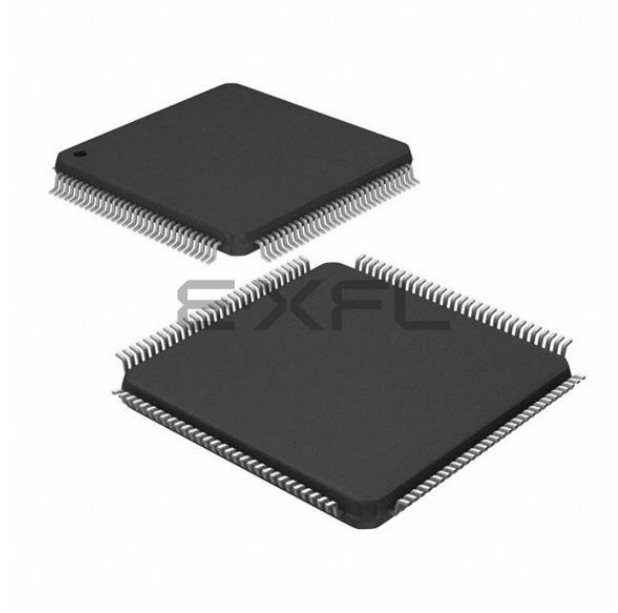
Infineon Technologies - MB90922NCSPMC-GS-273E1 Datasheet



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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, LINbus, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	256KB (256K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90922ncspmc-gs-273e1

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- 16-bit reload timer (4 channels)
  16-bit reload timer operation (select toggle output or one-shot output)
  Selectable event count function
- Real time watch timer (main clock)
  Operates directly from oscillator clock.
  Interrupt can be generated by second/minute/hour/date counter overflow.
- PPG timer (6 channels)
  Output pins (3 channels), external trigger input pin (1 channel)
  Operation clock frequencies : f_{CP}, $f_{CP}/2^2$, $f_{CP}/2^4$, $f_{CP}/2^6$
- Delay interrupt
  Generates interrupt for task switching.
  Interrupts to CPU can be generated/cleared by software setting.
- External interrupts (8 channels)
  8-channel independent operation
  Interrupt source setting available : “L” to “H” edge/ “H” to “L” edge/ “L” level/ “H” level.
- 8/10-bit A/D converter (8 channels)
  Conversion time : 3 µs (at f_{CP} = 32 MHz)
  External trigger activation available (P50/INT0/ADTG)
  Internal timer activation available (16-bit reload timer 1)
- UART(LIN/SCI) (4 channels)
  Equipped with full duplex double buffer
  Clock-asynchronous or clock-synchronous serial transfer is available
- CAN interface (4 channels : CAN0 and CAN2, and CAN1 and CAN3 share transmission and reception pins, and interrupt control registers).
  Conforms to CAN specifications version 2.0 Part A and B.
  Automatic resend in case of error.
  Automatic transfer in response to remote frame.
  16 prioritized message buffers for data and ID
  Multiple message support
  Flexible configuration for receive filter : Full bit compare/full bit mask/two partial bit masks
  Supports up to 1 Mbps
  CAN wakeup function (RX connected to INT0 internally)
- LCD controller/driver (32 segment x 4 common)
  Segment driver and command driver with direct LCD panel (display) drive capability
- Reset on detection of low voltage/program loop
  Automatic reset when low voltage is detected
  Program looping detection function
- Stepping motor controller (4 channels)
  High current output for each channel × 4
  Synchronized 8/10-bit PWM for each channel × 2
- Sound generator (2 channels)
  8-bit PWM signal mixed with tone frequency from 8-bit reload counter.
  PWM frequencies : 125 kHz, 62.5 kHz, 31.2 kHz, 15.6 kHz (at f_{CP} = 32 MHz)
  Tone frequencies : PWM frequency /2/ , divided by (reload frequency +1)
- Input/output ports
  General-purpose input/output port (CMOS output) 93 ports
- Function for port input level selection
  Automotive/CMOS-Schmitt
- Flash memory security function
  Protects the contents of Flash memory (Flash memory product only)

Pin no.	Pin name	I/O circuit type*1	Function
61	P54	I	General-purpose I/O port
	TX0		CAN interface 0 TX output pin
	TX2		CAN interface 2 TX output pin
	SGA1		Sound generator ch.1 SGA output pin
63	P55	I	General-purpose I/O port
	RX0		CAN interface 0 RX input pin
	RX2		CAN interface 2 RX input pin
	INT2		INT2 external interrupt input pin
91	P56	I	General-purpose I/O port
	SGO0		Sound generator ch.0 SGO output pin
	FRCK		Free-run timer clock input pin
92	P57	I	General-purpose I/O port
	SGA0		Sound generator ch.0 SGA output pin
39	P60	H	General-purpose I/O port
	AN0		A/D converter input pin
40	P61	H	General-purpose I/O port
	AN1		A/D converter input pin
41	P62	H	General-purpose I/O port
	AN2		A/D converter input pin
42	P63	H	General-purpose I/O port
	AN3		A/D converter input pin
43	P64	H	General-purpose I/O port
	AN4		A/D converter input pin
44	P65	H	General-purpose I/O port
	AN5		A/D converter input pin
45	P66	H	General-purpose I/O port
	AN6		A/D converter input pin
46	P67	H	General-purpose I/O port
	AN7		A/D converter input pin
67	P70	L	General-purpose output-only port
	PWM1P0		Stepping motor controller ch.0 output pin
68	P71	L	General-purpose output-only port
	PWM1M0		Stepping motor controller ch.0 output pin
69	P72	L	General-purpose output-only port
	PWM2P0		Stepping motor controller ch.0 output pin

