

Welcome to [E-XFL.COM](http://E-XFL.COM)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	LINbus, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	18
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 12x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	20-DIP (0.300", 7.62mm)
Supplier Device Package	20-PDIP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16f1578-e-p">https://www.e-xfl.com/product-detail/microchip-technology/pic16f1578-e-p</a>

# PIC16(L)F1574/5/8/9

## Analog Peripherals

- 10-Bit Analog-to-Digital Converter (ADC):
  - Up to 12 external channels
  - Conversion available during Sleep
- Two Comparators:
  - Low-Power/High-Speed modes
  - Fixed Voltage Reference at (non)inverting input(s)
  - Comparator outputs externally accessible
  - Synchronization with Timer1 clock source
  - Software hysteresis enable
- 5-Bit Digital-to-Analog Converter (DAC):
  - 5-bit resolution, rail-to-rail
  - Positive Reference Selection
  - Unbuffered I/O pin output
  - Internal connections to ADCs and comparators
- Voltage Reference:
  - Fixed Voltage Reference with 1.024V, 2.048V and 4.096V output levels

## Clocking Structure

- Precision Internal Oscillator:
  - Factory calibrated  $\pm 1\%$ , typical
  - Software-selectable clock speeds from 31 kHz to 32 MHz
- External Oscillator Block with:
  - Two external clock modes up to 32 MHz
- Digital Oscillator Input Available

**TABLE 1: PIC12(L)F1571/2 AND PIC16(L)F1574/5/8/9 FAMILY TYPES**

Device	Data Sheet Index	Program Flash Memory (Kwords)	Program Flash Memory (Kbytes)	Data SRAM (bytes)	I/O Pins	8-Bit/16-Bit Timers	Comparators	16-Bit PWM	10-Bit ADC (ch)	5-Bit DAC	CWG	EUSART	PPS	Debug <sup>(1)</sup>
PIC12(L)F1571	(A)	1	1.75	128	6	2/4 <sup>(2)</sup>	1	3	4	1	1	0	N	I
PIC12(L)F1572	(A)	2	3.5	256	6	2/4 <sup>(2)</sup>	1	3	4	1	1	1	N	I
PIC16(L)F1574	(B)	4	7	512	12	2/5 <sup>(3)</sup>	2	4	8	1	1	1	Y	I
PIC16(L)F1575	(B)	8	14	1024	12	2/5 <sup>(3)</sup>	2	4	8	1	1	1	Y	I
PIC16(L)F1578	(B)	4	7	512	18	2/5 <sup>(3)</sup>	2	4	12	1	1	1	Y	I
PIC16(L)F1579	(B)	8	14	1024	18	2/5 <sup>(3)</sup>	2	4	12	1	1	1	Y	I

**Note 1:** I – Debugging integrated on chip.

**2:** Three additional 16-bit timers available when not using the 16-bit PWM outputs.

**3:** Four additional 16-bit timers available when not using the 16-bit PWM outputs.

### Data Sheet Index:

- A)** DS-40001723 PIC12(L)F1571/2 Data Sheet, 8-Pin Flash, 8-bit MCU with High-Precision 16-bit PWM
- B)** Future Release PIC16(L)F1574/5/8/9 Data Sheet, 8-Pin Flash, 8-bit MCU with High-Precision 16-bit PWM

**Note:** For other small form-factor package availability and marking information, please visit <http://www.microchip.com/packaging> or contact your local sales office.

## 1.1 Register and Bit Naming Conventions

### 1.1.1 REGISTER NAMES

When there are multiple instances of the same peripheral in a device, the peripheral control registers will be depicted as the concatenation of a peripheral identifier, peripheral instance, and control identifier. The control registers section will show just one instance of all the register names with an 'x' in the place of the peripheral instance number. This naming convention may also be applied to peripherals when there is only one instance of that peripheral in the device to maintain compatibility with other devices in the family that contain more than one.

### 1.1.2 BIT NAMES

There are two variants for bit names:

- Short name: Bit function abbreviation
- Long name: Peripheral abbreviation + short name

#### 1.1.2.1 Short Bit Names

Short bit names are an abbreviation for the bit function. For example, some peripherals are enabled with the EN bit. The bit names shown in the registers are the short name variant.

Short bit names are useful when accessing bits in C programs. The general format for accessing bits by the short name is *RegisterName*bits.*ShortName*. For example, the enable bit, EN, in the COG1CON0 register can be set in C programs with the instruction `COG1CON0bits.EN = 1`.

Short names are generally not useful in assembly programs because the same name may be used by different peripherals in different bit positions. When this occurs, during the include file generation, all instances of that short bit name are appended with an underscore plus the name of the register in which the bit resides to avoid naming contentions.

#### 1.1.2.2 Long Bit Names

Long bit names are constructed by adding a peripheral abbreviation prefix to the short name. The prefix is unique to the peripheral thereby making every long bit name unique. The long bit name for the COG1 enable bit is the COG1 prefix, G1, appended with the enable bit short name, EN, resulting in the unique bit name G1EN.

Long bit names are useful in both C and assembly programs. For example, in C the COG1CON0 enable bit can be set with the `G1EN = 1` instruction. In assembly, this bit can be set with the `BSF COG1CON0,G1EN` instruction.

### 1.1.2.3 Bit Fields

Bit fields are two or more adjacent bits in the same register. Bit fields adhere only to the short bit naming convention. For example, the three Least Significant bits of the COG1CON0 register contain the mode control bits. The short name for this field is MD. There is no long bit name variant. Bit field access is only possible in C programs. The following example demonstrates a C program instruction for setting the COG1 to the Push-Pull mode:

```
COG1CON0bits.MD = 0x5;
```

Individual bits in a bit field can also be accessed with long and short bit names. Each bit is the field name appended with the number of the bit position within the field. For example, the Most Significant mode bit has the short bit name MD2 and the long bit name is G1MD2. The following two examples demonstrate assembly program sequences for setting the COG1 to Push-Pull mode:

Example 1:

```
MOVLW ~(1<<G1MD1)
ANDWF COG1CON0,F
MOVLW 1<<G1MD2 | 1<<G1MD0
IORWF COG1CON0,F
```

Example 2:

```
BSF COG1CON0,G1MD2
BCF COG1CON0,G1MD1
BSF COG1CON0,G1MD0
```

## 1.1.3 REGISTER AND BIT NAMING EXCEPTIONS

### 1.1.3.1 Status, Interrupt, and Mirror Bits

Status, interrupt enables, interrupt flags, and mirror bits are contained in registers that span more than one peripheral. In these cases, the bit name shown is unique so there is no prefix or short name variant.

