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Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPs
Connectivity	CANbus, I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (11K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 11x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ev32gm102-e-ss

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SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
C1RXF11SID	046C	SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3	SID2	SID1	SID0	_	EXIDE	—	EID17	EID16	xxxx
C1RXF11EID	046E		EID<15:0> xx									xxxx						
C1RXF12SID	0470	SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3	SID2	SID1	SID0		EXIDE	_	EID17	EID16	xxxx
C1RXF12EID	0472	EID<15:0>									xxxx							
C1RXF13SID	0474	SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3	SID2	SID1	SID0	_	EXIDE	_	EID17	EID16	xxxx
C1RXF13EID	0476					-			E	EID<15:0>								xxxx
C1RXF14SID	0478	SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3	SID2	SID1	SID0	_	EXIDE	_	EID17	EID16	xxxx
C1RXF14EID	047A		EID<15:0> xxx								xxxx							
C1RXF15SID	047C	SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3	SID2	SID1	SID0	_	EXIDE	_	EID17	EID16	xxxx
C1RXF15EID	047E		EID<15:0> xxxx															

TABLE 4-11: CAN1 REGISTER MAP WHEN WIN (C1CTRL<0>) = 1 FOR dsPIC33EVXXXGM10X DEVICES (CONTINUED)

Legend: x = unknown value on Reset; - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-12: SENT1 RECEIVER REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SENT1CON1	0500	SNTEN	—	SNTSIDL	_	RCVEN	TXM	TXPOL	CRCEN	PPP	SPCEN	_	PS	_	NIBCNT2	NIBCNT1	NIBCNT0	0000
SENT1CON2	0504		TICKTIME<15:0> (Transmit modes) or SYNCMAX<15:0> (Receive mode) FFFF								FFFF							
SENT1CON3	0508	FRAMETIME<15:0> (Transmit modes) or SYNCMIN<15:0> (Receive mode)									FFFF							
SENT1STAT	050C		_	—		_		—	_	PAUSE	NIB2	NIB1	NIB0	CRCERR	FRMERR	RXIDLE	SYNCTXEN	0000
SENT1SYNC	0510						Synchi	ronization	Time Perio	d Registe	r (Transmit	mode)						0000
SENT1DATL	0514	DATA4<3:0> DATA5<3:0> DATA6<3:0> CRC<3:0>							0000									
SENT1DATH	0516		STAT	<3:0>			DATA1	<3:0>			DATA2	2<3:0>			DATA	43<3:0>		0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-13: SENT2 RECEIVER REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SENT2CON1	0520	SNTEN	—	SNTSIDL	—	RCVEN	TXM	TXPOL	CRCEN	PPP	SPCEN	—	PS	-	NIBCNT2	NIBCNT1	NIBCNT0	0000
SENT2CON2	0524		TICKTIME<15:0> (Transmit modes) or SYNCMAX<15:0> (Receive mode) FFFF															
SENT2CON3	0528	FRAMETIME<15:0> (Transmit modes) or SYNCMIN<15:0> (Receive mode)										FFFF						
SENT2STAT	052C	_	_	—	_	_	_	-	_	PAUSE	NIB2	NIB1	NIB0	CRCERR	FRMERR	RXIDLE	SYNCTXEN	0000
SENT2SYNC	0530						Synchi	ronization	Time Perio	d Registe	r (Transmit	mode)		_				0000
SENT2DATL	0534	DATA4<3:0> DATA5<3:0> DATA6<3:0> CRC<3:0>								0000								
SENT2DATH	0536	STAT<3:0> DATA1<3:0> DATA2<3:0>						0000										

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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4.5 Modulo Addressing

Modulo Addressing mode is a method of providing an automated means to support circular data buffers using hardware. The objective is to remove the need for software to perform data address boundary checks when executing tightly looped code, as is typical in many DSP algorithms.

Modulo Addressing can operate in either Data or Program Space (since the Data Pointer mechanism is essentially the same for both). One circular buffer can be supported in each of the X (which also provides the pointers into Program Space) and Y Data Spaces. Modulo Addressing can operate on any W Register Pointer. However, it is not advisable to use W14 or W15 for Modulo Addressing, since these two registers are used as the SFP and SSP, respectively.

In general, any particular circular buffer can be configured to operate in only one direction, as there are certain restrictions on the buffer start address (for incrementing buffers) or end address (for decrementing buffers), based upon the direction of the buffer.

The only exception to the usage restrictions is for buffers that have a power-of-two length. As these buffers satisfy the start and end address criteria, they can operate in a Bidirectional mode (that is, address boundary checks are performed on both the lower and upper address boundaries).

4.5.1 START AND END ADDRESS

The Modulo Addressing scheme requires that a starting and ending address be specified and loaded into the 16-bit Modulo Buffer Address registers: XMODSRT, XMODEND, YMODSRT and YMODEND (see Table 4-1).

