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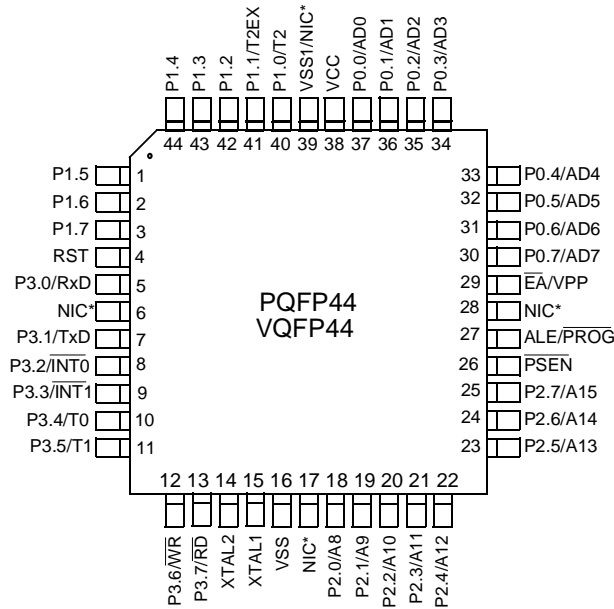
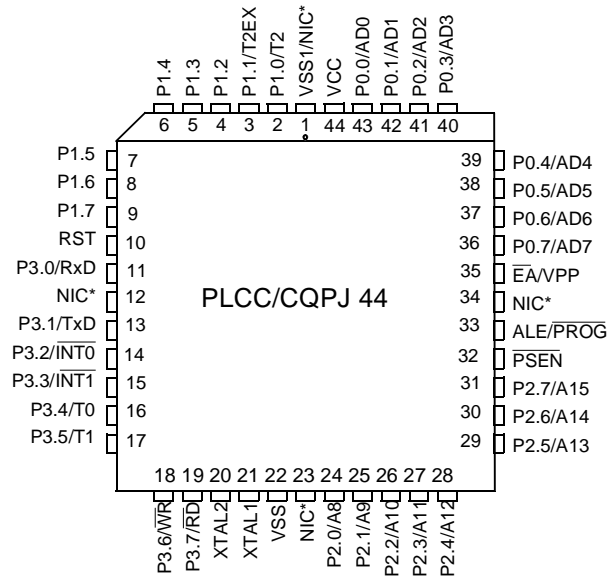
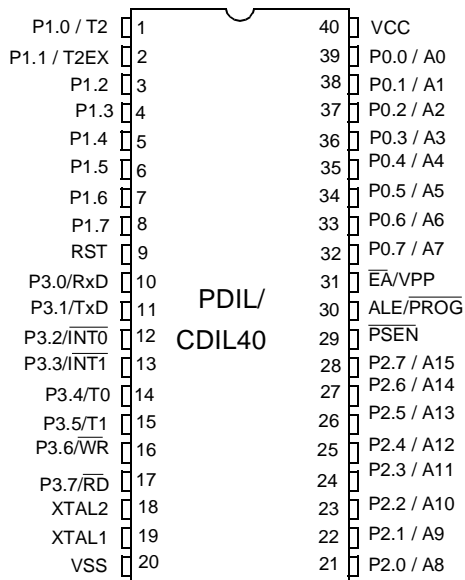
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	80C51
Core Size	8-Bit
Speed	40/20MHz
Connectivity	UART/USART
Peripherals	POR
Number of I/O	32
Program Memory Size	-
Program Memory Type	ROMless
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	44-PLCC (16.6x16.6)
Purchase URL	https://www.e-xfl.com/product-detail/atmel/at80c32x2-slrum

Pin Configuration



*NIC: No Internal Connection

Mnemonic	Pin Number			Type	Name and Function
	DIL	LCC	VQFP 1.4		
V _{SS}	20	22	16	I	Ground: 0V reference
V _{SS1}		1	39	I	Optional Ground: Contact the Sales Office for ground connection.
V _{CC}	40	44	38	I	Power Supply: This is the power supply voltage for normal, idle and power-down operation
P0.0-P0.7	39-32	43-36	37-30	I/O	Port 0: Port 0 is an open-drain, bidirectional I/O port. Port 0 pins that have 1s written to them float and can be used as high impedance inputs. Port 0 pins must be polarized to V _{CC} or V _{SS} in order to prevent any parasitic current consumption. Port 0 is also the multiplexed low-order address and data bus during access to external program and data memory. In this application, it uses strong internal pull-up when emitting 1s. Port 0 also inputs the code bytes during EPROM programming. External pull-ups are required during program verification during which P0 outputs the code bytes.
P1.0-P1.7	1-8	2-9	40-44 1-3	I/O	Port 1: Port 1 is an 8-bit bidirectional I/O port with internal pull-ups. Port 1 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 1 pins that are externally pulled low will source current because of the internal pull-ups. Port 1 also receives the low-order address byte during memory programming and verification. Alternate functions for Port 1 include:
	1	2	40	I/O	T2 (P1.0): Timer/Counter 2 external count input/Clockout
	2	3	41	I	T2EX (P1.1): Timer/Counter 2 Reload/Capture/Direction Control
P2.0-P2.7	21-28	24-31	18-25	I/O	Port 2: Port 2 is an 8-bit bidirectional I/O port with internal pull-ups. Port 2 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 2 pins that are externally pulled low will source current because of the internal pull-ups. Port 2 emits the high-order address byte during fetches from external program memory and during accesses to external data memory that use 16-bit addresses (MOVX atDPTR). In this application, it uses strong internal pull-ups emitting 1s. During accesses to external data memory that use 8-bit addresses (MOVX atRi), port 2 emits the contents of the P2 SFR. Some Port 2 pins receive the high order address bits during EPROM programming and verification: P2.0 to P2.4
P3.0-P3.7	10-17	11, 13-19	5, 7-13	I/O	Port 3: Port 3 is an 8-bit bidirectional I/O port with internal pull-ups. Port 3 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 3 pins that are externally pulled low will source current because of the internal pull-ups. Port 3 also serves the special features of the 80C51 family, as listed below.
	10	11	5	I	RXD (P3.0): Serial input port
	11	13	7	O	TXD (P3.1): Serial output port
	12	14	8	I	INT0 (P3.2): External interrupt 0

TS80C52X2 Enhanced Features

In comparison to the original 80C52, the TS80C52X2 implements some new features, which are:

- The X2 option
- The Dual Data Pointer
- The 4 level interrupt priority system
- The power-off flag
- The ONCE mode
- The ALE disabling
- Some enhanced features are also located in the UART and the Timer 2

