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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	HDMI-CEC, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	25
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 13x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f051k8t6tr

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

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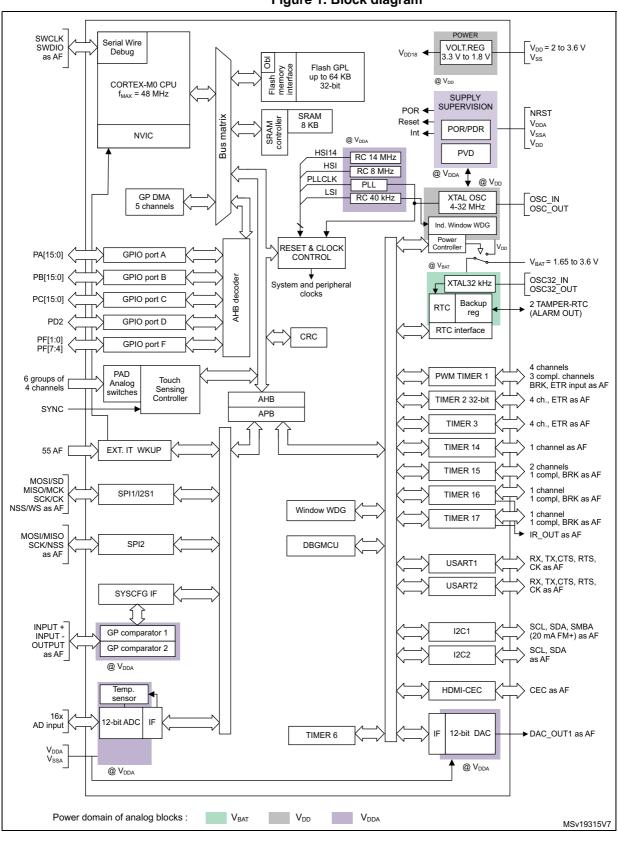


Figure 1. Block diagram



The I/O configuration can be locked if needed following a specific sequence in order to avoid spurious writing to the I/Os registers.

# **3.8** Direct memory access controller (DMA)

The 5-channel general-purpose DMAs manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers.

The DMA supports circular buffer management, removing the need for user code intervention when the controller reaches the end of the buffer.

Each channel is connected to dedicated hardware DMA requests, with support for software trigger on each channel. Configuration is made by software and transfer sizes between source and destination are independent.

DMA can be used with the main peripherals: SPIx, I2Sx, I2Cx, USARTx, all TIMx timers (except TIM14), DAC and ADC.

# 3.9 Interrupts and events

## 3.9.1 Nested vectored interrupt controller (NVIC)

The STM32F0xx family embeds a nested vectored interrupt controller able to handle up to 32 maskable interrupt channels (not including the 16 interrupt lines of Cortex<sup>®</sup>-M0) and 4 priority levels.

- Closely coupled NVIC gives low latency interrupt processing
- Interrupt entry vector table address passed directly to the core
- Closely coupled NVIC core interface
- Allows early processing of interrupts
- Processing of late arriving higher priority interrupts
- Support for tail-chaining
- Processor state automatically saved
- Interrupt entry restored on interrupt exit with no instruction overhead

This hardware block provides flexible interrupt management features with minimal interrupt latency.

# 3.9.2 Extended interrupt/event controller (EXTI)

The extended interrupt/event controller consists of 24 edge detector lines used to generate interrupt/event requests and wake-up the system. Each line can be independently configured to select the trigger event (rising edge, falling edge, both) and can be masked independently. A pending register maintains the status of the interrupt requests. The EXTI can detect an external line with a pulse width shorter than the internal clock period. Up to 55 GPIOs can be connected to the 16 external interrupt lines.

# 3.10 Analog-to-digital converter (ADC)

The 12-bit analog-to-digital converter has up to 16 external and 3 internal (temperature



hardware touch sensing controller and only requires few external components to operate. For operation, one capacitive sensing GPIO in each group is connected to an external capacitor and cannot be used as effective touch sensing channel.

