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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	LINbus, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	12
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 8x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	14-TSSOP (0.173", 4.40mm Width)
Supplier Device Package	14-TSSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1575-e-st

PIC16(L)F1574/5/8/9

TABLE 1-3: PIC16(L)F1578/9 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RC1/AN5/C1IN1-/C2IN1-	RC1	TTL/ST	CMOS/OD	General purpose input with IOC and WPU.
	AN5	AN	—	ADC Channel input.
	C1IN1-	AN	—	Comparator negative input.
	C2IN1-	AN	—	Comparator negative input.
RC2/AN6/C1IN2-/C2IN2-	RC2	TTL/ST	CMOS/OD	General purpose input with IOC and WPU.
	AN6	AN	—	ADC Channel input.
	C1IN2-	AN	—	Comparator negative input.
	C2IN2-	AN	—	Comparator negative input.
RC3/AN7/C1IN3-/C2IN3-	RC3	TTL/ST	CMOS/OD	General purpose input with IOC and WPU.
	AN7	AN	—	ADC Channel input.
	C1IN3-	AN	—	Comparator negative input.
	C2IN3-	AN	—	Comparator negative input.
RC4/ADCACT ⁽¹⁾	RC4	TTL/ST	CMOS/OD	General purpose input with IOC and WPU.
	ADCACT	TTL/ST	—	ADC Auto-conversion Trigger input.
RC5	RC5	TTL/ST	CMOS/OD	General purpose input with IOC and WPU.
OUT ⁽²⁾	C1OUT	—	CMOS	Comparator output.
	C2OUT	—	CMOS	Comparator output.
	PWM1OUT	—	CMOS	PWM1 output.
	PWM2OUT	—	CMOS	PWM2 output.
	PWM3OUT	—	CMOS	PWM3 output.
	PWM4OUT	—	CMOS	PWM4 output.
	CWG1A	—	CMOS	Complementary Output Generator Output A.
	CWG1B	—	CMOS	Complementary Output Generator Output B.
	TX/CK	—	CMOS	USART asynchronous TX data/synchronous clock output.
	DT ⁽³⁾	—	CMOS	USART synchronous data output.
VDD	VDD	Power	—	Positive supply.
VSS	VSS	Power	—	Ground reference.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open-Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C levels
HV = High Voltage XTAL = Crystal

- Note** 1: Default peripheral input. Input can be moved to any other pin with the PPS input selection registers.
2: All pin outputs default to PORT latch data. Any pin can be selected as a digital peripheral output with the PPS output selection registers. See Register 12-1.
3: These USART functions are bidirectional. The output pin selections must be the same as the input pin selections.

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4.2 Register Definitions: Configuration Words

REGISTER 4-1: CONFIGURATION WORD 1

U-1	U-1	R/P-1	R/P-1	R/P-1	U-1
—	—	CLKOUTEN	BOREN<1:0> ⁽¹⁾	—	—
bit 13					bit 8

R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	U-1	R/P-1	R/P-1
CP ⁽²⁾	MCLRE	PWRTEN ⁽¹⁾	WDTE<1:0>	—	—	FOSC<1:0>	—
bit 7							bit 0

Legend:

R = Readable bit P = Programmable bit U = Unimplemented bit, read as '1'
 '0' = Bit is cleared '1' = Bit is set n = Value when blank or after Bulk Erase

- bit 13-12 **Unimplemented:** Read as '1'
- bit 11 **CLKOUTEN:** Clock Out Enable bit
 1 = OFF – CLKOUT function is disabled. I/O or oscillator function on CLKOUT pin
 0 = ON – CLKOUT function is enabled on CLKOUT pin
- bit 10-9 **BOREN<1:0>:** Brown-out Reset Enable bits⁽¹⁾
 11 = ON – Brown-out Reset enabled. The SBOREN bit is ignored.
 10 = SLEEP – Brown-out Reset enabled while running and disabled in Sleep. The SBOREN bit is ignored.
 01 = SBODEN – Brown-out Reset controlled by the SBOREN bit in the BORCON register
 00 = OFF – Brown-out Reset disabled. The SBOREN bit is ignored.
- bit 8 **Unimplemented:** Read as '1'
- bit 7 **CP:** Flash Program Memory Code Protection bit⁽²⁾
 1 = OFF – Code protection off. Program Memory can be read and written.
 0 = ON – Code protection on. Program Memory cannot be read or written externally.
- bit 6 **MCLRE:** MCLR/VPP Pin Function Select bit
 If LVP bit = 1 (ON):
 This bit is ignored. MCLR/VPP pin function is MCLR; Weak pull-up enabled.
 If LVP bit = 0 (OFF):
 1 = ON – MCLR/VPP pin function is MCLR; Weak pull-up enabled.
 0 = OFF – MCLR/VPP pin function is digital input; MCLR internally disabled; Weak pull-up under control of pin's WPU control bit.
- bit 5 **PWRTEN:** Power-up Timer Enable bit⁽¹⁾
 1 = OFF – PWRT disabled
 0 = ON – PWRT enabled
- bit 4-3 **WDTE<1:0>:** Watchdog Timer Enable bit
 11 = ON – WDT enabled. SWDTEN is ignored.
 10 = SLEEP – WDT enabled while running and disabled in Sleep. SWDTEN is ignored.
 01 = SWDTEN – WDT controlled by the SWDTEN bit in the WDTCN register
 00 = OFF – WDT disabled. SWDTEN is ignored.
- bit 2 **Unimplemented:** Read as '1'
- bit 1-0 **FOSC<1:0>:** Oscillator Selection bits
 11 = ECH – External Clock, High-Power mode: CLKI on CLKI
 10 = ECM – External Clock, Medium Power mode: CLKI on CLKI
 01 = ECL – External Clock, Low-Power mode: CLKI on CLKI
 00 = INTOSC – I/O function on CLKI

- Note 1:** Enabling Brown-out Reset does not automatically enable Power-up Timer.
Note 2: Once enabled, code-protect can only be disabled by bulk erasing the device.

