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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-152e1

16-bit Microcontroller

CMOS

F²MC-16LX MB90920 Series

**MB90F922NC/F922NCS/922NCS/F923NC/F923NCS/
MB90F924NC/F924NCS/V920-101/V920-102**

■ DESCRIPTION

The MB90920 series is a family of general-purpose FUJITSU SEMICONDUCTOR 16-bit microcontrollers designed for applications such as vehicle instrument panel control.

The instruction set retains the AT architecture from the F²MC-8L and F²MC-16LX families, with further refinements including high-level language instructions, extended addressing modes, improved multiplication and division operations (signed), and bit processing. In addition, long word processing is made possible by the inclusion of a built-in 32-bit accumulator.

Note : F²MC is the abbreviation of FUJITSU Flexible Microcontroller.

■ FEATURES

- Clock
Built-in PLL clock frequency multiplication circuit.
Selection of machine clocks (PLL clocks) is allowed among frequency division by two on oscillation clock, and multiplication of 1 to 8 times of oscillation clock (for 4 MHz oscillation clock, 4 MHz to 32 MHz).
Operation by sub clock (up to 50 kHz : 100 kHz oscillation clock divided by two) is allowed.
- 16-bit input capture (8 channels)
Detects rising, falling, or both edges.
16-bit capture register × 8
The value of a 16-bit free-run timer counter is latched upon detection of an edge input to pin and an interrupt request is generated.

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For the information for microcontroller supports, see the following web site.

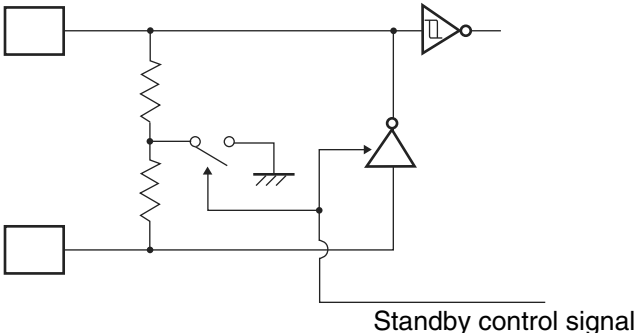
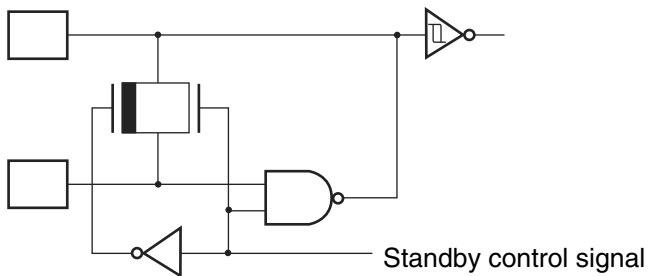
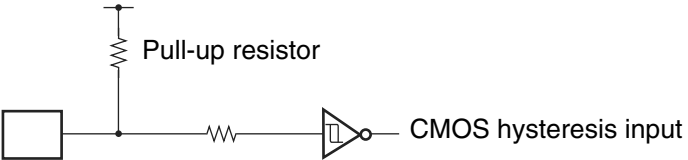

This web site includes the "**Customer Design Review Supplement**" which provides the latest cautions on system development and the minimal requirements to be checked to prevent problems before the system development.

<http://edevise.fujitsu.com/micom/en-support/>

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- 16-bit reload timer (4 channels)
16-bit reload timer operation (select toggle output or one-shot output)
Selectable event count function
- Real time watch timer (main clock)
Operates directly from oscillator clock.
Interrupt can be generated by second/minute/hour/date counter overflow.
- PPG timer (6 channels)
Output pins (3 channels), external trigger input pin (1 channel)
Operation clock frequencies : f_{CP} , $f_{CP}/2^2$, $f_{CP}/2^4$, $f_{CP}/2^6$
- Delay interrupt
Generates interrupt for task switching.
Interrupts to CPU can be generated/cleared by software setting.
- External interrupts (8 channels)
8-channel independent operation
Interrupt source setting available : “L” to “H” edge/ “H” to “L” edge/ “L” level/ “H” level.
- 8/10-bit A/D converter (8 channels)
Conversion time : 3 μ s (at $f_{CP} = 32$ MHz)
External trigger activation available (P50/INT0/ADTG)
Internal timer activation available (16-bit reload timer 1)
- UART(LIN/SCI) (4 channels)
Equipped with full duplex double buffer
Clock-asynchronous or clock-synchronous serial transfer is available
- CAN interface (4 channels : CAN0 and CAN2, and CAN1 and CAN3 share transmission and reception pins, and interrupt control registers).
Conforms to CAN specifications version 2.0 Part A and B.
Automatic resend in case of error.
Automatic transfer in response to remote frame.
16 prioritized message buffers for data and ID
Multiple message support
Flexible configuration for receive filter : Full bit compare/full bit mask/two partial bit masks
Supports up to 1 Mbps
CAN wakeup function (RX connected to INT0 internally)
- LCD controller/driver (32 segment x 4 common)
Segment driver and command driver with direct LCD panel (display) drive capability
- Reset on detection of low voltage/program loop
Automatic reset when low voltage is detected
Program looping detection function
- Stepping motor controller (4 channels)
High current output for each channel $\times 4$
Synchronized 8/10-bit PWM for each channel $\times 2$
- Sound generator (2 channels)
8-bit PWM signal mixed with tone frequency from 8-bit reload counter.
PWM frequencies : 125 kHz, 62.5 kHz, 31.2 kHz, 15.6 kHz (at $f_{CP} = 32$ MHz)
Tone frequencies : PWM frequency /2/ , divided by (reload frequency +1)
- Input/output ports
General-purpose input/output port (CMOS output) 93 ports
- Function for port input level selection
Automotive/CMOS-Schmitt
- Flash memory security function
Protects the contents of Flash memory (Flash memory product only)

