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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	HDMI-CEC, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	55
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 19x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f051r4t6

# **Contents**

1	Intro	duction		9		
2	Desc	cription		10		
3	Fund	ctional o	verview	13		
	3.1	ARM®-	Cortex®-M0 core	13		
	3.2	Memor	ies	13		
	3.3	Boot m	odes	13		
	3.4	Cyclic r	redundancy check calculation unit (CRC)	14		
	3.5	Power	management	14		
		3.5.1	Power supply schemes	14		
		3.5.2	Power supply supervisors	14		
		3.5.3	Voltage regulator	14		
		3.5.4	Low-power modes	15		
	3.6	Clocks	and startup	15		
	3.7	General-purpose inputs/outputs (GPIOs)				
	3.8	Direct r	memory access controller (DMA)	17		
	3.9	Interrup	ots and events	17		
		3.9.1	Nested vectored interrupt controller (NVIC)	17		
		3.9.2	Extended interrupt/event controller (EXTI)	17		
	3.10	Analog	-to-digital converter (ADC)	17		
		3.10.1	Temperature sensor	18		
		3.10.2	Internal voltage reference (V <sub>REFINT</sub> )			
		3.10.3	V <sub>BAT</sub> battery voltage monitoring	19		
	3.11	Digital-	to-analog converter (DAC)	19		
	3.12	Compa	rators (COMP)	19		
	3.13	Touch s	sensing controller (TSC)	19		
	3.14	Timers	and watchdogs	21		
		3.14.1	Advanced-control timer (TIM1)	21		
		3.14.2	General-purpose timers (TIM2, 3, 14, 15, 16, 17)	22		
		3.14.3	Basic timer TIM6	22		
		3.14.4	Independent watchdog (IWDG)			
		3.14.5	System window watchdog (WWDG)	23		



		3.14.6	SysTick timer	. 23
	3.15	Real-tir	me clock (RTC) and backup registers	. 23
	3.16	Inter-in	tegrated circuit interface (I <sup>2</sup> C)	. 24
	3.17	Univers	sal synchronous/asynchronous receiver/transmitter (USART)	. 25
	3.18		peripheral interface (SPI) / Inter-integrated sound interface (I <sup>2</sup> S)	
	3.19	High-de	efinition multimedia interface (HDMI) - consumer nics control (CEC)	
	3.20	Serial v	wire debug port (SW-DP)	. 26
4	Pino	uts and	pin descriptions	. 27
5	Mem	ory map	oping	. 39
6	Elect	rical ch	aracteristics	. 42
	6.1	Parame	eter conditions	. 42
		6.1.1	Minimum and maximum values	. 42
		6.1.2	Typical values	. 42
		6.1.3	Typical curves	. 42
		6.1.4	Loading capacitor	. 42
		6.1.5	Pin input voltage	. 42
		6.1.6	Power supply scheme	. 43
		6.1.7	Current consumption measurement	. 44
	6.2	Absolu	te maximum ratings	. 45
	6.3	Operati	ing conditions	. 47
		6.3.1	General operating conditions	. 47
		6.3.2	Operating conditions at power-up / power-down	. 47
		6.3.3	Embedded reset and power control block characteristics	. 48
		6.3.4	Embedded reference voltage	. 49
		6.3.5	Supply current characteristics	. 49
		6.3.6	Wakeup time from low-power mode	. 59
		6.3.7	External clock source characteristics	. 59
		6.3.8	Internal clock source characteristics	. 63
		6.3.9	PLL characteristics	. 66
		6.3.10	Memory characteristics	. 66
		6.3.11	EMC characteristics	. 67
		6.3.12	Electrical sensitivity characteristics	. 68
		6.3.13	I/O current injection characteristics	. 69

# List of tables

Table 1.	Device summary	1
Table 2.	STM32F051xx family device features and peripheral count	11
Table 3.	Temperature sensor calibration values	18
Table 4.	Internal voltage reference calibration values	
Table 5.	Capacitive sensing GPIOs available on STM32F051xx devices	20
Table 6.	Effective number of capacitive sensing channels on STM32F051xx	20
Table 7.	Timer feature comparison	
Table 8.	Comparison of I <sup>2</sup> C analog and digital filters	24
Table 9.	STM32F051xx I <sup>2</sup> C implementation	24
Table 10.	STM32F051xx USART implementation	25
Table 11.	STM32F051xx SPI/I <sup>2</sup> S implementation	26
Table 12.	Legend/abbreviations used in the pinout table	31
Table 13.	Pin definitions	31
Table 14.	Alternate functions selected through GPIOA_AFR registers for port A	
Table 15.	Alternate functions selected through GPIOB_AFR registers for port B	38
Table 16.	STM32F051xx peripheral register boundary addresses	40
Table 17.	Voltage characteristics	45
Table 18.	Current characteristics	46
Table 19.	Thermal characteristics	
Table 20.	General operating conditions	
Table 21.	Operating conditions at power-up / power-down	48
Table 22.	Embedded reset and power control block characteristics	48
Table 23.	Programmable voltage detector characteristics	48
Table 24.	Embedded internal reference voltage	49
Table 25.	Typical and maximum current consumption from V <sub>DD</sub> at 3.6 V	50
Table 26.	Typical and maximum current consumption from the V <sub>DDA</sub> supply	51
Table 27.	Typical and maximum current consumption in Stop and Standby modes	52
Table 28.	Typical and maximum current consumption from the V <sub>BAT</sub> supply	53
Table 29.	Typical current consumption, code executing from Flash memory, running from HSE 8 MHz crystal	54
Table 30.	Switching output I/O current consumption	
Table 31.	Peripheral current consumption	
Table 32.	Low-power mode wakeup timings	
Table 33.	High-speed external user clock characteristics	
Table 34.	Low-speed external user clock characteristics	
Table 35.	HSE oscillator characteristics	
Table 36.	LSE oscillator characteristics (f <sub>LSF</sub> = 32.768 kHz)	62
Table 37.	HSI oscillator characteristics	64
Table 38.	HSI14 oscillator characteristics	65
Table 39.	LSI oscillator characteristics	66
Table 40.	PLL characteristics	66
Table 41.	Flash memory characteristics	66
Table 42.	Flash memory endurance and data retention	67
Table 43.	EMS characteristics	
Table 44.	EMI characteristics	
Table 45.	ESD absolute maximum ratings	69
Table 46.	Electrical sensitivities	69
Table 47	I/O current injection susceptibility	70



