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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	80C51
Core Size	8-Bit
Speed	40/20MHz
Connectivity	UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	32
Program Memory Size	64KB (64K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-VQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/at87c51rd2-rltum">https://www.e-xfl.com/product-detail/microchip-technology/at87c51rd2-rltum</a>

facilitates multiprocessor communication (EUSART) and an X2 speed improvement mechanism.

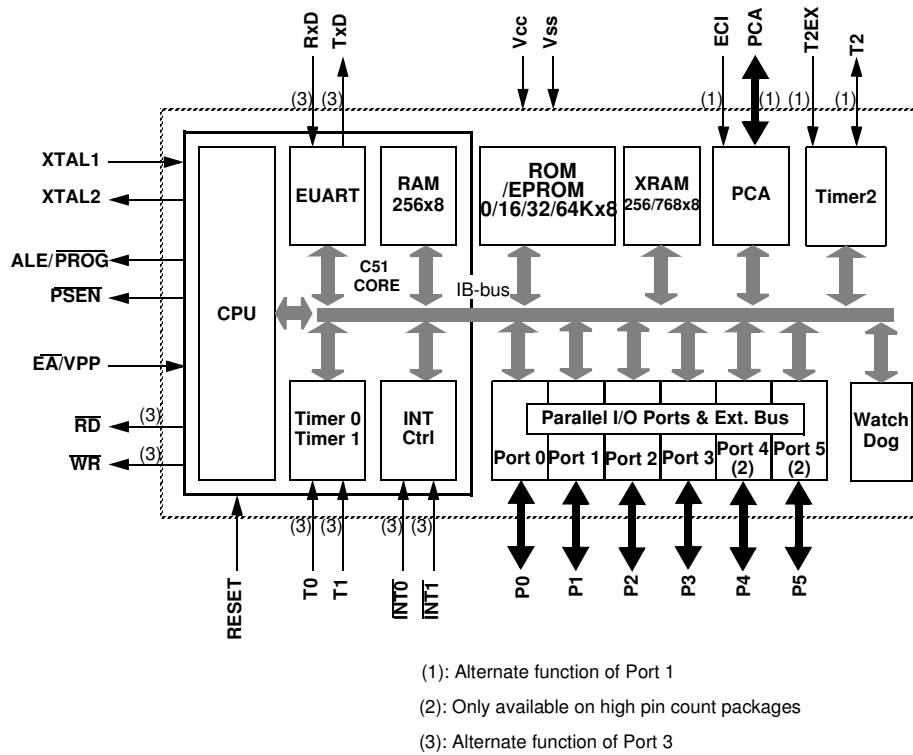
The fully static design of the TS80C51Rx2 allows to reduce system power consumption by bringing the clock frequency down to any value, even DC, without loss of data.

The TS80C51Rx2 has 2 software-selectable modes of reduced activity for further reduction in power consumption. In the idle mode the CPU is frozen while the timers, the serial port and the interrupt system are still operating. In the power-down mode the RAM is saved and all other functions are inoperative.

<b>PDIL40 PLCC44 VQFP44 1.4</b>	<b>ROM (bytes)</b>	<b>EPROM (bytes)</b>	<b>XRAM (bytes)</b>	<b>TOTAL RAM (bytes)</b>	<b>I/O</b>
TS80C51RA2	0	0	256	512	32
TS80C51RD2	0	0	768	1024	32
TS83C51RB2	16k	0	256	512	32
TS83C51RC2	32k	0	256	512	32
TS83C51RD2	64k	0	768	1024	32
TS87C51RB2	0	16k	256	512	32
TS87C51RC2	0	32k	256	512	32
TS87C51RD2	0	64k	768	1024	32

<b>PLCC68 VQFP64 1.4</b>	<b>ROM (bytes)</b>	<b>EPROM (bytes)</b>	<b>XRAM (bytes)</b>	<b>TOTAL RAM (bytes)</b>	<b>I/O</b>
TS80C51RD2	0	0	768	1024	48
TS83C51RD2	64k	0	768	1024	48
TS87C51RD2	0	64k	768	1024	48

