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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, I²C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	DMA, I²S, POR, PWM, WDT
Number of I/O	37
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	40K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 9x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f302cct6

Contents

Table 2. STM32F302xx family device features and peripheral counts

Peripheral		STM32F302Cx		STM32F302Rx		STM32F302Vx	
Flash (Kbytes)		128	256	128	256	128	256
SRAM (Kbytes) on data bus		32	40	32	40	32	40
Timers	Advanced control	1 (16-bit)					
	General purpose	5 (16-bit) 1 (32-bit)					
	Basic	1 (16-bit)					
PWM channels (all) (1)		26					
PWM channels (except complementary)		20					
Communication interfaces	SPI (I2S)(2)	3 (2)					
	I^2C	2					
	USART	3					
	UART	0		2			
	CAN	1					
	USB	1					
GPIOs	Normal I/Os (TC, TTa)	20		27		45 in LQFP100 37 in WLCSP100	
	5-volt tolerant I/Os (FT, FTf)	17		25		42 in LQFP100 40 in WLCSP100	
DMA channels		12					
Capacitive sensing channels		17		18		24	
12-bit ADCs		2					
Number of channels		9		16		17	
12-bit DAC channels		1					
Analog comparator		4					
Operational amplifiers		2					
CPU frequency		72 MHz					
Operating voltage		2.0 to 3.6 V					
Operating temperature		Ambient operating temperature: - 40 to 85 °C / - 40 to 105 °C Junction temperature: - 40 to 125 °C					
Packages		LQFP48		LQFP64		LQFP100 WLCSP100	

1. This total number considers also the PWMs generated on the complementary output channels
2. The SPI interfaces can work in an exclusive way in either the SPI mode or the I^2S audio mode.

3.7 Power management

3.7.1 Power supply schemes

- V_{SS}, V_{DD} = 2.0 to 3.6 V: external power supply for I/Os and the internal regulator. It is provided externally through V_{DD} pins.
- V_{SSA}, V_{DDA} = 2.0 to 3.6 V: external analog power supply for ADC, DAC, comparators operational amplifiers, reset blocks, RCs and PLL. The minimum voltage to be applied to V_{DDA} differs from one analog peripheral to another. *Table 3* provides the summary of the V_{DDA} ranges for analog peripherals. The V_{DDA} voltage level must be always greater or equal to the V_{DD} voltage level and must be provided first.
- V_{BAT} = 1.65 to 3.6 V: power supply for RTC, external clock 32 kHz oscillator and backup registers (through power switch) when V_{DD} is not present.

Table 3. External analog supply values for analog peripherals

Analog peripheral	Minimum V_{DDA} supply	Maximum V_{DDA} supply
ADC / COMP	2.0 V	3.6 V
DAC / OPAMP	2.4 V	3.6V

3.7.2 Power supply supervision

The device has an integrated power-on reset (POR) and power-down reset (PDR) circuits. They are always active, and ensure proper operation above a threshold of 2 V. The device remains in reset mode when the monitored supply voltage is below a specified threshold, $V_{POR/PDR}$, without the need for an external reset circuit.

- The POR monitors only the V_{DD} supply voltage. During the startup phase it is required that V_{DDA} should arrive first and be greater than or equal to V_{DD}.
- The PDR monitors both the V_{DD} and V_{DDA} supply voltages, however the V_{DDA} power supply supervisor can be disabled (by programming a dedicated Option bit) to reduce the power consumption if the application design ensures that V_{DDA} is higher than or equal to V_{DD}.

The device features an embedded programmable voltage detector (PVD) that monitors the V_{DD} power supply and compares it to the V_{PVD} threshold. An interrupt can be generated when V_{DD} drops below the V_{PVD} threshold and/or when V_{DD} is higher than the V_{PVD} threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

3.7.3 Voltage regulator

The regulator has three operation modes: main (MR), low-power (LPR), and power-down.

- The MR mode is used in the nominal regulation mode (Run)
- The LPR mode is used in Stop mode.
- The power-down mode is used in Standby mode: the regulator output is in high impedance, and the kernel circuitry is powered down thus inducing zero consumption.

The voltage regulator is always enabled after reset. It is disabled in Standby mode.

- 17-bit Auto-reload counter for periodic interrupt with wakeup from STOP/STANDBY capability.

The RTC clock sources can be:

- A 32.768 kHz external crystal
- A resonator or oscillator
- The internal low-power RC oscillator (typical frequency of 40 kHz)
- The high-speed external clock divided by 32.

3.19 Inter-integrated circuit interface (I^2C)

Up to two I^2C bus interfaces can operate in multimaster and slave modes. They can support standard (up to 100 KHz), fast (up to 400 KHz) and fast mode + (up to 1 MHz) modes.

Both support 7-bit and 10-bit addressing modes, multiple 7-bit slave addresses (2 addresses, 1 with configurable mask). They also include programmable analog and digital noise filters.

