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### What is "[Embedded - Microcontrollers](#)"?

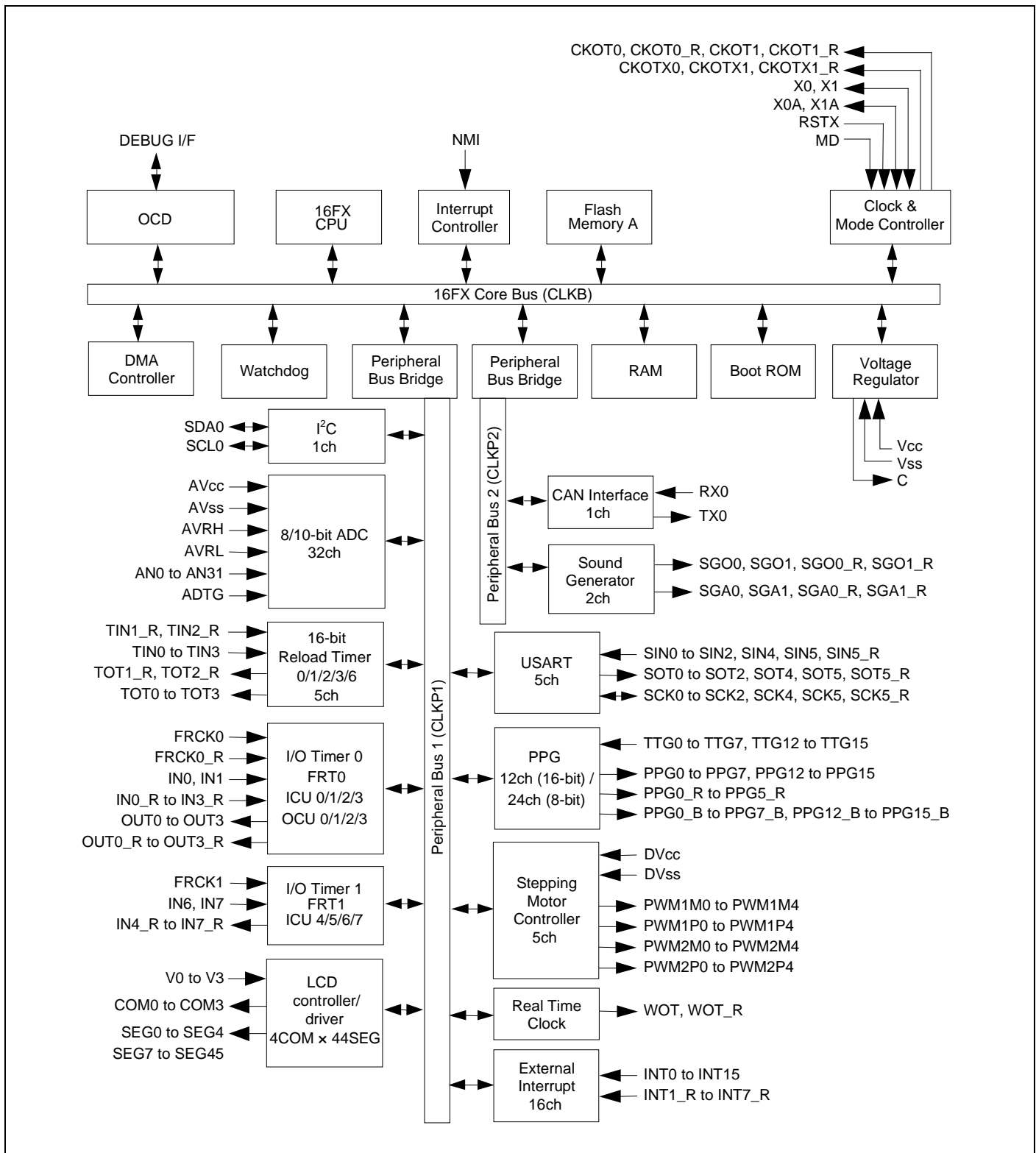
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

