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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-149e1

16-bit Microcontroller

CMOS

F²MC-16LX MB90920 Series

**MB90F922NC/F922NCS/922NCS/F923NC/F923NCS/
MB90F924NC/F924NCS/V920-101/V920-102**

■ DESCRIPTION

The MB90920 series is a family of general-purpose FUJITSU SEMICONDUCTOR 16-bit microcontrollers designed for applications such as vehicle instrument panel control.

The instruction set retains the AT architecture from the F²MC-8L and F²MC-16LX families, with further refinements including high-level language instructions, extended addressing modes, improved multiplication and division operations (signed), and bit processing. In addition, long word processing is made possible by the inclusion of a built-in 32-bit accumulator.

Note : F²MC is the abbreviation of FUJITSU Flexible Microcontroller.

■ FEATURES

- Clock
Built-in PLL clock frequency multiplication circuit.
Selection of machine clocks (PLL clocks) is allowed among frequency division by two on oscillation clock, and multiplication of 1 to 8 times of oscillation clock (for 4 MHz oscillation clock, 4 MHz to 32 MHz).
Operation by sub clock (up to 50 kHz : 100 kHz oscillation clock divided by two) is allowed.
- 16-bit input capture (8 channels)
Detects rising, falling, or both edges.
16-bit capture register × 8
The value of a 16-bit free-run timer counter is latched upon detection of an edge input to pin and an interrupt request is generated.

(Continued)

For the information for microcontroller supports, see the following web site.

This web site includes the "**Customer Design Review Supplement**" which provides the latest cautions on system development and the minimal requirements to be checked to prevent problems before the system development.

<http://edevise.fujitsu.com/micom/en-support/>

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- 16-bit reload timer (4 channels)
16-bit reload timer operation (select toggle output or one-shot output)
Selectable event count function
- Real time watch timer (main clock)
Operates directly from oscillator clock.
Interrupt can be generated by second/minute/hour/date counter overflow.
- PPG timer (6 channels)
Output pins (3 channels), external trigger input pin (1 channel)
Operation clock frequencies : f_{CP} , $f_{CP}/2^2$, $f_{CP}/2^4$, $f_{CP}/2^6$
- Delay interrupt
Generates interrupt for task switching.
Interrupts to CPU can be generated/cleared by software setting.
- External interrupts (8 channels)
8-channel independent operation
Interrupt source setting available : “L” to “H” edge/ “H” to “L” edge/ “L” level/ “H” level.
- 8/10-bit A/D converter (8 channels)
Conversion time : 3 μ s (at $f_{CP} = 32$ MHz)
External trigger activation available (P50/INT0/ADTG)
Internal timer activation available (16-bit reload timer 1)
- UART(LIN/SCI) (4 channels)
Equipped with full duplex double buffer
Clock-asynchronous or clock-synchronous serial transfer is available
- CAN interface (4 channels : CAN0 and CAN2, and CAN1 and CAN3 share transmission and reception pins, and interrupt control registers).
Conforms to CAN specifications version 2.0 Part A and B.
Automatic resend in case of error.
Automatic transfer in response to remote frame.
16 prioritized message buffers for data and ID
Multiple message support
Flexible configuration for receive filter : Full bit compare/full bit mask/two partial bit masks
Supports up to 1 Mbps
CAN wakeup function (RX connected to INT0 internally)
- LCD controller/driver (32 segment x 4 common)
Segment driver and command driver with direct LCD panel (display) drive capability
- Reset on detection of low voltage/program loop
Automatic reset when low voltage is detected
Program looping detection function
- Stepping motor controller (4 channels)
High current output for each channel $\times 4$
Synchronized 8/10-bit PWM for each channel $\times 2$
- Sound generator (2 channels)
8-bit PWM signal mixed with tone frequency from 8-bit reload counter.
PWM frequencies : 125 kHz, 62.5 kHz, 31.2 kHz, 15.6 kHz (at $f_{CP} = 32$ MHz)
Tone frequencies : PWM frequency /2/ , divided by (reload frequency +1)
- Input/output ports
General-purpose input/output port (CMOS output) 93 ports
- Function for port input level selection
Automotive/CMOS-Schmitt
- Flash memory security function
Protects the contents of Flash memory (Flash memory product only)

