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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-138e1

16-bit Microcontroller

CMOS

F²MC-16LX MB90920 Series

**MB90F922NC/F922NCS/922NCS/F923NC/F923NCS/
MB90F924NC/F924NCS/V920-101/V920-102**

■ DESCRIPTION

The MB90920 series is a family of general-purpose FUJITSU SEMICONDUCTOR 16-bit microcontrollers designed for applications such as vehicle instrument panel control.

The instruction set retains the AT architecture from the F²MC-8L and F²MC-16LX families, with further refinements including high-level language instructions, extended addressing modes, improved multiplication and division operations (signed), and bit processing. In addition, long word processing is made possible by the inclusion of a built-in 32-bit accumulator.

Note : F²MC is the abbreviation of FUJITSU Flexible Microcontroller.

■ FEATURES

- Clock
Built-in PLL clock frequency multiplication circuit.
Selection of machine clocks (PLL clocks) is allowed among frequency division by two on oscillation clock, and multiplication of 1 to 8 times of oscillation clock (for 4 MHz oscillation clock, 4 MHz to 32 MHz).
Operation by sub clock (up to 50 kHz : 100 kHz oscillation clock divided by two) is allowed.
- 16-bit input capture (8 channels)
Detects rising, falling, or both edges.
16-bit capture register × 8
The value of a 16-bit free-run timer counter is latched upon detection of an edge input to pin and an interrupt request is generated.

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For the information for microcontroller supports, see the following web site.

This web site includes the "**Customer Design Review Supplement**" which provides the latest cautions on system development and the minimal requirements to be checked to prevent problems before the system development.

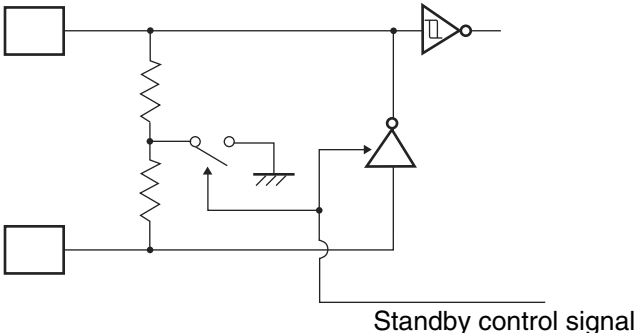
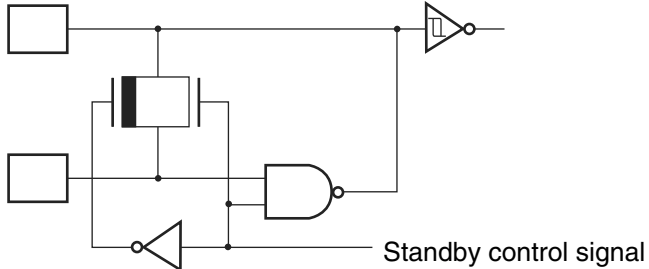
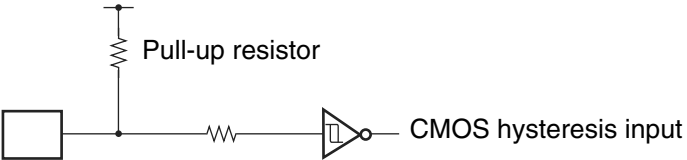
<http://edevise.fujitsu.com/micom/en-support/>

MB90920 Series

Pin no.	Pin name	I/O circuit type*1	Function
104	P13	I	General-purpose I/O port
	PPG5		16-bit PPG ch.5 output pin
109	P14	I	General-purpose I/O port
	TIN2		16-bit reload timer ch.2 TIN input pin
	IN1		Input capture ch.1 trigger input pin
110	P15	I	General-purpose I/O port
	IN0		Input capture ch.0 trigger input pin
111	COM0	P	LCD controller/driver common output pin
112	COM1	P	LCD controller/driver common output pin
113	COM2	P	LCD controller/driver common output pin
114	COM3	P	LCD controller/driver common output pin
115	P22	F	General-purpose I/O port
	SEG00		LCD controller/driver segment output pin
116	P23	F	General-purpose I/O port
	SEG01		LCD controller/driver segment output pin
117	P24	F	General-purpose I/O port
	SEG02		LCD controller/driver segment output pin
118	P25	F	General-purpose I/O port
	SEG03		LCD controller/driver segment output pin
119	P26	F	General-purpose I/O port
	SEG04		LCD controller/driver segment output pin
120	P27	F	General-purpose I/O port
	SEG05		LCD controller/driver segment output pin
1	P30	F	General-purpose I/O port
	SEG06		LCD controller/driver segment output pin
2	P31	F	General-purpose I/O port
	SEG07		LCD controller/driver segment output pin
3	P32	F	General-purpose I/O port
	SEG08		LCD controller/driver segment output pin
4	P33	F	General-purpose I/O port
	SEG09		LCD controller/driver segment output pin
5	P34	F	General-purpose I/O port
	SEG10		LCD controller/driver segment output pin
6	P35	F	General-purpose I/O port
	SEG11		LCD controller/driver segment output pin

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■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A	 Standby control signal	Oscillation circuit High-speed oscillation feedback resistance : approx. 1 MΩ (Flash memory product/MASK ROM product/Evaluation product)
B	 Standby control signal	Oscillation circuit Low-speed oscillation feedback resistance : approx. 10 MΩ
C	 Pull-up resistor CMOS hysteresis input	Input-only pin (with pull-up resistance) - Attached pull-up resistor : approx. 50 kΩ - CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$)
D	 CMOS hysteresis input	Input-only pin CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) Note: The MD2 pin of the Flash memory products uses this circuit type.

