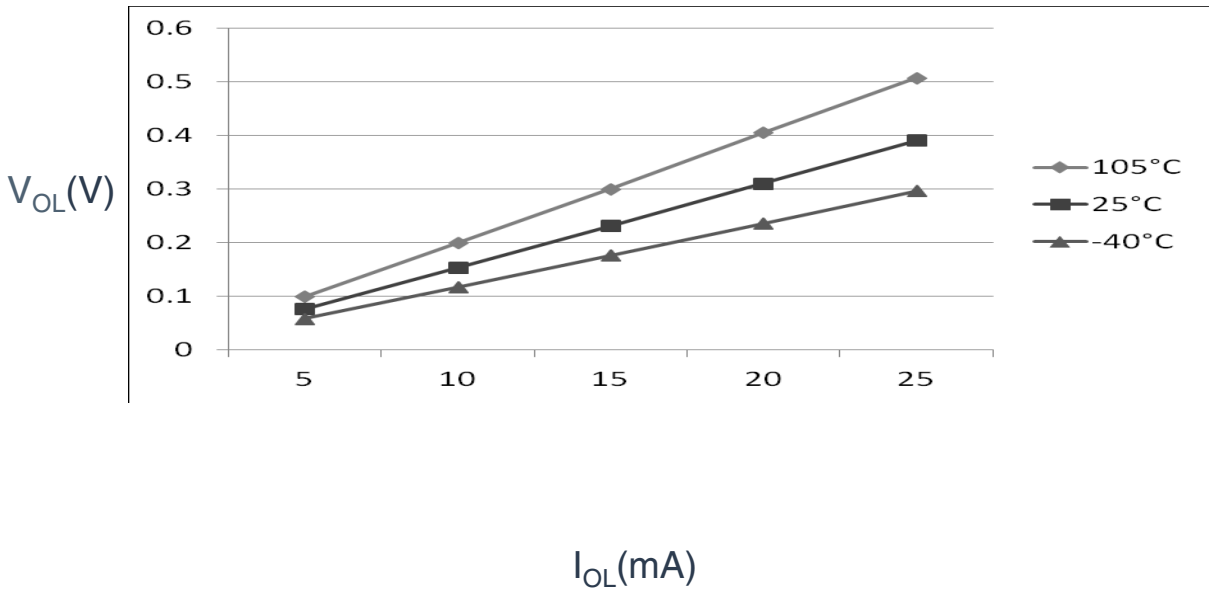


Figure 7. Typical V_{OL} Vs. I_{OL} (high drive strength) (V_{DD} = 5 V)

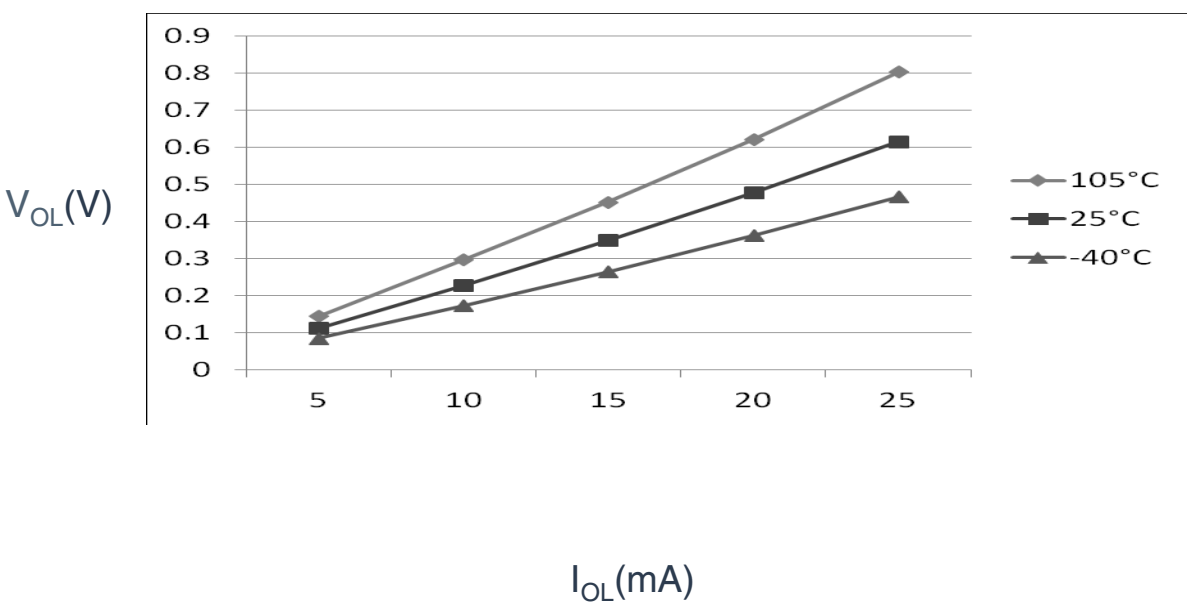


Figure 8. Typical V_{OL} Vs. I_{OL} (high drive strength) (V_{DD} = 3 V)

Table 5. Supply current characteristics (continued)

C	Parameter	Symbol	Core/Bus Freq	V_{DD} (V)	Typical[1]	Max[2]	Unit	Temp
C	ADC adder to Stop ADLPC = 1 ADLSMP = 1 ADCO = 1	—	—	5	86 (64-, 44-pin packages) 42 (32-pin package)	—	µA	–40 to 105 °C
C	MODE = 10B ADICLK = 11B			3	82 (64-, 44-pin packages) 41 (32-pin package)	—		
C	ACMP adder to Stop	—	—	5	12	—	µA	–40 to 105 °C
C				3	12	—		
C	LVD adder to stop[4]	—	—	5	128	—	µA	–40 to 105 °C
C				3	124	—		

1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
2. The Max current is observed at high temperature of 105 °C.
3. RTC adder causes I_{DD} to increase typically by less than 1 µA; RTC clock source is 1 kHz LPO clock.
4. LVD is periodically woken up from Stop by 5% duty cycle. The period is equal to or less than 2 ms.