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Pin no.	Pin name	I/O circuit type*1	Function
26	PD2	I	General-purpose I/O port
	SCK2		UART ch.2 serial clock I/O pin
27	PD3	J	General-purpose I/O port
	SIN3		UART ch.3 serial data input pin
28	PD4	I	General-purpose I/O port
	SOT3		UART ch.3 serial data output pin
29	PD5	I	General-purpose I/O port
	SCK3		UART ch.3 serial clock I/O pin
30	PD6	I	General-purpose I/O port
	TOT2		16-bit reload timer ch.2 TOT output pin
56	PE0	I	General-purpose I/O port
	TOT3		16-bit reload timer ch.3 TOT output pin
57	PE1	I	General-purpose I/O port
	TIN3		16-bit reload timer ch.3 TIN input pin
64	PE2	I	General-purpose I/O port
	SGO1		Sound generator ch.1 SGO output pin
62	RSTO	N	Internal reset signal output pin
65, 75, 85	DVCC	—	Power supply input pins dedicated for high current output buffer
66, 76, 86	DVSS	—	Power supply GND pins dedicated for high current output buffer
35	AVCC	—	A/D converter dedicated power supply input pin
38	AVSS	—	A/D converter dedicated power supply GND pin
36	AVRH	—	A/D converter Vref+ input pin. Vref- is fixed to AVSS.
89	MD0	D	Mode setting input pin. Connect to VCC pin.
88	MD1	D	Mode setting input pin. Connect to VCC pin.
87	MD2	D/E*2	Mode setting input pin. Connect to VSS pin.
17	C	—	External capacitor pin. Connect a 0.1 μF capacitor between this pin and the VSS pin.
15, 105	VCC	—	Power supply input pins
16, 47, 106	VSS	—	GND power supply pins

*1 : For I/O circuit type, refer to “ ■ I/O CIRCUIT TYPES”.

*2 : The I/O circuit type is D for Flash memory products and E for evaluation products.

• **Notes on operating in PLL clock mode**

On this microcontroller, if in case the crystal oscillator breaks off or an external reference clock input stops while the PLL clock mode is selected, a self-oscillator circuit contained in the PLL may continue its operation at its self-running frequency. However, FUJITSU SEMICONDUCTOR will not guarantee results of operations if such failure occurs.

• **Crystal oscillator circuit**

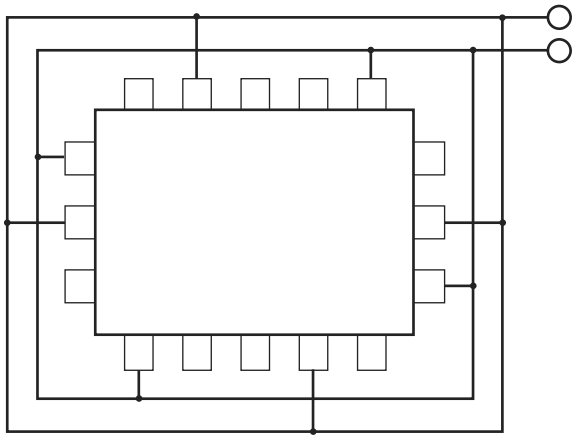
Noise around the X0/X1, or X0A/X1A pins may cause this device to operate abnormally. In the interest of stable operation it is strongly recommended that printed circuit artwork places ground bypass capacitors as close as possible to the X0/X1, X0A/X1A and crystal oscillator (or ceramic oscillator) and that oscillator lines do not cross the lines of other circuits.

Please ask each crystal maker to evaluate the oscillational characteristics of the crystal and this device.

• **Power supply pins**

Devices including multiple VCC or VSS pins are designed such that pins that need to be at the same potential are interconnected internally to prevent malfunctions such as latch-up. To reduce unnecessary radiation, prevent malfunctioning of the strobe signal due to the rise of ground level, and observe the standard for total output current, be sure to connect the VCC and VSS pins to the power supply and ground externally.

Always connect all of the VCC pins to the same potential and all of the VSS pins to ground as shown in the following diagram. The device will not operate correctly if multiple VCC or VSS pins are connected to different voltages, even if those voltages are within the guaranteed operating ranges.



Power supply input pins (Vcc/Vss)

In addition, care must be given to connecting the VCC and VSS pins of this device to the current supply source with as low impedance as possible. It is recommended that a 1.0 μF bypass capacitor be connected between the VCC and VSS pins as close to the pins as possible.

• **Sequence for connecting the A/D converter power supply and analog inputs**

The A/D converter power supply (AV_{CC}, AVRH) and analog inputs (AN0 to AN7) must be applied after the digital power supply (V_{CC}) is switched on. When turning the power off, the A/D converter power supply and analog inputs must be disconnected before the digital power supply is switched off (V_{CC}). Ensure that AVRH does not exceed AVcc during either power-on or power-off. Even when pins which double as analog input pins are used as input ports, be sure that the input voltage does not exceed AV_{CC} (turning on/off the analog and digital power supplies simultaneously is acceptable).

- **Serial communication**

In serial communication, reception of wrong data may occur due to noise or other causes. Therefore, design a printed circuit board to prevent noise from occurring. Taking account of the reception of wrong data, detect errors by measures such as adding a checksum to the end of data. If an error is detected, retransmit the data.

