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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-131e1

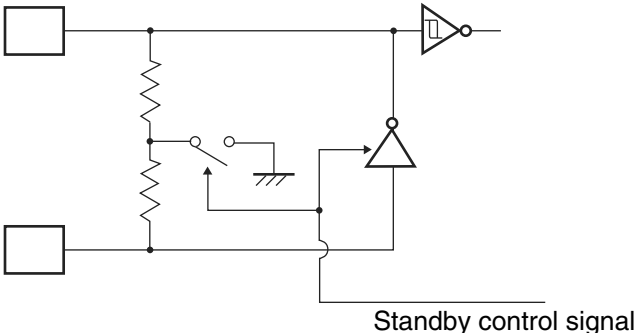
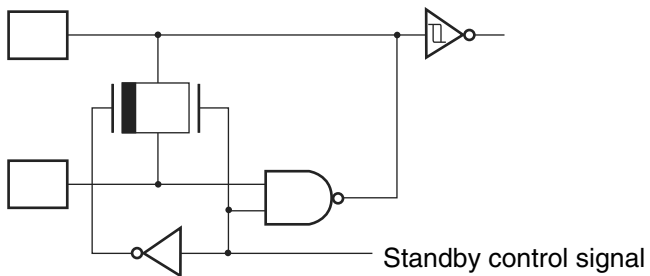
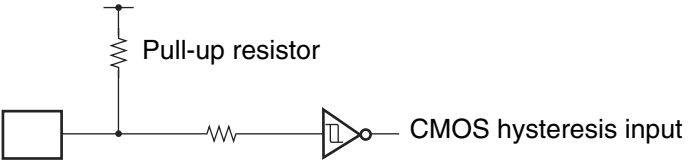

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Pin no.	Pin name	I/O circuit type*1	Function
26	PD2	I	General-purpose I/O port
	SCK2		UART ch.2 serial clock I/O pin
27	PD3	J	General-purpose I/O port
	SIN3		UART ch.3 serial data input pin
28	PD4	I	General-purpose I/O port
	SOT3		UART ch.3 serial data output pin
29	PD5	I	General-purpose I/O port
	SCK3		UART ch.3 serial clock I/O pin
30	PD6	I	General-purpose I/O port
	TOT2		16-bit reload timer ch.2 TOT output pin
56	PE0	I	General-purpose I/O port
	TOT3		16-bit reload timer ch.3 TOT output pin
57	PE1	I	General-purpose I/O port
	TIN3		16-bit reload timer ch.3 TIN input pin
64	PE2	I	General-purpose I/O port
	SGO1		Sound generator ch.1 SGO output pin
62	RSTO	N	Internal reset signal output pin
65, 75, 85	DVCC	—	Power supply input pins dedicated for high current output buffer
66, 76, 86	DVSS	—	Power supply GND pins dedicated for high current output buffer
35	AVCC	—	A/D converter dedicated power supply input pin
38	AVSS	—	A/D converter dedicated power supply GND pin
36	AVRH	—	A/D converter Vref+ input pin. Vref- is fixed to AVSS.
89	MD0	D	Mode setting input pin. Connect to VCC pin.
88	MD1	D	Mode setting input pin. Connect to VCC pin.
87	MD2	D/E*2	Mode setting input pin. Connect to VSS pin.
17	C	—	External capacitor pin. Connect a 0.1 μ F capacitor between this pin and the VSS pin.
15, 105	VCC	—	Power supply input pins
16, 47, 106	VSS	—	GND power supply pins

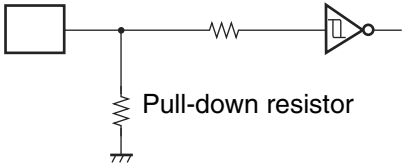
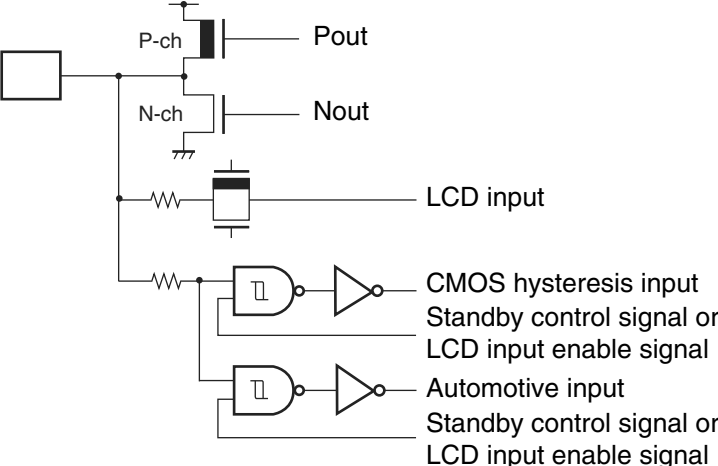
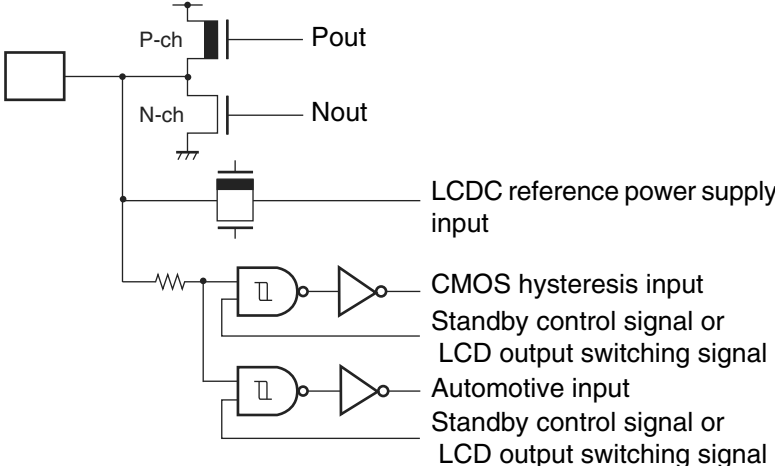
*1 : For I/O circuit type, refer to “■ I/O CIRCUIT TYPES”.

*2 : The I/O circuit type is D for Flash memory products and E for evaluation products.