5.1.3 EMC performance

Electromagnetic compatibility (EMC) performance is highly dependent on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation play a significant role in EMC performance. The system designer must consult the following applications notes, available on **nxp.com** for advice and guidance specifically targeted at optimizing EMC performance.

- AN2321: Designing for Board Level Electromagnetic Compatibility
- AN1050: Designing for Electromagnetic Compatibility (EMC) with HCMOS Microcontrollers
- AN1263: Designing for Electromagnetic Compatibility with Single-Chip Microcontrollers
- AN2764: Improving the Transient Immunity Performance of Microcontroller-Based Applications
- AN1259: System Design and Layout Techniques for Noise Reduction in MCU-Based Systems

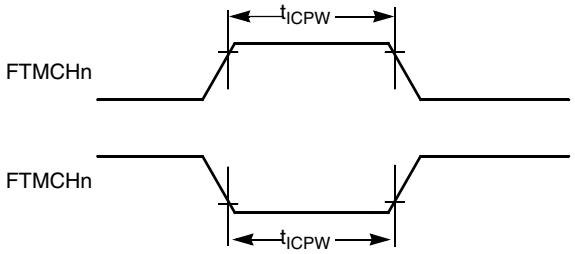


Figure 12. Timer input capture pulse

5.3 Thermal specifications

5.3.1 Thermal operating requirements

Table 9. Thermal operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
T_J	Die junction temperature	–40	125	°C	
T_A	Ambient temperature	–40	105	°C	1

1. Maximum T_A can be exceeded only if the user ensures that T_J does not exceed maximum T_J. The simplest method to determine T_J is: $T_J = T_A + \theta_{JA}$ x chip power dissipation

5.3.2 Thermal characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

Table 10. Thermal attributes

Board type	Symbol	Description	64 LQFP	64 QFP	44 LQFP	32 LQFP	Unit	Notes
Single-layer (1S)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	71	61	75	86	°C/W	1, 2
Four-layer (2s2p)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	53	47	53	57	°C/W	1, 3

Table continues on the next page...

Table 10. Thermal attributes (continued)

Board type	Symbol	Description	64 LQFP	64 QFP	44 LQFP	32 LQFP	Unit	Notes
Single-layer (1S)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	59	50	62	72	°C/W	1, 3
Four-layer (2s2p)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	46	41	47	51	°C/W	1, 3
—	$R_{\theta JB}$	Thermal resistance, junction to board	35	32	34	33	°C/W	4
—	$R_{\theta JC}$	Thermal resistance, junction to case	20	23	20	24	°C/W	5
—	Ψ_{JT}	Thermal characterization parameter, junction to package top outside center (natural convection)	5	8	5	6	°C/W	6

1. Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
2. Per JEDEC JESD51-2 with the single layer board (JESD51-3) horizontal.
3. Per JEDEC JESD51-6 with the board (JESD51-7) horizontal.
4. Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
5. Thermal resistance between the die and the solder pad on the bottom of the package. Interface resistance is ignored.
6. Thermal characterization parameter indicating the temperature difference between package top and the junction temperature per JEDEC JESD51-2. When Greek letters are not available, the thermal characterization.

The average chip-junction temperature (T_J) in °C can be obtained from:

$$T_J = T_A + (P_D \times \theta_{JA})$$

Where:

T_A = Ambient temperature, °C

θ_{JA} = Package thermal resistance, junction-to-ambient, °C/W

$P_D = P_{int} + P_{I/O}$

$P_{int} = I_{DD} \times V_{DD}$, Watts - chip internal power

$P_{I/O}$ = Power dissipation on input and output pins - user determined

For most applications, $P_{I/O} << P_{int}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$$P_D = K \div (T_J + 273\ °C)$$

Solving the equations above for K gives:

$$K = P_D \times (T_A + 273\ °C) + \theta_{JA} \times (P_D)^2$$

where K is a constant pertaining to the particular part. K can be determined by measuring P_D (at equilibrium) for an known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving the above equations iteratively for any value of T_A.