X2 Feature

The TS80C52X2 core needs only 6 clock periods per machine cycle. This feature called "X2" provides the following advantages:

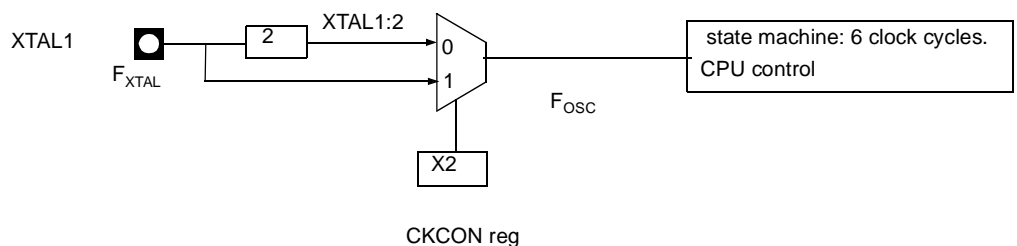
- Divide frequency crystals by 2 (cheaper crystals) while keeping same CPU power
- Save power consumption while keeping same CPU power (oscillator power saving)
- Save power consumption by dividing dynamically operating frequency by 2 in operating and idle modes
- Increase CPU power by 2 while keeping same crystal frequency

In order to keep the original C51 compatibility, a divider by 2 is inserted between the XTAL1 signal and the main clock input of the core (phase generator). This divider may be disabled by software.

Description

The clock for the whole circuit and peripheral is first divided by two before being used by the CPU core and peripherals. This allows any cyclic ratio to be accepted on XTAL1 input. In X2 mode, as this divider is bypassed, the signals on XTAL1 must have a cyclic ratio between 40 to 60%. Figure 1. shows the clock generation block diagram. X2 bit is validated on XTAL1÷2 rising edge to avoid glitches when switching from X2 to STD mode. Figure 2 shows the mode switching waveforms.

Figure 1. Clock Generation Diagram



Dual Data Pointer Register (Ddptr)

The additional data pointer can be used to speed up code execution and reduce code size in a number of ways.

The dual DPTR structure is a way by which the chip will specify the address of an external data memory location. There are two 16-bit DPTR registers that address the external memory, and a single bit called DPS = AUXR1/bit0 (See Table 5.) that allows the program code to switch between them (Refer to Figure 3).

Figure 3. Use of Dual Pointer

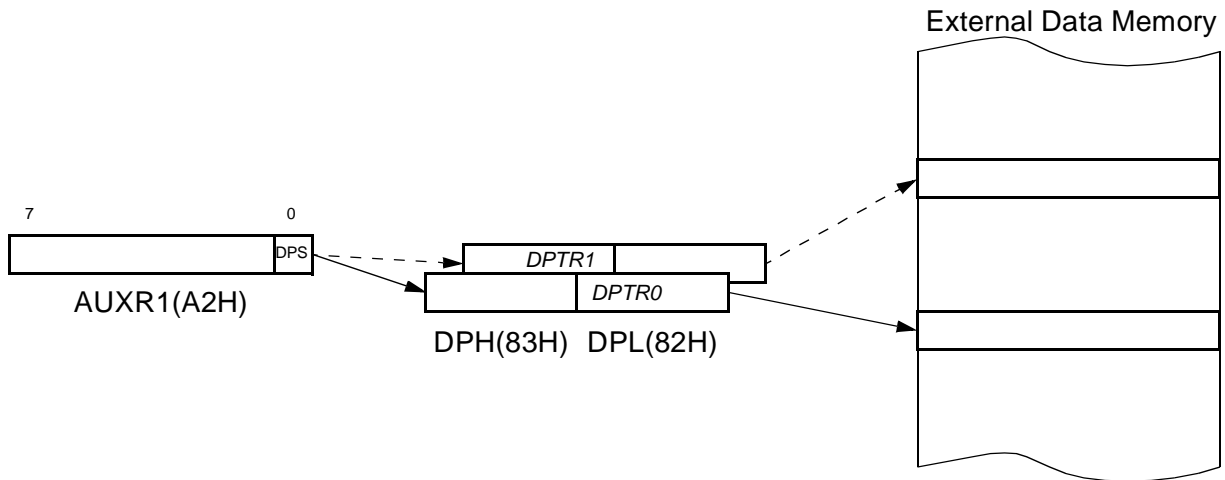


Table 4. AUXR1: Auxiliary Register 1

7	6	5	4	3	2	1	0
-	-	-	-	GF3	0	-	DPS
Bit Number	Bit Mnemonic	Description					
7	-	Reserved The value read from this bit is indeterminate. Do not set this bit.					
6	-	Reserved The value read from this bit is indeterminate. Do not set this bit.					
5	-	Reserved The value read from this bit is indeterminate. Do not set this bit.					
4	-	Reserved The value read from this bit is indeterminate. Do not set this bit.					
3	GF3	This bit is a general purpose user flag					
2	0	Reserved Always stuck at 0					
1	-	Reserved The value read from this bit is indeterminate. Do not set this bit.					
0	DPS	Data Pointer Selection Clear to select DPTR0. Set to select DPTR1.					

Reset Value = XXXX XXX0

Not bit addressable

Application

Software can take advantage of the additional data pointers to both increase speed and reduce code size, for example, block operations (copy, compare, search ...) are well served by using one data pointer as a 'source' pointer and the other one as a "destination" pointer.

