Microchip Technology - DSPIC33EV32GM002-I/SS Datasheet

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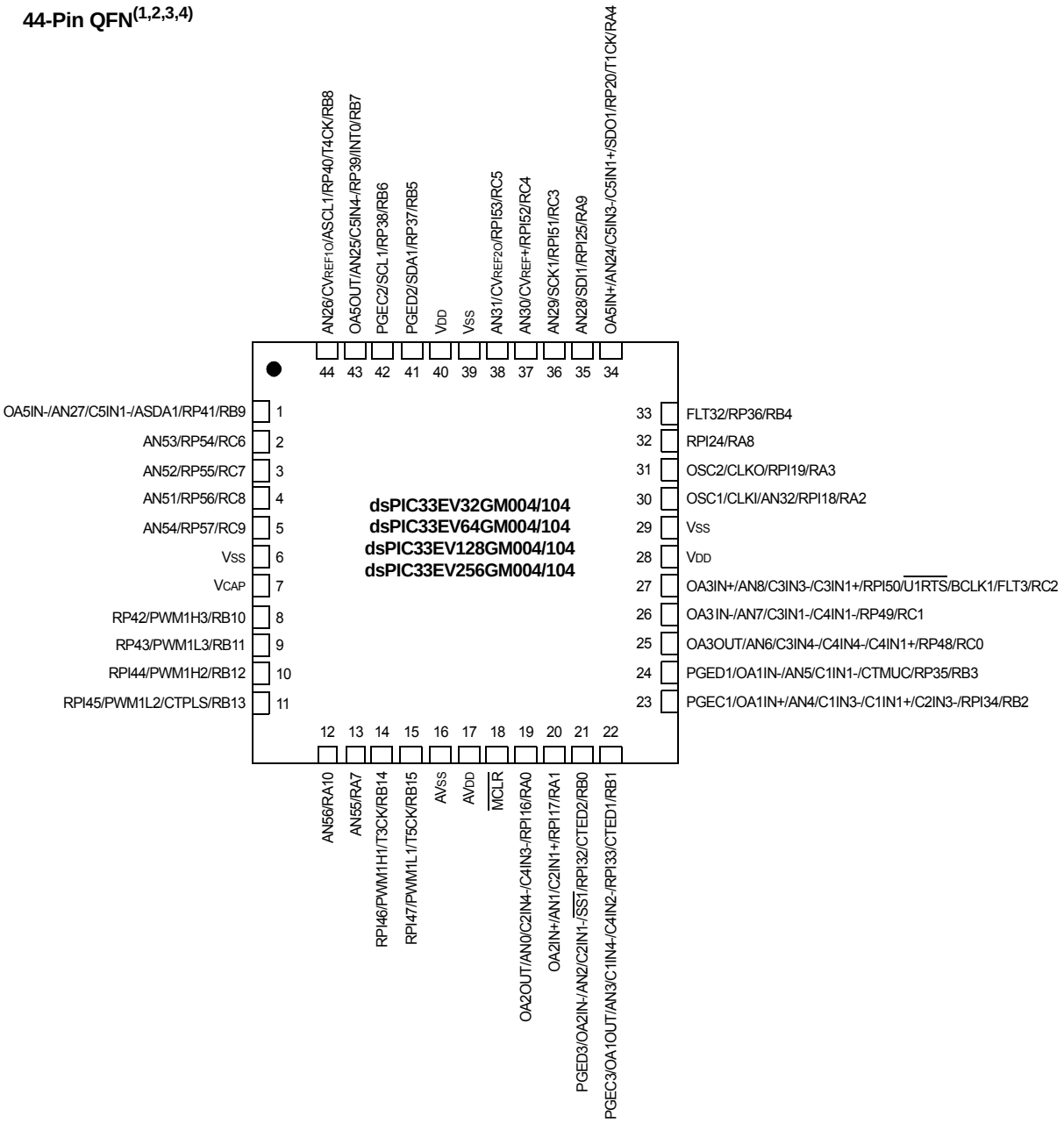
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (11K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 11x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ev32gm002-i-ss

Pin Diagrams (Continued)

44-Pin QFN(1,2,3,4)



Note 1: The RPn/RPIn pins can be used by any remappable peripheral with some limitation. See **Section 11.5 "Peripheral Pin Select (PPS)"** for available peripherals and information on limitations.

2: Every I/O port pin (RAx-RGx) can be used as a Change Notification pin (CNAx-CNGx). See **Section 11.0 "I/O Ports"** for more information.

3: If the op amp is selected when OPAEN (CMxCON<10>) = 1, the OAx input is used; otherwise, the ANx input is used.

4: The metal pad at the bottom of the device is not connected to any pins and is recommended to be connected to VSS externally.

TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Type	Buffer Type	PPS	Description
SCK2	I/O	ST	Yes	Synchronous serial clock input/output for SPI2.
SDI2	I	ST	Yes	SPI2 data in.
SDO2	O	—	Yes	SPI2 data out.
SS2	I/O	ST	Yes	SPI2 slave synchronization or frame pulse I/O.
SCL1	I/O	ST	No	Synchronous serial clock input/output for I2C1.
SDA1	I/O	ST	No	Synchronous serial data input/output for I2C1.
ASCL1	I/O	ST	No	Alternate synchronous serial clock input/output for I2C1.
ASDA1	I/O	ST	No	Alternate synchronous serial data input/output for I2C1.
C1RX	I	ST	Yes	CAN1 bus receive pin.
C1TX	O	—	Yes	CAN1 bus transmit pin.
SENT1TX	O	—	Yes	SENT1 transmit pin.
SENT1RX	I	—	Yes	SENT1 receive pin.
SENT2TX	O	—	Yes	SENT2 transmit pin.
SENT2RX	I	—	Yes	SENT2 receive pin.
CVREF	O	Analog	No	Comparator Voltage Reference output.
C1IN1+, C1IN2-, C1IN1-, C1IN3-	I	Analog	No	Comparator 1 inputs.
C1OUT	O	—	Yes	Comparator 1 output.
C2IN1+, C2IN2-, C2IN1-, C2IN3-	I	Analog	No	Comparator 2 inputs.
C2OUT	O	—	Yes	Comparator 2 output.
C3IN1+, C3IN2-, C2IN1-, C3IN3-	I	Analog	No	Comparator 3 inputs.
C3OUT	O	—	Yes	Comparator 3 output.
C4IN1+, C4IN2-, C4IN1-, C4IN3-	I	Analog	No	Comparator 4 inputs.
C4OUT	O	—	Yes	Comparator 4 output.
C5IN1+, C5IN2-, C5IN1-, C5IN3-	I	Analog	No	Comparator 5 inputs.
C5OUT	O	—	Yes	Comparator 5 output.
FLT1-FLT2	I	ST	Yes	PWM Fault Inputs 1 and 2.
FLT3-FLT8	I	ST	NO	PWM Fault Inputs 3 to 8.
FLT32	I	ST	NO	PWM Fault Input 32.
DTCMP1-DTCMP3	I	ST	Yes	PWM Dead-Time Compensation Inputs 1 to 3.
PWM1L-PWM3L	O	—	No	PWM Low Outputs 1 to 3.
PWM1H-PWM3H	O	—	No	PWM High Outputs 1 to 3.
SYNCI1	I	ST	Yes	PWM Synchronization Input 1.
SYNCO1	O	—	Yes	PWM Synchronization Output 1.
PGED1	I/O	ST	No	Data I/O pin for Programming/Debugging Communication Channel 1.
PGEC1	I	ST	No	Clock input pin for Programming/Debugging Communication Channel 1.
PGED2	I/O	ST	No	Data I/O pin for Programming/Debugging Communication Channel 2.
PGEC2	I	ST	No	Clock input pin for Programming/Debugging Communication Channel 2.
PGED3	I/O	ST	No	Data I/O pin for Programming/Debugging Communication Channel 3.
PGEC3	I	ST	No	Clock input pin for Programming/Debugging Communication Channel 3.
MCLR	I/P	ST	No	Master Clear (Reset) input. This pin is an active-low Reset to the device.

Legend: CMOS = CMOS compatible input or output; Analog = Analog input; P = Power
ST = Schmitt Trigger input with CMOS levels; O = Output; I = Input
PPS = Peripheral Pin Select; TTL = TTL input buffer

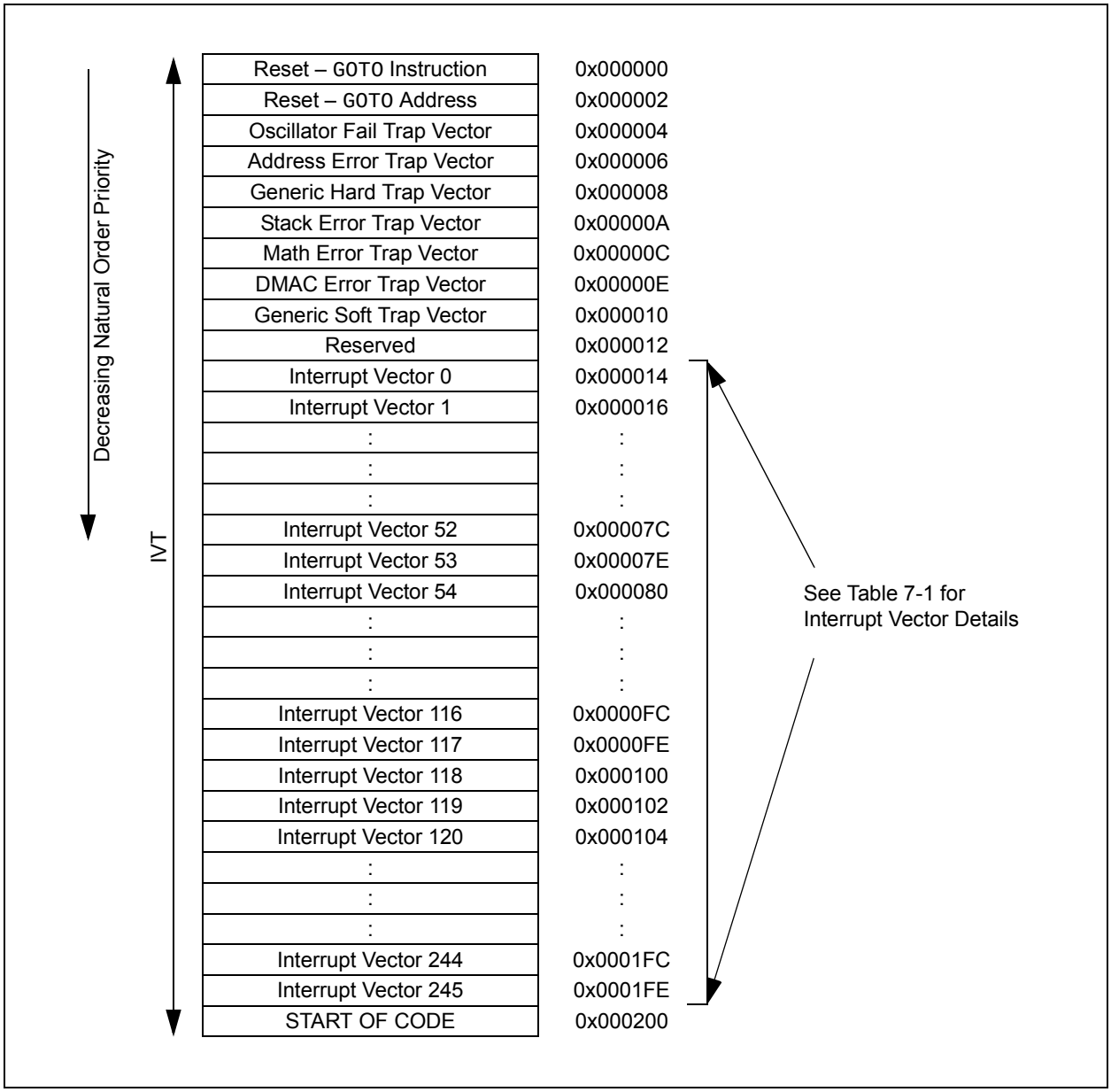
NOTES:

