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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	8051
Core Size	8-Bit
Speed	18MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LED, POR, PWM, WDT
Number of I/O	14
Program Memory Size	2KB (2K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 3.6V
Data Converters	A/D 4x8b; D/A 1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	16-TSSOP (0.173", 4.40mm Width)
Supplier Device Package	16-TSSOP
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/p89lpc916fdh-118

- Serial Flash In-Circuit Programming (ICP) allows simple production coding with commercial EPROM programmers. Flash security bits prevent reading of sensitive application programs.
- Watchdog timer with separate on-chip oscillator, requiring no external components. The Watchdog prescaler is selectable from 8 values.
- Low voltage brownout detect allows a graceful system shutdown when power fails. May optionally be configured as an interrupt.
- Idle and two different power-down reduced power modes. Improved wake-up from Power-down mode (a LOW interrupt input starts execution). Typical power-down current is 1 μA (total power-down with voltage comparators disabled).
- Active-LOW reset. On-chip power-on reset allows operation without external reset components. A reset counter and reset glitch suppression circuitry prevent spurious and incomplete resets. A software reset function is also available.
- Programmable port output configuration options: quasi-bidirectional, open drain, push-pull, input-only.
- Port ‘input pattern match’ detect. Port 0 may generate an interrupt when the value of the pins match or do not match a programmable pattern.
- LED drive capability (20 mA) on all port pins. A maximum limit is specified for the entire chip.
- Controlled slew rate port outputs to reduce EMI. Outputs have approximately 10 ns minimum ramp times.
- Only power and ground connections are required to operate the P89LPC915/916/917 when internal reset option is selected.
- Four interrupt priority levels.
- Five (P89LPC916), six (P89LPC915), or seven (P89LPC917) keypad interrupt inputs.
- Second data pointer.
- Schmitt trigger port inputs.
- Emulation support.

3. Product comparison overview

Table 1 highlights the differences between these three devices. For a complete list of device features, please see Section 2 “Features”.

Table 1. Product comparison overview

Type number	Comparator 2 output	SPI	T1 toggle/PWM	CLKOUT	$\overline{\text{INT1}}$	KBI
P89LPC915	X	-	-	-	X	6
P89LPC916	-	X	-	-	-	5
P89LPC917	X	-	X	X	X	7

