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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	LINbus, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	12
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 12x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SOIC (0.295", 7.50mm Width)
Supplier Device Package	20-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16f1578-e-so">https://www.e-xfl.com/product-detail/microchip-technology/pic16f1578-e-so</a>

**TABLE 4: 20-PIN ALLOCATION TABLE (PIC16(L)F1578/9)**

I/O	20-Pin PDIP/SOIC/SSOP	20-Pin UQFN	ADC	Reference	Comparator	Timers	PWM	EUSART	CWG	Interrupt	Pull-up	Basic
RA0	19	16	AN0	DAC1OUT1	C1IN+	—	—	—	—	IOC	Y	ICSPDAT
RA1	18	15	AN1	VREF+	C1IN0-/C2IN0-	—	—	—	—	IOC	Y	ICSPCLK
RA2	17	14	AN2	—	—	T0CKI <sup>(1)</sup>	—	—	CWG1IN <sup>(1)</sup>	INT <sup>(1)</sup> /IOC	Y	—
RA3	4	1	—	—	—	—	—	—	—	IOC	Y	MCLR/VPP
RA4	3	20	AN3	—	—	T1G <sup>(1)</sup>	—	—	—	IOC	Y	CLKOUT
RA5	2	19	—	—	—	T1CKI <sup>(1)</sup>	—	—	—	IOC	Y	CLKIN
RB4	13	10	AN10	—	—	—	—	—	—	IOC	Y	—
RB5	12	9	AN11	—	—	—	—	RX <sup>(1,3)</sup>	—	IOC	Y	—
RB6	11	8	—	—	—	—	—	—	—	IOC	Y	—
RB7	10	7	—	—	—	—	—	CK <sup>(1)</sup>	—	IOC	Y	—
RC0	16	13	AN4	—	C2IN+	—	—	—	—	IOC	Y	—
RC1	15	12	AN5	—	C1IN1-/C2IN1-	—	—	—	—	IOC	Y	—
RC2	14	11	AN6	—	C1IN2-/C2IN2-	—	—	—	—	IOC	Y	—
RC3	7	4	AN7	—	C1IN3-/C2IN3-	—	—	—	—	IOC	Y	—
RC4	6	3	ADCACT <sup>(1)</sup>	—	—	—	—	—	—	IOC	Y	—
RC5	5	2	—	—	—	—	—	—	—	IOC	Y	—
RC6	8	5	AN8	—	—	—	—	—	—	IOC	Y	—
RC7	9	6	AN9	—	—	—	—	—	—	IOC	Y	—
VDD	1	18	—	—	—	—	—	—	—	—	—	VDD
VSS	20	17	—	—	—	—	—	—	—	—	—	VSS
OUT <sup>(2)</sup>	—	—	—	—	C1OUT	—	PWM1OUT	DT <sup>(3)</sup>	CWG1A	—	—	—
	—	—	—	—	C2OUT	—	PWM2OUT	CK	CWG1B	—	—	—
	—	—	—	—	—	—	PWM3OUT	TX	—	—	—	—
	—	—	—	—	—	—	PWM4OUT	—	—	—	—	—

- Note**
- 1: Default peripheral input. Input can be moved to any other pin with the PPS Input Selection registers.
  - 2: All pin outputs default to PORT latch data. Any pin can be selected as a digital peripheral output with the PPS Output Selection registers.
  - 3: These peripheral functions are bidirectional. The output pin selections must be the same as the input pin selections.

**TABLE 3-15: SPECIAL FUNCTION REGISTER SUMMARY**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 0											
00Ch	PORTA	—	—	RA5	RA4	RA3	RA2	RA1	RA0	--xx xxxx	--xx xxxx
00Dh	PORTB <sup>(1)</sup>	RB7	RB6	RB5	RB4	—	—	—	—	xxxx ----	xxxx ----
00Eh	PORTC	RC7 <sup>(1)</sup>	RC6 <sup>(1)</sup>	RC5	RC4	RC3	RC2	RC1	RC0	xxxx xxxx	xxxx xxxx
00Fh	—	Unimplemented								—	—
010h	—	Unimplemented								—	—
011h	PIR1	TMR1GIF	ADIF	RCIF	TXIF	—	—	TMR2IF	TMR1IF	0000 --00	0000 --00
012h	PIR2	—	C2IF	C1IF	—	—	—	—	—	-00- ----	-00- ----
013h	PIR3	PWM4IF	PWM3IF	PWM2IF	PWM1IF	—	—	—	—	0000 ----	0000 ----
014h	—									—	—
015h	TMR0	Holding Register for the 8-bit Timer0 Count								xxxx xxxx	uuuu uuuu
016h	TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1 Count								xxxx xxxx	uuuu uuuu
017h	TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1 Count								xxxx xxxx	uuuu uuuu
018h	T1CON	TMR1CS<1:0>		T1CKPS<1:0>		—	T1SYNC	—	TMR1ON	0000 -0-0	uuuu -u-u
019h	T1GCON	TMR1GE	T1GPOL	T1GTM	T1GSPM	T1GGO/ DONE	T1GVAL	T1GSS<1:0>		0000 0x00	uuuu uxuu
01Ah	TMR2	Timer2 Module Register								0000 0000	0000 0000
01Bh	PR2	Timer2 Period Register								1111 1111	1111 1111
01Ch	T2CON	—	T2OUTPS<3:0>				TMR2ON	T2CKPS<1:0>		-000 0000	-000 0000
01Dh	—	Unimplemented								—	—
01Eh	—	Unimplemented								—	—
01Fh	—	Unimplemented								—	—

**Legend:** x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved. Shaded locations are unimplemented, read as '0'.

- Note**
- 1: PIC16(L)F1578/9 only.
  - 2: PIC16F1574/5/8/9 only.
  - 3: Unimplemented, read as '1'.

