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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

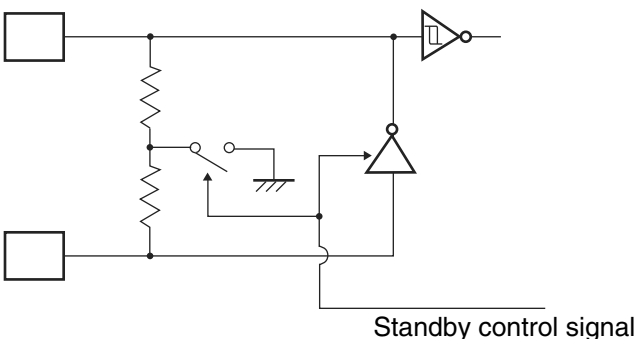
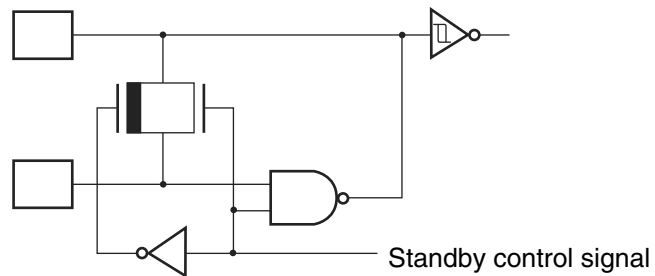
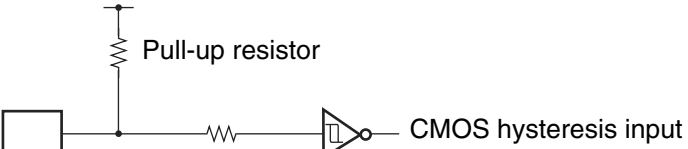

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-150e1

MB90920 Series

Pin no.	Pin name	I/O circuit type*1	Function
104	P13	I	General-purpose I/O port
	PPG5		16-bit PPG ch.5 output pin
109	P14	I	General-purpose I/O port
	TIN2		16-bit reload timer ch.2 TIN input pin
	IN1		Input capture ch.1 trigger input pin
110	P15	I	General-purpose I/O port
	IN0		Input capture ch.0 trigger input pin
111	COM0	P	LCD controller/driver common output pin
112	COM1	P	LCD controller/driver common output pin
113	COM2	P	LCD controller/driver common output pin
114	COM3	P	LCD controller/driver common output pin
115	P22	F	General-purpose I/O port
	SEG00		LCD controller/driver segment output pin
116	P23	F	General-purpose I/O port
	SEG01		LCD controller/driver segment output pin
117	P24	F	General-purpose I/O port
	SEG02		LCD controller/driver segment output pin
118	P25	F	General-purpose I/O port
	SEG03		LCD controller/driver segment output pin
119	P26	F	General-purpose I/O port
	SEG04		LCD controller/driver segment output pin
120	P27	F	General-purpose I/O port
	SEG05		LCD controller/driver segment output pin
1	P30	F	General-purpose I/O port
	SEG06		LCD controller/driver segment output pin
2	P31	F	General-purpose I/O port
	SEG07		LCD controller/driver segment output pin
3	P32	F	General-purpose I/O port
	SEG08		LCD controller/driver segment output pin
4	P33	F	General-purpose I/O port
	SEG09		LCD controller/driver segment output pin
5	P34	F	General-purpose I/O port
	SEG10		LCD controller/driver segment output pin
6	P35	F	General-purpose I/O port
	SEG11		LCD controller/driver segment output pin

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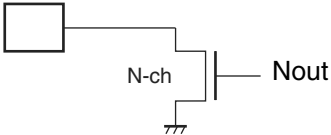
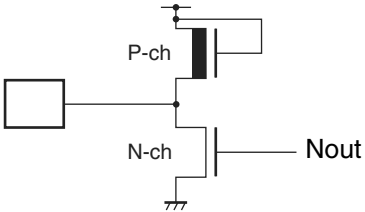

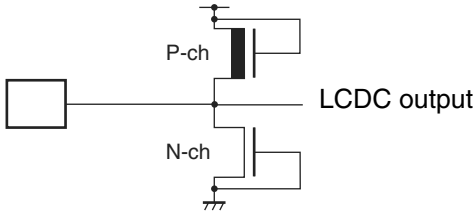
■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A	 <p>Standby control signal</p>	<p>Oscillation circuit</p> <p>High-speed oscillation feedback resistance : approx. 1 MΩ</p> <p>(Flash memory product/MASK ROM product/Evaluation product)</p>
B	 <p>Standby control signal</p>	<p>Oscillation circuit</p> <p>Low-speed oscillation feedback resistance : approx. 10 MΩ</p>
C	 <p>Pull-up resistor</p> <p>CMOS hysteresis input</p>	<p>Input-only pin (with pull-up resistance)</p> <ul style="list-style-type: none"> Attached pull-up resistor : approx. 50 kΩ CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$)
D	 <p>CMOS hysteresis input</p>	<p>Input-only pin</p> <ul style="list-style-type: none"> CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) <p>Note: The MD2 pin of the Flash memory products uses this circuit type.</p>