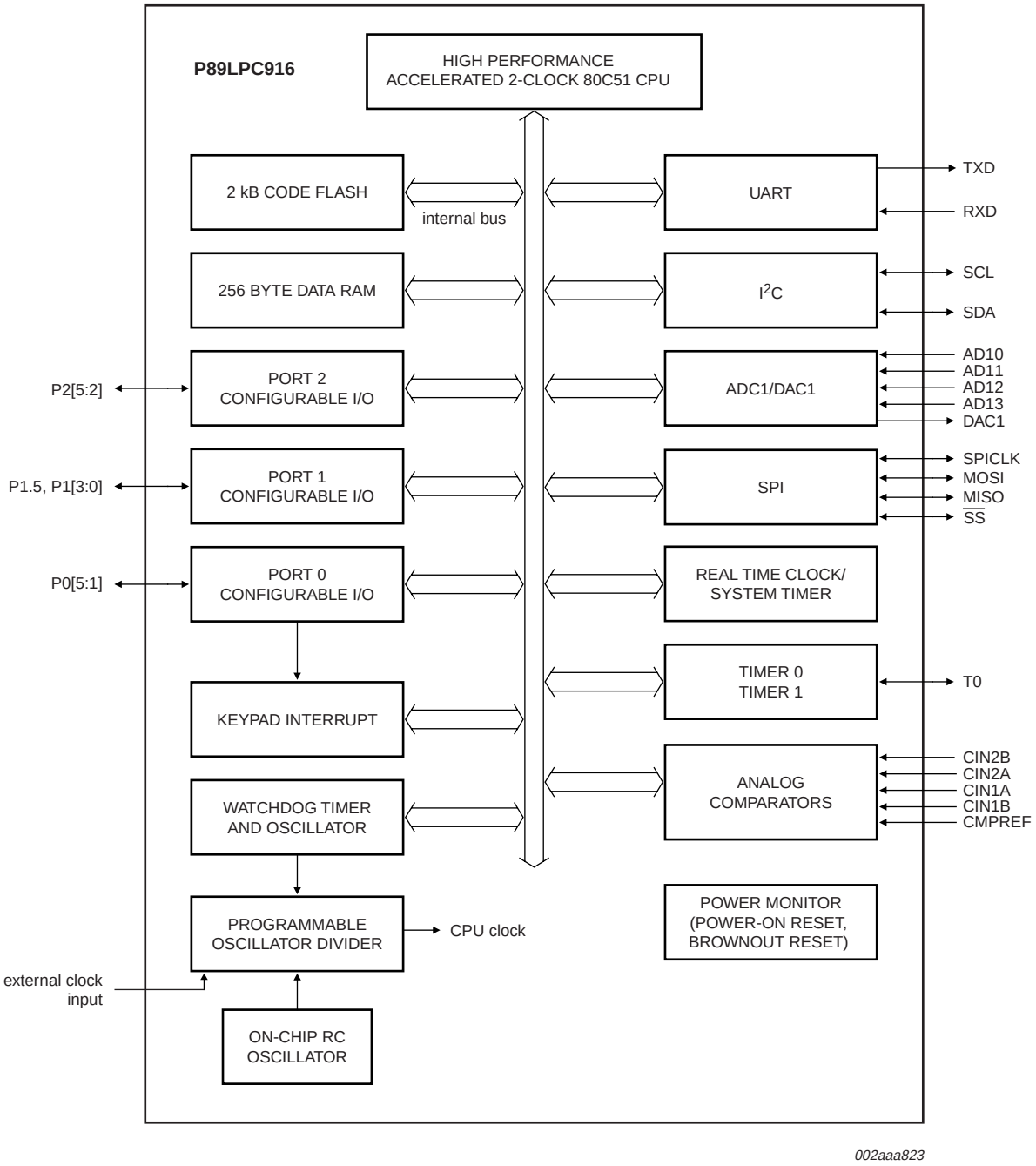

Fig 2. P89LPC916 block diagram

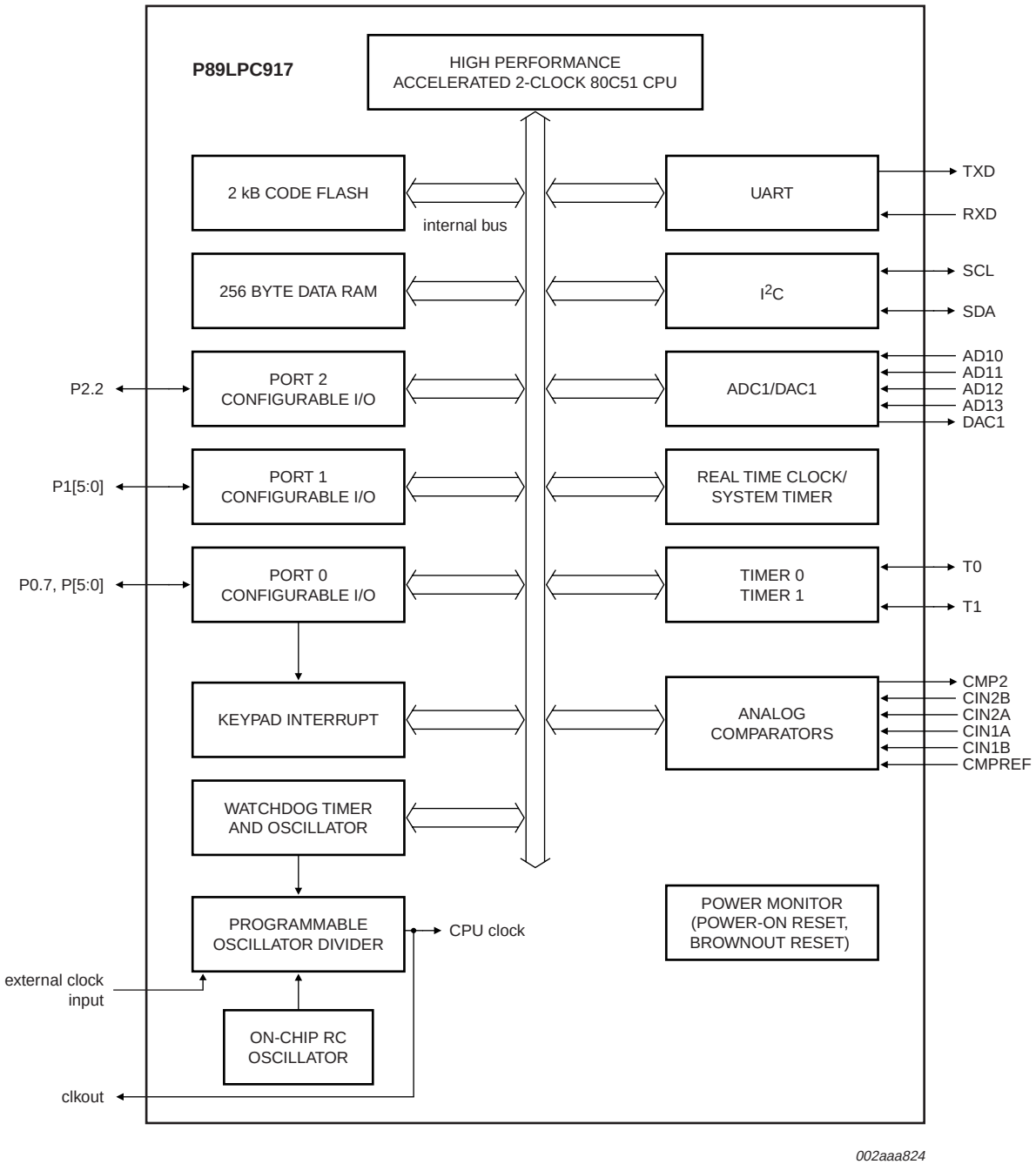

Fig 3. P89LPC917 block diagram

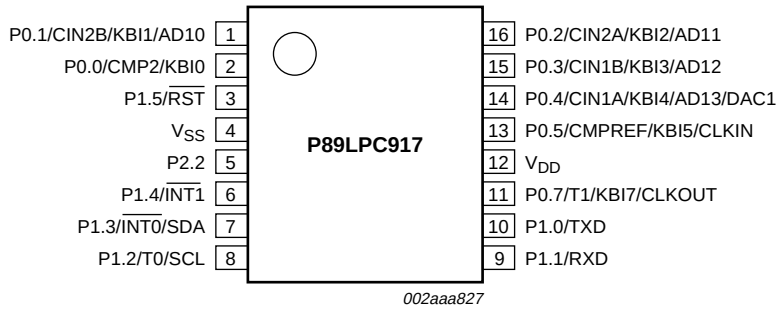

Fig 10. P89LPC917 TSSOP16 pin configuration

Table 7. P89LPC915 special function registers *…continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
FMCON	Program flash control (Read)	E4H	BUSY	-	-	-	HVA	HVE	SV	OI	70	0111 0000
	Program flash control (Write)	E4H	FMCMD.7	FMCMD.6	FMCMD.5	FMCMD.4	FMCMD.3	FMCMD.2	FMCMD.1	FMCMD.0		
FMDATA	Program flash data	E5H									00	0000 0000
I2ADR	I^2C slave address register	DBH	I2ADR.6	I2ADR.5	I2ADR.4	I2ADR.3	I2ADR.2	I2ADR.1	I2ADR.0	GC	00	0000 0000
	Bit address		**DF**	**DE**	**DD**	**DC**	**DB**	**DA**	**D9**	**D8**		
I2CON*	I^2C control register	D8H	-	I2EN	STA	STO	SI	AA	-	CRSEL	00	x000 00x0
I2DAT	I^2C data register	DAH										
I2SCLH	Serial clock generator/SCL duty cycle register high	DDH									00	0000 0000
I2SCLL	Serial clock generator/SCL duty cycle register low	DCH									00	0000 0000
I2STAT	I^2C status register	D9H	STA.4	STA.3	STA.2	STA.1	STA.0	0	0	0	F8	1111 1000
	Bit address		**AF**	**AE**	**AD**	**AC**	**AB**	**AA**	**A9**	**A8**		
IEN0*	Interrupt enable 0	A8H	EA	EWDRT	EBO	ES/ESR	ET1	EX1	ET0	EX0	00	0000 0000
	Bit address		**EF**	**EE**	**ED**	**EC**	**EB**	**EA**	**E9**	**E8**		
IEN1*	Interrupt enable 1	E8H	EAD	EST	-	-	-	EC	EKBI	EI2C	00[1]	00x0 0000
	Bit address		**BF**	**BE**	**BD**	**BC**	**BB**	**BA**	**B9**	**B8**		
IP0*	Interrupt priority 0	B8H	-	PWDRT	PBO	PS/PSR	PT1	PX1	PT0	PX0	00[1]	x000 0000
IP0H	Interrupt priority 0 high	B7H	-	PWDRTH	PBOH	PSH/PSRH	PT1H	PX1H	PT0H	PX0H	00[1]	x000 0000
	Bit address		**FF**	**FE**	**FD**	**FC**	**FB**	**FA**	**F9**	**F8**		
IP1*	Interrupt priority 1	F8H	PAD	PST	-	-	-	PC	PKBI	PI2C	00[1]	00x0 0000
IP1H	Interrupt priority 1 high	F7H	PADH	PSTH	-	-	-	PCH	PKBIH	PI2CH	00[1]	00x0 0000
KBCON	Keypad control register	94H	-	-	-	-	-	-	PATN_SEL	KBIF	00[1]	xxxx xx00
KBMASK	Keypad interrupt mask register	86H									00	0000 0000
KBPATN	Keypad pattern register										FF	1111 1111