ASSEMBLY LANGUAGE

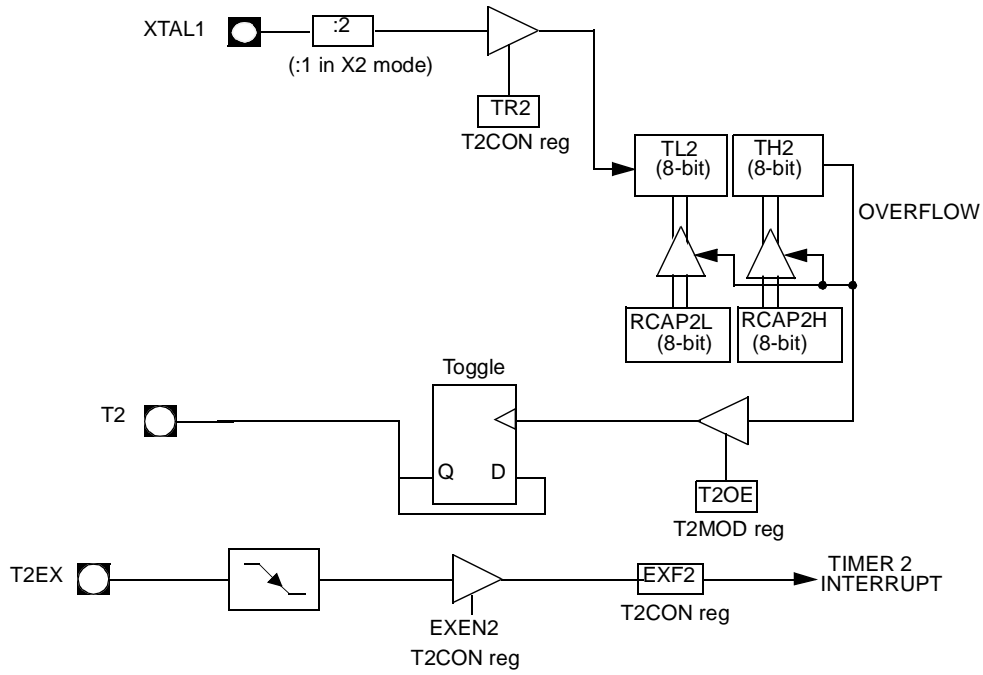
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; Block move using dual data pointers
; Destroys DPTR0, DPTR1, A and PSW
; note: DPS exits opposite of entry state
; unless an extra INC AUXR1 is added
;
00A2  AUXR1 EQU 0A2H
;
0000 909000MOV DPTR,#SOURCE ; address of SOURCE
0003 05A2 INC AUXR1 ; switch data pointers
0005 90A000 MOV DPTR,#DEST ; address of DEST
0008  LOOP:
0008 05A2 INC AUXR1 ; switch data pointers
000A E0 MOVX A,atDPTR ; get a byte from SOURCE
000B A3 INC DPTR ; increment SOURCE address
000C 05A2 INC AUXR1 ; switch data pointers
000E F0 MOVX atDPTR,A ; write the byte to DEST
000F A3 INC DPTR ; increment DEST address
0010 70F6JNZ LOOP ; check for 0 terminator
0012 05A2 INC AUXR1 ; (optional) restore DPS

```

INC is a short (2 bytes) and fast (12 clocks) way to manipulate the DPS bit in the AUXR1 SFR. However, note that the INC instruction does not directly force the DPS bit to a particular state, but simply toggles it. In simple routines, such as the block move example, only the fact that DPS is toggled in the proper sequence matters, not its actual value. In other words, the block move routine works the same whether DPS is '0' or '1' on entry. Observe that without the last instruction (INC AUXR1), the routine will exit with DPS in the opposite state.

Figure 5. Clock-Out Mode $C/\overline{T2} = 0$



TS80C52X2 Serial I/O Port

The serial I/O port in the TS80C52X2 is compatible with the serial I/O port in the 80C52. It provides both synchronous and asynchronous communication modes. It operates as an Universal Asynchronous Receiver and Transmitter (UART) in three full-duplex modes (Modes 1, 2 and 3). Asynchronous transmission and reception can occur simultaneously and at different baud rates

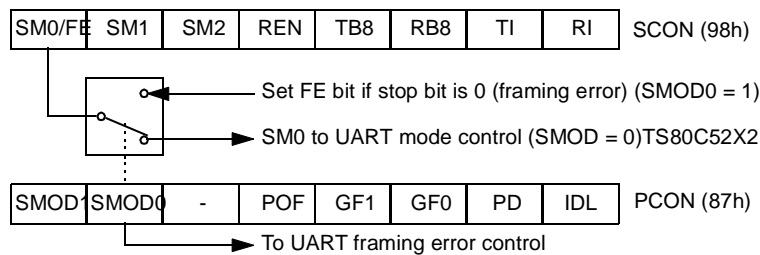
Serial I/O port includes the following enhancements:

- Framing error detection
- Automatic address recognition

Framing Error Detection

Framing bit error detection is provided for the three asynchronous modes (modes 1, 2 and 3). To enable the framing bit error detection feature, set SMOD0 bit in PCON register (See Figure 6).

Figure 6. Framing Error Block Diagram



When this feature is enabled, the receiver checks each incoming data frame for a valid stop bit. An invalid stop bit may result from noise on the serial lines or from simultaneous transmission by two CPUs. If a valid stop bit is not found, the Framing Error bit (FE) in SCON register (See Table 9.) bit is set.

Software may examine FE bit after each reception to check for data errors. Once set, only software or a reset can clear FE bit. Subsequently received frames with valid stop bits cannot clear FE bit. When FE feature is enabled, RI rises on stop bit instead of the last data bit (See Figure 7. and Figure 8.).

Figure 7. UART Timings in Mode 1

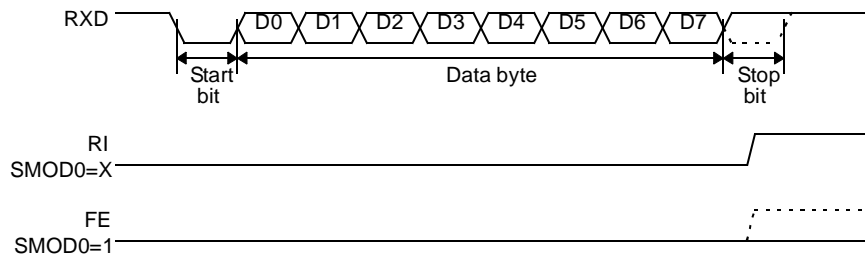


Table 10. PCON Register
PCON - Power Control Register (87h)

7	6	5	4	3	2	1	0
SMOD1	SMOD0	-	POF	GF1	GF0	PD	IDL
Bit Number	Bit Mnemonic	Description					
7	SMOD1	Serial port Mode bit 1 Set to select double baud rate in mode 1, 2 or 3.					
6	SMOD0	Serial port Mode bit 0 Clear to select SM0 bit in SCON register. Set to to select FE bit in SCON register.					
5	-	Reserved The value read from this bit is indeterminate. Do not set this bit.					
4	POF	Power-off Flag Clear to recognize next reset type. Set by hardware when VCC rises from 0 to its nominal voltage. Can also be set by software.					
3	GF1	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.					
2	GF0	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.					
1	PD	Power-down mode bit Cleared by hardware when reset occurs. Set to enter power-down mode.					
