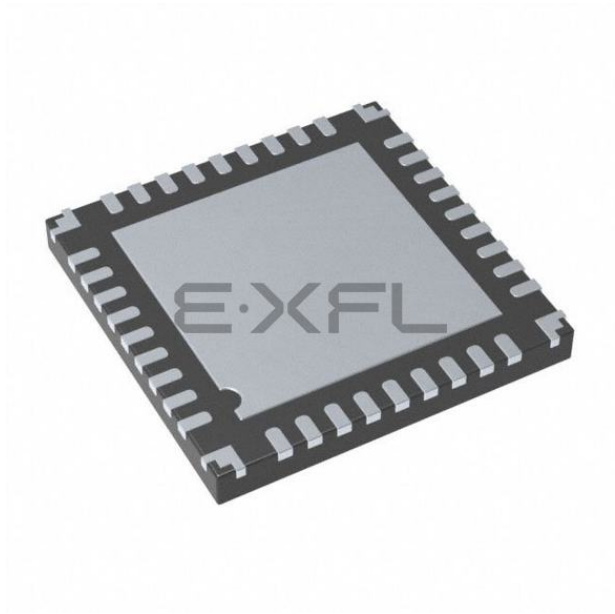
Microchip Technology - DSPIC33EV128GM003-I/M5 Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	25
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 13x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	36-UFQFN Exposed Pad
Supplier Device Package	36-UQFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ev128gm003-i-m5

3.5 Programmer's Model

The programmer's model for the dsPIC33EVXXXGM00X/10X family is shown in Figure 3-2. All registers in the programmer's model are memory-mapped and can be manipulated directly by instructions. Table 3-1 lists a description of each register.

In addition to the registers contained in the programmer's model, the dsPIC33EVXXXGM00X/10X family devices contain control registers for Modulo Addressing and Bit-Reversed Addressing, and interrupts. These registers are described in subsequent sections of this document.

All registers associated with the programmer's model are memory-mapped, as shown in Table 4-1.

TABLE 3-1: PROGRAMMER'S MODEL REGISTER DESCRIPTIONS

Register(s) Name	Description
W0 through W15(1)	Working Register Array
W0 through W14(1)	Alternate Working Register Array 1
W0 through W14(1)	Alternate Working Register Array 2
ACCA, ACCB	40-Bit DSP Accumulators
PC	23-Bit Program Counter
SR	ALU and DSP Engine STATUS Register
SPLIM	Stack Pointer Limit Value Register
TBLPAG	Table Memory Page Address Register
DSRPAG	Extended Data Space (EDS) Read Page Register
RCOUNT	REPEAT Loop Counter Register
DCOUNT	DO Loop Count Register
DOSTARTH(2), DOSTARTL(2)	DO Loop Start Address Register (High and Low)
DOENDH, DOENDL	DO Loop End Address Register (High and Low)
CORCON	Contains DSP Engine, DO Loop Control and Trap Status bits

Note 1: Memory-mapped W0 through W14 represents the value of the register in the currently active CPU context.

2: The DOSTARTH and DOSTARTL registers are read-only.

REGISTER 3-3: CTXTSTAT: CPU W REGISTER CONTEXT STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
—	—	—	—	—	CCTXI2	CCTXI1	CCTXI0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R-0	R/W-0	R/W-0
—	—	—	—	—	MCTXI2	MCTXI1	MCTXI0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **CCTXI<2:0>:** Current (W Register) Context Identifier bits
111 = Reserved
•
•
•
011 = Reserved
010 = Alternate Working Register Set 2 is currently in use
001 = Alternate Working Register Set 1 is currently in use
000 = Default register set is currently in use

bit 7-3 **Unimplemented:** Read as '0'

bit 2-0 **MCTXI<2:0>:** Manual (W Register) Context Identifier bits
111 = Reserved
•
•
•
011 = Reserved
010 = Alternate Working Register Set 2 was most recently manually selected
001 = Alternate Working Register Set 1 was most recently manually selected
000 = Default register set was most recently manually selected

TABLE 4-45: FUNDAMENTAL ADDRESSING MODES SUPPORTED

Addressing Mode	Description
File Register Direct	The address of the file register is specified explicitly.
Register Direct	The contents of a register are accessed directly.
Register Indirect	The contents of Wn form the Effective Address (EA).
Register Indirect Post-Modified	The contents of Wn form the EA. Wn is post-modified (incremented or decremented) by a constant value.
Register Indirect Pre-Modified	Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA.
Register Indirect with Register Offset (Register Indexed)	The sum of Wn and Wb forms the EA.
Register Indirect with Literal Offset	The sum of Wn and a literal forms the EA.

4.4.3 MOVE AND ACCUMULATOR INSTRUCTIONS

Move instructions and the DSP accumulator class of instructions provide a greater addressing flexibility than other instructions. In addition to the addressing modes supported by most MCU instructions, move and accumulator instructions also support Register Indirect with Register Offset Addressing mode, also referred to as Register Indexed mode.

Note: For the MOV instructions, the addressing mode specified in the instruction can differ for the source and destination EA. However, the 4-bit Wb (Register Offset) field is shared by both source and destination (but typically only used by one).

In summary, the following addressing modes are supported by move and accumulator instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-Modified
- Register Indirect Pre-Modified
- Register Indirect with Register Offset (Indexed)
- Register Indirect with Literal Offset
- 8-Bit Literal
- 16-Bit Literal

Note: Not all instructions support all the addressing modes given above. Individual instructions may support different subsets of these addressing modes.

4.4.4 MAC INSTRUCTIONS

The dual source operand DSP instructions (CLR, ED, EDAC, MAC, MPY, MPY.N, MOVSAC and MSC), also referred to as MAC instructions, use a simplified set of addressing modes to allow the user application to effectively manipulate the Data Pointers through register indirect tables.

The Two-Source Operand Prefetch registers must be members of the set, {W8, W9, W10, W11}. For data reads, W8 and W9 are always directed to the X RAGU, and W10 and W11 are always directed to the Y AGU. The Effective Addresses generated (before and after modification) must, therefore, be valid addresses within X Data Space for W8 and W9, and Y Data Space for W10 and W11.

Note: Register Indirect with Register Offset Addressing mode is available only for W9 (in X Data Space) and W11 (in Y Data Space).

In summary, the following addressing modes are supported by the MAC class of instructions:

- Register Indirect
- Register Indirect Post-Modified by 2
- Register Indirect Post-Modified by 4
- Register Indirect Post-Modified by 6
- Register Indirect with Register Offset (Indexed)

4.4.5 OTHER INSTRUCTIONS

Besides the addressing modes outlined previously, some instructions use literal constants of various sizes. For example, BRA (Branch) instructions use 16-bit signed literals to specify the Branch destination directly, whereas the DISI instruction uses a 14-bit unsigned literal field. In some instructions, such as ULNK, the source of an operand or result is implied by the opcode itself. Certain operations, such as a NOP, do not have any operands.

REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
T5MD	T4MD	T3MD	T2MD	T1MD	—	PWMMD	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	C1MD(1)	AD1MD
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **T5MD:** Timer5 Module Disable bit
1 = Timer5 module is disabled
0 = Timer5 module is enabled

bit 14 **T4MD:** Timer4 Module Disable bit
1 = Timer4 module is disabled
0 = Timer4 module is enabled

bit 13 **T3MD:** Timer3 Module Disable bit
1 = Timer3 module is disabled
0 = Timer3 module is enabled

bit 12 **T2MD:** Timer2 Module Disable bit
1 = Timer2 module is disabled
0 = Timer2 module is enabled

bit 11 **T1MD:** Timer1 Module Disable bit
1 = Timer1 module is disabled
0 = Timer1 module is enabled

bit 10 **Unimplemented:** Read as '0'

bit 9 **PWMMD:** PWM Module Disable bit
1 = PWM module is disabled
0 = PWM module is enabled

bit 8 **Unimplemented:** Read as '0'

bit 7 **I2C1MD:** I2C1 Module Disable bit
1 = I2C1 module is disabled
0 = I2C1 module is enabled

bit 6 **U2MD:** UART2 Module Disable bit
1 = UART2 module is disabled
0 = UART2 module is enabled

bit 5 **U1MD:** UART1 Module Disable bit
1 = UART1 module is disabled
0 = UART1 module is enabled

bit 4 **SPI2MD:** SPI2 Module Disable bit
1 = SPI2 module is disabled
0 = SPI2 module is enabled

bit 3 **SPI1MD:** SPI1 Module Disable bit
1 = SPI1 module is disabled
0 = SPI1 module is enabled

Note 1: This bit is available on dsPIC33EVXXXGM10X devices only.

REGISTER 11-7: RPINR12: PERIPHERAL PIN SELECT INPUT REGISTER 12

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT2R7	FLT2R6	FLT2R5	FLT2R4	FLT2R3	FLT2R2	FLT2R1	FLT2R0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT1R7	FLT1R6	FLT1R5	FLT1R4	FLT1R3	FLT1R2	FLT1R1	FLT1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **FLT2R<7:0>:** Assign PWM Fault 2 (FLT2) to the Corresponding RPn Pin bits
(see Table 11-2 for input pin selection numbers)
10110101 = Input tied to RPI181
•
•
•
00000001 = Input tied to CMP1
00000000 = Input tied to Vss

bit 7-0 **FLT1R<7:0>:** Assign PWM Fault 1 (FLT1) to the Corresponding RPn Pin bits
(see Table 11-2 for input pin selection numbers)
10110101 = Input tied to RPI181
•
•
•
00000001 = Input tied to CMP1
00000000 = Input tied to Vss

REGISTER 11-20: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP39R5	RP39R4	RP39R3	RP39R2	RP39R1	RP39R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP38R5	RP38R4	RP38R3	RP38R2	RP38R1	RP38R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP39R<5:0>:** Peripheral Output Function is Assigned to RP39 Output Pin bits (see Table 11-3 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP38R<5:0>:** Peripheral Output Function is Assigned to RP38 Output Pin bits (see Table 11-3 for peripheral function numbers)

REGISTER 11-21: RPOR3: PERIPHERAL PIN SELECT OUTPUT REGISTER 3

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP41R5	RP41R4	RP41R3	RP41R2	RP41R1	RP41R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP40R5	RP40R4	RP40R3	RP40R2	RP40R1	RP40R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP41R<5:0>:** Peripheral Output Function is Assigned to RP41 Output Pin bits (see Table 11-3 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP40R<5:0>:** Peripheral Output Function is Assigned to RP40 Output Pin bits (see Table 11-3 for peripheral function numbers)

REGISTER 11-28: RPOR10: PERIPHERAL PIN SELECT OUTPUT REGISTER 10

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP176R5	RP176R4	RP176R3	RP176R2	RP176R1	RP176R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP120R5(1)	RP120R4(1)	RP120R3(1)	RP120R2(1)	RP120R1(1)	RP120R0(1)
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP176R<5:0>:** Peripheral Output Function is Assigned to RP176 Output Pin bits (see Table 11-3 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP120R<5:0>:** Peripheral Output Function is Assigned to RP120 Output Pin bits(1) (see Table 11-3 for peripheral function numbers)

Note 1: RP120R<5:0> is present in dsPIC33EVXXXGM006/106 devices only.

REGISTER 11-29: RPOR11: PERIPHERAL PIN SELECT OUTPUT REGISTER 11

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP178R5	RP178R4	RP178R3	RP178R2	RP178R1	RP178R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP177R5	RP177R4	RP177R3	RP177R2	RP177R1	RP177R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP178R<5:0>:** Peripheral Output Function is Assigned to RP178 Output Pin bits (see Table 11-3 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP177R<5:0>:** Peripheral Output Function is Assigned to RP177 Output Pin bits (see Table 11-3 for peripheral function numbers)

REGISTER 17-13: IOCONx: PWMx I/O CONTROL REGISTER(2)

R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PENH	PENL	POLH	POLL	PMOD1(1)	PMOD0(1)	OVRENH	OVRENL
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OVRDAT1	OVRDAT0	FLTDAT1	FLTDAT0	CLDAT1	CLDAT0	SWAP	OSYNC
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **PENH:** PWMxH Output Pin Ownership bit
1 = PWMx module controls the PWMxH pin
0 = GPIO module controls the PWMxH pin

bit 14 **PENL:** PWMxL Output Pin Ownership bit
1 = PWMx module controls the PWMxL pin
0 = GPIO module controls the PWMxL pin

bit 13 **POLH:** PWMxH Output Pin Polarity bit
1 = PWMxH pin is active-low
0 = PWMxH pin is active-high

bit 12 **POLL:** PWMxL Output Pin Polarity bit
1 = PWMxL pin is active-low
0 = PWMxL pin is active-high

bit 11-10 **PMOD<1:0>:** PWMx I/O Pin Mode bits(1)
11 = Reserved; do not use
10 = PWMx I/O pin pair is in the Push-Pull Output mode
01 = PWMx I/O pin pair is in the Redundant Output mode
00 = PWMx I/O pin pair is in the Complementary Output mode

bit 9 **OVRENH:** Override Enable for PWMxH Pin bit
1 = OVRDAT1 controls the output on the PWMxH pin
0 = PWMx generator controls the PWMxH pin

bit 8 **OVRENL:** Override Enable for PWMxL Pin bit
1 = OVRDAT0 controls the output on the PWMxL pin
0 = PWMx generator controls the PWMxL pin

bit 7-6 **OVRDAT<1:0>:** Data for PWMxH, PWMxL Pins if Override is Enabled bits
If OVERENH = 1, PWMxH is driven to the state specified by OVRDAT1.
If OVERENL = 1, PWMxL is driven to the state specified by OVRDAT0.

bit 5-4 **FLTDAT<1:0>:** Data for PWMxH and PWMxL Pins if FLTMOD is Enabled bits
If Fault is active, PWMxH is driven to the state specified by FLTDAT1.
If Fault is active, PWMxL is driven to the state specified by FLTDAT0.

bit 3-2 **CLDAT<1:0>:** Data for PWMxH and PWMxL Pins if CLMOD is Enabled bits
If current limit is active, PWMxH is driven to the state specified by CLDAT1.
If current limit is active, PWMxL is driven to the state specified by CLDAT0.

Note 1: These bits should not be changed after the PWMx module is enabled (PTEN = 1).
2: If the PWMLOCK Configuration bit (FDEVOPT<0>) is a '1', the IOCONx register can only be written after the unlock sequence has been executed.

REGISTER 17-17: LEBDLYx: PWMx LEADING-EDGE BLANKING DELAY REGISTER

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	LEB<11:8>			
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
LEB<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Unimplemented:** Read as '0'

bit 11-0 **LEB<11:0>:** Leading-Edge Blanking Delay for Current-Limit and Fault Inputs bits

20.3 Receive Mode

The module can be configured for receive operation by setting the RCVEN (SENTxCON1<11>) bit. The time between each falling edge is compared to SYNCMIN<15:0> (SENTxCON3<15:0>) and SYNCMAX<15:0> (SENTxCON2<15:0>), and if the measured time lies between the minimum and maximum limits, the module begins to receive data. The validated Sync time is captured in the SENTxSYNC register and the tick time is calculated. Subsequent falling edges are verified to be within the valid data width and the data is stored in the SENTxDATH/L register. An interrupt event is generated at the completion of the message and the user software should read the SENTx Data register before the reception of the next nibble. The equation for SYNCMIN<15:0> and SYNCMAX<15:0> is shown in Equation 20-3.

