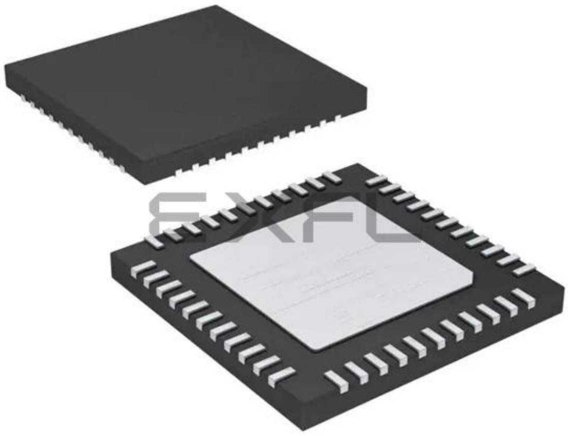
Microchip Technology - DSPIC33EV256GM104T-I/ML Datasheet



Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

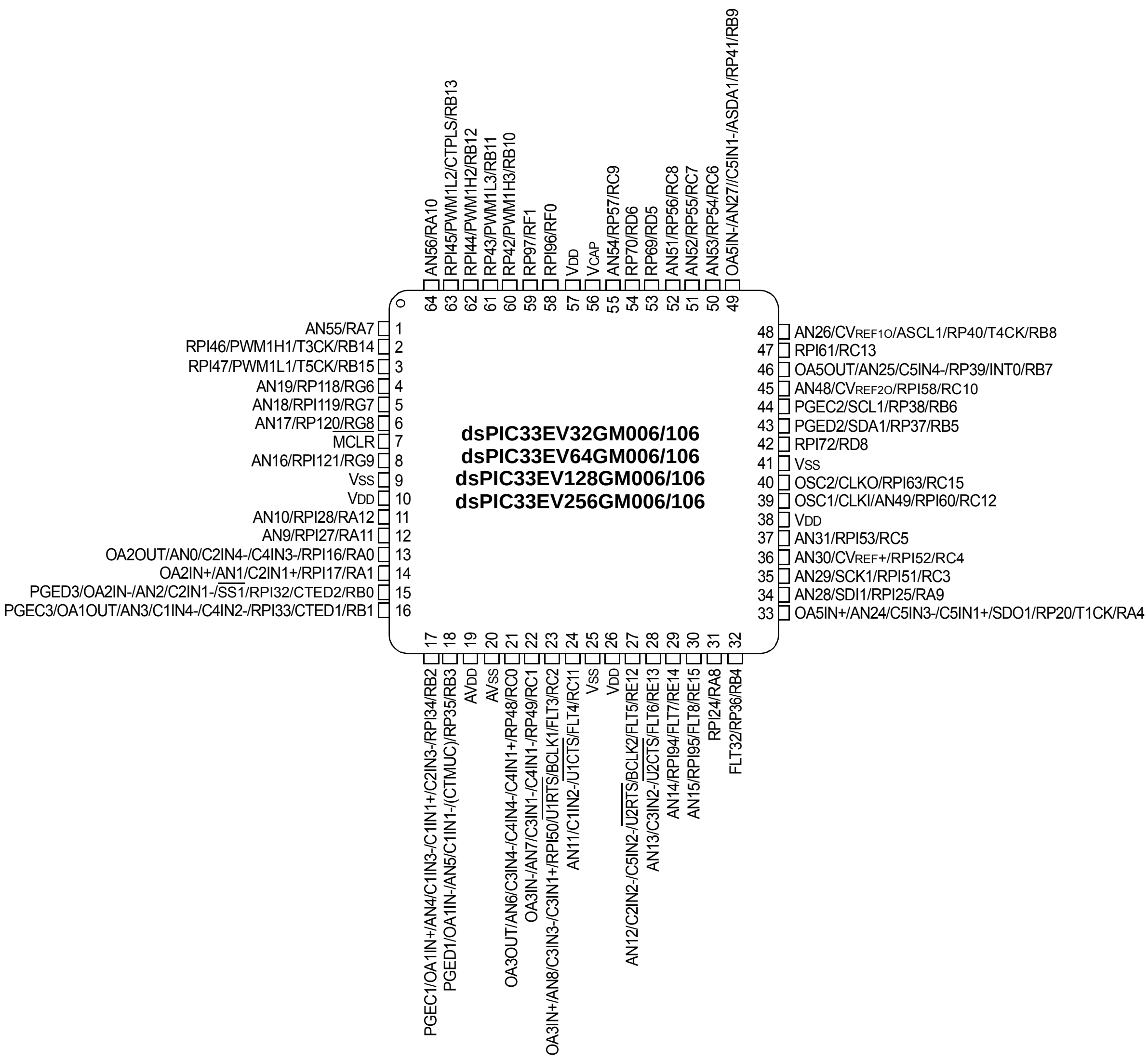
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	CANbus, I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	35
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 24x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-QFN (8x8)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ev256gm104t-i-ml

Pin Diagrams (Continued)

64-Pin TQFP(1,2,3)



Note 1: The RPn/RPIn pins can be used by any remappable peripheral with some limitation. See **Section 11.5 "Peripheral Pin Select (PPS)"** for available peripherals and information on limitations.

2: Every I/O port pin (RAx-RGx) can be used as a Change Notification pin (CNAx-CNGx). See **Section 11.0 "I/O Ports"** for more information.

3: If the op amp is selected when OPAEN (CMxCON<10>) = 1, the OAx input is used; otherwise, the ANx input is used.

3.7 Arithmetic Logic Unit (ALU)

The dsPIC33EVXXXGM00X/10X family ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are two's complement in nature. Depending on the operation, the ALU can affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as $\overline{\text{Borrow}}$ and $\overline{\text{Digit Borrow}}$ bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. The data for the ALU operation can come from the W register array or from the data memory, depending on the addressing mode of the instruction. Similarly, the output data from the ALU can be written to the W register array or a data memory location.

For information on the SR bits affected by each instruction, refer to the *"16-bit MCU and DSC Programmer's Reference Manual"* (DS70157).

The core CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

3.7.1 MULTIPLIER

Using the high-speed, 17-bit x 17-bit multiplier, the ALU supports unsigned, signed or mixed-sign operation in several MCU multiplication modes:

- 16-bit x 16-bit signed
- 16-bit x 16-bit unsigned
- 16-bit signed x 5-bit (literal) unsigned
- 16-bit signed x 16-bit unsigned
- 16-bit unsigned x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit signed
- 8-bit unsigned x 8-bit unsigned

3.7.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

- 32-bit signed/16-bit signed divide
- 32-bit unsigned/16-bit unsigned divide
- 16-bit signed/16-bit signed divide
- 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. The 16-bit signed and unsigned `DIV` instructions can specify any W register for both the 16-bit divisor (Wn) and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes the single-cycle per bit of the divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

3.8 DSP Engine

The DSP engine consists of a high-speed, 17-bit x 17-bit multiplier, a 40-bit barrel shifter and a 40-bit adder/subtracter (with two target accumulators, round and saturation logic).

The DSP engine can also perform inherent accumulator-to-accumulator operations that require no additional data. These instructions are `ADD`, `SUB` and `NEG`.

