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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details		
Product Status	Obsolete	
Core Processor	eZ8	
Core Size	8-Bit	
Speed	20MHz	
Connectivity	I ² C, IrDA, UART/USART	
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT	
Number of I/O	11	
Program Memory Size	8KB (8K x 8)	
Program Memory Type	FLASH	
EEPROM Size	-	
RAM Size	1K x 8	
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V	
Data Converters	-	
Oscillator Type	Internal	
Operating Temperature	0°C ~ 70°C (TA)	
Mounting Type	Surface Mount	
Package / Case	20-SSOP (0.209", 5.30mm Width)	
Supplier Device Package	-	
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f0811hh020sc00tr	

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- 2.7 V to 3.6 V operating voltage with 5 V-tolerant inputs
- 20-pin and 28-pin packages
- 0 °C to +70 °C standard temperature and -40 °C to +105 °C extended temperature operating ranges

Part Selection Guide

Table 1 identifies the basic features and package styles available for each device within the Z8 Encore! $XP^{\text{(B)}}$ F0822 Series product line.

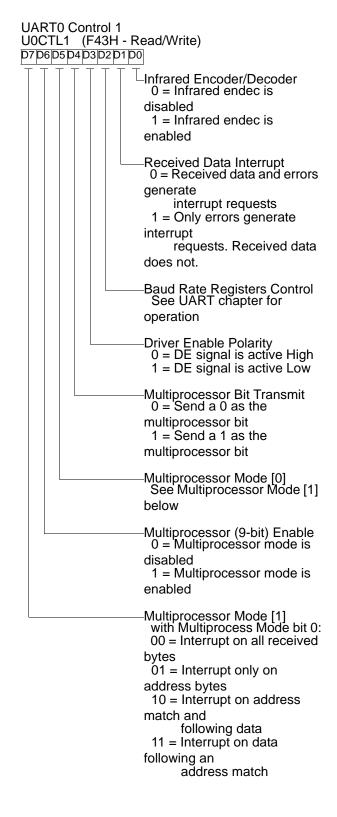
Table 1. Z8 Encore! XP® F0822 Series Part Selection Guide

Part	Flash	RAM		16-bit Timers	ADC	UARTs				ge Pin unts
Number	(KB)	(KB)	I/O	with PWM	_	with IrDA	I ² C	SPI	20	28
Z8F0822	8	1	19	2	5	1	1	1		Х
Z8F0821	8	1	11	2	2	1	1		Χ	
Z8F0812	8	1	19	2	0	1	1	1		Х
Z8F0811	8	1	11	2	0	1	1		Χ	
Z8F0422	4	1	19	2	5	1	1	1		Х
Z8F0421	4	1	11	2	2	1	1		Χ	
Z8F0412	4	1	19	2	0	1	1	1		Х
Z8F0411	4	1	11	2	0	1	1		Χ	

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Table 7. Register File Address Map (Continued)

Address				
(Hex)	Register Description	Mnemonic	Reset (Hex)	Page No
FCE	Reserved	_	00	
FCF	Interrupt Control	IRQCTL	00	67
GPIO Port A				
FD0	Port A Address	PAADDR	00	50
FD1	Port A Control	PACTL	00	51
FD2	Port A Input Data	PAIN	XX	54
FD3	Port A Output Data	PAOUT	00	55
GPIO Port B				
FD4	Port B Address	PBADDR	00	50
FD5	Port B Control	PBCTL	00	51
FD6	Port B Input Data	PBIN	XX	54
FD7	Port B Output Data	PBOUT	00	55
GPIO Port C				
FD8	Port C Address	PCADDR	00	50
FD9	Port C Control	PCCTL	00	51
FDA	Port C Input Data	PCIN	XX	54
FDB	Port C Output Data	PCOUT	00	55
FDC-FEF	Reserved	_	XX	
Watchdog Tir	mer (WDT)			
FF0	Watchdog Timer Control	WDTCTL	XXX00000b	86
FF1	Watchdog Timer Reload Upper Byte	WDTU	FF	87
FF2	Watchdog Timer Reload High Byte	WDTH	FF	87
FF3	Watchdog Timer Reload Low Byte	WDTL	FF	87
FF4-FF7	Reserved	_	XX	
Flash Memor	y Controller			
FF8	Flash Control	FCTL	00	159
FF8	Flash Status	FSTAT	00	160
FF9	Page Select	FPS	00	160
FF9 (if enabled) Flash Sector Protect	FPROT	00	161
FFA	Flash Programming Frequency High Byte	FFREQH	00	161
FFB	Flash Programming Frequency Low Byte		00	161
Read-Only M	emory			
FF8	Reserved	_	XX	
FF9	Page Select	RPS	00	160
FFA-FFB	Reserved	_	XX	
eZ8 CPU				
XX=Undefined				



```
ADC Control
ADCCTL (F70H - Read/Write)
D7 D6 D5 D4 D3 D2 D1 D0
                     -Analog Input Select
0000 = ANA0 0001 =
                     ANA1
                      0010 = ANA2
                                         0011 =
                     ANA3
                      0100 = ANA4
                      0101 through 21111 =
                     Reserved
                     Continuous Mode Select
                      0 = Single-shot conversion
                      1 = Continuous conversion
                     External VREF select 0 = Internal voltage
                     reference selected
                      1 = External voltage
                     reference selected
                     -Reserved
                     Conversion Enable
```

