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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

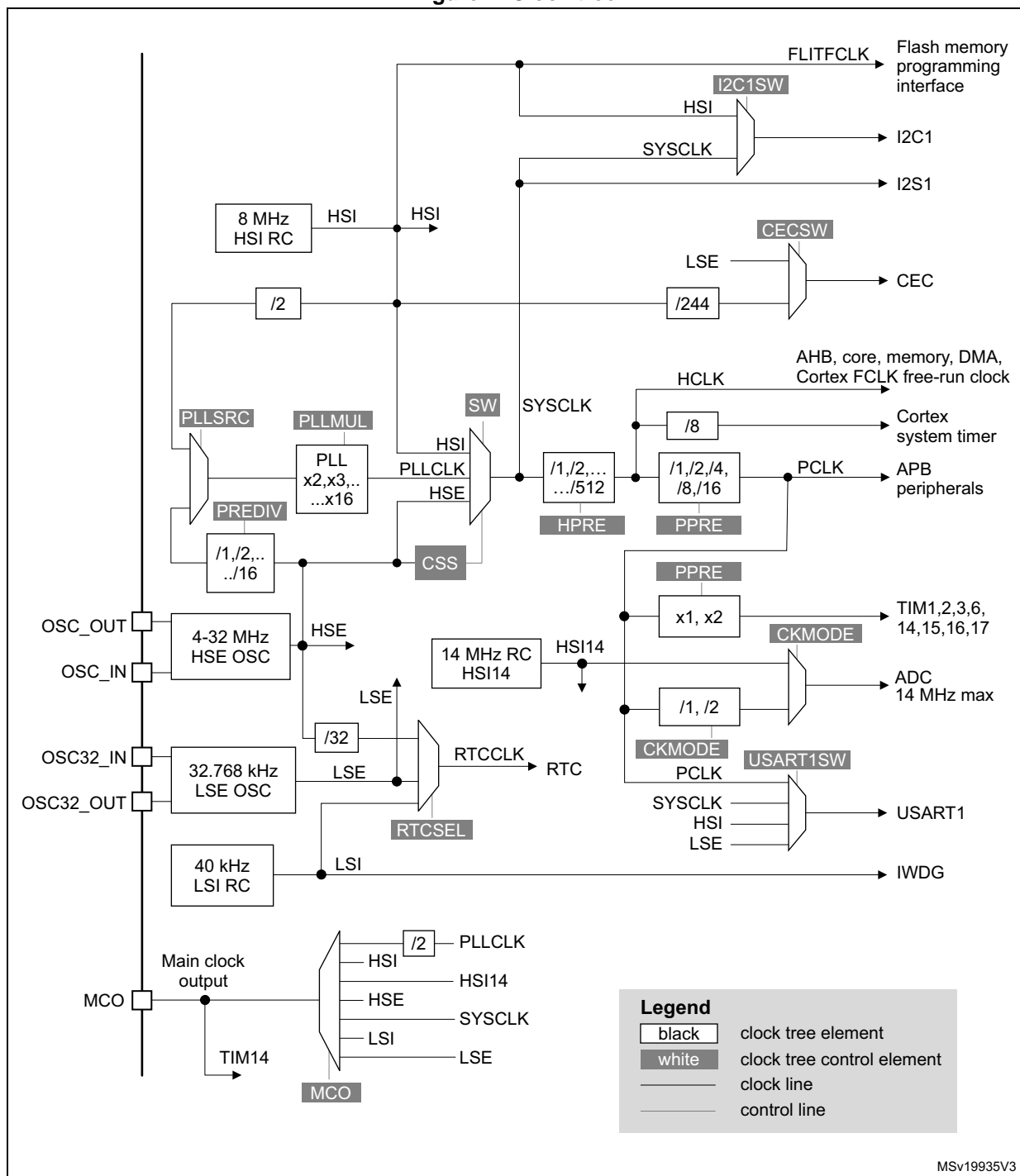
### Applications of "[Embedded - Microcontrollers](#)"

#### Details

|                            |   |
|----------------------------|---|
| Product Status             | Active  |
| Core Processor             | ARM® Cortex®-M0   |
| Core Size                  | 32-Bit Single-Core  |
| Speed                      | 48MHz   |
| Connectivity               | HDMI-CEC, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART   |
| Peripherals                | DMA, I <sup>2</sup> S, POR, PWM, WDT  |
| Number of I/O              | 25  |
| Program Memory Size        | 32KB (32K x 8)  |
| Program Memory Type        | FLASH   |
| EEPROM Size                | -   |
| RAM Size                   | 8K x 8  |
| Voltage - Supply (Vcc/Vdd) | 2V ~ 3.6V   |
| Data Converters            | A/D 13x12b; D/A 1x12b   |
| Oscillator Type            | Internal  |
| Operating Temperature      | -40°C ~ 85°C (TA)   |
| Mounting Type              | Surface Mount   |
| Package / Case             | 32-LQFP   |
| Supplier Device Package    | 32-LQFP (7x7)   |
| Purchase URL               | <a href="https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f051k6t6">https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f051k6t6</a> |

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Figure 2. Clock tree



MSv19935V3

### 3.7 General-purpose inputs/outputs (GPIOs)

Each of the GPIO pins can be configured by software as output (push-pull or open-drain), as input (with or without pull-up or pull-down) or as peripheral alternate function. Most of the GPIO pins are shared with digital or analog alternate functions.

Table 9. STM32F051xx I<sup>2</sup>C implementation (continued)

| I <sup>2</sup> C features <sup>(1)</sup> | I2C1 | I2C2 |
|--|------|------|
| SMBus                                    | X    | -    |
| Wakeup from STOP                         | X    | -    |

1. X = supported.

### 3.17 Universal synchronous/asynchronous receiver/transmitter (USART)

The device embeds up to two universal synchronous/asynchronous receivers/transmitters (USART1, USART2) which communicate at speeds of up to 6 Mbit/s.

They provide hardware management of the CTS, RTS and RS485 DE signals, multiprocessor communication mode, master synchronous communication and single-wire half-duplex communication mode. USART1 supports also SmartCard communication (ISO 7816), IrDA SIR ENDEC, LIN Master/Slave capability and auto baud rate feature, and has a clock domain independent of the CPU clock, allowing to wake up the MCU from Stop mode.

The USART interfaces can be served by the DMA controller.