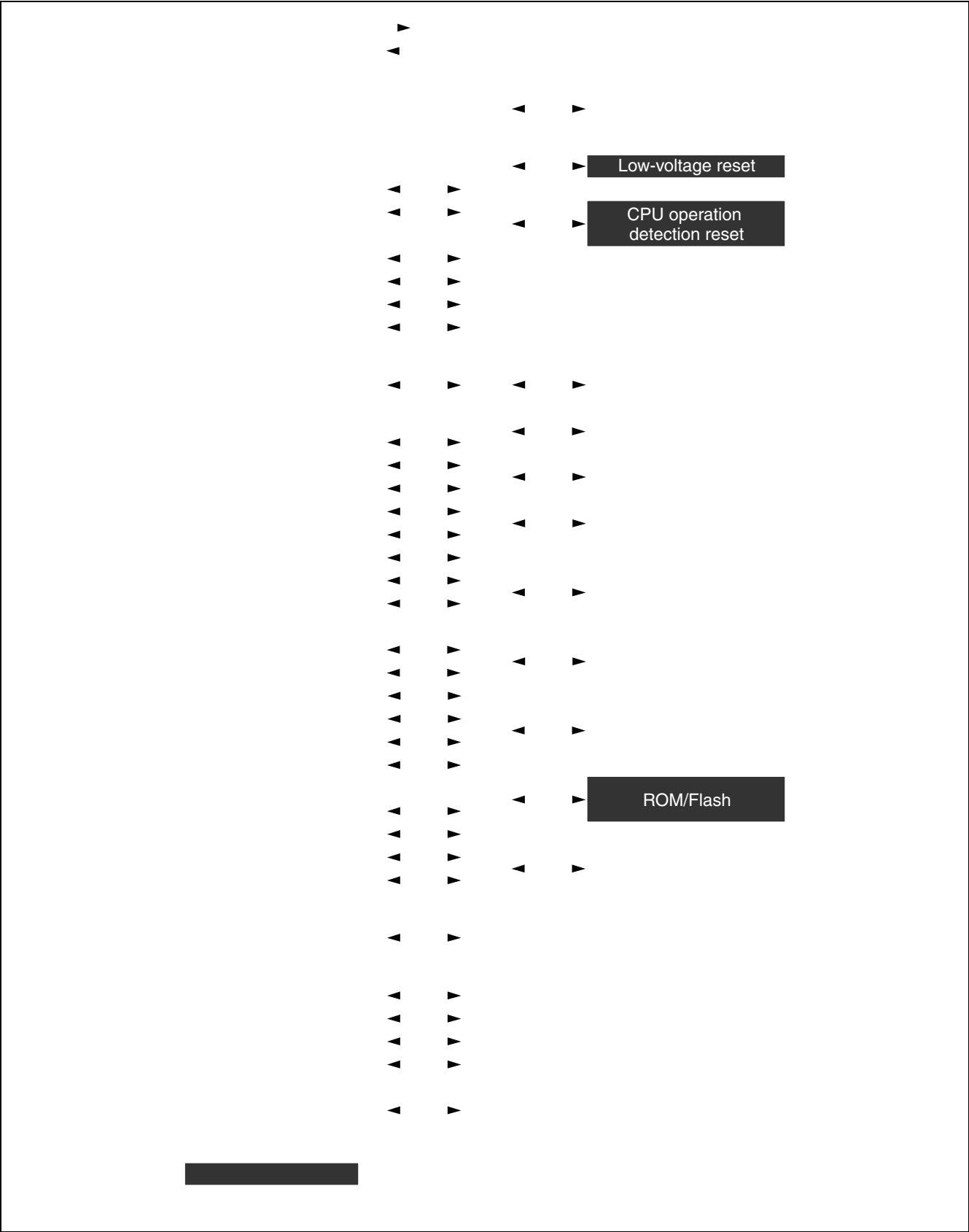
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MB90920 Series

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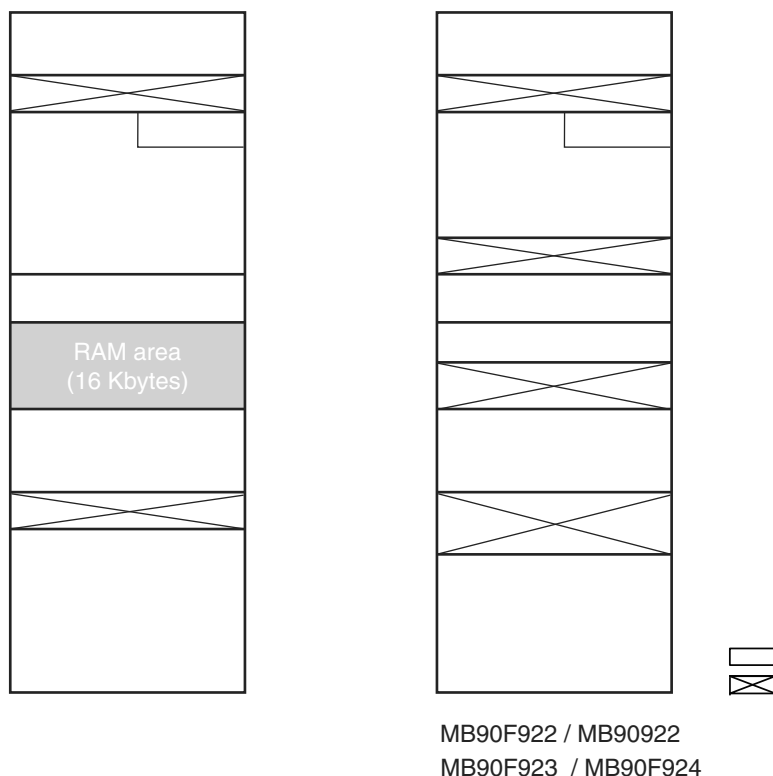
Type	Circuit	Remarks
N	<div style="display: flex; justify-content: space-around; align-items: flex-start;"> <div style="text-align: center;"> <p>Evaluation product</p>  </div> <div style="text-align: center;"> <p>Flash memory product</p>  </div> </div>	N-ch open-drain pin $I_{OL} = 4 \text{ mA}$
O		Input-only pin Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
P		LCDC output pin (COM pin)

■ BLOCK DIAGRAM



MB90920 Series

■ MEMORY MAP



Parts No.	ROM (Flash) capacitance	RAM capacitance	Address #1	Address #2	Address #3
MB90F922NC/F922NCS/922NCS	256 Kbytes	10 Kbytes	FC0000 _H	004000 _H	002900 _H
MB90F923NC/F923NCS	384 Kbytes	16 Kbytes	FA0000 _H	004A00 _H	003700 _H
MB90F924NC/F924NCS	512 Kbytes	24 Kbytes	F80000 _H	006A00 _H	003700 _H

* : Evaluation products do not contain internal ROM. Treat this address as the ROM decode area used by the tools.

