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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Not For New Designs
Core Processor	RX
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I ² C, SCI, SPI, USB
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	30
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 10x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-WFQFN Exposed Pad
Supplier Device Package	48-HWQFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f51115adne-ua

Table 1.1 Outline of Specifications (3/3)

Classification	Module/Function	Description
Communication function	USB 2.0 host/function module (USBc)	<ul style="list-style-type: none"> USB Device Controller (UDC) and transceiver for USB 2.0 are incorporated. Host (32-Kbyte or more ROM)/function module: 1 port Compliant with USB version 2.0 Transfer speed: Full-speed (12 Mbps), low-speed (1.5 Mbps) OTG (On-The-Go) is supported. Isochronous transfer is supported. BC (Battery Charger) is supported.
12-bit A/D converter (S12ADb)		<ul style="list-style-type: none"> 1 unit (1 unit × 14 channels) 12-bit resolution Minimum conversion time: 1.0 µs per channel when the ADCLK is operating at 32 MHz Operating modes Scan mode (single scan mode, continuous scan mode, and group scan mode) Double trigger mode (duplication of A/D conversion data) A/D conversion start conditions A software trigger, a trigger from a timer (MTU), an external trigger signal, or ELC
Temperature sensor (TEMPSA)		<ul style="list-style-type: none"> 1 channel The voltage of the temperature is converted into a digital value by the 12-bit A/D converter.
D/A converter (DA)		<ul style="list-style-type: none"> 2 channels 8-bit resolution Output voltage: 0 V to VCC
CRC calculator (CRC)		<ul style="list-style-type: none"> CRC code generation for arbitrary amounts of data in 8-bit units Select any of three generating polynomials: $X^8 + X^2 + X + 1$, $X^{16} + X^{15} + X^2 + 1$, or $X^{16} + X^{12} + X^5 + 1$ Generation of CRC codes for use with LSB first or MSB first communications is selectable.
Data operation circuit (DOC)		Comparison, addition, and subtraction of 16-bit data
Unique ID		32-byte ID code for the MCU
Power supply voltages/Operating frequencies		VCC = 1.8 to 2.4 V: 8 MHz, VCC = 2.4 to 2.7 V: 16 MHz, VCC = 2.7 to 3.6 V: 32 MHz
Supply current		3.2 mA at 32 MHz (typ.)
Operating temperature range		D version: -40 to +85°C, G version: -40 to +105°C
Packages		64-pin LFQFP (PLQP0064KB-A) 10 × 10 mm, 0.5 mm pitch 64-pin LQFP (PLQP0064GA-A) 14 × 14 mm, 0.8 mm pitch 64-pin WFLGA (PWLG0064KA-A) 5 × 5 mm, 0.5 mm pitch 48-pin LFQFP (PLQP0048KB-A) 7 × 7 mm, 0.5 mm pitch 48-pin HWQFN (PWQN0048KB-A) 7 × 7 mm, 0.5 mm pitch 40-pin HWQFN (PWQN0040KC-A) 6 × 6 mm, 0.50 mm pitch 36-pin WFLGA (PWLG0036KA-A) 4 × 4 mm, 0.5 mm pitch
On-chip debugging system		E1 emulator (FINE interface)

2.1 General-Purpose Registers (R0 to R15)

This CPU has 16 general-purpose registers (R0 to R15). R0 to R15 can be used as data registers or address registers. R0, a general-purpose register, also functions as the stack pointer (SP). The stack pointer is switched to operate as the interrupt stack pointer (ISP) or user stack pointer (USP) by the value of the stack pointer select bit (U) in the processor status word (PSW).

2.2 Control Registers

(1) Interrupt Stack Pointer (ISP)/User Stack Pointer (USP)

The stack pointer (SP) can be either of two types, the interrupt stack pointer (ISP) or the user stack pointer (USP). Whether the stack pointer operates as the ISP or USP depends on the value of the stack pointer select bit (U) in the processor status word (PSW).

Set the ISP or USP to a multiple of 4, as this reduces the numbers of cycles required to execute interrupt sequences and instructions entailing stack manipulation.

(2) Interrupt Table Register (INTB)

The interrupt table register (INTB) specifies the address where the relocatable vector table starts.

(3) Program Counter (PC)

The program counter (PC) indicates the address of the instruction being executed.

(4) Processor Status Word (PSW)

The processor status word (PSW) indicates the results of instruction execution or the state of the CPU.

(5) Backup PC (BPC)

The backup PC (BPC) is provided to speed up response to interrupts.

After a fast interrupt has been generated, the contents of the program counter (PC) are saved in the BPC register.

(6) Backup PSW (BPSW)

The backup PSW (BPSW) is provided to speed up response to interrupts.

After a fast interrupt has been generated, the contents of the processor status word (PSW) are saved in the BPSW. The allocation of bits in the BPSW corresponds to that in the PSW.

(7) Fast Interrupt Vector Register (FINTV)

The fast interrupt vector register (FINTV) is provided to speed up response to interrupts.

The FINTV register specifies a branch destination address when a fast interrupt has been generated.

2.3 Register Associated with DSP Instructions

(1) Accumulator (ACC)

The accumulator (ACC) is a 64-bit register used for DSP instructions. The accumulator is also used for the multiply and multiply-and-accumulate instructions; EMUL, EMULU, MUL, and RMPA, in which case the prior value in the accumulator is modified by execution of the instruction.

Use the MVTACHI and MVTACLO instructions for writing to the accumulator. The MVTACHI and MVTACLO instructions write data to the higher-order 32 bits (bits 63 to 32) and the lower-order 32 bits (bits 31 to 0), respectively.

Use the MVFACHI and MVFACMI instructions for reading data from the accumulator. The MVFACHI and MVFACMI instructions read data from the higher-order 32 bits (bits 63 to 32) and the middle 32 bits (bits 47 to 16), respectively.

4.1 I/O Register Addresses (Address Order)

Table 4.1 List of I/O Registers (Address Order) (1/16)

Address	Module Symbol	Register Name	Register Symbol	Number of Bits	Access Size	Number of Access States
0008 0000h	SYSTEM	Mode Monitor Register	MDMONR	16	16	3 ICLK
0008 0008h	SYSTEM	System Control Register 1	SYSCTR1	16	16	3 ICLK
0008 000Ch	SYSTEM	Standby Control Register	SBYCR	16	16	3 ICLK
0008 0010h	SYSTEM	Module Stop Control Register A	MSTPCRA	32	32	3 ICLK
0008 0014h	SYSTEM	Module Stop Control Register B	MSTPCRB	32	32	3 ICLK
0008 0018h	SYSTEM	Module Stop Control Register C	MSTPCRC	32	32	3 ICLK
0008 0020h	SYSTEM	System Clock Control Register	SCKCR	32	32	3 ICLK
0008 0026h	SYSTEM	System Clock Control Register 3	SCKCR3	16	16	3 ICLK
0008 0028h	SYSTEM	PLL Control Register	PLLCR	16	16	3 ICLK
0008 002Ah	SYSTEM	PLL Control Register 2	PLLCR2	8	8	3 ICLK
0008 0032h	SYSTEM	Main Clock Oscillator Control Register	MOSCCR	8	8	3 ICLK
0008 0033h	SYSTEM	Sub-Clock Oscillator Control Register	SOSCCR	8	8	3 ICLK
0008 0034h	SYSTEM	Low-Speed On-Chip Oscillator Control Register	LOCOCR	8	8	3 ICLK
0008 0035h	SYSTEM	IWDT-Dedicated On-Chip Oscillator Control Register	ILOCOCR	8	8	3 ICLK
0008 0036h	SYSTEM	High-Speed On-Chip Oscillator Control Register	HOCOCR	8	8	3 ICLK
0008 003Ch	SYSTEM	Oscillation Stabilization Flag Register	OSCOVFSR	8	8	3 ICLK
0008 003Eh	SYSTEM	CLKOUT Output Control Register	CKOCR	16	16	3 ICLK
0008 0040h	SYSTEM	Oscillation Stop Detection Control Register	OSTDCR	8	8	3 ICLK
0008 0041h	SYSTEM	Oscillation Stop Detection Status Register	OSTDSR	8	8	3 ICLK
0008 00A0h	SYSTEM	Operating Power Control Register	OPCCR	8	8	3 ICLK
0008 00A1h	SYSTEM	Sleep Mode Return Clock Source Switching Register	RSTCKCR	8	8	3 ICLK
0008 00A2h	SYSTEM	Main Clock Oscillator Wait Control Register	MOSCWTCR	8	8	3 ICLK
0008 00A5h	SYSTEM	High-Speed On-Chip Oscillator Wait Control Register	HOCOWTCR	8	8	3 ICLK
0008 00AAh	SYSTEM	Sub Operating Power Control Register	SOPCCR	8	8	3 ICLK
0008 00C0h	SYSTEM	Reset Status Register 2	RSTS2R	8	8	3 ICLK
0008 00C2h	SYSTEM	Software Reset Register	SWRR	16	16	3 ICLK
0008 00E0h	SYSTEM	Voltage Monitoring 1 Circuit Control Register 1	LVD1CR1	8	8	3 ICLK
0008 00E1h	SYSTEM	Voltage Monitoring 1 Circuit Status Register	LVD1SR	8	8	3 ICLK
0008 00E2h	SYSTEM	Voltage Monitoring 2 Circuit Control Register 1	LVD2CR1	8	8	3 ICLK
0008 00E3h	SYSTEM	Voltage Monitoring 2 Circuit Status Register	LVD2SR	8	8	3 ICLK
0008 03FEh	SYSTEM	Protect Register	PRCR	16	16	3 ICLK
0008 1300h	BSC	Bus Error Status Clear Register	BERCLR	8	8	2 ICLK
0008 1304h	BSC	Bus Error Monitoring Enable Register	BEREN	8	8	2 ICLK
0008 1308h	BSC	Bus Error Status Register 1	BERSR1	8	8	2 ICLK
0008 130Ah	BSC	Bus Error Status Register 2	BERSR2	16	16	2 ICLK
0008 1310h	BSC	Bus Priority Control Register	BUSPRI	16	16	2 ICLK
0008 2400h	DTC	DTC Control Register	DTCCR	8	8	2 ICLK
0008 2404h	DTC	DTC Vector Base Register	DTCVBR	32	32	2 ICLK
0008 2408h	DTC	DTC Address Mode Register	DTCADMOD	8	8	2 ICLK
0008 240Ch	DTC	DTC Module Start Register	DTCST	8	8	2 ICLK
0008 240Eh	DTC	DTC Status Register	DTCSTS	16	16	2 ICLK
0008 7010h	ICU	Interrupt Request Register 016	IR016	8	8	2 ICLK
0008 701Bh	ICU	Interrupt Request Register 027	IR027	8	8	2 ICLK
0008 701Ch	ICU	Interrupt Request Register 028	IR028	8	8	2 ICLK
0008 701Dh	ICU	Interrupt Request Register 029	IR029	8	8	2 ICLK
0008 7020h	ICU	Interrupt Request Register 032	IR032	8	8	2 ICLK
0008 7021h	ICU	Interrupt Request Register 033	IR033	8	8	2 ICLK
0008 7022h	ICU	Interrupt Request Register 034	IR034	8	8	2 ICLK
0008 7024h	ICU	Interrupt Request Register 036	IR036	8	8	2 ICLK
0008 7025h	ICU	Interrupt Request Register 037	IR037	8	8	2 ICLK