Table 10. STM32F051xx USART implementation

| USART modes/features <sup>(1)</sup>         | USART1 | USART2 |
|---|--------|--------|
| Hardware flow control for modem             | X      | X      |
| Continuous communication using DMA          | X      | X      |
| Multiprocessor communication                | X      | X      |
| Synchronous mode                            | X      | X      |
| Smartcard mode                              | X      | -      |
| Single-wire half-duplex communication       | X      | X      |
| IrDA SIR ENDEC block                        | X      | -      |
| LIN mode                                    | X      | -      |
| Dual clock domain and wakeup from Stop mode | X      | -      |
| Receiver timeout interrupt                  | X      | -      |
| Modbus communication                        | X      | -      |
| Auto baud rate detection                    | X      | -      |
| Driver Enable                               | X      | X      |

1. X = supported.

Figure 4. UFBGA64 package pinout

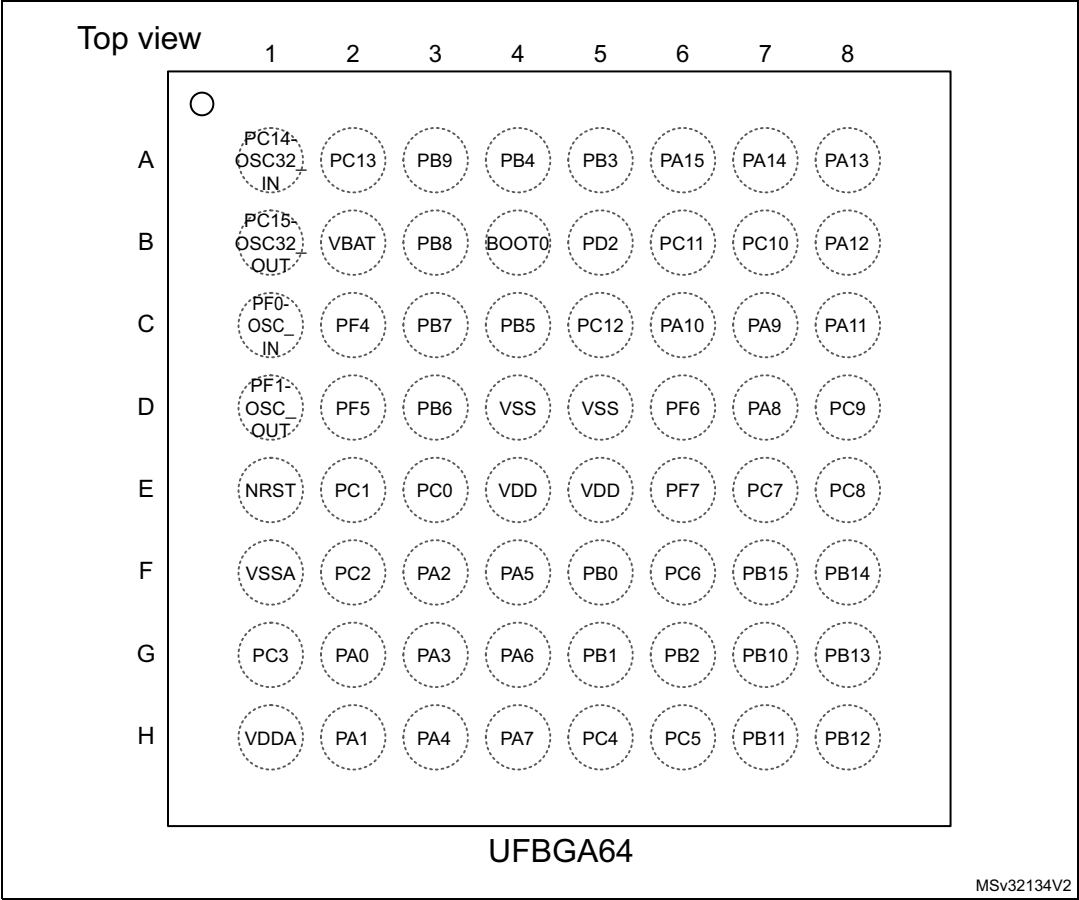


Figure 5. LQFP48 package pinout

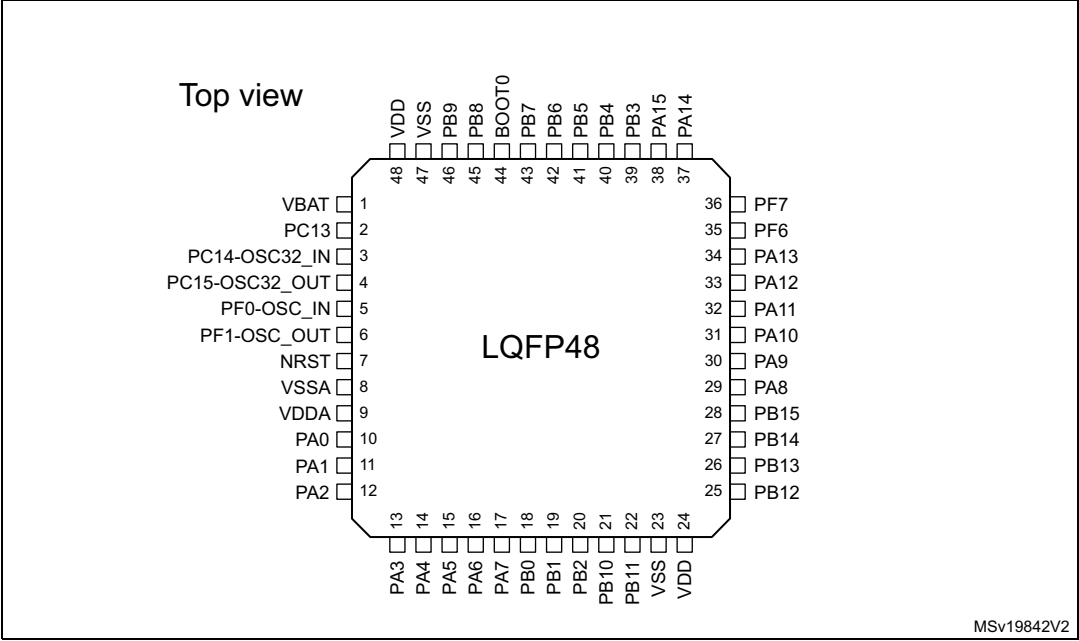


Table 13. Pin definitions (continued)

| Pin number |         |                 |         |        |          | Pin name<br>(function upon<br>reset) | Pin type | I/O structure | Notes  | Pin functions  |                      |
|------------|---------|-----------------|---------|--------|----------|--------------------------------------|----------|---------------|--------|--|----------------------|
| LQFP64     | UFBGA64 | LQFP48/UFQFPN48 | WLCSP36 | LQFP32 | UFQFPN32 |                                      |          |               |        | Alternate functions                                  | Additional functions |
| 58         | D3      | 42              | C4      | 29     | 29       | PB6                                  | I/O      | FTf           | -      | I2C1_SCL,<br>USART1_TX,<br>TIM16_CH1N,<br>TSC_G5_IO3 | -                    |
| 59         | C3      | 43              | A4      | 30     | 30       | PB7                                  | I/O      | FTf           | -      | I2C1_SDA,<br>USART1_RX,<br>TIM17_CH1N,<br>TSC_G5_IO4 | -                    |
| 60         | B4      | 44              | B4      | 31     | 31       | BOOT0                                | I        | B             | -      | Boot memory selection                                |                      |
| 61         | B3      | 45              | -       | -      | 32       | PB8                                  | I/O      | FTf           | (4)(5) | I2C1_SCL,<br>CEC,<br>TIM16_CH1,<br>TSC_SYNC          | -                    |
| 62         | A3      | 46              | -       | -      | -        | PB9                                  | I/O      | FTf           | (5)    | I2C1_SDA,<br>IR_OUT,<br>TIM17_CH1,<br>EVENTOUT       | -                    |
| 63         | D5      | 47              | D6      | 32     | 0        | VSS                                  | S        | -             | -      | Ground   |                      |
| 64         | E5      | 48              | A5      | 1      | 1        | VDD                                  | S        | -             | -      | Digital power supply                                 |                      |