The I/O configuration can be locked if needed following a specific sequence in order to avoid spurious writing to the I/Os registers.

# 3.8 Direct memory access controller (DMA)

The 5-channel general-purpose DMAs manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers.

The DMA supports circular buffer management, removing the need for user code intervention when the controller reaches the end of the buffer.

Each channel is connected to dedicated hardware DMA requests, with support for software trigger on each channel. Configuration is made by software and transfer sizes between source and destination are independent.

DMA can be used with the main peripherals: SPIx, I2Sx, I2Cx, USARTx, all TIMx timers (except TIM14), DAC and ADC.

# 3.9 Interrupts and events

#### 3.9.1 Nested vectored interrupt controller (NVIC)

The STM32F0xx family embeds a nested vectored interrupt controller able to handle up to 32 maskable interrupt channels (not including the 16 interrupt lines of Cortex -M0) and 4 priority levels.

- Closely coupled NVIC gives low latency interrupt processing
- Interrupt entry vector table address passed directly to the core
- Closely coupled NVIC core interface
- Allows early processing of interrupts
- Processing of late arriving higher priority interrupts
- Support for tail-chaining
- Processor state automatically saved
- Interrupt entry restored on interrupt exit with no instruction overhead

This hardware block provides flexible interrupt management features with minimal interrupt latency.

## 3.9.2 Extended interrupt/event controller (EXTI)

The extended interrupt/event controller consists of 24 edge detector lines used to generate interrupt/event requests and wake-up the system. Each line can be independently configured to select the trigger event (rising edge, falling edge, both) and can be masked independently. A pending register maintains the status of the interrupt requests. The EXTI can detect an external line with a pulse width shorter than the internal clock period. Up to 55 GPIOs can be connected to the 16 external interrupt lines.

# 3.10 Analog-to-digital converter (ADC)

The 12-bit analog-to-digital converter has up to 16 external and 3 internal (temperature



# 3.18 Serial peripheral interface (SPI) / Inter-integrated sound interface (I<sup>2</sup>S)

Up to two SPIs are able to communicate up to 18 Mbit/s in slave and master modes in full-duplex and half-duplex communication modes. The 3-bit prescaler gives 8 master mode frequencies and the frame size is configurable from 4 bits to 16 bits.

One standard I<sup>2</sup>S interface (multiplexed with SPI1) supporting four different audio standards can operate as master or slave at half-duplex communication mode. It can be configured to transfer 16 and 24 or 32 bits with 16-bit or 32-bit data resolution and synchronized by a specific signal. Audio sampling frequency from 8 kHz up to 192 kHz can be set by an 8-bit programmable linear prescaler. When operating in master mode, it can output a clock for an external audio component at 256 times the sampling frequency.

Table 11. OTHIOZI COTAX OF IT O Implementation					
SPI features <sup>(1)</sup>	SPI1	SPI2			
Hardware CRC calculation	Х	Х			
Rx/Tx FIFO	Х	Х			
NSS pulse mode	Х	Х			
I <sup>2</sup> S mode	X	-			
TI mode	Х	Х			

Table 11. STM32F051xx SPI/I<sup>2</sup>S implementation

# 3.19 High-definition multimedia interface (HDMI) - consumer electronics control (CEC)

The device embeds a HDMI-CEC controller that provides hardware support for the Consumer Electronics Control (CEC) protocol (Supplement 1 to the HDMI standard).

This protocol provides high-level control functions between all audiovisual products in an environment. It is specified to operate at low speeds with minimum processing and memory overhead. It has a clock domain independent from the CPU clock, allowing the HDMI\_CEC controller to wakeup the MCU from Stop mode on data reception.

# 3.20 Serial wire debug port (SW-DP)

An ARM SW-DP interface is provided to allow a serial wire debugging tool to be connected to the MCU.

<sup>1.</sup> X = supported.

