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What is "Embedded - Microcontrollers"?

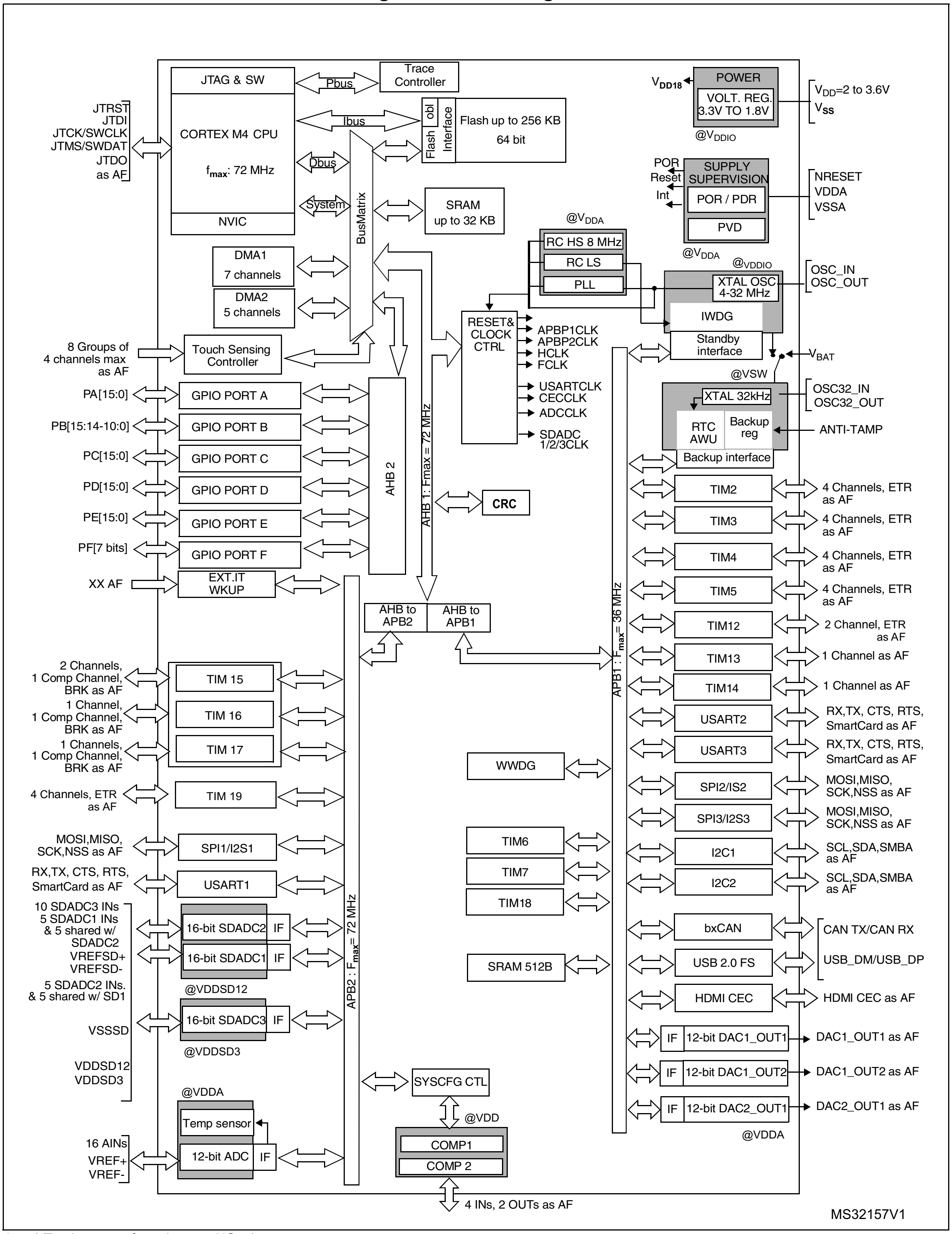
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, I²C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	DMA, I²S, POR, PWM, WDT
Number of I/O	36
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 1x12b, 3x16b; D/A 3x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f373cbt6

Contents

Figure 1. Block diagram



1. AF: alternate function on I/O pins.

3.13 16-bit sigma delta analog-to-digital converters (SDADC)

Three 16-bit sigma-delta analog-to-digital converters are embedded in the STM32F373xx. They have up to two separate supply voltages allowing the analog function voltage range to be independent from the STM32F373xx power supply. They share up to 21 input pins which may be configured in any combination of single-ended (up to 21) or differential inputs (up to 11).

The conversion speed is up to 16.6 ksps for each SDADC when converting multiple channels and up to 50 ksps per SDADC if single channel conversion is used. There are two conversion modes: single conversion mode or continuous mode, capable of automatically scanning any number of channels. The data can be automatically stored in a system RAM buffer, reducing the software overhead.

A timer triggering system can be used in order to control the start of conversion of the three SDADCs and/or the 12-bit fast ADC. This timing control is very flexible, capable of triggering simultaneous conversions or inserting a programmable delay between the ADCs.

Up to two external reference pins (VREFSD+, VREFSD-) and an internal 1.2/1.8 V reference can be used in conjunction with a programmable gain (x0.5 to x32) in order to fine-tune the input voltage range of the SDADC. VREFSD - pin is used as negative signal reference in case of single-ended input mode.

3.14 Digital-to-analog converter (DAC)

The devices feature two 12-bit buffered DACs with three output channels that can be used to convert three digital signals into three analog voltage signal outputs. The internal structure is composed of integrated resistor strings and an amplifier in inverting configuration.

This digital Interface supports the following features:

- Two DAC converters with three output channels:
  - DAC1 with two output channels
  - DAC2 with one output channel.
- 8-bit or 10-bit monotonic output
- Left or right data alignment in 12-bit mode
- Synchronized update capability
- Noise-wave generation (DAC1 only)
- Triangular wave generation (DAC1 only)
- Dual DAC channel independent or simultaneous conversions (DAC1 only)
- DMA capability for each channel
- External triggers for conversion

3.15 Fast comparators (COMP)

The STM32F373xx embeds 2 comparators with rail-to-rail inputs and high-speed output. The reference voltage can be internal or external (delivered by an I/O).