Table 6. Comparison of I2C analog and digital filters

	Analog filter	Digital filter
Pulse width of suppressed spikes	50 ns	Programmable length from 1 to 15 I2C peripheral clocks
Benefits	Available in Stop mode	1. Extra filtering capability vs. standard requirements. 2. Stable length
Drawbacks	Variations depending on temperature, voltage, process	Wakeup from Stop on address match is not available when digital filter is enabled.

In addition, they provide hardware support for SMBUS 2.0 and PMBUS 1.1: ARP capability, Host notify protocol, hardware CRC (PEC) generation/verification, timeouts verifications and ALERT protocol management. They also have a clock domain independent from the CPU clock, allowing the I2Cx (x=1,2) to wake up the MCU from Stop mode on address match.

The I2C interfaces can be served by the DMA controller.

Refer to *Table 7* for the features available in I2C1 and I2C2.

Table 7. STM32F302xB/STM32F302xC I^2C implementation

I2C features(1)	I2C1	I2C2
7-bit addressing mode	X	X
10-bit addressing mode	X	X
Standard mode (up to 100 kbit/s)	X	X
Fast mode (up to 400 kbit/s)	X	X
Fast Mode Plus with 20mA output drive I/Os (up to 1 Mbit/s)	X	X
Independent clock	X	X

3.22 Serial peripheral interface (SPI)/Inter-integrated sound interfaces (I2S)

Up to three SPIs are able to communicate up to 18 Mbits/s in slave and master modes in full-duplex and half-duplex communication modes. The 3-bit prescaler gives 8 master mode frequencies and the frame size is configurable from 4 bits to 16 bits.

Two standard I2S interfaces (multiplexed with SPI2 and SPI3) supporting four different audio standards can operate as master or slave at half-duplex and full duplex communication modes. They can be configured to transfer 16 and 24 or 32 bits with 16-bit or 32-bit data resolution and synchronized by a specific signal. Audio sampling frequency from 8 kHz up to 192 kHz can be set by 8-bit programmable linear prescaler. When operating in master mode it can output a clock for an external audio component at 256 times the sampling frequency.

Refer to *Table 9* for the features available in SPI1, SPI2 and SPI3.

Table 9. STM32F302xB/STM32F302xC SPI/I2S implementation

SPI features(1)	SPI1	SPI2	SPI3
Hardware CRC calculation	X	X	X
Rx/Tx FIFO	X	X	X
NSS pulse mode	X	X	X
I2S mode	-	X	X
TI mode	X	X	X

1. **X = supported.**

3.23 Controller area network (CAN)

The CAN is compliant with specifications 2.0A and B (active) with a bit rate up to 1 Mbit/s. It can receive and transmit standard frames with 11-bit identifiers as well as extended frames with 29-bit identifiers. It has three transmit mailboxes, two receive FIFOs with 3 stages and 14 scalable filter banks.

3.24 Universal serial bus (USB)

The STM32F302xB/STM32F302xC devices embed an USB device peripheral compatible with the USB full-speed 12 Mbs. The USB interface implements a full-speed (12 Mbit/s) function interface. It has software-configurable endpoint setting and suspend/resume support. The dedicated 48 MHz clock is generated from the internal main PLL (the clock source must use a HSE crystal oscillator). The USB has a dedicated 512-bytes SRAM memory for data transmission and reception.