Note: To select models without the ROM mirror function, refer to the “ROM Mirror Function Selection Module” in Hardware Manual. The image of the ROM data in the FF bank appears at the top of the 00 bank, in order to enable efficient use of small C compiler models. The lower 16-bits of the FF bank addresses are allocated to the same addresses as the lower 16-bits of the 00 bank, making it possible to reference tables in ROM without declaring the “far” modifier with the pointers. For example, when an access is made to the address 00C000_H, the actual address to be accessed is FFC000_H in ROM. Because the size of the FF bank ROM area exceeds 32 Kbytes, it is not possible to view the entire region in the 00 bank image. Therefore because the ROM data from FF8000_H to FFFFFFF_H appears in the image from 008000_H to 00FFFF_H, it is recommended that ROM data tables be stored in the area from FF8000_H to FFFFFFF_H.

Address	Register name	Symbol	Read/write	Resource name	Initial value
003970 _H to 003973 _H	(Disabled)				
003974 _H	Frequency data register 1	SGFR1	R/W	Sound generator 1	XXXXXXXX _B
003975 _H	Amplitude data register 1	SGAR1	R/W		00000000 _B
003976 _H	Decrement grade register 1	SGDR1	R/W		XXXXXXXX _B
003977 _H	Tone count register 1	SGTR1	R/W		XXXXXXXX _B
003978 _H to 00397F _H	(Disabled)				
003980 _H	PWM1 compare register 0	PWC10	R/W	Stepping motor controller 0	XXXXXXXX _B
003981 _H					XXXXXXXX _B
003982 _H	PWM2 compare register 0	PWC20	R/W		XXXXXXXX _B
003983 _H					XXXXXXXX _B
003984 _H	PWM1 select register 0	PWS10	R/W		00000000 _B
003985 _H	PWM2 select register 0	PWS20	R/W		X0000000 _B
003986 _H , 003987 _H	(Disabled)				
003988 _H	PWM1 compare register 1	PWC11	R/W	Stepping motor controller 1	XXXXXXXX _B
003989 _H					XXXXXXXX _B
00398A _H	PWM2 compare register 1	PWC21	R/W		XXXXXXXX _B
00398B _H					XXXXXXXX _B
00398C _H	PWM1 select register 1	PWS11	R/W		00000000 _B
00398D _H	PWM2 select register 1	PWS21	R/W		X0000000 _B
00398E _H , 00398F _H	(Disabled)				
003990 _H	PWM1 compare register 2	PWC12	R/W	Stepping motor controller 2	XXXXXXXX _B
003991 _H					XXXXXXXX _B
003992 _H	PWM2 compare register 2	PWC22	R/W		XXXXXXXX _B
003993 _H					XXXXXXXX _B
003994 _H	PWM1 select register 2	PWS12	R/W		00000000 _B
003995 _H	PWM2 select register 2	PWS22	R/W		X0000000 _B
003996 _H , 003997 _H	(Disabled)				

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MB90920 Series

List of Control Registers(2)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
000040 _H	000070 _H	0039C0 _H	0039D0 _H	Message buffer valid register	BVALR	R/W	00000000 _B 00000000 _B
000041 _H	000071 _H	0039C1 _H	0039D1 _H				
000042 _H	000072 _H	0039C2 _H	0039D2 _H	Transmit request register	TREQR	R/W	00000000 _B 00000000 _B
000043 _H	000073 _H	0039C3 _H	0039D3 _H				
000044 _H	000074 _H	0039C4 _H	0039D4 _H	Transmit cancel register	TCANR	W	00000000 _B 00000000 _B
000045 _H	000075 _H	0039C5 _H	0039D5 _H				
000046 _H	000076 _H	0039C6 _H	0039D6 _H	Transmit complete register	TCR	R/W	00000000 _B 00000000 _B
000047 _H	000077 _H	0039C7 _H	0039D7 _H				
000048 _H	000078 _H	0039C8 _H	0039D8 _H	Receive complete register	RCR	R/W	00000000 _B 00000000 _B
000049 _H	000079 _H	0039C9 _H	0039D9 _H				
00004A _H	00007A _H	0039CA _H	0039DA _H	Remote request receive register	RRTRR	R/W	00000000 _B 00000000 _B
00004B _H	00007B _H	0039CB _H	0039DB _H				
00004C _H	00007C _H	0039CC _H	0039DC _H	Receive overrun register	ROVRR	R/W	00000000 _B 00000000 _B
00004D _H	00007D _H	0039CD _H	0039DD _H				
00004E _H	00007E _H	0039CE _H	0039DE _H	Receive interrupt enable register	RIER	R/W	00000000 _B 00000000 _B
00004F _H	00007F _H	0039CF _H	0039DF _H				
003C08 _H	003D08 _H	003E08 _H	003F08 _H	IDE register	IDER	R/W	XXXXXXXX _B
003C09 _H	003D09 _H	003E09 _H	003F09 _H				XXXXXXXX _B
003C0A _H	003D0A _H	003E0A _H	003F0A _H	Transmit RTR register	TRTRR	R/W	00000000 _B
003C0B _H	003D0B _H	003E0B _H	003F0B _H				00000000 _B
003C0C _H	003D0C _H	003E0C _H	003F0C _H	Remote frame receive wait register	RFWTR	R/W	XXXXXXXX _B XXXXXXXX _B
003C0D _H	003D0D _H	003E0D _H	003F0D _H				
003C0E _H	003D0E _H	003E0E _H	003F0E _H	Transmit interrupt enable register	TIER	R/W	00000000 _B 00000000 _B
003C0F _H	003D0F _H	003E0F _H	003F0F _H				
003C10 _H	003D10 _H	003E10 _H	003F10 _H	Acceptance mask select register	AMSR	R/W	XXXXXXXX _B XXXXXXXX _B
003C11 _H	003D11 _H	003E11 _H	003F11 _H				XXXXXXXX _B XXXXXXXX _B
003C12 _H	003D12 _H	003E12 _H	003F12 _H				
003C13 _H	003D13 _H	003E13 _H	003F13 _H				
003C14 _H	003D14 _H	003E14 _H	003F14 _H	Acceptance mask register 0	AMR0	R/W	XXXXXXXX _B XXXXXXXX _B
003C15 _H	003D15 _H	003E15 _H	003F15 _H				XXXXXX--- _B XXXXXXXX _B
003C16 _H	003D16 _H	003E16 _H	003F16 _H				
003C17 _H	003D17 _H	003E17 _H	003F17 _H				
003C18 _H	003D18 _H	003E18 _H	003F18 _H	Acceptance mask register 1	AMR1	R/W	XXXXXXXX _B XXXXXXXX _B
003C19 _H	003D19 _H	003E19 _H	003F19 _H				XXXXXX--- _B XXXXXXXX _B
003C1A _H	003D1A _H	003E1A _H	003F1A _H				
003C1B _H	003D1B _H	003E1B _H	003F1B _H				