Table 13. Pin definitions (continued)

	P	in n	umbe	er		Table 13. Fill			•	T .	nctions
LQFP64	UFBGA64	LQFP48/UFQFPN48	WLCSP36	LQFP32	UFQFPN32	Pin name (function upon reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
7	E1	7	D5	4	4	NRST	I/O	RST	-	Device reset input / (active	
8	E3	-	-	-	-	PC0	I/O	TTa	-	EVENTOUT	ADC_IN10
9	E2	-	-	-	-	PC1	I/O	TTa	-	EVENTOUT	ADC_IN11
10	F2	-	-	-	-	PC2	I/O	TTa	-	EVENTOUT	ADC_IN12
11	G1	-	-	-	-	PC3	I/O	TTa	-	EVENTOUT	ADC_IN13
12	F1	8	D6	16	0	VSSA	S	-	(3)	Analog	ground
13	H1	9	E5	5	5	VDDA	S	-	-	Analog pov	wer supply
14	G2	10	F6	6	6	PA0	I/O	ТТа	-	USART2_CTS, TIM2_CH1_ETR, COMP1_OUT, TSC_G1_IO1	ADC_IN0, COMP1_INM6, RTC_TAMP2, WKUP1
15	H2	11	D4	7	7	PA1	I/O	ТТа	-	USART2_RTS, TIM2_CH2, TSC_G1_IO2, EVENTOUT	ADC_IN1, COMP1_INP
16	F3	12	E4	8	8	PA2	I/O	ТТа	-	USART2_TX, TIM2_CH3, TIM15_CH1, COMP2_OUT, TSC_G1_IO3	ADC_IN2, COMP2_INM6
17	G3	13	F5	9	9	PA3	I/O	TTa	-	USART2_RX, TIM2_CH4, TIM15_CH2, TSC_G1_IO4	ADC_IN3, COMP2_INP
18	C2	-	-	-	-	PF4	I/O	FT	-	EVENTOUT	-
19	D2	-	-	-	-	PF5	I/O	FT	-	EVENTOUT	-
20	Н3	14	С3	10	10	PA4	I/O	ТТа	-	SPI1_NSS, I2S1_WS, USART2_CK, TIM14_CH1, TSC_G2_IO1	ADC_IN4, COMP1_INM4, COMP2_INM4, DAC_OUT1
21	F4	15	D3	11	11	PA5	I/O	ТТа	-	SPI1_SCK, I2S1_CK, CEC, TIM2_CH1_ETR, TSC_G2_IO2	ADC_IN5, COMP1_INM5, COMP2_INM5

# 6.3 Operating conditions

## 6.3.1 General operating conditions

Table 20. General operating conditions

Symbol	Parameter Conditions		Min	Max	Unit	
f <sub>HCLK</sub>	Internal AHB clock frequency	-	0	48	MHz	
f <sub>PCLK</sub>	Internal APB clock frequency	-	0	48	IVI⊓∠	
V <sub>DD</sub>	Standard operating voltage	-	2.0	3.6	V	
V	Analog operating voltage (ADC and DAC not used)	Must have a potential equal	$V_{DD}$	3.6	V	
$V_{DDA}$	Analog operating voltage (ADC and DAC used)	to or higher than V <sub>DD</sub>	2.4	3.6	V	
V <sub>BAT</sub>	Backup operating voltage	-	1.65	3.6	V	
		TC and RST I/O	-0.3	V <sub>DDIOx</sub> +0.3		
<b>V</b>	I/O input voltage	TTa I/O	-0.3	V <sub>DDA</sub> +0.3 <sup>(1)</sup>	V	
$V_{IN}$		FT and FTf I/O	-0.3	5.5 <sup>(1)</sup>		
		BOOT0	0	5.5		
		LQFP64	-	444	mW	
		LQFP48	-	364		
	Power dissipation at $T_A$ = 85 °C for suffix 6 or $T_A$ = 105 °C for suffix 7 <sup>(2)</sup>	LQFP32	-	357		
$P_{D}$		UFQFPN32	-	526		
		UFQFPN48	-	625		
		UFBGA64	-	308		
		WLCSP36	-	333		
	Ambient temperature for the	Maximum power dissipation	<del>-4</del> 0	85	°C	
TA	suffix 6 version	Low power dissipation <sup>(3)</sup>	-40	105	C	
IA	Ambient temperature for the	Maximum power dissipation	<b>–40</b>	105	°C	
	suffix 7 version	Low power dissipation <sup>(3)</sup>	-40	125	1	
TJ	Junction temperature range	Suffix 6 version	c 6 version –40		°C	
IJ	Junction temperature range	Suffix 7 version	-40	125	°C	
	•	•		•		

<sup>1.</sup> For operation with a voltage higher than  $V_{DDIOx}$  + 0.3 V, the internal pull-up resistor must be disabled.

## 6.3.2 Operating conditions at power-up / power-down

The parameters given in *Table 21* are derived from tests performed under the ambient temperature condition summarized in *Table 20*.



<sup>2.</sup> If  $T_A$  is lower, higher  $P_D$  values are allowed as long as  $T_J$  does not exceed  $T_{Jmax}$ . See Section 7.8: Thermal characteristics.

In low power dissipation state, T<sub>A</sub> can be extended to this range as long as T<sub>J</sub> does not exceed T<sub>Jmax</sub> (see Section 7.8: Thermal characteristics).