- PC13, PC14 and PC15 are supplied through the power switch. Since the switch only sinks a limited amount of current (3 mA), the use of GPIOs PC13 to PC15 in output mode is limited:
  - The speed should not exceed 2 MHz with a maximum load of 30 pF.
  - These GPIOs must not be used as current sources (e.g. to drive an LED).
- After the first RTC domain power-up, PC13, PC14 and PC15 operate as GPIOs. Their function then depends on the content of the RTC registers which are not reset by the main reset. For details on how to manage these GPIOs, refer to the RTC domain and RTC register descriptions in the reference manual.
- Distinct VSSA pin is only available on packages with 48 and more pins. For all other packages, the pin number corresponds to the VSS pin to which VSSA pad of the silicon die is connected.
- On the LQFP32 package, PB2 and PB8 must be set to defined levels by software, as their corresponding pads on the silicon die are left unconnected. Apply the same recommendations as for unconnected pins.
- On the WLCSP36 package, PB8, PB9, PB10, PB11, PB12, PB13, PB14 and PB15 must be set to defined levels by software, as their corresponding pads on the silicon die are left unconnected. Apply the same recommendations as for unconnected pins.
- After reset, these pins are configured as SWDIO and SWCLK alternate functions, and the internal pull-up on the SWDIO pin and the internal pull-down on the SWCLK pin are activated.



Table 15. Alternate functions selected through GPIOB\_AFR registers for port B

| Pin name | AF0                 | AF1       | AF2        | AF3        |
|----------|---------------------|-----------|------------|------------|
| PB0      | EVENTOUT            | TIM3_CH3  | TIM1_CH2N  | TSC_G3_IO2 |
| PB1      | TIM14_CH1           | TIM3_CH4  | TIM1_CH3N  | TSC_G3_IO3 |
| PB2      |                     |           |            | TSC_G3_IO4 |
| PB3      | SPI1_SCK, I2S1_CK   | EVENTOUT  | TIM2_CH2   | TSC_G5_IO1 |
| PB4      | SPI1_MISO, I2S1_MCK | TIM3_CH1  | EVENTOUT   | TSC_G5_IO2 |
| PB5      | SPI1_MOSI, I2S1_SD  | TIM3_CH2  | TIM16_BKIN | I2C1_SMBA  |
| PB6      | USART1_TX           | I2C1_SCL  | TIM16_CH1N | TSC_G5_IO3 |
| PB7      | USART1_RX           | I2C1_SDA  | TIM17_CH1N | TSC_G5_IO4 |
| PB8      | CEC                 | I2C1_SCL  | TIM16_CH1  | TSC_SYNC   |
| PB9      | IR_OUT              | I2C1_SDA  | TIM17_CH1  | EVENTOUT   |
| PB10     | CEC                 | I2C2_SCL  | TIM2_CH3   | TSC_SYNC   |
| PB11     | EVENTOUT            | I2C2_SDA  | TIM2_CH4   | TSC_G6_IO1 |
| PB12     | SPI2_NSS            | EVENTOUT  | TIM1_BKIN  | TSC_G6_IO2 |
| PB13     | SPI2_SCK            |           | TIM1_CH1N  | TSC_G6_IO3 |
| PB14     | SPI2_MISO           | TIM15_CH1 | TIM1_CH2N  | TSC_G6_IO4 |
| PB15     | SPI2_MOSI           | TIM15_CH2 | TIM1_CH3N  | TIM15_CH1N |

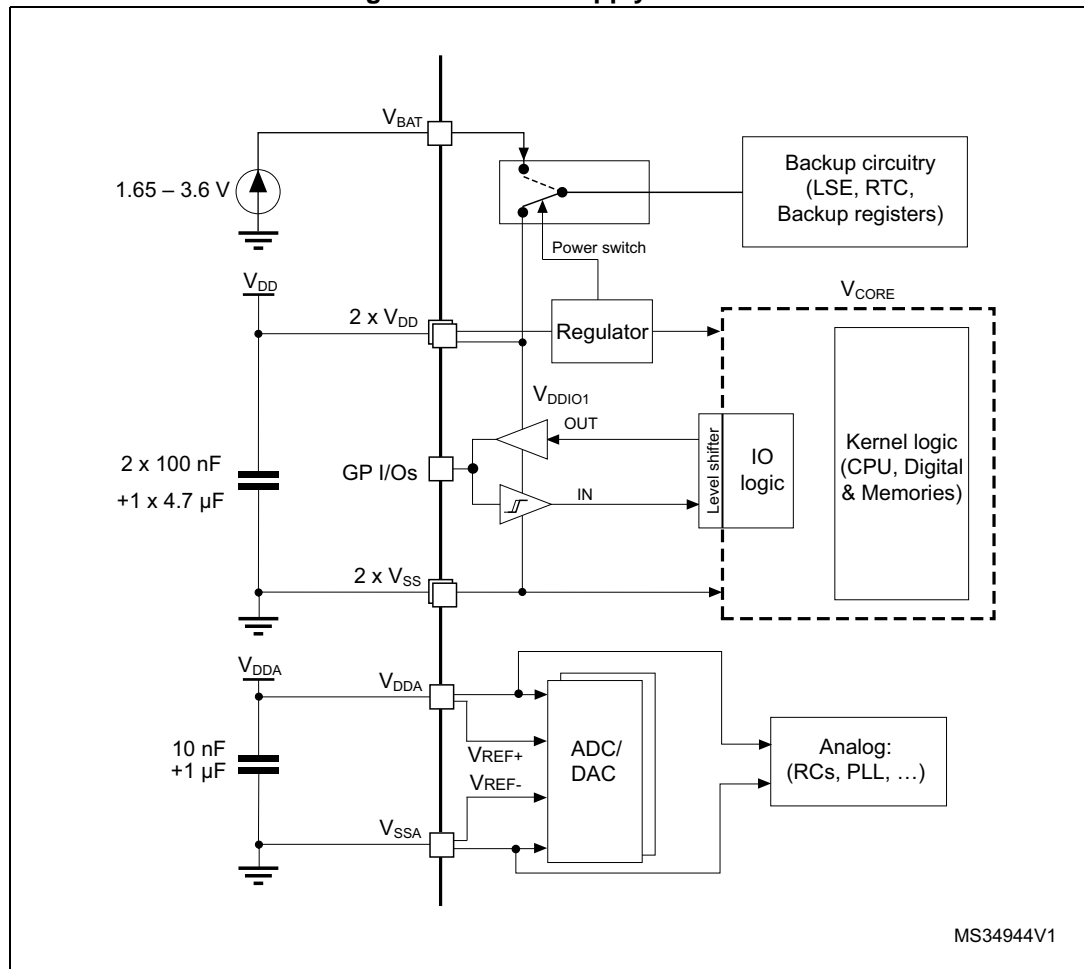
Table 16. STM32F051xx peripheral register boundary addresses