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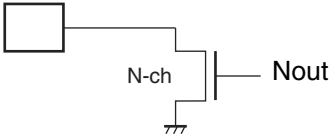
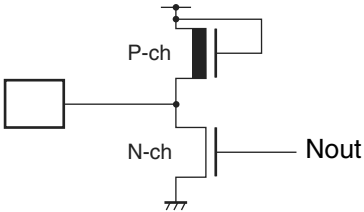
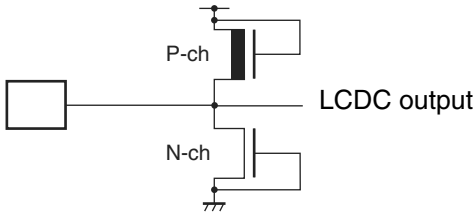
MB90920 Series

Type	Circuit	Remarks
H	P-ch N-ch Pout Nout Analog input CMOS hysteresis input Standby control signal or analog input enable signal Automotive input Standby control signal or analog input enable signal	A/D converter input common general-purpose port • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
I	P-ch N-ch Pout Nout CMOS hysteresis input Standby control signal Automotive input Standby control signal	General-purpose port • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
J	P-ch N-ch Pout Nout CMOS hysteresis input Standby control signal Automotive input Standby control signal CMOS input (SIN) Standby control signal	General-purpose port (serial input) • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • CMOS input (SIN) ($V_{IH}/V_{IL} = 0.7 V_{CC}/0.3 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)

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MB90920 Series

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Type	Circuit	Remarks
N	Evaluation product  Flash memory product 	N-ch open-drain pin $I_{OL} = 4 \text{ mA}$
O		Input-only pin Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
P		LCDC output pin (COM pin)

■ I/O MAP

Address	Register name	Symbol	Read/write	Resource name	Initial value
000000 _H	Port 0 data register	PDR0	R/W	Port 0	XXXXXXXX _B
000001 _H	Port 1 data register	PDR1	R/W	Port 1	XXXXXXXX _B
000002 _H	Port 2 data register	PDR2	R/W	Port 2	XXXXXXXX _B
000003 _H	Port 3 data register	PDR3	R/W	Port 3	XXXXXXXX _B
000004 _H	Port 4 data register	PDR4	R/W	Port 4	XXXXXXXX _B
000005 _H	Port 5 data register	PDR5	R/W	Port 5	XXXXXXXX _B
000006 _H	Port 6 data register	PDR6	R/W	Port 6	XXXXXXXX _B
000007 _H	Port 7 data register	PDR7	R/W	Port 7	XXXXXXXX _B
000008 _H	Port 8 data register	PDR8	R/W	Port 8	XXXXXXXX _B
000009 _H	Port 9 data register	PDR9	R/W	Port 9	XXXXXXXX _B
00000A _H , 00000B _H	(Disabled)				
00000C _H	Port C data register	PDRC	R/W	Port C	XXXXXXXX _B
00000D _H	Port D data register	PDRD	R/W	Port D	XXXXXXXX _B
00000E _H	Port E data register	PDRE	R/W	Port E	XXXXXXXX _B
00000F _H	(Disabled)				
000010 _H	Port 0 direction register	DDR0	R/W	Port 0	00000000 _B
000011 _H	Port 1 direction register	DDR1	R/W	Port 1	XX000000 _B
000012 _H	Port 2 direction register	DDR2	R/W	Port 2	000000XX _B
000013 _H	Port 3 direction register	DDR3	R/W	Port 3	00000000 _B
000014 _H	Port 4 direction register	DDR4	R/W	Port 4	00000000 _B
000015 _H	Port 5 direction register	DDR5	R/W	Port 5	00000000 _B
000016 _H	Port 6 direction register	DDR6	R/W	Port 6	00000000 _B
000017 _H	Port 7 direction register	DDR7	R/W	Port 7	00000000 _B
000018 _H	Port 8 direction register	DDR8	R/W	Port 8	00000000 _B
000019 _H	Port 9 direction register	DDR9	R/W	Port 9	X0000000 _B
00001A _H	Analog input enable	ADER6	R/W	Port 6, A/D	11111111 _B
00001B _H	(Disabled)				
00001C _H	Port C direction register	DDRC	R/W	Port C	00000000 _B
00001D _H	Port D direction register	DDRD	R/W	Port D	X0000000 _B
00001E _H	Port E direction register	DDRE	R/W	Port E	XXXXX000 _B
00001F _H	(Disabled)				
000020 _H	Lower A/D control status register	ADCS0	R/W	A/D converter	000XXXX0 _B
000021 _H	Higher A/D control status register	ADCS1	R/W		0000000X _B
000022 _H	Lower A/D control status register	ADCR0	R		00000000 _B
000023 _H	Higher A/D data register	ADCR1	R		XXXXXX00 _B