### 1.1.3.2 Legacy Peripherals

There are some peripherals that do not strictly adhere to these naming conventions. Peripherals that have existed for many years and are present in almost every device are the exceptions. These exceptions were necessary to limit the adverse impact of the new conventions on legacy code. Peripherals that do adhere to the new convention will include a table in the registers section indicating the long name prefix for each peripheral instance. Peripherals that fall into the exception category will not have this table. These peripherals include, but are not limited to, the following:

- EUSART
- MSSP

**TABLE 3-4: PIC16(L)F1575 MEMORY MAP, BANKS 0-7**

BANK0		BANK1		BANK2		BANK3		BANK4		BANK5		BANK6		BANK7	
000h	Core Registers (Table 3-2)	080h	Core Registers (Table 3-2)	100h	Core Registers (Table 3-2)	180h	Core Registers (Table 3-2)	200h	Core Registers (Table 3-2)	280h	Core Registers (Table 3-2)	300h	Core Registers (Table 3-2)	380h	Core Registers (Table 3-2)
00Bh		08Bh		10Bh		18Bh		20Bh		28Bh		30Bh		38Bh	
00Ch	PORTA	08Ch	TRISA	10Ch	LATA	18Ch	ANSELA	20Ch	WPUA	28Ch	ODCONA	30Ch	SLRCONA	38Ch	INLVLA
00Dh	—	08Dh	—	10Dh	—	18Dh	—	20Dh	—	28Dh	—	30Dh	—	38Dh	—
00Eh	PORTC	08Eh	TRISC	10Eh	LATC	18Eh	ANSELC	20Eh	WPUC	28Eh	ODCONC	30Eh	SLRCONC	38Eh	INLVLC
00Fh	—	08Fh	—	10Fh	—	18Fh	—	20Fh	—	28Fh	—	30Fh	—	38Fh	—
010h	—	090h	—	110h	—	190h	—	210h	—	290h	—	310h	—	390h	—
011h	PIR1	091h	PIE1	111h	CM1CON0	191h	PMADRL	211h	—	291h	—	311h	—	391h	IOCAP
012h	PIR2	092h	PIE2	112h	CM1CON1	192h	PMADRH	212h	—	292h	—	312h	—	392h	IOCAN
013h	PIR3	093h	PIE3	113h	CM2CON0	193h	PMDATL	213h	—	293h	—	313h	—	393h	IOCAF
014h	—	094h	—	114h	CM2CON1	194h	PMDATH	214h	—	294h	—	314h	—	394h	—
015h	TMR0	095h	OPTION_REG	115h	CMOUT	195h	PMCON1	215h	—	295h	—	315h	—	395h	—
016h	TMR1L	096h	PCON	116h	BORCON	196h	PMCON2	216h	—	296h	—	316h	—	396h	—
017h	TMR1H	097h	WDTCON	117h	FVRCON	197h	VREGCON <sup>(1)</sup>	217h	—	297h	—	317h	—	397h	IOCCP
018h	T1CON	098h	OSCTUNE	118h	DACCON0	198h	—	218h	—	298h	—	318h	—	398h	IOCCN
019h	T1GCON	099h	OSCCON	119h	DACCON1	199h	RCREG	219h	—	299h	—	319h	—	399h	IOCCF
01Ah	TMR2	09Ah	OSCSTAT	11Ah	—	19Ah	TXREG	21Ah	—	29Ah	—	31Ah	—	39Ah	—
01Bh	PR2	09Bh	ADRESL	11Bh	—	19Bh	SPBRGL	21Bh	—	29Bh	—	31Bh	—	39Bh	—
01Ch	T2CON	09Ch	ADRESH	11Ch	—	19Ch	SPBRGH	21Ch	—	29Ch	—	31Ch	—	39Ch	—
01Dh	—	09Dh	ADCON0	11Dh	—	19Dh	RCSTA	21Dh	—	29Dh	—	31Dh	—	39Dh	—
01Eh	—	09Eh	ADCON1	11Eh	—	19Eh	TXSTA	21Eh	—	29Eh	—	31Eh	—	39Eh	—
01Fh	—	09Fh	ADCON2	11Fh	—	19Fh	BAUDCON	21Fh	—	29Fh	—	31Fh	—	39Fh	—
020h		0A0h		120h		1A0h		220h		2A0h		320h		3A0h	
	General Purpose Register 80 Bytes		General Purpose Register 80 Bytes		General Purpose Register 80 Bytes		General Purpose Register 80 Bytes		General Purpose Register 80 Bytes		General Purpose Register 80 Bytes		General Purpose Register 80 Bytes		General Purpose Register 80 Bytes
06Fh		0EFh		16Fh		1EFh		26Fh		2EFh		36Fh		3EFh	
070h	Common RAM	0F0h	Accesses 70h – 7Fh	170h	Accesses 70h – 7Fh	1F0h	Accesses 70h – 7Fh	270h	Accesses 70h – 7Fh	2F0h	Accesses 70h – 7Fh	370h	Accesses 70h – 7Fh	3F0h	Accesses 70h – 7Fh
07Fh		0FFh		17Fh		1FFh		27Fh		2FFh		37Fh		3FFh	

**Legend:** ■ = Unimplemented data memory locations, read as '0'.

**Note 1:** Unimplemented on PIC16LF1575.

**TABLE 3-5: PIC16(L)F1578 MEMORY MAP, BANKS 0-7**

BANK0		BANK1		BANK2		BANK3		BANK4		BANK5		BANK6		BANK7	
000h	Core Registers (Table 3-2)	080h	Core Registers (Table 3-2)	100h	Core Registers (Table 3-2)	180h	Core Registers (Table 3-2)	200h	Core Registers (Table 3-2)	280h	Core Registers (Table 3-2)	300h	Core Registers (Table 3-2)	380h	Core Registers (Table 3-2)
00Bh		08Bh		10Bh		18Bh		20Bh		28Bh		30Bh		38Bh	
00Ch	PORTA	08Ch	TRISA	10Ch	LATA	18Ch	ANSELA	20Ch	WPUA	28Ch	ODCONA	30Ch	SLRCONA	38Ch	INLVLA
00Dh	PORTB	08Dh	TRISB	10Dh	LATB	18Dh	ANSELB	20Dh	WPUB	28Dh	ODCONB	30Dh	SLRCONB	38Dh	INLVLB
00Eh	PORTC	08Eh	TRISC	10Eh	LATC	18Eh	ANSELC	20Eh	WPUC	28Eh	ODCONC	30Eh	SLRCONC	38Eh	INLVLC
00Fh	—	08Fh	—	10Fh	—	18Fh	—	20Fh	—	28Fh	—	30Fh	—	38Fh	—
010h	—	090h	—	110h	—	190h	—	210h	—	290h	—	310h	—	390h	—
011h	PIR1	091h	PIE1	111h	CM1CON0	191h	PMADRL	211h	—	291h	—	311h	—	391h	IOCAP
012h	PIR2	092h	PIE2	112h	CM1CON1	192h	PMADRH	212h	—	292h	—	312h	—	392h	IOCAN
013h	PIR3	093h	PIE3	113h	CM2CON0	193h	PMDATL	213h	—	293h	—	313h	—	393h	IOCAF
014h	—	094h	—	114h	CM2CON1	194h	PMDATH	214h	—	294h	—	314h	—	394h	IOCBP
015h	TMR0	095h	OPTION_REG	115h	CMOUT	195h	PMCON1	215h	—	295h	—	315h	—	395h	IOCBN
016h	TMR1L	096h	PCON	116h	BORCON	196h	PMCON2	216h	—	296h	—	316h	—	396h	IOCBF
017h	TMR1H	097h	WDTCON	117h	FVRCON	197h	VREGCON <sup>(1)</sup>	217h	—	297h	—	317h	—	397h	IOCCP
018h	T1CON	098h	OSCTUNE	118h	DACCON0	198h	—	218h	—	298h	—	318h	—	398h	IOCCN
019h	T1GCON	099h	OSCCON	119h	DACCON1	199h	RCREG	219h	—	299h	—	319h	—	399h	IOCCF
01Ah	TMR2	09Ah	OSCSTAT	11Ah	—	19Ah	TXREG	21Ah	—	29Ah	—	31Ah	—	39Ah	—
01Bh	PR2	09Bh	ADRESL	11Bh	—	19Bh	SPBRGL	21Bh	—	29Bh	—	31Bh	—	39Bh	—
01Ch	T2CON	09Ch	ADRESH	11Ch	—	19Ch	SPBRGH	21Ch	—	29Ch	—	31Ch	—	39Ch	—
01Dh	—	09Dh	ADCON0	11Dh	—	19Dh	RCSTA	21Dh	—	29Dh	—	31Dh	—	39Dh	—
01Eh	—	09Eh	ADCON1	11Eh	—	19Eh	TXSTA	21Eh	—	29Eh	—	31Eh	—	39Eh	—
01Fh	—	09Fh	ADCON2	11Fh	—	19Fh	BAUDCON	21Fh	—	29Fh	—	31Fh	—	39Fh	—
020h	General Purpose Register 80 Bytes	0A0h	General Purpose Register 80 Bytes	120h	General Purpose Register 80 Bytes	1A0h	General Purpose Register 80 Bytes	220h	General Purpose Register 80 Bytes	2A0h	General Purpose Register 80 Bytes	320h	General Purpose Register 16 Bytes	3A0h	Unimplemented Read as '0'
												330h	Unimplemented Read as '0'		
06Fh	Common RAM	0EFh	Accesses 70h – 7Fh	16Fh	Accesses 70h – 7Fh	1EFh	Accesses 70h – 7Fh	26Fh	Accesses 70h – 7Fh	2EFh	Accesses 70h – 7Fh	36Fh	Accesses 70h – 7Fh	3EFh	Accesses 70h – 7Fh
070h		0F0h		170h		1F0h		270h		2F0h		370h		3F0h	
07Fh		0FFh		17Fh		1FFh		27Fh		2FFh		37Fh		3FFh	