MB90920 Series

(Continued)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A40 _H	003B40 _H	003740 _H	003840 _H	ID register 8	IDR8	R/W	XXXXXXXX _B XXXXXXXX _B
003A41 _H	003B41 _H	003741 _H	003841 _H				XXXXXX--- _B XXXXXXXX _B
003A42 _H	003B42 _H	003742 _H	003842 _H				
003A43 _H	003B43 _H	003743 _H	003843 _H				
003A44 _H	003B44 _H	003744 _H	003844 _H	ID register 9	IDR9	R/W	XXXXXXXX _B XXXXXXXX _B
003A45 _H	003B45 _H	003745 _H	003845 _H				XXXXXX--- _B XXXXXXXX _B
003A46 _H	003B46 _H	003746 _H	003846 _H				
003A47 _H	003B47 _H	003747 _H	003847 _H				
003A48 _H	003B48 _H	003748 _H	003848 _H	ID register 10	IDR10	R/W	XXXXXXXX _B XXXXXXXX _B
003A49 _H	003B49 _H	003749 _H	003849 _H				XXXXXX--- _B XXXXXXXX _B
003A4A _H	003B4A _H	00374A _H	00384A _H				
003A4B _H	003B4B _H	00374B _H	00384B _H				
003A4C _H	003B4C _H	00374C _H	00384C _H	ID register 11	IDR11	R/W	XXXXXXXX _B XXXXXXXX _B
003A4D _H	003B4D _H	00374D _H	00384D _H				XXXXXX--- _B XXXXXXXX _B
003A4E _H	003B4E _H	00374E _H	00384E _H				
003A4F _H	003B4F _H	00374F _H	00384F _H				
003A50 _H	003B50 _H	003750 _H	003850 _H	ID register 12	IDR12	R/W	XXXXXXXX _B XXXXXXXX _B
003A51 _H	003B51 _H	003751 _H	003851 _H				XXXXXX--- _B XXXXXXXX _B
003A52 _H	003B52 _H	003752 _H	003852 _H				
003A53 _H	003B53 _H	003753 _H	003853 _H				
003A54 _H	003B54 _H	003754 _H	003854 _H	ID register 13	IDR13	R/W	XXXXXXXX _B XXXXXXXX _B
003A55 _H	003B55 _H	003755 _H	003855 _H				XXXXXX--- _B XXXXXXXX _B
003A56 _H	003B56 _H	003756 _H	003856 _H				
003A57 _H	003B57 _H	003757 _H	003857 _H				
003A58 _H	003B58 _H	003758 _H	003858 _H	ID register 14	IDR14	R/W	XXXXXXXX _B XXXXXXXX _B
003A59 _H	003B59 _H	003759 _H	003859 _H				XXXXXX--- _B XXXXXXXX _B
003A5A _H	003B5A _H	00375A _H	00385A _H				
003A5B _H	003B5B _H	00375B _H	00385B _H				
003A5C _H	003B5C _H	00375C _H	00385C _H	ID register 15	IDR15	R/W	XXXXXXXX _B XXXXXXXX _B
003A5D _H	003B5D _H	00375D _H	00385D _H				XXXXXX--- _B XXXXXXXX _B
003A5E _H	003B5E _H	00375E _H	00385E _H				
003A5F _H	003B5F _H	00375F _H	00385F _H				