**TABLE 3-15: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 7											
38Ch	INLVLA	—	—	INLVLA5	INLVLA4	INLVLA3	INLVLA2	INLVLA1	INLVLA0	--11 1111	--11 1111
38Dh	INVLVB <sup>(1)</sup>	INVLVB7	INVLVB6	INVLVB5	INVLVB4	—	—	—	—	1111 ----	1111 ----
38Eh	INLVLC	INLVLC7 <sup>(1)</sup>	INLVLC6 <sup>(1)</sup>	INLVLC5	INLVLC4	INLVLC3	INLVLC2	INLVLC1	INLVLC0	1111 1111	1111 1111
38Fh to 390h	—	Unimplemented								—	—
391h	IOCAP	—	—	IOCAP5	IOCAP4	IOCAP3	IOCAP2	IOCAP1	IOCAP0	--00 0000	--00 0000
392h	IOCAN	—	—	IOCAN5	IOCAN4	IOCAN3	IOCAN2	IOCAN1	IOCAN0	--00 0000	--00 0000
393h	IOCAF	—	—	IOCAF5	IOCAF4	IOCAF3	IOCAF2	IOCAF1	IOCAF0	--00 0000	--00 0000
394h	IOCBP <sup>(1)</sup>	IOCBP7	IOCBP6	IOCBP5	IOCBP4	—	—	—	—	0000 ----	--00 ----
395h	IOCBN <sup>(1)</sup>	IOCBN7	IOCBN6	IOCBN5	IOCBN4	—	—	—	—	0000 ----	--00 ----
396h	IOCBF <sup>(1)</sup>	IOCBF7	IOCBF6	IOCBF5	IOCBF4	—	—	—	—	0000 ----	--00 ----
397h	IOCCP	IOCCP7 <sup>(1)</sup>	IOCCP6 <sup>(1)</sup>	IOCCP5	IOCCP4	IOCCP3	IOCCP2	IOCCP1	IOCCP0	0000 0000	0000 0000
398h	IOCCN	IOCCN7 <sup>(1)</sup>	IOCCN6 <sup>(1)</sup>	IOCCN5	IOCCN4	IOCCN3	IOCCN2	IOCCN1	IOCCN0	0000 0000	0000 0000
399h	IOCCF	IOCCF7 <sup>(1)</sup>	IOCCF6 <sup>(1)</sup>	IOCCF5	IOCCF4	IOCCF3	IOCCF2	IOCCF1	IOCCF0	0000 0000	0000 0000
39Ah to 39Fh	—	Unimplemented								—	—
Bank 8											
40Ch to 41Fh	—	Unimplemented								—	—
Bank 9											
48Ch to 49Fh	—	Unimplemented								—	—

**Legend:** x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved. Shaded locations are unimplemented, read as '0'.

- Note**
- 1: PIC16(L)F1578/9 only.
  - 2: PIC16F1574/5/8/9 only.
  - 3: Unimplemented, read as '1'.

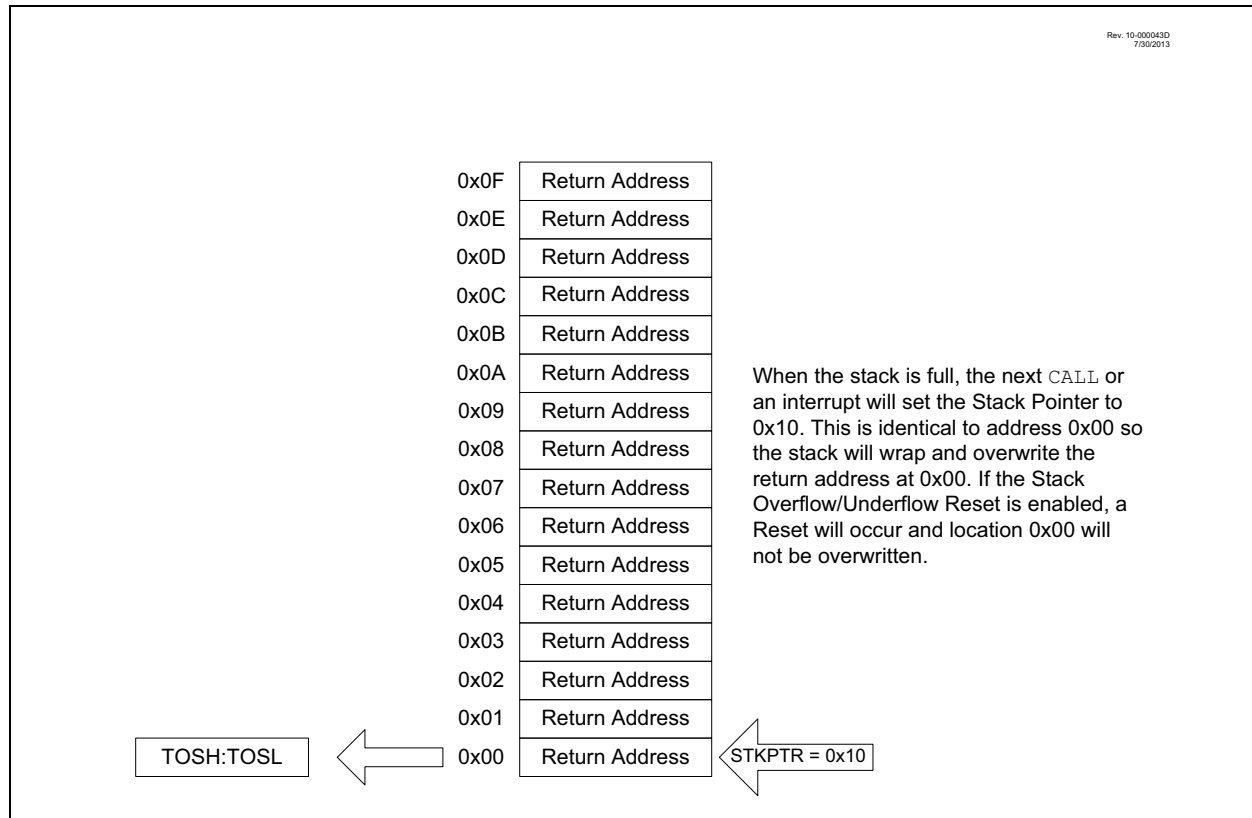
**TABLE 3-15: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 27											
D8Ch	—	Unimplemented								—	—
D8Dh	—	Unimplemented								—	—
D8Eh	PWMEN	—	—	—	—	PWM4EN_A	PWM3EN_A	PWM2EN_A	PWM1EN_A	---- 0000	---- 0000
D8Fh	PWMLD	—	—	—	—	PWM4LDA_A	PWM3LDA_A	PWM2LDA_A	PWM1LDA_A	---- 0000	---- 0000
D90h	PWMOUT	—	—	—	—	PWM4OUT_A	PWM3OUT_A	PWM2OUT_A	PWM1OUT_A	---- 0000	---- 0000
D91h	PWM1PHL	PH<7:0>								xxxx xxxx	uuuu uuuu
D92h	PWM1PHH	PH<15:8>								xxxx xxxx	uuuu uuuu
D93h	PWM1DCL	DC<7:0>								xxxx xxxx	uuuu uuuu
D94h	PWM1DCH	DC<15:8>								xxxx xxxx	uuuu uuuu
D95h	PWM1PRL	PR<7:0>								xxxx xxxx	uuuu uuuu
D96h	PWM1PRH	PR<15:8>								xxxx xxxx	uuuu uuuu
D97h	PWM1OFL	OF<7:0>								xxxx xxxx	uuuu uuuu
D98h	PWM1OFH	OF<15:8>								xxxx xxxx	uuuu uuuu
D99h	PWM1TMRL	TMR<7:0>								xxxx xxxx	uuuu uuuu
D9Ah	PWM1TMRH	TMR<15:8>								xxxx xxxx	uuuu uuuu
D9Bh	PWM1CON	EN	—	OUT	POL	MODE<1:0>		—	—	0-00 00--	0-00 00--
D9Ch	PWM1INTE	—	—	—	—	OFIE	PHIE	DCIE	PRIE	---- 000	---- 000
D9Dh	PWM1INTF	—	—	—	—	OFIF	PHIF	DCIF	PRIF	---- 000	---- 000
D9Eh	PWM1CLKCON	—	PS<2:0>			—	—	CS<1:0>		-000 -000	-000 --00
D9Fh	PWM1LDCON	LDA	LDT	—	—	—	—	LDS<1:0>		00-- -000	00-- --00
DA0h	PWM1OFCON	—	OFM<1:0>		OFO	—	—	OFS<1:0>		-000 -000	-000 --00
DA1h	PWM2PHL	PH<7:0>								xxxx xxxx	uuuu uuuu
DA2h	PWM2PHH	PH<15:8>								xxxx xxxx	uuuu uuuu
DA3h	PWM2DCL	DC<7:0>								xxxx xxxx	uuuu uuuu
DA4h	PWM2DCH	DC<15:8>								xxxx xxxx	uuuu uuuu
DA5h	PWM2PRL	PR<7:0>								xxxx xxxx	uuuu uuuu
DA6h	PWM2PRH	PR<15:8>								xxxx xxxx	uuuu uuuu
DA7h	PWM2OFL	OF<7:0>								xxxx xxxx	uuuu uuuu
DA8h	PWM2OFH	OF<15:8>								xxxx xxxx	uuuu uuuu
DA9h	PWM2TMRL	TMR<7:0>								xxxx xxxx	uuuu uuuu
DAAh	PWM2TMRH	TMR<15:8>								xxxx xxxx	uuuu uuuu

