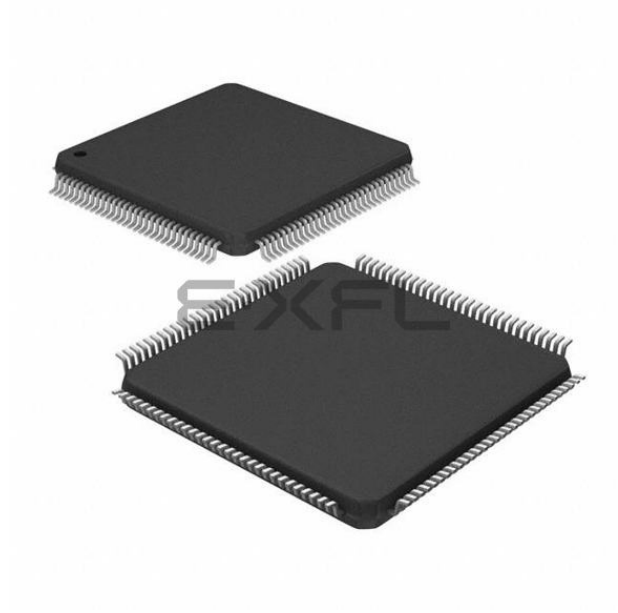
Infineon Technologies - MB90922NCSPMC-GS-128E1 Datasheet



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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-128e1

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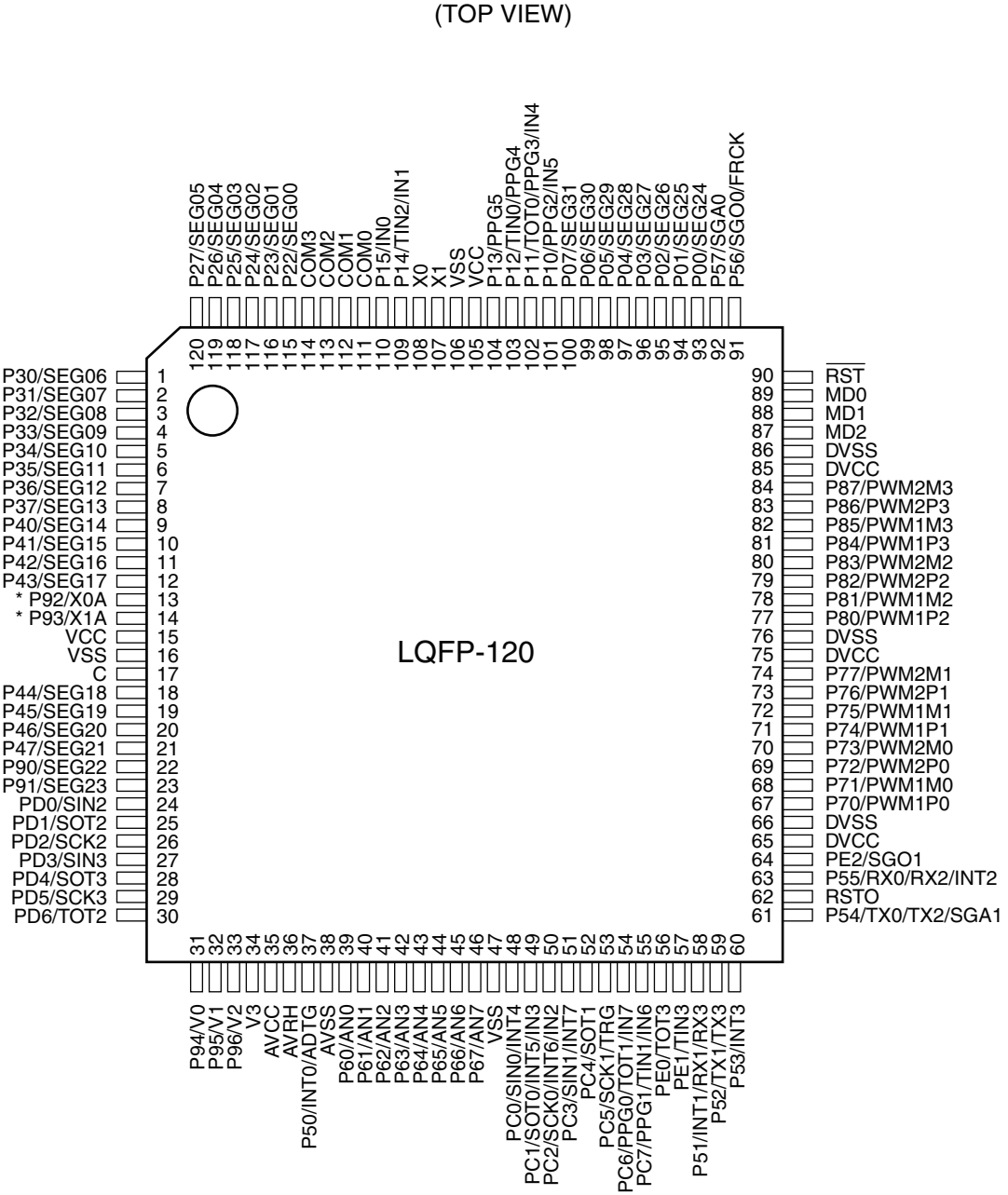
- 16-bit reload timer (4 channels)
  16-bit reload timer operation (select toggle output or one-shot output)
  Selectable event count function
- Real time watch timer (main clock)
  Operates directly from oscillator clock.
  Interrupt can be generated by second/minute/hour/date counter overflow.
- PPG timer (6 channels)
  Output pins (3 channels), external trigger input pin (1 channel)
  Operation clock frequencies : f_{CP}, $f_{CP}/2^2$, $f_{CP}/2^4$, $f_{CP}/2^6$
- Delay interrupt
  Generates interrupt for task switching.
  Interrupts to CPU can be generated/cleared by software setting.
- External interrupts (8 channels)
  8-channel independent operation
  Interrupt source setting available : “L” to “H” edge/ “H” to “L” edge/ “L” level/ “H” level.
- 8/10-bit A/D converter (8 channels)
  Conversion time : 3 µs (at f_{CP} = 32 MHz)
  External trigger activation available (P50/INT0/ADTG)
  Internal timer activation available (16-bit reload timer 1)
- UART(LIN/SCI) (4 channels)
  Equipped with full duplex double buffer
  Clock-asynchronous or clock-synchronous serial transfer is available
- CAN interface (4 channels : CAN0 and CAN2, and CAN1 and CAN3 share transmission and reception pins, and interrupt control registers).
  Conforms to CAN specifications version 2.0 Part A and B.
  Automatic resend in case of error.
  Automatic transfer in response to remote frame.
  16 prioritized message buffers for data and ID
  Multiple message support
  Flexible configuration for receive filter : Full bit compare/full bit mask/two partial bit masks
  Supports up to 1 Mbps
  CAN wakeup function (RX connected to INT0 internally)
- LCD controller/driver (32 segment x 4 common)
  Segment driver and command driver with direct LCD panel (display) drive capability
- Reset on detection of low voltage/program loop
  Automatic reset when low voltage is detected
  Program looping detection function
- Stepping motor controller (4 channels)
  High current output for each channel × 4
  Synchronized 8/10-bit PWM for each channel × 2
- Sound generator (2 channels)
  8-bit PWM signal mixed with tone frequency from 8-bit reload counter.
  PWM frequencies : 125 kHz, 62.5 kHz, 31.2 kHz, 15.6 kHz (at f_{CP} = 32 MHz)
  Tone frequencies : PWM frequency /2/ , divided by (reload frequency +1)
- Input/output ports
  General-purpose input/output port (CMOS output) 93 ports
- Function for port input level selection
  Automotive/CMOS-Schmitt
- Flash memory security function
  Protects the contents of Flash memory (Flash memory product only)