■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A	 <p>Standby control signal</p>	<p>Oscillation circuit</p> <p>High-speed oscillation feedback resistance : approx. 1 MΩ</p> <p>(Flash memory product/MASK ROM product/Evaluation product)</p>
B	 <p>Standby control signal</p>	<p>Oscillation circuit</p> <p>Low-speed oscillation feedback resistance : approx. 10 MΩ</p>
C	 <p>Pull-up resistor</p> <p>CMOS hysteresis input</p>	<p>Input-only pin (with pull-up resistance)</p> <ul style="list-style-type: none"> Attached pull-up resistor : approx. 50 kΩ CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$)
D	 <p>CMOS hysteresis input</p>	<p>Input-only pin</p> <ul style="list-style-type: none"> CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) <p>Note: The MD2 pin of the Flash memory products uses this circuit type.</p>

(Continued)

Type	Circuit	Remarks
K		<p>A/D converter input common general-purpose port (serial input)</p> <ul style="list-style-type: none"> • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • CMOS input (SIN) ($V_{IH}/V_{IL} = 0.7 V_{CC}/0.3 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)
L		<p>High current output port (SMC pin) CMOS output ($I_{OH}/I_{OL} = \pm 30 \text{ mA}$)</p>
M		<p>LCDC output common general-purpose port (serial input)</p> <ul style="list-style-type: none"> • CMOS output ($I_{OH}/I_{OL} = \pm 4 \text{ mA}$) • CMOS hysteresis input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.2 V_{CC}$) • CMOS input (SIN) ($V_{IH}/V_{IL} = 0.7 V_{CC}/0.3 V_{CC}$) • Automotive input ($V_{IH}/V_{IL} = 0.8 V_{CC}/0.5 V_{CC}$)

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■ I/O MAP

Address	Register name	Symbol	Read/write	Resource name	Initial value
000000 _H	Port 0 data register	PDR0	R/W	Port 0	XXXXXXXX _B
000001 _H	Port 1 data register	PDR1	R/W	Port 1	XXXXXXXX _B
000002 _H	Port 2 data register	PDR2	R/W	Port 2	XXXXXXXX _B
000003 _H	Port 3 data register	PDR3	R/W	Port 3	XXXXXXXX _B
000004 _H	Port 4 data register	PDR4	R/W	Port 4	XXXXXXXX _B
000005 _H	Port 5 data register	PDR5	R/W	Port 5	XXXXXXXX _B
000006 _H	Port 6 data register	PDR6	R/W	Port 6	XXXXXXXX _B
000007 _H	Port 7 data register	PDR7	R/W	Port 7	XXXXXXXX _B
000008 _H	Port 8 data register	PDR8	R/W	Port 8	XXXXXXXX _B
000009 _H	Port 9 data register	PDR9	R/W	Port 9	XXXXXXXX _B
00000A _H , 00000B _H	(Disabled)				
00000C _H	Port C data register	PDRC	R/W	Port C	XXXXXXXX _B
00000D _H	Port D data register	PDRD	R/W	Port D	XXXXXXXX _B
00000E _H	Port E data register	PDRE	R/W	Port E	XXXXXXXX _B
00000F _H	(Disabled)				
000010 _H	Port 0 direction register	DDR0	R/W	Port 0	00000000 _B
000011 _H	Port 1 direction register	DDR1	R/W	Port 1	XX000000 _B
000012 _H	Port 2 direction register	DDR2	R/W	Port 2	000000XX _B
000013 _H	Port 3 direction register	DDR3	R/W	Port 3	00000000 _B
000014 _H	Port 4 direction register	DDR4	R/W	Port 4	00000000 _B
000015 _H	Port 5 direction register	DDR5	R/W	Port 5	00000000 _B
000016 _H	Port 6 direction register	DDR6	R/W	Port 6	00000000 _B
000017 _H	Port 7 direction register	DDR7	R/W	Port 7	00000000 _B
000018 _H	Port 8 direction register	DDR8	R/W	Port 8	00000000 _B
000019 _H	Port 9 direction register	DDR9	R/W	Port 9	X0000000 _B
00001A _H	Analog input enable	ADER6	R/W	Port 6, A/D	11111111 _B
00001B _H	(Disabled)				
00001C _H	Port C direction register	DDRC	R/W	Port C	00000000 _B
00001D _H	Port D direction register	DDRD	R/W	Port D	X0000000 _B
00001E _H	Port E direction register	DDRE	R/W	Port E	XXXXX000 _B
00001F _H	(Disabled)				
000020 _H	Lower A/D control status register	ADCS0	R/W	A/D converter	000XXXX0 _B
000021 _H	Higher A/D control status register	ADCS1	R/W		0000000X _B
000022 _H	Lower A/D control status register	ADCR0	R		00000000 _B
000023 _H	Higher A/D data register	ADCR1	R		XXXXXX00 _B