**Legend:** x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved. Shaded locations are unimplemented, read as '0'.

- Note** 1: PIC16(L)F1578/9 only.  
 2: PIC16F1574/5/8/9 only.  
 3: Unimplemented, read as '1'.

**FIGURE 3-8: ACCESSING THE STACK EXAMPLE 4**



### 3.5.2 OVERFLOW/UNDERFLOW RESET

If the `STVREN` bit in Configuration Words is programmed to '1', the device will be reset if the stack is `PUSHed` beyond the sixteenth level or `POPed` beyond the first level, setting the appropriate bits (`STKOVF` or `STKUNF`, respectively) in the `PCON` register.

## 3.6 Indirect Addressing

The `INDFn` registers are not physical registers. Any instruction that accesses an `INDFn` register actually accesses the register at the address specified by the File Select Registers (`FSR`). If the `FSRn` address specifies one of the two `INDFn` registers, the read will return '0' and the write will not occur (though Status bits may be affected). The `FSRn` register value is created by the pair `FSRnH` and `FSRnL`.

The `FSR` registers form a 16-bit address that allows an addressing space with 65536 locations. These locations are divided into three memory regions:

- Traditional Data Memory
- Linear Data Memory
- Program Flash Memory

# PIC16(L)F1574/5/8/9

## REGISTER 5-2: OSCSTAT: OSCILLATOR STATUS REGISTER

U-0	R-0/q	R-q/q	R-0/q	R-0/q	R-q/q	R-0/q	R-0/q
—	PLL R	OSTS	HFIOFR	HFIOFL	MFIOFR	LFIOFR	HFIOFS
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

q = Conditional

bit 7 **Unimplemented:** Read as '0'

bit 6 **PLL R** 4x PLL Ready bit

1 = 4x PLL is ready

0 = 4x PLL is not ready

bit 5 **OSTS:** Oscillator Start-up Timer Status bit

1 = Running from the clock defined by the FOSC<1:0> bits of the Configuration Words

0 = Running from an internal oscillator (FOSC<1:0> = 00)

bit 4 **HFIOFR:** High-Frequency Internal Oscillator Ready bit

1 = HFINTOSC is ready

0 = HFINTOSC is not ready

bit 3 **HFIOFL:** High-Frequency Internal Oscillator Locked bit

1 = HFINTOSC is at least 2% accurate

0 = HFINTOSC is not 2% accurate

bit 2 **MFIOFR:** Medium-Frequency Internal Oscillator Ready bit

1 = MFINTOSC is ready

0 = MFINTOSC is not ready

bit 1 **LFIOFR:** Low-Frequency Internal Oscillator Ready bit

1 = LFINTOSC is ready

0 = LFINTOSC is not ready

bit 0 **HFIOFS:** High-Frequency Internal Oscillator Stable bit

1 = HFINTOSC is at least 0.5% accurate

0 = HFINTOSC is not 0.5% accurate

# PIC16(L)F1574/5/8/9

**REGISTER 7-5: PIR1: PERIPHERAL INTERRUPT REQUEST REGISTER 1**

R/W-0/0	R/W-0/0	R-0/0	R-0/0	U-0	U-0	R/W-0/0	R/W-0/0
TMR1GIF	ADIF	RCIF	TXIF	—	—	TMR2IF	TMR1IF
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 u = Bit is unchanged                  x = Bit is unknown                      -n/n = Value at POR and BOR/Value at all other Resets  
 '1' = Bit is set                          '0' = Bit is cleared

- bit 7                      **TMR1GIF:** Timer1 Gate Interrupt Flag bit  
                               1 = Interrupt is pending  
                               0 = Interrupt is not pending  
 bit 6                      **ADIF:** ADC Interrupt Flag bit  
                               1 = Interrupt is pending  
                               0 = Interrupt is not pending  
 bit 5                      **RCIF:** USART Receive Interrupt Flag bit  
                               1 = Interrupt is pending  
                               0 = Interrupt is not pending  
 bit 4                      **TXIF:** USART Transmit Interrupt Flag bit  
                               1 = Interrupt is pending  
                               0 = Interrupt is not pending  
 bit 3-2                   **Unimplemented:** Read as '0'  
 bit 1                      **TMR2IF:** Timer2 to PR2 Interrupt Flag bit  
                               1 = Interrupt is pending  
                               0 = Interrupt is not pending  
 bit 0                      **TMR1IF:** Timer1 Overflow Interrupt Flag bit  
                               1 = Interrupt is pending  
                               0 = Interrupt is not pending

**Note:** Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Interrupt Enable bit, GIE of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt. The USART RCIF and TXIF bits are read-only.



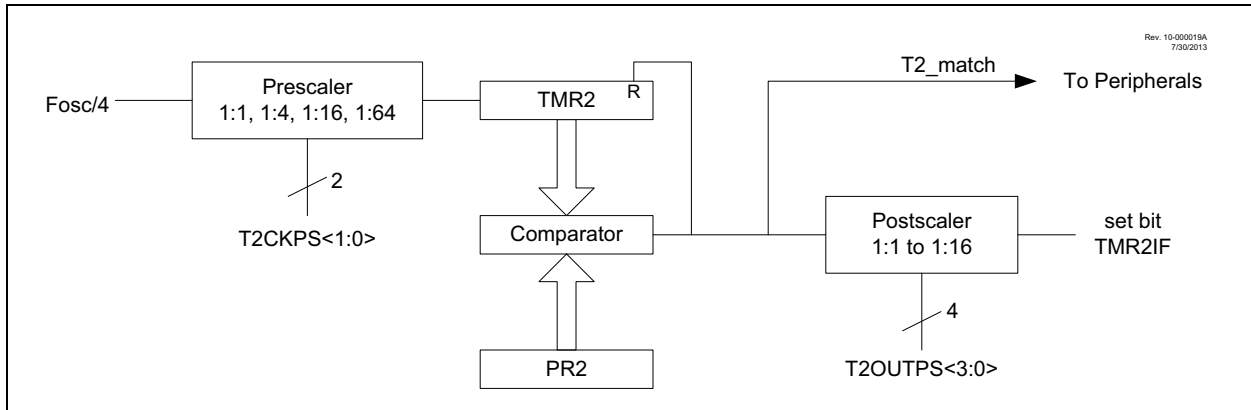
## 21.0 TIMER2 MODULE

The Timer2 module incorporates the following features:

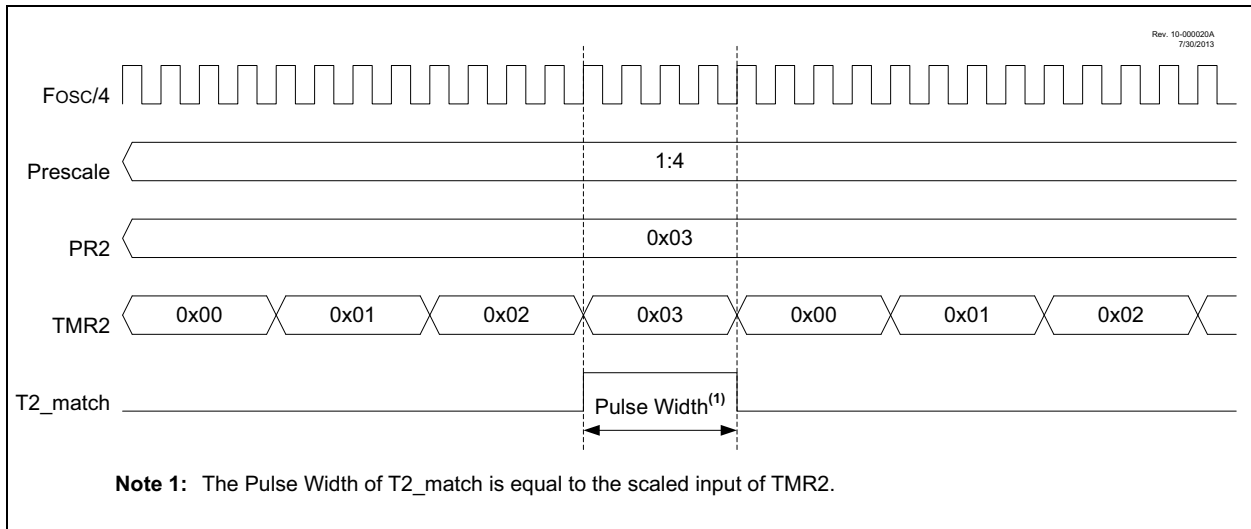
- 8-bit Timer and Period registers (TMR2 and PR2, respectively)
- Readable and writable (both registers)
- Software programmable prescaler (1:1, 1:4, 1:16, and 1:64)
- Software programmable postscaler (1:1 to 1:16)
- Interrupt on TMR2 match with PR2

See Figure 21-1 for a block diagram of Timer2.

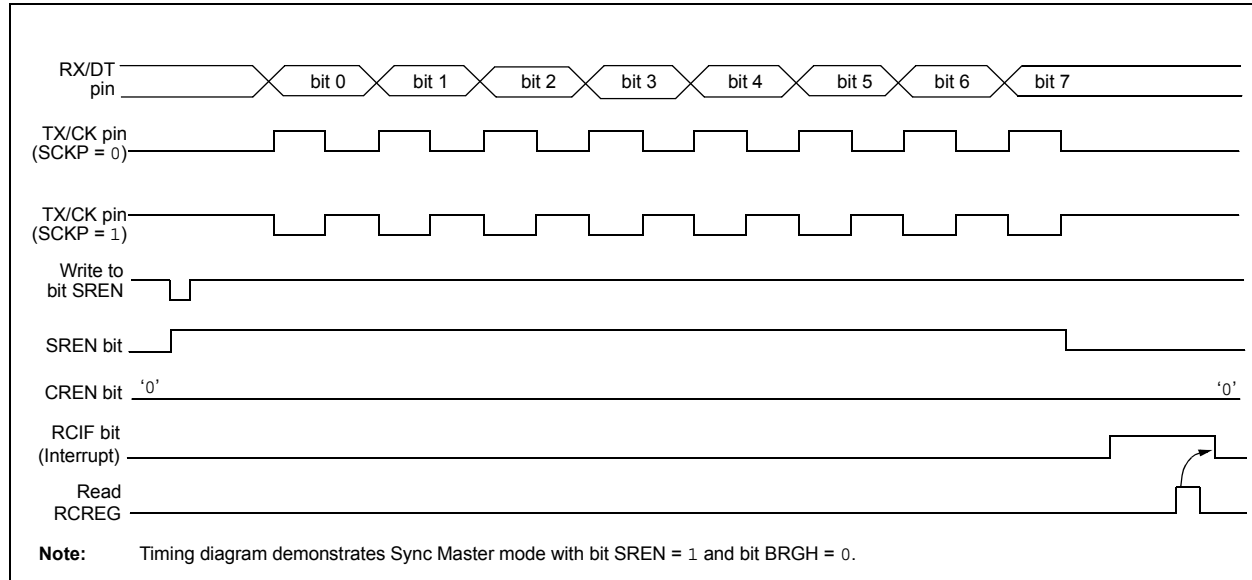
**FIGURE 21-1: TIMER2 BLOCK DIAGRAM**



**FIGURE 21-2: TIMER2 TIMING DIAGRAM**



**FIGURE 22-12: SYNCHRONOUS RECEPTION (MASTER MODE, SREN)**



**TABLE 22-8: SUMMARY OF REGISTERS ASSOCIATED WITH SYNCHRONOUS MASTER RECEPTION**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BAUDCON	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	204
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	86
PIE1	TMR1GIE	ADIE	RCIE	TXIE	—	—	TMR2IE	TMR1IE	87
PIR1	TMR1GIF	ADIF	RCIF	TXIF	—	—	TMR2IF	TMR1IF	90
RCREG	EUSART Receive Data Register								197*
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	203
SPBRGL	BRG<7:0>								205*
SPBRGH	BRG<15:8>								205*
TXSTA	CSRC	TX9	TXEN	SYNC	SEnDB	BRGH	TRMT	TX9D	202

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used for synchronous master reception.

\* Page provides register information.

## REGISTER 23-4: PWMxCLKCON: PWM CLOCK CONTROL REGISTER

U-0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	U-0	R/W-0/0	R/W-0/0
—	PS<2:0>			—	—	CS<1:0>	
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **PS<2:0>:** Clock Source Prescaler Select bits

111 = Divide clock source by 128

110 = Divide clock source by 64

101 = Divide clock source by 32

100 = Divide clock source by 16

011 = Divide clock source by 8

010 = Divide clock source by 4

001 = Divide clock source by 2

000 = No Prescaler

bit 3-2 **Unimplemented:** Read as '0'

bit 1-0 **CS<1:0>:** Clock Source Select bits

11 = Reserved

10 = LFINTOSC (continues to operate during Sleep)

01 = HFINTOSC (continues to operate during Sleep)

00 = FOSC

# PIC16(L)F1574/5/8/9

## 26.0 INSTRUCTION SET SUMMARY

Each instruction is a 14-bit word containing the operation code (opcode) and all required operands. The opcodes are broken into three broad categories.

