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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I²C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	62
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 24x10/12b; D/A 1x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-TFBGA
Supplier Device Package	80-TFBGA (5.5x5.5)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/sim3l157-c-glr

1. Related Documents and Conventions

1.1. Related Documents

This data sheet accompanies several documents to provide the complete description of the SiM3L1xx devices.

1.1.1. SiM3L1xx Reference Manual

The Silicon Laboratories SiM3L1xx Reference Manual provides the detailed description for each peripheral on the SiM3L1xx devices.

1.1.2. Hardware Access Layer (HAL) API Description

The Silicon Laboratories Hardware Access Layer (HAL) API provides C-language functions to modify and read each bit in the SiM3L1xx devices. This description can be found in the SiM3xxxx HAL API Reference Manual.

1.1.3. ARM Cortex-M3 Reference Manual

The ARM-specific features like the Nested Vectored Interrupt Controller are described in the ARM Cortex-M3 reference documentation. The online reference manual can be found here:
http://infocenter.arm.com/help/topic/com.arm.doc.subset.cortexm3/index.html#cortexm3.

1.2. Conventions

The block diagrams in this document use the following formatting conventions:

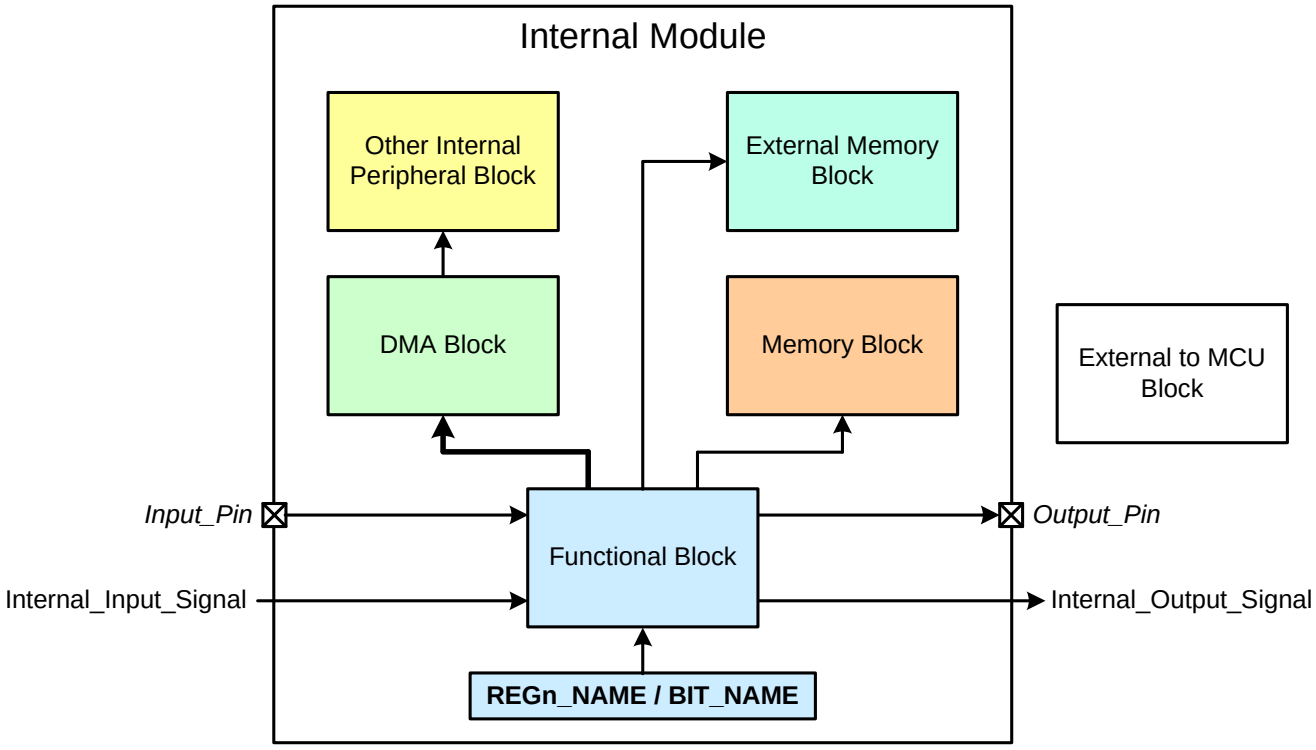

Figure 1.1. Block Diagram Conventions

3. Electrical Specifications

3.1. Electrical Characteristics

All electrical parameters in all Tables are specified under the conditions listed in Table 3.1, unless stated otherwise.

Table 3.1. Recommended Operating Conditions

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Operating Supply Voltage on VBAT/VBATDC	V_{BAT}		1.8	—	3.8	V
Operating Supply Voltage on VDC	V_{DC}		1.25	—	3.8	V
Operating Supply Voltage on VDRV	V_{DRV}		1.25	—	3.8	V
Operating Supply Voltage on VIO	V_{IO}		1.8	—	V_{BAT}	V
Operation Supply Voltage on VIORF	V_{IORF}		1.8	—	V_{BAT}	V
Operation Supply Voltage on VLCD	V_{LCD}		1.8	—	3.8	V
System Clock Frequency (AHB)	f_{AHB}		0	—	50	MHz
Peripheral Clock Frequency (APB)	f_{APB}		0	—	50	MHz
Operating Ambient Temperature	T_A		–40	—	+85	°C
Operating Junction Temperature	T_J		–40	—	105	°C

Note: All voltages with respect to V_{SS}.