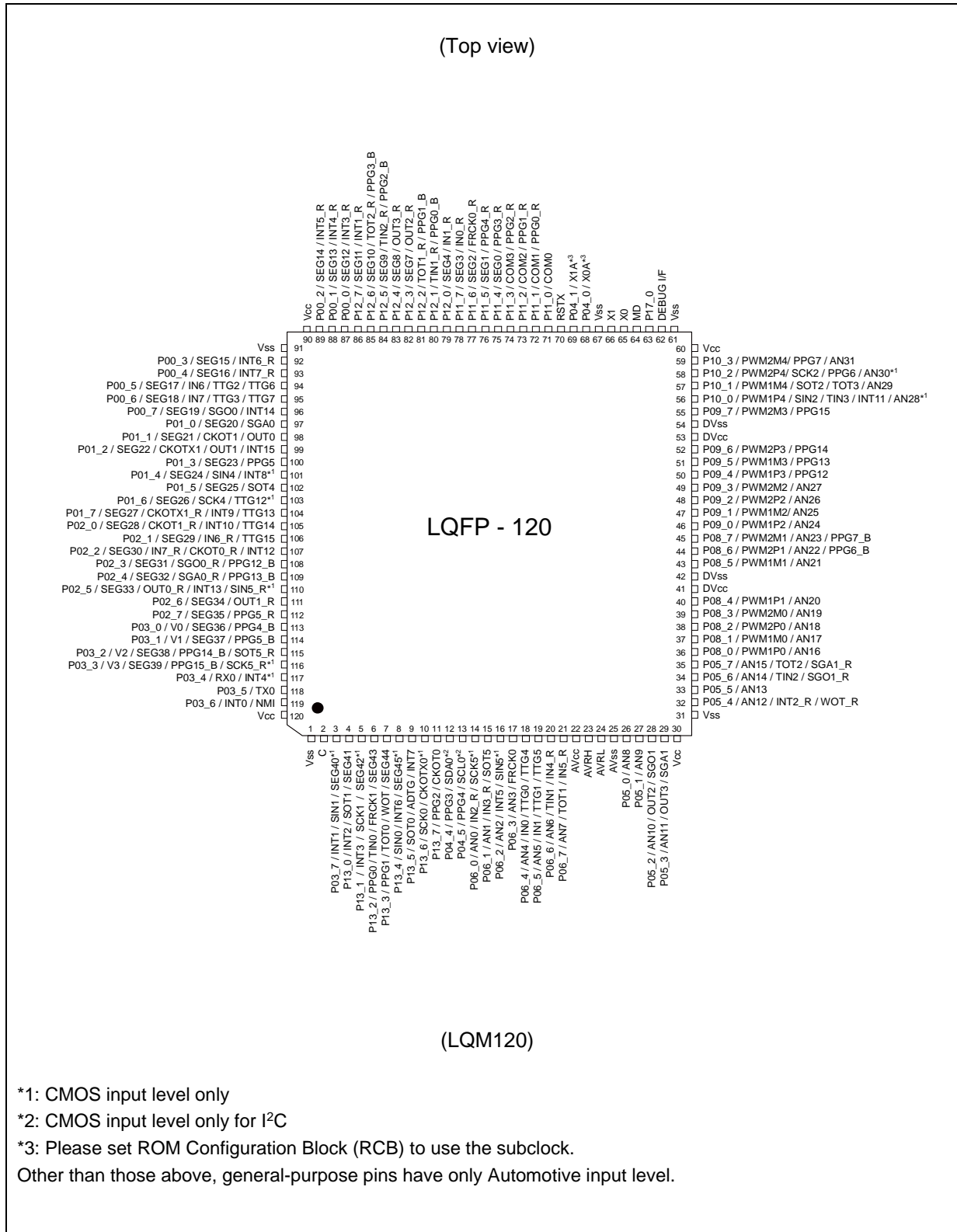
#### Details

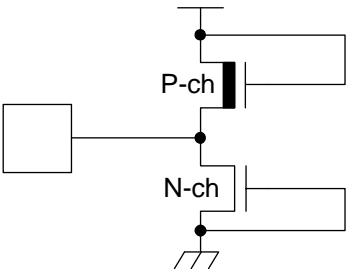
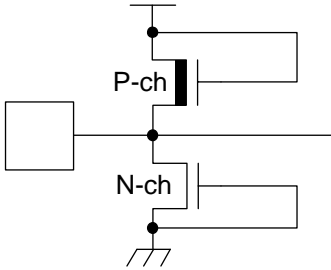
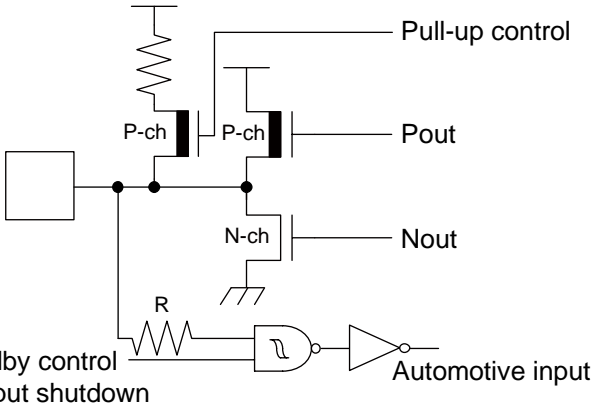
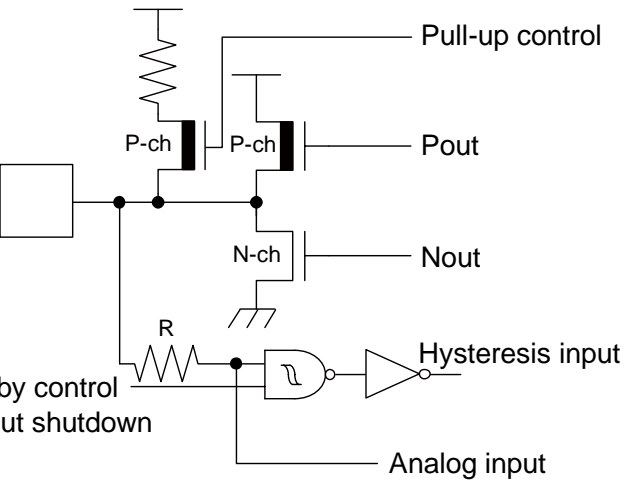
Product Status	Obsolete
Core Processor	F <sup>2</sup> MC-16FX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, I <sup>2</sup> C, LINbus, SCI, UART/USART
Peripherals	DMA, LCD, LVD, POR, PWM, WDT
Number of I/O	97
Program Memory Size	288KB (288K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 32x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	120-LQFP
Supplier Device Package	120-LQFP (16x16)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/mb96f6a6rbpmc-gse2">https://www.e-xfl.com/product-detail/infineon-technologies/mb96f6a6rbpmc-gse2</a>