TABLE 4-24: OUTPUT COMPARE REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
OC1CON1	0900	—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	—	ENFLTA	—	—	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0	0000
OC1CON2	0902	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC1RS	0904	Output Compare 1 Secondary Register																xxxx
OC1R	0906	Output Compare 1 Register																xxxx
OC1TMR	0908	Output Compare 1 Timer Value Register																xxxx
OC2CON1	090A	—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	—	ENFLTA	—	—	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0	0000
OC2CON2	090C	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC2RS	090E	Output Compare 2 Secondary Register																xxxx
OC2R	0910	Output Compare 2 Register																xxxx
OC2TMR	0912	Output Compare 2 Timer Value Register																xxxx
OC3CON1	0914	—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	—	ENFLTA	—	—	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0	0000
OC3CON2	0916	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC3RS	0918	Output Compare 3 Secondary Register																xxxx
OC3R	091A	Output Compare 3 Register																xxxx
OC3TMR	091C	Output Compare 3 Timer Value Register																xxxx
OC4CON1	091E	—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	—	ENFLTA	—	—	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0	0000
OC4CON2	0920	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC4RS	0922	Output Compare 4 Secondary Register																xxxx
OC4R	0924	Output Compare 4 Register																xxxx
OC4TMR	0926	Output Compare 4 Timer Value Register																xxxx

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

FIGURE 7-2: dsPIC33EVXXXGM00X/10X FAMILY INTERRUPT VECTOR TABLE



NOTES:

REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1 (CONTINUED)

bit 2 **Unimplemented:** Read as '0'

bit 1 **C1MD:** CAN1 Module Disable bit(1)
1 = CAN1 module is disabled
0 = CAN1 module is enabled

bit 0 **AD1MD:** ADC1 Module Disable bit
1 = ADC1 module is disabled
0 = ADC1 module is enabled

Note 1: This bit is available on dsPIC33EVXXXGM10X devices only.

REGISTER 10-2: PMD2: PERIPHERAL MODULE DISABLE CONTROL REGISTER 2

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	IC4MD	IC3MD	IC2MD	IC1MD
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	OC4MD	OC3MD	OC2MD	OC1MD
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Unimplemented:** Read as '0'

bit 11-8 **IC4MD:IC1MD:** Input Capture x (x = 1-4) Module Disable bits
1 = Input Capture x module is disabled
0 = Input Capture x module is enabled

bit 7-4 **Unimplemented:** Read as '0'

bit 3-0 **OC4MD:OC1MD:** Output Compare x (x = 1-4) Module Disable bits
1 = Output Compare x module is disabled
0 = Output Compare x module is enabled

TABLE 11-1: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)

Input Name(1)	Function Name	Register	Configuration Bits
External Interrupt 1	INT1	RPINR0	INT1R<7:0>
External Interrupt 2	INT2	RPINR1	INT2R<7:0>
Timer2 External Clock	T2CK	RPINR3	T2CKR<7:0>
Input Capture 1	IC1	RPINR7	IC1R<7:0>
Input Capture 2	IC2	RPINR7	IC2R<7:0>
Input Capture 3	IC3	RPINR8	IC3R<7:0>
Input Capture 4	IC4	RPINR8	IC4R<7:0>
Output Compare Fault A	OCFA	RPINR11	OCFAR<7:0>
PWM Fault 1	FLT1	RPINR12	FLT1R<7:0>
PWM Fault 2	FLT2	RPINR12	FLT2R<7:0>
UART1 Receive	U1RX	RPINR18	U1RXR<7:0>
UART2 Receive	U2RX	RPINR19	U2RXR<7:0>
SPI2 Data Input	SDI2	RPINR22	SDI2R<7:0>
SPI2 Clock Input	SCK2	RPINR22	SCK2R<7:0>
SPI2 Slave Select	$\overline{SS2}$	RPINR23	SS2R<7:0>
CAN1 Receive	C1RX	RPINR26	C1RXR<7:0>
PWM Sync Input 1	SYNCI1	RPINR37	SYNCI1R<7:0>
PWM Dead-Time Compensation 1	DTCMP1	RPINR38	DTCMP1R<7:0>
PWM Dead-Time Compensation 2	DTCMP2	RPINR39	DTCMP2R<7:0>
PWM Dead-Time Compensation 3	DTCMP3	RPINR39	DTCMP3R<7:0>
SENT1 Input	SENT1R	RPINR44	SENT1R<7:0>
SENT2 Input	SENT2R	RPINR45	SENT2R<7:0>

Note 1: Unless otherwise noted, all inputs use the Schmitt Trigger input buffers.

11.6 High-Voltage Detect (HVD)

dsPIC33EVXXXGM00X/10X devices contain High-Voltage Detection (HVD) which monitors the VCAP voltage. The HVD is used to monitor the VCAP supply voltage to ensure that an external connection does not raise the value above a safe level (~2.4V). If high core voltage is detected, all I/Os are disabled and put in a tri-state condition. The device remains in this I/O tri-state condition as long as the high-voltage condition is present.

11.7 I/O Helpful Tips

1. In some cases, certain pins, as defined in Table 30-10 under “Injection Current”, have internal protection diodes to VDD and VSS. The term, “Injection Current”, is also referred to as “Clamp Current”. On designated pins with sufficient external current-limiting precautions by the user, I/O pin input voltages are allowed to be greater or less than the data sheet absolute maximum ratings, with respect to the VSS and VDD supplies. Note that when the user application forward biases either of the high or low side internal input clamp diodes that the resulting current being injected into the device, that is clamped internally by the VDD and VSS power rails, may affect the ADC accuracy by four to six counts.
2. I/O pins that are shared with any analog input pin (i.e., ANx) are always analog pins by default after any Reset. Consequently, configuring a pin as an analog input pin automatically disables the digital input pin buffer and any attempt to read the digital input level by reading PORTx or LATx will always return a ‘0’, regardless of the digital logic level on the pin. To use a pin as a digital I/O pin on a shared ANx pin, the user application needs to configure the Analog Pin Configuration registers in the I/O ports module (i.e., ANSELx) by setting the appropriate bit that corresponds to that I/O port pin to a ‘0’.

