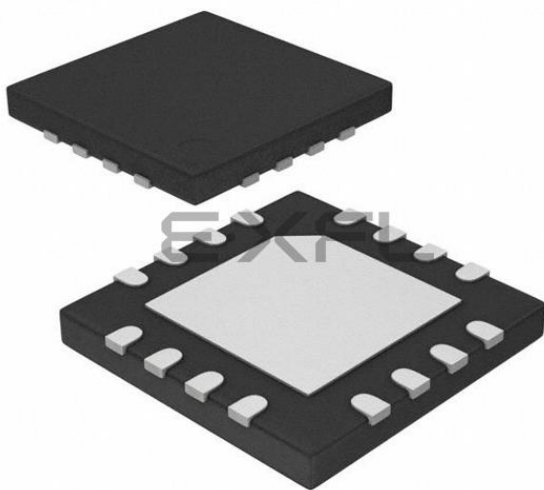




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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	LINbus, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	12
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 8x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	16-UQFN Exposed Pad
Supplier Device Package	16-UQFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1575-e-jq

3.3.2 SPECIAL FUNCTION REGISTER

The Special Function Registers are registers used by the application to control the desired operation of peripheral functions in the device. The Special Function Registers occupy the 20 bytes after the core registers of every data memory bank (addresses x0Ch/x8Ch through x1Fh/x9Fh). The registers associated with the operation of the peripherals are described in the appropriate peripheral chapter of this data sheet.

3.3.3 GENERAL PURPOSE RAM

There are up to 80 bytes of GPR in each data memory bank. The Special Function Registers occupy the 20 bytes after the core registers of every data memory bank (addresses x0Ch/x8Ch through x1Fh/x9Fh).

3.3.3.1 Linear Access to GPR

The general purpose RAM can be accessed in a non-banked method via the FSRs. This can simplify access to large memory structures. See **Section 3.6.2 “Linear Data Memory”** for more information.

3.3.4 COMMON RAM

There are 16 bytes of common RAM accessible from all banks.

3.3.5 DEVICE MEMORY MAPS

The memory maps are as shown in Table 3-3 through Table 3-13.

FIGURE 3-3: BANKED MEMORY PARTITIONING

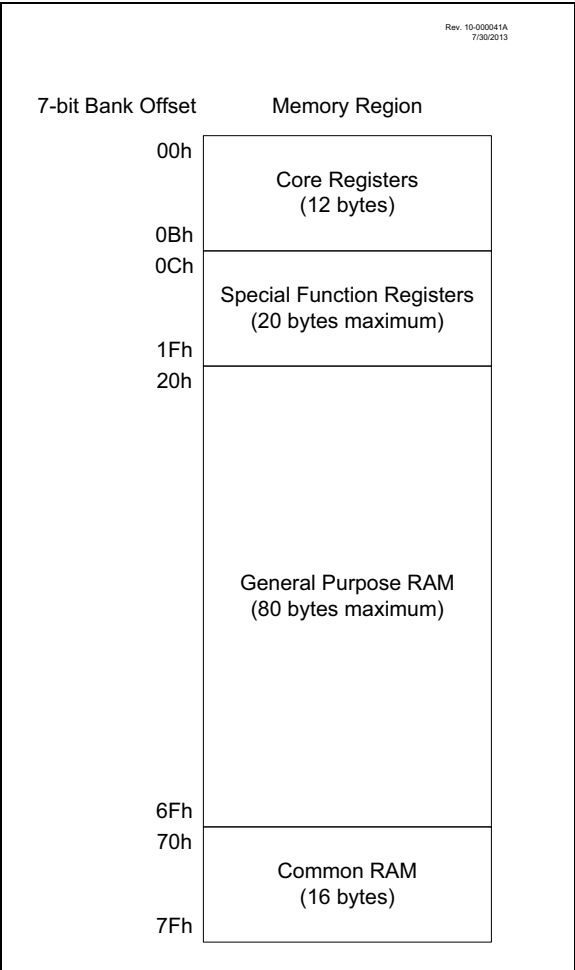


TABLE 3-15: SPECIAL FUNCTION REGISTER SUMMARY

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 0											
00Ch	PORTA	—	—	RA5	RA4	RA3	RA2	RA1	RA0	--xx xxxx	--xx xxxx
00Dh	PORTB ⁽¹⁾	RB7	RB6	RB5	RB4	—	—	—	—	xxxx ----	xxxx ----
00Eh	PORTC	RC7 ⁽¹⁾	RC6 ⁽¹⁾	RC5	RC4	RC3	RC2	RC1	RC0	xxxx xxxx	xxxx xxxx
00Fh	—	Unimplemented								—	—
010h	—	Unimplemented								—	—
011h	PIR1	TMR1GIF	ADIF	RCIF	TXIF	—	—	TMR2IF	TMR1IF	0000 --00	0000 --00
012h	PIR2	—	C2IF	C1IF	—	—	—	—	—	-00- ----	-00- ----
013h	PIR3	PWM4IF	PWM3IF	PWM2IF	PWM1IF	—	—	—	—	0000 ----	0000 ----
014h	—									—	—
015h	TMR0	Holding Register for the 8-bit Timer0 Count								xxxx xxxx	uuuu uuuu
016h	TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1 Count								xxxx xxxx	uuuu uuuu
017h	TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1 Count								xxxx xxxx	uuuu uuuu
018h	T1CON	TMR1CS<1:0>		T1CKPS<1:0>		—	T1SYNC	—	TMR1ON	0000 -0-0	uuuu -u-u
019h	T1GCON	TMR1GE	T1GPOL	T1GTM	T1GSPM	T1GGO/ DONE	T1GVAL	T1GSS<1:0>		0000 0x00	uuuu uxuu
01Ah	TMR2	Timer2 Module Register								0000 0000	0000 0000
01Bh	PR2	Timer2 Period Register								1111 1111	1111 1111
01Ch	T2CON	—	T2OUTPS<3:0>				TMR2ON	T2CKPS<1:0>		-000 0000	-000 0000
01Dh	—	Unimplemented								—	—
01Eh	—	Unimplemented								—	—
01Fh	—	Unimplemented								—	—

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved. Shaded locations are unimplemented, read as '0'.

- Note**
- 1: PIC16(L)F1578/9 only.
 - 2: PIC16F1574/5/8/9 only.
 - 3: Unimplemented, read as '1'.