EQUATION 20-3: SYNCMIN<15:0> AND SYNCMAX<15:0> CALCULATIONS

$$T_{TICK} = T_{CLK} \bullet (TICKTIME\langle 15{:}0\rangle + 1)$$

$$FRAMETIME\langle 15{:}0\rangle = T_{TICK}/T_{FRAME}$$

$$SyncCount = 8 \times F_{RCV} \times T_{TICK}$$

$$SYNCMIN\langle 15{:}0\rangle = 0.8 \times SyncCount$$

$$SYNCMAX\langle 15{:}0\rangle = 1.2 \times SyncCount$$

$$FRAMETIME\langle 15{:}0\rangle \geq 122 + 27N$$

$$FRAMETIME\langle 15{:}0\rangle \geq 848 + 12N$$

Where:
T_{FRAME} = Total time of the message from ms
N = The number of data nibbles in message, 1-6
F_{RCV} = FCY x prescaler
T_{CLK} = FCY/Prescaler

For TTICK = 3.0 µs and FCLK = 4 MHz, SYNCMIN<15:0> = 76.

Note: To ensure a Sync period can be identified, the value written to SYNCMIN<15:0> must be less than the value written to SYNCMAX<15:0>.

20.3.1 RECEIVE MODE CONFIGURATION

20.3.1.1 Initializing the SENTx Module:

Perform the following steps to initialize the module:

1. Write RCVEN (SENTxCON1<11>) = 1 for Receive mode.
2. Write NIBCNT<2:0> (SENTxCON1<2:0>) for the desired data frame length.
3. Write CRCEN (SENTxCON1<8>) for hardware or software CRC validation.
4. Write PPP (SENTxCON1<7>) = 1 if pause pulse is present.
5. Write SENTxCON2 with the value of SYNCMAXx (Nominal Sync Period + 20%).
6. Write SENTxCON3 with the value of SYNCMINx (Nominal Sync Period – 20%).
7. Enable interrupts and set interrupt priority.
8. Set the SNTEN (SENTxCON1<15>) bit to enable the module.

The data should be read from the SENTxDATH/L register after the completion of the CRC and before the next message frame's status nibble. The recommended method is to use the message frame completion interrupt trigger.

27.2 User OTP Memory

Locations, 800F80h-800FFEh, are a One-Time-Programmable (OTP) memory area. The user OTP words can be used for storing product information, such as serial numbers, system manufacturing dates, manufacturing lot numbers and other application-specific information.

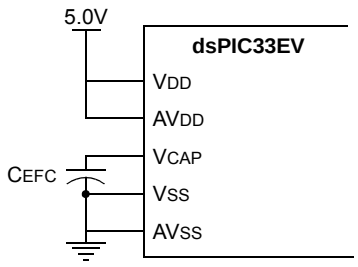
27.3 On-Chip Voltage Regulator

All of the dsPIC33EVXXXGM00X/10X family devices power their core digital logic at a nominal 1.8V. This can create a conflict for designs that are required to operate at a higher typical voltage, such as 5.0V. To simplify system design, all devices in the dsPIC33EVXXXGM00X/10X family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator provides power to the core from the other VDD pins. A low-ESR (less than 1 Ohm) capacitor (such as tantalum or ceramic) must be connected to the VCAP pin (see Figure 27-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in Table 30-5, located in **Section 30.0 "Electrical Characteristics"**.

Note:	It is important for the low-ESR capacitor to be placed as close as possible to the VCAP pin.

FIGURE 27-1: CONNECTIONS FOR THE ON-CHIP VOLTAGE REGULATOR(1,2,3)



Note 1: These are typical operating voltages. Refer to Table 30-4 located in **Section 30.1 "DC Characteristics"** for the full operating ranges of VDD and VCAP.

2: It is important for the low-ESR capacitor to be placed as close as possible to the VCAP pin.

3: Typical VCAP pin voltage = 1.8V when VDD ≥ VDDMIN.

27.4 Brown-out Reset (BOR)

The Brown-out Reset (BOR) module is based on an internal voltage reference circuit that monitors the regulated supply voltage, VCAP. The main purpose of the BOR module is to generate a device Reset when a brown-out condition occurs. Brown-out conditions are generally caused by glitches on the AC mains (for example, missing portions of the AC cycle waveform due to bad power transmission lines or voltage sags due to excessive current draw when a large inductive load is turned on).

A BOR generates a Reset pulse, which resets the device. The BOR selects the clock source based on the device Configuration bit values (FNOSC<2:0> and POSCMD<1:0>).

If an oscillator mode is selected, the BOR activates the Oscillator Start-up Timer (OST). The system clock is held until OST expires. If the PLL is used, the clock is held until the LOCK bit (OSCCON<5>) is '1'.

Concurrently, the Power-up Timer (PWRT) Time-out (TPWRT) is applied before the internal Reset is released. If TPWRT = 0 and a crystal oscillator is being used, then a nominal delay of TFSCM is applied. The total delay in this case is TFSCM. Refer to Parameter SY35 in Table 30-22 of **Section 30.0 "Electrical Characteristics"** for specific TFSCM values.

The BOR status bit (RCON<1>) is set to indicate that a BOR has occurred. The BOR circuit continues to operate while in Sleep or Idle mode and resets the device should VDD fall below the BOR threshold voltage.

TABLE 30-13: DC CHARACTERISTICS: PROGRAM MEMORY

DC CHARACTERISTICS			Standard Operating Conditions: 4.5V to 5.5V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	**Symbol**	**Characteristic**	**Min.**	**Typ.(1)**	**Max.**	**Units**	**Conditions**
		Program Flash Memory					
D130	EP	Cell Endurance	10,000	—	—	E/W	-40°C to +125°C
D131	VPR	VDD for Read	4.5	—	5.5	V	
D132b	VPEW	VDD for Self-Timed Write	4.5	—	5.5	V	
D134	TRETD	Characteristic Retention	20	—	—	Year	Provided no other specifications are violated, -40°C to +125°C
D135	IDDP	Supply Current During Programming	—	10	—	mA	
D136a	TRW	Row Write Cycle Time	0.657	—	0.691	ms	TRW = 4965 FRC cycles, TA = +85°C (see **Note 2)**
D136b	TRW	Row Write Cycle Time	0.651	—	0.698	ms	TRW = 4965 FRC cycles, TA = +125°C (see **Note 2)**
D137a	TPE	Page Erase Time	19.44	—	20.44	ms	TPE = 146893 FRC cycles, TA = +85°C (see **Note 2)**
D137b	TPE	Page Erase Time	19.24	—	20.65	ms	TPE = 146893 FRC cycles, TA = +125°C (see **Note 2)**
D138a	TWW	Word Write Cycle Time	45.78	—	48.15	µs	TWW = 346 FRC cycles, TA = +85°C (see **Note 2)**
D138b	TWW	Word Write Cycle Time	45.33	—	48.64	µs	TWW = 346 FRC cycles, TA = +125°C (see **Note 2)**

Note 1: Data in “Typ.” column is at 5.0V, +25°C unless otherwise stated.

2: Other conditions: FRC = 7.3728 MHz, TUN<5:0> = b'011111 (for Min), TUN<5:0> = b'100000 (for Max). This parameter depends on the FRC accuracy (see Table 30-20) and the value of the FRC Oscillator Tuning register.