The threshold can be one of the following:

- DACs channel outputs
- External I/O
- Internal reference voltage (V_{REFINT}) or submultiple (1/4 V_{REFINT}, 1/2 V_{REFINT} and 3/4 V_{REFINT})

The comparators can be combined into a window comparator.

Both comparators can wake up the device from Stop mode and generate interrupts and breaks for the timers.

3.16 Touch sensing controller (TSC)

The devices provide a simple solution for adding capacitive sensing functionality to any application. Capacitive sensing technology is able to detect the presence of a finger near an electrode which is protected from direct touch by a dielectric (glass, plastic, ...). The capacitive variation introduced by the finger (or any conductive object) is measured using a proven implementation based on a surface charge transfer acquisition principle. It consists of charging the electrode capacitance and then transferring a part of the accumulated charges into a sampling capacitor until the voltage across this capacitor has reached a specific threshold. To limit the CPU bandwidth usage this acquisition is directly managed by the hardware touch sensing controller and only requires few external components to operate.

The touch sensing controller is fully supported by the STMTouch touch sensing firmware library, which is free to use and allows touch sensing functionality to be implemented reliably in the end application.

Up to 24 touch sensing electrodes can be controlled by the TSC. The touch sensing I/Os are organized in 8 acquisition groups, with up to 4 I/Os in each group.

Table 3. Capacitive sensing GPIOs available on STM32F373xx devices

Group	Capacitive sensing signal name	Pin name	Group	Capacitive sensing signal name	Pin name
1	TSC_G1_IO1	PA0	5	TSC_G5_IO1	PB3
	TSC_G1_IO2	PA1		TSC_G5_IO2	PB4
	TSC_G1_IO3	PA2		TSC_G5_IO3	PB6
	TSC_G1_IO4	PA3		TSC_G5_IO4	PB7
2	TSC_G2_IO1	PA4(1)	6	TSC_G6_IO1	PB14
	TSC_G2_IO2	PA5(1)		TSC_G6_IO2	PB15
	TSC_G2_IO3	PA6(1)		TSC_G6_IO3	PD8
	TSC_G2_IO4	PA7		TSC_G6_IO4	PD9

3.17.3 Independent watchdog (IWDG)

The independent watchdog is based on a 12-bit downcounter and 8-bit prescaler. It is clocked from an independent 40 kHz internal RC and as it operates independently from the main clock, it can operate in Stop and Standby modes. It can be used either as a watchdog to reset the device when a problem occurs, or as a free running timer for application timeout management. It is hardware or software configurable through the option bytes. The counter can be frozen in debug mode.

3.17.4 System window watchdog (WWDG)

The system window watchdog is based on a 7-bit downcounter that can be set as free running. It can be used as a watchdog to reset the device when a problem occurs. It is clocked from the APB1 clock (PCLK1) derived from the main clock. It has an early warning interrupt capability and the counter can be frozen in debug mode.

3.17.5 SysTick timer

This timer is dedicated to real-time operating systems, but could also be used as a standard down counter. It features:

- A 24-bit down counter
- Autoreload capability
- Maskable system interrupt generation when the counter reaches 0
- Programmable clock source

3.18 Real-time clock (RTC) and backup registers

The RTC and the backup registers are supplied through a switch that takes power either from V_{DD} supply when present or through the V_{BAT} pin. The backup registers are thirty two 32-bit registers used to store 128 bytes of user application data.

They are not reset by a system or power reset, and they are not reset when the device wakes up from the Standby mode.

The RTC is an independent BCD timer/counter. Its main features are the following:

- Calendar with subsecond, seconds, minutes, hours (12 or 24 format), week day, date, month, year, in BCD (binary-coded decimal) format.
- Automatic correction for 28th, 29th (leap year), 30th and 31st day of the month.
- 2 programmable alarms with wake up from Stop and Standby mode capability.
- Periodic wakeup unit with programmable resolution and period.
- On-the-fly correction from 1 to 32767 RTC clock pulses. This can be used to synchronize it with a master clock.
- Digital calibration circuit with 1 ppm resolution, to compensate for quartz crystal inaccuracy.
- 3 anti-tamper detection pins with programmable filter. The MCU can be woken up from Stop and Standby modes on tamper event detection.
- Timestamp feature which can be used to save the calendar content. This function can triggered by an event on the timestamp pin, or by a tamper event. The MCU can be woken up from Stop and Standby modes on timestamp event detection.

Table 7. STM32F373xx I^2C implementation (continued)

I^2C features[(1)]	I2C1	I2C2
SMBus	X	X
Wakeup from STOP	X	X

1. X = supported.

3.20 Universal synchronous/asynchronous receiver transmitter (USART)

The STM32F373xx embeds three universal synchronous/asynchronous receiver transmitters (USART1, USART2 and USART3).

All USARTs interfaces are able to communicate at speeds of up to 9 Mbit/s.

They provide hardware management of the CTS and RTS signals, they support IrDA SIR ENDEC, the multiprocessor communication mode, the single-wire half-duplex communication mode, Smartcard mode (ISO/IEC 7816 compliant), autobaudrate feature and have LIN Master/Slave capability. The USART interfaces can be served by the DMA controller.

Refer to *Table 8* for the features of USART1, USART2 and USART3.

Table 8. STM32F373xx USART implementation

USART modes/features[(1)]	USART1	USART2	USART3
Hardware flow control for modem	X	X	X
Continuous communication using DMA	X	X	X
Multiprocessor communication	X	X	X
Synchronous mode	X	X	X
Smartcard mode	X	X	X
Single-wire half-duplex communication	X	X	X
IrDA SIR ENDEC block	X	X	X
LIN mode	X	X	X
Dual clock domain and wakeup from Stop mode	X	X	X
Receiver timeout interrupt	X	X	X
Modbus communication	X	X	X
Auto baud rate detection	X	X	X
Driver Enable	X	X	X

1. X = supported.

Table 10. Legend/abbreviations used in the pinout table

Name		Abbreviation	Definition
Pin name		Unless otherwise specified in brackets below the pin name, the pin function during and after reset is the same as the actual pin name	
Pin type		S	Supply pin
		I	Input only pin
		I/O	Input / output pin
I/O structure		FT	5 V tolerant I/O
		FTf	5 V tolerant I/O, FM+ capable
		TTa	3.3 V tolerant I/O directly connected to ADC
		TC	Standard 3.3 V I/O
		B	Dedicated BOOT0 pin
		RST	Bidirectional reset pin with embedded weak pull-up resistor
Notes		Unless otherwise specified by a note, all I/Os are set as floating inputs during and after reset	
Pin functions	Alternate functions	Functions selected through GPIOx_AFR registers	
	Additional functions	Functions directly selected/enabled through peripheral registers	

