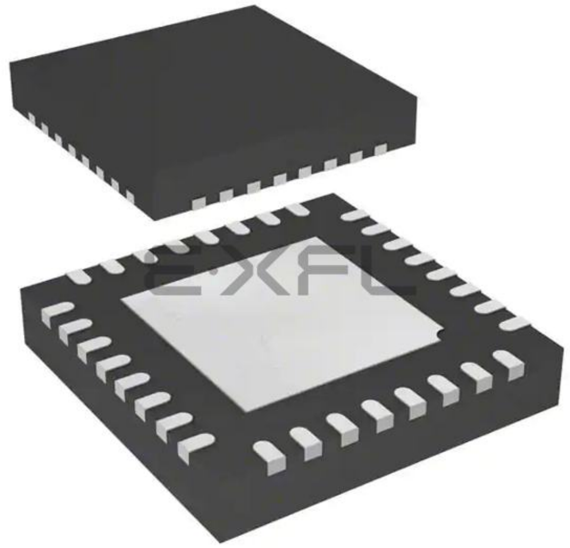

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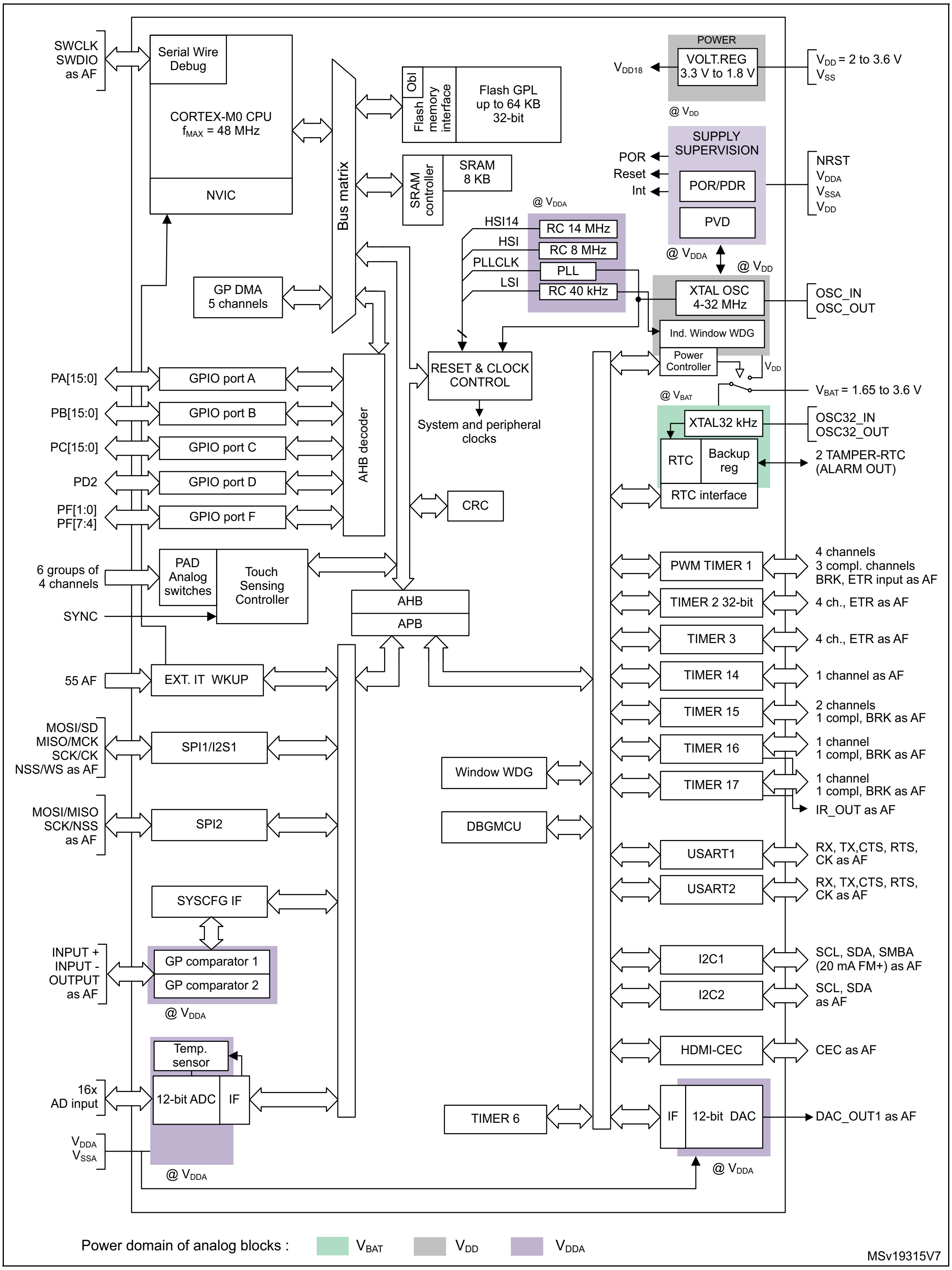
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	HDMI-CEC, I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	DMA, I²S, POR, PWM, WDT
Number of I/O	27
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 13x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	32-UFQFN Exposed Pad
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f051k4u7tr

Figure 1. Block diagram



3.4 Cyclic redundancy check calculation unit (CRC)

The CRC (cyclic redundancy check) calculation unit is used to get a CRC code from a 32-bit data word and a CRC-32 (Ethernet) polynomial.

Among other applications, CRC-based techniques are used to verify data transmission or storage integrity. In the scope of the EN/IEC 60335-1 standard, they offer a means of verifying the Flash memory integrity. The CRC calculation unit helps compute a signature of the software during runtime, to be compared with a reference signature generated at link-time and stored at a given memory location.

3.5 Power management

3.5.1 Power supply schemes

- $V_{DD} = V_{DDIO1}$ = 2.0 to 3.6 V: external power supply for I/Os (V_{DDIO1}) and the internal regulator. It is provided externally through VDD pins.
- V_{DDA} = from V_{DD} to 3.6 V: external analog power supply for ADC, DAC, Reset blocks, RCs and PLL (minimum voltage to be applied to V_{DDA} is 2.4 V when the ADC or DAC are used). It is provided externally through VDDA pin. The V_{DDA} voltage level must be always greater or equal to the V_{DD} voltage level and must be established first.
- V_{BAT} = 1.65 to 3.6 V: power supply for RTC, external clock 32 kHz oscillator and backup registers (through power switch) when V_{DD} is not present.