MB90920 Series

■ PRODUCT LINEUP

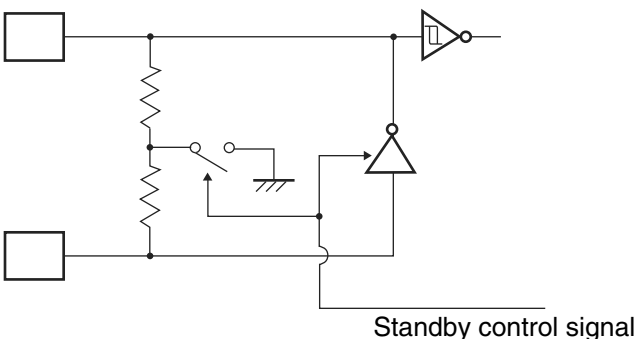
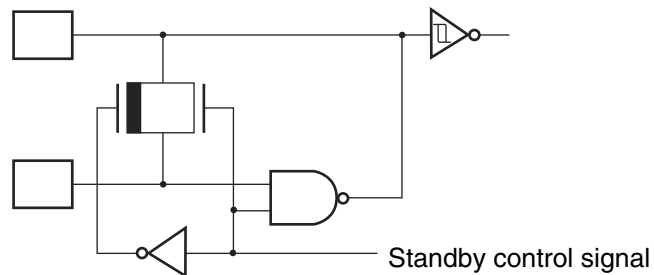
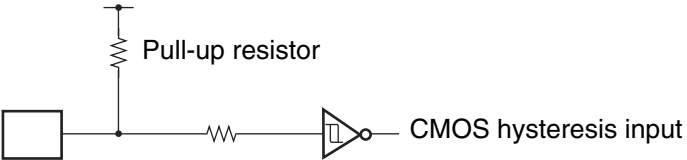
Part number Parameter	MB90 F922NC	MB90 F922NCS	MB90 F923NC	MB90 F923NCS	MB90 F924NC	MB90 F924NCS	MB90 922NCS	MB90 V920-101	MB90 V920-102
Type	Flash memory product						MASK ROM product	Evaluation product	
CPU	F ² MC-16LX CPU								
System clock	PLL clock multiplier circuit (× 1, × 2, × 3, × 4, × 8, 1/2 when PLL stopped) Minimum instruction execution time 31.25 ns (with 4 MHz oscillation clock × 8)								
Sub clock pins (X0A, X1A)	Yes	No	Yes	No	Yes	No	No	No	Yes
ROM	Flash memory 256 Kbytes		Flash memory 384 Kbytes		Flash memory 512 Kbytes		256 K bytes	External	
RAM	10 Kbytes		16 Kbytes		24 Kbytes		10 K bytes	30 Kbytes	
I/O port	91 ports	93 ports	91 ports	93 ports	91 ports	93 ports	93 ports	93 ports	91 ports
LCD controller	32 segment × 4 common								
LIN-UART	UART (LIN/SCI) 4 channels								
CAN interface	4 channels								
16-bit input capture	8 channels								
16-bit reload timer	4 channels								
16-bit free-run timer	1 channel								
Real time watch timer	1 channel								
16-bit PPG timer	6 channels								
External interrupt	8 channels								
8/10-bit A/D converter	8 channels								
Low-voltage/ CPU operating detection reset	Yes						No		
Stepping motor controller	4 channels								
Sound generator	2 channels								
Flash memory security	Yes						—		
Operating voltage	4.0 V to 5.5 V						4.5 V to 5.5 V		
Package	LQFP-120						PGA-299		

MB90920 Series

Pin no.	Pin name	I/O circuit type*1	Function
104	P13	I	General-purpose I/O port
	PPG5		16-bit PPG ch.5 output pin
109	P14	I	General-purpose I/O port
	TIN2		16-bit reload timer ch.2 TIN input pin
	IN1		Input capture ch.1 trigger input pin
110	P15	I	General-purpose I/O port
	IN0		Input capture ch.0 trigger input pin
111	COM0	P	LCD controller/driver common output pin
112	COM1	P	LCD controller/driver common output pin
113	COM2	P	LCD controller/driver common output pin
114	COM3	P	LCD controller/driver common output pin
115	P22	F	General-purpose I/O port
	SEG00		LCD controller/driver segment output pin
116	P23	F	General-purpose I/O port
	SEG01		LCD controller/driver segment output pin
117	P24	F	General-purpose I/O port
	SEG02		LCD controller/driver segment output pin
118	P25	F	General-purpose I/O port
	SEG03		LCD controller/driver segment output pin
119	P26	F	General-purpose I/O port
	SEG04		LCD controller/driver segment output pin
120	P27	F	General-purpose I/O port
	SEG05		LCD controller/driver segment output pin
1	P30	F	General-purpose I/O port
	SEG06		LCD controller/driver segment output pin
2	P31	F	General-purpose I/O port
	SEG07		LCD controller/driver segment output pin
3	P32	F	General-purpose I/O port
	SEG08		LCD controller/driver segment output pin
4	P33	F	General-purpose I/O port
	SEG09		LCD controller/driver segment output pin
5	P34	F	General-purpose I/O port
	SEG10		LCD controller/driver segment output pin
6	P35	F	General-purpose I/O port
	SEG11		LCD controller/driver segment output pin

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■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A	 Standby control signal	Oscillation circuit High-speed oscillation feedback resistance : approx. 1 MΩ (Flash memory product/MASK ROM product/Evaluation product)
B	 Standby control signal	Oscillation circuit Low-speed oscillation feedback resistance : approx. 10 MΩ
C	 Pull-up resistor CMOS hysteresis input	Input-only pin (with pull-up resistance) - Attached pull-up resistor : approx. 50 kΩ - CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$)
D	 CMOS hysteresis input	Input-only pin CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) Note: The MD2 pin of the Flash memory products uses this circuit type.

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MB90920 Series

Type	Circuit	Remarks
H	P-ch N-ch Pout Nout Analog input CMOS hysteresis input Standby control signal or analog input enable signal Automotive input Standby control signal or analog input enable signal	A/D converter input common general-purpose port • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
I	P-ch N-ch Pout Nout CMOS hysteresis input Standby control signal Automotive input Standby control signal	General-purpose port • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
J	P-ch N-ch Pout Nout CMOS hysteresis input Standby control signal Automotive input Standby control signal CMOS input (SIN) Standby control signal	General-purpose port (serial input) • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • CMOS input (SIN) ($V_{IH}/V_{IL} = 0.7 V_{CC}/0.3 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)