The touch sensing controller is fully supported by the STMTouch touch sensing firmware library, which is free to use and allows touch sensing functionality to be implemented reliably in the end application.

Group	Capacitive sensing signal name	Pin name	Group	Capacitive sensing signal name	Pin name
	TSC_G1_IO1	PA0		TSC_G4_IO1	PA9
1	TSC_G1_IO2	PA1	4	TSC_G4_IO2	PA10
1	TSC_G1_IO3	PA2	4	TSC_G4_IO3	PA11
	TSC_G1_IO4	PA3		TSC_G4_IO4	PA12
	TSC_G2_IO1	PA4		TSC_G5_IO1	PB3
2	TSC_G2_IO2	PA5	5	TSC_G5_IO2	PB4
2	TSC_G2_IO3	PA6	5	TSC_G5_IO3	PB6
	TSC_G2_IO4	PA7		TSC_G5_IO4	PB7
	TSC_G3_IO1	PC5		TSC_G6_IO1	PB11
3	TSC_G3_IO2	PB0	6	TSC_G6_IO2	PB12
5	TSC_G3_IO3	PB1	0	TSC_G6_IO3	PB13
	TSC_G3_IO4	PB2		TSC_G6_IO4	PB14

 Table 5. Capacitive sensing GPIOs available on STM32F051xx devices

Table 6. Effective number of capacitive	sensing channels on STM32F051xx
---	---------------------------------

	Number of capacitive sensing channels				
Analog I/O group	STM32F051Rx	STM32F051Cx	STM32F051Tx	STM32F051KxU (UFQFPN32)	STM32F051KxT (LQFP32)
G1	3	3	3	3	3
G2	3	3	3	3	3
G3	3	2	2	2	1
G4	3	3	3	3	3
G5	3	3	3	3	3
G6	3	3	0	0	0
Number of capacitive sensing channels	18	17	14	14	13

The RTC clock sources can be:

- a 32.768 kHz external crystal
- a resonator or oscillator
- the internal low-power RC oscillator (typical frequency of 40 kHz)
- the high-speed external clock divided by 32

# 3.16 Inter-integrated circuit interface (I<sup>2</sup>C)

Up to two I<sup>2</sup>C interfaces (I2C1 and I2C2) can operate in multimaster or slave modes. Both can support Standard mode (up to 100 kbit/s) and Fast mode (up to 400 kbit/s) and, I2C1 also supports Fast Mode Plus (up to 1 Mbit/s) with 20 mA output drive.

Both support 7-bit and 10-bit addressing modes, multiple 7-bit slave addresses (two addresses, one with configurable mask). They also include programmable analog and digital noise filters.

Aspect	Analog filter	Digital filter
Pulse width of suppressed spikes	≥ 50 ns	Programmable length from 1 to 15 I2Cx peripheral clocks
Benefits	Available in Stop mode	<ul> <li>Extra filtering capability vs.</li> <li>standard requirements</li> <li>Stable length</li> </ul>
Drawbacks	Variations depending on temperature, voltage, process	Wakeup from Stop on address match is not available when digital filter is enabled.

Table 8. Com	parison of I <sup>2</sup> C an	alog and digital filters
		alog and algital mitolo

In addition, I2C1 provides hardware support for SMBUS 2.0 and PMBUS 1.1: ARP capability, Host notify protocol, hardware CRC (PEC) generation/verification, timeouts verifications and ALERT protocol management. I2C1 also has a clock domain independent from the CPU clock, allowing the I2C1 to wake up the MCU from Stop mode on address match.

The I2C peripherals can be served by the DMA controller.

Refer to Table 9 for the differences between I2C1 and I2C2.