For more details on how to connect power pins, refer to *Figure 13: Power supply scheme*.

3.5.2 Power supply supervisors

The device has integrated power-on reset (POR) and power-down reset (PDR) circuits. They are always active, and ensure proper operation above a threshold of 2 V. The device remains in reset mode when the monitored supply voltage is below a specified threshold, $V_{POR/PDR}$, without the need for an external reset circuit.

- The POR monitors only the V_{DD} supply voltage. During the startup phase it is required that V_{DDA} should arrive first and be greater than or equal to V_{DD}.
- The PDR monitors both the V_{DD} and V_{DDA} supply voltages, however the V_{DDA} power supply supervisor can be disabled (by programming a dedicated Option bit) to reduce the power consumption if the application design ensures that V_{DDA} is higher than or equal to V_{DD}.

The device features an embedded programmable voltage detector (PVD) that monitors the V_{DD} power supply and compares it to the V_{PVD} threshold. An interrupt can be generated when V_{DD} drops below the V_{PVD} threshold and/or when V_{DD} is higher than the V_{PVD} threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

3.5.3 Voltage regulator

The regulator has two operating modes and it is always enabled after reset.

- Main (MR) is used in normal operating mode (Run).
- Low power (LPR) can be used in Stop mode where the power demand is reduced.

