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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, I²C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	DMA, I²S, POR, PWM, WDT
Number of I/O	87
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	40K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 17x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f302vct7

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1 Introduction

This datasheet provides the ordering information and mechanical device characteristics of the STM32F302xB/STM32F302xC microcontrollers.

This STM32F302xB/STM32F302xC datasheet should be read in conjunction with the STM32F302xx reference manual (RM0365). The reference manual is available from the STMicroelectronics website www.st.com.

For information on the Cortex®-M4 core with FPU, please refer to:

- **Cortex®-M4 with FPU Technical Reference Manual**, available from ARM website www.arm.com.
- **STM32F3xxx and STM32F4xxx Cortex®-M4 programming manual (PM0214)** available from our website www.st.com.

Table 4. STM32F302xB/STM32F302xC peripheral interconnect matrix (continued)

Interconnect source	Interconnect destination	Interconnect action
GPIO RTCCLK HSE/32 MC0	TIM16	Clock source used as input channel for HSI and LSI calibration
CSS CPU (hard fault) COMPx PVD GPIO	TIM1, TIM15, 16, 17	Timer break
GPIO	TIMx	External trigger, timer break
	ADCx DAC1	Conversion external trigger
DAC1	COMPx	Comparator inverting input

Note: For more details about the interconnect actions, please refer to the corresponding sections in the reference manual (RM0365.

3.9 Clocks and startup

System clock selection is performed on startup, however the internal RC 8 MHz oscillator is selected as default CPU clock on reset. An external 4-32 MHz clock can be selected, in which case it is monitored for failure. If failure is detected, the system automatically switches back to the internal RC oscillator. A software interrupt is generated if enabled. Similarly, full interrupt management of the PLL clock entry is available when necessary (for example with failure of an indirectly used external oscillator).

Several prescalers allow to configure the AHB frequency, the high speed APB (APB2) and the low speed APB (APB1) domains. The maximum frequency of the AHB and the high speed APB domains is 72 MHz, while the maximum allowed frequency of the low speed APB domain is 36 MHz.

3.10 General-purpose input/outputs (GPIOs)

Each of the GPIO pins can be configured by software as output (push-pull or open-drain), as input (with or without pull-up or pull-down) or as peripheral alternate function. Most of the GPIO pins are shared with digital or analog alternate functions. All GPIOs are high current capable except for analog inputs.

The I/Os alternate function configuration can be locked if needed following a specific sequence in order to avoid spurious writing to the I/Os registers.

Fast I/O handling allows I/O toggling up to 36 MHz.

3.11 Direct memory access (DMA)

The flexible general-purpose DMA is able to manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers. The DMA controller supports circular buffer management, avoiding the generation of interrupts when the controller reaches the end of the buffer.

Each of the 12 DMA channels is connected to dedicated hardware DMA requests, with software trigger support for each channel. Configuration is done by software and transfer sizes between source and destination are independent.

The DMA can be used with the main peripherals: SPI, I^2C, USART, general-purpose timers, DAC and ADC.

3.12 Interrupts and events

3.12.1 Nested vectored interrupt controller (NVIC)

The STM32F302xB/STM32F302xC devices embed a nested vectored interrupt controller (NVIC) able to handle up to 66 maskable interrupt channels and 16 priority levels.

The NVIC benefits are the following:

- Closely coupled NVIC gives low latency interrupt processing
- Interrupt entry vector table address passed directly to the core
- Closely coupled NVIC core interface
- Allows early processing of interrupts
- Processing of late arriving higher priority interrupts
- Support for tail chaining
- Processor state automatically saved
- Interrupt entry restored on interrupt exit with no instruction overhead

The NVIC hardware block provides flexible interrupt management features with minimal interrupt latency.

3.13 Fast analog-to-digital converter (ADC)

Two fast analog-to-digital converters 5 MSPS, with selectable resolution between 12 and 6 bit, are embedded in the STM32F302xB/STM32F302xC family devices. The ADCs have up to 17 external channels (5 channels multiplexed between ADC1 and ADC2). Channels can be configured to be either single-ended input or differential input. The ADCs can perform conversions in single-shot or scan modes. In scan mode, automatic conversion is performed on a selected group of analog inputs.

The ADCs have also internal channels: Temperature sensor connected to ADC1 channel 16, $V_{BAT/2}$ connected to ADC1 channel 17, Voltage reference V_{REFINT} connected to the 2 ADCs channel 18, VREFOPAMP1 connected to ADC1 channel 15 and VREFOPAMP2 connected to ADC2 channel 17.