I <sup>2</sup> C features <sup>(1)</sup>	I2C1	I2C2
7-bit addressing mode	Х	Х
10-bit addressing mode	X	Х
Standard mode (up to 100 kbit/s)	Х	Х
Fast mode (up to 400 kbit/s)	X	Х
Fast Mode Plus (up to 1 Mbit/s) with 20 mA output drive I/Os	X	-
Independent clock	Х	-



I <sup>2</sup> C features <sup>(1)</sup>	I2C1	I2C2
SMBus	Х	-
Wakeup from STOP	Х	-

Table 9. STM32F051xx I <sup>2</sup> C implementation (	(continued)
--	-------------

1. X = supported.

# 3.17 Universal synchronous/asynchronous receiver/transmitter (USART)

The device embeds up to two universal synchronous/asynchronous receivers/transmitters (USART1, USART2) which communicate at speeds of up to 6 Mbit/s.

They provide hardware management of the CTS, RTS and RS485 DE signals, multiprocessor communication mode, master synchronous communication and single-wire half-duplex communication mode. USART1 supports also SmartCard communication (ISO 7816), IrDA SIR ENDEC, LIN Master/Slave capability and auto baud rate feature, and has a clock domain independent of the CPU clock, allowing to wake up the MCU from Stop mode.

The USART interfaces can be served by the DMA controller.

USART modes/features <sup>(1)</sup>	USART1	USART2
Hardware flow control for modem	Х	Х
Continuous communication using DMA	Х	х
Multiprocessor communication	Х	х
Synchronous mode	Х	х
Smartcard mode	Х	-
Single-wire half-duplex communication	Х	х
IrDA SIR ENDEC block	Х	-
LIN mode	Х	-
Dual clock domain and wakeup from Stop mode	Х	-
Receiver timeout interrupt	Х	-
Modbus communication	Х	-
Auto baud rate detection	Х	-
Driver Enable	Х	х

#### Table 10. STM32F051xx USART implementation

1. X = supported.



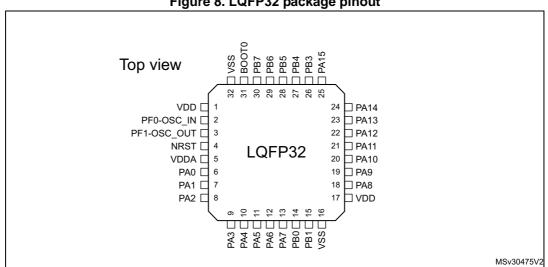
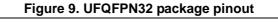
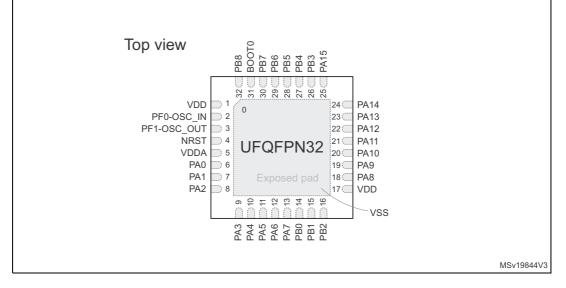


Figure 8. LQFP32 package pinout







	P	Pin nu	umbe	er							Pin functions		
LQFP64	UFBGA64	LQFP48/UFQFPN48	WLCSP36	LQFP32	UFQFPN32	Pin name (function upon reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions		
33	H8	25	-	-	-	PB12	I/O	FT	(5)	SPI2_NSS, TIM1_BKIN, TSC_G6_IO2, EVENTOUT	-		
34	G8	26	-	-	-	PB13	I/O	FT	(5)	SPI2_SCK, TIM1_CH1N, TSC_G6_IO3	-		
35	F8	27	-	-	-	PB14	I/O	FT	(5)	SPI2_MISO, TIM1_CH2N, TIM15_CH1, TSC_G6_IO4	-		
36	F7	28	-	-	-	PB15	I/O	FT	(5)	SPI2_MOSI, TIM1_CH3N, TIM15_CH1N, TIM15_CH2	RTC_REFIN		
37	F6	-	-	-	-	PC6	I/O	FT	-	TIM3_CH1	-		
38	E7	-	-	-	-	PC7	I/O	FT	-	TIM3_CH2	-		
39	E8	-	-	-	-	PC8	I/O	FT	-	TIM3_CH3	-		
40	D8	-	-	-	-	PC9	I/O	FT	-	TIM3_CH4	-		
41	D7	29	E2	18	18	PA8	I/O	FT	-	USART1_CK, TIM1_CH1, EVENTOUT, MCO	-		
42	C7	30	D1	19	19	PA9	I/O	FT	-	USART1_TX, TIM1_CH2, TIM15_BKIN, TSC_G4_IO1	-		
43	C6	31	C1	20	20	PA10	I/O	FT	-	USART1_RX, TIM1_CH3, TIM17_BKIN, TSC_G4_IO2	-		
44	C8	32	C2	21	21	PA11	I/O	FT	-	USART1_CTS, TIM1_CH4, COMP1_OUT, TSC_G4_IO3, EVENTOUT	-		