■ PIN ASSIGNMENT



(FPT-120P-M21)

* : MB90V920-101, MB90F922NCS,MB90F923NCS,MB90F924NCS,MB90922NCS : P92, P93
MB90V920-102, MB90F922NC,MB90F923NC,MB90F924NC : X0A, X1A

Pin no.	Pin name	I/O circuit type*1	Function
70	P73	L	General-purpose output-only port
	PWM2M0		Stepping motor controller ch.0 output pin
71	P74	L	General-purpose output-only port
	PWM1P1		Stepping motor controller ch.1 output pin
72	P75	L	General-purpose output-only port
	PWM1M1		Stepping motor controller ch.1 output pin
73	P76	L	General-purpose output-only port
	PWM2P1		Stepping motor controller ch.1 output pin
74	P77	L	General-purpose output-only port
	PWM2M1		Stepping motor controller ch.1 output pin
77	P80	L	General-purpose output-only port
	PWM1P2		Stepping motor controller ch.2 output pin
78	P81	L	General-purpose output-only port
	PWM1M2		Stepping motor controller ch.2 output pin
79	P82	L	General-purpose output-only port
	PWM2P2		Stepping motor controller ch.2 output pin
80	P83	L	General-purpose output-only port
	PWM2M2		Stepping motor controller ch.2 output pin
81	P84	L	General-purpose output-only port
	PWM1P3		Stepping motor controller ch.3 output pin
82	P85	L	General-purpose output-only port
	PWM1M3		Stepping motor controller ch.3 output pin
83	P86	L	General-purpose output-only port
	PWM2P3		Stepping motor controller ch.3 output pin
84	P87	L	General-purpose output-only port
	PWM2M3		Stepping motor controller ch.3 output pin
22	P90	F	General-purpose I/O port
	SEG22		LCD controller/driver segment output pin
23	P91	F	General-purpose I/O port
	SEG23		LCD controller/driver segment output pin
31	P94	G	General-purpose I/O port
	V0		LCD controller/driver reference power supply pin
32	P95	G	General-purpose I/O port
	V1		LCD controller/driver reference power supply pin

(Continued)

Pin no.	Pin name	I/O circuit type*1	Function
33	P96	G	General-purpose I/O port
	V2		LCD controller/driver reference power supply pin
34	V3	—	LCD controller/driver reference power supply pin
48	PC0	J	General-purpose I/O port
	SIN0		UART ch.0 serial data input pin
	INT4		INT4 external interrupt input pin
49	PC1	I	General-purpose I/O port
	SOT0		UART ch.0 serial data output pin
	INT5		INT5 external interrupt input pin
	IN3		Input capture ch.3 trigger input pin
50	PC2	I	General-purpose I/O port
	SCK0		UART ch.0 serial clock I/O pin
	INT6		INT6 external interrupt input pin
	IN2		Input capture ch.2 trigger input pin
51	PC3	J	General-purpose I/O port
	SIN1		UART ch.1 serial data input pin
	INT7		INT7 external interrupt input pin
52	PC4	I	General-purpose I/O port
	SOT1		UART ch.1 serial data output pin
53	PC5	I	General-purpose I/O port
	SCK1		UART ch.1 serial clock I/O pin
	TRG		16-bit PPG ch.0 to ch.5 external trigger input pin
54	PC6	I	General-purpose I/O port
	PPG0		16-bit PPG ch.0 output pin
	TOT1		16-bit reload timer ch.1 TOT output pin
	IN7		Input capture ch.7 trigger input pin
55	PC7	I	General-purpose I/O port
	PPG1		16-bit PPG ch.1 output pin
	TIN1		16-bit reload timer ch.1 TIN input pin
	IN6		Input capture ch.6 trigger input pin
24	PD0	J	General-purpose I/O port
	SIN2		UART ch.2 serial data input pin
25	PD1	I	General-purpose I/O port
	SOT2		UART ch.2 serial data output pin

