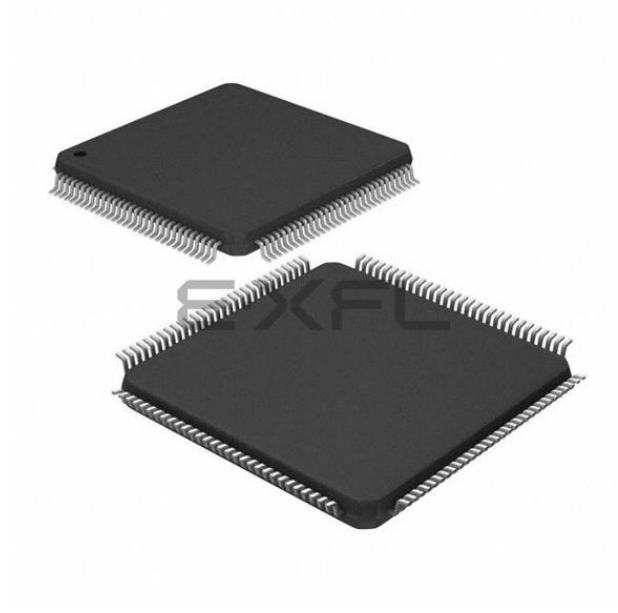
Infineon Technologies - MB90922NCSPMC-GS-238E1 Datasheet



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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-238e1

■ PRODUCT LINEUP

Part number / Parameter	MB90 F922NC	MB90 F922NCS	MB90 F923NC	MB90 F923NCS	MB90 F924NC	MB90 F924NCS	MB90 922NCS	MB90 V920-101	MB90 V920-102
Type	Flash memory product						MASK ROM product	Evaluation product	
CPU	F^2MC-16LX CPU								
System clock	PLL clock multiplier circuit (× 1, × 2, × 3, × 4, × 8, 1/2 when PLL stopped) Minimum instruction execution time 31.25 ns (with 4 MHz oscillation clock × 8)								
Sub clock pins (X0A, X1A)	Yes	No	Yes	No	Yes	No	No	No	Yes
ROM	Flash memory 256 Kbytes		Flash memory 384 Kbytes		Flash memory 512 Kbytes		256 K bytes	External	
RAM	10 Kbytes		16 Kbytes		24 Kbytes		10 K bytes	30 Kbytes	
I/O port	91 ports	93 ports	91 ports	93 ports	91 ports	93 ports	93 ports	93 ports	91 ports
LCD controller	32 segment × 4 common								
LIN-UART	UART (LIN/SCI) 4 channels								
CAN interface	4 channels								
16-bit input capture	8 channels								
16-bit reload timer	4 channels								
16-bit free-run timer	1 channel								
Real time watch timer	1 channel								
16-bit PPG timer	6 channels								
External interrupt	8 channels								
8/10-bit A/D converter	8 channels								
Low-voltage/ CPU operating detection reset	Yes							No	
Stepping motor controller	4 channels								
Sound generator	2 channels								
Flash memory security	Yes						—		
Operating voltage	4.0 V to 5.5 V							4.5 V to 5.5 V	
Package	LQFP-120							PGA-299	

■ PIN DESCRIPTIONS

Pin no.	Pin name	I/O circuit type*1	Function
108	X0	A	High-speed oscillation input pin
107	X1		High-speed oscillation output pin
13	X0A	B	Low-speed oscillation input pin
	P92	I	General-purpose I/O port
14	X1A	B	Low-speed oscillation output pin
	P93	I	General-purpose I/O port
90	$\overline{\text{RST}}$	C	Reset input pin
93	P00	F	General-purpose I/O port
	SEG24		LCD controller/driver segment output pin
94	P01	F	General-purpose I/O port
	SEG25		LCD controller/driver segment output pin
95	P02	F	General-purpose I/O port
	SEG26		LCD controller/driver segment output pin
96	P03	F	General-purpose I/O port
	SEG27		LCD controller/driver segment output pin
97	P04	F	General-purpose I/O port
	SEG28		LCD controller/driver segment output pin
98	P05	F	General-purpose I/O port
	SEG29		LCD controller/driver segment output pin
99	P06	F	General-purpose I/O port
	SEG30		LCD controller/driver segment output pin
100	P07	F	General-purpose I/O port
	SEG31		LCD controller/driver segment output pin
101	P10	I	General-purpose I/O port
	PPG2		16-bit PPG ch.2 output pin
	IN5		Input capture ch.5 trigger input pin
102	P11	I	General-purpose I/O port
	TOT0		16-bit reload timer ch.0 TOT output pin
	PPG3		16-bit PPG ch.3 output pin
	IN4		Input capture ch.4 trigger input pin
103	P12	I	General-purpose I/O port
	TIN0		16-bit reload timer ch.0 TIN input pin
	PPG4		16-bit PPG ch.4 output pin