Table 13. Pin definitions (continued)



Bus	Boundary address	Size	Peripheral
	0x4800 1800 - 0x5FFF FFFF	~384 MB	Reserved
	0x4800 1400 - 0x4800 17FF	1 KB	GPIOF
	0x4800 1000 - 0x4800 13FF	1 KB	Reserved
	0x4800 0C00 - 0x4800 0FFF	1 KB	GPIOD
AHB2 —	0x4800 0800 - 0x4800 0BFF	1 KB	GPIOC
	0x4800 0400 - 0x4800 07FF	1 KB	GPIOB
	0x4800 0000 - 0x4800 03FF	1 KB	GPIOA
	0x4002 4400 - 0x47FF FFFF	~128 MB	Reserved
	0x4002 4000 - 0x4002 43FF	1 KB	TSC
	0x4002 3400 - 0x4002 3FFF	3 KB	Reserved
	0x4002 3000 - 0x4002 33FF	1 KB	CRC
	0x4002 2400 - 0x4002 2FFF	3 KB	Reserved
AHB1	0x4002 2000 - 0x4002 23FF	1 KB	Flash memory interface
	0x4002 1400 - 0x4002 1FFF	3 KB	Reserved
	0x4002 1000 - 0x4002 13FF	1 KB	RCC
	0x4002 0400 - 0x4002 0FFF	3 KB	Reserved
	0x4002 0000 - 0x4002 03FF	1 KB	DMA
	0x4001 8000 - 0x4001 FFFF	32 KB	Reserved
	0x4001 5C00 - 0x4001 7FFF	9 KB	Reserved
	0x4001 5800 - 0x4001 5BFF	1 KB	DBGMCU
	0x4001 4C00 - 0x4001 57FF	3 KB	Reserved
	0x4001 4800 - 0x4001 4BFF	1 KB	TIM17
	0x4001 4400 - 0x4001 47FF	1 KB	TIM16
	0x4001 4000 - 0x4001 43FF	1 KB	TIM15
	0x4001 3C00 - 0x4001 3FFF	1 KB	Reserved
	0x4001 3800 - 0x4001 3BFF	1 KB	USART1
	0x4001 3400 - 0x4001 37FF	1 KB	Reserved
	0x4001 3000 - 0x4001 33FF	1 KB	SPI1/I2S1
APB	0x4001 2C00 - 0x4001 2FFF	1 KB	TIM1
	0x4001 2800 - 0x4001 2BFF	1 KB	Reserved
	0x4001 2400 - 0x4001 27FF	1 KB	ADC
	0x4001 0800 - 0x4001 23FF	7 KB	Reserved
	0x4001 0400 - 0x4001 07FF	1 KB	EXTI
	0x4001 0000 - 0x4001 03FF	1 KB	SYSCFG + COMP
	0x4000 8000 - 0x4000 FFFF	32 KB	Reserved

# Table 16. STM32F051xx peripheral register boundary addresses



# 6 Electrical characteristics

# 6.1 Parameter conditions

Unless otherwise specified, all voltages are referenced to V<sub>SS</sub>.