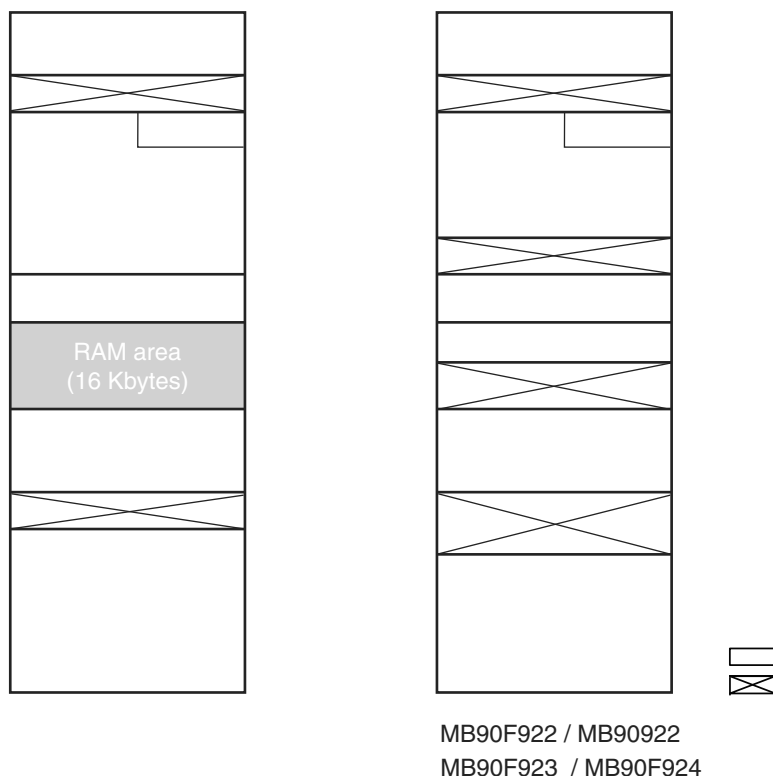
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Type	Circuit	Remarks
K		A/D converter input common general-purpose port (serial input) • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • CMOS input (SIN) ($V_{IH}/V_{IL} = 0.7 V_{CC}/0.3 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
L		High current output port (SMC pin) CMOS output ($I_{OH}/I_{OL} = \pm 30 \text{ mA}$)
M		LCDC output common general-purpose port (serial input) • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • CMOS input (SIN) ($V_{IH}/V_{IL} = 0.7 V_{CC}/0.3 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)

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MB90920 Series

■ MEMORY MAP



Parts No.	ROM (Flash) capacitance	RAM capacitance	Address #1	Address #2	Address #3
MB90F922NC/F922NCS/922NCS	256 Kbytes	10 Kbytes	FC0000 _H	004000 _H	002900 _H
MB90F923NC/F923NCS	384 Kbytes	16 Kbytes	FA0000 _H	004A00 _H	003700 _H
MB90F924NC/F924NCS	512 Kbytes	24 Kbytes	F80000 _H	006A00 _H	003700 _H

* : Evaluation products do not contain internal ROM. Treat this address as the ROM decode area used by the tools.

Note: To select models without the ROM mirror function, refer to the “ROM Mirror Function Selection Module” in Hardware Manual. The image of the ROM data in the FF bank appears at the top of the 00 bank, in order to enable efficient use of small C compiler models. The lower 16-bits of the FF bank addresses are allocated to the same addresses as the lower 16-bits of the 00 bank, making it possible to reference tables in ROM without declaring the “far” modifier with the pointers. For example, when an access is made to the address 00C000_H, the actual address to be accessed is FFC000_H in ROM. Because the size of the FF bank ROM area exceeds 32 Kbytes, it is not possible to view the entire region in the 00 bank image. Therefore because the ROM data from FF8000_H to FFFFFFF_H appears in the image from 008000_H to 00FFFF_H, it is recommended that ROM data tables be stored in the area from FF8000_H to FFFFFFF_H.

■ I/O MAP

Address	Register name	Symbol	Read/write	Resource name	Initial value
000000 _H	Port 0 data register	PDR0	R/W	Port 0	XXXXXXXX _B
000001 _H	Port 1 data register	PDR1	R/W	Port 1	XXXXXXXX _B
000002 _H	Port 2 data register	PDR2	R/W	Port 2	XXXXXXXX _B
000003 _H	Port 3 data register	PDR3	R/W	Port 3	XXXXXXXX _B
000004 _H	Port 4 data register	PDR4	R/W	Port 4	XXXXXXXX _B
000005 _H	Port 5 data register	PDR5	R/W	Port 5	XXXXXXXX _B
000006 _H	Port 6 data register	PDR6	R/W	Port 6	XXXXXXXX _B
000007 _H	Port 7 data register	PDR7	R/W	Port 7	XXXXXXXX _B
000008 _H	Port 8 data register	PDR8	R/W	Port 8	XXXXXXXX _B
000009 _H	Port 9 data register	PDR9	R/W	Port 9	XXXXXXXX _B
00000A _H , 00000B _H	(Disabled)				
00000C _H	Port C data register	PDRC	R/W	Port C	XXXXXXXX _B
00000D _H	Port D data register	PDRD	R/W	Port D	XXXXXXXX _B
00000E _H	Port E data register	PDRE	R/W	Port E	XXXXXXXX _B
00000F _H	(Disabled)				
000010 _H	Port 0 direction register	DDR0	R/W	Port 0	00000000 _B
000011 _H	Port 1 direction register	DDR1	R/W	Port 1	XX000000 _B
000012 _H	Port 2 direction register	DDR2	R/W	Port 2	000000XX _B
000013 _H	Port 3 direction register	DDR3	R/W	Port 3	00000000 _B
000014 _H	Port 4 direction register	DDR4	R/W	Port 4	00000000 _B
000015 _H	Port 5 direction register	DDR5	R/W	Port 5	00000000 _B
000016 _H	Port 6 direction register	DDR6	R/W	Port 6	00000000 _B
000017 _H	Port 7 direction register	DDR7	R/W	Port 7	00000000 _B
000018 _H	Port 8 direction register	DDR8	R/W	Port 8	00000000 _B
000019 _H	Port 9 direction register	DDR9	R/W	Port 9	X0000000 _B
00001A _H	Analog input enable	ADER6	R/W	Port 6, A/D	11111111 _B
00001B _H	(Disabled)				
00001C _H	Port C direction register	DDRC	R/W	Port C	00000000 _B
00001D _H	Port D direction register	DDRD	R/W	Port D	X0000000 _B
00001E _H	Port E direction register	DDRE	R/W	Port E	XXXXX000 _B
00001F _H	(Disabled)				
000020 _H	Lower A/D control status register	ADCS0	R/W	A/D converter	000XXXX0 _B
000021 _H	Higher A/D control status register	ADCS1	R/W		0000000X _B
000022 _H	Lower A/D control status register	ADCR0	R		00000000 _B
000023 _H	Higher A/D data register	ADCR1	R		XXXXXX00 _B