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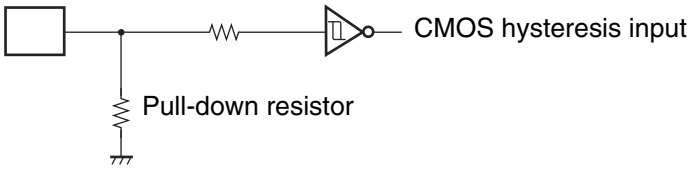
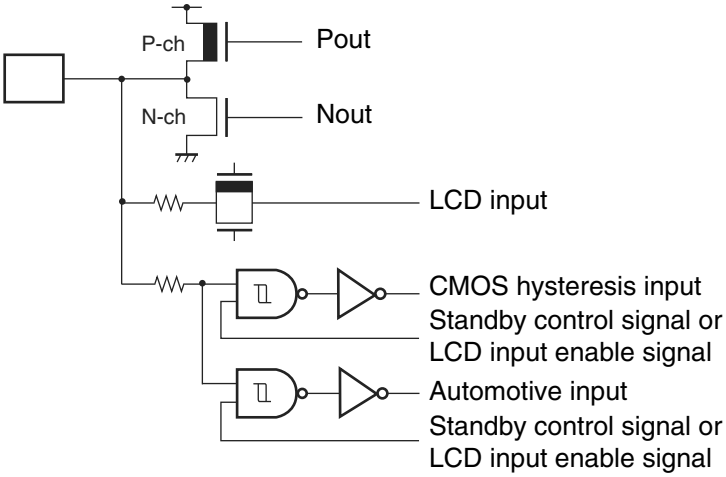
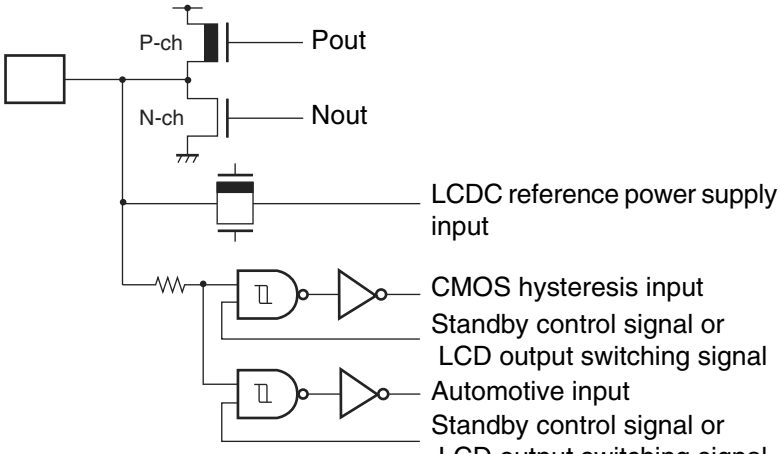
Type	Circuit	Remarks
E		Input-only pin (with pull-down resistance) • Attached pull-down resistance: approx. 50 kΩ • CMOS hysteresis input (V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}) Note: The MD2 pin of the evaluation products uses this circuit type.
F		LCD output common general-purpose port • CMOS output (I_{OH}/I_{OL} = ±4 mA) • Hysteresis input (V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}) • Automotive input (V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC})
G		LCDC reference power supply common general-purpose port • CMOS output (I_{OH}/I_{OL} = ±4 mA) • CMOS hysteresis input (V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}) • Automotive input (V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC})

(Continued)

- **Handling the power supply for high-current output buffer pins** (DV_{CC}, DV_{SS})

  - **Flash memory products and MASK ROM products (MB90F922NC/F922NCS/922NCS/F923NC/ F923NCS/F924NC/F924NCS)**

    In the Flash memory products and MASK ROM products, the power supply for the high-current output buffer pins (DV_{CC}, DV_{SS}) is isolated from the digital power supply (V_{CC}).
    Therefore, DVcc can therefore be set to a higher voltage than Vcc. If the power supply for the high-current output buffer pins (DV_{CC}, DV_{SS}) is supplied before the digital power supply (V_{CC}), however, care needs to be taken because it is possible that the port 7 or port 8 stepping motor outputs may momentarily output an “H” or “L” level. In order to prevent this, connect the digital power supply (V_{CC}) prior to connecting the power supply for the high-current output buffer pins. Even when the high-current output buffer pins are used as general-purpose ports, power should be supplied to the power supply pins for the high-current output buffer pins (DV_{CC}, DV_{SS}).

  - **Evaluation product** (**MB90V920-101**/**MB90V920-102**)

    In the evaluation products, the power supply for the high-current output buffer pins (DV_{CC}, DV_{SS}) is not isolated from the digital power supply (V_{CC}). Therefore, DV_{CC} must therefore be set to a lower voltage than Vcc. The power supply for the high-current output buffer pins (DV_{CC}, DV_{SS}) must always be applied after the digital power supply (V_{CC}) has been connected, and disconnected before the digital power supply (Vcc) is disconnected (the power supply for the high-current output buffer pins may also be connected and disconnected simultaneously with the digital power supply).
    Even when the high-current output buffer pins are used as general-purpose ports, power should be supplied to the power supply pins for the high-current output buffer pins (DV_{CC}, DV_{SS}).

- **Pull-up/pull-down resistors**

MB90920 series does not support internal pull-up/pull-down resistors. Use external components as necessary.

- **Precautions when not using a sub clock signal**

If the X0A and X1A pins are not connected to an oscillator, apply a pull-down resistance to the X0A pin and leave the X1A pin open.

- **Notes on operating when the external clock is stopped**

The MB90920 series is not guaranteed to operate correctly using the internal oscillator circuit when there is no external oscillator or the external clock input is stopped.

