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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	HDMI-CEC, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	25
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 13x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f051k4t6">https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f051k4t6</a>

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## 3.4 Cyclic redundancy check calculation unit (CRC)

The CRC (cyclic redundancy check) calculation unit is used to get a CRC code from a 32-bit data word and a CRC-32 (Ethernet) polynomial.

Among other applications, CRC-based techniques are used to verify data transmission or storage integrity. In the scope of the EN/IEC 60335-1 standard, they offer a means of verifying the Flash memory integrity. The CRC calculation unit helps compute a signature of the software during runtime, to be compared with a reference signature generated at link-time and stored at a given memory location.

## 3.5 Power management

### 3.5.1 Power supply schemes

- $V_{DD} = V_{DDIO1} = 2.0$  to  $3.6$  V: external power supply for I/Os ( $V_{DDIO1}$ ) and the internal regulator. It is provided externally through VDD pins.
- $V_{DDA}$  = from  $V_{DD}$  to  $3.6$  V: external analog power supply for ADC, DAC, Reset blocks, RCs and PLL (minimum voltage to be applied to  $V_{DDA}$  is  $2.4$  V when the ADC or DAC are used). It is provided externally through VDDA pin. The  $V_{DDA}$  voltage level must be always greater or equal to the  $V_{DD}$  voltage level and must be established first.
- $V_{BAT} = 1.65$  to  $3.6$  V: power supply for RTC, external clock  $32$  kHz oscillator and backup registers (through power switch) when  $V_{DD}$  is not present.

For more details on how to connect power pins, refer to [Figure 13: Power supply scheme](#).

### 3.5.2 Power supply supervisors

The device has integrated power-on reset (POR) and power-down reset (PDR) circuits. They are always active, and ensure proper operation above a threshold of  $2$  V. The device remains in reset mode when the monitored supply voltage is below a specified threshold,  $V_{POR/PDR}$ , without the need for an external reset circuit.

- The POR monitors only the  $V_{DD}$  supply voltage. During the startup phase it is required that  $V_{DDA}$  should arrive first and be greater than or equal to  $V_{DD}$ .
- The PDR monitors both the  $V_{DD}$  and  $V_{DDA}$  supply voltages, however the  $V_{DDA}$  power supply supervisor can be disabled (by programming a dedicated Option bit) to reduce the power consumption if the application design ensures that  $V_{DDA}$  is higher than or equal to  $V_{DD}$ .

The device features an embedded programmable voltage detector (PVD) that monitors the  $V_{DD}$  power supply and compares it to the  $V_{PVD}$  threshold. An interrupt can be generated when  $V_{DD}$  drops below the  $V_{PVD}$  threshold and/or when  $V_{DD}$  is higher than the  $V_{PVD}$  threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

### 3.5.3 Voltage regulator

The regulator has two operating modes and it is always enabled after reset.

- Main (MR) is used in normal operating mode (Run).
- Low power (LPR) can be used in Stop mode where the power demand is reduced.

Table 13. Pin definitions (continued)

Pin number						Pin name (function upon reset)	Pin type	I/O structure	Notes	Pin functions	
LQFP64	UFBGA64	LQFP48/UFQFPN48	WLCSP36	LQFP32	UFQFPN32					Alternate functions	Additional functions
22	G4	16	E3	12	12	PA6	I/O	TTa	-	SPI1_MISO, I2S1_MCK, TIM3_CH1, TIM1_BKIN, TIM16_CH1, COMP1_OUT, TSC_G2_IO3, EVENTOUT	ADC_IN6
23	H4	17	F4	13	13	PA7	I/O	TTa	-	SPI1_MOSI, I2S1_SD, TIM3_CH2, TIM14_CH1, TIM1_CH1N, TIM17_CH1, COMP2_OUT, TSC_G2_IO4, EVENTOUT	ADC_IN7
24	H5	-	-	-	-	PC4	I/O	TTa	-	EVENTOUT	ADC_IN14
25	H6	-	-	-	-	PC5	I/O	TTa	-	TSC_G3_IO1	ADC_IN15
26	F5	18	F3	14	14	PB0	I/O	TTa	-	TIM3_CH3, TIM1_CH2N, TSC_G3_IO2, EVENTOUT	ADC_IN8
27	G5	19	F2	15	15	PB1	I/O	TTa	-	TIM3_CH4, TIM14_CH1, TIM1_CH3N, TSC_G3_IO3	ADC_IN9
28	G6	20	D2	-	16	PB2	I/O	FT	(4)	TSC_G3_IO4	-
29	G7	21	-	-	-	PB10	I/O	FT	(5)	I2C2_SCL, CEC, TIM2_CH3, TSC_SYNC	-
30	H7	22	-	-	-	PB11	I/O	FT	(5)	I2C2_SDA, TIM2_CH4, TSC_G6_IO1, EVENTOUT	-
31	D4	23	F1	16	0	VSS	S	-	-	Ground	
32	E4	24	E1	17	17	VDD	S	-	-	Digital power supply	

Table 13. Pin definitions (continued)

Pin number						Pin name (function upon reset)	Pin type	I/O structure	Notes	Pin functions	
LQFP64	UFBGA64	LQFP48/UFQFPN48	WLCSP36	LQFP32	UFQFPN32					Alternate functions	Additional functions
33	H8	25	-	-	-	PB12	I/O	FT	(5)	SPI2_NSS, TIM1_BKIN, TSC_G6_IO2, EVENTOUT	-
34	G8	26	-	-	-	PB13	I/O	FT	(5)	SPI2_SCK, TIM1_CH1N, TSC_G6_IO3	-
35	F8	27	-	-	-	PB14	I/O	FT	(5)	SPI2_MISO, TIM1_CH2N, TIM15_CH1, TSC_G6_IO4	-
36	F7	28	-	-	-	PB15	I/O	FT	(5)	SPI2_MOSI, TIM1_CH3N, TIM15_CH1N, TIM15_CH2	RTC_REFIN
37	F6	-	-	-	-	PC6	I/O	FT	-	TIM3_CH1	-
38	E7	-	-	-	-	PC7	I/O	FT	-	TIM3_CH2	-
39	E8	-	-	-	-	PC8	I/O	FT	-	TIM3_CH3	-
40	D8	-	-	-	-	PC9	I/O	FT	-	TIM3_CH4	-
41	D7	29	E2	18	18	PA8	I/O	FT	-	USART1_CK, TIM1_CH1, EVENTOUT, MCO	-
42	C7	30	D1	19	19	PA9	I/O	FT	-	USART1_TX, TIM1_CH2, TIM15_BKIN, TSC_G4_IO1	-
43	C6	31	C1	20	20	PA10	I/O	FT	-	USART1_RX, TIM1_CH3, TIM17_BKIN, TSC_G4_IO2	-
44	C8	32	C2	21	21	PA11	I/O	FT	-	USART1_CTS, TIM1_CH4, COMP1_OUT, TSC_G4_IO3, EVENTOUT	-

