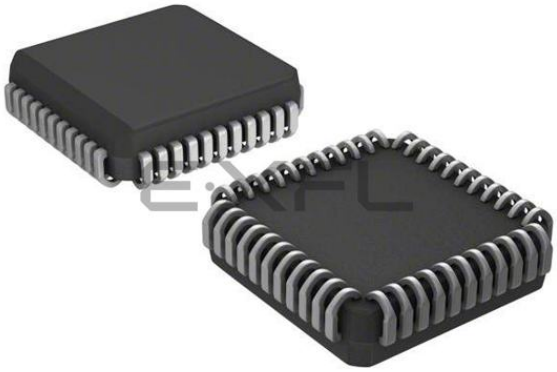
Microchip Technology - SST89E58RD2-40-C-NJE Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	8051
Core Size	8-Bit
Speed	40MHz
Connectivity	EBI/EMI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	36
Program Memory Size	40KB (40K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	External
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	44-PLCC (16.59x16.59)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/sst89e58rd2-40-c-nje

Not Recommended for New Designs

Product Description

The SST89E54RD2A/RDA and SST89E58RD2A/RDA are members of the FlashFlex family of 8-bit microcontroller products designed and manufactured with SST patented and proprietary SuperFlash CMOS semiconductor process technology. The split-gate cell design and thick-oxide tunneling injector offer significant cost and reliability benefits for SST customers. The devices use the 8051 instruction set and are pin-for-pin compatible with standard 8051 microcontroller devices.

The devices come with 24/40 KByte of on-chip flash EEPROM program memory which is partitioned into 2 independent program memory blocks. The primary Block 0 occupies 16/32 KByte of internal program memory space and the secondary Block 1 occupies 8 KByte of internal program memory space.

The 8-KByte secondary block can be mapped to the lowest location of the 16/32 KByte address space; it can also be hidden from the program counter and used as an independent EEPROM-like data memory.

In addition to the 24/40 KByte of EEPROM program memory on-chip and 1024 x8 bits of on-chip RAM, the devices can address up to 64 KByte of external program memory and up to 64 KByte of external RAM.

The flash memory blocks can be programmed via a standard 87C5x OTP EPROM programmer fitted with a special adapter and the firmware for SST devices. During power-on reset, the devices can be configured as either a slave to an external host for source code storage or a master to an external host for an in-application programming (IAP) operation. The devices are designed to be programmed in-system and in-application on the printed circuit board for maximum flexibility. The devices are pre-programmed with an example of the bootstrap loader in the memory, demonstrating the initial user program code loading or subsequent user code updating via the IAP operation. The sample bootstrap loader is available for the user's reference and convenience only; SST does not guarantee its functionality or usefulness. Chip-Erase or Block-Erase operations will erase the pre-programmed sample code.

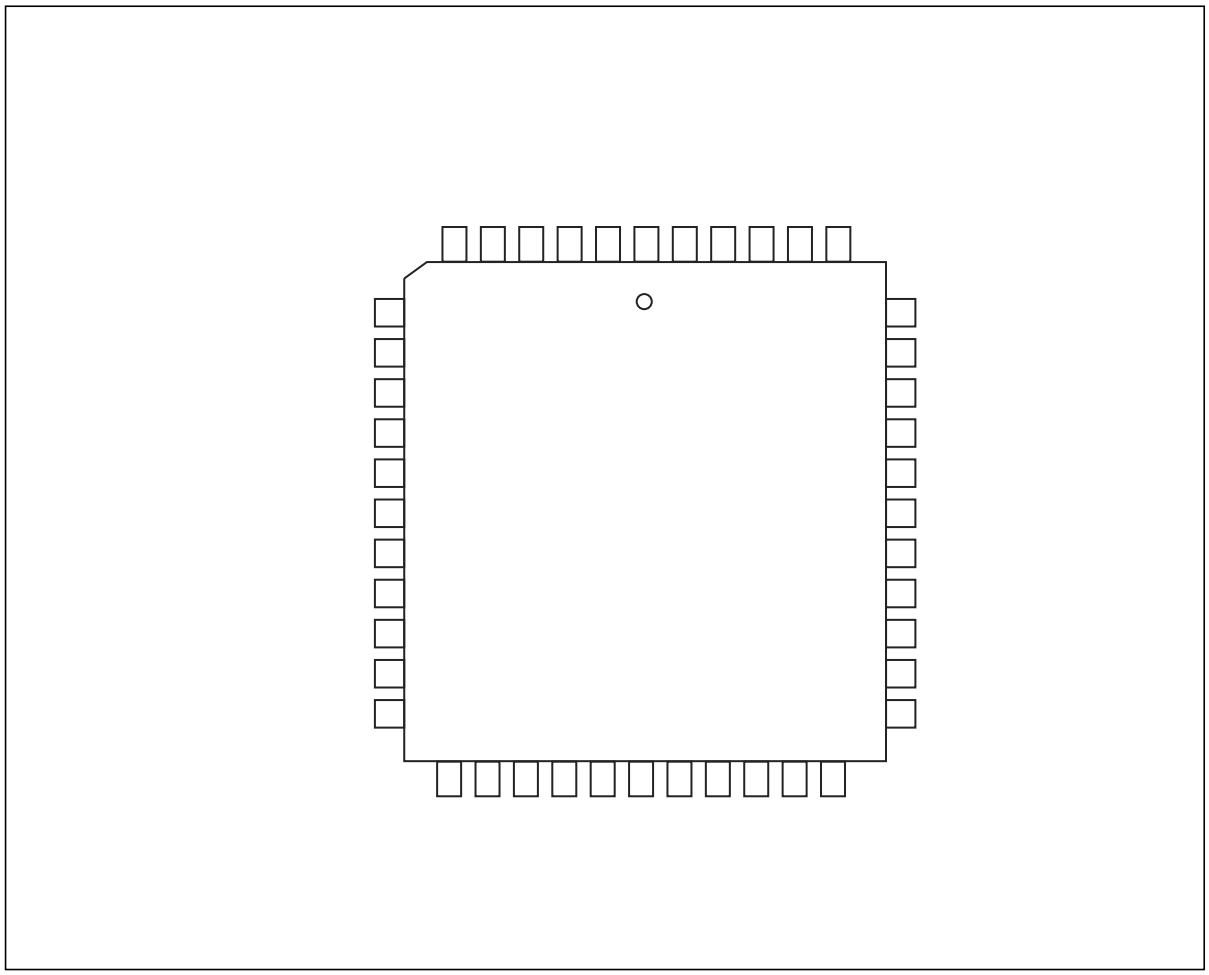

Figure 4: Pin Assignments for 44-lead PLCC

Memory Organization

The device has separate address spaces for program and data memory.