6 Peripheral operating requirements and behaviors

6.1 Core modules

6.1.1 SWD electricals

Table 11. SWD full voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	2.7	5.5	V
J1	SWD_CLK frequency of operation • Serial wire debug	0	20	MHz
J2	SWD_CLK cycle period	1/J1	—	ns
J3	SWD_CLK clock pulse width • Serial wire debug	20	—	ns
J4	SWD_CLK rise and fall times	—	3	ns
J9	SWD_DIO input data setup time to SWD_CLK rise	10	—	ns
J10	SWD_DIO input data hold time after SWD_CLK rise	3	—	ns
J11	SWD_CLK high to SWD_DIO data valid	—	35	ns
J12	SWD_CLK high to SWD_DIO high-Z	5	—	ns

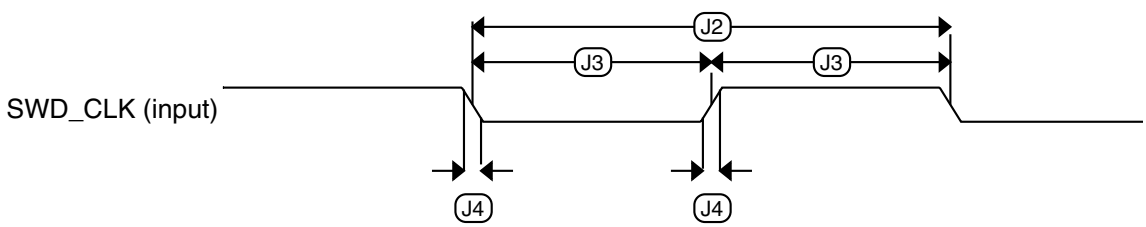


Figure 13. Serial wire clock input timing

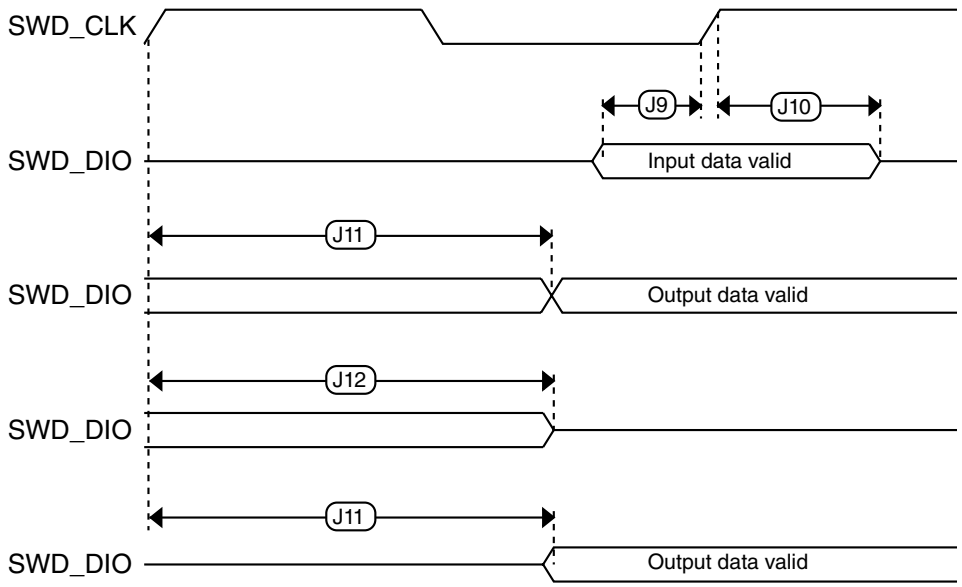


Figure 14. Serial wire data timing

6.2 External oscillator (OSC) and ICS characteristics

Table 12. OSC and ICS specifications (temperature range = -40 to 105 °C ambient)

Num	C	Characteristic		Symbol	Min	Typical[1]	Max	Unit
1	C	Crystal or resonator frequency	Low range (RANGE = 0)	f_{lo}	31.25	32.768	39.0625	kHz
	C		High range (RANGE = 1)	f_{hi}	4	—	20	MHz
2	D	Load capacitors		C1, C2	See Note[2]			
3	D	Feedback resistor	Low Frequency, Low-Power Mode[3]	R_F	—	—	—	MΩ
			Low Frequency, High-Gain Mode		—	10	—	MΩ
			High Frequency, Low-Power Mode		—	1	—	MΩ
			High Frequency, High-Gain Mode		—	1	—	MΩ
4	D	Series resistor - Low Frequency	Low-Power Mode [3]	R_S	—	0	—	kΩ
			High-Gain Mode		—	200	—	kΩ
5	D	Series resistor - High Frequency	Low-Power Mode[3]	R_S	—	0	—	kΩ

Table continues on the next page...

Table 12. OSC and ICS specifications (temperature range = -40 to 105 °C ambient) (continued)

Num	C	Characteristic		Symbol	Min	Typical[1]	Max	Unit
	D	Series resistor - High Frequency, High-Gain Mode	4 MHz		—	0	—	kΩ
	D		8 MHz		—	0	—	kΩ
	D		16 MHz		—	0	—	kΩ
6	C	Crystal start-up time low range = 32.768 kHz crystal; High range = 20 MHz crystal[4,5]	Low range, low power	t_{CSTL}	—	1000	—	ms
	C		Low range, high gain		—	800	—	ms
	C		High range, low power	t_{CSTH}	—	3	—	ms
	C		High range, high gain		—	1.5	—	ms
7	T	Internal reference start-up time		t_{IRST}	—	20	50	µs
8	P	Internal reference clock (IRC) frequency trim range		f_{int_t}	31.25	—	39.0625	kHz
9	P	Internal reference clock frequency, factory trimmed,	T = 25 °C, V_{DD} = 5 V	f_{int_ft}	—	31.25	—	kHz
10	P	DCO output frequency range	FLL reference = fint_t, flo, or fhi/RDIV	f_{dco}	16	—	20	MHz
11	P	Factory trimmed internal oscillator accuracy	T = 25 °C, V_{DD} = 5 V	Δf_{int_ft}	-0.5	—	0.5	%
12	C	Deviation of IRC over temperature when trimmed at T = 25 °C, V_{DD} = 5 V	Over temperature range from -40 °C to 105°C	Δf_{int_t}	-1	—	0.5	%
			Over temperature range from 0 °C to 105°C	Δf_{int_t}	-0.5	—	0.5	
13	C	Frequency accuracy of DCO output using factory trim value	Over temperature range from -40 °C to 105°C	Δf_{dco_ft}	-1.5	—	1	%
			Over temperature range from 0 °C to 105°C	Δf_{dco_ft}	-1	—	1	
14	C	FLL acquisition time[4,6]		$t_{Acquire}$	—	—	2	ms
15	C	Long term jitter of DCO output clock (averaged over 2 ms interval)[7]		C_{Jitter}	—	0.02	0.2	$\%f_{dco}$