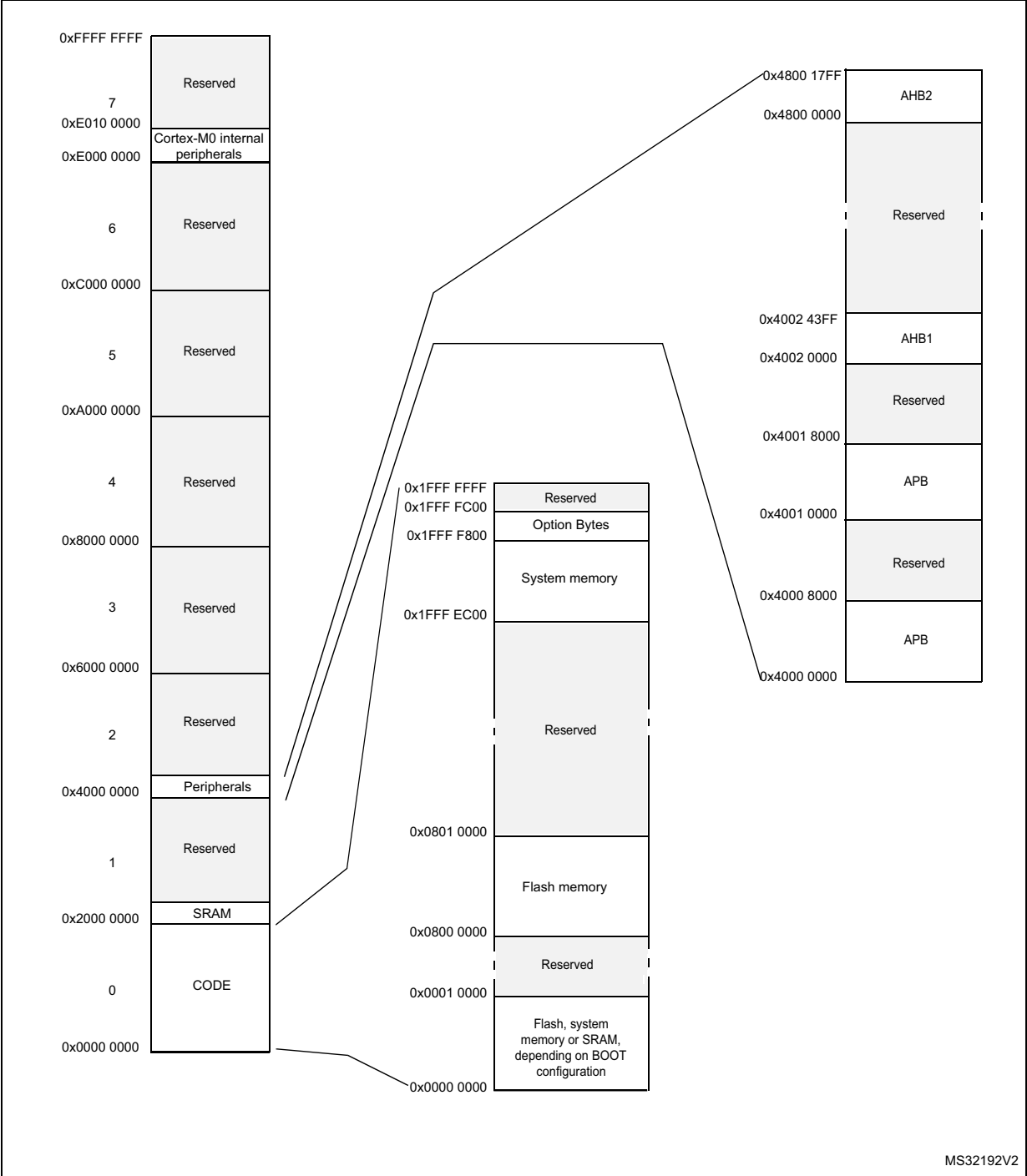
**Table 14. Alternate functions selected through GPIOA\_AFR registers for port A**

Pin name	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
PA0	-	USART2_CTS	TIM2_CH1_ETR	TSC_G1_IO1		-	-	COMP1_OUT
PA1	EVENTOUT	USART2_RTS	TIM2_CH2	TSC_G1_IO2			-	-
PA2	TIM15_CH1	USART2_TX	TIM2_CH3	TSC_G1_IO3	-	-	-	COMP2_OUT
PA3	TIM15_CH2	USART2_RX	TIM2_CH4	TSC_G1_IO4	-	-	-	-
PA4	SPI1_NSS, I2S1_WS	USART2_CK	-	TSC_G2_IO1	TIM14_CH1	-	-	-
PA5	SPI1_SCK, I2S1_CK	CEC	TIM2_CH1_ETR	TSC_G2_IO2	-	-	-	-
PA6	SPI1_MISO, I2S1_MCK	TIM3_CH1	TIM1_BKIN	TSC_G2_IO3		TIM16_CH1	EVENTOUT	COMP1_OUT
PA7	SPI1_MOSI, I2S1_SD	TIM3_CH2	TIM1_CH1N	TSC_G2_IO4	TIM14_CH1	TIM17_CH1	EVENTOUT	COMP2_OUT
PA8	MCO	USART1_CK	TIM1_CH1	EVENTOUT		-	-	-
PA9	TIM15_BKIN	USART1_TX	TIM1_CH2	TSC_G4_IO1	-	-	-	-
PA10	TIM17_BKIN	USART1_RX	TIM1_CH3	TSC_G4_IO2	-	-	-	-
PA11	EVENTOUT	USART1_CTS	TIM1_CH4	TSC_G4_IO3	-	-	-	COMP1_OUT
PA12	EVENTOUT	USART1_RTS	TIM1_ETR	TSC_G4_IO4	-	-	-	COMP2_OUT
PA13	SWDIO	IR_OUT		-	-	-	-	-
PA14	SWCLK	USART2_TX	-	-	-	-	-	-
PA15	SPI1_NSS, I2S1_WS	USART2_RX	TIM2_CH1_ETR	EVENTOUT		-	-	-

5 Memory mapping

To the difference of STM32F051x8 memory map in [Figure 10](#), the two bottom code memory spaces of STM32F051x4/STM32F051x6 end at 0x0000 3FFF/0x0000 7FFF and 0x0800 3FFF/0x0000 7FFF, respectively.