Program Flash Memory

There are two internal flash memory blocks in the device. The primary flash memory block (Block 0) has 16/32 KByte. The secondary flash memory block (Block 1) has 8 KByte. Since the total program address space is limited to 64 KByte, the SFCF[1:0] bit are used to control program bank selection. Please refer to Figures 5 and 6 for the program memory configuration. Program bank selection is described in the next section.

The 16K/32K x8 primary SuperFlash block is organized as 128/256 sectors, each sector consists of 128 Bytes.

The 8K x8 secondary SuperFlash block is organized as 64 sectors, each sector consists also of 128 Bytes.

For both blocks, the 7 least significant program address bits select the byte within the sector. The remainder of the program address bits select the sector within the block.

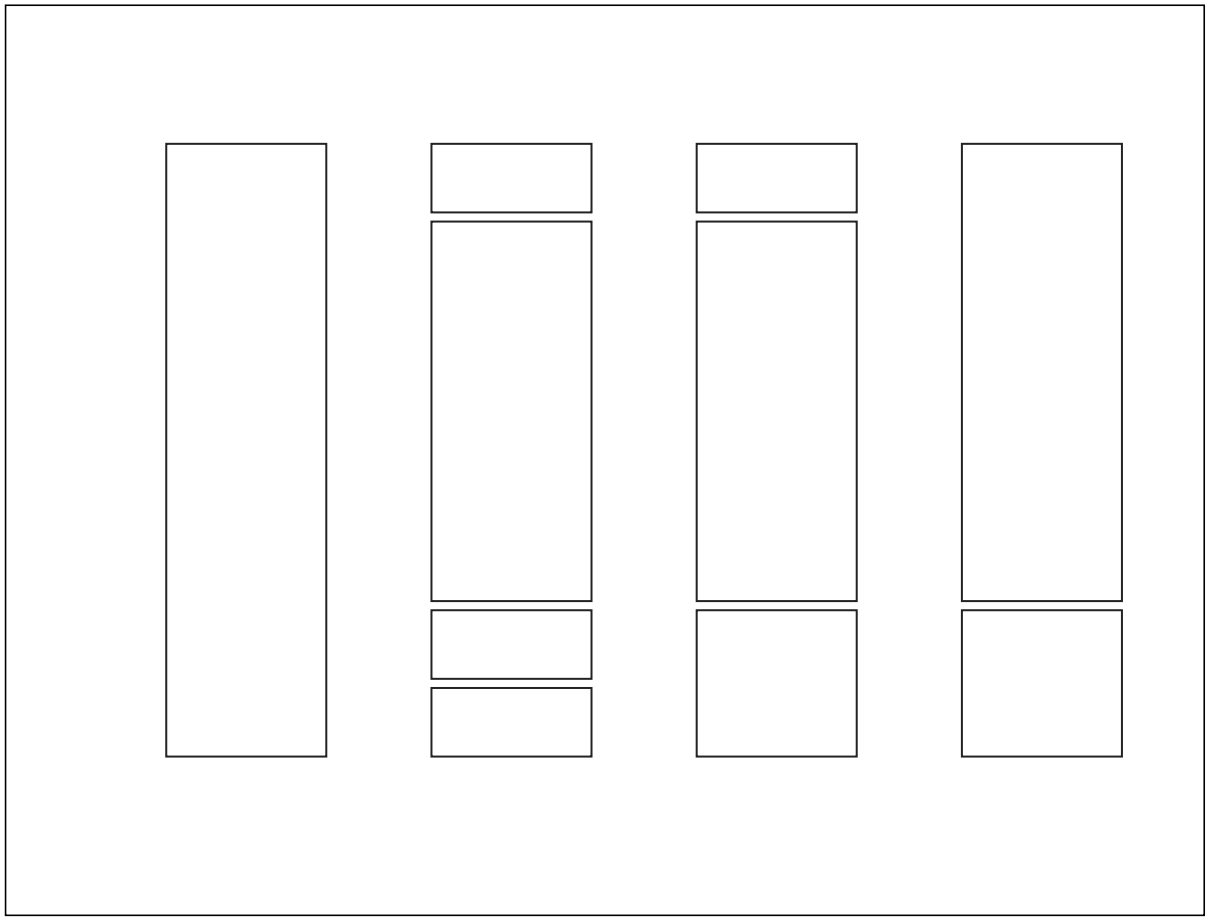

Figure 5: Program Memory Organization for 16 KByte SST89E54RDxA

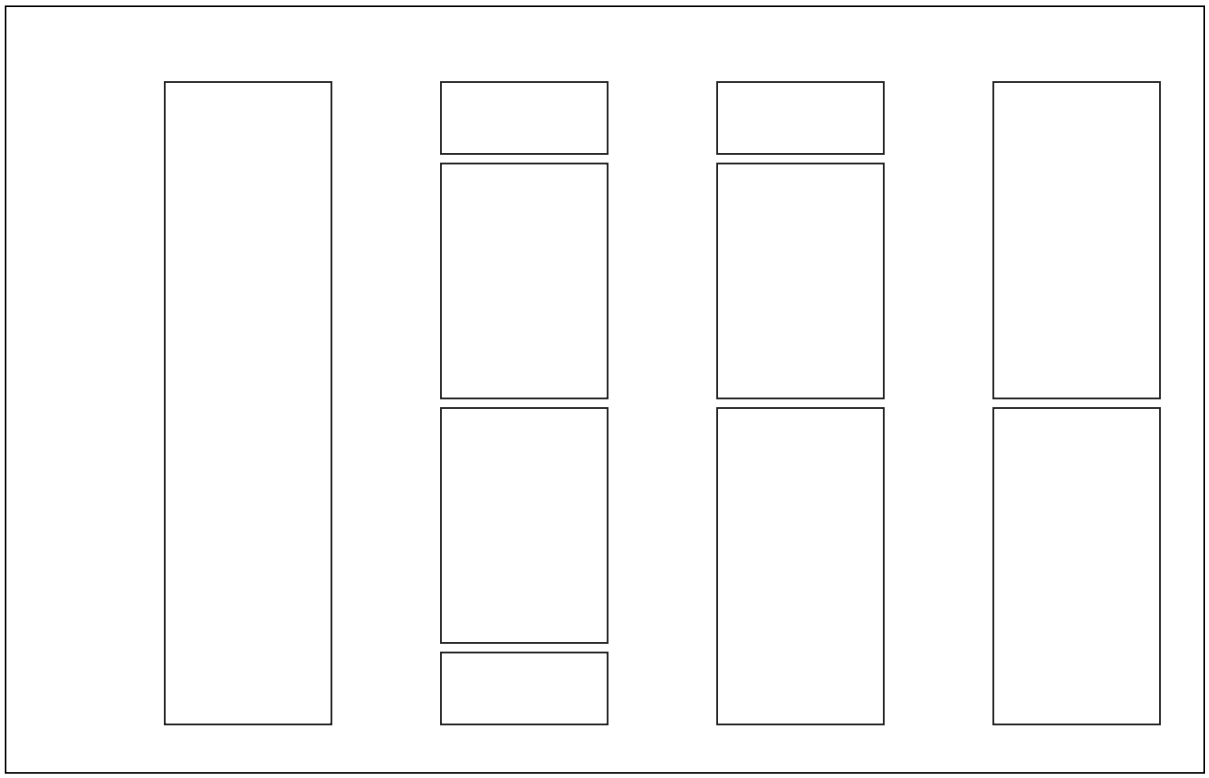

Figure 6: Program Memory Organization for 32 KByte SST89E58RDxA

Program Memory Block Switching

The program memory block switching feature of the device allows either Block 1 or the lowest 8 KByte of Block 0 to be used for the lowest 8 KByte of the program address space. SFCF[1:0] controls program memory block switching.