Table 3.2. Power Consumption (Continued)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SARADC0	I_{SARADC}	Sampling at 1 Msps, Internal VREF used	—	1.2	1.6	mA
		Sampling at 250 ksps, lowest power mode settings.	—	390	540	µA
Temperature Sensor	I_{TSENSE}		—	75	110	µA
Internal SAR Reference	I_{REFFS}	Normal Power Mode	—	680	—	µA
		Normal Power Mode	—	160	—	µA
VREF0	I_{REFP}		—	80	—	µA
Comparator 0 (CMP0), Comparator 1 (CMP1)	I_{CMP}	CMPMD = 11	—	0.5	2	µA
		CMPMD = 10	—	3	8	µA
		CMPMD = 01	—	10	16	µA
		CMPMD = 00	—	25	42	µA
IDAC0[8]	I_{IDAC}		—	70	100	µA
Voltage Supply Monitor (VMON0)	I_{VMON}		—	10	22	µA
Flash Current on VBAT						
Write Operation	$I_{FLASH-W}$		—	—	8	mA
Erase Operation	$I_{FLASH-E}$		—	—	15	mA

Notes:

1. Currents are additive. For example, where I_{BAT} is specified and the mode is not mutually exclusive, enabling the functions increases supply current by the specified amount.
2. Includes all peripherals that cannot have clocks gated in the Clock Control module.
3. Includes LDO and PLL0OSC (>20 MHz) or LPOSC0 (≤20 MHz) supply current.
4. Internal Digital and Memory LDOs scaled to optimal output voltage.
5. Flash AHB clock turned off.
6. Running from internal LFO, Includes LFO supply current.
7. LCD0 current does not include switching currents for external load.
8. IDAC output current not included.
9. Does not include LC tank circuit.
10. Does not include digital drive current or pullup current for active port I/O. Unloaded I_{VIO} is included in all I_{BAT} PM8 production test measurements.

Table 3.5. On-Chip Regulators

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
DC-DC Buck Converter						
Input Voltage Range	V_{DCIN}		1.8	—	3.8	V
Input Supply to Output Voltage Differential (for regulation)	V_{DCREG}		0.45	—	—	V
Output Voltage Range	V_{DCOUT}		1.25	—	3.8	V
Output Voltage Accuracy	V_{DCACC}		—	±25	—	mV
Output Current	I_{DCOUT}		—	—	90	mA
Inductor Value[1]	L_{DC}		0.47	0.56	0.68	µH
Inductor Current Rating	I_{LDC}	I_{load} < 50 mA	450	—	—	mA
		I_{load} > 50 mA	550	—	—	mA
Output Capacitor Value	C_{DCOUT}		1	2.2	10	µF
Input Capacitor Value[2]	C_{DCIN}		—	4.7	—	µF
Load Regulation	R_{load}		—	0.03	—	mV/mA
Maximum DC Load Current During Startup	I_{DCMAX}		—	—	5	mA
Switching Clock Frequency	F_{DCCLK}		1.9	2.9	3.8	MHz
Local Oscillator Frequency	F_{DCOSC}		2.4	2.9	3.4	MHz
LDO Regulators						
Input Voltage Range[3]	V_{LDOIN}	Sourced from VBAT	1.8	—	3.8	V
		Sourced from VDC	1.9	—	3.8	V
Output Voltage Range[4]	V_{LDO}		0.8	—	1.9	V
LDO Output Voltage Accuracy	V_{LDOACC}		—	±25	—	mV
Output Settings in PM8 (All LDOs)	V_{LDO}	1.8 V ≤ V_{BAT} ≤ 2.9 V	1.5			V
		1.95 V ≤ V_{BAT} ≤ 3.5 V	1.8			V
		2.0 V ≤ V_{BAT} ≤ 3.8 V	1.9			V

Notes:

1. See reference manual for recommended inductors.
2. Recommended: X7R or X5R ceramic capacitors with low ESR. Example: Murata GRM21BR71C225K with ESR < 10 mΩ (@ frequency > 1 MHz).
3. Input voltage specification accounts for the internal LDO dropout voltage under the maximum load condition to ensure that the LDO output voltage will remain at a valid level as long as V_{LDOIN} is at or above the specified minimum.
4. The memory LDO output should always be set equal to or lower than the output of the analog LDO. When lowering both LDOs (for example to go into PM8 under low supply conditions), first adjust the memory LDO and then the analog LDO. When raising the output of both LDOs, adjust the analog LDO before adjusting the memory LDO.
5. Output range represents the programmable output range, and does not reflect the minimum voltage under all conditions. Dropout when the input supply is close to the output setting is normal, and accounted for.
6. Analog peripheral specifications assume a 1.8 V output on the analog LDO.

Table 3.5. On-Chip Regulators (Continued)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Memory LDO Output Setting[5]	V_{LDOMEM}	During Programming	1.8	—	1.9	V
		During Normal Operation	1.5	—	1.9	V
Digital LDO Output Setting	V_{LDODIG}	$F_{AHB} \leq 20$ MHz	1.0	—	1.9	V
		$F_{AHB} > 20$ MHz	1.2	—	1.9	V
Analog LDO Output Setting During Normal Operation[6]	V_{LDOANA}		1.8			V

Notes:

1. See reference manual for recommended inductors.
2. Recommended: X7R or X5R ceramic capacitors with low ESR. Example: Murata GRM21BR71C225K with ESR < 10 mΩ (@ frequency > 1 MHz).
3. Input voltage specification accounts for the internal LDO dropout voltage under the maximum load condition to ensure that the LDO output voltage will remain at a valid level as long as V_{LDOIN} is at or above the specified minimum.
4. The memory LDO output should always be set equal to or lower than the output of the analog LDO. When lowering both LDOs (for example to go into PM8 under low supply conditions), first adjust the memory LDO and then the analog LDO. When raising the output of both LDOs, adjust the analog LDO before adjusting the memory LDO.
5. Output range represents the programmable output range, and does not reflect the minimum voltage under all conditions. Dropout when the input supply is close to the output setting is normal, and accounted for.
6. Analog peripheral specifications assume a 1.8 V output on the analog LDO.