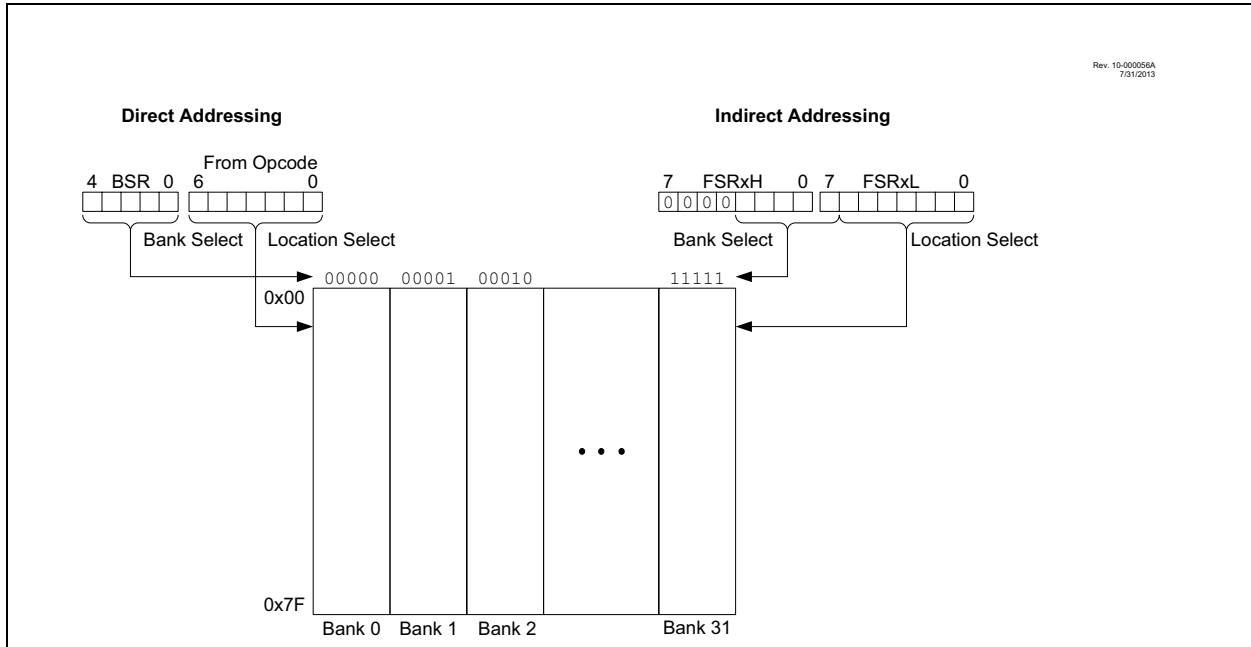
**Legend:** ■ = Unimplemented data memory locations, read as '0'.