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MB90920 Series

Address	Register name	Symbol	Read/write	Resource name	Initial value
000083 _H	(Disabled)				
000084 _H	PWM control register 2	PWC2	R/W	Stepping motor controller 2	000000X0 _B
000085 _H	(Disabled)				
000086 _H	PWM control register 3	PWC3	R/W	Stepping motor controller 3	000000X0 _B
000087 _H	(Disabled)				
000088 _H	LCD output control register 3	LOCR3	R/W	LCDC	XXXXXX111 _B
000089 _H	(Disabled)				
00008A _H	A/D setting register 0	ADSR0	R/W	A/D converter	00000000 _B
00008B _H	A/D setting register 1	ADSR1	R/W		00000000 _B
00008C _H	Port input level select 0	PIL0	R/W	Port input level select	00000000 _B
00008D _H	Port input level select 1	PIL1	R/W		XXXX0000 _B
00008E _H	Port input level select 2	PIL2	R/W		XXXX0000 _B
00008F _H to 00009D _H	(Disabled)				
00009E _H	Program address detection control register	PACSR	R/W	Address match detection	XXXX0X0X _B
00009F _H	Delayed Interrupt/Release Register	DIRR	R/W	Delay interrupt	XXXXXXXX0 _B
0000A0 _H	Power saving mode control register	LPMCR	R/W	Power saving control circuit	00011000 _B
0000A1 _H	Clock select register	CKSCR	R/W, R		11111100 _B
0000A2 _H to 0000A7 _H	(Disabled)				
0000A8 _H	Watchdog timer control register	WDTC	R, W	Watchdog timer	XXXXXX111 _B
0000A9 _H	Time-base timer control register	TBTC	R/W, W	Time-base timer	1XX00100 _B
0000AA _H	Watch timer control register	WTC	R/W, W, R	Watch timer (sub clock)	10001000 _B
0000AB _H to 0000AD _H	(Disabled)				
0000AE _H	Flash memory control status register	FMCS	R/W	Flash interface	000X0000 _B
0000AF _H	(Disabled)				

(Continued)

Address	Register name	Symbol	Read/write	Resource name	Initial value
0000B0 _H	Interrupt control register 00	ICR00	R/W	Interrupt controller	00000111 _B
0000B1 _H	Interrupt control register 01	ICR01	R/W		00000111 _B
0000B2 _H	Interrupt control register 02	ICR02	R/W		00000111 _B
0000B3 _H	Interrupt control register 03	ICR03	R/W		00000111 _B
0000B4 _H	Interrupt control register 04	ICR04	R/W		00000111 _B
0000B5 _H	Interrupt control register 05	ICR05	R/W		00000111 _B
0000B6 _H	Interrupt control register 06	ICR06	R/W		00000111 _B
0000B7 _H	Interrupt control register 07	ICR07	R/W		00000111 _B
0000B8 _H	Interrupt control register 08	ICR08	R/W		00000111 _B
0000B9 _H	Interrupt control register 09	ICR09	R/W		00000111 _B
0000BA _H	Interrupt control register 10	ICR10	R/W		00000111 _B
0000BB _H	Interrupt control register 11	ICR11	R/W		00000111 _B
0000BC _H	Interrupt control register 12	ICR12	R/W		00000111 _B
0000BD _H	Interrupt control register 13	ICR13	R/W		00000111 _B
0000BE _H	Interrupt control register 14	ICR14	R/W		00000111 _B
0000BF _H	Interrupt control register 15	ICR15	R/W		00000111 _B
0000C0 _H to 0000C3 _H	(Disabled)				
0000C4 _H	Serial mode register 1	SMR1	R/W, W	UART (LIN/SCI) 1	00000000 _B
0000C5 _H	Serial control register 1	SCR1	R/W, W		00000000 _B
0000C6 _H	Reception/transmission data register 1	RDR1/ TDR1	R/W		00000000 _B
0000C7 _H	Serial status register 1	SSR1	R/W, R		00001000 _B
0000C8 _H	Extended communication control register 1	ECCR1	R/W, R		000000XX _B
0000C9 _H	Extended status control register 1	ESCR1	R/W		00000100 _B
0000CA _H	Baud rate generator register 10	BGR10	R/W		00000000 _B
0000CB _H	Baud rate generator register 11	BGR11	R/W, R		00000000 _B
0000CC _H	Lower watch timer control register	WTCRL	R/W	Real-time watch timer	000XXXX0 _B
0000CD _H	Middle watch timer control register	WTCRM	R/W		00000000 _B
0000CE _H	Higher watch timer control register	WTCRH	R/W		XXXXXX00 _B
0000CF _H	Sub clock control register	PSCCR	W	Sub clock	XXXX0000 _B
0000D0 _H	Input capture control status 4/5	ICS45	R/W	Input capture 4/5	00000000 _B
0000D1 _H	Input capture edge register 4/5	ICE45	R/W, R		XXXXXXXX _B
0000D2 _H	Input capture control status 6/7	ICS67	R/W	Input capture 6/7	00000000 _B
0000D3 _H	Input capture edge register 6/7	ICE67	R/W, R		XXX0X0XX _B