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MB90920 Series

Address	Register name	Symbol	Read/write	Resource name	Initial value
000083 _H	(Disabled)				
000084 _H	PWM control register 2	PWC2	R/W	Stepping motor controller 2	000000X0 _B
000085 _H	(Disabled)				
000086 _H	PWM control register 3	PWC3	R/W	Stepping motor controller 3	000000X0 _B
000087 _H	(Disabled)				
000088 _H	LCD output control register 3	LOCR3	R/W	LCDC	XXXXXX111 _B
000089 _H	(Disabled)				
00008A _H	A/D setting register 0	ADSR0	R/W	A/D converter	00000000 _B
00008B _H	A/D setting register 1	ADSR1	R/W		00000000 _B
00008C _H	Port input level select 0	PIL0	R/W	Port input level select	00000000 _B
00008D _H	Port input level select 1	PIL1	R/W		XXXX0000 _B
00008E _H	Port input level select 2	PIL2	R/W		XXXX0000 _B
00008F _H to 00009D _H	(Disabled)				
00009E _H	Program address detection control register	PACSR	R/W	Address match detection	XXXX0X0X _B
00009F _H	Delayed Interrupt/Release Register	DIRR	R/W	Delay interrupt	XXXXXXXX0 _B
0000A0 _H	Power saving mode control register	LPMCR	R/W	Power saving control circuit	00011000 _B
0000A1 _H	Clock select register	CKSCR	R/W, R		11111100 _B
0000A2 _H to 0000A7 _H	(Disabled)				
0000A8 _H	Watchdog timer control register	WDTC	R, W	Watchdog timer	XXXXXX111 _B
0000A9 _H	Time-base timer control register	TBTC	R/W, W	Time-base timer	1XX00100 _B
0000AA _H	Watch timer control register	WTC	R/W, W, R	Watch timer (sub clock)	10001000 _B
0000AB _H to 0000AD _H	(Disabled)				
0000AE _H	Flash memory control status register	FMCS	R/W	Flash interface	000X0000 _B
0000AF _H	(Disabled)				

(Continued)

Address	Register name	Symbol	Read/write	Resource name	Initial value
0000B0 _H	Interrupt control register 00	ICR00	R/W	Interrupt controller	00000111 _B
0000B1 _H	Interrupt control register 01	ICR01	R/W		00000111 _B
0000B2 _H	Interrupt control register 02	ICR02	R/W		00000111 _B
0000B3 _H	Interrupt control register 03	ICR03	R/W		00000111 _B
0000B4 _H	Interrupt control register 04	ICR04	R/W		00000111 _B
0000B5 _H	Interrupt control register 05	ICR05	R/W		00000111 _B
0000B6 _H	Interrupt control register 06	ICR06	R/W		00000111 _B
0000B7 _H	Interrupt control register 07	ICR07	R/W		00000111 _B
0000B8 _H	Interrupt control register 08	ICR08	R/W		00000111 _B
0000B9 _H	Interrupt control register 09	ICR09	R/W		00000111 _B
0000BA _H	Interrupt control register 10	ICR10	R/W		00000111 _B
0000BB _H	Interrupt control register 11	ICR11	R/W		00000111 _B
0000BC _H	Interrupt control register 12	ICR12	R/W		00000111 _B
0000BD _H	Interrupt control register 13	ICR13	R/W		00000111 _B
0000BE _H	Interrupt control register 14	ICR14	R/W		00000111 _B
0000BF _H	Interrupt control register 15	ICR15	R/W		00000111 _B
0000C0 _H to 0000C3 _H	(Disabled)				
0000C4 _H	Serial mode register 1	SMR1	R/W, W	UART (LIN/SCI) 1	00000000 _B
0000C5 _H	Serial control register 1	SCR1	R/W, W		00000000 _B
0000C6 _H	Reception/transmission data register 1	RDR1/ TDR1	R/W		00000000 _B
0000C7 _H	Serial status register 1	SSR1	R/W, R		00001000 _B
0000C8 _H	Extended communication control register 1	ECCR1	R/W, R		000000XX _B
0000C9 _H	Extended status control register 1	ESCR1	R/W		00000100 _B
0000CA _H	Baud rate generator register 10	BGR10	R/W		00000000 _B
0000CB _H	Baud rate generator register 11	BGR11	R/W, R		00000000 _B
0000CC _H	Lower watch timer control register	WTCRL	R/W	Real-time watch timer	000XXXX0 _B
0000CD _H	Middle watch timer control register	WTCRM	R/W		00000000 _B
0000CE _H	Higher watch timer control register	WTCRH	R/W		XXXXXX00 _B
0000CF _H	Sub clock control register	PSCCR	W	Sub clock	XXXX0000 _B
0000D0 _H	Input capture control status 4/5	ICS45	R/W	Input capture 4/5	00000000 _B
0000D1 _H	Input capture edge register 4/5	ICE45	R/W, R		XXXXXXXX _B
0000D2 _H	Input capture control status 6/7	ICS67	R/W	Input capture 6/7	00000000 _B
0000D3 _H	Input capture edge register 6/7	ICE67	R/W, R		XXX0X0XX _B