Table 2: SFCF Values for Program Memory Block Switching

SFCF[1:0]	Program Memory Block Switching
10, 11	Block 1 is not visible to the PC; Block 1 is reachable only via in-application programming from E000H - FFFFH.
01	Both Block 0 and Block 1 are visible to the PC. Block 0 is occupied from 0000H - 7FFFH. Block 1 is occupied from E000H - FFFFH.
00	Block 1 is overlaid onto the low 8K of the program address space; occupying address locations 0000H - 1FFFH. When the PC falls within 0000H - 1FFFH, the instruction will be fetched from Block 1 instead of Block 0. Outside of 0000H - 1FFFH, Block 0 is used. Locations 0000H - 1FFFH of Block 0 are reachable through in-application programming.

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Interrupt Enable (IE)

Location	7	6	5	4	3	2	1	0	Reset Value
A8H	EA	EC	ET2	ES	ET1	EX1	ET0	EX0	00H

Symbol	Function
EA	Global Interrupt Enable. 0 = Disable 1 = Enable
EC	PCA Interrupt Enable.
ET2	Timer 2 Interrupt Enable.
ES	Serial Interrupt Enable.
ET1	Timer 1 Interrupt Enable.
EX1	External 1 Interrupt Enable.
ET0	Timer 0 Interrupt Enable.
EX0	External 0 Interrupt Enable.

Interrupt Enable A (IEA)

Location	7	6	5	4	3	2	1	0	Reset Value
E8H	-	-	-	-	EBO	-	-	-	xxxx0xxxb

Symbol	Function
EBO	Brown-out Interrupt Enable. 1 = Enable the interrupt 0 = Disable the interrupt

Interrupt Priority (IP)

Location	7	6	5	4	3	2	1	0	Reset Value
B8H	-	PPC	PT2	PS	PT1	PX1	PT0	PX0	x0000000b

Symbol	Function
PPC	PCA interrupt priority bit
PT2	Timer 2 interrupt priority bit
PS	Serial Port interrupt priority bit
PT1	Timer 1 interrupt priority bit
PX1	External interrupt 1 priority bit
PT0	Timer 0 interrupt priority bit
PX0	External interrupt 0 priority bit

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Watchdog Timer Data/Reload Register (WDTD)

Location	7	6	5	4	3	2	1	0	Reset Value
85H	Watchdog Timer Data/Reload								00H

Symbol	Function
WDTD	Initial/Reload value in Watchdog Timer. New value won't be effective until WDT is set.

PCA Timer/Counter Control Register[1] (CCON)

Location	7	6	5	4	3	2	1	0	Reset Value
D8H	CF	CR	-	CCF4	CCF3	CCF2	CCF1	CCF0	00x00000b

1. Bit addressable

Symbol	Function
CF	PCA Counter Overflow Flag Set by hardware when the counter rolls over. CF flags an interrupt if bit ECF in CMOD is set. CF may be set by either hardware or software, but can only cleared by software.
CR	PCA Counter Run control bit Set by software to turn the PCA counter on. Must be cleared by software to turn the PCA counter off.
-	Not implemented, reserved for future use. **Note:** User should not write '1's to reserved bits. The value read from a reserved bit is indeterminate.
CCF4	PCA Module 4 interrupt flag. Set by hardware when a match or capture occurs. Must be cleared by software.
CCF3	PCA Module 3 interrupt flag. Set by hardware when a match or capture occurs. Must be cleared by software.
CCF2	PCA Module 2 interrupt flag. Set by hardware when a match or capture occurs. Must be cleared by software.
CCF1	PCA Module 1 interrupt flag. Set by hardware when a match or capture occurs. Must be cleared by software.
CCF0	PCA Module 0 interrupt flag. Set by hardware when a match or capture occurs. Must be cleared by software.

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PCA Compare/Capture Module Mode Register[1] (CCAPMn)

Location	7	6	5	4	3	2	1	0	Reset Value
DAH	-	ECOM0	CAPP0	CAPN0	MAT0	TOG0	PWM0	ECCF0	00xxx000b
DBH	-	ECOM1	CAPP1	CAPN1	MAT1	TOG1	PWM1	ECCF1	00xxx000b
DCH	-	ECOM2	CAPP2	CAPN2	MAT2	TOG2	PWM2	ECCF2	00xxx000b
DDH	-	ECOM3	CAPP3	CAPN3	MAT3	TOG3	PWM3	ECCF3	00xxx000b
DEH	-	ECOM4	CAPP4	CAPN4	MAT4	TOG4	PWM4	ECCF4	00xxx000b

1. Not bit addressable

Symbol	Function
-	Not implemented, reserved for future use. **Note:** User should not write ‘1’s to reserved bits. The value read from a reserved bit is indeterminate.
ECOMn	Enable Comparator 0: Disables the comparator function 1: Enables the comparator function
CAPPn	Capture Positive 0: Disables positive edge capture on CEX[4:0] 1: Enables positive edge capture on CEX[4:0]
CAPNn	Capture Negative 0: Disables negative edge capture on CEX[4:0] 1: Enables negative edge capture on CEX[4:0]
MATn	Match: Set ECOM[4:0] and MAT[4:0] to implement the software timer mode 0: Disables software timer mode 1: A match of the PCA counter with this module’s compare/capture register causes the CCFn bit in CCON to be set, flagging an interrupt.
TOGn	Toggle 0: Disables toggle function 1: A match of the PCA counter with this module’s compare/capture register causes the the CEXn pin to toggle.
PWMn	Pulse Width Modulation mode 0: Disables PWM mode 1: Enables CEXn pin to be used as a pulse width modulated output
ECCFn	Enable CCF Interrupt 0: Disables compare/capture flag CCF[4:0] in the CCON register to generate an interrupt request. 1: Enables compare/capture flag CCF[4:0] in the CCON register to generate an interrupt request.