Figure 4. UFBGA64 package pinout

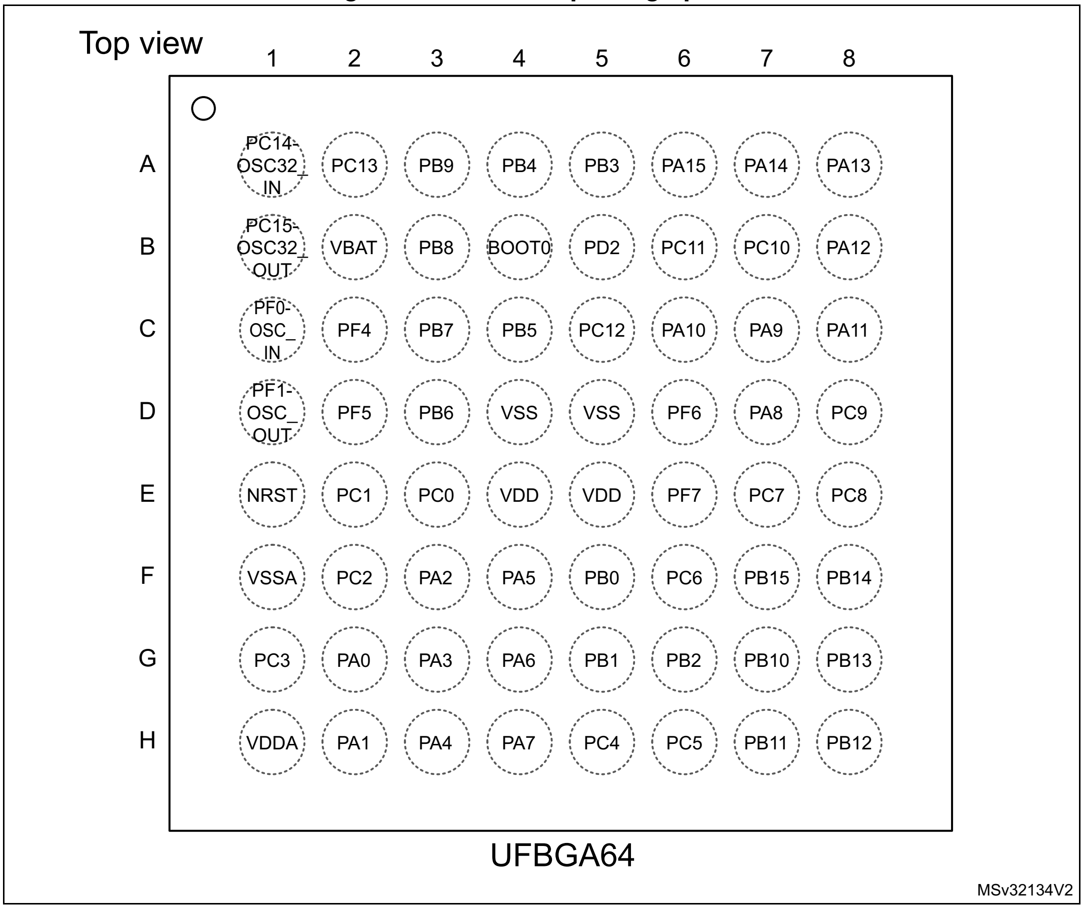


Figure 5. LQFP48 package pinout

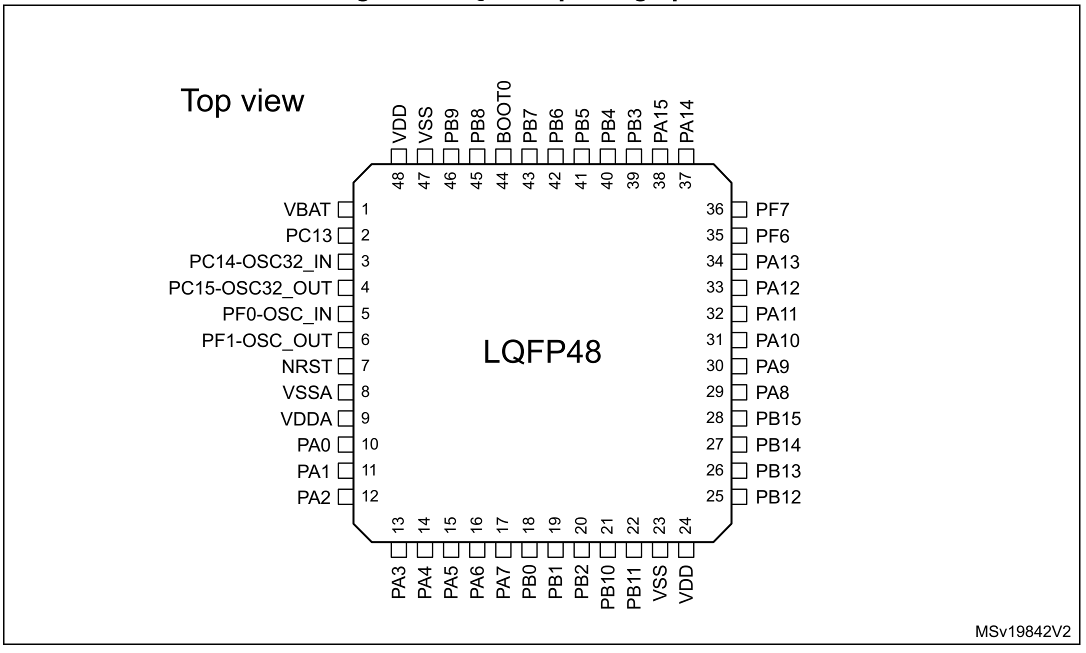


Table 12. Legend/abbreviations used in the pinout table

Name		Abbreviation	Definition
Pin name		Unless otherwise specified in brackets below the pin name, the pin function during and after reset is the same as the actual pin name	
Pin type		S	Supply pin
		I	Input-only pin
		I/O	Input / output pin
I/O structure		FT	5 V-tolerant I/O
		FTf	5 V-tolerant I/O, FM+ capable
		TTa	3.3 V-tolerant I/O directly connected to ADC
		TC	Standard 3.3 V I/O
		B	Dedicated BOOT0 pin
		RST	Bidirectional reset pin with embedded weak pull-up resistor
Notes		Unless otherwise specified by a note, all I/Os are set as floating inputs during and after reset.	
Pin functions	Alternate functions	Functions selected through GPIOx_AFR registers	
	Additional functions	Functions directly selected/enabled through peripheral registers	

Table 13. Pin definitions

Pin number						Pin name (function upon reset)	Pin type	I/O structure	Notes	Pin functions	
LQFP64	UFBGA64	LQFP48/UFQFPN48	WLCSP36	LQFP32	UFQFPN32					Alternate functions	Additional functions
1	B2	1	-	-	-	VBAT	S	-	-	Backup power supply	
2	A2	2	A6	-	-	PC13	I/O	TC	(1)(2)	-	RTC_TAMP1, RTC_TS, RTC_OUT, WKUP2
3	A1	3	B6	-	-	PC14-OSC32_IN (PC14)	I/O	TC	(1)(2)	-	OSC32_IN
4	B1	4	C6	-	-	PC15-OSC32_OUT (PC15)	I/O	TC	(1)(2)	-	OSC32_OUT
5	C1	5	B5	2	2	PF0-OSC_IN (PF0)	I/O	FT	-	-	OSC_IN
6	D1	6	C5	3	3	PF1-OSC_OUT (PF1)	I/O	FT	-	-	OSC_OUT

Table 13. Pin definitions (continued)

Pin number						Pin name (function upon reset)	Pin type	I/O structure	Notes	Pin functions	
LQFP64	UFBGA64	LQFP48/UFQFPN48	WLCSP36	LQFP32	UFQFPN32					Alternate functions	Additional functions
33	H8	25	-	-	-	PB12	I/O	FT	(5)	SPI2_NSS, TIM1_BKIN, TSC_G6_IO2, EVENTOUT	-
34	G8	26	-	-	-	PB13	I/O	FT	(5)	SPI2_SCK, TIM1_CH1N, TSC_G6_IO3	-
35	F8	27	-	-	-	PB14	I/O	FT	(5)	SPI2_MISO, TIM1_CH2N, TIM15_CH1, TSC_G6_IO4	-
36	F7	28	-	-	-	PB15	I/O	FT	(5)	SPI2_MOSI, TIM1_CH3N, TIM15_CH1N, TIM15_CH2	RTC_REFIN
37	F6	-	-	-	-	PC6	I/O	FT	-	TIM3_CH1	-
38	E7	-	-	-	-	PC7	I/O	FT	-	TIM3_CH2	-
39	E8	-	-	-	-	PC8	I/O	FT	-	TIM3_CH3	-
40	D8	-	-	-	-	PC9	I/O	FT	-	TIM3_CH4	-
41	D7	29	E2	18	18	PA8	I/O	FT	-	USART1_CK, TIM1_CH1, EVENTOUT, MCO	-
42	C7	30	D1	19	19	PA9	I/O	FT	-	USART1_TX, TIM1_CH2, TIM15_BKIN, TSC_G4_IO1	-
43	C6	31	C1	20	20	PA10	I/O	FT	-	USART1_RX, TIM1_CH3, TIM17_BKIN, TSC_G4_IO2	-
44	C8	32	C2	21	21	PA11	I/O	FT	-	USART1_CTS, TIM1_CH4, COMP1_OUT, TSC_G4_IO3, EVENTOUT	-

Table 14. Alternate functions selected through GPIOA_AFR registers for port A

Pin name	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
PA0	-	USART2_CTS	TIM2_CH1_ETR	TSC_G1_IO1		-	-	COMP1_OUT
PA1	EVENTOUT	USART2_RTS	TIM2_CH2	TSC_G1_IO2			-	-
PA2	TIM15_CH1	USART2_TX	TIM2_CH3	TSC_G1_IO3	-	-	-	COMP2_OUT
PA3	TIM15_CH2	USART2_RX	TIM2_CH4	TSC_G1_IO4	-	-	-	-
PA4	SPI1_NSS, I2S1_WS	USART2_CK	-	TSC_G2_IO1	TIM14_CH1	-	-	-
PA5	SPI1_SCK, I2S1_CK	CEC	TIM2_CH1_ETR	TSC_G2_IO2	-	-	-	-
PA6	SPI1_MISO, I2S1_MCK	TIM3_CH1	TIM1_BKIN	TSC_G2_IO3		TIM16_CH1	EVENTOUT	COMP1_OUT
PA7	SPI1_MOSI, I2S1_SD	TIM3_CH2	TIM1_CH1N	TSC_G2_IO4	TIM14_CH1	TIM17_CH1	EVENTOUT	COMP2_OUT
PA8	MCO	USART1_CK	TIM1_CH1	EVENTOUT		-	-	-
PA9	TIM15_BKIN	USART1_TX	TIM1_CH2	TSC_G4_IO1	-	-	-	-
PA10	TIM17_BKIN	USART1_RX	TIM1_CH3	TSC_G4_IO2	-	-	-	-
PA11	EVENTOUT	USART1_CTS	TIM1_CH4	TSC_G4_IO3	-	-	-	COMP1_OUT
PA12	EVENTOUT	USART1_RTS	TIM1_ETR	TSC_G4_IO4	-	-	-	COMP2_OUT
PA13	SWDIO	IR_OUT		-	-	-	-	-
PA14	SWCLK	USART2_TX	-	-	-	-	-	-
PA15	SPI1_NSS, I2S1_WS	USART2_RX	TIM2_CH1_ETR	EVENTOUT		-	-	-