1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
2. See crystal or resonator manufacturer's recommendation.
3. Load capacitors (C_1,C_2), feedback resistor (R_F) and series resistor (R_S) are incorporated internally when RANGE = HGO = 0.
4. This parameter is characterized and not tested on each device.
5. Proper PC board layout procedures must be followed to achieve specifications.
6. This specification applies to any time the FLL reference source or reference divider is changed, trim value changed, or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
7. Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{Bus}. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DD} and V_{SS} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

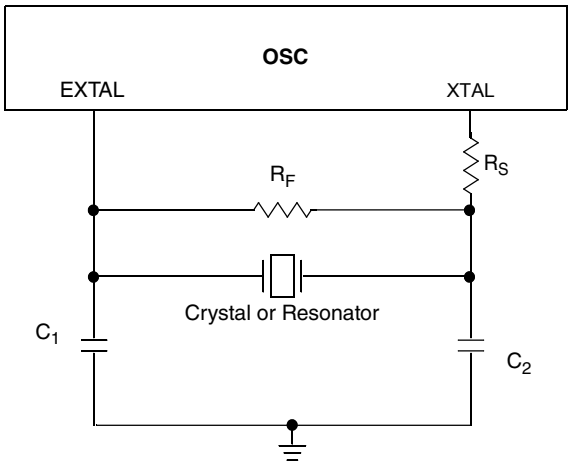


Figure 15. Typical crystal or resonator circuit

6.3 NVM specifications

This section provides details about program/erase times and program/erase endurance for the flash and EEPROM memories.

Table 13. Flash and EEPROM characteristics

C	Characteristic	Symbol	Min[1]	Typical[2]	Max[3]	Unit[4]
D	Supply voltage for program/erase –40 °C to 105 °C	$V_{prog/erase}$	2.7	—	5.5	V
D	Supply voltage for read operation	V_{Read}	2.7	—	5.5	V
D	NVM Bus frequency	f_{NVMBUS}	1	—	25	MHz
D	NVM Operating frequency	f_{NVMOP}	0.8	1	1.05	MHz
D	Erase Verify All Blocks	t_{VFYALL}	—	—	17338	t_{cyc}
D	Erase Verify Flash Block	t_{RD1BLK}	—	—	16913	t_{cyc}
D	Erase Verify EEPROM Block	t_{RD1BLK}	—	—	810	t_{cyc}
D	Erase Verify Flash Section	t_{RD1SEC}	—	—	484	t_{cyc}
D	Erase Verify EEPROM Section	$t_{DRD1SEC}$	—	—	555	t_{cyc}
D	Read Once	t_{RDONCE}	—	—	450	t_{cyc}
D	Program Flash (2 word)	t_{PGM2}	0.12	0.12	0.29	ms
D	Program Flash (4 word)	t_{PGM4}	0.20	0.21	0.46	ms
D	Program Once	$t_{PGMONCE}$	0.20	0.21	0.21	ms
D	Program EEPROM (1 Byte)	t_{DPGM1}	0.10	0.10	0.27	ms
D	Program EEPROM (2 Byte)	t_{DPGM2}	0.17	0.18	0.43	ms
D	Program EEPROM (3 Byte)	t_{DPGM3}	0.25	0.26	0.60	ms
D	Program EEPROM (4 Byte)	t_{DPGM4}	0.32	0.33	0.77	ms
D	Erase All Blocks	t_{ERSALL}	96.01	100.78	101.49	ms
D	Erase Flash Block	t_{ERSBLK}	95.98	100.75	101.44	ms

Table continues on the next page...

Table 13. Flash and EEPROM characteristics (continued)

C	Characteristic	Symbol	Min[1]	Typical[2]	Max[3]	Unit[4]
D	Erase Flash Sector	t_{ERSPG}	19.10	20.05	20.08	ms
D	Erase EEPROM Sector	t_{DERSPG}	4.81	5.05	20.57	ms
D	Unsecure Flash	t_{UNSECU}	96.01	100.78	101.48	ms
D	Verify Backdoor Access Key	t_{VFYKEY}	—	—	464	t_{cyc}
D	Set User Margin Level	t_{MLOADU}	—	—	407	t_{cyc}
C	FLASH Program/erase endurance T_L to T_H = -40 °C to 105 °C	n_{FLPE}	10 k	100 k	—	Cycles
C	EEPROM Program/erase endurance TL to TH = -40 °C to 105 °C	n_{FLPE}	50 k	500 k	—	Cycles
C	Data retention at an average junction temperature of T_{Javg} = 85°C after up to 10,000 program/erase cycles	t_{D_ret}	15	100	—	years

1. Minimum times are based on maximum f_{NVMOP} and maximum f_{NVMBUS}
2. Typical times are based on typical f_{NVMOP} and maximum f_{NVMBUS}
3. Maximum times are based on typical f_{NVMOP} and typical f_{NVMBUS} plus aging
4. $t_{cyc} = 1 / f_{NVMBUS}$

Program and erase operations do not require any special power sources other than the normal V_{DD} supply. For more detailed information about program/erase operations, see the Flash Memory Module section in the reference manual.