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REGISTER 5-2: OSCSTAT: OSCILLATOR STATUS REGISTER

U-0	R-0/q	R-q/q	R-0/q	R-0/q	R-q/q	R-0/q	R-0/q
—	PLL R	OSTS	HFIOFR	HFIOFL	MFIOFR	LFIOFR	HFIOFS
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Conditional

bit 7	Unimplemented: Read as '0'
bit 6	PLL R 4x PLL Ready bit 1 = 4x PLL is ready 0 = 4x PLL is not ready
bit 5	OSTS: Oscillator Start-up Timer Status bit 1 = Running from the clock defined by the FOSC<1:0> bits of the Configuration Words 0 = Running from an internal oscillator (FOSC<1:0> = 00)
bit 4	HFIOFR: High-Frequency Internal Oscillator Ready bit 1 = HFINTOSC is ready 0 = HFINTOSC is not ready
bit 3	HFIOFL: High-Frequency Internal Oscillator Locked bit 1 = HFINTOSC is at least 2% accurate 0 = HFINTOSC is not 2% accurate
bit 2	MFIOFR: Medium-Frequency Internal Oscillator Ready bit 1 = MFINTOSC is ready 0 = MFINTOSC is not ready
bit 1	LFIOFR: Low-Frequency Internal Oscillator Ready bit 1 = LFINTOSC is ready 0 = LFINTOSC is not ready
bit 0	HFIOFS: High-Frequency Internal Oscillator Stable bit 1 = HFINTOSC is at least 0.5% accurate 0 = HFINTOSC is not 0.5% accurate

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6.1 Power-On Reset (POR)

The POR circuit holds the device in Reset until VDD has reached an acceptable level for minimum operation. Slow rising VDD, fast operating speeds or analog performance may require greater than minimum VDD. The PWRT, BOR or MCLR features can be used to extend the start-up period until all device operation conditions have been met.

6.1.1 POWER-UP TIMER (PWRT)

The Power-up Timer provides a nominal 64 ms time-out on POR or Brown-out Reset.

The device is held in Reset as long as PWRT is active. The PWRT delay allows additional time for the VDD to rise to an acceptable level. The Power-up Timer is enabled by clearing the PWRTE bit in Configuration Words.

The Power-up Timer starts after the release of the POR and BOR.

For additional information, refer to Application Note AN607, "Power-up Trouble Shooting" (DS00607).

6.2 Brown-Out Reset (BOR)

The BOR circuit holds the device in Reset when VDD reaches a selectable minimum level. Between the POR and BOR, complete voltage range coverage for execution protection can be implemented.

The Brown-out Reset module has four operating modes controlled by the BOREN<1:0> bits in Configuration Words. The four operating modes are:

- BOR is always on
- BOR is off when in Sleep
- BOR is controlled by software
- BOR is always off

Refer to Table 6-1 for more information.

The Brown-out Reset voltage level is selectable by configuring the BORV bit in Configuration Words.

A VDD noise rejection filter prevents the BOR from triggering on small events. If VDD falls below VBOR for a duration greater than parameter TBORDC, the device will reset. See Figure 6-2 for more information.

TABLE 6-1: BOR OPERATING MODES

BOREN<1:0>	SBOREN	Device Mode	BOR Mode	Instruction Execution upon: Release of POR or Wake-up from Sleep
11	X	X	Active	Waits for BOR ready ⁽¹⁾ (BORRDY = 1)
10	X	Awake	Active	Waits for BOR ready (BORRDY = 1)
		Sleep	Disabled	
01	1	X	Active	Waits for BOR ready ⁽¹⁾ (BORRDY = 1)
	0	X	Disabled	Begins immediately (BORRDY = x)
00	X	X	Disabled	

Note 1: In these specific cases, "release of POR" and "wake-up from Sleep," there is no delay in start-up. The BOR ready flag, (BORRDY = 1), will be set before the CPU is ready to execute instructions because the BOR circuit is forced on by the BOREN<1:0> bits.

6.2.1 BOR IS ALWAYS ON

When the BOREN bits of Configuration Words are programmed to '11', the BOR is always on. The device start-up will be delayed until the BOR is ready and VDD is higher than the BOR threshold.

BOR protection is active during Sleep. The BOR does not delay wake-up from Sleep.

6.2.2 BOR IS OFF IN SLEEP

When the BOREN bits of Configuration Words are programmed to '10', the BOR is on, except in Sleep. The device start-up will be delayed until the BOR is ready and VDD is higher than the BOR threshold.

BOR protection is not active during Sleep. The device wake-up will be delayed until the BOR is ready.

6.2.3 BOR CONTROLLED BY SOFTWARE

When the BOREN bits of Configuration Words are programmed to '01', the BOR is controlled by the SBOREN bit of the BORCON register. The device start-up is not delayed by the BOR ready condition or the VDD level.

BOR protection begins as soon as the BOR circuit is ready. The status of the BOR circuit is reflected in the BORRDY bit of the BORCON register.

BOR protection is unchanged by Sleep.

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6.12 Determining the Cause of a Reset

Upon any Reset, multiple bits in the STATUS and PCON registers are updated to indicate the cause of the Reset. Table 6-3 and Table 6-4 show the Reset conditions of these registers.