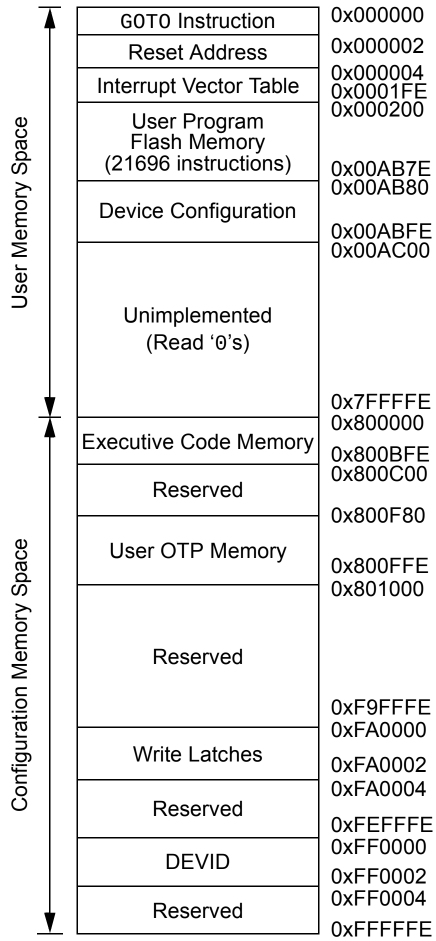
The DSP engine has options selected through bits in the CPU Core Control register (CORCON) as follows:

- Fractional or Integer DSP Multiply (IF)
- Signed, Unsigned or Mixed-Sign DSP Multiply (US)
- Conventional or Convergent Rounding (RND)
- Automatic Saturation On/Off for ACCA (SATA)
- Automatic Saturation On/Off for ACCB (SATB)
- Automatic Saturation On/Off for Writes to Data Memory (SATDW)
- Accumulator Saturation mode Selection (ACCSAT)

TABLE 3-2: DSP INSTRUCTIONS SUMMARY

Instruction	Algebraic Operation	ACC Write Back
`CLR`	$A = 0$	Yes
`ED`	$A = (x - y)^2$	No
`EDAC`	$A = A + (x - y)^2$	No
`MAC`	$A = A + (x \bullet y)$	Yes
`MAC`	$A = A + x^2$	No
`MOVSAC`	No change in A	Yes
`MPY`	$A = x \bullet y$	No
`MPY`	$A = x^2$	No
`MPY.N`	$A = - x \bullet y$	No
`MSC`	$A = A - x \bullet y$	Yes

FIGURE 4-2: PROGRAM MEMORY MAP FOR dsPIC33EV64GM00X/10X DEVICES(1)



Note 1: Memory areas are not shown to scale.

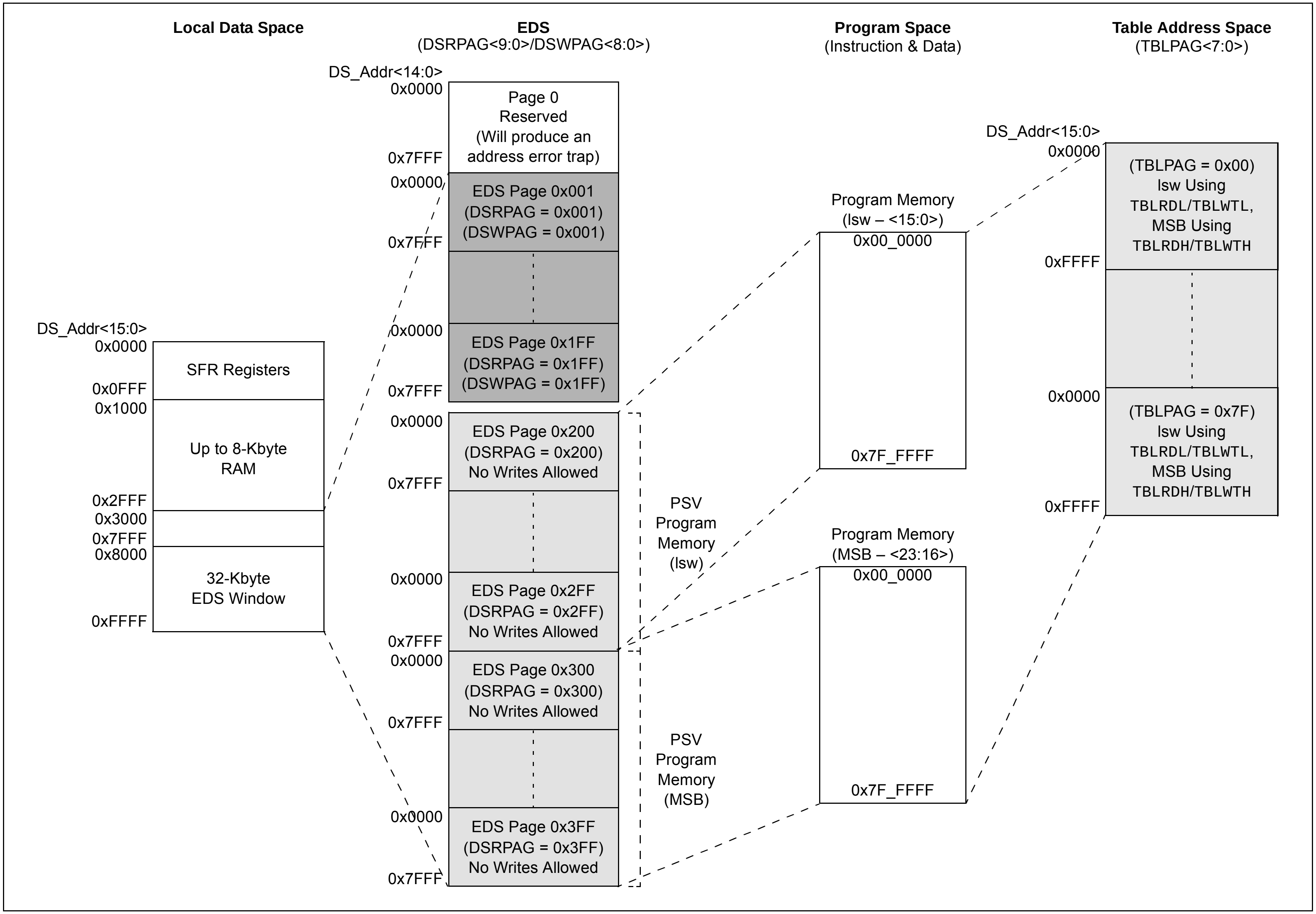
4.3 Special Function Register Maps

TABLE 4-1: CPU CORE REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
W0	0000	W0 (WREG)																0000
W1	0002	W1																0000
W2	0004	W2																0000
W3	0006	W3																0000
W4	0008	W4																0000
W5	000A	W5																0000
W6	000C	W6																0000
W7	000E	W7																0000
W8	0010	W8																0000
W9	0012	W9																0000
W10	0014	W10																0000
W11	0016	W11																0000
W12	0018	W12																0000
W13	001A	W13																0000
W14	001C	W14																0000
W15	001E	W15																0800
SPLIM	0020	SPLIM																xxxx
ACCAL	0022	ACCAL																xxxx
ACCAH	0024	ACCAH																xxxx
ACCAU	0026	Sign Extension of ACCA<39>								ACCAU								xxxx
ACCBL	0028	ACCBL																xxxx
ACCBH	002A	ACCBH																xxxx
ACCBU	002C	Sign Extension of ACCB<39>								ACCBU								xxxx
PCL	002E	Program Counter Low Word Register															—	0000
PCH	0030	—	—	—	—	—	—	—	—	—	Program Counter High Word Register							0000
DSRPAG	0032	—	—	—	—	—	—	Data Space Read Page Register										0001
DSWPAG	0034	—	—	—	—	—	—	—	Data Space Write Page Register									0001
RCOUNT	0036	REPEAT Loop Counter Register															0	xxxx
DCOUNT	0038	DCOUNT<15:1>															0	xxxx
DOSTARTL	003A	DOSTARTL<15:1>															0	xxxx
DOSTARTH	003C	—	—	—	—	—	—	—	—	—	—	DOSTARTH<5:0>						00xx
DOENDL	003E	DOENDL<15:1>															—	xxxx

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

FIGURE 4-11: PAGED DATA MEMORY SPACE



REGISTER 5-2: NVMADRU: NONVOLATILE MEMORY UPPER ADDRESS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
NVMADRU<23:16>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as ‘0’

bit 7-0 **NVMADRU<23:16>:** NVM Memory Upper Write Address bits

Selects the upper 8 bits of the location to program or erase in program Flash memory. This register may be read or written to by the user application.