0 = Conversion is complete 1 = Begin conversion

ADC Data High Byte
ADCD_H (F72H - Read Only)

D7 D6 D5 D4 D3 D2 D1 D0

ADC Data [9:2]

ADC Data Low Bits
ADCD_L (F73H - Read Only)
D7 D6 D5 D4 D3 D2 D1 D0
Reserved
ADC Data [1:0]

Reset and Stop Mode Recovery

The Reset Controller within the Z8 Encore! XP[®] F0822 Series controls Reset and Stop Mode Recovery operation. In typical operation, the following events cause a Reset to occur:

- Power-On Reset (POR)
- Voltage Brownout
- WDT time-out (when configured through the WDT_RES Option Bit to initiate a Reset)
- External RESET pin assertion
- On-Chip Debugger initiated Reset (OCDCTL[0] set to 1)

When the Z8 Encore! XP F0822 Series device is in STOP mode, a Stop Mode Recovery is initiated by any of the following events:

- WDT time-out
- GPIO Port input pin transition on an enabled Stop Mode Recovery source
- DBG pin driven Low

Reset Types

Z8 Encore! XP F0822 Series provides two types of reset operation (System Reset and Stop Mode Recovery). The type of reset is a function of both the current operating mode of the Z8 Encore! XP F0822 Series device and the source of the Reset. Table 8 lists the types of Resets and their operating characteristics.

Table 8. Reset and Stop Mode Recovery Characteristics and Latency

	Reset Characterist	ics and	Latency
Reset Type	Control Registers	eZ8 CPU	Reset Latency (Delay)
System Reset	Reset (as applicable)	Reset	66 WDT Oscillator cycles + 16 System Clock cycles
Stop Mode Recovery	Unaffected, except WDT_CTL register	Reset	66 WDT Oscillator cycles + 16 System Clock cycles

Power-On Reset

Each device in the Z8 Encore! XP^{\circledR} F0822 Series contains an internal POR circuit. The POR circuit monitors the supply voltage and holds the device in the Reset state until the supply voltage reaches a safe operating level. After the supply voltage exceeds the POR voltage threshold (V_{POR}), the POR Counter is enabled and counts 66 cycles of the WDT oscillator. After the POR counter times out, the XTAL Counter is enabled to count a total of 16 system clock pulses. The device is held in the Reset state until both the POR Counter and XTAL counter have timed out. After the Z8 Encore! XP F0822 Series device exits the POR state, the eZ8 CPU fetches the Reset vector. Following POR, the POR status bit in the Watchdog Timer Control Register (WDTCTL) is set to 1.

Figure 6 displays POR operation. See Electrical Characteristics for POR threshold voltage (V_{POR}) .