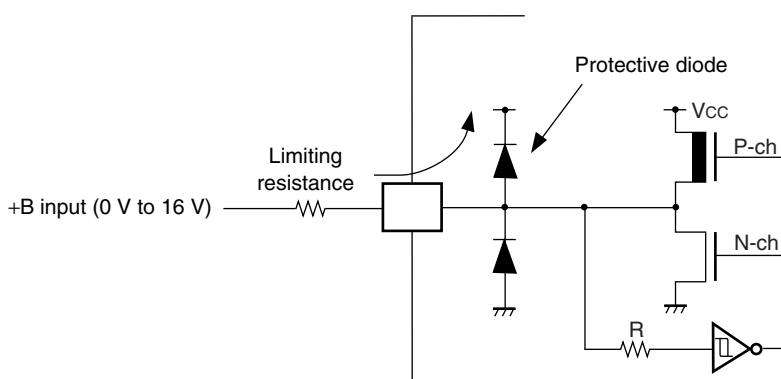
List of Message Buffers (Data register)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A80 _H to 003A87 _H	003B80 _H to 003B87 _H	003780 _H to 003787 _H	003880 _H to 003887 _H	Data register 0 (8 bytes)	DTR0	R/W	XXXXXXXX _B to XXXXXXXX _B
003A88 _H to 003A8F _H	003B88 _H to 003B8F _H	003788 _H to 00378F _H	003888 _H to 00388F _H	Data register 1 (8 bytes)	DTR1	R/W	XXXXXXXX _B to XXXXXXXX _B
003A90 _H to 003A97 _H	003B90 _H to 003B97 _H	003790 _H to 003797 _H	003890 _H to 003897 _H	Data register 2 (8 bytes)	DTR2	R/W	XXXXXXXX _B to XXXXXXXX _B
003A98 _H to 003A9F _H	003B98 _H to 003B9F _H	003798 _H to 00379F _H	003898 _H to 00389F _H	Data register 3 (8 bytes)	DTR3	R/W	XXXXXXXX _B to XXXXXXXX _B
003AA0 _H to 003AA7 _H	003BA0 _H to 003BA7 _H	0037A0 _H to 0037A7 _H	0038A0 _H to 0038A7 _H	Data register 4 (8 bytes)	DTR4	R/W	XXXXXXXX _B to XXXXXXXX _B
003AA8 _H to 003AAF _H	003BA8 _H to 003BAF _H	0037A8 _H to 0037AF _H	0038A8 _H to 0038AF _H	Data register 5 (8 bytes)	DTR5	R/W	XXXXXXXX _B to XXXXXXXX _B
003AB0 _H to 003AB7 _H	003BB0 _H to 003BB7 _H	0037B0 _H to 0037B7 _H	0038B0 _H to 0038B7 _H	Data register 6 (8 bytes)	DTR6	R/W	XXXXXXXX _B to XXXXXXXX _B
003AB8 _H to 003ABF _H	003BB8 _H to 003BBF _H	0037B8 _H to 0037BF _H	0038B8 _H to 0038BF _H	Data register 7 (8 bytes)	DTR7	R/W	XXXXXXXX _B to XXXXXXXX _B
003AC0 _H to 003AC7 _H	003BC0 _H to 003BC7 _H	0037C0 _H to 0037C7 _H	0038C0 _H to 0038C7 _H	Data register 8 (8 bytes)	DTR8	R/W	XXXXXXXX _B to XXXXXXXX _B
003AC8 _H to 003ACF _H	003BC8 _H to 003BCF _H	0037C8 _H to 0037CF _H	0038C8 _H to 0038CF _H	Data register 9 (8 bytes)	DTR9	R/W	XXXXXXXX _B to XXXXXXXX _B
003AD0 _H to 003AD7 _H	003BD0 _H to 003BD7 _H	0037D0 _H to 0037D7 _H	0038D0 _H to 0038D7 _H	Data register 10 (8 bytes)	DTR10	R/W	XXXXXXXX _B to XXXXXXXX _B
003AD8 _H to 003ADF _H	003BD8 _H to 003BDF _H	0037D8 _H to 0037DF _H	0038D8 _H to 0038DF _H	Data register 11 (8 bytes)	DTR11	R/W	XXXXXXXX _B to XXXXXXXX _B
003AE0 _H to 003AE7 _H	003BE0 _H to 003BE7 _H	0037E0 _H to 0037E7 _H	0038E0 _H to 0038E7 _H	Data register 12 (8 bytes)	DTR12	R/W	XXXXXXXX _B to XXXXXXXX _B
003AE8 _H to 003AEF _H	003BE8 _H to 003BEF _H	0037E8 _H to 0037EF _H	0038E8 _H to 0038EF _H	Data register 13 (8 bytes)	DTR13	R/W	XXXXXXXX _B to XXXXXXXX _B
003AF0 _H to 003AF7 _H	003BF0 _H to 003BF7 _H	0037F0 _H to 0037F7 _H	0038F0 _H to 0038F7 _H	Data register 14 (8 bytes)	DTR14	R/W	XXXXXXXX _B to XXXXXXXX _B
003AF8 _H to 003AFF _H	003BF8 _H to 003BFF _H	0037F8 _H to 0037FF _H	0038F8 _H to 0038FF _H	Data register 15 (8 bytes)	DTR15	R/W	XXXXXXXX _B to XXXXXXXX _B

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- *5 : Average output current is defined as the average value of the current flowing through any one of the corresponding pins within a period of 100 ms. The “average value” can be calculated by multiplying the “operating current” by the “operating factor”.
- *6 : Average total output current is defined as the average value of the current flowing through all of the corresponding pins within a period of 100 ms. The “average value” can be calculated by multiplying the “operating current” by the “operating factor”.
- *7 :
 - Applicable to pins: P10 to P15, P50 to P57, P60 to P67, P70 to P77, P80 to P87, PC0 to PC7, PD0 to PD6, PE0 to PE2
 - Use within recommended operating conditions.
 - Use at DC voltage (current) .
 - The +B signal should always be applied with a limiting resistance placed between the +B signal and the microcontroller.
 - The value of the limiting resistance should be set so that when the +B signal is applied, the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
 - Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
 - Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the microcontroller may partially malfunction on power supplied through the +B signal pin.
 - Note that if the +B input is applied during power-on, the power supply voltage may reach a level such that the power-on reset does not function due to the power supplied from the +B signal.
 - Care must be taken not to leave +B input pins open.
 - Note that analog system input/output pins (LCD drive pins, comparator input pins, etc.) cannot accept +B signal inputs.
 - Sample recommended circuit :