- **Flash memory security function**

A security bit is located within the Flash memory region. The security function is activated by writing the protection code 01_H to the security bit.
Do not write the value 01_H to this address if you are not using the security function.
Please refer to following table for the address of the security bit.

	Flash memory size	Address for security bit
MB90F922NC MB90F922NCS	Built-in 2 Mbits Flash Memory	$FC0001_H$
MB90F923NCS	Built-in 3 Mbits Flash Memory	$F80001_H$
MB90F924NCS	Built-in 4 Mbits Flash Memory	$F80001_H$

Address	Register name	Symbol	Read/write	Resource name	Initial value
000083H	(Disabled)				
000084H	PWM control register 2	PWC2	R/W	Stepping motor controller 2	000000X0B
000085H	(Disabled)				
000086H	PWM control register 3	PWC3	R/W	Stepping motor controller 3	000000X0B
000087H	(Disabled)				
000088H	LCD output control register 3	LOCR3	R/W	LCDC	XXXXX111B
000089H	(Disabled)				
00008AH	A/D setting register 0	ADSR0	R/W	A/D converter	00000000B
00008BH	A/D setting register 1	ADSR1	R/W		00000000B
00008CH	Port input level select 0	PIL0	R/W	Port input level select	00000000B
00008DH	Port input level select 1	PIL1	R/W		XXXX0000B
00008EH	Port input level select 2	PIL2	R/W		XXXX0000B
00008FH to 00009DH	(Disabled)				
00009EH	Program address detection control register	PACSR	R/W	Address match detection	XXXX0X0XB
00009FH	Delayed Interrupt/Release Register	DIRR	R/W	Delay interrupt	XXXXXXX0B
0000A0H	Power saving mode control register	LPMCR	R/W	Power saving control circuit	00011000B
0000A1H	Clock select register	CKSCR	R/W, R		11111100B
0000A2H to 0000A7H	(Disabled)				
0000A8H	Watchdog timer control register	WDTC	R, W	Watchdog timer	XXXXX111B
0000A9H	Time-base timer control register	TBTC	R/W, W	Time-base timer	1XX00100B
0000AAH	Watch timer control register	WTC	R/W, W, R	Watch timer (sub clock)	10001000B
0000ABH to 0000ADH	(Disabled)				
0000AEH	Flash memory control status register	FMCS	R/W	Flash interface	000X0000B
0000AFH	(Disabled)				

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Address	Register name	Symbol	Read/write	Resource name	Initial value
003700H to 0037FFH	Area reserved for CAN Controller 2. Refer to "■ CAN CONTROLLERS"				
003800H to 0038FFH	Area reserved for CAN Controller 3. Refer to "■ CAN CONTROLLERS"				
003900H to 00391FH	(Disabled)				
003920H	PPG0 down counter register	PDCR0	R	16-bit PPG0	11111111B
003921H					11111111B
003922H	PPG0 cycle setting register	PCSR0	W		11111111B
003923H					11111111B
003924H	PPG0 duty setting register	PDUT0	W	16-bit PPG0	00000000B
003925H					00000000B
003926H	PPG0 output division setting register	PPGDIV0	R/W, R		11111100B
003927H	(Disabled)				
003928H	PPG1 down counter register	PDCR1	R	16-bit PPG1	11111111B
003929H					11111111B
00392AH	PPG1 cycle setting register	PCSR1	W		11111111B
00392BH					11111111B
00392CH	PPG1 duty setting register	PDUT1	W		00000000B
00392DH					00000000B
00392EH	PPG1output division setting register	PPGDIV1	R/W, R		11111100B
00392FH	(Disabled)				
003930H	PPG2 down counter register	PDCR2	R	16-bit PPG2	11111111B
003931H					11111111B
003932H	PPG2 cycle setting register	PCSR2	W		11111111B
003933H					11111111B
003934H	PPG2 duty setting register	PDUT2	W		00000000B
003935H					00000000B
003936H	PPG2 output division setting register	PPGDIV2	R/W, R		11111100B
003937H to 00393FH	(Disabled)				
003940H	Input capture register 4	IPCP4	R	Input capture 4/5	XXXXXXXXB
003941H					XXXXXXXXB
003942H	Input capture register 5	IPCP5	R		XXXXXXXXB
003943H					XXXXXXXXB

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■ CAN CONTROLLERS

The CAN controller has the following features :

- Conforms to CAN Specification Version 2.0 Part A and B
  - Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmission/reception message buffers
  - 29-bit ID and 8-byte data
  - Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
  - 2 acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 kbps to 2 Mbps (when input clock is at 16 MHz)

List of Control Registers(1)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003C00H	003D00H	003E00H	003F00H	Control status register	CSR	R/W, R	00---000B 0----0-1B
003C01H	003D01H	003E01H	003F01H				
003C02H	003D02H	003E02H	003F02H	Last event indicator register	LEIR	R/W	--------B 000-0000B
003C03H	003D03H	003E03H	003F03H				
003C04H	003D04H	003E04H	003F04H	RX/TX error counter	RTEC	R	00000000B 00000000B
003C05H	003D05H	003E05H	003F05H				
003C06H	003D06H	003E06H	003F06H	Bit timing register	BTR	R/W	-1111111B 11111111B
003C07H	003D07H	003E07H	003F07H				

List of Control Registers(2)