**Note 1:** Unimplemented on PIC16LF1578.

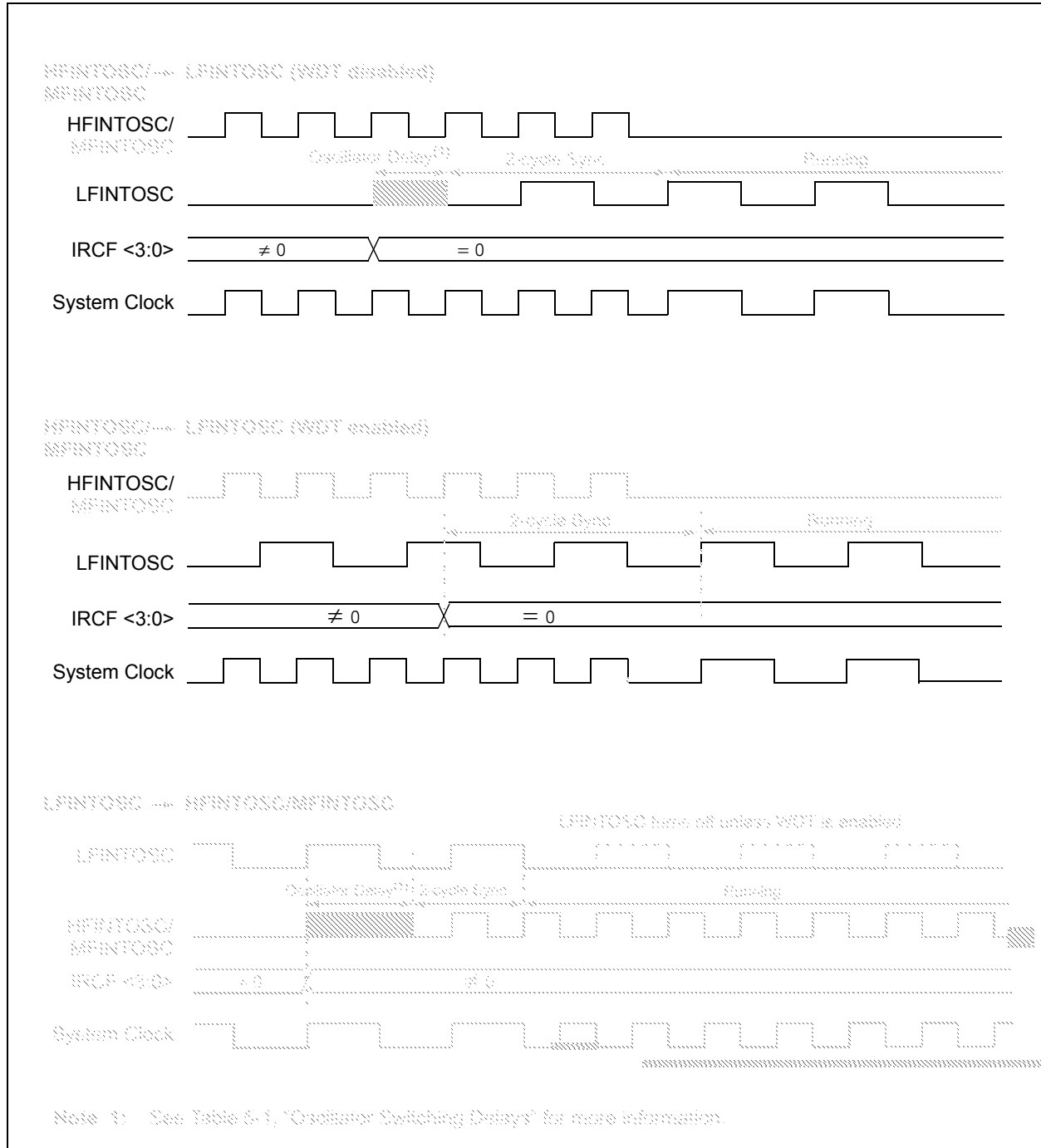
## 3.6.1 TRADITIONAL DATA MEMORY

The traditional data memory is a region from FSR address 0x000 to FSR address 0xFFF. The addresses correspond to the absolute addresses of all SFR, GPR and common registers.

**FIGURE 3-10: TRADITIONAL DATA MEMORY MAP**



**FIGURE 5-3: INTERNAL OSCILLATOR SWITCH TIMING**



## 7.3 Interrupts During Sleep

Some interrupts can be used to wake from Sleep. To wake from Sleep, the peripheral must be able to operate without the system clock. The interrupt source must have the appropriate Interrupt Enable bit(s) set prior to entering Sleep.

On waking from Sleep, if the GIE bit is also set, the processor will branch to the interrupt vector. Otherwise, the processor will continue executing instructions after the `SLEEP` instruction. The instruction directly after the `SLEEP` instruction will always be executed before branching to the ISR. Refer to **Section 8.0 “Power-Down Mode (Sleep)”** for more details.

## 7.4 INT Pin

The INT pin can be used to generate an asynchronous edge-triggered interrupt. This interrupt is enabled by setting the INTE bit of the INTCON register. The INTEDG bit of the OPTION\_REG register determines on which edge the interrupt will occur. When the INTEDG bit is set, the rising edge will cause the interrupt. When the INTEDG bit is clear, the falling edge will cause the interrupt. The INTF bit of the INTCON register will be set when a valid edge appears on the INT pin. If the GIE and INTE bits are also set, the processor will redirect program execution to the interrupt vector.

## 7.5 Automatic Context Saving

Upon entering an interrupt, the return PC address is saved on the stack. Additionally, the following registers are automatically saved in the shadow registers:

- W register
- STATUS register (except for  $\overline{TO}$  and  $\overline{PD}$ )
- BSR register
- FSR registers
- PCLATH register

Upon exiting the Interrupt Service Routine, these registers are automatically restored. Any modifications to these registers during the ISR will be lost. If modifications to any of these registers are desired, the corresponding shadow register should be modified and the value will be restored when exiting the ISR. The shadow registers are available in Bank 31 and are readable and writable. Depending on the user's application, other registers may also need to be saved.



**TABLE 7-1: SUMMARY OF REGISTERS ASSOCIATED WITH INTERRUPTS**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	86
OPTION_REG	$\overline{\text{WPUEN}}$	INTEDG	TMR0CS	TMR0SE	PSA	PS<2:0>			178
PIE1	TMR1GIE	ADIE	RCIE	TXIE	—	—	TMR2IE	TMR1IE	87
PIE2	—	C2IE	C1IE	—	—	—	—	—	88
PIE3	PWM4IE	PWM3IE	PWM2IE	PWM1IE	—	—	—	—	89
PIR1	TMR1GIF	ADIF	RCIF	TXIF	—	—	TMR2IF	TMR1IF	90
PIR2	—	C2IF	C1IF	—	—	—	—	—	91
PIR3	PWM4IF	PWM3IF	PWM2IF	PWM1IF	—	—	—	—	92

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used by interrupts.

## REGISTER 10-5: PMCON1: PROGRAM MEMORY CONTROL 1 REGISTER

U-1	R/W-0/0	R/W-0/0	R/W/HC-0/0	R/W/HC-x/q <sup>(2)</sup>	R/W-0/0	R/S/HC-0/0	R/S/HC-0/0
— <sup>(1)</sup>	CFGS	LWLO <sup>(3)</sup>	FREE	WRERR	WREN	WR	RD
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
S = Bit can only be set	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HC = Bit is cleared by hardware

- bit 7      **Unimplemented:** Read as '1'
- bit 6      **CFGS:** Configuration Select bit  
 1 = Access Configuration, User ID and Device ID Registers  
 0 = Access Flash program memory
- bit 5      **LWLO:** Load Write Latches Only bit<sup>(3)</sup>  
 1 = Only the addressed program memory write latch is loaded/updated on the next WR command  
 0 = The addressed program memory write latch is loaded/updated and a write of all program memory write latches will be initiated on the next WR command
- bit 4      **FREE:** Program Flash Erase Enable bit  
 1 = Performs an erase operation on the next WR command (hardware cleared upon completion)  
 0 = Performs a write operation on the next WR command
- bit 3      **WRERR:** Program/Erase Error Flag bit<sup>(2)</sup>  
 1 = Condition indicates an improper program or erase sequence attempt or termination (bit is set automatically on any set attempt (write '1') of the WR bit).  
 0 = The program or erase operation completed normally.
- bit 2      **WREN:** Program/Erase Enable bit  
 1 = Allows program/erase cycles  
 0 = Inhibits programming/erasing of program Flash
- bit 1      **WR:** Write Control bit  
 1 = Initiates a program Flash program/erase operation.  
       The operation is self-timed and the bit is cleared by hardware once operation is complete.  
       The WR bit can only be set (not cleared) in software.  
 0 = Program/erase operation to the Flash is complete and inactive.
- bit 0      **RD:** Read Control bit  
 1 = Initiates a program Flash read. Read takes one cycle. RD is cleared in hardware. The RD bit can only be set (not cleared) in software.  
 0 = Does not initiate a program Flash read.

- Note 1:** Unimplemented bit, read as '1'.  
**Note 2:** The WRERR bit is automatically set by hardware when a program memory write or erase operation is started (WR = 1).  
**Note 3:** The LWLO bit is ignored during a program memory erase operation (FREE = 1).