Table 29. Typical current consumption, code executing from Flash memory, running from HSE 8 MHz crystal

Symbol	Parameter	£	Typical con Run i	sumption in mode	Typical con Sleep	Unit	
	raiametei	f <sub>HCLK</sub>	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Oilit
		48 MHz	23.2	13.3	13.2	3.1	
		36 MHz	17.6	10.3	10.1	2.6	
		32 MHz	15.6	9.3	9.0	2.4	
	Current	24 MHz	12.1	7.4	7.0	2.0	
	consumption	16 MHz	8.4	5.1	5.0	1.6	mA
I <sub>DD</sub>	from V <sub>DD</sub> supply	8 MHz	4.5	3.0	2.8	1.1	ША
	supply	4 MHz	2.8	2.0	2.0	1.1	
		2 MHz	1.9	1.5	1.5	1.0	
		1 MHz	1.5	1.3	1.3	1.0	
		500 kHz	1.2	1.2	1.1	1.0	
		48 MHz		1	51		
		36 MHz		1′	13		
		32 MHz		10	01		
	Current	24 MHz		7	9		
l	consumption	16 MHz		5	7		μA
I <sub>DDA</sub>	from V <sub>DDA</sub> supply	8 MHz		2	.2		μΛ
	Supply	4 MHz		2	.2		
		2 MHz		2	.2		
		1 MHz		2	.2		
		500 kHz		2	.2		

#### I/O system current consumption

The current consumption of the I/O system has two components: static and dynamic.

#### I/O static current consumption

All the I/Os used as inputs with pull-up generate current consumption when the pin is externally held low. The value of this current consumption can be simply computed by using the pull-up/pull-down resistors values given in *Table 48: I/O static characteristics*.

For the output pins, any external pull-down or external load must also be considered to estimate the current consumption.

Additional I/O current consumption is due to I/Os configured as inputs if an intermediate voltage level is externally applied. This current consumption is caused by the input Schmitt



#### High-speed external clock generated from a crystal/ceramic resonator

The high-speed external (HSE) clock can be supplied with a 4 to 32 MHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on design simulation results obtained with typical external components specified in *Table 35*. In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Symbol	Parameter	Conditions <sup>(1)</sup>	Min <sup>(2)</sup>	Тур	Max <sup>(2)</sup>	Unit
f <sub>OSC_IN</sub>	Oscillator frequency	-	4	8	32	MHz
R <sub>F</sub>	Feedback resistor	-	-	200	-	kΩ
		During startup <sup>(3)</sup>	-	-	8.5	
		$V_{DD}$ = 3.3 V, Rm = 30 $\Omega$ , CL = 10 pF@8 MHz	-	0.4	-	
		$V_{DD} = 3.3 \text{ V},$ $Rm = 45 \Omega,$ $CL = 10 \text{ pF}@8 \text{ MHz}$	- 0.5 -		-	
I <sub>DD</sub>	HSE current consumption	$V_{DD}$ = 3.3 V, Rm = 30 $\Omega$ , CL = 5 pF@32 MHz	-	0.8	-	mA
		$V_{DD}$ = 3.3 V, Rm = 30 $\Omega$ , CL = 10 pF@32 MHz	-	1	-	
		$V_{DD}$ = 3.3 V, Rm = 30 $\Omega$ , CL = 20 pF@32 MHz	-	1.5	-	
9 <sub>m</sub>	Oscillator transconductance	Startup	10	-	-	mA/V
t <sub>SU(HSE)</sub> <sup>(4)</sup>	Startup time	V <sub>DD</sub> is stabilized	-	2	-	ms

Table 35. HSE oscillator characteristics

For  $C_{L1}$  and  $C_{L2}$ , it is recommended to use high-quality external ceramic capacitors in the 5 pF to 20 pF range (Typ.), designed for high-frequency applications, and selected to match the requirements of the crystal or resonator (see *Figure 17*).  $C_{L1}$  and  $C_{L2}$  are usually the same size. The crystal manufacturer typically specifies a load capacitance which is the series combination of  $C_{L1}$  and  $C_{L2}$ . PCB and MCU pin capacitance must be included (10 pF can be used as a rough estimate of the combined pin and board capacitance) when sizing  $C_{L1}$  and  $C_{L2}$ .

Note:

For information on selecting the crystal, refer to the application note AN2867 "Oscillator design guide for ST microcontrollers" available from the ST website www.st.com.



<sup>1.</sup> Resonator characteristics given by the crystal/ceramic resonator manufacturer.

<sup>2.</sup> Guaranteed by design, not tested in production.

<sup>3.</sup> This consumption level occurs during the first 2/3 of the  $t_{\text{SU(HSE)}}$  startup time

<sup>4.</sup> t<sub>SU(HSE)</sub> is the startup time measured from the moment it is enabled (by software) to a stabilized 8 MHz oscillation is reached. This value is measured for a standard crystal resonator and it can vary significantly with the crystal manufacturer

Note:

For information on selecting the crystal, refer to the application note AN2867 "Oscillator design guide for ST microcontrollers" available from the ST website www.st.com.