REGISTER 5-3: NVMADR: NONVOLATILE MEMORY LOWER ADDRESS REGISTER

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
NVMADR<15:8>							
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
NVMADR<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-0 **NVMADR<15:0>:** NVM Memory Lower Write Address bits

Selects the lower 16 bits of the location to program or erase in program Flash memory. This register may be read or written to by the user application.

REGISTER 6-1: RCON: RESET CONTROL REGISTER(1) (CONTINUED)

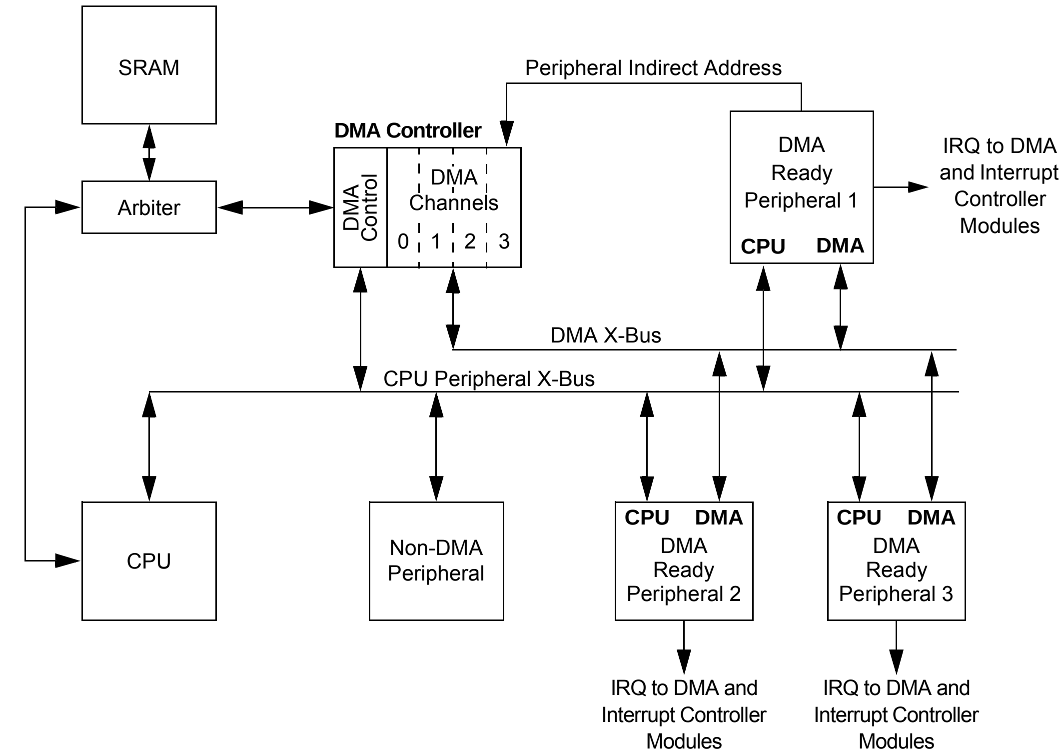
bit 3	**SLEEP:** Wake-up from Sleep Flag bit 1 = Device has been in Sleep mode 0 = Device has not been in Sleep mode
bit 2	**IDLE:** Wake-up from Idle Flag bit 1 = Device was in Idle mode 0 = Device was not in Idle mode
bit 1	**BOR:** Brown-out Reset Flag bit 1 = A Brown-out Reset has occurred 0 = A Brown-out Reset has not occurred
bit 0	**POR:** Power-on Reset Flag bit 1 = A Power-on Reset has occurred 0 = A Power-on Reset has not occurred

Note 1: All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

2: If the FWDTEN<1:0> Configuration bits are ‘11’ (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

Figure 8-2 illustrates the DMA Controller block diagram.

FIGURE 8-2: DMA CONTROLLER BLOCK DIAGRAM



Note: CPU and DMA address buses are not shown for clarity.

8.1 DMAC Controller Registers

Each DMAC Channel x (where x = 0 to 3) contains the following registers:

- 16-Bit DMA Channel x Control Register (DMAxCON)
- 16-Bit DMA Channel x IRQ Select Register (DMAxREQ)
- 32-Bit DMA Channel x Start Address Register A High/Low (DMAxSTAH/L)
- 32-Bit DMA Channel x Start Address Register B High/Low (DMAxSTBH/L)
- 16-Bit DMA Channel x Peripheral Address Register (DMAxPAD)
- 14-Bit DMA Channel x Transfer Count Register (DMAxCNT)

Additional status registers (DMAPWC, DMARQC, DMAPPS, DMALCA and DSADRH/L) are common to all DMAC channels. These status registers provide information on write and request collisions, as well as on last address and channel access information.

The DMA Interrupt Flags (DMAxIF) are located in an IFSx register in the interrupt controller. The corresponding DMA Interrupt Enable bits (DMAxIE) are located in an IECx register in the interrupt controller and the corresponding DMA Interrupt Priority bits (DMAxIP) are located in an IPCx register in the interrupt controller.

REGISTER 11-6: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OCFAR<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as ‘0’

bit 7-0 **OCFAR<7:0>:** Assign Output Compare Fault A (OCFA) to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers)

10110101 = Input tied to RPI181
•
•
•
00000001 = Input tied to CMP1
00000000 = Input tied to Vss

17.2 PWM Resources

Many useful resources are provided on the main product page on the Microchip web site (www.microchip.com) for the devices listed in this data sheet. This product page contains the latest updates and additional information.

Note:	In case the above link is not accessible, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en555464

17.2.1 KEY RESOURCES

- **"High-Speed PWM"** (DS70645) in the *"dsPIC33/PIC24 Family Reference Manual"*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

REGISTER 17-13: IOCONx: PWMx I/O CONTROL REGISTER(2) (CONTINUED)

bit 1	**SWAP:** SWAP PWMxH and PWMxL Pins bit 1 = PWMxH output signal is connected to the PWMxL pin; PWMxL output signal is connected to the PWMxH pin 0 = PWMxH and PWMxL pins are mapped to their respective pins
bit 0	**OSYNC:** Output Override Synchronization bit 1 = Output overrides through the OVRDAT<1:0> bits are synchronized to the PWMx time base 0 = Output overrides through the OVRDAT<1:0> bits occur on the next CPU clock boundary

Note 1: These bits should not be changed after the PWMx module is enabled (PTEN = 1).

2: If the PWMLOCK Configuration bit (FDEVOPT<0>) is a '1', the IOCONx register can only be written after the unlock sequence has been executed.

REGISTER 17-14: TRIGx: PWMx PRIMARY TRIGGER COMPARE VALUE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
TRGCMP<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
TRGCMP<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0	**TRGCMP<15:0>:** Trigger Control Value bits When the primary PWMx functions in the local time base, this register contains the compare values that can trigger the ADC module.