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MB90920 Series

Address	Register name	Symbol	Read/write	Resource name	Initial value
0000D4 _H	Lower timer control status register 2	TMCSR2L	R/W	16-bit reload timer 2	00000000 _B
0000D5 _H	Higher timer control status register 2	TMCSR2H	R/W		XXX10000 _B
0000D6 _H	Lower timer control status register 3	TMCSR3L	R/W	16-bit reload timer 3	00000000 _B
0000D7 _H	Higher timer control status register 3	TMCSR3H	R/W		XXX10000 _B
0000D8 _H	Lower sound control register 1	SGCRL1	R/W	Sound generator 1	00000000 _B
0000D9 _H	Higher sound control register 1	SGCRH1	R/W		0XXXX100 _B
0000DA _H	Lower PPG3 control status register	PCNTL3	R/W	16-bit PPG3	00000000 _B
0000DB _H	Higher PPG3 control status register	PCNTH3	R/W		00000001 _B
0000DC _H	Lower PPG4 control status register	PCNTL4	R/W	16-bit PPG4	00000000 _B
0000DD _H	Higher PPG4 control status register	PCNTH4	R/W		00000001 _B
0000DE _H	Lower PPG5 control status register	PCNTL5	R/W	16-bit PPG5	00000000 _B
0000DF _H	Higher PPG5 control status register	PCNTH5	R/W		00000001 _B
0000E0 _H	Serial mode register 2	SMR2	R/W, W	UART (LIN/SCI) 2	00000000 _B
0000E1 _H	Serial control register 2	SCR2	R/W, W		00000000 _B
0000E2 _H	Reception/transmission data register 2	RDR2/ TDR2	R/W		00000000 _B
0000E3 _H	Serial status register 2	SSR2	R/W, R		00001000 _B
0000E4 _H	Extended communication control register 2	ECCR2	R/W, R		000000XX _B
0000E5 _H	Extended status control register 2	ESCR2	R/W		00000100 _B
0000E6 _H	Baud rate generator register 20	BGR20	R/W		00000000 _B
0000E7 _H	Baud rate generator register 21	BGR21	R/W, R		00000000 _B
0000E8 _H	Serial mode register 3	SMR3	R/W, W	UART (LIN/SCI) 3	00000000 _B
0000E9 _H	Serial control register 3	SCR3	R/W, W		00000000 _B
0000EA _H	Reception/transmission data register 3	RDR3/ TDR3	R/W		00000000 _B
0000EB _H	Serial status register 3	SSR3	R/W, R		00001000 _B
0000EC _H	Extended communication control register 3	ECCR3	R/W, R		000000XX _B
0000ED _H	Extended status control register 3	ESCR3	R/W		00000100 _B
0000EE _H	Baud rate generator register 30	BGR30	R/W		00000000 _B
0000EF _H	Baud rate generator register 31	BGR31	R/W, R		00000000 _B
001FF0 _H	Program address detection register 0	PADR0	R/W	Address match detection	XXXXXXXX _B
001FF1 _H	Program address detection register 1	PADR0	R/W		XXXXXXXX _B
001FF2 _H	Program address detection register 2	PADR0	R/W		XXXXXXXX _B
001FF3 _H	Program address detection register 3	PADR1	R/W		XXXXXXXX _B
001FF4 _H	Program address detection register 4	PADR1	R/W		XXXXXXXX _B
001FF5 _H	Program address detection register 5	PADR1	R/W		XXXXXXXX _B

(Continued)

Address	Register name	Symbol	Read/write	Resource name	Initial value
003970 _H to 003973 _H	(Disabled)				
003974 _H	Frequency data register 1	SGFR1	R/W	Sound generator 1	XXXXXXXX _B
003975 _H	Amplitude data register 1	SGAR1	R/W		00000000 _B
003976 _H	Decrement grade register 1	SGDR1	R/W		XXXXXXXX _B
003977 _H	Tone count register 1	SGTR1	R/W		XXXXXXXX _B
003978 _H to 00397F _H	(Disabled)				
003980 _H	PWM1 compare register 0	PWC10	R/W	Stepping motor controller 0	XXXXXXXX _B
003981 _H					XXXXXXXX _B
003982 _H	PWM2 compare register 0	PWC20	R/W		XXXXXXXX _B
003983 _H					XXXXXXXX _B
003984 _H	PWM1 select register 0	PWS10	R/W		00000000 _B
003985 _H	PWM2 select register 0	PWS20	R/W		X0000000 _B
003986 _H , 003987 _H	(Disabled)				
003988 _H	PWM1 compare register 1	PWC11	R/W	Stepping motor controller 1	XXXXXXXX _B
003989 _H					XXXXXXXX _B
00398A _H	PWM2 compare register 1	PWC21	R/W		XXXXXXXX _B
00398B _H					XXXXXXXX _B
00398C _H	PWM1 select register 1	PWS11	R/W		00000000 _B
00398D _H	PWM2 select register 1	PWS21	R/W		X0000000 _B
00398E _H , 00398F _H	(Disabled)				
003990 _H	PWM1 compare register 2	PWC12	R/W	Stepping motor controller 2	XXXXXXXX _B
003991 _H					XXXXXXXX _B
003992 _H	PWM2 compare register 2	PWC22	R/W		XXXXXXXX _B
003993 _H					XXXXXXXX _B
003994 _H	PWM1 select register 2	PWS12	R/W		00000000 _B
003995 _H	PWM2 select register 2	PWS22	R/W		X0000000 _B
003996 _H , 003997 _H	(Disabled)				

(Continued)