### 3. Block Diagram

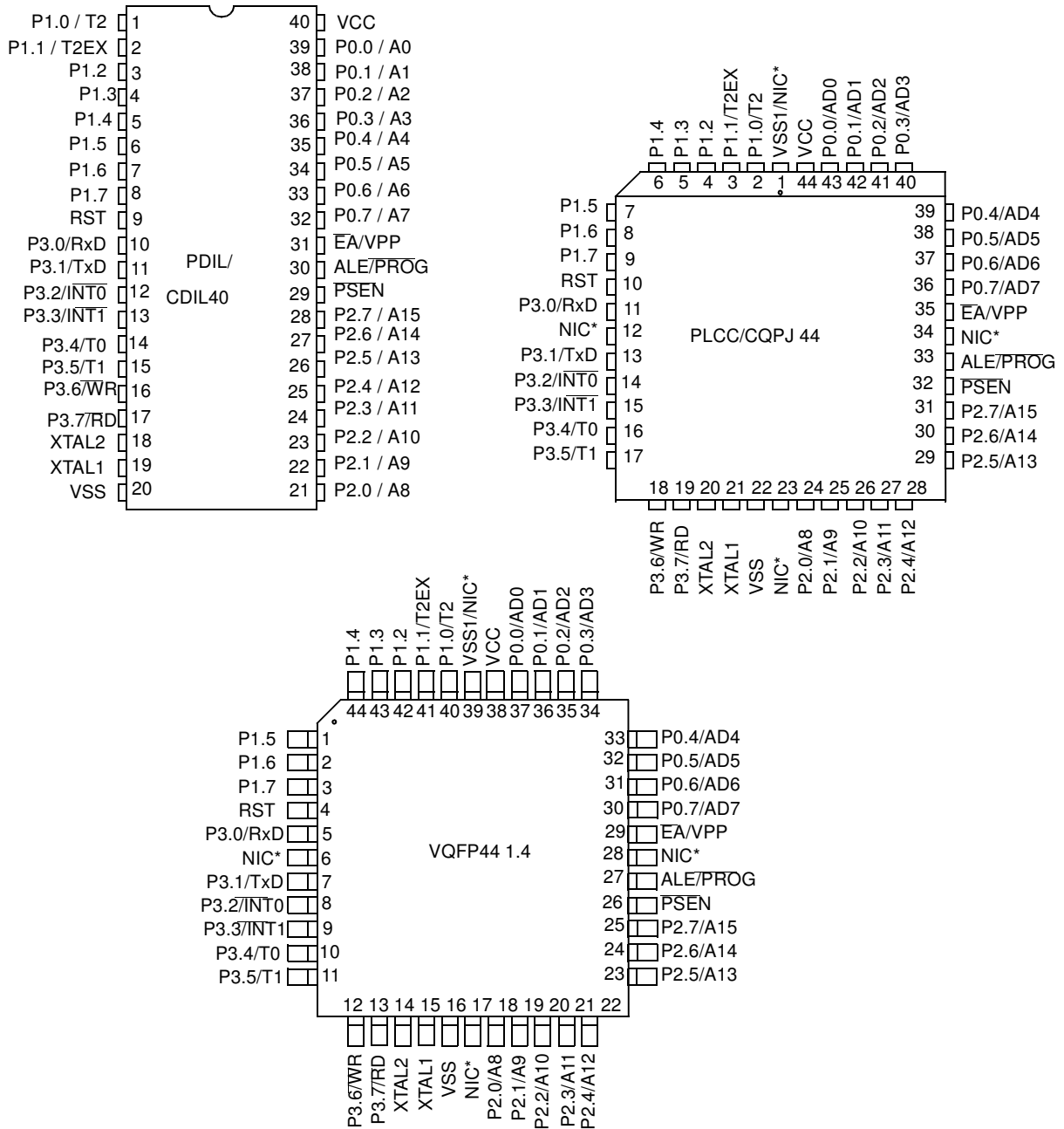


**Table 4-1.** All SFRs with their address and their reset value

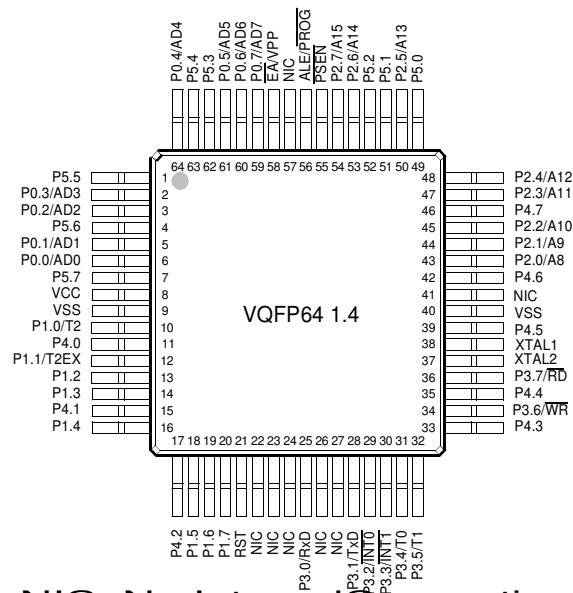
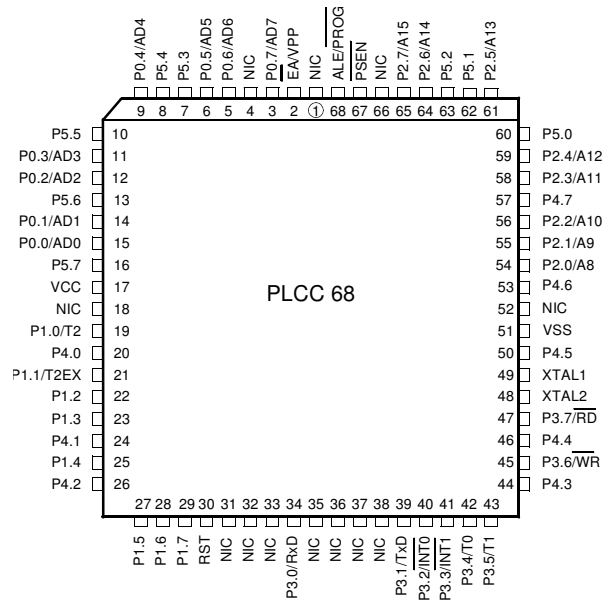
	Bit addressable	Non Bit addressable							
	0/8	1/9	2/A	3/B	4/C	5/D	6/E	7/F	
F8h		CH 0000 0000	CCAP0H XXXX XXXX	CCAP1H XXXX XXXX	CCAPL2H XXXX XXXX	CCAPL3H XXXX XXXX	CCAPL4H XXXX XXXX		FFh
F0h	B 0000 0000								F7h
E8h	P5 bit addressable 1111 1111	CL 0000 0000	CCAP0L XXXX XXXX	CCAP1L XXXX XXXX	CCAPL2L XXXX XXXX	CCAPL3L XXXX XXXX	CCAPL4L XXXX XXXX		EFh
E0h	ACC 0000 0000								E7h
D8h	CCON 00X0 0000	CMOD 00XX X000	CCAPM0 X000 0000	CCAPM1 X000 0000	CCAPM2 X000 0000	CCAPM3 X000 0000	CCAPM4 X000 0000		DFh
D0h	PSW 0000 0000								D7h
C8h	T2CON 0000 0000	T2MOD XXXX XX00	RCAP2L 0000 0000	RCAP2H 0000 0000	TL2 0000 0000	TH2 0000 0000			CFh
C0h	P4 bit addressable 1111 1111							P5 byte addressable 1111 1111	C7h
B8h	IP X000 000	SADEN 0000 0000							BFh
B0h	P3 1111 1111							IPH X000 0000	B7h
A8h	IE 0000 0000	SADDR 0000 0000							AFh
A0h	P2 1111 1111		AUXR1 XXXX0XX0				WDTRST XXXX XXXX	WDTPRG XXXX X000	A7h
98h	SCON 0000 0000	SBUF XXXX XXXX							9Fh
90h	P1 1111 1111								97h
88h	TCON 0000 0000	TMOD 0000 0000	TL0 0000 0000	TL1 0000 0000	TH0 0000 0000	TH1 0000 0000	AUXR XXXXXXXX00	CKCON XXXX XXX0	8Fh
80h	P0 1111 1111	SP 0000 0111	DPL 0000 0000	DPH 0000 0000				PCON 00X1 0000	87h
	0/8	1/9	2/A	3/B	4/C	5/D	6/E	7/F	