REGISTER 20-1: SENTxCON1: SENTx CONTROL REGISTER 1

R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
SNTEN	—	SNTSIDL	—	RCVEN	TXM(1)	TXPOL(1)	CRCEN
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
PPP	SPCEN(2)	—	PS	—	NIBCNT2	NIBCNT1	NIBCNT0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15 **SNTEN:** SENTx Enable bit
1 = SENTx is enabled
0 = SENTx is disabled

bit 14 **Unimplemented:** Read as ‘0’

bit 13 **SNTSIDL:** SENTx Stop in Idle Mode bit
1 = Discontinues module operation when the device enters Idle mode
0 = Continues module operation in Idle mode

bit 12 **Unimplemented:** Read as ‘0’

bit 11 **RCVEN:** SENTx Receive Enable bit
1 = SENTx operates as a receiver
0 = SENTx operates as a transmitter (sensor)

bit 10 **TXM:** SENTx Transmit Mode bit(1)
1 = SENTx transmits data frame only when triggered using the SYNCTXEN status bit
0 = SENTx transmits data frames continuously while SNTEN = 1

bit 9 **TXPOL:** SENTx Transmit Polarity bit(1)
1 = SENTx data output pin is low in the Idle state
0 = SENTx data output pin is high in the Idle state

bit 8 **CRCEN:** CRC Enable bit
Module in Receive Mode (RCVEN = 1):
1 = SENTx performs CRC verification on received data using the preferred J2716 method
0 = SENTx does not perform CRC verification on received data
Module in Transmit Mode (RCVEN = 1):
1 = SENTx automatically calculates CRC using the preferred J2716 method
0 = SENTx does not calculate CRC

bit 7 **PPP:** Pause Pulse Present bit
1 = SENTx is configured to transmit/receive SENT messages with pause pulse
0 = SENTx is configured to transmit/receive SENT messages without pause pulse

bit 6 **SPCEN:** Short PWM Code Enable bit(2)
1 = SPC control from external source is enabled
0 = SPC control from external source is disabled

bit 5 **Unimplemented:** Read as ‘0’

bit 4 **PS:** SENTx Module Clock Prescaler (divider) bits
1 = Divide-by-4
0 = Divide-by-1

Note 1: This bit has no function in Receive mode (RCVEN = 1).
2: This bit has no function in Transmit mode (RCVEN = 0).

REGISTER 24-7: ADxCSSH: ADCx INPUT SCAN SELECT REGISTER HIGH(2) (CONTINUED)

bit 1	**CSS17:** ADCx Input Scan Selection bit 1 = Selects ANx for input scan 0 = Skips ANx for input scan
bit 0	**CSS16:** ADCx Input Scan Selection bit 1 = Selects ANx for input scan 0 = Skips ANx for input scan

Note 1: If the op amp is selected (OPAEN bit (CMxCON<10>) = 1), the OAx input is used; otherwise, the ANx input is used.

2: All bits in this register can be selected by the user application. However, inputs selected for scan without a corresponding input on the device convert V_{REFL}.

Figure 25-2, shows the user-programmable blanking function block diagram.

FIGURE 25-2: USER-PROGRAMMABLE BLANKING FUNCTION BLOCK DIAGRAM

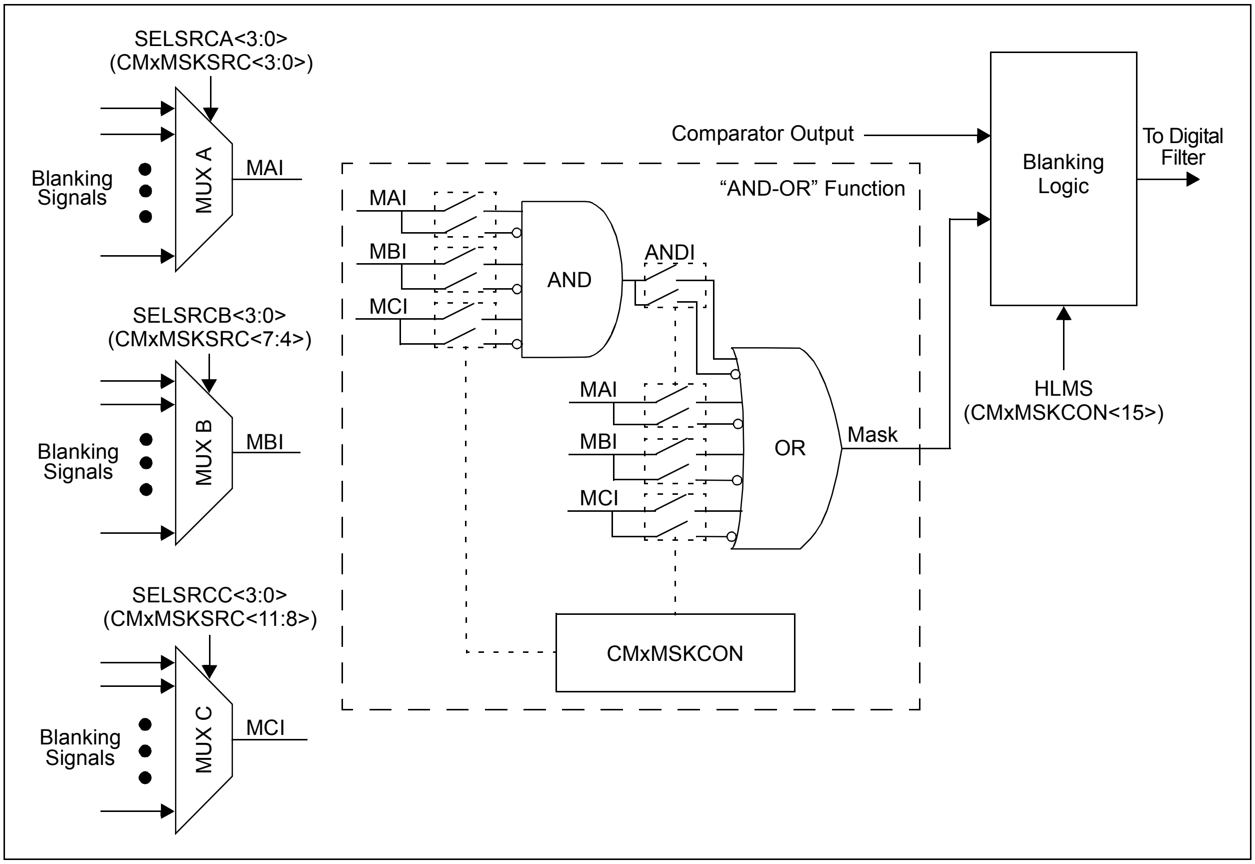
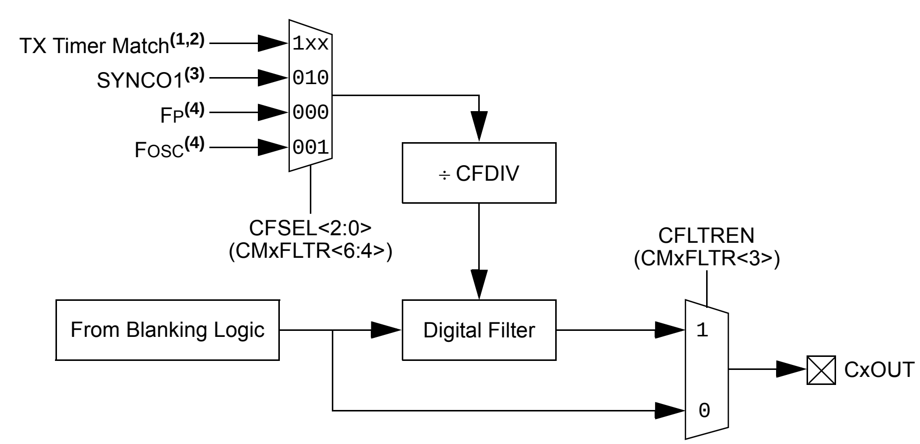


Figure 25-3, shows the digital filter interconnect block diagram.