4 Pinouts and pin description

Figure 4. STM32F302xB/STM32F302xC LQFP48 pinout

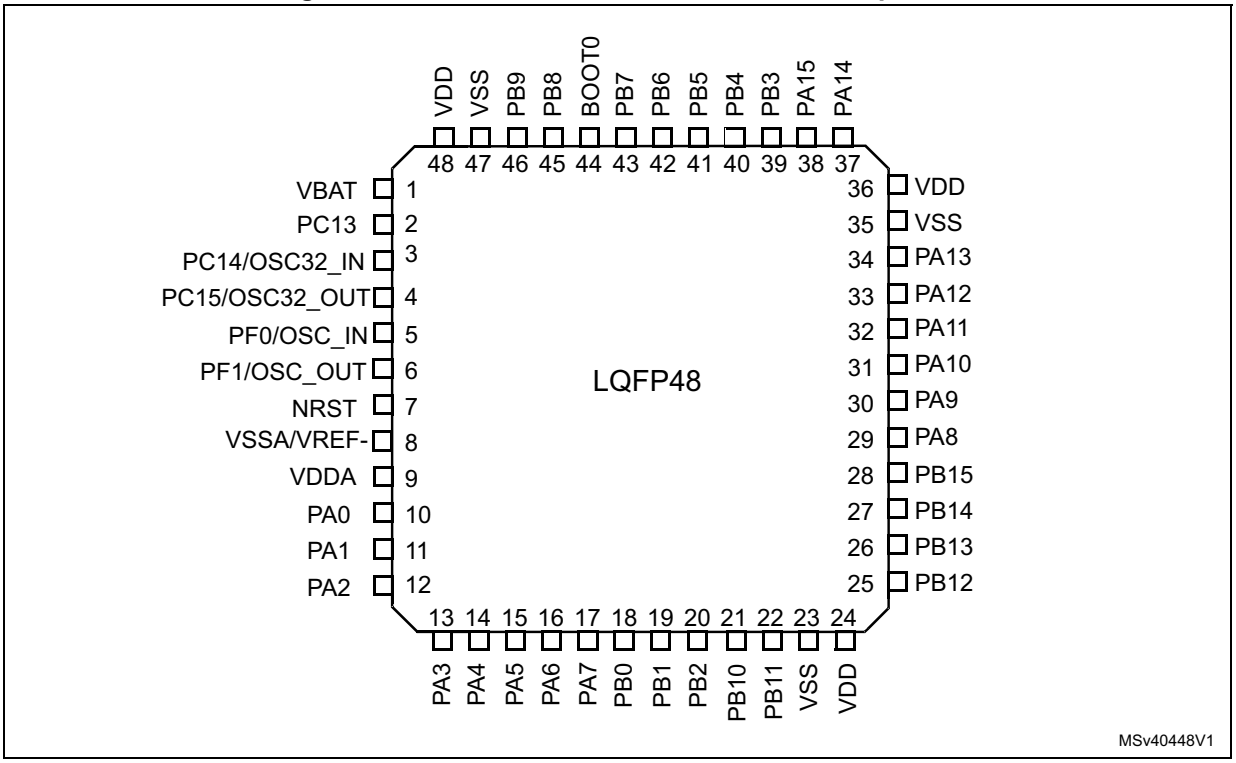


Table 14. Alternate functions for port A

Port & Pin Name	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF14	AF15
PA0	-	TIM2_CH1_ETR	-	TSC_G1_IO1	-	-	-	USART2_CTS	COMP1_OUT			-	-	-	EVENTOUT
PA1	RTC_REFIN	TIM2_CH2	-	TSC_G1_IO2	-	-	-	USART2_RTS_DE		TIM15_CH1N	-	-	-	-	EVENTOUT
PA2	-	TIM2_CH3	-	TSC_G1_IO3	-	-	-	USART2_TX	COMP2_OUT	TIM15_CH1	-	-	-	-	EVENTOUT
PA3	-	TIM2_CH4	-	TSC_G1_IO4	-	-	-	USART2_RX	-	TIM15_CH2	-	-	-	-	EVENTOUT
PA4	-	-	TIM3_CH2	TSC_G2_IO1	-	SPI1_NSS	SPI3_NSS, I2S3_WS	USART2_CK	-	-	-	-	-	-	EVENTOUT
PA5	-	TIM2_CH1_ETR	-	TSC_G2_IO2	-	SPI1_SCK	-	-	-	-	-	-	-	-	EVENTOUT
PA6	-	TIM16_CH1	TIM3_CH1	TSC_G2_IO3		SPI1_MISO	TIM1_BKIN	-	COMP1_OUT	-	-	-	-	-	EVENTOUT
PA7	-	TIM17_CH1	TIM3_CH2	TSC_G2_IO4		SPI1_MOSI	TIM1_CH1N	-	COMP2_OUT	-	-	-	-	-	EVENTOUT
PA8	MCO	-	-	-	I2C2_SMBA	I2S2_MCK	TIM1_CH1	USART1_CK		-	TIM4_ETR	-	-	-	EVENTOUT
PA9	-	-	-	TSC_G4_IO1	I2C2_SCL	I2S3_MCK	TIM1_CH2	USART1_TX		TIM15_BKIN	TIM2_CH3	-	-	-	EVENTOUT
PA10	-	TIM17_BKIN	-	TSC_G4_IO2	I2C2_SDA	-	TIM1_CH3	USART1_RX	COMP6_OUT	-	TIM2_CH4		-	-	EVENTOUT
PA11	-	-	-	-	-	-	TIM1_CH1N	USART1_CTS	COMP1_OUT	CAN_RX	TIM4_CH1	TIM1_CH4	TIM1_BKIN2	USB_DM	EVENTOUT

6.3 Operating conditions

6.3.1 General operating conditions

Table 24. General operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
f_{HCLK}	Internal AHB clock frequency	-	0	72	MHz
f_{PCLK1}	Internal APB1 clock frequency	-	0	36	
f_{PCLK2}	Internal APB2 clock frequency	-	0	72	
V_{DD}	Standard operating voltage	-	2	3.6	V
V_{DDA}	Analog operating voltage (OPAMP and DAC not used)	Must have a potential equal to or higher than V_{DD}	2	3.6	V
	Analog operating voltage (OPAMP and DAC used)		2.4	3.6	
V_{BAT}	Backup operating voltage	-	1.65	3.6	V
V_{IN}	I/O input voltage	TC I/O	–0.3	V_{DD}+0.3	V
		TTa I/O	–0.3	V_{DDA}+0.3	
		FT and FTf I/O(1)	–0.3	5.5	
		BOOT0	0	5.5	
P_D	Power dissipation at T_A = 85 °C for suffix 6 or T_A = 105 °C for suffix 7(2)	WLCSP100	-	500	mW
		LQFP100	-	488	
		LQFP64	-	444	
		LQFP48	-	364	
T_A	Ambient temperature for 6 suffix version	Maximum power dissipation	–40	85	°C
		Low-power dissipation(3)	–40	105	
	Ambient temperature for 7 suffix version	Maximum power dissipation	–40	105	°C
		Low-power dissipation(3)	–40	125	
T_J	Junction temperature range	6 suffix version	–40	105	°C
		7 suffix version	–40	125	

1. To sustain a voltage higher than V_{DD}+0.3 V, the internal pull-up/pull-down resistors must be disabled.
2. If T_A is lower, higher P_D values are allowed as long as T_J does not exceed T_{Jmax} (see *Section 7.5: Thermal characteristics*).
3. In low-power dissipation state, T_A can be extended to this range as long as T_J does not exceed T_{Jmax} (see *Section 7.5: Thermal characteristics*).