Figure 10. STM32F051x8 memory map



## 6 Electrical characteristics

### 6.1 Parameter conditions

Unless otherwise specified, all voltages are referenced to  $V_{SS}$ .

#### 6.1.1 Minimum and maximum values

Unless otherwise specified, the minimum and maximum values are guaranteed in the worst conditions of ambient temperature, supply voltage and frequencies by tests in production on 100% of the devices with an ambient temperature at  $T_A = 25\text{ }^{\circ}\text{C}$  and  $T_A = T_{A\text{max}}$  (given by the selected temperature range).

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes and are not tested in production. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation (mean  $\pm 3\sigma$ ).

#### 6.1.2 Typical values

Unless otherwise specified, typical data are based on  $T_A = 25\text{ }^{\circ}\text{C}$ ,  $V_{DD} = V_{DDA} = 3.3\text{ V}$ . They are given only as design guidelines and are not tested.

Typical ADC accuracy values are determined by characterization of a batch of samples from a standard diffusion lot over the full temperature range, where 95% of the devices have an error less than or equal to the value indicated (mean  $\pm 2\sigma$ ).

#### 6.1.3 Typical curves

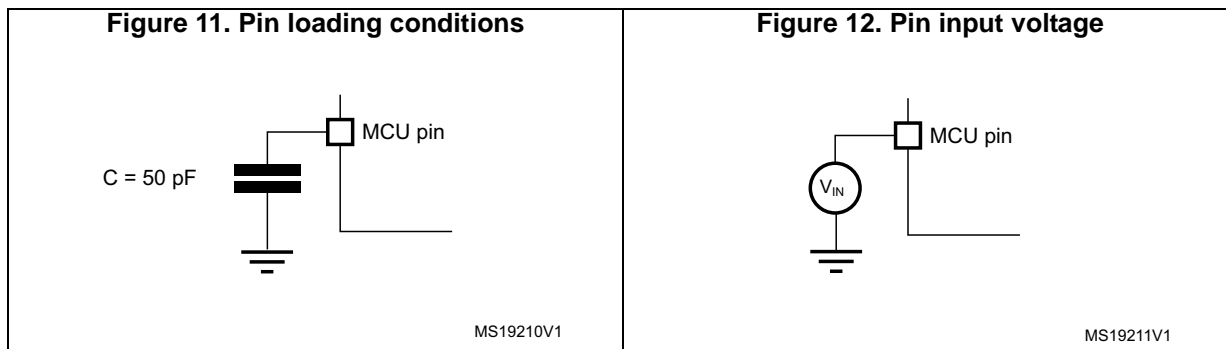
Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

#### 6.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in [Figure 11](#).

#### 6.1.5 Pin input voltage

The input voltage measurement on a pin of the device is described in [Figure 12](#).





## 6.2 Absolute maximum ratings

Stresses above the absolute maximum ratings listed in [Table 17: Voltage characteristics](#), [Table 18: Current characteristics](#) and [Table 19: Thermal characteristics](#) may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

**Table 17. Voltage characteristics<sup>(1)</sup>**

Symbol	Ratings	Min	Max	Unit
$V_{DD}-V_{SS}$	External main supply voltage	- 0.3	4.0	V
$V_{DDA}-V_{SS}$	External analog supply voltage	- 0.3	4.0	V
$V_{DD}-V_{DDA}$	Allowed voltage difference for $V_{DD} > V_{DDA}$	-	0.4	V
$V_{BAT}-V_{SS}$	External backup supply voltage	- 0.3	4.0	V
$V_{IN}^{(2)}$	Input voltage on FT and FTf pins	$V_{SS} - 0.3$	$V_{DDIOx} + 4.0^{(3)}$	V
	Input voltage on TTa pins	$V_{SS} - 0.3$	4.0	V
	BOOT0	0	9.0	V
	Input voltage on any other pin	$V_{SS} - 0.3$	4.0	V
$ \Delta V_{DDx} $	Variations between different $V_{DD}$ power pins	-	50	mV
$ V_{SSx} - V_{SS} $	Variations between all the different ground pins	-	50	mV
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	see <a href="#">Section 6.3.12: Electrical sensitivity characteristics</a>		-

1. All main power ( $V_{DD}$ ,  $V_{DDA}$ ) and ground ( $V_{SS}$ ,  $V_{SSA}$ ) pins must always be connected to the external power supply, in the permitted range.
2.  $V_{IN}$  maximum must always be respected. Refer to [Table 18: Current characteristics](#) for the maximum allowed injected current values.
3. Valid only if the internal pull-up/pull-down resistors are disabled. If internal pull-up or pull-down resistor is enabled, the maximum limit is 4 V.

Table 25. Typical and maximum current consumption from  $V_{DD}$  at 3.6 V (continued)

Symbol	Parameter	Conditions	f <sub>HCLK</sub>	All peripherals enabled				All peripherals disabled				Unit
				Typ	Max @ T <sub>A</sub> <sup>(1)</sup>			Typ	Max @ T <sub>A</sub> <sup>(1)</sup>			
					25 °C	85 °C	105 °C		25 °C	85 °C	105 °C	
I <sub>DD</sub>	Supply current in Sleep mode	HSE bypass, PLL on	48 MHz	14.0	15.3 <sup>(2)</sup>	15.3	16.0 <sup>(2)</sup>	2.8	3.0 <sup>(2)</sup>	3.0	3.2 <sup>(2)</sup>	mA
			32 MHz	9.5	10.2	10.2	10.7	2.0	2.1	2.1	2.3	
			24 MHz	7.3	7.8	7.8	8.3	1.5	1.7	1.7	1.9	
		HSE bypass, PLL off	8 MHz	2.6	2.9	2.9	3.0	0.6	0.8	0.8	0.8	
			1 MHz	0.4	0.6	0.6	0.6	0.2	0.4	0.4	0.4	
		HSI clock, PLL on	48 MHz	14.0	15.3	15.3	16.0	3.8	4.0	4.1	4.2	
			32 MHz	9.5	10.2	10.2	10.7	2.6	2.7	2.8	2.8	
			24 MHz	7.3	7.8	7.8	8.3	2.0	2.1	2.1	2.1	
		HSI clock, PLL off	8 MHz	2.6	2.9	2.9	3.0	0.6	0.8	0.8	0.8	

1. Data based on characterization results, not tested in production unless otherwise specified.

2. Data based on characterization results and tested in production (using one common test limit for sum of  $I_{DD}$  and  $I_{DDA}$ ).