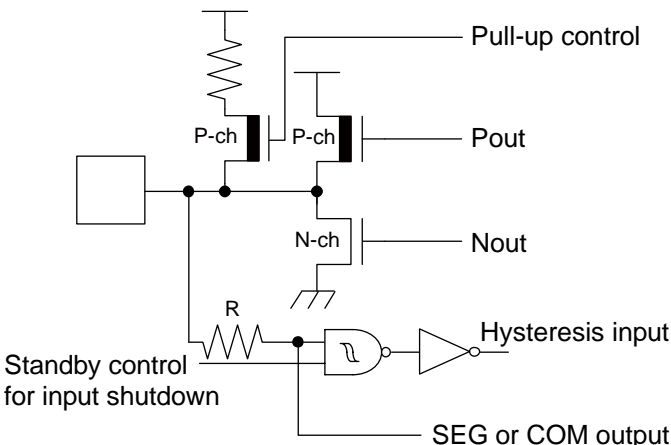
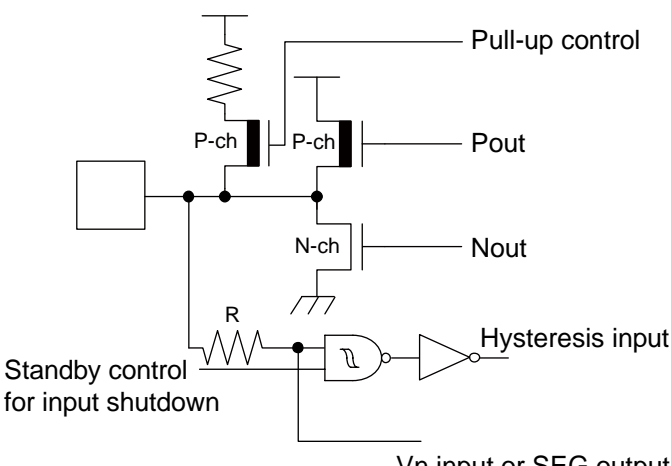
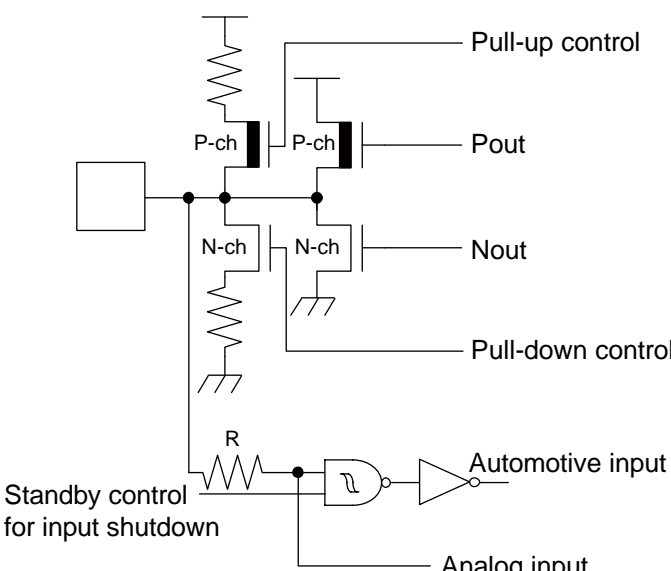
## 2. Block Diagram