Table 27. Programmable voltage detector characteristics

Symbol	Parameter	Conditions	Min(1)	Typ	Max(1)	Unit
V_{PVD0}	PVD threshold 0	Rising edge	2.1	2.18	2.26	V
		Falling edge	2	2.08	2.16	
V_{PVD1}	PVD threshold 1	Rising edge	2.19	2.28	2.37	
		Falling edge	2.09	2.18	2.27	
V_{PVD2}	PVD threshold 2	Rising edge	2.28	2.38	2.48	
		Falling edge	2.18	2.28	2.38	
V_{PVD3}	PVD threshold 3	Rising edge	2.38	2.48	2.58	
		Falling edge	2.28	2.38	2.48	
V_{PVD4}	PVD threshold 4	Rising edge	2.47	2.58	2.69	
		Falling edge	2.37	2.48	2.59	
V_{PVD5}	PVD threshold 5	Rising edge	2.57	2.68	2.79	
		Falling edge	2.47	2.58	2.69	
V_{PVD6}	PVD threshold 6	Rising edge	2.66	2.78	2.9	
		Falling edge	2.56	2.68	2.8	
V_{PVD7}	PVD threshold 7	Rising edge	2.76	2.88	3	
		Falling edge	2.66	2.78	2.9	
$V_{PVDhyst}$(2)	PVD hysteresis	-	-	100	-	mV
IDD(PVD)	PVD current consumption	-	-	0.15	0.26	µA

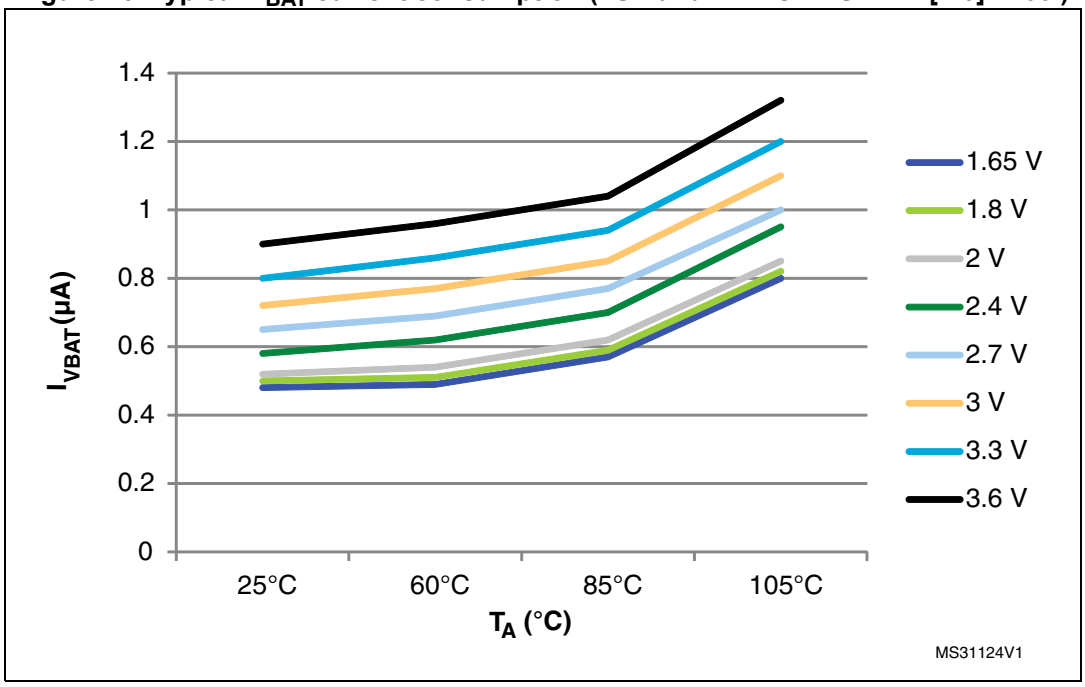
1. Guaranteed by characterization results.
2. Guaranteed by design.