| Bus  | Boundary address          | Size    | Peripheral             |
|------|---------------------------|---------|------------------------|
|      | 0x4800 1800 - 0x5FFF FFFF | ~384 MB | Reserved               |
| AHB2 | 0x4800 1400 - 0x4800 17FF | 1 KB    | GPIOF                  |
|      | 0x4800 1000 - 0x4800 13FF | 1 KB    | Reserved               |
|      | 0x4800 0C00 - 0x4800 0FFF | 1 KB    | GPIOD                  |
|      | 0x4800 0800 - 0x4800 0BFF | 1 KB    | GPIOC                  |
|      | 0x4800 0400 - 0x4800 07FF | 1 KB    | GPIOB                  |
|      | 0x4800 0000 - 0x4800 03FF | 1 KB    | GPIOA                  |
|      | 0x4002 4400 - 0x47FF FFFF | ~128 MB | Reserved               |
| AHB1 | 0x4002 4000 - 0x4002 43FF | 1 KB    | TSC                    |
|      | 0x4002 3400 - 0x4002 3FFF | 3 KB    | Reserved               |
|      | 0x4002 3000 - 0x4002 33FF | 1 KB    | CRC                    |
|      | 0x4002 2400 - 0x4002 2FFF | 3 KB    | Reserved               |
|      | 0x4002 2000 - 0x4002 23FF | 1 KB    | Flash memory interface |
|      | 0x4002 1400 - 0x4002 1FFF | 3 KB    | Reserved               |
|      | 0x4002 1000 - 0x4002 13FF | 1 KB    | RCC                    |
|      | 0x4002 0400 - 0x4002 0FFF | 3 KB    | Reserved               |
|      | 0x4002 0000 - 0x4002 03FF | 1 KB    | DMA                    |
|      | 0x4001 8000 - 0x4001 FFFF | 32 KB   | Reserved               |
| APB  | 0x4001 5C00 - 0x4001 7FFF | 9 KB    | Reserved               |
|      | 0x4001 5800 - 0x4001 5BFF | 1 KB    | DBGMCU                 |
|      | 0x4001 4C00 - 0x4001 57FF | 3 KB    | Reserved               |
|      | 0x4001 4800 - 0x4001 4BFF | 1 KB    | TIM17                  |
|      | 0x4001 4400 - 0x4001 47FF | 1 KB    | TIM16                  |
|      | 0x4001 4000 - 0x4001 43FF | 1 KB    | TIM15                  |
|      | 0x4001 3C00 - 0x4001 3FFF | 1 KB    | Reserved               |
|      | 0x4001 3800 - 0x4001 3BFF | 1 KB    | USART1                 |
|      | 0x4001 3400 - 0x4001 37FF | 1 KB    | Reserved               |
|      | 0x4001 3000 - 0x4001 33FF | 1 KB    | SPI1/I2S1              |
|      | 0x4001 2C00 - 0x4001 2FFF | 1 KB    | TIM1                   |
|      | 0x4001 2800 - 0x4001 2BFF | 1 KB    | Reserved               |
|      | 0x4001 2400 - 0x4001 27FF | 1 KB    | ADC                    |
|      | 0x4001 0800 - 0x4001 23FF | 7 KB    | Reserved               |
|      | 0x4001 0400 - 0x4001 07FF | 1 KB    | EXTI                   |
|      | 0x4001 0000 - 0x4001 03FF | 1 KB    | SYSCFG + COMP          |
|      | 0x4000 8000 - 0x4000 FFFF | 32 KB   | Reserved               |



### 6.1.6 Power supply scheme

### Figure 13. Power supply scheme



**Caution:** Each power supply pair ( $V_{DD}/V_{SS}$ ,  $V_{DDA}/V_{SSA}$  etc.) must be decoupled with filtering ceramic capacitors as shown above. These capacitors must be placed as close as possible to, or below, the appropriate pins on the underside of the PCB to ensure the good functionality of the device.

Table 18. Current characteristics

| Symbol                | Ratings   | Max.                 | Unit |
|-----------------------|---|----------------------|------|
| $\Sigma I_{VDD}$      | Total current into sum of all VDD power lines (source) <sup>(1)</sup>           | 120                  | mA   |
| $\Sigma I_{VSS}$      | Total current out of sum of all VSS ground lines (sink) <sup>(1)</sup>          | -120                 |      |
| $I_{VDD(PIN)}$        | Maximum current into each VDD power pin (source) <sup>(1)</sup>                 | 100                  |      |
| $I_{VSS(PIN)}$        | Maximum current out of each VSS ground pin (sink) <sup>(1)</sup>                | -100                 |      |
| $I_{IO(PIN)}$         | Output current sunk by any I/O and control pin                                  | 25                   |      |
|                       | Output current source by any I/O and control pin                                | -25                  |      |
| $\Sigma I_{IO(PIN)}$  | Total output current sunk by sum of all I/Os and control pins <sup>(2)</sup>    | 80                   |      |
|                       | Total output current sourced by sum of all I/Os and control pins <sup>(2)</sup> | -80                  |      |
| $I_{INJ(PIN)}^{(3)}$  | Injected current on B, FT and FTf pins  | -5/+0 <sup>(4)</sup> |      |
|                       | Injected current on TC and RST pin  | ± 5                  |      |
|                       | Injected current on TTa pins <sup>(5)</sup>                                     | ± 5                  |      |
| $\Sigma I_{INJ(PIN)}$ | Total injected current (sum of all I/O and control pins) <sup>(6)</sup>         | ± 25                 |      |

1. All main power (VDD, VDDA) and ground (VSS, VSSA) pins must always be connected to the external power supply, in the permitted range.
2. This current consumption must be correctly distributed over all I/Os and control pins. The total output current must not be sunk/sourced between two consecutive power supply pins referring to high pin count QFP packages.
3. A positive injection is induced by  $V_{IN} > V_{DDIOx}$  while a negative injection is induced by  $V_{IN} < V_{SS}$ .  $I_{INJ(PIN)}$  must never be exceeded. Refer to [Table 17: Voltage characteristics](#) for the maximum allowed input voltage values.
4. Positive injection is not possible on these I/Os and does not occur for input voltages lower than the specified maximum value.
5. On these I/Os, a positive injection is induced by  $V_{IN} > V_{DDA}$ . Negative injection disturbs the analog performance of the device. See note <sup>(2)</sup> below [Table 54: ADC accuracy](#).
6. When several inputs are submitted to a current injection, the maximum  $\Sigma I_{INJ(PIN)}$  is the absolute sum of the positive and negative injected currents (instantaneous values).

Table 19. Thermal characteristics

| Symbol    | Ratings                      | Value       | Unit |
|-----------|------------------------------|-------------|------|
| $T_{STG}$ | Storage temperature range    | -65 to +150 | °C   |
| $T_J$     | Maximum junction temperature | 150         | °C   |