6.1.7 Current consumption measurement

Figure 14. Current consumption measurement scheme

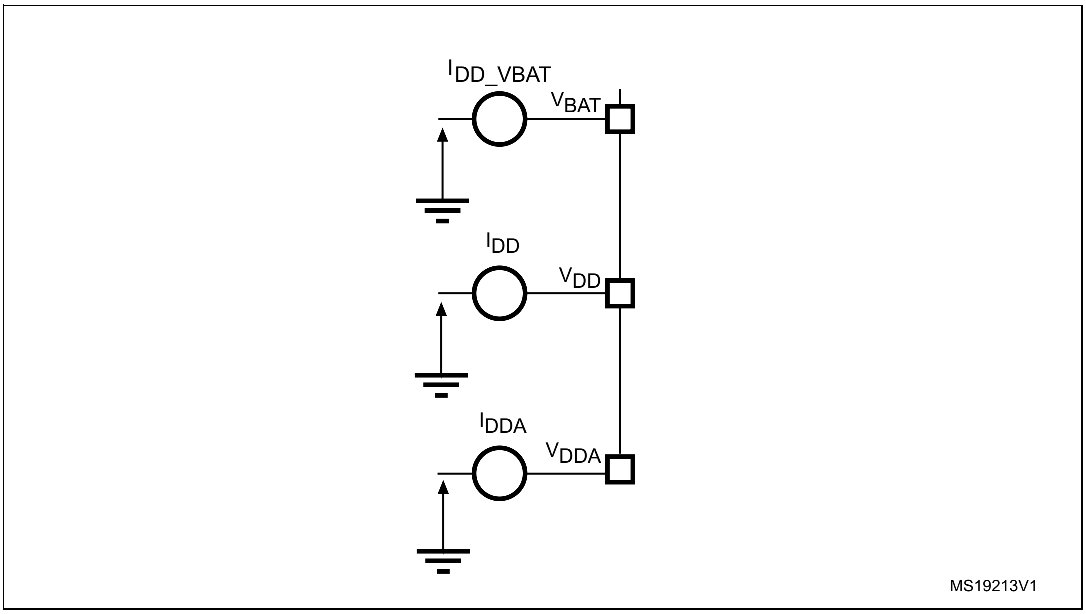


Table 30. Switching output I/O current consumption

Symbol	Parameter	Conditions[(1)]	I/O toggling frequency (f_{SW})	Typ	Unit
I_{SW}	I/O current consumption	V_{DDIOx} = 3.3 V C = C_{INT}	4 MHz	0.07	mA
			8 MHz	0.15	
			16 MHz	0.31	
			24 MHz	0.53	
			48 MHz	0.92	
		V_{DDIOx} = 3.3 V C_{EXT} = 0 pF C = C_{INT} + C_{EXT}+ C_S	4 MHz	0.18	
			8 MHz	0.37	
			16 MHz	0.76	
			24 MHz	1.39	
			48 MHz	2.188	
		V_{DDIOx} = 3.3 V C_{EXT} = 10 pF C = C_{INT} + C_{EXT}+ C_S	4 MHz	0.32	
			8 MHz	0.64	
			16 MHz	1.25	
			24 MHz	2.23	
			48 MHz	4.442	
		V_{DDIOx} = 3.3 V C_{EXT} = 22 pF C = C_{INT} + C_{EXT}+ C_S	4 MHz	0.49	
			8 MHz	0.94	
			16 MHz	2.38	
			24 MHz	3.99	
		V_{DDIOx} = 3.3 V C_{EXT} = 33 pF C = C_{INT} + C_{EXT}+ C_S	4 MHz	0.64	
			8 MHz	1.25	
			16 MHz	3.24	
			24 MHz	5.02	
		V_{DDIOx} = 3.3 V C_{EXT} = 47 pF C = C_{INT} + C_{EXT}+ C_S C = C_{int}	4 MHz	0.81	
			8 MHz	1.7	
			16 MHz	3.67	
		V_{DDIOx} = 2.4 V C_{EXT} = 47 pF C = C_{INT} + C_{EXT}+ C_S C = C_{int}	4 MHz	0.66	
			8 MHz	1.43	
			16 MHz	2.45	
			24 MHz	4.97	

1. C_S = 7 pF (estimated value).

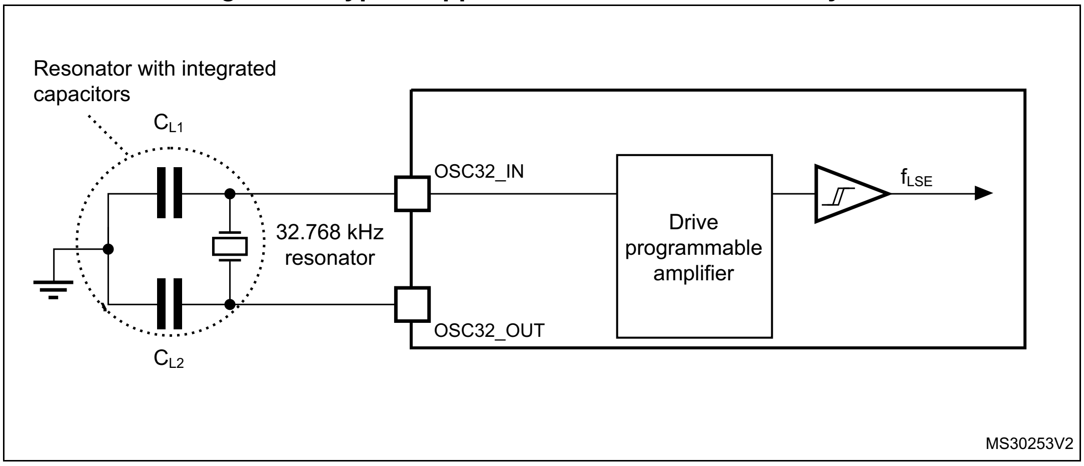
Table 31. Peripheral current consumption (continued)

Peripheral		Typical consumption at 25 °C	Unit
APB	APB-Bridge[(2)]	3	µA/MHz
	SYSCFG	3	
	ADC[(3)]	5	
	TIM1	17	
	SPI1	10	
	USART1	19	
	TIM15	11	
	TIM16	8	
	TIM17	8	
	DBG (MCU Debug Support)	0.5	
	TIM2	17	
	TIM3	13	
	TIM6	3	
	TIM14	6	
	WWDG	1	
	SPI2	7	
	USART2	7	
	I2C1	4	
	I2C2	5	
	DAC	2	
	PWR	1	
	CEC	2	
	All APB peripherals	**149**	

1. The BusMatrix automatically is active when at least one master is ON (CPU or DMA1)
2. The APBx Bridge is automatically active when at least one peripheral is ON on the same Bus.
3. The power consumption of the analog part (I_{DDA}) of peripherals such as ADC is not included. Refer to the tables of characteristics in the subsequent sections.