TABLE 6-3: RESET STATUS BITS AND THEIR SIGNIFICANCE

STKOVF	STKUNF	RWDT	RMCLR	RI	POR	BOR	TO	PD	Condition
0	0	1	1	1	0	x	1	1	Power-on Reset
0	0	1	1	1	0	x	0	x	Illegal, \overline{TO} is set on \overline{POR}
0	0	1	1	1	0	x	x	0	Illegal, \overline{PD} is set on \overline{POR}
0	0	u	1	1	u	0	1	1	Brown-out Reset
u	u	0	u	u	u	u	0	u	WDT Reset
u	u	u	u	u	u	u	0	0	WDT Wake-up from Sleep
u	u	u	u	u	u	u	1	0	Interrupt Wake-up from Sleep
u	u	u	0	u	u	u	u	u	\overline{MCLR} Reset during normal operation
u	u	u	0	u	u	u	1	0	\overline{MCLR} Reset during Sleep
u	u	u	u	0	u	u	u	u	RESET Instruction Executed
1	u	u	u	u	u	u	u	u	Stack Overflow Reset (STVREN = 1)
u	1	u	u	u	u	u	u	u	Stack Underflow Reset (STVREN = 1)

TABLE 6-4: RESET CONDITION FOR SPECIAL REGISTERS

Condition	Program Counter	STATUS Register	PCON Register
Power-on Reset	0000h	---1 1000	00-- 110x
\overline{MCLR} Reset during normal operation	0000h	---u uuuu	uu-- 0uuu
\overline{MCLR} Reset during Sleep	0000h	---1 0uuu	uu-- 0uuu
WDT Reset	0000h	---0 uuuu	uu-- uuuu
WDT Wake-up from Sleep	PC + 1	---0 0uuu	uu-- uuuu
Brown-out Reset	0000h	---1 1uuu	00-- 11u0
Interrupt Wake-up from Sleep	PC + 1 ⁽¹⁾	---1 0uuu	uu-- uuuu
RESET Instruction Executed	0000h	---u uuuu	uu-- u0uu
Stack Overflow Reset (STVREN = 1)	0000h	---u uuuu	1u-- uuuu
Stack Underflow Reset (STVREN = 1)	0000h	---u uuuu	u1-- uuuu

Legend: u = unchanged, x = unknown, - = unimplemented bit, reads as '0'.

Note 1: When the wake-up is due to an interrupt and the Global Interrupt Enable bit (GIE) is set, the return address is pushed on the stack and PC is loaded with the interrupt vector (0004h) after execution of PC + 1.

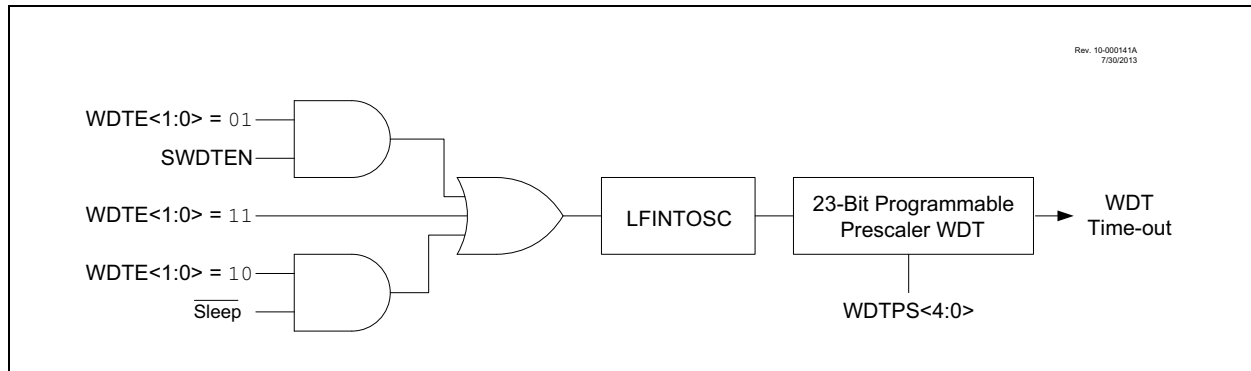
9.0 WATCHDOG TIMER (WDT)

The Watchdog Timer is a system timer that generates a Reset if the firmware does not issue a `CLRWDT` instruction within the time-out period. The Watchdog Timer is typically used to recover the system from unexpected events.

The WDT has the following features:

- Independent clock source
- Multiple operating modes
 - WDT is always on
 - WDT is off when in Sleep
 - WDT is controlled by software
 - WDT is always off
- Configurable time-out period is from 1 ms to 256 seconds (nominal)
- Multiple Reset conditions
- Operation during Sleep

FIGURE 9-1: WATCHDOG TIMER BLOCK DIAGRAM



9.6 Register Definitions: Watchdog Control

REGISTER 9-1: WDTCON: WATCHDOG TIMER CONTROL REGISTER

U-0	U-0	R/W-0/0	R/W-1/1	R/W-0/0	R/W-1/1	R/W-1/1	R/W-0/0
—	—	WDTPS<4:0>					SWDTEN
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-6 **Unimplemented:** Read as '0'

bit 5-1 **WDTPS<4:0>:** Watchdog Timer Period Select bits⁽¹⁾

Bit Value = Prescale Rate

11111 = Reserved. Results in minimum interval (1:32)

.

.

.

10011 = Reserved. Results in minimum interval (1:32)

10010 = 1:8388608 (2^{23}) (Interval 256s nominal)

10001 = 1:4194304 (2^{22}) (Interval 128s nominal)

10000 = 1:2097152 (2^{21}) (Interval 64s nominal)

01111 = 1:1048576 (2^{20}) (Interval 32s nominal)

01110 = 1:524288 (2^{19}) (Interval 16s nominal)

01101 = 1:262144 (2^{18}) (Interval 8s nominal)

01100 = 1:131072 (2^{17}) (Interval 4s nominal)

01011 = 1:65536 (Interval 2s nominal) (Reset value)

01010 = 1:32768 (Interval 1s nominal)

01001 = 1:16384 (Interval 512 ms nominal)

01000 = 1:8192 (Interval 256 ms nominal)

00111 = 1:4096 (Interval 128 ms nominal)

00110 = 1:2048 (Interval 64 ms nominal)

00101 = 1:1024 (Interval 32 ms nominal)

00100 = 1:512 (Interval 16 ms nominal)

00011 = 1:256 (Interval 8 ms nominal)

00010 = 1:128 (Interval 4 ms nominal)

00001 = 1:64 (Interval 2 ms nominal)

00000 = 1:32 (Interval 1 ms nominal)

bit 0 **SWDTEN:** Software Enable/Disable for Watchdog Timer bit

If WDTE<1:0> = 1x:

This bit is ignored.