Additional logic functions embedded in the ADC interface allow:

- Simultaneous sample and hold
- Interleaved sample and hold
- Single-shunt phase current reading techniques.

The ADC can be served by the DMA controller. 3 analog watchdogs per ADC are available.

An analog watchdog feature allows very precise monitoring of the converted voltage of one, some or all selected channels. An interrupt is generated when the converted voltage is outside the programmed thresholds.

The events generated by the general-purpose timers and the advanced-control timer (TIM1) can be internally connected to the ADC start trigger and injection trigger, respectively, to allow the application to synchronize A/D conversion and timers.

3.13.1 Temperature sensor

The temperature sensor (TS) generates a voltage V_{SENSE} that varies linearly with temperature.

The temperature sensor is internally connected to the ADC1_IN16 input channel which is used to convert the sensor output voltage into a digital value.

The sensor provides good linearity but it has to be calibrated to obtain good overall accuracy of the temperature measurement. As the offset of the temperature sensor varies from chip to chip due to process variation, the uncalibrated internal temperature sensor is suitable for applications that detect temperature changes only.

To improve the accuracy of the temperature sensor measurement, each device is individually factory-calibrated by ST. The temperature sensor factory calibration data are stored by ST in the system memory area, accessible in read-only mode.

3.13.2 Internal voltage reference (V_{REFINT})

The internal voltage reference (V_{REFINT}) provides a stable (bandgap) voltage output for the ADC and Comparators. V_{REFINT} is internally connected to the ADCx_IN18, x=1...2 input channel. The precise voltage of V_{REFINT} is individually measured for each part by ST during production test and stored in the system memory area. It is accessible in read-only mode.

Table 13. STM32F302xB/STM32F302xC pin definitions (continued)

Pin number				Pin name (function after reset)	Pin type	I/O structure	Notes	Pin functions	
WLCSP100	LQFP100	LQFP64	LQFP48					Alternate functions	Additional functions
C9	7	2	2	PC13(2)	I/O	TC	-	TIM1_CH1N	WKUP2, RTC_TAMP1, RTC_TS, RTC_OUT
C10	8	3	3	PC14(2) OSC32_IN (PC14)	I/O	TC	-	-	OSC32_IN
D9	9	4	4	PC15(2) OSC32_ OUT (PC15)	I/O	TC	-	-	OSC32_OUT
D10	10	-	-	PF9	I/O	FT	(1)	TIM15_CH1, SPI2_SCK, EVENTOUT	-
E10	11	-	-	PF10	I/O	FT	(1)	TIM15_CH2, SPI2_SCK, EVENTOUT	-
F10	12	5	5	PF0- OSC_IN (PF0)	I/O	FTf	-	TIM1_CH3N, I2C2_SDA,	OSC_IN
F9	13	6	6	PF1- OSC_OUT (PF1)	I/O	FTf	-	I2C2_SCL	OSC_OUT
E9	14	7	7	NRST	I/O	RST		Device reset input / internal reset output (active low)	
G10	15	8	-	PC0	I/O	TTa	(1)	EVENTOUT	ADC12_IN6
G9	16	9	-	PC1	I/O	TTa	(1)	EVENTOUT	ADC12_IN7
G8	17	10	-	PC2	I/O	TTa	(1)	EVENTOUT	ADC12_IN8
H10	18	11	-	PC3	I/O	TTa	(1)	TIM1_BKIN2, EVENTOUT	ADC12_IN9
E8	19	-	-	PF2	I/O	TTa	(1)	EVENTOUT	ADC12_IN10
H8	20	12	8	VSSA/ VREF-	S	-	-	Analog ground/Negative reference voltage	
J8	21	-	-	VREF+(3)	S	-	-	Positive reference voltage	
J10	22	-	-	VDDA	S	-	-	Analog power supply	
-	-	13	9	VDDA/ VREF+	S	-	-	Analog power supply/Positive reference voltage	
H9	23	14	10	PA0	I/O	TTa	(4)	USART2_CTS, TIM2_CH1_ETR, TSC_G1_IO1, COMP1_OUT, EVENTOUT	ADC1_IN1, COMP1_INM, RTC_ TAMP2, WKUP1

Table 13. STM32F302xB/STM32F302xC pin definitions (continued)