(Continued)

Address	Register name	Symbol	Read/write	Resource name	Initial value
0000B0 _H	Interrupt control register 00	ICR00	R/W	Interrupt controller	00000111 _B
0000B1 _H	Interrupt control register 01	ICR01	R/W		00000111 _B
0000B2 _H	Interrupt control register 02	ICR02	R/W		00000111 _B
0000B3 _H	Interrupt control register 03	ICR03	R/W		00000111 _B
0000B4 _H	Interrupt control register 04	ICR04	R/W		00000111 _B
0000B5 _H	Interrupt control register 05	ICR05	R/W		00000111 _B
0000B6 _H	Interrupt control register 06	ICR06	R/W		00000111 _B
0000B7 _H	Interrupt control register 07	ICR07	R/W		00000111 _B
0000B8 _H	Interrupt control register 08	ICR08	R/W		00000111 _B
0000B9 _H	Interrupt control register 09	ICR09	R/W		00000111 _B
0000BA _H	Interrupt control register 10	ICR10	R/W		00000111 _B
0000BB _H	Interrupt control register 11	ICR11	R/W		00000111 _B
0000BC _H	Interrupt control register 12	ICR12	R/W		00000111 _B
0000BD _H	Interrupt control register 13	ICR13	R/W		00000111 _B
0000BE _H	Interrupt control register 14	ICR14	R/W		00000111 _B
0000BF _H	Interrupt control register 15	ICR15	R/W		00000111 _B
0000C0 _H to 0000C3 _H	(Disabled)				
0000C4 _H	Serial mode register 1	SMR1	R/W, W	UART (LIN/SCI) 1	00000000 _B
0000C5 _H	Serial control register 1	SCR1	R/W, W		00000000 _B
0000C6 _H	Reception/transmission data register 1	RDR1/ TDR1	R/W		00000000 _B
0000C7 _H	Serial status register 1	SSR1	R/W, R		00001000 _B
0000C8 _H	Extended communication control register 1	ECCR1	R/W, R		000000XX _B
0000C9 _H	Extended status control register 1	ESCR1	R/W		00000100 _B
0000CA _H	Baud rate generator register 10	BGR10	R/W		00000000 _B
0000CB _H	Baud rate generator register 11	BGR11	R/W, R		00000000 _B
0000CC _H	Lower watch timer control register	WTCRL	R/W	Real-time watch timer	000XXXX0 _B
0000CD _H	Middle watch timer control register	WTCRM	R/W		00000000 _B
0000CE _H	Higher watch timer control register	WTCRH	R/W		XXXXXX00 _B
0000CF _H	Sub clock control register	PSCCR	W	Sub clock	XXXX0000 _B
0000D0 _H	Input capture control status 4/5	ICS45	R/W	Input capture 4/5	00000000 _B
0000D1 _H	Input capture edge register 4/5	ICE45	R/W, R		XXXXXXXX _B
0000D2 _H	Input capture control status 6/7	ICS67	R/W	Input capture 6/7	00000000 _B
0000D3 _H	Input capture edge register 6/7	ICE67	R/W, R		XXX0X0XX _B

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MB90920 Series

List of Control Registers(2)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
000040 _H	000070 _H	0039C0 _H	0039D0 _H	Message buffer valid register	BVALR	R/W	00000000 _B 00000000 _B
000041 _H	000071 _H	0039C1 _H	0039D1 _H				
000042 _H	000072 _H	0039C2 _H	0039D2 _H	Transmit request register	TREQR	R/W	00000000 _B 00000000 _B
000043 _H	000073 _H	0039C3 _H	0039D3 _H				
000044 _H	000074 _H	0039C4 _H	0039D4 _H	Transmit cancel register	TCANR	W	00000000 _B 00000000 _B
000045 _H	000075 _H	0039C5 _H	0039D5 _H				
000046 _H	000076 _H	0039C6 _H	0039D6 _H	Transmit complete register	TCR	R/W	00000000 _B 00000000 _B
000047 _H	000077 _H	0039C7 _H	0039D7 _H				
000048 _H	000078 _H	0039C8 _H	0039D8 _H	Receive complete register	RCR	R/W	00000000 _B 00000000 _B
000049 _H	000079 _H	0039C9 _H	0039D9 _H				
00004A _H	00007A _H	0039CA _H	0039DA _H	Remote request receive register	RRTRR	R/W	00000000 _B 00000000 _B
00004B _H	00007B _H	0039CB _H	0039DB _H				
00004C _H	00007C _H	0039CC _H	0039DC _H	Receive overrun register	ROVRR	R/W	00000000 _B 00000000 _B
00004D _H	00007D _H	0039CD _H	0039DD _H				
00004E _H	00007E _H	0039CE _H	0039DE _H	Receive interrupt enable register	RIER	R/W	00000000 _B 00000000 _B
00004F _H	00007F _H	0039CF _H	0039DF _H				
003C08 _H	003D08 _H	003E08 _H	003F08 _H	IDE register	IDER	R/W	XXXXXXXX _B
003C09 _H	003D09 _H	003E09 _H	003F09 _H				XXXXXXXX _B
003C0A _H	003D0A _H	003E0A _H	003F0A _H	Transmit RTR register	TRTRR	R/W	00000000 _B
003C0B _H	003D0B _H	003E0B _H	003F0B _H				00000000 _B
003C0C _H	003D0C _H	003E0C _H	003F0C _H	Remote frame receive wait register	RFWTR	R/W	XXXXXXXX _B XXXXXXXX _B
003C0D _H	003D0D _H	003E0D _H	003F0D _H				
003C0E _H	003D0E _H	003E0E _H	003F0E _H	Transmit interrupt enable register	TIER	R/W	00000000 _B 00000000 _B
003C0F _H	003D0F _H	003E0F _H	003F0F _H				
003C10 _H	003D10 _H	003E10 _H	003F10 _H	Acceptance mask select register	AMSR	R/W	XXXXXXXX _B XXXXXXXX _B
003C11 _H	003D11 _H	003E11 _H	003F11 _H				XXXXXXXX _B XXXXXXXX _B
003C12 _H	003D12 _H	003E12 _H	003F12 _H				
003C13 _H	003D13 _H	003E13 _H	003F13 _H				
003C14 _H	003D14 _H	003E14 _H	003F14 _H	Acceptance mask register 0	AMR0	R/W	XXXXXXXX _B XXXXXXXX _B
003C15 _H	003D15 _H	003E15 _H	003F15 _H				
003C16 _H	003D16 _H	003E16 _H	003F16 _H				XXXXXX--- _B XXXXXXXX _B
003C17 _H	003D17 _H	003E17 _H	003F17 _H				
003C18 _H	003D18 _H	003E18 _H	003F18 _H	Acceptance mask register 1	AMR1	R/W	XXXXXXXX _B XXXXXXXX _B
003C19 _H	003D19 _H	003E19 _H	003F19 _H				
003C1A _H	003D1A _H	003E1A _H	003F1A _H				XXXXXX--- _B XXXXXXXX _B
003C1B _H	003D1B _H	003E1B _H	003F1B _H				