Table 3.14. Comparator

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Response Time, CMPMD = 00 (Highest Speed)	t_{RESP0}	+100 mV Differential	—	100	—	ns
		–100 mV Differential	—	150	—	ns
Response Time, CMPMD = 11 (Lowest Power)	t_{RESP3}	+100 mV Differential	—	1.4	—	µs
		–100 mV Differential	—	3.5	—	µs
Positive Hysteresis Mode 0 (CPMD = 00)	HYS_{CP+}	CMPHYP = 00	—	0.37	—	mV
		CMPHYP = 01	—	7.9	—	mV
		CMPHYP = 10	—	16.7	—	mV
		CMPHYP = 11	—	32.8	—	mV
Negative Hysteresis Mode 0 (CPMD = 00)	HYS_{CP-}	CMPHYN = 00	—	0.37	—	mV
		CMPHYN = 01	—	–7.9	—	mV
		CMPHYN = 10	—	–16.1	—	mV
		CMPHYN = 11	—	–32.7	—	mV
Positive Hysteresis Mode 1 (CPMD = 01)	HYS_{CP+}	CMPHYP = 00	—	0.47	—	mV
		CMPHYP = 01	—	5.85	—	mV
		CMPHYP = 10	—	12	—	mV
		CMPHYP = 11	—	24.4	—	mV
Negative Hysteresis Mode 1 (CPMD = 01)	HYS_{CP-}	CMPHYN = 00	—	0.47	—	mV
		CMPHYN = 01	—	–6.0	—	mV
		CMPHYN = 10	—	–12.1	—	mV
		CMPHYN = 11	—	–24.6	—	mV
Positive Hysteresis Mode 2 (CPMD = 10)	HYS_{CP+}	CMPHYP = 00	—	0.66	—	mV
		CMPHYP = 01	—	4.55	—	mV
		CMPHYP = 10	—	9.3	—	mV
		CMPHYP = 11	—	19	—	mV
Negative Hysteresis Mode 2 (CPMD = 10)	HYS_{CP-}	CMPHYN = 00	—	0.6	—	mV
		CMPHYN = 01	—	–4.5	—	mV
		CMPHYN = 10	—	–9.5	—	mV
		CMPHYN = 11	—	–19	—	mV

peripherals and may individually shut down and gate the clocks of any or all peripherals for power savings.

The on-chip debugging interface (SWJ-DP) allows non-intrusive (uses no on-chip resources), full speed, in-circuit debugging using the production MCU installed in the final application. This debug logic supports inspection and modification of memory and registers, setting breakpoints, single stepping, and run and halt commands. All analog and digital peripherals are fully functional while debugging.

Each device is specified for 1.8 to 3.8 V operation over the industrial temperature range (–40 to +85 °C). The SiM3L1xx devices are available in 40-pin or 64-pin QFN and 64-pin or 80-pin TQFP packages. All package options are lead-free and RoHS compliant. See Table 5.1 for ordering information. A block diagram is included in Figure 4.1.

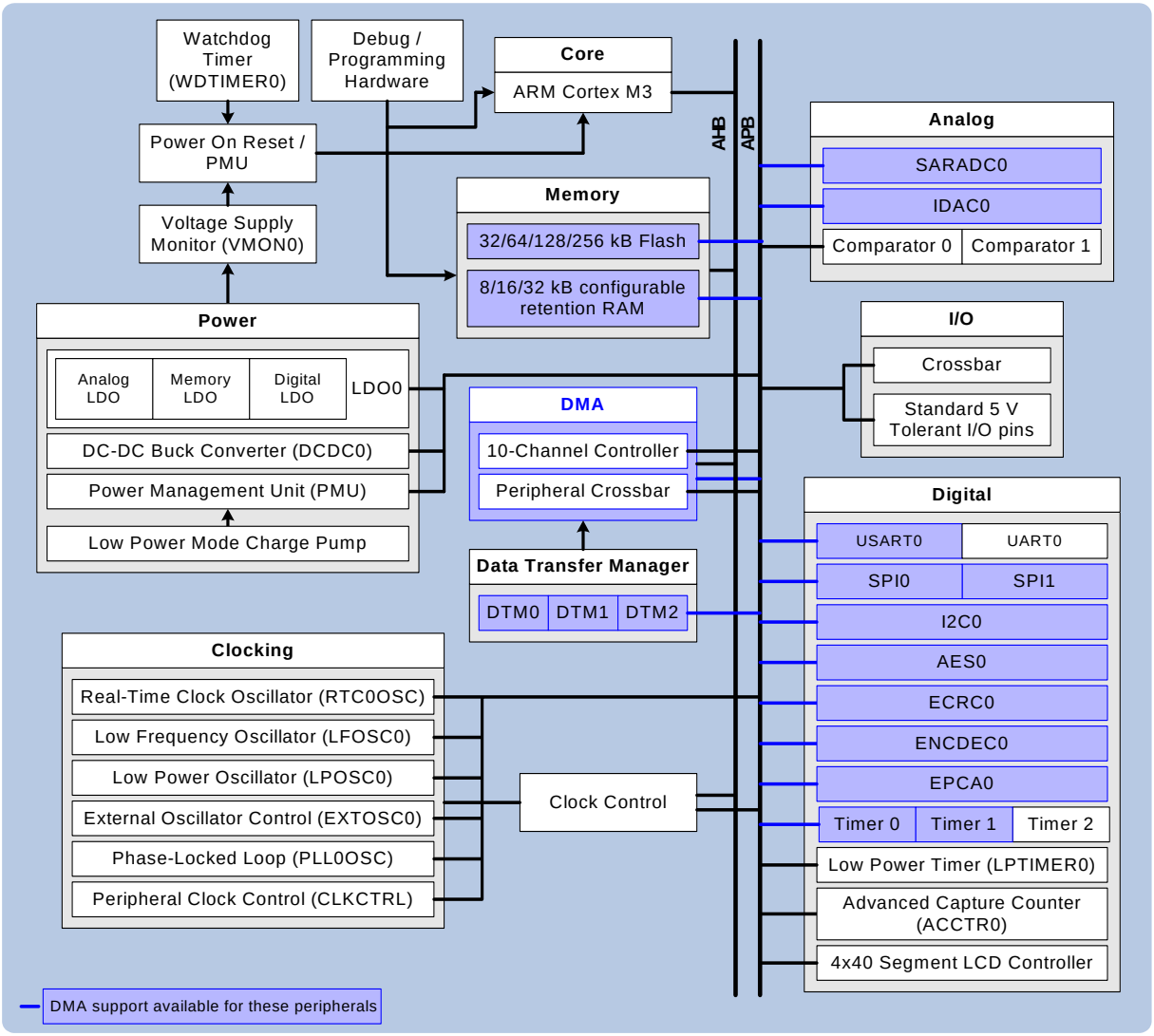

Figure 4.1. Precision32™ SiM3L1xx Family Block Diagram

4.1.6. Process/Voltage/Temperature Monitor (TIMER2 and PVTOSC0)

The Process/Voltage/Temperature monitor consists of two modules (TIMER2 and PVTOSC0) designed to monitor the digital circuit performance of the SiM3L1xx device.

The PVT oscillator (PVTOSC0) consists of two oscillators, one operating from the memory LDO and one operating from the digital LDO. These oscillators have two independent speed options and provide the clocks for two 16-bit timers in the TIMER2 module using the EX input. By monitoring the resulting counts of the TIMER2 timers, firmware can monitor the current device performance and increase the scalable LDO regulator (LDO0) output voltages as needed or decrease the output voltages to save power.