- **Characteristic difference between flash device and MASK ROM device**

In the flash device and the MASK ROM device, the electrical characteristic including current consumption, ESD, latch-up, the noise characteristic, and oscillation characteristic, etc. is different according to the difference between the chip layout and the memory structure.

Reconfirm the electrical characteristic when the product is replaced by another product of the same series.

Address	Register name	Symbol	Read/write	Resource name	Initial value
000024H	Compare clear register	CPCLR	R/W	16-bit free-run timer	XXXXXXXXB
000025H			R/W		XXXXXXXXB
000026H	Timer data register	TCDT	R/W		00000000B
000027H			R/W		00000000B
000028H	Lower timer control status register	TCCSL	R/W		00000000B
000029H	Higher timer control status register	TCCSH	R/W		01-00000B
00002AH	Lower PPG0 control status register	PCNTL0	R/W	16-bit PPG0	00000000B
00002BH	Higher PPG0 control status register	PCNTH0	R/W		00000001B
00002CH	Lower PPG1 control status register	PCNTL1	R/W	16-bit PPG1	00000000B
00002DH	Higher PPG1 control status register	PCNTH1	R/W		00000001B
00002EH	Lower PPG2 control status register	PCNTL2	R/W	16-bit PPG2	00000000B
00002FH	Higher PPG2 control status register	PCNTH2	R/W		00000001B
000030H	External interrupt enable	ENIR	R/W	External interrupt	00000000B
000031H	External interrupt request	EIRR	R/W		00000000B
000032H	Lower external interrupt level	ELVRL	R/W		00000000B
000033H	Higher external interrupt level	ELVRH	R/W		00000000B
000034H	Serial mode register 0	SMR0	R/W, W	UART (LIN/SCI) 0	00000000B
000035H	Serial control register 0	SCR0	R/W, W		00000000B
000036H	Reception/transmission data register 1	RDR0/ TDR0	R/W		00000000B
000037H	Serial status register 0	SSR0	R/W, R		00001000B
000038H	Extended communication control register 0	ECCR0	R/W, R		000000XXB
000039H	Extended status control register 0	ESCR0	R/W		00000100B
00003AH	Baud rate generator register 00	BGR00	R/W		00000000B
00003BH	Baud rate generator register 01	BGR01	R/W, R		00000000B
00003CH to 00003FH	(Disabled)				
000040H to 00004FH	Area reserved for CAN Controller 0. Refer to "■ CAN CONTROLLERS"				
000050H	Lower timer control status register 0	TMCSR0L	R/W	16-bit reload timer 0	00000000B
000051H	Higher timer control status register 0	TMCSR0H	R/W		XXX10000B
000052H	Timer register 0/reload register 0	TMR0/ TMRLR0	R/W		XXXXXXXXB
000053H					XXXXXXXXB

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Address	Register name	Symbol	Read/write	Resource name	Initial value
0000B0H	Interrupt control register 00	ICR00	R/W	Interrupt controller	00000111B
0000B1H	Interrupt control register 01	ICR01	R/W		00000111B
0000B2H	Interrupt control register 02	ICR02	R/W		00000111B
0000B3H	Interrupt control register 03	ICR03	R/W		00000111B
0000B4H	Interrupt control register 04	ICR04	R/W		00000111B
0000B5H	Interrupt control register 05	ICR05	R/W		00000111B
0000B6H	Interrupt control register 06	ICR06	R/W		00000111B
0000B7H	Interrupt control register 07	ICR07	R/W		00000111B
0000B8H	Interrupt control register 08	ICR08	R/W		00000111B
0000B9H	Interrupt control register 09	ICR09	R/W		00000111B
0000BAH	Interrupt control register 10	ICR10	R/W		00000111B
0000BBH	Interrupt control register 11	ICR11	R/W		00000111B
0000BCH	Interrupt control register 12	ICR12	R/W		00000111B
0000BDH	Interrupt control register 13	ICR13	R/W		00000111B
0000BEH	Interrupt control register 14	ICR14	R/W		00000111B
0000BFH	Interrupt control register 15	ICR15	R/W		00000111B
0000C0H to 0000C3H	(Disabled)				
0000C4H	Serial mode register 1	SMR1	R/W, W	UART (LIN/SCI) 1	00000000B
0000C5H	Serial control register 1	SCR1	R/W, W		00000000B
0000C6H	Reception/transmission data register 1	RDR1/ TDR1	R/W		00000000B
0000C7H	Serial status register 1	SSR1	R/W, R		00001000B
0000C8H	Extended communication control register 1	ECCR1	R/W, R		000000XXB
0000C9H	Extended status control register 1	ESCR1	R/W		00000100B
0000CAH	Baud rate generator register 10	BGR10	R/W		00000000B
0000CBH	Baud rate generator register 11	BGR11	R/W, R		00000000B
0000CCH	Lower watch timer control register	WTCRL	R/W	Real-time watch timer	000XXXX0B
0000CDH	Middle watch timer control register	WTCRM	R/W		00000000B
0000CEH	Higher watch timer control register	WTCRH	R/W		XXXXXX00B
0000CFH	Sub clock control register	PSCCR	W	Sub clock	XXXX0000B
0000D0H	Input capture control status 4/5	ICS45	R/W	Input capture 4/5	00000000B
0000D1H	Input capture edge register 4/5	ICE45	R/W, R		XXXXXXXXB
0000D2H	Input capture control status 6/7	ICS67	R/W	Input capture 6/7	00000000B
0000D3H	Input capture edge register 6/7	ICE67	R/W, R		XXX0X0XXB