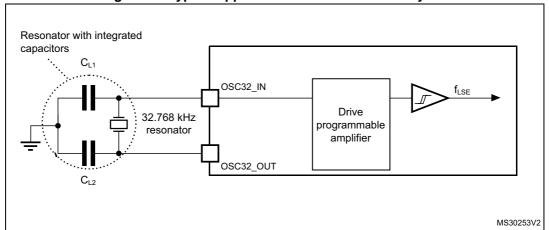


Figure 18. Typical application with a 32.768 kHz crystal

Note:

An external resistor is not required between OSC32\_IN and OSC32\_OUT and it is forbidden to add one.

#### 6.3.8 Internal clock source characteristics

The parameters given in *Table 37* are derived from tests performed under ambient temperature and supply voltage conditions summarized in *Table 20: General operating conditions*. The provided curves are characterization results, not tested in production.

Symbol	Parameter	Conditions	Min <sup>(1)</sup>	Unit	
N <sub>END</sub>	Endurance	$T_A = -40 \text{ to } +105 ^{\circ}\text{C}$	10	kcycle	
	Data retention	1 kcycle <sup>(2)</sup> at T <sub>A</sub> = 85 °C	30		
t <sub>RET</sub>		1 kcycle <sup>(2)</sup> at T <sub>A</sub> = 105 °C	10	Year	
		10 kcycle <sup>(2)</sup> at T <sub>A</sub> = 55 °C	20		

Table 42. Flash memory endurance and data retention

#### 6.3.11 EMC characteristics

Susceptibility tests are performed on a sample basis during device characterization.

#### Functional EMS (electromagnetic susceptibility)

While a simple application is executed on the device (toggling 2 LEDs through I/O ports). the device is stressed by two electromagnetic events until a failure occurs. The failure is indicated by the LEDs:

- Electrostatic discharge (ESD) (positive and negative) is applied to all device pins until a functional disturbance occurs. This test is compliant with the IEC 61000-4-2 standard.
- FTB: A Burst of Fast Transient voltage (positive and negative) is applied to V<sub>DD</sub> and V<sub>SS</sub> through a 100 pF capacitor, until a functional disturbance occurs. This test is compliant with the IEC 61000-4-4 standard.

A device reset allows normal operations to be resumed.

The test results are given in *Table 43*. They are based on the EMS levels and classes defined in application note AN1709.

Symbol	Parameter	Conditions	Level/ Class
V <sub>FESD</sub>	Voltage limits to be applied on any I/O pin to induce a functional disturbance	$V_{DD}$ = 3.3 V, LQFP64, $T_{A}$ = +25 °C, $f_{HCLK}$ = 48 MHz, conforming to IEC 61000-4-2	2B
V <sub>EFTB</sub>	Fast transient voltage burst limits to be applied through 100 pF on V <sub>DD</sub> and V <sub>SS</sub> pins to induce a functional disturbance	$V_{DD}$ = 3.3 V, LQFP64, $T_A$ = +25°C, $f_{HCLK}$ = 48 MHz, conforming to IEC 61000-4-4	4B

Table 43. EMS characteristics

## Designing hardened software to avoid noise problems

EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. It should be noted that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user applies EMC software optimization and prequalification tests in relation with the EMC level requested for his application.



<sup>1.</sup> Data based on characterization results, not tested in production.

<sup>2.</sup> Cycling performed over the whole temperature range.

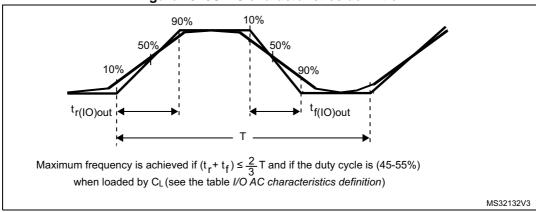


Figure 23. I/O AC characteristics definition

## 6.3.15 NRST pin characteristics

The NRST pin input driver uses the CMOS technology. It is connected to a permanent pull-up resistor,  $R_{\text{PU}}$ .

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature and supply voltage conditions summarized in *Table 20: General operating conditions*.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit		
V <sub>IL(NRST)</sub>	NRST input low level voltage	-	-	-	0.3 V <sub>DD</sub> +0.07 <sup>(1)</sup>	V		
V <sub>IH(NRST)</sub>	NRST input high level voltage	-	0.445 V <sub>DD</sub> +0.398 <sup>(1)</sup>	-	-	, v		
V <sub>hys(NRST)</sub>	NRST Schmitt trigger voltage hysteresis	-	-	200	-	mV		
R <sub>PU</sub>	Weak pull-up equivalent resistor <sup>(2)</sup>	V <sub>IN</sub> = V <sub>SS</sub>	25	40	55	kΩ		
V <sub>F(NRST)</sub>	NRST input filtered pulse	-	-	-	100 <sup>(1)</sup>	ns		
V <sub>NF(NRST)</sub>	NRST input not filtered pulse	2.7 < V <sub>DD</sub> < 3.6	300 <sup>(3)</sup>	-	-	ns		
	TWIST Input not intered pulse	2.0 < V <sub>DD</sub> < 3.6	500 <sup>(3)</sup>	-	-	115		

Table 51. NRST pin characteristics

<sup>1.</sup> Data based on design simulation only. Not tested in production.

<sup>2.</sup> The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance is minimal (~10% order).