If WDTE<1:0> = 01:

1 = WDT is turned on

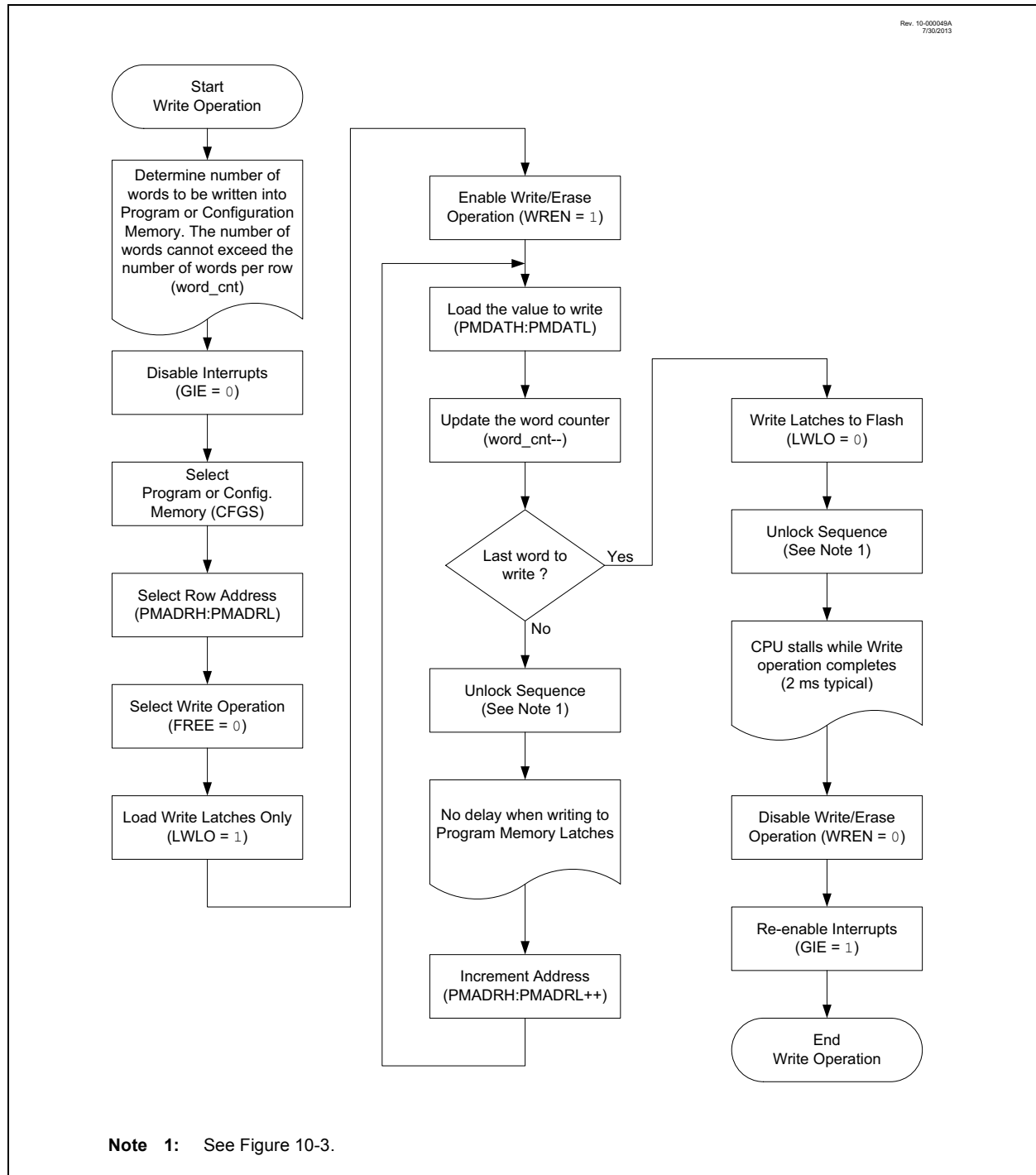
0 = WDT is turned off

If WDTE<1:0> = 00:

This bit is ignored.

Note 1: Times are approximate. WDT time is based on 31 kHz LFINTOSC.

FIGURE 10-6: FLASH PROGRAM MEMORY WRITE FLOWCHART



11.1.7 PORTA FUNCTIONS AND OUTPUT PRIORITIES

Each pin defaults to the PORT latch data after Reset. Other functions are selected with the peripheral pin select logic. See **Section 12.0 “Peripheral Pin Select (PPS) Module”** for more information. Analog input functions, such as ADC inputs, are not shown in the peripheral pin select lists. These inputs are active when the I/O pin is set for Analog mode using the ANSELA register. Digital output functions may continue to control the pin when it is in Analog mode.

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TABLE 14-1: PERIPHERALS REQUIRING THE FIXED VOLTAGE REFERENCE (FVR)

Peripheral	Conditions	Description
HFINTOSC	FOSC<2:0> = 010 and IRCF<3:0> = 000x	INTOSC is active and device is not in Sleep.
BOR	BOREN<1:0> = 11	BOR always enabled.
	BOREN<1:0> = 10 and BORFS = 1	BOR disabled in Sleep mode, BOR Fast Start enabled.
	BOREN<1:0> = 01 and BORFS = 1	BOR under software control, BOR Fast Start enabled.
LDO	All PIC16F1574/5/8/9 devices, when VREGPM = 1 and not in Sleep	The device runs off of the Low-Power Regulator when in Sleep mode.

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16.3 Register Definitions: ADC Control

REGISTER 16-1: ADCON0: ADC CONTROL REGISTER 0

U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	CHS<4:0>					GO/DONE	ADON
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7 **Unimplemented:** Read as '0'

bit 6-2 **CHS<4:0>:** Analog Channel Select bits

00000 = AN0

00001 = AN1

00010 = AN2

00011 = AN3

00100 = AN4

00101 = AN5

00110 = AN6

00111 = AN7

01000 = AN8⁽⁴⁾

01001 = AN9⁽⁴⁾

01010 = AN10⁽⁴⁾

01011 = AN11⁽⁴⁾

01100 = Reserved. No channel connected.