Table 4.1 List of I/O Registers (Address Order) (10/16)

Address	Module Symbol	Register Name	Register Symbol	Number of Bits	Access Size	Number of Access States
0008 A025h	SCI1	Receive Data Register	RDR	8	8	2 or 3 PCLKB
0008 A026h	SCI1	Smart Card Mode Register	SCMR	8	8	2 or 3 PCLKB
0008 A027h	SCI1	Serial Extended Mode Register	SEMR	8	8	2 or 3 PCLKB
0008 A028h	SCI1	Noise Filter Setting Register	SNFR	8	8	2 or 3 PCLKB
0008 A029h	SCI1	I ² C Mode Register 1	SIMR1	8	8	2 or 3 PCLKB
0008 A02Ah	SCI1	I ² C Mode Register 2	SIMR2	8	8	2 or 3 PCLKB
0008 A02Bh	SCI1	I ² C Mode Register 3	SIMR3	8	8	2 or 3 PCLKB
0008 A02Ch	SCI1	I ² C Status Register	SISR	8	8	2 or 3 PCLKB
0008 A02Dh	SCI1	SPI Mode Register	SPMR	8	8	2 or 3 PCLKB
0008 A0A0h	SCI5	Serial Mode Register	SMR	8	8	2 or 3 PCLKB
0008 A0A1h	SCI5	Bit Rate Register	BRR	8	8	2 or 3 PCLKB
0008 A0A2h	SCI5	Serial Control Register	SCR	8	8	2 or 3 PCLKB
0008 A0A3h	SCI5	Transmit Data Register	TDR	8	8	2 or 3 PCLKB
0008 A0A4h	SCI5	Serial Status Register	SSR	8	8	2 or 3 PCLKB
0008 A0A5h	SCI5	Receive Data Register	RDR	8	8	2 or 3 PCLKB
0008 A0A6h	SCI5	Smart Card Mode Register	SCMR	8	8	2 or 3 PCLKB
0008 A0A7h	SCI5	Serial Extended Mode Register	SEMR	8	8	2 or 3 PCLKB
0008 A0A8h	SCI5	Noise Filter Setting Register	SNFR	8	8	2 or 3 PCLKB
0008 A0A9h	SCI5	I ² C Mode Register 1	SIMR1	8	8	2 or 3 PCLKB
0008 A0AAh	SCI5	I ² C Mode Register 2	SIMR2	8	8	2 or 3 PCLKB
0008 A0ABh	SCI5	I ² C Mode Register 3	SIMR3	8	8	2 or 3 PCLKB
0008 A0ACh	SCI5	I ² C Status Register	SISR	8	8	2 or 3 PCLKB
0008 A0ADh	SCI5	SPI Mode Register	SPMR	8	8	2 or 3 PCLKB
0008 B000h	CAC	CAC Control Register 0	CACR0	8	8	2 or 3 PCLKB
0008 B001h	CAC	CAC Control Register 1	CACR1	8	8	2 or 3 PCLKB
0008 B002h	CAC	CAC Control Register 2	CACR2	8	8	2 or 3 PCLKB
0008 B003h	CAC	CAC Interrupt Request Enable Register	CAICR	8	8	2 or 3 PCLKB
0008 B004h	CAC	CAC Status Register	CASTR	8	8	2 or 3 PCLKB
0008 B006h	CAC	CAC Upper-Limit Value Setting Register	CAULVR	16	16	2 or 3 PCLKB
0008 B008h	CAC	CAC Lower-Limit Value Setting Register	CALLVR	16	16	2 or 3 PCLKB
0008 B00Ah	CAC	CAC Counter Buffer Register	CACNTBR	16	16	2 or 3 PCLKB
0008 B080h	DOC	DOC Control Register	DOCR	8	8	2 or 3 PCLKB
0008 B082h	DOC	DOC Data Input Register	DODIR	16	16	2 or 3 PCLKB
0008 B084h	DOC	DOC Data Setting Register	DODSR	16	16	2 or 3 PCLKB
0008 B100h	ELC	Event Link Control Register	ELCR	8	8	2 or 3 PCLKB
0008 B102h	ELC	Event Link Setting Register 1	ELSR1	8	8	2 or 3 PCLKB
0008 B103h	ELC	Event Link Setting Register 2	ELSR2	8	8	2 or 3 PCLKB
0008 B104h	ELC	Event Link Setting Register 3	ELSR3	8	8	2 or 3 PCLKB
0008 B105h	ELC	Event Link Setting Register 4	ELSR4	8	8	2 or 3 PCLKB
0008 B108h	ELC	Event Link Setting Register 7	ELSR7	8	8	2 or 3 PCLKB
0008 B110h	ELC	Event Link Setting Register 15	ELSR15	8	8	2 or 3 PCLKB
0008 B111h	ELC	Event Link Setting Register 16	ELSR16	8	8	2 or 3 PCLKB
0008 B113h	ELC	Event Link Setting Register 18	ELSR18	8	8	2 or 3 PCLKB
0008 B115h	ELC	Event Link Setting Register 20	ELSR20	8	8	2 or 3 PCLKB
0008 B117h	ELC	Event Link Setting Register 22	ELSR22	8	8	2 or 3 PCLKB
0008 B119h	ELC	Event Link Setting Register 24	ELSR24	8	8	2 or 3 PCLKB
0008 B11Ah	ELC	Event Link Setting Register 25	ELSR25	8	8	2 or 3 PCLKB
0008 B11Fh	ELC	Event Link Option Setting Register A	ELOPA	8	8	2 or 3 PCLKB
0008 B120h	ELC	Event Link Option Setting Register B	ELOPB	8	8	2 or 3 PCLKB
0008 B121h	ELC	Event Link Option Setting Register C	ELOPC	8	8	2 or 3 PCLKB
0008 B123h	ELC	Port Group Setting Register 1	PGR1	8	8	2 or 3 PCLKB
0008 B125h	ELC	Port Group Control Register 1	PGC1	8	8	2 or 3 PCLKB

Table 4.1 List of I/O Registers (Address Order) (11/16)