The length of a circular buffer is not directly specified. It is determined by the difference between the corresponding start and end addresses. The maximum possible length of the circular buffer is 32K words (64 Kbytes).

4.5.2 W ADDRESS REGISTER SELECTION

The Modulo and Bit-Reversed Addressing Control register, MODCON<15:0>, contains enable flags, as well as a W register field to specify the W Address registers. The XWM and YWM fields select the registers that operate with Modulo Addressing:

- If XWM = 1111, X RAGU and X WAGU Modulo Addressing is disabled
- If YWM = 1111, Y AGU Modulo Addressing is disabled

The X Address Space Pointer W register (XWM) to which Modulo Addressing is to be applied is stored in MODCON<3:0> (see Table 4-1). Modulo Addressing is enabled for X Data Space when XWM is set to any value other than '1111' and the XMODEN bit (MODCON<15>) is set

The Y Address Space Pointer W register (YWM) to which Modulo Addressing is to be applied is stored in MODCON<7:4>. Modulo Addressing is enabled for Y Data Space when YWM is set to any value other than '1111' and the YMODEN bit (MODCON<14>) is set.

Figure 4-15 shows an example of Modulo Addressing operation.

Note: Y Data Space Modulo Addressing EA calculations assume word-sized data (LSb of every EA is always clear).



FIGURE 4-15: MODULO ADDRESSING OPERATION EXAMPLE

REGISTER 6-1: RCON: RESET CONTROL REGISTER⁽¹⁾ (CONTINUED)

bit 3	SLEEP: Wake-up from Sleep Flag bit
	1 = Device has been in Sleep mode
	0 = Device has not been in Sleep mode
bit 2	IDLE: Wake-up from Idle Flag bit
	1 = Device was in Idle mode
	0 = Device was not in Idle mode
bit 1	BOR: Brown-out Reset Flag bit
	1 = A Brown-out Reset has occurred
	0 = A Brown-out Reset has not occurred
bit 0	POR: Power-on Reset Flag bit
	1 = A Power-on Reset has occurred
	0 = A Power-on Reset has not occurred

- **Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.
 - 2: If the FWDTEN<1:0> Configuration bits are '11' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

dsPIC33EVXXXGM00X/10X FAMILY

FIGURE 7-1: dspic33evXXXGM00X/10X FAMILY ALTERNATE INTERRUPT VECTOR TAB	URE 7-1:	dsPIC33EVXXXGM00X/10X FAMILY ALTERNATE INTERRUPT VECTOR TABL
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	Peronyod	BSI M < 12.0 > (1) + 0.000000	
	Beggnved	BSLIN(<12.0<7 + 0.000000)	
	Casillatar Esil Tran Vestor	BSLIM<12.0×7+0000002	
		BSLIM<12:0×() + 0x000004	
	Address Error Trap Vector	BSLIM<12.0×7+00000000000000000000000000000000000	
	Generic Hard Trap Vector	BSLIM<12:0>(1)+0x000008	
	Stack Error Trap Vector	BSLIM<12.0>(1)+0.000000A	
	Math Error Trap Vector	BSLIM<12:0>(1)+0x00000C	
	DMAC Error Trap Vector	BSLIM<12:0>(1) + 0x00000E	
	Generic Soft Trap Vector	BSLIM<12:0>(1) + 0x000010	
	Reserved	BSLIM<12:0>(') + 0x000012	-
	Interrupt Vector 0	BSLIM<12:0>(') + 0x000014	
	Interrupt Vector 1	BSLIM<12:0>(1) + 0x000016	
	:	:	
	:	:	
	:	:	
5	Interrupt Vector 52	BSLIM<12:0> ⁽¹⁾ + 0x00007C	
	Interrupt Vector 53	BSLIM<12:0> ⁽¹⁾ + 0x00007E	\backslash
	Interrupt Vector 54	BSLIM<12:0> ⁽¹⁾ + 0x000080	See Table 7-1 for
	:] :	Interrupt Vector Details
	:	:	1
	:	:	
	Interrupt Vector 116	BSLIM<12:0> ⁽¹⁾ + 0x0000FC	
	Interrupt Vector 117	BSLIM<12:0> ⁽¹⁾ + 0x00007E	
	Interrupt Vector 118	BSLIM<12:0> ⁽¹⁾ + 0x000100	
	Interrupt Vector 119	BSLIM<12:0> ⁽¹⁾ + 0x000102	
	Interrupt Vector 120	BSLIM<12:0> ⁽¹⁾ + 0x000104	
	:] :	
	:] :	
	:	1 :	
	Interrupt Vector 244	BSLIM<12:0> ⁽¹⁾ + 0x0001FC	
V	Interrupt Vector 245	BSLIM<12:0> ⁽¹⁾ + 0x0001FE	
Note	1. The address depends on the si	ze of the Boot Segment defined by	v BSLIM<12.0>
NOLG	[(BSLIM<12:0> – 1) x 0x400] +	Offset.	J DOLIM (12.0 ⁻ .