The PVT monitor has the following features:

- Two separate oscillators and timers for the memory and digital logic voltage domains.
- Two oscillator output divider settings.
- Provides a method for monitoring digital performance to allow firmware to adjust the scalable LDO regulator output voltages to the lowest level possible, saving power.

4.6.6. Low Power Mode Advanced Capture Counter (ACCTR0)

The SiM3L1xx devices contain a low-power Advanced Capture Counter module that runs from the RTC0 clock domain and can be used with digital inputs, switch topology circuits (reed switches), or with LC resonant circuits. For switch topology circuits, the module charges one or two external lines by pulsing internal pull-up resistors and detecting whether the reed switch is open or closed. For LC resonant circuits, the inputs are periodically energized to produce a dampened sine wave and configurable discriminator circuits detect the resulting decay time-constant.

The advanced capture counter has the following general features:

- Single or differential inputs supporting single, dual, and quadrature modes of operation.
- Variety of interrupt and PM8 wake up sources.
- Provides feedback of the direction history, current and previous states, and condition flags.

The advanced capture counter has the following features for switch circuit topologies:

- Ultra low power input comparators.
- Supports a wide range of pull-up resistor values with a self-calibration engine.
- Asymmetrical integrators for low-pass filtering and switch debounce.
- Two 24-bit counters and two 24-bit digital threshold comparators.
- Supports switch flutter detection.

For LC resonant circuit topologies, the advanced capture counter includes:

- Separate minimum and maximum count registers and polarity, pulse, and toggle controls.
- Zone-based programmable timing.
- Two input comparators with support for a positive side input bias at VIO divided by 2.
- Supports a configurable excitation pulse width based on a 40 MHz oscillator and timer or an external digital stop signal.
- Two 8-bit peak counters that saturate at full scale for detecting the number of LC resonant peaks.
- Two discriminators with programmable thresholds.
- Supports a sample and hold mode for Wheatstone bridges.

All devices in the SiM3L1xx family include the low power mode advanced capture counter (ACCTR0). Table 4.2 lists the supported inputs and outputs for each of the packages.

Table 4.2. SiM3L1xx Supported Advanced Capture Counter Inputs and Outputs

Input/Output	SiM3L1x7	SiM3L1x6	SiM3L1x4
ACCTR0_IN0	✓	✓	✓
ACCTR0_IN1	✓	✓	✓
ACCTR0_LCIN0	✓	✓	
ACCTR0_LCIN1	✓	✓	✓
ACCTR0_STOP0	✓	✓	✓
ACCTR0_STOP1	✓	✓	✓
ACCTR0_LCPUL0	✓	✓	
ACCTR0_LCPUL1	✓	✓	
ACCTR0_LCBIAS0	✓	✓	
ACCTR0_LCBIAS1	✓	✓	
ACCTR0_DBG0	✓	✓	
ACCTR0_DBG1	✓	✓	

Table 6.1. Pin Definitions and Alternate Functions for SiM3L1x7 (Continued)

Pin Name	Type	Pin Numbers (TQFP-80)	I/O Voltage Domain	Crossbar Capability	Port Match	LCD Interface	Output Toggle Logic	External Trigger Inputs / Digital Functions	Analog Functions
PB1.8	Standard I/O	58	VIO	✓	✓	LCD0.31			CMP0P.3
PB1.9	Standard I/O	57	VIO	✓	✓	LCD0.30			CMP0N.3
PB1.10	Standard I/O	56	VIO	✓	✓	LCD0.29			CMP1P.3
PB1.11	Standard I/O	55	VIO	✓	✓	LCD0.28			CMP1N.3
PB2.0	Standard I/O	54	VIORF	✓	✓			LPT0T8 INT1.0 WAKE.12 SPI1_CTS	ADC0.8 CMP0P.4
PB2.1	Standard I/O	53	VIORF	✓	✓			LPT0T9 INT1.1 WAKE.13 VIORFCLK	ADC0.9 CMP0N.4
PB2.4	Standard I/O	51	VIORF	✓	✓			LPT0T12 INT1.4 SPI1_SCLK	ADC0.10 CMP0P.5
PB2.5	Standard I/O	50	VIORF	✓	✓			LPT0T13 INT1.5 SPI1_MISO	ADC0.11 CMP0N.5
PB2.6	Standard I/O	49	VIORF	✓	✓			LPT0T14 INT1.6 SPI1_MOSI	ADC0.12 CMP1P.5
PB2.7	Standard I/O	48	VIORF	✓	✓			INT1.7 SPI1_NSS	ADC0.13 CMP1N.5
PB3.0	Standard I/O	47	VIO	✓	✓	LCD0.27		INT1.8	ADC0.14
PB3.1	Standard I/O	46	VIO	✓	✓	LCD0.26		INT1.9	ADC0.15
PB3.2	Standard I/O	45	VIO	✓	✓	LCD0.25		INT1.10	ADC0.16
PB3.3	Standard I/O	44	VIO	✓	✓	LCD0.24		INT1.11	ADC0.17