•

•

•

11100 = Reserved. No channel connected.

11101 = Temperature Indicator⁽¹⁾

11110 = DAC (Digital-to-Analog Converter)⁽²⁾

11111 = FVR (Fixed Voltage Reference) Buffer 1 Output⁽³⁾

bit 1 **GO/DONE:** ADC Conversion Status bit

1 = ADC conversion cycle in progress. Setting this bit starts an ADC conversion cycle.

This bit is automatically cleared by hardware when the ADC conversion has completed.

0 = ADC conversion completed/not in progress

bit 0 **ADON:** ADC Enable bit

1 = ADC is enabled

0 = ADC is disabled and consumes no operating current

Note 1: See Section 15.0 "Temperature Indicator Module" for more information.

2: See Section 17.0 "5-Bit Digital-to-Analog Converter (DAC) Module" for more information.

3: See Section 14.0 "Fixed Voltage Reference (FVR)" for more information.

4: Available on PIC16(L)F1578/9 devices only.

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REGISTER 16-6: ADRESH: ADC RESULT REGISTER HIGH (ADRESH) ADFM = 1

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
—	—	—	—	—	—	ADRES<9:8>	
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-2 **Reserved:** Do not use.

bit 1-0 **ADRES<9:8>**: ADC Result Register bits
Upper two bits of 10-bit conversion result

REGISTER 16-7: ADRESL: ADC RESULT REGISTER LOW (ADRESL) ADFM = 1

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
ADRES<7:0>							
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0 **ADRES<7:0>**: ADC Result Register bits
Lower eight bits of 10-bit conversion result

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20.5.2.1 T1G Pin Gate Operation

The T1G pin is one source for Timer1 gate control. It can be used to supply an external source to the Timer1 gate circuitry.

20.5.2.2 Timer0 Overflow Gate Operation

When Timer0 increments from FFh to 00h, a low-to-high pulse will automatically be generated and internally supplied to the Timer1 gate circuitry.

20.5.3 TIMER1 GATE TOGGLE MODE

When Timer1 Gate Toggle mode is enabled, it is possible to measure the full-cycle length of a Timer1 gate signal, as opposed to the duration of a single level pulse.

The Timer1 gate source is routed through a flip-flop that changes state on every incrementing edge of the signal. See Figure 20-4 for timing details.

Timer1 Gate Toggle mode is enabled by setting the T1GTM bit of the T1GCON register. When the T1GTM bit is cleared, the flip-flop is cleared and held clear. This is necessary in order to control which edge is measured.

Note: Enabling Toggle mode at the same time as changing the gate polarity may result in indeterminate operation.

20.5.4 TIMER1 GATE SINGLE-PULSE MODE

When Timer1 Gate Single-Pulse mode is enabled, it is possible to capture a single pulse gate event. Timer1 Gate Single-Pulse mode is first enabled by setting the T1GSPM bit in the T1GCON register. Next, the T1GGO/DONE bit in the T1GCON register must be set. The Timer1 will be fully enabled on the next incrementing edge. On the next trailing edge of the pulse, the T1GGO/DONE bit will automatically be cleared. No other gate events will be allowed to increment Timer1 until the T1GGO/DONE bit is once again set in software. See Figure 20-5 for timing details.

If the Single Pulse Gate mode is disabled by clearing the T1GSPM bit in the T1GCON register, the T1GGO/DONE bit should also be cleared.

Enabling the Toggle mode and the Single-Pulse mode simultaneously will permit both sections to work together. This allows the cycle times on the Timer1 gate source to be measured. See Figure 20-6 for timing details.

20.5.5 TIMER1 GATE VALUE STATUS

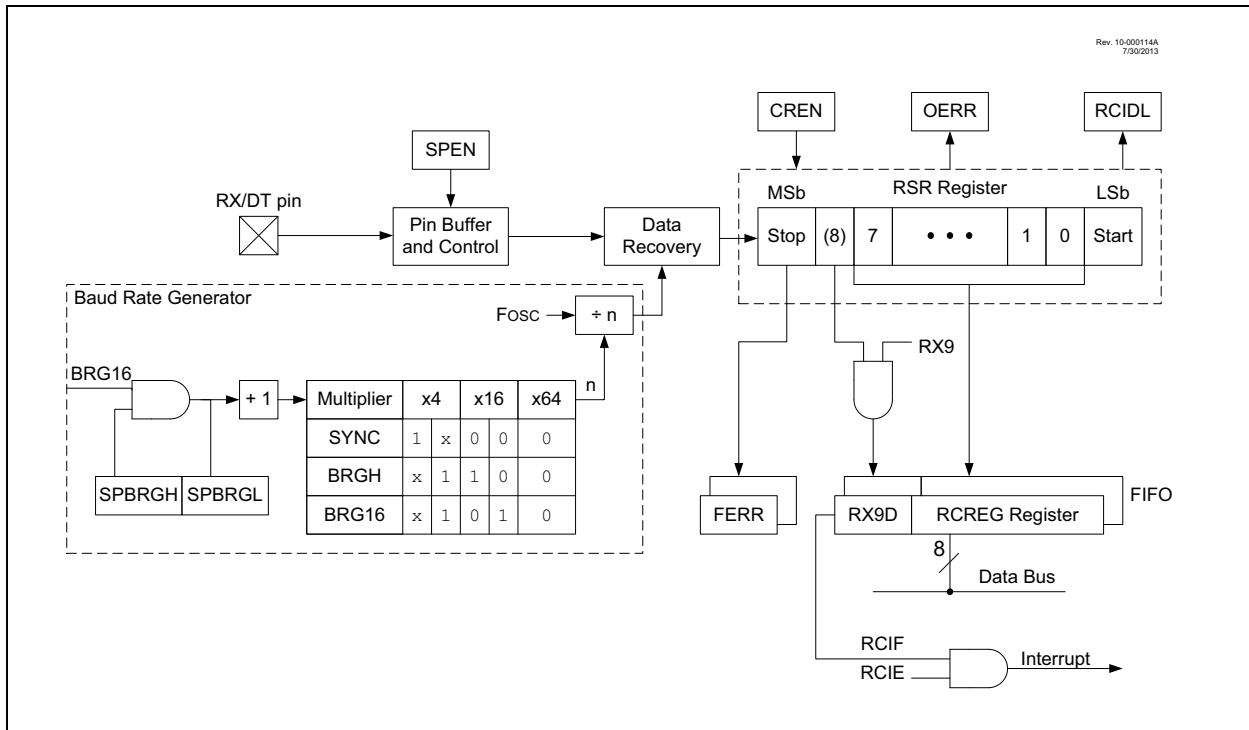
When Timer1 Gate Value Status is utilized, it is possible to read the most current level of the gate control value. The value is stored in the T1GVAL bit in the T1GCON register. The T1GVAL bit is valid even when the Timer1 gate is not enabled (TMR1GE bit is cleared).