Address				Register	Abbre-viation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
000040H	000070H	0039C0H	0039D0H	Message buffer valid register	BVALR	R/W	00000000B
000041H	000071H	0039C1H	0039D1H				00000000B
000042H	000072H	0039C2H	0039D2H	Transmit request register	TREQR	R/W	00000000B
000043H	000073H	0039C3H	0039D3H				00000000B
000044H	000074H	0039C4H	0039D4H	Transmit cancel register	TCANR	W	00000000B
000045H	000075H	0039C5H	0039D5H				00000000B
000046H	000076H	0039C6H	0039D6H	Transmit complete register	TCR	R/W	00000000B
000047H	000077H	0039C7H	0039D7H				00000000B
000048H	000078H	0039C8H	0039D8H	Receive complete register	RCR	R/W	00000000B
000049H	000079H	0039C9H	0039D9H				00000000B
00004AH	00007AH	0039CAH	0039DAH	Remote request receive register	RRTRR	R/W	00000000B
00004BH	00007BH	0039CBH	0039DBH				00000000B
00004CH	00007CH	0039CCH	0039DCH	Receive overrun register	ROVRR	R/W	00000000B
00004DH	00007DH	0039CDH	0039DDH				00000000B
00004EH	00007EH	0039CEH	0039DEH	Receive interrupt enable register	RIER	R/W	00000000B
00004FH	00007FH	0039CFH	0039DFH				00000000B
003C08H	003D08H	003E08H	003F08H	IDE register	IDER	R/W	XXXXXXXXB
003C09H	003D09H	003E09H	003F09H				XXXXXXXXB
003C0AH	003D0AH	003E0AH	003F0AH	Transmit RTR register	TRTRR	R/W	00000000B
003C0BH	003D0BH	003E0BH	003F0BH				00000000B
003C0CH	003D0CH	003E0CH	003F0CH	Remote frame receive wait register	RFWTR	R/W	XXXXXXXXB
003C0DH	003D0DH	003E0DH	003F0DH				XXXXXXXXB
003C0EH	003D0EH	003E0EH	003F0EH	Transmit interrupt enable register	TIER	R/W	00000000B
003C0FH	003D0FH	003E0FH	003F0FH				00000000B
003C10H	003D10H	003E10H	003F10H	Acceptance mask select register	AMSR	R/W	XXXXXXXXB
003C11H	003D11H	003E11H	003F11H				XXXXXXXXB
003C12H	003D12H	003E12H	003F12H				XXXXXXXXB
003C13H	003D13H	003E13H	003F13H				XXXXXXXXB
003C14H	003D14H	003E14H	003F14H	Acceptance mask register 0	AMR0	R/W	XXXXXXXXB
003C15H	003D15H	003E15H	003F15H				XXXXXXXXB
003C16H	003D16H	003E16H	003F16H				XXXXX---B
003C17H	003D17H	003E17H	003F17H				XXXXXXXXB
003C18H	003D18H	003E18H	003F18H	Acceptance mask register 1	AMR1	R/W	XXXXXXXXB
003C19H	003D19H	003E19H	003F19H				XXXXXXXXB
003C1AH	003D1AH	003E1AH	003F1AH				XXXXX---B
003C1BH	003D1BH	003E1BH	003F1BH				XXXXXXXXB

List of Message Buffers (DLC Registers)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A60H	003B60H	003760H	003860H	DLC register 0	DLCR0	R/W	----XXXXB
003A61H	003B61H	003761H	003861H				
003A62H	003B62H	003762H	003862H	DLC register 1	DLCR1	R/W	----XXXXB
003A63H	003B63H	003763H	003863H				
003A64H	003B64H	003764H	003864H	DLC register 2	DLCR2	R/W	----XXXXB
003A65H	003B65H	003765H	003865H				
003A66H	003B66H	003766H	003866H	DLC register 3	DLCR3	R/W	----XXXXB
003A67H	003B67H	003767H	003867H				
003A68H	003B68H	003768H	003868H	DLC register 4	DLCR4	R/W	----XXXXB
003A69H	003B69H	003769H	003869H				
003A6AH	003B6AH	00376AH	00386AH	DLC register 5	DLCR5	R/W	----XXXXB
003A6BH	003B6BH	00376BH	00386BH				
003A6CH	003B6CH	00376CH	00386CH	DLC register 6	DLCR6	R/W	----XXXXB
003A6DH	003B6DH	00376DH	00386DH				
003A6EH	003B6EH	00376EH	00386EH	DLC register 7	DLCR7	R/W	----XXXXB
003A6FH	003B6FH	00376FH	00386FH				
003A70H	003B70H	003770H	003870H	DLC register 8	DLCR8	R/W	----XXXXB
003A71H	003B71H	003771H	003871H				
003A72H	003B72H	003772H	003872H	DLC register 9	DLCR9	R/W	----XXXXB
003A73H	003B73H	003773H	003873H				
003A74H	003B74H	003774H	003874H	DLC register 10	DLCR10	R/W	----XXXXB
003A75H	003B75H	003775H	003875H				
003A76H	003B76H	003776H	003876H	DLC register 11	DLCR11	R/W	----XXXXB
003A77H	003B77H	003777H	003877H				
003A78H	003B78H	003778H	003878H	DLC register 12	DLCR12	R/W	----XXXXB
003A79H	003B79H	003779H	003879H				
003A7AH	003B7AH	00377AH	00387AH	DLC register 13	DLCR13	R/W	----XXXXB
003A7BH	003B7BH	00377BH	00387BH				
003A7CH	003B7CH	00377CH	00387CH	DLC register 14	DLCR14	R/W	----XXXXB
003A7DH	003B7DH	00377DH	00387DH				
003A7EH	003B7EH	00377EH	00387EH	DLC register 15	DLCR15	R/W	----XXXXB
003A7FH	003B7FH	00377FH	00387FH				

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Interrupt source	EI²OS corresponding	Interrupt vector			Interrupt control register		Priority *2
		Number		Address	ICR	Address	
UART 1 RX	◎	#37	25H	FFFF68H	ICR13	0000BDH*1	High
UART 1 TX	△	#38	26H	FFFF64H			
UART 0 RX	◎	#39	27H	FFFF60H	ICR14	0000BEH*1	
UART 0 TX	△	#40	28H	FFFF5CH			
Flash memory status	×	#41	29H	FFFF58H	ICR15	0000BFH*1	
Delay interrupt generator module	×	#42	2AH	FFFF54H			Low

◎ : Usable, and has expanded intelligent I/O services (EI²OS) stop function
○ : Usable
△ : Usable when interrupt sources sharing ICR are not in use
× : Unusable

*1 : • Peripheral functions that share the ICR register have the same interrupt level.
• If the expanded intelligent I/O service (EI²OS) is used with peripheral functions that share the ICR register, only one of the peripheral functions that share the register can be used.
• When the expanded intelligent I/O service (EI²OS) is specified for one of the peripheral functions that shares the ICR register, interrupts cannot be used from the other peripheral functions that share the register.