Pin number				Pin name (function after reset)	Pin type	I/O structure	Notes	Pin functions	
WLCSP100	LQFP100	LQFP64	LQFP48					Alternate functions	Additional functions
C3	82	-	-	PD1	I/O	FT	(1)	CAN_TX, EVENTOUT	-
A4	83	54	-	PD2	I/O	FT	(1)	UART5_RX, TIM3_ETR, EVENTOUT	-
B4	84	-	-	PD3	I/O	FT	(1)	USART2_CTS, TIM2_CH1_ETR, EVENTOUT	-
C4	85	-	-	PD4	I/O	FT	(1)	USART2_RTS_DE, TIM2_CH2, EVENTOUT	-
-	86	-	-	PD5	I/O	FT	(1)	USART2_TX, EVENTOUT	-
-	87	-	-	PD6	I/O	FT	(1)	USART2_RX, TIM2_CH4, EVENTOUT	-
D4	88	-	-	PD7	I/O	FT	(1)	USART2_CK, TIM2_CH3, EVENTOUT	-
A5	89	55	39	PB3	I/O	FT	-	SPI3_SCK, I2S3_CK, SPI1_SCK, USART2_TX, TIM2_CH2, TIM3_ETR, TIM4_ETR, TSC_G5_IO1, JTDO-TRACESWO, EVENTOUT	-
B5	90	56	40	PB4	I/O	FT	-	SPI3_MISO, I2S3ext_SD, SPI1_MISO, USART2_RX, TIM3_CH1, TIM16_CH1, TIM17_BKIN, TSC_G5_IO2, NJTRST, EVENTOUT	-
A6	91	57	41	PB5	I/O	FT	-	SPI3_MOSI, SPI1_MOSI, I2S3_SD, I2C1_SMBA, USART2_CK, TIM16_BKIN, TIM3_CH2, TIM17_CH1, EVENTOUT	-
B6	92	58	42	PB6	I/O	FTf	-	I2C1_SCL, USART1_TX, TIM16_CH1N, TIM4_CH1, TSC_G5_IO3EVENTOUT	-
C5	93	59	43	PB7	I/O	FTf	-	I2C1_SDA, USART1_RX, TIM3_CH4, TIM4_CH2, TIM17_CH1N, TSC_G5_IO4, EVENTOUT	-
A7	94	60	44	BOOT0	I	B	-	Boot memory selection	

The parameters given in Table 30 to Table 34 are derived from tests performed under ambient temperature and supply voltage conditions summarized in Table 24.

Table 30. Typical and maximum current consumption from V_{DD} supply at V_{DD} = 3.6V

Symbol	Parameter	Conditions	f_{HCLK}	All peripherals enabled				All peripherals disabled				Unit
				Typ	Max @ T_A (1)			Typ	Max @ T_A (1)			
					25 °C	85 °C	105 °C		25 °C	85 °C	105 °C	
I_{DD}	Supply current in Run mode, executing from Flash	External clock (HSE bypass)	72 MHz	61.2	65.8	67.6	68.5	27.8	30.3	30.7	31.5	mA
			64 MHz	54.7	59.1	60.2	61.1	24.6	27.2	27.6	28.3	
			48 MHz	41.7	45.1	46.2	47.2	19.2	21.1	21.4	21.8	
			32 MHz	28.1	31.5	32.5	32.7	12.9	14.6	14.8	15.3	
			24 MHz	21.4	23.7	24.4	25.2	10.0	11.4	11.4	12.1	
			8 MHz	7.4	8.4	8.6	9.4	3.6	4.1	4.4	5.0	
			1 MHz	1.3	1.6	1.8	2.6	0.8	1.0	1.2	2.1	
		Internal clock (HSI)	64 MHz	49.7	54.4	55.4	56.3	24.5	27.2	27.4	28.1	
			48 MHz	37.9	42.2	43.0	43.5	18.9	21.4	21.5	21.6	
			32 MHz	25.8	29.2	29.2	30.0	12.7	14.2	14.6	15.2	
			24 MHz	19.7	22.3	22.6	23.2	6.7	7.7	7.9	8.5	
			8 MHz	6.9	7.8	8.3	8.8	3.5	4.0	4.4	5.0	
	Supply current in Run mode, executing from RAM	External clock (HSE bypass)	72 MHz	60.8	66.2(2)	69.7	70.4(2)	27.4	31.7(2)	32.2	32.5(2)	
			64 MHz	54.3	59.1	62.2	63.3	24.3	28.3	28.7	28.8	
			48 MHz	41.0	45.6	47.3	47.9	18.3	21.6	21.9	22.1	
			32 MHz	27.6	32.4	32.4	32.9	12.3	15.0	15.2	15.4	
			24 MHz	20.8	23.9	24.3	25.0	9.3	11.3	11.4	12.0	
			8 MHz	6.9	7.8	8.7	9.0	3.1	3.7	4.2	4.9	
			1 MHz	0.9	1.2	1.5	2.3	0.4	0.6	1.0	1.8	
		Internal clock (HSI)	64 MHz	49.2	53.9	55.2	57.4	23.9	27.8	28.2	28.4	
			48 MHz	37.3	40.8	41.4	44.1	18.2	21.0	21.6	21.9	
			32 MHz	25.1	27.6	29.1	30.1	12.0	14.0	14.5	15.1	
			24 MHz	19.0	21.6	22.1	22.9	6.3	7.2	7.7	8.1	
			8 MHz	6.4	7.3	7.9	8.4	3.0	3.5	4.0	4.7	