0	IDL	Idle mode bit Clear by hardware when interrupt or reset occurs. Set to enter idle mode.					

Reset Value = 00X1 0000b

Not bit addressable

Power-off flag reset value will be 1 only after a power on (cold reset). A warm reset doesn't affect the value of this bit.

Table 14. IPH Register
IPH - Interrupt Priority High Register (B7h)

7	6	5	4	3	2	1	0															
-	-	PT2H	PSH	PT1H	PX1H	PT0H	PX0H															
Bit Number	Bit Mnemonic	Description																				
7	-	Reserved The value read from this bit is indeterminate. Do not set this bit.																				
6	-	Reserved The value read from this bit is indeterminate. Do not set this bit.																				
5	PT2H	Timer 2 overflow interrupt Priority High bit <table border="1"> <thead> <tr> <th>PT2H</th> <th>PT2</th> <th>Priority Level</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Lowest</td> </tr> <tr> <td>0</td> <td>1</td> <td></td> </tr> <tr> <td>1</td> <td>0</td> <td></td> </tr> <tr> <td>1</td> <td>1</td> <td>Highest</td> </tr> </tbody> </table>						PT2H	PT2	Priority Level	0	0	Lowest	0	1		1	0		1	1	Highest
PT2H	PT2	Priority Level																				
0	0	Lowest																				
0	1																					
1	0																					
1	1	Highest																				
4	PSH	Serial port Priority High bit <table border="1"> <thead> <tr> <th>PSH</th> <th>PS</th> <th>Priority Level</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Lowest</td> </tr> <tr> <td>0</td> <td>1</td> <td></td> </tr> <tr> <td>1</td> <td>0</td> <td></td> </tr> <tr> <td>1</td> <td>1</td> <td>Highest</td> </tr> </tbody> </table>						PSH	PS	Priority Level	0	0	Lowest	0	1		1	0		1	1	Highest
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3	PT1H	Timer 1 overflow interrupt Priority High bit <table border="1"> <thead> <tr> <th>PT1H</th> <th>PT1</th> <th>Priority Level</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Lowest</td> </tr> <tr> <td>0</td> <td>1</td> <td></td> </tr> <tr> <td>1</td> <td>0</td> <td></td> </tr> <tr> <td>1</td> <td>1</td> <td>Highest</td> </tr> </tbody> </table>						PT1H	PT1	Priority Level	0	0	Lowest	0	1		1	0		1	1	Highest
PT1H	PT1	Priority Level																				
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1	0																					
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PX1H	PX1	Priority Level																				
0	0	Lowest																				
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1	0																					
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PX0H	PX0	Priority Level																				
0	0	Lowest																				
0	1																					
1	0																					
1	1	Highest																				

Reset Value = XX00 0000b
Not bit addressable



ONCE™ Mode (ON Chip Emulation)

The ONCE mode facilitates testing and debugging of systems using TS80C52X2 without removing the circuit from the board. The ONCE mode is invoked by driving certain pins of the TS80C52X2; the following sequence must be exercised:

- Pull ALE low while the device is in reset (RST high) and $\overline{\text{PSEN}}$ is high.
- Hold ALE low as RST is deactivated.

While the TS80C52X2 is in ONCE mode, an emulator or test CPU can be used to drive the circuit. Table 26. shows the status of the port pins during ONCE mode.

Normal operation is restored when normal reset is applied.

Table 16. External Pin Status during ONCE Mode

ALE	PSEN	Port 0	Port 1	Port 2	Port 3	XTAL1/2
Weak pull-up	Weak pull-up	Float	Weak pull-up	Weak pull-up	Weak pull-up	Active

12,000 $\mu\text{W}/\text{cm}^2$ rating for 30 minutes, at a distance of about 25 mm, should be sufficient. An exposure of 1 hour is recommended with most of standard erasers.