Table 26. Typical and maximum current consumption from the  $V_{DDA}$  supply

Symbol	Parameter	Conditions (1)	f <sub>HCLK</sub>	V <sub>DDA</sub> = 2.4 V				V <sub>DDA</sub> = 3.6 V				Unit
				Typ	Max @ T <sub>A</sub> <sup>(2)</sup>			Typ	Max @ T <sub>A</sub> <sup>(2)</sup>			
					25 °C	85 °C	105 °C		25 °C	85 °C	105 °C	
I <sub>DDA</sub>	Supply current in Run or Sleep mode, code executing from Flash memory or RAM	HSE bypass, PLL on	48 MHz	150	170 <sup>(3)</sup>	178	182 <sup>(3)</sup>	164	183 <sup>(3)</sup>	195	198 <sup>(3)</sup>	µA
			32 MHz	104	121	126	128	113	129	135	138	
			24 MHz	82	96	100	103	88	102	106	108	
		HSE bypass, PLL off	8 MHz	2.0	2.7	3.1	3.3	3.5	3.8	4.1	4.4	
			1 MHz	2.0	2.7	3.1	3.3	3.5	3.8	4.1	4.4	
		HSI clock, PLL on	48 MHz	220	240	248	252	244	263	275	278	
			32 MHz	174	191	196	198	193	209	215	218	
			24 MHz	152	167	173	174	168	183	190	192	
		HSI clock, PLL off	8 MHz	72	79	82	83	83.5	91	94	95	

1. Current consumption from the  $V_{DDA}$  supply is independent of whether the digital peripherals are enabled or disabled, being in Run or Sleep mode or executing from Flash memory or RAM. Furthermore, when the PLL is off,  $I_{DDA}$  is independent of clock frequencies.

2. Data based on characterization results, not tested in production unless otherwise specified.

3. Data based on characterization results and tested in production (using one common test limit for sum of  $I_{DD}$  and  $I_{DDA}$ ).

## High-speed internal (HSI) RC oscillator

Table 37. HSI oscillator characteristics<sup>(1)</sup>

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{\text{HSI}}$	Frequency	-	-	8	-	MHz
TRIM	HSI user trimming step	-	-	-	1 <sup>(2)</sup>	%
DuCy <sub>(HSI)</sub>	Duty cycle	-	45 <sup>(2)</sup>	-	55 <sup>(2)</sup>	%
ACC <sub>HSI</sub>	Accuracy of the HSI oscillator	$T_A = -40$ to $105^\circ\text{C}$	-2.8 <sup>(3)</sup>	-	3.8 <sup>(3)</sup>	%
		$T_A = -10$ to $85^\circ\text{C}$	-1.9 <sup>(3)</sup>	-	2.3 <sup>(3)</sup>	
		$T_A = 0$ to $85^\circ\text{C}$	-1.9 <sup>(3)</sup>	-	2 <sup>(3)</sup>	
		$T_A = 0$ to $70^\circ\text{C}$	-1.3 <sup>(3)</sup>	-	2 <sup>(3)</sup>	
		$T_A = 0$ to $55^\circ\text{C}$	-1 <sup>(3)</sup>	-	2 <sup>(3)</sup>	
		$T_A = 25^\circ\text{C}^{(4)}$	-1	-	1	
$t_{\text{su(HSI)}}$	HSI oscillator startup time	-	1 <sup>(2)</sup>	-	2 <sup>(2)</sup>	$\mu\text{s}$
$I_{\text{DDA(HSI)}}$	HSI oscillator power consumption	-	-	80	100 <sup>(2)</sup>	$\mu\text{A}$

1.  $V_{\text{DDA}} = 3.3\text{ V}$ ,  $T_A = -40$  to  $105^\circ\text{C}$  unless otherwise specified.
2. Guaranteed by design, not tested in production.
3. Data based on characterization results, not tested in production.
4. Factory calibrated, parts not soldered.

Figure 19. HSI oscillator accuracy characterization results for soldered parts

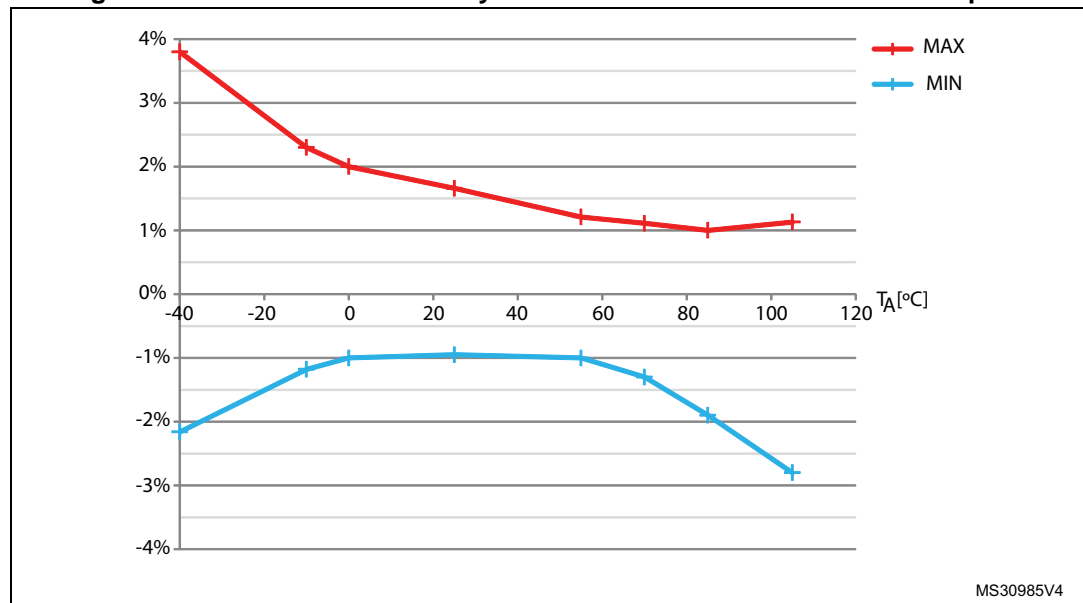


Table 45. ESD absolute maximum ratings

Symbol	Ratings	Conditions	Packages	Class	Maximum value <sup>(1)</sup>	Unit
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	$T_A = +25\text{ }^{\circ}\text{C}$ , conforming to JESD22-A114	All	2	2000	V
$V_{ESD(CDM)}$	Electrostatic discharge voltage (charge device model)	$T_A = +25\text{ }^{\circ}\text{C}$ , conforming to ANSI/ESD STM5.3.1	All	C3	250	V

1. Data based on characterization results, not tested in production.

### Static latch-up

Two complementary static tests are required on six parts to assess the latch-up performance:

- A supply overvoltage is applied to each power supply pin.
- A current injection is applied to each input, output and configurable I/O pin.

These tests are compliant with EIA/JESD 78A IC latch-up standard.