TABLE 3-15: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 7											
38Ch	INLVLA	—	—	INLVLA5	INLVLA4	INLVLA3	INLVLA2	INLVLA1	INLVLA0	--11 1111	--11 1111
38Dh	INVLVB ⁽¹⁾	INVLVB7	INVLVB6	INVLVB5	INVLVB4	—	—	—	—	1111 ----	1111 ----
38Eh	INLVLC	INLVLC7 ⁽¹⁾	INLVLC6 ⁽¹⁾	INLVLC5	INLVLC4	INLVLC3	INLVLC2	INLVLC1	INLVLC0	1111 1111	1111 1111
38Fh to 390h	—	Unimplemented								—	—
391h	IOCAP	—	—	IOCAP5	IOCAP4	IOCAP3	IOCAP2	IOCAP1	IOCAP0	--00 0000	--00 0000
392h	IOCAN	—	—	IOCAN5	IOCAN4	IOCAN3	IOCAN2	IOCAN1	IOCAN0	--00 0000	--00 0000
393h	IOCAF	—	—	IOCAF5	IOCAF4	IOCAF3	IOCAF2	IOCAF1	IOCAF0	--00 0000	--00 0000
394h	IOCBP ⁽¹⁾	IOCBP7	IOCBP6	IOCBP5	IOCBP4	—	—	—	—	0000 ----	--00 ----
395h	IOCBN ⁽¹⁾	IOCBN7	IOCBN6	IOCBN5	IOCBN4	—	—	—	—	0000 ----	--00 ----
396h	IOCBF ⁽¹⁾	IOCBF7	IOCBF6	IOCBF5	IOCBF4	—	—	—	—	0000 ----	--00 ----
397h	IOCCP	IOCCP7 ⁽¹⁾	IOCCP6 ⁽¹⁾	IOCCP5	IOCCP4	IOCCP3	IOCCP2	IOCCP1	IOCCP0	0000 0000	0000 0000
398h	IOCCN	IOCCN7 ⁽¹⁾	IOCCN6 ⁽¹⁾	IOCCN5	IOCCN4	IOCCN3	IOCCN2	IOCCN1	IOCCN0	0000 0000	0000 0000
399h	IOCCF	IOCCF7 ⁽¹⁾	IOCCF6 ⁽¹⁾	IOCCF5	IOCCF4	IOCCF3	IOCCF2	IOCCF1	IOCCF0	0000 0000	0000 0000
39Ah to 39Fh	—	Unimplemented								—	—
Bank 8											
40Ch to 41Fh	—	Unimplemented								—	—
Bank 9											
48Ch to 49Fh	—	Unimplemented								—	—

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved. Shaded locations are unimplemented, read as '0'.

- Note**
- 1: PIC16(L)F1578/9 only.
 - 2: PIC16F1574/5/8/9 only.
 - 3: Unimplemented, read as '1'.

TABLE 3-15: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 10											
50Ch to 51Fh	—	Unimplemented								—	—
Bank 11											
58Ch to 59Fh	—	Unimplemented								—	—
Bank 12											
60Ch to 61Fh	—	Unimplemented								—	—
Bank 13											
68Ch to 690h	—	Unimplemented								—	—
691h	CWG1DBR	—	—	CWG1DBR<5:0>						--00 0000	--00 0000
692h	CWG1DBF	—	—	CWG1DBF<5:0>						--xx xxxx	--xx xxxx
693h	CWG1CON0	G1EN	—	—	G1POLB	G1POLA	—	—	G1CS0	0--0 0--0	0--0 0--0
694h	CWG1CON1	G1ASDLB<1:0>		G1ASDLA<1:0>		—	G1IS<2:0>			0000 -000	0000 -000
695h	CWG1CON2	G1ASE	G1ARSEN	—	—	G1ASDSC2	G1ASDSC1	G1ASDSPPS	—	00-- 000-	00-- 000-
696h to 69Fh	—	Unimplemented								—	—
Banks 14-26											
x0Ch/ x8Ch — x1Fh/ x9Fh	—	Unimplemented								—	—

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved. Shaded locations are unimplemented, read as '0'.

- Note** 1: PIC16(L)F1578/9 only.
 2: PIC16F1574/5/8/9 only.
 3: Unimplemented, read as '1'.

5.2.2.3 Internal Oscillator Frequency Adjustment

The 500 kHz internal oscillator is factory calibrated. This internal oscillator can be adjusted in software by writing to the OSCTUNE register (Register 5-3). Since the HFINTOSC and MFINTOSC clock sources are derived from the 500 kHz internal oscillator a change in the OSCTUNE register value will apply to both.

The default value of the OSCTUNE register is '0'. The value is a 6-bit two's complement number. A value of 1Fh will provide an adjustment to the maximum frequency. A value of 20h will provide an adjustment to the minimum frequency.

When the OSCTUNE register is modified, the oscillator frequency will begin shifting to the new frequency. Code execution continues during this shift. There is no indication that the shift has occurred.

OSCTUNE does not affect the LFINTOSC frequency. Operation of features that depend on the LFINTOSC clock source frequency, such as the Power-up Timer (PWRT), Watchdog Timer (WDT), and peripherals, are *not* affected by the change in frequency.

5.2.2.4 LFINTOSC

The Low-Frequency Internal Oscillator (LFINTOSC) is an uncalibrated 31 kHz internal clock source.

The output of the LFINTOSC connects to a multiplexer (see Figure 5-1). Select 31 kHz, via software, using the IRCF<3:0> bits of the OSCCON register. See **Section 5.2.2.8 "Internal Oscillator Clock Switch Timing"** for more information. The LFINTOSC is also the frequency for the Power-up Timer (PWRT) and Watchdog Timer (WDT).

The LFINTOSC is enabled by selecting 31 kHz (IRCF<3:0> bits of the OSCCON register = 000) as the system clock source (SCS bits of the OSCCON register = 1x), or when any of the following are enabled:

- Configure the IRCF<3:0> bits of the OSCCON register for the desired LF frequency, and
- FOSC<1:0> = 00, or
- Set the System Clock Source (SCS) bits of the OSCCON register to '1x'

Peripherals that use the LFINTOSC are:

- Power-up Timer (PWRT)
- Watchdog Timer (WDT)

The Low-Frequency Internal Oscillator Ready bit (LFIOFR) of the OSCSTAT register indicates when the LFINTOSC is running.

5.2.2.5 FRC

The FRC clock is an uncalibrated, nominal 600 kHz peripheral clock source.

The FRC is automatically turned on by the peripherals requesting the FRC clock.

The FRC clock will continue to run during Sleep.

5.2.2.6 Internal Oscillator Frequency Selection

The system clock speed can be selected via software using the Internal Oscillator Frequency Select bits, IRCF<3:0> of the OSCCON register.

The postscaler outputs of the 16 MHz HFINTOSC, **500 kHz MFINTOSC**, and **31 kHz LFINTOSC** output connect to a multiplexer (see Figure 5-1). The Internal Oscillator Frequency Select bits IRCF<3:0> of the OSCCON register select the frequency output of the internal oscillators. One of the following frequencies can be selected via software:

- 32 MHz (requires 4x PLL)
- 16 MHz
- 8 MHz
- 4 MHz
- 2 MHz
- 1 MHz
- 500 kHz (default after Reset)
- 250 kHz
- 125 kHz
- 62.5 kHz
- 31.25 kHz
- 31 kHz (LFINTOSC)

Note: Following any Reset, the IRCF<3:0> bits of the OSCCON register are set to '0111' and the frequency selection is set to 500 kHz. The user can modify the IRCF bits to select a different frequency.

The IRCF<3:0> bits of the OSCCON register allow duplicate selections for some frequencies. These duplicate choices can offer system design trade-offs. Lower power consumption can be obtained when changing oscillator sources for a given frequency. Faster transition times can be obtained between frequency changes that use the same oscillator source.

PIC16(L)F1574/5/8/9

6.12 Determining the Cause of a Reset

Upon any Reset, multiple bits in the STATUS and PCON registers are updated to indicate the cause of the Reset. Table 6-3 and Table 6-4 show the Reset conditions of these registers.