6.2. SiM3L1x6 Pin Definitions

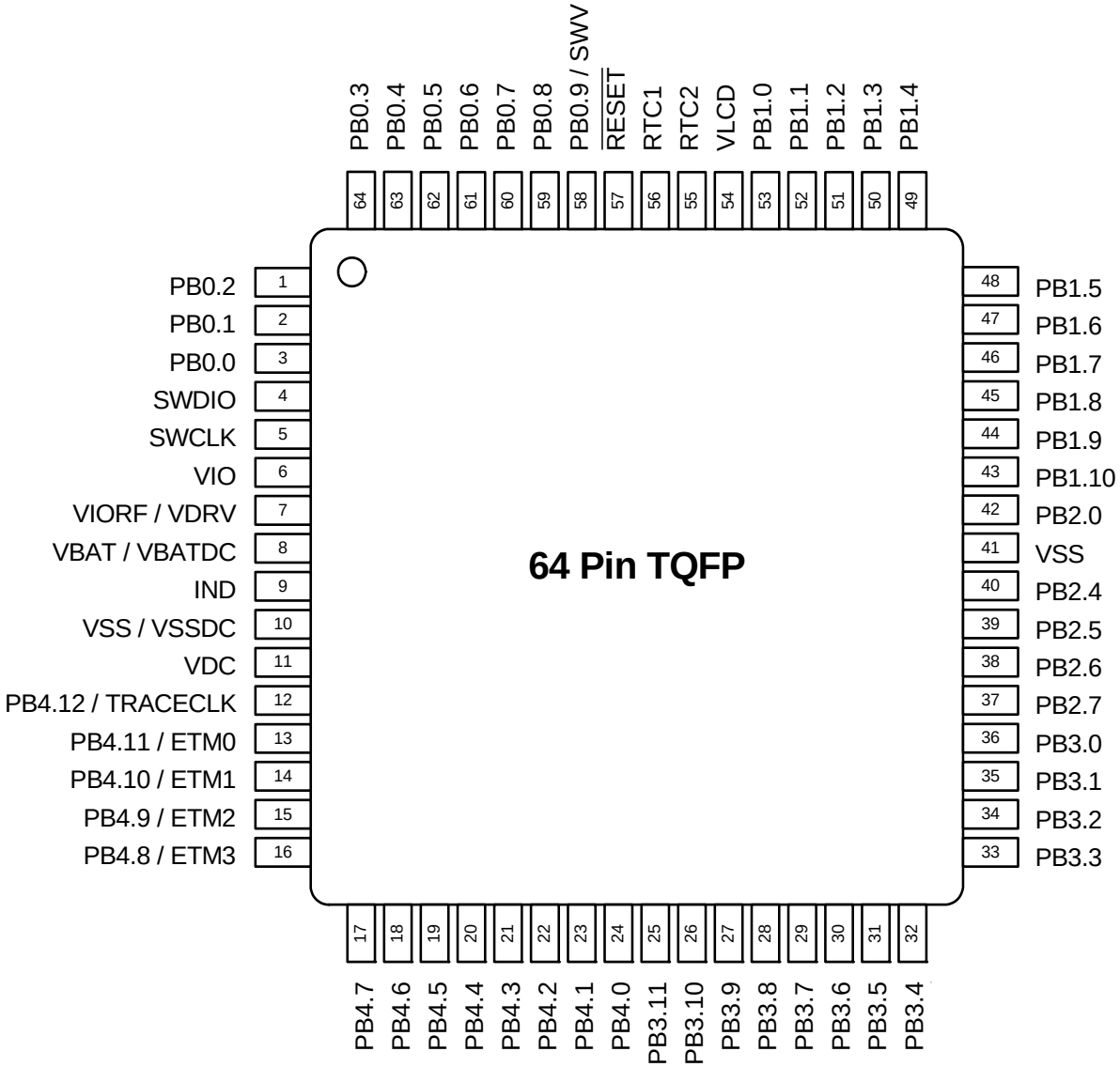

Figure 6.2. SiM3L1x6-GQ Pinout

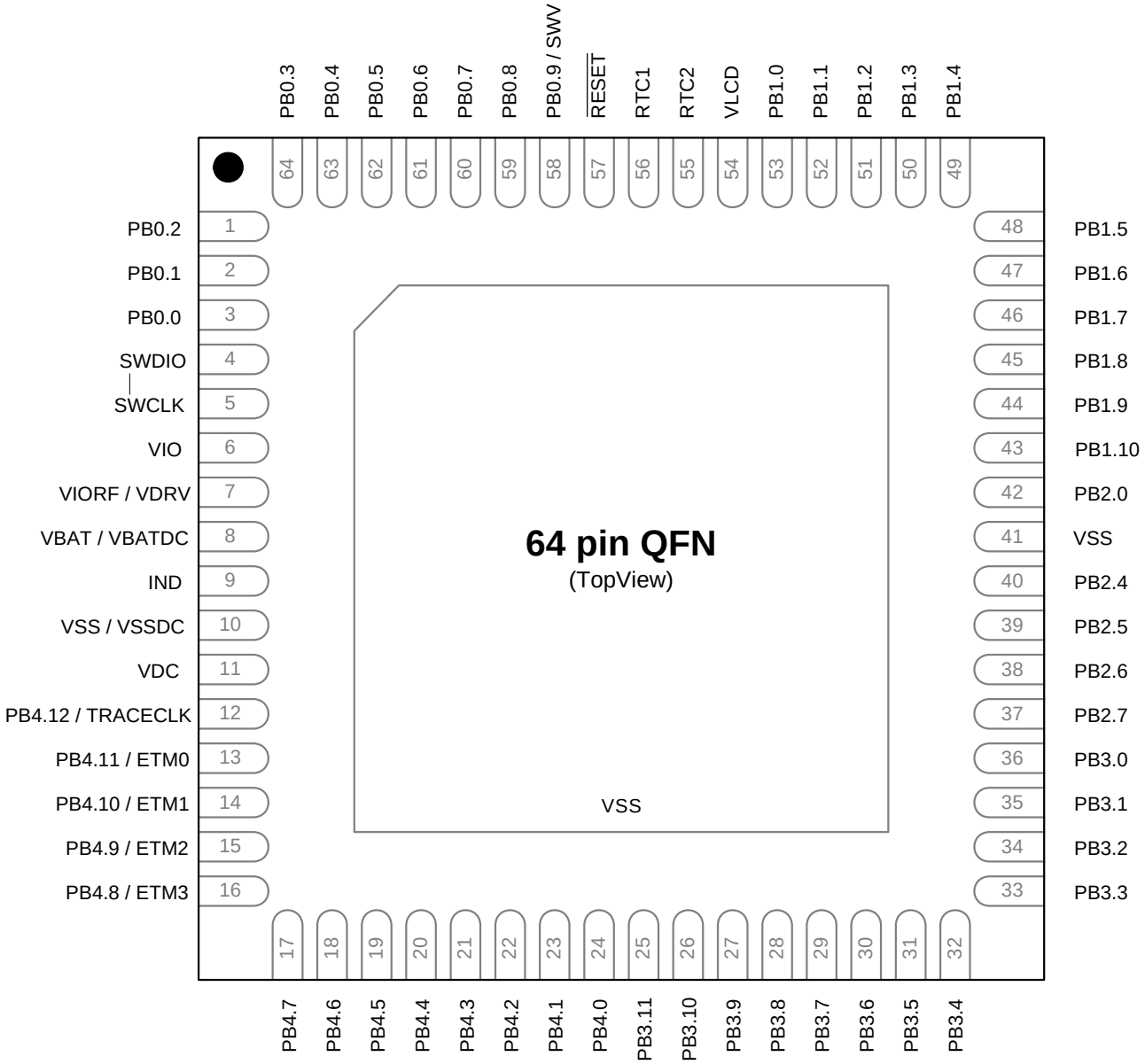

Figure 6.3. SiM3L1x6-GM Pinout

Table 6.2. Pin Definitions and Alternate Functions for SiM3L1x6 (Continued)