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—		—	—	—
bit 15							bit 8
U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0

REGISTER 8-14: DMAPPS: DMA PING-PONG STATUS REGISTER

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
—	—	—	—	PPST3	PPST2	PPST1	PPST0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-4	Unimplemented: Read as '0'
bit 3	PPST3: Channel 3 Ping-Pong Mode Status Flag bit
	1 = DMA3STB register is selected0 = DMA3STA register is selected
bit 2	PPST2: Channel 2 Ping-Pong Mode Status Flag bit
	1 = DMA2STB register is selected
	0 = DMA2STA register is selected
bit 1	PPST1: Channel 1 Ping-Pong Mode Status Flag bit
	1 = DMA1STB register is selected
	0 = DMA1STA register is selected
bit 0	PPST0: Channel 0 Ping-Pong mode Status Flag bit
	1 = DMA0STB register is selected
	0 = DMA0STA register is selected

Table 9-1 provides the Configuration bits which allow users to choose between the various clock modes.

Oscillator Mode	Oscillator Source	POSCMD<1:0>	FNOSC<2:0>
Fast RC Oscillator with Divide-by-N (FRCDIVN) ^(1,2)	Internal	xx	111
Fast RC Oscillator with Divide-by-16 (FRCDIV16) ⁽¹⁾	Internal	xx	110
Low-Power RC Oscillator (LPRC) ⁽¹⁾	Internal	xx	101
Primary Oscillator (HS) with PLL (HSPLL)	Primary	10	011
Primary Oscillator (XT) with PLL (XTPLL)	Primary	01	011
Primary Oscillator (EC) with PLL (ECPLL) ⁽¹⁾	Primary	00	011
Primary Oscillator (HS)	Primary	10	010
Primary Oscillator (XT)	Primary	01	010
Primary Oscillator (EC) ⁽¹⁾	Primary	00	010
Fast RC Oscillator (FRC) with Divide-by-N and PLL (FRCPLL) ⁽¹⁾	Internal	XX	001
Fast RC Oscillator (FRC) ⁽¹⁾	Internal	xx	000

TABLE 9-1: CONFIGURATION BIT VALUES FOR CLOCK SELECTION

Note 1: OSC2 pin function is determined by the OSCIOFNC Configuration bit.

2: This is the default oscillator mode for an unprogrammed (erased) device.

NOTES:

REGISTER 11-3: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	_	—	—	—	—
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			T2CK	R<7:0>			
bit 7							bit 0
Legend:							

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **T2CKR<7:0>:** Assign Timer2 External Clock (T2CK) to the Corresponding RPn pin bits (see Table 11-2 for input pin selection numbers) 10110101 = Input tied to RPI181 •

• 00000001 = Input tied to CMP1 00000000 = Input tied to Vss

REGISTER 17-1: PTCON: PWMx TIME BASE CONTROL REGISTER (CONTINUED)

bit 6-4	SYNCSRC<2:0>: Synchronous Source Selection bits ⁽¹⁾					
	111 = Reserved					
	•					
	•					
	•					
	100 = Reserved					
	011 = Reserved					
	010 = Reserved					
	001 = Reserved					
	000 = SYNCI1 input from PPS					
bit 3-0	SEVTPS<3:0>: Special Event Trigger Output Postscaler Select bits ⁽¹⁾					
	1111 = 1:16 postscaler generates a Special Event Trigger on every sixteenth compare match event					
	•					
	•					
	•					
	0001 = 1:2 postscaler generates a Special Event Trigger on every second compare match event					
	0000 = 1:1 postscaler generates a Special Event Trigger on every compare match event					

Note 1: These bits should be changed only when PTEN = 0. In addition, when using the SYNCI1 feature, the user application must program the Period register with a value that is slightly larger than the expected period of the external synchronization input signal.

REGISTER 17-2: PTCON2: PWMx PRIMARY MASTER CLOCK DIVIDER SELECT REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	_	_	_	_	—	—
						bit 8
U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	_	_	_	F	PCLKDIV<2:0>(1)
						bit 0
	U-0 —	U-0 U-0 — — —	U-0 U-0 U-0 — — — —	U-0 U-0 U-0 U-0 — — — — —	U-0 U-0 U-0 U-0 R/W-0 — — — — — —	U-0 U-0 U-0 U-0 R/W-0 R/W-0 — — — — — PCLKDIV<2:0> ⁽¹

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-3 Unimplemented: Read as '0'

bit 2-0 PCLKDIV<2:0>: PWMx Input Clock Prescaler (Divider) Select bits⁽¹⁾

- 111 = Reserved
- 110 = Divide-by-64
- 101 = Divide-by-32
- 100 = Divide-by-16
- 011 = Divide-by-8
- 010 = Divide-by-4
- 001 = Divide-by-2