MB90920 Series

List of Control Registers(2)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
000040 _H	000070 _H	0039C0 _H	0039D0 _H	Message buffer valid register	BVALR	R/W	00000000 _B 00000000 _B
000041 _H	000071 _H	0039C1 _H	0039D1 _H				
000042 _H	000072 _H	0039C2 _H	0039D2 _H	Transmit request register	TREQR	R/W	00000000 _B 00000000 _B
000043 _H	000073 _H	0039C3 _H	0039D3 _H				
000044 _H	000074 _H	0039C4 _H	0039D4 _H	Transmit cancel register	TCANR	W	00000000 _B 00000000 _B
000045 _H	000075 _H	0039C5 _H	0039D5 _H				
000046 _H	000076 _H	0039C6 _H	0039D6 _H	Transmit complete register	TCR	R/W	00000000 _B 00000000 _B
000047 _H	000077 _H	0039C7 _H	0039D7 _H				
000048 _H	000078 _H	0039C8 _H	0039D8 _H	Receive complete register	RCR	R/W	00000000 _B 00000000 _B
000049 _H	000079 _H	0039C9 _H	0039D9 _H				
00004A _H	00007A _H	0039CA _H	0039DA _H	Remote request receive register	RRTRR	R/W	00000000 _B 00000000 _B
00004B _H	00007B _H	0039CB _H	0039DB _H				
00004C _H	00007C _H	0039CC _H	0039DC _H	Receive overrun register	ROVRR	R/W	00000000 _B 00000000 _B
00004D _H	00007D _H	0039CD _H	0039DD _H				
00004E _H	00007E _H	0039CE _H	0039DE _H	Receive interrupt enable register	RIER	R/W	00000000 _B 00000000 _B
00004F _H	00007F _H	0039CF _H	0039DF _H				
003C08 _H	003D08 _H	003E08 _H	003F08 _H	IDE register	IDER	R/W	XXXXXXXX _B
003C09 _H	003D09 _H	003E09 _H	003F09 _H				XXXXXXXX _B
003C0A _H	003D0A _H	003E0A _H	003F0A _H	Transmit RTR register	TRTRR	R/W	00000000 _B
003C0B _H	003D0B _H	003E0B _H	003F0B _H				00000000 _B
003C0C _H	003D0C _H	003E0C _H	003F0C _H	Remote frame receive wait register	RFWTR	R/W	XXXXXXXX _B XXXXXXXX _B
003C0D _H	003D0D _H	003E0D _H	003F0D _H				
003C0E _H	003D0E _H	003E0E _H	003F0E _H	Transmit interrupt enable register	TIER	R/W	00000000 _B 00000000 _B
003C0F _H	003D0F _H	003E0F _H	003F0F _H				
003C10 _H	003D10 _H	003E10 _H	003F10 _H	Acceptance mask select register	AMSR	R/W	XXXXXXXX _B XXXXXXXX _B
003C11 _H	003D11 _H	003E11 _H	003F11 _H				XXXXXXXX _B XXXXXXXX _B
003C12 _H	003D12 _H	003E12 _H	003F12 _H				
003C13 _H	003D13 _H	003E13 _H	003F13 _H				
003C14 _H	003D14 _H	003E14 _H	003F14 _H	Acceptance mask register 0	AMR0	R/W	XXXXXXXX _B XXXXXXXX _B
003C15 _H	003D15 _H	003E15 _H	003F15 _H				
003C16 _H	003D16 _H	003E16 _H	003F16 _H				XXXXXX--- _B XXXXXXXX _B
003C17 _H	003D17 _H	003E17 _H	003F17 _H				
003C18 _H	003D18 _H	003E18 _H	003F18 _H	Acceptance mask register 1	AMR1	R/W	XXXXXXXX _B XXXXXXXX _B
003C19 _H	003D19 _H	003E19 _H	003F19 _H				
003C1A _H	003D1A _H	003E1A _H	003F1A _H				XXXXXX--- _B XXXXXXXX _B
003C1B _H	003D1B _H	003E1B _H	003F1B _H				

■ INTERRUPT SOURCES, INTERRUPT VECTORS, AND INTERRUPT CONTROL REGISTERS

Interrupt source	EI ² OS corresponding	Interrupt vector			Interrupt control register		Priority *2
		Number		Address	ICR	Address	
Reset	×	#08	08 _H	FFFFDC _H	—	—	High ↑ ↓ Low
INT9 instruction	×	#09	09 _H	FFFFD8 _H	—	—	
Exception processing	×	#10	0A _H	FFFFD4 _H	—	—	
CAN0 received/CAN2 received	×	#11	0B _H	FFFFD0 _H	ICR00	0000B0 _H *1	
CAN0 transmitted/node status/ CAN2 transmitted/node status	×	#12	0C _H	FFFFCC _H			
CAN1 received/CAN3 received	×	#13	0D _H	FFFFC8 _H	ICR01	0000B1 _H *1	
CAN1 transmitted/node status/ CAN3 transmitted/node status/SIO	×	#14	0E _H	FFFFC4 _H			
Input capture 0	△	#15	0F _H	FFFFC0 _H	ICR02	0000B2 _H *1	
DTP/ external interrupt - ch.0/ch.1 detected	△	#16	10 _H	FFFFBC _H			
Reload timer 0	△	#17	11 _H	FFFFB8 _H	ICR03	0000B3 _H *1	
Reload timer 2	△	#18	12 _H	FFFFB4 _H			
Input capture 1	△	#19	13 _H	FFFFB0 _H	ICR04	0000B4 _H *1	
DTP/ external interrupt - ch.2/ch.3 detected	△	#20	14 _H	FFFFAC _H			
Input capture 2	△	#21	15 _H	FFFFA8 _H	ICR05	0000B5 _H *1	
Reload timer 3	△	#22	16 _H	FFFFA4 _H			
Input capture 3/4/5/6/7	△	#23	17 _H	FFFFA0 _H	ICR06	0000B6 _H *1	
DTP/ external interrupt - ch.4/ ch.5 detected UART3 RX	△	#24	18 _H	FFFF9C _H			
PPG timer 0	△	#25	19 _H	FFFF98 _H	ICR07	0000B7 _H *1	
DTP/ external interrupt - ch.6/ ch.7 detected UART3 TX	△	#26	1A _H	FFFF94 _H			
PPG timer 1	△	#27	1B _H	FFFF90 _H	ICR08	0000B8 _H *1	
Reload timer 1	△	#28	1C _H	FFFF8C _H			
PPG timer 2/3/4/5	○	#29	1D _H	FFFF88 _H	ICR09	0000B9 _H *1	
Real time watch timer watch timer (sub clock)	×	#30	1E _H	FFFF84 _H			
Free-run timer overflow/clear	×	#31	1F _H	FFFF80 _H	ICR10	0000BA _H *1	
A/D converter conversion complete	○	#32	20 _H	FFFF7C _H			
Sound generator 0/1	×	#33	21 _H	FFFF78 _H	ICR11	0000BB _H *1	
Time-base timer	×	#34	22 _H	FFFF74 _H			
UART2 RX	○	#35	23 _H	FFFF70 _H	ICR12	0000BC _H *1	
UART2 TX	△	#36	24 _H	FFFF6C _H			