- Input/output equivalent circuit



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

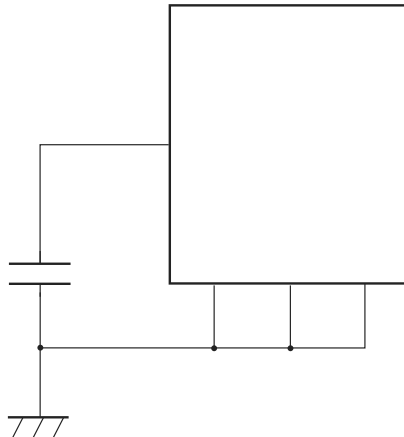
2. Recommended Operating Conditions

($V_{SS} = DV_{SS} = AV_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Value		Unit	Remarks
		Min	Max		
Power supply voltage	V_{CC}	4.0	5.5	V	The low voltage detection reset operates when the power supply voltage reaches $4.2\text{ V} \pm 0.2\text{ V}$.
	AV_{CC} DV_{CC}	4.4	5.5	V	Maintain stop operation status The low voltage detection reset operates when the power supply voltage reaches $4.2\text{ V} \pm 0.2\text{ V}$.
Smoothing capacitor*	C_S	0.1	1.0	μF	Use a ceramic capacitor or other capacitor of equivalent frequency characteristics. Use a capacitor with a capacitance greater than this capacitor as the bypass capacitor for the V_{CC} pin.
Operating temperature	T_A	- 40	+ 105	$^{\circ}\text{C}$	

* : Refer to the following diagram for details on the connection of the smoothing capacitor C_S .

- C pin connection diagram



WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

MB90920 Series

(Continued)

($V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = DV_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^\circ\text{C}$ to $+105 \text{ }^\circ\text{C}$)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
LCDC leakage current	I_{LCDC}	V0 to V3, COMm (m = 0 to 3) , SEGN, (n = 00 to 31)	—	—	—	5.0	μA	
LCD output impedance	R_{vcom}	COMn (n = 0 to 3)	—	—	—	4.5	$\text{k}\Omega$	
	R_{vseg}	SEGN (n = 00 to 31)	—	—	—	17	$\text{k}\Omega$	

* : Power supply current values assume an external clock supplied to the X1 pin and X1A pin. Users must be aware that power supply current levels differ depending on whether an external clock or oscillator is used.

(2) Reset input

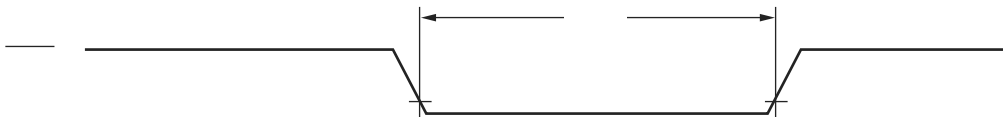
($V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C}$ to $+105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value		Unit	Remarks
			Min	Max		
Reset input time	t_{RSTL}	\overline{RST}	500	—	ns	During normal operation
			Oscillator oscillation time* + $16 t_{CP}$	—	ms	In stop mode, sub clock mode, sub sleep mode, and watch mode
			100	—	μs	In time-base timer mode

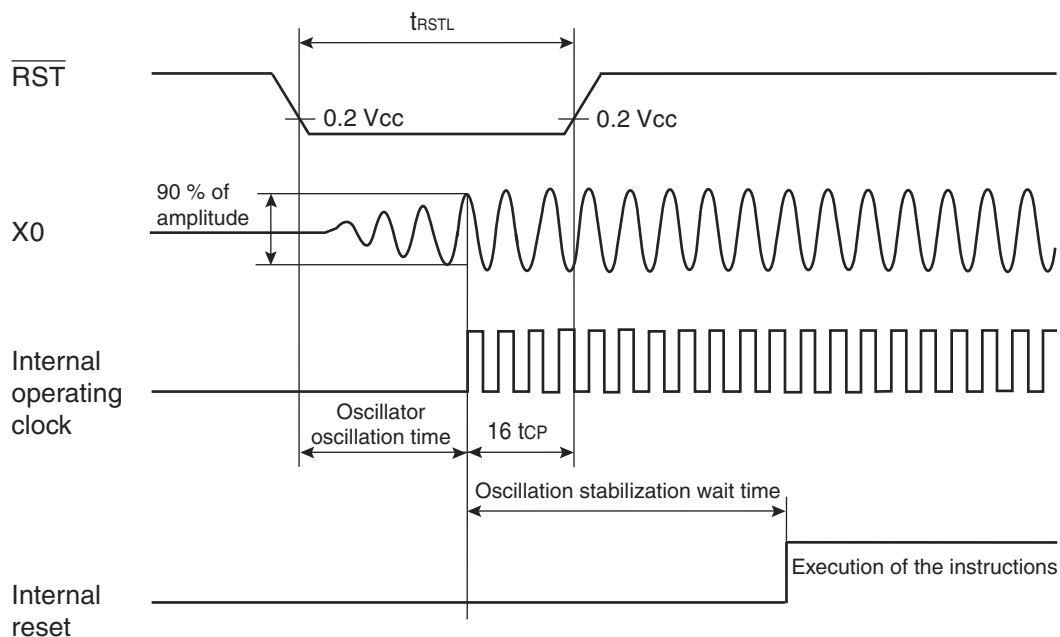
*: The oscillation time of the oscillator is the time taken to reach 90% of the amplitude. The oscillation time of a crystal oscillator is between several ms and tens of ms. The oscillation time of a ceramic oscillator is between hundreds of μs and several ms. The oscillation time of an external clock is 0 ms.