20.5.6 TIMER1 GATE EVENT INTERRUPT

When Timer1 Gate Event Interrupt is enabled, it is possible to generate an interrupt upon the completion of a gate event. When the falling edge of T1GVAL occurs, the TMR1GIF flag bit in the PIR1 register will be set. If the TMR1GIE bit in the PIE1 register is set, then an interrupt will be recognized.

The TMR1GIF flag bit operates even when the Timer1 gate is not enabled (TMR1GE bit is cleared).

FIGURE 22-2: EUSART RECEIVE BLOCK DIAGRAM



The operation of the EUSART module is controlled through three registers:

- Transmit Status and Control (TXSTA)
- Receive Status and Control (RCSTA)
- Baud Rate Control (BAUDCON)

These registers are detailed in Register 22-1, Register 22-2 and Register 22-3, respectively.

When the receiver or transmitter section is not enabled then the corresponding RX or TX pin may be used for general purpose input and output.

FIGURE 22-12: SYNCHRONOUS RECEPTION (MASTER MODE, SREN)

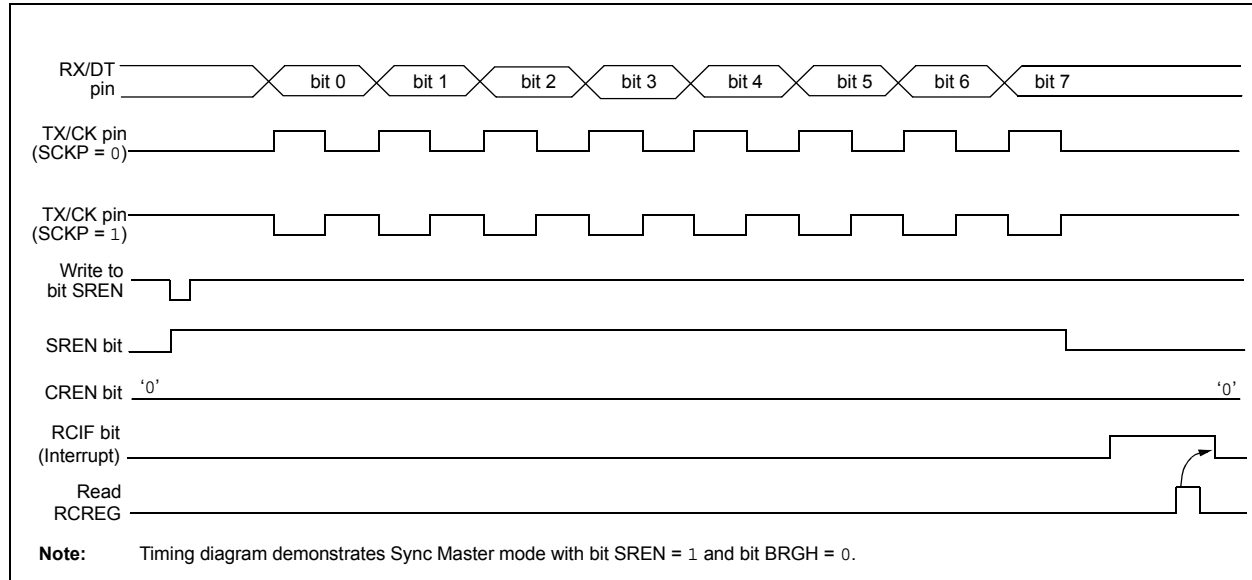


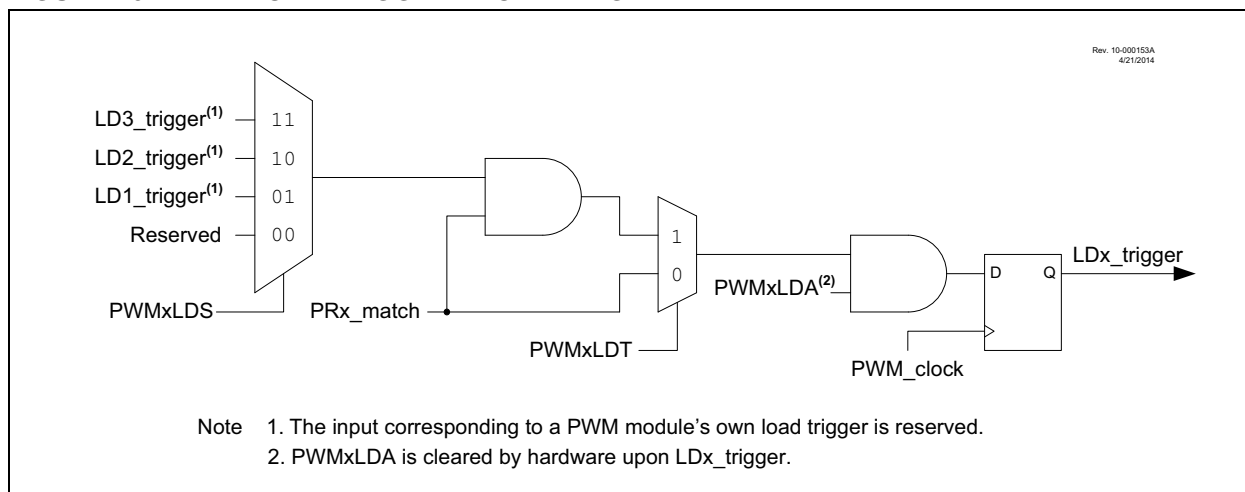
TABLE 22-8: SUMMARY OF REGISTERS ASSOCIATED WITH SYNCHRONOUS MASTER RECEPTION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BAUDCON	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	204
INTCON	GIE	PEIE	TMR0IE	INTE	IOCF	TMR0IF	INTF	IOCF	86
PIE1	TMR1GIE	ADIE	RCIE	TXIE	—	—	TMR2IE	TMR1IE	87
PIR1	TMR1GIF	ADIF	RCIF	TXIF	—	—	TMR2IF	TMR1IF	90
RCREG	EUSART Receive Data Register								197*
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	203
SPBRGL	BRG<7:0>								205*
SPBRGH	BRG<15:8>								205*
TXSTA	CSRC	TX9	TXEN	SYNC	SEnDB	BRGH	TRMT	TX9D	202