Table 8. P89LPC916 special function registers *…continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
FMCON	Program flash control (Read)	E4H	BUSY	-	-	-	HVA	HVE	SV	OI	70	0111 0000
	Program flash control (Write)	E4H	FMCMD.7	FMCMD.6	FMCMD.5	FMCMD.4	FMCMD.3	FMCMD.2	FMCMD.1	FMCMD.0		
FMDATA	Program flash data	E5H									00	0000 0000
I2ADR	I^2C slave address register	DBH	I2ADR.6	I2ADR.5	I2ADR.4	I2ADR.3	I2ADR.2	I2ADR.1	I2ADR.0	GC	00	0000 0000
	Bit address		**DF**	**DE**	**DD**	**DC**	**DB**	**DA**	**D9**	**D8**		
I2CON*	I^2C control register	D8H	-	I2EN	STA	STO	SI	AA	-	CRSEL	00	x000 00x0
I2DAT	I^2C data register	DAH										
I2SCLH	Serial clock generator/SCL duty cycle register high	DDH									00	0000 0000
I2SCLL	Serial clock generator/SCL duty cycle register low	DCH									00	0000 0000
I2STAT	I^2C status register	D9H	STA.4	STA.3	STA.2	STA.1	STA.0	0	0	0	F8	1111 1000
	Bit address		**AF**	**AE**	**AD**	**AC**	**AB**	**AA**	**A9**	**A8**		
IEN0*	Interrupt enable 0	A8H	EA	EWDRT	EBO	ES/ESR	ET1	-	ET0	EX0	00	0000 0000
	Bit address		**EF**	**EE**	**ED**	**EC**	**EB**	**EA**	**E9**	**E8**		
IEN1*	Interrupt enable 1	E8H	EAD	EST	-	-	ESPI	EC	EKBI	EI2C	00[1]	00x0 0000
	Bit address		**BF**	**BE**	**BD**	**BC**	**BB**	**BA**	**B9**	**B8**		
IP0*	Interrupt priority 0	B8H	-	PWDRT	PBO	PS/PSR	PT1	-	PT0	PX0	00[1]	x000 0000
IP0H	Interrupt priority 0 high	B7H	-	PWDRTH	PBOH	PSH/PSRH	PT1H	-	PT0H	PX0H	00[1]	x000 0000
	Bit address		**FF**	**FE**	**FD**	**FC**	**FB**	**FA**	**F9**	**F8**		
IP1*	Interrupt priority 1	F8H	PAD	PST	-	-	PSPI	PC	PKBI	PI2C	00[1]	00x0 0000
IP1H	Interrupt priority 1 high	F7H	PADH	PSTH	-	-	PSPIH	PCH	PKBIH	PI2CH	00[1]	00x0 0000
KBCON	Keypad control register	94H	-	-	-	-	-	-	PATN_SEL	KBIF	00[1]	xxxx xx00
KBMASK	Keypad interrupt mask register	86H									00	0000 0000
KBPATN	Keypad pattern register										FF	1111 1111

Table 8. P89LPC916 special function registers *…continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
		Bit address	**87**	**86**	**85**	**84**	**83**	**82**	**81**	**80**		
P0*	Port 0	80H	-	-	CMPREF /KB5	CIN1A /KB4	CIN1B /KB3	CIN2A /KB2	CIN2B /KB1	-	[1]	
		Bit address	**97**	**96**	**95**	**94**	**93**	**92**	**91**	**90**		
P1*	Port 1	90H	-	-	$\overline{RST}$	-	$\overline{INT0}$/ SDA	T0/SCL	RXD	TXD	[1]	
		Bit address	**A7**	**A6**	**A5**	**A4**	**A3**	**A2**	**A1**	**A0**		
P2*	Port 2	A0H	-	-	SPICLK	$\overline{SS}$	MISO	MOSI	-	-	[1]	
P0M1	Port 0 output mode 1	84H	(P0M1.7)	(P0M1.6)	(P0M1.5)	(P0M1.4)	(P0M1.3)	(P0M1.2)	(P0M1.1)	(P0M1.0)	FF[1]	1111 1111
P0M2	Port 0 output mode 2	85H	(P0M2.7)	(P0M2.6)	(P0M2.5)	(P0M2.4)	(P0M2.3)	(P0M2.2)	(P0M2.1)	(P0M2.0)	00[1]	0000 0000
P1M1	Port 1 output mode 1	91H	(P1M1.7)	(P1M1.6)	-	(P1M1.4)	(P1M1.3)	(P1M1.2)	(P1M1.1)	(P1M1.0)	D3[1]	11x1 xx11
P1M2	Port 1 output mode 2	92H	(P1M2.7)	(P1M2.6)	-	(P1M2.4)	(P1M2.3)	(P1M2.2)	(P1M2.1)	(P1M2.0)	00[1]	00x0 xx00
P2M1	Port 2 output mode 1	A4H	-	-	(P2M1.5)	(P2M1.4)	(P2M1.3)	(P2M1.2)	-	-	FF[1]	11x1 xx11
P2M2	Port 2 output mode 2	A5H	-	-	(P2M2.5)	(P2M2.4)	(P2M2.3)	(P2M2.2)	-	-	00[1]	00x0 xx00
PCON	Power control register	87H	SMOD1	SMOD0	BOPD	BOI	GF1	GF0	PMOD1	PMOD0	00	0000 0000
PCONA	Power control register A	B5H	RTCPD	-	VCPD	ADPD	I2PD	SPPD	SPD	-	00[1]	0000 0000
		Bit address	**D7**	**D6**	**D5**	**D4**	**D3**	**D2**	**D1**	**D0**		
PSW*	Program status word	D0H	CY	AC	F0	RS1	RS0	OV	F1	P	00	0000 0000
PT0AD	Port 0 digital input disable	F6H	-	-	PT0AD.5	PT0AD.4	PT0AD.3	PT0AD.2	PT0AD.1	-	00	xx00 000x
RSTSRC	Reset source register	DFH	-	-	BOF	POF	R_BK	R_WD	R_SF	R_EX	[3]	
RTCCON	RTC control	D1H	RTCF	RTCS1	RTCS0	-	-	-	ERTC	RTCEN	60[1][6]	011x xx00
RTCH	RTC register high	D2H									00[6]	0000 0000
RTCL	RTC register low	D3H									00[6]	0000 0000
SADDR	Serial port address register	A9H									00	0000 0000
SADEN	Serial port address enable	B9H									00	0000 0000
SBUF	Serial Port data buffer register	99H									xx	xxxx xxxx
		Bit address	**9F**	**9E**	**9D**	**9C**	**9B**	**9A**	**99**	**98**		
SCON*	Serial port control	98H	SM0/FE	SM1	SM2	REN	TB8	RB8	TI	RI	00	0000 0000