000 = Divide-by-1, maximum PWMx timing resolution (power-on default)

Note 1: These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PENH	PENL	POLH	POLL	PMOD1 ⁽¹⁾	PMOD0 ⁽¹⁾	OVRENH	OVRENL
bit 15						-	bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OVRDAT1	OVRDAT0	FLTDAT1	FLTDAT0	CLDAT1	CLDAT0	SWAP	OSYNC
bit 7							bit 0
r							
Legend:							
R = Readabl	le bit	W = Writable	bit	U = Unimpler	nented bit, reac	l as '0'	
-n = Value at	t POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
bit 15	PENH: PWM: 1 = PWMx mo 0 = GPIO mo	xH Output Pin odule controls dule controls th	Ownership bit the PWMxH p าe PWMxH piı	: in n			
bit 14	PENL: PWM> 1 = PWMx mo 0 = GPIO mo	KL Output Pin C odule controls dule controls the the the the the test of te	Dwnership bit the PWMxL pi ne PWMxL pir	in า			
bit 13	POLH: PWMx 1 = PWMxH p 0 = PWMxH p	xH Output Pin pin is active-lov pin is active-hig	Polarity bit v gh				
bit 12	POLL: PWM>	L Output Pin F	Polarity bit				
	1 = PWMxL p 0 = PWMxL p	in is active-low in is active-hig	/ h				
bit 11-10	PMOD<1:0>:	PWMx I/O Pin	1 Mode bits ⁽¹⁾				
	11 = Reserve 10 = PWMx // 01 = PWMx // 00 = PWMx //	d; do not use /O pin pair is in /O pin pair is in /O pin pair is in	i the Push-Pul i the Redunda i the Complem	Il Output mode Int Output mode nentary Output	e mode		
bit 9	OVRENH: OV	verride Enable	for PWMxH P	in bit			
	1 = OVRDAT 0 = PWMx ge	1 controls the c nerator contro	output on the I Is the PWMxH	PWMxH pin I pin			
bit 8	OVRENL: Ov	erride Enable	for PWMxL Pi	n bit			
	1 = OVRDAT(0 = PWMx ge	0 controls the c nerator contro	output on the I Is the PWMxL	PWMxL pin . pin			
bit 7-6	OVRDAT<1:0 If OVERENH If OVERENL)>: Data for PV = 1, PWMxH is = 1, PWMxL is	VMxH, PWMx s driven to the driven to the	L Pins if Overri state specified state specified	de is Enabled b by OVRDAT1. by OVRDAT0.	vits	
bit 5-4	FLTDAT<1:0:	>: Data for PW	MxH and PW	MxL Pins if FL1	MOD is Enable	ed bits	
	If Fault is acting If Fault is acting	ve, PWMxH is ve, PWMxL is	driven to the s driven to the s	state specified state specified I	by FLTDAT1. by FLTDAT0.		
bit 3-2	CLDAT<1:0> If current limit If current limit	: Data for PWN is active, PWN is active, PWN	/IxH and PWM /IxH is driven /IxL is driven t	1xL Pins if CLN to the state spe to the state spe	IOD is Enabled ecified by CLDA ecified by CLDA	bits \T1. T0.	
Note 1. T	hasa hite should	not he change	d after the D\A	/My module is (anabled (PTEN	= 1)	

REGISTER 17-13: IOCONx: PWMx I/O CONTROL REGISTER⁽²⁾

Note 1: These bits should not be changed after the PWMx module is enabled (PTEN = 1). **2:** If the PWMI OCK Configuration bit (EDEVOPT<0>) is a '1' the IOCONy register can only be

2: If the PWMLOCK Configuration bit (FDEVOPT<0>) is a '1', the IOCONx register can only be written after the unlock sequence has been executed.

REGISTER 17-15: FCLCONx: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER⁽¹⁾ (CONTINUED)

bit 7-3	FLTSRC<4:0>: Fault Control Signal Source Select for PWM Generator x bits 11111 = Fault 32 (default) 11110 = Reserved
	•
	•
	•
	01100 = Op Amp/Comparator 5 01011 = Comparator 4 01010 = Op Amp/Comparator 3 01001 = Op Amp/Comparator 2 01000 = Op Amp/Comparator 1 00111 = Fault 8 00110 = Fault 7 00101 = Fault 7 00101 = Fault 6 00100 = Fault 5 00011 = Fault 4 00010 = Fault 3 00001 = Fault 2 00000 = Fault 1
bit 2	FLTPOL: Fault Polarity for PWM Generator x bit ⁽²⁾
	 1 = The selected Fault source is active-low 0 = The selected Fault source is active-high
bit 1-0	FLTMOD<1:0>: Fault Mode for PWM Generator x bits
	 11 = Fault input is disabled 10 = Reserved 01 = The selected Fault source forces the PWMxH, PWMxL pins to FLTDAT<1:0> values (cycle) 00 = The selected Fault source forces the PWMxH, PWMxL pins to FLTDAT<1:0> values (latched condition)