Table 34. Typical and maximum current consumption from V_{BAT} supply

Symbol	Para meter	Conditions (1)	Typ @V_{BAT}								Max @V_{BAT} = 3.6 V(2)			Unit
			1.65V	1.8V	2V	2.4V	2.7V	3V	3.3V	3.6V	T_A = 25°C	T_A = 85°C	T_A = 105°C	
I_{DD_VBAT}	Backup domain supply current	LSE & RTC ON; "Xtal mode" lower driving capability; LSEDRV[1:0] = '00'	0.48	0.50	0.52	0.58	0.65	0.72	0.80	0.90	1.1	1.5	2.0	µA
		LSE & RTC ON; "Xtal mode" higher driving capability; LSEDRV[1:0] = '11'	0.83	0.86	0.90	0.98	1.03	1.10	1.20	1.30	1.5	2.2	2.9	

1. Crystal used: Abracon ABS07-120-32.768 kHz-T with a CL of 6 pF for typical values.
2. Guaranteed by characterization results.

Figure 13. Typical V_{BAT} current consumption (LSE and RTC ON/LSEDRV[1:0] = '00')



On-chip peripheral current consumption

The MCU is placed under the following conditions:

- all I/O pins are in analog input configuration
- all peripherals are disabled unless otherwise mentioned
- the given value is calculated by measuring the current consumption
  - with all peripherals clocked off
  - with only one peripheral clocked on
- ambient operating temperature at 25°C and $V_{DD} = V_{DDA} = 3.3$ V.

Table 38. Peripheral current consumption

Peripheral	Typical consumption(1)	Unit
	I_{DD}	
BusMatrix (2)	12.6	µA/MHz
DMA1	7.6	
DMA2	6.1	
CRC	2.1	
GPIOA	10.0	
GPIOB	10.3	
GPIOC	2.2	
GPIOD	8.8	
GPIOE	3.3	
GPIOF	3.0	
TSC	5.5	
ADC1&2	17.3	
APB2-Bridge (3)	3.6	
SYSCFG	7.3	
TIM1	40.0	
SPI1	8.8	
USART1	23.3	
TIM15	17.1	
TIM16	10.1	
TIM17	11.0	
APB1-Bridge (3)	6.1	
TIM2	49.1	
TIM3	38.8	
TIM4	38.3	

6.3.6 Wakeup time from low-power mode

The wakeup times given in *Table 39* are measured starting from the wakeup event trigger up to the first instruction executed by the CPU:

- For Stop or Sleep mode: the wakeup event is WFE.
- WKUP1 (PA0) pin is used to wakeup from Standby, Stop and Sleep modes.

All timings are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 24*.

Table 39. Low-power mode wakeup timings

Symbol	Parameter	Conditions	Typ @V_{DD}, V_{DD} = V_{DDA}						Max	Unit
			2.0 V	2.4 V	2.7 V	3 V	3.3 V	3.6 V		
t_{WUSTOP}	Wakeup from Stop mode	Regulator in run mode	4.1	3.9	3.8	3.7	3.6	3.5	4.5	µs
		Regulator in low-power mode	7.9	6.7	6.1	5.7	5.4	5.2	9	
$t_{WUSTANDBY}$(1)	Wakeup from Standby mode	LSI and IWDG OFF	69.2	60.3	56.4	53.7	51.7	50	100	
$t_{WUSLEEP}$	Wakeup from Sleep mode	-	6						-	CPU clock cycles

1. Guaranteed by characterization results.

6.3.7 External clock source characteristics

High-speed external user clock generated from an external source

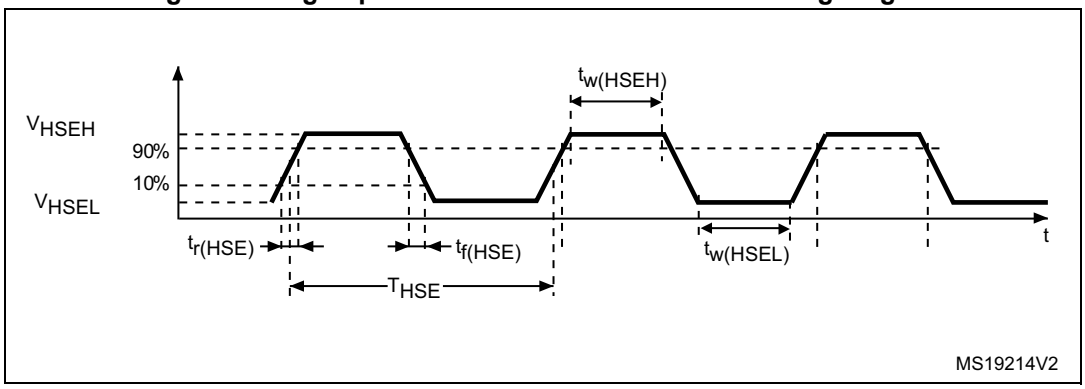
In bypass mode the HSE oscillator is switched off and the input pin is a standard GPIO. The external clock signal has to respect the I/O characteristics in *Section 6.3.14*. However, the recommended clock input waveform is shown in *Figure 14*.