Note:	Although it is not possible to use a digital input pin when its analog function is enabled, it is possible to use the digital I/O output function, TRISx = 0x0, while the analog function is also enabled. However, this is not recommended, particularly if the analog input is connected to an external analog voltage source, which would create signal contention between the analog signal and the output pin driver.

3. Most I/O pins have multiple functions. Referring to the device pin diagrams in this data sheet, the priorities of the functions allocated to any pins are indicated by reading the pin name, from left-to-right. The left most function name takes precedence over any function to its right in the naming convention; for example, AN16/T2CK/T7CK/RC1. This indicates that AN16 is the highest priority in this example and will supersede all other functions to its right in the list. Those other functions to its right, even if enabled, would not work as long as any other function to its left was enabled. This rule applies to all of the functions listed for a given pin.
4. Each pin has an internal weak pull-up resistor and pull-down resistor that can be configured using the CNPUx and CNPDx registers, respectively. These resistors eliminate the need for external resistors in certain applications. The internal pull-up is up to ~(VDD – 0.8), not VDD. This value is still above the minimum VIH of CMOS and TTL devices.
5. When driving LEDs directly, the I/O pin can source or sink more current than what is specified in the VOH/IOH and VOL/IOL DC characteristic specifications. The respective IOH and IOL current rating only applies to maintaining the corresponding output at or above the VOH, and at or below the VOL levels. However, for LEDs, unlike digital inputs of an externally connected device, they are not governed by the same minimum VIH/VIL levels. An I/O pin output can safely sink or source any current less than that listed in the absolute maximum rating section of this data sheet. For example:

   VOH = 4.4V at IOH = -8 mA and VDD = 5V

   The maximum output current sourced by any 8 mA I/O pin = 12 mA.

   LED source current, <12 mA, is technically permitted. For more information, refer to the VOH/IOH specifications in **Section 30.0 “Electrical Characteristics”**.

12.0 TIMER1

Note 1: This data sheet summarizes the features of the dsPIC33EVXXXGM00X/10X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"Timers"** (DS70362) in the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer that can operate as a free-running, interval timer/counter.

The Timer1 module has the following unique features over other timers:

- Can be Operated in Asynchronous Counter mode from an External Clock Source
- The Timer1 External Clock Input (T1CK) can Optionally be Synchronized to the Internal Device Clock and the Clock Synchronization is Performed after the Prescaler

A block diagram of Timer1 is shown in Figure 12-1.

The Timer1 module can operate in one of the following modes:

- Timer mode
- Gated Timer mode
- Synchronous Counter mode
- Asynchronous Counter mode

In Timer and Gated Timer modes, the input clock is derived from the internal instruction cycle clock (FCY). In Synchronous and Asynchronous Counter modes, the input clock is derived from the external clock input at the T1CK pin.

The Timer modes are determined by the following bits:

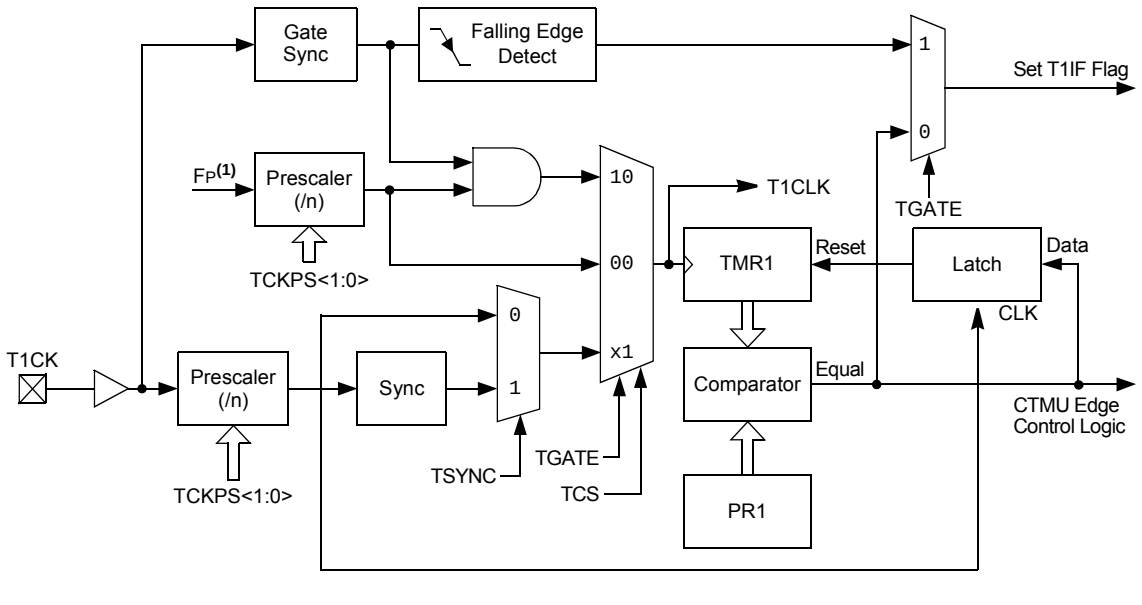
- Timer Clock Source Control bit (TCS): T1CON<1>
- Timer Synchronization Control bit (TSYNC): T1CON<2>
- Timer Gate Control bit (TGATE): T1CON<6>

Timer control bit settings for different operating modes are given in Table 12-1.

TABLE 12-1: TIMER MODE SETTINGS

Mode	TCS	TGATE	TSYNC
Timer	0	0	x
Gated Timer	0	1	x
Synchronous Counter	1	x	1
Asynchronous Counter	1	x	0

FIGURE 12-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM



Note 1: FP is the peripheral clock.

REGISTER 17-13: IOCONx: PWMx I/O CONTROL REGISTER(2) (CONTINUED)

bit 1 **SWAP:** SWAP PWMxH and PWMxL Pins bit
1 = PWMxH output signal is connected to the PWMxL pin; PWMxL output signal is connected to the PWMxH pin
0 = PWMxH and PWMxL pins are mapped to their respective pins

bit 0 **OSYNC:** Output Override Synchronization bit
1 = Output overrides through the OVRDAT<1:0> bits are synchronized to the PWMx time base
0 = Output overrides through the OVRDAT<1:0> bits occur on the next CPU clock boundary

Note 1: These bits should not be changed after the PWMx module is enabled (PTEN = 1).
2: If the PWMLOCK Configuration bit (FDEVOPT<0>) is a '1', the IOCONx register can only be written after the unlock sequence has been executed.