- **Note 1:** If the PWMLOCK Configuration bit (FDEVOPT<0>) is a '1', the FCLCONx register can only be written after the unlock sequence has been executed.
 - 2: These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

REGISTER 20-1: SENTxCON1: SENTx CONTROL REGISTER 1 (CONTINUED)

- bit 3 Unimplemented: Read as '0'
- bit 2-0 NIBCNT<2:0>: Nibble Count Control bits
 - 111 = Reserved; do not use
 - 110 = Module transmits/receives 6 data nibbles in a SENT data pocket
 - 101 = Module transmits/receives 5 data nibbles in a SENT data pocket
 - 100 = Module transmits/receives 4 data nibbles in a SENT data pocket
 - 011 = Module transmits/receives 3 data nibbles in a SENT data pocket
 - 010 = Module transmits/receives 2 data nibbles in a SENT data pocket
 - $\tt 001$ = Module transmits/receives 1 data nibbles in a SENT data pocket
 - 000 = Reserved; do not use
- **Note 1:** This bit has no function in Receive mode (RCVEN = 1).
 - 2: This bit has no function in Transmit mode (RCVEN = 0).

REGISTER 25-3: CM4CON: COMPARATOR 4 CONTROL REGISTER (CONTINUED)

bit 7-6	EVPOL<1:0>: Trigger/Event/Interrupt Polarity Select bits ⁽²⁾
	 11 = Trigger/event/interrupt generated on any change of the comparator output (while CEVT = 0) 10 = Trigger/event/interrupt generated only on high-to-low transition of the polarity selected comparator output (while CEVT = 0)
	If CPOL = 1 (inverted polarity): Low-to-high transition of the comparator output.
	If CPOL = 0 (non-inverted polarity): High-to-low transition of the comparator output.
	01 = Trigger/event/interrupt generated only on low-to-high transition of the polarity selected comparator output (while CEVT = 0)
	If CPOL = 1 (inverted polarity): High-to-low transition of the comparator output.
	If CPOL = 0 (non-inverted polarity): Low-to-high transition of the comparator output.
	00 = Trigger/event/interrupt generation is disabled
bit 5	Unimplemented: Read as '0'
bit 4	CREF: Comparator 4 Reference Select bit (VIN+ input) ⁽¹⁾
	 1 = VIN+ input connects to the internal CVREFIN voltage 0 = VIN+ input connects to the C4IN1+ pin
bit 3-2	Unimplemented: Read as '0'
bit 1-0	CCH<1:0>: Comparator 4 Channel Select bits ⁽¹⁾
	 11 = VIN- input of comparator connects to the C4IN4- pin 10 = VIN- input of comparator connects to the C4IN3- pin 01 = VIN- input of comparator connects to the C4IN2- pin 00 = VIN- input of comparator connects to the C4IN1- pin
Note 1:	Inputs that are selected and not available will be tied to Vss. See the " Pin Diagrams " section for available inputs for each package.

2: After configuring the comparator, either for a high-to-low or low-to-high COUT transition (EVPOL<1:0> (CMxCON<7:6>) = 10 or 01), the comparator Event bit, CEVT (CMxCON<9>), and the Comparator Combined Interrupt Flag, CMPIF (IFS1<2>), must be cleared before enabling the Comparator Interrupt Enable bit, CMPIE (IEC1<2>).

Bit Field	Register	Description
DMTCNT<31:16>	FDMCNTH	Upper 16 Bits of 32-Bit Field that Configures the DMT Instruction Count Time-out Value bits
DMTEN	FDMT	Deadman Timer Enable bit 1 = Deadman Timer is enabled and cannot be disabled by software 0 = Deadman Timer is disabled and can be enabled by software
PWMLOCK	FDEVOPT	PWM Lock Enable bit 1 = Certain PWM registers may only be written after a key sequence 0 = PWM registers may be written without a key sequence
ALTI2C1	FDEVOPT	Alternate I ² C Pins for I2C1 bit 1 = I2C1 is mapped to the SDA1/SCL1 pins 0 = I2C1 is mapped to the ASDA1/ASCL1 pins
CTXT1<2:0>	FALTREG	Specifies the Alternate Working Register Set 1 Association with Interrupt Priority Level (IPL) bits 111 = Not assigned 110 = Alternate Register Set 1 is assigned to IPL Level 6 101 = Alternate Register Set 1 is assigned to IPL Level 5 100 = Alternate Register Set 1 is assigned to IPL Level 4 011 = Alternate Register Set 1 is assigned to IPL Level 3 010 = Alternate Register Set 1 is assigned to IPL Level 2 001 = Alternate Register Set 1 is assigned to IPL Level 2 001 = Alternate Register Set 1 is assigned to IPL Level 1
CTXT2<2:0>	FALTREG	Specifies the Alternate Working Register Set 2 Association with Interrupt Priority Level (IPL) bits 111 = Not assigned 110 = Alternate Register Set 2 is assigned to IPL Level 6 101 = Alternate Register Set 2 is assigned to IPL Level 5 100 = Alternate Register Set 2 is assigned to IPL Level 4 011 = Alternate Register Set 2 is assigned to IPL Level 3 010 = Alternate Register Set 2 is assigned to IPL Level 2 001 = Alternate Register Set 2 is assigned to IPL Level 2 001 = Alternate Register Set 2 is assigned to IPL Level 1