TABLE 30-14: ELECTRICAL CHARACTERISTICS: INTERNAL BAND GAP REFERENCE VOLTAGE

DC CHARACTERISTICS			Standard Operating Conditions: 4.5V to 5.5V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	**Symbol**	**Characteristic**	**Min.**	**Typ.**	**Max.**	**Units**	**Conditions**
DVR10	VBG	Internal Band Gap Reference Voltage	1.14	1.2	1.26	V	

FIGURE 32-5: TYPICAL IDD vs. VDD (EC MODE, 60 MIPS)

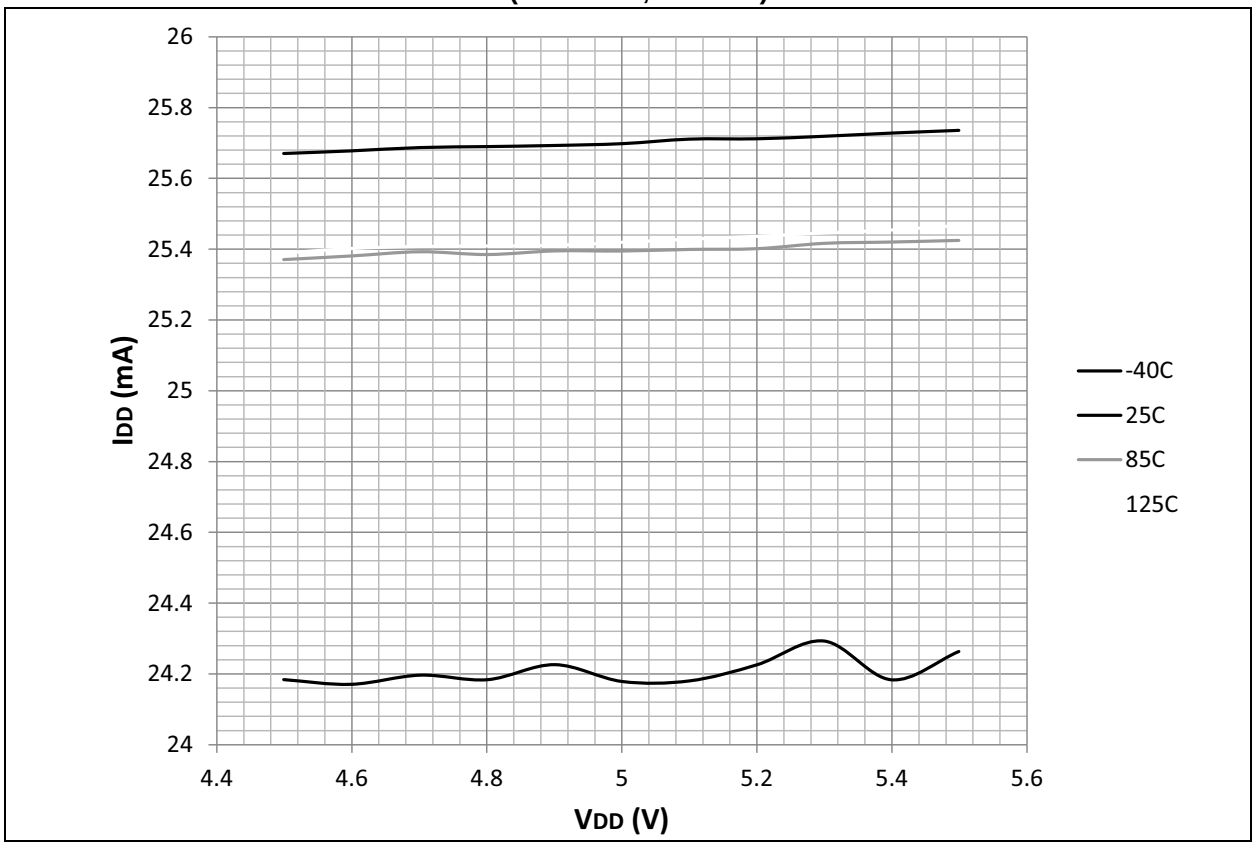


FIGURE 32-6: TYPICAL IDD vs. VDD (EC MODE, 70 MIPS)