Table 30. Typical and maximum current consumption from V_{DD} supply at V_{DD} = 3.6V (continued)

Symbol	Parameter	Conditions	f_{HCLK}	All peripherals enabled				All peripherals disabled				Unit
				Typ	Max @ T_A(1)			Typ	Max @ T_A(1)			
					25 °C	85 °C	105 °C		25 °C	85 °C	105 °C	
I_{DD}	Supply current in Sleep mode, executing from Flash or RAM	External clock (HSE bypass)	72 MHz	44.0	48.4	49.4	50.5	6.6	7.5	7.9	8.7	mA
			64 MHz	39.2	43.3	44.0	45.2	6.0	6.8	7.2	7.9	
			48 MHz	29.6	32.7	33.3	34.3	4.5	5.2	5.6	6.3	
			32 MHz	19.7	23.3	23.3	23.5	3.1	3.5	4.0	4.8	
			24 MHz	14.9	17.6	17.8	18.3	2.4	2.8	3.3	3.9	
			8 MHz	4.9	5.7	6.1	6.9	0.8	1.0	1.4	2.2	
			1 MHz	0.6	0.9	1.2	2.1	0.1	0.3	0.6	1.5	
		Internal clock (HSI)	64 MHz	34.2	38.1	39.2	40.3	5.7	6.3	6.8	7.5	
			48 MHz	25.8	28.7	29.6	30.3	4.3	4.8	5.2	5.9	
			32 MHz	17.4	19.4	19.9	20.7	2.9	3.2	3.7	4.5	
			24 MHz	13.2	15.1	15.6	15.9	1.5	1.8	2.2	2.9	
			8 MHz	4.5	5.0	5.6	6.2	0.7	0.9	1.2	2.1	

1. Guaranteed by characterization results unless otherwise specified.
2. Data based on characterization results and tested in production with code executing from RAM.

Table 31. Typical and maximum current consumption from the V_{DDA} supply

Symbol	Parameter	Conditions (1)	f_{HCLK}	V_{DDA} = 2.4 V				V_{DDA} = 3.6 V				Unit
				Typ	Max @ T_A(2)			Typ	Max @ T_A(2)			
					25 °C	85 °C	105 °C		25 °C	85 °C	105 °C	
I_{DDA}	Supply current in Run/Sleep mode, code executing from Flash or RAM	HSE bypass	72 MHz	225	276	289	297	245	302	319	329	µA
			64 MHz	198	249	261	268	216	270	284	293	
			48 MHz	149	195	204	211	159	209	222	230	
			32 MHz	102	145	152	157	110	154	162	169	
			24 MHz	80	119	124	128	86	126	131	135	
			8 MHz	2	3	4	6	3	4	5	9	
			1 MHz	2	3	5	7	3	4	6	9	
		HSI clock	64 MHz	270	323	337	344	299	354	371	381	
			48 MHz	220	269	280	286	244	293	309	318	
			32 MHz	173	218	228	233	193	239	251	257	
			24 MHz	151	194	200	204	169	211	219	225	
			8 MHz	73	97	99	103	88	105	110	116	

1. Current consumption from the V_{DDA} supply is independent of whether the peripherals are on or off. Furthermore when the PLL is off, I_{DDA} is independent from the frequency.
2. Guaranteed by characterization results.