■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A	 <p>Standby control signal</p>	<p>Oscillation circuit</p> <p>High-speed oscillation feedback resistance : approx. 1 MΩ</p> <p>(Flash memory product/MASK ROM product/Evaluation product)</p>
B	 <p>Standby control signal</p>	<p>Oscillation circuit</p> <p>Low-speed oscillation feedback resistance : approx. 10 MΩ</p>
C	 <p>Pull-up resistor</p> <p>CMOS hysteresis input</p>	<p>Input-only pin (with pull-up resistance)</p> <ul style="list-style-type: none"> Attached pull-up resistor : approx. 50 kΩ CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$)
D	 <p>CMOS hysteresis input</p>	<p>Input-only pin</p> <ul style="list-style-type: none"> CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) <p>Note: The MD2 pin of the Flash memory products uses this circuit type.</p>

(Continued)

Type	Circuit	Remarks
E	 <p>CMOS hysteresis input</p> <p>Pull-down resistor</p>	<p>Input-only pin (with pull-down resistance)</p> <ul style="list-style-type: none"> Attached pull-down resistance: approx. 50 kΩ CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) <p>Note: The MD2 pin of the evaluation products uses this circuit type.</p>
F	 <p>P-ch Pout</p> <p>N-ch Nout</p> <p>LCD input</p> <p>CMOS hysteresis input Standby control signal or LCD input enable signal</p> <p>Automotive input Standby control signal or LCD input enable signal</p>	<p>LCD output common general-purpose port</p> <ul style="list-style-type: none"> CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) Hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
G	 <p>P-ch Pout</p> <p>N-ch Nout</p> <p>LCDC reference power supply input</p> <p>CMOS hysteresis input Standby control signal or LCD output switching signal</p> <p>Automotive input Standby control signal or LCD output switching signal</p>	<p>LCDC reference power supply common general-purpose port</p> <ul style="list-style-type: none"> CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)

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- **Notes on operating in PLL clock mode**

On this microcontroller, if in case the crystal oscillator breaks off or an external reference clock input stops while the PLL clock mode is selected, a self-oscillator circuit contained in the PLL may continue its operation at its self-running frequency. However, FUJITSU SEMICONDUCTOR will not guarantee results of operations if such failure occurs.

- **Crystal oscillator circuit**

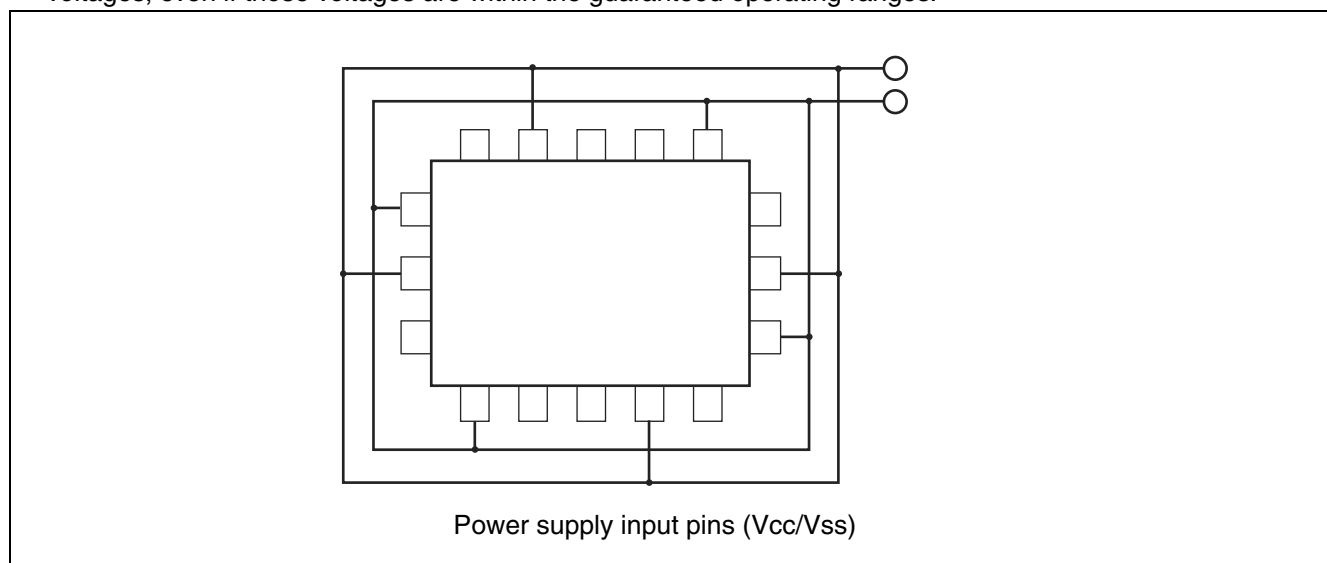
Noise around the X0/X1, or X0A/X1A pins may cause this device to operate abnormally. In the interest of stable operation it is strongly recommended that printed circuit artwork places ground bypass capacitors as close as possible to the X0/X1, X0A/X1A and crystal oscillator (or ceramic oscillator) and that oscillator lines do not cross the lines of other circuits.

Please ask each crystal maker to evaluate the oscillational characteristics of the crystal and this device.

- **Power supply pins**

Devices including multiple VCC or VSS pins are designed such that pins that need to be at the same potential are interconnected internally to prevent malfunctions such as latch-up. To reduce unnecessary radiation, prevent malfunctioning of the strobe signal due to the rise of ground level, and observe the standard for total output current, be sure to connect the VCC and VSS pins to the power supply and ground externally.

Always connect all of the VCC pins to the same potential and all of the VSS pins to ground as shown in the following diagram. The device will not operate correctly if multiple VCC or VSS pins are connected to different voltages, even if those voltages are within the guaranteed operating ranges.



In addition, care must be given to connecting the VCC and VSS pins of this device to the current supply source with as low impedance as possible. It is recommended that a 1.0 μ F bypass capacitor be connected between the VCC and VSS pins as close to the pins as possible.

- **Sequence for connecting the A/D converter power supply and analog inputs**

The A/D converter power supply (AV_{CC} , AV_{RH}) and analog inputs (AN0 to AN7) must be applied after the digital power supply (V_{CC}) is switched on. When turning the power off, the A/D converter power supply and analog inputs must be disconnected before the digital power supply is switched off (V_{CC}). Ensure that AV_{RH} does not exceed AV_{CC} during either power-on or power-off. Even when pins which double as analog input pins are used as input ports, be sure that the input voltage does not exceed AV_{CC} (turning on/off the analog and digital power supplies simultaneously is acceptable).

- **Handling the power supply for high-current output buffer pins (DV_{CC} , DV_{SS})**

- **Flash memory products and MASK ROM products (MB90F922NC/F922NCS/922NCS/F923NC/F923NCS/F924NC/F924NCS)**

In the Flash memory products and MASK ROM products, the power supply for the high-current output buffer pins (DV_{CC} , DV_{SS}) is isolated from the digital power supply (V_{CC}).