Address	Module Symbol	Register Name	Register Symbol	Number of Bits	Access Size	Number of Access States
0008 B127h	ELC	Port Buffer Register 1	PDBF1	8	8	2 or 3 PCLKB
0008 B129h	ELC	Event Link Port Setting Register 0	PEL0	8	8	2 or 3 PCLKB
0008 B12Ah	ELC	Event Link Port Setting Register 1	PEL1	8	8	2 or 3 PCLKB
0008 B12Dh	ELC	Event Link Software Event Generation Register	ELSEGR	8	8	2 or 3 PCLKB
0008 B300h	SCI12	Serial Mode Register	SMR	8	8	2 or 3 PCLKB
0008 B301h	SCI12	Bit Rate Register	BRR	8	8	2 or 3 PCLKB
0008 B302h	SCI12	Serial Control Register	SCR	8	8	2 or 3 PCLKB
0008 B303h	SCI12	Transmit Data Register	TDR	8	8	2 or 3 PCLKB
0008 B304h	SCI12	Serial Status Register	SSR	8	8	2 or 3 PCLKB
0008 B305h	SCI12	Receive Data Register	RDR	8	8	2 or 3 PCLKB
0008 B306h	SCI12	Smart Card Mode Register	SCMR	8	8	2 or 3 PCLKB
0008 B307h	SCI12	Serial Extended Mode Register	SEMR	8	8	2 or 3 PCLKB
0008 B308h	SCI12	Noise Filter Setting Register	SNFR	8	8	2 or 3 PCLKB
0008 B309h	SCI12	I ² C Mode Register 1	SIMR1	8	8	2 or 3 PCLKB
0008 B30Ah	SCI12	I ² C Mode Register 2	SIMR2	8	8	2 or 3 PCLKB
0008 B30Bh	SCI12	I ² C Mode Register 3	SIMR3	8	8	2 or 3 PCLKB
0008 B30Ch	SCI12	I ² C Status Register	SISR	8	8	2 or 3 PCLKB
0008 B30Dh	SCI12	SPI Mode Register	SPMR	8	8	2 or 3 PCLKB
0008 B320h	SCI12	Extended Serial Mode Enable Register	ESMER	8	8	2 or 3 PCLKB
0008 B321h	SCI12	Control Register 0	CR0	8	8	2 or 3 PCLKB
0008 B322h	SCI12	Control Register 1	CR1	8	8	2 or 3 PCLKB
0008 B323h	SCI12	Control Register 2	CR2	8	8	2 or 3 PCLKB
0008 B324h	SCI12	Control Register 3	CR3	8	8	2 or 3 PCLKB
0008 B325h	SCI12	Port Control Register	PCR	8	8	2 or 3 PCLKB
0008 B326h	SCI12	Interrupt Control Register	ICR	8	8	2 or 3 PCLKB
0008 B327h	SCI12	Status Register	STR	8	8	2 or 3 PCLKB
0008 B328h	SCI12	Status Clear Register	STCR	8	8	2 or 3 PCLKB
0008 B329h	SCI12	Control Field 0 Data Register	CF0DR	8	8	2 or 3 PCLKB
0008 B32Ah	SCI12	Control Field 0 Compare Enable Register	CF0CR	8	8	2 or 3 PCLKB
0008 B32Bh	SCI12	Control Field 0 Receive Data Register	CF0RR	8	8	2 or 3 PCLKB
0008 B32Ch	SCI12	Primary Control Field 1 Data Register	PCF1DR	8	8	2 or 3 PCLKB
0008 B32Dh	SCI12	Secondary Control Field 1 Data Register	SCF1DR	8	8	2 or 3 PCLKB
0008 B32Eh	SCI12	Control Field 1 Compare Enable Register	CF1CR	8	8	2 or 3 PCLKB
0008 B32Fh	SCI12	Control Field 1 Receive Data Register	CF1RR	8	8	2 or 3 PCLKB
0008 B330h	SCI12	Timer Control Register	TCR	8	8	2 or 3 PCLKB
0008 B331h	SCI12	Timer Mode Register	TMR	8	8	2 or 3 PCLKB
0008 B332h	SCI12	Timer Prescaler Register	TPRE	8	8	2 or 3 PCLKB
0008 B333h	SCI12	Timer Count Register	TCNT	8	8	2 or 3 PCLKB
0008 C000h	PORT0	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C001h	PORT1	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C002h	PORT2	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C003h	PORT3	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C004h	PORT4	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C005h	PORT5	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C00Ah	PORTA	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C00Bh	PORTB	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C00Ch	PORTC	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C00Eh	PORTE	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C012h	PORTJ	Port Direction Register	PDR	8	8	2 or 3 PCLKB
0008 C020h	PORT0	Port Output Data Register	PODR	8	8	2 or 3 PCLKB
0008 C021h	PORT1	Port Output Data Register	PODR	8	8	2 or 3 PCLKB
0008 C022h	PORT2	Port Output Data Register	PODR	8	8	2 or 3 PCLKB

Table 4.1 List of I/O Registers (Address Order) (14/16)

Address	Module Symbol	Register Name	Register Symbol	Number of Bits	Access Size	Number of Access States
0008 C19Fh	MPC	PB7 Pin Function Control Register	PB7PFS	8	8	2 or 3 PCLKB
0008 C1A2h	MPC	PC2 Pin Function Control Register	PC2PFS	8	8	2 or 3 PCLKB
0008 C1A3h	MPC	PC3 Pin Function Control Register	PC3PFS	8	8	2 or 3 PCLKB
0008 C1A4h	MPC	PC4 Pin Function Control Register	PC4PFS	8	8	2 or 3 PCLKB
0008 C1A5h	MPC	PC5 Pin Function Control Register	PC5PFS	8	8	2 or 3 PCLKB
0008 C1A6h	MPC	PC6 Pin Function Control Register	PC6PFS	8	8	2 or 3 PCLKB
0008 C1A7h	MPC	PC7 Pin Function Control Register	PC7PFS	8	8	2 or 3 PCLKB
0008 C1B0h	MPC	PE0 Pin Function Control Register	PE0PFS	8	8	2 or 3 PCLKB
0008 C1B1h	MPC	PE1 Pin Function Control Register	PE1PFS	8	8	2 or 3 PCLKB
0008 C1B2h	MPC	PE2 Pin Function Control Register	PE2PFS	8	8	2 or 3 PCLKB
0008 C1B3h	MPC	PE3 Pin Function Control Register	PE3PFS	8	8	2 or 3 PCLKB
0008 C1B4h	MPC	PE4 Pin Function Control Register	PE4PFS	8	8	2 or 3 PCLKB
0008 C1B5h	MPC	PE5 Pin Function Control Register	PE5PFS	8	8	2 or 3 PCLKB
0008 C1B6h	MPC	PE6 Pin Function Control Register	PE6PFS	8	8	2 or 3 PCLKB
0008 C1B7h	MPC	PE7 Pin Function Control Register	PE7PFS	8	8	2 or 3 PCLKB
0008 C1D6h	MPC	PJ6 Pin Function Control Register	PJ6PFS	8	8	2 or 3 PCLKB
0008 C1D7h	MPC	PJ7 Pin Function Control Register	PJ7PFS	8	8	2 or 3 PCLKB
0008 C290h	SYSTEM	Reset Status Register 0	RSTSR0	8	8	4 or 5 PCLKB
0008 C291h	SYSTEM	Reset Status Register 1	RSTSR1	8	8	4 or 5 PCLKB
0008 C293h	SYSTEM	Main Clock Oscillator Forced Oscillation Control Register	MOFCR	8	8	4 or 5 PCLKB
0008 C297h	SYSTEM	Voltage Monitoring Circuit Control Register	LVCMPCR	8	8	4 or 5 PCLKB
0008 C298h	SYSTEM	Voltage Detection Level Select Register	LVDLVLR	8	8	4 or 5 PCLKB
0008 C29Ah	SYSTEM	Voltage Monitoring 1 Circuit Control Register 0	LVD1CR0	8	8	4 or 5 PCLKB
0008 C29Bh	SYSTEM	Voltage Monitoring 2 Circuit Control Register 0	LVD2CR0	8	8	4 or 5 PCLKB
0008 C400h	RTC	64-Hz Counter	R64CNT	8	8	2 or 3 PCLKB
0008 C402h	RTC	Second Counter	RSECCNT	8	8	2 or 3 PCLKB
0008 C402h	RTC	Binary Counter 0	BCNT0	8	8	2 or 3 PCLKB
0008 C404h	RTC	Minute Counter	RMINCNT	8	8	2 or 3 PCLKB
0008 C404h	RTC	Binary Counter 1	BCNT1	8	8	2 or 3 PCLKB
0008 C406h	RTC	Hour Counter	RHRCNT	8	8	2 or 3 PCLKB
0008 C406h	RTC	Binary Counter 2	BCNT2	8	8	2 or 3 PCLKB
0008 C408h	RTC	Day-Of-Week Counter	RWKCNT	8	8	2 or 3 PCLKB
0008 C408h	RTC	Binary Counter 3	BCNT3	8	8	2 or 3 PCLKB
0008 C40Ah	RTC	Date Counter	RDAYCNT	8	8	2 or 3 PCLKB
0008 C40Ch	RTC	Month Counter	RMONCNT	8	8	2 or 3 PCLKB
0008 C40Eh	RTC	Year Counter	RYRCNT	16	16	2 or 3 PCLKB
0008 C410h	RTC	Second Alarm Register	RSECAR	8	8	2 or 3 PCLKB
0008 C410h	RTC	Binary Counter 0 Alarm Register	BCNT0AR	8	8	2 or 3 PCLKB
0008 C412h	RTC	Minute Alarm Register	RMINAR	8	8	2 or 3 PCLKB
0008 C412h	RTC	Binary Counter 1 Alarm Register	BCNT1AR	8	8	2 or 3 PCLKB
0008 C414h	RTC	Hour Alarm Register	RHRAR	8	8	2 or 3 PCLKB
0008 C414h	RTC	Binary Counter 2 Alarm Register	BCNT2AR	8	8	2 or 3 PCLKB
0008 C416h	RTC	Day-of-Week Alarm Register	RWKAR	8	8	2 or 3 PCLKB
0008 C416h	RTC	Binary Counter 3 Alarm Register	BCNT3AR	8	8	2 or 3 PCLKB
0008 C418h	RTC	Date Alarm Register	RDAYAR	8	8	2 or 3 PCLKB
0008 C418h	RTC	Binary Counter 0 Alarm Enable Register	BCNT0AER	8	8	2 or 3 PCLKB
0008 C41Ah	RTC	Month Alarm Register	RMONAR	8	8	2 or 3 PCLKB
0008 C41Ah	RTC	Binary Counter 1 Alarm Enable Register	BCNT1AER	8	8	2 or 3 PCLKB
0008 C41Ch	RTC	Year Alarm Register	RYRAR	16	16	2 or 3 PCLKB
0008 C41Ch	RTC	Binary Counter 2 Alarm Enable Register	BCNT2AER	16	16	2 or 3 PCLKB
0008 C41Eh	RTC	Year Alarm Enable Register	RYRAREN	8	8	2 or 3 PCLKB
0008 C41Eh	RTC	Binary Counter 3 Alarm Enable Register	BCNT3AER	8	8	2 or 3 PCLKB