REGISTER 17-14: TRIGx: PWMx PRIMARY TRIGGER COMPARE VALUE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
TRGCMP<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
TRGCMP<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **TRGCMP<15:0>:** Trigger Control Value bits
When the primary PWMx functions in the local time base, this register contains the compare values that can trigger the ADC module.

NOTES:

20.2 Transmit Mode

By default, the SENTx module is configured for transmit operation. The module can be configured for continuous asynchronous message frame transmission, or alternatively, for Synchronous mode triggered by software. When enabled, the transmitter will send a Sync followed by the appropriate number of data nibbles, an optional CRC and optional pause pulse. The tick period used by the SENTx transmitter is set by writing a value to the TICKTIME<15:0> (SENTxCON2<15:0>) bits. The tick period calculations are shown in Equation 20-1.

EQUATION 20-1: TICK PERIOD CALCULATION

$$TICKTIME\langle 15:0\rangle = \frac{T_{TICK}}{T_{CLK}} - 1$$

An optional pause pulse can be used in Asynchronous mode to provide a fixed message frame time period. The frame period used by the SENTx transmitter is set by writing a value to the FRAMETIME<15:0> (SENTxCON3<15:0>) bits. The formulas used to calculate the value of frame time are shown in Equation 20-2.

EQUATION 20-2: FRAME TIME CALCULATIONS

$$FRAMETIME\langle 15:0\rangle = T_{TICK}/T_{FRAME}$$

$$FRAMETIME\langle 15:0\rangle \geq 122 + 27N$$

$$FRAMETIME\langle 15:0\rangle \geq 848 + 12N$$

Where:

T_{FRAME} = Total time of the message from ms

N = The number of data nibbles in message, 1-6

Note: The module will not produce a pause period with less than 12 ticks, regardless of the FRAMETIME<15:0> value. FRAMETIME<15:0> values beyond 2047 will have no effect on the length of a data frame.

20.2.1 TRANSMIT MODE CONFIGURATION

20.2.1.1 Initializing the SENTx Module:

Perform the following steps to initialize the module:

1. Write RCVEN (SENTxCON1<11>) = 0 for Transmit mode.
2. Write TXM (SENTxCON1<10>) = 0 for Asynchronous Transmit mode or TXM = 1 for Synchronous mode.
3. Write NIBCNT<2:0> (SENTxCON1<2:0>) for the desired data frame length.
4. Write CRCEN (SENTxCON1<8>) for hardware or software CRC calculation.
5. Write PPP (SENTxCON1<7>) for optional pause pulse.
6. If PPP = 1, write TFRAME to SENTxCON3.
7. Write SENTxCON2 with the appropriate value for desired tick period.
8. Enable interrupts and set interrupt priority.
9. Write initial status and data values to SENTxDATH/L.
10. If CRCEN = 0, calculate CRC and write the value to CRC<3:0> (SENTxDATL<3:0>).
11. Set the SNTEN (SENTxCON1<15>) bit to enable the module.

User software updates to SENTxDATH/L must be performed after the completion of the CRC and before the next message frame's status nibble. The recommended method is to use the message frame completion interrupt to trigger data writes.

REGISTER 20-2: SENTxSTAT: SENTx STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R/C-0	R-0	R/W-0, HC
PAUSE	NIB2	NIB1	NIB0	CRCERR	FRMERR	RXIDLE	SYNCTXEN(1)
bit 7							bit 0

Legend:	C = Clearable bit	HC = Hardware Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **PAUSE:** Pause Period Status bit
1 = The module is transmitting/receiving a pause period
0 = The module is not transmitting/receiving a pause period

bit 6-4 **NIB<2:0>:** Nibble Status bit
Module in Transmit Mode (RCVEN = 0):
111 = Module is transmitting a CRC nibble
110 = Module is transmitting Data Nibble 6
101 = Module is transmitting Data Nibble 5
100 = Module is transmitting Data Nibble 4
011 = Module is transmitting Data Nibble 3
010 = Module is transmitting Data Nibble 2
001 = Module is transmitting Data Nibble 1
000 = Module is transmitting a status nibble or pause period, or is not transmitting
Module in Receive Mode (RCVEN = 1):
111 = Module is receiving a CRC nibble or was receiving this nibble when an error occurred
110 = Module is receiving Data Nibble 6 or was receiving this nibble when an error occurred
101 = Module is receiving Data Nibble 5 or was receiving this nibble when an error occurred
100 = Module is receiving Data Nibble 4 or was receiving this nibble when an error occurred
011 = Module is receiving Data Nibble 3 or was receiving this nibble when an error occurred
010 = Module is receiving Data Nibble 2 or was receiving this nibble when an error occurred
001 = Module is receiving Data Nibble 1 or was receiving this nibble when an error occurred
000 = Module is receiving a status nibble or waiting for Sync

bit 3 **CRCERR:** CRC Status bit (Receive mode only)
1 = A CRC error occurred for the 1-6 data nibbles in SENTxDATH/L
0 = A CRC error has not occurred

bit 2 **FRMERR:** Framing Error Status bit (Receive mode only)
1 = A data nibble was received with less than 12 tick periods or greater than 27 tick periods
0 = Framing error has not occurred

bit 1 **RXIDLE:** SENTx Receiver Idle Status bit (Receive mode only)
1 = The SENTx data bus has been Idle (high) for a period of SYNCMAX<15:0> or greater
0 = The SENTx data bus is not Idle

Note 1: In Receive mode (RCVEN = 1), the SYNCTXEN bit is read-only.