FIGURE 25-3: DIGITAL FILTER INTERCONNECT BLOCK DIAGRAM



Note 1: See the Type C Timer Block Diagram (Figure 13-2).
2: See the Type B Timer Block Diagram (Figure 13-1).
3: See the PWMx Module Register Interconnect Diagram (Figure 17-2).
4: See the Oscillator System Diagram (Figure 9-1).

27.5 Watchdog Timer (WDT)

For dsPIC33EVXXXGM00X/10X family devices, the WDT is driven by the LPRC oscillator. When the WDT is enabled, the clock source is also enabled.

27.5.1 PRESCALER/POSTSCALER

The nominal WDT clock source from LPRC is 32 kHz. This feeds a prescaler that can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the WDTPRE Configuration bit. With a 32 kHz input, the prescaler yields a WDT Time-out Period (T_{WDT}), as shown in Parameter SY12 in Table 30-22.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPOST<3:0> Configuration bits (FWDT<3:0>), which allow the selection of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler, time-out periods ranging from 1 ms to 131 seconds can be achieved.

The WDT, prescaler and postscaler are reset:

- On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSCx bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

Note:	The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.

27.5.2 SLEEP AND IDLE MODES

If the WDT is enabled, it continues to run during Sleep or Idle modes. When the WDT time-out occurs, the device wakes the device and code execution continues from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bit (RCON<3:2>) needs to be cleared in software after the device wakes up.

27.5.3 ENABLING WDT

The WDT is enabled or disabled by the FWDTEN<1:0> Configuration bits in the FWDT Configuration register. When the FWDTEN<1:0> Configuration bits are set, the WDT is always enabled.

The WDT can be optionally controlled in software when the FWDTENx Configuration bits have been programmed to '00'. The WDT is enabled in software by setting the SWDTEN control bit (RCON<5>). The SWDTEN control bit is cleared on any device Reset. The software WDT option allows the user application to enable the WDT for critical code segments and disable the WDT during non-critical segments for maximum power savings.

The WDT flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

27.5.4 WDT WINDOW

The Watchdog Timer has an optional Windowed mode enabled by programming the WINDIS bit in the WDT Configuration register (FWDT<7>). In the Windowed mode (WINDIS = 0), the WDT should be cleared based on the settings in the programmable Watchdog Timer Window (WDTWIN<1:0>) select bits.

FIGURE 27-2: WDT BLOCK DIAGRAM

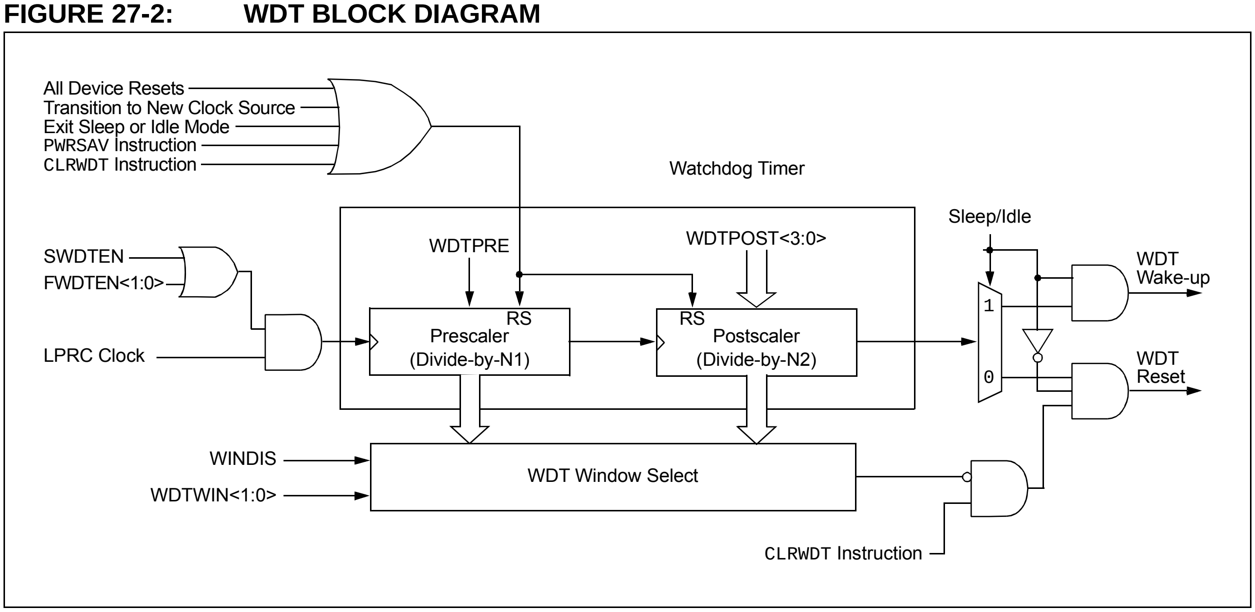
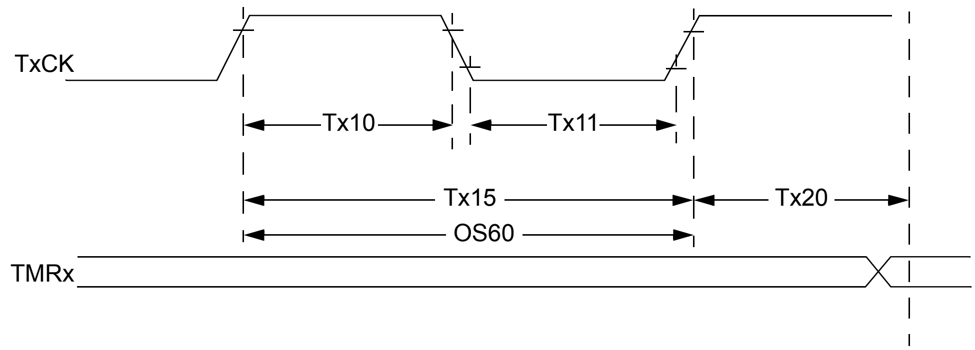


FIGURE 30-6: TIMER1-TIMER5 EXTERNAL CLOCK TIMING CHARACTERISTICS



Note: Refer to Figure 30-1 for load conditions.

TABLE 30-23: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS(1)

AC CHARACTERISTICS				Standard Operating Conditions: 4.5V to 5.5V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	**Symbol**	**Characteristic(2)**		**Min.**	**Typ.**	**Max.**	**Units**	**Conditions**
TA10	TTXH	T1CK High Time	Synchronous mode	Greater of: 20 or (TCY + 20)/N	—	—	ns	Must also meet Parameter TA15, N = Prescaler Value (1, 8, 64, 256)
			Asynchronous mode	35	—	—	ns	
TA11	TTXL	T1CK Low Time	Synchronous mode	Greater of: 20 or (TCY + 20)/N	—	—	ns	Must also meet Parameter TA15, N = Prescaler Value (1, 8, 64, 256)
			Asynchronous mode	10	—	—	ns	
TA15	TTXP	T1CK Input Period	Synchronous mode	Greater of: 40 or (2 TCY + 40)/N	—	—	ns	N = Prescaler Value (1, 8, 64, 256)
OS60	Ft1	T1CK Oscillator Input Frequency Range (oscillator enabled by setting TCS (T1CON<1>) bit)		DC	—	50	kHz	
TA20	TCKEXTMRL	Delay from External T1CK Clock Edge to Timer Increment		0.75 TCY + 40	—	1.75 TCY + 40	ns	

Note 1: Timer1 is a Type A.