List of Message Buffers (ID Registers)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A00 _H to 003A1F _H	003B00 _H to 003B1F _H	003700 _H to 00371F _H	003800 _H to 00381F _H	General-purpose RAM	—	R/W	XXXXXXXX _B to XXXXXXXX _B
003A20 _H	003B20 _H	003720 _H	003820 _H	ID register 0	IDR0	R/W	XXXXXXXX _B XXXXXXXX _B
003A21 _H	003B21 _H	003721 _H	003821 _H				XXXXXX--- _B XXXXXXXX _B
003A22 _H	003B22 _H	003722 _H	003822 _H				
003A23 _H	003B23 _H	003723 _H	003823 _H				
003A24 _H	003B24 _H	003724 _H	003824 _H	ID register 1	IDR1	R/W	XXXXXXXX _B XXXXXXXX _B
003A25 _H	003B25 _H	003725 _H	003825 _H				XXXXXX--- _B XXXXXXXX _B
003A26 _H	003B26 _H	003726 _H	003826 _H				
003A27 _H	003B27 _H	003727 _H	003827 _H				
003A28 _H	003B28 _H	003728 _H	003828 _H	ID register 2	IDR2	R/W	XXXXXXXX _B XXXXXXXX _B
003A29 _H	003B29 _H	003729 _H	003829 _H				XXXXXX--- _B XXXXXXXX _B
003A2A _H	003B2A _H	00372A _H	00382A _H				
003A2B _H	003B2B _H	00372B _H	00382B _H				
003A2C _H	003B2C _H	00372C _H	00382C _H	ID register 3	IDR3	R/W	XXXXXXXX _B XXXXXXXX _B
003A2D _H	003B2D _H	00372D _H	00382D _H				XXXXXX--- _B XXXXXXXX _B
003A2E _H	003B2E _H	00372E _H	00382E _H				
003A2F _H	003B2F _H	00372F _H	00382F _H				
003A30 _H	003B30 _H	003730 _H	003830 _H	ID register 4	IDR4	R/W	XXXXXXXX _B XXXXXXXX _B
003A31 _H	003B31 _H	003731 _H	003831 _H				XXXXXX--- _B XXXXXXXX _B
003A32 _H	003B32 _H	003732 _H	003832 _H				
003A33 _H	003B33 _H	003733 _H	003833 _H				
003A34 _H	003B34 _H	003734 _H	003834 _H	ID register 5	IDR5	R/W	XXXXXXXX _B XXXXXXXX _B
003A35 _H	003B35 _H	003735 _H	003835 _H				XXXXXX--- _B XXXXXXXX _B
003A36 _H	003B36 _H	003736 _H	003836 _H				
003A37 _H	003B37 _H	003737 _H	003837 _H				
003A38 _H	003B38 _H	003738 _H	003838 _H	ID register 6	IDR6	R/W	XXXXXXXX _B XXXXXXXX _B
003A39 _H	003B39 _H	003739 _H	003839 _H				XXXXXX--- _B XXXXXXXX _B
003A3A _H	003B3A _H	00373A _H	00383A _H				
003A3B _H	003B3B _H	00373B _H	00383B _H				
003A3C _H	003B3C _H	00373C _H	00383C _H	ID register 7	IDR7	R/W	XXXXXXXX _B XXXXXXXX _B
003A3D _H	003B3D _H	00373D _H	00383D _H				XXXXXX--- _B XXXXXXXX _B
003A3E _H	003B3E _H	00373E _H	00383E _H				
003A3F _H	003B3F _H	00373F _H	00383F _H				

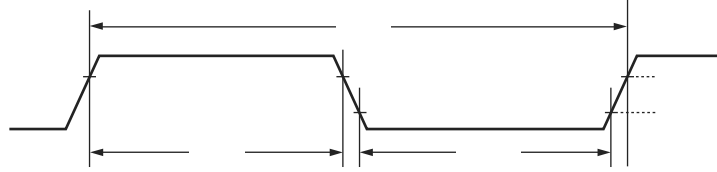
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■ INTERRUPT SOURCES, INTERRUPT VECTORS, AND INTERRUPT CONTROL REGISTERS