Table 40. High-speed external user clock characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSE_ext}	User external clock source frequency(1)	-	1	8	32	MHz
V_{HSEH}	OSC_IN input pin high level voltage		$0.7V_{DD}$	-	V_{DD}	V
V_{HSEL}	OSC_IN input pin low level voltage		V_{SS}	-	$0.3V_{DD}$	
$t_{w(HSEH)}$ $t_{w(HSEL)}$	OSC_IN high or low time(1)		15	-	-	ns
$t_{r(HSE)}$ $t_{f(HSE)}$	OSC_IN rise or fall time(1)		-	-	20	

1. Guaranteed by design.

Figure 14. High-speed external clock source AC timing diagram



Prequalification trials

Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the NRST pin or the Oscillator pins for 1 second.

To complete these trials, ESD stress can be applied directly on the device, over the range of specification values. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring (see application note AN1015).

Electromagnetic Interference (EMI)

The electromagnetic field emitted by the device are monitored while a simple application is executed (toggling 2 LEDs through the I/O ports). This emission test is compliant with IEC 61967-2 standard which specifies the test board and the pin loading.

Table 50. EMI characteristics

Symbol	Parameter	Conditions	Monitored frequency band	Max vs. [f_{HSE}/f_{HCLK}]	Unit
				8/72 MHz	
S_{EMI}	Peak level	V_{DD} = 3.6 V, T_A = 25 °C, LQFP100 package compliant with IEC 61967-2	0.1 to 30 MHz	**7**	dBµV
			30 to 130 MHz	**20**	
			130 MHz to 1GHz	**27**	
			SAE EMI Level	**4**	-

6.3.12 Electrical sensitivity characteristics

Based on three different tests (ESD, LU) using specific measurement methods, the device is stressed in order to determine its performance in terms of electrical sensitivity.

Electrostatic discharge (ESD)

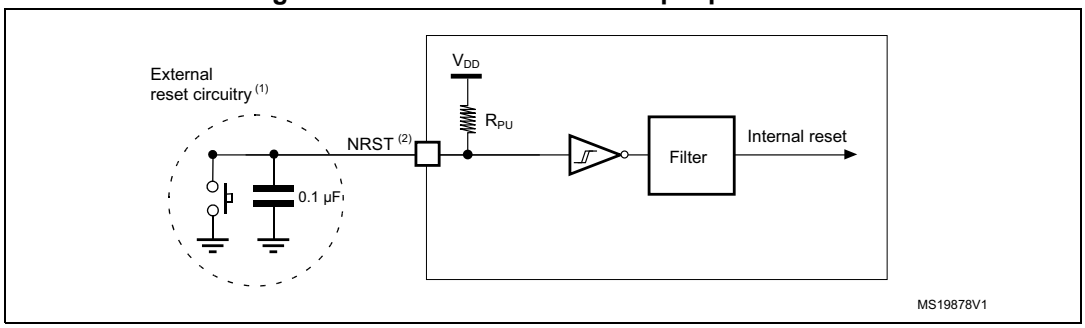
Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts × (n+1) supply pins). This test conforms to the JESD22-A114, ANSI/ESD STM5.3.1 standard.

Table 51. ESD absolute maximum ratings

Symbol	Ratings	Conditions		Class	Maximum value(1)	Unit
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	T_A = +25 °C, conforming to JESD22-A114		2	2000	V
$V_{ESD(CDM)}$	Electrostatic discharge voltage (charge device model)	T_A = +25 °C, conforming to ANSI/ESD STM5.3.1	WLCSP100 package	3	250	
			Packages except WLCSP100	4	500	

1. Guaranteed by characterization results.

Figure 24. Recommended NRST pin protection



1. The reset network protects the device against parasitic resets.
2. The user must ensure that the level on the NRST pin can go below the $V_{IL(NRST)}$ max level specified in *Table 57*. Otherwise the reset will not be taken into account by the device.

6.3.16 Timer characteristics

The parameters given in *Table 58* are guaranteed by design.

Refer to *Section 6.3.14: I/O port characteristics* for details on the input/output alternate function characteristics (output compare, input capture, external clock, PWM output).

Table 58. TIMx(1)(2) characteristics

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{res(TIM)}$	Timer resolution time	-	1	-	$t_{TIMxCLK}$
		$f_{TIMxCLK}$ = 72 MHz	13.9	-	ns
		$f_{TIM1CLK}$ = 144 MHz	6.95	-	ns
f_{EXT}	Timer external clock frequency on CH1 to CH4	-	0	$f_{TIMxCLK}/2$	MHz
		$f_{TIMxCLK}$ = 72 MHz	0	36	MHz
Res_{TIM}	Timer resolution	TIMx (except TIM2)	-	16	bit
		TIM2	-	32	
$t_{COUNTER}$	16-bit counter clock period	-	1	65536	$t_{TIMxCLK}$
		$f_{TIMxCLK}$ = 72 MHz	0.0139	910	µs
		$f_{TIM1CLK}$ = 144 MHz	0.0069	455	µs
t_{MAX_COUNT}	Maximum possible count with 32-bit counter	-	-	65536 × 65536	$t_{TIMxCLK}$
		$f_{TIMxCLK}$ = 72 MHz	-	59.65	s
		$f_{TIM1CLK}$ = 144 MHz	-	29.825	s

1. TIMx is used as a general term to refer to the TIM1, TIM2, TIM3, TIM4, TIM15, TIM16 and TIM17 timers.
2. Guaranteed by design.