### 3. Pin Assignment



Type	Circuit	Remarks
F		Power supply input protection circuit
G		<ul style="list-style-type: none"> <li>■ A/D converter ref+ (AVRH)/ ref- (AVRL) power supply input pin with protection circuit</li> <li>■ Without protection circuit against <math>V_{CC}</math> for pins AVRH/AVRL</li> </ul>
H		<ul style="list-style-type: none"> <li>■ CMOS level output (<math>I_{OL} = 4mA</math>, <math>I_{OH} = -4mA</math>)</li> <li>■ Automotive input with input shutdown function</li> <li>■ Programmable pull-up resistor</li> </ul>
I		<ul style="list-style-type: none"> <li>■ CMOS level output (<math>I_{OL} = 4mA</math>, <math>I_{OH} = -4mA</math>)</li> <li>■ CMOS hysteresis input with input shutdown function</li> <li>■ Programmable pull-up resistor</li> <li>■ Analog input</li> </ul>

Type	Circuit	Remarks
P		<ul style="list-style-type: none"> <li>■ CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>)</li> <li>■ CMOS hysteresis inputs with input shutdown function</li> <li>■ Programmable pull-up resistor</li> <li>■ SEG or COM output</li> </ul>
Q		<ul style="list-style-type: none"> <li>■ CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>)</li> <li>■ CMOS hysteresis inputs with input shutdown function</li> <li>■ Programmable pull-up resistor</li> <li>■ Vn input or SEG output</li> </ul>
R		<ul style="list-style-type: none"> <li>■ CMOS level output (programmable <math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math> and <math>I_{OL} = 30\text{mA}</math>, <math>I_{OH} = -30\text{mA}</math>)</li> <li>■ Automotive input with input shutdown function</li> <li>■ Programmable pull-up / pull-down resistor</li> <li>■ Analog input</li> </ul>

## 11. Interrupt Vector Table

Vector Number	Offset in Vector Table	Vector Name	Cleared by DMA	Index in ICR to Program	Description
0	3FC <sub>H</sub>	CALLV0	No	-	CALLV instruction
1	3F8 <sub>H</sub>	CALLV1	No	-	CALLV instruction
2	3F4 <sub>H</sub>	CALLV2	No	-	CALLV instruction
3	3F0 <sub>H</sub>	CALLV3	No	-	CALLV instruction
4	3EC <sub>H</sub>	CALLV4	No	-	CALLV instruction
5	3E8 <sub>H</sub>	CALLV5	No	-	CALLV instruction
6	3E4 <sub>H</sub>	CALLV6	No	-	CALLV instruction
7	3E0 <sub>H</sub>	CALLV7	No	-	CALLV instruction
8	3DC <sub>H</sub>	RESET	No	-	Reset vector
9	3D8 <sub>H</sub>	INT9	No	-	INT9 instruction
10	3D4 <sub>H</sub>	EXCEPTION	No	-	Undefined instruction execution
11	3D0 <sub>H</sub>	NMI	No	-	Non-Maskable Interrupt
12	3CC <sub>H</sub>	DLY	No	12	Delayed Interrupt
13	3C8 <sub>H</sub>	RC_TIMER	No	13	RC Clock Timer
14	3C4 <sub>H</sub>	MC_TIMER	No	14	Main Clock Timer
15	3C0 <sub>H</sub>	SC_TIMER	No	15	Sub Clock Timer
16	3BC <sub>H</sub>	LVDI	No	16	Low Voltage Detector
17	3B8 <sub>H</sub>	EXTINT0	Yes	17	External Interrupt 0
18	3B4 <sub>H</sub>	EXTINT1	Yes	18	External Interrupt 1
19	3B0 <sub>H</sub>	EXTINT2	Yes	19	External Interrupt 2
20	3AC <sub>H</sub>	EXTINT3	Yes	20	External Interrupt 3
21	3A8 <sub>H</sub>	EXTINT4	Yes	21	External Interrupt 4
22	3A4 <sub>H</sub>	EXTINT5	Yes	22	External Interrupt 5
23	3A0 <sub>H</sub>	EXTINT6	Yes	23	External Interrupt 6
24	39C <sub>H</sub>	EXTINT7	Yes	24	External Interrupt 7
25	398 <sub>H</sub>	EXTINT8	Yes	25	External Interrupt 8
26	394 <sub>H</sub>	EXTINT9	Yes	26	External Interrupt 9
27	390 <sub>H</sub>	EXTINT10	Yes	27	External Interrupt 10
28	38C <sub>H</sub>	EXTINT11	Yes	28	External Interrupt 11
29	388 <sub>H</sub>	EXTINT12	Yes	29	External Interrupt 12
30	384 <sub>H</sub>	EXTINT13	Yes	30	External Interrupt 13
31	380 <sub>H</sub>	EXTINT14	Yes	31	External Interrupt 14
32	37C <sub>H</sub>	EXTINT15	Yes	32	External Interrupt 15
33	378 <sub>H</sub>	CAN0	No	33	CAN Controller 0
34	374 <sub>H</sub>	-	-	34	Reserved
35	370 <sub>H</sub>	-	-	35	Reserved
36	36C <sub>H</sub>	-	-	36	Reserved
37	368 <sub>H</sub>	-	-	37	Reserved
38	364 <sub>H</sub>	PPG0	Yes	38	Programmable Pulse Generator 0
39	360 <sub>H</sub>	PPG1	Yes	39	Programmable Pulse Generator 1