Pin Name	Type	Pin Numbers	I/O Voltage Domain	Crossbar Capability	Port Match	LCD Interface	Output Toggle Logic	External Trigger Inputs / Digital Functions	Analog Functions
PB1.1	Standard I/O	52	VIO	XBR0	✓	LCD0.30		LPT0T5 INT0.13 ACCTR0_LCBIAS1	CMP0N.2
PB1.2	Standard I/O	51	VIO	XBR0	✓	LCD0.29		LPT0T6 INT0.14 UART0_TX	CMP1P.2
PB1.3	Standard I/O	50	VIO	XBR0	✓	LCD0.28		LPT0T7 INT0.15 UART0_RX	CMP1N.2
PB1.4	Standard I/O	49	VIO	XBR0	✓	LCD0.27		ACCTR0_DBG0	ADC0.3
PB1.5	Standard I/O	48	VIO	XBR0	✓	LCD0.26		ACCTR0_DBG1	ADC0.4
PB1.6	Standard I/O	47	VIO	XBR0	✓	LCD0.25		RTC0TCLK_OUT	ADC0.5
PB1.7	Standard I/O	46	VIO	XBR0	✓	LCD0.24			CMP0P.3
PB1.8	Standard I/O	45	VIO	XBR0	✓	LCD0.23			CMP0N.3
PB1.9	Standard I/O	44	VIO	XBR0	✓	LCD0.22			CMP1P.3
PB1.10	Standard I/O	43	VIO	XBR0	✓	LCD0.21			CMP1N.3
PB2.0	Standard I/O	42	VIORF	XBR0	✓			LPT0T8 INT1.0 WAKE.12 SPI1_CTS	ADC0.6 CMP0P.4
PB2.4	Standard I/O	40	VIORF	XBR0	✓			LPT0T12 INT1.4 SPI1_SCLK	ADC0.7 CMP0P.5

Table 6.2. Pin Definitions and Alternate Functions for SiM3L1x6 (Continued)

Pin Name	Type	Pin Numbers	I/O Voltage Domain	Crossbar Capability	Port Match	LCD Interface	Output Toggle Logic	External Trigger Inputs / Digital Functions	Analog Functions
PB2.5	Standard I/O	39	VIORF	XBR0	✓			LPT0T13 INT1.5 SPI1_MISO	ADC0.8 CMP0N.5
PB2.6	Standard I/O	38	VIORF	XBR0	✓			LPT0T14 INT1.6 SPI1_MOSI	ADC0.9 CMP1P.5
PB2.7	Standard I/O	37	VIORF	XBR0	✓			INT1.7 SPI1_NSS	ADC0.10 CMP1N.5
PB3.0	Standard I/O	36	VIO	XBR0	✓	LCD0.20		INT1.8	ADC0.11
PB3.1	Standard I/O	35	VIO	XBR0	✓	LCD0.19		INT1.9	ADC0.12
PB3.2	Standard I/O	34	VIO	XBR0	✓	LCD0.18		INT1.10	CMP0P.6
PB3.3	Standard I/O	33	VIO	XBR0	✓	LCD0.17		INT1.11	CMP0N.6
PB3.4	Standard I/O	32	VIO	XBR0	✓	LCD0.16		INT1.12	CMP0P.7
PB3.5	Standard I/O	31	VIO	XBR0	✓	LCD0.15		INT1.13	CMP0N.7
PB3.6	Standard I/O	30	VIO	XBR0	✓	LCD0.14		INT1.14	CMP1P.7
PB3.7	Standard I/O	29	VIO	XBR0	✓	LCD0.13		INT1.15	CMP1N.7
PB3.8	Standard I/O	28	VIO		✓	LCD0.12			ADC0.13
PB3.9	Standard I/O	27	VIO		✓	LCD0.11			ADC0.14
PB3.10	Standard I/O	26	VIO		✓	COM0.3			
PB3.11	Standard I/O	25	VIO		✓	COM0.2			

Table 6.2. Pin Definitions and Alternate Functions for SiM3L1x6 (Continued)

Pin Name	Type	Pin Numbers	I/O Voltage Domain	Crossbar Capability	Port Match	LCD Interface	Output Toggle Logic	External Trigger Inputs / Digital Functions	Analog Functions
PB4.0	Standard I/O	24	VIO		✓	COM0.1			
PB4.1	Standard I/O	23	VIO		✓	COM0.0			
PB4.2	Standard I/O	22	VIO		✓	LCD0.10			ADC0.19
PB4.3	Standard I/O	21	VIO		✓	LCD0.9			
PB4.4	Standard I/O	20	VIO		✓	LCD0.8			
PB4.5	Standard I/O	19	VIO		✓	LCD0.7			
PB4.6	Standard I/O	18	VIO		✓	LCD0.6		PMU_Asleep	
PB4.7	Standard I/O	17	VIO		✓	LCD0.5			
PB4.8/ETM3	Standard I/O / ETM	16	VIO		✓	LCD0.4			
PB4.9/ETM2	Standard I/O / ETM	15	VIO		✓	LCD0.3			
PB4.10/ ETM1	Standard I/O / ETM	14	VIO		✓	LCD0.2			
PB4.11/ ETM0	Standard I/O / ETM	13	VIO		✓	LCD0.1			
PB4.12/ TRACECLK	Standard I/O / ETM	12	VIO		✓	LCD0.0			