*2 : Priority applies when interrupts of the same level are generated.

■ ELECTRICAL CHARACTERISTICS

1. Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	V_{SS} – 0.3	V_{SS} + 6.0	V	
	AV_{CC}	V_{SS} – 0.3	V_{SS} + 6.0	V	$AV_{CC} = V_{CC}$*2
	AVRH	V_{SS} – 0.3	V_{SS} + 6.0	V	$AV_{CC} \geq$ AVRH*2
	DV_{CC}	V_{SS} – 0.3	V_{SS} + 6.0	V	$DV_{CC} = V_{CC}$*2
Input voltage*1	V_I	V_{SS} – 0.3	V_{CC} + 0.3	V	*3
Output voltage*1	V_O	V_{SS} – 0.3	V_{CC} + 0.3	V	
Maximum clamp current	I_{CLAMP}	– 4	+ 4	mA	*7
Total maximum clamp current	$\Sigma \lvert I_{CLAMP} \rvert$	—	40	mA	*7
"L" level maximum output current*4	I_{OL1}	—	15	mA	Except P70 to P77 and P80 to P87
	I_{OL2}	—	40	mA	P70 to P77 and P80 to P87
"L" level average output current*5	I_{OLAV1}	—	4	mA	Except P70 to P77 and P80 to P87
	I_{OLAV2}	—	30	mA	P70 to P77 and P80 to P87
"L" level maximum total output current	ΣI_{OL1}	—	100	mA	Except P70 to P77 and P80 to P87
	ΣI_{OL2}	—	330	mA	P70 to P77 and P80 to P87
"L" level average total output current	ΣI_{OLAV1}	—	50	mA	Except P70 to P77 and P80 to P87
	ΣI_{OLAV2}	—	250	mA	P70 to P77 and P80 to P87
"H" level maximum output current	I_{OH1}*4	—	–15	mA	Except P70 to P77 and P80 to P87
	I_{OH2}*4	—	–40	mA	P70 to P77 and P80 to P87
"H" level average output current	I_{OHAV1}*5	—	–4	mA	Except P70 to P77 and P80 to P87
	I_{OHAV2}*5	—	–30	mA	P70 to P77 and P80 to P87
"H" level maximum total output current	ΣI_{OH1}	—	–100	mA	Except P70 to P77 and P80 to P87
	ΣI_{OH2}	—	–330	mA	P70 to P77 and P80 to P87
"H" level average total output current	ΣI_{OHAV1}*6	—	–50	mA	Except P70 to P77 and P80 to P87
	ΣI_{OHAV2}*6	—	–250	mA	P70 to P77 and P80 to P87
Power consumption	P_D	—	625	mW	
Operating temperature	T_A	– 40	+ 105	°C	
Storage temperature	T_{STG}	– 55	+ 150	°C	

*1 : The parameter is based on $V_{SS} = AV_{SS} = DV_{SS} = 0.0$ V.

*2 : AV_{CC}, AVRH must not exceed V_{CC}, and AVRH must not exceed AV_{CC}.
When using an evaluation product, DV_{CC} must not exceed V_{CC} (however, DV_{CC} can be set to a higher voltage than V_{CC} when using a Flash memory product).

*3 : If the input current or the maximum input current is limited using external components, I_{CLAMP} is the applicable rating instead of V_I.

*4 : Maximum output current is defined as the peak value of current through any one of the corresponding pins.

(Continued)

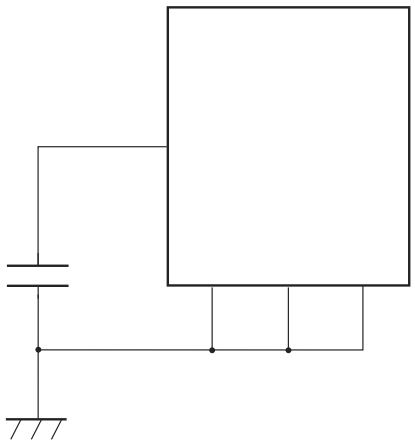
2. Recommended Operating Conditions

(V_{SS} = DV_{SS} = AV_{SS} = 0.0 V)

Parameter	Symbol	Value		Unit	Remarks
		Min	Max		
Power supply voltage	V_{CC} AV_{CC} DV_{CC}	4.0	5.5	V	The low voltage detection reset operates when the power supply voltage reaches 4.2 V ± 0.2 V.
		4.4	5.5	V	Maintain stop operation status The low voltage detection reset operates when the power supply voltage reaches 4.2 V ± 0.2 V.
Smoothing capacitor*	C_S	0.1	1.0	µF	Use a ceramic capacitor or other capacitor of equivalent frequency characteristics. Use a capacitor with a capacitance greater than this capacitor as the bypass capacitor for the V_{CC} pin.
Operating temperature	T_A	− 40	+ 105	°C	

* : Refer to the following diagram for details on the connection of the smoothing capacitor C_S.