Note: For information on selecting the crystal, refer to the application note AN2867 "Oscillator design guide for ST microcontrollers" available from the ST website www.st.com.

Figure 18. Typical application with a 32.768 kHz crystal



Note: An external resistor is not required between OSC32_IN and OSC32_OUT and it is forbidden to add one.

6.3.8 Internal clock source characteristics

The parameters given in *Table 37* are derived from tests performed under ambient temperature and supply voltage conditions summarized in *Table 20: General operating conditions*. The provided curves are characterization results, not tested in production.

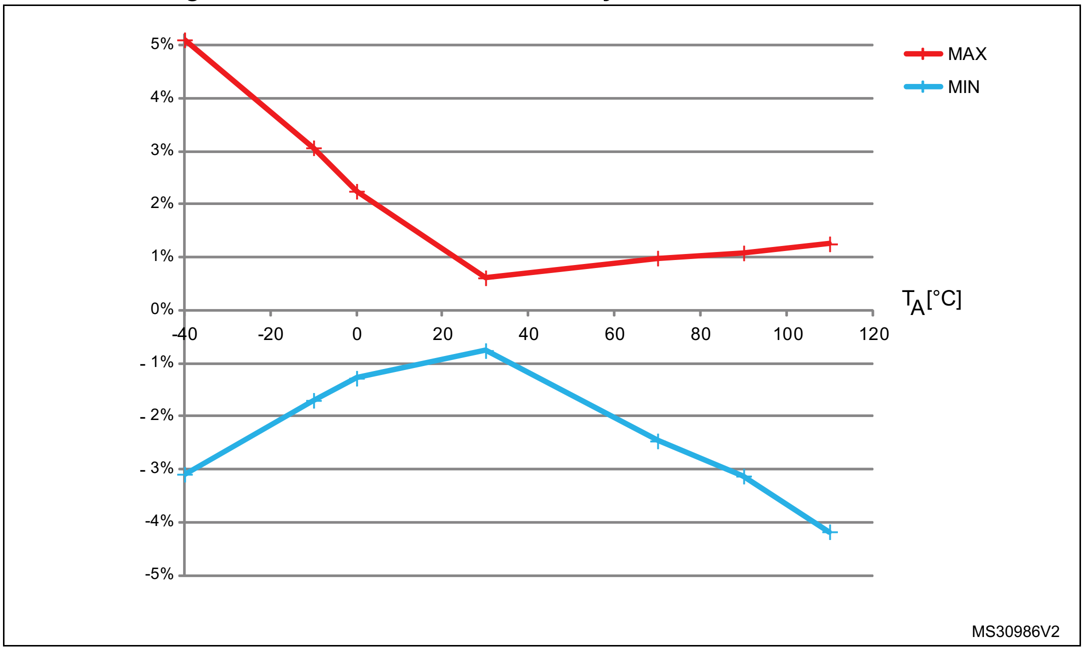
High-speed internal 14 MHz (HSI14) RC oscillator (dedicated to ADC)

Table 38. HSI14 oscillator characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI14}	Frequency	-	-	14	-	MHz
TRIM	HSI14 user-trimming step	-	-	-	1(2)	%
$DuCy_{(HSI14)}$	Duty cycle	-	45(2)	-	55(2)	%
ACC_{HSI14}	Accuracy of the HSI14 oscillator (factory calibrated)	T_A = –40 to 105 °C	–4.2(3)	-	5.1(3)	%
		T_A = –10 to 85 °C	–3.2(3)	-	3.1(3)	%
		T_A = 0 to 70 °C	–2.5(3)	-	2.3(3)	%
		T_A = 25 °C	–1	-	1	%
$t_{su(HSI14)}$	HSI14 oscillator startup time	-	1(2)	-	2(2)	µs
$I_{DDA(HSI14)}$	HSI14 oscillator power consumption	-	-	100	150(2)	µA

1. V_{DDA} = 3.3 V, T_A = –40 to 105 °C unless otherwise specified.
2. Guaranteed by design, not tested in production.
3. Data based on characterization results, not tested in production.

Figure 20. HSI14 oscillator accuracy characterization results



Input/output AC characteristics

The definition and values of input/output AC characteristics are given in *Figure 23* and *Table 50*, respectively. Unless otherwise specified, the parameters given are derived from tests performed under the ambient temperature and supply voltage conditions summarized in *Table 20: General operating conditions*.

Table 50. I/O AC characteristics(1)(2)