## 6.1.1 Minimum and maximum values

Unless otherwise specified, the minimum and maximum values are guaranteed in the worst conditions of ambient temperature, supply voltage and frequencies by tests in production on 100% of the devices with an ambient temperature at  $T_A = 25$  °C and  $T_A = T_A max$  (given by the selected temperature range).

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes and are not tested in production. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation (mean  $\pm 3\sigma$ ).

# 6.1.2 Typical values

Unless otherwise specified, typical data are based on  $T_A = 25$  °C,  $V_{DD} = V_{DDA} = 3.3$  V. They are given only as design guidelines and are not tested.

Typical ADC accuracy values are determined by characterization of a batch of samples from a standard diffusion lot over the full temperature range, where 95% of the devices have an error less than or equal to the value indicated (mean  $\pm 2\sigma$ ).

## 6.1.3 Typical curves

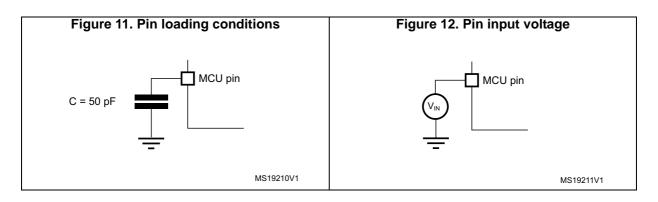
Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

# 6.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in *Figure 11*.

## 6.1.5 Pin input voltage

The input voltage measurement on a pin of the device is described in *Figure 12*.





# 6.2 Absolute maximum ratings

Stresses above the absolute maximum ratings listed in *Table 17: Voltage characteristics*, *Table 18: Current characteristics* and *Table 19: Thermal characteristics* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Symbol	Ratings	Min	Мах	Unit
V <sub>DD</sub> -V <sub>SS</sub>	External main supply voltage	- 0.3	4.0	V
V <sub>DDA</sub> -V <sub>SS</sub>	External analog supply voltage	- 0.3	4.0	V
V <sub>DD</sub> -V <sub>DDA</sub>	Allowed voltage difference for $V_{DD} > V_{DDA}$	-	0.4	V
V <sub>BAT</sub> –V <sub>SS</sub>	External backup supply voltage	- 0.3	4.0	V
	Input voltage on FT and FTf pins	V <sub>SS</sub> - 0.3	V <sub>DDIOx</sub> + 4.0 <sup>(3)</sup>	V
V <sub>IN</sub> <sup>(2)</sup>	Input voltage on TTa pins	V <sub>SS</sub> - 0.3	4.0	V
VIN (	BOOT0	0	9.0	V
	Input voltage on any other pin	V <sub>SS</sub> - 0.3	4.0	V
ΔV <sub>DDx</sub>	Variations between different $V_{DD}$ power pins	-	50	mV
V <sub>SSx</sub> - V <sub>SS</sub>	Variations between all the different ground pins	-	50	mV
		see Section 6.3 sensitivity chara	-	

Table 17. Voltage characteristics <sup>(1)</sup>	)
--	---

1. All main power ( $V_{DD}$ ,  $V_{DDA}$ ) and ground ( $V_{SS}$ ,  $V_{SSA}$ ) pins must always be connected to the external power supply, in the permitted range.

2. V<sub>IN</sub> maximum must always be respected. Refer to *Table 18: Current characteristics* for the maximum allowed injected current values.

3. Valid only if the internal pull-up/pull-down resistors are disabled. If internal pull-up or pull-down resistor is enabled, the maximum limit is 4 V.



	Participante ST. Peripheral current consumption (continued)							
	Peripheral	Typical consumption at 25 °C	Unit					
	APB-Bridge <sup>(2)</sup>	3						
	SYSCFG	3						
	ADC <sup>(3)</sup>	5						
	TIM1	17						
	SPI1	10						
	USART1	19						
	TIM15	11						
	TIM16	8						
	TIM17	8						
	DBG (MCU Debug Support)	0.5						
	TIM2	17						
APB	TIM3	13	µA/MHz					
	TIM6	3						
	TIM14	6						
	WWDG	1						
	SPI2	7						
	USART2	7						
	I2C1	4						
	I2C2	5						
	DAC	2						
	PWR	1						
	CEC	2						
	All APB peripherals	149						

 Table 31. Peripheral current consumption (continued)

1. The BusMatrix automatically is active when at least one master is ON (CPU or DMA1)

2. The APBx Bridge is automatically active when at least one peripheral is ON on the same Bus.

3. The power consumption of the analog part ( $I_{DDA}$ ) of peripherals such as ADC is not included. Refer to the tables of characteristics in the subsequent sections.