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Pin no.	Pin name	I/O circuit type*1	Function
7	P36	F	General-purpose I/O port
	SEG12		LCD controller/driver segment output pin
8	P37	F	General-purpose I/O port
	SEG13		LCD controller/driver segment output pin
9	P40	F	General-purpose I/O port
	SEG14		LCD controller/driver segment output pin
10	P41	F	General-purpose I/O port
	SEG15		LCD controller/driver segment output pin
11	P42	F	General-purpose I/O port
	SEG16		LCD controller/driver segment output pin
12	P43	F	General-purpose I/O port
	SEG17		LCD controller/driver segment output pin
18	P44	F	General-purpose I/O port
	SEG18		LCD controller/driver segment output pin
19	P45	F	General-purpose I/O port
	SEG19		LCD controller/driver segment output pin
20	P46	F	General-purpose I/O port
	SEG20		LCD controller/driver segment output pin
21	P47	F	General-purpose I/O port
	SEG21		LCD controller/driver segment output pin
37	P50	I	General-purpose I/O port
	INT0		INT0 external interrupt input pin
	ADTG		A/D converter external trigger input pin
58	P51	I	General-purpose I/O port
	INT1		INT1 external interrupt input pin
	RX1		CAN interface 1 RX input pin
	RX3		CAN interface 3 RX input pin
59	P52	I	General-purpose I/O port
	TX1		CAN interface 1 TX output pin
	TX3		CAN interface 3 TX output pin
60	P53	I	General-purpose I/O port
	INT3		INT3 external interrupt input pin

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Pin no.	Pin name	I/O circuit type*1	Function
70	P73	L	General-purpose output-only port
	PWM2M0		Stepping motor controller ch.0 output pin
71	P74	L	General-purpose output-only port
	PWM1P1		Stepping motor controller ch.1 output pin
72	P75	L	General-purpose output-only port
	PWM1M1		Stepping motor controller ch.1 output pin
73	P76	L	General-purpose output-only port
	PWM2P1		Stepping motor controller ch.1 output pin
74	P77	L	General-purpose output-only port
	PWM2M1		Stepping motor controller ch.1 output pin
77	P80	L	General-purpose output-only port
	PWM1P2		Stepping motor controller ch.2 output pin
78	P81	L	General-purpose output-only port
	PWM1M2		Stepping motor controller ch.2 output pin
79	P82	L	General-purpose output-only port
	PWM2P2		Stepping motor controller ch.2 output pin
80	P83	L	General-purpose output-only port
	PWM2M2		Stepping motor controller ch.2 output pin
81	P84	L	General-purpose output-only port
	PWM1P3		Stepping motor controller ch.3 output pin
82	P85	L	General-purpose output-only port
	PWM1M3		Stepping motor controller ch.3 output pin
83	P86	L	General-purpose output-only port
	PWM2P3		Stepping motor controller ch.3 output pin
84	P87	L	General-purpose output-only port
	PWM2M3		Stepping motor controller ch.3 output pin
22	P90	F	General-purpose I/O port
	SEG22		LCD controller/driver segment output pin
23	P91	F	General-purpose I/O port
	SEG23		LCD controller/driver segment output pin
31	P94	G	General-purpose I/O port
	V0		LCD controller/driver reference power supply pin
32	P95	G	General-purpose I/O port
	V1		LCD controller/driver reference power supply pin

(Continued)

Pin no.	Pin name	I/O circuit type*1	Function
33	P96	G	General-purpose I/O port
	V2		LCD controller/driver reference power supply pin
34	V3	—	LCD controller/driver reference power supply pin
48	PC0	J	General-purpose I/O port
	SIN0		UART ch.0 serial data input pin
	INT4		INT4 external interrupt input pin
49	PC1	I	General-purpose I/O port
	SOT0		UART ch.0 serial data output pin
	INT5		INT5 external interrupt input pin
	IN3		Input capture ch.3 trigger input pin
50	PC2	I	General-purpose I/O port
	SCK0		UART ch.0 serial clock I/O pin
	INT6		INT6 external interrupt input pin
	IN2		Input capture ch.2 trigger input pin
51	PC3	J	General-purpose I/O port
	SIN1		UART ch.1 serial data input pin
	INT7		INT7 external interrupt input pin
52	PC4	I	General-purpose I/O port
	SOT1		UART ch.1 serial data output pin
53	PC5	I	General-purpose I/O port
	SCK1		UART ch.1 serial clock I/O pin
	TRG		16-bit PPG ch.0 to ch.5 external trigger input pin
54	PC6	I	General-purpose I/O port
	PPG0		16-bit PPG ch.0 output pin
	TOT1		16-bit reload timer ch.1 TOT output pin
	IN7		Input capture ch.7 trigger input pin
55	PC7	I	General-purpose I/O port
	PPG1		16-bit PPG ch.1 output pin
	TIN1		16-bit reload timer ch.1 TIN input pin
	IN6		Input capture ch.6 trigger input pin
24	PD0	J	General-purpose I/O port
	SIN2		UART ch.2 serial data input pin
25	PD1	I	General-purpose I/O port
	SOT2		UART ch.2 serial data output pin

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Pin no.	Pin name	I/O circuit type*1	Function
26	PD2	I	General-purpose I/O port
	SCK2		UART ch.2 serial clock I/O pin
27	PD3	J	General-purpose I/O port
	SIN3		UART ch.3 serial data input pin
28	PD4	I	General-purpose I/O port
	SOT3		UART ch.3 serial data output pin
29	PD5	I	General-purpose I/O port
	SCK3		UART ch.3 serial clock I/O pin
30	PD6	I	General-purpose I/O port
	TOT2		16-bit reload timer ch.2 TOT output pin
56	PE0	I	General-purpose I/O port
	TOT3		16-bit reload timer ch.3 TOT output pin
57	PE1	I	General-purpose I/O port
	TIN3		16-bit reload timer ch.3 TIN input pin
64	PE2	I	General-purpose I/O port
	SGO1		Sound generator ch.1 SGO output pin
62	RSTO	N	Internal reset signal output pin
65, 75, 85	DVCC	—	Power supply input pins dedicated for high current output buffer
66, 76, 86	DVSS	—	Power supply GND pins dedicated for high current output buffer
35	AVCC	—	A/D converter dedicated power supply input pin
38	AVSS	—	A/D converter dedicated power supply GND pin
36	AVRH	—	A/D converter Vref+ input pin. Vref- is fixed to AVSS.
89	MD0	D	Mode setting input pin. Connect to VCC pin.
88	MD1	D	Mode setting input pin. Connect to VCC pin.
87	MD2	D/E*2	Mode setting input pin. Connect to VSS pin.
17	C	—	External capacitor pin. Connect a 0.1 μF capacitor between this pin and the VSS pin.
15, 105	VCC	—	Power supply input pins
16, 47, 106	VSS	—	GND power supply pins