Note : t_{CP} is the internal operating clock cycle time. (Unit : ns)

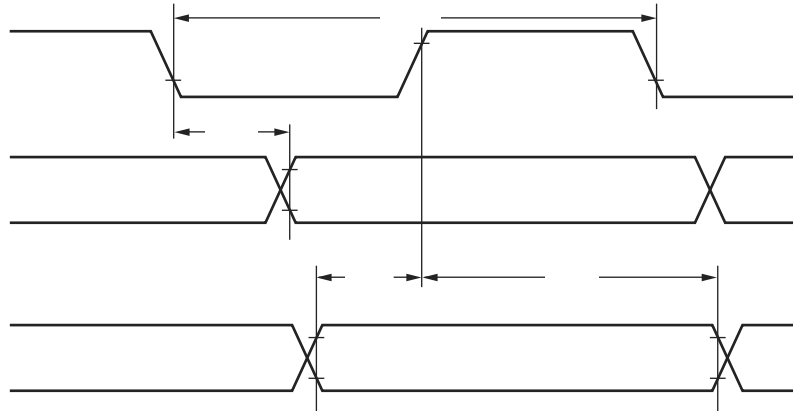
- During normal operation



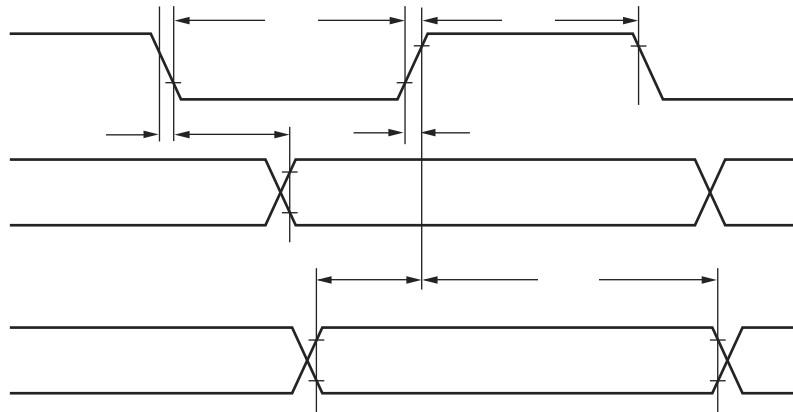
- In stop mode, sub clock mode, sub sleep mode, watch mode, and power-on



- Internal shift clock mode



- External shift clock mode



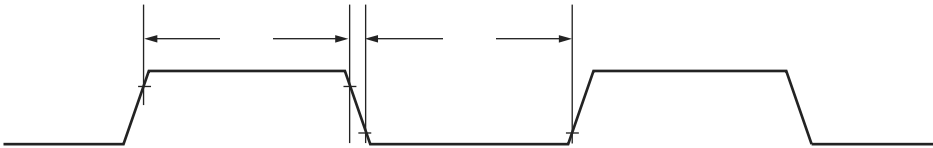
(5) Timer input timing

(V_{CC} = 5.0 V±10%, V_{SS} = AV_{SS} = 0.0 V, T_A = -40 °C to +105 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Input pulse width	t _{TIWH} t _{TIWL}	TIN0, TIN1, IN0 to IN3	—	4 t _{CP}	—	ns

Note : t_{CP} is the internal operating clock cycle time. Refer to “ (1) Clock timing”.

- Timer input timing



MB90920 Series

5. A/D Converter

(1) Electrical Characteristics

($V_{CC} = AV_{CC} = AVR_H = 4.0\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	− 3.0	—	+ 3.0	LSB	
Non-linear error	—	—	− 2.5	—	+ 2.5	LSB	
Differential linear error	—	—	− 1.9	—	+ 1.9	LSB	
Zero transition voltage	V_{OT}	AN0 to AN7	$AV_{SS} - 1.5\text{ LSB}$	$AV_{SS} + 0.5\text{ LSB}$	$AV_{SS} + 2.5\text{ LSB}$	V	1 LSB = ($AVR_H - AV_{SS}$) / 1024
Full scale transition voltage	V_{FST}	AN0 to AN7	$AVR_H - 3.5\text{ LSB}$	$AVR_H - 1.5\text{ LSB}$	$AVR_H + 0.5\text{ LSB}$	V	
Sampling time	t_{SMP}	—	0.4	—	16500	μs	4.5 V \leq $AV_{CC} \leq$ 5.5 V
			1.0				4.0 V \leq $AV_{CC} \leq$ 4.5 V
Compare time	t_{CMP}	—	0.66	—	—	μs	4.5 V \leq $AV_{CC} \leq$ 5.5 V
			2.2				4.0 V \leq $AV_{CC} \leq$ 4.5 V
A/D conversion time	t_{CNV}	—	1.44	—	—	μs	*1
Analog port input current	I_{AIN}	AN0 to AN7	− 0.3	—	+ 10	μA	
Analog input voltage	V_{AIN}	AN0 to AN7	0	—	AVR_H	V	
Reference voltage	$AV+$	AVR_H	$AV_{SS} + 2.7$	—	AV_{CC}	V	
Power supply current	I_A	AV_{CC}	—	2.3	6.0	mA	
	I_{AH}		—	—	5	μA	*2
Reference voltage supply current	I_R	AVR_H	—	520	900	μA	$V_{AVR_H} = 5.0\text{ V}$
	I_{RH}		—	—	5	μA	*2
Inter-channel variation	—	AN0 to AN7	—	—	4	LSB	

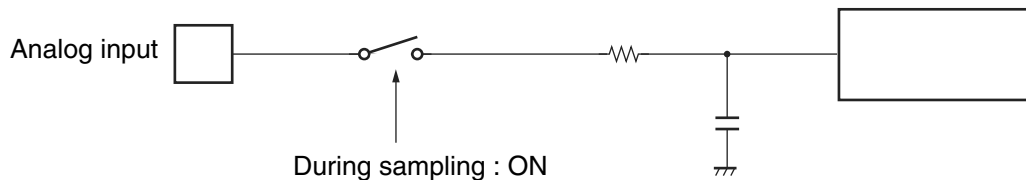
*1 : The time per channel (4.5 V \leq $AV_{CC} \leq$ 5.5 V, and internal operating frequency = 32 MHz) .