Table 9. P89LPC917 special function registers *…continued*

** indicates SFRs that are bit addressable.*

Name	Description	SFR addr.	Bit functions and addresses								Reset value	
			MSB							LSB	Hex	Binary
		Bit address	**87**	**86**	**85**	**84**	**83**	**82**	**81**	**80**		
P0*	Port 0	80H	T1/KB7/ CLKOUT	-	CMPREF /KB5	CIN1A /KB4	CIN1B /KB3	CIN2A /KB2	CIN2B /KB1	CMP2 /KB0	[1]	
		Bit address	**97**	**96**	**95**	**94**	**93**	**92**	**91**	**90**		
P1*	Port 1	90H	-	-	$\overline{\text{RST}}$	$\overline{\text{INT1}}$	$\overline{\text{INT0}}$/ SDA	T0/SCL	RXD	TXD	[1]	
		Bit address	**B7**	**B6**	**B5**	**B4**	**B3**	**B2**	**B1**	**B0**		
P0M1	Port 0 output mode 1	84H	(P0M1.7)	-	(P0M1.5)	(P0M1.4)	(P0M1.3)	(P0M1.2)	(P0M1.1)	(P0M1.0)	FF[1]	1111 1111
P0M2	Port 0 output mode 2	85H	(P0M2.7)	-	(P0M2.5)	(P0M2.4)	(P0M2.3)	(P0M2.2)	(P0M2.1)	(P0M2.0)	00[1]	0000 0000
P1M1	Port 1 output mode 1	91H	-	-	-	(P1M1.4)	(P1M1.3)	(P1M1.2)	(P1M1.1)	(P1M1.0)	D3[1]	11x1 xx11
P1M2	Port 1 output mode 2	92H	-	-	-	(P1M2.4)	(P1M2.3)	(P1M2.2)	(P1M2.1)	(P1M2.0)	00[1]	00x0 xx00
PCON	Power control register	87H	SMOD1	SMOD0	BOPD	BOI	GF1	GF0	PMOD1	PMOD0	00	0000 0000
PCONA	Power control register A	B5H	RTCPD	-	VCPD	ADPD	I2PD	-	SPD	-	00[1]	0000 0000
		Bit address	**D7**	**D6**	**D5**	**D4**	**D3**	**D2**	**D1**	**D0**		
PSW*	Program status word	D0H	CY	AC	F0	RS1	RS0	OV	F1	P	00	0000 0000
PT0AD	Port 0 digital input disable	F6H	-	-	PT0AD.5	PT0AD.4	PT0AD.3	PT0AD.2	PT0AD.1	-	00	xx00 000x
RSTSRC	Reset source register	DFH	-	-	BOF	POF	R_BK	R_WD	R_SF	R_EX	[3]	
RTCCON	RTC control	D1H	RTCF	RTCS1	RTCS0	-	-	-	ERTC	RTCEN	60[1][6]	011x xx00
RTCH	RTC register high	D2H									00[6]	0000 0000
RTCL	RTC register low	D3H									00[6]	0000 0000
SADDR	Serial port address register	A9H									00	0000 0000
SADEN	Serial port address enable	B9H									00	0000 0000
SBUF	Serial Port data buffer register	99H									xx	xxxx xxxx
		Bit address	**9F**	**9E**	**9D**	**9C**	**9B**	**9A**	**99**	**98**		
SCON*	Serial port control	98H	SM0/FE	SM1	SM2	REN	TB8	RB8	TI	RI	00	0000 0000
SSTAT	Serial port extended status register	BAH	DBMOD	INTLO	CIDIS	DBISEL	FE	BR	OE	STINT	00	0000 0000
SP	Stack pointer	81H									07	0000 0111
TAMOD	Timer 0 and 1 auxiliary mode	8FH	-	-	-	T1M2	-	-	-	T0M2	00	xxx0 xxx0

8.6 External clock input option

In this configuration, the processor clock is derived from an external source driving the CLKIN pin. The rate may be from 0 Hz up to 18 MHz.

When using an external clock input frequency above 12 MHz, the reset input function of P1.5 must be enabled. An external circuit is required to hold the device in reset at power-up until V_{DD} has reached its specified level. When system power is removed V_{DD} will fall below the minimum specified operating voltage. When using an external clock input frequency above 12 MHz, in some applications, an external brownout detect circuit may be required to hold the device in reset when V_{DD} falls below the minimum specified operating voltage.

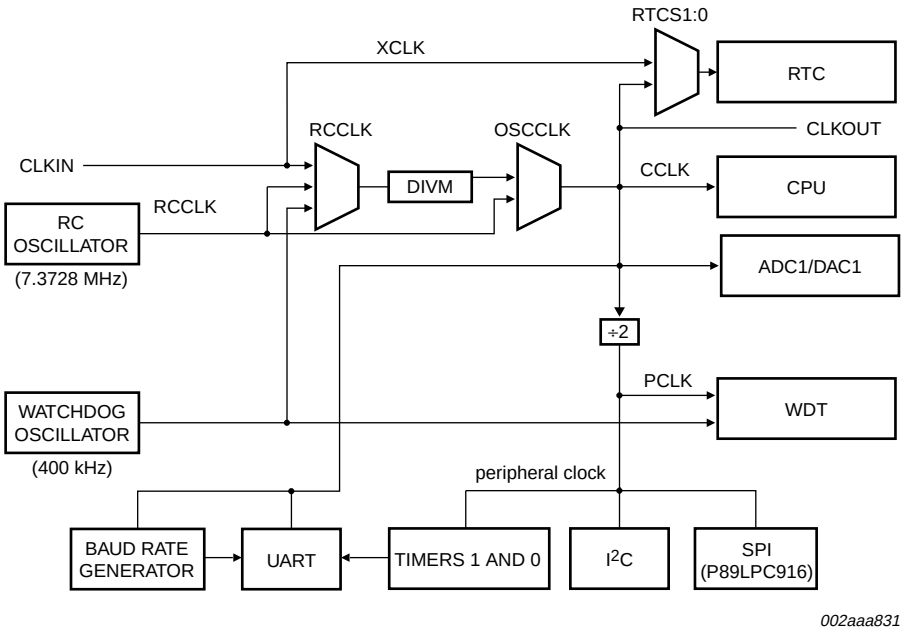

Fig 11. Block diagram of oscillator control

8.7 CCLK wake-up delay

The P89LPC915/916/917 has an internal wake-up timer that delays the clock until it stabilizes. The delay is 224 OSCCLK cycles plus 60 µs to 100 µs.