Table 11. STM32F373xx pin definitions

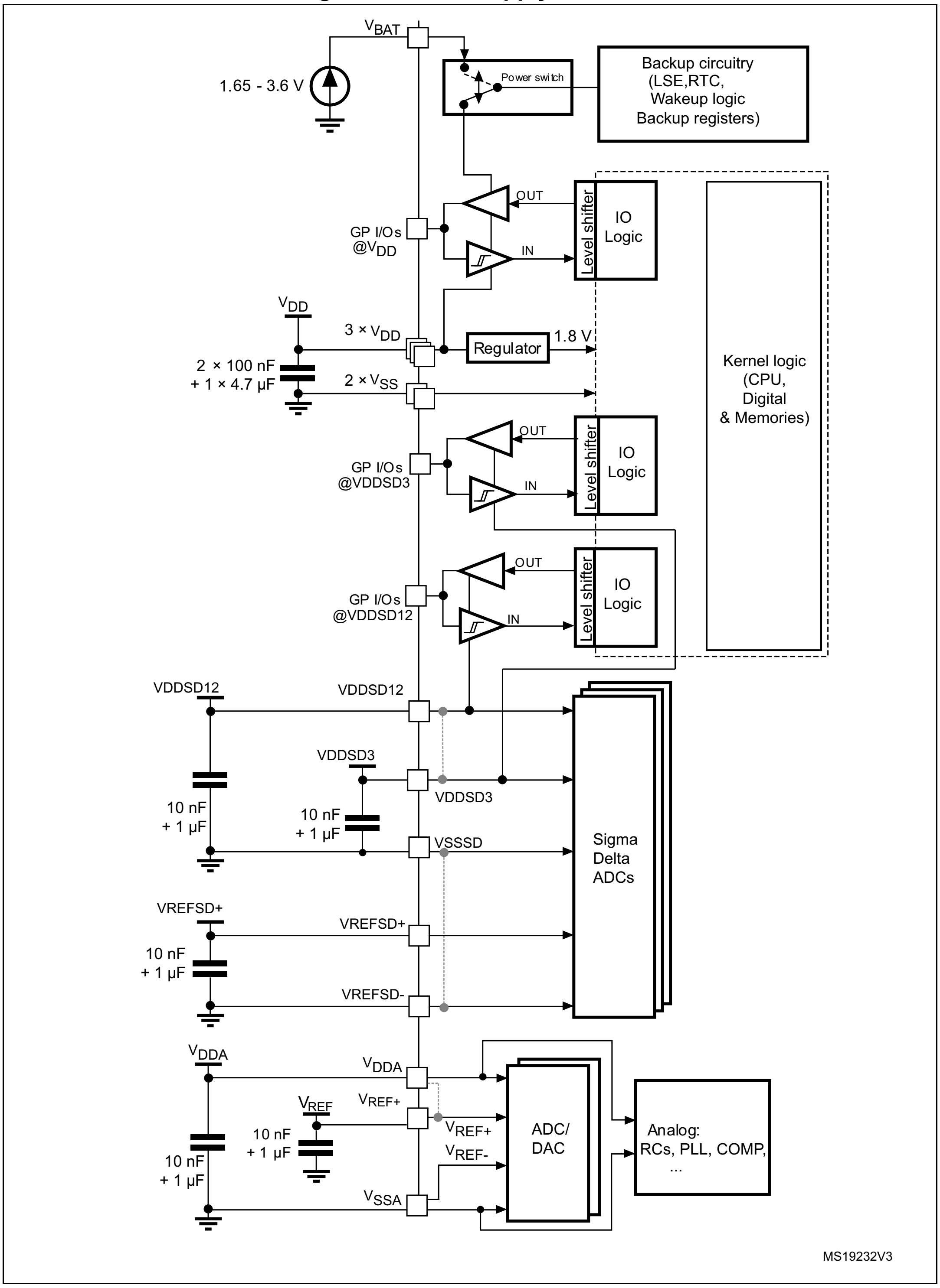
Pin numbers				Pin name (function after reset)	Pin type	I/O structure	Notes	Pin functions	
LQFP100	UFBGA100	LQFP64	LQFP48					Alternate function	Additional functions
1	B2	-	-	PE2	I/O	FT	(2)	TSC_G7_IO1, TRACECLK	-
2	A1	-	-	PE3	I/O	FT	(2)	TSC_G7_IO2, TRACED0	-
3	B1	-	-	PE4	I/O	FT	(2)	TSC_G7_IO3, TRACED1	-
4	C2	-	-	PE5	I/O	FT	(2)	TSC_G7_IO4, TRACED2	-
5	D2	-	-	PE6	I/O	FT	(2)	TRACED3	WKUP3, RTC_TAMPER3
6	E2	1	1	VBAT	S	-	-	Backup power supply	
7	C1	2	2	PC13(1)	I/O	TC	-	-	WKUP2, ALARM_OUT, CALIB_OUT, TIMESTAMP, RTC_TAMPER1

Table 11. STM32F373xx pin definitions (continued)