Erasure of the EPROM begins to occur when the chip is exposed to light with wavelength shorter than approximately 4,000 Å. Since sunlight and fluorescent lighting have wavelengths in this range, exposure to these light sources over an extended time (about 1 week in sunlight, or 3 years in room-level fluorescent lighting) could cause inadvertent erasure. If an application subjects the device to this type of exposure, it is suggested that an opaque label be placed over the window.

Signature Bytes

The TS80/87C52X2 has four signature bytes in location 30h, 31h, 60h and 61h. To read these bytes follow the procedure for EPROM verify but activate the control lines provided in Table 31. for Read Signature Bytes. Table 35. shows the content of the signature byte for the TS80/87C52X2.

Table 21. Signature Bytes Content

Location	Contents	Comment
30h	58h	Manufacturer Code: Atmel
31h	57h	Family Code: C51 X2
60h	2Dh	Product name: TS80C52X2
60h	ADh	Product name:TS87C52X2
60h	20h	Product name: TS80C32X2
61h	FFh	Product revision number



Electrical Characteristics

Absolute Maximum Ratings⁽¹⁾

Ambient Temperature Under Bias:	
C = commercial.....	0°C to 70°C
I = industrial.....	-40°C to 85°C
Storage Temperature.....	-65°C to + 150°C
Voltage on V _{CC} to V _{SS}	-0.5V to + 7 V
Voltage on V _{PP} to V _{SS}	-0.5V to + 13 V
Voltage on Any Pin to V _{SS}	-0.5V to V _{CC} + 0.5V
Power Dissipation.....	1 W ⁽²⁾

- Notes:
1. Stresses at or above those listed under “ Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
 2. This value is based on the maximum allowable die temperature and the thermal resistance of the package.

Power Consumption Measurement

Since the introduction of the first C51 devices, every manufacturer made operating I_{cc} measurements under reset, which made sense for the designs where the CPU was running under reset. In Atmel new devices, the CPU is no more active during reset, so the power consumption is very low but is not really representative of what will happen in the customer system. That’s why, while keeping measurements under Reset, Atmel presents a new way to measure the operating I_{cc}:

Using an internal test ROM, the following code is executed:

Label: SJMP Label (80 FE)

Ports 1, 2, 3 are disconnected, Port 0 is tied to FFh, EA = V_{cc}, RST = V_{ss}, XTAL2 is not connected and XTAL1 is driven by the clock.

This is much more representative of the real operating I_{cc}.

DC Parameters for Standard Voltage

T_A = 0°C to +70°C; V_{SS} = 0 V; V_{CC} = 5V ± 10%; F = 0 to 40 MHz.

T_A = -40°C to +85°C; V_{SS} = 0 V; V_{CC} = 5V ± 10%; F = 0 to 40 MHz.

Table 22. DC Parameters in Standard Voltage

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
V _{IL}	Input Low Voltage	-0.5		0.2 V _{CC} - 0.1	V	
V _{IH}	Input High Voltage except XTAL1, RST	0.2 V _{CC} + 0.9		V _{CC} + 0.5	V	
V _{IH1}	Input High Voltage, XTAL1, RST	0.7 V _{CC}		V _{CC} + 0.5	V	
V _{OL}	Output Low Voltage, ports 1, 2, 3 ⁽⁶⁾			0.3	V	I _{OL} = 100 μA ⁽⁴⁾
				0.45	V	I _{OL} = 1.6 mA ⁽⁴⁾
				1.0	V	I _{OL} = 3.5 mA ⁽⁴⁾
V _{OL1}	Output Low Voltage, port 0 ⁽⁶⁾			0.3	V	I _{OL} = 200 μA ⁽⁴⁾
				0.45	V	I _{OL} = 3.2 mA ⁽⁴⁾
				1.0	V	I _{OL} = 7.0 mA ⁽⁴⁾
V _{OL2}	Output Low Voltage, ALE, $\overline{\text{PSEN}}$			0.3	V	I _{OL} = 100 μA ⁽⁴⁾
				0.45	V	I _{OL} = 1.6 mA ⁽⁴⁾
				1.0	V	I _{OL} = 3.5 mA ⁽⁴⁾

DC Parameters for Low Voltage

$T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$; $V_{SS} = 0\text{ V}$; $V_{CC} = 2.7\text{ V}$ to 5.5 V ; $F = 0$ to 30 MHz .
 $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$; $V_{SS} = 0\text{ V}$; $V_{CC} = 2.7\text{ V}$ to 5.5 V ; $F = 0$ to 30 MHz .

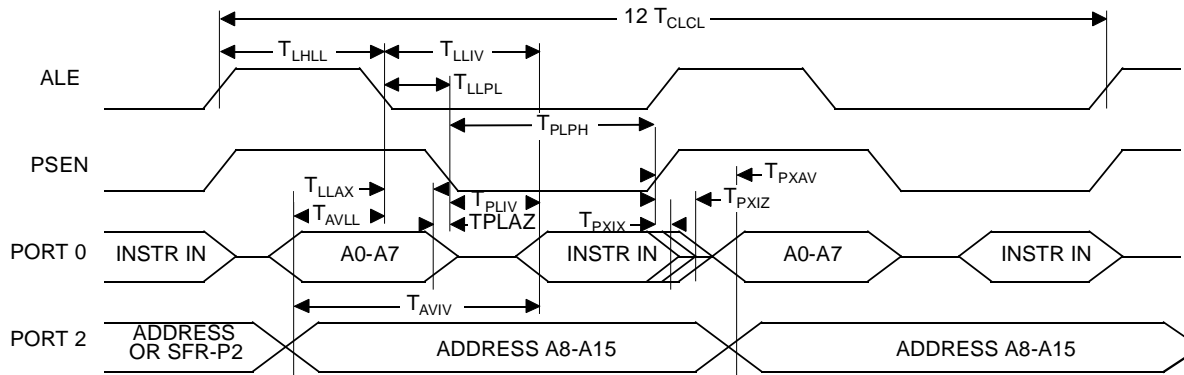
Table 23. DC Parameters for Low Voltage

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
V_{IL}	Input Low Voltage	-0.5		$0.2 V_{CC} - 0.1$	V	
V_{IH}	Input High Voltage except XTAL1, RST	$0.2 V_{CC} + 0.9$		$V_{CC} + 0.5$	V	