Vector Number	Offset in Vector Table	Vector Name	Cleared by DMA	Index in ICR to Program	Description
116	22C <sub>H</sub>	-	-	116	Reserved
117	228 <sub>H</sub>	-	-	117	Reserved
118	224 <sub>H</sub>	-	-	118	Reserved
119	220 <sub>H</sub>	-	-	119	Reserved
120	21C <sub>H</sub>	-	-	120	Reserved
121	218 <sub>H</sub>	SG1	No	121	Sound Generator 1
122	214 <sub>H</sub>	-	-	122	Reserved
123	210 <sub>H</sub>	-	-	123	Reserved
124	20C <sub>H</sub>	-	-	124	Reserved
125	208 <sub>H</sub>	-	-	125	Reserved
126	204 <sub>H</sub>	-	-	126	Reserved
127	200 <sub>H</sub>	-	-	127	Reserved
128	1FC <sub>H</sub>	-	-	128	Reserved
129	1F8 <sub>H</sub>	-	-	129	Reserved
130	1F4 <sub>H</sub>	-	-	130	Reserved
131	1F0 <sub>H</sub>	-	-	131	Reserved
132	1EC <sub>H</sub>	-	-	132	Reserved
133	1E8 <sub>H</sub>	FLASHA	Yes	133	Flash memory A interrupt
134	1E4 <sub>H</sub>	-	-	134	Reserved
135	1E0 <sub>H</sub>	-	-	135	Reserved
136	1DC <sub>H</sub>	-	-	136	Reserved
137	1D8 <sub>H</sub>	-	-	137	Reserved
138	1D4 <sub>H</sub>	-	-	138	Reserved
139	1D0 <sub>H</sub>	ADCRC0	No	139	A/D Converter 0 - Range Comparator
140	1CC <sub>H</sub>	ADCPD0	No	140	A/D Converter 0 - Pulse detection
141	1C8 <sub>H</sub>	-	-	141	Reserved
142	1C4 <sub>H</sub>	-	-	142	Reserved
143	1C0 <sub>H</sub>	-	-	143	Reserved

**■ Static Electricity**

Because semiconductor devices are particularly susceptible to damage by static electricity, you must take the following precautions:

- (1) Maintain relative humidity in the working environment between 40% and 70%. Use of an apparatus for ion generation may be needed to remove electricity.
- (2) Electrically ground all conveyors, solder vessels, soldering irons and peripheral equipment.
- (3) Eliminate static body electricity by the use of rings or bracelets connected to ground through high resistance (on the level of 1 MΩ).  
Wearing of conductive clothing and shoes, use of conductive floor mats and other measures to minimize shock loads is recommended.
- (4) Ground all fixtures and instruments, or protect with anti-static measures.
- (5) Avoid the use of styrofoam or other highly static-prone materials for storage of completed board assemblies.

**12.3 Precautions for Use Environment**

Reliability of semiconductor devices depends on ambient temperature and other conditions as described above.

For reliable performance, do the following:

- (1) Humidity  
Prolonged use in high humidity can lead to leakage in devices as well as printed circuit boards. If high humidity levels are anticipated, consider anti-humidity processing.
- (2) Discharge of Static Electricity  
When high-voltage charges exist close to semiconductor devices, discharges can cause abnormal operation. In such cases, use anti-static measures or processing to prevent discharges.
- (3) Corrosive Gases, Dust, or Oil  
Exposure to corrosive gases or contact with dust or oil may lead to chemical reactions that will adversely affect the device. If you use devices in such conditions, consider ways to prevent such exposure or to protect the devices.
- (4) Radiation, Including Cosmic Radiation  
Most devices are not designed for environments involving exposure to radiation or cosmic radiation. Users should provide shielding as appropriate.
- (5) Smoke, Flame  
**CAUTION:** Plastic molded devices are flammable, and therefore should not be used near combustible substances. If devices begin to smoke or burn, there is danger of the release of toxic gases.

Customers considering the use of Cypress products in other special environmental conditions should consult with sales representatives.



Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current in Stop mode <sup>*3</sup>	I <sub>CCH</sub>	V <sub>CC</sub>	-	-	20	60	μA	T <sub>A</sub> = +25°C
				-	-	880	μA	T <sub>A</sub> = +105°C
Flash Power Down current	I <sub>CCFLASHPD</sub>		-	-	36	70	μA	
Power supply current for active Low Voltage detector <sup>*4</sup>	I <sub>CCLVD</sub>		Low voltage detector enabled	-	5	-	μA	T <sub>A</sub> = +25°C
				-	-	12.5	μA	T <sub>A</sub> = +105°C
Flash Write/ Erase current <sup>*5</sup>	I <sub>CCFLASH</sub>		-	-	12.5	-	mA	T <sub>A</sub> = +25°C
				-	-	20	mA	T <sub>A</sub> = +105°C

\*1: The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32kHz external clock connected to the Sub oscillator. See chapter "Standby mode and voltage regulator control circuit" of the Hardware Manual for further details about voltage regulator control. Current for "On Chip Debugger" part is not included. Power supply current in Run mode does not include Flash Write / Erase current.

\*2: The power supply current in Timer mode is the value when Flash is in Power-down / reset mode.  
 When Flash is not in Power-down / reset mode,  $I_{CCFLASHPD}$  must be added to the Power supply current.  
 The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32kHz external clock connected to the Sub oscillator. The current for "On Chip Debugger" part is not included.

\*3: The power supply current in Stop mode is the value when Flash is in Power-down / reset mode.  
 When Flash is not in Power-down / reset mode,  $I_{CCFLASHPD}$  must be added to the Power supply current.

\*4: When low voltage detector is enabled,  $I_{CCLVD}$  must be added to Power supply current.

\*5: When Flash Write / Erase program is executed,  $I_{CCFLASH}$  must be added to Power supply current.

**14.3.2 Pin Characteristics**
 $(V_{CC} = AV_{CC} = DV_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = AV_{SS} = DV_{SS} = 0V, T_A = -40^{\circ}C \text{ to } +105^{\circ}C)$ 

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
"H" level input voltage	$V_{IH}$	Port inputs Pnn_m	-	$V_{CC} \times 0.7$	-	$V_{CC} + 0.3$	V	CMOS Hysteresis input
			-	$V_{CC} \times 0.8$	-	$V_{CC} + 0.3$	V	AUTOMOTIVE Hysteresis input
	$V_{IHx0S}$	X0	External clock in "Fast Clock Input mode"	$VD \times 0.8$	-	VD	V	VD=1.8V±0.15V
	$V_{IHx0AS}$	X0A	External clock in "Oscillation mode"	$V_{CC} \times 0.8$	-	$V_{CC} + 0.3$	V	
	$V_{IHR}$	RSTX	-	$V_{CC} \times 0.8$	-	$V_{CC} + 0.3$	V	CMOS Hysteresis input
	$V_{IHM}$	MD	-	$V_{CC} - 0.3$	-	$V_{CC} + 0.3$	V	CMOS Hysteresis input
	$V_{IHD}$	DEBUG I/F	-	2.0	-	$V_{CC} + 0.3$	V	TTL Input
"L" level input voltage	$V_{IL}$	Port inputs Pnn_m	-	$V_{SS} - 0.3$	-	$V_{CC} \times 0.3$	V	CMOS Hysteresis input
			-	$V_{SS} - 0.3$	-	$V_{CC} \times 0.5$	V	AUTOMOTIVE Hysteresis input
	$V_{ILx0S}$	X0	External clock in "Fast Clock Input mode"	$V_{SS}$	-	$VD \times 0.2$	V	VD=1.8V±0.15V
	$V_{ILx0AS}$	X0A	External clock in "Oscillation mode"	$V_{SS} - 0.3$	-	$V_{CC} \times 0.2$	V	
	$V_{ILR}$	RSTX	-	$V_{SS} - 0.3$	-	$V_{CC} \times 0.2$	V	CMOS Hysteresis input
	$V_{ILM}$	MD	-	$V_{SS} - 0.3$	-	$V_{SS} + 0.3$	V	CMOS Hysteresis input
	$V_{ILD}$	DEBUG I/F	-	$V_{SS} - 0.3$	-	0.8	V	TTL Input

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input leak current	$I_{IL}$	Pnn_m	$V_{SS} < V_I < V_{CC}$ $AV_{SS}, AV_{RL} < V_I < AV_{CC}, AVR_H$	- 1	-	+ 1	$\mu A$	Single port pin except high current output I/O for SMC
		P08_m, P09_m, P10_m	$DV_{SS} < V_I < DV_{CC}$ $AV_{SS}, AV_{RL} < V_I < AV_{CC}, AVR_H$	- 3	-	+ 3	$\mu A$	
Total LCD leak current	$\Sigma  I_{LCD} $	All SEG/ COM pin	$V_{CC} = 5.0V$	-	0.5	10	$\mu A$	Maximum leakage current of all LCD pins
Internal LCD divide resistance	$R_{LCD}$	Between V3 and V2, V2 and V1, V1 and V0	$V_{CC} = 5.0V$	6.25	12.5	25	$k\Omega$	
Pull-up resistance value	$R_{PU}$	Pnn_m	$V_{CC} = 5.0V \pm 10\%$	25	50	100	$k\Omega$	
Pull-down resistance value	$R_{DOWN}$	P08_m, P09_m, P10_m	$V_{CC} = 5.0V \pm 10\%$	25	50	100	$k\Omega$	
Input capacitance	$C_{IN}$	Other than C, Vcc, Vss, DVcc, DVss, AVcc, AVss, AVRH, AVRL, P08_m, P09_m, P10_m	-	-	5	15	pF	
		P08_m, P09_m, P10_m	-	-	15	30	pF	

\*: In the case of driving stepping motor directly or high current outputs, set "1" to the bit in the Port High Drive Register (PHDRnn:HDx="1").