<table>
<tr><th>OSPEEDRy [1:0] value(1)</th><th>Symbol</th><th>Parameter</th><th>Conditions</th><th>Min</th><th>Max</th><th>Unit</th></tr>
<tr><td rowspan="3">x0</td><td>$f_{max(IO)out}$</td><td>Maximum frequency(3)</td><td rowspan="3">C_L = 50 pF</td><td>-</td><td>2</td><td>MHz</td></tr>
<tr><td>$t_{f(IO)out}$</td><td>Output fall time</td><td>-</td><td>125</td><td rowspan="2">ns</td></tr>
<tr><td>$t_{r(IO)out}$</td><td>Output rise time</td><td>-</td><td>125</td></tr>
<tr><td rowspan="3">01</td><td>$f_{max(IO)out}$</td><td>Maximum frequency(3)</td><td rowspan="3">C_L = 50 pF</td><td>-</td><td>10</td><td>MHz</td></tr>
<tr><td>$t_{f(IO)out}$</td><td>Output fall time</td><td>-</td><td>25</td><td rowspan="2">ns</td></tr>
<tr><td>$t_{r(IO)out}$</td><td>Output rise time</td><td>-</td><td>25</td></tr>
<tr><td rowspan="9">11</td><td rowspan="3">$f_{max(IO)out}$</td><td rowspan="3">Maximum frequency(3)</td><td>C_L = 30 pF, $V_{DDIOx} \geq 2.7$ V</td><td>-</td><td>50</td><td rowspan="3">MHz</td></tr>
<tr><td>C_L = 50 pF, $V_{DDIOx} \geq 2.7$ V</td><td>-</td><td>30</td></tr>
<tr><td>C_L = 50 pF, $V_{DDIOx} < 2.7$ V</td><td>-</td><td>20</td></tr>
<tr><td rowspan="3">$t_{f(IO)out}$</td><td rowspan="3">Output fall time</td><td>C_L = 30 pF, $V_{DDIOx} \geq 2.7$ V</td><td>-</td><td>5</td><td rowspan="6">ns</td></tr>
<tr><td>C_L = 50 pF, $V_{DDIOx} \geq 2.7$ V</td><td>-</td><td>8</td></tr>
<tr><td>C_L = 50 pF, $V_{DDIOx} < 2.7$ V</td><td>-</td><td>12</td></tr>
<tr><td rowspan="3">$t_{r(IO)out}$</td><td rowspan="3">Output rise time</td><td>C_L = 30 pF, $V_{DDIOx} \geq 2.7$ V</td><td>-</td><td>5</td></tr>
<tr><td>C_L = 50 pF, $V_{DDIOx} \geq 2.7$ V</td><td>-</td><td>8</td></tr>
<tr><td>C_L = 50 pF, $V_{DDIOx} < 2.7$ V</td><td>-</td><td>12</td></tr>
<tr><td rowspan="3">Fm+ configuration (4)</td><td>$f_{max(IO)out}$</td><td>Maximum frequency(3)</td><td rowspan="3">C_L = 50 pF</td><td>-</td><td>2</td><td>MHz</td></tr>
<tr><td>$t_{f(IO)out}$</td><td>Output fall time</td><td>-</td><td>12</td><td rowspan="2">ns</td></tr>
<tr><td>$t_{r(IO)out}$</td><td>Output rise time</td><td>-</td><td>34</td></tr>
<tr><td>-</td><td>t_{EXTIpw}</td><td>Pulse width of external signals detected by the EXTI controller</td><td>-</td><td>10</td><td>-</td><td>ns</td></tr>
</table>

1. The I/O speed is configured using the OSPEEDRx[1:0] bits. Refer to the STM32F0xxxx RM0091 reference manual for a description of GPIO Port configuration register.
2. Guaranteed by design, not tested in production.
3. The maximum frequency is defined in *Figure 23*.
4. When Fm+ configuration is set, the I/O speed control is bypassed. Refer to the STM32F0xxxx reference manual RM0091 for a detailed description of Fm+ I/O configuration.

Table 53. R_{AIN} max for f_{ADC} = 14 MHz (continued)

T_S (cycles)	t_S (µs)	R_{AIN} max (kΩ)(1)
28.5	2.04	25.2
41.5	2.96	37.2
55.5	3.96	50
71.5	5.11	NA
239.5	17.1	NA

1. Guaranteed by design, not tested in production.

Table 54. ADC accuracy(1)(2)(3)

Symbol	Parameter	Test conditions	Typ	Max(4)	Unit
ET	Total unadjusted error	f_{PCLK} = 48 MHz, f_{ADC} = 14 MHz, R_{AIN} < 10 kΩ V_{DDA} = 3 V to 3.6 V T_A = 25 °C	±1.3	±2	LSB
EO	Offset error		±1	±1.5	
EG	Gain error		±0.5	±1.5	
ED	Differential linearity error		±0.7	±1	
EL	Integral linearity error		±0.8	±1.5	
ET	Total unadjusted error	f_{PCLK} = 48 MHz, f_{ADC} = 14 MHz, R_{AIN} < 10 kΩ V_{DDA} = 2.7 V to 3.6 V T_A = - 40 to 105 °C	±3.3	±4	LSB
EO	Offset error		±1.9	±2.8	
EG	Gain error		±2.8	±3	
ED	Differential linearity error		±0.7	±1.3	
EL	Integral linearity error		±1.2	±1.7	
ET	Total unadjusted error	f_{PCLK} = 48 MHz, f_{ADC} = 14 MHz, R_{AIN} < 10 kΩ V_{DDA} = 2.4 V to 3.6 V T_A = 25 °C	±3.3	±4	LSB
EO	Offset error		±1.9	±2.8	
EG	Gain error		±2.8	±3	
ED	Differential linearity error		±0.7	±1.3	
EL	Integral linearity error		±1.2	±1.7	

1. ADC DC accuracy values are measured after internal calibration.
2. ADC Accuracy vs. Negative Injection Current: Injecting negative current on any of the standard (non-robust) analog input pins should be avoided as this significantly reduces the accuracy of the conversion being performed on another analog input. It is recommended to add a Schottky diode (pin to ground) to standard analog pins which may potentially inject negative current.
Any positive injection current within the limits specified for $I_{INJ(PIN)}$ and $\Sigma I_{INJ(PIN)}$ in *Section 6.3.14* does not affect the ADC accuracy.
3. Better performance may be achieved in restricted V_{DDA}, frequency and temperature ranges.
4. Data based on characterization results, not tested in production.