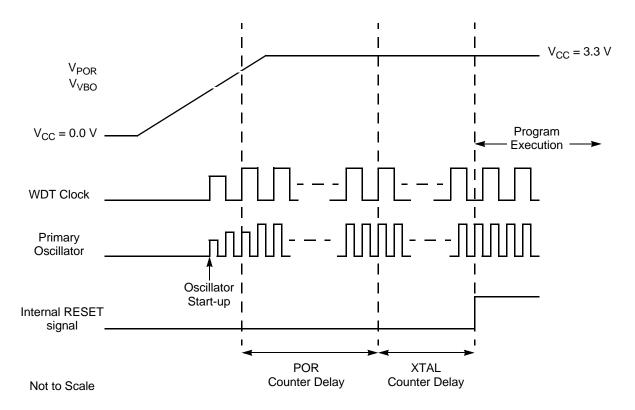


Figure 6. Power-On Reset Operation

Voltage Brownout Reset

The devices in Z8 Encore! XP F0822 Series provide low Voltage Brownout protection. The VBO circuit senses when the supply voltage drops to an unsafe level (below the VBO threshold voltage) and forces the device into the Reset state. While the supply voltage

Table 43. Timer 0–1 PWM High Byte Register (TxPWMH)

BITS	7	6	5	4	3	2	1	0		
FIELD		PWMH								
RESET				()					
R/W		R/W								
ADDR				F04H,	F0CH					

Table 44. Timer 0–1 PWM Low Byte Register (TxPWML)

BITS	7	6	5	4	3	2	1	0			
FIELD		PWML									
RESET		0									
R/W		R/W									
ADDR				F05H,	F0DH						

PWMH and PWML—Pulse-Width Modulator High and Low Bytes

These two bytes, {PWMH[7:0], PWML[7:0]}, form a 16-bit value that is compared to the current 16-bit timer count. When a match occurs, the PWM output changes state. The PWM output value is set by the TPOL bit in the Timer Control Register (TxCTL) register.

The TxPWMH and TxPWML registers also store the 16-bit captured timer value when operating in CAPTURE or CAPTURE/COMPARE modes.

Timer 0–3 Control 0 Registers

The Timer 0–3 Control 0 (TxCTL0) registers (Table 45) allow cascading of the Timers.

Table 45. Timer 0–3 Control 0 Register (TxCTL0)

BITS	7	6	5	4	3	2	1	0		
FIELD		Reserved		CSC	CSC Reserved					
RESET		Ō								
R/W		R/W								
ADDR			F	06H, F0EH,	F16H, F1E	Н				

CSC—Cascade Timers

0 = Timer Input signal comes from the pin.

1 = For Timer 0, input signal is connected to Timer 1 output. For Timer 1, input signal is connected to Timer 0 output.

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PSEL—Parity Select

0 =Even parity is transmitted and expected on all received data.

1 = Odd parity is transmitted and expected on all received data.

SBRK—Send Break

This bit pauses or breaks data transmission by forcing the Transmit data output to 0. Sending a break interrupts any transmission in progress, so ensure that the transmitter has finished sending data before setting this bit. The UART does not automatically generate a STOP Bit when SBRK is deasserted. Software must time the duration of the Break and the duration of any STOP Bit time desired following the Break.

0 = No break is sent.

1 = The output of the transmitter is zero.

STOP—STOP Bit Select

0 = The transmitter sends one stop bit.

1 = The transmitter sends two stop bits.

LBEN—Loop Back Enable

0 = Normal operation.

1 = All transmitted data is looped back to the receiver.

Table 57. UART Control 1 Register (U0CTL1)

BITS	7	6	5	4	3	2	1	0			
FIELD	MPMD[1]	MPEN	MPMD[0]	MPBT	DEPOL	BRGCTL	RDAIRQ	IREN			
RESET		0									
R/W		R/W									
ADDR				F4	3H						

MPMD[1:0]—Multiprocessor Mode

If Multiprocessor (9-bit) mode is enabled,

00 = The UART generates an interrupt request on all received bytes (data and address).

- 01 = The UART generates an interrupt request only on received address bytes.
- 10 = The UART generates an interrupt request when a received address byte matches the value stored in the Address Compare Register and on all successive data bytes until an address mismatch occurs.
- 11 = The UART generates an interrupt request on all received data bytes for which the most recent address byte matched the value in the Address Compare Register.

MPEN—Multiprocessor (9-bit) Enable

This bit is used to enable Multiprocessor (9-bit) mode.

0 = Disable Multiprocessor (9-bit) mode.

1 = Enable Multiprocessor (9-bit) mode.

The Master and Slave are each capable of exchanging a character of data during a sequence of NUMBITS clock cycles (see NUMBITS field in the SPIMODE Register). In both Master and Slave SPI devices, data is shifted on one edge of the SCK and is sampled on the opposite edge where data is stable. Edge polarity is determined by the SPI phase and polarity control.