Table 32. Typical and maximum V_{DD} consumption in Stop and Standby modes

Symbol	Parameter	Conditions	Typ @V_{DD} (V_{DD}=V_{DDA})						Max(1)			Unit
			2.0 V	2.4 V	2.7 V	3.0 V	3.3 V	3.6 V	T_A = 25 °C	T_A = 85 °C	T_A = 105 °C	
I_{DD}	Supply current in Stop mode	Regulator in run mode, all oscillators OFF	20.05	20.33	20.42	20.50	20.67	20.80	44.2(2)	350	735(2)	µA
		Regulator in low-power mode, all oscillators OFF	7.63	7.77	7.90	8.07	8.17	8.33	30.6(2)	335	720(2)	
	Supply current in Standby mode	LSI ON and IWDG ON	0.80	0.96	1.09	1.23	1.37	1.51	-	-	-	
		LSI OFF and IWDG OFF	0.60	0.74	0.83	0.93	1.02	1.11	5.0(2)	7.8	13.3(2)	

1. Guaranteed by characterization results unless otherwise specified.
2. Data based on characterization results and tested in production.

Table 33. Typical and maximum V_{DDA} consumption in Stop and Standby modes

Symbol	Parameter	Conditions		Typ @V_{DD} (V_{DD} = V_{DDA})						Max(1)			Unit
				2.0 V	2.4 V	2.7 V	3.0 V	3.3 V	3.6 V	T_A = 25 °C	T_A = 85 °C	T_A = 105 °C	
I_{DDA}	Supply current in Stop mode	V_{DDA} monitoring ON	Regulator in run mode, all oscillators OFF	1.81	1.95	2.07	2.20	2.35	2.52	3.7	5.5	8.8	µA
			Regulator in low-power mode, all oscillators OFF	1.81	1.95	2.07	2.20	2.35	2.52	3.7	5.5	8.8	
	Supply current in Standby mode		LSI ON and IWDG ON	2.22	2.42	2.59	2.78	3.0	3.24	-	-	-	
			LSI OFF and IWDG OFF	1.69	1.82	1.94	2.08	2.23	2.40	3.5	5.4	9.2	
	Supply current in Stop mode	V_{DDA} monitoring OFF	Regulator in run mode, all oscillators OFF	1.05	1.08	1.10	1.15	1.22	1.29	-	-	-	
			Regulator in low-power mode, all oscillators OFF	1.05	1.08	1.10	1.15	1.22	1.29	-	-	-	
	Supply current in Standby mode		LSI ON and IWDG ON	1.44	1.52	1.60	1.71	1.84	1.98	-	-	-	
			LSI OFF and IWDG OFF	0.93	0.95	0.98	1.02	1.08	1.15	-	-	-	

1. Guaranteed by characterization results.

The total consumption is the sum of IDD and IDDA.

I/O system current consumption

The current consumption of the I/O system has two components: static and dynamic.

I/O static current consumption

All the I/Os used as inputs with pull-up generate current consumption when the pin is externally held low. The value of this current consumption can be simply computed by using the pull-up/pull-down resistors values given in *Table 54: I/O static characteristics*.

For the output pins, any external pull-down or external load must also be considered to estimate the current consumption.

Additional I/O current consumption is due to I/Os configured as inputs if an intermediate voltage level is externally applied. This current consumption is caused by the input Schmitt trigger circuits used to discriminate the input value. Unless this specific configuration is required by the application, this supply current consumption can be avoided by configuring these I/Os in analog mode. This is notably the case of ADC input pins which should be configured as analog inputs.

Caution: Any floating input pin can also settle to an intermediate voltage level or switch inadvertently, as a result of external electromagnetic noise. To avoid current consumption related to floating pins, they must either be configured in analog mode, or forced internally to a definite digital value. This can be done either by using pull-up/down resistors or by configuring the pins in output mode.

I/O dynamic current consumption

In addition to the internal peripheral current consumption (see*Table 38: Peripheral current consumption*), the I/Os used by an application also contribute to the current consumption. When an I/O pin switches, it uses the current from the MCU supply voltage to supply the I/O pin circuitry and to charge/discharge the capacitive load (internal or external) connected to the pin:

$$I_{SW} = V_{DD} \times f_{SW} \times C$$

where

I_{SW} is the current sunk by a switching I/O to charge/discharge the capacitive load