6.3. SiM3L1x4 Pin Definitions

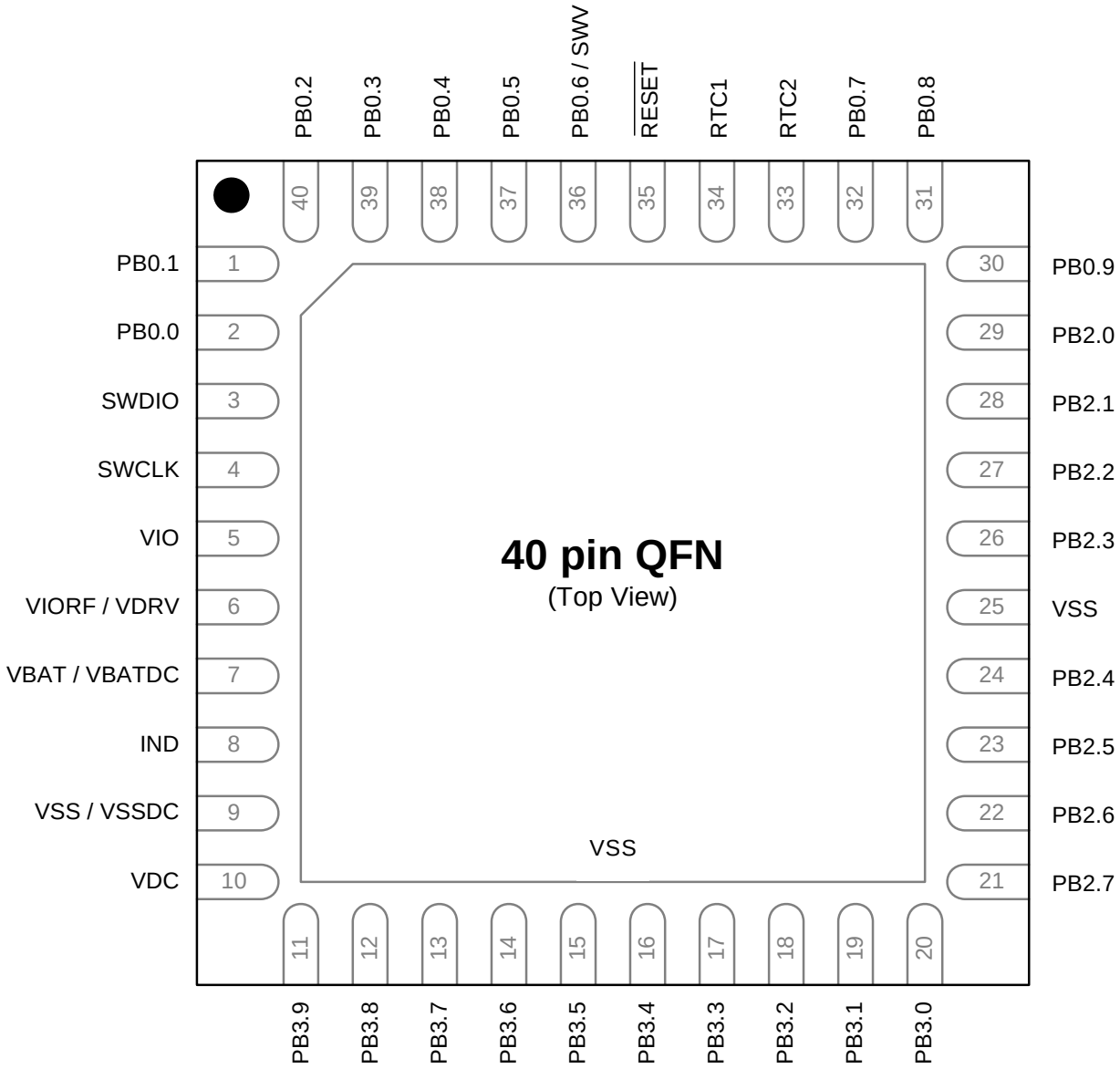

Figure 6.4. SiM3L1x4-GM Pinout

Table 6.3. Pin Definitions and Alternate Functions for SiM3L1x4 (Continued)

Pin Name	Type	Pin Numbers	I/O Voltage Domain	Crossbar Capability	Port Match	Output Toggle Logic	External Trigger Inputs / Digital Functions	Analog Functions
PB0.2	Standard I/O	40	VIO	XBR0	✓	✓	INT0.2 WAKE.3	ADC0.23 CMP0N.1 CMP1N.0 XTAL1
PB0.3	Standard I/O	39	VIO	XBR0	✓	✓	INT0.3 WAKE.4	ADC0.0 CMP0P.1 IDAC0
PB0.4	Standard I/O	38	VIO	XBR0	✓	✓	INT0.4 WAKE.5	ACCTR0_IN0
PB0.5	Standard I/O	37	VIO	XBR0	✓	✓	INT0.5 WAKE.6	ACCTR0_IN1
PB0.6/SWV	Standard I/O /Serial Wire Viewer	36	VIO	XBR0	✓	✓	LPT0T0 LPT0OUT0 INT0.6 WAKE.8	
PB0.7	Standard I/O	32	VIO	XBR0	✓	✓	LPT0T6 INT0.7 UART0_TX	CMP1P.2
PB0.8	Standard I/O	31	VIO	XBR0	✓	✓	LPT0T7 INT0.8 UART0_RX	CMP1N.2
PB0.9	Standard I/O	30	VIO	XBR0	✓	✓	LPT0T1 INT0.9 RTC0TCLK_OUT	ADC0.1
PB2.0	Standard I/O	29	VIORF	XBR0	✓		LPT0T8 INT1.0 WAKE.12 SPI1_CTS	ADC0.2 CMP0P.4

Table 6.3. Pin Definitions and Alternate Functions for SiM3L1x4 (Continued)

Pin Name	Type	Pin Numbers	I/O Voltage Domain	Crossbar Capability	Port Match	Output Toggle Logic	External Trigger Inputs / Digital Functions	Analog Functions
PB3.6	Standard I/O	14	VIO	XBR0	✓		INT1.14	ADC0.13
PB3.7	Standard I/O	13	VIO	XBR0	✓		INT1.15	ADC0.14
PB3.8	Standard I/O	12	VIO		✓			ADC0.15
PB3.9	Standard I/O	11	VIO		✓			ADC0.16