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Address	Register name	Symbol	Read/write	Resource name	Initial value
003700H to 0037FFH	Area reserved for CAN Controller 2. Refer to "■ CAN CONTROLLERS"				
003800H to 0038FFH	Area reserved for CAN Controller 3. Refer to "■ CAN CONTROLLERS"				
003900H to 00391FH	(Disabled)				
003920H	PPG0 down counter register	PDCR0	R	16-bit PPG0	11111111B
003921H					11111111B
003922H	PPG0 cycle setting register	PCSR0	W		11111111B
003923H					11111111B
003924H	PPG0 duty setting register	PDUT0	W	16-bit PPG0	00000000B
003925H					00000000B
003926H	PPG0 output division setting register	PPGDIV0	R/W, R		11111100B
003927H	(Disabled)				
003928H	PPG1 down counter register	PDCR1	R	16-bit PPG1	11111111B
003929H					11111111B
00392AH	PPG1 cycle setting register	PCSR1	W		11111111B
00392BH					11111111B
00392CH	PPG1 duty setting register	PDUT1	W		00000000B
00392DH					00000000B
00392EH	PPG1output division setting register	PPGDIV1	R/W, R		11111100B
00392FH	(Disabled)				
003930H	PPG2 down counter register	PDCR2	R	16-bit PPG2	11111111B
003931H					11111111B
003932H	PPG2 cycle setting register	PCSR2	W		11111111B
003933H					11111111B
003934H	PPG2 duty setting register	PDUT2	W		00000000B
003935H					00000000B
003936H	PPG2 output division setting register	PPGDIV2	R/W, R		11111100B
003937H to 00393FH	(Disabled)				
003940H	Input capture register 4	IPCP4	R	Input capture 4/5	XXXXXXXXB
003941H					XXXXXXXXB
003942H	Input capture register 5	IPCP5	R		XXXXXXXXB
003943H					XXXXXXXXB

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Address	Register name	Symbol	Read/write	Resource name	Initial value
003944H	Input capture register 6	IPCP6	R	Input capture 6/7	XXXXXXXXB
003945H					XXXXXXXXB
003946H	Input capture register 7	IPCP7	R		XXXXXXXXB
003947H					XXXXXXXXB
003948H to 00394FH	(Disabled)				
003950H	Minute data register 2/Reload register 2	TMR2/ TMRLR2	R/W	16-bit reload timer 2	XXXXXXXXB
003951H					XXXXXXXXB
003952H	Minute data register 3/Reload register 3	TMR3/ TMRLR3	R/W	16-bit reload timer 3	XXXXXXXXB
003953H					XXXXXXXXB
003954H to 003957H	(Disabled)				
003958H	Sub second data register	WTBR	R/W	Real time watch timer	XXXXXXXXB
003959H					XXXXXXXXB
00395AH					XXXXXXXXB
00395BH	Second data register	WTSR	R/W		XX000000B
00395CH	Minute data register	WTMR	R/W		XX000000B
00395DH	Hour data register	WTHR	R/W		XXX00000B
00395EH	Day data register	WTDR	R/W		00X00001B
00395FH	(Disabled)				
003960H	LCD display RAM	VRAM	R/W	LCD controller/ driver	XXXXXXXXB
003961H					XXXXXXXXB
003962H					XXXXXXXXB
003963H					XXXXXXXXB
003964H					XXXXXXXXB
003965H					XXXXXXXXB
003966H					XXXXXXXXB
003967H					XXXXXXXXB
003968H					XXXXXXXXB
003969H					XXXXXXXXB
00396AH					XXXXXXXXB
00396BH					XXXXXXXXB
00396CH					XXXXXXXXB
00396DH					XXXXXXXXB
00396EH					XXXXXXXXB
00396FH					XXXXXXXXB

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Address				Register	Abbre-viation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A40H	003B40H	003740H	003840H	ID register 8	IDR8	R/W	XXXXXXXXB XXXXXXXXB
003A41H	003B41H	003741H	003841H				
003A42H	003B42H	003742H	003842H				XXXXX---B XXXXXXXXB
003A43H	003B43H	003743H	003843H				
003A44H	003B44H	003744H	003844H	ID register 9	IDR9	R/W	XXXXXXXXB XXXXXXXXB
003A45H	003B45H	003745H	003845H				
003A46H	003B46H	003746H	003846H				XXXXX---B XXXXXXXXB
003A47H	003B47H	003747H	003847H				
003A48H	003B48H	003748H	003848H	ID register 10	IDR10	R/W	XXXXXXXXB XXXXXXXXB
003A49H	003B49H	003749H	003849H				
003A4AH	003B4AH	00374AH	00384AH				XXXXX---B XXXXXXXXB
003A4BH	003B4BH	00374BH	00384BH				
003A4CH	003B4CH	00374CH	00384CH	ID register 11	IDR11	R/W	XXXXXXXXB XXXXXXXXB
003A4DH	003B4DH	00374DH	00384DH				
003A4EH	003B4EH	00374EH	00384EH				XXXXX---B XXXXXXXXB
003A4FH	003B4FH	00374FH	00384FH				
003A50H	003B50H	003750H	003850H	ID register 12	IDR12	R/W	XXXXXXXXB XXXXXXXXB
003A51H	003B51H	003751H	003851H				
003A52H	003B52H	003752H	003852H				XXXXX---B XXXXXXXXB
003A53H	003B53H	003753H	003853H				
003A54H	003B54H	003754H	003854H	ID register 13	IDR13	R/W	XXXXXXXXB XXXXXXXXB
003A55H	003B55H	003755H	003855H				
003A56H	003B56H	003756H	003856H				XXXXX---B XXXXXXXXB
003A57H	003B57H	003757H	003857H				
003A58H	003B58H	003758H	003858H	ID register 14	IDR14	R/W	XXXXXXXXB XXXXXXXXB
003A59H	003B59H	003759H	003859H				
003A5AH	003B5AH	00375AH	00385AH				XXXXX---B XXXXXXXXB
003A5BH	003B5BH	00375BH	00385BH				
003A5CH	003B5CH	00375CH	00385CH	ID register 15	IDR15	R/W	XXXXXXXXB XXXXXXXXB
003A5DH	003B5DH	00375DH	00385DH				
003A5EH	003B5EH	00375EH	00385EH				XXXXX---B XXXXXXXXB
003A5FH	003B5FH	00375FH	00385FH				