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SPI Control Register (SPCR)

Location	7	6	5	4	3	2	1	0	Reset Value
D5H	SPIE	SPE	DORD	MSTR	CPOL	CPHA	SPR1	SPR0	00H

Symbol	Function
SPIE	If both SPIE and ES are set to one, SPI interrupts are enabled.
SPE	SPI enable bit. 0: Disables SPI. 1: Enables SPI and connects SS#, MOSI, MISO, and SCK to pins P1.4, P1.5, P1.6, P1.7.
DORD	Data Transmission Order. 0: MSB first in data transmission. 1: LSB first in data transmission.
MSTR	Master/Slave select. 0: Selects Slave mode. 1: Selects Master mode.
CPOL	Clock Polarity 0: SCK is low when idle (Active High). 1: SCK is high when idle (Active Low).
CPHA	Clock Phase control bit. The CPHA bit with the CPOL bit control the clock and data relationship between master and slave. See Figures 21 and 22. 0: Shift triggered on the leading edge of the clock. 1: Shift triggered on the trailing edge of the clock.
SPR1, SPR0	SPI Clock Rate Select bits. These two bits control the SCK rate of the device configured as master. SPR1 and SPR0 have no effect on the slave. The relationship between SCK and the oscillator frequency, f_{OSC}, is as follows:

SPR1	SPR0	SCK = f_{OSC} divided by
0	0	4
0	1	16
1	0	64
1	1	128

SPI Status Register (SPSR)

Location	7	6	5	4	3	2	1	0	Reset Value
AAH	SPIF	WCOL	-	-	-	-	-	-	00xxxxxxb

Symbol	Function
SPIF	SPI Interrupt Flag. Upon completion of data transfer, this bit is set to 1. If SPIE =1 and ES =1, an interrupt is then generated. This bit is cleared by software.
WCOL	Write Collision Flag. Set if the SPI data register is written to during data transfer. This bit is cleared by software.

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Serial Port Control Register (SCON)

Location	7	6	5	4	3	2	1	0	Reset Value
98H	SM0/FE	SM1	SM2	REN	TB8	RB8	TI	RI	00000000b

Symbol	Function
FE	Set SMOD0 = 1 to access FE bit. 0: No framing error 1: Framing Error. Set by receiver when an invalid stop bit is detected. This bit needs to be cleared by software.
SM0	SMOD0 = 0 to access SM0 bit. Serial Port Mode Bit 0
SM1	Serial Port Mode Bit 1

SM0	SM1	Mode	Description	Baud Rate[1]
0	0	0	Shift Register	f_{OSC}/6 (6 clock mode) or f_{OSC}/12 (12 clock mode)
0	1	1	8-bit UART	Variable
1	0	2	9-bit UART	f_{OSC}/32 or f_{OSC}/16 (6 clock mode) or f_{OSC}/64 or f_{OSC}/32 (12 clock mode)
1	1	3	9-bit UART	Variable

1. f_{OSC} = oscillator frequency

SM2	Enables the Automatic Address Recognition feature in Modes 2 or 3. If SM2 = 1 then RI will not be set unless the received 9th data bit (RB8) is 1, indicating an address, and the received byte is a given or broadcast address. In Mode 1, if SM2 = 1 then RI will not be activated unless a valid stop bit was received. In Mode 0, SM2 should be 0.
REN	Enables serial reception. 0: to disable reception. 1: to enable reception.
TB8	The 9th data bit that will be transmitted in Modes 2 and 3. Set or clear by software as desired.
RB8	In Modes 2 and 3, the 9th data bit that was received. In Mode 1, if SM2 = 0, RB8 is the stop bit that was received. In Mode 0, RB8 is not used.
TI	Transmit interrupt flag. Set by hardware at the end of the 8th bit time in Mode 0, or at the beginning of the stop bit in the other modes, in any serial transmission, Must be cleared by software.
RI	Receive interrupt flag. Set by hardware at the end of the8th bit time in Mode 0, or halfway through the stop bit time in the other modes, in any serial reception (except see SM2). Must be cleared by software.

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Sector-Erase

The Sector-Erase command erases all of the bytes in a sector. The sector size for the flash memory blocks is 128 Bytes. The selection of the sector to be erased is determined by the contents of SFAH and SFAL.

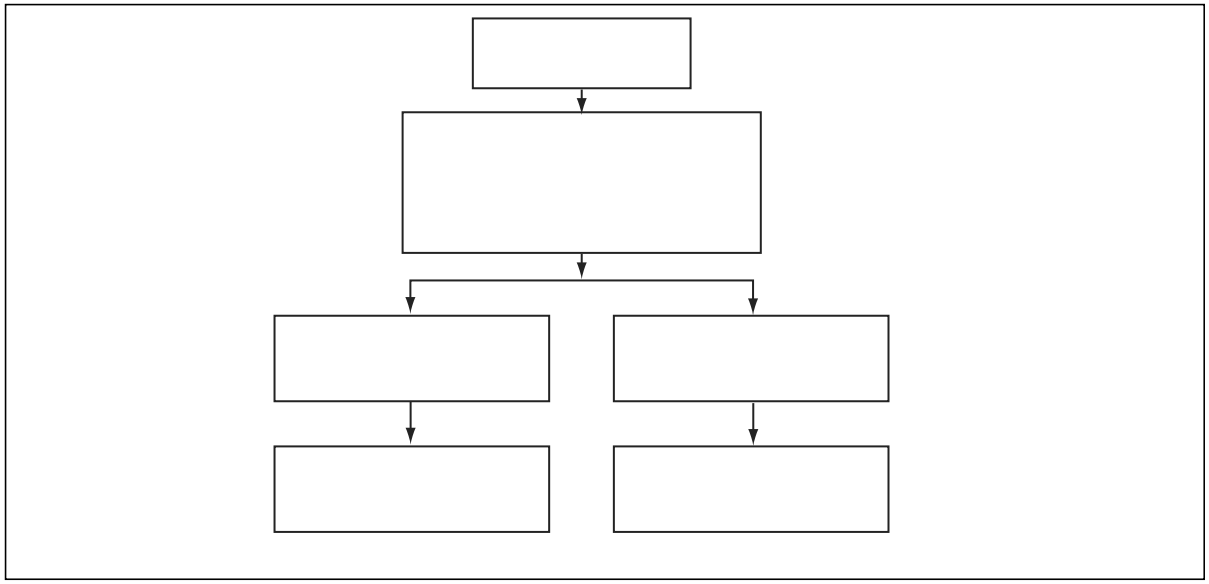

Figure 11: Sector-Erase

Byte-Program

The Byte-Program command programs data into a single byte. The address is determined by the contents of SFAH and SFAL. The data byte is in SFDT.