reserved

## 5. Pin Configuration



\*NIC: No Internal Connection

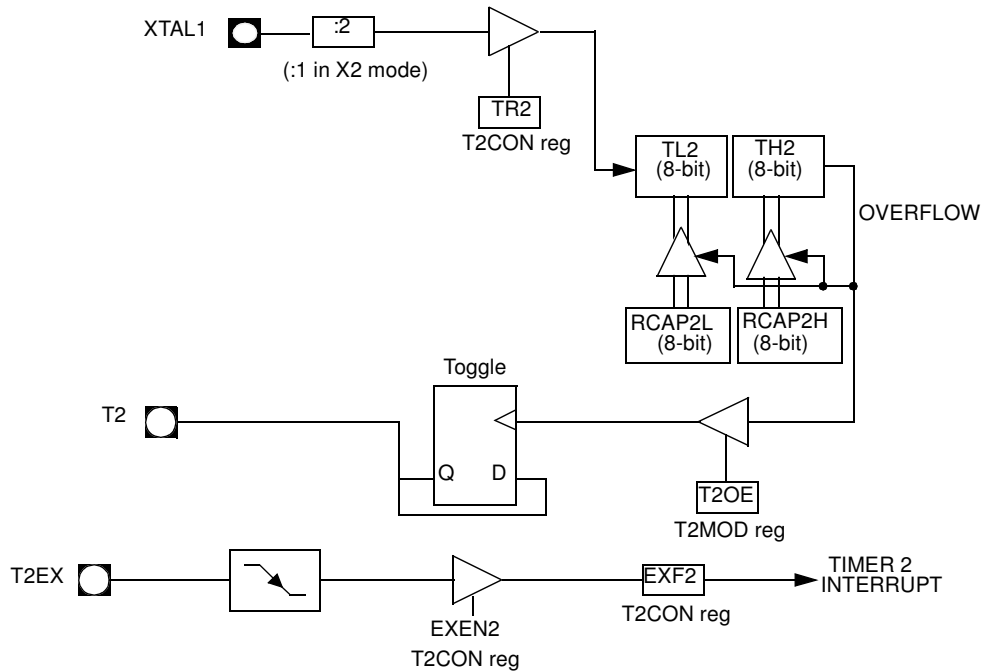


NIC: No Internal Connection

PSEN	67	55
$\overline{EA}/VPP$	2	58
XTAL1	49	38
XTAL2	48	37
P4.0	20	11
P4.1	24	15
P4.2	26	17
P4.3	44	33
P4.4	46	35
P4.5	50	39
P4.6	53	42
P4.7	57	46
P5.0	60	49
P5.1	62	51
P5.2	63	52
P5.3	7	62
P5.4	8	63
P5.5	10	1
P5.6	13	4
P5.7	16	7

It is possible to use timer 2 as a baud rate generator and a clock generator simultaneously. For this configuration, the baud rates and clock frequencies are not independent since both functions use the values in the RCAP2H and RCAP2L registers.

**Figure 6-3.** Clock-Out Mode  $C/\overline{T2} = 0$



**Table 6-2.** T2CON Register  
T2CON - Timer 2 Control Register (C8h)

7	6	5	4	3	2	1	0
TF2	EXF2	RCLK	TCLK	EXEN2	TR2	C/T2#	CP/RL2#



Bit Number	Bit Mnemonic	Description
7	TF2	<b>Timer 2 overflow Flag</b> Must be cleared by software. Set by hardware on timer 2 overflow, if RCLK = 0 and TCLK = 0.
6	EXF2	<b>Timer 2 External Flag</b> Set when a capture or a reload is caused by a negative transition on T2EX pin if EXEN2=1. When set, causes the CPU to vector to timer 2 interrupt routine when timer 2 interrupt is enabled. Must be cleared by software. EXF2 doesn't cause an interrupt in Up/down counter mode (DCEN = 1)
5	RCLK	<b>Receive Clock bit</b> Clear to use timer 1 overflow as receive clock for serial port in mode 1 or 3. Set to use timer 2 overflow as receive clock for serial port in mode 1 or 3.
4	TCLK	<b>Transmit Clock bit</b> Clear to use timer 1 overflow as transmit clock for serial port in mode 1 or 3. Set to use timer 2 overflow as transmit clock for serial port in mode 1 or 3.
3	EXEN2	<b>Timer 2 External Enable bit</b> Clear to ignore events on T2EX pin for timer 2 operation. Set to cause a capture or reload when a negative transition on T2EX pin is detected, if timer 2 is not used to clock the serial port.
2	TR2	<b>Timer 2 Run control bit</b> Clear to turn off timer 2. Set to turn on timer 2.
1	C/T2#	<b>Timer/Counter 2 select bit</b> Clear for timer operation (input from internal clock system: F <sub>OSC</sub> ). Set for counter operation (input from T2 input pin, falling edge trigger). Must be 0 for clock out mode.
0	CP/RL2#	<b>Timer 2 Capture/Reload bit</b> If RCLK=1 or TCLK=1, CP/RL2# is ignored and timer is forced to auto-reload on timer 2 overflow. Clear to auto-reload on timer 2 overflows or negative transitions on T2EX pin if EXEN2=1. Set to capture on negative transitions on T2EX pin if EXEN2=1.