- Byte Oriented
- Bit Oriented
- Literal and Control

The literal and control category contains the most varied instruction word format.

Table 26-3 lists the instructions recognized by the MPASM™ assembler.

All instructions are executed within a single instruction cycle, with the following exceptions, which may take two or three cycles:

- Subroutine takes two cycles (CALL, CALLW)
- Returns from interrupts or subroutines take two cycles (RETURN, RETLW, RETFIE)
- Program branching takes two cycles (GOTO, BRA, BRW, BTFSS, BTFSC, DECFSZ, INCSFZ)
- One additional instruction cycle will be used when any instruction references an indirect file register and the file select register is pointing to program memory.

One instruction cycle consists of 4 oscillator cycles; for an oscillator frequency of 4 MHz, this gives a nominal instruction execution rate of 1 MHz.

All instruction examples use the format '0xhh' to represent a hexadecimal number, where 'h' signifies a hexadecimal digit.

## 26.1 Read-Modify-Write Operations

Any instruction that specifies a file register as part of the instruction performs a Read-Modify-Write (R-M-W) operation. The register is read, the data is modified, and the result is stored according to either the instruction, or the destination designator 'd'. A read operation is performed on a register even if the instruction writes to that register.

**TABLE 26-1: OPCODE FIELD DESCRIPTIONS**

Field	Description
f	Register file address (0x00 to 0x7F)
W	Working register (accumulator)
b	Bit address within an 8-bit file register
k	Literal field, constant data or label
x	Don't care location (= 0 or 1). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools.
d	Destination select; d = 0: store result in W, d = 1: store result in file register f. Default is d = 1.
n	FSR or INDF number. (0-1)
mm	Pre-post increment-decrement mode selection

**TABLE 26-2: ABBREVIATION DESCRIPTIONS**

Field	Description
PC	Program Counter
$\overline{TO}$	Time-Out bit
C	Carry bit
DC	Digit Carry bit
Z	Zero bit
$\overline{PD}$	Power-Down bit

# PIC16(L)F1574/5/8/9

**TABLE 26-3: ENHANCED MID-RANGE INSTRUCTION SET**

Mnemonic, Operands		Description	Cycles	14-Bit Opcode				Status Affected	Notes
				MSb		LSb			
BYTE-ORIENTED FILE REGISTER OPERATIONS									
ADDWF	f, d	Add W and f	1	00	0111	dfff	ffff	C, DC, Z	2
ADDWFC	f, d	Add with Carry W and f	1	11	1101	dfff	ffff	C, DC, Z	2
ANDWF	f, d	AND W with f	1	00	0101	dfff	ffff	Z	2
ASRF	f, d	Arithmetic Right Shift	1	11	0111	dfff	ffff	C, Z	2
LSLF	f, d	Logical Left Shift	1	11	0101	dfff	ffff	C, Z	2
LSRF	f, d	Logical Right Shift	1	11	0110	dfff	ffff	C, Z	2
CLRF	f	Clear f	1	00	0001	1fff	ffff	Z	2
CLRW	—	Clear W	1	00	0001	0000	00xx	Z	
COMF	f, d	Complement f	1	00	1001	dfff	ffff	Z	2
DECF	f, d	Decrement f	1	00	0011	dfff	ffff	Z	2
INCF	f, d	Increment f	1	00	1010	dfff	ffff	Z	2
IORWF	f, d	Inclusive OR W with f	1	00	0100	dfff	ffff	Z	2
MOVF	f, d	Move f	1	00	1000	dfff	ffff	Z	2
MOVWF	f	Move W to f	1	00	0000	1fff	ffff		2
RLF	f, d	Rotate Left f through Carry	1	00	1101	dfff	ffff	C	2
RRF	f, d	Rotate Right f through Carry	1	00	1100	dfff	ffff	C	2
SUBWF	f, d	Subtract W from f	1	00	0010	dfff	ffff	C, DC, Z	2
SUBWFB	f, d	Subtract with Borrow W from f	1	11	1011	dfff	ffff	C, DC, Z	2
SWAPF	f, d	Swap nibbles in f	1	00	1110	dfff	ffff		2
XORWF	f, d	Exclusive OR W with f	1	00	0110	dfff	ffff	Z	2
BYTE ORIENTED SKIP OPERATIONS									
DECFSZ	f, d	Decrement f, Skip if 0	1(2)	00	1011	dfff	ffff		1, 2
INCFSZ	f, d	Increment f, Skip if 0	1(2)	00	1111	dfff	ffff		1, 2
BIT-ORIENTED FILE REGISTER OPERATIONS									
BCF	f, b	Bit Clear f	1	01	00bb	bfff	ffff		2
BSF	f, b	Bit Set f	1	01	01bb	bfff	ffff		2
BIT-ORIENTED SKIP OPERATIONS									
BTFSC	f, b	Bit Test f, Skip if Clear	1 (2)	01	10bb	bfff	ffff		1, 2
BTFSS	f, b	Bit Test f, Skip if Set	1 (2)	01	11bb	bfff	ffff		1, 2
LITERAL OPERATIONS									
ADDLW	k	Add literal and W	1	11	1110	kkkk	kkkk	C, DC, Z	
ANDLW	k	AND literal with W	1	11	1001	kkkk	kkkk	Z	
IORLW	k	Inclusive OR literal with W	1	11	1000	kkkk	kkkk	Z	
MOVLB	k	Move literal to BSR	1	00	0000	001k	kkkk		
MOVLW	k	Move literal to PCLATH	1	11	0001	1kkk	kkkk		
MOVLW	k	Move literal to W	1	11	0000	kkkk	kkkk		
SUBLW	k	Subtract W from literal	1	11	1100	kkkk	kkkk	C, DC, Z	
XORLW	k	Exclusive OR literal with W	1	11	1010	kkkk	kkkk	Z	

**Note 1:** If the Program Counter (PC) is modified, or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a NOP.

- 2:** If this instruction addresses an INDF register and the MSb of the corresponding FSR is set, this instruction will require one additional instruction cycle.