TABLE 27-2: dsPIC33EVXXXGM00X/10X CONFIGURATION BITS DESCRIPTION (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax		Description	# of Words	# of Cycles	Status Flags Affected
53	MUL	MUL.SS	Wb,Ws,Wnd	{Wnd + 1, Wnd} = signed(Wb) * signed(Ws)	1	1	None
		MUL.SS	Wb,Ws,Acc	Accumulator = signed(Wb) * signed(Ws)	1	1	None
		MUL.SU	Wb,Ws,Wnd	{Wnd + 1, Wnd} = signed(Wb) * unsigned(Ws)	1	1	None
		MUL.SU	Wb,Ws,Acc	Accumulator = signed(Wb) * unsigned(Ws)	1	1	None
		MUL.SU	Wb,#lit5,Acc	Accumulator = signed(Wb) * unsigned(lit5)	1	1	None
		MUL.US	Wb,Ws,Wnd	{Wnd + 1, Wnd} = unsigned(Wb) * signed(Ws)	1	1	None
		MUL.US	Wb,Ws,Acc	Accumulator = unsigned(Wb) * signed(Ws)	1	1	None
		MUL.UU	Wb,Ws,Wnd	{Wnd + 1, Wnd} = unsigned(Wb) * unsigned(Ws)	1	1	None
		MUL.UU	Wb,#lit5,Acc	Accumulator = unsigned(Wb) * unsigned(lit5)	1	1	None
		MUL.UU	Wb,Ws,Acc	Accumulator = unsigned(Wb) * unsigned(Ws)	1	1	None
		MULW.SS	Wb,Ws,Wnd	Wnd = signed(Wb) * signed(Ws)	1	1	None
		MULW.SU	Wb,Ws,Wnd	Wnd = signed(Wb) * unsigned(Ws)	1	1	None
		MULW.US	Wb,Ws,Wnd	Wnd = unsigned(Wb) * signed(Ws)	1	1	None
		MULW.UU	Wb,Ws,Wnd	Wnd = unsigned(Wb) * unsigned(Ws)	1	1	None
		MUL.SU	Wb,#lit5,Wnd	{Wnd + 1, Wnd} = signed(Wb) * unsigned(lit5)	1	1	None
		MUL.SU	Wb,#lit5,Wnd	Wnd = signed(Wb) * unsigned(lit5)	1	1	None
		MUL.UU	Wb,#lit5,Wnd	{Wnd + 1, Wnd} = unsigned(Wb) * unsigned(lit5)	1	1	None
		MUL.UU	Wb,#lit5,Wnd	Wnd = unsigned(Wb) * unsigned(lit5)	1	1	None
		MUL	f	W3:W2 = f * WREG	1	1	None
54	NEG	NEG	Acc	Negate Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
		NEG	f	$f = \overline{f} + 1$	1	1	C,DC,N,OV,Z
		NEG	f,WREG	WREG = \overline{f} + 1	1	1	C,DC,N,OV,Z
		NEG	Ws,Wd	$Wd = \overline{Ws} + 1$	1	1	C,DC,N,OV,Z
55	NOP	NOP		No Operation	1	1	None
		NOPR		No Operation	1	1	None
56	POP	POP	f	Pop f from Top-of-Stack (TOS)	1	1	None
		POP	Wdo	Pop from Top-of-Stack (TOS) to Wdo	1	1	None
		POP.D	Wnd	Pop from Top-of-Stack (TOS) to W(nd):W(nd + 1)	1	2	None
		POP.S		Pop Shadow Registers	1	1	All
57	PUSH	PUSH	f	Push f to Top-of-Stack (TOS)	1	1	None
		PUSH	Wso	Push Wso to Top-of-Stack (TOS)	1	1	None
		PUSH.D	Wns	Push W(ns):W(ns + 1) to Top-of-Stack (TOS)	1	2	None
		PUSH.S		Push Shadow Registers	1	1	None
58	PWRSAV	PWRSAV	#lit1	Go into Sleep or Idle mode	1	1	WDTO,Sleep
59	RCALL	RCALL	Expr	Relative Call	1	4	SFA
L		RCALL	Wn	Computed Call	1	4	SFA
60	REPEAT	REPEAT	#lit15	Repeat Next Instruction lit15 + 1 times	1	1	None
		REPEAT	Wn	Repeat Next Instruction (Wn) + 1 times	1	1	None
61	RESET	RESET		Software device Reset	1	1	None
62	RETFIE	RETFIE		Return from interrupt	1	6 (5)	SFA

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Note: Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.