2: These parameters are characterized but not tested in manufacturing.

32.0 CHARACTERISTICS FOR INDUSTRIAL/EXTENDED TEMPERATURE DEVICES (-40°C TO +125°C)

32.1 IDD

FIGURE 32-1: TYPICAL/MAXIMUM IDD vs. FOSC (EC MODE, 10 MHz TO 70 MHz, 5.5V MAX)

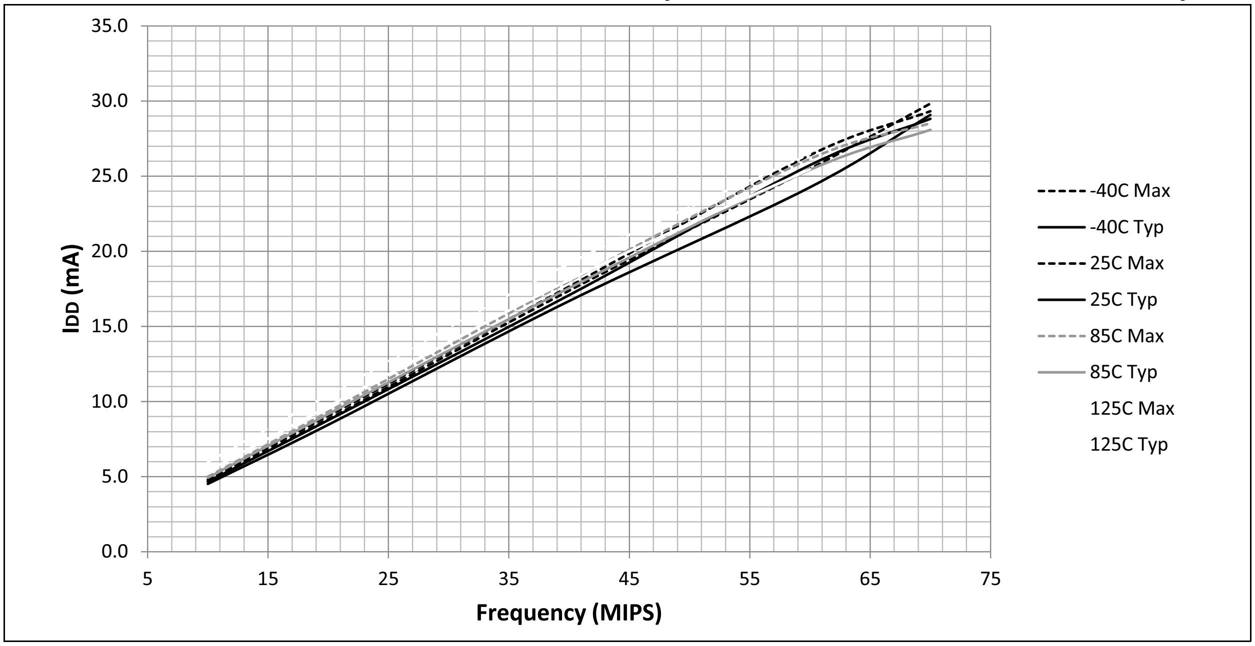


FIGURE 32-2: TYPICAL IDD vs. VDD (EC MODE, 10 MIPS)

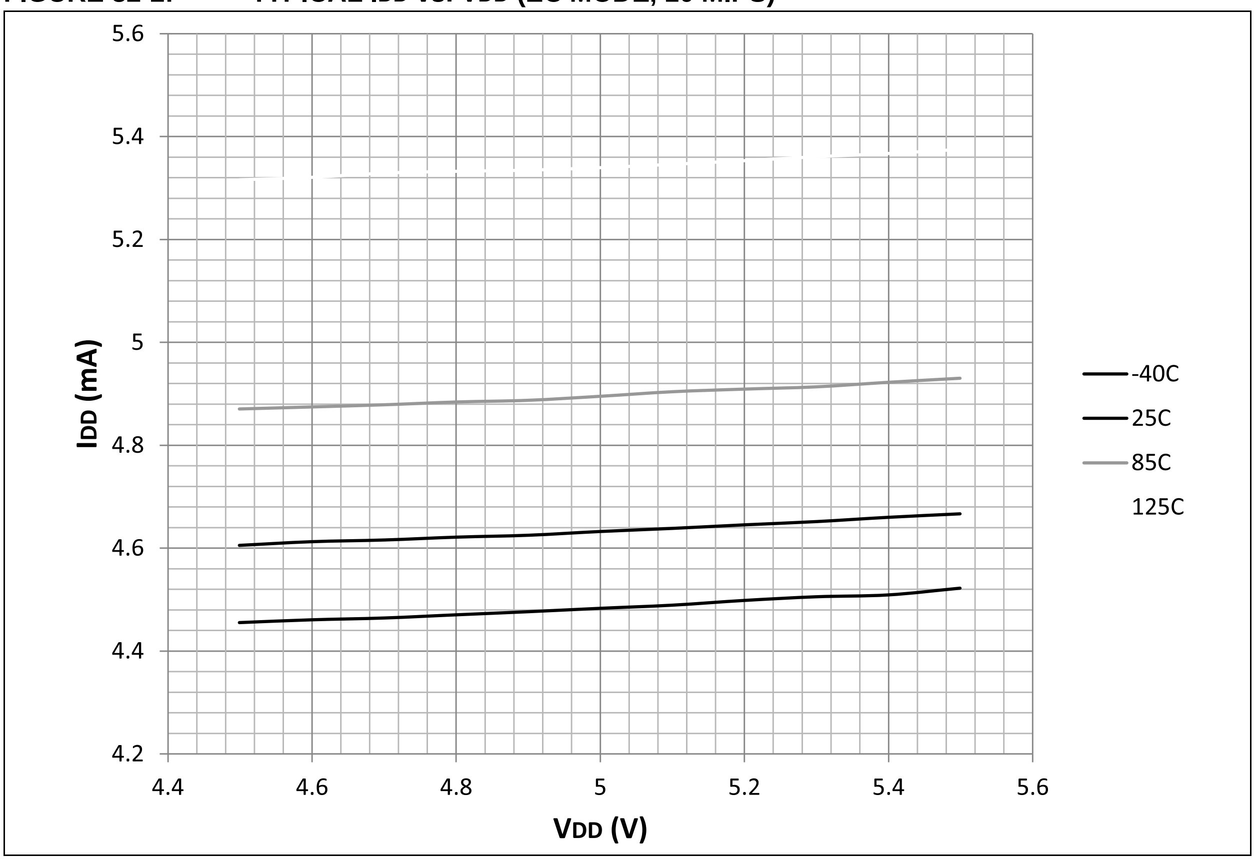


FIGURE 32-31: TYPICAL VOH 4x DRIVER PINS vs. IOH (GENERAL PURPOSE I/Os, TEMPERATURES AS NOTED)