• C pin connection diagram



WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

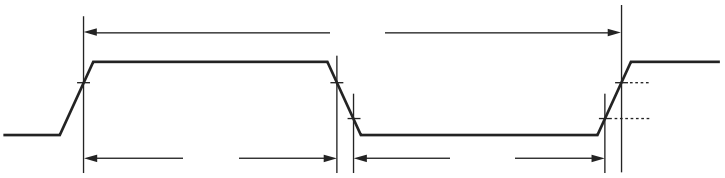
4. AC Characteristics

(1) Clock timing

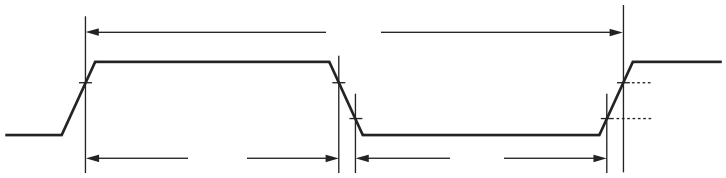
(V_{CC} = 5.0 V ±10%, V_{SS} = DV_{SS} = AV_{SS} = 0.0 V, T_A = –40 °C to +105 °C)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Clock frequency	F_C	X0, X1	—	3	—	16	MHz	1/2 (PLL stopped) When using the oscillator circuit
				3	—	32	MHz	1/2 (PLL stopped) When using an external clock
				4	—	32	MHz	PLL multiplied by 1
				3	—	16	MHz	PLL multiplied by 2
				3	—	10.7	MHz	PLL multiplied by 3
				3	—	8	MHz	PLL multiplied by 4
				3	—	5.33	MHz	PLL multiplied by 6
				3	—	4	MHz	PLL multiplied by 8
	F_{LC}	X0A, X1A		—	32.768	—	kHz	
Clock cycle time	t_{CYL}	X0, X1		62.5	—	333	ns	When using an oscillator
				31.25	—	333	ns	External clock input
	t_{LCYL}	X0A, X1A		—	30.5	—	µs	
Input clock pulse width	P_{WH}, P_{WL}	X0		5	—	—	ns	Use duty ratio of 50% ± 3% as a guideline
	P_{WLH}, P_{WLL}	X0A		—	15.2	—	µs	
Input clock rise and fall time	tcr, tcf	X0		—	—	5	ns	When using an external clock signal
Internal operating clock frequency	F_{CP}	—		1.5	—	32	MHz	Using main clock (PLL clock)
	F_{LCP}	—		—	8.192	—	kHz	Using sub clock
Internal operating clock cycle time	t_{CP}	—		31.25	—	666	ns	Using main clock (PLL clock)
	t_{LCP}	—		—	122.1	—	µs	Using sub clock

• X0, X1 clock timing

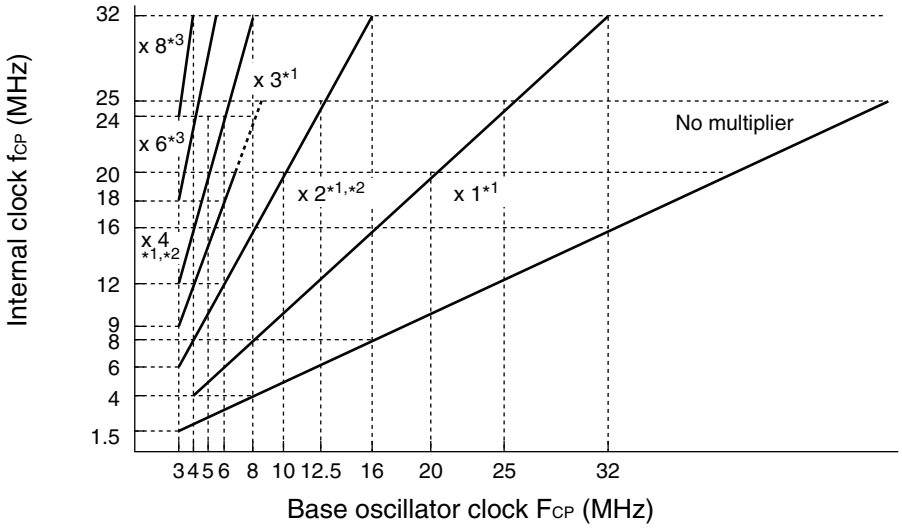


• X0A, X1A clock timing



(Continued)

Base oscillator frequency vs. Internal operating clock frequency



*1 : When the PLL multiplier is × 1, × 2, × 3 or × 4 and the internal clock is 20 MHz < f_{CP} ≤ 32 MHz, set DIV2 bit = "1"*4, CS2 bit = "1" in the PSCCR register.
[Example] When using a base oscillator frequency of 24 MHz at PLL × 1 :
CKSCR register : CS1 bit = "0", CS0 bit = "0"
PSCCR register : DIV2 bit = "1"*4,CS2 bit = "1"
[Example] When using a base oscillator frequency of 6 MHz at PLL × 3 :
CKSCR register : CS1 bit = "1", CS0 bit = "0"
PSCCR register : DIV2 bit = "1"*4, CS2 bit = "1"

*2 : When the PLL multiplier is × 2 or × 4 and the internal clock is 20 MHz < f_{CP} ≤ 32 MHz, the following settings are also supported.
PLL × 2 : CKSCR register : CS1 bit = "0", CS0 bit = "0"
PSCCR register : DIV2 bit = "0"*4, CS2 bit = "0"
PLL × 4 : CKSCR register : CS1 bit = "0", CS0 bit = "1"
PSCCR register : DIV2 bit = "0"*4, CS2 bit = "0"

*3 : When the PLL multiplier is set to × 6 or × 8 set "DIV2 bit = "0"*4 CS2 bit = "1" and "PLL2 bit = 1" in the PSCCR register.
[Example] When using a base oscillator frequency of 4 MHz at PLL × 6 :
CKSCR register : CS1 bit = "1", CS0 bit = "0"
PLLOS register : DIV2 bit = "0"*4, CS2 bit = "1"
[Example] When using a base oscillator frequency of 3 MHz at PLL × 8 :
CKSCR register : CS1 bit = "1", CS0 bit = "1"
PLLOS register : DIV2 bit = "0"*4, CS2 bit = "1"

*4 : The DIV2 bit is assigned to bit 9 of the PSCCR register and the CS2 bit is assigned to bit 8 of the PSCCR register. Both bits have a default value of "0".