TABLE 30-6:	DC CHARACTERISTICS: OPERATING CURRENT (IDD)	
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DC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 4.5V to 5.5V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$			
Param.	Тур. ⁽²⁾	Max.	Units		Conditio	ons
Operating Cur	rent (IDD) ⁽¹⁾					
DC20d	4.5	5.5	mA	-40°C		
DC20a	4.65	5.6	mA	+25°C	5.01/	
DC20b	4.85	6.0	mA	+85°C	5.00	
DC20c	5.6	7.2	mA	+125°C		
DC22d	8.6	10.6	mA	-40°C		
DC22a	8.8	10.8	mA	+25°C	5.0V	
DC22b	9.1	11.1	mA	+85°C		20 MIF 3
DC22c	9.8	12.6	mA	+125°C		
DC23d	16.8	18.5	mA	-40°C		
DC23a	17.2	19.0	mA	+25°C	5.0\/	
DC23b	17.55	19.2	mA	+85°C	5.0 V	40 MIF 3
DC23c	18.3	21.0	mA	+125°C		
DC24d	25.15	28.0	mA	-40°C		
DC24a	25.5	28.0	mA	+25°C	5.0\/	
DC24b	25.5	28.0	mA	+85°C	5.0 v	
DC24c	25.55	28.5	mA	+125°C		
DC25d	29.0	31.0	mA	-40°C		
DC25a	28.5	31.0	mA	+25°C	5.0V	70 MIPS
DC25b	28.3	31.0	mA	+85°C		

Note 1: IDD is primarily a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows:

 Oscillator is configured in EC mode and external clock is active, OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)

- · CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as outputs and driving low
- MCLR = VDD, WDT and FSCM are disabled
- CPU, SRAM, program memory and data memory are operational
- No peripheral modules are operating or being clocked (defined PMDx bits are all ones)
- CPU executing
 - while(1)

```
{
NOP();
```

```
NOP ( )
```

2: Data in "Typ." column is at 5.0V, +25°C unless otherwise stated.

DC CHARACTERISTICS			Standard Operating Conc (unless otherwise stated) Operating temperature -4 -4			ndition: d) -40°C ≤ -40°C ≤	ditions: 4.5V to 5.5V i) $40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $40^{\circ}C \le TA \le +125^{\circ}C$ for Extended		
Param No.	Symbol	Characteristic	Min.	Min. Typ. ⁽¹⁾ Max.		Units	Conditions		
		Program Flash Memory							
D130	Eр	Cell Endurance	10,000	—	_	E/W	-40°C to +125°C		
D131	Vpr	VDD for Read	4.5	—	5.5	V			
D132b	VPEW	VDD for Self-Timed Write	4.5	—	5.5	V			
D134	TRETD	Characteristic Retention	20	—	—	Year	Provided no other specifications are violated, -40°C to +125°C		
D135	IDDP	Supply Current During Programming	—	10	—	mA			
D136a	Trw	Row Write Cycle Time	0.657	_	0.691	ms	Trw = 4965 FRC cycles, Ta = +85°C (see Note 2)		
D136b	Trw	Row Write Cycle Time	0.651	—	0.698	ms	Trw = 4965 FRC cycles, Ta = +125°C (see Note 2)		
D137a	TPE	Page Erase Time	19.44	—	20.44	ms	TPE = 146893 FRC cycles, TA = +85°C (see Note 2)		
D137b	TPE	Page Erase Time	19.24	-	20.65	ms	TPE = 146893 FRC cycles, TA = +125°C (see Note 2)		
D138a	Tww	Word Write Cycle Time	45.78	_	48.15	μs	Tww = 346 FRC cycles, TA = +85°C (see Note 2)		
D138b	Tww	Word Write Cycle Time	45.33	_	48.64	μs	Tww = 346 FRC cycles, Ta = +125°C (see Note 2)		

TABLE 30-13: DC CHARACTERISTICS: PROGRAM MEMORY

Note 1: Data in "Typ." column is at 5.0V, +25°C unless otherwise stated.

2: Other conditions: FRC = 7.3728 MHz, TUN<5:0> = b'011111 (for Min), TUN<5:0> = b'100000 (for Max). This parameter depends on the FRC accuracy (see Table 30-20) and the value of the FRC Oscillator Tuning register.