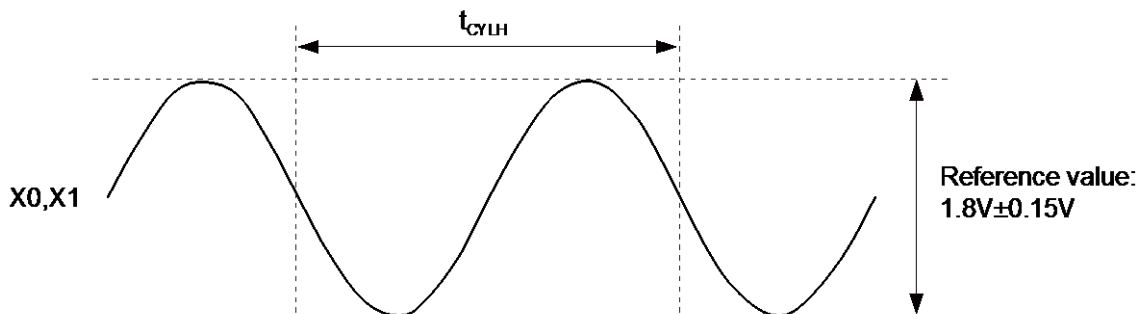
## 14.4 AC Characteristics

### 14.4.1 Main Clock Input Characteristics

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_D = 1.8V \pm 0.15V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^\circ C$  to  $+105^\circ C$ )

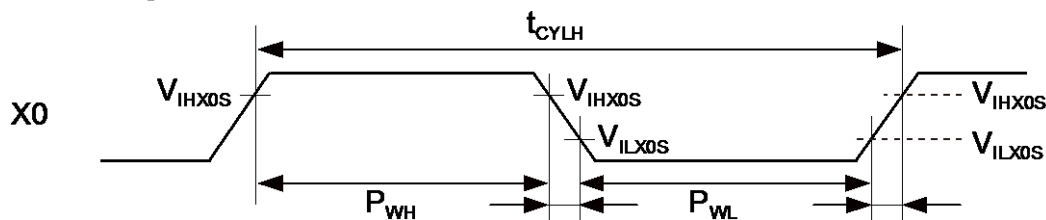
Parameter	Symbol	Pin Name	Value			Unit	Remarks
			Min	Typ	Max		
Input frequency	$f_c$	X0, X1	4	-	8	MHz	When using a crystal oscillator, PLL off
			-	-	8	MHz	When using an opposite phase external clock, PLL off
			4	-	8	MHz	When using a crystal oscillator or opposite phase external clock, PLL on
Input frequency	$f_{FCI}$	X0	-	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL off
			4	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL on
Input clock cycle	$t_{CYLH}$	-	125	-	-	ns	
Input clock pulse width	$P_{WH}, P_{WL}$	-	55	-	-	ns	

#### When using the crystal oscillator



The amplitude changes by resistance, capacity which added outside or the difference of the device.