8.8 CCLK modification: DIVM register

The OSCCLK frequency can be divided down up to 510 times by configuring a dividing register, DIVM, to generate CCLK. This feature makes it possible to temporarily run the CPU at a lower rate, reducing power consumption. By dividing the clock, the CPU can retain the ability to respond to events that would not exit Idle mode by executing its normal program at a lower rate. This can also allow bypassing the oscillator start-up time in cases where Power-down mode would otherwise be used. The value of DIVM may be changed by the program at any time without interrupting code execution.

8.9 Low power select

The P89LPC915/916/917 is designed to run at 18 MHz (CCLK) maximum. However, if CCLK is 8 MHz or slower, the CLKLP SFR bit (AUXR1.7) can be set to '1' to lower the power consumption further. On any reset, CLKLP is '0' allowing highest performance access. This bit can then be set in software if CCLK is running at 8 MHz or slower.

8.10 Memory organization

The various P89LPC915/916/917 memory spaces are as follows:

- DATA

  128 bytes of internal data memory space (00H:7FH) accessed via direct or indirect addressing, using instructions other than MOVX and MOVC. All or part of the Stack may be in this area.

- IDATA

  Indirect Data. 256 bytes of internal data memory space (00H:FFH) accessed via indirect addressing using instructions other than MOVX and MOVC. All or part of the Stack may be in this area. This area includes the DATA area and the 128 bytes immediately above it.

- SFR

  Special Function Registers. Selected CPU registers and peripheral control and status registers, accessible only via direct addressing.

- CODE

  64 kB of Code memory space, accessed as part of program execution and via the MOVC instruction. The P89LPC915/916/917 devices have 2 kB of on-chip Code memory.

8.11 Data RAM arrangement

The 256 bytes of on-chip RAM are organized as shown in Table 10.

Table 10. On-chip data memory usages

Type	Data RAM	Size (bytes)
DATA	Memory that can be addressed directly and indirectly	128
IDATA	Memory that can be addressed indirectly	256

8.12 Interrupts

The P89LPC915/916/917 uses a four priority level interrupt structure. This allows great flexibility in controlling the handling of the many interrupt sources.

The P89LPC915 and P89LPC917 support 13 interrupt sources: external interrupts 0 and 1, timers 0 and 1, serial port TX, serial port RX, combined serial port RX/TX, brownout detect, watchdog/RTC, I^2C-bus, keyboard, comparators 1 and 2, and ADC completion.

The P89LPC916 supports 14 interrupt sources: external interrupts 0 and 1, timers 0 and 1, serial port TX, serial port RX, combined serial port RX/TX, brownout detect, watchdog/RTC, I^2C-bus, keyboard, comparators 1 and 2, SPI, and ADC completion.

In the ‘Timer’ function, the register is incremented every machine cycle.

In the ‘Counter’ function, the register is incremented in response to a 1-to-0 transition at its corresponding external input pin, T0 or T1. In this function, the external input is sampled once during every machine cycle.

Timer 0 has five operating modes (Modes 0, 1, 2, 3 and 6).

Timer 1 has four operating modes (Modes 0, 1, 2, and 3), except on the P89LPC917 where Timer 1 also has Mode 6. Modes 0, 1, 2 and 6 are the same for both Timers/Counters. Mode 3 is different.

8.17.1 Mode 0

Putting either Timer into Mode 0 makes it look like an 8048 Timer, which is an 8-bit Counter with a divide-by-32 prescaler. In this mode, the Timer register is configured as a 13-bit register. Mode 0 operation is the same for Timer 0 and Timer 1.

8.17.2 Mode 1

Mode 1 is the same as Mode 0, except that all 16 bits of the timer register are used.

8.17.3 Mode 2

Mode 2 configures the Timer register as an 8-bit Counter with automatic reload. Mode 2 operation is the same for Timer 0 and Timer 1.

8.17.4 Mode 3

When Timer 1 is in Mode 3 it is stopped. Timer 0 in Mode 3 forms two separate 8-bit counters and is provided for applications that require an extra 8-bit timer. When Timer 1 is in Mode 3 it can still be used by the serial port as a baud rate generator.

8.17.5 Mode 6

In this mode, the corresponding timer can be changed to a PWM with a full period of 256 timer clocks.

8.17.6 Timer overflow toggle output

Timer 0 (and Timer 1 on the P89LPC917) can be configured to automatically toggle a port output whenever a timer overflow occurs. The same device pins that are used for the T0 and T1 count inputs are also used for the timer toggle outputs. The port outputs will be a logic 1 prior to the first timer overflow when this mode is turned on.

8.18 RTC/system timer

The P89LPC915/916/917 have a simple RTC that allows a user to continue running an accurate timer while the rest of the device is powered down. The RTC can be a wake-up or an interrupt source. The RTC is a 23-bit down-counter comprised of a 7-bit prescaler and a 16-bit loadable down-counter. When it reaches all ‘0’s, the counter will be reloaded again and the RTCF flag will be set.

The clock source for this counter can be either the CPU clock (CCLK) or the external clock input, provided that the external clock input is not being used as the CPU clock. If the external clock input is used as the CPU clock, then the RTC will use CCLK as its clock source. Only power-on reset will reset the RTC and its associated SFRs to the default state.

8.19 UART

The P89LPC915/916/917 has an enhanced UART that is compatible with the conventional 80C51 UART except that Timer 2 overflow cannot be used as a baud rate source. The P89LPC915/916/917 does include an independent Baud Rate Generator. The baud rate can be selected from the oscillator (divided by a constant), Timer 1 overflow, or the independent Baud Rate Generator. In addition to the baud rate generation, enhancements over the standard 80C51 UART include Framing Error detection, automatic address recognition, selectable double buffering and several interrupt options. The UART can be operated in 4 modes: shift register, 8-bit UART, 9-bit UART, and CPU clock/32 or CPU clock/16.

8.19.1 Mode 0

Serial data enters and exits through RXD. TXD outputs the shift clock. 8 bits are transmitted or received, LSB first. The baud rate is fixed at $\frac{1}{16}$ of the CPU clock frequency.

8.19.2 Mode 1

10 bits are transmitted (through TXD) or received (through RXD): a start bit (logic 0), 8 data bits (LSB first), and a stop bit (logic 1). When data is received, the stop bit is stored in RB8_n in Special Function Register SnCON. The baud rate is variable and is determined by the Timer 1 overflow rate or the Baud Rate Generator (described in Section 8.19.5 “Baud rate generator and selection”).