#### Software recommendations

The software flowchart must include the management of runaway conditions such as:

- Corrupted program counter
- Unexpected reset
- Critical Data corruption (for example control registers)

#### **Prequalification trials**

Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the NRST pin or the Oscillator pins for 1 second.

To complete these trials, ESD stress can be applied directly on the device, over the range of specification values. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring (see application note AN1015).

#### **Electromagnetic Interference (EMI)**

The electromagnetic field emitted by the device are monitored while a simple application is executed (toggling 2 LEDs through the I/O ports). This emission test is compliant with IEC 61967-2 standard which specifies the test board and the pin loading.

Symbol	Parameter	Conditions	Monitored	Max vs. [f <sub>HSE</sub> /f <sub>HCLK</sub> ]	Unit	
Cymbol			frequency band	8/48 MHz	•	
		$V_{DD}$ = 3.6 V, $T_A$ = 25 °C, LQFP64 package compliant with IEC 61967-2	0.1 to 30 MHz	-3		
0	Peak level		30 to 130 MHz	28	dBµV	
S <sub>EMI</sub>			130 MHz to 1 GHz	23		
			EMI Level	4	-	

#### Table 44. EMI characteristics

# 6.3.12 Electrical sensitivity characteristics

Based on three different tests (ESD, LU) using specific measurement methods, the device is stressed in order to determine its performance in terms of electrical sensitivity.

## **Electrostatic discharge (ESD)**

Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts  $\times$  (n+1) supply pins). This test conforms to the JESD22-A114/C101 standard.

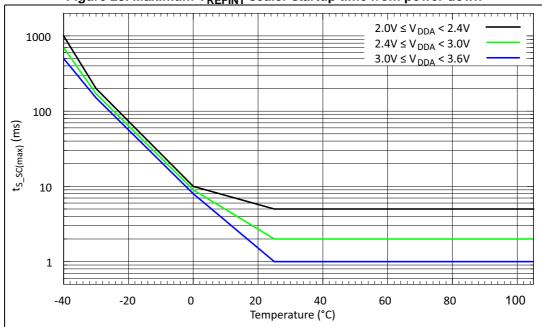


Symbol	Parameter	Conditions		Min <sup>(1)</sup>	Тур	Max <sup>(1)</sup>	Unit
		No hysteresis (COMPxHYST[1:0]=00)	-	-	0	-	
		Low hysteresis (COMPxHYST[1:0]=01)	High speed mode	3		13	
			All other power modes	5	8	10	mV
V <sub>hys</sub>	Comparator hysteresis       Medium hysteresis       High speed mode         (COMPxHYST[1:0]=10)       All other power       modes         High hysteresis       High speed mode       All other power         (COMPxHYST[1:0]=11)       High speed mode       All other power         Medium hysteresis       All other power       All other         Medium hysteresis       All other power       All other         Medium hysteresis       All other       All other         Medium hysteresis       All other       All other         Medium hysteresis       All other       All other         Medium hyster		High speed mode	7	15	26	
				9		19	
		18		49			
			-	19	31	40	