REGISTER 21-2: UxSTA: UARTx STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	U-0	R/W-0, HC	R/W-0	R-0	R-1
UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN(1)	UTXBF	TRMT
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-1	R-0	R-0	R/C-0	R-0
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7							bit 0

Legend:	C = Clearable bit	HC = Hardware Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15,13 **UTXISEL<1:0>:** UARTx Transmission Interrupt Mode Selection bits
- 11 = Reserved; do not use
- 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR), and as a result, the transmit buffer becomes empty
- 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed
- 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)

bit 14 **UTXINV:** UARTx Transmit Polarity Inversion bit

If IREN = 0:
- 1 = UxTX Idle state is '0'
- 0 = UxTX Idle state is '1'

If IREN = 1:
- 1 = IrDA® encoded UxTX Idle state is '1'
- 0 = IrDA encoded UxTX Idle state is '0'

bit 12 **Unimplemented:** Read as '0'

bit 11 **UTXBRK:** UARTx Transmit Break bit
- 1 = Sends Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion
- 0 = Sync Break transmission is disabled or has completed

bit 10 **UTXEN:** UARTx Transmit Enable bit(1)
- 1 = Transmit is enabled, UxTX pin is controlled by UARTx
- 0 = Transmit is disabled, any pending transmission is aborted and the buffer is reset; UxTX pin is controlled by the PORT

bit 9 **UTXBF:** UARTx Transmit Buffer Full Status bit (read-only)
- 1 = Transmit buffer is full
- 0 = Transmit buffer is not full, at least one more character can be written

bit 8 **TRMT:** Transmit Shift Register (TSR) Empty bit (read-only)
- 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)
- 0 = Transmit Shift Register is not empty, a transmission is in progress or queued

bit 7-6 **URXISEL<1:0>:** UARTx Receive Interrupt Mode Selection bits
- 11 = Interrupt is set on UxRSR transfer, making the receive buffer full (i.e., has 4 data characters)
- 10 = Interrupt is set on UxRSR transfer, making the receive buffer 3/4 full (i.e., has 3 data characters)
- 0x = Interrupt is set when any character is received and transferred from the UxRSR to the receive buffer; receive buffer has one or more characters

Note 1: Refer to **"Universal Asynchronous Receiver Transmitter (UART)"** (DS70000582) in the *"dsPIC33/PIC24 Family Reference Manual"* for information on enabling the UART module for transmit operation.

27.0 SPECIAL FEATURES

Note: This data sheet summarizes the features of the dsPIC33EVXXXGM00X/10X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

The dsPIC33EVXXXGM00X/10X family devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection and CodeGuard™ Security
- In-Circuit Serial Programming™ (ICSP™)
- In-Circuit Emulation

27.1 Configuration Bits

In dsPIC33EVXXXGM00X/10X family devices, the Configuration bytes are implemented as volatile memory. This means that configuration data must be programmed each time the device is powered up. Configuration data is stored at the top of the on-chip program memory space, known as the Flash Configuration bytes. Their specific locations are shown in Table 27-1. The configuration data is automatically loaded from the Flash Configuration bytes to the proper Configuration Shadow registers during device Resets.

Note: Configuration data is reloaded on all types of device Resets.

When creating applications for these devices, users should always specifically allocate the location of the Flash Configuration bytes for configuration data in their code for the compiler. This is to ensure that program code is not stored in this address when the code is compiled.

The upper 2 bytes of all Flash Configuration Words in program memory should always be '1111 1111 1111 1111'. This makes them appear to be NOP instructions in the remote event that their locations are ever executed by accident. Since Configuration bits are not implemented in the corresponding locations, writing '1's to these locations has no effect on device operation.

Note: Performing a page erase operation on the last page of program memory clears the Flash Configuration bytes, enabling code protection as a result. Therefore, users should avoid performing page erase operations on the last page of program memory.

The Configuration Flash bytes map is shown in Table 27-1.

TABLE 27-2: dsPIC33EVXXXGM00X/10X CONFIGURATION BITS DESCRIPTION (CONTINUED)

Bit Field	Register	Description
DMTCNT<31:16>	FDMCNTH	Upper 16 Bits of 32-Bit Field that Configures the DMT Instruction Count Time-out Value bits
DMTEN	FDMT	Deadman Timer Enable bit 1 = Deadman Timer is enabled and cannot be disabled by software 0 = Deadman Timer is disabled and can be enabled by software
PWMLOCK	FDEVOPT	PWM Lock Enable bit 1 = Certain PWM registers may only be written after a key sequence 0 = PWM registers may be written without a key sequence
ALTI2C1	FDEVOPT	Alternate I^2C Pins for I2C1 bit 1 = I2C1 is mapped to the SDA1/SCL1 pins 0 = I2C1 is mapped to the ASDA1/ASCL1 pins
CTXT1<2:0>	FALTREG	Specifies the Alternate Working Register Set 1 Association with Interrupt Priority Level (IPL) bits 111 = Not assigned 110 = Alternate Register Set 1 is assigned to IPL Level 6 101 = Alternate Register Set 1 is assigned to IPL Level 5 100 = Alternate Register Set 1 is assigned to IPL Level 4 011 = Alternate Register Set 1 is assigned to IPL Level 3 010 = Alternate Register Set 1 is assigned to IPL Level 2 001 = Alternate Register Set 1 is assigned to IPL Level 1 000 = Not assigned
CTXT2<2:0>	FALTREG	Specifies the Alternate Working Register Set 2 Association with Interrupt Priority Level (IPL) bits 111 = Not assigned 110 = Alternate Register Set 2 is assigned to IPL Level 6 101 = Alternate Register Set 2 is assigned to IPL Level 5 100 = Alternate Register Set 2 is assigned to IPL Level 4 011 = Alternate Register Set 2 is assigned to IPL Level 3 010 = Alternate Register Set 2 is assigned to IPL Level 2 001 = Alternate Register Set 2 is assigned to IPL Level 1 000 = Not assigned

TABLE 31-13: PLL CLOCK TIMING SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 4.5V to 5.5V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C				
Param No.	Symbol	Characteristic	Min.	Typ.(1)	Max.	Units	Conditions
HOS50	FPLLI	PLL Voltage Controlled Oscillator (VCO) Input Frequency Range	0.8	—	8.0	MHz	ECPLL, XTPLL modes
HOS51	FSYS	On-Chip VCO System Frequency	120	—	340	MHz	
HOS52	TLOCK	PLL Start-up Time (Lock Time)	0.9	1.5	3.1	ms	
HOS53	DCLK	CLKO Stability (Jitter)(2)	-3	0.5	3	%	