(4) UART0/1/2/3 (LIN/SCI)

- **Bit setting: ESCR0/1/2/3:SCES=0, ECCR0/1/2/3:SCDE=0**

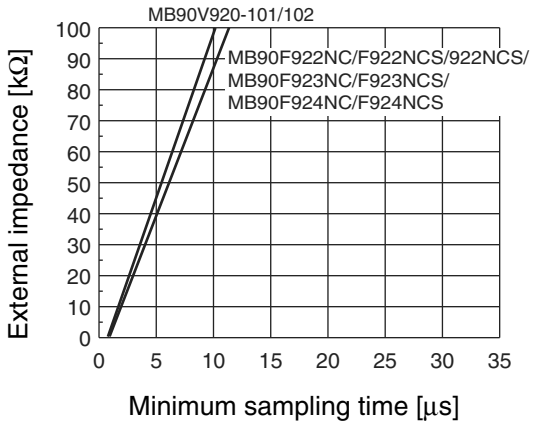
(V_{CC} = 5.0 V±10 %, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to +105 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pin C_L = 80 pF + 1TTL	5 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		− 50	+ 50	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↑ → valid SIN hold time	t_{SHIXI}			0	—	ns
Serial clock “L” pulse width	t_{SLSH}	SCK0 to SCK3	External shift clock mode output pin C_L = 80 pF + 1TTL	3 t_{CP} − t_R	—	ns
Serial clock “H” pulse width	t_{SHSL}			t_{CP} + 10	—	ns
SCK ↓ → SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	2 t_{CP} + 60	ns
Valid SIN → SCK ↑	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK ↑ → valid SIN hold time	t_{SHIXE}			t_{CP} + 30	—	ns
SCK ↓ time	t_F	SCK0 to SCK3		—	10	ns
SCK ↑ time	t_R			—	10	ns

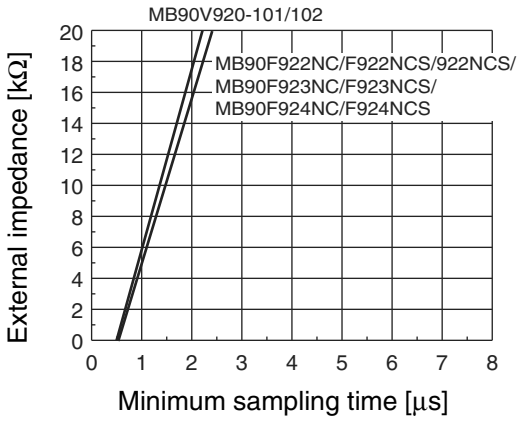
Notes : • Depending on the machine clock frequency to be used, the maximum baud rate may be limited by some parameters. These parameters are shown in “MB90920 series hardware manual”.
• C_L is the load capacitance connected to the pin during testing.
• t_{CP} is the internal operating clock cycle time. Refer to “ (1) Clock timing”.

- The relationship between the external impedance and minimum sampling time
- At 4.5 V ≤ AVcc ≤ 5.5 V

(External impedance = 0 kΩ to 100 kΩ)

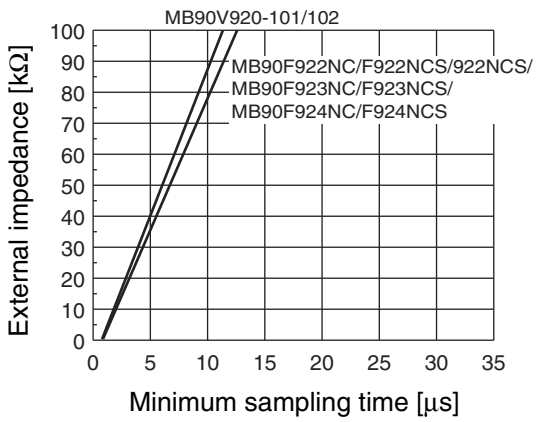


(External impedance = 0 kΩ to 20 kΩ)

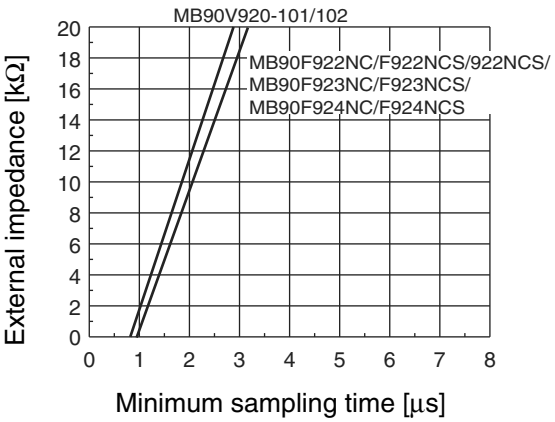


- At 4.0 V ≤ AVcc ≤ 4.5 V

(External impedance = 0 kΩ to 100 kΩ)



(External impedance = 0 kΩ to 20 kΩ)



- About errors
  As |AVRH - AVSS| becomes smaller, the relative errors grow larger.

■ MAJOR CHANGES IN THIS EDITION

Page	Section	Change Results
12	■I/O CIRCUIT TYPE	Corrected the circuit type B.
20	■ HANDLING DEVICES	Added the following items; • Serial communication • Characteristic difference between flash device and MASK ROM device
31	■ I/O MAP	Corrected “Address: 003970$_H$”. Clock supervisor control register → (Disabled)
46	■ ELECTRICAL CHARACTERISTICS 3. DC Characteristics	Added the item for “LCD output impedance”.
68	■ ORDERING INFORMATION	Corrected the part numbers; MB90V920-101 → MB90V920-101CR MB90V920-102 → MB90V920-102CR

The vertical lines marked in the left side of the page show the changes.