8.19.3 Mode 2

11 bits are transmitted (through TXD) or received (through RXD): start bit (logic 0), 8 data bits (LSB first), a programmable 9th data bit, and a stop bit (logic 1). When data is transmitted, the 9th data bit (TB8 in SCON) can be assigned the value of ‘0’ or ‘1’. Or, for example, the parity bit (P, in the PSW) could be moved into TB8. When data is received, the 9th data bit goes into RB8 in Special Function Register SCON, while the stop bit is not saved. The baud rate is programmable to either $\frac{1}{16}$ or $\frac{1}{32}$ of the CPU clock frequency, as determined by the SMOD1 bit in PCON. The SMOD1 bit controls the Timer 1 output rate available to the UART.

8.19.4 Mode 3

11 bits are transmitted (through TXD) or received (through RXD): a start bit (logic 0), 8 data bits (LSB first), a programmable 9th data bit, and a stop bit (logic 1). In fact, Mode 3 is the same as Mode 2 in all respects except baud rate. The baud rate in Mode 3 is variable and is determined by the Timer 1 overflow rate or the Baud Rate Generator (described in Section 8.19.5 “Baud rate generator and selection”).

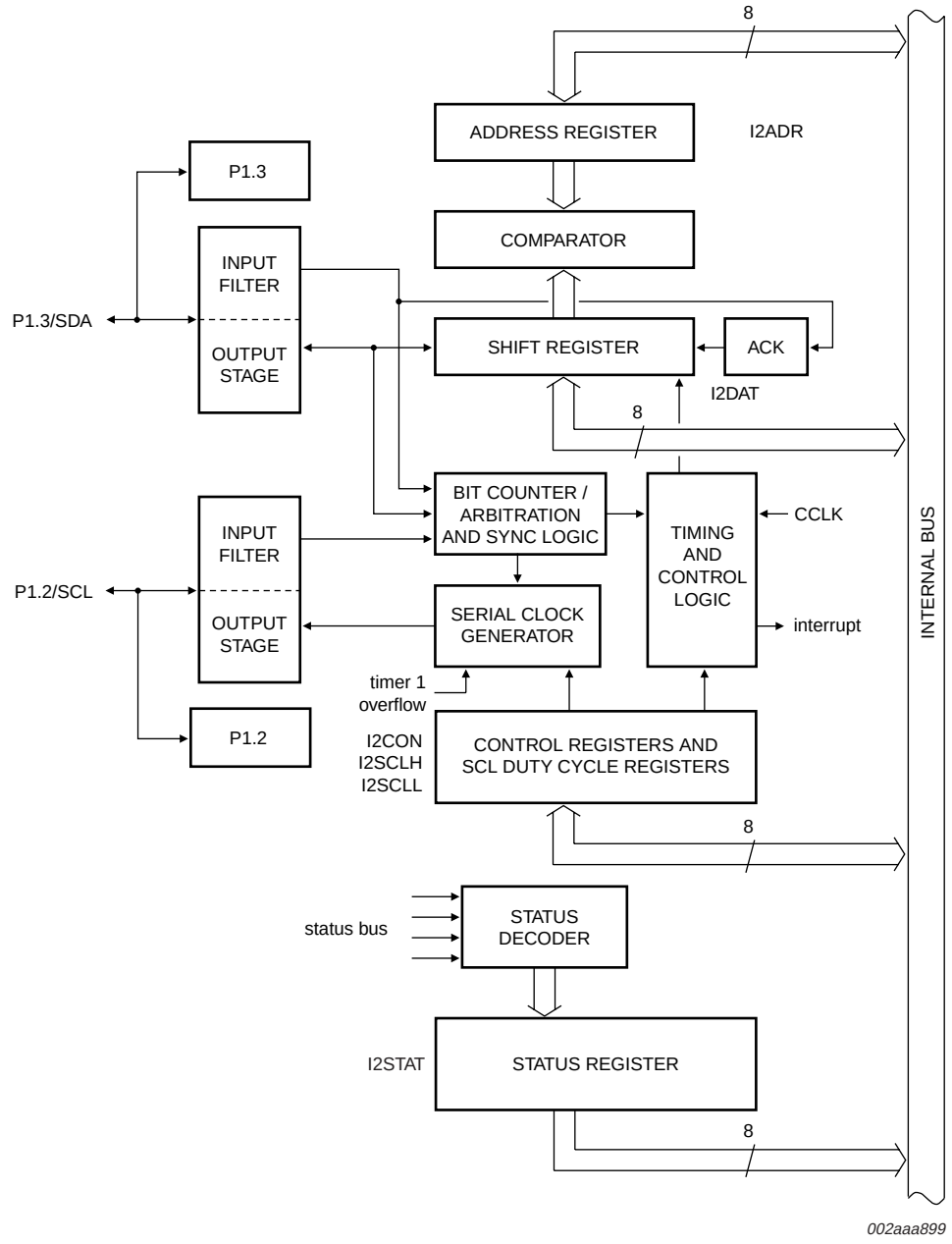

Fig 15. I²C-bus serial interface block diagram

8.21.1 Typical SPI configurations

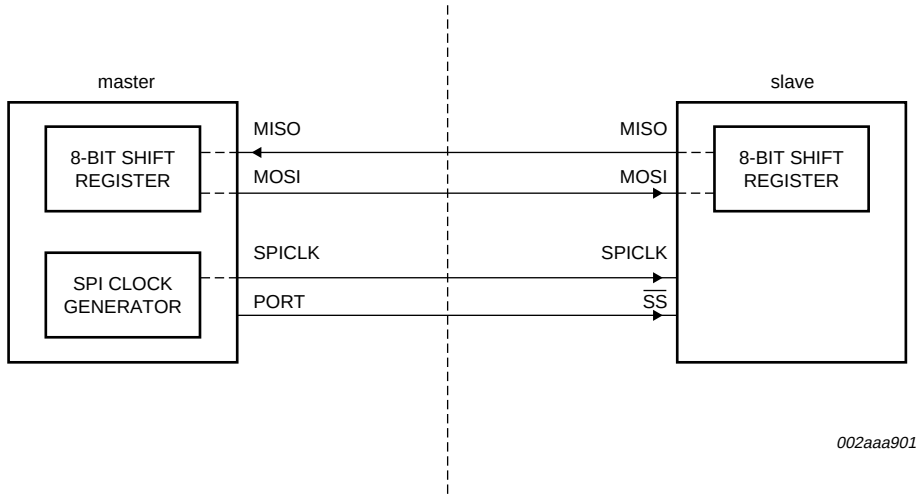

Fig 17. SPI single master single slave configuration

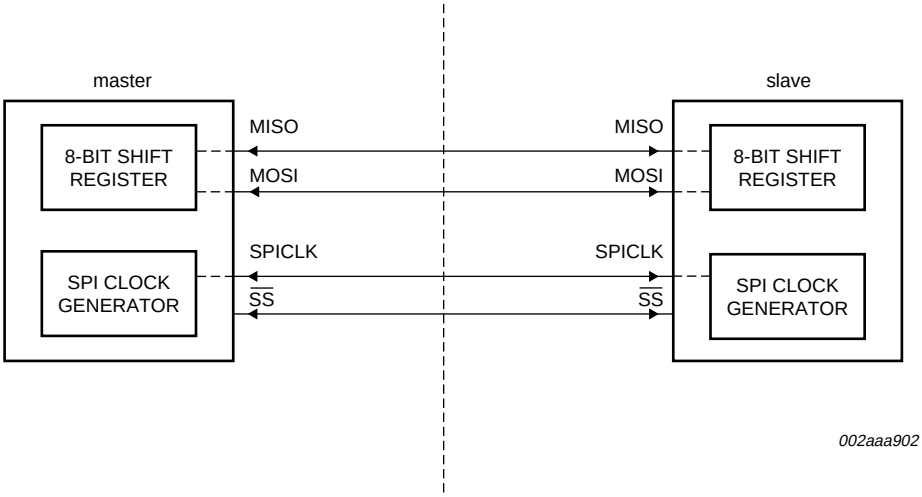

Fig 18. SPI dual device configuration, where either can be a master or a slave

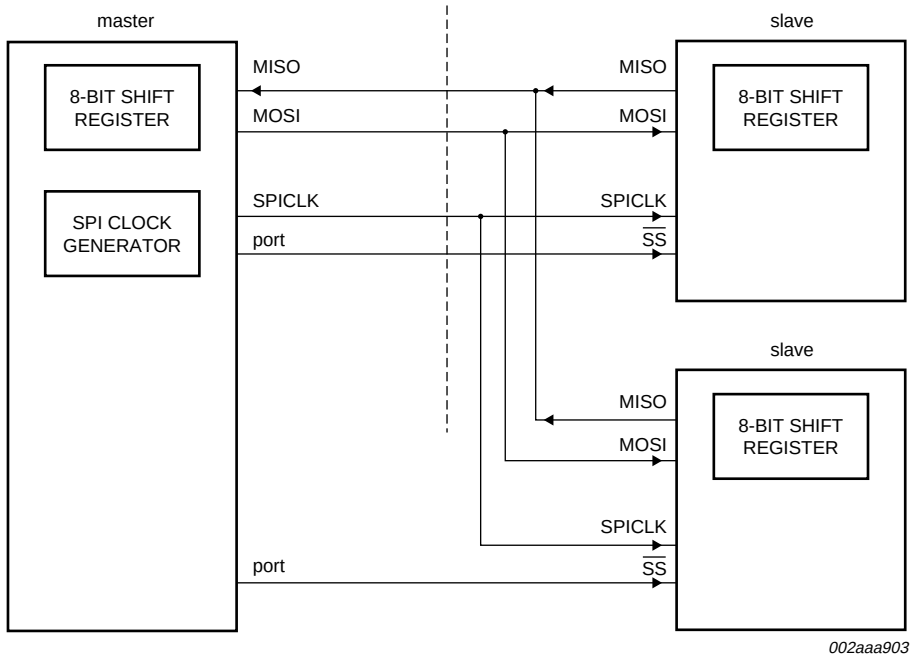

Fig 19. SPI single master multiple slaves configuration

8.28 User sector security bytes

There are eight User Sector Security Bytes on the P89LPC915/916/917. Each byte corresponds to one sector. Please see the P89LPC915/916/917 *User's Manual* for additional details.

9. A/D converter

9.1 General description

The P89LPC915/916/917 devices have a single 8-bit, 4-channel multiplexed analog-to-digital converter with a DAC module. A block diagram of the A/D converter is shown in Figure 22. The A/D consists of a 4-input multiplexer which feeds a sample-and-hold circuit providing an input signal to one of two comparator inputs. The control logic in combination with the SAR drives a digital-to-analog converter which provides the other input to the comparator. The output of the comparator is fed to the SAR.

9.2 Features

- Single 8-bit, 4-channel multiplexed input, successive approximation A/D converter.
- Four A/D result registers.
- Six operating modes:
  - Fixed channel, single conversion mode.
  - Fixed channel, continuous conversion mode.
  - Auto scan, single conversion mode.
  - Auto scan, continuous conversion mode.
  - Dual channel, continuous conversion mode.
  - Single step mode.
- Three conversion start modes:
  - Timer triggered start.
  - Start immediately.
  - Edge triggered.
- 8-bit conversion time of ≥3.9 μs at an A/D clock of 3.3 MHz.
- Interrupt or polled operation.
- Boundary limits interrupt.