*1 : For I/O circuit type, refer to “ ■ I/O CIRCUIT TYPES”.

*2 : The I/O circuit type is D for Flash memory products and E for evaluation products.

■ HANDLING DEVICES

• Strictly observe maximum rated voltages (preventing latch-up)

In CMOS IC devices, a condition known as latch-up may occur if voltages higher than V_{CC} or lower than V_{SS} are applied to input or output pins other than medium or high withstand voltage pins, or if the voltage applied between VCC and VSS pins exceeds the rated voltage level. If a latch-up occurs, the power supply current may increase dramatically and may destroy semiconductor elements. When using semiconductor devices, always take sufficient care to avoid exceeding maximum ratings.

When the analog system power supply is switched on or off, be careful not to apply the analog power supply (AV_{CC}, AVRH), the analog input voltages and the power supply voltage for the high current output buffer pins (DV_{CC}) in excess of the digital power supply voltage (V_{CC}).

Once the digital power supply voltage (V_{CC}) has been disconnected, the analog power supply (AV_{CC}, AVRH) and the power supply voltage for the high current output buffer pins (DV_{CC}) may be turned on in any sequence.

• Supply voltage stabilization

Rapid fluctuations in the power supply voltage can cause malfunctions even if the Vcc power supply voltage remains within the warranted operating range. It is recommended that the power supply be stabilized such that ripple fluctuations (P-P value) at commercial frequencies (50 Hz/60 Hz) be limited to within 10% of the standard V_{CC} value, and that transient fluctuations due to power supply switching, etc. be limited to a rate of 0.1 V/ms or less.

• Precautions when turning the power on

In order to prevent the built-in step-down circuits from malfunctioning, the time taken for the voltage to rise (0.2 V to 2.7 V) during power-on should be less than 50 μs.

• Handling unused pins

If unused input pins are left open, they may cause malfunctions or latch-up which may lead to permanent damage to the semiconductor. Unused input pins should therefore be pulled up or pulled down through a resistor of at least 2 kΩ.

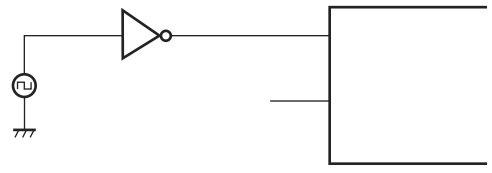
Unused input/output pins may be set to the output state and left open, or set to the input state and connected to a pull-up or pull-down resistance of 2 kΩ or more.

• Handling A/D converter power supply pins

Even if the A/D converter is not used, the power supply pins should be connected such as $AV_{CC} = V_{CC}$, and $AV_{SS} = AVRH = V_{SS}$.

• Notes on using an external clock

Even when an external clock is used, an oscillation stabilization wait time is required following power-on reset or release from sub clock mode or stop mode. Furthermore, only the X0A pin should be driven when an external clock is used, with the X1A pin open as shown in the following diagram. Do not use high-speed oscillation pins (X0 and X1) for external clock input.