6.4 Analog

6.4.1 ADC characteristics

Table 14. 5 V 12-bit ADC operating conditions

Characteristic	Conditions	Symbol	Min	Typ[1]	Max	Unit	Comment
Reference potential	• Low • High	V_{REFL} V_{REFH}	V_{SSA} V_{DDA}	— —	V_{SSA} V_{DDA}	V	—
Supply voltage	Absolute	V_{DDA}	2.7	—	5.5	V	—
	Delta to V_{DD} (V_{DD}-V_{DDA})	ΔV_{DDA}	-100	0	+100	mV	—
Ground voltage	Delta to V_{SS} (V_{SS}-V_{SSA})	ΔV_{SSA}	-100	0	+100	mV	—
Input voltage		V_{ADIN}	V_{REFL}	—	V_{REFH}	V	—
Input capacitance		C_{ADIN}	—	4.5	5.5	pF	—

Table continues on the next page...

Table 15. 12-bit ADC characteristics (V_{REFH} = V_{DDA}, V_{REFL} = V_{SSA}) (continued)

Characteristic	Conditions	C	Symbol	Min	Typ[1]	Max	Unit
	8-bit mode	T		—	±0.5	±1.0	
Quantization error	≤12 bit modes	D	E_Q	—	—	±0.5	LSB[4]
Input leakage error[8]	all modes	D	E_{IL}	I_{In} * R_{AS}			mV
Temp sensor slope	-40 °C–25 °C	D	m	—	3.266	—	mV/°C
	25 °C–125 °C			—	3.638	—	
Temp sensor voltage	25 °C	D	V_{TEMP25}	—	1.396	—	V

1. Typical values assume V_{DDA} = 5.0 V, Temp = 25 °C, f_{ADCK}=1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. Includes quantization
3. This parameter is valid for the temperature range of 25 °C to 50 °C.
4. 1 LSB = (V_{REFH} - V_{REFL})/2^N
5. Monotonicity and no-missing-codes guaranteed in 10-bit and 8-bit modes
6. V_{ADIN} = V_{SSA}
7. V_{ADIN} = V_{DDA}
8. I_{In} = leakage current (refer to DC characteristics)

6.4.2 Analog comparator (ACMP) electricals

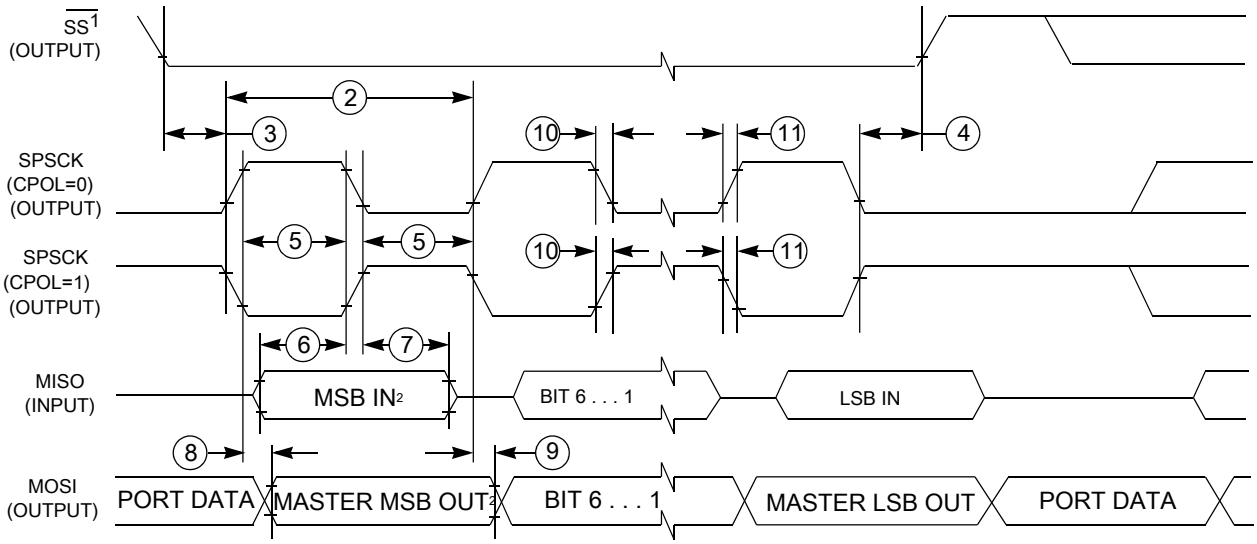
Table 16. Comparator electrical specifications