Table 46. Electrical sensitivities

Symbol	Parameter	Conditions	Class
LU	Static latch-up class	$T_A = +105\text{ }^{\circ}\text{C}$ conforming to JESD78A	II level A

### 6.3.13 I/O current injection characteristics

As a general rule, current injection to the I/O pins, due to external voltage below  $V_{SS}$  or above  $V_{DDIOx}$  (for standard, 3.3 V-capable I/O pins) should be avoided during normal product operation. However, in order to give an indication of the robustness of the microcontroller in cases when abnormal injection accidentally happens, susceptibility tests are performed on a sample basis during device characterization.

#### Functional susceptibility to I/O current injection

While a simple application is executed on the device, the device is stressed by injecting current into the I/O pins programmed in floating input mode. While current is injected into the I/O pin, one at a time, the device is checked for functional failures.

The failure is indicated by an out of range parameter: ADC error above a certain limit (higher than 5 LSB TUE), out of conventional limits of induced leakage current on adjacent pins (out of the  $-5\text{ }\mu\text{A}/+0\text{ }\mu\text{A}$  range) or other functional failure (for example reset occurrence or oscillator frequency deviation).

The characterization results are given in [Table 47](#).

Negative induced leakage current is caused by negative injection and positive induced leakage current is caused by positive injection.

Table 47. I/O current injection susceptibility

Symbol	Description	Functional susceptibility		Unit
		Negative injection	Positive injection	
$I_{INJ}$	Injected current on BOOT0	–0	NA	mA
	Injected current on PA10, PA12, PB4, PB5, PB10, PB15 and PD2 pins with induced leakage current on adjacent pins less than –10 $\mu$ A	–5	NA	
	Injected current on all other FT and FTf pins	–5	NA	
	Injected current on PA6 and PC0	–0	+5	
	Injected current on all other TTa, TC and RST pins	–5	+5	

### 6.3.14 I/O port characteristics

#### General input/output characteristics

Unless otherwise specified, the parameters given in [Table 48](#) are derived from tests performed under the conditions summarized in [Table 20: General operating conditions](#). All I/Os are designed as CMOS- and TTL-compliant (except BOOT0).

Table 48. I/O static characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IL}$	Low level input voltage	TC and TTa I/O	-	-	$0.3 V_{DDIOx} + 0.07^{(1)}$	V
		FT and FTf I/O	-	-	$0.475 V_{DDIOx} - 0.2^{(1)}$	
		BOOT0	-	-	$0.3 V_{DDIOx} - 0.3^{(1)}$	
		All I/Os except BOOT0 pin	-	-	$0.3 V_{DDIOx}$	
$V_{IH}$	High level input voltage	TC and TTa I/O	$0.445 V_{DDIOx} + 0.398^{(1)}$	-	-	V
		FT and FTf I/O	$0.5 V_{DDIOx} + 0.2^{(1)}$	-	-	
		BOOT0	$0.2 V_{DDIOx} + 0.95^{(1)}$	-	-	
		All I/Os except BOOT0 pin	$0.7 V_{DDIOx}$	-	-	
$V_{hys}$	Schmitt trigger hysteresis	TC and TTa I/O	-	$200^{(1)}$	-	mV
		FT and FTf I/O	-	$100^{(1)}$	-	
		BOOT0	-	$300^{(1)}$	-	

### Output driving current

The GPIOs (general purpose input/outputs) can sink or source up to  $\pm 8$  mA, and sink or source up to  $\pm 20$  mA (with a relaxed  $V_{OL}/V_{OH}$ ).

In the user application, the number of I/O pins which can drive current must be limited to respect the absolute maximum rating specified in [Section 6.2](#):

- The sum of the currents sourced by all the I/Os on  $V_{DDIOx}$ , plus the maximum consumption of the MCU sourced on  $V_{DD}$ , cannot exceed the absolute maximum rating  $\Sigma I_{VDD}$  (see [Table 17: Voltage characteristics](#)).
- The sum of the currents sunk by all the I/Os on  $V_{SS}$ , plus the maximum consumption of the MCU sunk on  $V_{SS}$ , cannot exceed the absolute maximum rating  $\Sigma I_{VSS}$  (see [Table 17: Voltage characteristics](#)).

### Output voltage levels

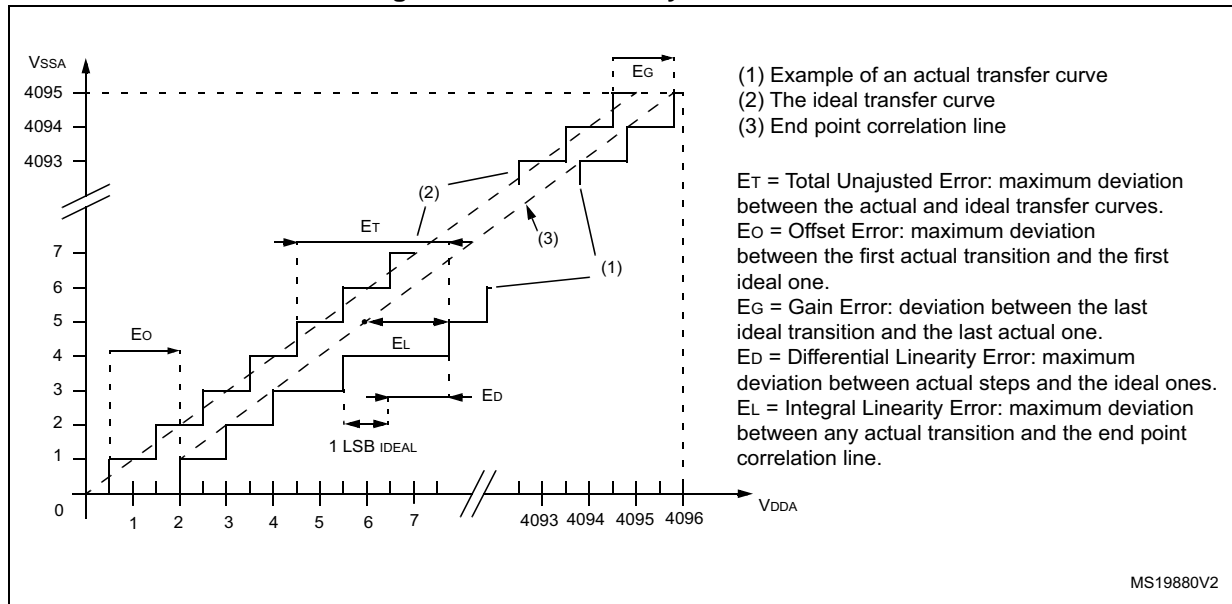
Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature and supply voltage conditions summarized in [Table 20: General operating conditions](#). All I/Os are CMOS- and TTL-compliant (FT, TTa or TC unless otherwise specified).