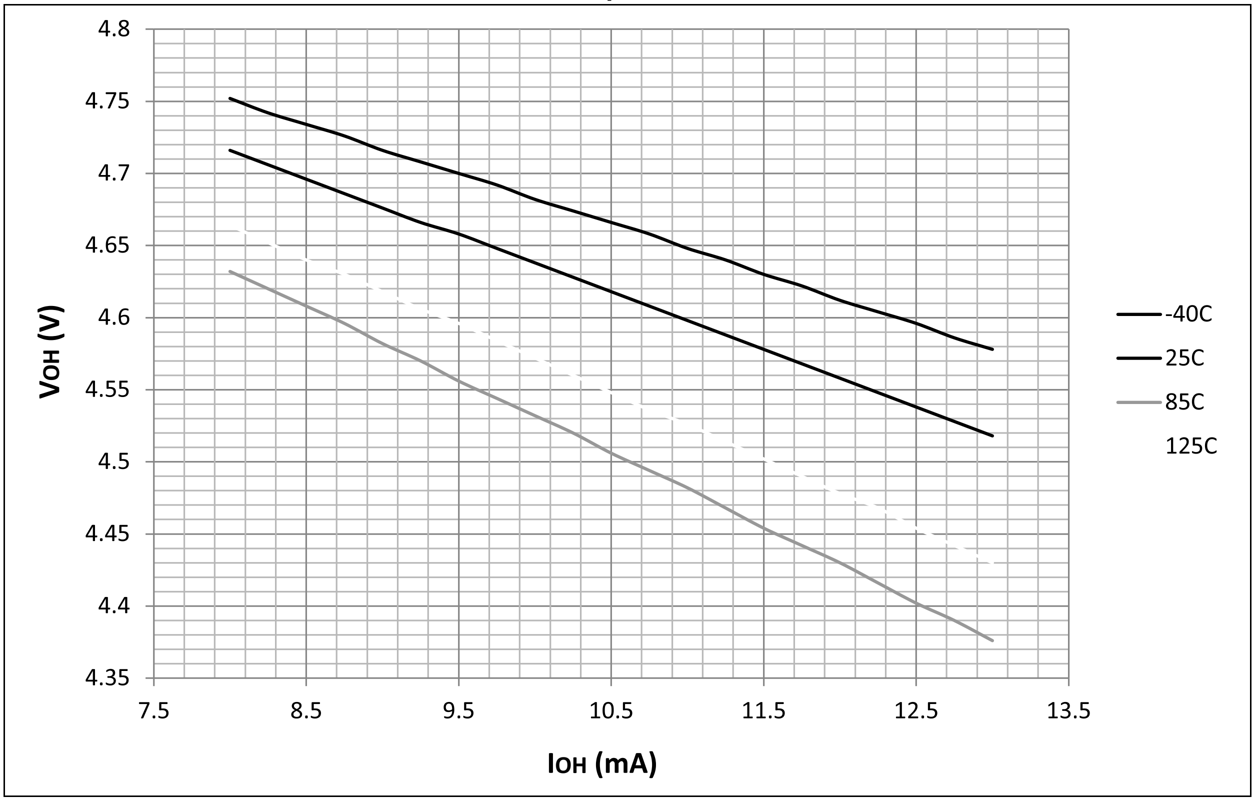
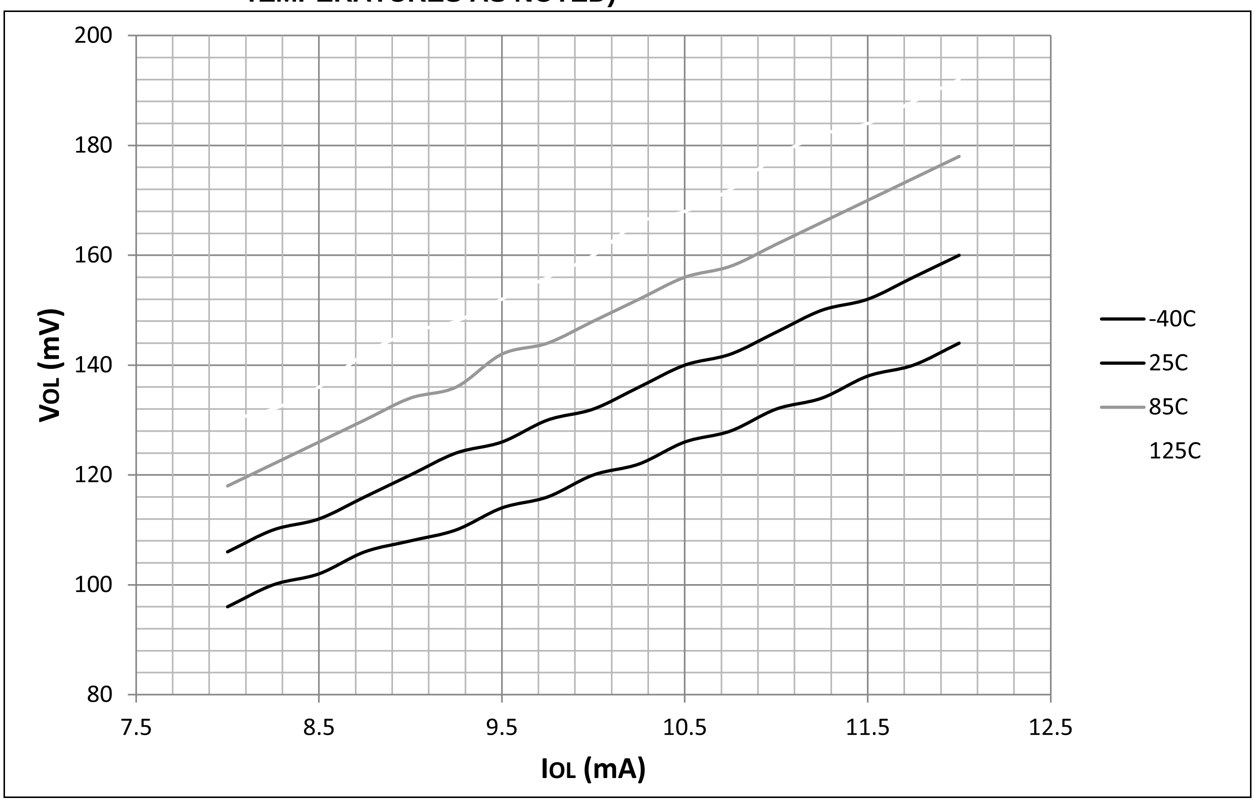


FIGURE 32-32: TYPICAL VOL 8x DRIVER PINS vs. IOL (GENERAL PURPOSE I/Os, TEMPERATURES AS NOTED)



33.3 IDOZE

FIGURE 33-9: TYPICAL IDOZE vs. VDD (DOZE 1:2, 70 MIPS)