Therefore, DV_{CC} can therefore be set to a higher voltage than V_{CC} . If the power supply for the high-current output buffer pins (DV_{CC} , DV_{SS}) is supplied before the digital power supply (V_{CC}), however, care needs to be taken because it is possible that the port 7 or port 8 stepping motor outputs may momentarily output an “H” or “L” level. In order to prevent this, connect the digital power supply (V_{CC}) prior to connecting the power supply for the high-current output buffer pins. Even when the high-current output buffer pins are used as general-purpose ports, power should be supplied to the power supply pins for the high-current output buffer pins (DV_{CC} , DV_{SS}).

- **Evaluation product (MB90V920-101/MB90V920-102)**

In the evaluation products, the power supply for the high-current output buffer pins (DV_{CC} , DV_{SS}) is not isolated from the digital power supply (V_{CC}). Therefore, DV_{CC} must therefore be set to a lower voltage than V_{CC} . The power supply for the high-current output buffer pins (DV_{CC} , DV_{SS}) must always be applied after the digital power supply (V_{CC}) has been connected, and disconnected before the digital power supply (V_{CC}) is disconnected (the power supply for the high-current output buffer pins may also be connected and disconnected simultaneously with the digital power supply).

Even when the high-current output buffer pins are used as general-purpose ports, power should be supplied to the power supply pins for the high-current output buffer pins (DV_{CC} , DV_{SS}).

- **Pull-up/pull-down resistors**

MB90920 series does not support internal pull-up/pull-down resistors. Use external components as necessary.

- **Precautions when not using a sub clock signal**

If the X0A and X1A pins are not connected to an oscillator, apply a pull-down resistance to the X0A pin and leave the X1A pin open.

- **Notes on operating when the external clock is stopped**

The MB90920 series is not guaranteed to operate correctly using the internal oscillator circuit when there is no external oscillator or the external clock input is stopped.

- **Flash memory security function**

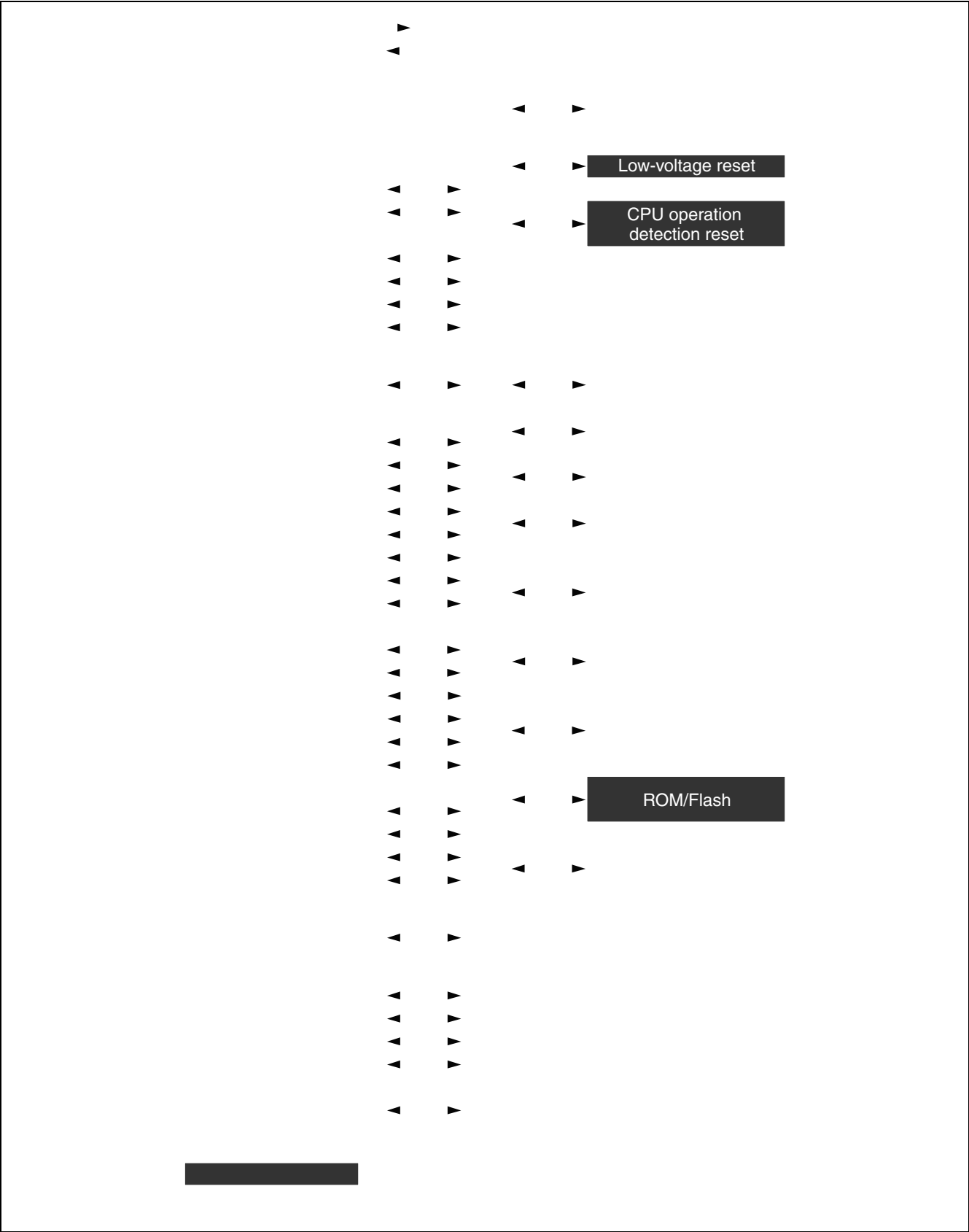
A security bit is located within the Flash memory region. The security function is activated by writing the protection code 01_H to the security bit.

Do not write the value 01_H to this address if you are not using the security function.

Please refer to following table for the address of the security bit.