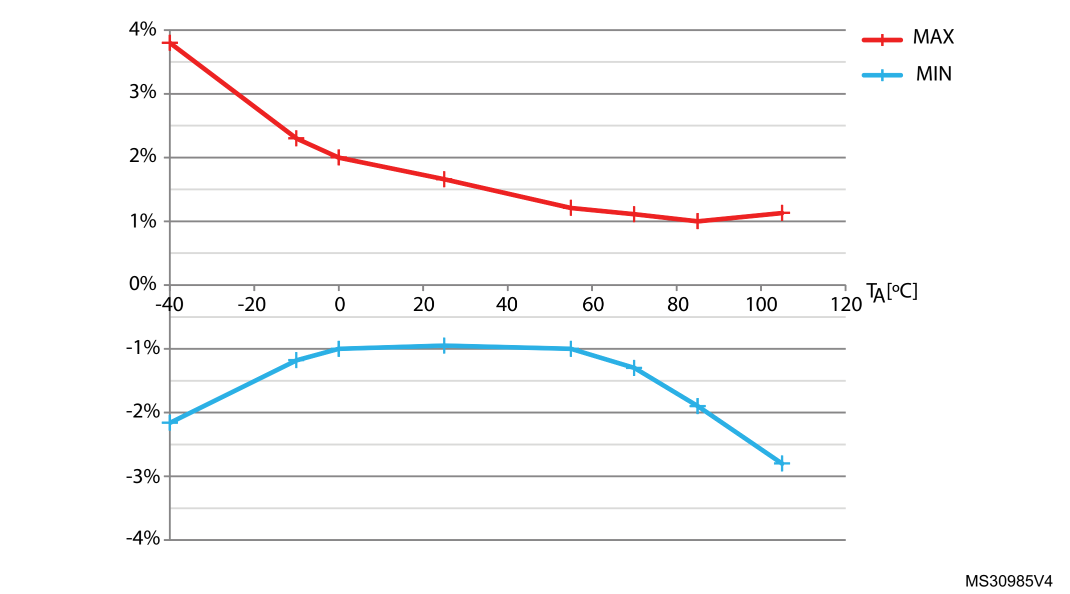
V_{DD} is the MCU supply voltage

f_{SW} is the I/O switching frequency

C is the total capacitance seen by the I/O pin: $C = C_{INT} + C_{EXT} + C_S$

The test pin is configured in push-pull output mode and is toggled by software at a fixed frequency.

Figure 18. HSI oscillator accuracy characterization results for soldered parts



Low-speed internal (LSI) RC oscillator

Table 45. LSI oscillator characteristics(1)

Symbol	Parameter	Min	Typ	Max	Unit
f_{LSI}	Frequency	30	40	50	kHz
$t_{su(LSI)}$(2)	LSI oscillator startup time	-	-	85	µs
$I_{DD(LSI)}$(2)	LSI oscillator power consumption	-	0.75	1.2	µA

1. V_{DDA} = 3.3 V, T_A = –40 to 105 °C unless otherwise specified.
2. Guaranteed by design.

Static latch-up

Two complementary static tests are required on six parts to assess the latch-up performance:

- A supply overvoltage is applied to each power supply pin
- A current injection is applied to each input, output and configurable I/O pin

These tests are compliant with EIA/JESD 78A IC latch-up standard.

Table 52. Electrical sensitivities

Symbol	Parameter	Conditions	Class
LU	Static latch-up class	T_A = +105 °C conforming to JESD78A	II level A

6.3.13 I/O current injection characteristics

As a general rule, current injection to the I/O pins, due to external voltage below V_{SS} or above V_{DD} (for standard, 3 V-capable I/O pins) should be avoided during normal product operation. However, in order to give an indication of the robustness of the microcontroller in cases when abnormal injection accidentally happens, susceptibility tests are performed on a sample basis during device characterization.

Functional susceptibility to I/O current injection

While a simple application is executed on the device, the device is stressed by injecting current into the I/O pins programmed in floating input mode. While current is injected into the I/O pin, one at a time, the device is checked for functional failures.

The failure is indicated by an out of range parameter: ADC error above a certain limit (higher than 5 LSB TUE), out of conventional limits of induced leakage current on adjacent pins (out of –5 µA/+0 µA range), or other functional failure (for example reset occurrence or oscillator frequency deviation).

The test results are given in *Table 53*.

Table 67. USB: Full-speed electrical characteristics[(1)]

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Driver characteristics						
t_r	Rise time[(2)]	C_L = 50 pF	4	-	20	ns
t_f	Fall time[(2)]	C_L = 50 pF	4	-	20	ns
t_{rfm}	Rise/ fall time matching	t_r/t_f	90	-	110	%
V_{CRS}	Output signal crossover voltage	-	1.3	-	2.0	V
Output driver Impedance[(3)]	Z_{DRV}	driving high and low	28	40	44	Ω

1. Guaranteed by design.
2. Measured from 10% to 90% of the data signal. For more detailed informations, please refer to USB Specification - Chapter 7 (version 2.0).
3. No external termination series resistors are required on USB_DP (D+) and USB_DM (D-), the matching impedance is already included in the embedded driver.