(Continued)

Address	Register name	Symbol	Read/write	Resource name	Initial value
003970 _H to 003973 _H	(Disabled)				
003974 _H	Frequency data register 1	SGFR1	R/W	Sound generator 1	XXXXXXXX _B
003975 _H	Amplitude data register 1	SGAR1	R/W		00000000 _B
003976 _H	Decrement grade register 1	SGDR1	R/W		XXXXXXXX _B
003977 _H	Tone count register 1	SGTR1	R/W		XXXXXXXX _B
003978 _H to 00397F _H	(Disabled)				
003980 _H	PWM1 compare register 0	PWC10	R/W	Stepping motor controller 0	XXXXXXXX _B
003981 _H					XXXXXXXX _B
003982 _H	PWM2 compare register 0	PWC20	R/W		XXXXXXXX _B
003983 _H					XXXXXXXX _B
003984 _H	PWM1 select register 0	PWS10	R/W		00000000 _B
003985 _H	PWM2 select register 0	PWS20	R/W		X0000000 _B
003986 _H , 003987 _H	(Disabled)				
003988 _H	PWM1 compare register 1	PWC11	R/W	Stepping motor controller 1	XXXXXXXX _B
003989 _H					XXXXXXXX _B
00398A _H	PWM2 compare register 1	PWC21	R/W		XXXXXXXX _B
00398B _H					XXXXXXXX _B
00398C _H	PWM1 select register 1	PWS11	R/W		00000000 _B
00398D _H	PWM2 select register 1	PWS21	R/W		X0000000 _B
00398E _H , 00398F _H	(Disabled)				
003990 _H	PWM1 compare register 2	PWC12	R/W	Stepping motor controller 2	XXXXXXXX _B
003991 _H					XXXXXXXX _B
003992 _H	PWM2 compare register 2	PWC22	R/W		XXXXXXXX _B
003993 _H					XXXXXXXX _B
003994 _H	PWM1 select register 2	PWS12	R/W		00000000 _B
003995 _H	PWM2 select register 2	PWS22	R/W		X0000000 _B
003996 _H , 003997 _H	(Disabled)				

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MB90920 Series

(Continued)

Address	Register name	Symbol	Read/write	Resource name	Initial value
003998 _H	PWM1 compare register 3	PWC13	R/W	Stepping motor controller 3	XXXXXXXX _B
003999 _H					XXXXXXXX _B
00399A _H	PWM2 compare register 3	PWC23	R/W		XXXXXXXX _B
00399B _H					XXXXXXXX _B
00399C _H	PWM1 select register 3	PWS13	R/W		00000000 _B
00399D _H	PWM2 select register 3	PWS23	R/W		X0000000 _B
00399E _H to 0039A5 _H	(Disabled)				
0039A6 _H	Flash write control register 0	FWR0	R/W	Flash I/F	00000000 _B
0039A7 _H	Flash write control register 1	FWR1			00000000 _B
0039A8 _H to 0039BF _H	(Disabled)				
0039C0 _H to 0039DF _H	Area reserved for CAN Controller 2. Refer to “■ CAN CONTROLLERS”				
0039E0 _H to 0039FF _H	Area reserved for CAN Controller 3. Refer to “■ CAN CONTROLLERS”				
003A00 _H to 003AFF _H	Area reserved for CAN Controller 0. Refer to “■ CAN CONTROLLERS”				
003B00 _H to 003BFF _H	Area reserved for CAN Controller 1. Refer to “■ CAN CONTROLLERS”				
003C00 _H to 003CFF _H	Area reserved for CAN Controller 0. Refer to “■ CAN CONTROLLERS”				
003D00 _H to 003DFF _H	Area reserved for CAN Controller 1. Refer to “■ CAN CONTROLLERS”				
003E00 _H to 003EFF _H	Area reserved for CAN Controller 2. Refer to “■ CAN CONTROLLERS”				
003F00 _H to 003FFF _H	Area reserved for CAN Controller 3. Refer to “■ CAN CONTROLLERS”				

■ CAN CONTROLLERS

The CAN controller has the following features :

- Conforms to CAN Specification Version 2.0 Part A and B
 - Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmission/reception message buffers
 - 29-bit ID and 8-byte data
 - Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
 - 2 acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 kbps to 2 Mbps (when input clock is at 16 MHz)