TABLE 6-3: RESET STATUS BITS AND THEIR SIGNIFICANCE

STKOVF	STKUNF	RWDT	RMCLR	RI	POR	BOR	TO	PD	Condition
0	0	1	1	1	0	x	1	1	Power-on Reset
0	0	1	1	1	0	x	0	x	Illegal, $\overline{TO}$ is set on $\overline{POR}$
0	0	1	1	1	0	x	x	0	Illegal, $\overline{PD}$ is set on $\overline{POR}$
0	0	u	1	1	u	0	1	1	Brown-out Reset
u	u	0	u	u	u	u	0	u	WDT Reset
u	u	u	u	u	u	u	0	0	WDT Wake-up from Sleep
u	u	u	u	u	u	u	1	0	Interrupt Wake-up from Sleep
u	u	u	0	u	u	u	u	u	$\overline{MCLR}$ Reset during normal operation
u	u	u	0	u	u	u	1	0	$\overline{MCLR}$ Reset during Sleep
u	u	u	u	0	u	u	u	u	RESET Instruction Executed
1	u	u	u	u	u	u	u	u	Stack Overflow Reset (STVREN = 1)
u	1	u	u	u	u	u	u	u	Stack Underflow Reset (STVREN = 1)

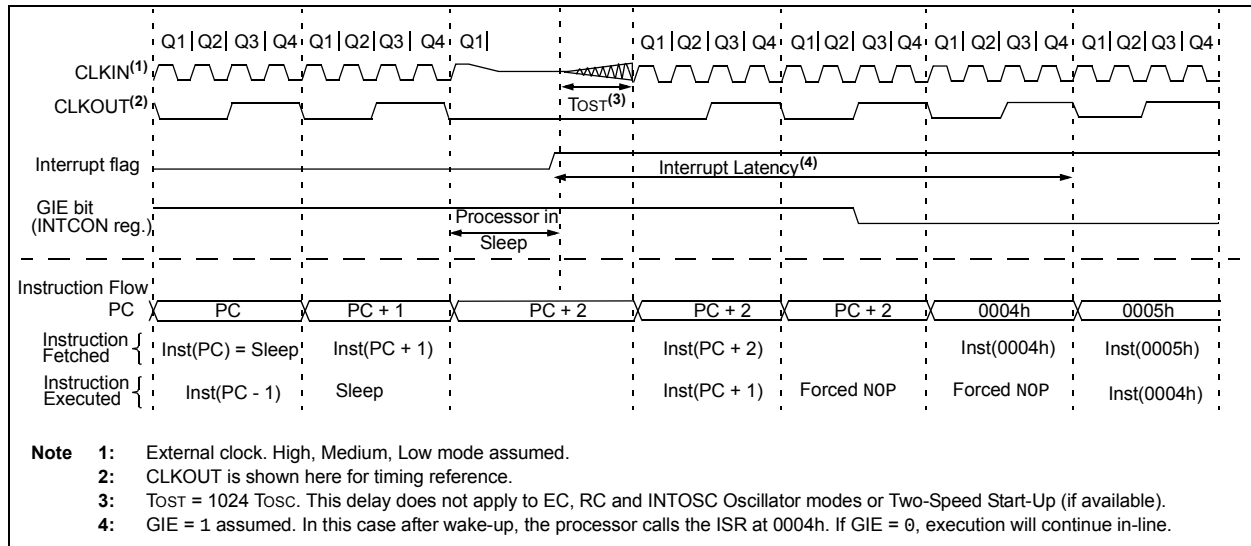
TABLE 6-4: RESET CONDITION FOR SPECIAL REGISTERS

Condition	Program Counter	STATUS Register	PCON Register
Power-on Reset	0000h	---1 1000	00-- 110x
$\overline{MCLR}$ Reset during normal operation	0000h	---u uuuu	uu-- 0uuu
$\overline{MCLR}$ Reset during Sleep	0000h	---1 0uuu	uu-- 0uuu
WDT Reset	0000h	---0 uuuu	uu-- uuuu
WDT Wake-up from Sleep	PC + 1	---0 0uuu	uu-- uuuu
Brown-out Reset	0000h	---1 1uuu	00-- 11u0
Interrupt Wake-up from Sleep	PC + 1 ⁽¹⁾	---1 0uuu	uu-- uuuu
RESET Instruction Executed	0000h	---u uuuu	uu-- u0uu
Stack Overflow Reset (STVREN = 1)	0000h	---u uuuu	1u-- uuuu
Stack Underflow Reset (STVREN = 1)	0000h	---u uuuu	u1-- uuuu

Legend: u = unchanged, x = unknown, - = unimplemented bit, reads as '0'.

Note 1: When the wake-up is due to an interrupt and the Global Interrupt Enable bit (GIE) is set, the return address is pushed on the stack and PC is loaded with the interrupt vector (0004h) after execution of PC + 1.

FIGURE 8-1: WAKE-UP FROM SLEEP THROUGH INTERRUPT



8.2 Low-Power Sleep Mode

This device contains an internal Low Dropout (LDO) voltage regulator, which allows the device I/O pins to operate at voltages up to 5.5V while the internal device logic operates at a lower voltage. The LDO and its associated reference circuitry must remain active when the device is in Sleep mode.

Low-Power Sleep mode allows the user to optimize the operating current in Sleep. Low-Power Sleep mode can be selected by setting the VREGPM bit of the VREGCON register, putting the LDO and reference circuitry in a low-power state whenever the device is in Sleep.

8.2.1 SLEEP CURRENT VS. WAKE-UP TIME

In the Default Operating mode, the LDO and reference circuitry remain in the normal configuration while in Sleep. The device is able to exit Sleep mode quickly since all circuits remain active. In Low-Power Sleep mode, when waking up from Sleep, an extra delay time is required for these circuits to return to the normal configuration and stabilize.

The Low-Power Sleep mode is beneficial for applications that stay in Sleep mode for long periods of time. The Normal mode is beneficial for applications that need to wake from Sleep quickly and frequently.

8.2.2 PERIPHERAL USAGE IN SLEEP

Some peripherals that can operate in Sleep mode will not operate properly with the Low-Power Sleep mode selected. The LDO will remain in the Normal Power mode when those peripherals are enabled. The Low-Power Sleep mode is intended for use with these peripherals:

- Brown-Out Reset (BOR)
- Watchdog Timer (WDT)
- External interrupt pin/Interrupt-on-change pins
- Timer1 (with external clock source)

The Complementary Waveform Generator (CWG) module can utilize the HFINTOSC oscillator as either a clock source or as an input source. Under certain conditions, when the HFINTOSC is selected for use with the CWG module, the HFINTOSC will remain active during Sleep. This will have a direct effect on the Sleep mode current.

Please refer to section 24.10 “Operation During Sleep” for more information.

Note: The PIC16LF1574/5/8/9 devices do not have a configurable Low-Power Sleep mode. PIC16LF1574/5/8/9 are unregulated devices and are always in the lowest power state when in Sleep, with no wake-up time penalty. These devices have a lower maximum V_{DD} and I/O voltage than the PIC16F1574/5/8/9 devices. See Section 27.0 “Electrical Specifications” for more information.

REGISTER 11-12: ANSELB: PORTB ANALOG SELECT REGISTER

U-0	U-0	R/W-1/1	R/W-1/1	U-0	U-0	U-0	U-0
—	—	ANSB5	ANSB4	—	—	—	—
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-6 **Unimplemented:** Read as '0'

bit 5-4 **ANSB<5:4>:** Analog Select between Analog or Digital Function on pins RB<5:4>, respectively
 0 = Digital I/O. Pin is assigned to port or digital special function.
 1 = Analog input. Pin is assigned as analog input⁽¹⁾. Digital input buffer disabled.

bit 3-0 **Unimplemented:** Read as '0'

Note 1: When setting a pin to an analog input, the corresponding TRIS bit must be set to Input mode in order to allow external control of the voltage on the pin.