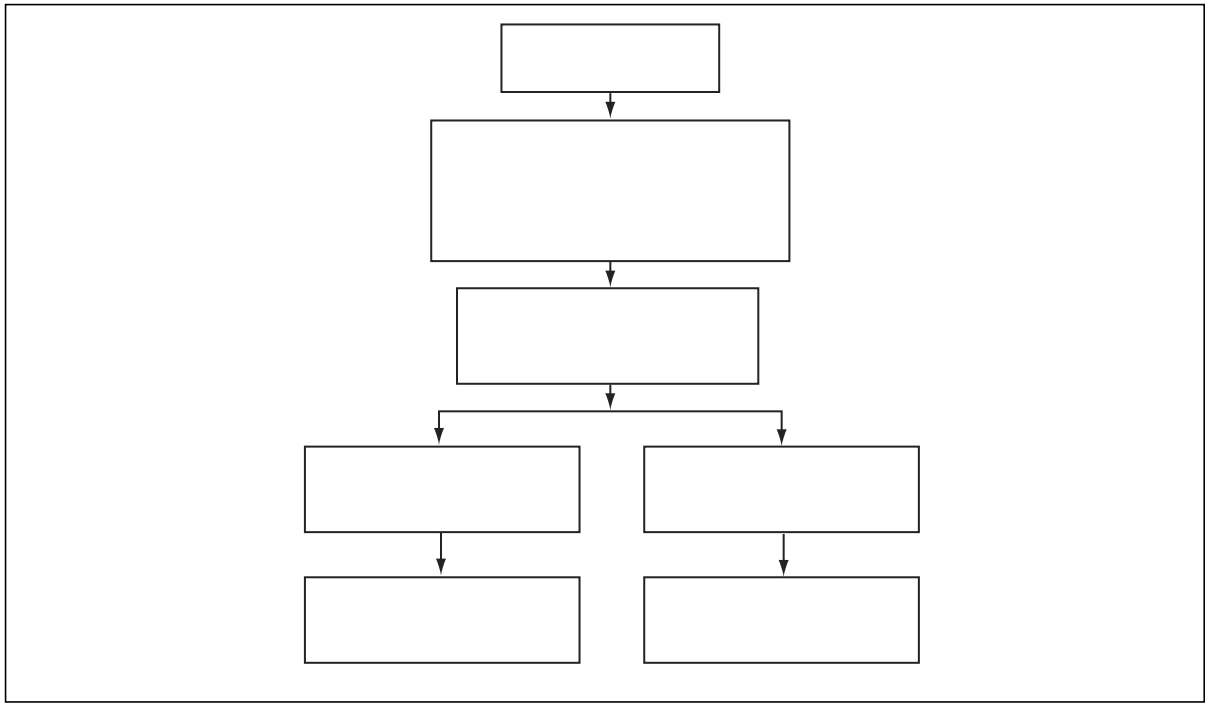

Figure 12: Byte-Program

Table 16: Timer/Counter 2

	Mode	T2CON	
		Internal Control[1]	External Control[2]
Used as Timer	16-bit Auto-Reload	00H	08H
	16-bit Capture	01H	09H
	Baud rate generator receive and transmit same baud rate	34H	36H
	Receive only	24H	26H
	Transmit only	14H	16H
Used as Counter	16-bit Auto-Reload	02H	0AH
	16-bit Capture	03H	0BH

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1. Capture/Reload occurs only on timer/counter overflow.
2. Capture/Reload occurs on timer/counter overflow and a 1 to 0 transition on T2EX (P1.1) pin except when Timer 2 is used in the baud rate generating mode.

Programmable Clock-Out

A 50% duty cycle clock can be programmed to come out on P1.0. This pin, besides being a regular I/O pin, has two alternate functions. It can be programmed:

1. to input the external clock for Timer/Counter 2, or
2. to output a 50% duty cycle clock ranging from 122 Hz to 8 MHz at a 16 MHz operating frequency (61 Hz to 4 MHz in 12 clock mode).

To configure Timer/Counter 2 as a clock generator, bit
C/#T2 (in T2CON) must be cleared and bit T20E in T2MOD must be set. Bit TR2 (T2CON.2) also must be set to start the timer.

The Clock-Out frequency depends on the oscillator frequency and the reload value of Timer 2 capture registers (RCAP2H, RCAP2L) as shown in this equation:

$$\frac{\text{Oscillator Frequency}}{n \times (65536 - \text{RCAP2H, RCAP2L})}$$

n =2 (in 6 clock mode)
4 (in 12 clock mode)

Where (RCAP2H, RCAP2L) = the contents of RCAP2H and RCAP2L taken as a 16-bit unsigned integer.

In the Clock-Out mode, Timer 2 roll-overs will not generate an interrupt. This is similar to when it is used as a baud-rate generator. It is possible to use Timer 2 as a baud-rate generator and a clock generator simultaneously. Note, however, that the baud-rate and the Clock-Out frequency will not be the same.