Sample external clock connection

- **Serial communication**

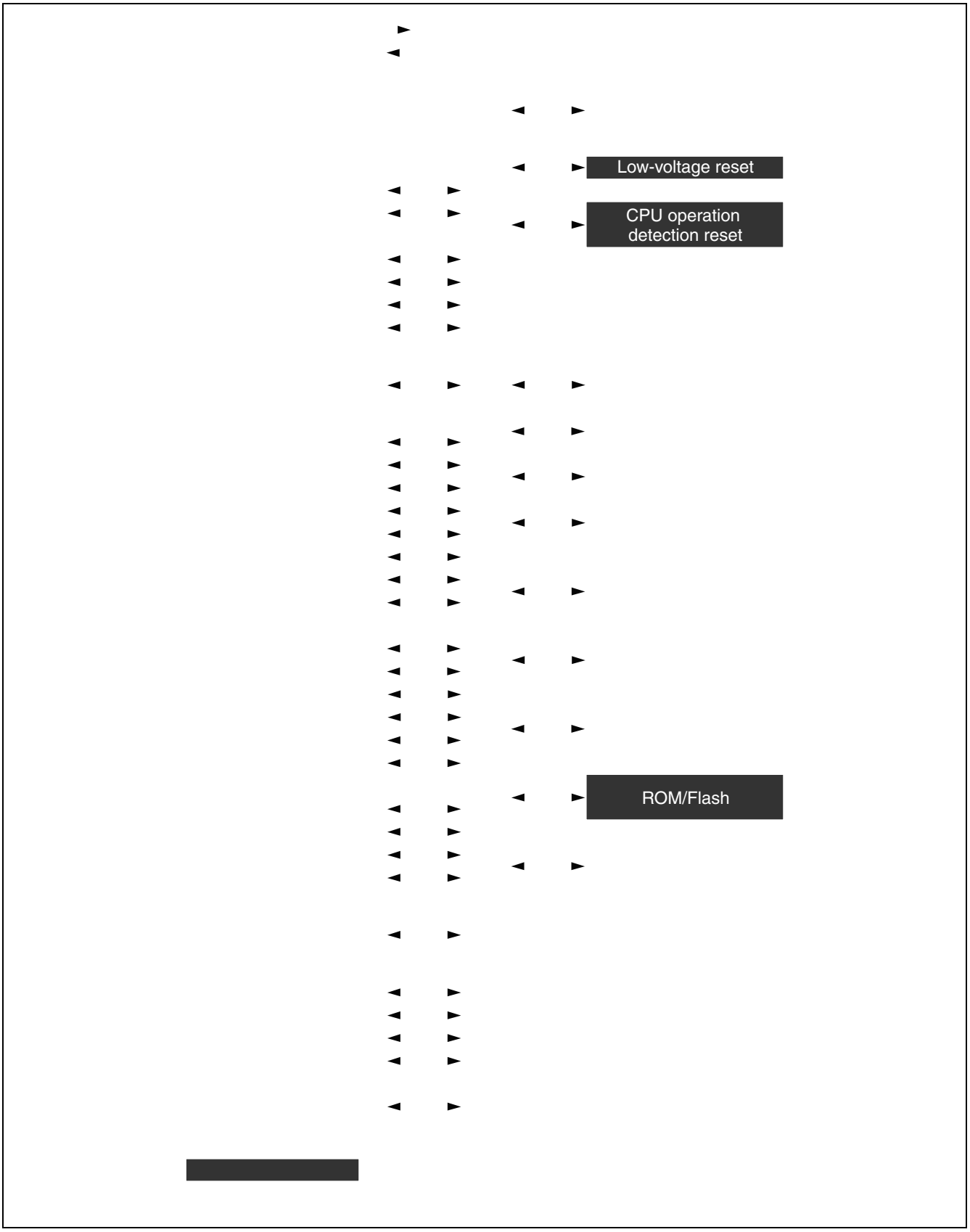
In serial communication, reception of wrong data may occur due to noise or other causes. Therefore, design a printed circuit board to prevent noise from occurring. Taking account of the reception of wrong data, detect errors by measures such as adding a checksum to the end of data. If an error is detected, retransmit the data.

- **Characteristic difference between flash device and MASK ROM device**

In the flash device and the MASK ROM device, the electrical characteristic including current consumption, ESD, latch-up, the noise characteristic, and oscillation characteristic, etc. is different according to the difference between the chip layout and the memory structure.

Reconfirm the electrical characteristic when the product is replaced by another product of the same series.

■ BLOCK DIAGRAM



■ I/O MAP

Address	Register name	Symbol	Read/write	Resource name	Initial value
000000H	Port 0 data register	PDR0	R/W	Port 0	XXXXXXXXB
000001H	Port 1 data register	PDR1	R/W	Port 1	XXXXXXXXB
000002H	Port 2 data register	PDR2	R/W	Port 2	XXXXXXXXB
000003H	Port 3 data register	PDR3	R/W	Port 3	XXXXXXXXB
000004H	Port 4 data register	PDR4	R/W	Port 4	XXXXXXXXB
000005H	Port 5 data register	PDR5	R/W	Port 5	XXXXXXXXB
000006H	Port 6 data register	PDR6	R/W	Port 6	XXXXXXXXB
000007H	Port 7 data register	PDR7	R/W	Port 7	XXXXXXXXB
000008H	Port 8 data register	PDR8	R/W	Port 8	XXXXXXXXB
000009H	Port 9 data register	PDR9	R/W	Port 9	XXXXXXXXB
00000AH, 00000BH	(Disabled)				
00000CH	Port C data register	PDRC	R/W	Port C	XXXXXXXXB
00000DH	Port D data register	PDRD	R/W	Port D	XXXXXXXXB
00000EH	Port E data register	PDRE	R/W	Port E	XXXXXXXXB
00000FH	(Disabled)				
000010H	Port 0 direction register	DDR0	R/W	Port 0	00000000B
000011H	Port 1 direction register	DDR1	R/W	Port 1	XX000000B
000012H	Port 2 direction register	DDR2	R/W	Port 2	000000XXB
000013H	Port 3 direction register	DDR3	R/W	Port 3	00000000B
000014H	Port 4 direction register	DDR4	R/W	Port 4	00000000B
000015H	Port 5 direction register	DDR5	R/W	Port 5	00000000B
000016H	Port 6 direction register	DDR6	R/W	Port 6	00000000B
000017H	Port 7 direction register	DDR7	R/W	Port 7	00000000B
000018H	Port 8 direction register	DDR8	R/W	Port 8	00000000B
000019H	Port 9 direction register	DDR9	R/W	Port 9	X0000000B
00001AH	Analog input enable	ADER6	R/W	Port 6, A/D	11111111B
00001BH	(Disabled)				
00001CH	Port C direction register	DDRC	R/W	Port C	00000000B
00001DH	Port D direction register	DDRD	R/W	Port D	X0000000B
00001EH	Port E direction register	DDRE	R/W	Port E	XXXXX000B
00001FH	(Disabled)				
000020H	Lower A/D control status register	ADCS0	R/W	A/D converter	000XXXX0B
000021H	Higher A/D control status register	ADCS1	R/W		0000000XB
000022H	Lower A/D control status register	ADCR0	R		00000000B
000023H	Higher A/D data register	ADCR1	R		XXXXXX00B