6.3.18 Comparator characteristics

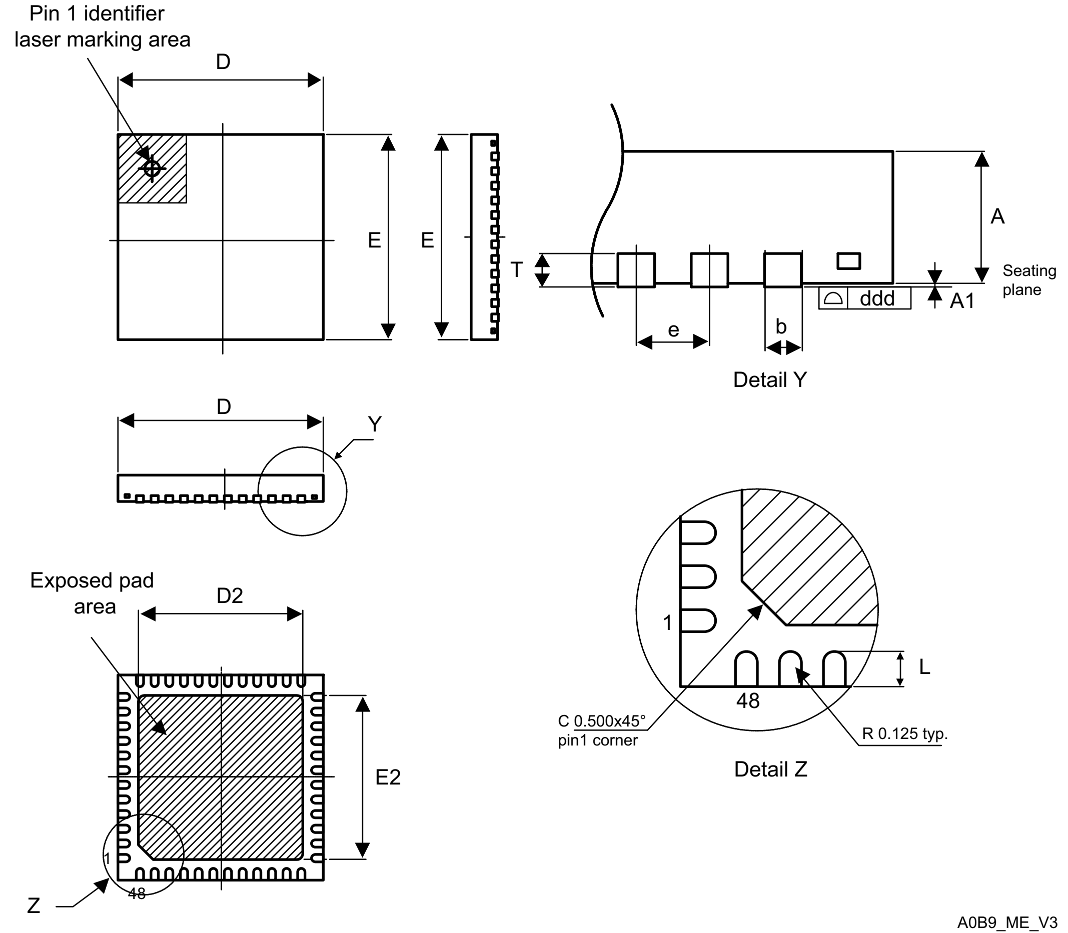
Table 56. Comparator characteristics

Symbol	Parameter	Conditions	Min(1)	Typ	Max(1)	Unit
V_{DDA}	Analog supply voltage	-	V_{DD}	-	3.6	V
V_{IN}	Comparator input voltage range	-	0	-	V_{DDA}	-
V_{SC}	V_{REFINT} scaler offset voltage	-	-	±5	±10	mV
t_{S_SC}	V_{REFINT} scaler startup time from power down	First V_{REFINT} scaler activation after device power on	-	-	1000 (2)	ms
		Next activations	-	-	0.2	ms
t_{START}	Comparator startup time	Startup time to reach propagation delay specification	-	-	60	µs
t_D	Propagation delay for 200 mV step with 100 mV overdrive	Ultra-low power mode	-	2	4.5	µs
		Low power mode	-	0.7	1.5	µs
		Medium power mode	-	0.3	0.6	µs
		High speed mode, $V_{DDA} \geq 2.7$ V	-	50	100	ns
		High speed mode, $V_{DDA} < 2.7$ V	-	100	240	ns
	Propagation delay for full range step with 100 mV overdrive	Ultra-low power mode	-	2	7	µs
		Low power mode	-	0.7	2.1	µs
		Medium power mode	-	0.3	1.2	µs
		High speed mode, $V_{DDA} \geq 2.7$ V	-	90	180	ns
		High speed mode, $V_{DDA} < 2.7$ V	-	110	300	ns
V_{offset}	Comparator offset error	-	-	±4	±10	mV
dV_{offset}/dT	Offset error temperature coefficient	-	-	18	-	µV/°C
$I_{DD(COMP)}$	COMP current consumption	Ultra-low power mode	-	1.2	1.5	µA
		Low power mode	-	3	5	µA
		Medium power mode	-	10	15	µA
		High speed mode	-	75	100	µA

7.4 UFQFPN48 package information

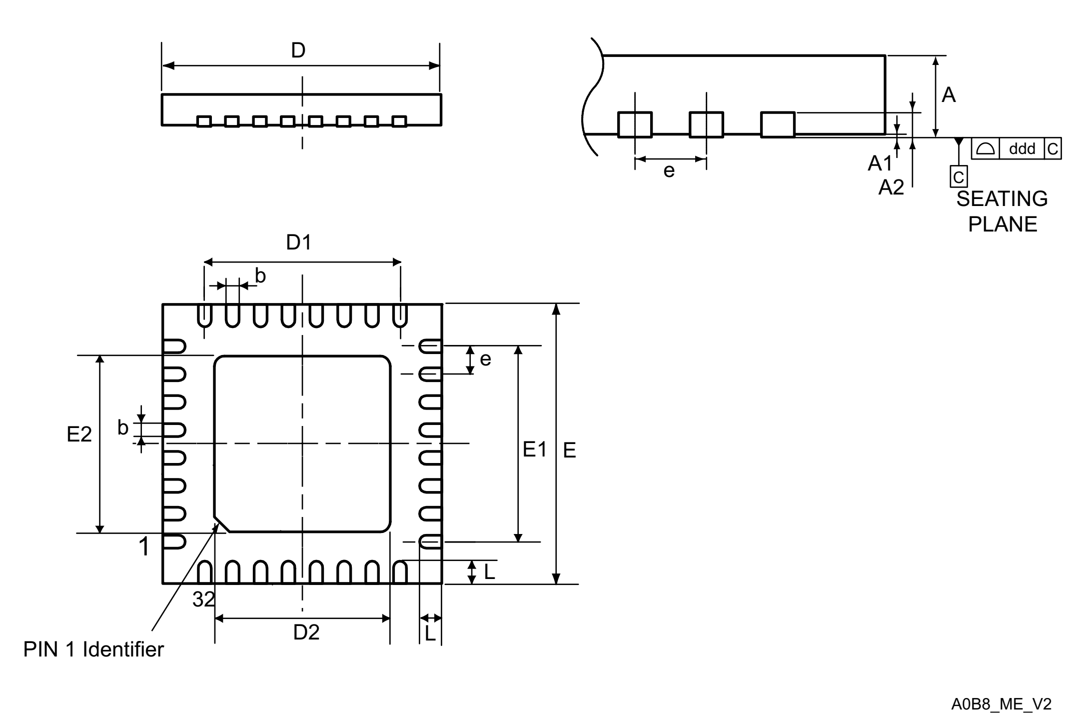
UFQFPN48 is a 48-lead, 7x7 mm, 0.5 mm pitch, ultra-thin fine-pitch quad flat package.

Figure 43. UFQFPN48 package outline



1. Drawing is not to scale.
2. All leads/pads should also be soldered to the PCB to improve the lead/pad solder joint life.
3. There is an exposed die pad on the underside of the UFQFPN package. It is recommended to connect and solder this back-side pad to PCB ground.