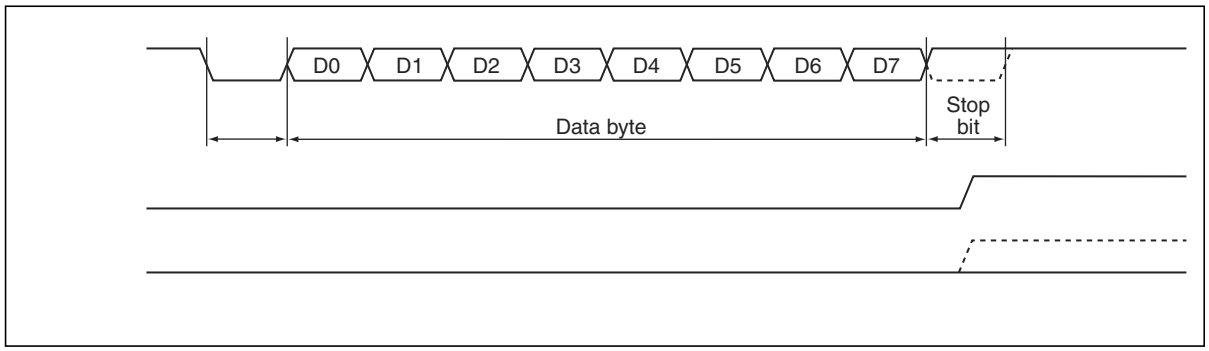

Figure 18: UART Timings in Mode 1

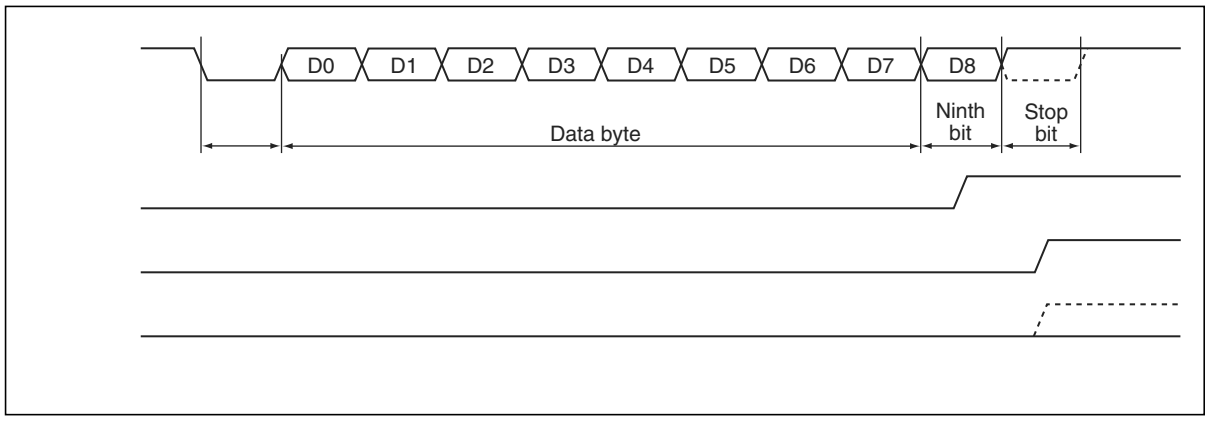

Figure 19: UART Timings in Modes 2 and 3

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Using the Given Address to Select Slaves

Any bits masked off by a 0 from SADEN become a “don’t care” bit for the given address. Any bit masked off by a 1, becomes ANDED with SADDR. The “don’t cares” provide flexibility in the user-defined addresses to address more slaves when using the given address.

Shown in the example above, Slave 1 has been given an address of 1111 0001 (SADDR). The SADEN byte has been used to mask off bits to a given address to allow more combinations of selecting Slave 1 and Slave 2. In this case for the given addresses, the last bit (LSB) of Slave 1 is a “don’t care” and the last bit of Slave 2 is a 1. To communicate with Slave 1 and Slave 2, the master would need to send an address with the last bit equal to 1 (e.g. 1111 0001) since Slave 1’s last bit is a don’t care and Slave 2’s last bit has to be a 1. To communicate with Slave 1 alone, the master would send an address with the last bit equal to 0 (e.g. 1111 0000), since Slave 2’s last bit is a 1. See the table below for other possible combinations.

Select Slave 1 Only		
Slave 1	**Given Address**	**Possible Addresses**
	1111 0X0X	1111 0000 1111 0100

Select Slave 2 Only		
Slave 2	**Given Address**	**Possible Addresses**
	1111 0XX1	1111 0111 1111 0011

Select Slaves 1 and 2	
Slaves 1 and 2	**Possible Addresses**
	1111 0001 1111 0101

If the user added a third slave such as the example below:

Slave 3

SADDR = 1111 1001
SADEN = 1111 0101
GIVEN = 1111 X0X1

The user could use the possible addresses above to select slave 3 only. Another combination could be to select slave 2 and 3 only as shown below.

Select Slaves 2 and 3 Only	
Slaves 2 and 3	**Possible Addresses**
	1111 0011

More than one slave may have the same SADDR address as well, and a given address could be used to modify the address so that it is unique.

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This routine should not be part of an interrupt service routine. If the program counter goes astray and gets stuck in an infinite loop, interrupts will still be serviced and the watchdog will keep getting reset. Thus, the purpose of the watchdog would be defeated. Instead, call this subroutine from the main program of the PCA timer.

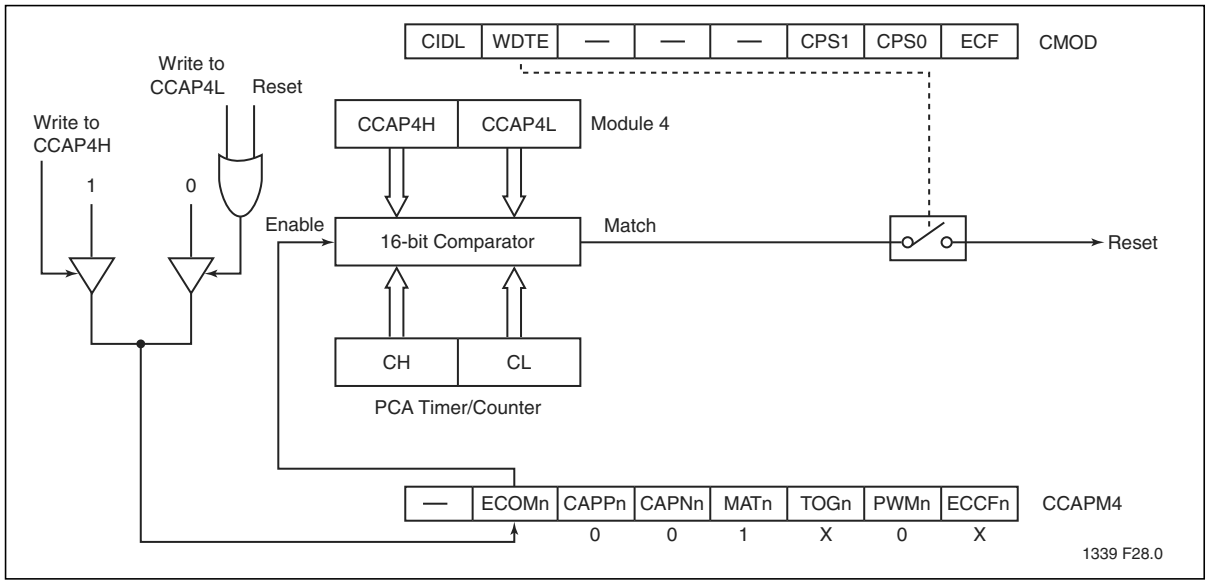

Figure 29: PCA Watchdog Timer (Module 4 only)

Power-Saving Modes

The device provides two power saving modes of operation for applications where power consumption is critical. The two modes are idle and power-down, see Table 27.

Idle Mode

Idle mode is entered setting the IDL bit in the PCON register. In idle mode, the program counter (PC) is stopped. The system clock continues to run and all interrupts and peripherals remain active. The on-chip RAM and the special function registers hold their data during this mode.

The device exits idle mode through either a system interrupt or a hardware reset. Exiting idle mode via system interrupt, the start of the interrupt clears the IDL bit and exits idle mode. After exit the Interrupt Service Routine, the interrupted program resumes execution beginning at the instruction immediately following the instruction which invoked the idle mode. A hardware reset starts the device similar to a power-on reset.