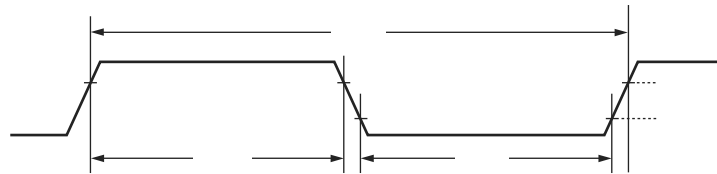
Interrupt source	EI ² OS corresponding	Interrupt vector			Interrupt control register		Priority *2
		Number		Address	ICR	Address	
Reset	×	#08	08 _H	FFFFDC _H	—	—	High ↑ ↓ Low
INT9 instruction	×	#09	09 _H	FFFFD8 _H	—	—	
Exception processing	×	#10	0A _H	FFFFD4 _H	—	—	
CAN0 received/CAN2 received	×	#11	0B _H	FFFFD0 _H	ICR00	0000B0 _H *1	
CAN0 transmitted/node status/ CAN2 transmitted/node status	×	#12	0C _H	FFFFCC _H			
CAN1 received/CAN3 received	×	#13	0D _H	FFFFC8 _H	ICR01	0000B1 _H *1	
CAN1 transmitted/node status/ CAN3 transmitted/node status/SIO	×	#14	0E _H	FFFFC4 _H			
Input capture 0	△	#15	0F _H	FFFFC0 _H	ICR02	0000B2 _H *1	
DTP/ external interrupt - ch.0/ch.1 detected	△	#16	10 _H	FFFFBC _H			
Reload timer 0	△	#17	11 _H	FFFFB8 _H	ICR03	0000B3 _H *1	
Reload timer 2	△	#18	12 _H	FFFFB4 _H			
Input capture 1	△	#19	13 _H	FFFFB0 _H	ICR04	0000B4 _H *1	
DTP/ external interrupt - ch.2/ch.3 detected	△	#20	14 _H	FFFFAC _H			
Input capture 2	△	#21	15 _H	FFFFA8 _H	ICR05	0000B5 _H *1	
Reload timer 3	△	#22	16 _H	FFFFA4 _H			
Input capture 3/4/5/6/7	△	#23	17 _H	FFFFA0 _H	ICR06	0000B6 _H *1	
DTP/ external interrupt - ch.4/ ch.5 detected UART3 RX	△	#24	18 _H	FFFF9C _H			
PPG timer 0	△	#25	19 _H	FFFF98 _H	ICR07	0000B7 _H *1	
DTP/ external interrupt - ch.6/ ch.7 detected UART3 TX	△	#26	1A _H	FFFF94 _H			
PPG timer 1	△	#27	1B _H	FFFF90 _H	ICR08	0000B8 _H *1	
Reload timer 1	△	#28	1C _H	FFFF8C _H			
PPG timer 2/3/4/5	○	#29	1D _H	FFFF88 _H	ICR09	0000B9 _H *1	
Real time watch timer watch timer (sub clock)	×	#30	1E _H	FFFF84 _H			
Free-run timer overflow/clear	×	#31	1F _H	FFFF80 _H	ICR10	0000BA _H *1	
A/D converter conversion complete	○	#32	20 _H	FFFF7C _H			
Sound generator 0/1	×	#33	21 _H	FFFF78 _H	ICR11	0000BB _H *1	
Time-base timer	×	#34	22 _H	FFFF74 _H			
UART2 RX	○	#35	23 _H	FFFF70 _H	ICR12	0000BC _H *1	
UART2 TX	△	#36	24 _H	FFFF6C _H			

(Continued)

- X0, X1 clock timing

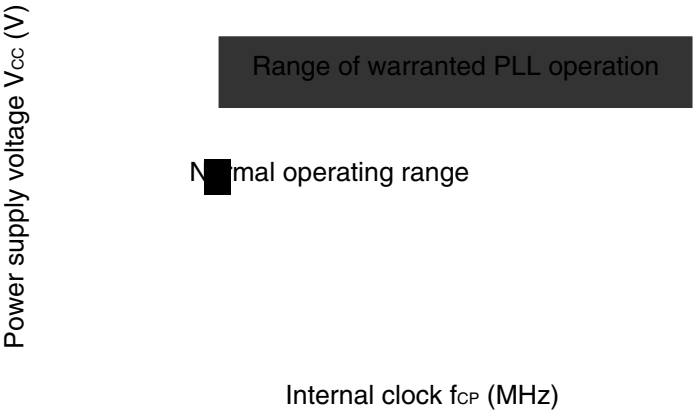


- X0A, X1A clock timing



• **Guaranteed PLL Operation Range**

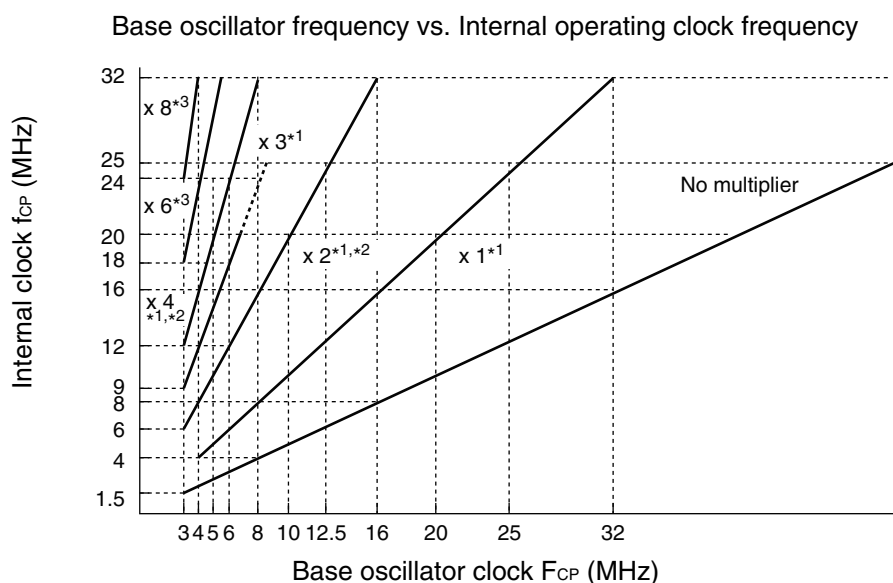
Internal operating clock frequency vs. Power supply voltage



- Notes :
- For PLL 1 × only, use with $f_{CP} = 4$ MHz or greater.
 - Refer to “5. A/D Converter (1) Electrical Characteristics” for details on the A/D converter operating frequency.