Legend: — = unimplemented location, read as '0'. Shaded cells are not used for synchronous master reception.

* Page provides register information.

FIGURE 23-2: LOAD TRIGGER BLOCK DIAGRAM



23.1 Fundamental Operation

The PWM module produces a 16-bit resolution pulse width modulated output.

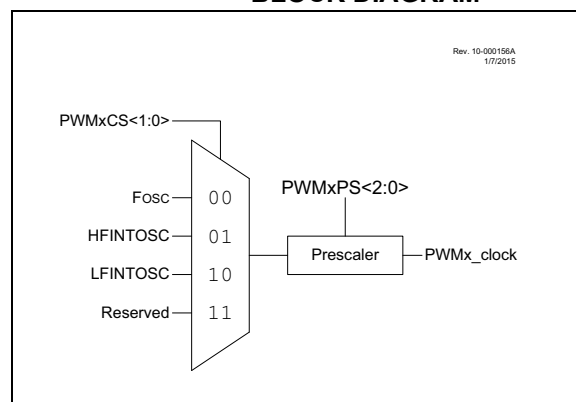
Each PWM module has an independent timer driven by a selection of clock sources determined by the PWMxCLKCON register (Register 23-4). The timer value is compared to event count registers to generate the various events of a the PWM waveform, such as the period and duty cycle. For a block diagram describing the clock sources refer to Figure 23-3.

Each PWM module can be enabled individually using the EN bit of the PWMxCON register, or several PWM modules can be enabled simultaneously using the mirror bits of the PWMEN register.

The current state of the PWM output can be read using the OUT bit of the PWMxCON register. In some modes this bit can be set and cleared by software giving additional software control over the PWM waveform. This bit is synchronized to Fosc/4 and therefore does not change in real time with respect to the PWM_clock.

Note: If PWM_clock > Fosc/4, the OUT bit may not accurately represent the output state of the PWM.

FIGURE 23-3: PWM CLOCK SOURCE BLOCK DIAGRAM



23.1.1 PWMx PIN CONFIGURATION

All PWM outputs are multiplexed with the PORT data latch, so the pins must also be configured as outputs by clearing the associated PORT TRIS bits.

The slew rate feature may be configured to optimize the rate to be used in conjunction with the PWM outputs. High-speed output switching is attained by clearing the associated PORT SLRCON bits.

The PWM outputs can be configured to be open-drain outputs by setting the associated PORT ODCON bits.

23.1.2 PWMx Output Polarity

The output polarity is inverted by setting the POL bit of the PWMxCON register. The polarity control affects the PWM output even when the module is not enabled.

Note: There are no long and short bit name variants for the following three mirror registers

REGISTER 23-17: PWMEN: PWMEN BIT ACCESS REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	PWM4EN_A	PWM3EN_A	PWM2EN_A	PWM1EN_A
bit 7				bit 0			

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set '0' = Bit is cleared

bit 7-4 **Unimplemented:** Read as '0'
bit 3-0 **PWMxEN:** PWM4/PWM3/PWM2/PWM1 Enable bits
Mirror copy of EN bits in PWMxCON<7>

REGISTER 23-18: PWMLD: LD BIT ACCESS REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	PWM4LDA_A	PWM3LDA_A	PWM2LDA_A	PWM1LDA_A
bit 7				bit 0			

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set '0' = Bit is cleared

bit 7-4 **Unimplemented:** Read as '0'
bit 3-0 **PWMxLDA:** PWM4/PWM3/PWM2/PWM1 LD bits
Mirror copy of LD bits in PWMxLDCON<7>

REGISTER 23-19: PWMOUT: PWMOUT BIT ACCESS REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	PWM4OUT_A	PWM3OUT_A	PWM2OUT_A	PWM1OUT_A
bit 7				bit 0			

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set '0' = Bit is cleared

bit 7-4 **Unimplemented:** Read as '0'
bit 3-0 **PWMxOUT:** PWM4/PWM3/PWM2/PWM1 Output bits
Mirror copy of OUT bits in PWMxCON<5>

RETFIE	Return from Interrupt
Syntax:	[<i>label</i>] RETFIE
Operands:	None
Operation:	TOS → PC, 1 → GIE
Status Affected:	None
Description:	Return from Interrupt. Stack is POPed and Top-of-Stack (TOS) is loaded in the PC. Interrupts are enabled by setting Global Interrupt Enable bit, GIE (INTCON<7>). This is a 2-cycle instruction.
Words:	1
Cycles:	2
<u>Example:</u>	RETFIE After Interrupt PC = TOS GIE = 1