#### Table 56. Comparator characteristics (continued)

1. Data based on characterization results, not tested in production.

2. For more details and conditions see Figure 28: Maximum  $V_{REFINT}$  scaler startup time from power down.



#### Figure 28. Maximum $V_{\text{REFINT}}$ scaler startup time from power down



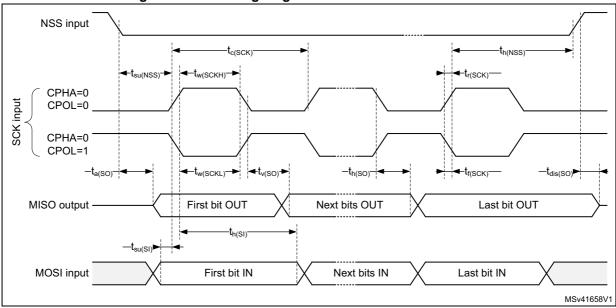
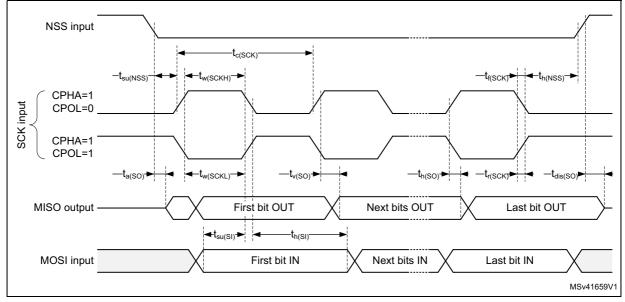


Figure 29. SPI timing diagram - slave mode and CPHA = 0



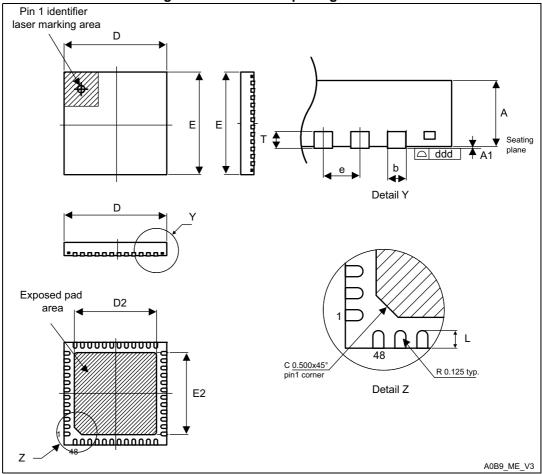


1. Measurement points are done at CMOS levels: 0.3  $V_{\text{DD}}$  and 0.7  $V_{\text{DD}}$ 



# 7.4 UFQFPN48 package information

UFQFPN48 is a 48-lead, 7x7 mm, 0.5 mm pitch, ultra-thin fine-pitch quad flat package.





1. Drawing is not to scale.

- 2. All leads/pads should also be soldered to the PCB to improve the lead/pad solder joint life.
- 3. There is an exposed die pad on the underside of the UFQFPN package. It is recommended to connect and solder this back-side pad to PCB ground.

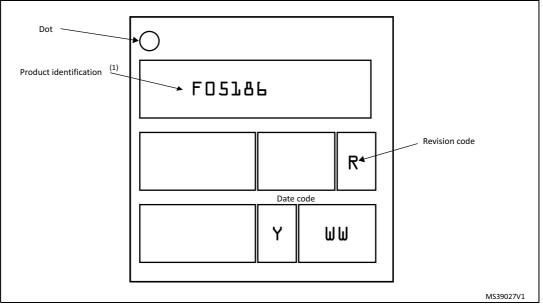




#### **Device marking**

The following figure gives an example of topside marking orientation versus ball A1 identifier location.

Other optional marking or inset/upset marks, which identify the parts throughout supply chain operations, are not indicated below.



#### Figure 48. WLCSP36 package marking example

 Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.