**Table 49. Output voltage characteristics<sup>(1)</sup>**

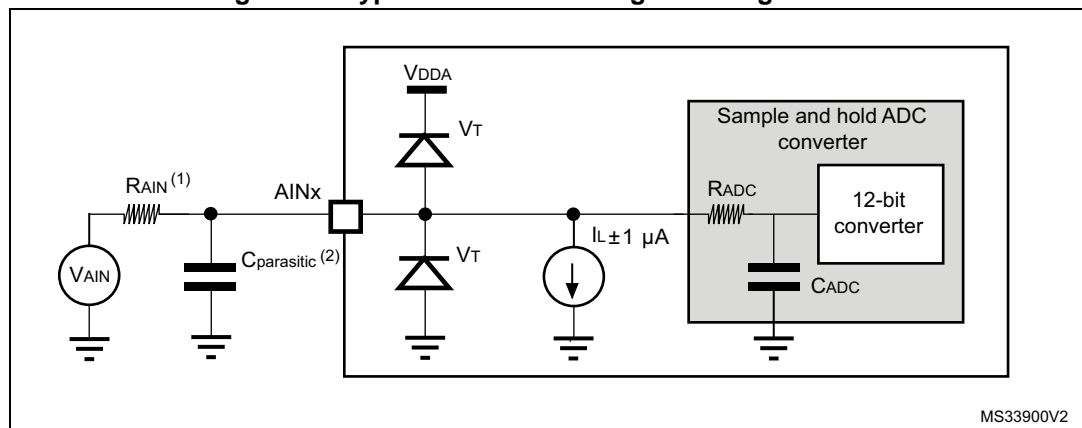
Symbol	Parameter	Conditions	Min	Max	Unit
$V_{OL}$	Output low level voltage for an I/O pin	CMOS port <sup>(2)</sup> $ I_{IO}  = 8$ mA $V_{DDIOx} \geq 2.7$ V	-	0.4	V
$V_{OH}$	Output high level voltage for an I/O pin		$V_{DDIOx} - 0.4$	-	
$V_{OL}$	Output low level voltage for an I/O pin	TTL port <sup>(2)</sup> $ I_{IO}  = 8$ mA $V_{DDIOx} \geq 2.7$ V	-	0.4	V
$V_{OH}$	Output high level voltage for an I/O pin		2.4	-	
$V_{OL}^{(3)}$	Output low level voltage for an I/O pin	$ I_{IO}  = 20$ mA $V_{DDIOx} \geq 2.7$ V	-	1.3	V
$V_{OH}^{(3)}$	Output high level voltage for an I/O pin		$V_{DDIOx} - 1.3$	-	
$V_{OL}^{(3)}$	Output low level voltage for an I/O pin	$ I_{IO}  = 6$ mA	-	0.4	V
$V_{OH}^{(3)}$	Output high level voltage for an I/O pin		$V_{DDIOx} - 0.4$	-	
$V_{OLFm+}^{(3)}$	Output low level voltage for an FTf I/O pin in Fm+ mode	$ I_{IO}  = 20$ mA $V_{DDIOx} \geq 2.7$ V	-	0.4	V
		$ I_{IO}  = 10$ mA	-	0.4	V

1. The  $I_{IO}$  current sourced or sunk by the device must always respect the absolute maximum rating specified in [Table 17: Voltage characteristics](#), and the sum of the currents sourced or sunk by all the I/Os (I/O ports and control pins) must always respect the absolute maximum ratings  $\Sigma I_{IO}$ .
2. TTL and CMOS outputs are compatible with JEDEC standards JESD36 and JESD52.
3. Data based on characterization results. Not tested in production.

### Figure 25. ADC accuracy characteristics



**Figure 26. Typical connection diagram using the ADC**



1. Refer to [Table 52: ADC characteristics](#) for the values of  $R_{AIN}$ ,  $R_{ADC}$  and  $C_{ADC}$ .
2.  $C_{parasitic}$  represents the capacitance of the PCB (dependent on soldering and PCB layout quality) plus the pad capacitance (roughly 7 pF). A high  $C_{parasitic}$  value will downgrade conversion accuracy. To remedy this,  $f_{ADC}$  should be reduced.

## General PCB design guidelines

Power supply decoupling should be performed as shown in [Figure 13: Power supply scheme](#). The 10 nF capacitor should be ceramic (good quality) and it should be placed as close as possible to the chip.

Table 56. Comparator characteristics (continued)

Symbol	Parameter	Conditions	Min <sup>(1)</sup>	Typ	Max <sup>(1)</sup>	Unit
$V_{\text{hys}}$	Comparator hysteresis	No hysteresis (COMPxHYST[1:0]=00)	-	0	-	mV
		Low hysteresis (COMPxHYST[1:0]=01)	High speed mode	8	13	
			All other power modes		10	
		Medium hysteresis (COMPxHYST[1:0]=10)	High speed mode	15	26	
			All other power modes		19	
		High hysteresis (COMPxHYST[1:0]=11)	High speed mode	31	49	
			All other power modes		40	

1. Data based on characterization results, not tested in production.

2. For more details and conditions see [Figure 28: Maximum  \$V\_{\text{REFINT}}\$  scaler startup time from power down](#).

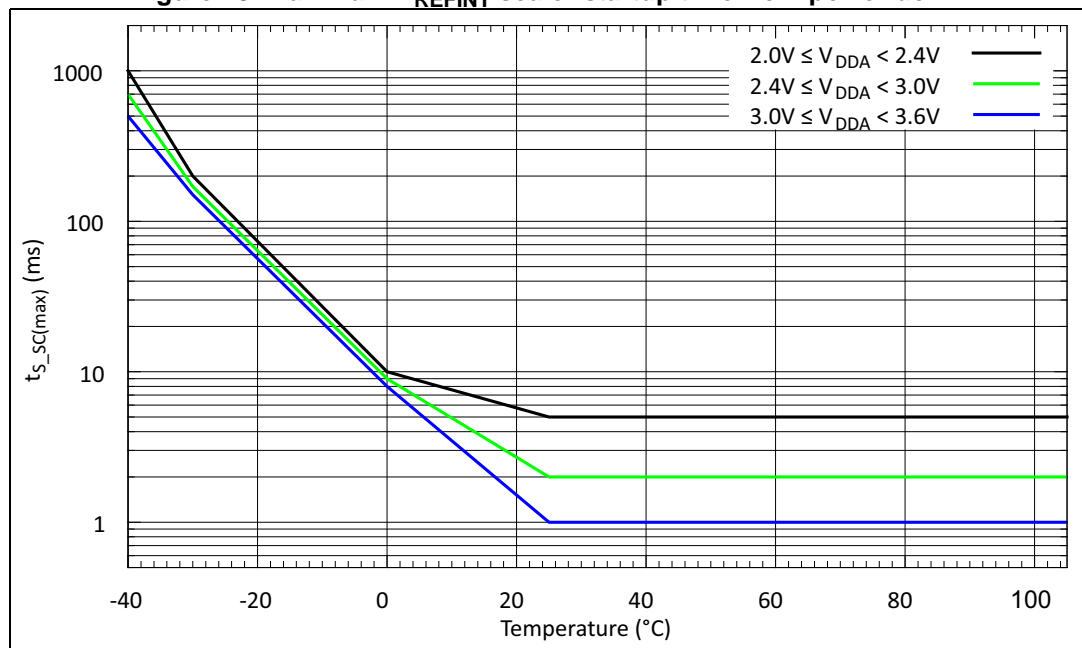
Figure 28. Maximum  $V_{\text{REFINT}}$  scaler startup time from power down