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage	V_{DDA}	2.7	—	5.5	V
T	Supply current (Operation mode)	I_{DDA}	—	10	20	µA
D	Analog input voltage	V_{AIN}	V_{SS} - 0.3	—	V_{DDA}	V
P	Analog input offset voltage	V_{AIO}	—	—	40	mV
C	Analog comparator hysteresis (HYST=0)	V_H	—	15	20	mV
C	Analog comparator hysteresis (HYST=1)	V_H	—	20	30	mV
T	Supply current (Off mode)	I_{DDAOFF}	—	60	—	nA
C	Propagation Delay	t_D	—	0.4	1	µs

6.5 Communication interfaces

6.5.1 SPI switching specifications

The serial peripheral interface (SPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The following tables provide timing characteristics for classic SPI timing modes. See the SPI chapter of the chip's reference manual for information about the modified transfer formats used for



1.If configured as output

2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 18. SPI master mode timing (CPHA=1)

Table 18. SPI slave mode timing

Num.	Symbol	Description	Min.	Max.	Unit	Comment
1	f_{op}	Frequency of operation	0	$f_{Bus}/4$	Hz	f_{Bus} is the bus clock as defined in Control timing.
2	t_{SPSCK}	SPSCK period	4 x t_{Bus}	—	ns	$t_{Bus} = 1/f_{Bus}$
3	t_{Lead}	Enable lead time	1	—	t_{Bus}	—
4	t_{Lag}	Enable lag time	1	—	t_{Bus}	—
5	t_{WSPSCK}	Clock (SPSCK) high or low time	t_{Bus} - 30	—	ns	—
6	t_{SU}	Data setup time (inputs)	15	—	ns	—
7	t_{HI}	Data hold time (inputs)	25	—	ns	—
8	t_a	Slave access time	—	t_{Bus}	ns	Time to data active from high-impedance state
9	t_{dis}	Slave MISO disable time	—	t_{Bus}	ns	Hold time to high-impedance state
10	t_v	Data valid (after SPSCK edge)	—	25	ns	—
11	t_{HO}	Data hold time (outputs)	0	—	ns	—
12	t_{RI}	Rise time input	—	t_{Bus} - 25	ns	—
	t_{FI}	Fall time input				
13	t_{RO}	Rise time output	—	25	ns	—
	t_{FO}	Fall time output				

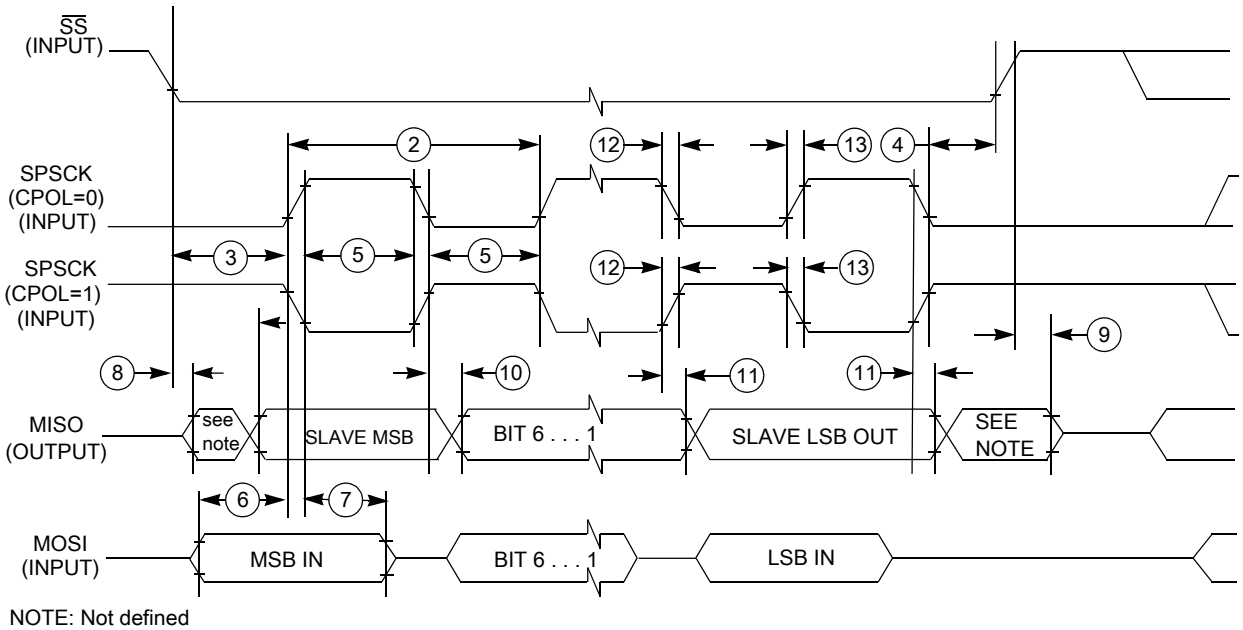


Figure 19. SPI slave mode timing (CPHA = 0)