List of Message Buffers (DLC Registers)

Address				Register	Abbreviation	Access	Initial Value
CAN0	CAN1	CAN2	CAN3				
003A60H	003B60H	003760H	003860H	DLC register 0	DLCR0	R/W	----XXXXB
003A61H	003B61H	003761H	003861H				
003A62H	003B62H	003762H	003862H	DLC register 1	DLCR1	R/W	----XXXXB
003A63H	003B63H	003763H	003863H				
003A64H	003B64H	003764H	003864H	DLC register 2	DLCR2	R/W	----XXXXB
003A65H	003B65H	003765H	003865H				
003A66H	003B66H	003766H	003866H	DLC register 3	DLCR3	R/W	----XXXXB
003A67H	003B67H	003767H	003867H				
003A68H	003B68H	003768H	003868H	DLC register 4	DLCR4	R/W	----XXXXB
003A69H	003B69H	003769H	003869H				
003A6AH	003B6AH	00376AH	00386AH	DLC register 5	DLCR5	R/W	----XXXXB
003A6BH	003B6BH	00376BH	00386BH				
003A6CH	003B6CH	00376CH	00386CH	DLC register 6	DLCR6	R/W	----XXXXB
003A6DH	003B6DH	00376DH	00386DH				
003A6EH	003B6EH	00376EH	00386EH	DLC register 7	DLCR7	R/W	----XXXXB
003A6FH	003B6FH	00376FH	00386FH				
003A70H	003B70H	003770H	003870H	DLC register 8	DLCR8	R/W	----XXXXB
003A71H	003B71H	003771H	003871H				
003A72H	003B72H	003772H	003872H	DLC register 9	DLCR9	R/W	----XXXXB
003A73H	003B73H	003773H	003873H				
003A74H	003B74H	003774H	003874H	DLC register 10	DLCR10	R/W	----XXXXB
003A75H	003B75H	003775H	003875H				
003A76H	003B76H	003776H	003876H	DLC register 11	DLCR11	R/W	----XXXXB
003A77H	003B77H	003777H	003877H				
003A78H	003B78H	003778H	003878H	DLC register 12	DLCR12	R/W	----XXXXB
003A79H	003B79H	003779H	003879H				
003A7AH	003B7AH	00377AH	00387AH	DLC register 13	DLCR13	R/W	----XXXXB
003A7BH	003B7BH	00377BH	00387BH				
003A7CH	003B7CH	00377CH	00387CH	DLC register 14	DLCR14	R/W	----XXXXB
003A7DH	003B7DH	00377DH	00387DH				
003A7EH	003B7EH	00377EH	00387EH	DLC register 15	DLCR15	R/W	----XXXXB
003A7FH	003B7FH	00377FH	00387FH				

■ INTERRUPT SOURCES, INTERRUPT VECTORS, AND INTERRUPT CONTROL REGISTERS

Interrupt source	EI²OS corresponding	Interrupt vector			Interrupt control register		Priority *2
		Number		Address	ICR	Address	
Reset	×	#08	08H	FFFFDCH	—	—	High
INT9 instruction	×	#09	09H	FFFFD8H	—	—	
Exception processing	×	#10	0AH	FFFFD4H	—	—	
CAN0 received/CAN2 received	×	#11	0BH	FFFFD0H	ICR00	0000B0H*1	
CAN0 transmitted/node status/ CAN2 transmitted/node status	×	#12	0CH	FFFFCCH			
CAN1 received/CAN3 received	×	#13	0DH	FFFFC8H	ICR01	0000B1H*1	
CAN1 transmitted/node status/ CAN3 transmitted/node status/SIO	×	#14	0EH	FFFFC4H			
Input capture 0	△	#15	0FH	FFFFC0H	ICR02	0000B2H*1	
DTP/ external interrupt - ch.0/ch.1 detected	△	#16	10H	FFFFBCH			
Reload timer 0	△	#17	11H	FFFFB8H	ICR03	0000B3H*1	
Reload timer 2	△	#18	12H	FFFFB4H			
Input capture 1	△	#19	13H	FFFFB0H	ICR04	0000B4H*1	
DTP/ external interrupt - ch.2/ch.3 detected	△	#20	14H	FFFFACH			
Input capture 2	△	#21	15H	FFFFA8H	ICR05	0000B5H*1	
Reload timer 3	△	#22	16H	FFFFA4H			
Input capture 3/4/5/6/7	△	#23	17H	FFFFA0H	ICR06	0000B6H*1	
DTP/ external interrupt - ch.4/ ch.5 detected UART3 RX	△	#24	18H	FFFF9CH			
PPG timer 0	△	#25	19H	FFFF98H	ICR07	0000B7H*1	
DTP/ external interrupt - ch.6/ ch.7 detected UART3 TX	△	#26	1AH	FFFF94H			
PPG timer 1	△	#27	1BH	FFFF90H	ICR08	0000B8H*1	
Reload timer 1	△	#28	1CH	FFFF8CH			
PPG timer 2/3/4/5	○	#29	1DH	FFFF88H	ICR09	0000B9H*1	
Real time watch timer watch timer (sub clock)	×	#30	1EH	FFFF84H			
Free-run timer overflow/clear	×	#31	1FH	FFFF80H	ICR10	0000BAH *1	
A/D converter conversion complete	○	#32	20H	FFFF7CH			
Sound generator 0/1	×	#33	21H	FFFF78H	ICR11	0000BBH*1	
Time-base timer	×	#34	22H	FFFF74H			
UART2 RX	○	#35	23H	FFFF70H	ICR12	0000BCH*1	
UART2 TX	△	#36	24H	FFFF6CH			Low