Reset Value = 0000 0000b

Bit addressable

**Table 6-3.** T2MOD Register  
T2MOD - Timer 2 Mode Control Register (C9h)

7	6	5	4	3	2	1	0
-	-	-	-	-	-	T2OE	DCEN

## 6.3 Programmable Counter Array PCA

The PCA provides more timing capabilities with less CPU intervention than the standard timer/counters. Its advantages include reduced software overhead and improved accuracy. The PCA consists of a dedicated timer/counter which serves as the time base for an array of five compare/capture modules. Its clock input can be programmed to count any one of the following signals:

- Oscillator frequency  $\div 12$  ( $\div 6$  in X2 mode)
- Oscillator frequency  $\div 4$  ( $\div 2$  in X2 mode)
- Timer 0 overflow
- External input on ECI (P1.2)

Each compare/capture modules can be programmed in any one of the following modes:

- rising and/or falling edge capture,
- software timer,
- high-speed output, or
- pulse width modulator.

Module 4 can also be programmed as a watchdog timer (See Section "PCA Watchdog Timer", page 33).

When the compare/capture modules are programmed in the capture mode, software timer, or high speed output mode, an interrupt can be generated when the module executes its function. All five modules plus the PCA timer overflow share one interrupt vector.

The PCA timer/counter and compare/capture modules share Port 1 for external I/O. These pins are listed below. If the port is not used for the PCA, it can still be used for standard I/O.

PCA component	External I/O Pin
16-bit Counter	P1.2 / ECI
16-bit Module 0	P1.3 / CEX0
16-bit Module 1	P1.4 / CEX1
16-bit Module 2	P1.5 / CEX2
16-bit Module 3	P1.6 / CEX3
16-bit Module 4	P1.7 / CEX4

**The PCA timer** is a common time base for all five modules (See Figure 6-4). The timer count source is determined from the CPS1 and CPS0 bits in the **CMOD SFR** (See Table 6-4) and can be programmed to run at:

- 1/12 the oscillator frequency. (Or 1/6 in X2 Mode)
- 1/4 the oscillator frequency. (Or 1/2 in X2 Mode)
- The Timer 0 overflow
- The input on the ECI pin (P1.2)

Figure 6-4. PCA Timer/Counter

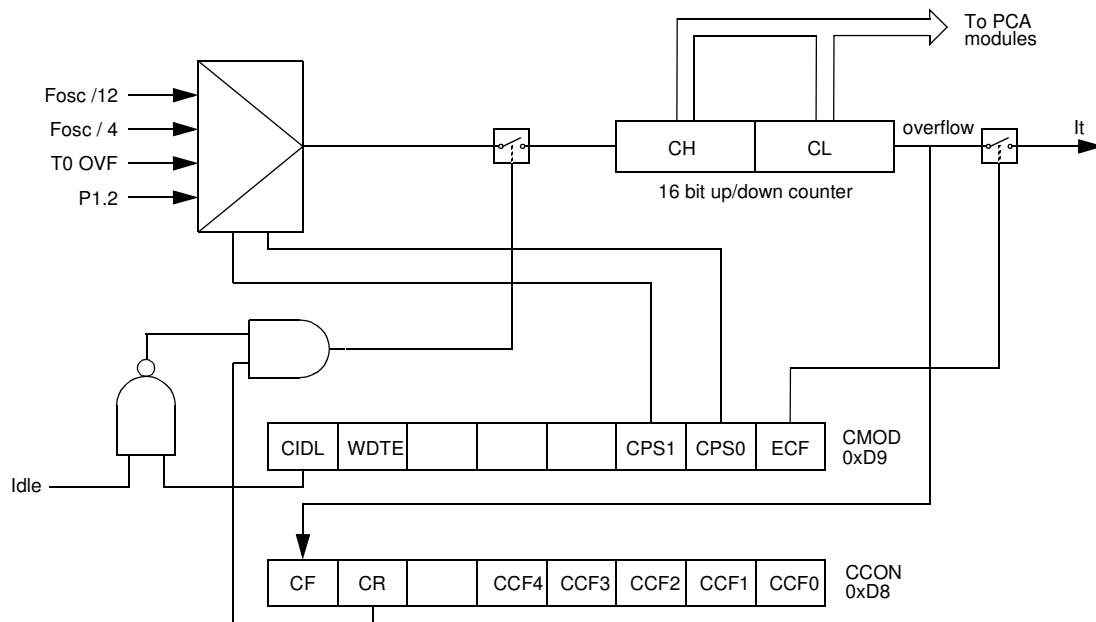


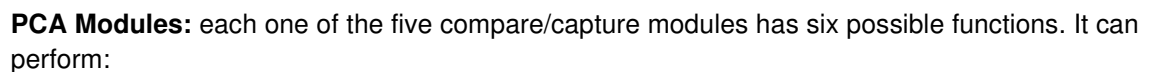
Table 6-4. CMOD: PCA Counter Mode Register

CMOD									
Address 0D9H		CIDL	WDTE	-	-	-	CPS1	CPS0	ECF
Reset value		0	0	X	X	X	0	0	0

Symbol	Function		
CIDL	Counter Idle control: CIDL = 0 programs the PCA Counter to continue functioning during idle Mode. CIDL = 1 programs it to be gated off during idle.		
WDTE	Watchdog Timer Enable: WDTE = 0 disables Watchdog Timer function on PCA Module 4. WDTE = 1 enables it.		
-	Not implemented, reserved for future use. <sup>(1)</sup>		
CPS1	PCA Count Pulse Select bit 1.		
CPS0	PCA Count Pulse Select bit 0.		
	CPS1	CPS0	Selected PCA input. <sup>(2)</sup>
	0	0	Internal clock $f_{osc}/12$ ( Or $f_{osc}/6$ in X2 Mode).
	0	1	Internal clock $f_{osc}/4$ ( Or $f_{osc}/2$ in X2 Mode).
	1	0	Timer 0 Overflow
	1	1	External clock at ECI/P1.2 pin (max rate = $f_{osc}/8$ )
ECF	PCA Enable Counter Overflow interrupt: ECF = 1 enables CF bit in CCON to generate an interrupt. ECF = 0 disables that function of CF.		