List of Control Registers(1)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003C00 _H	003D00 _H	003E00 _H	003F00 _H	Control status register	CSR	R/W, R	00---000 _B 0----0-1 _B
003C01 _H	003D01 _H	003E01 _H	003F01 _H				
003C02 _H	003D02 _H	003E02 _H	003F02 _H	Last event indicator register	LEIR	R/W	----- _B 000-0000 _B
003C03 _H	003D03 _H	003E03 _H	003F03 _H				
003C04 _H	003D04 _H	003E04 _H	003F04 _H	RX/TX error counter	RTEC	R	00000000 _B 00000000 _B
003C05 _H	003D05 _H	003E05 _H	003F05 _H				
003C06 _H	003D06 _H	003E06 _H	003F06 _H	Bit timing register	BTR	R/W	-1111111 _B 11111111 _B
003C07 _H	003D07 _H	003E07 _H	003F07 _H				

MB90920 Series

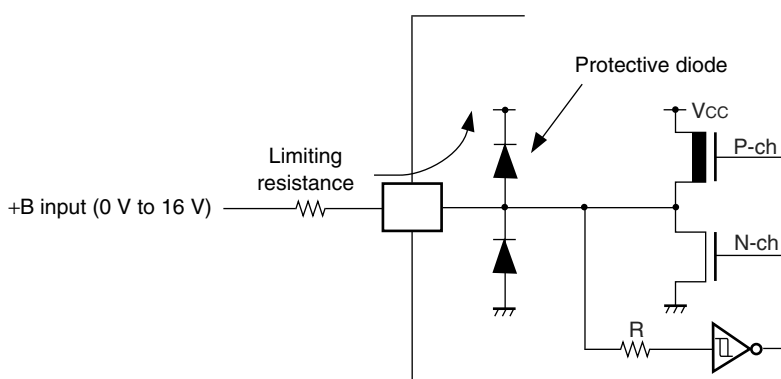
List of Control Registers(2)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
000040 _H	000070 _H	0039C0 _H	0039D0 _H	Message buffer valid register	BVALR	R/W	00000000 _B 00000000 _B
000041 _H	000071 _H	0039C1 _H	0039D1 _H				
000042 _H	000072 _H	0039C2 _H	0039D2 _H	Transmit request register	TREQR	R/W	00000000 _B 00000000 _B
000043 _H	000073 _H	0039C3 _H	0039D3 _H				
000044 _H	000074 _H	0039C4 _H	0039D4 _H	Transmit cancel register	TCANR	W	00000000 _B 00000000 _B
000045 _H	000075 _H	0039C5 _H	0039D5 _H				
000046 _H	000076 _H	0039C6 _H	0039D6 _H	Transmit complete register	TCR	R/W	00000000 _B 00000000 _B
000047 _H	000077 _H	0039C7 _H	0039D7 _H				
000048 _H	000078 _H	0039C8 _H	0039D8 _H	Receive complete register	RCR	R/W	00000000 _B 00000000 _B
000049 _H	000079 _H	0039C9 _H	0039D9 _H				
00004A _H	00007A _H	0039CA _H	0039DA _H	Remote request receive register	RRTRR	R/W	00000000 _B 00000000 _B
00004B _H	00007B _H	0039CB _H	0039DB _H				
00004C _H	00007C _H	0039CC _H	0039DC _H	Receive overrun register	ROVRR	R/W	00000000 _B 00000000 _B
00004D _H	00007D _H	0039CD _H	0039DD _H				
00004E _H	00007E _H	0039CE _H	0039DE _H	Receive interrupt enable register	RIER	R/W	00000000 _B 00000000 _B
00004F _H	00007F _H	0039CF _H	0039DF _H				
003C08 _H	003D08 _H	003E08 _H	003F08 _H	IDE register	IDER	R/W	XXXXXXXX _B
003C09 _H	003D09 _H	003E09 _H	003F09 _H				XXXXXXXX _B
003C0A _H	003D0A _H	003E0A _H	003F0A _H	Transmit RTR register	TRTRR	R/W	00000000 _B
003C0B _H	003D0B _H	003E0B _H	003F0B _H				00000000 _B
003C0C _H	003D0C _H	003E0C _H	003F0C _H	Remote frame receive wait register	RFWTR	R/W	XXXXXXXX _B XXXXXXXX _B
003C0D _H	003D0D _H	003E0D _H	003F0D _H				
003C0E _H	003D0E _H	003E0E _H	003F0E _H	Transmit interrupt enable register	TIER	R/W	00000000 _B 00000000 _B
003C0F _H	003D0F _H	003E0F _H	003F0F _H				
003C10 _H	003D10 _H	003E10 _H	003F10 _H	Acceptance mask select register	AMSR	R/W	XXXXXXXX _B XXXXXXXX _B
003C11 _H	003D11 _H	003E11 _H	003F11 _H				XXXXXXXX _B XXXXXXXX _B
003C12 _H	003D12 _H	003E12 _H	003F12 _H				
003C13 _H	003D13 _H	003E13 _H	003F13 _H				
003C14 _H	003D14 _H	003E14 _H	003F14 _H	Acceptance mask register 0	AMR0	R/W	XXXXXXXX _B XXXXXXXX _B
003C15 _H	003D15 _H	003E15 _H	003F15 _H				XXXXXX--- _B XXXXXXXX _B
003C16 _H	003D16 _H	003E16 _H	003F16 _H				
003C17 _H	003D17 _H	003E17 _H	003F17 _H				
003C18 _H	003D18 _H	003E18 _H	003F18 _H	Acceptance mask register 1	AMR1	R/W	XXXXXXXX _B XXXXXXXX _B
003C19 _H	003D19 _H	003E19 _H	003F19 _H				XXXXXX--- _B XXXXXXXX _B
003C1A _H	003D1A _H	003E1A _H	003F1A _H				
003C1B _H	003D1B _H	003E1B _H	003F1B _H				