	Flash memory size	Address for security bit
MB90F922NC MB90F922NCS	Built-in 2 Mbits Flash Memory	FC0001 _H
MB90F923NCS	Built-in 3 Mbits Flash Memory	F80001 _H
MB90F924NCS	Built-in 4 Mbits Flash Memory	F80001 _H

■ BLOCK DIAGRAM



MB90920 Series

Address	Register name	Symbol	Read/write	Resource name	Initial value
000024 _H	Compare clear register	CPCLR	R/W	16-bit free-run timer	XXXXXXXX _B
000025 _H			R/W		XXXXXXXX _B
000026 _H	Timer data register	TCDT	R/W		00000000 _B
000027 _H			R/W		00000000 _B
000028 _H	Lower timer control status register	TCCSL	R/W		00000000 _B
000029 _H	Higher timer control status register	TCCSH	R/W		01-00000 _B
00002A _H	Lower PPG0 control status register	PCNTL0	R/W	16-bit PPG0	00000000 _B
00002B _H	Higher PPG0 control status register	PCNTH0	R/W		00000001 _B
00002C _H	Lower PPG1 control status register	PCNTL1	R/W	16-bit PPG1	00000000 _B
00002D _H	Higher PPG1 control status register	PCNTH1	R/W		00000001 _B
00002E _H	Lower PPG2 control status register	PCNTL2	R/W	16-bit PPG2	00000000 _B
00002F _H	Higher PPG2 control status register	PCNTH2	R/W		00000001 _B
000030 _H	External interrupt enable	ENIR	R/W	External interrupt	00000000 _B
000031 _H	External interrupt request	EIRR	R/W		00000000 _B
000032 _H	Lower external interrupt level	ELVRL	R/W		00000000 _B
000033 _H	Higher external interrupt level	ELVRH	R/W		00000000 _B
000034 _H	Serial mode register 0	SMR0	R/W, W	UART (LIN/SCI) 0	00000000 _B
000035 _H	Serial control register 0	SCR0	R/W, W		00000000 _B
000036 _H	Reception/transmission data register 1	RDR0/ TDR0	R/W		00000000 _B
000037 _H	Serial status register 0	SSR0	R/W, R		00001000 _B
000038 _H	Extended communication control register 0	ECCR0	R/W, R		000000XX _B
000039 _H	Extended status control register 0	ESCR0	R/W		00000100 _B
00003A _H	Baud rate generator register 00	BGR00	R/W		00000000 _B
00003B _H	Baud rate generator register 01	BGR01	R/W, R		00000000 _B
00003C _H to 00003F _H	(Disabled)				
000040 _H to 00004F _H	Area reserved for CAN Controller 0. Refer to “■ CAN CONTROLLERS”				
000050 _H	Lower timer control status register 0	TMCSR0L	R/W	16-bit reload timer 0	00000000 _B
000051 _H	Higher timer control status register 0	TMCSR0H	R/W		XXX10000 _B
000052 _H	Timer register 0/reload register 0	TMR0/ TMRLR0	R/W		XXXXXXXX _B
000053 _H					XXXXXXXX _B

(Continued)

MB90920 Series

Address	Register name	Symbol	Read/write	Resource name	Initial value
003944 _H	Input capture register 6	IPCP6	R	Input capture 6/7	XXXXXXXX _B
003945 _H					XXXXXXXX _B
003946 _H	Input capture register 7	IPCP7	R		XXXXXXXX _B
003947 _H					XXXXXXXX _B
003948 _H to 00394F _H	(Disabled)				
003950 _H	Minute data register 2/Reload register 2	TMR2/ TMRLR2	R/W	16-bit reload timer 2	XXXXXXXX _B
003951 _H					XXXXXXXX _B
003952 _H	Minute data register 3/Reload register 3	TMR3/ TMRLR3	R/W	16-bit reload timer 3	XXXXXXXX _B
003953 _H					XXXXXXXX _B
003954 _H to 003957 _H	(Disabled)				
003958 _H	Sub second data register	WTBR	R/W	Real time watch timer	XXXXXXXX _B
003959 _H					XXXXXXXX _B
00395A _H					XXXXXXXX _B
00395B _H	Second data register	WTSR	R/W		XX000000 _B
00395C _H	Minute data register	WTMR	R/W		XX000000 _B
00395D _H	Hour data register	WTHR	R/W		XXX00000 _B
00395E _H	Day data register	WTDR	R/W		00X00001 _B
00395F _H	(Disabled)				
003960 _H	LCD display RAM	VRAM	R/W	LCD controller/ driver	XXXXXXXX _B
003961 _H					XXXXXXXX _B
003962 _H					XXXXXXXX _B
003963 _H					XXXXXXXX _B
003964 _H					XXXXXXXX _B
003965 _H					XXXXXXXX _B
003966 _H					XXXXXXXX _B
003967 _H					XXXXXXXX _B
003968 _H					XXXXXXXX _B
003969 _H					XXXXXXXX _B
00396A _H					XXXXXXXX _B
00396B _H					XXXXXXXX _B
00396C _H					XXXXXXXX _B
00396D _H					XXXXXXXX _B
00396E _H					XXXXXXXX _B
00396F _H					XXXXXXXX _B

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MB90920 Series

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Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A40 _H	003B40 _H	003740 _H	003840 _H	ID register 8	IDR8	R/W	XXXXXXXX _B XXXXXXXX _B
003A41 _H	003B41 _H	003741 _H	003841 _H				XXXXXX--- _B XXXXXXXX _B
003A42 _H	003B42 _H	003742 _H	003842 _H				
003A43 _H	003B43 _H	003743 _H	003843 _H				
003A44 _H	003B44 _H	003744 _H	003844 _H	ID register 9	IDR9	R/W	XXXXXXXX _B XXXXXXXX _B
003A45 _H	003B45 _H	003745 _H	003845 _H				XXXXXX--- _B XXXXXXXX _B
003A46 _H	003B46 _H	003746 _H	003846 _H				
003A47 _H	003B47 _H	003747 _H	003847 _H				
003A48 _H	003B48 _H	003748 _H	003848 _H	ID register 10	IDR10	R/W	XXXXXXXX _B XXXXXXXX _B
003A49 _H	003B49 _H	003749 _H	003849 _H				XXXXXX--- _B XXXXXXXX _B
003A4A _H	003B4A _H	00374A _H	00384A _H				
003A4B _H	003B4B _H	00374B _H	00384B _H				
003A4C _H	003B4C _H	00374C _H	00384C _H	ID register 11	IDR11	R/W	XXXXXXXX _B XXXXXXXX _B
003A4D _H	003B4D _H	00374D _H	00384D _H				XXXXXX--- _B XXXXXXXX _B
003A4E _H	003B4E _H	00374E _H	00384E _H				
003A4F _H	003B4F _H	00374F _H	00384F _H				
003A50 _H	003B50 _H	003750 _H	003850 _H	ID register 12	IDR12	R/W	XXXXXXXX _B XXXXXXXX _B
003A51 _H	003B51 _H	003751 _H	003851 _H				XXXXXX--- _B XXXXXXXX _B
003A52 _H	003B52 _H	003752 _H	003852 _H				
003A53 _H	003B53 _H	003753 _H	003853 _H				
003A54 _H	003B54 _H	003754 _H	003854 _H	ID register 13	IDR13	R/W	XXXXXXXX _B XXXXXXXX _B
003A55 _H	003B55 _H	003755 _H	003855 _H				XXXXXX--- _B XXXXXXXX _B
003A56 _H	003B56 _H	003756 _H	003856 _H				
003A57 _H	003B57 _H	003757 _H	003857 _H				
003A58 _H	003B58 _H	003758 _H	003858 _H	ID register 14	IDR14	R/W	XXXXXXXX _B XXXXXXXX _B
003A59 _H	003B59 _H	003759 _H	003859 _H				XXXXXX--- _B XXXXXXXX _B
003A5A _H	003B5A _H	00375A _H	00385A _H				
003A5B _H	003B5B _H	00375B _H	00385B _H				
003A5C _H	003B5C _H	00375C _H	00385C _H	ID register 15	IDR15	R/W	XXXXXXXX _B XXXXXXXX _B
003A5D _H	003B5D _H	00375D _H	00385D _H				XXXXXX--- _B XXXXXXXX _B
003A5E _H	003B5E _H	00375E _H	00385E _H				
003A5F _H	003B5F _H	00375F _H	00385F _H				