1. User software should not write 1s to reserved bits. These bits may be used in future 8051 family products to invoke new features. In that case, the reset or inactive value of the new bit will be 0, and its active value will be 1. The value read from a reserved bit is indeterminate.
2.  $f_{osc}$  = oscillator frequency

The CMOD SFR includes three additional bits associated with the PCA (See Figure 6-4 and Table 6-4).

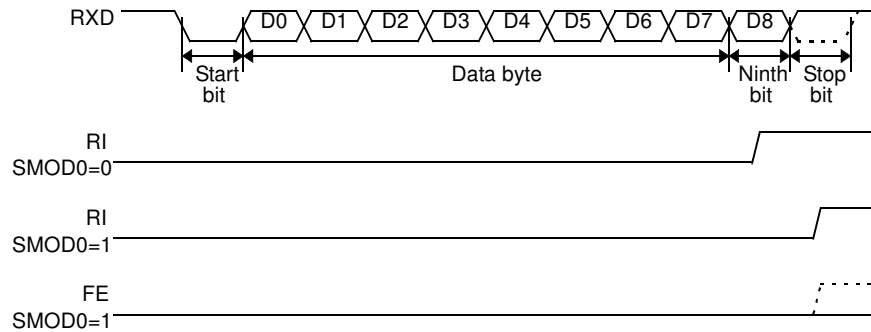


- In addition, module 4 can be used as a Watchdog Timer.

Each module in the PCA has a special function register associated with it. These registers are: CCAPM0 for module 0, CCAPM1 for module 1, etc. (See Table 6-6). The registers contain the bits that control the mode that each module will operate in.

- 4188F-8051-01/08

**Figure 6-12.** UART Timings in Modes 2 and 3



### 6.4.2 Automatic Address Recognition

The automatic address recognition feature is enabled when the multiprocessor communication feature is enabled (SM2 bit in SCON register is set).

Implemented in hardware, automatic address recognition enhances the multiprocessor communication feature by allowing the serial port to examine the address of each incoming command frame. Only when the serial port recognizes its own address, the receiver sets RI bit in SCON register to generate an interrupt. This ensures that the CPU is not interrupted by command frames addressed to other devices.

If desired, you may enable the automatic address recognition feature in mode 1. In this configuration, the stop bit takes the place of the ninth data bit. Bit RI is set only when the received command frame address matches the device's address and is terminated by a valid stop bit.

To support automatic address recognition, a device is identified by a given address and a broadcast address.

**Note:** The multiprocessor communication and automatic address recognition features cannot be enabled in mode 0 (i.e. setting SM2 bit in SCON register in mode 0 has no effect).

### 6.4.3 Given Address

Each device has an individual address that is specified in SADDR register; the SADEN register is a mask byte that contains don't-care bits (defined by zeros) to form the device's given address. The don't-care bits provide the flexibility to address one or more slaves at a time. The following example illustrates how a given address is formed.

To address a device by its individual address, the SADEN mask byte must be 1111 1111b.

For example:

```
SADDR0101 0110b
SADEN1111 1100b
Given0101 01XXb
```

The following is an example of how to use given addresses to address different slaves:

```
Slave A:SADDR1111 0001b
SADEN1111 1010b
Given1111 0X0Xb
```

```
Slave B:SADDR1111 0011b
SADEN1111 1001b
Given1111 0XX1b
```

**Table 6-19.** IPH Register  
IPH - Interrupt Priority High Register (B7h)

7	6	5	4	3	2	1	0
-	PPCH	PT2H	PSH	PT1H	PX1H	PT0H	PX0H
Bit Number	Bit Mnemonic	Description					
7	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.					
6	PPCH	PCA interrupt priority bit high. <u>PPCH</u> <u>PPC</u> <u>Priority Level</u> 0 0 Lowest 0 1 1 0 1 1 Highest					
5	PT2H	Timer 2 overflow interrupt Priority High bit <u>PT2H</u> <u>PT2</u> <u>Priority Level</u> 0 0 Lowest 0 1 1 0 1 1 Highest					
4	PSH	Serial port Priority High bit <u>PSH</u> <u>PS</u> <u>Priority Level</u> 0 0 Lowest 0 1 1 0 1 1 Highest					
3	PT1H	Timer 1 overflow interrupt Priority High bit <u>PT1H</u> <u>PT1</u> <u>Priority Level</u> 0 0 Lowest 0 1 1 0 1 1 Highest					
2	PX1H	External interrupt 1 Priority High bit <u>PX1H</u> <u>PX1</u> <u>Priority Level</u> 0 0 Lowest 0 1 1 0 1 1 Highest					
1	PT0H	Timer 0 overflow interrupt Priority High bit <u>PT0H</u> <u>PT0</u> <u>Priority Level</u> 0 0 Lowest 0 1 1 0 1 1 Highest					
0	PX0H	External interrupt 0 Priority High bit <u>PX0H</u> <u>PX0</u> <u>Priority Level</u> 0 0 Lowest 0 1 1 0 1 1 Highest					