# PIC16(L)F1574/5/8/9

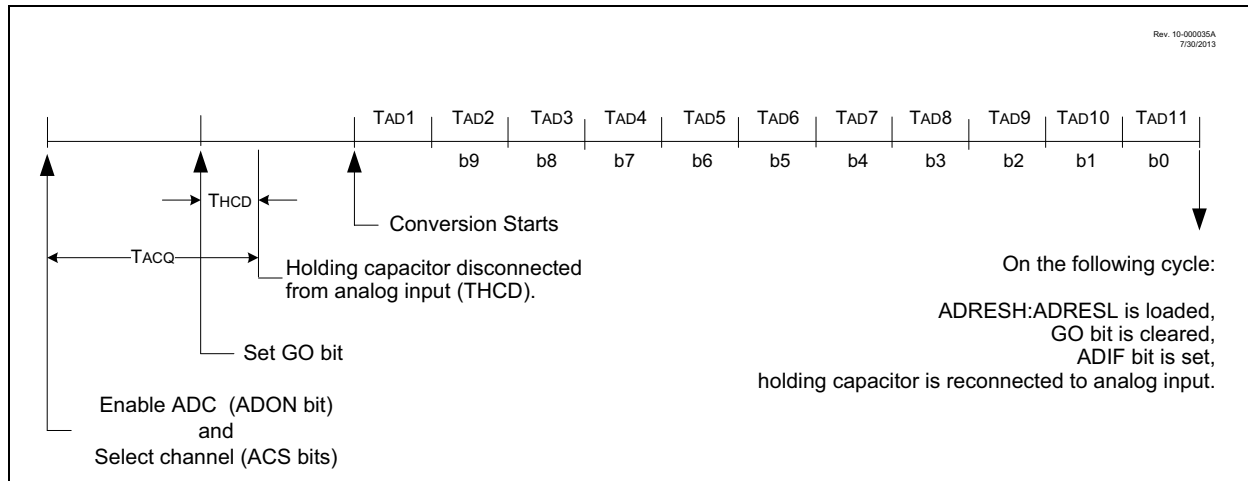
**TABLE 16-1: ADC CLOCK PERIOD (TAD) Vs. DEVICE OPERATING FREQUENCIES**

ADC Clock Period (TAD)		Device Frequency (Fosc)				
ADC Clock Source	ADCS<2:0 >	20 MHz	16 MHz	8 MHz	4 MHz	1 MHz
Fosc/2	000	100 ns	125 ns	250 ns	500 ns	2.0 μs
Fosc/4	100	200 ns	250 ns	500 ns	1.0 μs	4.0 μs
Fosc/8	001	400 ns	500 ns	1.0 μs	2.0 μs	8.0 μs
Fosc/16	101	800 ns	1.0 μs	2.0 μs	4.0 μs	16.0 μs
Fosc/32	010	1.6 μs	2.0 μs	4.0 μs	8.0 μs	32.0 μs
Fosc/64	110	3.2 μs	4.0 μs	8.0 μs	16.0 μs	64.0 μs
FRC	x11	1.0-6.0 μs	1.0-6.0 μs	1.0-6.0 μs	1.0-6.0 μs	1.0-6.0 μs

**Legend:** Shaded cells are outside of recommended range.

**Note:** The TAD period when using the FRC clock source can fall within a specified range, (see TAD parameter). The TAD period when using the FOSC-based clock source can be configured for a more precise TAD period. However, the FRC clock source must be used when conversions are to be performed with the device in Sleep mode.

**FIGURE 16-2: ANALOG-TO-DIGITAL CONVERSION TAD CYCLES**



## 18.2.5 COMPARATOR OUTPUT POLARITY

Inverting the output of the comparator is functionally equivalent to swapping the comparator inputs. The polarity of the comparator output can be inverted by setting the CxPOL bit of the CMxCON0 register. Clearing the CxPOL bit results in a non-inverted output.

Table 18-2 shows the output state versus input conditions, including polarity control.

**TABLE 18-2: COMPARATOR OUTPUT STATE VS. INPUT CONDITIONS**

Input Condition	CxPOL	CxOUT
$CxVN > CxVP$	0	0
$CxVN < CxVP$	0	1
$CxVN > CxVP$	1	1
$CxVN < CxVP$	1	0

## 18.2.6 COMPARATOR SPEED/POWER SELECTION

The trade-off between speed or power can be optimized during program execution with the CxSP control bit. The default state for this bit is '1' which selects the Normal Speed mode. Device power consumption can be optimized at the cost of slower comparator propagation delay by clearing the CxSP bit to '0'.

## 18.3 Analog Input Connection Considerations

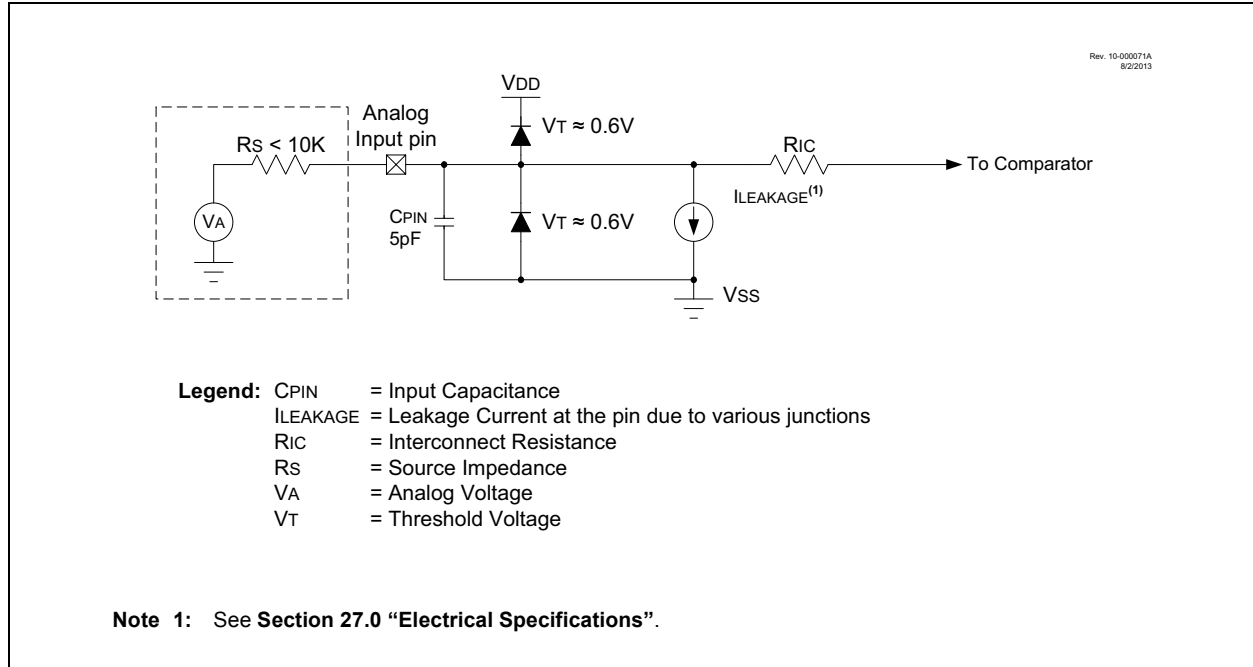
A simplified circuit for an analog input is shown in Figure 18-3. Since the analog input pins share their connection with a digital input, they have reverse biased ESD protection diodes to VDD and VSS. The analog input, therefore, must be between VSS and VDD. If the input voltage deviates from this range by more than 0.6V in either direction, one of the diodes is forward-biased and a latch-up may occur.