(Continued)

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*1 : When the PLL multiplier is $\times 1$, $\times 2$, $\times 3$ or $\times 4$ and the internal clock is $20 \text{ MHz} < f_{CP} \leq 32 \text{ MHz}$, set DIV2 bit = "1"*4, CS2 bit = "1" in the PSCCR register.

[Example] When using a base oscillator frequency of 24 MHz at PLL $\times 1$:

CKSCR register : CS1 bit = "0", CS0 bit = "0"

PSCCR register : DIV2 bit = "1"*4, CS2 bit = "1"

[Example] When using a base oscillator frequency of 6 MHz at PLL $\times 3$:

CKSCR register : CS1 bit = "1", CS0 bit = "0"

PSCCR register : DIV2 bit = "1"*4, CS2 bit = "1"

*2 : When the PLL multiplier is $\times 2$ or $\times 4$ and the internal clock is $20 \text{ MHz} < f_{CP} \leq 32 \text{ MHz}$, the following settings are also supported.

PLL $\times 2$: CKSCR register : CS1 bit = "0", CS0 bit = "0"

PSCCR register : DIV2 bit = "0"*4, CS2 bit = "0"

PLL $\times 4$: CKSCR register : CS1 bit = "0", CS0 bit = "1"

PSCCR register : DIV2 bit = "0"*4, CS2 bit = "0"

*3 : When the PLL multiplier is set to $\times 6$ or $\times 8$ set "DIV2 bit = "0"*4 CS2 bit = "1" and "PLL2 bit = 1" in the PSCCR register.

[Example] When using a base oscillator frequency of 4 MHz at PLL $\times 6$:

CKSCR register : CS1 bit = "1", CS0 bit = "0"

PLLOS register : DIV2 bit = "0"*4, CS2 bit = "1"

[Example] When using a base oscillator frequency of 3 MHz at PLL $\times 8$:

CKSCR register : CS1 bit = "1", CS0 bit = "1"

PLLOS register : DIV2 bit = "0"*4, CS2 bit = "1"

*4 : The DIV2 bit is assigned to bit 9 of the PSCCR register and the CS2 bit is assigned to bit 8 of the PSCCR register. Both bits have a default value of "0".

(2) Reset input

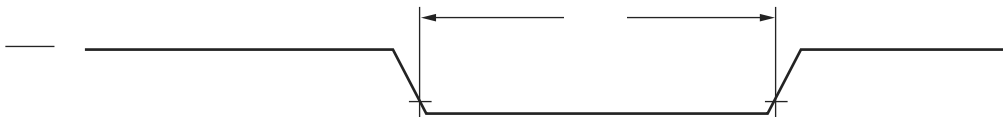
($V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C}$ to $+105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value		Unit	Remarks
			Min	Max		
Reset input time	t_{RSTL}	$\overline{RST}$	500	—	ns	During normal operation
			Oscillator oscillation time* + $16 t_{CP}$	—	ms	In stop mode, sub clock mode, sub sleep mode, and watch mode
			100	—	μs	In time-base timer mode

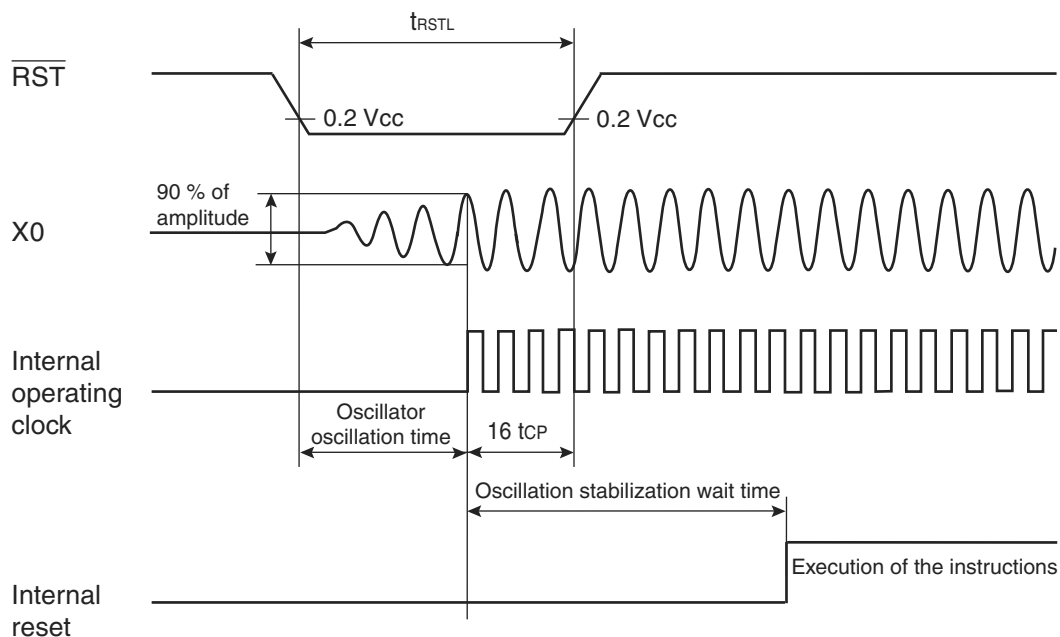
*: The oscillation time of the oscillator is the time taken to reach 90% of the amplitude. The oscillation time of a crystal oscillator is between several ms and tens of ms. The oscillation time of a ceramic oscillator is between hundreds of μs and several ms. The oscillation time of an external clock is 0 ms.