5. Electrical Characteristics

5.1 Absolute Maximum Ratings

Table 5.1 Absolute Maximum Ratings

Conditions: VSS = AVSS0 = VREFL0 = VSS_USB = 0 V

Item		Symbol	Value	Unit
Power supply voltage		VCC, VCC_USB	-0.3 to +4.6	V
Input voltage	Ports for 5 V tolerant* ¹	V _{in}	-0.3 to +6.5	V
	Ports P40 to P44, P46, ports PJ6, PJ7	V _{in}	-0.3 to AVCC0 +0.3	V
	Ports other than above	V _{in}	-0.3 to VCC +0.3	V
Reference power supply voltage		VREFH0	-0.3 to AVCC0 +0.3	V
Analog power supply voltage		AVCC0	-0.3 to +4.6	V
Analog input voltage		V _{AN}	-0.3 to AVCC0 +0.3 (when AN000 to AN004 and AN006 used) -0.3 to VCC + 0.3 (when AN008 to AN015 used)	V
Operating temperature* ²		T _{opr}	-40 to +85 -40 to +105	°C
Storage temperature		T _{stg}	-55 to +125	°C

Caution: Permanent damage to the MCU may result if absolute maximum ratings are exceeded.

To preclude any malfunctions due to noise interference, insert capacitors of high frequency characteristics between the VCC and VSS pins, between the AVCC0 and AVSS0 pins, between the VCC_USB and VSS_USB pins, and between the VREFH0 and VREFL0 pins. Place capacitors of about 0.1 µF as close as possible to every power supply pin and use the shortest and heaviest possible traces. Also, connect capacitors as stabilization capacitance.

Connect the VCL pin to a VSS pin via a 4.7 µF capacitor. The capacitor must be placed close to the pin, refer to section 5.12.1, Connecting VCL Capacitor and Bypass Capacitors.

Do not input signals or an I/O pull-up power supply to ports other than 5-V tolerant ports while the device is not powered. The current injection that results from input of such a signal or I/O pull-up may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements.

If input voltage (within the specified range from -0.3 to + 6.5V) is applied to 5-V tolerant ports, it will not cause problems such as damage to the MCU.

Note 1. Ports P16, P17, PA6, and PB0 are 5 V tolerant.

Note 2. The upper limit of operating temperature is 85°C or 105°C, depending on the product. For details, refer to 1.2 List of Products.

Table 5.2 Operating Conditions

Item	Symbol	Conditions	Min.	Typ.	Max.	Unit
Power supply voltages	VCC* ¹	When USB not used	1.8	—	3.6	V
		When USB used	3.0	—	3.6	V
	VSS		—	0	—	V
USB power supply voltages	VCC_USB		—	VCC	—	V
	VSS_USB		—	0	—	V
Analog power supply voltages	AVCC0* ^{1, *2}		1.8	—	3.6	V
	AVSS0		—	0	—	V
	VREFH0		1.8	—	AVCC0	V
	VREFL0		—	0	—	V

Note 1. When powering on AVCC0 and VCC, power them on at the same time or VCC first.

Note 2. For details, refer to section 30.7.10, Voltage Range of Analog Power Supply Pins in the User's Manual: Hardware.

Table 5.4 DC Characteristics (2)Conditions: $1.8 \text{ V} \leq \text{VCC} = \text{VCC_USB} < 2.7 \text{ V}$, $1.8 \text{ V} \leq \text{AVSS0} < 2.7 \text{ V}$, $\text{VSS} = \text{AVSS0} = \text{VSS_USB} = 0 \text{ V}$, $T_a = -40 \text{ to } +105^\circ\text{C}$

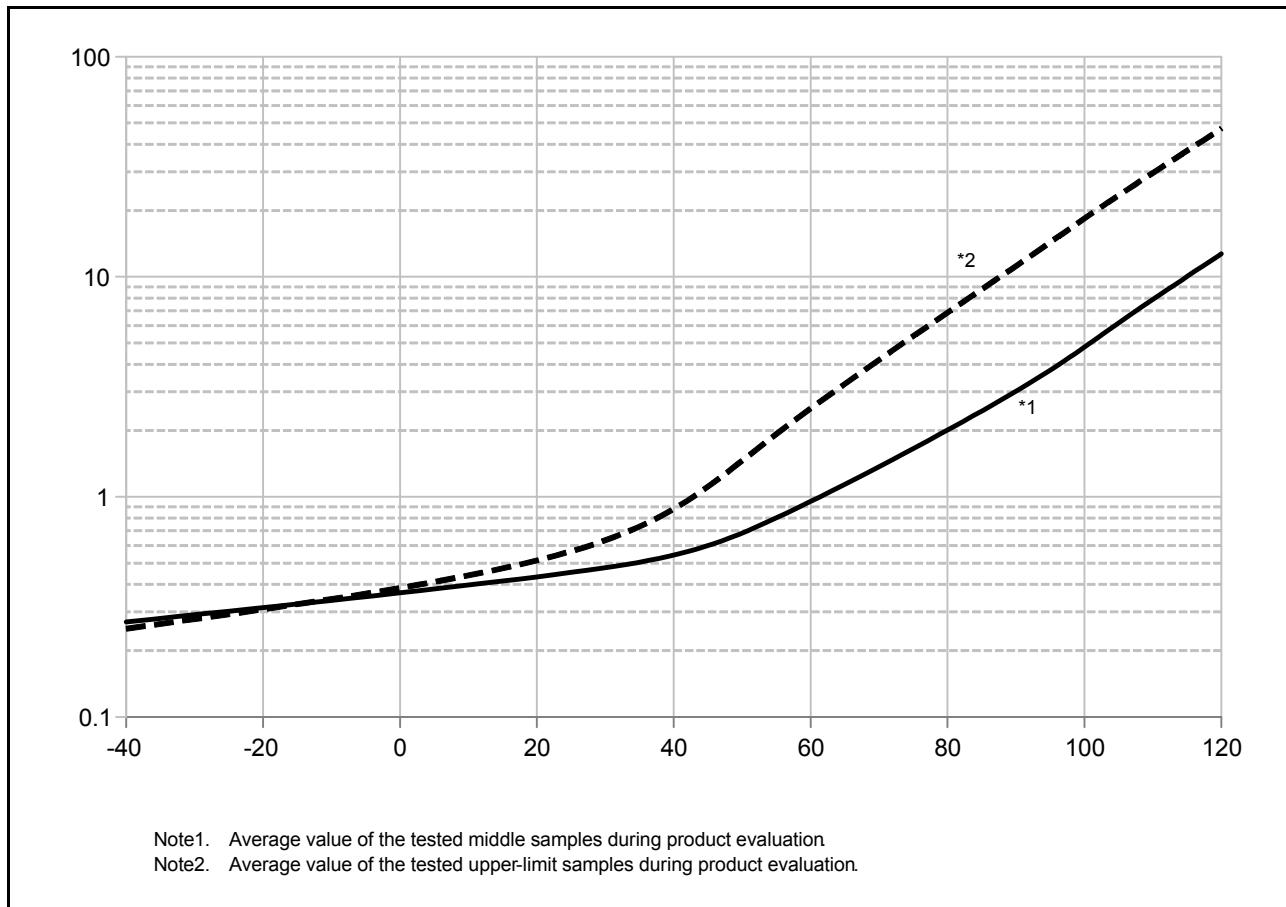
Item	Symbol	Min.	Typ.	Max.	Unit	Test Conditions
Schmitt trigger input voltage	V_{IH}	$\text{VCC} \times 0.8$	—	5.8	V	
		$\text{VCC} \times 0.8$	—	$\text{VCC} + 0.3$		
	All pins	—0.3	—	$\text{VCC} \times 0.2$		
	ΔV_T	$\text{VCC} \times 0.01$	—	—		
Input voltage (except for Schmitt trigger input pins)	V_{IH}	$\text{VCC} \times 0.9$	—	$\text{VCC} + 0.3$	V	
		$\text{VCC} \times 0.8$	—	$\text{VCC} + 0.3$		
		$\text{AVCC0} \times 0.7$	—	$\text{AVCC0} + 0.3$		
	V_{IL}	—0.3	—	$\text{VCC} \times 0.1$		
		—0.3	—	$\text{VCC} \times 0.2$		
		—0.3	—	$\text{AVCC0} \times 0.3$		

Table 5.5 DC Characteristics (3)Conditions: $1.8 \text{ V} \leq \text{VCC} = \text{VCC_USB} \leq 3.6 \text{ V}$, $1.8 \text{ V} \leq \text{AVSS0} \leq 3.6 \text{ V}$, $\text{VSS} = \text{AVSS0} = \text{VSS_USB} = 0 \text{ V}$, $T_a = -40 \text{ to } +105^\circ\text{C}$

Item	Symbol	Min.	Typ.	Max.	Unit	Test Conditions
Input leakage current	$ I_{in} $	—	—	1.0	μA	$V_{in} = 0 \text{ V}, \text{VCC}$
Three-state leakage current (off-state)	$ I_{TSI} $	—	—	1.0	μA	$V_{in} = 0 \text{ V}, 5.8 \text{ V}$
		—	—	1.0		$V_{in} = 0 \text{ V}, \text{VCC}$
Input capacitance	C_{in}	—	—	15	pF	$V_{in} = 0 \text{ mV},$ $\text{Frequency: } 1 \text{ MHz},$ $T_a = 25^\circ\text{C}$
		—	—	30		