Reset Value = X000 0000b

Not bit addressable

Bit Number	Bit Mnemonic	Description																																				
7	T4	<b>Reserved</b> Do not try to set or clear this bit.																																				
6	T3																																					
5	T2																																					
4	T1																																					
3	T0																																					
2	S2	WDT Time-out select bit 2																																				
1	S1	WDT Time-out select bit 1																																				
0	S0	WDT Time-out select bit 0																																				
		<table><tr><td><u>S2</u></td><td><u>S1</u></td><td><u>S0</u></td><td><u>Selected Time-out</u></td></tr><tr><td>0</td><td>0</td><td>0</td><td><math>0(2^{14} - 1)</math> machine cycles, 16.3 ms @ 12 MHz</td></tr><tr><td>0</td><td>0</td><td>1</td><td><math>1(2^{15} - 1)</math> machine cycles, 32.7 ms @ 12 MHz</td></tr><tr><td>0</td><td>1</td><td>0</td><td><math>0(2^{16} - 1)</math> machine cycles, 65.5 ms @ 12 MHz</td></tr><tr><td>0</td><td>1</td><td>1</td><td><math>1(2^{17} - 1)</math> machine cycles, 131 ms @ 12 MHz</td></tr><tr><td>1</td><td>0</td><td>0</td><td><math>0(2^{18} - 1)</math> machine cycles, 262 ms @ 12 MHz</td></tr><tr><td>1</td><td>0</td><td>1</td><td><math>1(2^{19} - 1)</math> machine cycles, 542 ms @ 12 MHz</td></tr><tr><td>1</td><td>1</td><td>0</td><td><math>0(2^{20} - 1)</math> machine cycles, 1.05 s @ 12 MHz</td></tr><tr><td>1</td><td>1</td><td>1</td><td><math>1(2^{21} - 1)</math> machine cycles, 2.09 s @ 12 MHz</td></tr></table>	<u>S2</u>	<u>S1</u>	<u>S0</u>	<u>Selected Time-out</u>	0	0	0	$0(2^{14} - 1)$ machine cycles, 16.3 ms @ 12 MHz	0	0	1	$1(2^{15} - 1)$ machine cycles, 32.7 ms @ 12 MHz	0	1	0	$0(2^{16} - 1)$ machine cycles, 65.5 ms @ 12 MHz	0	1	1	$1(2^{17} - 1)$ machine cycles, 131 ms @ 12 MHz	1	0	0	$0(2^{18} - 1)$ machine cycles, 262 ms @ 12 MHz	1	0	1	$1(2^{19} - 1)$ machine cycles, 542 ms @ 12 MHz	1	1	0	$0(2^{20} - 1)$ machine cycles, 1.05 s @ 12 MHz	1	1	1	$1(2^{21} - 1)$ machine cycles, 2.09 s @ 12 MHz
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1	1	1	$1(2^{21} - 1)$ machine cycles, 2.09 s @ 12 MHz																																			

Reset value XXXX X000

### 6.8.2 WDT during Power-down and Idle

In Power-down mode the oscillator stops, which means the WDT also stops. While in Power-down mode the user does not need to service the WDT. There are 2 methods of exiting Power-down mode: by a hardware reset or via a level activated external interrupt which is enabled prior to entering Power-down mode. When Power-down is exited with hardware reset, servicing the WDT should occur as it normally should whenever the TS80C51Rx2 is reset. Exiting Power-down with an interrupt is significantly different. The interrupt is held low long enough for the oscillator to stabilize. When the interrupt is brought high, the interrupt is serviced. To prevent the WDT from resetting the device while the interrupt pin is held low, the WDT is not started until the interrupt is pulled high. It is suggested that the WDT be reset during the interrupt service routine.

To ensure that the WDT does not overflow within a few states of exiting of powerdown, it is best to reset the WDT just before entering powerdown.

In the Idle mode, the oscillator continues to run. To prevent the WDT from resetting the TS80C51Rx2 while in Idle mode, the user should always set up a timer that will periodically exit Idle, service the WDT, and re-enter Idle mode.

## 9. TS87C51RB2/RC2/RD2 EPROM

### 9.1 EPROM Structure

The TS87C51RB2/RC2/RD2 EPROM is divided in two different arrays:

- the code array:16/32/64 Kbytes.
- the encryption array:64 bytes.

In addition a third non programmable array is implemented:

- the signature array: 4 bytes.

### 9.2 EPROM Lock System

The program Lock system, when programmed, protects the on-chip program against software piracy.

#### 9.2.1 Encryption Array

Within the EPROM array are 64 bytes of encryption array that are initially unprogrammed (all FF's). Every time a byte is addressed during program verify, 6 address lines are used to select a byte of the encryption array. This byte is then exclusive-NOR'ed (XNOR) with the code byte, creating an encrypted verify byte. The algorithm, with the encryption array in the unprogrammed state, will return the code in its original, unmodified form.

When using the encryption array, one important factor needs to be considered. If a byte has the value FFh, verifying the byte will produce the encryption byte value. If a large block (>64 bytes) of code is left unprogrammed, a verification routine will display the content of the encryption array. For this reason all the unused code bytes should be programmed with random values. This will ensure program protection.

#### 9.2.2 Program Lock Bits

The three lock bits, when programmed according to Table 9-1.9.2.3, will provide different level of protection for the on-chip code and data.