CAN (controller area network) interface

Refer to *Section 6.3.14: I/O port characteristics* for more details on the input/output alternate function characteristics (CAN_TX and CAN_RX).

Table 73. ADC accuracy, 64-pin packages(1)(2)(3)

Symbol	Parameter	Conditions			Min(4)	Max (4)	Unit
ET	Total unadjusted error	ADC clock freq. ≤ 72 MHz, Sampling freq. ≤ 5 Msps $2.0\ V \leq V_{DDA} \leq 3.6\ V$ 64-pin package	Single ended	Fast channel 5.1 Ms	-	±6.5	LSB
				Slow channel 4.8 Ms	-	±6.5	
			Differential	Fast channel 5.1 Ms	-	±4	
				Slow channel 4.8 Ms	-	±4.5	
EO	Offset error		Single ended	Fast channel 5.1 Ms	-	±3	
				Slow channel 4.8 Ms	-	±3	
			Differential	Fast channel 5.1 Ms	-	±2.5	
				Slow channel 4.8 Ms	-	±2.5	
EG	Gain error		Single ended	Fast channel 5.1 Ms	-	±6	
				Slow channel 4.8 Ms	-	±6	
			Differential	Fast channel 5.1 Ms	-	±3.5	
				Slow channel 4.8 Ms	-	±4	
ED	Differential linearity error		Single ended	Fast channel 5.1 Ms	-	±1.5	
				Slow channel 4.8 Ms	-	±1.5	
			Differential	Fast channel 5.1 Ms	-	±1.5	
				Slow channel 4.8 Ms	-	±1.5	
EL	Integral linearity error		Single ended	Fast channel 5.1 Ms	-	±3	
				Slow channel 4.8 Ms	-	±3.5	
			Differential	Fast channel 5.1 Ms	-	±2	
				Slow channel 4.8 Ms	-	±2.5	
ENOB (5)	Effective number of bits		Single ended	Fast channel 5.1 Ms	10.4	-	bits
				Slow channel 4.8 Ms	10.4	-	
			Differential	Fast channel 5.1 Ms	10.8	-	
				Slow channel 4.8 Ms	10.8	-	
SINAD (5)	Signal-to-noise and distortion ratio		Single ended	Fast channel 5.1 Ms	64	-	dB
				Slow channel 4.8 Ms	63	-	
			Differential	Fast channel 5.1 Ms	67	-	
				Slow channel 4.8 Ms	67	-	

Table 77. Operational amplifier characteristics[1] (continued)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
PGA gain	Non inverting gain value	-	-	2	-	-
			-	4	-	-
			-	8	-	-
			-	16	-	-
$R_{network}$	R2/R1 internal resistance values in PGA mode [3]	Gain=2	-	5.4/5.4	-	kΩ
		Gain=4	-	16.2/5.4	-	
		Gain=8	-	37.8/5.4	-	
		Gain=16	-	40.5/2.7	-	
PGA gain error	PGA gain error	-	-1%	-	1%	
I_{bias}	OPAMP input bias current	-	-	-	±0.2[4]	µA
PGA BW	PGA bandwidth for different non inverting gain	PGA Gain = 2, Cload = 50pF, Rload = 4 KΩ	-	4	-	MHz
		PGA Gain = 4, Cload = 50pF, Rload = 4 KΩ	-	2	-	
		PGA Gain = 8, Cload = 50pF, Rload = 4 KΩ	-	1	-	
		PGA Gain = 16, Cload = 50pF, Rload = 4 KΩ	-	0.5	-	
en	Voltage noise density	@ 1KHz, Output loaded with 4 KΩ	-	109	-	$\frac{nV}{\sqrt{Hz}}$
		@ 10KHz, Output loaded with 4 KΩ	-	43	-	

1. Guaranteed by design.
2. The saturation voltage can be also limited by the Iload (drive current).
3. R2 is the internal resistance between OPAMP output and OPAMP inverting input.
R1 is the internal resistance between OPAMP inverting input and ground.
The PGA gain =1+R2/R1
4. Mostly TTa I/O leakage, when used in analog mode.