Table 5.6 DC Characteristics (4)Conditions: $1.8 \text{ V} \leq \text{VCC} = \text{VCC_USB} \leq 3.6 \text{ V}$, $1.8 \text{ V} \leq \text{AVSS0} \leq 3.6 \text{ V}$, $\text{VSS} = \text{AVSS0} = \text{VSS_USB} = 0 \text{ V}$, $T_a = -40 \text{ to } +105^\circ\text{C}$

Item	Symbol	Min.	Typ.	Max.	Unit	Test Conditions
Input pull-up resistor	R_U	10	20	100	$\text{k}\Omega$	$V_{in} = 0 \text{ V}$

**Figure 5.10 Temperature Dependency in Software Standby Mode (Reference Data)****Table 5.11 DC Characteristics (9)**Conditions: $1.8 \text{ V} \leq \text{VCC} = \text{VCC_USB} \leq 3.6 \text{ V}$, $1.8 \text{ V} \leq \text{AVCC0} \leq 3.6 \text{ V}$, $\text{VSS} = \text{AVSS0} = \text{VSS_USB} = 0 \text{ V}$

Item	Symbol	Typ.	Max.	Unit	Test Conditions
Permissible total consumption power* ¹	Pd	—	300	mW	D version ($T_a = -40 \text{ to } 85^\circ\text{C}$)
		—	105		G version ($T_a = -40 \text{ to } 105^\circ\text{C}$)* ²

Note 1. Total power dissipated by the entire chip (including output currents).

Note 2. Please contact Renesas Electronics sales office for derating under $T_a = +85^\circ\text{C}$ to 105°C . Derating is the systematic reduction of load for the sake of improved reliability.

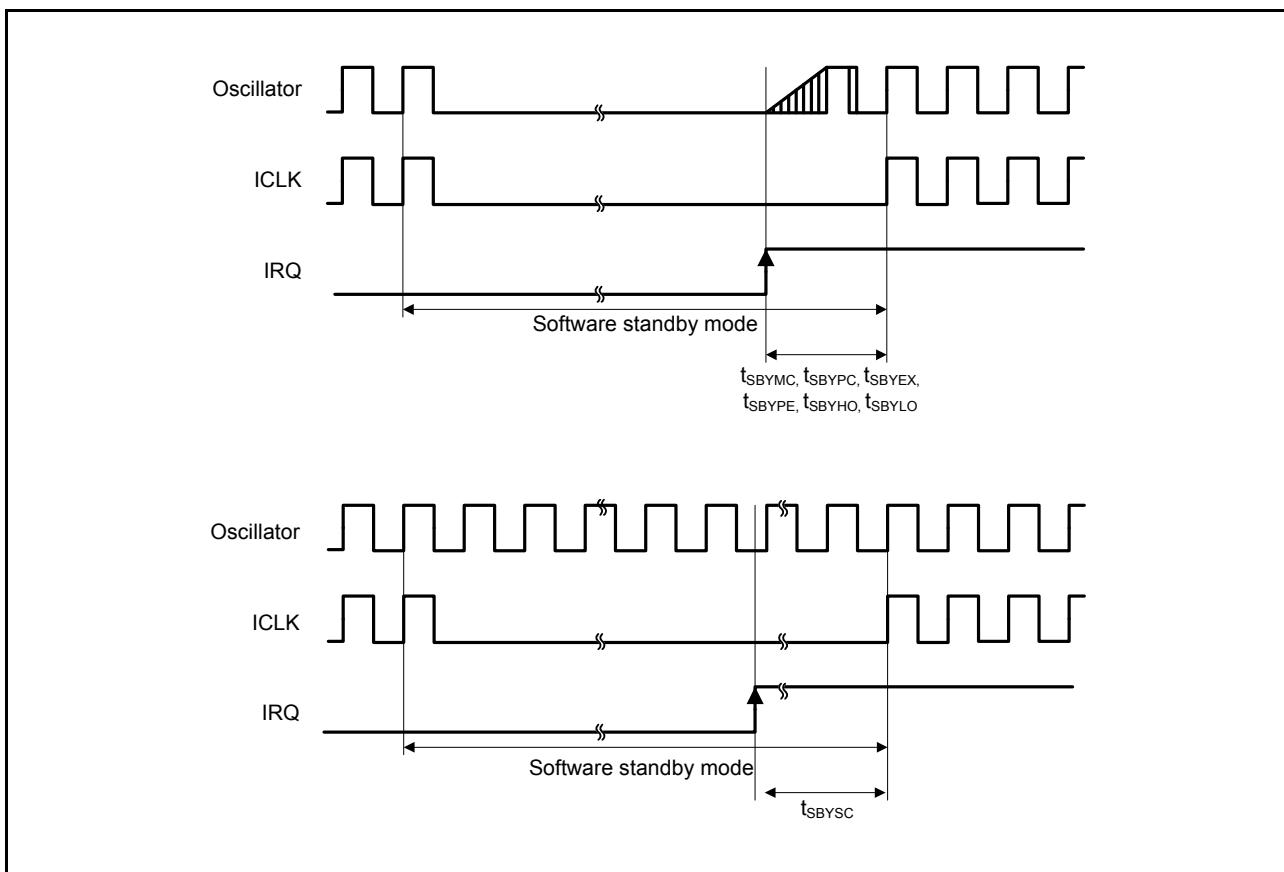
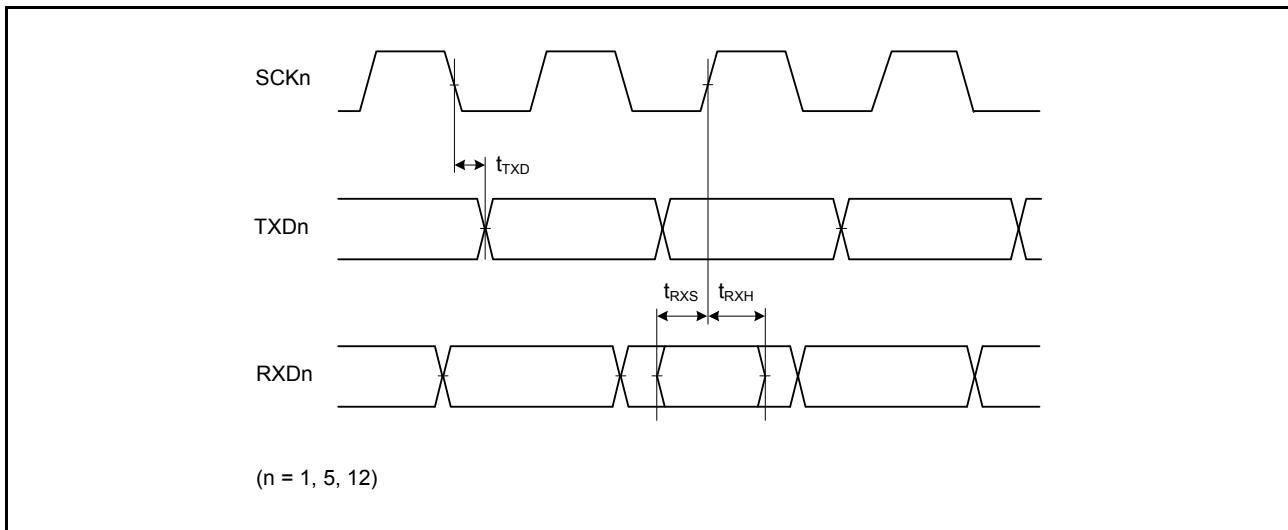
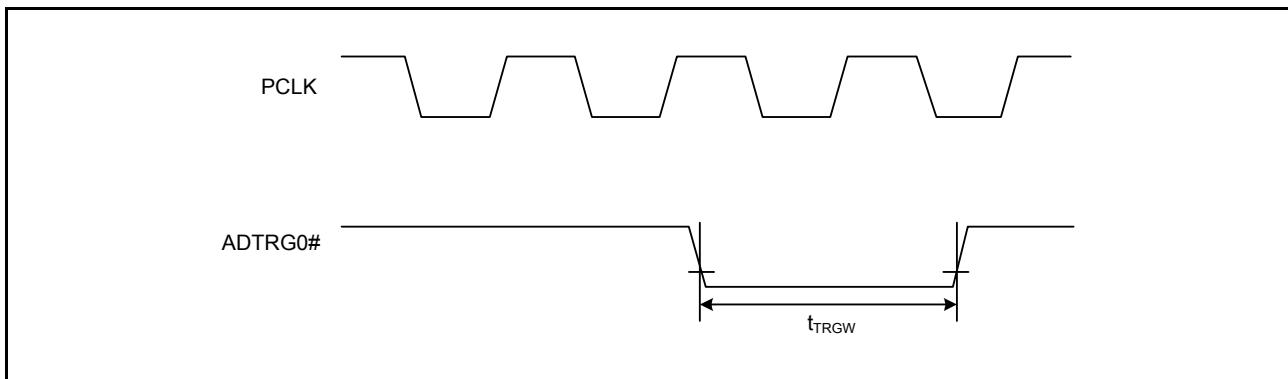
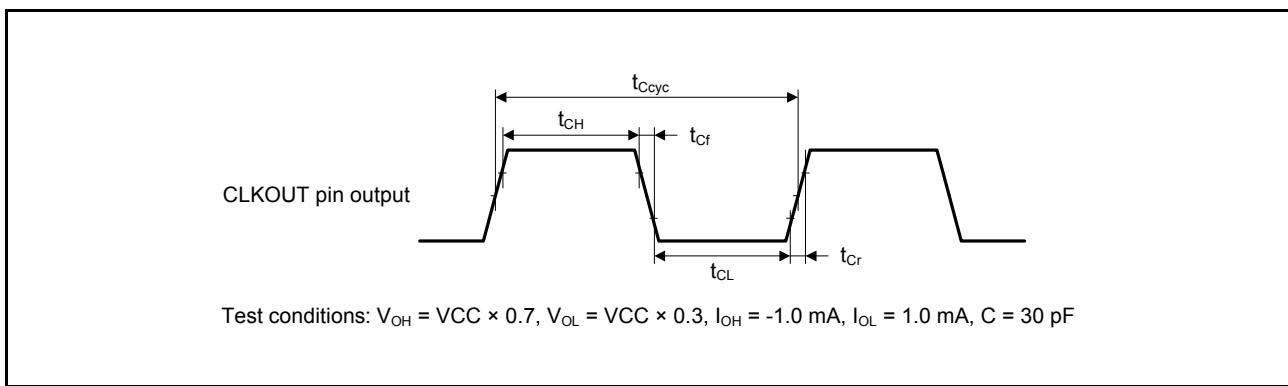