REGISTER 11-13: WPUB: WEAK PULL-UP PORTB REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	U-0	U-0	U-0	U-0
WPUB7	WPUB6	WPUB5	WPUB4	—	—	—	—
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-4 **WPUB<7:4>:** Weak Pull-up Register bits
 1 = Pull-up enabled
 0 = Pull-up disabled

bit 3-0 **Unimplemented:** Read as '0'

Note 1: Global $\overline{\text{WPUEN}}$ bit of the OPTION_REG register must be cleared for individual pull-ups to be enabled.

2: The weak pull-up device is automatically disabled if the pin is configured as an output.

15.0 TEMPERATURE INDICATOR MODULE

This family of devices is equipped with a temperature circuit designed to measure the operating temperature of the silicon die. The circuit's range of operating temperature falls between -40°C and $+85^{\circ}\text{C}$. The output is a voltage that is proportional to the device temperature. The output of the temperature indicator is internally connected to the device ADC.

The circuit may be used as a temperature threshold detector or a more accurate temperature indicator, depending on the level of calibration performed. A one-point calibration allows the circuit to indicate a temperature closely surrounding that point. A two-point calibration allows the circuit to sense the entire range of temperature more accurately. Reference Application Note AN1333, "Use and Calibration of the Internal Temperature Indicator" (DS01333) for more details regarding the calibration process.

15.1 Circuit Operation

Figure 15-1 shows a simplified block diagram of the temperature circuit. The proportional voltage output is achieved by measuring the forward voltage drop across multiple silicon junctions.

Equation 15-1 describes the output characteristics of the temperature indicator.

EQUATION 15-1: V_{OUT} RANGES

High Range: $V_{OUT} = V_{DD} - 4V_T$

Low Range: $V_{OUT} = V_{DD} - 2V_T$

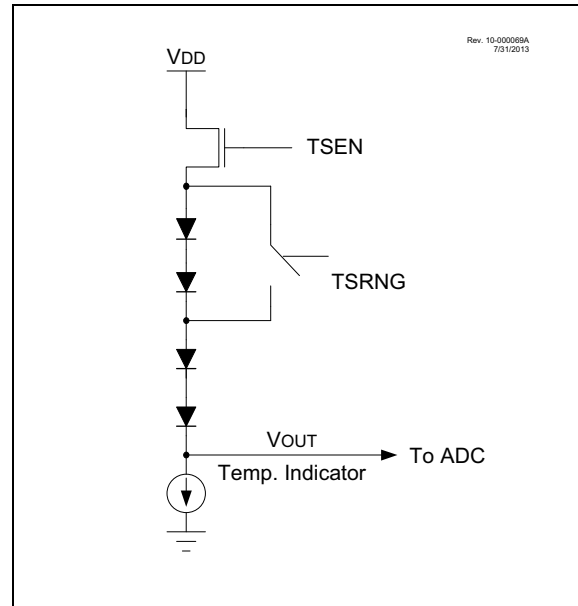
The temperature sense circuit is integrated with the Fixed Voltage Reference (FVR) module. See **Section 14.0 "Fixed Voltage Reference (FVR)"** for more information.

The circuit is enabled by setting the TSEN bit of the FVRCON register. When disabled, the circuit draws no current.

The circuit operates in either high or low range. The high range, selected by setting the TSRNG bit of the FVRCON register, provides a wider output voltage. This provides more resolution over the temperature range, but may be less consistent from part to part. This range requires a higher bias voltage to operate and thus, a higher V_{DD} is needed.

The low range is selected by clearing the TSRNG bit of the FVRCON register. The low range generates a lower voltage drop and thus, a lower bias voltage is needed to operate the circuit. The low range is provided for low voltage operation.

FIGURE 15-1: TEMPERATURE CIRCUIT DIAGRAM



15.2 Minimum Operating V_{DD}

When the temperature circuit is operated in low range, the device may be operated at any operating voltage that is within specifications.

When the temperature circuit is operated in high range, the device operating voltage, V_{DD} , must be high enough to ensure that the temperature circuit is correctly biased.

Table 15-1 shows the recommended minimum V_{DD} vs. range setting.

TABLE 15-1: RECOMMENDED V_{DD} VS. RANGE

Min. V_{DD} , TSRNG = 1	Min. V_{DD} , TSRNG = 0
3.6V	1.8V

15.3 Temperature Output

The output of the circuit is measured using the internal Analog-to-Digital Converter. A channel is reserved for the temperature circuit output. Refer to **Section 16.0 "Analog-to-Digital Converter (ADC) Module"** for detailed information.

15.4 ADC Acquisition Time

To ensure accurate temperature measurements, the user must wait at least $200\ \mu\text{s}$ after the ADC input multiplexer is connected to the temperature indicator output before the conversion is performed. In addition, the user must wait $200\ \mu\text{s}$ between sequential conversions of the temperature indicator output.

PIC16(L)F1574/5/8/9

17.6 Register Definitions: DAC Control

REGISTER 17-1: DACCON0: VOLTAGE REFERENCE CONTROL REGISTER 0

R/W-0/0	U-0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	U-0	U-0
DACEN	—	DACOE	—	DACPSS<1:0>	—	—	—
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set '0' = Bit is cleared

bit 7 **DACEN:** DAC Enable bit
1 = DAC is enabled
0 = DAC is disabled

bit 6 **Unimplemented:** Read as '0'

bit 5 **DACOE:** DAC Voltage Output Enable bit
1 = DAC voltage level is output on the DACOUT1 pin
0 = DAC voltage level is disconnected from the DACOUT1 pin

bit 4 **Unimplemented:** Read as '0'

bit 3-2 **DACPSS<1:0>:** DAC Positive Source Select bits
11 = Reserved
10 = FVR_buffer2
01 = VREF+ pin
00 = VDD

bit 1-0 **Unimplemented:** Read as '0'

REGISTER 17-2: DACCON1: VOLTAGE REFERENCE CONTROL REGISTER 1

U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—					DACR<4:0>
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set '0' = Bit is cleared

bit 7-5 **Unimplemented:** Read as '0'

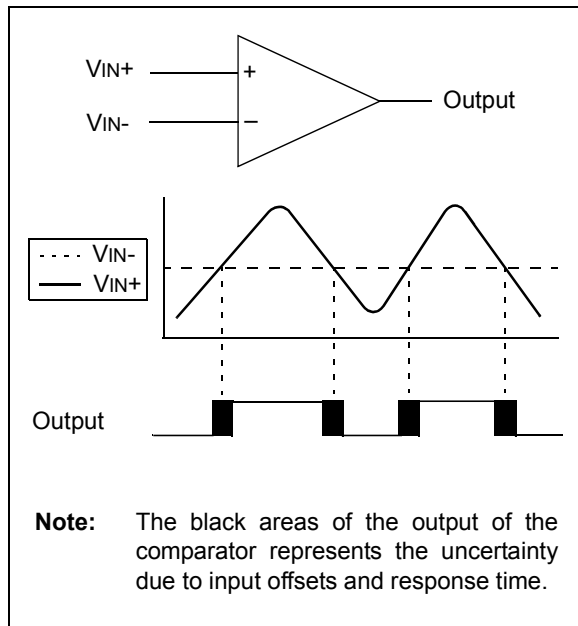
bit 4-0 **DACR<4:0>:** DAC Voltage Output Select bits

TABLE 17-1: SUMMARY OF REGISTERS ASSOCIATED WITH THE DAC MODULE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
DACCON0	DACEN	—	DACOE	—	DACPSS<1:0>	—	—	—	168
DACCON1	—	—	—					DACR<4:0>	168

Legend: — = Unimplemented location, read as '0'. Shaded cells are not used with the DAC module.