Pin numbers				Pin name (function after reset)	Pin type	I/O structure	Notes	Pin functions	
LQFP100	UFBGA100	LQFP64	LQFP48					Alternate function	Additional functions
38	M7	-	-	PE7	I/O	TC	(3) (2)	-	SDADC1_AIN3P, SDADC1_AIN4M, SDADC2_AIN5P, SDADC2_AIN6M
39	L7	29	21	PE8	I/O	TC	(3)	-	SDADC1_AIN8P, SDADC2_AIN8P
40	M8	30	22	PE9	I/O	TC	(3)	-	SDADC1_AIN7P, SDADC1_AIN8M, SDADC2_AIN7P, SDADC2_AIN8M
41	L8	-	-	PE10	I/O	TC	(3) (2)	-	SDADC1_AIN2P
42	M9	-	-	PE11	I/O	TC	(3) (2)	-	SDADC1_AIN1P, SDADC1_AIN2M, SDADC2_AIN4P
43	L9	-	-	PE12	I/O	TC	(3) (2)	-	SDADC1_AIN0P, SDADC2_AIN3P, SDADC2_AIN4M
44	M10	-	-	PE13	I/O	TC	(3) (2)	-	SDADC1_AIN0M , SDADC2_AIN2P
45	M11	-	-	PE14	I/O	TC	(3) (2)	-	SDADC2_AIN1P, SDADC2_AIN2M
46	M12	-	-	PE15	I/O	TC	(3) (2)	USART3_RX	SDADC2_AIN0P
47	L10	-	-	PB10	I/O	TC	(3) (2)	SPI2_SCK/I2S2_CK, USART3_TX, CEC, TSC_SYNC, TIM2_CH3	SDADC2_AIN0M
48	L11	-	-	VREFSD-	S	-	(2)	External reference voltage for SDADC1, SDADC2, SDADC3 (negative input), negative SDADC analog input in SDADC single ended mode	
49	F12	-	-	VSSSD	S	-	(2)	SDADC1, SDADC2, SDADC3 ground	
-	-	31	23	VSSSD/ VREFSD-	S	-	-	SDADC1, SDADC2, SDADC3 ground / External reference voltage for SDADC1, SDADC2, SDADC3 (negative input), negative SDADC analog input in SDADC single ended mode	
50	G12	-	-	VDDSD12	S	-	(2)	SDADC1 and SDADC2 power supply	
-	-	32	24	VDDSD	S	-	-	SDADC1, SDADC2, SDADC3 power supply	

6.1.6 Power supply scheme

Figure 9. Power supply scheme



1. Dotted lines represent the internal connections on low pin count packages, joining the dedicated supply pins.

6.3.5 Supply current characteristics

The current consumption is a function of several parameters and factors such as the operating voltage, ambient temperature, I/O pin loading, device software configuration, operating frequencies, I/O pin switching rate, program location in memory and executed binary code.
The current consumption is measured as described in *Figure 10: Current consumption measurement scheme*.
All Run-mode current consumption measurements given in this section are performed with a reduced code that gives a consumption equivalent to CoreMark code.

Typical and maximum current consumption

The MCU is placed under the following conditions:

- All I/O pins are in input mode with a static value at V_{DD} or V_{SS} (no load)
- All peripherals are disabled except when explicitly mentioned
- The Flash memory access time is adjusted to the f_{HCLK} frequency (0 wait state from 0 to 24 MHz, 1 wait state from 24 to 48 MHz and 2 wait states from 48 MHz to 72 MHz)
- Prefetch in ON (reminder: this bit must be set before clock setting and bus prescaling)
- When the peripherals are enabled $f_{APB1} = f_{AHB}/2$, $f_{APB2} = f_{AHB}$
- When f_{HCLK} > 8 MHz PLL is ON and PLL inputs is equal to HSI/2 = 4 MHz (if internal clock is used) or HSE = 8 MHz (if HSE bypass mode is used)

The parameters given in *Table 28* to *Table 34* are derived from tests performed under ambient temperature and supply voltage conditions summarized in *Table 22*.

Table 28. Typical and maximum current consumption from V_{DD} supply at V_{DD} = 3.6 V(1)

Symbol	Parameter	Conditions	f_{HCLK}	All peripherals enabled				All peripherals disabled				Unit
				Typ	Max @ T_A (2)			Typ	Max @ T_A (2)			
					25 °C	85 °C	105 °C		25 °C	85 °C	105 °C	
I_{DD}	Supply current in Run mode, code executing from Flash	HSE bypass, PLL on	72 MHz	63.1	70.7	71.5	73.4	29.2	31.1	31.7	34.2	mA
			64 MHz	56.3	63.3	64.1	64.9	26.1	27.8	28.4	30.4	
			48 MHz	42.5	48.5	48.0	50.1	19.9	22.6	21.9	23.1	
			32 MHz	28.8	31.4	32.2	34.3	13.1	16.1	14.9	16.2	
			24 MHz	21.9	24.4	24.4	25.8	10.1	10.9	11.9	12.4	
		HSE bypass, PLL off	8 MHz	7.3	8.0	9.3	9.3	3.7	4.1	4.4	5.0	
			1 MHz	1.1	1.5	1.8	2.3	0.8	1.1	1.4	1.9	
		HSI clock, PLL on	64 MHz	51.7	57.7	58.0	60.4	25.8	27.6	28.1	30.1	
			48 MHz	38.6	45.9	43.5	46.9	19.8	21.9	21.7	22.8	
			32 MHz	26.4	31.1	29.7	31.9	13.1	15.7	14.8	16.2	
			24 MHz	20.3	22.6	22.6	23.7	6.9	7.5	8.1	8.8	
		HSI clock, PLL off	8 MHz	7.0	7.6	8.8	8.8	3.7	4.1	4.4	5.0	

Table 31. Typical and maximum V_{DDA} consumption in Stop and Standby modes

Symbol	Parameter	Conditions		Typ@V_{DD} (V_{DD}=V_{DDA})						Max(1)			Unit
				2.0 V	2.4 V	2.7 V	3.0 V	3.3 V	3.6 V	T_A= 25 °C	T_A= 85 °C	T_A= 105 °C	
I_{DDA}	Supply current in Stop mode	V_{DDA} and V_{DDSD12}	Regulator in run mode, all oscillators OFF	1.99	2.07	2.19	2.33	2.46	2.64	10.8	11.8	12.4	µA
			Regulator in low-power mode, all oscillators OFF	1.99	2.07	2.18	2.32	2.47	2.63	10.6	11.5	12.5	
	Supply current in Standby mode		LSI ON and IWDG ON	2.44	2.53	2.7	2.89	3.09	3.33	-	-	-	
			LSI OFF and IWDG OFF	1.87	1.94	2.06	2.19	2.35	2.51	4.1	4.5	4.8	
IDDAmon	Supply current for V_{DDA} and V_{DDSD12} monitoring	-		0.95	1.02	1.12	1.2	1.27	1.4	-	-	-	