List of Message Buffers (DLC Registers)

Address				Register	Abbrevia- tion	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A60 _H	003B60 _H	003760 _H	003860 _H	DLC register 0	DLCR0	R/W	----XXXX _B
003A61 _H	003B61 _H	003761 _H	003861 _H				
003A62 _H	003B62 _H	003762 _H	003862 _H	DLC register 1	DLCR1	R/W	----XXXX _B
003A63 _H	003B63 _H	003763 _H	003863 _H				
003A64 _H	003B64 _H	003764 _H	003864 _H	DLC register 2	DLCR2	R/W	----XXXX _B
003A65 _H	003B65 _H	003765 _H	003865 _H				
003A66 _H	003B66 _H	003766 _H	003866 _H	DLC register 3	DLCR3	R/W	----XXXX _B
003A67 _H	003B67 _H	003767 _H	003867 _H				
003A68 _H	003B68 _H	003768 _H	003868 _H	DLC register 4	DLCR4	R/W	----XXXX _B
003A69 _H	003B69 _H	003769 _H	003869 _H				
003A6A _H	003B6A _H	00376A _H	00386A _H	DLC register 5	DLCR5	R/W	----XXXX _B
003A6B _H	003B6B _H	00376B _H	00386B _H				
003A6C _H	003B6C _H	00376C _H	00386C _H	DLC register 6	DLCR6	R/W	----XXXX _B
003A6D _H	003B6D _H	00376D _H	00386D _H				
003A6E _H	003B6E _H	00376E _H	00386E _H	DLC register 7	DLCR7	R/W	----XXXX _B
003A6F _H	003B6F _H	00376F _H	00386F _H				
003A70 _H	003B70 _H	003770 _H	003870 _H	DLC register 8	DLCR8	R/W	----XXXX _B
003A71 _H	003B71 _H	003771 _H	003871 _H				
003A72 _H	003B72 _H	003772 _H	003872 _H	DLC register 9	DLCR9	R/W	----XXXX _B
003A73 _H	003B73 _H	003773 _H	003873 _H				
003A74 _H	003B74 _H	003774 _H	003874 _H	DLC register 10	DLCR10	R/W	----XXXX _B
003A75 _H	003B75 _H	003775 _H	003875 _H				
003A76 _H	003B76 _H	003776 _H	003876 _H	DLC register 11	DLCR11	R/W	----XXXX _B
003A77 _H	003B77 _H	003777 _H	003877 _H				
003A78 _H	003B78 _H	003778 _H	003878 _H	DLC register 12	DLCR12	R/W	----XXXX _B
003A79 _H	003B79 _H	003779 _H	003879 _H				
003A7A _H	003B7A _H	00377A _H	00387A _H	DLC register 13	DLCR13	R/W	----XXXX _B
003A7B _H	003B7B _H	00377B _H	00387B _H				
003A7C _H	003B7C _H	00377C _H	00387C _H	DLC register 14	DLCR14	R/W	----XXXX _B
003A7D _H	003B7D _H	00377D _H	00387D _H				
003A7E _H	003B7E _H	00377E _H	00387E _H	DLC register 15	DLCR15	R/W	----XXXX _B
003A7F _H	003B7F _H	00377F _H	00387F _H				

■ INTERRUPT SOURCES, INTERRUPT VECTORS, AND INTERRUPT CONTROL REGISTERS

Interrupt source	EI ² OS corresponding	Interrupt vector			Interrupt control register		Priority *2
		Number		Address	ICR	Address	
Reset	×	#08	08 _H	FFFFDC _H	—	—	<div>High</div> <div>↑</div> <div>↓</div> <div>Low</div>
INT9 instruction	×	#09	09 _H	FFFFD8 _H	—	—	
Exception processing	×	#10	0A _H	FFFFD4 _H	—	—	
CAN0 received/CAN2 received	×	#11	0B _H	FFFFD0 _H	ICR00	0000B0 _H *1	
CAN0 transmitted/node status/ CAN2 transmitted/node status	×	#12	0C _H	FFFFCC _H			
CAN1 received/CAN3 received	×	#13	0D _H	FFFFC8 _H	ICR01	0000B1 _H *1	
CAN1 transmitted/node status/ CAN3 transmitted/node status/SIO	×	#14	0E _H	FFFFC4 _H			
Input capture 0	△	#15	0F _H	FFFFC0 _H	ICR02	0000B2 _H *1	
DTP/ external interrupt - ch.0/ch.1 detected	△	#16	10 _H	FFFFBC _H			
Reload timer 0	△	#17	11 _H	FFFFB8 _H	ICR03	0000B3 _H *1	
Reload timer 2	△	#18	12 _H	FFFFB4 _H			
Input capture 1	△	#19	13 _H	FFFFB0 _H	ICR04	0000B4 _H *1	
DTP/ external interrupt - ch.2/ch.3 detected	△	#20	14 _H	FFFFAC _H			
Input capture 2	△	#21	15 _H	FFFFA8 _H	ICR05	0000B5 _H *1	
Reload timer 3	△	#22	16 _H	FFFFA4 _H			
Input capture 3/4/5/6/7	△	#23	17 _H	FFFFA0 _H	ICR06	0000B6 _H *1	
DTP/ external interrupt - ch.4/ ch.5 detected UART3 RX	△	#24	18 _H	FFFF9C _H			
PPG timer 0	△	#25	19 _H	FFFF98 _H	ICR07	0000B7 _H *1	
DTP/ external interrupt - ch.6/ ch.7 detected UART3 TX	△	#26	1A _H	FFFF94 _H			
PPG timer 1	△	#27	1B _H	FFFF90 _H	ICR08	0000B8 _H *1	
Reload timer 1	△	#28	1C _H	FFFF8C _H			
PPG timer 2/3/4/5	○	#29	1D _H	FFFF88 _H	ICR09	0000B9 _H *1	
Real time watch timer watch timer (sub clock)	×	#30	1E _H	FFFF84 _H			
Free-run timer overflow/clear	×	#31	1F _H	FFFF80 _H	ICR10	0000BA _H *1	
A/D converter conversion complete	○	#32	20 _H	FFFF7C _H			
Sound generator 0/1	×	#33	21 _H	FFFF78 _H	ICR11	0000BB _H *1	
Time-base timer	×	#34	22 _H	FFFF74 _H			
UART2 RX	○	#35	23 _H	FFFF70 _H	ICR12	0000BC _H *1	
UART2 TX	△	#36	24 _H	FFFF6C _H			