6.3.17 Communications interfaces

I²C interface characteristics

The I²C interface meets the timings requirements of the I²C-bus specification and user manual rev.03 for:

- Standard-mode (Sm) : with a bit rate up to 100 Kbits/s
- Fast-mode (Fm) : with a bit rate up to 400 Kbits/s
- Fast-mode Plus (Fm+) : with a bit rate up to 1Mbits/s

The I²C timings requirements are guaranteed by design when the I²C peripheral is properly configured (refer to Reference manual).

The SDA and SCL I/O requirements are met with the following restrictions: the SDA and SCL I/O pins are “true” open-drain. When configured as open-drain, the PMOS connected between the I/O pin and VDDIOx is disabled, but is still present. Only FTf I/O pins support Fm+ low level output current maximum requirement. Refer to *Section 6.3.14: I/O port characteristics*.

All I²C I/Os embed an analog filter. refer to the *Table 62: I2C analog filter characteristics*.

Table 61. I2C timings specification (see I2C specification, rev.03, June 2007)(1)

Symbol	Parameter	Standard mode		Fast mode		Fast Mode Plus		Unit
		Min	Max	Min	Max	Min	Max	
f_{SCL}	SCL clock frequency	0	100	0	400	0	1000	KHz
t_{LOW}	Low period of the SCL clock	4.7	-	1.3	-	0.5	-	µs
t_{HIGH}	High Period of the SCL clock	4		0.6		0.26	-	µs
t_r	Rise time of both SDA and SCL signals	-	1000	-	300	-	120	ns
t_f	Fall time of both SDA and SCL signals	-	300	-	300	-	120	ns
$t_{HD;DAT}$	Data hold time	0	-	0	-	0	-	µs
$t_{VD;DAT}$	Data valid time	-	3.45(2)	-	0.9(2)	-	0.45(2)	µs
$t_{VD;ACK}$	Data valid acknowledge time	-	3.45(2)	-	0.9(2)	-	0.45(2)	µs
$t_{SU;DAT}$	Data setup time	250	-	100	-	50	-	ns
$t_{HD:STA}$	Hold time (repeated) START condition	4.0	-	0.6	-	0.26	-	µs
$t_{SU:STA}$	Set-up time for a repeated START condition	4.7	-	0.6	-	0.26		µs
$t_{SU:STO}$	Set-up time for STOP condition	4.0	-	0.6	-	0.26	-	µs
t_{BUF}	Bus free time between a STOP and START condition	4.7	-	1.3	-	0.5	-	µs
C_b	Capacitive load for each bus line	-	400	-	400	-	550	pF
t_{SP}	Pulse width of spikes that are suppressed by the analog filter for Standard and Fast mode	0	50(3)	0	50(3)	-	-	ns

Table 73. ADC accuracy, 64-pin packages(1)(2)(3)

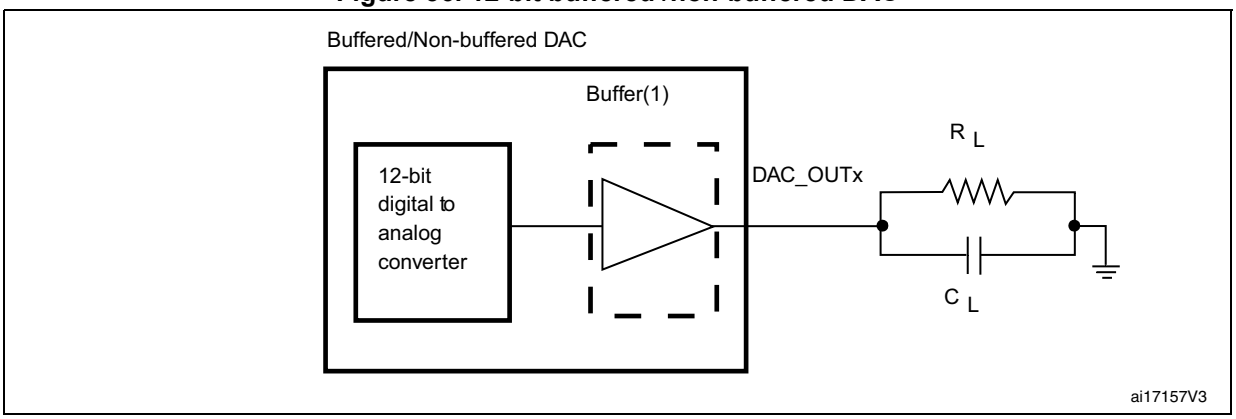
Symbol	Parameter	Conditions			Min(4)	Max (4)	Unit
ET	Total unadjusted error	ADC clock freq. ≤ 72 MHz, Sampling freq. ≤ 5 Msps 2.0 V ≤ V_{DDA} ≤ 3.6 V 64-pin package	Single ended	Fast channel 5.1 Ms	-	±6.5	LSB
				Slow channel 4.8 Ms	-	±6.5	
			Differential	Fast channel 5.1 Ms	-	±4	
				Slow channel 4.8 Ms	-	±4.5	
EO	Offset error		Single ended	Fast channel 5.1 Ms	-	±3	
				Slow channel 4.8 Ms	-	±3	
			Differential	Fast channel 5.1 Ms	-	±2.5	
				Slow channel 4.8 Ms	-	±2.5	
EG	Gain error		Single ended	Fast channel 5.1 Ms	-	±6	
				Slow channel 4.8 Ms	-	±6	
			Differential	Fast channel 5.1 Ms	-	±3.5	
				Slow channel 4.8 Ms	-	±4	
ED	Differential linearity error		Single ended	Fast channel 5.1 Ms	-	±1.5	
				Slow channel 4.8 Ms	-	±1.5	
			Differential	Fast channel 5.1 Ms	-	±1.5	
				Slow channel 4.8 Ms	-	±1.5	
EL	Integral linearity error		Single ended	Fast channel 5.1 Ms	-	±3	
				Slow channel 4.8 Ms	-	±3.5	
			Differential	Fast channel 5.1 Ms	-	±2	
				Slow channel 4.8 Ms	-	±2.5	
ENOB (5)	Effective number of bits		Single ended	Fast channel 5.1 Ms	10.4	-	bits
				Slow channel 4.8 Ms	10.4	-	
			Differential	Fast channel 5.1 Ms	10.8	-	
				Slow channel 4.8 Ms	10.8	-	
SINAD (5)	Signal-to-noise and distortion ratio		Single ended	Fast channel 5.1 Ms	64	-	dB
				Slow channel 4.8 Ms	63	-	
			Differential	Fast channel 5.1 Ms	67	-	
				Slow channel 4.8 Ms	67	-	