Slave Select

The active Low Slave Select (\overline{SS}) input signal selects a Slave SPI device. \overline{SS} must be Low prior to all data communication to and from the Slave device. \overline{SS} must stay Low for the full duration of each character transferred. The \overline{SS} signal can stay Low during the transfer of multiple characters or can deassert between each character.

When the SPI is configured as the only Master in an SPI system, the \overline{SS} pin is set as either an input or an output. For communication between the Z8 Encore! XP F0822 Series device's SPI Master and external Slave devices, the \overline{SS} signal, as an output, asserts the \overline{SS} input pin on one of the Slave devices. Other GPIO output pins can also be employed to select external SPI Slave devices.

When the SPI is configured as one Master in a multi-master SPI system, the \overline{SS} pin should be set as an input. The \overline{SS} input signal on the Master must be High. If the \overline{SS} signal goes Low (indicating another Master is driving the SPI bus), a Collision error flag is set in the SPI Status Register.

SPI Clock Phase and Polarity Control

The SPI supports four combinations of serial clock phase and polarity using two bits in the SPI Control Register. The clock polarity bit, CLKPOL, selects an active high or active low clock and has no effect on the transfer format. Table 62 lists the SPI Clock Phase and Polarity Operation parameters. The clock phase bit, PHASE, selects one of two fundamentally different transfer formats. For proper data transmission, the clock phase and polarity must be identical for the SPI Master and the SPI Slave. The Master always places data on the MOSI line a half-cycle before the receive clock edge (SCK signal), in order for the Slave to latch the data.

Table 62. SPI Clock Phase (PHASE) and Clock Polarity (CLKPOL) Operation

PHASE	CLKPOL	SCK Transmit Edge	SCK Receive Edge	SCK Idle State
0	0	Falling	Rising	Low
0	1	Rising	Falling	High
1	0	Rising	Falling	Low
1	1	Falling	Rising	High

RD—Read

This bit indicates the direction of transfer of the data. It is active High during a read. The status of this bit is determined by the least-significant bit of the I²C Shift register after the START bit is set.

TAS—Transmit Address State

This bit is active High while the address is being shifted out of the I²C Shift Register.

DSS—Data Shift State

This bit is active High while data is being shifted to or from the I²C Shift Register.

NCKI—NACK Interrupt

This bit is set high when a Not Acknowledge condition is received or sent and neither the START nor the STOP bit is active. When set, this bit generates an interrupt that can only be cleared by setting the START or STOP bit, allowing you to specify whether you want to perform a STOP or a repeated START.

I²C Control Register

The I²C Control Register (Table 72) enables the I²C operation.

Table 72. I²C Control Register (I2CCTL)

BITS	7	6	5	4	3	2	1	0			
FIELD	IEN	START	STOP	BIRQ	TXI	NAK	FLUSH	FILTEN			
RESET		0									
R/W	R/W	R/W R/W1 R/W1 R/W R/W1 W1 R/W									
ADDR				F5	2H						

IEN—I²C Enable

 $1 = \text{The } I^2C$ transmitter and receiver are enabled.

 $0 = \text{The I}^2\text{C}$ transmitter and receiver are disabled.

START—Send Start Condition

This bit sends the Start condition. Once asserted, it is cleared by the I²C Controller after it sends the START condition or if the IEN bit is deasserted. If this bit is 1, it cannot be cleared to 0 by writing to the register. After this bit is set, the Start condition is sent if there is data in the I²C Data or I²C Shift register. If there is no data in one of these registers, the I²C Controller waits until the data register is written. If this bit is set while the I²C Controller is shifting out data, it generates a START condition after the byte shifts and the acknowledge phase completes. If the STOP bit is also set, it also waits until the STOP condition is sent before sending the START condition.

STOP—Send Stop Condition

This bit causes the I²C Controller to issue a STOP condition after the byte in the I²C Shift register has completed transmission or after a byte is received in a receive operation. Once

PS022517-0508 I2C Controller

- 5. Re-write the page written in step 2 to the Page Select Register.
- 6. Write Flash Memory using LDC or LDCI instructions to program the Flash.
- 7. Repeat step 6 to program additional memory locations on the same page.
- 8. Write 00H to the Flash Control Register to lock the Flash Controller.