(Continued)

■ ELECTRICAL CHARACTERISTICS

1. Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	V_{SS} – 0.3	V_{SS} + 6.0	V	
	AV_{CC}	V_{SS} – 0.3	V_{SS} + 6.0	V	$AV_{CC} = V_{CC}$*2
	AVRH	V_{SS} – 0.3	V_{SS} + 6.0	V	$AV_{CC} \geq$ AVRH*2
	DV_{CC}	V_{SS} – 0.3	V_{SS} + 6.0	V	$DV_{CC} = V_{CC}$*2
Input voltage*1	V_I	V_{SS} – 0.3	V_{CC} + 0.3	V	*3
Output voltage*1	V_O	V_{SS} – 0.3	V_{CC} + 0.3	V	
Maximum clamp current	I_{CLAMP}	– 4	+ 4	mA	*7
Total maximum clamp current	$\Sigma \lvert I_{CLAMP} \rvert$	—	40	mA	*7
"L" level maximum output current*4	I_{OL1}	—	15	mA	Except P70 to P77 and P80 to P87
	I_{OL2}	—	40	mA	P70 to P77 and P80 to P87
"L" level average output current*5	I_{OLAV1}	—	4	mA	Except P70 to P77 and P80 to P87
	I_{OLAV2}	—	30	mA	P70 to P77 and P80 to P87
"L" level maximum total output current	ΣI_{OL1}	—	100	mA	Except P70 to P77 and P80 to P87
	ΣI_{OL2}	—	330	mA	P70 to P77 and P80 to P87
"L" level average total output current	ΣI_{OLAV1}	—	50	mA	Except P70 to P77 and P80 to P87
	ΣI_{OLAV2}	—	250	mA	P70 to P77 and P80 to P87
"H" level maximum output current	I_{OH1}*4	—	–15	mA	Except P70 to P77 and P80 to P87
	I_{OH2}*4	—	–40	mA	P70 to P77 and P80 to P87
"H" level average output current	I_{OHAV1}*5	—	–4	mA	Except P70 to P77 and P80 to P87
	I_{OHAV2}*5	—	–30	mA	P70 to P77 and P80 to P87
"H" level maximum total output current	ΣI_{OH1}	—	–100	mA	Except P70 to P77 and P80 to P87
	ΣI_{OH2}	—	–330	mA	P70 to P77 and P80 to P87
"H" level average total output current	ΣI_{OHAV1}*6	—	–50	mA	Except P70 to P77 and P80 to P87
	ΣI_{OHAV2}*6	—	–250	mA	P70 to P77 and P80 to P87
Power consumption	P_D	—	625	mW	
Operating temperature	T_A	– 40	+ 105	°C	
Storage temperature	T_{STG}	– 55	+ 150	°C	

*1 : The parameter is based on $V_{SS} = AV_{SS} = DV_{SS} = 0.0$ V.

*2 : AV_{CC}, AVRH must not exceed V_{CC}, and AVRH must not exceed AV_{CC}.
When using an evaluation product, DV_{CC} must not exceed V_{CC} (however, DV_{CC} can be set to a higher voltage than V_{CC} when using a Flash memory product).

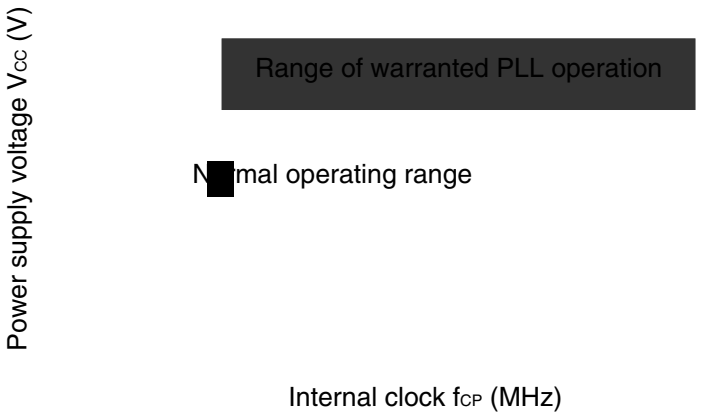
*3 : If the input current or the maximum input current is limited using external components, I_{CLAMP} is the applicable rating instead of V_I.

*4 : Maximum output current is defined as the peak value of current through any one of the corresponding pins.

(Continued)

• **Guaranteed PLL Operation Range**

Internal operating clock frequency vs. Power supply voltage



Notes : • For PLL 1 × only, use with tcp = 4 MHz or greater.
• Refer to “5. A/D Converter (1) Electrical Characteristics” for details on the A/D converter operating frequency.