Note : t_{CP} is the internal operating clock cycle time. (Unit : ns)

- During normal operation



- In stop mode, sub clock mode, sub sleep mode, watch mode, and power-on



MB90920 Series

5. A/D Converter

(1) Electrical Characteristics

($V_{CC} = AV_{CC} = AVRH = 4.0\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	− 3.0	—	+ 3.0	LSB	
Non-linear error	—	—	− 2.5	—	+ 2.5	LSB	
Differential linear error	—	—	− 1.9	—	+ 1.9	LSB	
Zero transition voltage	V_{OT}	AN0 to AN7	$AV_{SS} - 1.5\text{ LSB}$	$AV_{SS} + 0.5\text{ LSB}$	$AV_{SS} + 2.5\text{ LSB}$	V	1 LSB = ($AVRH - AV_{SS}$) / 1024
Full scale transition voltage	V_{FST}	AN0 to AN7	$AVRH - 3.5\text{ LSB}$	$AVRH - 1.5\text{ LSB}$	$AVRH + 0.5\text{ LSB}$	V	
Sampling time	t_{SMP}	—	0.4	—	16500	μs	4.5 V $\leq$ $AV_{CC} \leq$ 5.5 V
			1.0				4.0 V $\leq$ $AV_{CC} \leq$ 4.5 V
Compare time	t_{CMP}	—	0.66	—	—	μs	4.5 V $\leq$ $AV_{CC} \leq$ 5.5 V
			2.2				4.0 V $\leq$ $AV_{CC} \leq$ 4.5 V
A/D conversion time	t_{CNV}	—	1.44	—	—	μs	*1
Analog port input current	I_{AIN}	AN0 to AN7	− 0.3	—	+ 10	μA	
Analog input voltage	V_{AIN}	AN0 to AN7	0	—	$AVRH$	V	
Reference voltage	$AV+$	$AVRH$	$AV_{SS} + 2.7$	—	AV_{CC}	V	
Power supply current	I_A	AV_{CC}	—	2.3	6.0	mA	
	I_{AH}		—	—	5	μA	*2
Reference voltage supply current	I_R	$AVRH$	—	520	900	μA	$V_{AVRH} = 5.0\text{ V}$
	I_{RH}		—	—	5	μA	*2
Inter-channel variation	—	AN0 to AN7	—	—	4	LSB	

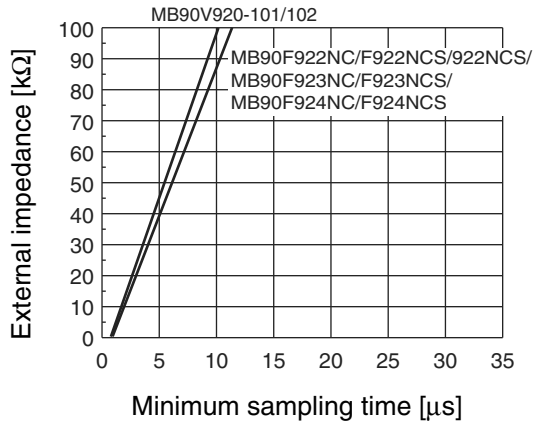
*1 : The time per channel (4.5 V $\leq$ $AV_{CC} \leq$ 5.5 V, and internal operating frequency = 32 MHz) .

*2 : Defined as supply current (when $V_{CC} = AV_{CC} = AVRH = 5.0\text{ V}$) with A/D converter not operating, and CPU in stop mode.

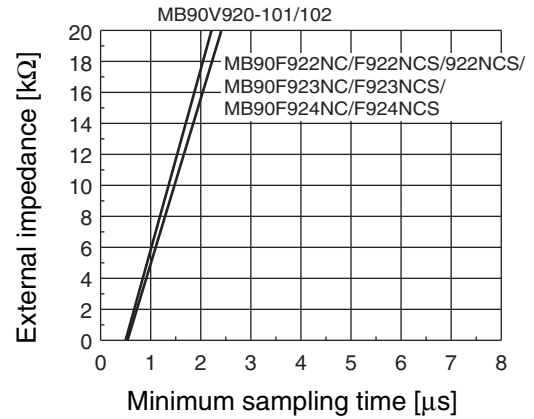
MB90920 Series

- The relationship between the external impedance and minimum sampling time
- At $4.5\text{ V} \leq AV_{CC} \leq 5.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)

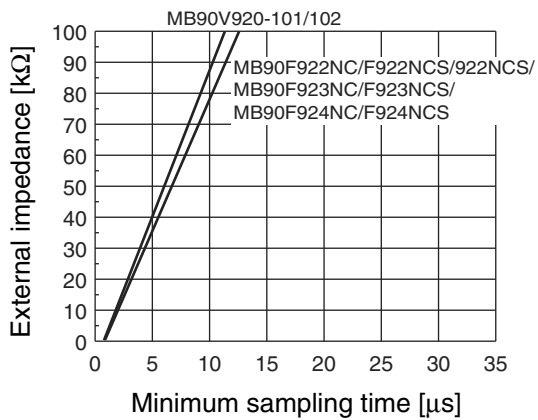


(External impedance = 0 k Ω to 20 k Ω)

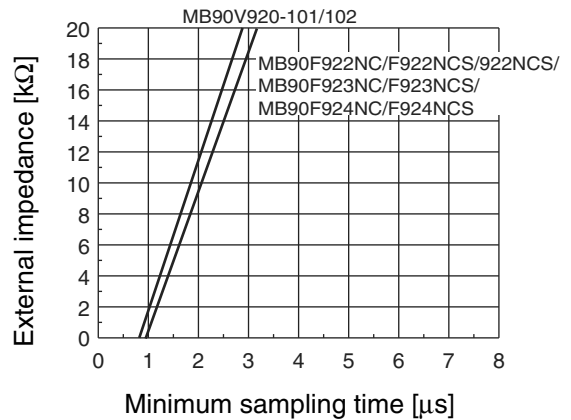


- At $4.0\text{ V} \leq AV_{CC} \leq 4.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)



(External impedance = 0 k Ω to 20 k Ω)



- About errors

As $|AV_{RH} - AV_{SS}|$ becomes smaller, the relative errors grow larger.

MEMO