A maximum source impedance of 10 kΩ is recommended for the analog sources. Also, any external component connected to an analog input pin, such as a capacitor or a Zener diode, should have very little leakage current to minimize inaccuracies introduced.

**Note 1:** When reading a PORT register, all pins configured as analog inputs will read as a '0'. Pins configured as digital inputs will convert as an analog input, according to the input specification.

**2:** Analog levels on any pin defined as a digital input, may cause the input buffer to consume more current than is specified.

**FIGURE 18-3: ANALOG INPUT MODEL**



## 21.5 Register Definitions: Timer2 Control

**REGISTER 21-1: T2CON: TIMER2 CONTROL REGISTER**

U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	T2OUTPS<3:0>				TMR2ON	T2CKPS<1:0>	
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

- bit 7           **Unimplemented:** Read as '0'
- bit 6-3       **T2OUTPS<3:0>:** Timer2 Output Postscaler Select bits
  - 0000 = 1:1 Postscaler
  - 0001 = 1:2 Postscaler
  - 0010 = 1:3 Postscaler
  - 0011 = 1:4 Postscaler
  - 0100 = 1:5 Postscaler
  - 0101 = 1:6 Postscaler
  - 0110 = 1:7 Postscaler
  - 0111 = 1:8 Postscaler
  - 1000 = 1:9 Postscaler
  - 1001 = 1:10 Postscaler
  - 1010 = 1:11 Postscaler
  - 1011 = 1:12 Postscaler
  - 1100 = 1:13 Postscaler
  - 1101 = 1:14 Postscaler
  - 1110 = 1:15 Postscaler
  - 1111 = 1:16 Postscaler
- bit 2           **TMR2ON:** Timer2 On bit
  - 1 = Timer2 is on
  - 0 = Timer2 is off
- bit 1-0       **T2CKPS<1:0>:** Timer2 Clock Prescale Select bits
  - 00 = Prescaler is 1
  - 01 = Prescaler is 4
  - 10 = Prescaler is 16
  - 11 = Prescaler is 64

**TABLE 21-1: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER2**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
INTCON	GIE	PEIE	TMR0IE	INTE	IOCFIE	TMR0IF	INTF	IOCFIF	86
PIE1	TMR1GIE	ADIE	RCIE	TXIE	—	—	TMR2IE	TMR1IE	87
PIR1	TMR1GIF	ADIF	RCIF	TXIF	—	—	TMR2IF	TMR1IF	90
PR2	Timer2 Module Period Register								189*
T2CON	—	T2OUTPS<3:0>				TMR2ON	T2CKPS<1:0>		191
TMR2	Holding Register for the 8-bit TMR2 Count								189*

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used for Timer2 module.

\* Page provides register information.

**Note 1:** PIC16(L)F1575 only.

# PIC16(L)F1574/5/8/9

**TABLE 22-3: BAUD RATE FORMULAS**

Configuration Bits			BRG/EUSART Mode	Baud Rate Formula
SYNC	BRG16	BRGH		
0	0	0	8-bit/Asynchronous	$F_{osc}/[64 (n+1)]$
0	0	1	8-bit/Asynchronous	$F_{osc}/[16 (n+1)]$
0	1	0	16-bit/Asynchronous	
0	1	1	16-bit/Asynchronous	$F_{osc}/[4 (n+1)]$
1	0	x	8-bit/Synchronous	
1	1	x	16-bit/Synchronous	

**Legend:** x = Don't care, n = value of SPBRGH, SPBRGL register pair.

**TABLE 22-4: SUMMARY OF REGISTERS ASSOCIATED WITH THE BAUD RATE GENERATOR**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BAUDCON	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	204
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	203
SPBRGL	BRG<7:0>								205*
SPBRGH	BRG<15:8>								205*
TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	202

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used for the Baud Rate Generator.

\* Page provides register information.

# PIC16(L)F1574/5/8/9

## REGISTER 23-2: PWMxINTE: PWM INTERRUPT ENABLE REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	OFIE	PHIE	DCIE	PRIE
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                  -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

- bit 7-4            **Unimplemented:** Read as '0'
- bit 3            **OFIE:** Offset Interrupt Enable bit  
1 = Interrupt CPU on Offset Match  
0 = Do not interrupt CPU on Offset Match
- bit 2            **PHIE:** Phase Interrupt Enable bit  
1 = Interrupt CPU on Phase Match  
0 = Do not Interrupt CPU on Phase Match
- bit 1            **DCIE:** Duty Cycle Interrupt Enable bit  
1 = Interrupt CPU on Duty Cycle Match  
0 = Do not interrupt CPU on Duty Cycle Match
- bit 0            **PRIE:** Period Interrupt Enable bit  
1 = Interrupt CPU on Period Match  
0 = Do not interrupt CPU on Period Match

## REGISTER 23-3: PWMxINTF: PWM INTERRUPT REQUEST REGISTER

U-0	U-0	U-0	U-0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
—	—	—	—	OFIF	PHIF	DCIF	PRIF
bit 7				bit 0			

### Legend:

HC = Bit is cleared by hardware                      HS = Bit is set by hardware  
R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                  -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

- bit 7-4            **Unimplemented:** Read as '0'
- bit 3            **OFIF:** Offset Interrupt Flag bit<sup>(1)</sup>  
1 = Offset Match Event occurred  
0 = Offset Match Event did not occur
- bit 2            **PHIF:** Phase Interrupt Flag bit<sup>(1)</sup>  
1 = Phase Match Event occurred  
0 = Phase Match Event did not occur
- bit 1            **DCIF:** Duty Cycle Interrupt Flag bit<sup>(1)</sup>  
1 = Duty Cycle Match Event occurred  
0 = Duty Cycle Match Event did not occur
- bit 0            **PRIF:** Period Interrupt Flag bit<sup>(1)</sup>  
1 = Period Match Event occurred  
0 = Period Match Event did not occur

**Note 1:** Bit is forced clear by hardware while module is disabled (EN = 0).

# PIC16(L)F1574/5/8/9

---

## REGISTER 23-15: PWMxTMRH: PWMx TIMER HIGH REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
TMR<15:8>							
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0      **TMR<15:8>**: PWM Timer High bits  
Upper eight bits of PWM timer counter

## REGISTER 23-16: PWMxTMRL: PWMx TIMER LOW REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
TMR<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0      **TMR<7:0>**: PWM Timer Low bits  
Lower eight bits of PWM timer counter



# PIC16(L)F1574/5/8/9

## 24.0 COMPLEMENTARY WAVEFORM GENERATOR (CWG) MODULE

The Complementary Waveform Generator (CWG) produces a complementary waveform with dead-band delay from a selection of input sources.