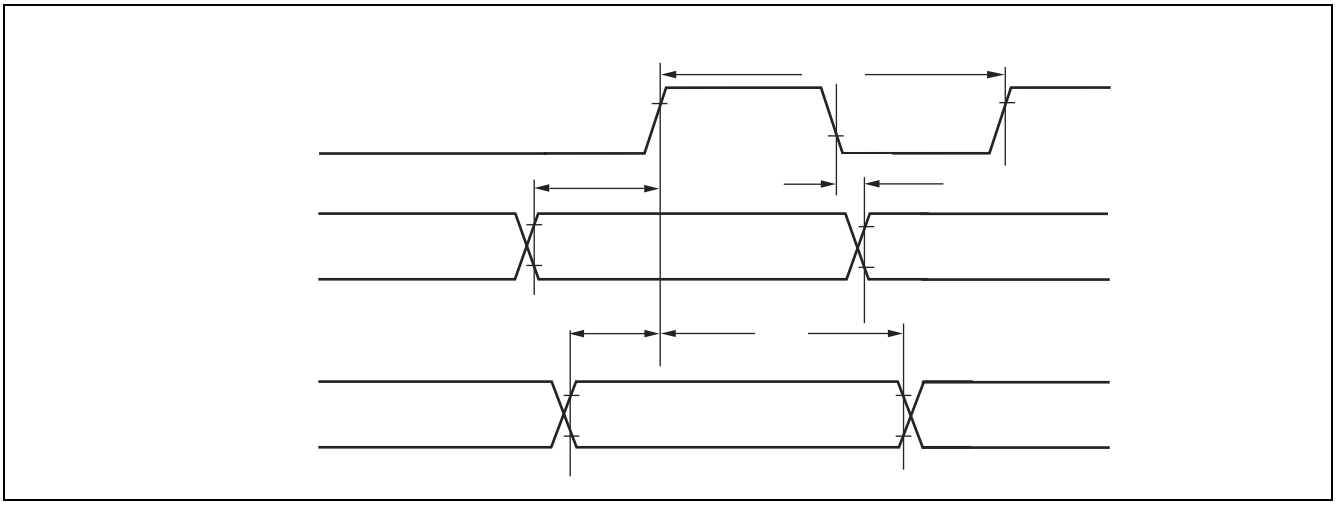
(Continued)

• **Bit setting: ESCR0/1/2/3:SCES=1, ECCR0/1/2/3:SCDE=1**

(V_{CC} = 5.0 V±10%, V_{SS} = AV_{SS} = 0.0 V, T_A = –40 °C to +105 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pin C_L = 80 pF + 1TTL	5 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		– 50	+ 50	ns
Valid SIN → SCK ↓	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↑ → valid SIN hold time	t_{SHIXI}			0	—	ns
SOT → SCK ↑ delay time	t_{SOVHI}	SCK0 to SCK3, SOT0 to SOT3		3 t_{CP} – 70	—	ns

Notes :
- Depending on the machine clock frequency to be used, the maximum baud rate may be limited by some parameters. These parameters are shown in “MB90920 series hardware manual”.
- C_L is the load capacitance connected to the pin during testing.
- t_{CP} is the internal operating clock cycle time. Refer to “ (1) Clock timing”.



5. A/D Converter

(1) Electrical Characteristics

(V_{CC} = AV_{CC} = AVRH = 4.0 V to 5.5 V, V_{SS} = AV_{SS} = 0.0 V, T_A = –40 °C to +105 °C)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	– 3.0	—	+ 3.0	LSB	
Non-linear error	—	—	– 2.5	—	+ 2.5	LSB	
Differential linear error	—	—	– 1.9	—	+ 1.9	LSB	
Zero transition voltage	V_{OT}	AN0 to AN7	AV_{SS} – 1.5 LSB	AV_{SS} + 0.5 LSB	AV_{SS} + 2.5 LSB	V	1 LSB = (AVRH – AV_{SS}) / 1024
Full scale transition voltage	V_{FST}	AN0 to AN7	AVRH – 3.5 LSB	AVRH – 1.5 LSB	AVRH + 0.5 LSB	V	
Sampling time	t_{SMP}	—	0.4	—	16500	µs	4.5 V ≤ AVcc ≤ 5.5 V
			1.0				4.0 V ≤ AVcc ≤ 4.5 V
Compare time	t_{CMP}	—	0.66	—	—	µs	4.5 V ≤ AVcc ≤ 5.5 V
			2.2				4.0 V ≤ AVcc ≤ 4.5 V
A/D conversion time	t_{CNV}	—	1.44	—	—	µs	*1
Analog port input current	I_{AIN}	AN0 to AN7	– 0.3	—	+ 10	µA	
Analog input voltage	V_{AIN}	AN0 to AN7	0	—	AVRH	V	
Reference voltage	AV+	AVRH	AVss + 2.7	—	AV_{CC}	V	
Power supply current	I_A	AV_{CC}	—	2.3	6.0	mA	
	I_{AH}		—	—	5	µA	*2
Reference voltage supply current	I_R	AVRH	—	520	900	µA	V_{AVRH} = 5.0 V
	I_{RH}		—	—	5	µA	*2
Inter-channel variation	—	AN0 to AN7	—	—	4	LSB	

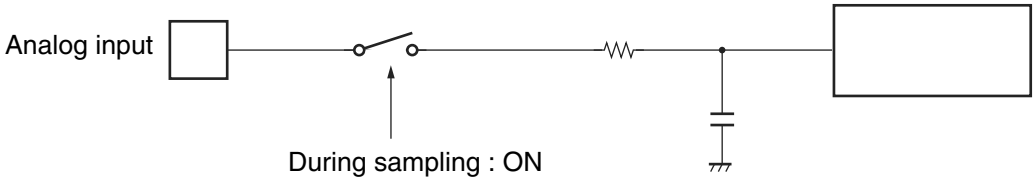
*1 : The time per channel (4.5 V ≤ AV_{CC} ≤ 5.5 V, and internal operating frequency = 32 MHz) .