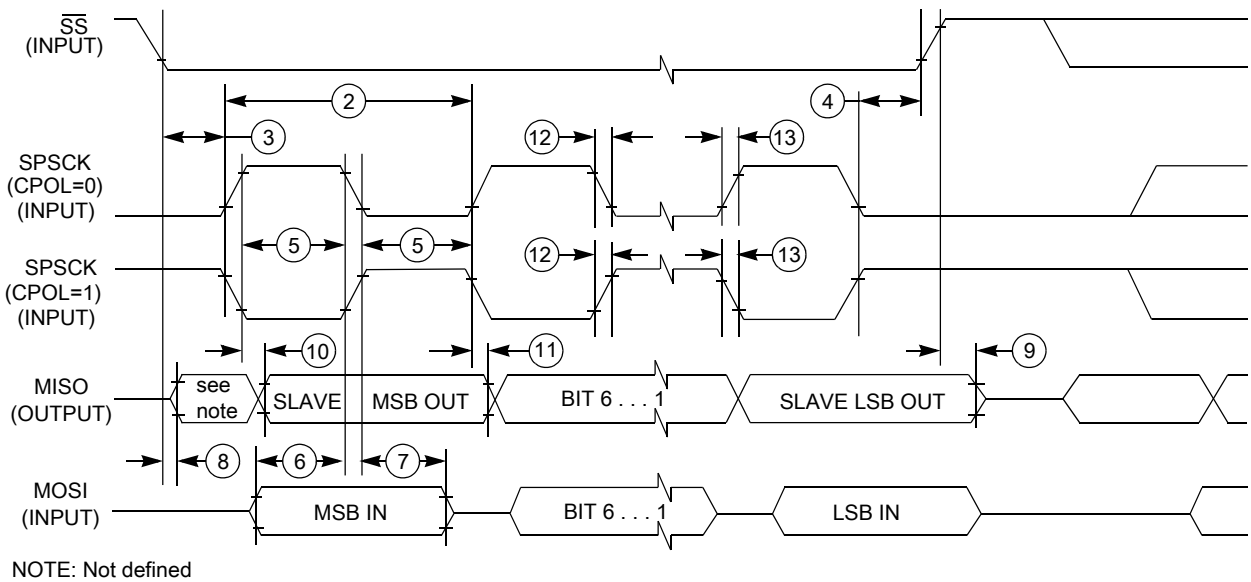


Figure 20. SPI slave mode timing (CPHA=1)

7 Dimensions

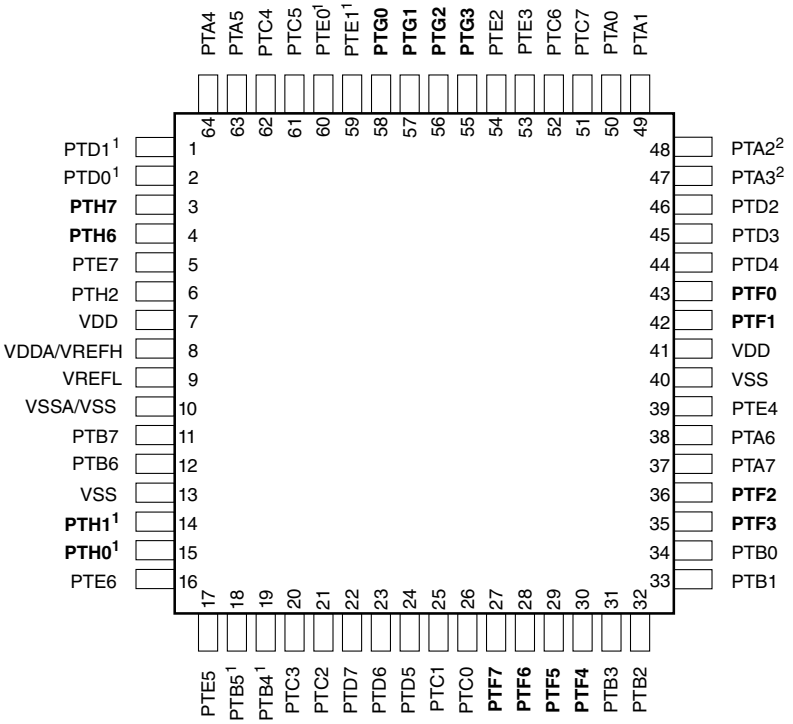
7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

Table 19. Pin availability by package pin-count (continued)