Figure 52. UFQFPN32 package outline



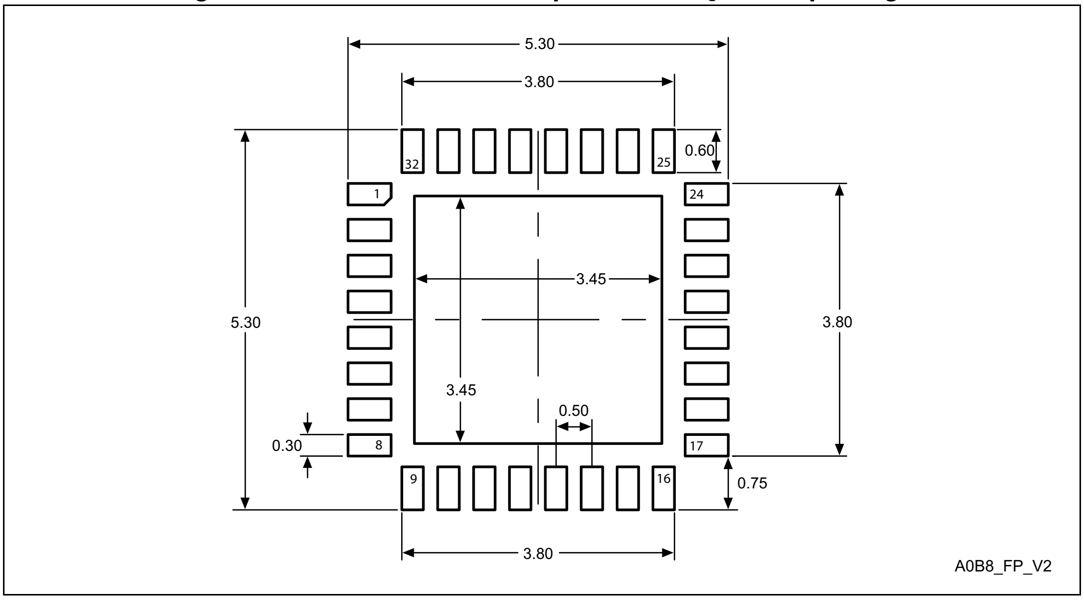
1. Drawing is not to scale.
2. All leads/pads should also be soldered to the PCB to improve the lead/pad solder joint life.
3. There is an exposed die pad on the underside of the UFQFPN package. This pad is used for the device ground and must be connected. It is referred to as pin 0 in *Table: Pin definitions*.

Table 73. UFQFPN32 package mechanical data

Symbol	millimeters			inches(1)		
	Min	Typ	Max	Min	Typ	Max
A	0.500	0.550	0.600	0.0197	0.0217	0.0236
A1	0.000	0.020	0.050	0.0000	0.0008	0.0020
A3	-	0.152	-	-	0.0060	-
b	0.180	0.230	0.280	0.0071	0.0091	0.0110
D	4.900	5.000	5.100	0.1929	0.1969	0.2008
D1	3.400	3.500	3.600	0.1339	0.1378	0.1417
D2	3.400	3.500	3.600	0.1339	0.1378	0.1417
E	4.900	5.000	5.100	0.1929	0.1969	0.2008
E1	3.400	3.500	3.600	0.1339	0.1378	0.1417
E2	3.400	3.500	3.600	0.1339	0.1378	0.1417
e	-	0.500	-	-	0.0197	-
L	0.300	0.400	0.500	0.0118	0.0157	0.0197
ddd	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 53. Recommended footprint for UFQFPN32 package



1. Dimensions are expressed in millimeters.

7.8 Thermal characteristics

The maximum chip junction temperature ($T_J$max) must never exceed the values given in *Table 20: General operating conditions*.

The maximum chip-junction temperature, T_J max, in degrees Celsius, may be calculated using the following equation:

$$T_J \max = T_A \max + (P_D \max \times \Theta_{JA})$$

Where:

- T_A max is the maximum ambient temperature in °C,
- Θ_{JA} is the package junction-to-ambient thermal resistance, in °C/W,
- P_D max is the sum of P_{INT} max and $P_{I/O}$ max (P_D max = P_{INT} max + $P_{I/O}$max),
- P_{INT} max is the product of I_{DD} and V_{DD}, expressed in Watts. This is the maximum chip internal power.

$P_{I/O}$ max represents the maximum power dissipation on output pins where:

$$P_{I/O} \max = \Sigma (V_{OL} \times I_{OL}) + \Sigma ((V_{DDIOx} - V_{OH}) \times I_{OH}),$$

taking into account the actual V_{OL} / I_{OL} and V_{OH} / I_{OH} of the I/Os at low and high level in the application.

Table 74. Package thermal characteristics

Symbol	Parameter	Value	Unit
Θ_{JA}	**Thermal resistance junction-ambient** LQFP64 - 10 × 10 mm / 0.5 mm pitch	45	°C/W
	Thermal resistance junction-ambient LQFP48 - 7 × 7 mm	55	
	Thermal resistance junction-ambient LQFP32 - 7 × 7 mm	56	
	Thermal resistance junction-ambient UFBGA64 - 5 × 5 mm	65	
	Thermal resistance junction-ambient UFQFPN48 - 7 × 7 mm	32	
	Thermal resistance junction-ambient UFQFPN32 - 5 × 5 mm	38	
	Thermal resistance junction-ambient WLCSP36 - 2.6 × 2.7 mm	60	

7.8.1 Reference document

JESD51-2 Integrated Circuits Thermal Test Method Environment Conditions - Natural Convection (Still Air). Available from www.jedec.org

7.8.2 Selecting the product temperature range

When ordering the microcontroller, the temperature range is specified in the ordering information scheme shown in *Section 8: Ordering information*.

Table 76. Document revision history (continued)

Date	Revision	Changes
06-Jan-2017	7	***Section 6: Electrical characteristics*:** – *Table 36: LSE oscillator characteristics (f_{LSE} = 32.768 kHz)* - information on configuring different drive capabilities removed. See the corresponding reference manual. – *Table 24: Embedded internal reference voltage* - V_{REFINT} values – *Table 55: DAC characteristics* - min. R_{LOAD} to V_{DDA} defined – *Figure 29: SPI timing diagram - slave mode and CPHA = 0* and *Figure 30: SPI timing diagram - slave mode and CPHA = 1* enhanced and corrected ***Section 8: Ordering information*:** – The name of the section changed from the previous “Part numbering”