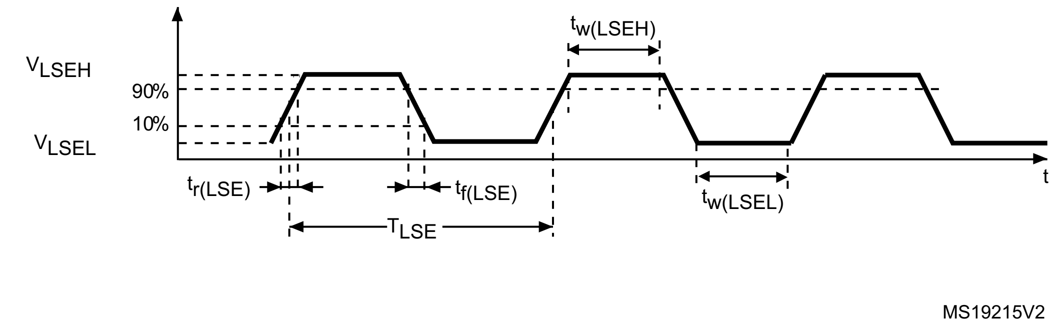
1. Data based on characterization results and tested in production.
2. To obtain data with monitoring OFF is necessary to substract the IDDAmon current.

Table 32. Typical and maximum current consumption from V_{BAT} supply(1)

Symbol	Parameter	Conditions	Typ @ V_{BAT}							Max(2)			Unit
			= 1.65 V	= 1.8 V	= 2.0 V	= 2.4 V	= 2.7 V	= 3.3 V	= 3.6 V	T_A= 25 °C	T_A= 85 °C	T_A= 105 °C	
I_{DD_VBAT}	Backup domain supply current	LSE & RTC ON; "Xtal mode" lower driving capability; LSEDRV[1:0] = '00'	0.50	0.52	0.55	0.63	0.70	0.87	0.95	1.1	1.6	2.2	µA
		LSE & RTC ON; "Xtal mode" higher driving capability; LSEDRV[1:0] = '11'	0.85	0.90	0.93	1.02	1.10	1.27	1.38	1.6	2.4	3.0	

1. Crystal used: Abracon ABS07-120-32.768kHz-T with 6 pF of CL for typical values.
2. Guaranteed by characterization results.

Figure 13. Low-speed external clock source AC timing diagram



High-speed external clock generated from a crystal/ceramic resonator

The high-speed external (HSE) clock can be supplied with a 4 to 32 MHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on design simulation results obtained with typical external components specified in *Table 40*. In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Table 40. HSE oscillator characteristics

Symbol	Parameter	Conditions(1)	Min(2)	Typ	Max(2)	Unit
f_{OSC_IN}	Oscillator frequency	-	4	8	32	MHz
R_F	Feedback resistor	-	-	200	-	kΩ
I_{DD}	HSE current consumption	During startup(3)	-	-	8.5	mA
		V_{DD} = 3.3 V, Rm= 30 Ω, CL= 10 pF@8 MHz	-	0.4	-	
		V_{DD} = 3.3 V, Rm= 45 Ω, CL= 10 pF@8 MHz	-	0.5	-	
		V_{DD} = 3.3 V, Rm= 30 Ω, CL=5 pF@32 MHz	-	0.8	-	
		V_{DD} = 3.3 V, Rm= 30 Ω, CL= 10 pF@32 MHz	-	1	-	
		V_{DD} = 3.3 V, Rm= 30 Ω, CL= 20 pF@32 MHz	-	1.5	-	
g_m	Oscillator transconductance	Startup	10	-	-	mA/V
$t_{SU(HSE)}$(4)	Startup time	V_{DD} is stabilized	-	2	-	ms

1. Resonator characteristics given by the crystal/ceramic resonator manufacturer.
2. Guaranteed by design.
3. This consumption level occurs during the first 2/3 of the $t_{SU(HSE)}$ startup time
4. $t_{SU(HSE)}$ is the startup time measured from the moment it is enabled (by software) to a stabilized 8 MHz oscillation is reached. This value is measured for a standard crystal resonator and it can vary significantly with the crystal manufacturer

Low-speed external clock generated from a crystal resonator

The low-speed external (LSE) clock can be supplied with a 32.768 kHz crystal resonator oscillator. All the information given in this paragraph are based on design simulation results obtained with typical external components specified in *Table 41*. In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

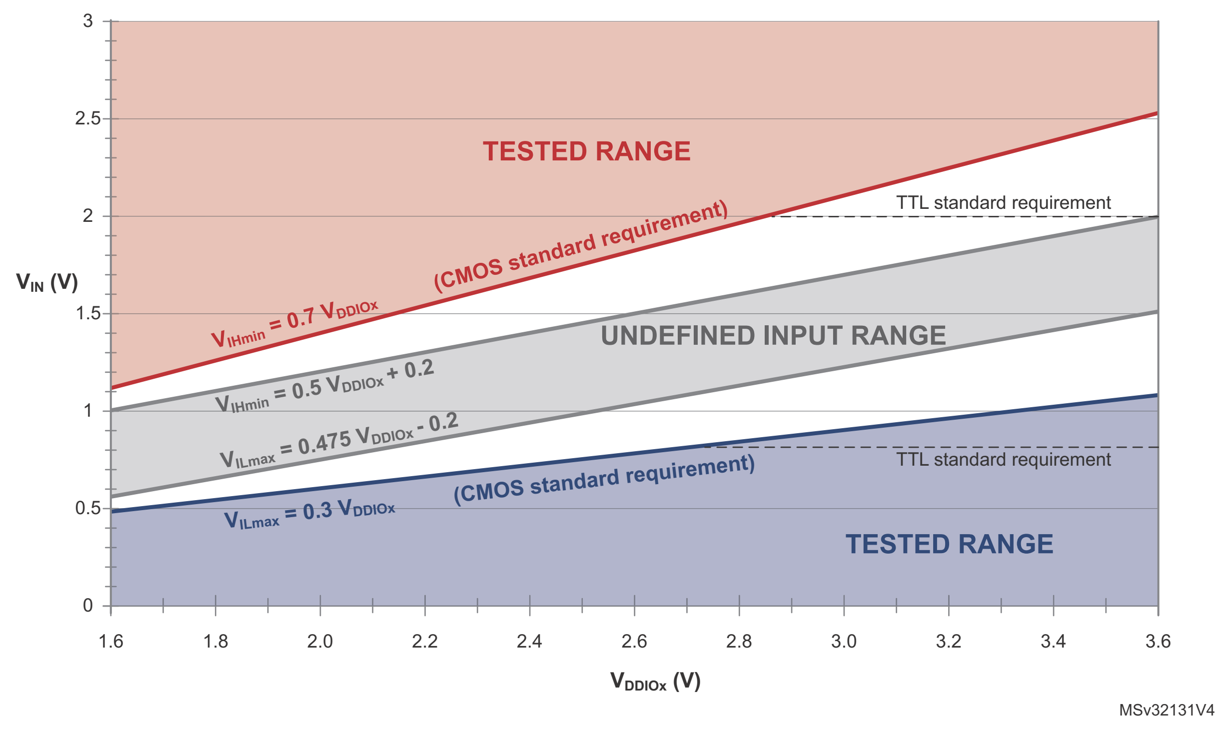
Table 41. LSE oscillator characteristics (f_{LSE} = 32.768 kHz)