FIGURE 18-2: SINGLE COMPARATOR



18.2 Comparator Control

The comparator has two control registers: CMxCON0 and CMxCON1.

The CMxCON0 register (see Register 18-1) contains Control and Status bits for the following:

- Enable
- Output selection
- Output polarity
- Speed/Power selection
- Hysteresis enable
- Output synchronization

The CMxCON1 register (see Register 18-2) contains Control bits for the following:

- Interrupt enable
- Interrupt edge polarity
- Positive input channel selection
- Negative input channel selection

18.2.1 COMPARATOR ENABLE

Setting the CxON bit of the CMxCON0 register enables the comparator for operation. Clearing the CxON bit disables the comparator resulting in minimum current consumption.

18.2.2 COMPARATOR POSITIVE INPUT SELECTION

Configuring the CxPCH<1:0> bits of the CMxCON1 register directs an internal voltage reference or an analog pin to the non-inverting input of the comparator:

- CxIN+ analog pin
- DAC1_output
- FVR_buffer2
- Vss

See **Section 14.0 “Fixed Voltage Reference (FVR)”** for more information on the Fixed Voltage Reference module.

See **Section 17.0 “5-Bit Digital-to-Analog Converter (DAC) Module”** for more information on the DAC input signal.

Any time the comparator is disabled (CxON = 0), all comparator inputs are disabled.

18.2.3 COMPARATOR NEGATIVE INPUT SELECTION

The CxNCH<2:0> bits of the CMxCON0 register direct one of the input sources to the comparator inverting input.

Note: To use CxIN+ and CxINx- pins as analog input, the appropriate bits must be set in the ANSEL register and the corresponding TRIS bits must also be set to disable the output drivers.

18.2.4 COMPARATOR OUTPUT SELECTION

The output of the comparator can be monitored by reading either the CxOUT bit of the CMxCON0 register or the MCxOUT bit of the CMOUT register. In order to make the output available for an external connection, the following conditions must be true:

- Corresponding TRIS bit must be cleared
- CxON bit of the CMxCON0 register must be set

The synchronous comparator output signal (CxOUT_sync) is available to the following peripheral(s):

- Analog-to-Digital Converter (ADC)
- Timer1

The asynchronous comparator output signal (CxOUT_async) is available to the following peripheral(s):

- Complementary Waveform Generator (CWG)

Note: The internal output of the comparator is latched with each instruction cycle. Unless otherwise specified, external outputs are not latched.

20.0 TIMER1 MODULE WITH GATE CONTROL

The Timer1 module is a 16-bit timer/counter with the following features:

- 16-bit timer/counter register pair (TMR1H:TMR1L)
- Programmable internal or external clock source
- 2-bit prescaler
- Optionally synchronized comparator out
- Multiple Timer1 gate (count enable) sources
- Interrupt on overflow

- Wake-up on overflow (external clock, Asynchronous mode only)
- ADC Auto-Conversion Trigger(s)
- Selectable Gate Source Polarity
- Gate Toggle mode
- Gate Single-Pulse mode
- Gate Value Status
- Gate Event Interrupt

Figure 20-1 is a block diagram of the Timer1 module.

FIGURE 20-1: TIMER1 BLOCK DIAGRAM

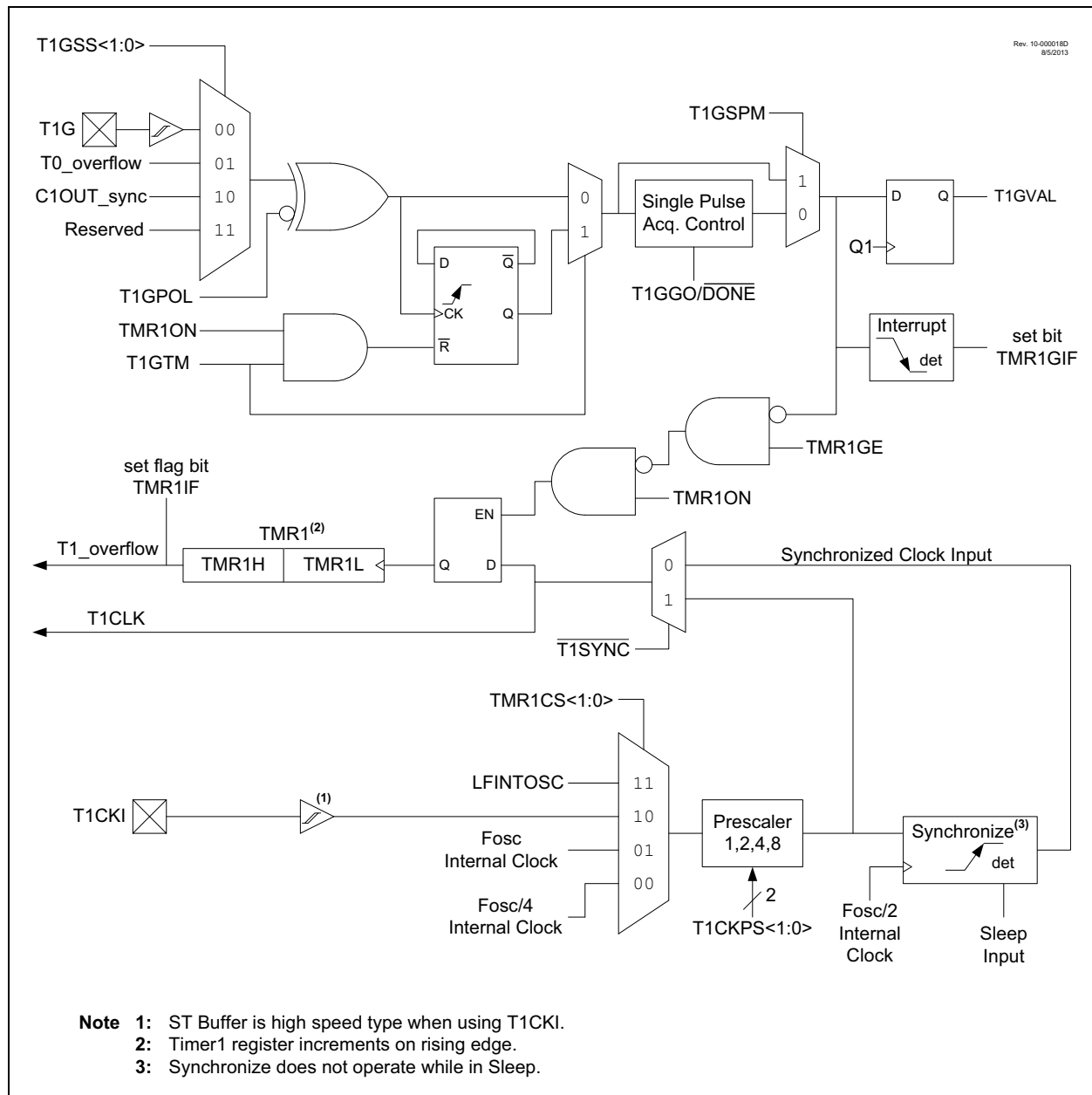
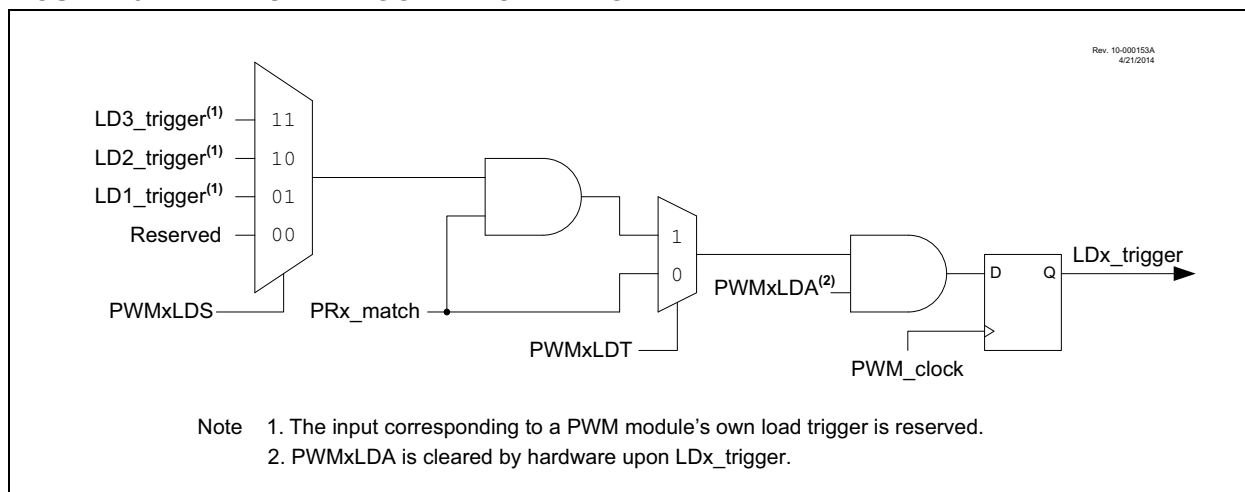