(Continued)

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3. DC Characteristics

($V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = DV_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C}$ to $+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
“H” level input voltage	V_{IHA}	—	—	$0.8 V_{CC}$	—	—	V	Pin inputs if Automotive input levels are selected
	V_{IHS}	—	—	$0.8 V_{CC}$	—	—	V	Pin inputs if CMOS hysteresis input levels are selected
	V_{IHC}	—	—	$0.7 V_{CC}$	—	—	V	\overline{RST} input pin (CMOS hysteresis)
“L” level input voltage	V_{ILA}	—	—	—	—	$0.5 V_{CC}$	V	Pin inputs if Automotive input levels are selected
	V_{ILS}	—	—	—	—	$0.2 V_{CC}$	V	Pin inputs if CMOS hysteresis input levels are selected
	V_{ILR}	—	—	—	—	$0.3 V_{CC}$	V	\overline{RST} input pin (CMOS hysteresis)
Power supply current*	I_{CC}	V_{CC}	Maximum operating frequency $F_{CP} = 32\text{ MHz}$, normal operation	—	35	45	mA	
			Maximum operating frequency $F_{CP} = 32\text{ MHz}$, writing Flash memory	—	55	65	mA	
	I_{CCS}		Operating frequency $F_{CP} = 32\text{ MHz}$, sleep mode	—	13	20	mA	
	I_{CTS}		Operating frequency $F_{CP} = 2\text{ MHz}$, time-base timer mode	—	0.6	1.0	mA	
	I_{CTSPLL}		Operating frequency $F_{CP} = 32\text{ MHz}$, PLL timer mode, External frequency = 4 MHz	—	2.5	4	mA	
	I_{CCL}		Operating frequency $F_{CP} = 8\text{ kHz}$, $T_A = +25\text{ }^{\circ}\text{C}$, sub clock operation	—	120	270	μA	
	I_{CCLS}		Operating frequency $F_{CP} = 8\text{ kHz}$, $T_A = +25\text{ }^{\circ}\text{C}$, sub sleep operation	—	100	200	μA	
	I_{CCT}		Operating frequency $F_{CP} = 8\text{ kHz}$, $T_A = +25\text{ }^{\circ}\text{C}$, watch mode	—	90	180	μA	
	I_{CCH}		$T_A = +25\text{ }^{\circ}\text{C}$, stop mode	—	80	170	μA	

(Continued)

(2) Reset input

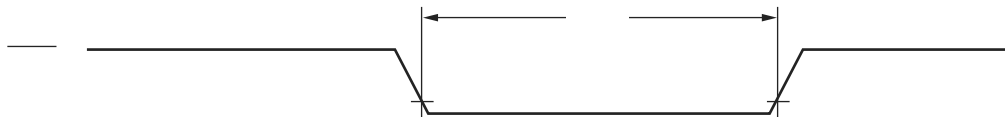
($V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C}$ to $+105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value		Unit	Remarks
			Min	Max		
Reset input time	t_{RSTL}	\overline{RST}	500	—	ns	During normal operation
			Oscillator oscillation time* + $16 t_{CP}$	—	ms	In stop mode, sub clock mode, sub sleep mode, and watch mode
			100	—	μs	In time-base timer mode

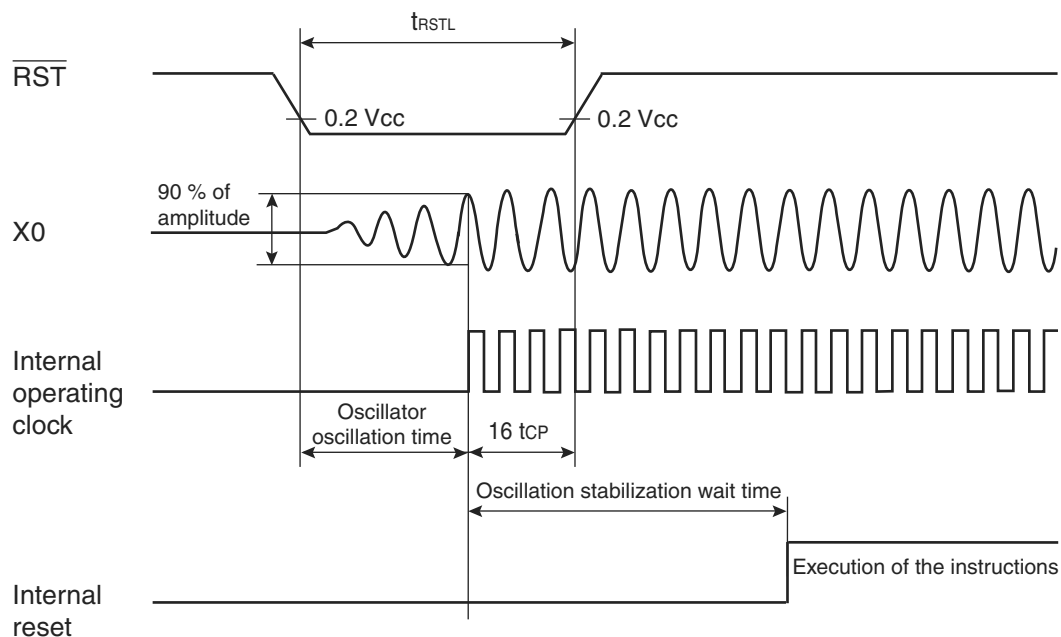
*: The oscillation time of the oscillator is the time taken to reach 90% of the amplitude. The oscillation time of a crystal oscillator is between several ms and tens of ms. The oscillation time of a ceramic oscillator is between hundreds of μs and several ms. The oscillation time of an external clock is 0 ms.