Page Erase

Flash memory can be erased one page (512 bytes) at a time. Page Erasing the Flash memory sets all bytes in that page to the value FFH. The Page Select Register identifies the page to be erased. While the Flash Controller executes the Page Erase operation, the eZ8 CPU idles but the system clock and on-chip peripherals continue to operate. The eZ8 CPU resumes operation after the Page Erase operation completes. Interrupts that occur when the Page Erase operation is in progress are serviced once the Page Erase operation is complete. When the Page Erase operation is complete, the Flash Controller returns to its locked state. Only pages located in unprotected sectors can be erased.

Follow the steps below to perform a Page Erase operation:

- 1. Write 00H to the Flash Control Register to reset the Flash Controller.
- 2. Write the page to be erased to the Page Select Register.
- 3. Write the first unlock command 73H to the Flash Control Register.
- 4. Write the second unlock command 8CH to the Flash Control Register.
- 5. Re-write the page written in step 2 to the Page Select Register.
- 6. Write the Page Erase command 95H to the Flash Control Register.

Mass Erase

The Flash memory cannot be Mass Erased by user code.

Flash Controller Bypass

The Flash Controller can be bypassed and the control signals for the Flash memory brought out to the GPIO pins. Bypassing the Flash Controller allows faster Programming algorithms by controlling the Flash programming signals directly.

Flash Controller Bypass is recommended for gang programming applications and large volume customers who do not require in-circuit programming of the Flash memory.

For more information on bypassing the Flash Controller, refer to *Third-Party Flash Programming Support for Z8 Encore! XP*, available for download at www.zilog.com.

PS022517-0508 Flash Memory

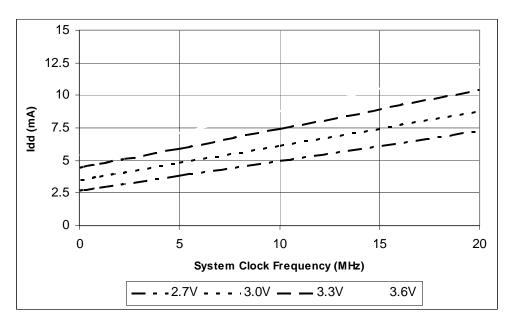


Figure 41. Typical Active Mode I_{DD} Versus System Clock Frequency

Figure 42 displays the maximum active mode current consumption across the full operating temperature range of the device and versus the system clock frequency. All GPIO pins are configured as outputs and driven High.

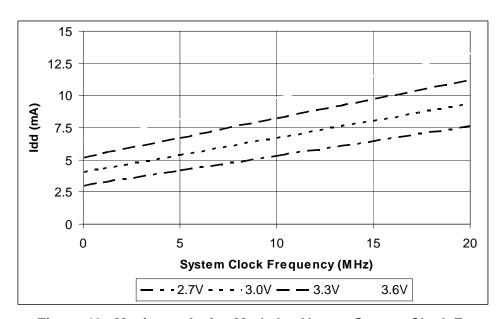


Figure 42. Maximum Active Mode I_{DD} Versus System Clock Frequency

PS022517-0508 Electrical Characteristics

SPI MASTER Mode Timing

Figure 51 and Table 108 provide timing information for SPI MASTER mode pins. Timing is shown with SCK rising edge used to source MOSI output data, SCK falling edge used to sample MISO input data. Timing on the SS output pin(s) is controlled by software.

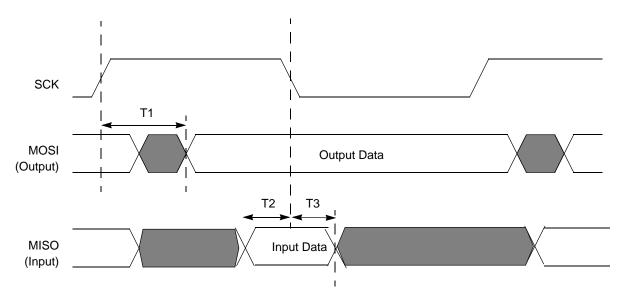


Figure 51. SPI MASTER Mode Timing

Table 108. SPI MASTER Mode Timing

		Delay (ns)					
Param	eter Abbreviation	Minimum	Maximum				
SPI MA	ASTER						
T ₁	SCK Rise to MOSI output Valid Delay	-5	+5				
T ₂	MISO input to SCK (receive edge) Setup Time	20					
T ₃	MISO input to SCK (receive edge) Hold Time	0					