Table 27. Typical and maximum current consumption in Stop and Standby modes

| Sym-<br>bol      | Para-<br>meter                 | Conditions                                       | Typ @V <sub>DD</sub> (V <sub>DD</sub> = V <sub>DDA</sub> ) |       |       |       |       |       | Max <sup>(1)</sup>        |                           |                            | Unit               |
|------------------|--------------------------------|--|--|-------|-------|-------|-------|-------|---------------------------|---------------------------|----------------------------|--------------------|
|                  |                                |  | 2.0 V  | 2.4 V | 2.7 V | 3.0 V | 3.3 V | 3.6 V | T <sub>A</sub> =<br>25 °C | T <sub>A</sub> =<br>85 °C | T <sub>A</sub> =<br>105 °C |                    |
| I <sub>DD</sub>  | Supply current in Stop mode    | Regulator in run mode, all oscillators OFF       | 15   | 15.1  | 15.3  | 15.5  | 15.7  | 16    | (2)                       |                           | (2)                        | μA                 |
|                  |                                | Regulator in low-power mode, all oscillators OFF | 3.2  | 3.3   | 3.4   | 3.5   | 3.7   | 4     | (2)                       |                           | (2)                        |                    |
|                  | Supply current in Standby mode | LSI ON and IWDG ON                               | 0.8  | 1.0   | 1.1   | 1.2   | 1.4   | 1.5   | -                         | -                         | -                          |                    |
|                  |                                | LSI OFF and IWDG OFF                             | 0.7  | 0.8   | 0.9   | 1.0   | 1.1   | 1.3   | 2 <sup>(2)</sup>          | 2.5                       | 3 <sup>(2)</sup>           |                    |
| I <sub>DDA</sub> | Supply current in Stop mode    | V <sub>DDA</sub> monitoring ON                   | Regulator in run mode, all oscillators OFF                 | 1.9   | 2     | 2.2   | 2.3   | 2.5   | 2.6                       | 3.5 <sup>(2)</sup>        | 3.5                        | 4.5 <sup>(2)</sup> |
|                  |                                |  | Regulator in low-power mode, all oscillators OFF           | 1.9   | 2     | 2.2   | 2.3   | 2.5   | 2.6                       | 3.5 <sup>(2)</sup>        | 3.5                        | 4.5 <sup>(2)</sup> |
|                  | Supply current in Standby mode | V <sub>DDA</sub> monitoring ON                   | LSI ON and IWDG ON   | 2.3   | 2.5   | 2.7   | 2.9   | 3.1   | 3.3                       | -                         | -                          | -                  |
|                  |                                |  | LSI OFF and IWDG OFF                                       | 1.8   | 1.9   | 2     | 2.2   | 2.3   | 2.5                       | 3.5 <sup>(2)</sup>        | 3.5                        | 4.5 <sup>(2)</sup> |
|                  | Supply current in Stop mode    | V <sub>DDA</sub> monitoring OFF                  | Regulator in run mode, all oscillators OFF                 | 1.1   | 1.2   | 1.2   | 1.2   | 1.3   | 1.4                       | -                         | -                          | -                  |
|                  |                                |  | Regulator in low-power mode, all oscillators OFF           | 1.1   | 1.2   | 1.2   | 1.2   | 1.3   | 1.4                       | -                         | -                          | -                  |
|                  | Supply current in Standby mode | V <sub>DDA</sub> monitoring OFF                  | LSI ON and IWDG ON   | 1.5   | 1.6   | 1.7   | 1.8   | 1.9   | 2.0                       | -                         | -                          | -                  |
|                  |                                |  | LSI OFF and IWDG OFF                                       | 1     | 1.0   | 1.1   | 1.1   | 1.2   | 1.2                       | -                         | -                          | -                  |

1. Data based on characterization results, not tested in production unless otherwise specified.

2. Data based on characterization results and tested in production (using one common test limit for sum of I<sub>DD</sub> and I<sub>DDA</sub>).

trigger circuits used to discriminate the input value. Unless this specific configuration is required by the application, this supply current consumption can be avoided by configuring these I/Os in analog mode. This is notably the case of ADC input pins which should be configured as analog inputs.

**Caution:** Any floating input pin can also settle to an intermediate voltage level or switch inadvertently, as a result of external electromagnetic noise. To avoid current consumption related to floating pins, they must either be configured in analog mode, or forced internally to a definite digital value. This can be done either by using pull-up/down resistors or by configuring the pins in output mode.

#### I/O dynamic current consumption

In addition to the internal peripheral current consumption measured previously (see [Table 31: Peripheral current consumption](#)), the I/Os used by an application also contribute to the current consumption. When an I/O pin switches, it uses the current from the I/O supply voltage to supply the I/O pin circuitry and to charge/discharge the capacitive load (internal or external) connected to the pin:

$$I_{SW} = V_{DDIOx} \times f_{SW} \times C$$

where

$I_{SW}$  is the current sunk by a switching I/O to charge/discharge the capacitive load

$V_{DDIOx}$  is the I/O supply voltage

$f_{SW}$  is the I/O switching frequency

$C$  is the total capacitance seen by the I/O pin:  $C = C_{INT} + C_{EXT} + C_S$

$C_S$  is the PCB board capacitance including the pad pin.

The test pin is configured in push-pull output mode and is toggled by software at a fixed frequency.

### On-chip peripheral current consumption

The current consumption of the on-chip peripherals is given in [Table 31](#). The MCU is placed under the following conditions:

- All I/O pins are in analog mode
- All peripherals are disabled unless otherwise mentioned
- The given value is calculated by measuring the current consumption
  - with all peripherals clocked off
  - with only one peripheral clocked on
- Ambient operating temperature and supply voltage conditions summarized in [Table 17: Voltage characteristics](#)

**Table 31. Peripheral current consumption**

| Peripheral |                            | Typical consumption at 25 °C | Unit   |
|------------|----------------------------|------------------------------|--------|
| AHB        | BusMatrix <sup>(1)</sup>   | 5                            | μA/MHz |
|            | DMA1                       | 7                            |        |
|            | SRAM                       | 1                            |        |
|            | Flash memory interface     | 14                           |        |
|            | CRC                        | 2                            |        |
|            | GPIOA                      | 9                            |        |
|            | GPIOB                      | 12                           |        |
|            | GPIOC                      | 2                            |        |
|            | PIOD                       | 1                            |        |
|            | GPIOF                      | 1                            |        |
|            | TSC                        | 6                            |        |
|            | <b>All AHB peripherals</b> | <b>55</b>                    |        |

## High-speed internal 14 MHz (HSI14) RC oscillator (dedicated to ADC)

Table 38. HSI14 oscillator characteristics<sup>(1)</sup>

| Symbol                  | Parameter   | Conditions   | Min                 | Typ | Max                | Unit          |
|-------------------------|---|--|---------------------|-----|--------------------|---------------|
| $f_{\text{HSI14}}$      | Frequency   | -  | -                   | 14  | -                  | MHz           |
| TRIM                    | HSI14 user-trimming step                              | -  | -                   | -   | 1 <sup>(2)</sup>   | %             |
| DuCy <sub>(HSI14)</sub> | Duty cycle  | -  | 45 <sup>(2)</sup>   | -   | 55 <sup>(2)</sup>  | %             |
| ACC <sub>HSI14</sub>    | Accuracy of the HSI14 oscillator (factory calibrated) | $T_A = -40 \text{ to } 105 \text{ }^\circ\text{C}$ | -4.2 <sup>(3)</sup> | -   | 5.1 <sup>(3)</sup> | %             |
|                         |   | $T_A = -10 \text{ to } 85 \text{ }^\circ\text{C}$  | -3.2 <sup>(3)</sup> | -   | 3.1 <sup>(3)</sup> | %             |
|                         |   | $T_A = 0 \text{ to } 70 \text{ }^\circ\text{C}$    | -2.5 <sup>(3)</sup> | -   | 2.3 <sup>(3)</sup> | %             |
|                         |   | $T_A = 25 \text{ }^\circ\text{C}$                  | -1                  | -   | 1                  | %             |
| $t_{\text{su(HSI14)}}$  | HSI14 oscillator startup time                         | -  | 1 <sup>(2)</sup>    | -   | 2 <sup>(2)</sup>   | $\mu\text{s}$ |
| $I_{\text{DDA(HSI14)}}$ | HSI14 oscillator power consumption                    | -  | -                   | 100 | 150 <sup>(2)</sup> | $\mu\text{A}$ |

1.  $V_{\text{DDA}} = 3.3 \text{ V}$ ,  $T_A = -40 \text{ to } 105 \text{ }^\circ\text{C}$  unless otherwise specified.
2. Guaranteed by design, not tested in production.
3. Data based on characterization results, not tested in production.