V_{IH1}	Input High Voltage, XTAL1, RST	$0.7 V_{CC}$		$V_{CC} + 0.5$	V	
V_{OL}	Output Low Voltage, ports 1, 2, 3 ⁽⁶⁾			0.45	V	$I_{OL} = 0.8\text{ mA}$ ⁽⁴⁾
V_{OL1}	Output Low Voltage, port 0, ALE, $\overline{\text{PSEN}}$ ⁽⁶⁾			0.45	V	$I_{OL} = 1.6\text{ mA}$ ⁽⁴⁾
V_{OH}	Output High Voltage, ports 1, 2, 3	$0.9 V_{CC}$			V	$I_{OH} = -10\ \mu\text{A}$
V_{OH1}	Output High Voltage, port 0, ALE, $\overline{\text{PSEN}}$	$0.9 V_{CC}$			V	$I_{OH} = -40\ \mu\text{A}$
I_{IL}	Logical 0 Input Current ports 1, 2 and 3			-50	μA	$V_{in} = 0.45\text{V}$
I_{LI}	Input Leakage Current			± 10	μA	$0.45\text{V} < V_{in} < V_{CC}$
I_{TL}	Logical 1 to 0 Transition Current, ports 1, 2, 3			-650	μA	$V_{in} = 2.0\text{ V}$
R_{RST}	RST Pulldown Resistor	50	90 ⁽⁵⁾	200	$\text{k}\Omega$	
CIO	Capacitance of I/O Buffer			10	pF	$F_c = 1\text{ MHz}$ $T_A = 25^\circ\text{C}$
I_{PD}	Power Down Current		20 ⁽⁵⁾ 10 ⁽⁵⁾	50 30	μA	$V_{CC} = 2.0\text{ V}$ to 5.5V ⁽³⁾ $V_{CC} = 2.0\text{ V}$ to 3.3 V ⁽³⁾
I_{CC} under RESET	Power Supply Current Maximum values, X1 mode: ⁽⁷⁾			1 + 0.2 Freq (MHz) at 12MHz 3.4 at 16MHz 4.2	mA	$V_{CC} = 3.3\text{ V}$ ⁽¹⁾
I_{CC} operating	Power Supply Current Maximum values, X1 mode: ⁽⁷⁾			1 + 0.3 Freq (MHz) at 12MHz 4.6 at 16MHz 5.8	mA	$V_{CC} = 3.3\text{ V}$ ⁽⁸⁾
I_{CC} idle	Power Supply Current Maximum values, X1 mode: ⁽⁷⁾			0.15 Freq (MHz) + 0.2 at 12MHz 2 at 16MHz 2.6	mA	$V_{CC} = 3.3\text{ V}$ ⁽²⁾

- Notes:
- I_{CC} under reset is measured with all output pins disconnected; XTAL1 driven with T_{CLCH} , $T_{CHCL} = 5\text{ ns}$ (see Figure 17.), $V_{IL} = V_{SS} + 0.5\text{V}$, $V_{IH} = V_{CC} - 0.5\text{V}$; XTAL2 N.C.; $\overline{\text{EA}} = \text{RST} = \text{Port } 0 = V_{CC}$. I_{CC} would be slightly higher if a crystal oscillator used.
 - Idle I_{CC} is measured with all output pins disconnected; XTAL1 driven with T_{CLCH} , $T_{CHCL} = 5\text{ ns}$, $V_{IL} = V_{SS} + 0.5\text{V}$, $V_{IH} = V_{CC} - 0.5\text{V}$; XTAL2 N.C.; Port 0 = V_{CC} ; $\overline{\text{EA}} = \text{RST} = V_{SS}$ (see Figure 15.).
 - Power Down I_{CC} is measured with all output pins disconnected; $\overline{\text{EA}} = V_{SS}$, PORT 0 = V_{CC} ; XTAL2 NC.; RST = V_{SS} (see Figure 16.).
 - Capacitance loading on Ports 0 and 2 may cause spurious noise pulses to be superimposed on the V_{OL} s of ALE and Ports 1 and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins make 1 to 0 transitions during bus operation. In the worst cases (capacitive loading 100pF), the noise pulse on the ALE line may exceed 0.45V with maxi V_{OL} peak 0.6V. A Schmitt Trigger use is not necessary.
 - Typicals are based on a limited number of samples and are not guaranteed. The values listed are at room temperature and 5V.
 - Under steady state (non-transient) conditions, I_{OL} must be externally limited as follows:
 Maximum I_{OL} per port pin: 10 mA
 Maximum I_{OL} per 8-bit port:

**External Program Memory
Read Cycle**

Figure 18. External Program Memory Read Cycle



**External Data Memory
Characteristics**

Table 29. Symbol Description

Symbol	Parameter
T _{RLRH}	\overline{RD} Pulse Width
T _{WLWH}	\overline{WR} Pulse Width
T _{RLDV}	\overline{RD} to Valid Data In
T _{RHDX}	Data Hold After \overline{RD}
T _{RHDZ}	Data Float After \overline{RD}
T _{LLDV}	ALE to Valid Data In
T _{AVDV}	Address to Valid Data In
T _{LLWL}	ALE to \overline{WR} or \overline{RD}
T _{AVWL}	Address to \overline{WR} or \overline{RD}
T _{QVWX}	Data Valid to \overline{WR} Transition
T _{QVWH}	Data set-up to \overline{WR} High
T _{WHQX}	Data Hold After \overline{WR}
T _{RLAZ}	\overline{RD} Low to Address Float
T _{WHLH}	\overline{RD} or \overline{WR} High to ALE high

Table 30. AC Parameters for a Fix Clock

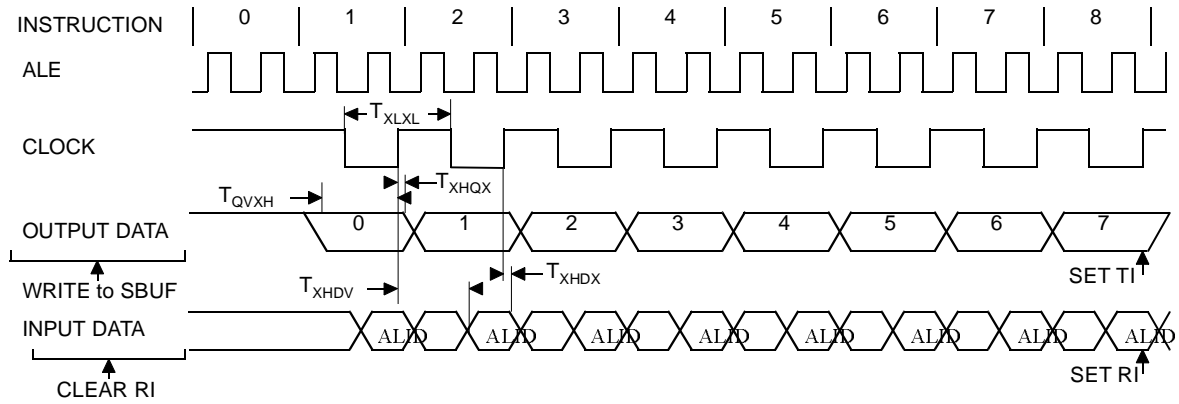