TABLE 30-14: ELECTRICAL CHARACTERISTICS: INTERNAL BAND GAP REFERENCE VOLTAGE

DC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 4.5V to 5.5V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Param No.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Conditions		
DVR10	Vbg	Internal Band Gap Reference Voltage	1.14	1.2	1.26	V			



AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 4.5V to 5.5V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic ⁽²⁾		Min.	Тур.	Max.	Units	Conditions
TA10	ТтхН	T1CK High Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	_	_	ns	Must also meet Parameter TA15, N = Prescaler Value (1, 8, 64, 256)
			Asynchronous mode	35	_	—	ns	
TA11	ΤτxL	T1CK Low Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	_	_	ns	Must also meet Parameter TA15, N = Prescaler Value (1, 8, 64, 256)
			Asynchronous mode	10	—	—	ns	
TA15	ΤτχΡ	T1CK Input Period	Synchronous mode	Greater of: 40 or (2 Tcy + 40)/N	—	_	ns	N = Prescaler Value (1, 8, 64, 256)
OS60	Ft1	T1CK Oscillator Input Frequency Range (oscillator enabled by setting TCS (T1CON<1>) bit)		DC	_	50	kHz	
TA20	TCKEXTMRL	Delay from External T1CK Clock Edge to Timer Increment		0.75 TCY + 40	_	1.75 Tcy + 40	ns	

TABLE 30-23: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS⁽¹⁾

Note 1: Timer1 is a Type A.

2: These parameters are characterized but not tested in manufacturing.

TABLE 30-50: OP AMP/COMPARATOR x SPECIFICATIONS

DC CHARACTERISTICS			Standard Op (unless othe Operating ter	erating rwise st	Conditions (s ated) $e -40^{\circ}C \le TA$	proditions (see Note 3): 4.5V to 5.5V ed) -40°C \leq TA \leq +85°C for Industrial				
					$-40^{\circ}C \le TA$	-40°C \leq TA \leq +125°C for Extended				
Param No.	aram Symbol Characteristic		Min.	Тур. ⁽¹⁾	Max.	Units	Conditions			
Comparator AC Characteristics										
CM10	Tresp	Response Time	—	19	80	ns	V+ input step of 100 mV, V- input held at VDD/2			
CM11	Тмс2о∨	Comparator Mode Change to Output Valid	—	_	10	μs				
		Con	nparator DC C	haracte	ristics					
CM30	VOFFSET	Comparator Offset Voltage	-80	±60	80	mV				
CM31	VHYST	Input Hysteresis Voltage	—	30	_	mV				
CM32	TRISE/ TFALL	Comparator Output Rise/Fall Time	—	20	—	ns	1 pF load capacitance on input			
CM33	Vgain	Open-Loop Voltage Gain	—	90	—	db				
CM34	VICM	Input Common-Mode Voltage	AVss	—	AVDD	V				
	Op Amp AC Characteristics									
CM20	SR	Slew Rate	—	9	—	V/µs	10 pF load			
CM21	Рм	Phase Margin	—	35	_	°C	G = 100V/V, 10 pF load			
CM22	Gм	Gain Margin	—	20	_	db	G = 100V/V, 10 pF load			
CM23	GBW	Gain Bandwidth	—	10		MHz	10 pF load			
		O	o Amp DC Cha	aracteris	stics					
CM40	VCMR	Common-Mode Input Voltage Range	AVss	-	AVDD	V				
CM41	CMRR	Common-Mode Rejection Ratio	—	45	_	db	VCM = AVDD/2			
CM42	VOFFSET	Op Amp Offset Voltage	-50	±6	50	mV				
CM43	Vgain	Open-Loop Voltage Gain	—	90		db				
CM44	los	Input Offset Current	—	-	_	_	See pad leakage currents in Table 30-10			
CM45	Ів	Input Bias Current	—	-	_	_	See pad leakage currents in Table 30-10			
CM46	Ιουτ	Output Current		_	420	μA	With minimum value of RFEEDBACK (CM48)			
CM48	RFEEDBACK	Feedback Resistance Value	8	_		kΩ	Note 2			
CM49a	Vout	Output Voltage	AVss + 0.075	_	AVDD - 0.075	V	Ιουτ = 420 μΑ			

Note 1: Data in "Typ." column is at 5.0V, +25°C unless otherwise stated.

2: Resistances can vary by ±10% between op amps.

3: Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules: ADC, op amp/comparator and comparator voltage reference, will have degraded performance. Refer to Parameter BO10 in Table 30-12 for the minimum and maximum BOR values.

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN or VQFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS						
Dimension	MIN	NOM	MAX				
Number of Pins	N	44					
Pitch	е	0.65 BSC					
Overall Height	A	0.80	0.90	1.00			
Standoff	A1	0.00	0.02	0.05			
Terminal Thickness	A3	0.20 REF					
Overall Width	E	8.00 BSC					
Exposed Pad Width	E2	6.25	6.45	6.60			
Overall Length	D	8.00 BSC					
Exposed Pad Length	D2	6.25	6.45	6.60			
Terminal Width	b	0.20	0.30	0.35			
Terminal Length	L	0.30	0.40	0.50			
Terminal-to-Exposed-Pad	K	0.20	-	-			

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated
- 3. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-103D Sheet 2 of 2