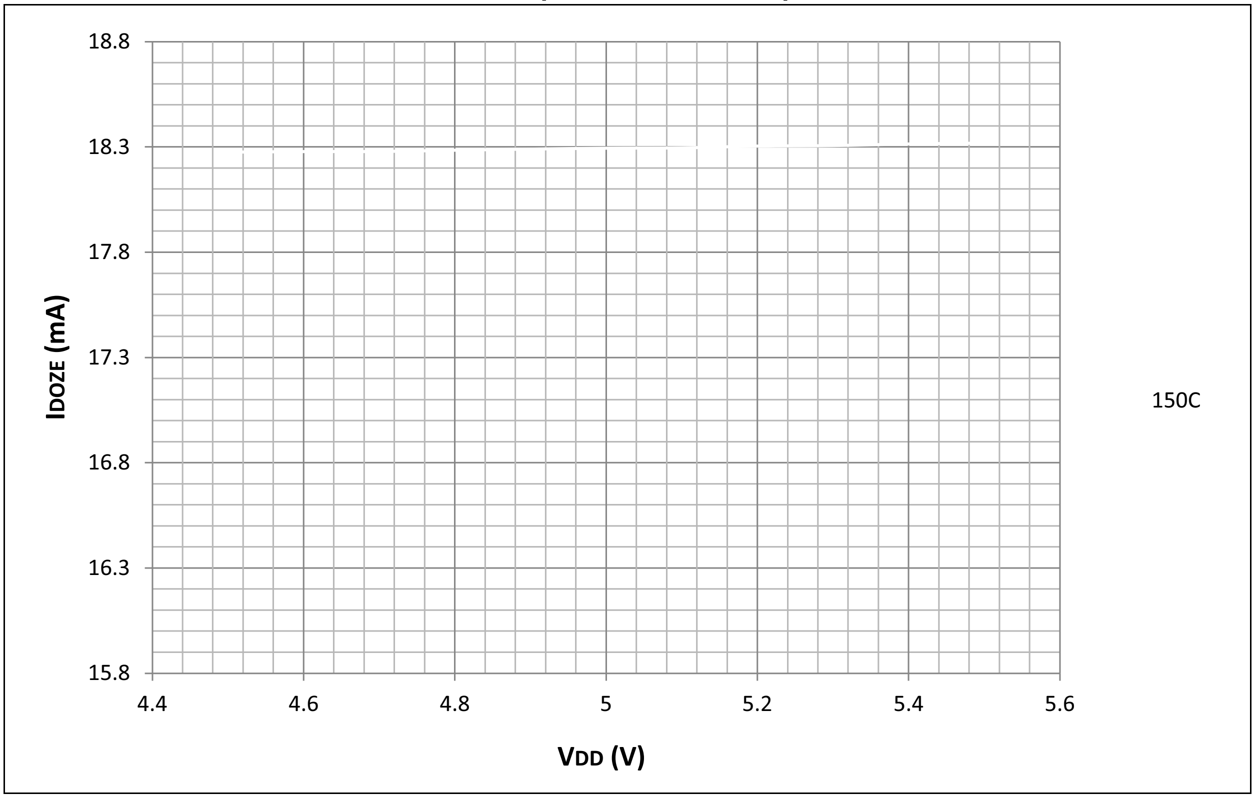
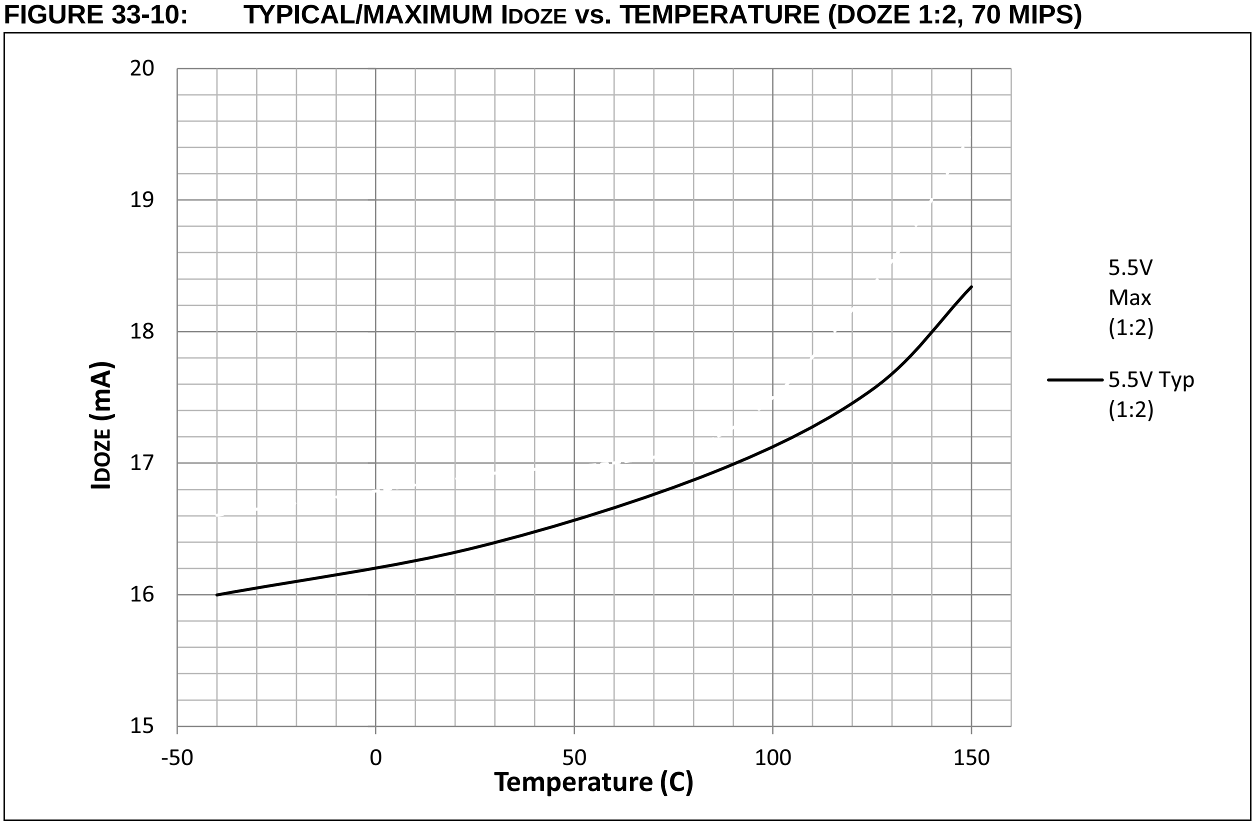


FIGURE 33-10: TYPICAL/MAXIMUM IDOZE vs. TEMPERATURE (DOZE 1:2, 70 MIPS)



PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

dsPIC 33 EV XXX GM0 0X T PT - XXX

- **Microchip Trademark** — dsPIC
- **Architecture** — 33
- **Core Family** — EV
- **Program Memory Size (Kbytes)** — XXX
- **Product Group** — GM0
- **Pin Count** — 0X
- **Tape and Reel Flag (if applicable)** — T
- **Package** — PT
- **Pattern** — XXX

Architecture:	33	=	16-Bit Digital Signal Controller
Family:	EV	=	Enhanced Voltage
Product Group:	GM	=	General Purpose plus Motor Control Family
Pin Count:	02	=	28-Pin
	04	=	44-Pin
	06	=	64-Pin
Temperature Range	I	=	-40°C to +85°C (Industrial)
	E	=	-40°C to +125°C (Extended)
	H	=	-40°C to +150°C (High)
Package:	MM	=	Plastic Quad Flat, No Lead Package – (28-pin) 6x6x0.9 mm body (QFN-S)
	SO	=	Plastic Small Outline – (28-pin) 7.50 mm body (SOIC)
	SS	=	Plastic Shrink Small Outline – (28-pin) 5.30 mm body (SSOP)
	SP	=	Skinny Plastic Dual In-Line – (28-pin) 300 mil body (SPDIP)
	ML	=	Plastic Quad Flat, No Lead Package – (44-pin) 8x8 mm body (QFN)
	MR	=	Plastic Quad Flat, No Lead Package – (64-pin) 9x9x0.9 mm body (QFN)
	PT	=	Plastic Thin Quad Flatpack – (44-pin) 10x10x1 mm body (TQFP)
	PT	=	Plastic Thin Quad Flatpack – (64-pin) 10x10x1 mm body (TQFP)

Example:

dsPIC33EV256GM006-I/PT:
dsPIC33, Enhanced Voltage,
256-Kbyte Program Memory, 64-Pin,
Industrial Temperature, TQFP Package.