RETLW	Return with literal in W
Syntax:	[<i>label</i>] RETLW <i>k</i>
Operands:	0 ≤ <i>k</i> ≤ 255
Operation:	<i>k</i> → (W); TOS → PC
Status Affected:	None
Description:	The W register is loaded with the 8-bit literal ' <i>k</i> '. The program counter is loaded from the top of the stack (the return address). This is a 2-cycle instruction.
Words:	1
Cycles:	2
<u>Example:</u>	CALL TABLE;W contains table ;offset value ;W now has table value . . . ADDWF PC ;W = offset RETLW k1 ;Begin table RETLW k2 ; . . . RETLW kn ; End of table
TABLE	
	Before Instruction W = 0x07 After Instruction W = value of k8

RETURN	Return from Subroutine
Syntax:	[<i>label</i>] RETURN
Operands:	None
Operation:	TOS → PC
Status Affected:	None
Description:	Return from subroutine. The stack is POPed and the top of the stack (TOS) is loaded into the program counter. This is a 2-cycle instruction.

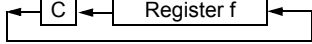
RLF	Rotate Left f through Carry
Syntax:	[<i>label</i>] RLF <i>f</i> , <i>d</i>
Operands:	0 ≤ <i>f</i> ≤ 127 <i>d</i> ∈ [0,1]
Operation:	See description below
Status Affected:	C
Description:	The contents of register ' <i>f</i> ' are rotated one bit to the left through the Carry flag. If ' <i>d</i> ' is '0', the result is placed in the W register. If ' <i>d</i> ' is '1', the result is stored back in register ' <i>f</i> '.
	
Words:	1
Cycles:	1
<u>Example:</u>	RLF REG1,0 Before Instruction REG1 = 1110 0110 C = 0 After Instruction REG1 = 1110 0110 W = 1100 1100 C = 1

TABLE 27-2: SUPPLY CURRENT (IDD)^(1,2)

PIC16LF1574/5/8/9		Standard Operating Conditions (unless otherwise stated)					
PIC16F1574/5/8/9							
Param. No.	Device Characteristics	Min.	Typ†	Max.	Units	Conditions	
						VDD	Note
D013		—	41	51	μA	1.8	Fosc = 1 MHz, External Clock (ECM), Medium Power mode
		—	69	80	μA	3.0	
D013		—	79	107	μA	2.3	Fosc = 1 MHz, External Clock (ECM), Medium Power mode
		—	105	138	μA	3.0	
		—	151	184	μA	5.0	
D014		—	134	152	μA	1.8	Fosc = 4 MHz, External Clock (ECM), Medium Power mode
		—	234	268	μA	3.0	
D014		—	201	255	μA	2.3	Fosc = 4 MHz, External Clock (ECM), Medium Power mode
		—	270	329	μA	3.0	
		—	344	431	μA	5.0	
D015		—	7	19	μA	1.8	Fosc = 31 kHz, LFINTOSC, -40°C ≤ TA ≤ +85°C
		—	9	20	μA	3.0	
D015		—	15	25	μA	2.3	Fosc = 31 kHz, LFINTOSC, -40°C ≤ TA ≤ +85°C
		—	18	28	μA	3.0	
		—	20	29	μA	5.0	
D016		—	128	174	μA	1.8	Fosc = 500 kHz, MFINTOSC
		—	153	203	μA	3.0	
D016		—	166	241	μA	2.3	Fosc = 500 kHz, MFINTOSC
		—	187	273	μA	3.0	
		—	249	332	μA	5.0	
D017*		—	0.6	0.7	mA	1.8	Fosc = 8 MHz, HFINTOSC
		—	0.9	1.1	mA	3.0	
D017*		—	0.7	1.0	mA	2.3	Fosc = 8 MHz, HFINTOSC
		—	1.0	1.1	mA	3.0	
		—	1.1	1.2	mA	5.0	
D018		—	0.9	1.0	mA	1.8	Fosc = 16 MHz, HFINTOSC
		—	1.3	1.4	mA	3.0	
D018		—	1.1	1.3	mA	2.3	Fosc = 16 MHz, HFINTOSC
		—	1.3	1.5	mA	3.0	
		—	1.5	1.8	mA	5.0	

* These parameters are characterized but not tested.

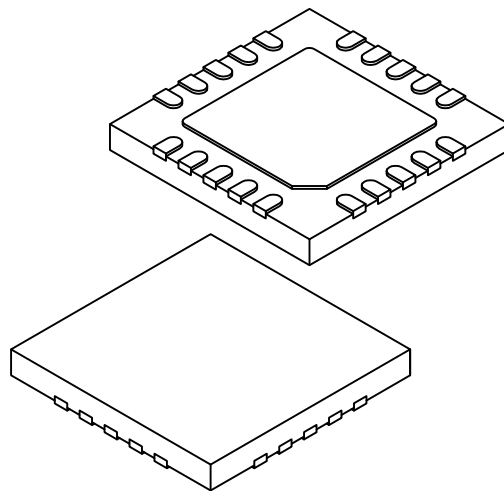
† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** The test conditions for all IDD measurements in active operation mode are: CLKIN = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to VSS; MCLR = VDD; WDT disabled.
- 2:** The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption.
- 3:** PLL required for 32 MHz operation.

PIC16(L)F1574/5/8/9

20-Lead Ultra Thin Plastic Quad Flat, No Lead Package (GZ) - 4x4x0.5 mm Body [UQFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Terminals	N	20		
Pitch	e	0.50 BSC		
Overall Height	A	0.45	0.50	0.55
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	A3	0.127 REF		
Overall Width	E	4.00 BSC		
Exposed Pad Width	E2	2.60	2.70	2.80
Overall Length	D	4.00 BSC		
Exposed Pad Length	D2	2.60	2.70	2.80
Terminal Width	b	0.20	0.25	0.30
Terminal Length	L	0.30	0.40	0.50
Terminal-to-Exposed-Pad	K	0.20	-	-

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated
3. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-255A Sheet 2 of 2