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■ ELECTRICAL CHARACTERISTICS

1. Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V _{CC}	V _{SS} – 0.3	V _{SS} + 6.0	V	
	AV _{CC}	V _{SS} – 0.3	V _{SS} + 6.0	V	AV _{CC} = V _{CC} *2
	AVRH	V _{SS} – 0.3	V _{SS} + 6.0	V	AV _{CC} ≥ AVRH*2
	DV _{CC}	V _{SS} – 0.3	V _{SS} + 6.0	V	DV _{CC} = V _{CC} *2
Input voltage*1	V _I	V _{SS} – 0.3	V _{CC} + 0.3	V	*3
Output voltage*1	V _O	V _{SS} – 0.3	V _{CC} + 0.3	V	
Maximum clamp current	I _{CLAMP}	– 4	+ 4	mA	*7
Total maximum clamp current	Σ I _{CLAMP}	—	40	mA	*7
“L” level maximum output current*4	I _{OL1}	—	15	mA	Except P70 to P77 and P80 to P87
	I _{OL2}	—	40	mA	P70 to P77 and P80 to P87
“L” level average output current*5	I _{OLAV1}	—	4	mA	Except P70 to P77 and P80 to P87
	I _{OLAV2}	—	30	mA	P70 to P77 and P80 to P87
“L” level maximum total output current	ΣI _{OL1}	—	100	mA	Except P70 to P77 and P80 to P87
	ΣI _{OL2}	—	330	mA	P70 to P77 and P80 to P87
“L” level average total output current	ΣI _{OLAV1}	—	50	mA	Except P70 to P77 and P80 to P87
	ΣI _{OLAV2}	—	250	mA	P70 to P77 and P80 to P87
“H” level maximum output current	I _{OH1} *4	—	–15	mA	Except P70 to P77 and P80 to P87
	I _{OH2} *4	—	–40	mA	P70 to P77 and P80 to P87
“H” level average output current	I _{OHAV1} *5	—	–4	mA	Except P70 to P77 and P80 to P87
	I _{OHAV2} *5	—	–30	mA	P70 to P77 and P80 to P87
“H” level maximum total output current	ΣI _{OH1}	—	–100	mA	Except P70 to P77 and P80 to P87
	ΣI _{OH2}	—	–330	mA	P70 to P77 and P80 to P87
“H” level average total output current	ΣI _{OHAV1} *6	—	–50	mA	Except P70 to P77 and P80 to P87
	ΣI _{OHAV2} *6	—	–250	mA	P70 to P77 and P80 to P87
Power consumption	P _D	—	625	mW	
Operating temperature	T _A	– 40	+ 105	°C	
Storage temperature	T _{STG}	– 55	+ 150	°C	

*1 : The parameter is based on V_{SS} = AV_{SS} = DV_{SS} = 0.0 V.

*2 : AV_{CC}, AVRH must not exceed V_{CC}, and AVRH must not exceed AV_{CC}.

When using an evaluation product, DV_{CC} must not exceed V_{CC} (however, DV_{CC} can be set to a higher voltage than V_{CC} when using a Flash memory product).

*3 : If the input current or the maximum input current is limited using external components, I_{CLAMP} is the applicable rating instead of V_I.

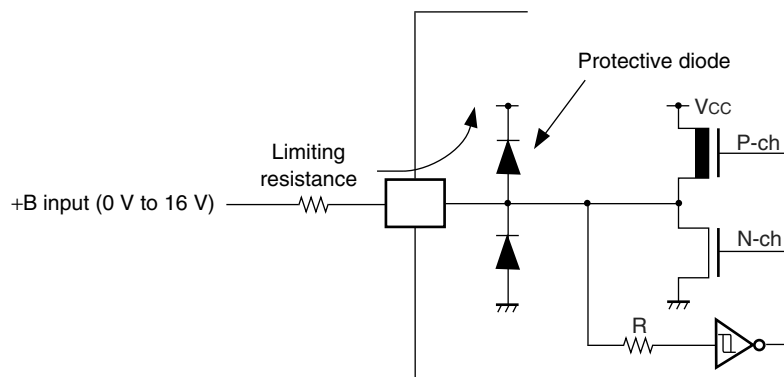
*4 : Maximum output current is defined as the peak value of current through any one of the corresponding pins.