Note 1: Data in "Typ." column is at 5.0V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: This jitter specification is based on clock cycle-by-clock cycle measurements. To get the effective jitter for individual time bases or communication clocks used by the application, use the following formula:

$$\text{Effective Jitter} = \frac{DCLK}{\sqrt{\frac{FOSC}{\text{Time Base or Communication Clock}}}}$$

For example, if FOSC = 120 MHz and the SPI bit rate = 10 MHz, the effective jitter is as follows:

$$\text{Effective Jitter} = \frac{DCLK}{\sqrt{\frac{120}{10}}} = \frac{DCLK}{\sqrt{12}} = \frac{DCLK}{3.464}$$

TABLE 31-14: INTERNAL FRC ACCURACY

AC CHARACTERISTICS		Standard Operating Conditions: 4.5V to 5.5V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C					
Param No.	Characteristic	Min	Typ	Max	Units	Conditions	
Internal FRC Accuracy @ FRC Frequency = 7.3728 MHz							
HF20C	FRC	-3	1	+3	%	-40°C ≤ TA ≤ +150°C	VDD = 4.5V to 5.5V

TABLE 31-15: INTERNAL LPRC ACCURACY

AC CHARACTERISTICS		Standard Operating Conditions: 4.5V to 5.5V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C					
Param No.	Characteristic	Min	Typ	Max	Units	Conditions	
LPRC @ 32.768 kHz(1,2)							
HF21C	LPRC	-30	10	+30	%	-40°C ≤ TA ≤ +150°C	VDD = 4.5V to 5.5V

Note 1: Change of LPRC frequency as VDD changes.

2: LPRC accuracy impacts the Watchdog Timer Time-out Period (TWDT1). See **Section 27.5 "Watchdog Timer (WDT)"** for more information.

FIGURE 32-3: TYPICAL IDD vs. VDD (EC MODE, 20 MIPS)

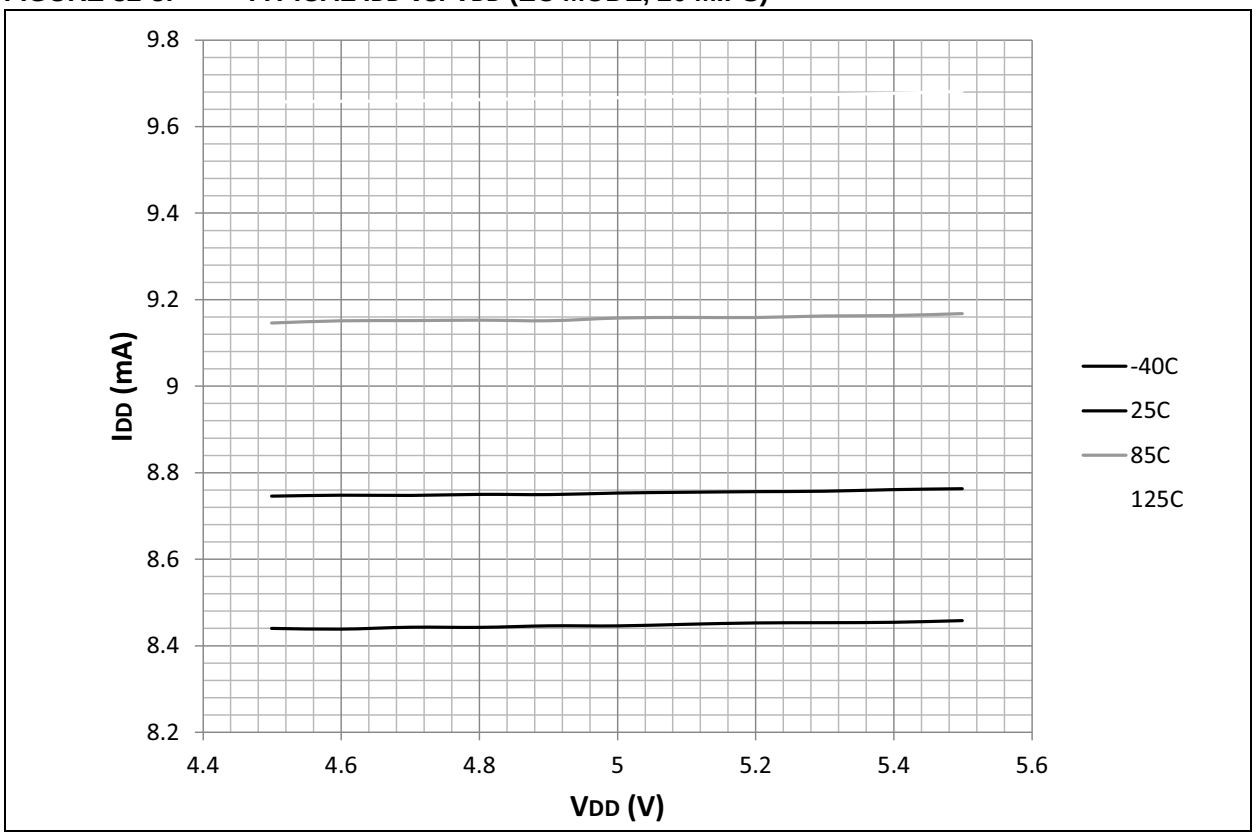


FIGURE 32-4: TYPICAL IDD vs. VDD (EC MODE, 40 MIPS)