Table 75. DAC characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t_{WAKEUP}(3)	Wakeup time from off state (Setting the ENx bit in the DAC Control register)	$C_{LOAD} \leq 50$ pF, $R_{LOAD} \geq 5$ kΩ	-	6.5	10	µs
PSRR+ (1)	Power supply rejection ratio (to V_{DDA}) (static DC measurement	$C_{LOAD} = 50$ pF, No $R_{LOAD} \geq 5$ kΩ,	-	–67	–40	dB

1. Guaranteed by design.
2. Quiescent mode refers to the state of the DAC a keeping steady value on the output, so no dynamic consumption is involved.
3. Guaranteed by characterization results.

Figure 36. 12-bit buffered /non-buffered DAC



1. The DAC integrates an output buffer that can be used to reduce the output impedance and to drive external loads directly without the use of an external operational amplifier. The buffer can be bypassed by configuring the BOFFx bit in the DAC_CR register.

Table 88. Document revision history (continued)

Date	Revision	Changes
29-Jan-2015	4	Updated cover page with ADC up to 17 channels. Updated *Section 6.3.20: Comparator characteristics* modifying ts_sc characteristics in *Table 76* and adding *Figure 37: Maximum VREFINT scaler startup time from power down*. Updated I_{DD} data in *Table 42: HSE oscillator characteristics*.
17-Apr-2015	5	Updated *Figure 1: STM32F302xB/STM32F302xC block diagram* changing 32 KB of SRAM by 40 KB of SRAM. Updated *Section 7: Package information*: with new package information structure adding 1 sub paragraph for each package. Updated *Figure 41: LQFP100 – 14 x 14 mm, low-profile quad flat package top view example* removing gate mark. Added note for all package device markings: “the following figure gives an example of topside marking orientation versus pin 1 identifier location”. Updated *Table 82: LQFP64 – 10 x 10 mm, low-profile quad flat package mechanical data*. Updated *Table 7: STM32F302xB/STM32F302xC peripheral interconnect matrix* removing TIM8 reference and updating note below the table, replacing by a reference to RM0365.
22-Feb-2016	6	Added WLCSP100: – Updated cover page. – Updated *Table 2: STM32F302xx family device features and peripheral counts*. – Added *Figure 7: STM32F302xB/STM32F302xC WLCSP100 pinout*. – Updated *Table 13: STM32F302xB/STM32F302xC pin definitions*. – Updated *Table 24: General operating conditions*. – Added *Section 7.4: WLCSP100 - 0.4 mm pitch wafer level chip scale package information*. – Updated *Table 86: Package thermal characteristics*. – Updated *Table 87: Ordering information scheme*. Updated *Figure 4*, *Figure 5*, *Figure 6*, *Table 13* and *Table 22* removing all VDD and VSS indexes. Updated all the notes removing ‘not tested in production’. Updated *Table 68: ADC characteristics* adding V_{REF}- negative voltage reference. Updated *Table 21: Voltage characteristics* adding table note 4. Updated *Table 43: LSE oscillator characteristics (fLSE = 32.768 kHz)* LSEDRV[1:0] bits. Updated *Table 28: Embedded internal reference voltage* V_{REFINT} internal reference voltage (min and typ values). Updated *Table 51: ESD absolute maximum ratings* ESD CDM at class 3 and 4 including WLCSP100 package information.