Figure 20. HSI14 oscillator accuracy characterization results

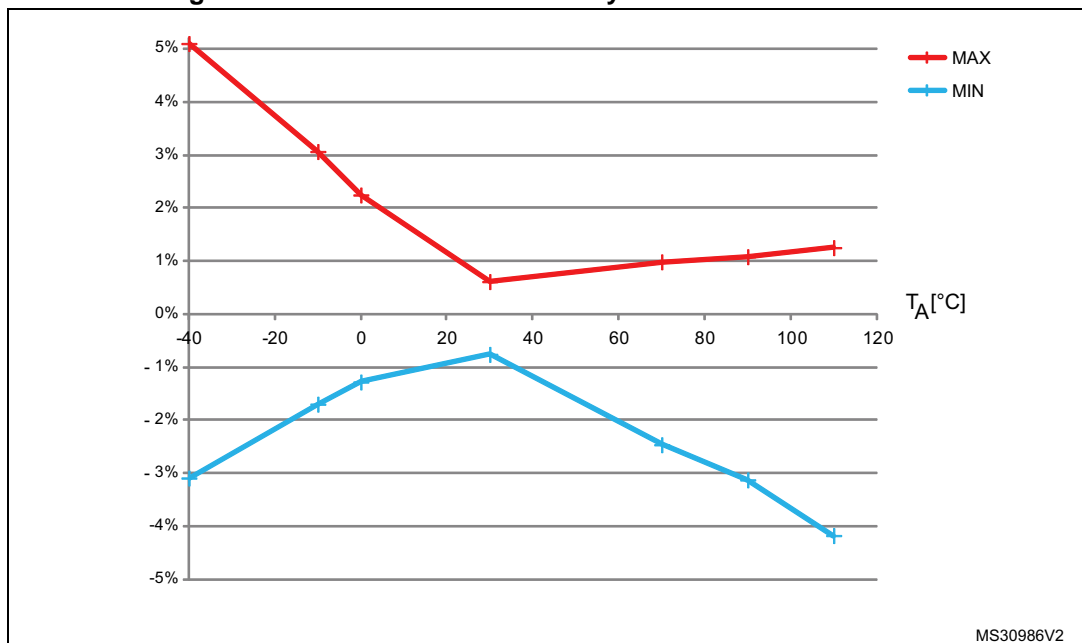
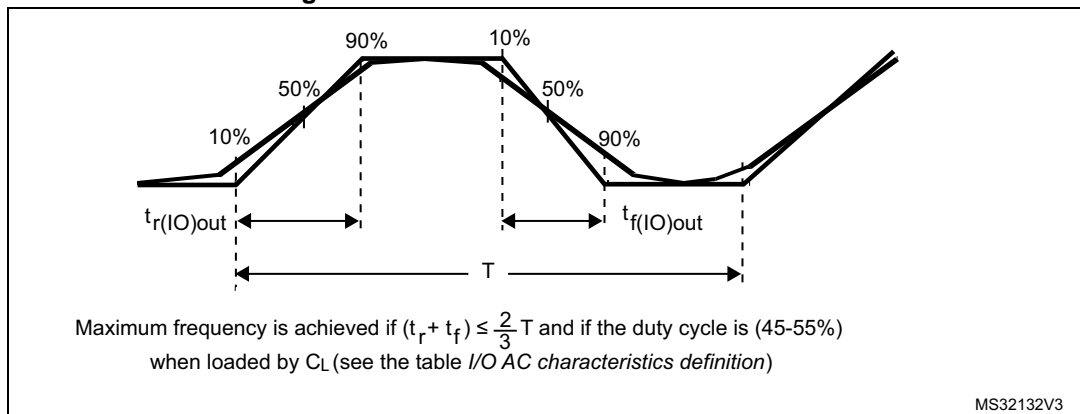


Figure 23. I/O AC characteristics definition



### 6.3.15 NRST pin characteristics

The NRST pin input driver uses the CMOS technology. It is connected to a permanent pull-up resistor,  $R_{PU}$ .

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature and supply voltage conditions summarized in [Table 20: General operating conditions](#).

Table 51. NRST pin characteristics

| Symbol          | Parameter                                       | Conditions           | Min                          | Typ | Max                       | Unit |
|-----------------|---|----------------------|------------------------------|-----|---------------------------|------|
| $V_{IL(NRST)}$  | NRST input low level voltage                    | -                    | -                            | -   | $0.3 V_{DD} + 0.07^{(1)}$ | V    |
| $V_{IH(NRST)}$  | NRST input high level voltage                   | -                    | $0.445 V_{DD} + 0.398^{(1)}$ | -   | -                         |      |
| $V_{hys(NRST)}$ | NRST Schmitt trigger voltage hysteresis         | -                    | -                            | 200 | -                         | mV   |
| $R_{PU}$        | Weak pull-up equivalent resistor <sup>(2)</sup> | $V_{IN} = V_{SS}$    | 25                           | 40  | 55                        | kΩ   |
| $V_F(NRST)$     | NRST input filtered pulse                       | -                    | -                            | -   | $100^{(1)}$               | ns   |
| $V_{NF(NRST)}$  | NRST input not filtered pulse                   | $2.7 < V_{DD} < 3.6$ | $300^{(3)}$                  | -   | -                         | ns   |
|                 |   | $2.0 < V_{DD} < 3.6$ | $500^{(3)}$                  | -   | -                         |      |