*2 : Defined as supply current (when V_{CC} = AV_{CC} = AVRH = 5.0 V) with A/D converter not operating, and CPU in stop mode.

• **Notes on the external impedance and sampling time of analog inputs**

A/D converter with sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting A/D conversion precision. Therefore, to satisfy the A/D conversion precision standard, consider the relationship between the external impedance and minimum sampling time and either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. If the sampling time is still not sufficient, connect a capacitor of about 0.1 μF to the analog input pin.

• Analog input equivalent circuit



MB90F922NC/F922NCS/ F923NC/F923NCS/F924NC/F924NCS
MB90922NCS

	R	C
4.5 V ≤ AVcc ≤ 5.5 V :	2.6 kΩ (Max)	8.5 pF (Max)
4.0 V ≤ AVcc ≤ 4.5 V :	12.1 kΩ (Max)	8.5 pF (Max)

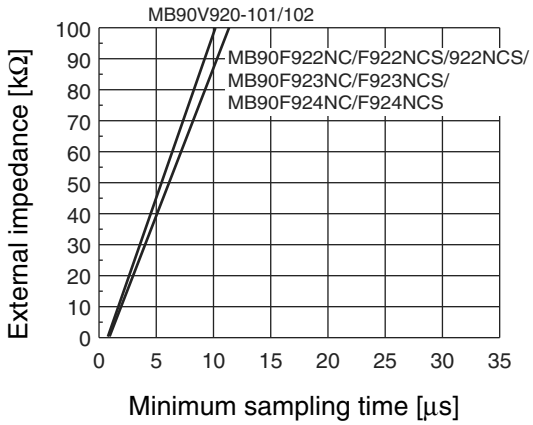
MB90V920-101/102

4.5 V ≤ AVcc ≤ 5.5 V :	2.0 kΩ (Max)	14.4 pF (Max)
4.0 V ≤ AVcc ≤ 4.5 V :	8.2 kΩ (Max)	14.4 pF (Max)

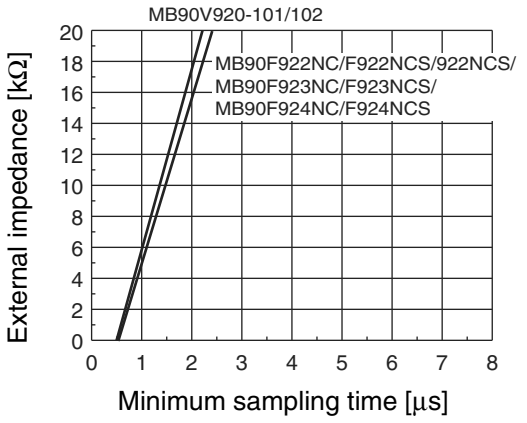
Note : The values are reference values.

- The relationship between the external impedance and minimum sampling time
- At 4.5 V ≤ AVcc ≤ 5.5 V

(External impedance = 0 kΩ to 100 kΩ)

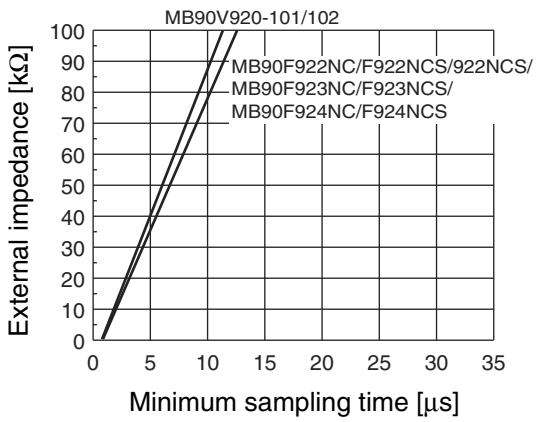


(External impedance = 0 kΩ to 20 kΩ)

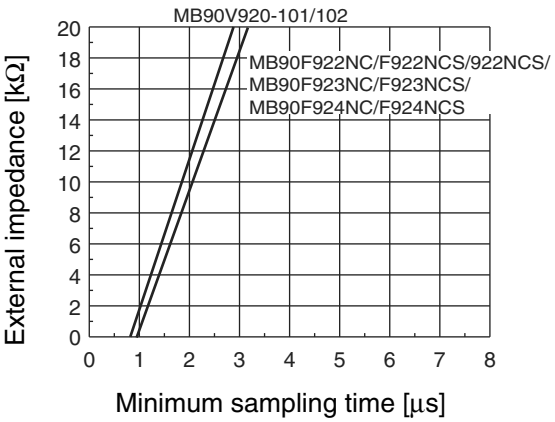


- At 4.0 V ≤ AVcc ≤ 4.5 V

(External impedance = 0 kΩ to 100 kΩ)



(External impedance = 0 kΩ to 20 kΩ)



- About errors
  As |AVRH - AVSS| becomes smaller, the relative errors grow larger.

MEMO

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