FIGURE 23-2: LOAD TRIGGER BLOCK DIAGRAM



23.1 Fundamental Operation

The PWM module produces a 16-bit resolution pulse width modulated output.

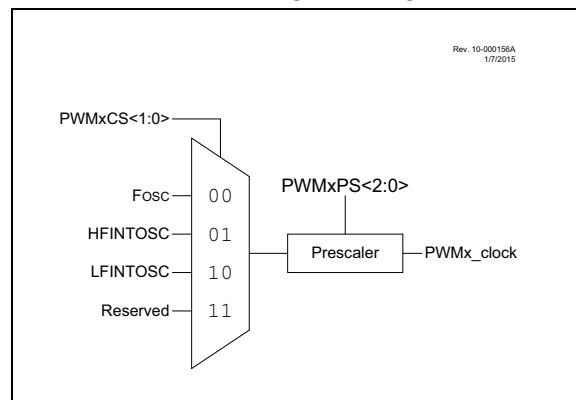
Each PWM module has an independent timer driven by a selection of clock sources determined by the PWMxCLKCON register (Register 23-4). The timer value is compared to event count registers to generate the various events of a the PWM waveform, such as the period and duty cycle. For a block diagram describing the clock sources refer to Figure 23-3.

Each PWM module can be enabled individually using the EN bit of the PWMxCON register, or several PWM modules can be enabled simultaneously using the mirror bits of the PWMEN register.

The current state of the PWM output can be read using the OUT bit of the PWMxCON register. In some modes this bit can be set and cleared by software giving additional software control over the PWM waveform. This bit is synchronized to Fosc/4 and therefore does not change in real time with respect to the PWM_clock.

Note: If PWM_clock > Fosc/4, the OUT bit may not accurately represent the output state of the PWM.

FIGURE 23-3: PWM CLOCK SOURCE BLOCK DIAGRAM



23.1.1 PWMx PIN CONFIGURATION

All PWM outputs are multiplexed with the PORT data latch, so the pins must also be configured as outputs by clearing the associated PORT TRIS bits.

The slew rate feature may be configured to optimize the rate to be used in conjunction with the PWM outputs. High-speed output switching is attained by clearing the associated PORT SLRCON bits.

The PWM outputs can be configured to be open-drain outputs by setting the associated PORT ODCON bits.

23.1.2 PWMx Output Polarity

The output polarity is inverted by setting the POL bit of the PWMxCON register. The polarity control affects the PWM output even when the module is not enabled.

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REGISTER 24-2: CWGxCON1: CWG CONTROL REGISTER 1

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	U-0	R/W-0/0	R/W-0/0	R/W-0/0
GxASDLB<1:0>		GxASDLA<1:0>		—	GxIS<2:0>		
bit 7				bit 0			

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

- bit 7-6 **GxASDLB<1:0>**: CWGx Shutdown State for CWGxB
 When an auto shutdown event is present (GxASE = 1):
 11 = CWGxB pin is driven to '1', regardless of the setting of the GxPOLB bit.
 10 = CWGxB pin is driven to '0', regardless of the setting of the GxPOLB bit.
 01 = CWGxB pin is tri-stated
 00 = CWGxB pin is driven to its inactive state after the selected dead-band interval. GxPOLB still will control the polarity of the output.
- bit 5-4 **GxASDLA<1:0>**: CWGx Shutdown State for CWGxA
 When an auto shutdown event is present (GxASE = 1):
 11 = CWGxA pin is driven to '1', regardless of the setting of the GxPOLA bit.
 10 = CWGxA pin is driven to '0', regardless of the setting of the GxPOLA bit.
 01 = CWGxA pin is tri-stated
 00 = CWGxA pin is driven to its inactive state after the selected dead-band interval. GxPOLA still will control the polarity of the output.
- bit 3 **Unimplemented**: Read as '0'
- bit 2-0 **GxIS<2:0>**: CWGx Input Source Select bits
 111 = Reserved
 110 = CWG input pin
 101 = PWM4 – PWM4_out
 100 = PWM3 – PWM3_out
 011 = PWM2 – PWM2_out
 010 = PWM1 – PWM1_out
 001 = Comparator C2 – C2OUT_sync
 000 = Comparator C1 – C1OUT_sync

DECFSZ	Decrement f, Skip if 0
Syntax:	[<i>label</i>] DECFSZ f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) - 1 \rightarrow (\text{destination})$; skip if result = 0
Status Affected:	None
Description:	The contents of register 'f' are decremented. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'. If the result is '1', the next instruction is executed. If the result is '0', then a NOP is executed instead, making it a 2-cycle instruction.

INCFSZ	Increment f, Skip if 0
Syntax:	[<i>label</i>] INCFSZ f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) + 1 \rightarrow (\text{destination})$, skip if result = 0
Status Affected:	None
Description:	The contents of register 'f' are incremented. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'. If the result is '1', the next instruction is executed. If the result is '0', a NOP is executed instead, making it a 2-cycle instruction.

GOTO	Unconditional Branch
Syntax:	[<i>label</i>] GOTO k
Operands:	$0 \leq k \leq 2047$
Operation:	$k \rightarrow \text{PC}<10:0>$ $\text{PCLATH}<6:3> \rightarrow \text{PC}<14:11>$
Status Affected:	None
Description:	GOTO is an unconditional branch. The 11-bit immediate value is loaded into PC bits <10:0>. The upper bits of PC are loaded from PCLATH<4:3>. GOTO is a 2-cycle instruction.