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- *5 : Average output current is defined as the average value of the current flowing through any one of the corresponding pins within a period of 100 ms. The “average value” can be calculated by multiplying the “operating current” by the “operating factor”.
- *6 : Average total output current is defined as the average value of the current flowing through all of the corresponding pins within a period of 100 ms. The “average value” can be calculated by multiplying the “operating current” by the “operating factor”.
- *7 :
 - Applicable to pins: P10 to P15, P50 to P57, P60 to P67, P70 to P77, P80 to P87, PC0 to PC7, PD0 to PD6, PE0 to PE2
 - Use within recommended operating conditions.
 - Use at DC voltage (current) .
 - The +B signal should always be applied with a limiting resistance placed between the +B signal and the microcontroller.
 - The value of the limiting resistance should be set so that when the +B signal is applied, the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
 - Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
 - Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the microcontroller may partially malfunction on power supplied through the +B signal pin.
 - Note that if the +B input is applied during power-on, the power supply voltage may reach a level such that the power-on reset does not function due to the power supplied from the +B signal.
 - Care must be taken not to leave +B input pins open.
 - Note that analog system input/output pins (LCD drive pins, comparator input pins, etc.) cannot accept +B signal inputs.
 - Sample recommended circuit :

- Input/output equivalent circuit



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

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($V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = DV_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^\circ\text{C}$ to $+105 \text{ }^\circ\text{C}$)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input leakage current	I_{IL}	All input pins	$V_{CC} = DV_{CC} = AV_{CC} = 5.5 \text{ V}$, $V_{SS} < V_I < V_{CC}$	—	—	10	μA	
Input capacitance 1	C_{IN1}	All pins except V_{CC} , V_{SS} , DV_{CC} , DV_{SS} , AV_{CC} , AV_{SS} , C, P70 to P77, P80 to P87	—	—	—	15	pF	
Input capacitance 2	C_{IN2}	P70 to P77, P80 to P87	—	—	—	45	pF	
Pull-up resistance	R_{UP}	\overline{RST}	—	25	50	100	k Ω	
Pull-down resistance	R_{DOWN}	MD2	—	—	—	100	k Ω	Excluding Flash memory product
General-purpose output “H” voltage	V_{OH1}	All pins except P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OH} = -4.0 \text{ mA}$	$V_{CC} - 0.5$	—	—	V	
Stepping motor output “H” voltage	V_{OH2}	P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OH} = -30.0 \text{ mA}$	$V_{CC} - 0.5$	—	—	V	
General-purpose output “L” voltage	V_{OL1}	All pins except P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OL} = 4.0 \text{ mA}$	—	—	0.4	V	
Stepping motor output “L” voltage	V_{OL2}	P70 to P77, P80 to P87	$V_{CC} = 4.5 \text{ V}$, $I_{OL} = 30.0 \text{ mA}$	—	—	0.55	V	
Stepping motor output phase variation “H”	ΔV_{OH}	PWM1Pn, PWM1Mn, PWM2Pn, PWM2Mn, n = 0 to 3	$V_{CC} = 4.5 \text{ V}$, $I_{OH} = -30.0 \text{ mA}$, maximum deviation V_{OH2}	—	—	90	mV	
Stepping motor output phase variation “L”	ΔV_{OL}	PWM1Pn, PWM1Mn, PWM2Pn, PWM2Mn, n = 0 to 3	$V_{CC} = 4.5 \text{ V}$, $I_{OL} = 30.0 \text{ mA}$, maximum deviation V_{OH2}	—	—	90	mV	
LCD internal divider resistance	R_{LCD}	Between V0 and V1, Between V1 and V2, Between V2 and V3	—	50	100	200	k Ω	Evaluation product
				8.75	12.5	17.0	k Ω	Flash memory product

(Continued)

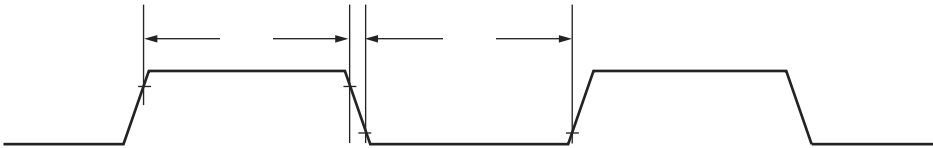
(5) Timer input timing

($V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C}$ to $+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Input pulse width	t_{TIWH} t_{TIWL}	TIN0, TIN1, IN0 to IN3	—	4 t_{CP}	—	ns

Note : t_{CP} is the internal operating clock cycle time. Refer to “(1) Clock timing”.