Figure 5.34 Software Standby Mode Cancellation Timing

**Figure 5.43** SCI Input/Output Timing: Clock Synchronous Mode**Figure 5.44** A/D Converter External Trigger Input Timing**Figure 5.45** CLKOUT Output Timing

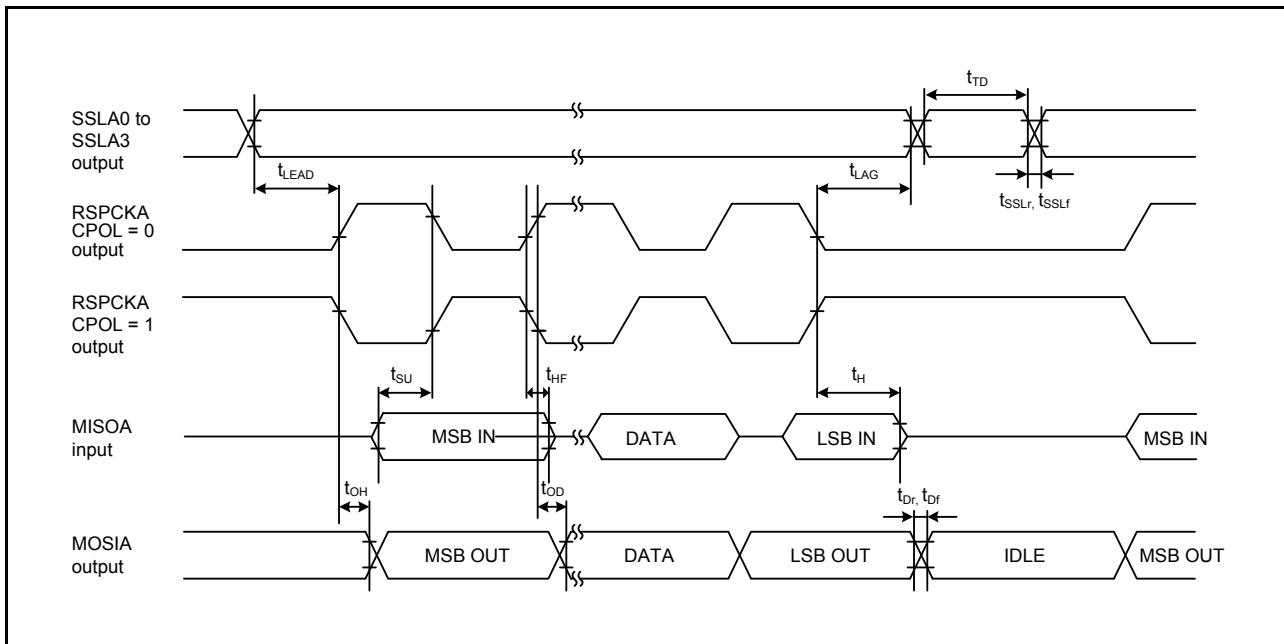


Figure 5.50 RSPI Timing (Master, CPHA = 1) (Bit Rate: PCLKB Set to Divided by 2)

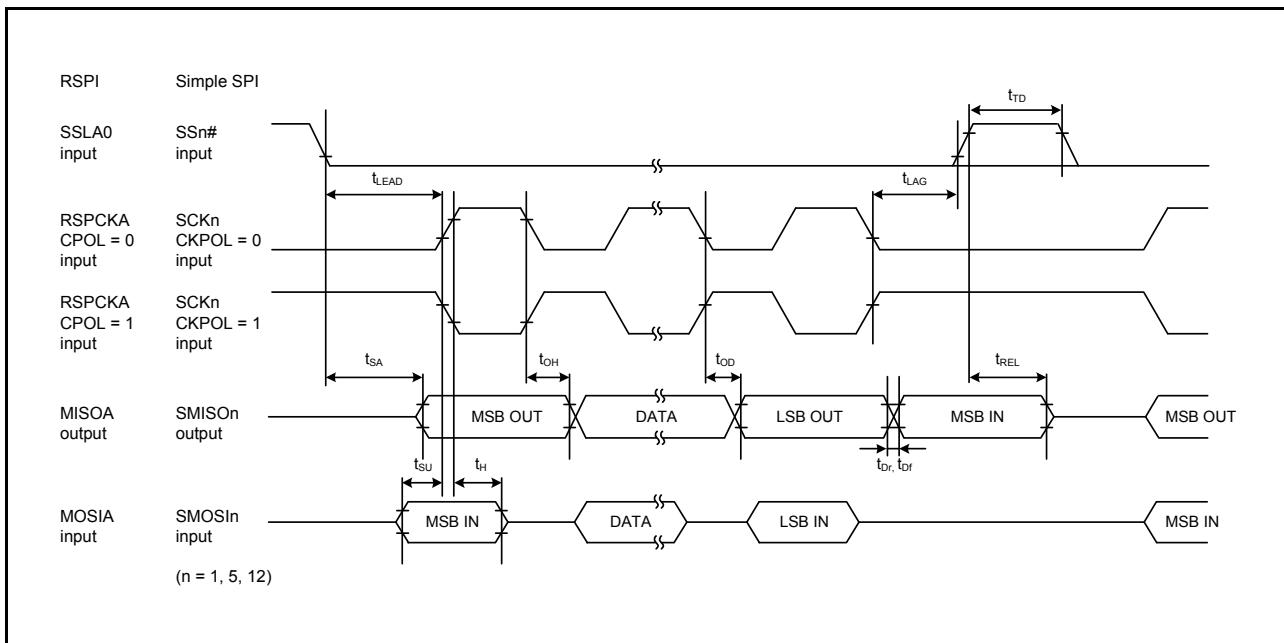


Figure 5.51 RSPI Timing (Slave, CPHA = 0) and Simple SPI Timing (Slave, CKPH = 1)

5.5 A/D Conversion Characteristics

Table 5.38 A/D Conversion Characteristics (1)

Conditions: $2.7 \text{ V} \leq \text{VCC} = \text{VCC_USB} \leq 3.6 \text{ V}$, $2.7 \text{ V} \leq \text{AVCC}_0 \leq 3.6 \text{ V}$, $2.7 \text{ V} \leq \text{VREFH}_0 \leq \text{AVCC}_0$,
 $\text{VSS} = \text{AVSS}_0 = \text{VREFL}_0 = \text{VSS_USB} = 0 \text{ V}$, $T_a = -40 \text{ to } +105^\circ\text{C}$

Item	Min.	Typ.	Max.	Unit	Test Conditions
Frequency	4	—	32	MHz	
Resolution	—	—	12	Bit	
Conversion time ^{*1} (Operation at PCLKD = 32 MHz)	1.031 (0.313) ^{*2}	—	—	μs	High-precision channel ADCSR.ADHSC bit = 1 ADSSTRn.SST[7:0] bits = 09h
	1.375 (0.641) ^{*2}	—	—		Normal-precision channel ADCSR.ADHSC bit = 1 ADSSTRn.SST[7:0] bits = 14h
Analog input effective range	0	—	VREFH0	V	
Offset error	—	±0.5	±4.5	LSB	High-precision channel PJ6PFS.ASEL bit = 1 PJ7PFS.ASEL bit = 1
			±6.0	LSB	Other than above
Full-scale error	—	±0.75	±4.5	LSB	High-precision channel PJ6PFS.ASEL bit = 1 PJ7PFS.ASEL bit = 1
			±6.0	LSB	Other than above
Quantization error	—	±0.5	—	LSB	
Absolute accuracy	—	±1.25	±5.0	LSB	High-precision channel PJ6PFS.ASEL bit = 1 PJ7PFS.ASEL bit = 1
			±8.0	LSB	Other than above
DNL differential nonlinearity error	—	±1.0	—	LSB	
INL integral nonlinearity error	—	±1.0	±3.0	LSB	

Note: • The characteristics apply when no pin functions other than A/D converter input are used. Absolute accuracy includes quantization errors. Offset error, full-scale error, DNL differential nonlinearity error, and INL integral nonlinearity error do not include quantization errors.

Note 1. The conversion time is the sum of the sampling time and the comparison time. As the test conditions, the number of sampling states is indicated.

Note 2. The value in parentheses indicates the sampling time.