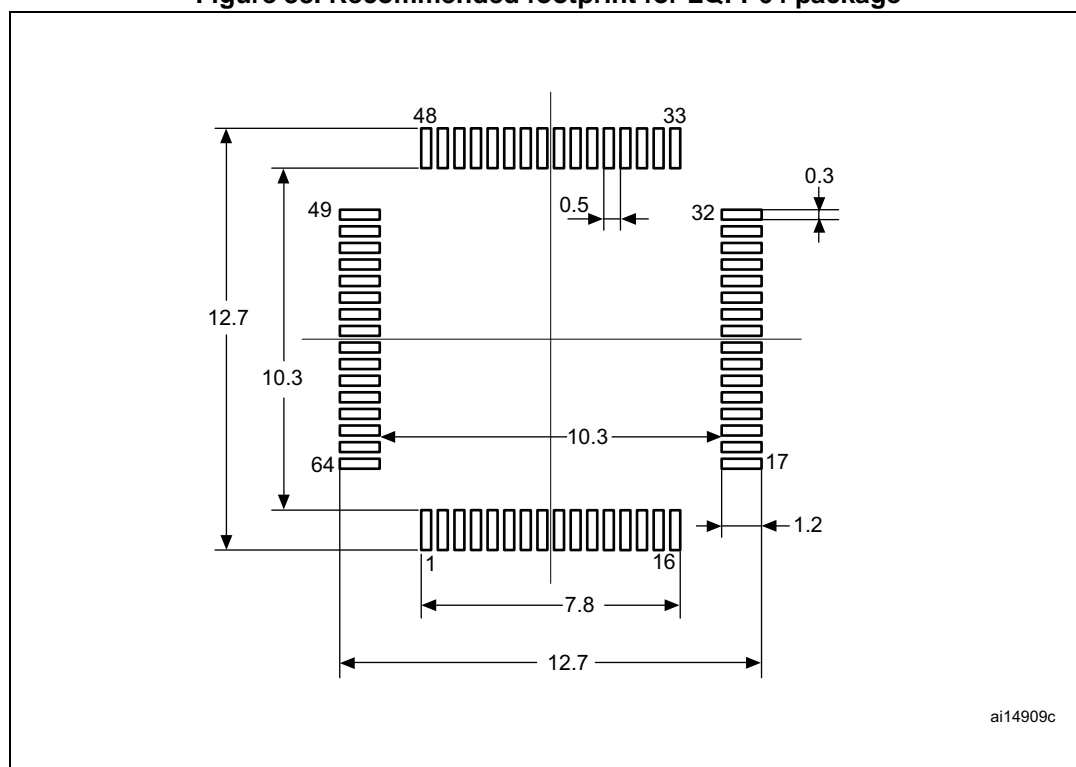


Table 67. LQFP64 package mechanical data (continued)

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
E3	-	7.500	-	-	0.2953	-
e	-	0.500	-	-	0.0197	-
K	0°	3.5°	7°	0°	3.5°	7°
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
ccc	-	-	0.080	-	-	0.0031

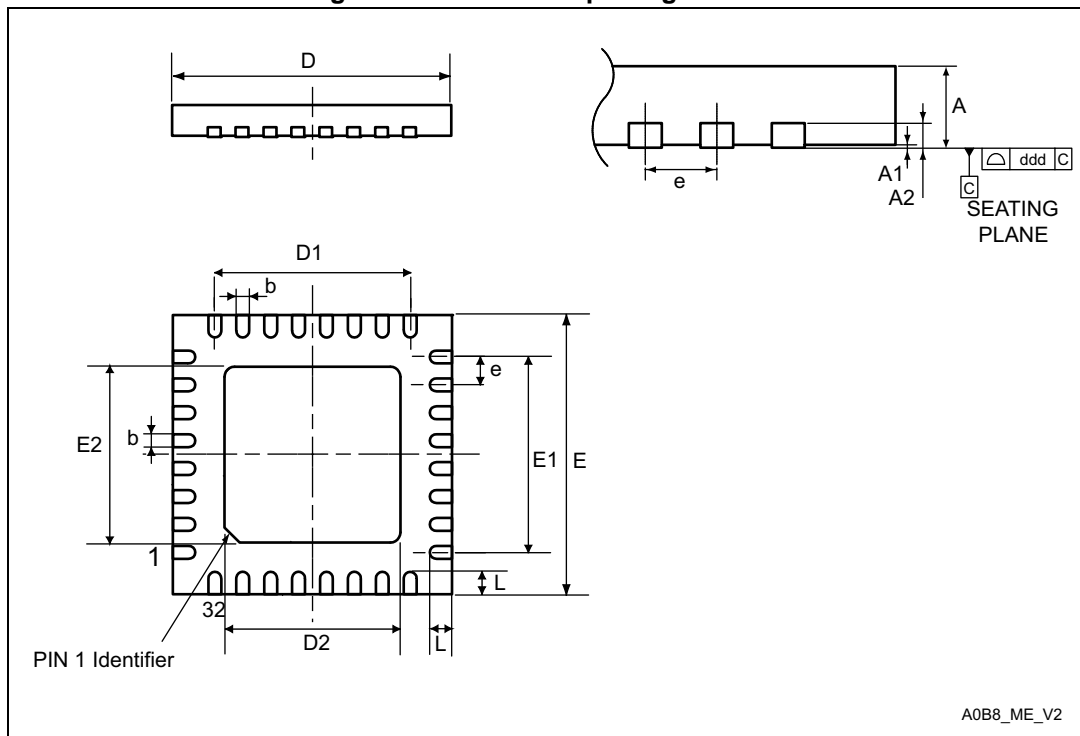
1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 38. Recommended footprint for LQFP64 package