Symbol	Parameter	Conditions(1)	Min(2)	Typ	Max(2)	Unit
I_{DD}	LSE current consumption	LSEDRV[1:0]=00 lower driving capability	-	0.5	0.9	µA
		LSEDRV[1:0]= 10 medium low driving capability	-	-	1	
		LSEDRV[1:0] = 01 medium high driving capability	-	-	1.3	
		LSEDRV[1:0]=11 higher driving capability	-	-	1.6	
g_m	Oscillator transconductance	LSEDRV[1:0]=00 lower driving capability	5	-	-	µA/V
		LSEDRV[1:0]= 10 medium low driving capability	8	-	-	
		LSEDRV[1:0] = 01 medium high driving capability	15	-	-	
		LSEDRV[1:0]=11 higher driving capability	25	-	-	
$t_{SU(LSE)}$(3)	Startup time	V_{DD} is stabilized	-	2	-	s

1. Refer to the note and caution paragraphs below the table, and to the application note AN2867 “Oscillator design guide for ST microcontrollers”.
2. Guaranteed by design.
3. $t_{SU(LSE)}$ is the startup time measured from the moment it is enabled (by software) to a stabilized 32.768 kHz oscillation is reached. This value is measured for a standard crystal and it can vary significantly with the crystal manufacturer

Note: For information on selecting the crystal, refer to the application note AN2867 “Oscillator design guide for ST microcontrollers” available from the ST website www.st.com.

Figure 18. Five volt tolerant (FT and FTf) I/O input characteristics - CMOS port



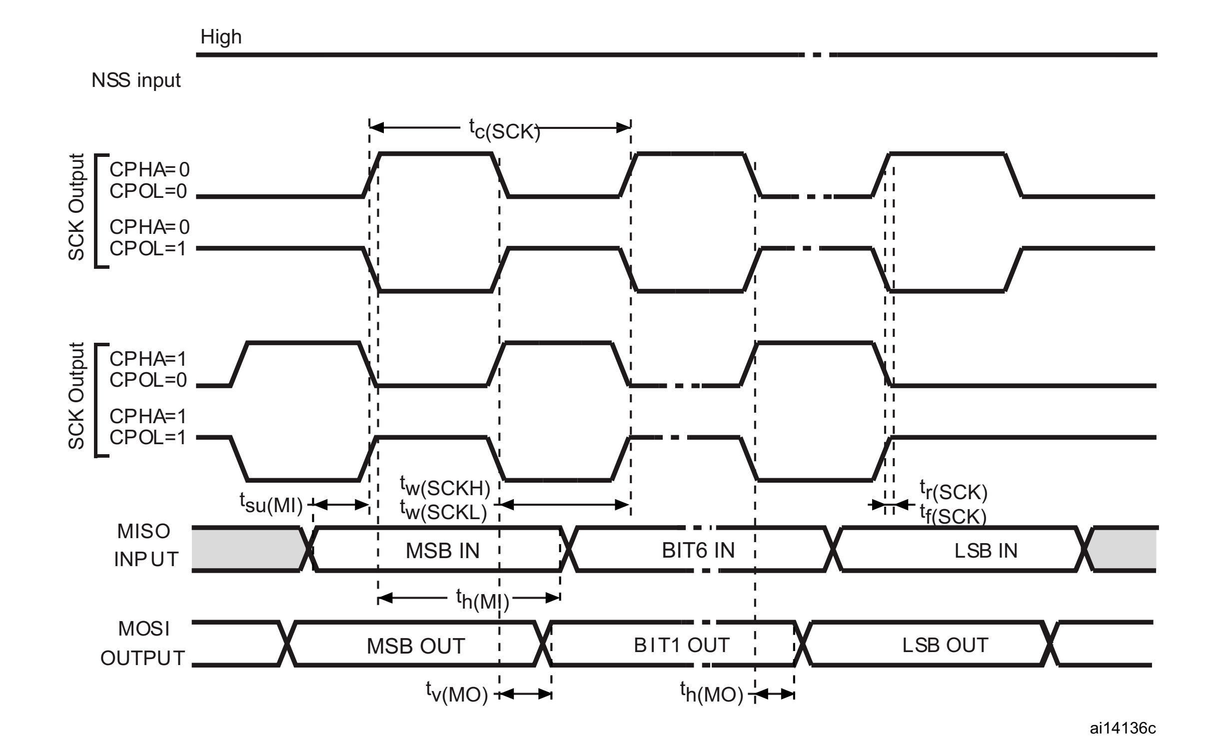
Output driving current

The GPIOs (general purpose input/outputs) can sink or source up to ± 8 mA, and sink or source up to ± 20 mA (with a relaxed V_{OL}/V_{OH}).

In the user application, the number of I/O pins which can drive current must be limited to respect the absolute maximum rating specified in *Section 6.2*:

- The sum of the currents sourced by all the I/Os on all VDD_x and VDDSDx, plus the maximum Run consumption of the MCU sourced on V_{DD} cannot exceed the absolute maximum rating ΣI_{VDD} (see *Table 20*).
- The sum of the currents sunk by all the I/Os on all VSS_x and VSSSD, plus the maximum Run consumption of the MCU sunk on V_{SS} cannot exceed the absolute maximum rating ΣI_{VSS} (see *Table 20*).