IORLW	Inclusive OR literal with W
Syntax:	[<i>label</i>] IORLW k
Operands:	$0 \leq k \leq 255$
Operation:	$(W) .\text{OR. } k \rightarrow (W)$
Status Affected:	Z
Description:	The contents of the W register are OR'ed with the 8-bit literal 'k'. The result is placed in the W register.

INCF	Increment f
Syntax:	[<i>label</i>] INCF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) + 1 \rightarrow (\text{destination})$
Status Affected:	Z
Description:	The contents of register 'f' are incremented. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'.

IORWF	Inclusive OR W with f
Syntax:	[<i>label</i>] IORWF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(W) .\text{OR. } (f) \rightarrow (\text{destination})$
Status Affected:	Z
Description:	Inclusive OR the W register with register 'f'. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'.

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LSLF Logical Left Shift

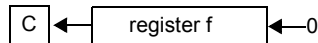
Syntax: `[label] LSLF f{,d}`

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $(f<7>) \rightarrow C$
 $(f<6:0>) \rightarrow \text{dest}<7:1>$
 $0 \rightarrow \text{dest}<0>$

Status Affected: C, Z

Description: The contents of register 'f' are shifted one bit to the left through the Carry flag. A '0' is shifted into the LSb. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f'.



LSRF Logical Right Shift

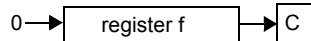
Syntax: `[label] LSRF f{,d}`

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $0 \rightarrow \text{dest}<7>$
 $(f<7:1>) \rightarrow \text{dest}<6:0>$,
 $(f<0>) \rightarrow C$,

Status Affected: C, Z

Description: The contents of register 'f' are shifted one bit to the right through the Carry flag. A '0' is shifted into the MSb. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f'.



MOVF Move f

Syntax: `[label] MOVF f,d`

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $(f) \rightarrow (\text{dest})$

Status Affected: Z

Description: The contents of register f is moved to a destination dependent upon the status of d. If d = 0, destination is W register. If d = 1, the destination is file register f itself. d = 1 is useful to test a file register since status flag Z is affected.

Words: 1

Cycles: 1

Example: `MOVF FSR, 0`

After Instruction
W = value in FSR register
Z = 1

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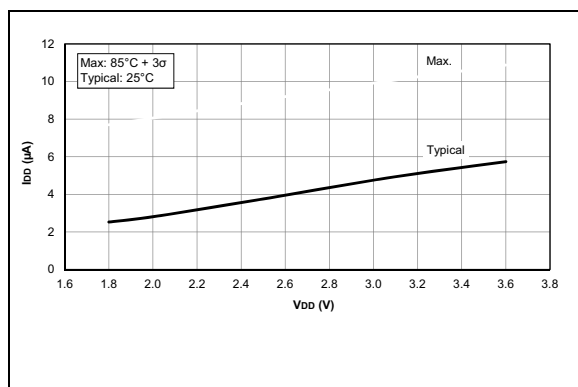


FIGURE 28-1: I_{DD} , EC Oscillator, Low-Power Mode, $F_{osc} = 32$ kHz, PIC16LF1574/5/8/9 Only.

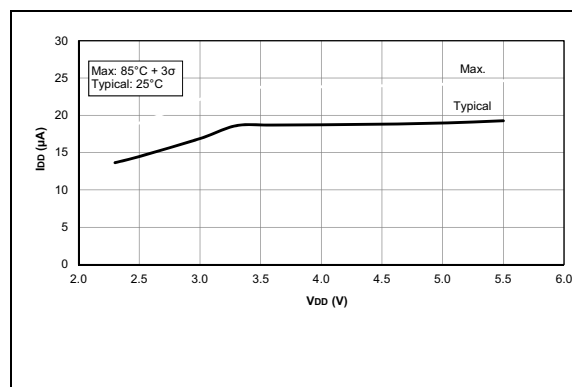


FIGURE 28-2: I_{DD} , EC Oscillator, Low-Power Mode, $F_{osc} = 32$ kHz, PIC16F1574/5/8/9 Only.

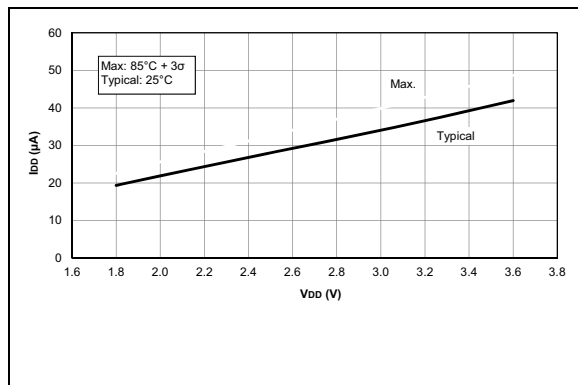


FIGURE 28-3: I_{DD} , EC Oscillator, Low-Power Mode, $F_{osc} = 500$ kHz, PIC16LF1574/5/8/9 Only.

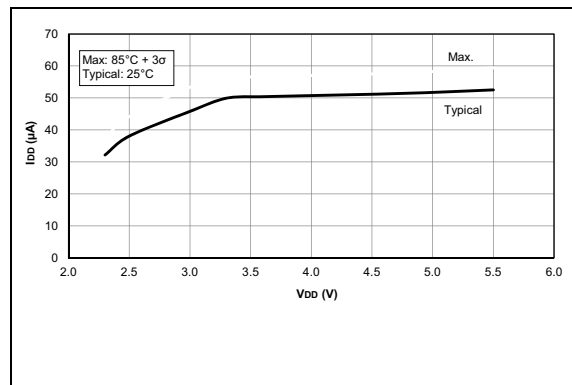


FIGURE 28-4: I_{DD} , EC Oscillator, Low-Power Mode, $F_{osc} = 500$ kHz, PIC16F1574/5/8/9 Only.

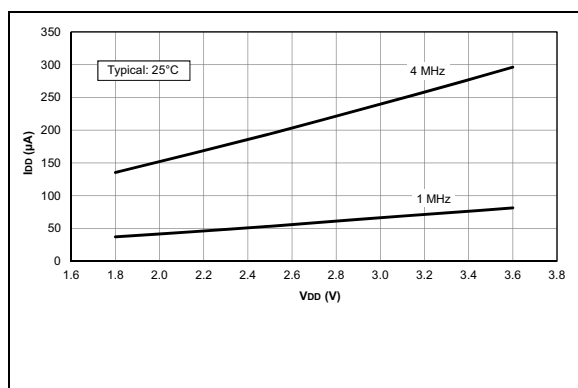


FIGURE 28-5: I_{DD} Typical, EC Oscillator, Medium Power Mode, PIC16LF1574/5/8/9 Only.

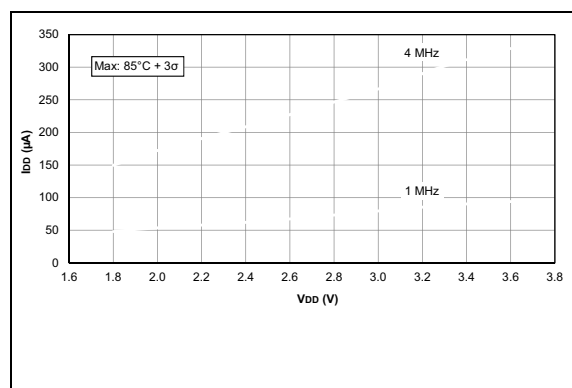


FIGURE 28-6: I_{DD} Maximum, EC Oscillator, Medium Power Mode, PIC16LF1574/5/8/9 Only.