<sup>3.</sup> Data based on design simulation only. Not tested in production.

Prescaler divider	PR[2:0] bits	Min timeout RL[11:0]= 0x000	Max timeout RL[11:0]= 0xFFF	Unit
/4	0	0.1	409.6	
/8	1	0.2	819.2	
/16	2	0.4	1638.4	
/32	3	0.8	3276.8	ms
/64	4	1.6	6553.6	
/128	5	3.2	13107.2	
/256	6 or 7	6.4	26214.4	

Table 60. IWDG min/max timeout period at 40 kHz (LSI)<sup>(1)</sup>

These timings are given for a 40 kHz clock but the microcontroller internal RC frequency can vary from 30 to 60 kHz. Moreover, given an exact RC oscillator frequency, the exact timings still depend on the phasing of the APB interface clock versus the LSI clock so that there is always a full RC period of uncertainty.

Table 01: WWD0 IIIII/IIIax tillicoat Valde at 40 IIII 2 (1 0217)					
Prescaler	WDGTB	Min timeout value	Max timeout value	Unit	
1	0	0.0853	5.4613		
2	1	0.1706	10.9226	me	
4	2	0.3413	21.8453	ms	
8	3	0.6826	43.6906		

Table 61. WWDG min/max timeout value at 48 MHz (PCLK)

#### 6.3.22 Communication interfaces

## I<sup>2</sup>C interface characteristics

The I<sup>2</sup>C interface meets the timings requirements of the I<sup>2</sup>C-bus specification and user manual rev. 03 for:

- Standard-mode (Sm): with a bit rate up to 100 kbit/s
- Fast-mode (Fm): with a bit rate up to 400 kbit/s
- Fast-mode Plus (Fm+): with a bit rate up to 1 Mbit/s.

The I<sup>2</sup>C timings requirements are guaranteed by design when the I2Cx peripheral is properly configured (refer to Reference manual).

The SDA and SCL I/O requirements are met with the following restrictions: the SDA and SCL I/O pins are not "true" open-drain. When configured as open-drain, the PMOS connected between the I/O pin and  $V_{\rm DDIOX}$  is disabled, but is still present. Only FTf I/O pins support Fm+ low level output current maximum requirement. Refer to Section 6.3.14: I/O port characteristics for the I<sup>2</sup>C I/Os characteristics.

All I<sup>2</sup>C SDA and SCL I/Os embed an analog filter. Refer to the table below for the analog filter characteristics:

# 7 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK<sup>®</sup> packages, depending on their level of environmental compliance. ECOPACK<sup>®</sup> specifications, grade definitions and product status are available at: <a href="https://www.st.com">www.st.com</a>. ECOPACK<sup>®</sup> is an ST trademark.

# 7.1 UFBGA64 package information

UFBGA64 is a 64-ball, 5 x 5 mm, 0.5 mm pitch ultra-fine-profile ball grid array package.

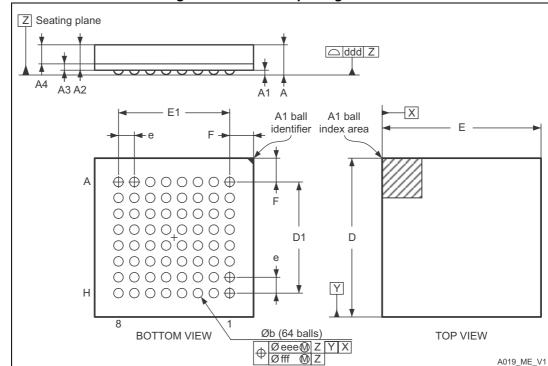


Figure 34. UFBGA64 package outline

1. Drawing is not to scale.

Table 65. UFBGA64 package mechanical data

Symbol	millimeters			inches <sup>(1)</sup>		
Symbol	Min	Тур	Max	Min	Тур	Max
А	0.460	0.530	0.600	0.0181	0.0209	0.0236
A1	0.050	0.080	0.110	0.0020	0.0031	0.0043
A2	0.400	0.450	0.500	0.0157	0.0177	0.0197
A3	0.080	0.130	0.180	0.0031	0.0051	0.0071
A4	0.270	0.320	0.370	0.0106	0.0126	0.0146



Table 68. LQFP48 package mechanical data

0	millimeters			inches <sup>(1)</sup>		
Symbol	Min	Тур	Max	Min	Тур	Max
Α	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
С	0.090	-	0.200	0.0035	-	0.0079
D	8.800	9.000	9.200	0.3465	0.3543	0.3622
D1	6.800	7.000	7.200	0.2677	0.2756	0.2835
D3	-	5.500	-	-	0.2165	-
E	8.800	9.000	9.200	0.3465	0.3543	0.3622
E1	6.800	7.000	7.200	0.2677	0.2756	0.2835
E3	-	5.500	-	-	0.2165	-
е	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7°	0°	3.5°	7°
CCC	-	-	0.080	-	-	0.0031

<sup>1.</sup> Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 41. Recommended footprint for LQFP48 package 9.70 ai14911d

1. Dimensions are expressed in millimeters.

# 7.6 LQFP32 package information

LQFP32 is a 32-pin, 7 x 7 mm low-profile quad flat package.