- DAC output to a port pin with high output impedance.
- Clock divider.
- Power-down mode.

9.4.4 Auto scan, continuous conversion mode

Any combination of the four input channels can be selected for conversion. A conversion of each selected input will be performed and the result placed in the result register which corresponds to the selected input channel. An interrupt, if enabled, will be generated after all selected channels have been converted. The process will repeat starting with the first selected channel. Additional conversion results will again cycle through the four result registers, overwriting the previous results.Continous conversions continue until terminated by the user.

9.4.5 Dual channel, continuous conversion mode

This is a variation of the auto scan continuous conversion mode where conversion occurs on two user-selectable inputs. The result of the conversion of the first channel is placed in result register, AD1DAT0. The result of the conversion of the second channel is placed in result register, AD1DAT1. The first channel is again converted and its result stored in AD1DAT2. The second channel is again converted and its result placed in AD1DAT3. An interrupt is generated, if enabled, after every set of four conversions (two conversions per channel).

9.4.6 Single step mode

This special mode allows ‘single-stepping’ in an auto scan conversion mode. Any combination of the four input channels can be selected for conversion. After each channel is converted, an interrupt is generated, if enabled, and the A/D waits for the next start condition. May be used with any of the start modes.

9.5 Conversion start modes

9.5.1 Timer triggered start

An A/D conversion is started by the overflow of Timer 0. Once a conversion has started, additional Timer 0 triggers are ignored until the conversion has completed. The Timer triggered start mode is available in all A/D operating modes.

9.5.2 Start immediately

Programming this mode immediately starts a conversion.This start mode is available in all A/D operating modes.

9.5.3 Edge triggered

An A/D conversion is started by rising or falling edge of P1.4. Once a conversion has started, additional edge triggers are ignored until the conversion has completed. The edge triggered start mode is available in all A/D operating modes.

9.6 Boundary limits interrupt

The A/D converter has both a high and low boundary limit register. After the four MSBs have been converted, these four bits are compared with the four MSBs of the boundary high and low registers. If the four MSBs of the conversion are outside the limit an interrupt will be generated, if enabled. If the conversion result is within the limits, the boundary limits will again be compared after all 8 bits have been converted. An interrupt will be generated, if enabled, if the result is outside the boundary limits. The boundary limit may be disabled by clearing the boundary limit interrupt enable.