1. Data based on design simulation only. Not tested in production.

2. The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance is minimal (~10% order).

3. Data based on design simulation only. Not tested in production.

### 6.3.18 Comparator characteristics

Table 56. Comparator characteristics

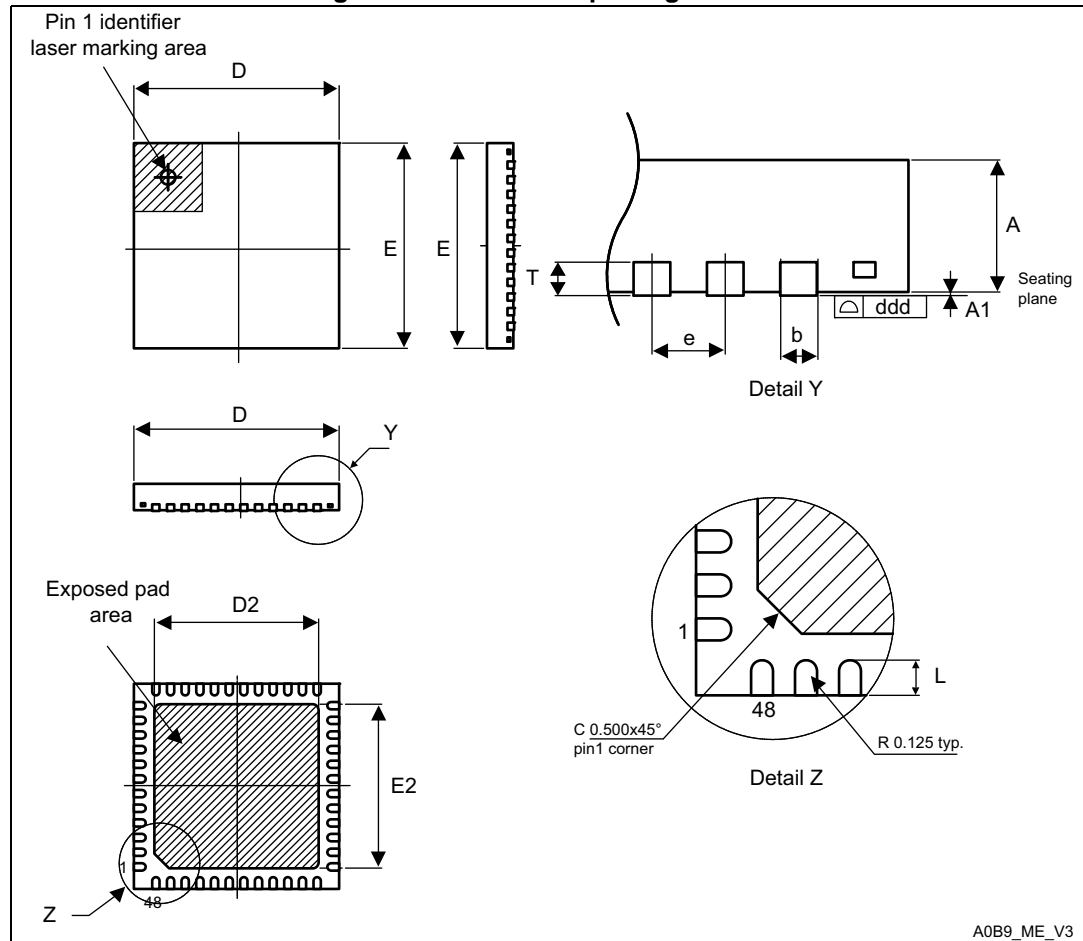
| Symbol                   | Parameter   | Conditions  | Min <sup>(1)</sup>       | Typ | Max <sup>(1)</sup>  | Unit  |    |
|--------------------------|---|---|--------------------------|-----|---------------------|-------|----|
| V <sub>DDA</sub>         | Analog supply voltage                                       | -   | V <sub>DD</sub>          | -   | 3.6                 | V     |    |
| V <sub>IN</sub>          | Comparator input voltage range                              | -   | 0                        | -   | V <sub>DDA</sub>    | -     |    |
| V <sub>SC</sub>          | V <sub>REFINT</sub> scaler offset voltage                   | -   | -                        | ±5  | ±10                 | mV    |    |
| t <sub>S_SC</sub>        | V <sub>REFINT</sub> scaler startup time from power down     | First V <sub>REFINT</sub> scaler activation after device power on | -                        | -   | 1000 <sup>(2)</sup> | ms    |    |
|                          |   | Next activations  | -                        | -   | 0.2                 |       |    |
| t <sub>START</sub>       | Comparator startup time                                     | Startup time to reach propagation delay specification             | -                        | -   | 60                  | µs    |    |
| t <sub>D</sub>           | Propagation delay for 200 mV step with 100 mV overdrive     | Ultra-low power mode  |                          | -   | 2                   | 4.5   | µs |
|                          |   | Low power mode  |                          | -   | 0.7                 | 1.5   |    |
|                          |   | Medium power mode   |                          | -   | 0.3                 | 0.6   |    |
|                          |   | High speed mode   | V <sub>DDA</sub> ≥ 2.7 V | -   | 50                  | 100   | ns |
|                          | V <sub>DDA</sub> < 2.7 V                                    |   | -                        | 100 | 240                 |       |    |
|                          | Propagation delay for full range step with 100 mV overdrive | Ultra-low power mode  |                          | -   | 2                   | 7     | µs |
|                          |   | Low power mode  |                          | -   | 0.7                 | 2.1   |    |
|                          |   | Medium power mode   |                          | -   | 0.3                 | 1.2   |    |
|                          |   | High speed mode   | V <sub>DDA</sub> ≥ 2.7 V | -   | 90                  | 180   | ns |
|                          |   |   | V <sub>DDA</sub> < 2.7 V | -   | 110                 | 300   |    |
| V <sub>offset</sub>      |   | Comparator offset error   | -                        | -   | ±4                  | ±10   | mV |
| dV <sub>offset</sub> /dT | Offset error temperature coefficient                        | -   | -                        | 18  | -                   | µV/°C |    |
| I <sub>DD(COMP)</sub>    | COMP current consumption                                    | Ultra-low power mode  |                          | -   | 1.2                 | 1.5   | µA |
|                          |   | Low power mode  |                          | -   | 3                   | 5     |    |
|                          |   | Medium power mode   |                          | -   | 10                  | 15    |    |
|                          |   | High speed mode   |                          | -   | 75                  | 100   |    |



## 7.4 UFQFPN48 package information

UFQFPN48 is a 48-lead, 7x7 mm, 0.5 mm pitch, ultra-thin fine-pitch quad flat package.

Figure 43. UFQFPN48 package outline



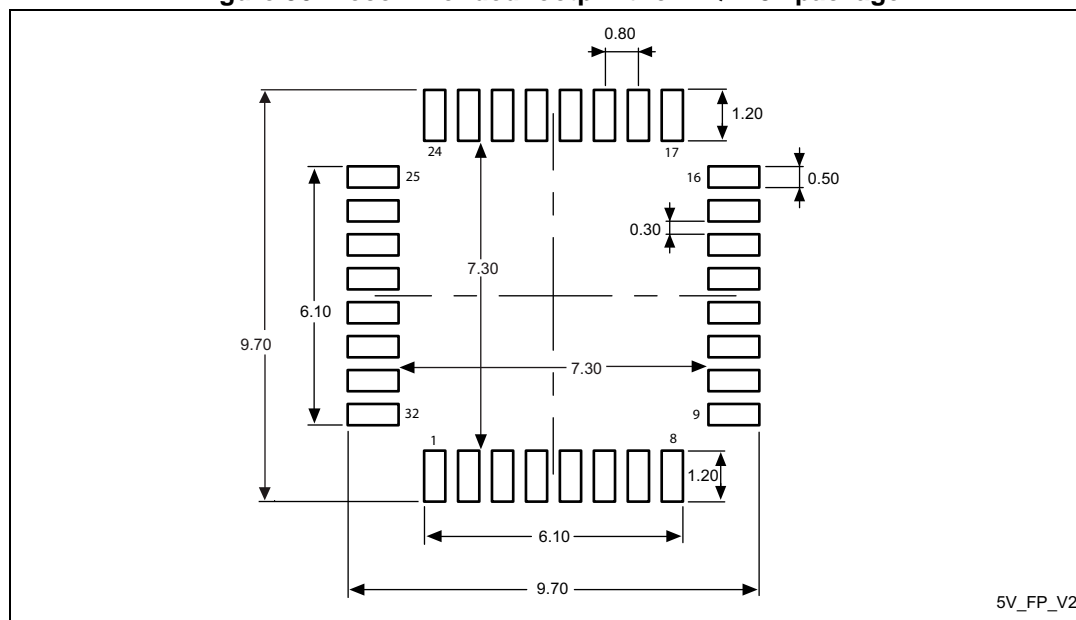
1. Drawing is not to scale.
2. All leads/pads should also be soldered to the PCB to improve the lead/pad solder joint life.
3. There is an exposed die pad on the underside of the UFQFPN package. It is recommended to connect and solder this back-side pad to PCB ground.