Power-down Mode

The power-down mode is entered by setting the PD bit in the PCON register. In the power-down mode, the clock is stopped and external interrupts are active for level sensitive interrupts only. SRAM contents are retained during power-down, the minimum V_{DD} level is 2.0V.

The device exits power-down mode through either an enabled external level sensitive interrupt or a hardware reset. The start of the interrupt clears the PD bit and exits power-down. Holding the external interrupt pin low restarts the oscillator, the signal must hold low at least 1024 clock cycles before bringing back high to complete the exit. Upon interrupt signal being restored to logic $V_{IH,}$ the first instruction of the interrupt service routine will execute. A hardware reset starts the device similar to power-on reset.

To exit properly out of power-down, the reset or external interrupt should not be executed before the V_{DD} line is restored to its normal operating voltage. Be sure to hold V_{DD} voltage long enough at its normal operating level for the oscillator to restart and stabilize (normally less than 10 ms).

System Clock and Clock Options

Clock Input Options and Recommended Capacitor Values for Oscillator

Shown in Figure 33 are the input and output of an internal inverting amplifier (XTAL1, XTAL2), which can be configured for use as an on-chip oscillator.

When driving the device from an external clock source, XTAL2 should be left disconnected and XTAL1 should be driven.

At start-up, the external oscillator may encounter a higher capacitive load at XTAL1 due to interaction between the amplifier and its feedback capacitance. However, the capacitance will not exceed 15 pF once the external signal meets the V_{IL} and V_{IH} specifications.

Crystal manufacturer, supply voltage, and other factors may cause circuit performance to differ from one application to another. C1 and C2 should be adjusted appropriately for each design. Table 28, shows the typical values for C1 and C2 vs. crystal type for various frequencies

Table 28: Recommended Values for C1 and C2 by Crystal Type

Crystal	C1 = C2
Quartz	20-30pF
Ceramic	40-50pF

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More specific information about on-chip oscillator design can be found in the ***FlashFlex Oscillator Circuit Design Considerations*** application note.

AC Electrical Characteristics

AC Characteristics:

(Over Operating Conditions: Load Capacitance for Port 0, ALE#, and PSEN# = 100pF; Load Capacitance for All Other Outputs = 80pF)

Table 36: AC Electrical Characteristics (1 of 2)
T_A = -40°C to +85°C, V_{DD} = 4.5-5.5V@40MHz, V_{SS} = 0V

		Oscillator				
		40 MHz (x1 Mode) 20 MHz (x2 Mode)		Variable		
Symbol	Parameter	Min	Max	Min	Max	Units
$1/T_{CLCL}$	x1 Mode Oscillator Frequency	0	40	0	40	MHz
$1/2T_{CLCL}$	x2 Mode Oscillator Frequency	0	20	0	20	MHz
T_{LHLL}	ALE Pulse Width	35		$2T_{CLCL}$ - 15		ns
T_{AVLL}	Address Valid to ALE Low			T_{CLCL} - 25 (3V)		ns
		10		T_{CLCL} - 15 (5V)		ns
T_{LLAX}	Address Hold After ALE Low			T_{CLCL} - 25 (3V)		ns
		10		T_{CLCL} - 15 (5V)		ns
T_{LLIV}	ALE Low to Valid Instr In				$4T_{CLCL}$ - 65 (3V)	ns
			55		$4T_{CLCL}$ - 45 (5V)	ns
T_{LLPL}	ALE Low to PSEN# Low			T_{CLCL} - 25 (3V)		ns
		10		T_{CLCL} - 15 (5V)		ns
T_{PLPH}	PSEN# Pulse Width	60		$3T_{CLCL}$ - 25 (3V) $3T_{CLCL}$ - 15 (5V)		ns
T_{PLIV}	PSEN# Low to Valid Instr In				$3T_{CLCL}$ - 55 (3V)	ns
			25		$3T_{CLCL}$ - 50 (5V)	ns
T_{PXIX}	Input Instr Hold After PSEN#			0		ns
T_{PXIZ}	Input Instr Float After PSEN#				T_{CLCL} - 5 (3V)	ns
			10		T_{CLCL} - 15 (5V)	ns
T_{PXAV}	PSEN# to Address valid	17		T_{CLCL} - 8		ns
T_{AVIV}	Address to Valid Instr In				$5T_{CLCL}$ - 80 (3V)	ns
			65		$5T_{CLCL}$ - 60 (5V)	ns
T_{PLAZ}	PSEN# Low to Address Float		10		10	ns
T_{RLRH}	RD# Pulse Width	120		$6T_{CLCL}$ - 40 (3V) $6T_{CLCL}$ - 30 (5V)		ns
T_{WLWH}	Write Pulse Width (WE#)	120		$6T_{CLCL}$ - 40 (3V) $6T_{CLCL}$ - 30 (5V)		ns
T_{RLDV}	RD# Low to Valid Data In				$5T_{CLCL}$ - 90 (3V)	ns
			75		$5T_{CLCL}$ - 50 (5V)	ns
T_{RHDX}	Data Hold After RD#	0		0		ns
T_{RHDZ}	Data Float After RD#				$2T_{CLCL}$ - 25 (3V)	ns
			38		$2T_{CLCL}$ - 12 (5V)	ns
T_{LLDV}	ALE Low to Valid Data In				$8T_{CLCL}$ - 90 (3V)	ns
			150		$8T_{CLCL}$ - 50 (5V)	ns
T_{AVDV}	Address to Valid Data In				$9T_{CLCL}$ - 90 (3V)	ns
			150		$9T_{CLCL}$ - 75 (5V)	ns