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Address	Register name	Symbol	Read/write	Resource name	Initial value
000024H	Compare clear register	CPCLR	R/W	16-bit free-run timer	XXXXXXXXB
000025H			R/W		XXXXXXXXB
000026H	Timer data register	TCDT	R/W		00000000B
000027H			R/W		00000000B
000028H	Lower timer control status register	TCCSL	R/W		00000000B
000029H	Higher timer control status register	TCCSH	R/W		01-00000B
00002AH	Lower PPG0 control status register	PCNTL0	R/W	16-bit PPG0	00000000B
00002BH	Higher PPG0 control status register	PCNTH0	R/W		00000001B
00002CH	Lower PPG1 control status register	PCNTL1	R/W	16-bit PPG1	00000000B
00002DH	Higher PPG1 control status register	PCNTH1	R/W		00000001B
00002EH	Lower PPG2 control status register	PCNTL2	R/W	16-bit PPG2	00000000B
00002FH	Higher PPG2 control status register	PCNTH2	R/W		00000001B
000030H	External interrupt enable	ENIR	R/W	External interrupt	00000000B
000031H	External interrupt request	EIRR	R/W		00000000B
000032H	Lower external interrupt level	ELVRL	R/W		00000000B
000033H	Higher external interrupt level	ELVRH	R/W		00000000B
000034H	Serial mode register 0	SMR0	R/W, W	UART (LIN/SCI) 0	00000000B
000035H	Serial control register 0	SCR0	R/W, W		00000000B
000036H	Reception/transmission data register 1	RDR0/ TDR0	R/W		00000000B
000037H	Serial status register 0	SSR0	R/W, R		00001000B
000038H	Extended communication control register 0	ECCR0	R/W, R		000000XXB
000039H	Extended status control register 0	ESCR0	R/W		00000100B
00003AH	Baud rate generator register 00	BGR00	R/W		00000000B
00003BH	Baud rate generator register 01	BGR01	R/W, R		00000000B
00003CH to 00003FH	(Disabled)				
000040H to 00004FH	Area reserved for CAN Controller 0. Refer to "■ CAN CONTROLLERS"				
000050H	Lower timer control status register 0	TMCSR0L	R/W	16-bit reload timer 0	00000000B
000051H	Higher timer control status register 0	TMCSR0H	R/W		XXX10000B
000052H	Timer register 0/reload register 0	TMR0/ TMRLR0	R/W		XXXXXXXXB
000053H					XXXXXXXXB

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Address	Register name	Symbol	Read/write	Resource name	Initial value
000054H	Lower timer control status register 1	TMCSR1L	R/W	16-bit reload timer 1	00000000B
000055H	Higher timer control status register 1	TMCSR1H	R/W		XXX10000B
000056H	Timer register 1/reload register 1	TMR1/ TMRLR1	R/W		XXXXXXXXB
000057H					XXXXXXXXB
000058H	LCD output control register 1	LOCR1	R/W	LCDC	11111111B
000059H	LCD output control register 2	LOCR2	R/W		00000000B
00005AH	Lower sound control register 0	SGCRL0	R/W	Sound generator 0	00000000B
00005BH	Higher sound control register 0	SGCRH0	R/W		0XXXX100B
00005CH	Frequency data register 0	SGFR0	R/W		XXXXXXXXB
00005DH	Amplitude data register 0	SGAR0	R/W		00000000B
00005EH	Decrement grade register 0	SGDR0	R/W		XXXXXXXXB
00005FH	Tone count register 0	SGTR0	R/W		XXXXXXXXB
000060H	Input capture register 0	IPCP0	R	Input capture 0/1	XXXXXXXXB
000061H					XXXXXXXXB
000062H	Input capture register 1	IPCP1	R		XXXXXXXXB
000063H					XXXXXXXXB
000064H	Input capture register 2	IPCP2	R	Input capture 2/3	XXXXXXXXB
000065H					XXXXXXXXB
000066H	Input capture register 3	IPCP3	R		XXXXXXXXB
000067H					XXXXXXXXB
000068H	Input capture control status 0/1	ICS01	R/W	Input capture 0/1	00000000B
000069H	Input capture edge register 0/1	ICE01	R/W		XXX0X0XXB
00006AH	Input capture control status 2/3	ICS23	R/W	Input capture 2/3	00000000B
00006BH	Input capture edge register 2/3	ICE23	R/W		XXXXXXXXB
00006CH	Lower LCD control register	LCRL	R/W	LCD controller/ driver	00010000B
00006DH	Higher LCD control register	LCRH	R/W		00000000B
00006EH	Low voltage/CPU operation detection reset control register	LVRC	R/W	Low voltage/CPU operation detection reset	00111000B
00006FH	ROM mirror	ROMM	W	ROM mirror	XXXXXXX1B
000070H to 00007FH	Area reserved for CAN Controller 1. Refer to "■ CAN CONTROLLERS"				
000080H	PWM control register 0	PWC0	R/W	Stepping motor controller 0	000000X0B
000081H	(Disabled)				
000082H	PWM control register 1	PWC1	R/W	Stepping motor controller 1	000000X0B