## 27.2 Standard Operating Conditions

The standard operating conditions for any device are defined as:

Operating Voltage:  $V_{DDMIN} \leq V_{DD} \leq V_{DDMAX}$

Operating Temperature:  $T_{A\_MIN} \leq T_A \leq T_{A\_MAX}$

### V<sub>DD</sub> — Operating Supply Voltage<sup>(1)</sup>

#### PIC16LF1574/5/8/9

V<sub>DDMIN</sub> (F<sub>osc</sub> ≤ 16 MHz) ..... +1.8V

V<sub>DDMIN</sub> (F<sub>osc</sub> ≤ 32 MHz) ..... +2.5V

V<sub>DDMAX</sub> ..... +3.6V

#### PIC16F1574/5/8/9

V<sub>DDMIN</sub> (F<sub>osc</sub> ≤ 16 MHz) ..... +2.3V

V<sub>DDMIN</sub> (F<sub>osc</sub> ≤ 32 MHz) ..... +2.5V

V<sub>DDMAX</sub> ..... +5.5V

### T<sub>A</sub> — Operating Ambient Temperature Range

#### Industrial Temperature

T<sub>A\\_MIN</sub> ..... -40°C

T<sub>A\\_MAX</sub> ..... +85°C

#### Extended Temperature

T<sub>A\\_MIN</sub> ..... -40°C

T<sub>A\\_MAX</sub> ..... +125°C

**Note 1:** See Parameter D001, DS Characteristics: Supply Voltage.

# PIC16(L)F1574/5/8/9

FIGURE 27-1: VOLTAGE FREQUENCY GRAPH,  $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ , PIC16F1574/5/8/9 ONLY

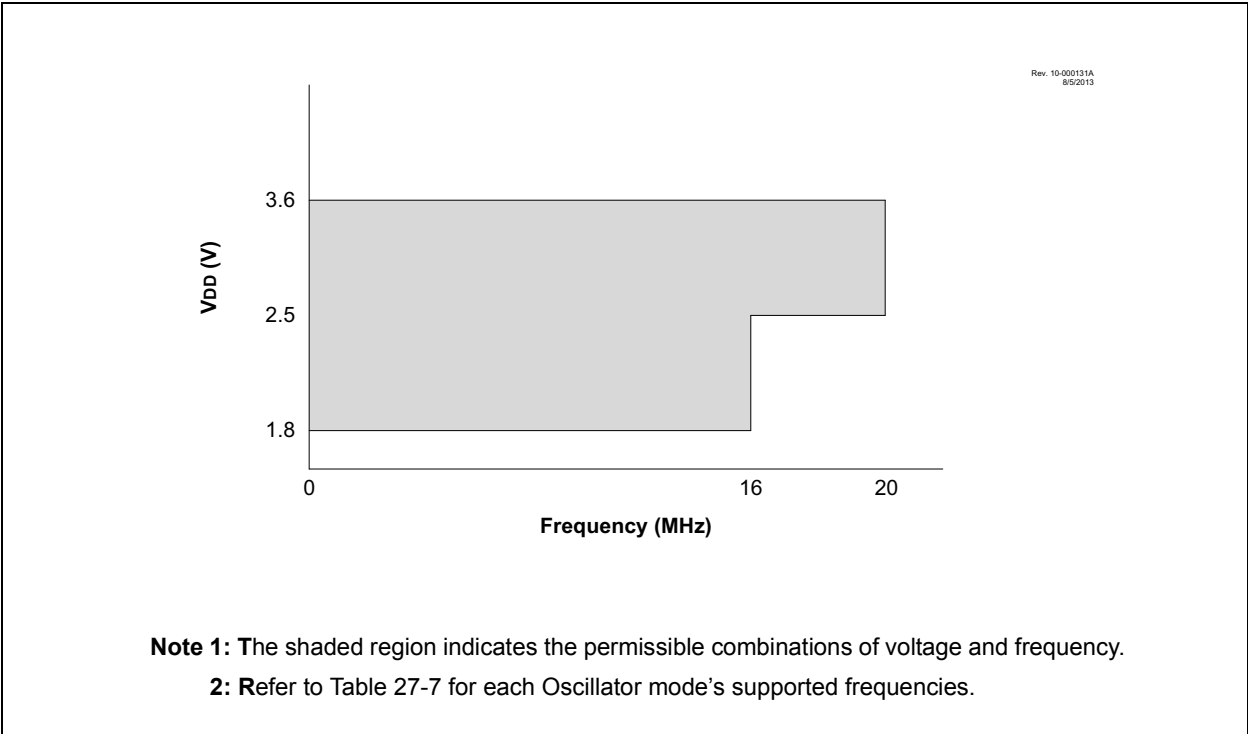
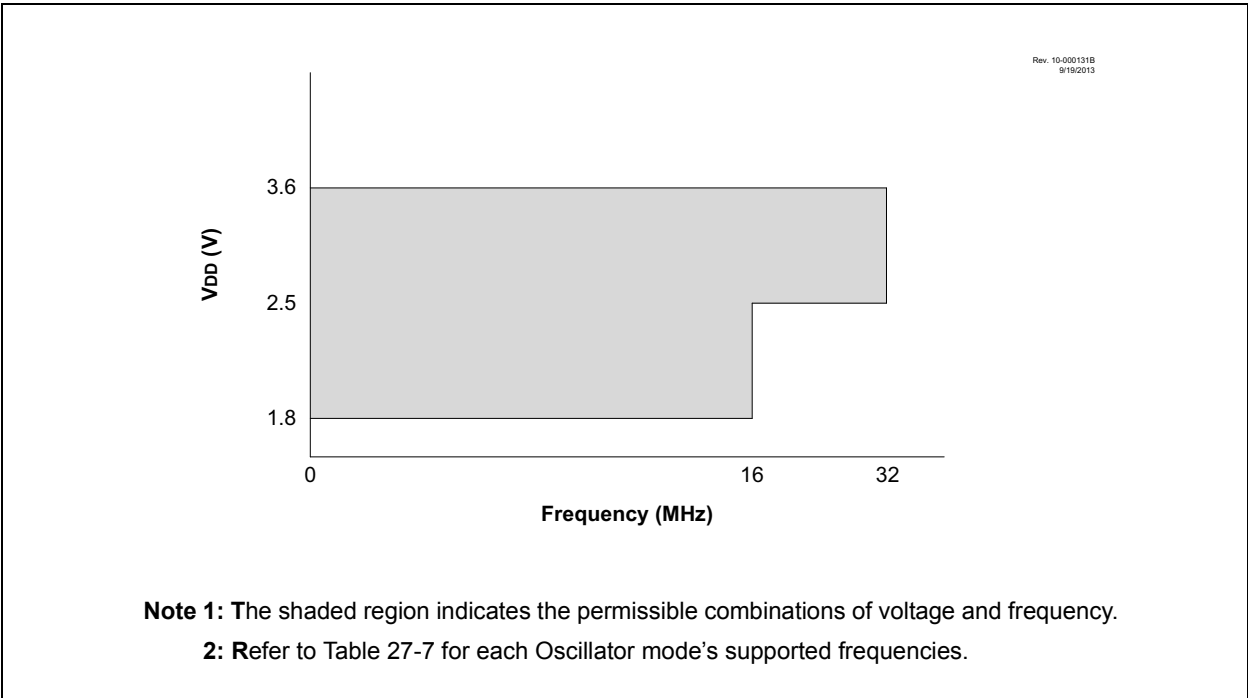
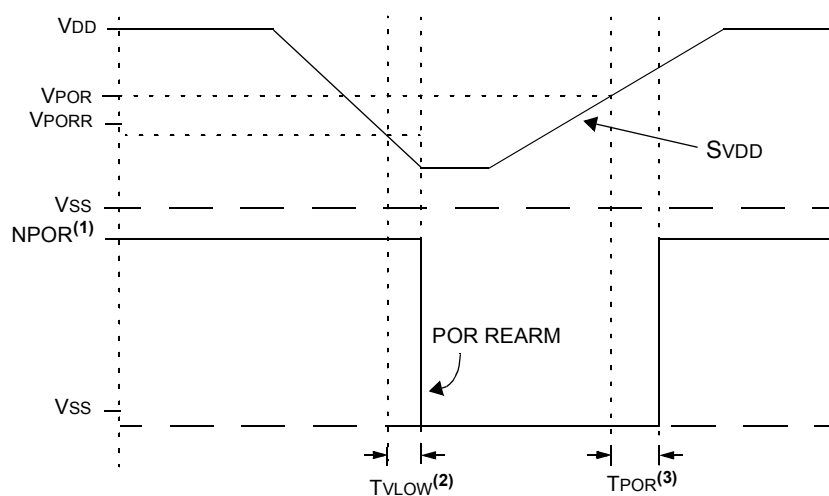