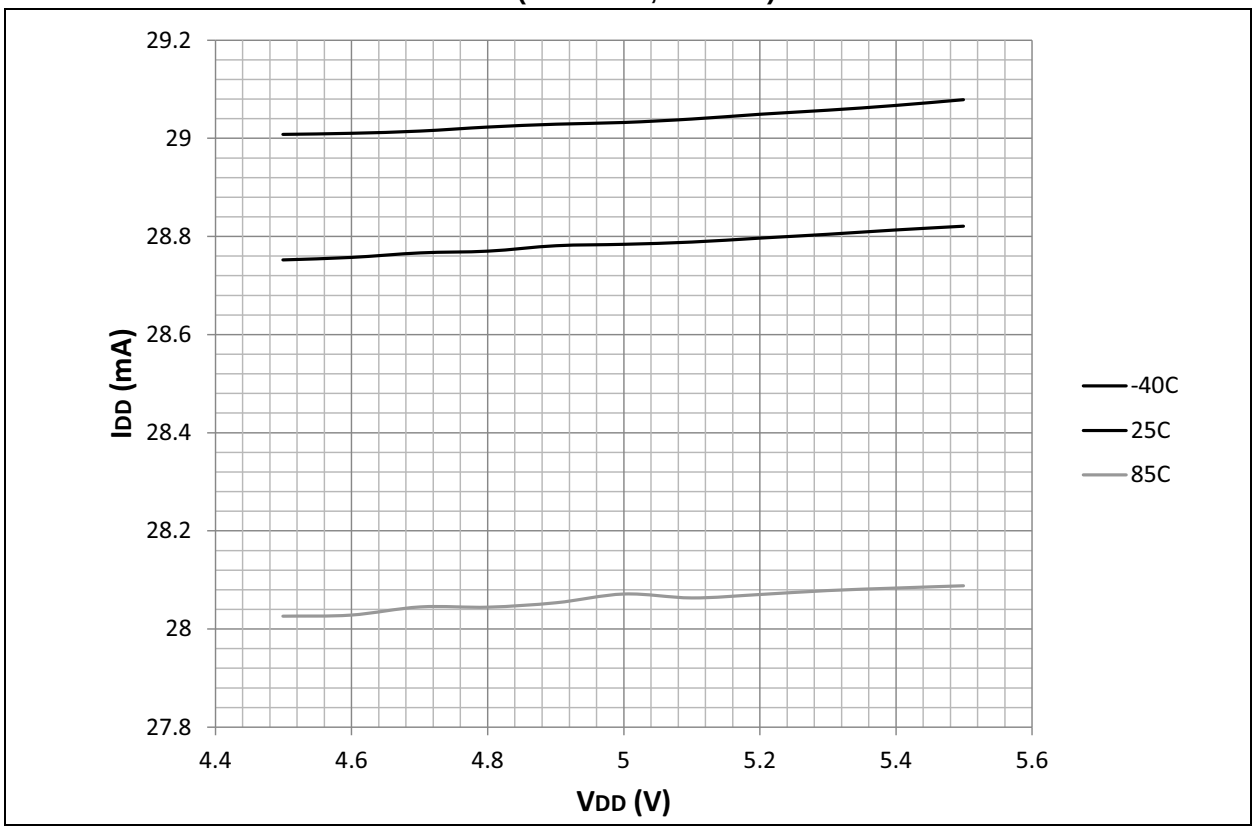
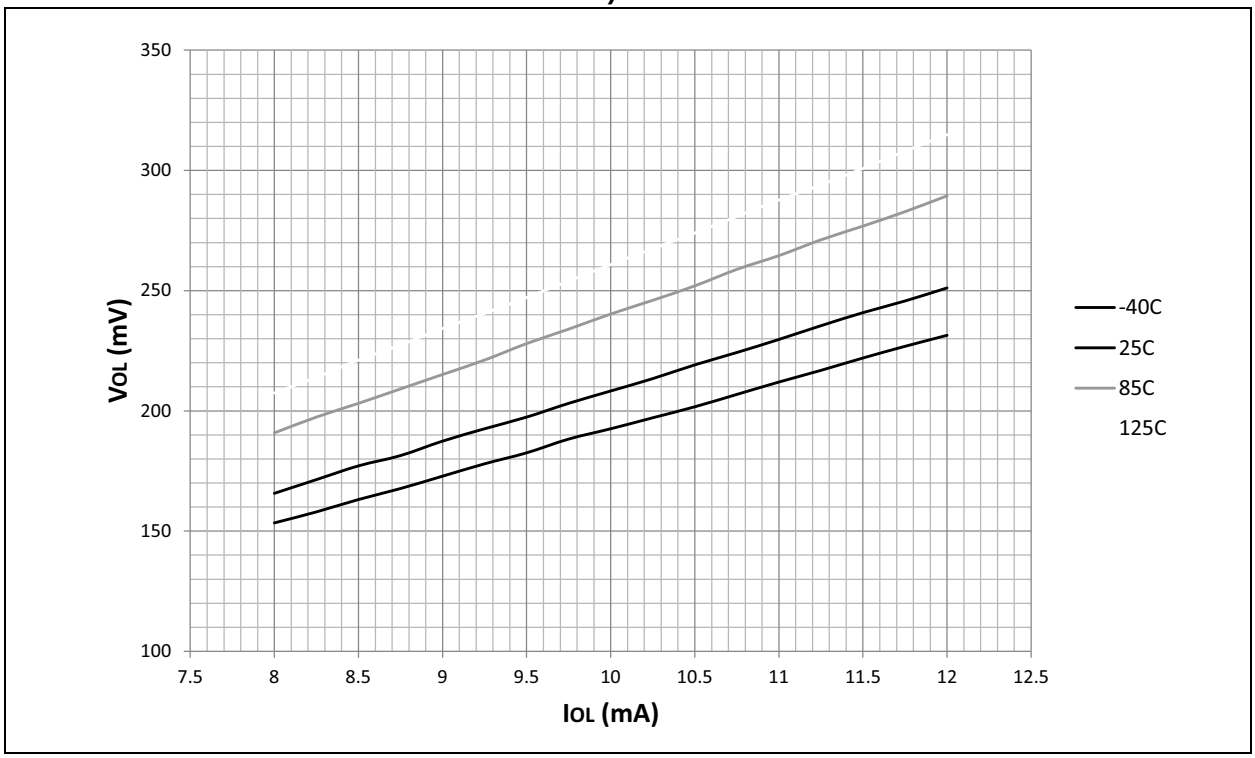
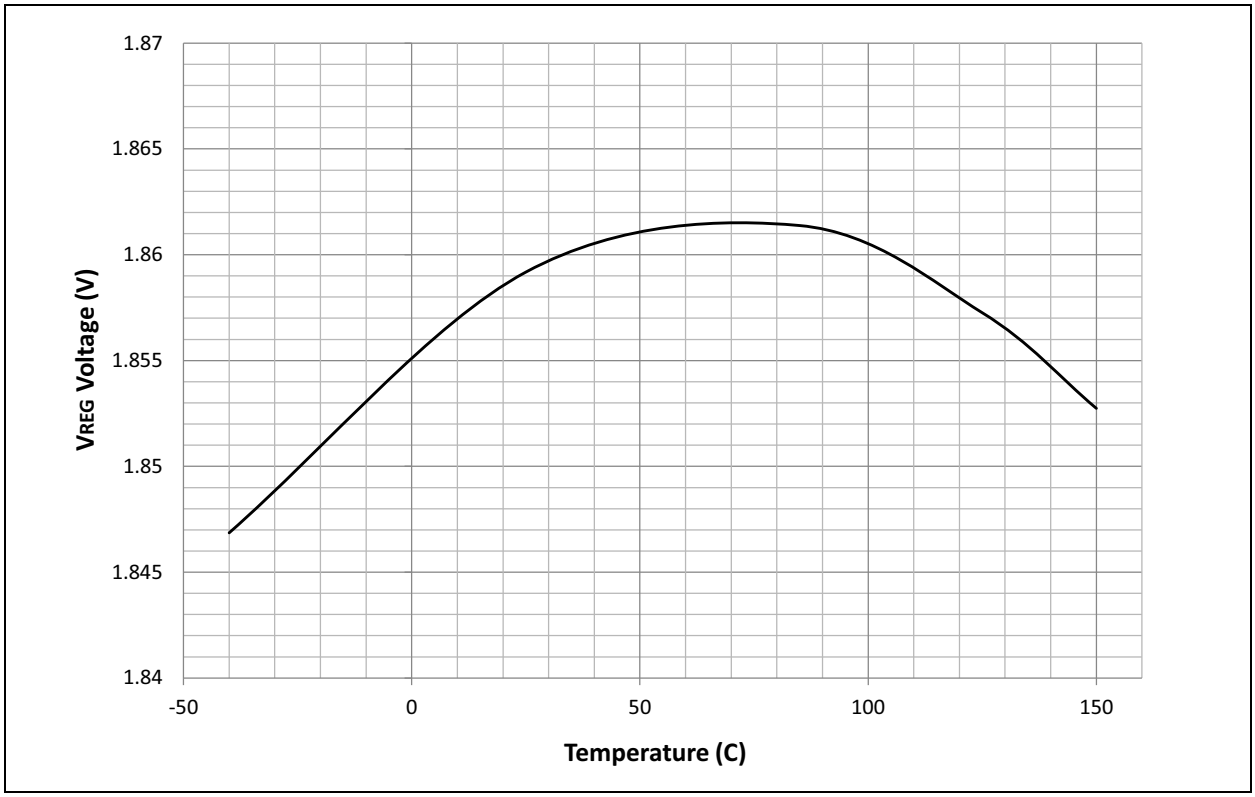


FIGURE 32-33: TYPICAL VOL 4x DRIVER PINS vs. IOL (GENERAL PURPOSE I/Os, TEMPERATURES AS NOTED)



32.11 VREG

FIGURE 32-34: TYPICAL REGULATOR VOLTAGE vs. TEMPERATURE



32.17 ADC DNL

FIGURE 32-41: TYPICAL DNL (V_{DD} = 5.5V, -40°C)