1. Dimensions are expressed in millimeters.

Figure 52. UFQFPN32 package outline



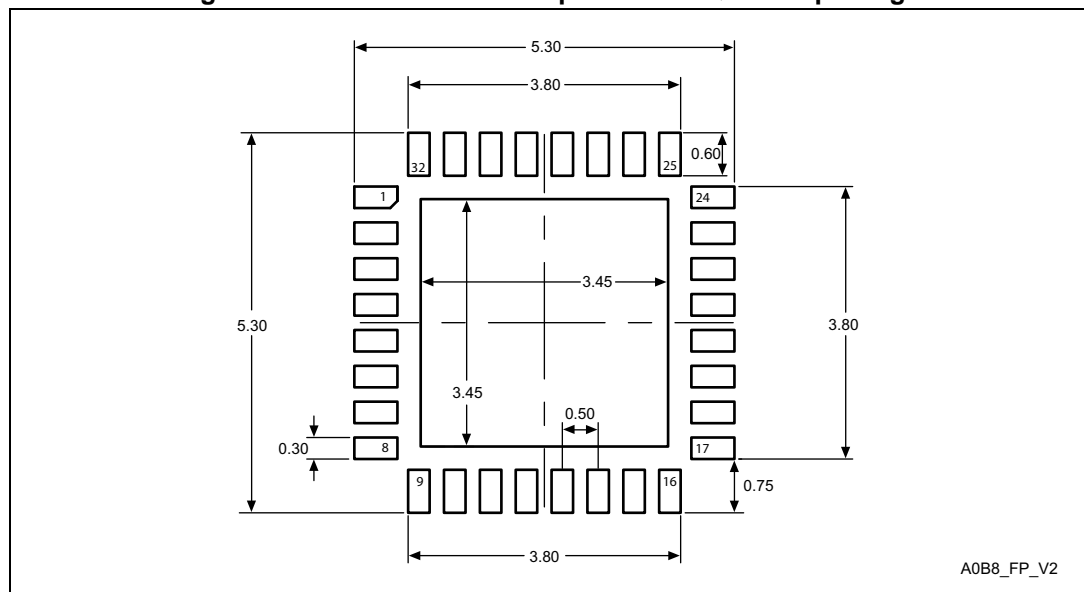
1. Drawing is not to scale.
2. All leads/pads should also be soldered to the PCB to improve the lead/pad solder joint life.
3. There is an exposed die pad on the underside of the UFQFPN package. This pad is used for the device ground and must be connected. It is referred to as pin 0 in *Table: Pin definitions*.

Table 73. UFQFPN32 package mechanical data

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	0.500	0.550	0.600	0.0197	0.0217	0.0236
A1	0.000	0.020	0.050	0.0000	0.0008	0.0020
A3	-	0.152	-	-	0.0060	-
b	0.180	0.230	0.280	0.0071	0.0091	0.0110
D	4.900	5.000	5.100	0.1929	0.1969	0.2008
D1	3.400	3.500	3.600	0.1339	0.1378	0.1417
D2	3.400	3.500	3.600	0.1339	0.1378	0.1417
E	4.900	5.000	5.100	0.1929	0.1969	0.2008
E1	3.400	3.500	3.600	0.1339	0.1378	0.1417
E2	3.400	3.500	3.600	0.1339	0.1378	0.1417
e	-	0.500	-	-	0.0197	-
L	0.300	0.400	0.500	0.0118	0.0157	0.0197
ddd	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 53. Recommended footprint for UFQFPN32 package



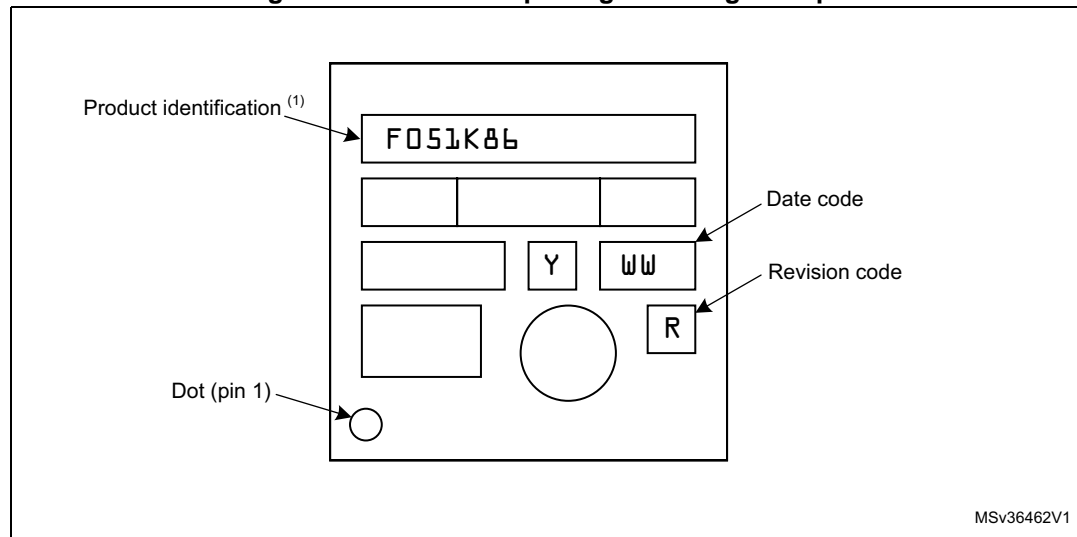
1. Dimensions are expressed in millimeters.

## Device marking

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Other optional marking or inset/upset marks, which identify the parts throughout supply chain operations, are not indicated below.

**Figure 54. UFQFPN32 package marking example**



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

Table 76. Document revision history (continued)

Date	Revision	Changes
06-Jan-2017	7	<p><b>Section 6: Electrical characteristics:</b></p> <ul style="list-style-type: none"> <li>– <i>Table 36: LSE oscillator characteristics (<math>f_{LSE} = 32.768</math> kHz)</i> - information on configuring different drive capabilities removed. See the corresponding reference manual.</li> <li>– <i>Table 24: Embedded internal reference voltage</i> - <math>V_{REFINT}</math> values</li> <li>– <i>Table 55: DAC characteristics</i> - min. <math>R_{LOAD}</math> to <math>V_{DDA}</math> defined</li> <li>– <i>Figure 29: SPI timing diagram - slave mode and CPHA = 0</i> and <i>Figure 30: SPI timing diagram - slave mode and CPHA = 1</i> enhanced and corrected</li> </ul> <p><b>Section 8: Ordering information:</b></p> <ul style="list-style-type: none"> <li>– The name of the section changed from the previous “Part numbering”</li> </ul>