10. Limiting values

Table 14. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).[1]

Symbol	Parameter	Conditions	Min	Max	Unit
$T_{amb(bias)}$	operating bias ambient temperature		–55	+125	°C
T_{stg}	storage temperature range		–65	+150	°C
$I_{OH(I/O)}$	HIGH-level output current per I/O pin		-	8	mA
$I_{OL(I/O)}$	LOW-level output current per I/O pin		-	20	mA
$I_{I/O(tot)(max)}$	maximum total I/O current		-	120	mA
V_n	voltage on any pin (except V_{SS})	with respect to V_{DD}	-	3.5	V
$P_{tot(pack)}$	total power dissipation per package	based on package heat transfer, not device power consumption	-	1.5	W

[1] The following applies to Table 14:

a) This product includes circuitry specifically designed for the protection of its internal devices from the damaging effects of excessive static charge. Nonetheless, it is suggested that conventional precautions be taken to avoid applying greater than the rated maximum.

b) Parameters are valid over ambient temperature range unless otherwise specified. All voltages are with respect to V_{SS} unless otherwise noted.

Table 17. Dynamic characteristics (18 MHz)

V_{DD} = 3.0 V to 3.6 V unless otherwise specified.
T_{amb} = −40 °C to +85 °C, or −40 °C to +125 °C (see Table 3 on page 3), unless otherwise specified.[1][2]

Symbol	Parameter	Conditions	Variable clock		f_{osc} = 18 MHz		Unit
			Min	Max	Min	Max	
$f_{osc(RC)}$	internal RC oscillator frequency	industrial	7.189	7.557	7.189	7.557	MHz
		extended	7.004	7.741	7.004	7.741	MHz
$f_{osc(WD)}$	internal watchdog oscillator frequency		320	520	320	520	kHz
f_{CLKLP}	low power select clock frequency		0	8	-	-	MHz
Glitch filter							
t_{gr}	glitch rejection time	P1.5/$\overline{RST}$ pin	-	50	-	50	ns
		any pin except P1.5/$\overline{RST}$	-	15	-	15	ns
t_{sa}	signal acceptance time	P1.5/$\overline{RST}$ pin	125	-	125	-	ns
		any pin except P1.5/$\overline{RST}$	50	-	50	-	ns
External clock							
f_{osc}	oscillator frequency		0	18	-	-	MHz
$T_{cy(clk)}$	clock cycle time	see Figure 28	55	-	-	-	ns
t_{CHCX}	clock HIGH time	see Figure 28	22	$T_{cy(CLK)} - t_{CLCX}$	22	-	ns
t_{CLCX}	clock LOW time	see Figure 28	22	$T_{cy(CLK)} - t_{CHCX}$	22	-	ns
t_{CLCH}	clock rise time	see Figure 28	-	5	-	5	ns
t_{CHCL}	clock fall time	see Figure 28	-	5	-	5	ns
Shift register (UART mode 0)							
T_{XLXL}	serial port clock cycle time	see Figure 27	$16T_{cy(CLK)}$	-	888	-	ns
t_{QVXH}	output data set-up to clock rising edge time	see Figure 27	$13T_{cy(CLK)}$	-	722	-	ns
t_{XHQX}	output data hold after clock rising edge time	see Figure 27	-	$T_{cy(CLK)}$ + 20	-	75	ns
t_{XHDX}	input data hold after clock rising edge time	see Figure 27	-	0	-	0	ns
t_{XHDV}	input data valid to clock rising edge time	see Figure 27	150	-	150	-	ns
SPI interface							
f_{SPI}	SPI operating frequency						
	slave		0	$^{CCLK}/_{6}$	0	3.0	MHz
	master		-	$^{CCLK}/_{4}$	-	4.5	MHz
T_{SPICYC}	SPI cycle time	see Figure 23, 24, 25, 26					
	slave		$^{6}/_{CCLK}$	-	333	-	ns
	master		$^{4}/_{CCLK}$	-	222	-	ns
$t_{SPILEAD}$	SPI enable lead time	see Figure 25, 26					
	slave		250	-	250	-	ns
t_{SPILAG}	SPI enable lag time	see Figure 25, 26	250	-	250	-	ns

Table 17. Dynamic characteristics (18 MHz) *…continued*

V_{DD} = 3.0 V to 3.6 V unless otherwise specified.

T_{amb} = −40 °C to +85 °C, or −40 °C to +125 °C (see Table 3 on page 3), unless otherwise specified.[1][2]

Symbol	Parameter	Conditions	Variable clock		f_{osc} = 18 MHz		Unit
			Min	Max	Min	Max	
$t_{SPICLKH}$	SPICLK HIGH time	see Figure 23, 24, 25, 26					
	master		$^{2}/_{CCLK}$	-	111	-	ns
	slave		$^{3}/_{CCLK}$	-	167	-	ns
$t_{SPICLKL}$	SPICLK LOW time	see Figure 23, 24, 25, 26					
	master		$^{2}/_{CCLK}$	-	111	-	ns
	slave		$^{3}/_{CCLK}$	-	167	-	ns
t_{SPIDSU}	SPI data set-up time	see Figure 23, 24, 25, 26					
	master or slave		100	-	100	-	ns
t_{SPIDH}	SPI data hold time	see Figure 23, 24, 25, 26					
	master or slave		100	-	100	-	ns
t_{SPIA}	SPI access time	see Figure 25, 26					
	slave		0	80	0	80	ns
t_{SPIDIS}	SPI disable time	see Figure 25, 26					
	slave		0	160	-	160	ns
t_{SPIDV}	SPI enable to output data valid time	see Figure 23, 24, 25, 26					
	slave		-	160	-	160	ns
	master		-	111	-	111	ns
t_{SPIOH}	SPI output data hold time	see Figure 23, 24, 25, 26	0	-	0	-	ns
t_{SPIR}	SPI rise time	see Figure 23, 24, 25, 26					
	SPI outputs (SPICLK, MOSI, MISO)		-	100	-	100	ns
	SPI inputs (SPICLK, MOSI, MISO, $\overline{SS}$)		-	2000	-	2000	ns
t_{SPIF}	SPI fall time	see Figure 23, 24, 25, 26					
	SPI outputs (SPICLK, MOSI, MISO)		-	100	-	100	ns
	SPI inputs (SPICLK, MOSI, MISO, $\overline{SS}$)		-	2000	-	2000	ns

[1] Parameters are valid over ambient temperature range unless otherwise specified.

[2] Parts are tested to 2 MHz, but are guaranteed to operate down to 0 Hz.