*2 : Defined as supply current (when $V_{CC} = AV_{CC} = AVR_H = 5.0\text{ V}$) with A/D converter not operating, and CPU in stop mode.

• Notes on the external impedance and sampling time of analog inputs

A/D converter with sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting A/D conversion precision. Therefore, to satisfy the A/D conversion precision standard, consider the relationship between the external impedance and minimum sampling time and either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. If the sampling time is still not sufficient, connect a capacitor of about 0.1 μF to the analog input pin.

• Analog input equivalent circuit



MB90F922NC/F922NCS/ F923NC/F923NCS/F924NC/F924NCS
MB90922NCS

	R	C
$4.5\text{ V} \leq \text{AVcc} \leq 5.5\text{ V}$	2.6 k Ω (Max)	8.5 pF (Max)
$4.0\text{ V} \leq \text{AVcc} \leq 4.5\text{ V}$	12.1 k Ω (Max)	8.5 pF (Max)

MB90V920-101/102

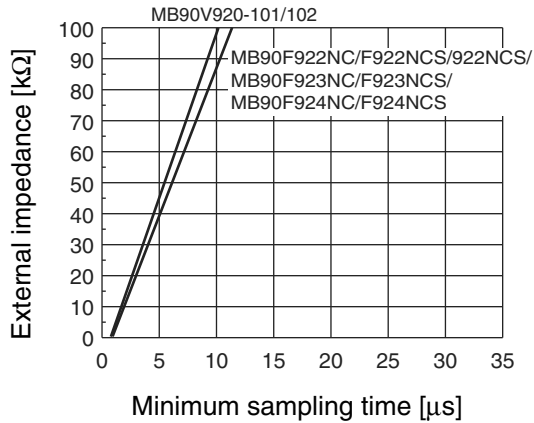
$4.5\text{ V} \leq \text{AVcc} \leq 5.5\text{ V}$	2.0 k Ω (Max)	14.4 pF (Max)
$4.0\text{ V} \leq \text{AVcc} \leq 4.5\text{ V}$	8.2 k Ω (Max)	14.4 pF (Max)

Note : The values are reference values.

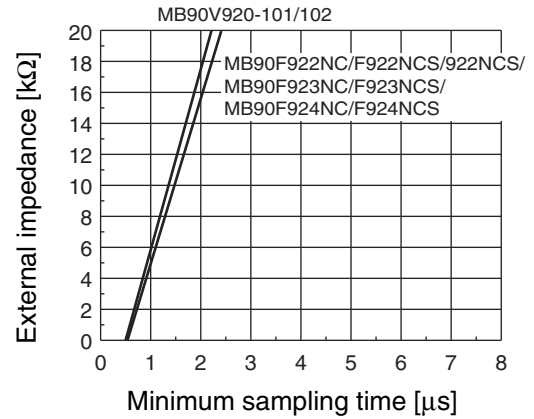
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- The relationship between the external impedance and minimum sampling time
- At $4.5\text{ V} \leq AV_{CC} \leq 5.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)

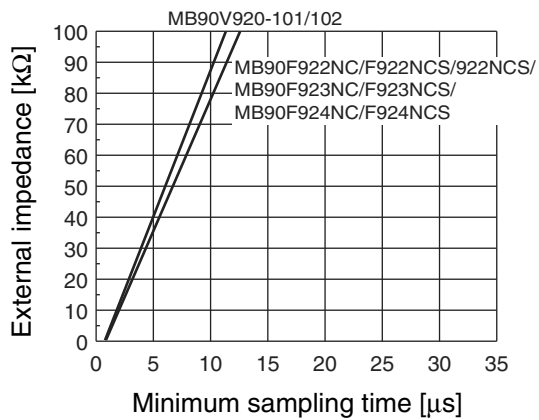


(External impedance = 0 k Ω to 20 k Ω)

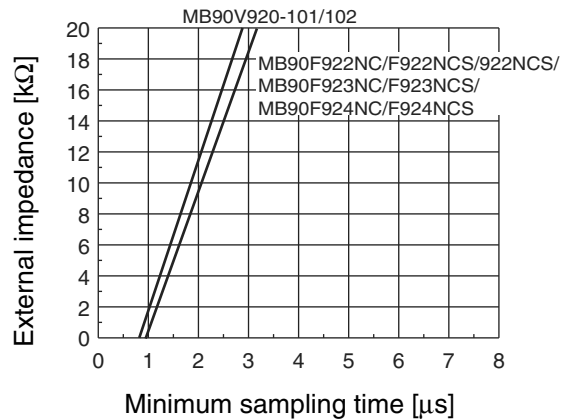


- At $4.0\text{ V} \leq AV_{CC} \leq 4.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)



(External impedance = 0 k Ω to 20 k Ω)



- About errors

As $|AV_{RH} - AV_{SS}|$ becomes smaller, the relative errors grow larger.

MB90920 Series

■ ORDERING INFORMATION

Part number	Package	Remarks
MB90F922NCPMC MB90F922NCSPMC MB90922NCSPMC MB90F923NCPMC MB90F923NCSPMC MB90F924NCPMC MB90F924NCSPMC	120-pin plastic LQFP (FPT-120P-M21)	
MB90V920-101CR MB90V920-102CR	299-pin ceramic PGA (PGA-299C-A01)	For evaluation

MB90920 Series

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