Figure 24. SPI timing diagram - master mode(1)



1. Measurement points are done at $0.5V_{DD}$ level and with external C_L = 30 pF.

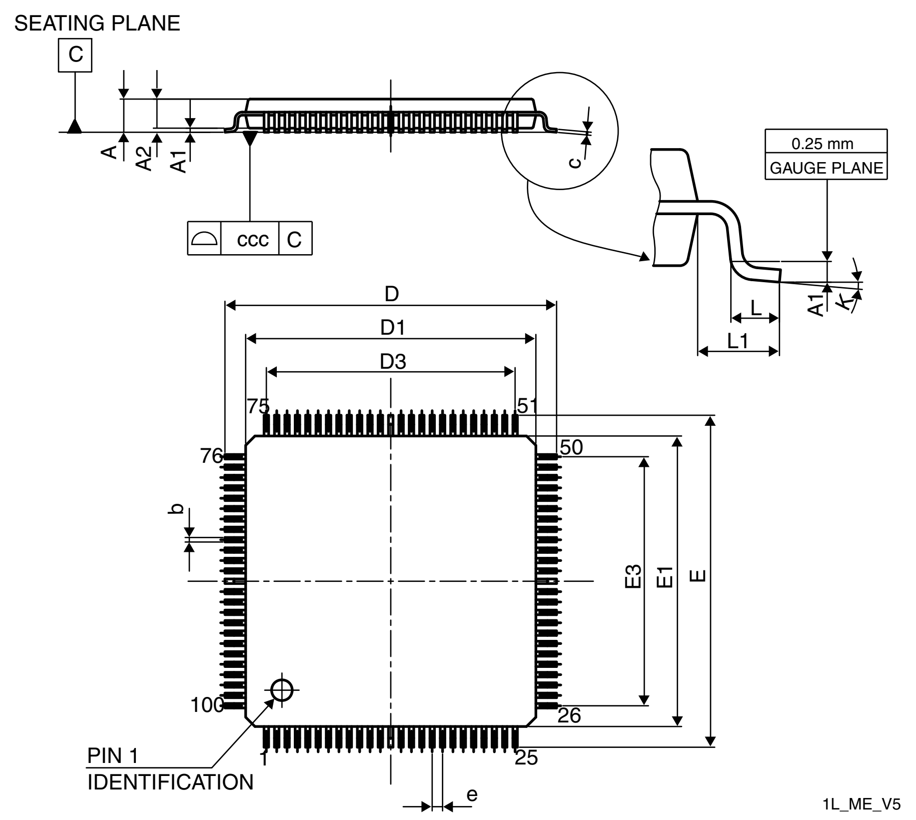
6.3.19 Comparator characteristics

Table 64. Comparator characteristics

Symbol	Parameter	Conditions		Min	Typ	Max[1]	Unit
V_{DDA}	Analog supply voltage	-		2	-	3.6	V
V_{IN}	Comparator input voltage range	-		0	-	V_{DDA}	V
V_{BG}	V_{REFINT} scaler input voltage	-		-	1.2	-	V
V_{SC}	V_{REFINT} scaler offset voltage	-		-	±5	±10	mV
t_{S_SC}	Scaler startup time from power down	First V_{REFINT} scaler activation after device power on		-	-	1000[2]	ms
		Next activations				0.2	
t_{START}	Comparator startup time	Startup time to reach propagation delay specification		-	-	60	µs
t_D	Propagation delay for 200 mV step with 100 mV overdrive	Ultra-low power mode		-	2	4.5	µs
		Low power mode		-	0.7	1.5	
		Medium power mode		-	0.3	0.6	
		High speed mode	$V_{DDA} \geq 2.7$ V	-	50	100	ns
			$V_{DDA} < 2.7$ V	-	100	240	
	Propagation delay for full range step with 100 mV overdrive	Ultra-low power mode		-	2	7	µs
		Low power mode		-	0.7	2.1	
		Medium power mode		-	0.3	1.2	
		High speed mode	$V_{DDA} \geq 2.7$ V	-	90	180	ns
			$V_{DDA} < 2.7$ V	-	110	300	
V_{offset}	Comparator offset error	-		-	±4	±10	mV
dV_{offset}/dT	Offset error temperature coefficient	-		-	18	-	µV/°C
$I_{DD(COMP)}$	COMP current consumption	Ultra-low power mode		-	1.2	1.5	µA
		Low power mode		-	3	5	
		Medium power mode		-	10	15	
		High speed mode		-	75	100	

7.2 LQFP100 package information

Figure 35. LQFP100 - 100-pin, 14 x 14 mm low-profile quad flat package outline



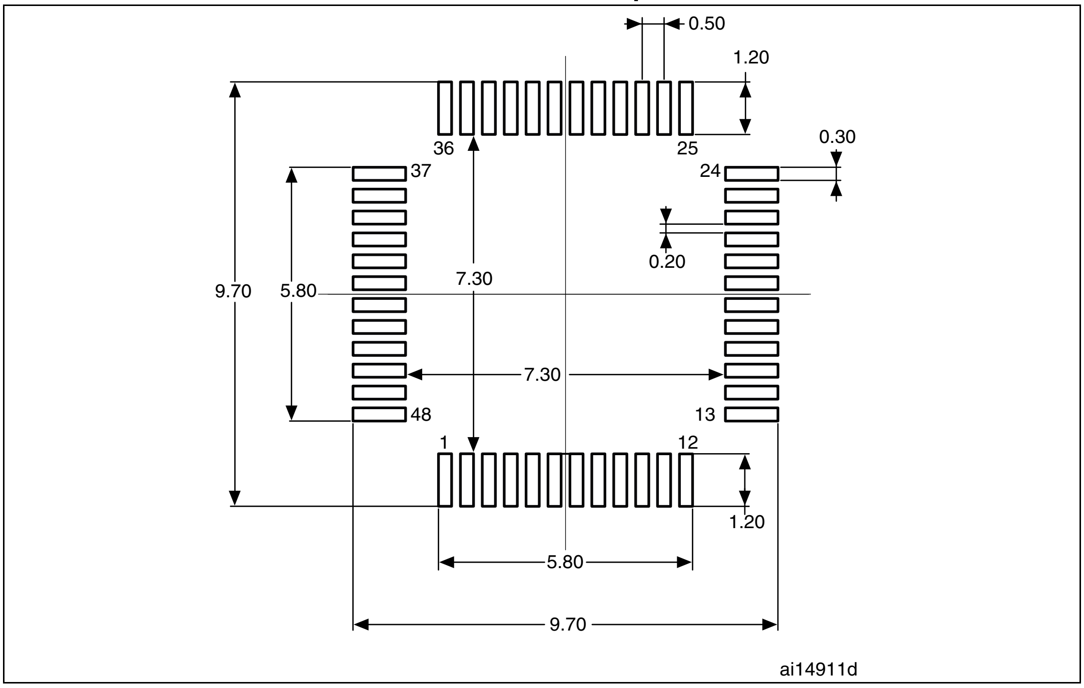
1. Drawing is not to scale.