6.3.23 V_{BAT} monitoring characteristics

Table 80. V_{BAT} monitoring characteristics

Symbol	Parameter	Min	Typ	Max	Unit
R	Resistor bridge for V_{BAT}	-	50	-	KΩ
Q	Ratio on V_{BAT} measurement	-	2	-	
Er(1)	Error on Q	-1	-	+1	%
T_{S_vbat}(1)(2)	ADC sampling time when reading the V_{BAT} 1mV accuracy	2.2	-	-	µs

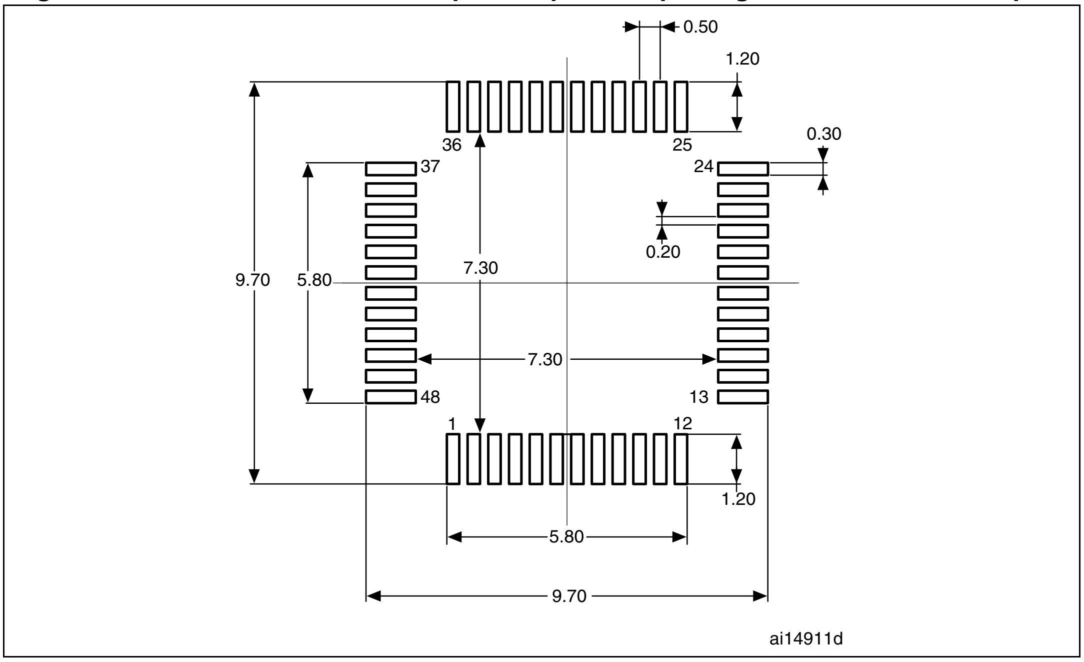
1. Guaranteed by design.
2. Shortest sampling time can be determined in the application by multiple iterations.

Table 83. LQFP48 – 7 x 7 mm, low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches[(1)]		
	Min	Typ	Max	Min	Typ	Max
E1	6.80	7.00	7.20	0.2677	0.2756	0.2835
E3	-	5.50	-	-	0.2165	-
e	-	0.50	-	-	0.0197	-
L	0.45	0.60	0.75	0.0177	0.0236	0.0295
L1	-	1.00	-	-	0.0394	-
K	0°	3.5°	7°	0°	3.5°	7°
ccc	-	-	0.08	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 46. LQFP48 - 7 x 7 mm, low-profile quad flat package recommended footprint



1. Dimensions are in millimeters.

Table 88. Document revision history (continued)

Date	Revision	Changes
06-May-2016	7	Updated *Figure 5: STM32F302xB/STM32F302xC LQFP64 pinout* replacing VSS by PF4. Updated *Table 13: STM32F302xB/STM32F302xC pin definitions*: – Adding ‘digital power supply’ in the Pin function column at the line corresponding to K8/28/19 pins. – Adding VSS digital ground line with WLCSP100 K9 and K10 pins connected. – Replacing in VDD line for WLCSP100: ‘A10, B10’ by ‘A9, A10, B10, B8’. Updated *Figure 21: Five volt tolerant (FT and FTf) I/O input characteristics - CMOS port*. Updated *Table 77: Operational amplifier characteristics* high saturation and low saturation voltages. Updated *Table 13: STM32F302xB/STM32F302xC pin definitions* adding note ‘Fast ADC channel’ for ADCx_IN1..5. Updated *Table 75: DAC characteristics* resistive load. Updated *Table 68: ADC characteristics* adding CMIR parameter and modifying tSTAB parameter characteristics.