FIGURE 27-2: VOLTAGE FREQUENCY GRAPH,  $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ , PIC16LF1574/5/8/9 ONLY



# PIC16(L)F1574/5/8/9

FIGURE 27-3: POR AND POR REARM WITH SLOW RISING V<sub>DD</sub>



- Note** 1: When NPOR is low, the device is held in Reset.  
2: TPOR 1  $\mu$ s typical.  
3: TVLOW 2.7  $\mu$ s typical.



# PIC16(L)F1574/5/8/9

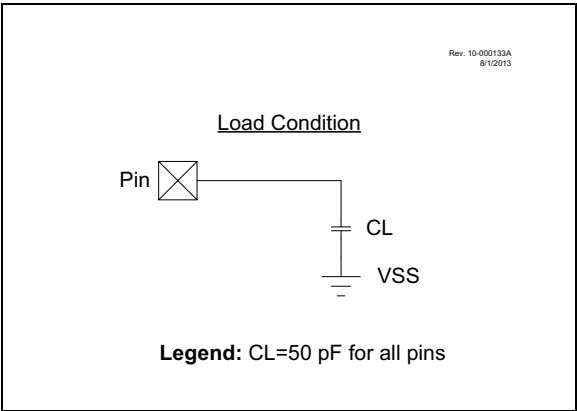
## 27.4 AC Characteristics

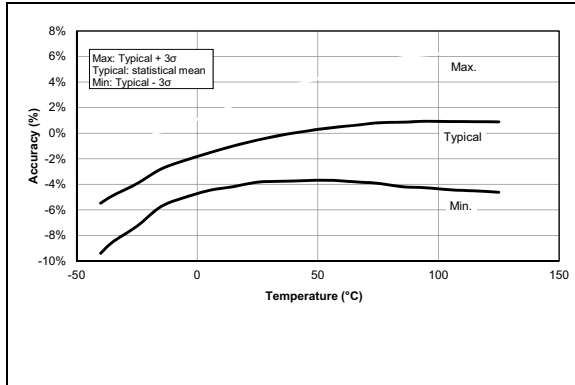
Timing Parameter Symbolology has been created with one of the following formats:

- 1. TppS2ppS
- 2. TppS

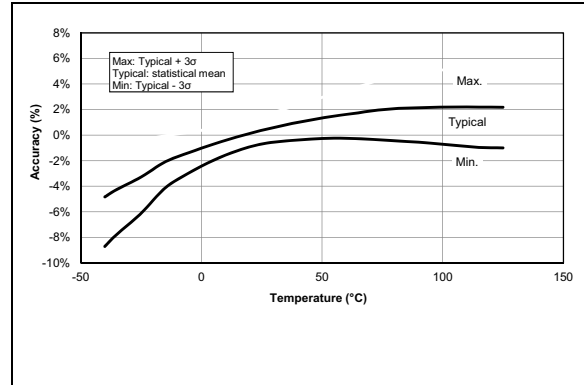
<b>T</b>			
F	Frequency	T	Time
Lowercase letters (pp) and their meanings:			
<b>pp</b>			
cc	CCP1	osc	CLKIN
ck	CLKOUT	rd	$\overline{RD}$
cs	$\overline{CS}$	rw	$\overline{RD}$ or $\overline{WR}$
di	SDIx	sc	SCKx
do	SDO	ss	$\overline{SS}$
dt	Data in	t0	T0CKI
io	I/O PORT	t1	T1CKI
mc	MCLR	wr	$\overline{WR}$
Uppercase letters and their meanings:			
<b>S</b>			
F	Fall	P	Period
H	High	R	Rise
I	Invalid (High-impedance)	V	Valid
L	Low	Z	High-impedance

FIGURE 27-4: LOAD CONDITIONS

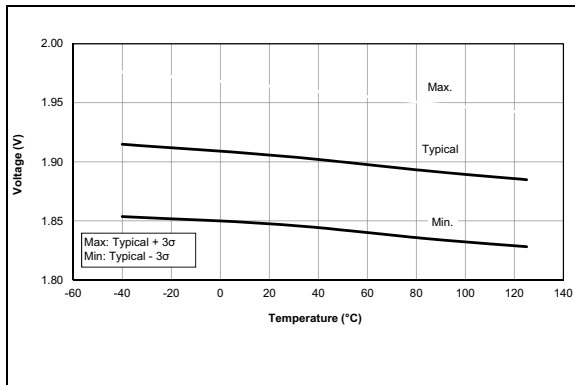




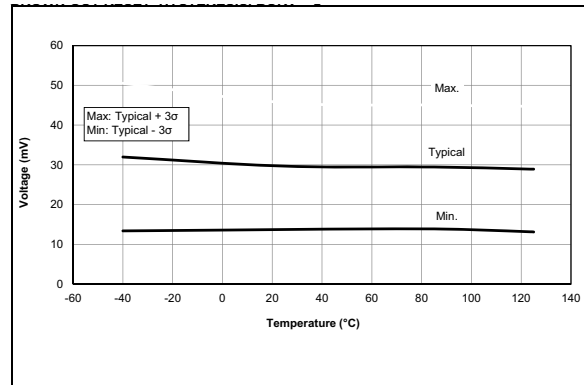
**FIGURE 28-43:** HFINTOSC Accuracy Over Temperature,  $V_{DD} = 1.8V$ , LF Devices Only.



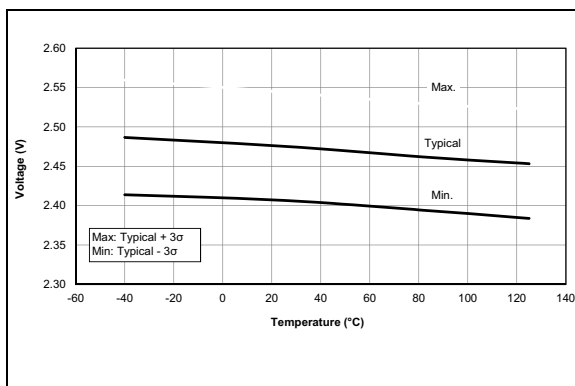
**FIGURE 28-44:** HFINTOSC Accuracy Over Temperature,  $2.3V \leq V_{DD} \leq 5.5V$ .