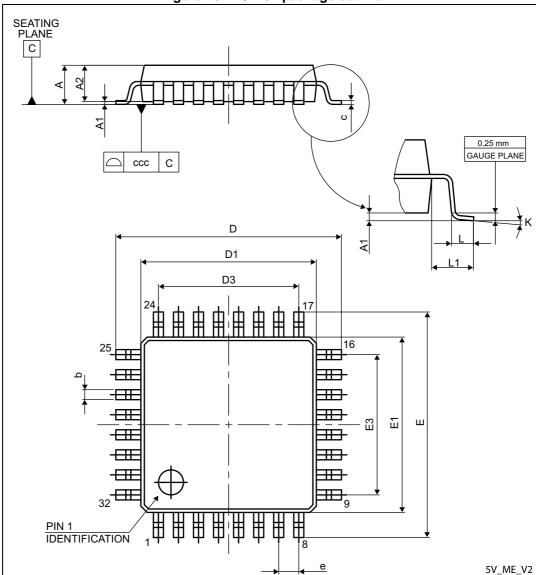


Figure 49. LQFP32 package outline

1. Drawing is not to scale.



### 7.8 Thermal characteristics

The maximum chip junction temperature (T<sub>J</sub>max) must never exceed the values given in *Table 20: General operating conditions*.

The maximum chip-junction temperature,  $T_J$  max, in degrees Celsius, may be calculated using the following equation:

$$T_J \max = T_A \max + (P_D \max x \Theta_{JA})$$

#### Where:

- T<sub>A</sub> max is the maximum ambient temperature in °C,
- Θ<sub>JA</sub> is the package junction-to-ambient thermal resistance, in °C/W,
- $P_D$  max is the sum of  $P_{INT}$  max and  $P_{I/O}$  max ( $P_D$  max =  $P_{INT}$  max +  $P_{I/O}$ max),
- P<sub>INT</sub> max is the product of I<sub>DD</sub> and V<sub>DD</sub>, expressed in Watts. This is the maximum chip internal power.

P<sub>I/O</sub> max represents the maximum power dissipation on output pins where:

$$P_{I/O}$$
 max =  $\Sigma (V_{OL} \times I_{OL}) + \Sigma ((V_{DDIOx} - V_{OH}) \times I_{OH})$ ,

taking into account the actual  $V_{OL}$  /  $I_{OL}$  and  $V_{OH}$  /  $I_{OH}$  of the I/Os at low and high level in the application.

Symbol	Parameter	Value	Unit
	Thermal resistance junction-ambient LQFP64 - 10 × 10 mm / 0.5 mm pitch	45	
	Thermal resistance junction-ambient LQFP48 - 7 × 7 mm	55	
$\Theta_{JA}$	Thermal resistance junction-ambient LQFP32 - 7 × 7 mm	56	
	Thermal resistance junction-ambient UFBGA64 - 5 × 5 mm	65	°C/W
	Thermal resistance junction-ambient UFQFPN48 - 7 × 7 mm	32	
	Thermal resistance junction-ambient UFQFPN32 - 5 × 5 mm	38	
	Thermal resistance junction-ambient WLCSP36 - 2.6 × 2.7 mm	60	

Table 74. Package thermal characteristics

#### 7.8.1 Reference document

JESD51-2 Integrated Circuits Thermal Test Method Environment Conditions - Natural Convection (Still Air). Available from www.jedec.org

## 7.8.2 Selecting the product temperature range

When ordering the microcontroller, the temperature range is specified in the ordering information scheme shown in *Section 8: Ordering information*.



Each temperature range suffix corresponds to a specific guaranteed ambient temperature at maximum dissipation and, to a specific maximum junction temperature.

As applications do not commonly use the STM32F051xx at maximum dissipation, it is useful to calculate the exact power consumption and junction temperature to determine which temperature range will be best suited to the application.

The following examples show how to calculate the temperature range needed for a given application.

### **Example 1: High-performance application**

Assuming the following application conditions:

Maximum ambient temperature  $T_{Amax}$  = 82 °C (measured according to JESD51-2),  $I_{DDmax}$  = 50 mA,  $V_{DD}$  = 3.5 V, maximum 20 I/Os used at the same time in output at low level with  $I_{OL}$  = 8 mA,  $V_{OL}$ = 0.4 V and maximum 8 I/Os used at the same time in output at low level with  $I_{OL}$  = 20 mA,  $V_{OL}$ = 1.3 V

 $P_{INTmax} = 50 \text{ mA} \times 3.5 \text{ V} = 175 \text{ mW}$ 

 $P_{IOmax} = 20 \times 8 \text{ mA} \times 0.4 \text{ V} + 8 \times 20 \text{ mA} \times 1.3 \text{ V} = 272 \text{ mW}$ 

This gives: P<sub>INTmax</sub> = 175 mW and P<sub>IOmax</sub> = 272 mW:

 $P_{Dmax} = 175 + 272 = 447 \text{ mW}$ 

Using the values obtained in *Table 74*  $T_{Jmax}$  is calculated as follows:

For LQFP64, 45 °C/W

 $T_{\text{lmax}}$  = 82 °C + (45 °C/W × 447 mW) = 82 °C + 20.115 °C = 102.115 °C

This is within the range of the suffix 6 version parts ( $-40 < T_J < 105$  °C) see *Table 20: General operating conditions*.