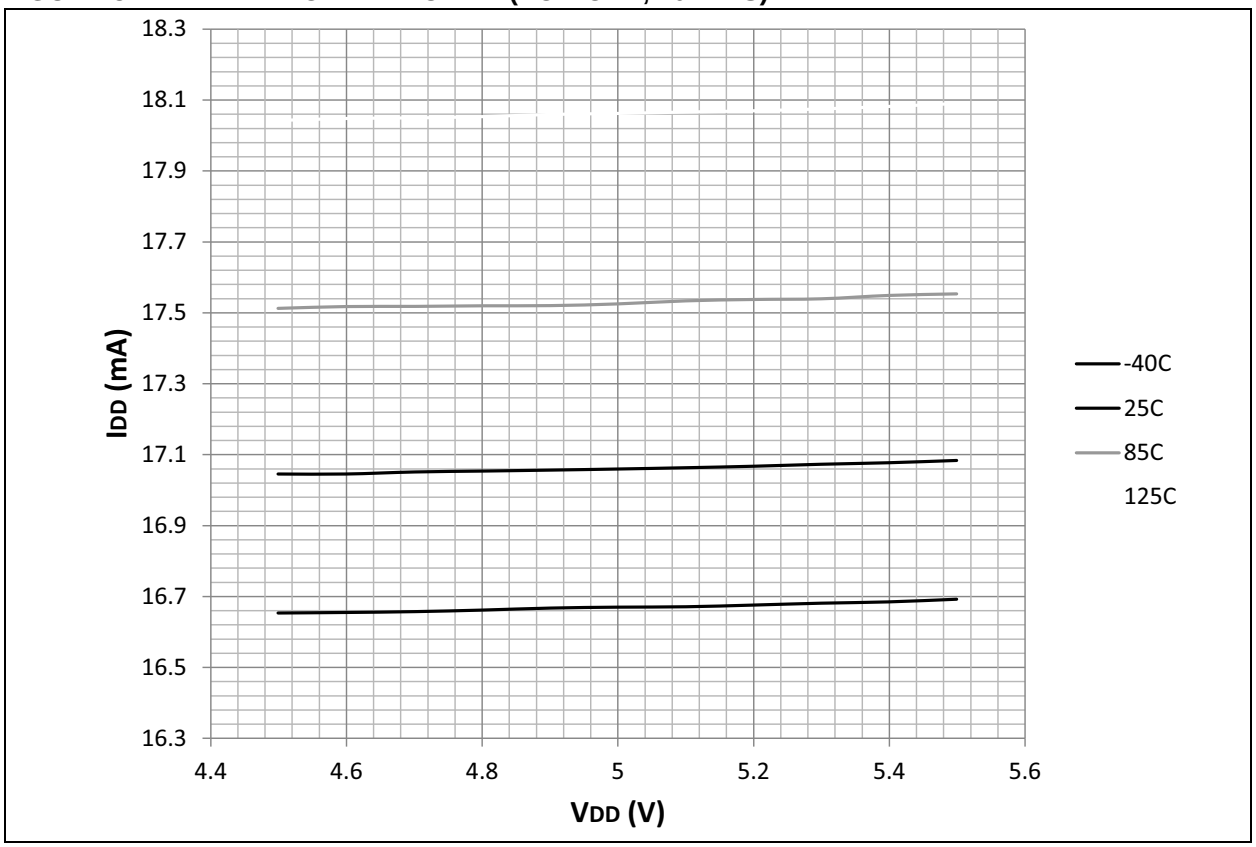
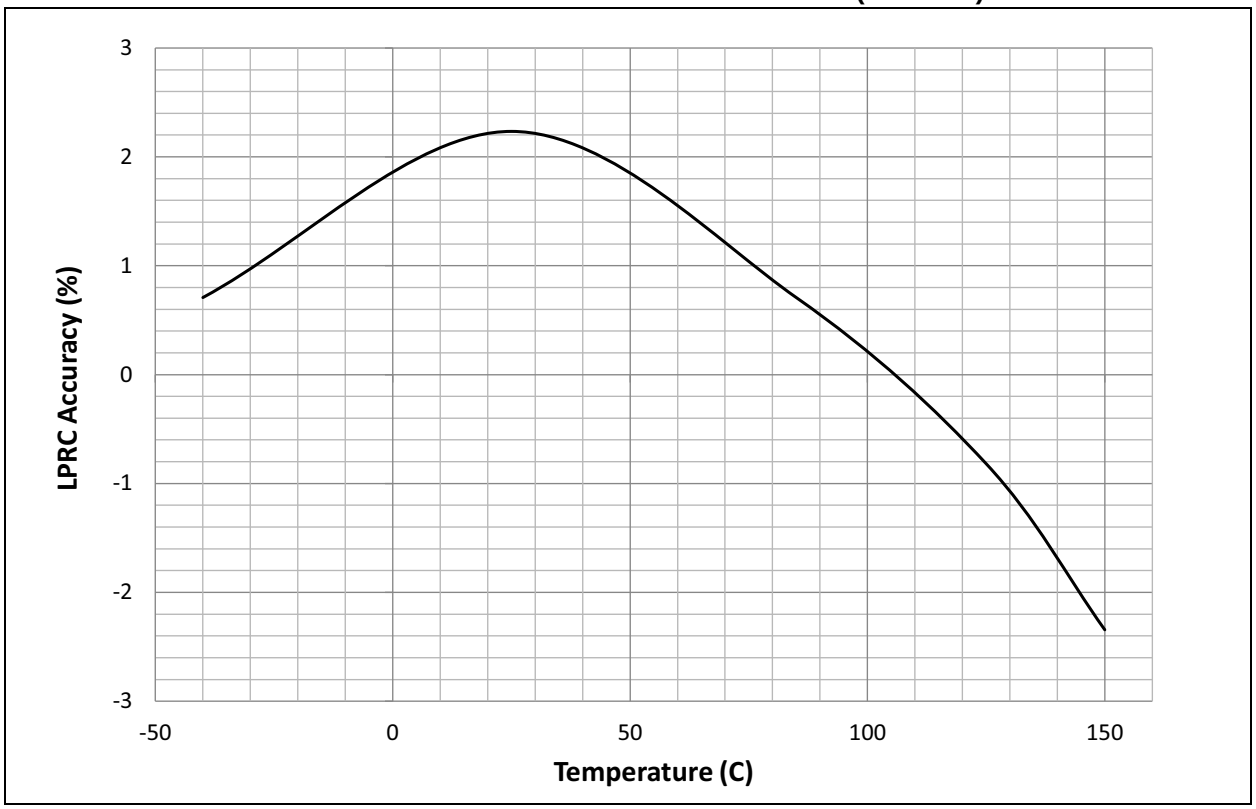


FIGURE 33-19: TYPICAL LPRC ACCURACY vs. TEMPERATURE (5.5V VDD)



33.7 Leakage Current

FIGURE 33-20: TYPICAL IIL vs. TEMPERATURE (MCLR)