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- *5 : Average output current is defined as the average value of the current flowing through any one of the corresponding pins within a period of 100 ms. The “average value” can be calculated by multiplying the “operating current” by the “operating factor”.
- *6 : Average total output current is defined as the average value of the current flowing through all of the corresponding pins within a period of 100 ms. The “average value” can be calculated by multiplying the “operating current” by the “operating factor”.
- *7 :
 - Applicable to pins: P10 to P15, P50 to P57, P60 to P67, P70 to P77, P80 to P87, PC0 to PC7, PD0 to PD6, PE0 to PE2
 - Use within recommended operating conditions.
 - Use at DC voltage (current) .
 - The +B signal should always be applied with a limiting resistance placed between the +B signal and the microcontroller.
 - The value of the limiting resistance should be set so that when the +B signal is applied, the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
 - Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
 - Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the microcontroller may partially malfunction on power supplied through the +B signal pin.
 - Note that if the +B input is applied during power-on, the power supply voltage may reach a level such that the power-on reset does not function due to the power supplied from the +B signal.
 - Care must be taken not to leave +B input pins open.
 - Note that analog system input/output pins (LCD drive pins, comparator input pins, etc.) cannot accept +B signal inputs.
 - Sample recommended circuit :

- Input/output equivalent circuit



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

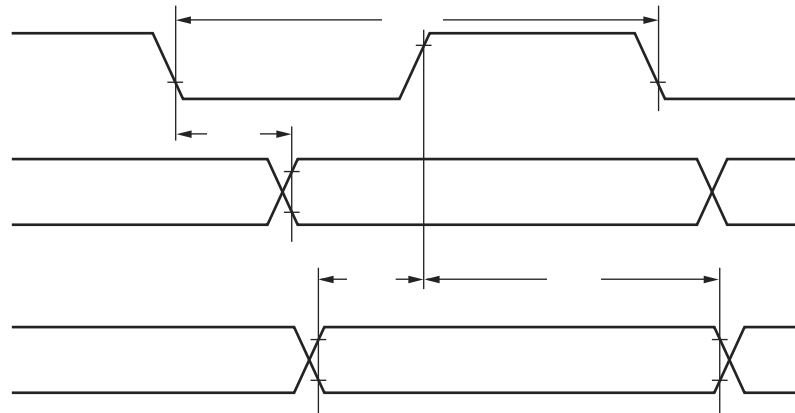
MB90920 Series

($V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = DV_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C}$ to $+105 \text{ }^{\circ}\text{C}$)

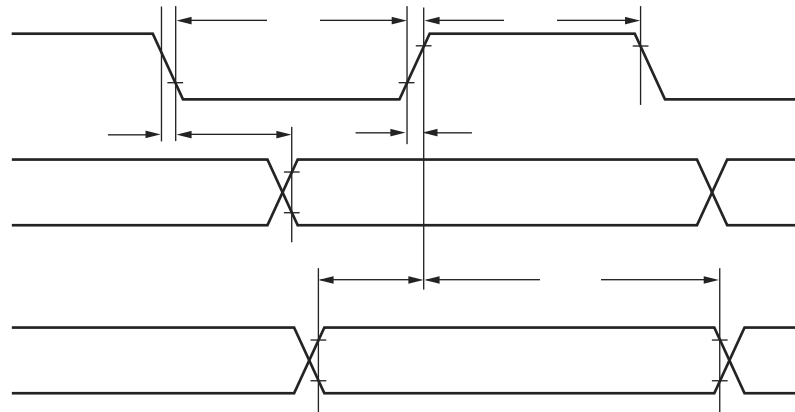
Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input leakage current	I_{IL}	All input pins	$V_{CC} = DV_{CC} = AV_{CC} = 5.5 \text{ V}$, $V_{SS} < V_I < V_{CC}$	—	—	10	μA	
Input capacitance 1	C_{IN1}	All pins except V_{CC} , V_{SS} , DV_{CC} , DV_{SS} , AV_{CC} , AV_{SS} , C, P70 to P77, P80 to P87	—	—	—	15	pF	
Input capacitance 2	C_{IN2}	P70 to P77, P80 to P87	—	—	—	45	pF	
Pull-up resistance	R_{UP}	$\overline{RST}$	—	25	50	100	k Ω	
Pull-down resistance	R_{DOWN}	MD2	—	—	—	100	k Ω	Excluding Flash memory product
General-purpose output “H” voltage	V_{OH1}	All pins except P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OH} = -4.0 \text{ mA}$	$V_{CC} - 0.5$	—	—	V	
Stepping motor output “H” voltage	V_{OH2}	P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OH} = -30.0 \text{ mA}$	$V_{CC} - 0.5$	—	—	V	
General-purpose output “L” voltage	V_{OL1}	All pins except P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OL} = 4.0 \text{ mA}$	—	—	0.4	V	
Stepping motor output “L” voltage	V_{OL2}	P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OL} = 30.0 \text{ mA}$	—	—	0.55	V	
Stepping motor output phase variation “H”	ΔV_{OH}	PWM1Pn, PWM1Mn, PWM2Pn, PWM2Mn, n = 0 to 3	$V_{CC} = 4.5 \text{ V}$, $I_{OH} = -30.0 \text{ mA}$, maximum deviation V_{OH2}	—	—	90	mV	
Stepping motor output phase variation “L”	ΔV_{OL}	PWM1Pn, PWM1Mn, PWM2Pn, PWM2Mn, n = 0 to 3	$V_{CC} = 4.5 \text{ V}$, $I_{OL} = 30.0 \text{ mA}$, maximum deviation V_{OH2}	—	—	90	mV	
LCD internal divider resistance	R_{LCD}	Between V0 and V1, Between V1 and V2, Between V2 and V3	—	50	100	200	k Ω	Evaluation product
				8.75	12.5	17.0	k Ω	Flash memory product