The CWG module has the following features:

- Selectable dead-band clock source control
- Selectable input sources
- Output enable control
- Output polarity control
- Dead-band control with independent 6-bit rising and falling edge dead-band counters
- Auto-shutdown control with:
  - Selectable shutdown sources
  - Auto-restart enable
  - Auto-shutdown pin override control

### 24.1 Fundamental Operation

The CWG generates two output waveforms from the selected input source.

The off-to-on transition of each output can be delayed from the on-to-off transition of the other output, thereby, creating a time delay immediately where neither output is driven. This is referred to as dead time and is covered in **Section 24.5 “Dead-Band Control”**. A typical operating waveform, with dead band, generated from a single input signal is shown in Figure 24-2.

It may be necessary to guard against the possibility of circuit faults or a feedback event arriving too late or not at all. In this case, the active drive must be terminated before the Fault condition causes damage. This is referred to as auto-shutdown and is covered in **Section 24.9 “Auto-Shutdown Control”**.

### 24.2 Clock Source

The CWG module allows the following clock sources to be selected:

- FOSC (system clock)
- HFINTOSC (16 MHz only)

The clock sources are selected using the G1CS0 bit of the CWGxCON0 register (Register 24-1).

## 24.3 Selectable Input Sources

The CWG generates the output waveforms from the input sources in Table 24-1.

**TABLE 24-1: SELECTABLE INPUT SOURCES**

Source Peripheral	Signal Name
CWG input pin	CWGxIN pin
Comparator C1	C1OUT_sync
Comparator C2	C2OUT_sync
PWM1	PWM1_output
PWM2	PWM2_output
PWM3	PWM3_output
PWM4	PWM4_output

The input sources are selected using the GxIS<2:0> bits in the CWGxCON1 register (Register 24-2).

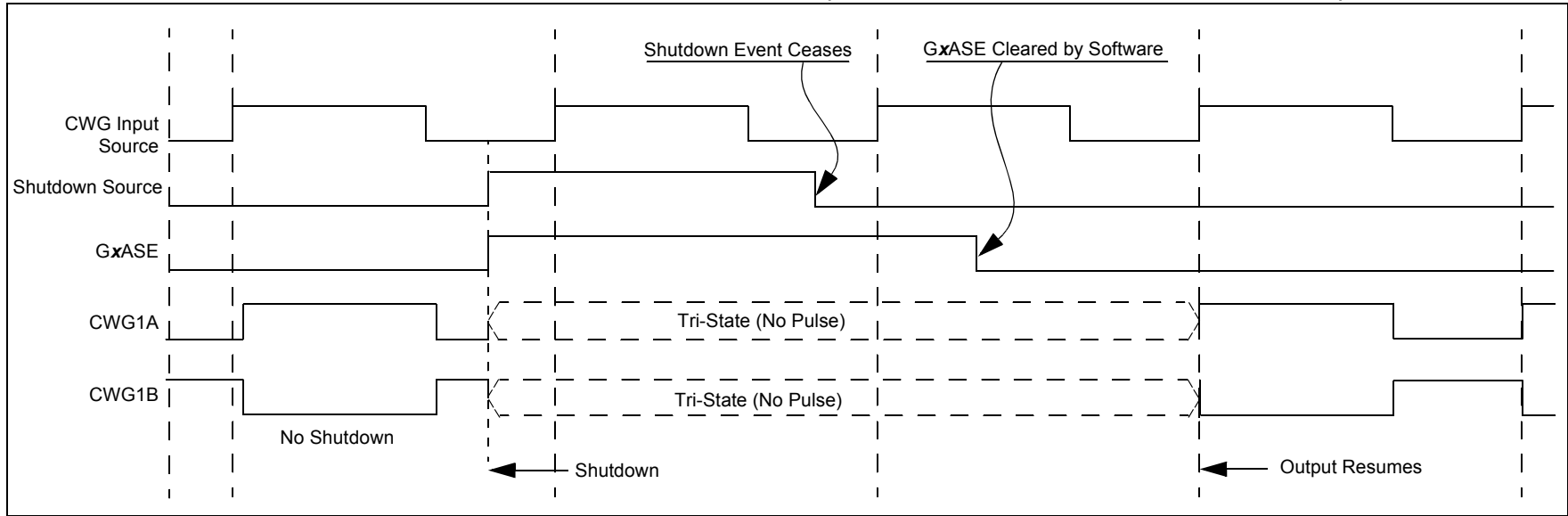
## 24.4 Output Control

Immediately after the CWG module is enabled, the complementary drive is configured with both CWGxA and CWGxB drives cleared.

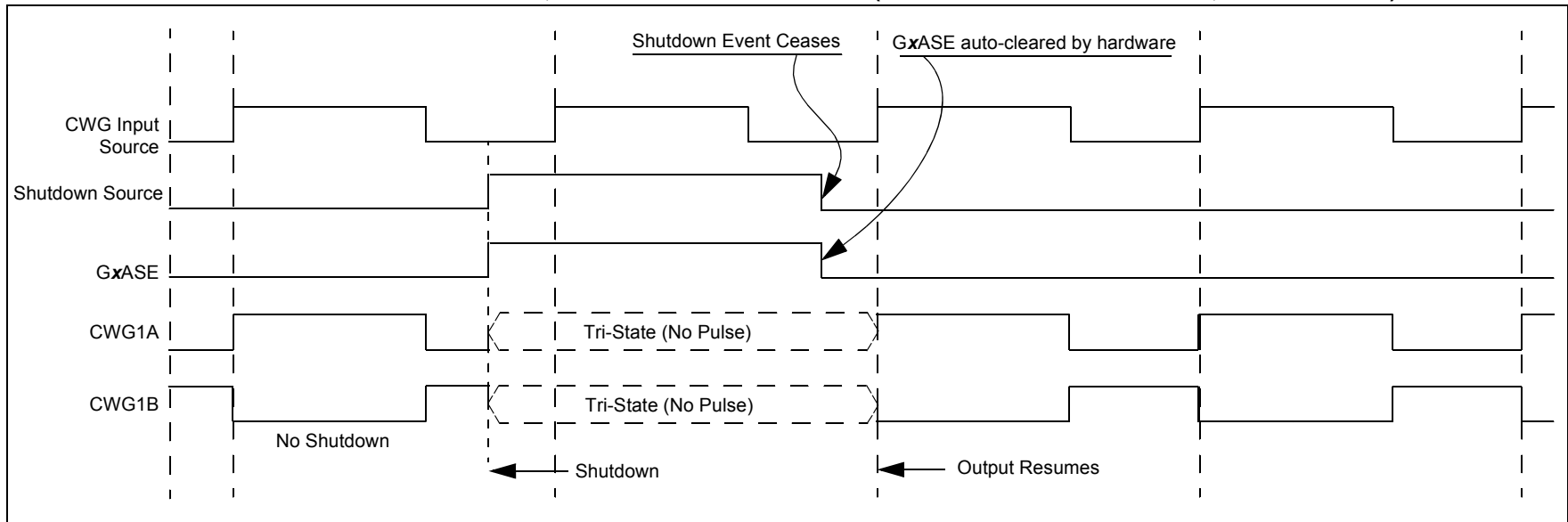
### 24.4.1 POLARITY CONTROL

The polarity of each CWG output can be selected independently. When the output polarity bit is set, the corresponding output is active-high. Clearing the output polarity bit configures the corresponding output as active-low. However, polarity does not affect the override levels. Output polarity is selected with the GxPOLA and GxPOLB bits of the CWGxCON0 register.