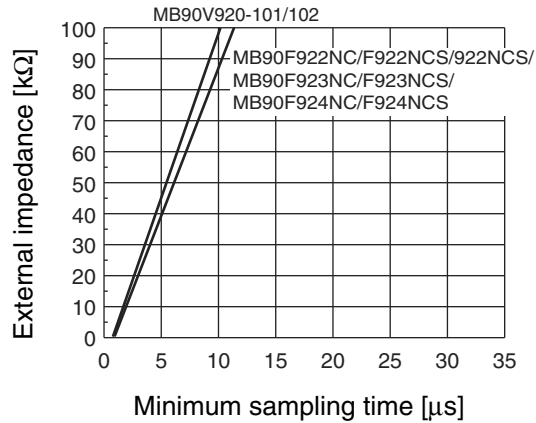
- Timer input timing



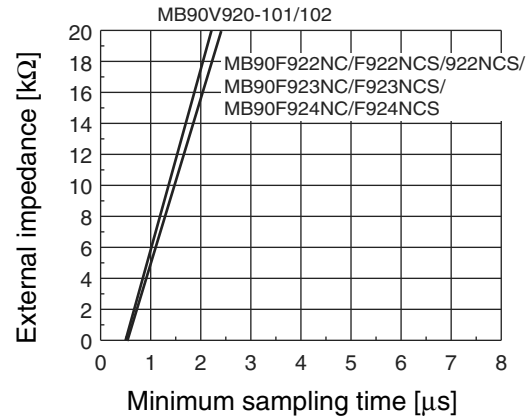
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- The relationship between the external impedance and minimum sampling time
- At $4.5\text{ V} \leq AV_{CC} \leq 5.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)

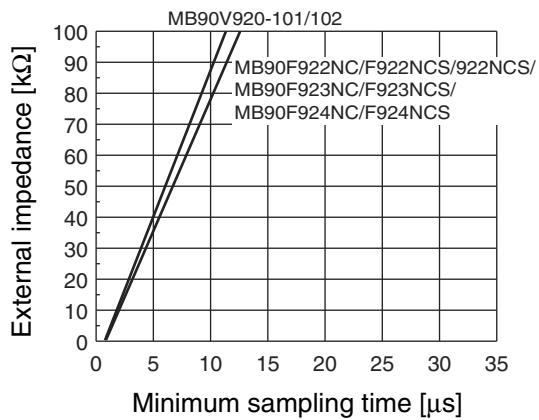


(External impedance = 0 k Ω to 20 k Ω)

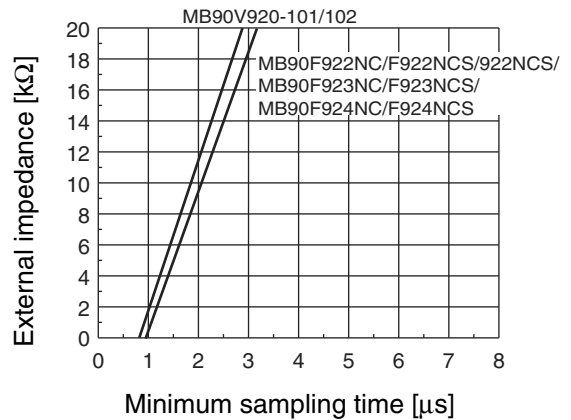


- At $4.0\text{ V} \leq AV_{CC} \leq 4.5\text{ V}$

(External impedance = 0 k Ω to 100 k Ω)



(External impedance = 0 k Ω to 20 k Ω)



- About errors

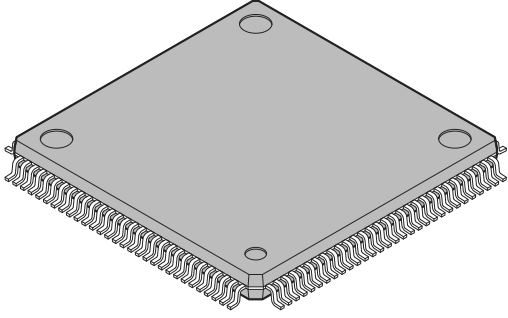
As $|AV_{RH} - AV_{SS}|$ becomes smaller, the relative errors grow larger.