6.4. TQFP-80 Package Specifications

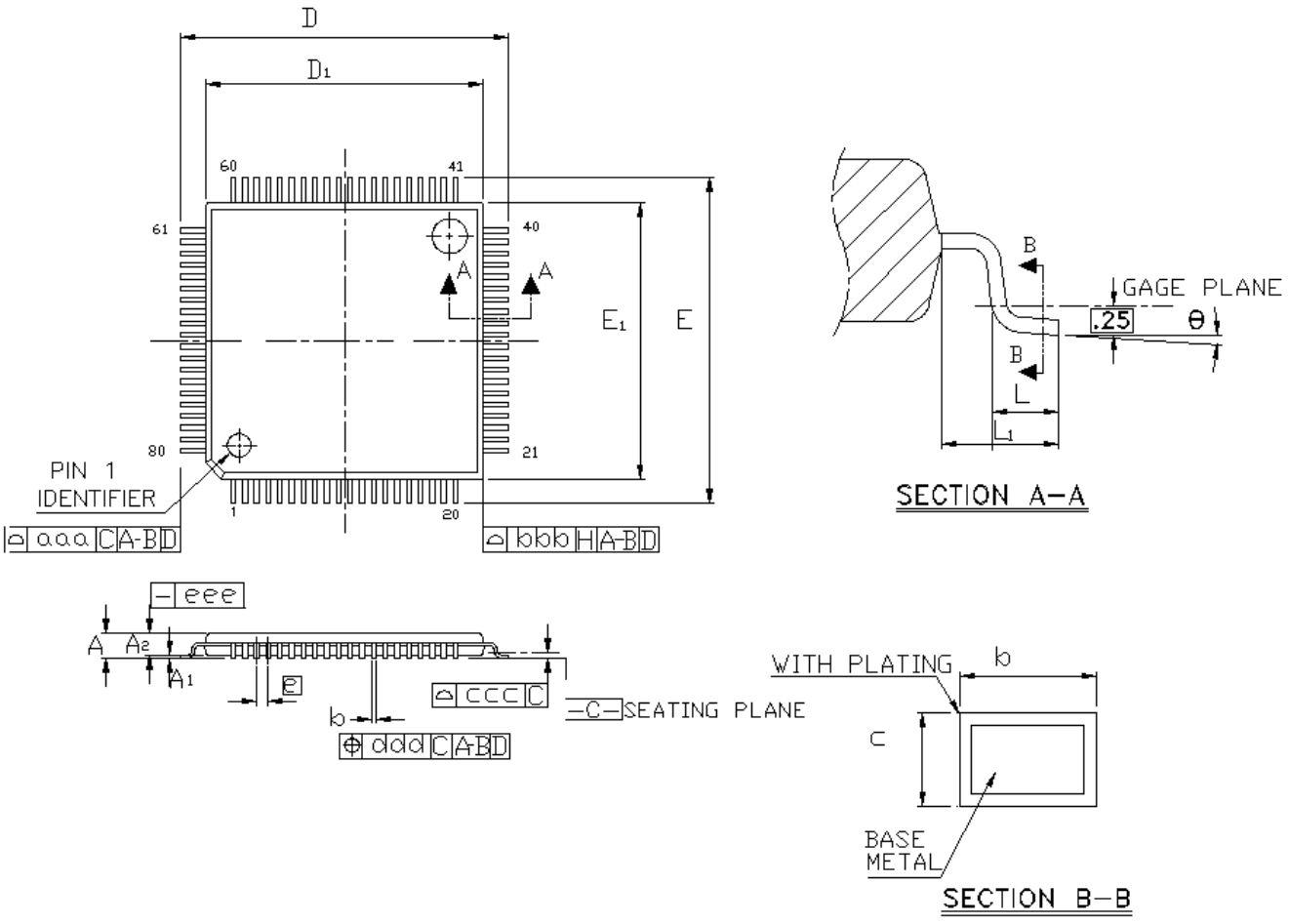

Figure 6.5. TQFP-80 Package Drawing

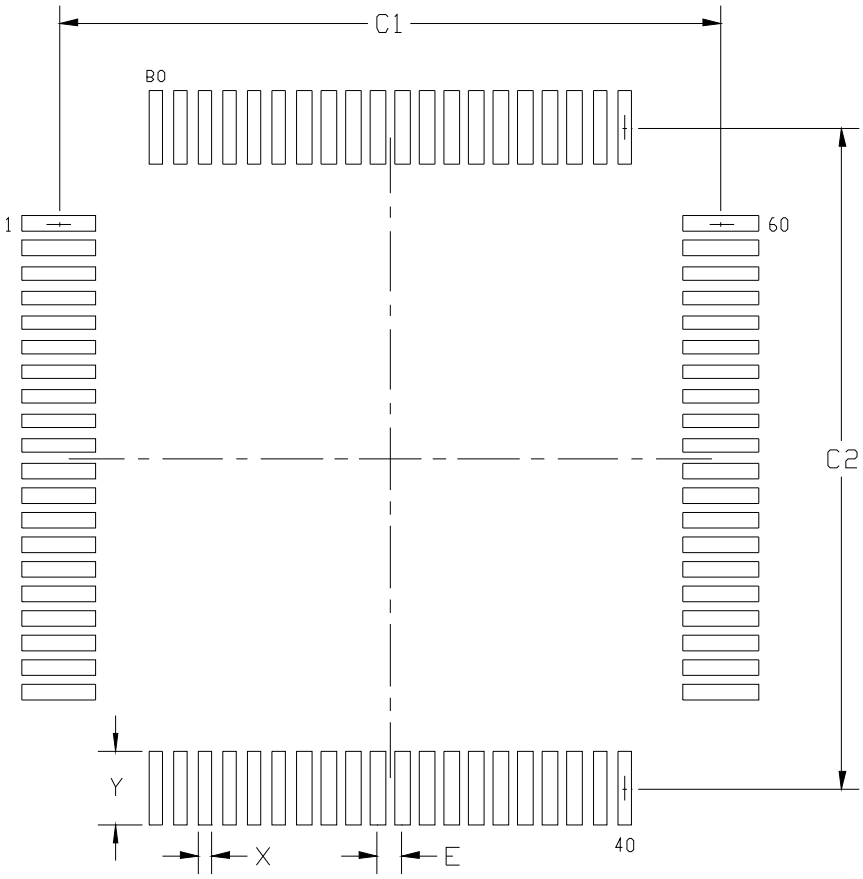

Figure 6.6. TQFP-80 Landing Diagram

Table 6.5. TQFP-80 Landing Diagram Dimensions

Dimension	Min	Max
C1	13.30	13.40
C2	13.30	13.40
E	0.50 BSC	
X	0.20	0.30
Y	1.40	1.50

Notes:
1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. This land pattern design is based on the IPC-7351 guidelines.