### Table 72. LQFP32 package mechanical data

| Symbol | millimeters |       |       | inches <sup>(1)</sup> |        |        |
|--------|-------------|-------|-------|-----------------------|--------|--------|
|        | Min         | Typ   | Max   | Min                   | Typ    | Max    |
| A      | -           | -     | 1.600 | -                     | -      | 0.0630 |
| A1     | 0.050       | -     | 0.150 | 0.0020                | -      | 0.0059 |
| A2     | 1.350       | 1.400 | 1.450 | 0.0531                | 0.0551 | 0.0571 |
| b      | 0.300       | 0.370 | 0.450 | 0.0118                | 0.0146 | 0.0177 |
| c      | 0.090       | -     | 0.200 | 0.0035                | -      | 0.0079 |
| D      | 8.800       | 9.000 | 9.200 | 0.3465                | 0.3543 | 0.3622 |
| D1     | 6.800       | 7.000 | 7.200 | 0.2677                | 0.2756 | 0.2835 |
| D3     | -           | 5.600 | -     | -                     | 0.2205 | -      |
| E      | 8.800       | 9.000 | 9.200 | 0.3465                | 0.3543 | 0.3622 |
| E1     | 6.800       | 7.000 | 7.200 | 0.2677                | 0.2756 | 0.2835 |
| E3     | -           | 5.600 | -     | -                     | 0.2205 | -      |
| e      | -           | 0.800 | -     | -                     | 0.0315 | -      |
| L      | 0.450       | 0.600 | 0.750 | 0.0177                | 0.0236 | 0.0295 |
| L1     | -           | 1.000 | -     | -                     | 0.0394 | -      |
| k      | 0°          | 3.5°  | 7°    | 0°                    | 3.5°   | 7°     |
| ccc    | -           | -     | 0.100 | -                     | -      | 0.0039 |

1. Values in inches are converted from mm and rounded to 4 decimal digits.

**Figure 50. Recommended footprint for LQFP32 package**



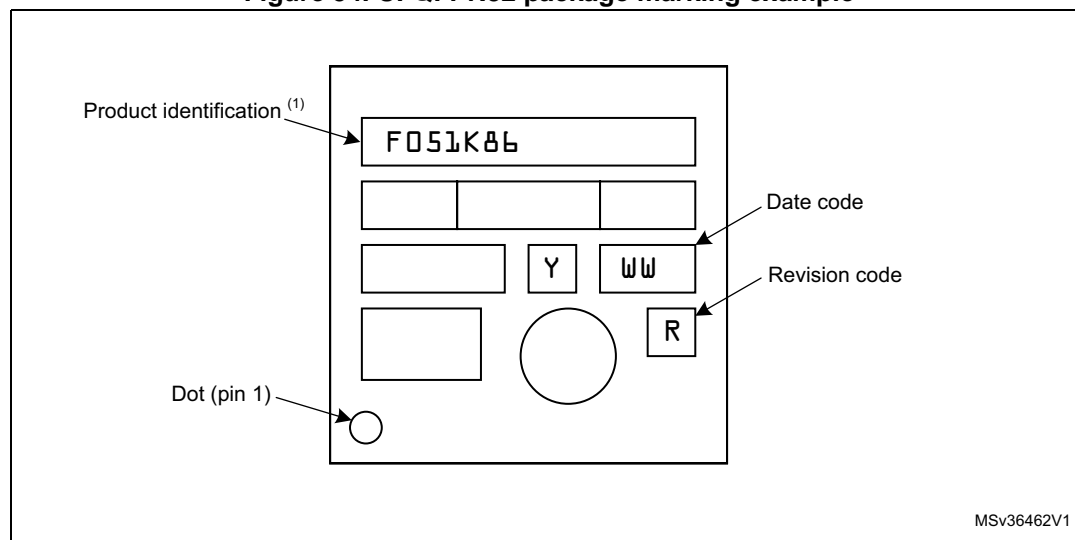
1. Dimensions are expressed in millimeters.

## Device marking

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Other optional marking or inset/upset marks, which identify the parts throughout supply chain operations, are not indicated below.

**Figure 54. UFQFPN32 package marking example**



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

## 8 Ordering information

For a list of available options (memory, package, and so on) or for further information on any aspect of this device, please contact your nearest ST sales office.

**Table 75. Ordering information scheme**

|   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
|---|-------|---|-----|---|---|---|---|---|--|--|--|--|--|--|--|--|
| <b>Example:</b>   | STM32 | F | 051 | R | 8 | T | 6 | x |  |  |  |  |  |  |  |  |
| <b>Device family</b>                                      |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| STM32 = ARM-based 32-bit microcontroller                  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| <b>Product type</b>                                       |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| F = General-purpose                                       |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| <b>Sub-family</b>   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| 051 = STM32F051xx   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| <b>Pin count</b>  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| K = 32 pins   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| T = 36 pins   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| C = 48 pins   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| R = 64 pins   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| <b>User code memory size</b>                              |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| 4 = 16 Kbyte  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| 6 = 32 Kbyte  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| 8 = 64 Kbyte  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| <b>Package</b>  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| H = UFBGA   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| T = LQFP  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| U = UFQFPN  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| Y = WLCSP   |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| <b>Temperature range</b>                                  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| 6 = −40 °C to +85 °C                                      |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| 7 = −40 °C to +105 °C                                     |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| <b>Options</b>  |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| xxx = code ID of programmed parts (includes packing type) |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| TR = tape and reel packing                                |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |
| blank = tray packing                                      |       |   |     |   |   |   |   |   |  |  |  |  |  |  |  |  |

Table 76. Document revision history (continued)

| Date        | Revision | Changes   |
|-------------|----------|---|
| 06-Jan-2017 | 7        | <p><b>Section 6: Electrical characteristics:</b></p> <ul style="list-style-type: none"> <li>– <i>Table 36: LSE oscillator characteristics (<math>f_{LSE} = 32.768</math> kHz)</i> - information on configuring different drive capabilities removed. See the corresponding reference manual.</li> <li>– <i>Table 24: Embedded internal reference voltage</i> - <math>V_{REFINT}</math> values</li> <li>– <i>Table 55: DAC characteristics</i> - min. <math>R_{LOAD}</math> to <math>V_{DDA}</math> defined</li> <li>– <i>Figure 29: SPI timing diagram - slave mode and CPHA = 0</i> and <i>Figure 30: SPI timing diagram - slave mode and CPHA = 1</i> enhanced and corrected</li> </ul> <p><b>Section 8: Ordering information:</b></p> <ul style="list-style-type: none"> <li>– The name of the section changed from the previous “Part numbering”</li> </ul> |