Differential nonlinearity error (DNL)

Differential nonlinearity error is the difference between 1 LSB width based on the ideal A/D conversion characteristics and the width of the actually output code.

Offset error

Offset error is the difference between a transition point of the ideal first output code and the actual first output code.

Full-scale error

Full-scale error is the difference between a transition point of the ideal last output code and the actual last output code.

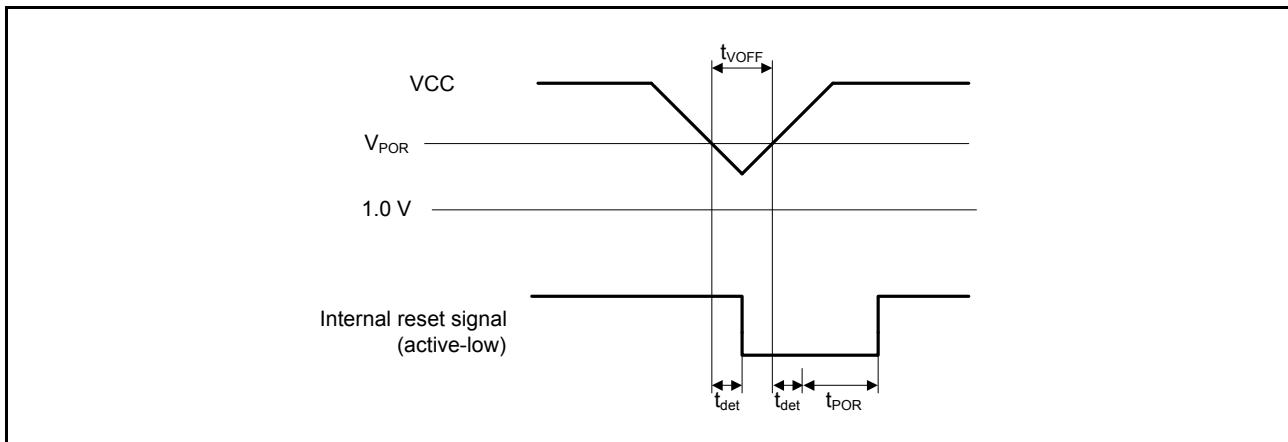


Figure 5.58 Voltage Detection Reset Timing

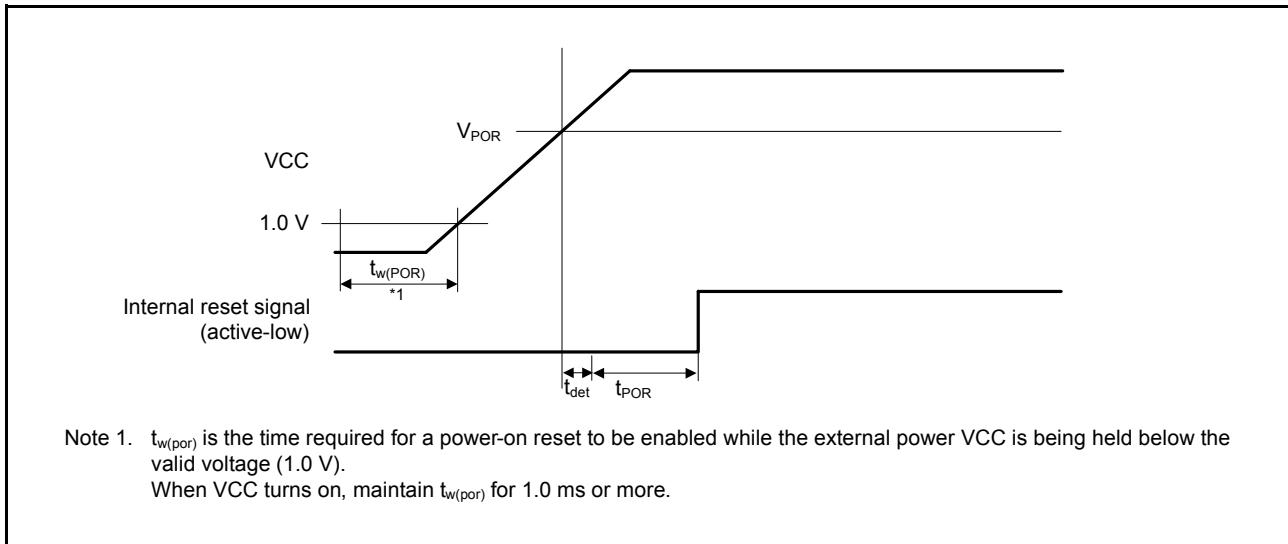


Figure 5.59 Power-On Reset Timing

Appendix 1. Package Dimensions

Information on the latest version of the package dimensions or mountings has been displayed in “Packages” on Renesas Electronics Corporation website.

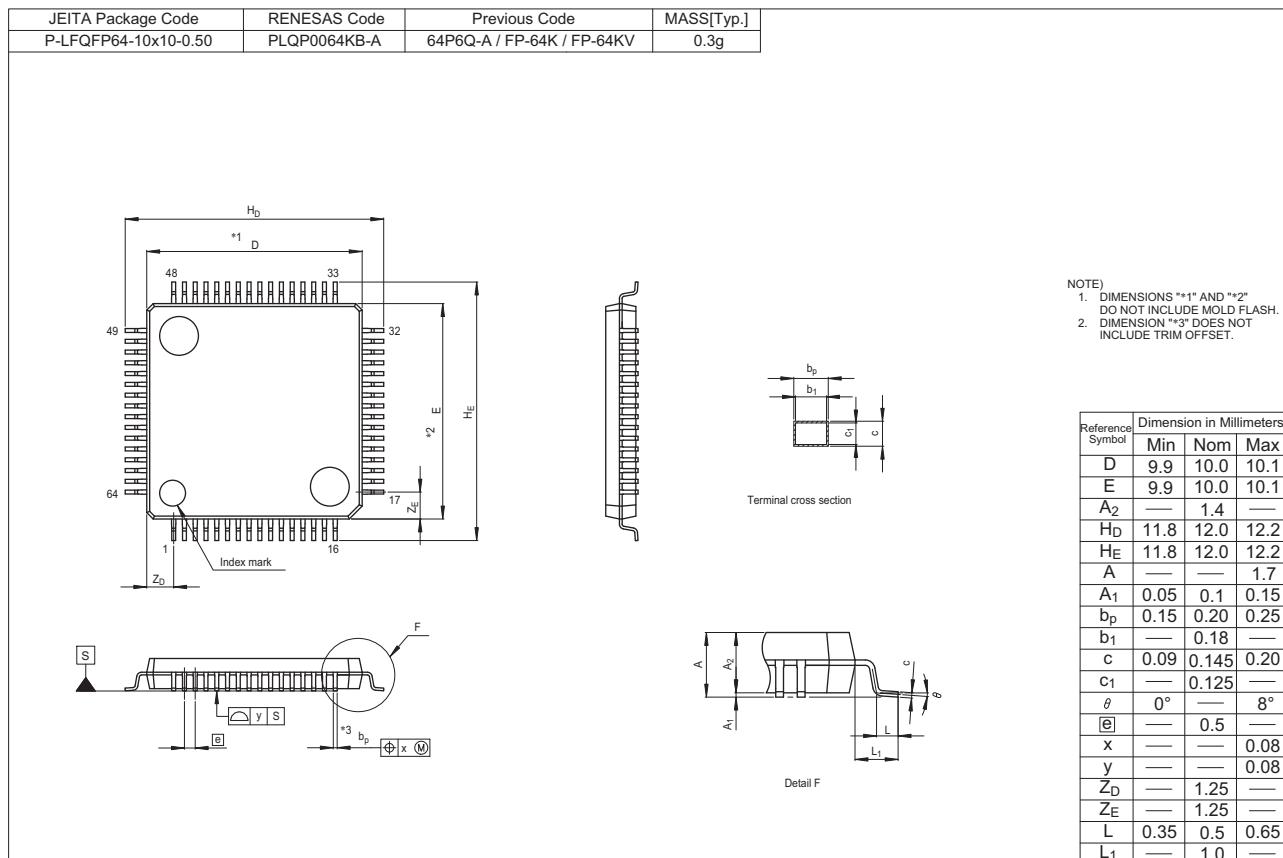


Figure A 64-Pin LFQFP (PLQP0064KB-A)