Table 78. LQPF100 - 100-pin, 14 x 14 mm low-profile quad flat package mechanical data

Symbol	millimeters			inches(1)		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	-	0.200	0.0035	-	0.0079
D	15.800	16.000	16.200	0.6220	0.6299	0.6378
D1	13.800	14.000	14.200	0.5433	0.5512	0.5591
D3	-	12.000	-	-	0.4724	-
E	15.800	16.000	16.200	0.6220	0.6299	0.6378
E1	13.800	14.000	14.200	0.5433	0.5512	0.5591
E3	-	12.000	-	-	0.4724	-
e	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0.0°	3.5°	7.0°	0.0°	3.5°	7.0°
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 42. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package recommended footprint

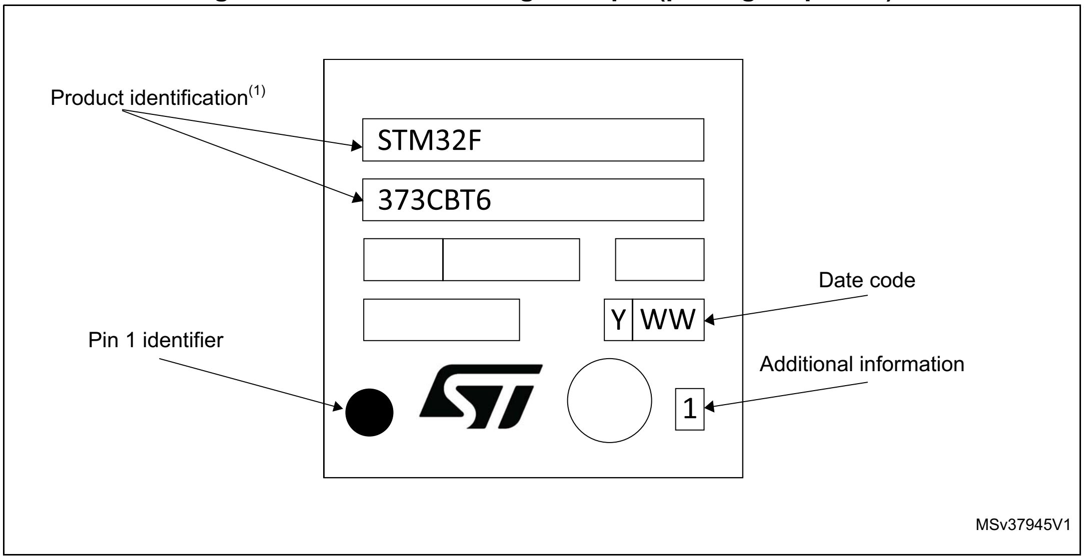


1. Dimensions are expressed in millimeters.

Device marking for LQFP48

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Figure 43. LQFP48 marking example (package top view)



1. Samples marked “ES” are to be considered as “Engineering Samples”: i.e. they are intended to be sent to customer for electrical compatibility evaluation and may be used to start customer qualification where specifically authorized by ST in writing. In no event ST will be liable for any customer usage in production. Only if ST has authorized in writing the customer qualification Engineering Samples can be used for reliability qualification trials.

Table 83. Document revision history (continued)

Date	Revision	Changes
18-Mar-2014	5	Renamed part number STM32F37x to STM32F373xx Added note1 in *Table 28: Typical and maximum current consumption from VDD supply at VDD = 3.6 V* Updated *Chapter 3.14: Digital-to-analog converter (DAC)* Updated, added note 2 and 3 in *Table 57: I2C analog filter characteristics* Renamed t_{SP} symbol with $t_{AF.}$ Added note for EG Symbol in *Table 74: SDADC characteristics* Added all packages top view
21-Jul-2015	6	Updated *Section 7* Updated *Section 3.13* Updated *Section 3.7.1*, *Section 3.7.4* Updated *Table 11: STM32F373xx pin definitions*, *Table 19: Voltage characteristics*, *Table 49: ESD absolute maximum ratings*, *Table 74: SDADC characteristics*, *Table 76: UFBGA100 - 100-pin, 7 x 7 mm, 0.50 mm pitch, ultra fine pitch ball grid array package mechanical data*, and *Table 78: LQPF100 - 100-pin, 14 x 14 mm low-profile quad flat package mechanical data* Updated *Figure 2: STM32F373xx LQFP48 pinout*, *Figure 9: Power supply scheme*, *Figure 32: UFBGA100 - 100-pin, 7 x 7 mm, 0.50 mm pitch, ultra fine pitch ball grid array package outline*, *Figure 34: UFBGA100 marking example (package top view)*, *Figure 36: LQFP100 - 100-pin, 14 x 14 mm low-profile quad flat recommended footprint*, *Figure 37: LQFP100 marking example (package top view)*, *Figure 38: LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package outline*, *Figure 39: LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package recommended footprint*, *Figure 40: LQFP64 marking example (package top view)*, *Figure 42: LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package recommended footprint*, *Figure 43: LQFP48 marking example (package top view)*. Added *Table 32: Typical and maximum current consumption from VBAT supply*, *Table 49: ESD absolute maximum ratings*, *Table 64: Comparator characteristics*, *Table 77: UFBGA100 recommended PCB design rules (0.5 mm pitch BGA)*. Added *Figure 11: Typical VBAT current consumption (LSE and RTC ON/LSEDRV[1:0]='00')*, *Figure 30: Maximum VREFINT scaler startup time from power down*, *Figure 33: UFBGA100 - 100-pin, 7 x 7 mm, 0.50 mm pitch, ultra fine pitch ball grid array package recommended footprint*.