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Table 126. eZ8 CPU Instruction Summary (Continued)

Assembly	Symbolic	Address Mode		_ Opcode(s)			Fla	ıgs		Fetch	Instr.	
Mnemonic	Operation	dst	src	(Hex)	С	Z	S	٧	D	Н	Cycles	
LD dst, rc	dst ← src	r	IM	0C-FC	-	-	-	-	-	-	2	2
		r	X(r)	C7	•						3	3
		X(r)	r	D7	•						3	4
		r	lr	E3	•						2	3
		R	R	E4	•						3	2
		R	IR	E5	•						3	4
		R	IM	E6	-						3	2
		IR	IM	E7	-						3	3
		lr	r	F3	-						2	3
		IR	R	F5	-						3	3
LDC dst, src	dst ← src	r	Irr	C2	-	-	-	-	-	-	2	5
		lr	Irr	C5	-						2	9
		Irr	r	D2	•						2	5
LDCI dst, src	dst ← src	lr	Irr	C3	-	-	-	-	-	-	2	9
	$r \leftarrow r + 1$ $rr \leftarrow rr + 1$	Irr	lr	D3	-						2	9
LDE dst, src	dst ← src	r	Irr	82	-	-	-	-	-	-	2	5
		Irr	r	92	•						2	5
LDEI dst, src	dst ← src	lr	Irr	83	-	-	-	-	-	-	2	9
	$r \leftarrow r + 1$ $rr \leftarrow rr + 1$	Irr	lr	93	-						2	9

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Ordering Information

Order Z8 Encore! XP F0822 Series from Zilog[®], using the following part numbers. For more information regarding ordering, consult your local Zilog sales office. Zilog website at www.zilog.com lists all regional offices and provides additional Z8 Encore! XP product information.

Description of the second of t	ւ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ Տ	W W W A M W	الالا الالالالالالالالالالالالالالالالا	interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	1 ² C	SPI	UARTs with IrDA	Description
Standard Temperature: 0	°C to 70	°C								
Z8F0821HH020SC	8 KB	1 KB	11	16	2	2	1	0	1	SSOP 20-pin package
Z8F0821PH020SC	8 KB	1 KB	11	16	2	2	1	0	1	PDIP 20-pin package
Z8F0822SJ020SC	8 KB	1 KB	19	19	2	5	1	1	1	SOIC 28-pin package
Z8F0822PJ020SC	8 KB	1 KB	19	19	2	5	1	1	1	PDIP 28-pin package
Extended Temperature: -40° to +105°C										
Z8F0821HH020EC	8 KB	1 KB	11	16	2	2	1	0	1	SSOP 20-pin package
Z8F0821PH020EC	8 KB	1 KB	11	16	2	2	1	0	1	PDIP 20-pin package
Z8F0822SJ020EC	8 KB	1 KB	19	19	2	5	1	1	1	SOIC 28-pin package
Z8F0822PJ020EC	8 KB	1 KB	19	19	2	5	1	1	1	PDIP 28-pin package

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Table 28F04xx with 4 KB Fla	Esp. 10-Bit	WY WA Analog	수 I/O Lines	Interrupts	20 16-Bit Timers w/PWM	at A/D Channels	-i- 	SPI	UARTs with IrDA	Description
Standard Temperature:	0 °C to 70	°C								
Z8F0421HH020SC	4 KB	1 KB	11	16	2	2	1	0	1	SSOP 20-pin package
Z8F0421PH020SC	4 KB	1 KB	11	16	2	2	1	0	1	PDIP 20-pin package
Z8F0422SJ020SC	4 KB	1 KB	19	19	2	5	1	1	1	SOIC 28-pin package
Z8F0422PJ020SC	4 KB	1 KB	19	19	2	5	1	1	1	PDIP 28-pin package
Extended Temperature: -40 °C to 105 °C										
Z8F0421HH020EC	4 KB	1 KB	11	16	2	2	1	0	1	SSOP 20-pin package
Z8F0421PH020EC	4 KB	1 KB	11	16	2	2	1	0	1	PDIP 20-pin package
Z8F0422SJ020EC	4 KB	1 KB	19	19	2	5	1	1	1	SOIC 28-pin package
Z8F0422PJ020EC	4 KB	1 KB	19	19	2	5	1	1	1	PDIP 28-pin package

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