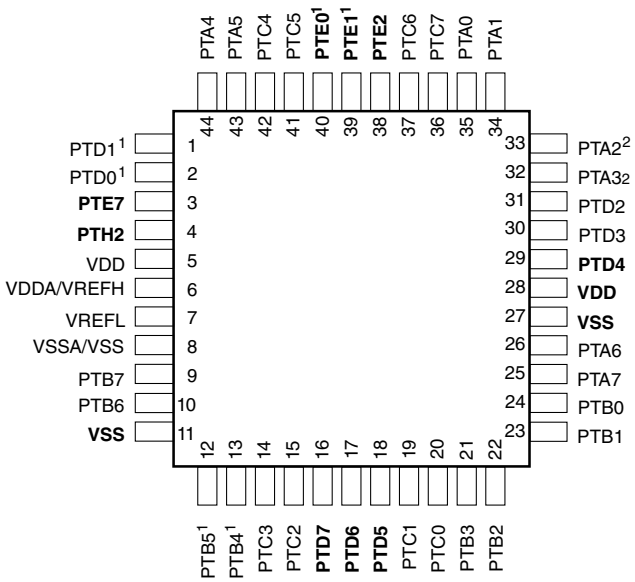
Pin Number			Lowest Priority <-- --> Highest				
64-QFP/ LQFP	44-LQFP	32-LQFP	Port Pin	Alt 1	Alt 2	Alt 3	Alt 4
19	13	10	PTB4[1]	FTM2_CH4	SPI0_MISO	$\overline{\text{NMI}}$	ACMP1_IN2
20	14	11	PTC3	FTM2_CH3	—	—	ADC0_SE11
21	15	12	PTC2	FTM2_CH2	—	—	ADC0_SE10
22	16	—	PTD7	KBI1_P7	UART2_TX	—	—
23	17	—	PTD6	KBI1_P6	UART2_RX	—	—
24	18	—	PTD5	KBI1_P5	—	—	—
25	19	13	PTC1	—	FTM2_CH1	—	ADC0_SE9
26	20	14	PTC0	—	FTM2_CH0	—	ADC0_SE8
27	—	—	PTF7	—	—	—	ADC0_SE15
28	—	—	PTF6	—	—	—	ADC0_SE14
29	—	—	PTF5	—	—	—	ADC0_SE13
30	—	—	PTF4	—	—	—	ADC0_SE12
31	21	15	PTB3	KBI0_P7	SPI0_MOSI	FTM0_CH1	ADC0_SE7
32	22	16	PTB2	KBI0_P6	SPI0_SCK	FTM0_CH0	ADC0_SE6
33	23	17	PTB1	KBI0_P5	UART0_TX	—	ADC0_SE5
34	24	18	PTB0	KBI0_P4	UART0_RX	—	ADC0_SE4
35	—	—	PTF3	—	—	—	—
36	—	—	PTF2	—	—	—	—
37	25	19	PTA7	—	FTM2_FLT2	ACMP1_IN1	ADC0_SE3
38	26	20	PTA6	—	FTM2_FLT1	ACMP1_IN0	ADC0_SE2
39	—	—	PTE4	—	—	—	—
40	27	—	—	—	—	—	VSS
41	28	—	—	—	—	—	VDD
42	—	—	PTF1	—	—	—	—
43	—	—	PTF0	—	—	—	—
44	29	—	PTD4	KBI1_P4	—	—	—
45	30	21	PTD3	KBI1_P3	SPI1_PCS0	—	—
46	31	22	PTD2	KBI1_P2	SPI1_MISO	—	—
47	32	23	PTA3[4]	KBI0_P3	UART0_TX	I2C0_SCL	—
48	33	24	PTA2[4]	KBI0_P2	UART0_RX	I2C0_SDA	—
49	34	25	PTA1	KBI0_P1	FTM0_CH1	ACMP0_IN1	ADC0_SE1
50	35	26	PTA0	KBI0_P0	FTM0_CH0	ACMP0_IN0	ADC0_SE0
51	36	27	PTC7	—	UART1_TX	—	—
52	37	28	PTC6	—	UART1_RX	—	—
53	—	—	PTE3	—	SPI0_PCS0	—	—
54	38	—	PTE2	—	SPI0_MISO	—	—
55	—	—	PTG3	—	—	—	—
56	—	—	PTG2	—	—	—	—

Table continues on the next page...



Pins in **bold** are not available on less pin-count packages.
1. High source/sink current pins
2. True open drain pins

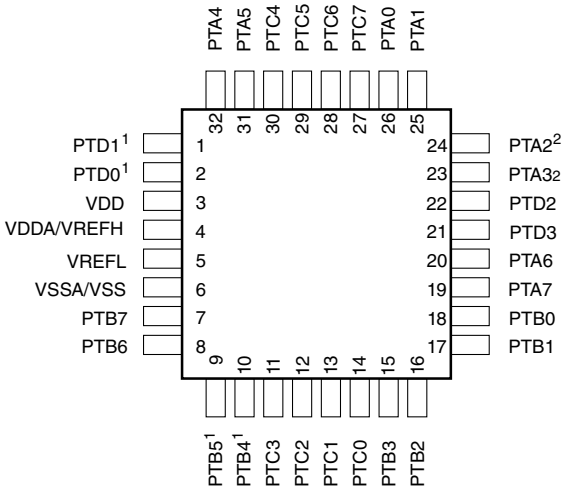
Figure 21. 64-pin QFP/LQFP packages



Pins in **bold** are not available on less pin-count packages.

1. High source/sink current pins
2. True open drain pins

Figure 22. 44-pin LQFP package



1. High source/sink current pins
2. True open drain pins

Figure 23. 32-pin LQFP package

9 Revision history

The following table provides a revision history for this document.

Table 20. Revision history

Rev. No.	Date	Substantial Changes
3	07/2013	Initial public release.
4	10/2014	• Updated all the V_{DDAD} to V_{DDA}, V_{SSAD} to V_{SSA} • Updated the features of OSC, ICS, UART, KBI and ADC in the front page • Updated I_{LAT} and V_{CDM} in the ESD handling ratings • Added V_{IN} and removed V_{DIO}, V_{AIO} in the Voltage and current operating ratings • Updated DC characteristics • Added the item of ACMP adder to Stop and a note to the Max. in Supply current characteristics • Added EMC radiated emissions operating behaviors • Added f_{Sys} and a note to t_{IHIL} in the Control timing • Added a new section of Thermal operating requirements • Updated J1, J10 and J11 in the SWD electricals • Updated External oscillator (OSC) and ICS characteristics • Added reference potential and a note to the E_{TUE} and E_{ZS} in ADC characteristics • Updated SPI switching specifications
5	07/2016	• Updated the Typical value of E_{TUE} in 12-bit mode and added a note to the 12-bit mode of E_{TUE} and INL in the ADC characteristics.

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