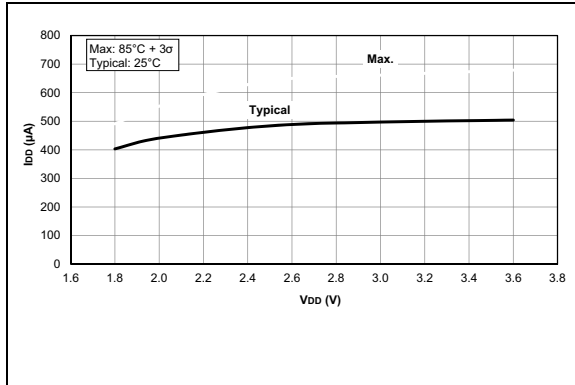


FIGURE 28-31: *I_{pd}*, Comparator, Low-Power Mode ($CxSP = 0$), PIC16LF1574/5/8/9 Only.

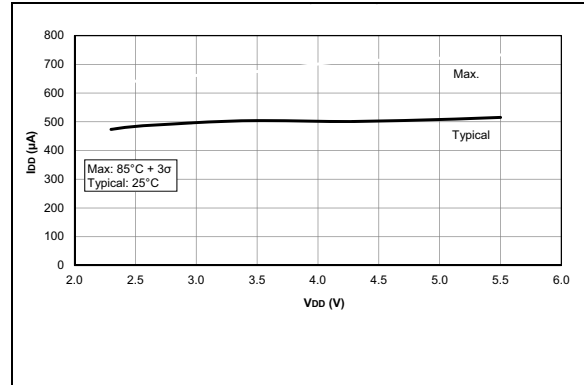


FIGURE 28-32: *I_{pd}*, Comparator, Low-Power Mode ($CxSP = 0$), PIC16F1574/5/8/9 Only.

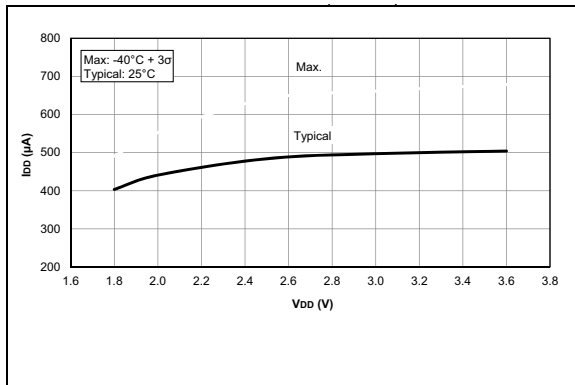


FIGURE 28-33: *I_{pd}*, Comparator, Normal Power Mode ($CxSP = 1$), PIC16LF1574/5/8/9 Only.

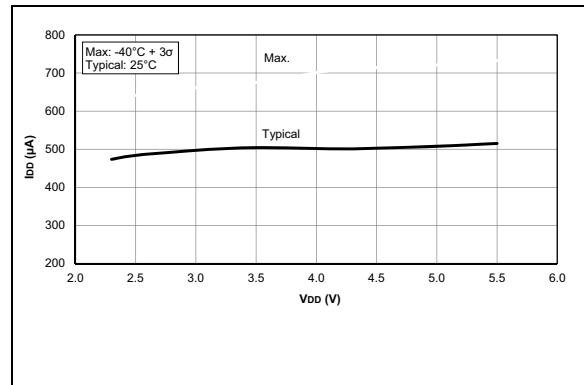


FIGURE 28-34: *I_{pd}*, Comparator, Normal Power Mode ($CxSP = 1$), PIC16F1574/5/8/9 Only.

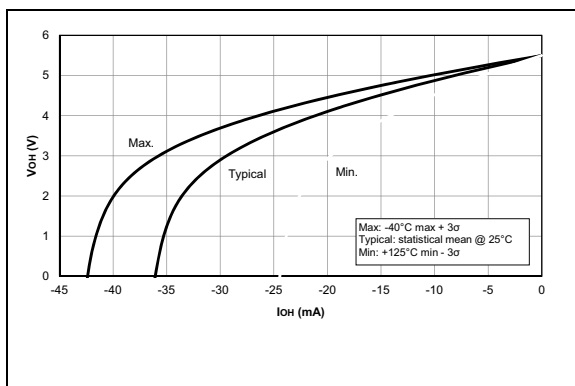


FIGURE 28-35: *VOH* vs. *IOH* Over Temperature, $V_{DD} = 5.5V$, PIC16F1574/5/8/9 Only.

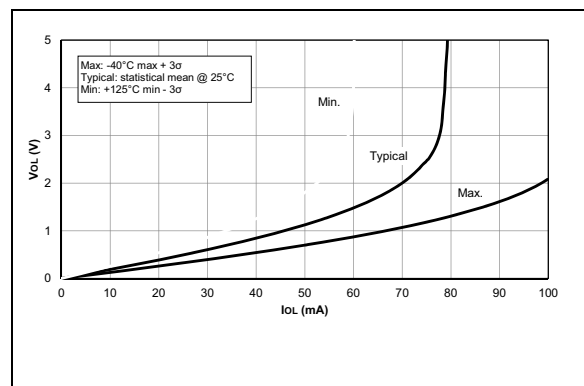
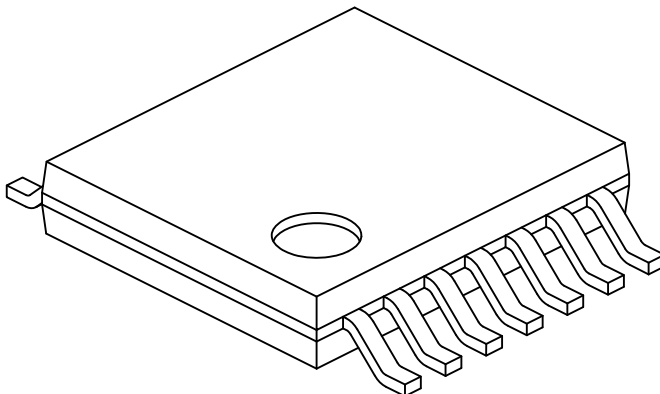


FIGURE 28-36: *VOL* vs. *IOL* Over Temperature, $V_{DD} = 5.5V$, PIC16F1574/5/8/9 Only.

PIC16(L)F1574/5/8/9

14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packageing>



		Units	MILLIMETERS		
Dimension Limits			MIN	NOM	MAX
Number of Pins	N		14		
Pitch	e		0.65 BSC		
Overall Height	A		-	-	1.20
Molded Package Thickness	A2		0.80	1.00	1.05
Standoff	A1		0.05	-	0.15
Overall Width	E		6.40 BSC		
Molded Package Width	E1		4.30	4.40	4.50
Molded Package Length	D		4.90	5.00	5.10
Foot Length	L		0.45	0.60	0.75
Footprint	(L1)		1.00 REF		
Foot Angle	ϕ		0°	-	8°
Lead Thickness	c		0.09	-	0.20
Lead Width	b		0.19	-	0.30

Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing No. C04-087C Sheet 2 of 2