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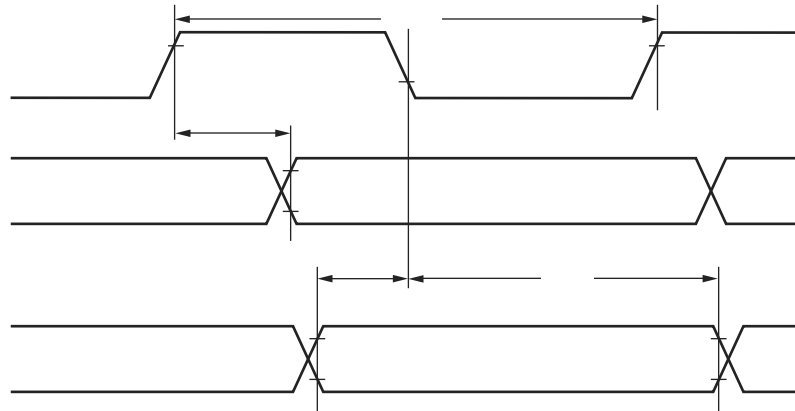
- Internal shift clock mode



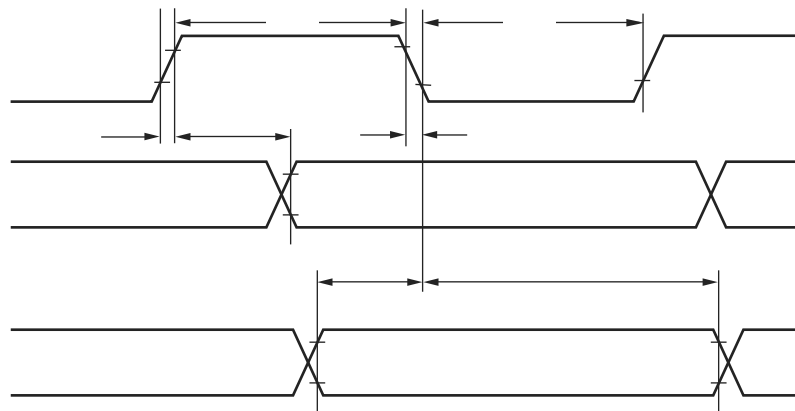
- External shift clock mode



- Internal shift clock mode



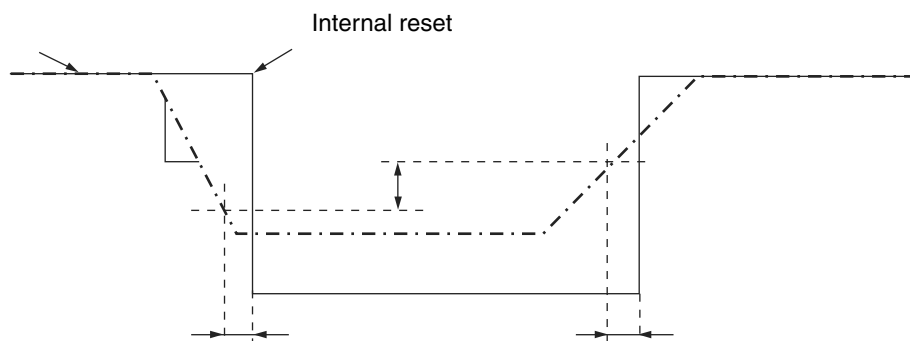
- External shift clock mode



(7) Low voltage detection

($V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C}$ to $+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Detection voltage	V_{DL}	VCC	—	4.0	4.2	4.4	V	Flash memory product, during voltage drop
				3.7	4.0	4.3	V	Evaluation product, during voltage drop
Hysteresis width	V_{HYS}	VCC	—	190	—	—	mV	Flash memory product, during voltage rise
				0.1	—	—	V	Evaluation product, during voltage rise
Power supply voltage change rate	dV/dt	VCC	—	− 0.1	—	+ 0.1	V/ μs	Flash memory product, dV/dt at low voltage reset
				−0.004	—	+ 0.004	V/ μs	Flash memory product, dV/dt at standard value of low voltage detection/release voltage
				− 0.1	—	+ 0.02	V/ μs	Evaluation product
Detection delay time	t_d	—	—	—	—	3.2	μs	Flash memory product, when $dV/dt \leq 0.004\text{ V}/\mu\text{s}$
				—	—	35	μs	Evaluation product



MB90920 Series

■ MAJOR CHANGES IN THIS EDITION

Page	Section	Change Results
12	■ I/O CIRCUIT TYPE	Corrected the circuit type B.
20	■ HANDLING DEVICES	Added the following items; • Serial communication • Characteristic difference between flash device and MASK ROM device
31	■ I/O MAP	Corrected “Address: 003970 _H ”. Clock supervisor control register → (Disabled)
46	■ ELECTRICAL CHARACTERISTICS 3. DC Characteristics	Added the item for “LCD output impedance”.
68	■ ORDERING INFORMATION	Corrected the part numbers; MB90V920-101 → MB90V920-101CR MB90V920-102 → MB90V920-102CR

The vertical lines marked in the left side of the page show the changes.

MEMO