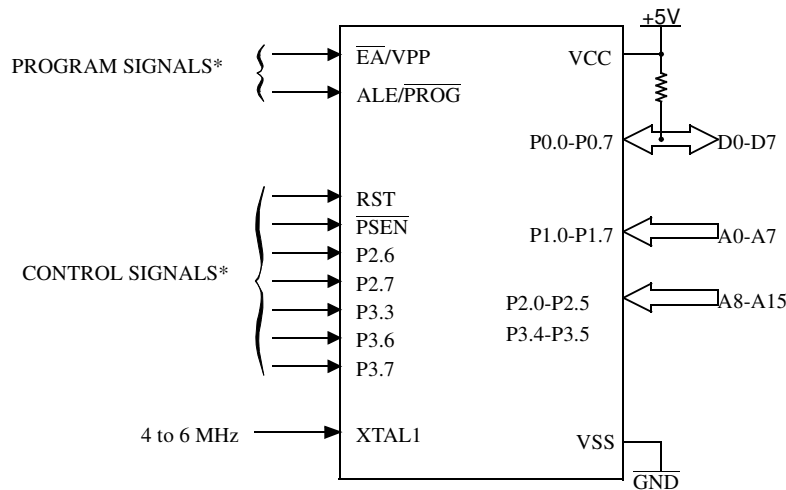
**Table 9-1.** Program Lock bits

Program Lock Bits				Protection Description
Security level	LB1	LB2	LB3	
1	U	U	U	No program lock features enabled. Code verify will still be encrypted by the encryption array if programmed. MOVC instruction executed from external program memory returns non encrypted data.
2	P	U	U	MOVC instruction executed from external program memory are disabled from fetching code bytes from internal memory, EA is sampled and latched on reset, and further programming of the EPROM is disabled.
3	U	P	U	Same as 2, also verify is disabled.
4	U	U	P	Same as 3, also external execution is disabled.

U: unprogrammed,  
P: programmed



**Figure 9-1.** Set-Up Modes Configuration



\* See Table 31, for proper value on these inputs

### 9.3.3 Programming Algorithm

The Improved Quick Pulse algorithm is based on the Quick Pulse algorithm and decreases the number of pulses applied during byte programming from 25 to 1.

To program the TS87C51RB2/RC2/RD2 the following sequence must be exercised:

- Step 1: Activate the combination of control signals.
- Step 2: Input the valid address on the address lines.
- Step 3: Input the appropriate data on the data lines.
- Step 4: Raise  $\overline{EA}/VPP$  from VCC to VPP (typical 12.75V).
- Step 5: Pulse ALE/ $\overline{PROG}$  once.
- Step 6: Lower  $\overline{EA}/VPP$  from VPP to VCC

Repeat step 2 through 6 changing the address and data for the entire array or until the end of the object file is reached (See [Figure 9-2](#)).

### 9.3.4 Verify algorithm

Code array verify must be done after each byte or block of bytes is programmed. In either case, a complete verify of the programmed array will ensure reliable programming of the TS87C51RB2/RC2/RD2.

P 2.7 is used to enable data output.

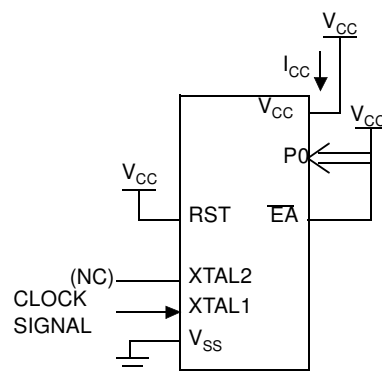
To verify the TS87C51RB2/RC2/RD2 code the following sequence must be exercised:

- Step 1: Activate the combination of program and control signals.
- Step 2: Input the valid address on the address lines.
- Step 3: Read data on the data lines.

Repeat step 2 through 3 changing the address for the entire array verification (See [Figure 9-2](#)).

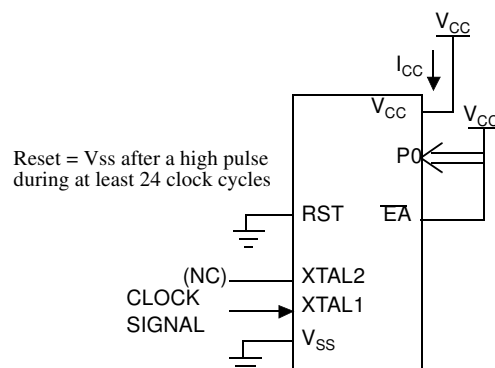
4. Capacitance loading on Ports 0 and 2 may cause spurious noise pulses to be superimposed on the  $V_{OL}$ s of ALE and Ports 1 and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins make 1 to 0 transitions during bus operation. In the worst cases (capacitive loading 100pF), the noise pulse on the ALE line may exceed 0.45V with maxi  $V_{OL}$  peak 0.6V. A Schmitt Trigger use is not necessary.
5. Typicals are based on a limited number of samples and are not guaranteed. The values listed are at room temperature and 5V.
6. Under steady state (non-transient) conditions,  $I_{OL}$  must be externally limited as follows:  
 Maximum  $I_{OL}$  per port pin: 10 mA  
 Maximum  $I_{OL}$  per 8-bit port:  
 Port 0: 26 mA  
 Ports 1, 2, 3 and 4 and 5 when available: 15 mA  
 Maximum total  $I_{OL}$  for all output pins: 71 mA  
 If  $I_{OL}$  exceeds the test condition,  $V_{OL}$  may exceed the related specification. Pins are not guaranteed to sink current greater than the listed test conditions.
7. For other values, please contact your sales office.
8. Operating  $I_{CC}$  is measured with all output pins disconnected; XTAL1 driven with  $T_{CLCH}$ ,  $T_{CHCL} = 5$  ns (see Figure 11-5.),  $V_{IL} = V_{SS} + 0.5$  V,  $V_{IH} = V_{CC} - 0.5$  V; XTAL2 N.C.;  $\overline{EA} = \text{Port 0} = V_{CC}$ ; RST =  $V_{SS}$ . The internal ROM runs the code 80 FE (label: SJMP label).  $I_{CC}$  would be slightly higher if a crystal oscillator is used. Measurements are made with OTP products when possible, which is the worst case.

**Figure 11-1.**  $I_{CC}$  Test Condition, under reset



All other pins are disconnected.