Note : t_{CP} is the internal operating clock cycle time. (Unit : ns)

• During normal operation



• In stop mode, sub clock mode, sub sleep mode, watch mode, and power-on



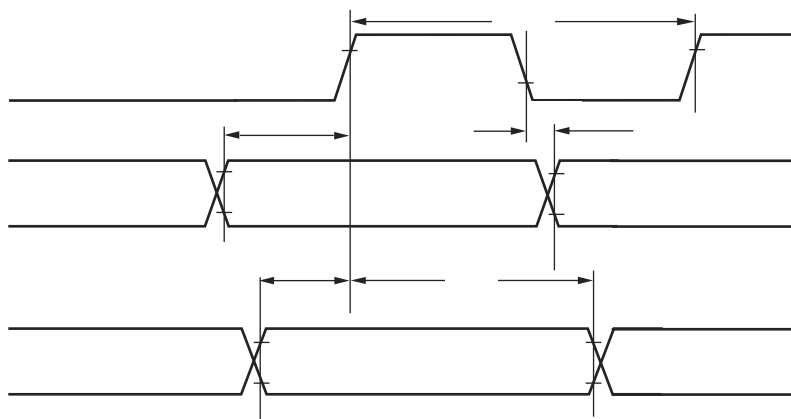
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- Bit setting: ESCR0/1/2/3:SCES=1, ECCR0/1/2/3:SCDE=1

($V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C}$ to $+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Serial clock cycle time	t _{SCYC}	SCK0 to SCK3	Internal shift clock mode output pin C _L = 80 pF + 1TTL	5 t _{CP}	—	ns
SCK ↓ → SOT delay time	t _{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		– 50	+ 50	ns
Valid SIN → SCK ↓	t _{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		t _{CP} + 80	—	ns
SCK ↑ → valid SIN hold time	t _{SHIXI}			0	—	ns
SOT → SCK ↑ delay time	t _{SOVHI}	SCK0 to SCK3, SOT0 to SOT3		3 t _{CP} – 70	—	ns

- Notes :
- Depending on the machine clock frequency to be used, the maximum baud rate may be limited by some parameters. These parameters are shown in “MB90920 series hardware manual”.
 - C_L is the load capacitance connected to the pin during testing.
 - t_{CP} is the internal operating clock cycle time. Refer to “(1) Clock timing”.



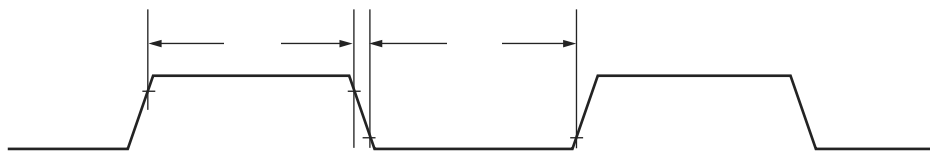
(6) Trigger input timing

($V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C}$ to $+105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Input pulse width	t_{TRGH} , t_{TRGL}	INT0 to INT7	—	200	—	ns	During normal operation
		ADTG	—	$t_{CP} + 200$	—	ns	

Note : t_{CP} is the internal operating clock cycle time. Refer to “(1) Clock timing”.

- Trigger input timing



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5. A/D Converter

(1) Electrical Characteristics

($V_{CC} = AV_{CC} = AVRH = 4.0\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	− 3.0	—	+ 3.0	LSB	
Non-linear error	—	—	− 2.5	—	+ 2.5	LSB	
Differential linear error	—	—	− 1.9	—	+ 1.9	LSB	
Zero transition voltage	V_{OT}	AN0 to AN7	$AV_{SS} - 1.5\text{ LSB}$	$AV_{SS} + 0.5\text{ LSB}$	$AV_{SS} + 2.5\text{ LSB}$	V	1 LSB = ($AVRH - AV_{SS}$) / 1024
Full scale transition voltage	V_{FST}	AN0 to AN7	$AVRH - 3.5\text{ LSB}$	$AVRH - 1.5\text{ LSB}$	$AVRH + 0.5\text{ LSB}$	V	
Sampling time	t_{SMP}	—	0.4	—	16500	μs	$4.5\text{ V} \leq AV_{CC} \leq 5.5\text{ V}$
			1.0				$4.0\text{ V} \leq AV_{CC} \leq 4.5\text{ V}$
Compare time	t_{CMP}	—	0.66	—	—	μs	$4.5\text{ V} \leq AV_{CC} \leq 5.5\text{ V}$
			2.2				$4.0\text{ V} \leq AV_{CC} \leq 4.5\text{ V}$
A/D conversion time	t_{CNV}	—	1.44	—	—	μs	*1
Analog port input current	I_{AIN}	AN0 to AN7	− 0.3	—	+ 10	μA	
Analog input voltage	V_{AIN}	AN0 to AN7	0	—	$AVRH$	V	
Reference voltage	$AV+$	$AVRH$	$AV_{SS} + 2.7$	—	AV_{CC}	V	
Power supply current	I_A	AV_{CC}	—	2.3	6.0	mA	
	I_{AH}		—	—	5	μA	*2
Reference voltage supply current	I_R	$AVRH$	—	520	900	μA	$V_{AVRH} = 5.0\text{ V}$
	I_{RH}		—	—	5	μA	*2
Inter-channel variation	—	AN0 to AN7	—	—	4	LSB	

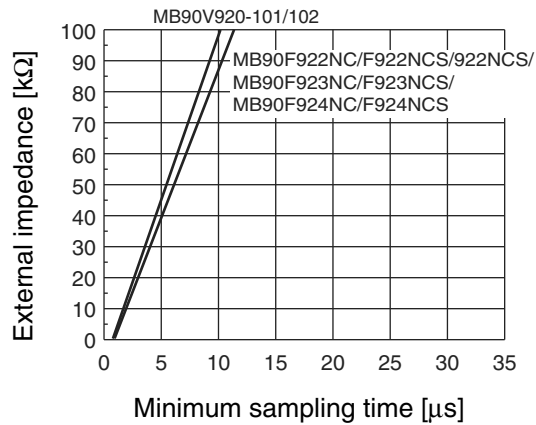
*1 : The time per channel ($4.5\text{ V} \leq AV_{CC} \leq 5.5\text{ V}$, and internal operating frequency = 32 MHz) .

*2 : Defined as supply current (when $V_{CC} = AV_{CC} = AVRH = 5.0\text{ V}$) with A/D converter not operating, and CPU in stop mode.