In this case, parts must be ordered at least with the temperature range suffix 6 (see Section 8: Ordering information).

Note:

With this given  $P_{Dmax}$  we can find the  $T_{Amax}$  allowed for a given device temperature range (order code suffix 6 or 7).

```
Suffix 6: T_{Amax} = T_{Jmax} - (45^{\circ}\text{C/W} \times 447 \text{ mW}) = 105\text{-}20.115 = 84.885 ^{\circ}\text{C}
Suffix 7: T_{Amax} = T_{Jmax} - (45^{\circ}\text{C/W} \times 447 \text{ mW}) = 125\text{-}20.115 = 104.885 ^{\circ}\text{C}
```

#### **Example 2: High-temperature application**

Using the same rules, it is possible to address applications that run at high ambient temperatures with a low dissipation, as long as junction temperature  $T_J$  remains within the specified range.

Assuming the following application conditions:

Maximum ambient temperature  $T_{Amax}$  = 100 °C (measured according to JESD51-2),  $I_{DDmax}$  = 20 mA,  $V_{DD}$  = 3.5 V, maximum 20 I/Os used at the same time in output at low level with  $I_{OL}$  = 8 mA,  $V_{OL}$ = 0.4 V

 $P_{INTmax}$  = 20 mA × 3.5 V= 70 mW

 $P_{IOmax} = 20 \times 8 \text{ mA} \times 0.4 \text{ V} = 64 \text{ mW}$ 

This gives:  $P_{INTmax} = 70 \text{ mW}$  and  $P_{IOmax} = 64 \text{ mW}$ :

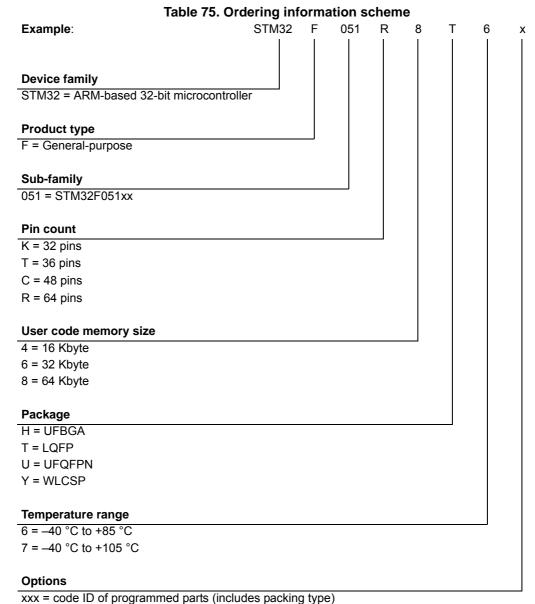
 $P_{Dmax} = 70 + 64 = 134 \text{ mW}$ 

Thus:  $P_{Dmax} = 134 \text{ mW}$ 



#### **Ordering information** 8

For a list of available options (memory, package, and so on) or for further information on any aspect of this device, please contact your nearest ST sales office.



TR = tape and reel packing

blank = tray packing

Table 76. Document revision history (continued)

Date	Revision	Changes		
Date	Kevision			
28-Aug-2015	5	Updated the following:  DAC and power management feature descriptions in Features  Table 2: STM32F051xx family device features and peripheral count  Section 3.5.1: Power supply schemes  Figure 13: Power supply scheme  Table 17: Voltage characteristics  Table 20: General operating conditions: updated the footnote for V <sub>IN</sub> parameter  Table 28: Typical and maximum current consumption from the V <sub>BAT</sub> supply  Table 52: ADC characteristics  Table 33: High-speed external user clock characteristics: replaced V <sub>DD</sub> with V <sub>DDIOX</sub> Table 34: Low-speed external user clock characteristics: replaced V <sub>DD</sub> with V <sub>DDIOX</sub> Table 37: HSI oscillator characteristics and Figure 19: HSI oscillator accuracy characterization results for soldered parts  Table 38: HSI14 oscillator characteristics: changed the min value for ACC <sub>HSI14</sub> Table 41: Flash memory characteristics: changed the values for t <sub>ME</sub> and I <sub>DD</sub> in write mode  Table 43: EMS characteristics: changed the value of V <sub>EFTB</sub> Table 45: ESD absolute maximum ratings  Figure 10: STM32F051x8 memory map  Figure 21: TC and TTa I/O input characteristics  Figure 22: Five volt tolerant (FT and FTf) I/O input characteristics  Figure 23: I/O AC characteristics definition  tstart definition in Table 24: Embedded internal reference voltage  tstart definition in Table 24: Embedded internal reference voltage  tstart definition in Table 52: ADC characteristics  Table 56: Comparator characteristics: changed the description and values for V <sub>SC</sub> , V <sub>DDA</sub> and V <sub>REFINT</sub> scaler startup time from power down  Table 57: TS characteristics: changed the min value for T <sub>S-vbat</sub> and the typical value for R parameters  Section 6.3.22: Communication interfaces: updated the description and features in the subsection I <sup>2</sup> C interface characteristics:  Table 64: FS characteristics: updated the min values for data input hold time (master and slave receiver)		