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Address	Register name	Symbol	Read/write	Resource name	Initial value
003700H to 0037FFH	Area reserved for CAN Controller 2. Refer to "■ CAN CONTROLLERS"				
003800H to 0038FFH	Area reserved for CAN Controller 3. Refer to "■ CAN CONTROLLERS"				
003900H to 00391FH	(Disabled)				
003920H	PPG0 down counter register	PDCR0	R	16-bit PPG0	11111111B
003921H					11111111B
003922H	PPG0 cycle setting register	PCSR0	W		11111111B
003923H					11111111B
003924H	PPG0 duty setting register	PDUT0	W	16-bit PPG0	00000000B
003925H					00000000B
003926H	PPG0 output division setting register	PPGDIV0	R/W, R		11111100B
003927H	(Disabled)				
003928H	PPG1 down counter register	PDCR1	R	16-bit PPG1	11111111B
003929H					11111111B
00392AH	PPG1 cycle setting register	PCSR1	W		11111111B
00392BH					11111111B
00392CH	PPG1 duty setting register	PDUT1	W		00000000B
00392DH					00000000B
00392EH	PPG1output division setting register	PPGDIV1	R/W, R		11111100B
00392FH	(Disabled)				
003930H	PPG2 down counter register	PDCR2	R	16-bit PPG2	11111111B
003931H					11111111B
003932H	PPG2 cycle setting register	PCSR2	W		11111111B
003933H					11111111B
003934H	PPG2 duty setting register	PDUT2	W		00000000B
003935H					00000000B
003936H	PPG2 output division setting register	PPGDIV2	R/W, R		11111100B
003937H to 00393FH	(Disabled)				
003940H	Input capture register 4	IPCP4	R	Input capture 4/5	XXXXXXXXB
003941H					XXXXXXXXB
003942H	Input capture register 5	IPCP5	R		XXXXXXXXB
003943H					XXXXXXXXB

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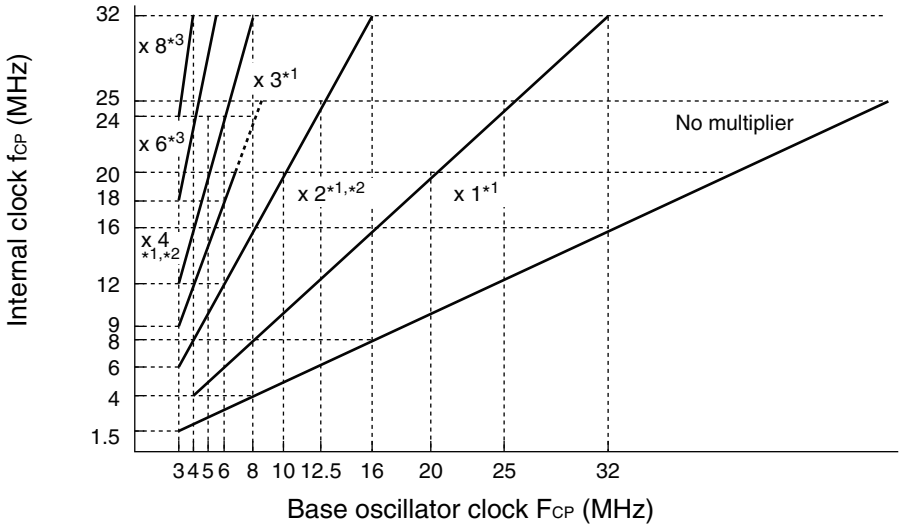
Address				Register	Abbre-viation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A40H	003B40H	003740H	003840H	ID register 8	IDR8	R/W	XXXXXXXXB XXXXXXXXB
003A41H	003B41H	003741H	003841H				
003A42H	003B42H	003742H	003842H				XXXXX---B XXXXXXXXB
003A43H	003B43H	003743H	003843H				
003A44H	003B44H	003744H	003844H	ID register 9	IDR9	R/W	XXXXXXXXB XXXXXXXXB
003A45H	003B45H	003745H	003845H				
003A46H	003B46H	003746H	003846H				XXXXX---B XXXXXXXXB
003A47H	003B47H	003747H	003847H				
003A48H	003B48H	003748H	003848H	ID register 10	IDR10	R/W	XXXXXXXXB XXXXXXXXB
003A49H	003B49H	003749H	003849H				
003A4AH	003B4AH	00374AH	00384AH				XXXXX---B XXXXXXXXB
003A4BH	003B4BH	00374BH	00384BH				
003A4CH	003B4CH	00374CH	00384CH	ID register 11	IDR11	R/W	XXXXXXXXB XXXXXXXXB
003A4DH	003B4DH	00374DH	00384DH				
003A4EH	003B4EH	00374EH	00384EH				XXXXX---B XXXXXXXXB
003A4FH	003B4FH	00374FH	00384FH				
003A50H	003B50H	003750H	003850H	ID register 12	IDR12	R/W	XXXXXXXXB XXXXXXXXB
003A51H	003B51H	003751H	003851H				
003A52H	003B52H	003752H	003852H				XXXXX---B XXXXXXXXB
003A53H	003B53H	003753H	003853H				
003A54H	003B54H	003754H	003854H	ID register 13	IDR13	R/W	XXXXXXXXB XXXXXXXXB
003A55H	003B55H	003755H	003855H				
003A56H	003B56H	003756H	003856H				XXXXX---B XXXXXXXXB
003A57H	003B57H	003757H	003857H				
003A58H	003B58H	003758H	003858H	ID register 14	IDR14	R/W	XXXXXXXXB XXXXXXXXB
003A59H	003B59H	003759H	003859H				
003A5AH	003B5AH	00375AH	00385AH				XXXXX---B XXXXXXXXB
003A5BH	003B5BH	00375BH	00385BH				
003A5CH	003B5CH	00375CH	00385CH	ID register 15	IDR15	R/W	XXXXXXXXB XXXXXXXXB
003A5DH	003B5DH	00375DH	00385DH				
003A5EH	003B5EH	00375EH	00385EH				XXXXX---B XXXXXXXXB
003A5FH	003B5FH	00375FH	00385FH				