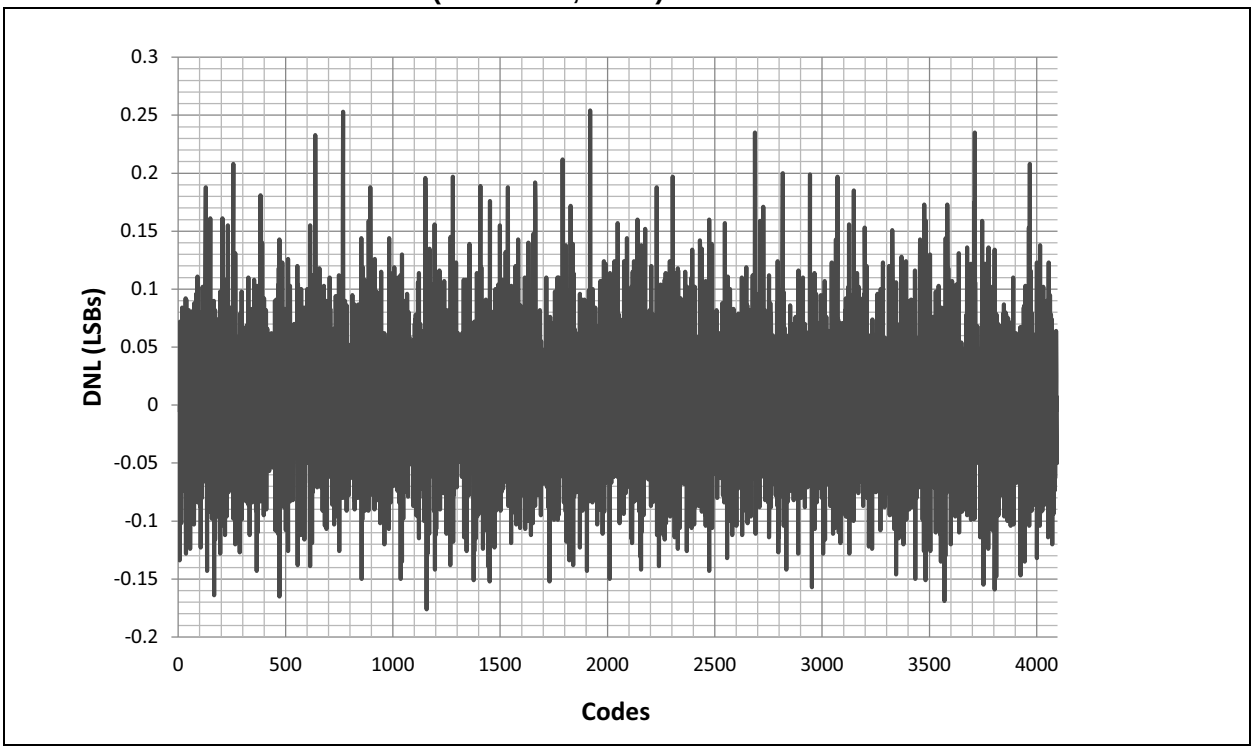


FIGURE 32-42: TYPICAL DNL (V_{DD} = 5.5V, +25°C)

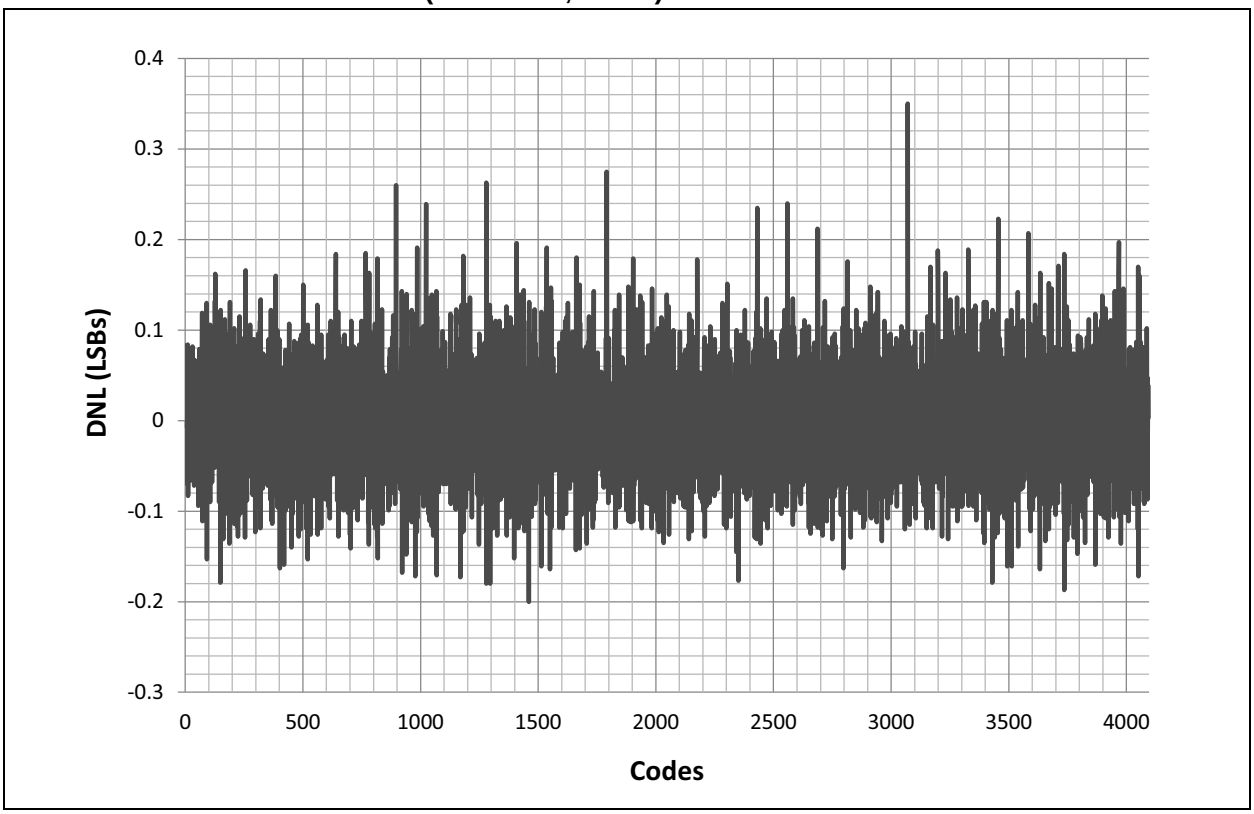


FIGURE 32-47: TYPICAL INL (V_{DD} = 5.5V, +85°C)