Speed	-M 40 MHz		-V X2 mode 30 MHz 60 MHz equiv.		-V standard mode 40 MHz		-L X2 mode 20 MHz 40 MHz equiv.		-L standard mode 30 MHz		Units
	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
T_{RLRH}	130		85		135		125		175		ns
T_{WLWH}	130		85		135		125		175		ns
T_{RLDV}		100		60		102		95		137	ns
T_{RHDX}	0		0		0		0		0		ns
T_{RHDZ}		30		18		35		25		42	ns
T_{LLDV}		160		98		165		155		222	ns
T_{AVDV}		165		100		175		160		235	ns
T_{LLWL}	50	100	30	70	55	95	45	105	70	130	ns
T_{AVWL}	75		47		80		70		103		ns
T_{QVWX}	10		7		15		5		13		ns
T_{QVWH}	160		107		165		155		213		ns
T_{WHQX}	15		9		17		10		18		ns
T_{RLAZ}		0		0		0		0		0	ns
T_{WHLH}	10	40	7	27	15	35	5	45	13	53	ns

Table 34. AC Parameters for a Variable Clock: Derating Formula

Symbol	Type	Standard Clock	X2 Clock	-M	-V	-L	Units
T_{XLXL}	Min	12 T	6 T				ns
T_{QVHX}	Min	10 T - x	5 T - x	50	50	50	ns
T_{XHGX}	Min	2 T - x	T - x	20	20	20	ns
T_{XHDX}	Min	x	x	0	0	0	ns
T_{XHDV}	Max	10 T - x	5 T - x	133	133	133	ns

Shift Register Timing Waveforms

Figure 21. Shift Register Timing Waveforms



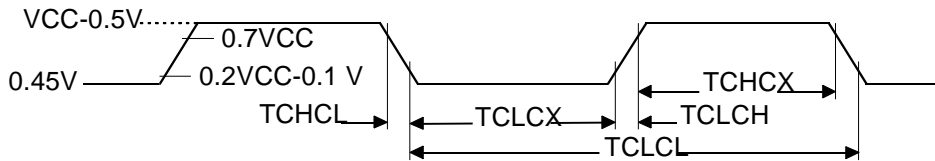
External Clock Drive Characteristics (XTAL1)

Table 36. AC Parameters

Symbol	Parameter	Min	Max	Units
T_{CLCL}	Oscillator Period	25		ns
T_{CHCX}	High Time	5		ns
T_{CLCX}	Low Time	5		ns
T_{CLCH}	Rise Time		5	ns
T_{CHCL}	Fall Time		5	ns
T_{CHCX}/T_{CLCX}	Cyclic ratio in X2 mode	40	60	%

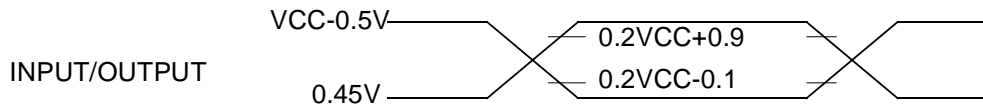
External Clock Drive Waveforms

Figure 23. External Clock Drive Waveforms



AC Testing Input/Output Waveforms

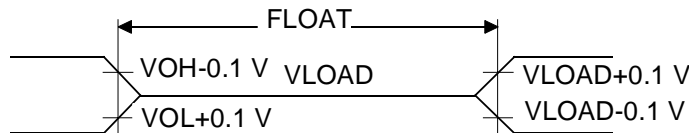
Figure 24. AC Testing Input/Output Waveforms



AC inputs during testing are driven at $V_{CC} - 0.5$ for a logic "1" and $0.45V$ for a logic "0". Timing measurement are made at V_{IH} min for a logic "1" and V_{IL} max for a logic "0".

Float Waveforms

Figure 25. Float Waveforms

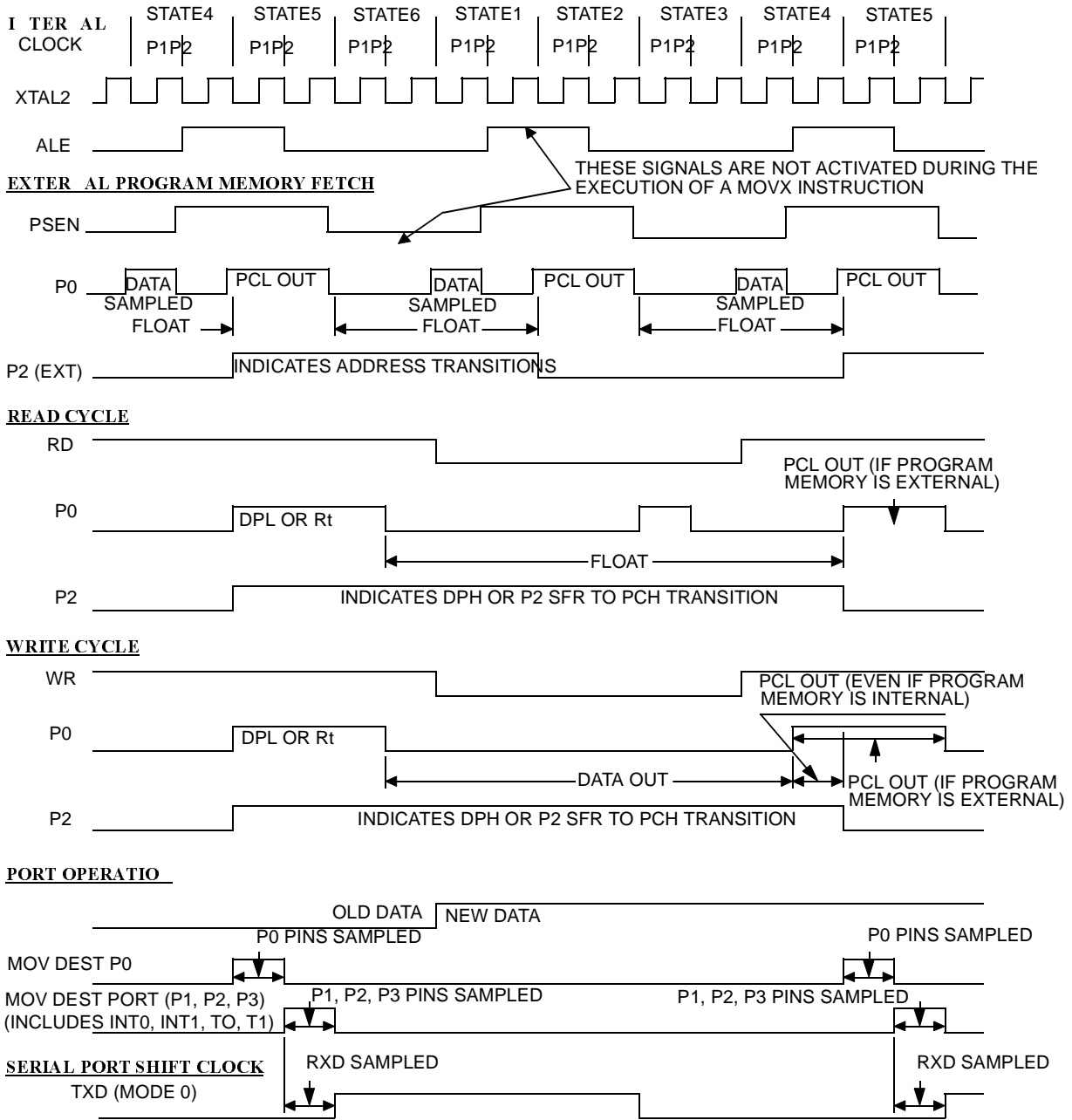


For timing purposes a port pin is no longer floating when a 100 mV change from load voltage occurs and begins to float when a 100 mV change from the loaded V_{OH}/V_{OL} level occurs. $I_{OL}/I_{OH} \geq \pm 20mA$.

Clock Waveforms

Valid in normal clock mode. In X2 mode XTAL2 signal must be changed to XTAL2 divided by two.

Figure 26. Clock Waveforms



This diagram indicates when signals are clocked internally. The time it takes the signals to propagate to the pins, however, ranges from 25 to 125 ns. This propagation delay is dependent on variables such as temperature and pin loading. Propagation also varies from output to output and component. Typically though ($T_A = 25^\circ\text{C}$ fully loaded) $\overline{\text{RD}}$ and $\overline{\text{WR}}$ propagation delays are approximately 50ns. The other signals are typically 85 ns. Propagation delays are incorporated in the AC specifications.

Ordering Information

Table 37. Possible Ordering Entries

Part Number ⁽³⁾	Memory Size	Supply Voltage	Temperature Range	Max Frequency	Package	Packing
TS80C32X2-MCA	ROMLess	5V \pm 10%	Commercial	40 MHz ⁽¹⁾	PDIL40	Stick
TS80C32X2-MCB	ROMLess	5V \pm 10%	Commercial	40 MHz ⁽¹⁾	PLCC44	Stick
TS80C32X2-MCC	ROMLess	5V \pm 10%	Commercial	40 MHz ⁽¹⁾	PQFP44	Tray
TS80C32X2-MCE	ROMLess	5V \pm 10%	Commercial	40 MHz ⁽¹⁾	VQFP44	Tray
TS80C32X2-LCA	ROMLess	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	PDIL40	Stick
TS80C32X2-LCB	ROMLess	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	PLCC44	Stick
TS80C32X2-LCC	ROMLess	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	PQFP44	Tray
TS80C32X2-LCE	ROMLess	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	VQFP44	Tray
TS80C32X2-VCA	ROMLess	5V \pm 10%	Commercial	60 MHz ⁽³⁾	PDIL40	Stick
TS80C32X2-VCB	ROMLess	5V \pm 10%	Commercial	60 MHz ⁽³⁾	PLCC44	Stick