(Continued)

Base oscillator frequency vs. Internal operating clock frequency



*1 : When the PLL multiplier is × 1, × 2, × 3 or × 4 and the internal clock is 20 MHz < f_{CP} ≤ 32 MHz, set DIV2 bit = "1"*4, CS2 bit = "1" in the PSCCR register.
[Example] When using a base oscillator frequency of 24 MHz at PLL × 1 :
CKSCR register : CS1 bit = "0", CS0 bit = "0"
PSCCR register : DIV2 bit = "1"*4,CS2 bit = "1"
[Example] When using a base oscillator frequency of 6 MHz at PLL × 3 :
CKSCR register : CS1 bit = "1", CS0 bit = "0"
PSCCR register : DIV2 bit = "1"*4, CS2 bit = "1"

*2 : When the PLL multiplier is × 2 or × 4 and the internal clock is 20 MHz < f_{CP} ≤ 32 MHz, the following settings are also supported.
PLL × 2 : CKSCR register : CS1 bit = "0", CS0 bit = "0"
PSCCR register : DIV2 bit = "0"*4, CS2 bit = "0"
PLL × 4 : CKSCR register : CS1 bit = "0", CS0 bit = "1"
PSCCR register : DIV2 bit = "0"*4, CS2 bit = "0"

*3 : When the PLL multiplier is set to × 6 or × 8 set "DIV2 bit = "0"*4 CS2 bit = "1" and "PLL2 bit = 1" in the PSCCR register.
[Example] When using a base oscillator frequency of 4 MHz at PLL × 6 :
CKSCR register : CS1 bit = "1", CS0 bit = "0"
PLLOS register : DIV2 bit = "0"*4, CS2 bit = "1"
[Example] When using a base oscillator frequency of 3 MHz at PLL × 8 :
CKSCR register : CS1 bit = "1", CS0 bit = "1"
PLLOS register : DIV2 bit = "0"*4, CS2 bit = "1"

*4 : The DIV2 bit is assigned to bit 9 of the PSCCR register and the CS2 bit is assigned to bit 8 of the PSCCR register. Both bits have a default value of "0".

• **Bit setting: ESCR0/1/2/3:SCES=1, ECCR0/1/2/3:SCDE=0**

(V_{CC} = 5.0 V±10%, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to +105 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pin C_L = 80 pF + 1TTL	5 t_{CP}	—	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		− 50	+ 50	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↓ → valid SIN hold time	t_{SLIXI}			0	—	ns
Serial clock “H” pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pin C_L = 80 pF + 1TTL	3 t_{CP} − t_R	—	ns
Serial clock “L” pulse width	t_{SLSH}			t_{CP} + 10	—	ns
SCK ↑ → SOT delay time	t_{SHOVE}	SCK0 to SCK3, SOT0 to SOT3		—	2 t_{CP} + 60	ns
Valid SIN → SCK ↓	t_{IVSLE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK ↓ → valid SIN hold time	t_{SLIXE}			t_{CP} + 30	—	ns
SCK ↓ time	t_F	SCK0 to SCK3		—	10	ns
SCK ↑ time	t_R			—	10	ns

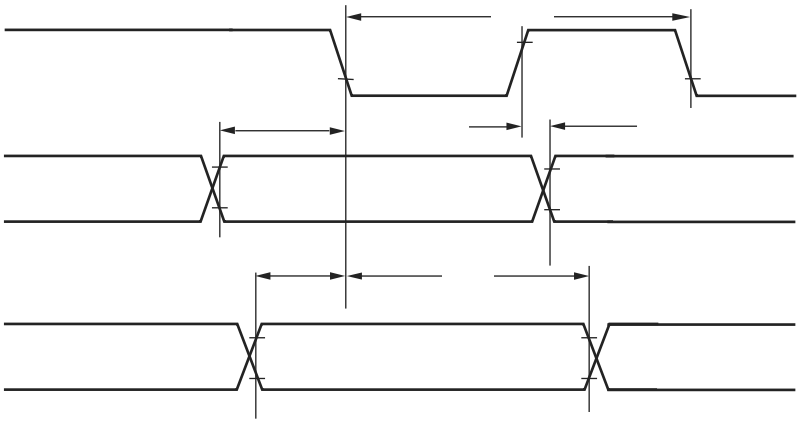
Notes : • Depending on the machine clock frequency to be used, the maximum baud rate may be limited by some parameters. These parameters are shown in “MB90920 series hardware manual”.
• C_L is the load capacitance connected to the pin during testing.
• t_{CP} is the internal operating clock cycle time. Refer to “ (1) Clock timing”.

• **Bit setting: ESCR0/1/2/3:SCES=0, ECCR0/1/2/3:SCDE=1**

(V_{CC} = 5.0 V±10%, V_{SS} = AV_{SS} = 0.0 V, T_A = –40 °C to +105 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pin C_L = 80 pF + 1TTL	5 t_{CP}	—	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		– 50	+ 50	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↓ → valid SIN hold time	t_{SLIXI}			0	—	ns
SOT → SCK ↓ delay time	t_{SOVLI}	SCK0 to SCK3, SOT0 to SOT3		3 t_{CP} – 70	—	ns

Notes : • Depending on the machine clock frequency to be used, the maximum baud rate may be limited by some parameters. These parameters are shown in “MB90920 series hardware manual”.
• C_L is the load capacitance connected to the pin during testing.
• t_{CP} is the internal operating clock cycle time. Refer to “ (1) Clock timing”.