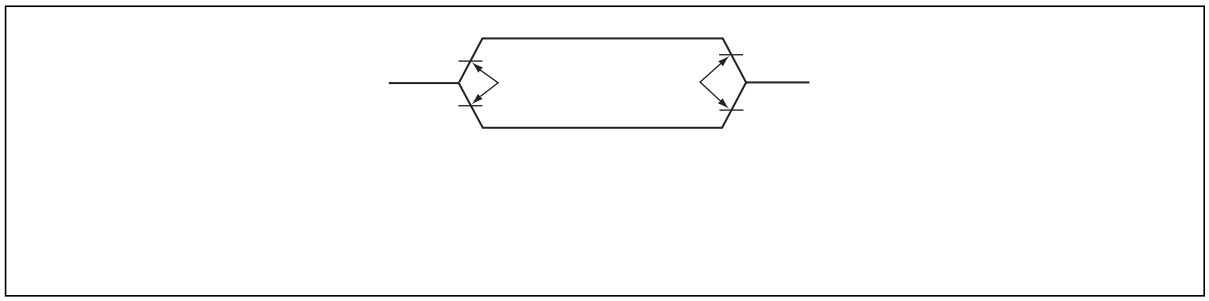

Figure 41: Float Waveform

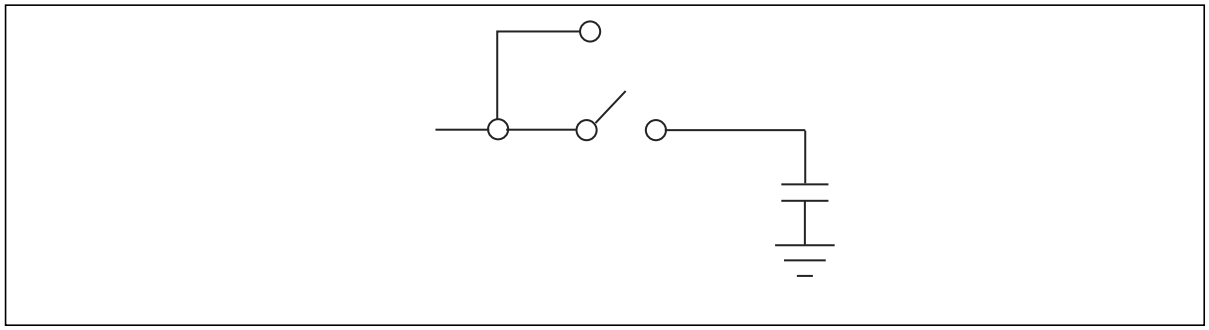

Figure 42: A Test Load Example

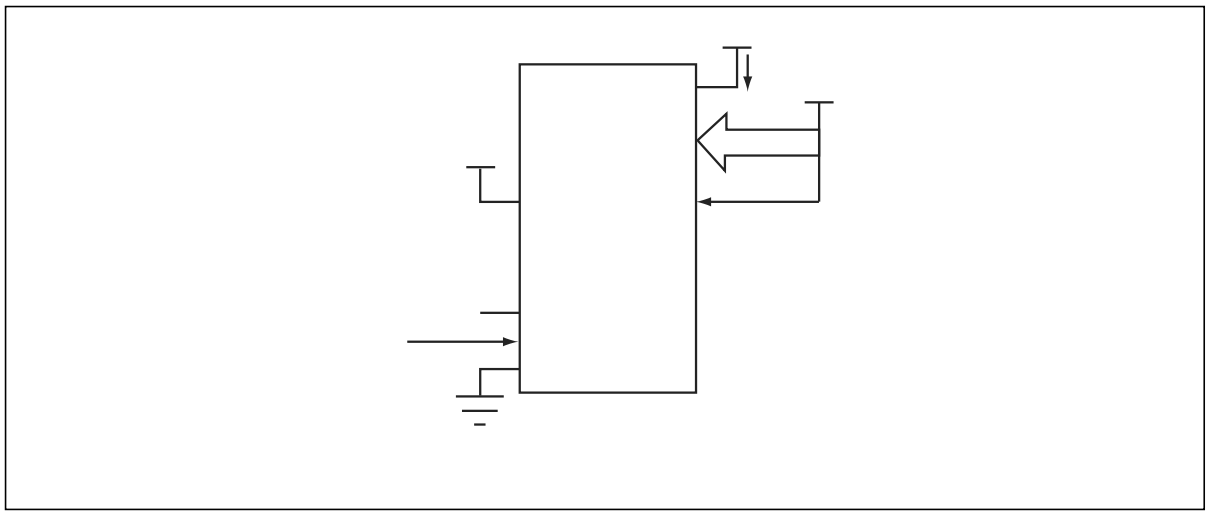

Figure 43: I_{DD} Test Condition, Active Mode

Packaging Diagrams

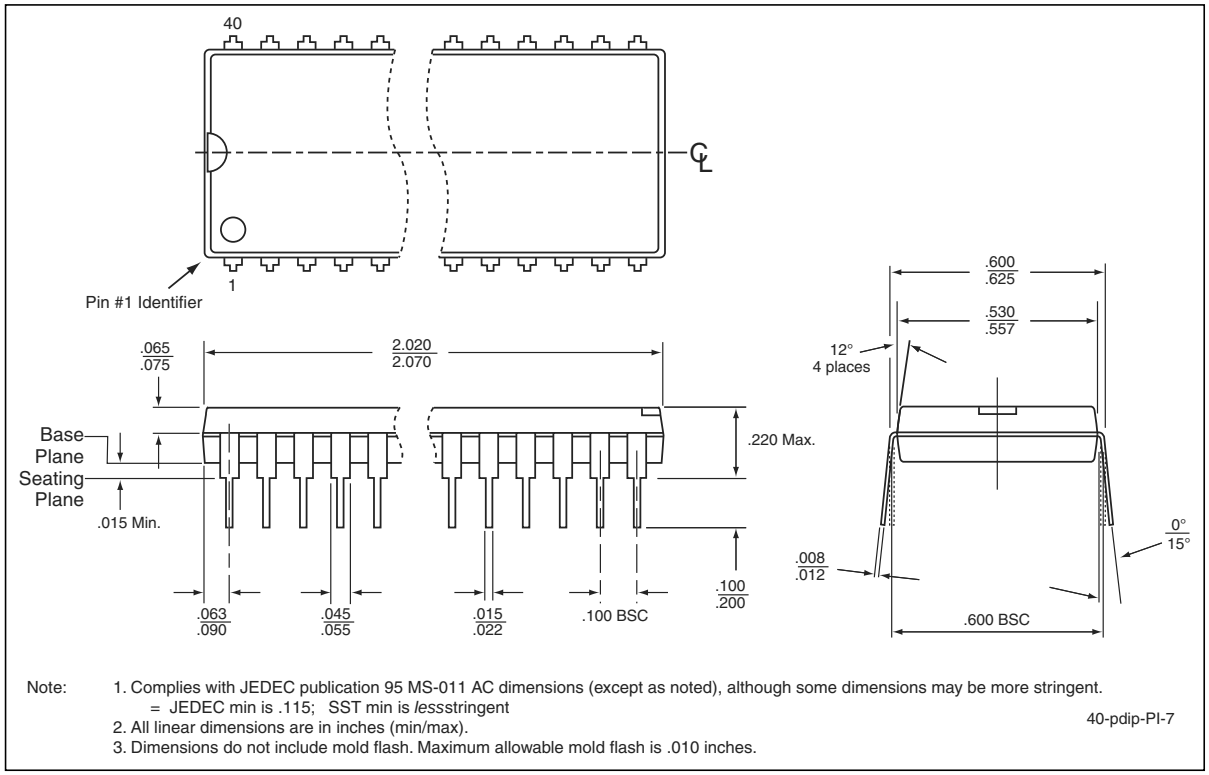

Figure 46: 40-Pin Plastic Dual In-line Pins (PDIP)
SST Package Code: PI