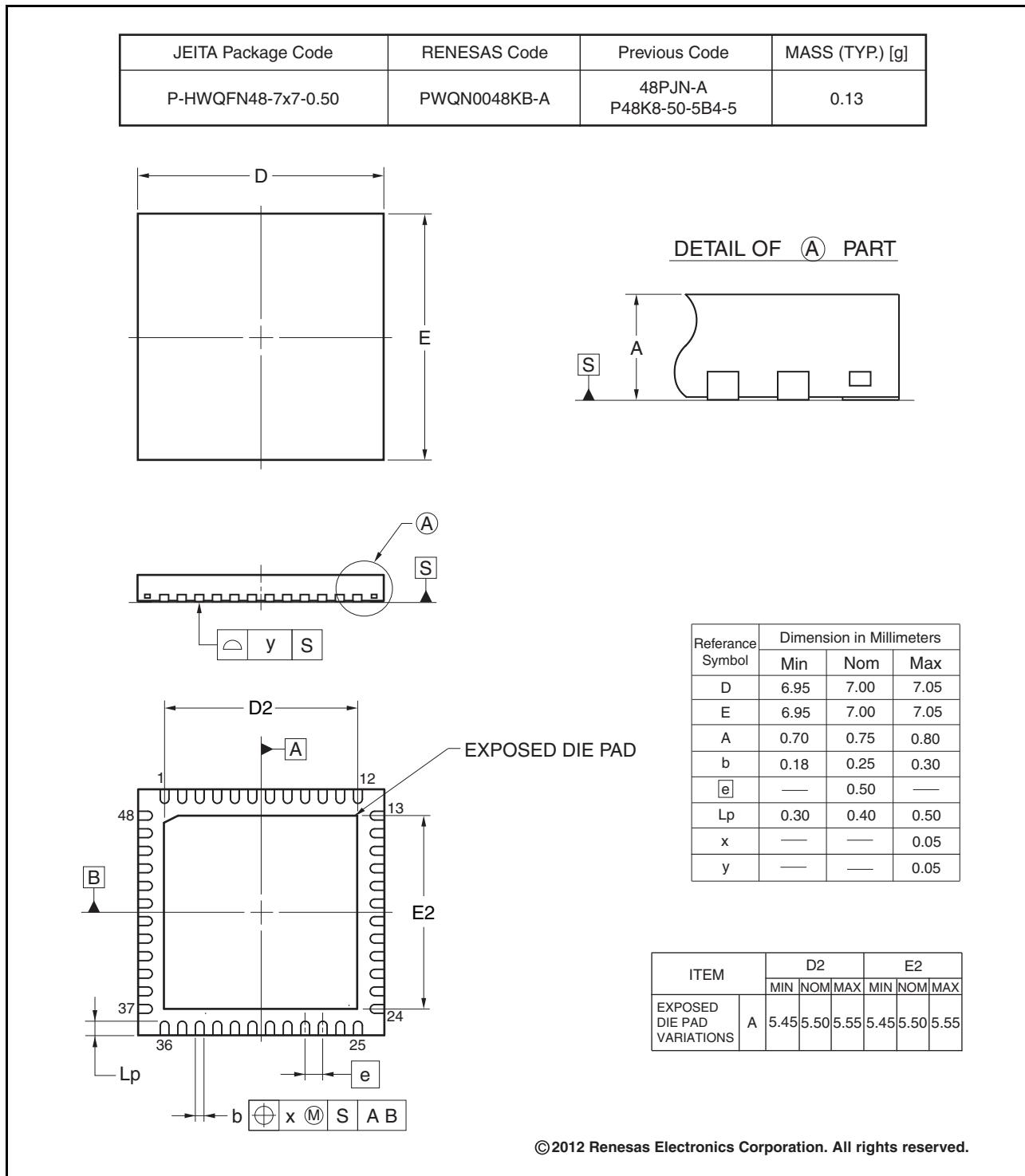


Figure E 48-Pin HWQFN (PWQN0048KB-A)

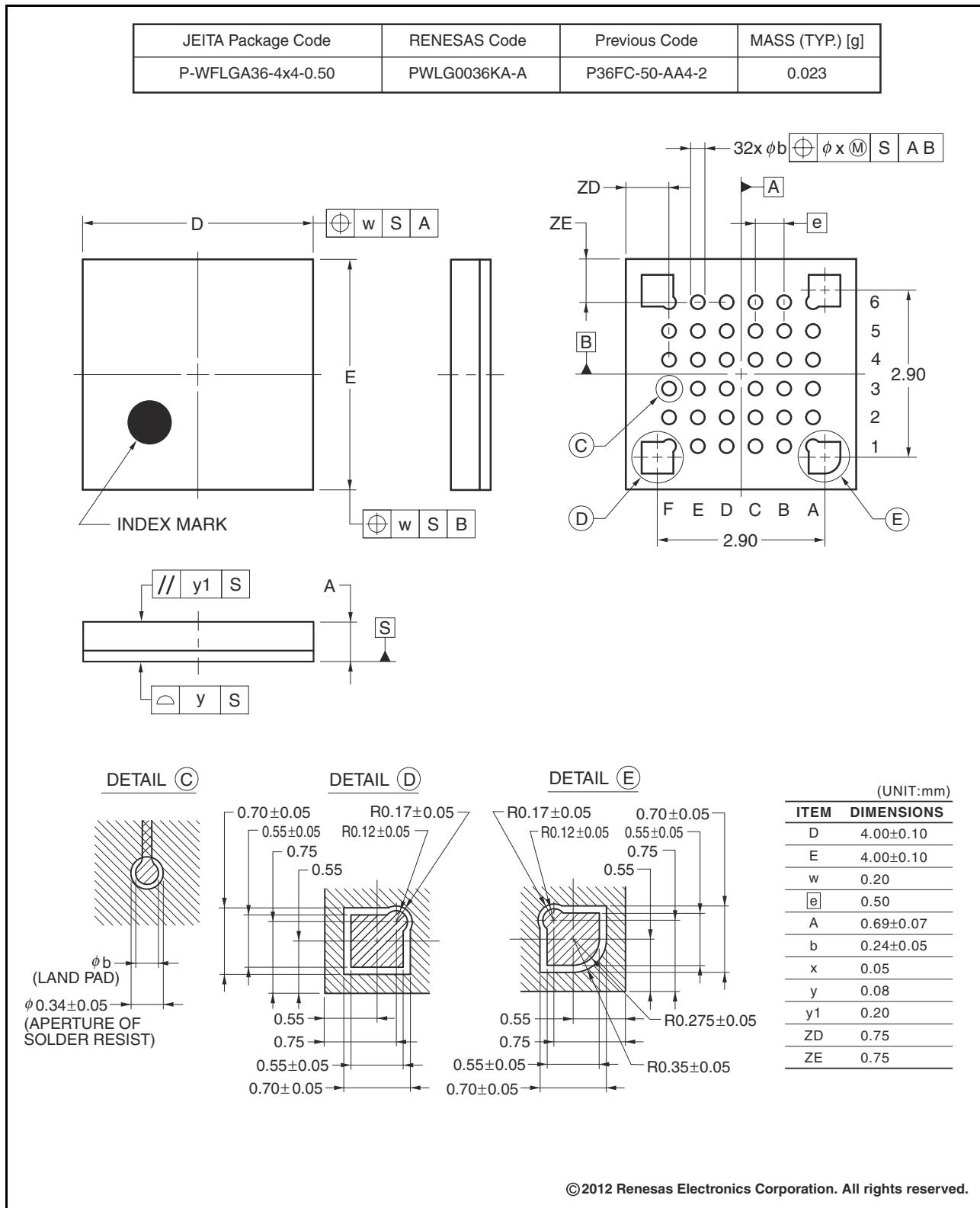


Figure G 36-Pin WFLGA (PWLG0036KA-A)

Classifications

- Items with Technical Update document number: Changes according to the corresponding issued Technical Update
- Items without Technical Update document number: Minor changes that do not require Technical Update to be issued

Rev.	Date	Description		Classification
		Page	Summary	
1.30	May 31, 2016	1. Overview		
		18 to 26	Table 1.5 to 1.9 Note 2 regarding I/O power source is AVCC0 for the ports (P4, PJ6, and PJ7), added	
		5. Electrical Characteristics		
		49	Table 5.1 Absolute Maximum Ratings, Analog power supply voltage added	
		49	Table 5.2 Recommended Operating Conditions, VREFH0 / VREFL0 added	
		58	Figure 5.4 Voltage Dependency in High-Speed Operating Mode (Reference Data) added	
		59	Figure 5.5 Voltage Dependency in Middle-Speed Operating Mode (Reference Data) added	
		59	Figure 5.6 Voltage Dependency in Low-Speed Operating Mode (Reference Data) added	
		60	Table 5.9 DC Characteristics (7), Increment for IWDT operation added	
		62	Table 5.10 DC Characteristics (8), Increment for IWDT operation added	
		62	Figure 5.9 Voltage Dependency in Software Standby Mode (Reference Data) added	
		63	Figure 5.10 Temperature Dependency in Software Standby Mode (Reference Data) added	
		63	Table 5.11 DC Characteristics (9) added	TN-RX*-A134A/E
		64	Table 5.12 DC Characteristics (10), LDV1, 2 added	
		66, 67	Table 5.18 Permissible Output Currents is divided into D version and G version	TN-RX*-A134A/E
		110	Table 5.49 ROM (Flash Memory for Code Storage) Characteristics (2), Erasure time - 256-Kbyte added	TN-RX*-A132A/E
		111	Table 5.50 ROM (Flash Memory for Code Storage) Characteristics (3), Temperature range for the programming/erasure operation changed and Erasure time - 256-Kbyte added	TN-RX*-A132A/E
		112	Table 5.52 E2 DataFlash Characteristics (2), Low speed FCLK changed and Erasure time - 8-Kbyte added	TN-RX*-A132A/E
		112	Table 5.53 E2 DataFlash Characteristics (3), Temperature range for the programming/erasure operation changed, Low speed FCLK changed and Erasure time - 8-Kbyte added	TN-RX*-A132A/E
		113, 114	5.12 Usage Notes added	

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NOTES FOR CMOS DEVICES

- (1) VOLTAGE APPLICATION WAVEFORM AT INPUT PIN: Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between VIL (MAX) and VIH (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between VIL (MAX) and VIH (MIN).
- (2) HANDLING OF UNUSED INPUT PINS: Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.
- (3) PRECAUTION AGAINST ESD: A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.
- (4) STATUS BEFORE INITIALIZATION: Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.
- (5) POWER ON/OFF SEQUENCE: In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current. The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.
- (6) INPUT OF SIGNAL DURING POWER OFF STATE : Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.