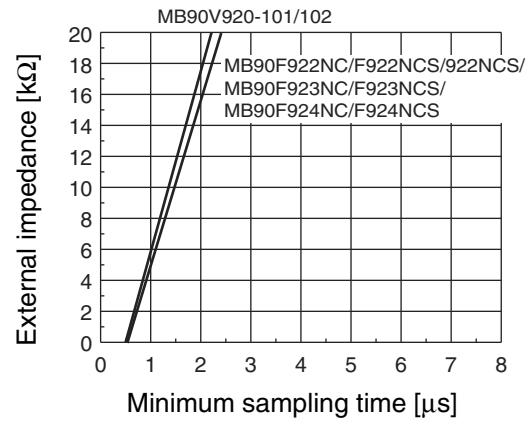
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- The relationship between the external impedance and minimum sampling time
- At $4.5\text{ V} \leq AV_{CC} \leq 5.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)

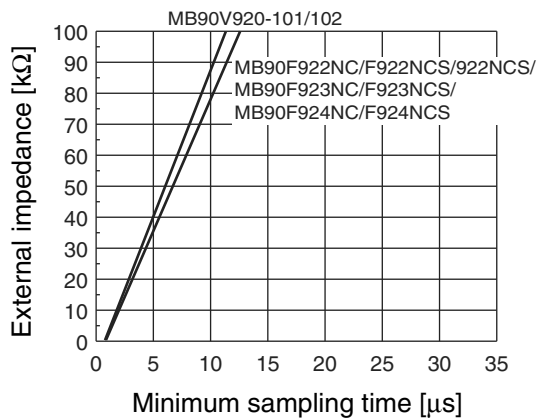


(External impedance = 0 k Ω to 20 k Ω)

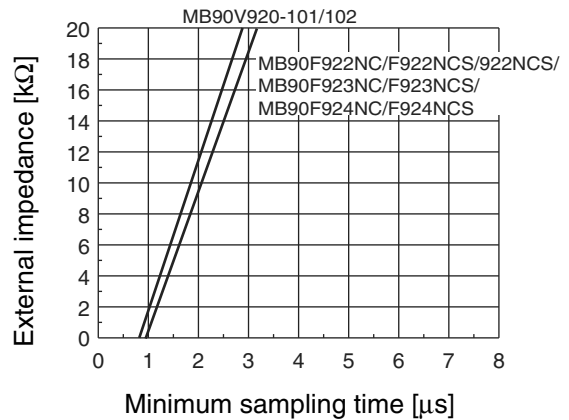


- At $4.0\text{ V} \leq AV_{CC} \leq 4.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)



(External impedance = 0 k Ω to 20 k Ω)

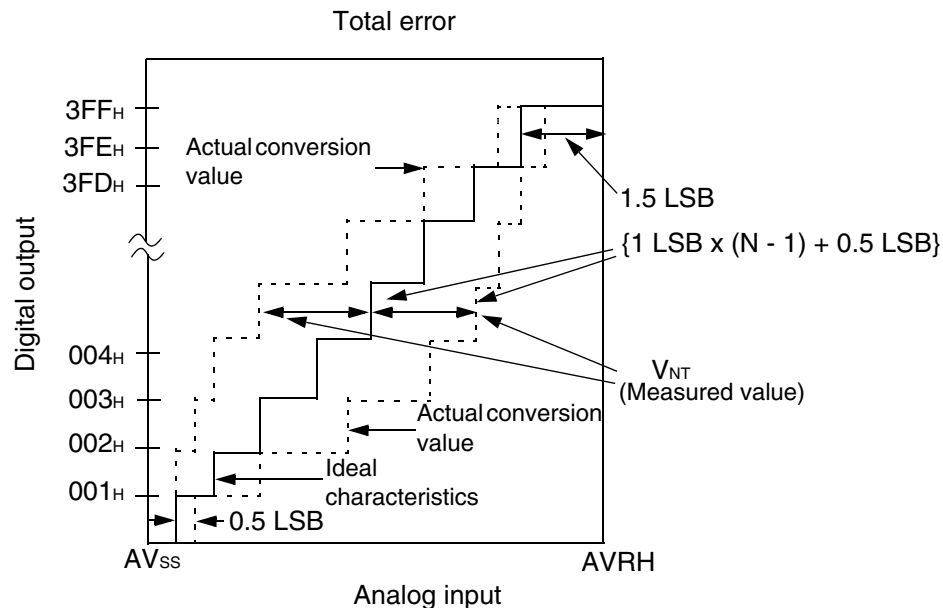


- About errors

As $|AV_{RH} - AV_{SS}|$ becomes smaller, the relative errors grow larger.

(2) Definition of terms

- Resolution : Analog changes that are identifiable by the A/D converter.
- Non-Linear error : The deviation of the straight line connecting the zero transition point (“00 0000 0000” \longleftrightarrow “00 0000 0001”) with the full-scale transition point (“11 1111 1110” \longleftrightarrow “11 1111 1111”) from actual conversion characteristics.
- Differential linear error : The deviation from the ideal value of the input voltage needed to change the output code by 1 LSB.
- Total error : The total error is the difference between the actual value and the theoretical value, and includes zero-transition error/full-scale transition error and linear error.



$$\text{Total error for digital output } N = \frac{V_{NT} - \{1 \text{ LSB} \times (N - 1) + 0.5 \text{ LSB}\}}{1 \text{ LSB}} \quad [\text{LSB}]$$

$$1 \text{ LSB (Ideal)} = \frac{AVRH - AVSS}{1024} \quad [\text{V}]$$

N : A/D converter digital output value

$$V_{OT} \text{ (Ideal)} = AVSS + 0.5 \text{ LSB} \quad [\text{V}]$$

$$V_{FST} \text{ (Ideal)} = AVRH - 1.5 \text{ LSB} \quad [\text{V}]$$

V_{NT} : Voltage when the digital output changes from (N - 1) to N

(Continued)

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■ MAJOR CHANGES IN THIS EDITION

Page	Section	Change Results
12	■ I/O CIRCUIT TYPE	Corrected the circuit type B.
20	■ HANDLING DEVICES	Added the following items; <ul style="list-style-type: none">• Serial communication• Characteristic difference between flash device and MASK ROM device
31	■ I/O MAP	Corrected “Address: 003970 _H ”. Clock supervisor control register → (Disabled)
46	■ ELECTRICAL CHARACTERISTICS 3. DC Characteristics	Added the item for “LCD output impedance”.
68	■ ORDERING INFORMATION	Corrected the part numbers; MB90V920-101 → MB90V920-101CR MB90V920-102 → MB90V920-102CR

The vertical lines marked in the left side of the page show the changes.

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