**Figure 11-2.** Operating  $I_{CC}$  Test Condition



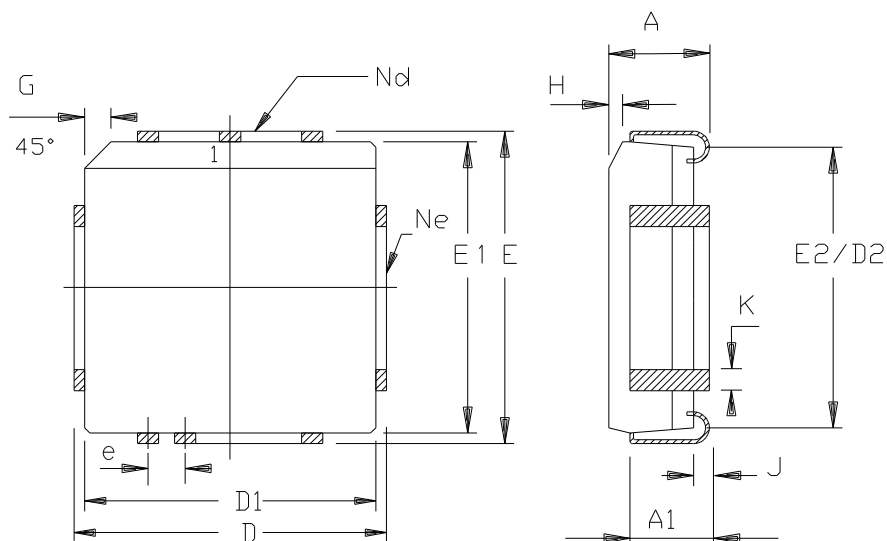
All other pins are disconnected.

Part Number	Memory size	Supply Voltage	Temperature Range	Max Frequency	Package	Packing
TS87C51RD2-MCA	OBSOLETE					
TS87C51RD2-MCB						
TS87C51RD2-MCE						
TS87C51RD2-MIA						
TS87C51RD2-MIB						
TS87C51RD2-MIE						
TS87C51RD2-LCA						
TS87C51RD2-LCB						
TS87C51RD2-LCE						
TS87C51RD2-LIA						
TS87C51RD2-LIB						
TS87C51RD2-LIE						
TS87C51RD2-VCA						
TS87C51RD2-VCB						
TS87C51RD2-VCE						
TS87C51RD2-VCL						
TS87C51RD2-VIA						
TS87C51RD2-VIB						
TS87C51RD2-VIE						
AT87C51RD2-3CSUM	OTP 64k Bytes	5V	Industrial & Green	40 MHz (20 MHz X2)	PDIL40	Stick
AT87C51RD2-SLSUM	OTP 64k Bytes	5V	Industrial & Green	40 MHz (20 MHz X2)	PLCC44	Stick
AT87C51RD2-RLTUM	OTP 64k Bytes	5V	Industrial & Green	40 MHz (20 MHz X2)	VQFP44	Tray
AT87C51RD2-3CSUL	OTP 64k Bytes	3-5V	Industrial & Green	30 MHz (20 MHz X2)	PDIL40	Stick
AT87C51RD2-SLSUL	OTP 64k Bytes	3-5V	Industrial & Green	30 MHz (20 MHz X2)	PLCC44	Stick
AT87C51RD2-RLTUL	OTP 64k Bytes	3-5V	Industrial & Green	30 MHz (20 MHz X2)	VQFP44	Tray

Part Number	Memory size	Supply Voltage	Temperature Range	Max Frequency	Package	Packing
TS83C51RC2-MCA	OBSOLETE					
TS83C51RC2-MCB						
TS83C51RC2-MCE						
TS83C51RC2-MIA						
TS83C51RC2-MIB						
TS83C51RC2-MIE						
TS83C51RC2-LCA						
TS83C51RC2-LCB						
TS83C51RC2-LCE						
TS83C51RC2-LIA						
TS83C51RC2-LIB						
TS83C51RC2-LIE						
TS83C51RC2-VCA						
TS83C51RC2-VCB						
TS83C51RC2-VCE						
TS83C51RC2-VIA						
TS83C51RC2-VIB						
TS83C51RC2-VIE						
AT83C51RC2-3CSUM	ROM 32k Bytes	5V	Industrial & Green	40 MHz (20 MHz X2)	PDIL40	Stick
AT83C51RC2-SLSUM	ROM 32k Bytes	5V	Industrial & Green	40 MHz (20 MHz X2)	PLCC44	Stick
AT83C51RC2-RLTUM	ROM 32k Bytes	5V	Industrial & Green	40 MHz (20 MHz X2)	VQFP44	Tray
AT83C51RC2-3CSUL	ROM 32k Bytes	3-5V	Industrial & Green	30 MHz (20 MHz X2)	PDIL40	Stick
AT83C51RC2-SLSUL	ROM 32k Bytes	3-5V	Industrial & Green	30 MHz (20 MHz X2)	PLCC44	Stick
AT83C51RC2-RLTUL	ROM 32k Bytes	3-5V	Industrial & Green	30 MHz (20 MHz X2)	VQFP44	Tray

## 13.5 PLCC68

68 PINS PLCC



	MM		INCH	
A	4. 20	5. 08	. 165	. 200
A1	2. 29	3. 30	. 090	. 130
D	25. 02	25. 27	. 985	. 995
D1	24. 13	24. 33	. 950	. 958
D2	22. 61	23. 62	. 890	. 930
E	25. 02	25. 27	. 985	. 995
E1	24. 13	24. 33	. 950	. 958
E2	22. 61	23. 62	. 890	. 930
e	1. 27	BSC	. 050	BSC
G	1. 07	1. 22	. 042	. 048
H	1. 07	1. 42	. 042	. 056
J	0. 51	-	. 020	-
K	0. 33	0. 53	. 013	. 021
Nd	17		17	
Ne	17		17	
PKG STD		00		

## 14. Datasheet Revision History

### 14.1 Changes from 4188E to 4188F

1. Removed TS80C51RD2 and AT80C51RD2 from “Ordering Information” on page 73.
2. Removed non-green part numbers from ordering information.