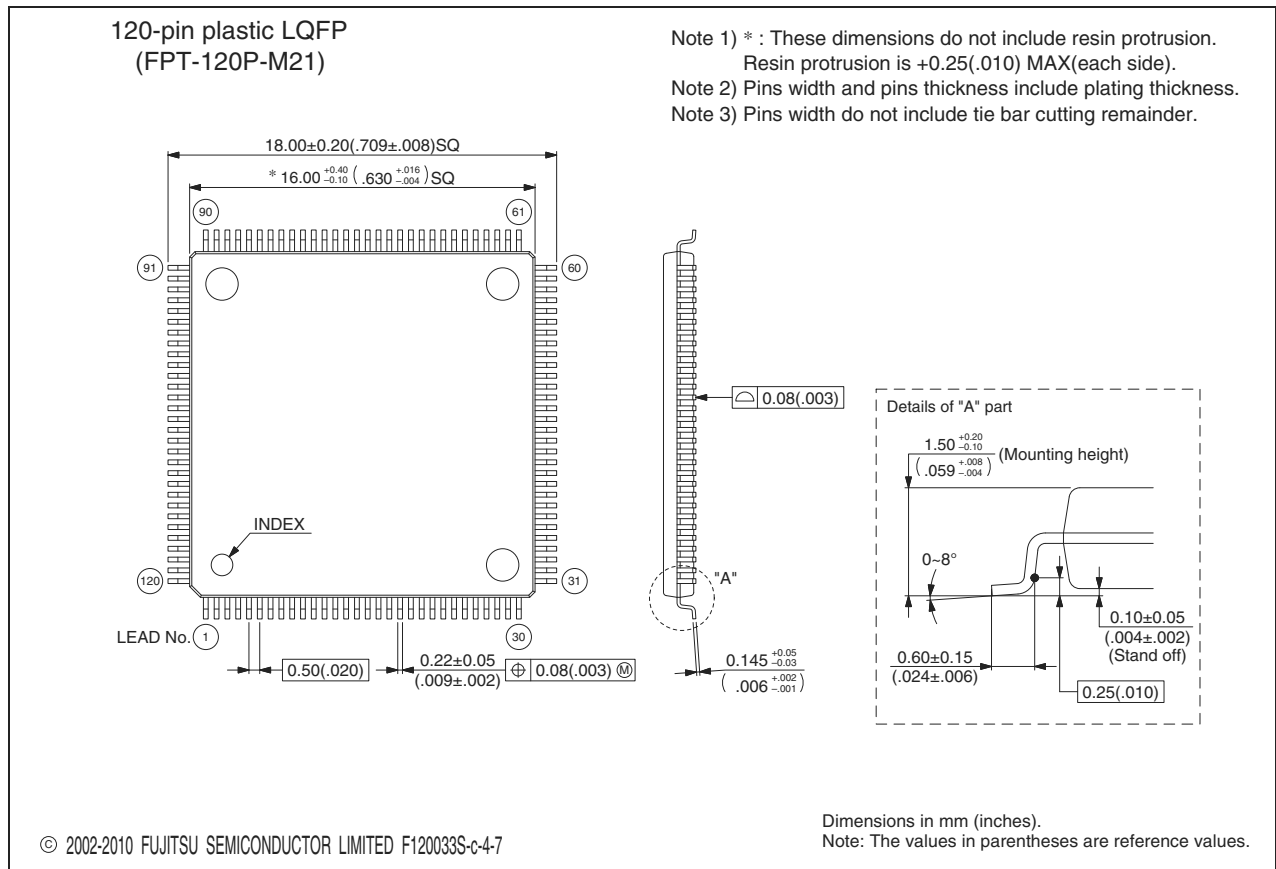
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■ ORDERING INFORMATION

Part number	Package	Remarks
MB90F922NCPMC MB90F922NCSPMC MB90922NCSPMC MB90F923NCPMC MB90F923NCSPMC MB90F924NCPMC MB90F924NCSPMC	120-pin plastic LQFP (FPT-120P-M21)	
MB90V920-101CR MB90V920-102CR	299-pin ceramic PGA (PGA-299C-A01)	For evaluation

■ PACKAGE DIMENSION

 <p>120-pin plastic LQFP</p> <p>(FPT-120P-M21)</p>	Lead pitch	0.50 mm
	Package width × package length	16.0 × 16.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	0.88 g
	Code (Reference)	P-LFQFP120-16×16-0.50



Please check the latest package dimension at the following URL.
<http://edevic.fujitsu.com/package/en-search/>

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■ MAJOR CHANGES IN THIS EDITION

Page	Section	Change Results
12	■ I/O CIRCUIT TYPE	Corrected the circuit type B.
20	■ HANDLING DEVICES	Added the following items; <ul style="list-style-type: none">• Serial communication• Characteristic difference between flash device and MASK ROM device
31	■ I/O MAP	Corrected “Address: 003970 _H ”. Clock supervisor control register → (Disabled)
46	■ ELECTRICAL CHARACTERISTICS 3. DC Characteristics	Added the item for “LCD output impedance”.
68	■ ORDERING INFORMATION	Corrected the part numbers; MB90V920-101 → MB90V920-101CR MB90V920-102 → MB90V920-102CR

The vertical lines marked in the left side of the page show the changes.

MEMO

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