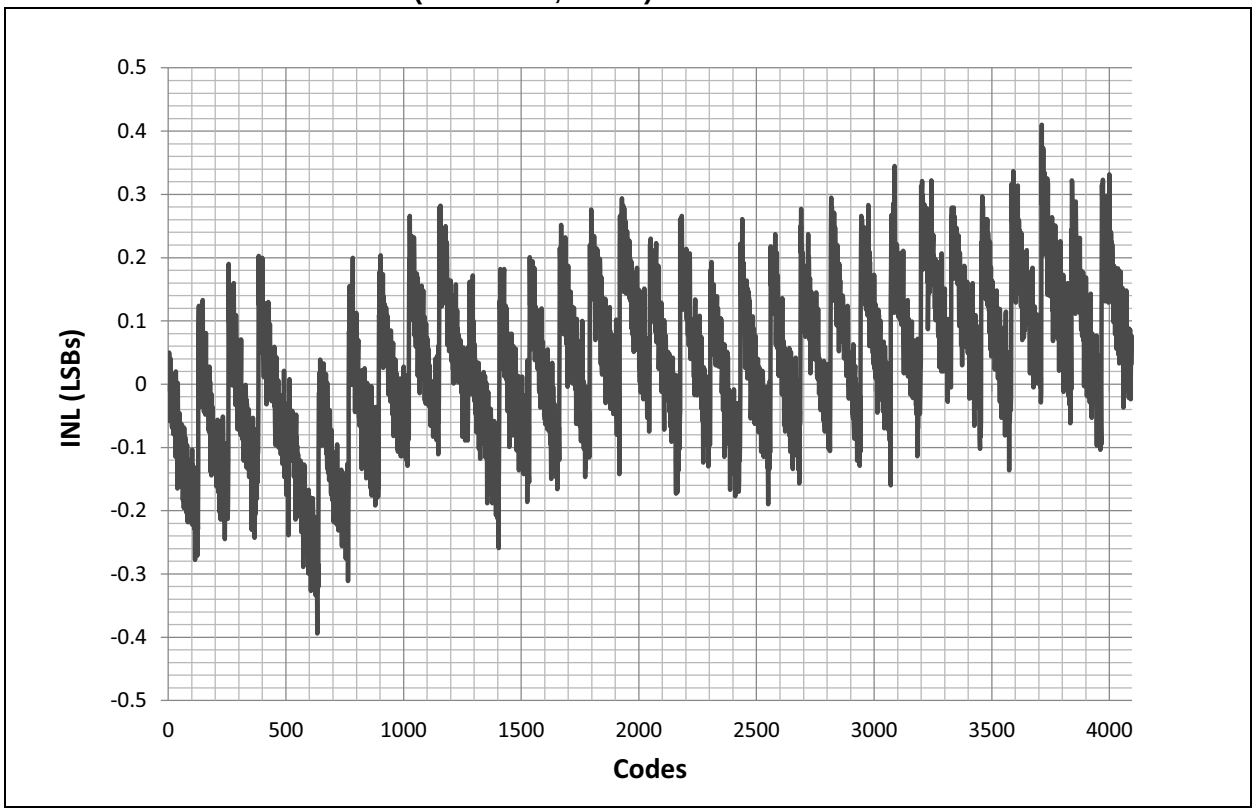
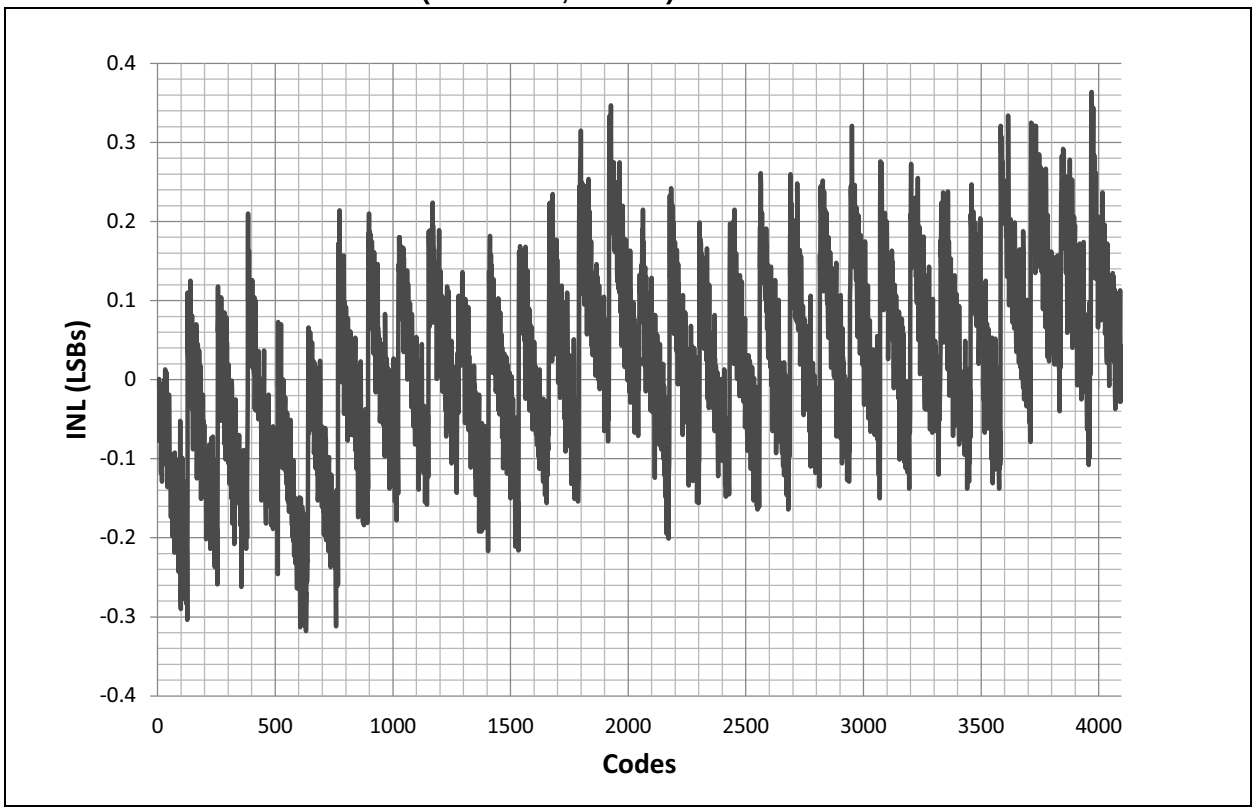


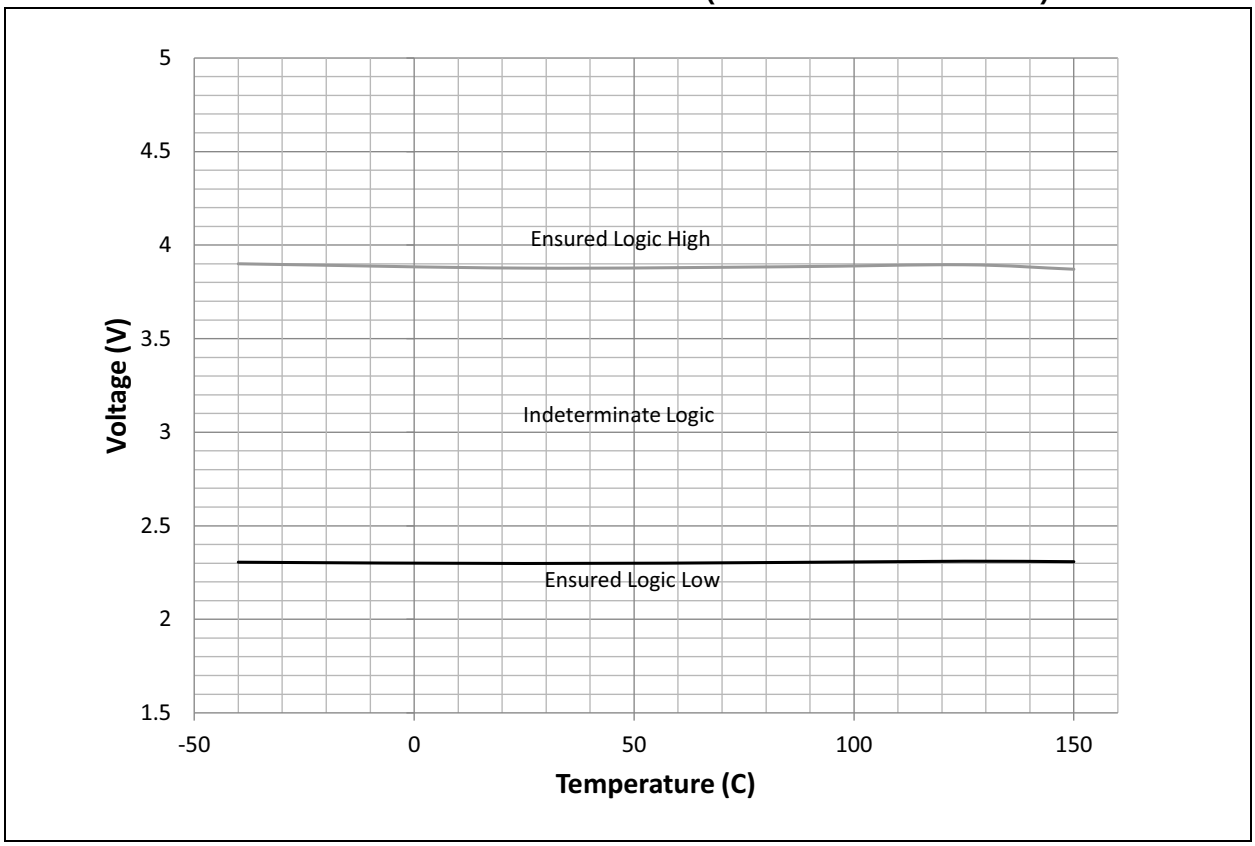
FIGURE 32-48: TYPICAL INL (V_{DD} = 5.5V, +125°C)