**FIGURE 24-5: SHUTDOWN FUNCTIONALITY, AUTO-RESTART DISABLED ( $GxARSEN = 0$ ,  $GxASDLA = 01$ ,  $GxASDLB = 01$ )**

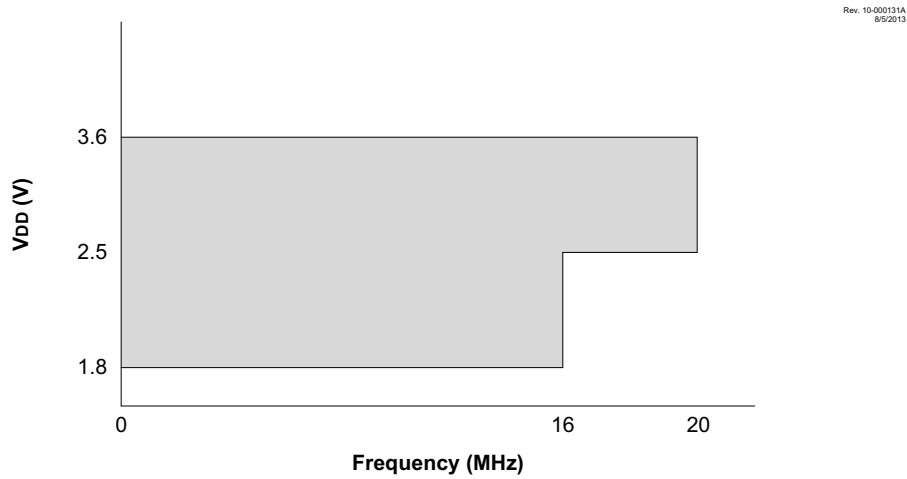


**FIGURE 24-6: SHUTDOWN FUNCTIONALITY, AUTO-RESTART ENABLED ( $GxARSEN = 1$ ,  $GxASDLA = 01$ ,  $GxASDLB = 01$ )**



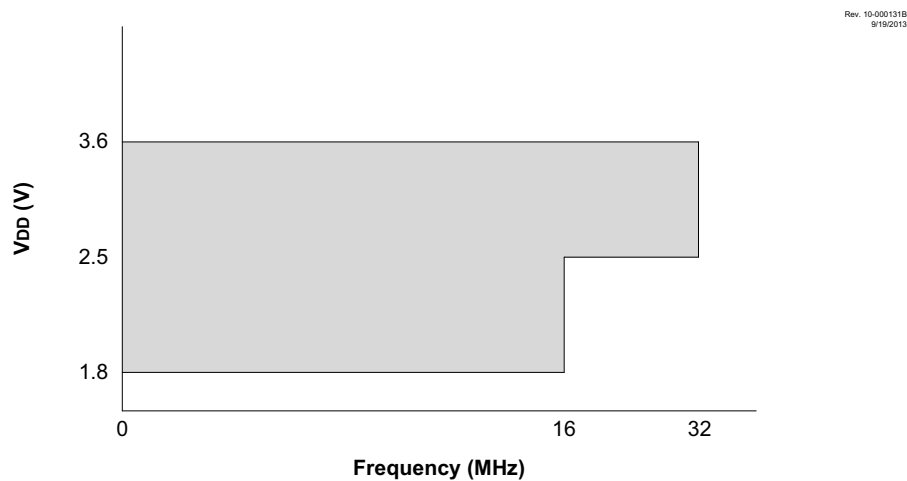
# PIC16(L)F1574/5/8/9

**FIGURE 27-1: VOLTAGE FREQUENCY GRAPH,  $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ , PIC16F1574/5/8/9 ONLY**



- Note 1:** The shaded region indicates the permissible combinations of voltage and frequency.  
**Note 2:** Refer to Table 27-7 for each Oscillator mode's supported frequencies.

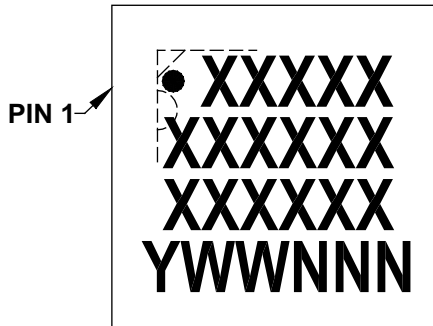
**FIGURE 27-2: VOLTAGE FREQUENCY GRAPH,  $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ , PIC16LF1574/5/8/9 ONLY**



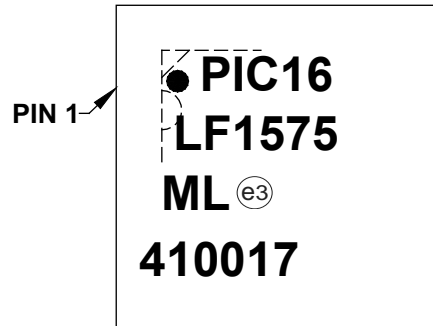
- Note 1:** The shaded region indicates the permissible combinations of voltage and frequency.  
**Note 2:** Refer to Table 27-7 for each Oscillator mode's supported frequencies.

## Package Marking Information (Continued)

16-Lead UQFN (4x4x0.5mm)



Example

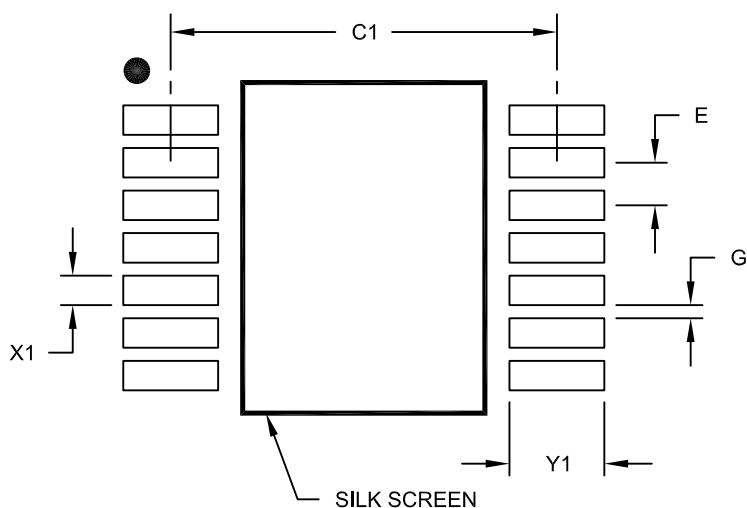


<b>Legend:</b>	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC® designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

## 14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

		Units	MILLIMETERS		
		Dimension Limits	MIN	NOM	MAX
Contact Pitch	E			0.65 BSC	
Contact Pad Spacing	C1			5.90	
Contact Pad Width (X14)	X1				0.45
Contact Pad Length (X14)	Y1				1.45
Distance Between Pads	G	0.20			

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2087A