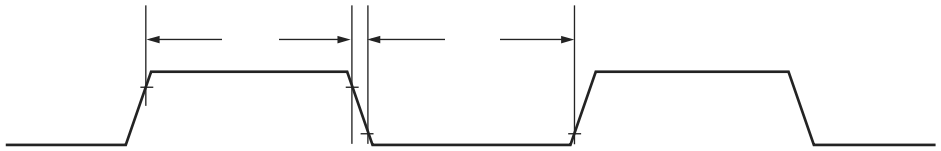
(6) Trigger input timing

(V_{CC} = 5.0 V±10%, V_{SS} = AV_{SS} = 0.0 V, T_A = –40 °C to +105 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Input pulse width	t_{TRGH}, t_{TRGL}	INT0 to INT7	—	200	—	ns	During normal operation
		ADTG	—	t_{CP} + 200	—	ns	

Note : t_{CP} is the internal operating clock cycle time. Refer to “ (1) Clock timing”.

- Trigger input timing

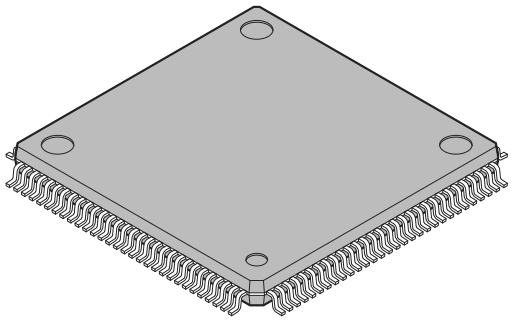


6. Flash Memory Program/Erase Characteristics

Parameter	Conditions	Value			Unit	Remarks
		Min	Typ	Max		
Sector erase time	T_A = + 25 °C V_{CC} = 5.0 V	—	0.9	3.6	s	Excludes pre-programming before erase
Word (16-bit width) programming time		—	23	370	µs	Excludes system-level overhead
Chip programming time	T_A = + 25 °C, V_{CC} = 5.0 V	—	3.4	55	s	
Erase/program cycle	—	10000	—	—	cycle	
Flash memory data retention time	Average T_A = + 85 °C	20	—	—	year	*

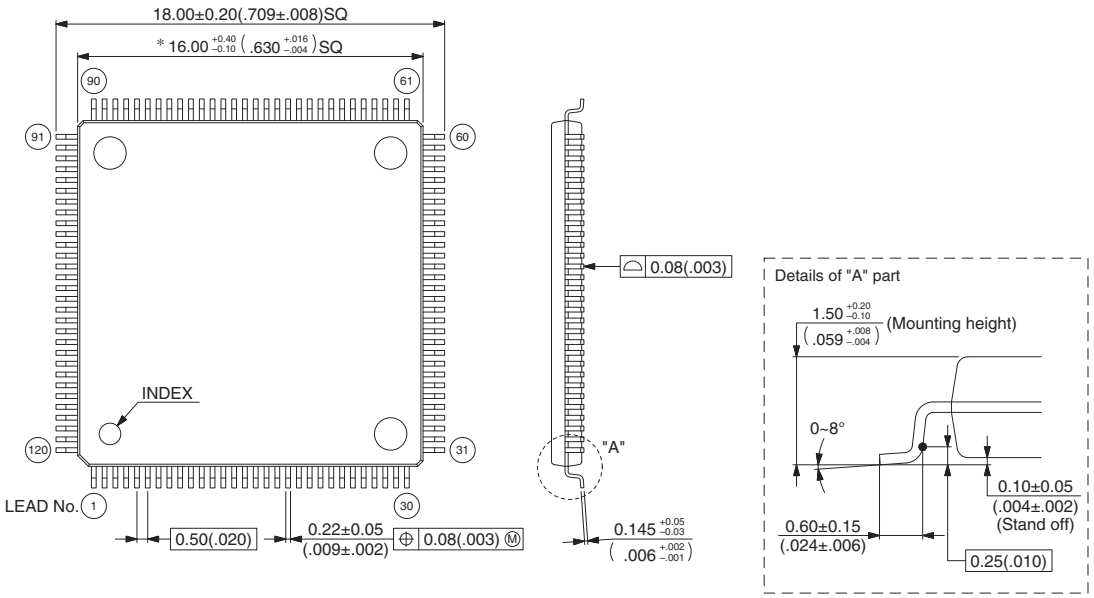
* : This value is calculated from the results of evaluating the reliability of the technology (using Arrhenius equation to translate high temperature measurements into normalized value at + 85 °C) .

■ PACKAGE DIMENSION

120-pin plastic LQFP		
	Lead pitch	0.50 mm
	Package width × package length	16.0 × 16.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	0.88 g
(FPT-120P-M21)	Code (Reference)	P-LFQFP120-16×16-0.50

120-pin plastic LQFP
(FPT-120P-M21)

Note 1) * : These dimensions do not include resin protrusion.
Resin protrusion is +0.25(.010) MAX(each side).
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.



Dimensions in mm (inches).
Note: The values in parentheses are reference values.

Please check the latest package dimension at the following URL.
http://edevice.fujitsu.com/package/en-search/