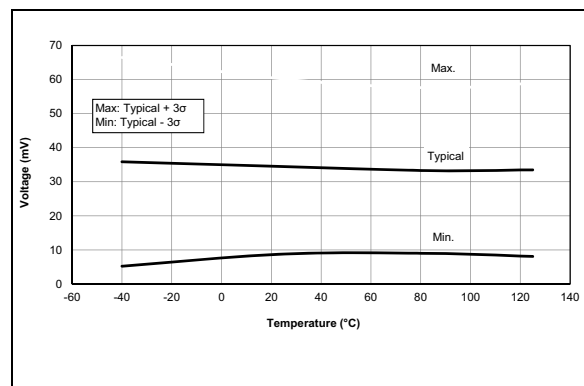
**FIGURE 28-45:** Brown-Out Reset Voltage,  $BORV = 1$ , PIC16LF1574/5/8/9 Only.



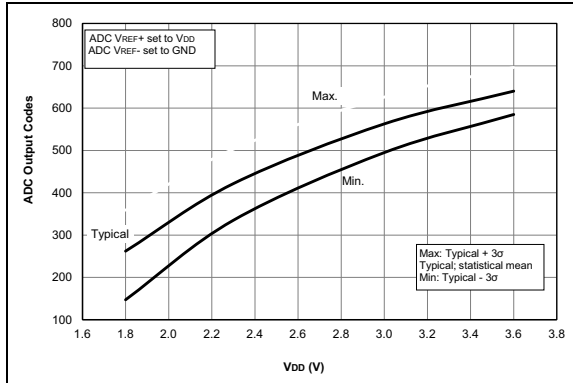
**FIGURE 28-46:** Brown-Out Reset Hysteresis,  $BORV = 1$ , PIC16LF1574/5/8/9 Only.



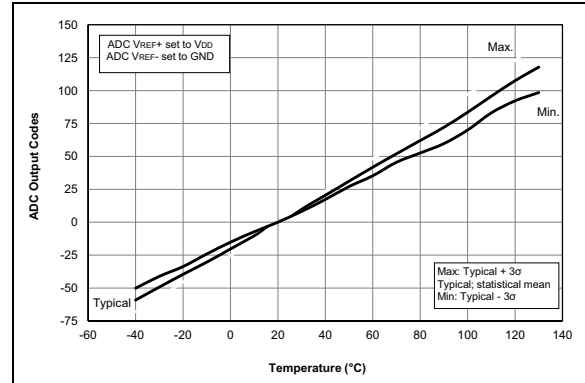
**FIGURE 28-47:** Brown-Out Reset Voltage,  $BORV = 1$ , PIC16F1574/5/8/9 Only.



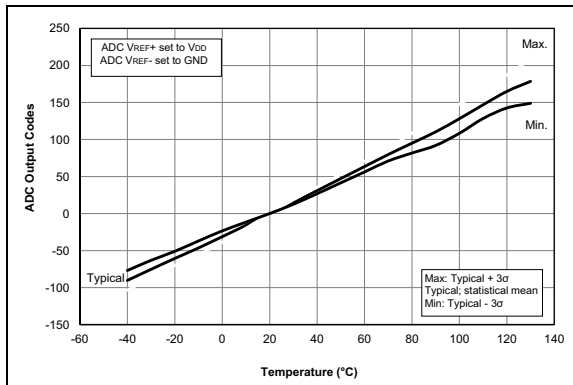
**FIGURE 28-48:** Brown-Out Reset Hysteresis,  $BORV = 1$ , PIC16F1574/5/8/9 Only.



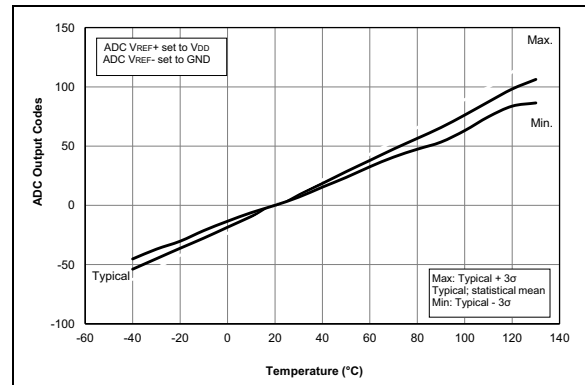
**FIGURE 28-67:** Temperature Indicator Initial Offset, Low Range, Temp = 20°C, LF Devices Only.



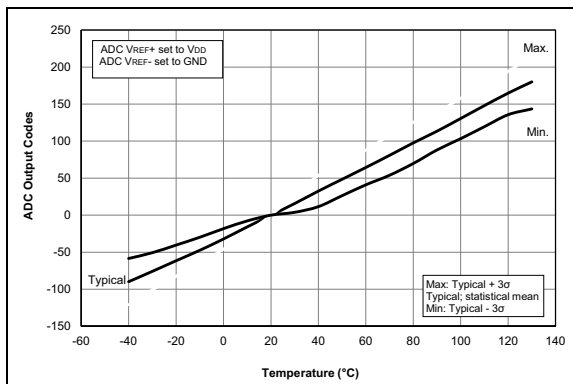
**FIGURE 28-68:** Temperature Indicator Slope Normalized TO 20°C, High Range, VDD = 5.5V, F Devices Only.



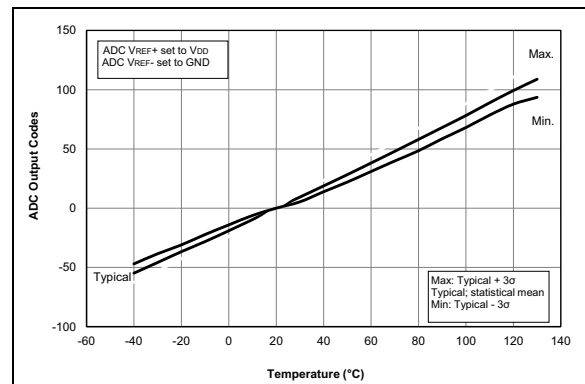
**FIGURE 28-69:** Temperature Indicator Slope Normalized TO 20°C, High Range, VDD = 3.6V, F Devices Only.



**FIGURE 28-70:** Temperature Indicator Slope Normalized TO 20°C, Low Range, VDD = 3.0V, F Devices Only.



**FIGURE 28-71:** Temperature Indicator Slope Normalized TO 20°C, Low Range, VDD = 1.8V, LF Devices Only.



**FIGURE 28-72:** Temperature Indicator Slope Normalized TO 20°C, Low Range, VDD = 3.0V, LF Devices Only.

## 29.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® X IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB XC Compiler
  - MPASM™ Assembler
  - MPLINK™ Object Linker/  
MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for  
Various Device Families
- Simulators
  - MPLAB X SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
  - MPLAB ICD 3
  - PICKit™ 3
- Device Programmers
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards,  
Evaluation Kits and Starter Kits
- Third-party development tools

## 29.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

### Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

### User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

### Project-Based Workspaces:

- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

### File History and Bug Tracking:

- Local file history feature
- Built-in support for Bugzilla issue tracker

## 14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>