Date	Revision	Changes
Date 13-Jan-2014	Revision 4 (continued)	Added "Negative induced leakage current is caused by negative injection and positive induced leakage current is caused by positive injection" in Section Functional susceptibility to I/O current injection.         Replaced reference "JESD22-C101" with "ANSI/ESD STM5.3.1" in Table : ESD absolute maximum ratings.         Merged Table: Typical and maximum VDD consumption in Stop and Standby modes and Table: Typical and maximum VDDA consumption in Stop and Standby modes into Table: Typical and maximum current consumption in Stop and Standby modes.         Updated:         – Table: Temperature sensor calibration values,         – Table: Internal voltage reference calibration values,         – Table: General operating conditions,         – Table: Urrent characteristics,         – Table: Low-power mode wakeup timings,         – Table: VO current injection susceptibility,         – Table: Vo static characteristics,         – Table: Vo static characteristics,         – Table: NRST pin characteristics,         – Figure: Power supply scheme,         – Figure: TC and TTa I/O input characteristics,         – Figure: HO AC characteristics definition,         – Figure: LOFP64 – 10 x 10 mm 64 pin low-profile quad flat package outline,         – Figure: LOFP64 recommended footprint,         – Figure: LOFP64 recommended fo

Table 76. Document revision history (continued)



Data	Revision	Changes
Date	Revision	Changes
28-Aug-2015	5 (continued)	<ul> <li>Table 31: Peripheral current consumption</li> <li>Addition of WLCSP36 package. Updates in:</li> <li>Section 2: Description</li> <li>Table 2: STM32F051xx family device features and peripheral count</li> <li>Section 4: Pinouts and pin descriptions with the addition of Figure 7: WLCSP36 package pinout</li> <li>Table 13: Pin definitions</li> <li>Table 20: General operating conditions</li> <li>Section 7: Package information with the addition of Section 7.5: WLCSP36 package information</li> <li>Table 74: Package thermal characteristics</li> <li>Section 8: Part numbering</li> <li>Update of the device marking examples in Section 7: Package information.</li> </ul>
16-Dec-2015	6	<ul> <li>Section 2: Description:</li> <li>Table 2: STM32F051xx family device features and peripheral count - number of SPIs corrected for 64-pin packages</li> <li>Figure 1: Block diagram modified</li> <li>Section 3: Functional overview:</li> <li>Figure 2: Clock tree modified; divider for CEC corrected</li> <li>Table 8: Comparison of I<sup>2</sup>C analog and digital filters - adding 20 mA information for FastPlus mode</li> <li>Section 4: Pinouts and pin descriptions:</li> <li>Package pinout figures updated (look and feel)</li> <li>Figure 7: WLCSP36 package pinout - now presented in top view</li> <li>Table 13: Pin definitions - notes added (VSSA corrected to pin 16 on LQFP32); note 5 added</li> <li>Section 5: Memory mapping:</li> <li>added information on STM32F051x4/x6 difference versus STM32F051x8 map in Figure 10</li> <li>Section 6: Electrical characteristics:</li> <li>Table 24: Embedded internal reference voltage - removed - 40°C-85°C temperature range line and the associated note</li> <li>Table 48: I/O static characteristics - removed note</li> <li>Section 6.3.16: 12-bit ADC characteristics - changed introductory sentence</li> <li>Table 52: ADC characteristics updated and table footnotes 3 and 4 added</li> <li>Table 59: TIMx characteristics modified</li> <li>Table 64: I<sup>2</sup>S characteristics reorganized</li> <li>Figure 52: UFQFPN32 package outline - figure footnotes added</li> </ul>

Table 76. Document revision history (continued)



Date	Revision	Changes
06-Jan-2017	7	<ul> <li>Section 6: Electrical characteristics:</li> <li>Table 36: LSE oscillator characteristics (f<sub>LSE</sub> = 32.768 kHz) - information on configuring different drive capabilities removed. See the corresponding reference manual.</li> <li>Table 24: Embedded internal reference voltage - V<sub>REFINT</sub> values</li> <li>Table 55: DAC characteristics - min. R<sub>LOAD</sub> to V<sub>DDA</sub> defined</li> <li>Figure 29: SPI timing diagram - slave mode and CPHA = 0 and Figure 30: SPI timing diagram - slave mode and CPHA = 1 enhanced and corrected</li> <li>Section 8: Ordering information:</li> <li>The name of the section changed from the previous "Part numbering"</li> </ul>

Table 76. Document revision history (continued)