NOTES:

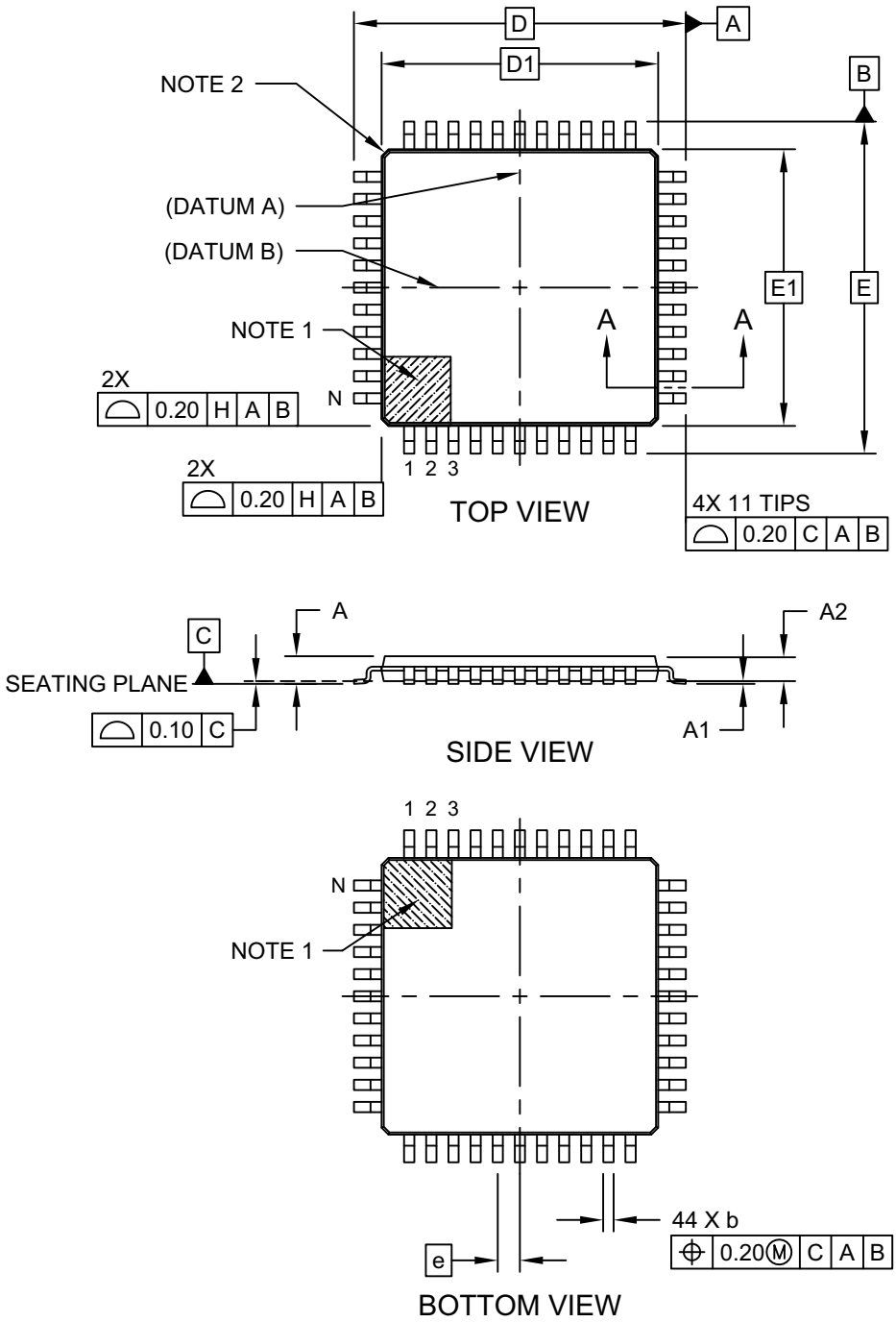
33.9 Voltage Input High (VIH) – Voltage Input Low (VIL)

FIGURE 33-25: TYPICAL VIH/VIL vs. TEMPERATURE (GENERAL PURPOSE I/Os)



44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-076C Sheet 1 of 2

APPENDIX A: REVISION HISTORY

Revision A (December 2013)

This is the initial version of this document.

Revision B (June 2014)

This revision incorporates the following updates:

- Sections:
  - Added **Section 31.0 “High-Temperature Electrical Characteristics”**
  - Updated the **“Power Management”**section, the **“Input/Output”** section, **Section 3.3 “Data Space Addressing”**, **Section 4.2 “Data Address Space”**, **Section 4.3.2 “Extended X Data Space”**, **Section 4.6.1 “Bit-Reversed Addressing Implementation”**, **Section 7.4.1 “INTCON1 through INTCON4”**, **Section 11.7 “I/O Helpful Tips”**
  - Updated note in **Section 17.0 “High-Speed PWM Module”**, **Section 18.0 “Serial Peripheral Interface (SPI)”**, **Section 27.8 “Code Protection and CodeGuard™ Security”**
  - Updated title of **Section 20.0 “Single-Edge Nibble Transmission (SENT)”**
  - Updated **Section 34.0 “Packaging Information”**. Deleted e3, Pb-free and Industrial (I) temperature range indication throughout the section, and updated the packaging diagrams
  - Updated the **“Product Identification System”** section
- Registers:
  - Updated Register 3-2, Register 7-2, Register 7-6, Register 9-2, Register 11-3, Register 14-1, Register 14-3, Register 14-11, Register 15-1, Register 22-4
- Figures:
  - Added Figure 4-6, Figure 4-8, Figure 4-14, Figure 4-15, Figure 14-1, Figure 16-1, Figure 17-2, Figure 23-1, Figure 24-1
- Tables:
  - Updated Table 1, Table 27-1, Table 27-2, Table 30-6, Table 30-7, Table 30-8, Table 30-9, Table 30-10, Table 30-11, Table 30-12, Table 30-38, Table 30-50, Table 30-53 and added Table 31-11,
- Changes to text and formatting were incorporated throughout the document

Revision C (November 2014)

This revision incorporates the following updates:

- Sections:
  - Added note in **Section 5.2 “RTSP Operation”**
  - Updated “**Section 5.4 “Error Correcting Code (ECC)”**
  - Deleted 44-Terminal Very Thin Leadless Array Package (TL) - 6x6x0.9 mm Body With Exposed Pad (VTLA).
- Registers
  - Updated Register 7-6
- Figures:
  - Updated Figure 4-1, Figure 4-3, Figure 4-4
- Tables:
  - Updated Table 27-2, Table 31-13, Table 31-14, Table 31-15
  - Added Table 31-16, Table 31-17

Revision D (April 2015)

This revision incorporates the following updates:

- Sections:
  - Updated the Clock Management, Timers/ Output Compare/Input Capture, Communication Interfaces and Input/Output sections at the beginning of the data sheet (Page 1 and Page 2).
  - Updated all pin diagrams at the beginning of the data sheet (Page 4 through Page 9).
  - Added **Section 11.6 “High-Voltage Detect (HVD)”**
  - Updated **Section 13.0 “Timer2/3 and Timer4/5”**
  - Corrects all Buffer heading numbers in **Section 22.4 “CAN Message Buffers”**
- Registers
  - Updated Register 3-2, Register 25-2, Register 26-2
- Figures
  - Updated Figure 26-1, Figure 30-5, Figure 30-32
- Tables
  - Updated Table 1, Table 4-25, Table 30-10, Table 30-22, Table 30-53 and Table 31-8
- Changes to text and formatting were incorporated throughout the document