TS80C32X2-VCC	ROMLess	5V \pm 10%	Commercial	60 MHz ⁽³⁾	PQFP44	Tray
TS80C32X2-VCE	ROMLess	5V \pm 10%	Commercial	60 MHz ⁽³⁾	VQFP44	Tray
TS80C32X2-MIA	ROMLess	5V \pm 10%	Industrial	40 MHz ⁽¹⁾	PDIL40	Stick
TS80C32X2-MIB	ROMLess	5V \pm 10%	Industrial	40 MHz ⁽¹⁾	PLCC44	Stick
TS80C32X2-MIC	ROMLess	5V \pm 10%	Industrial	40 MHz ⁽¹⁾	PQFP44	Tray
TS80C32X2-MIE	ROMLess	5V \pm 10%	Industrial	40 MHz ⁽¹⁾	VQFP44	Tray
TS80C32X2-LIA	ROMLess	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	PDIL40	Stick
TS80C32X2-LIB	ROMLess	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	PLCC44	Stick
TS80C32X2-LIC	ROMLess	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	PQFP44	Tray
TS80C32X2-LIE	ROMLess	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	VQFP44	Tray
TS80C32X2-VIA	ROMLess	5V \pm 10%	Industrial	60 MHz ⁽³⁾	PDIL40	Stick
TS80C32X2-VIB	ROMLess	5V \pm 10%	Industrial	60 MHz ⁽³⁾	PLCC44	Stick
TS80C32X2-VIC	ROMLess	5V \pm 10%	Industrial	60 MHz ⁽³⁾	PQFP44	Tray
TS80C32X2-VIE	ROMLess	5V \pm 10%	Industrial	60 MHz ⁽³⁾	VQFP44	Tray
AT80C32X2-3CSUM	ROMLess	5V \pm 10%	Industrial & Green	40 MHz ⁽¹⁾	PDIL40	Stick
AT80C32X2-SLSUM	ROMLess	5V \pm 10%	Industrial & Green	40 MHz ⁽¹⁾	PLCC44	Stick
AT80C32X2-RLTUM	ROMLess	5V \pm 10%	Industrial & Green	40 MHz ⁽¹⁾	VQFP44	Tray
AT80C32X2-RLTUM	ROMLess	5V \pm 10%	Industrial & Green	40 MHz ⁽¹⁾	VQFP44	Tape & Reel
AT80C32X2-3CSUL	ROMLess	2.7 to 5.5V	Industrial & Green	30 MHz ⁽¹⁾	PDIL40	Stick
AT80C32X2-SLSUL	ROMLess	2.7 to 5.5V	Industrial & Green	30 MHz ⁽¹⁾	PLCC44	Stick

Table 37. Possible Ordering Entries (Continued)

Part Number ⁽³⁾	Memory Size	Supply Voltage	Temperature Range	Max Frequency	Package	Packing
AT80C52X2zzz-3CSUL	8K ROM	2.7 to 5.5V	Industrial & Green	30 MHz ⁽¹⁾	PDIL40	Stick
AT80C52X2zzz-SLSUL	8K ROM	2.7 to 5.5V	Industrial & Green	30 MHz ⁽¹⁾	PLCC44	Stick
AT80C52X2zzz-RTLUL	8K ROM	2.7 to 5.5V	Industrial & Green	30 MHz ⁽¹⁾	VQFP44	Tray
AT80C52X2zzz-3CSUV	8K ROM	5V ±10%	Industrial & Green	60 MHz ⁽³⁾	PDIL40	Stick
AT80C52X2zzz-SLSUV	8K ROM	5V ±10%	Industrial & Green	60 MHz ⁽³⁾	PLCC44	Stick
AT80C52X2zzz-RTLUV	8K ROM	5V ±10%	Industrial & Green	60 MHz ⁽³⁾	VQFP44	Tray
TS87C52X2-MCA	8K OTP	5V ±10%	Commercial	40 MHz ⁽¹⁾	PDIL40	Stick
TS87C52X2-MCB	8K OTP	5V ±10%	Commercial	40 MHz ⁽¹⁾	PLCC44	Stick
TS87C52X2-MCC	8K OTP	5V ±10%	Commercial	40 MHz ⁽¹⁾	PQFP44	Tray
TS87C52X2-MCE	8K OTP	5V ±10%	Commercial	40 MHz ⁽¹⁾	VQFP44	Tray
TS87C52X2-LCA	8K OTP	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	PDIL40	Stick
TS87C52X2-LCB	8K OTP	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	PLC44	Stick
TS87C52X2-LCC	8K OTP	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	PQFP44	Tray
TS87C52X2-LCE	8K OTP	2.7 to 5.5V	Commercial	30 MHz ⁽¹⁾	VQFP44	Tray
TS87C52X2-VCA	8K OTP	5V ±10%	Commercial	60 MHz ⁽³⁾	PDIL40	Stick
TS87C52X2-VCB	8K OTP	5V ±10%	Commercial	60 MHz ⁽³⁾	PLCC44	Stick
TS87C52X2-VCC	8K OTP	5V ±10%	Commercial	60 MHz ⁽³⁾	PQFP44	Tray
TS87C52X2-VCE	8K OTP	5V ±10%	Commercial	60 MHz ⁽³⁾	VQFP44	Tray
TS87C52X2-MIA	8K OTP	5V ±10%	Industrial	40 MHz ⁽¹⁾	PDIL40	Stick
TS87C52X2-MIB	8K OTP	5V ±10%	Industrial	40 MHz ⁽¹⁾	PLCC44	Stick
TS87C52X2-MIC	8K OTP	5V ±10%	Industrial	40 MHz ⁽¹⁾	PQFP44	Tray
TS87C52X2-MIE	8K OTP	5V ±10%	Industrial	40 MHz ⁽¹⁾	VQFP44	Tray
TS87C52X2-LIA	8K OTP	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	PDIL40	Stick
TS87C52X2-LIB	8K OTP	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	PLCC44	Stick
TS87C52X2-LIC	8K OTP	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	PQFP44	Tray
TS87C52X2-LIE	8K OTP	2.7 to 5.5V	Industrial	30 MHz ⁽¹⁾	VQFP44	Tray
TS87C52X2-VIA	8K OTP	5V ±10%	Industrial	60 MHz ⁽³⁾	PDIL40	Stick
TS87C52X2-VIB	8K OTP	5V ±10%	Industrial	60 MHz ⁽³⁾	PLCC44	Stick
TS87C52X2-VIC	8K OTP	5V ±10%	Industrial	60 MHz ⁽³⁾	PQFP44	Tray
TS87C52X2-VIE	8K OTP	5V ±10%	Industrial	60 MHz ⁽³⁾	VQFP44	Tray