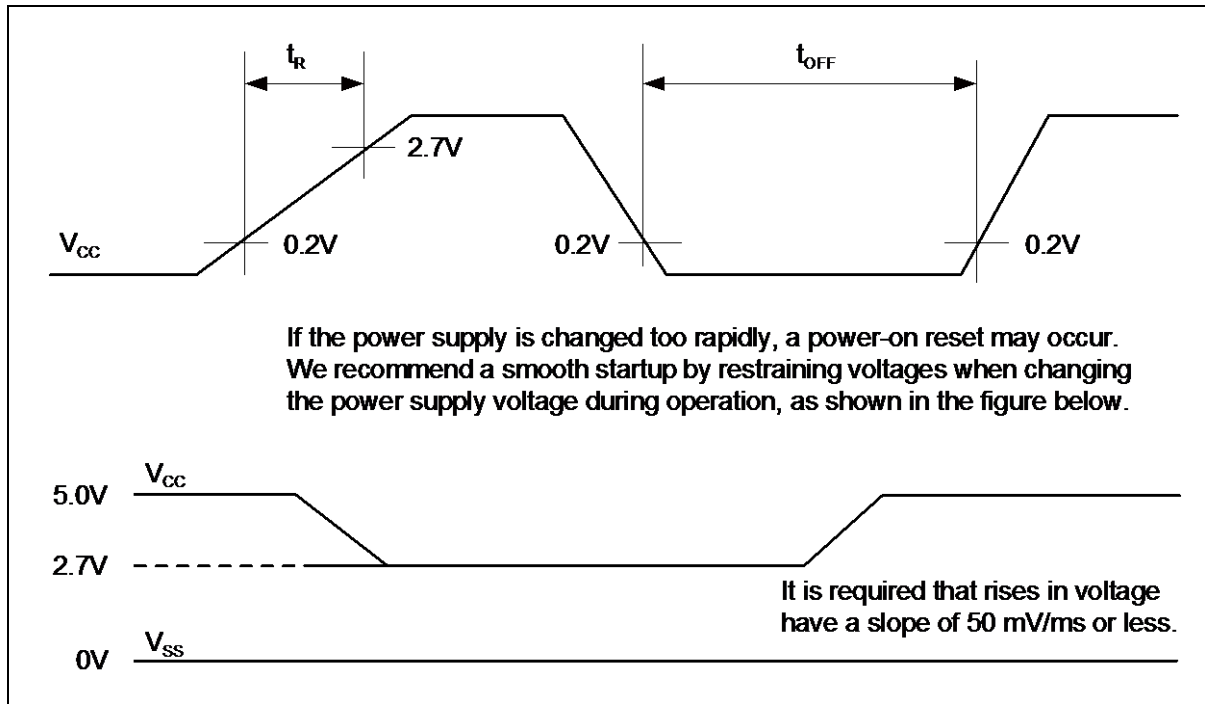
#### When using the external clock



#### 14.4.7 Power-on Reset Timing

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

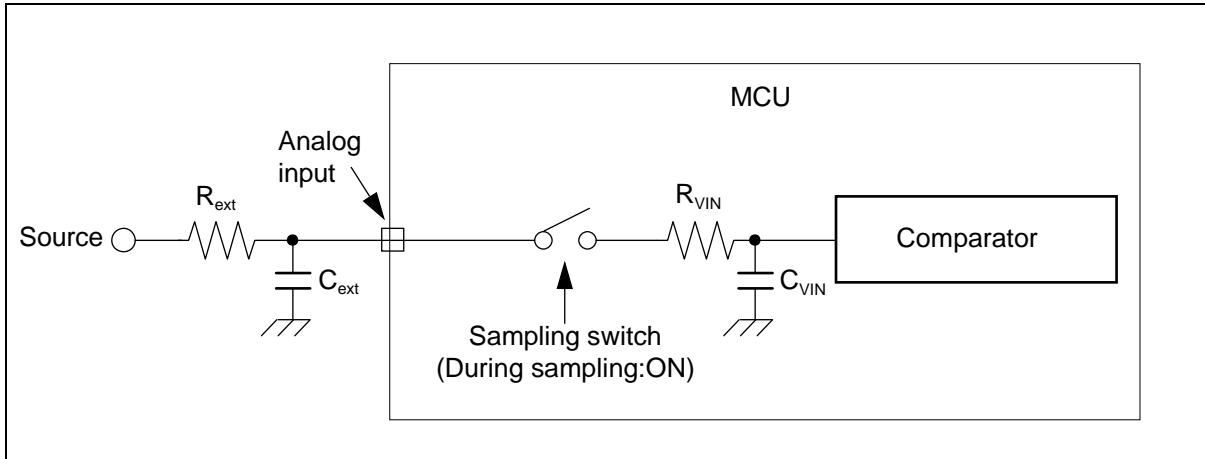
Parameter	Symbol	Pin Name	Value			Unit
			Min	Typ	Max	
Power on rise time	$t_R$	$V_{CC}$	0.05	-	30	ms
Power off time	$t_{OFF}$	$V_{CC}$	1	-	-	ms



#### 14.5.2 Accuracy and Setting of the A/D Converter Sampling Time

If the external impedance is too high or the sampling time too short, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting the A/D conversion precision.

To satisfy the A/D conversion precision, a sufficient sampling time must be selected. The required sampling time ( $T_{\text{samp}}$ ) depends on the external driving impedance  $R_{\text{ext}}$ , the board capacitance of the A/D converter input pin  $C_{\text{ext}}$  and the  $AV_{\text{CC}}$  voltage level. The following replacement model can be used for the calculation:



$R_{\text{ext}}$ : External driving impedance

$C_{\text{ext}}$ : Capacitance of PCB at A/D converter input

$C_{\text{VIN}}$ : Analog input capacity (I/O, analog switch and ADC are contained)

$R_{\text{VIN}}$ : Analog input impedance (I/O, analog switch and ADC are contained)

The following approximation formula for the replacement model above can be used:

$$T_{\text{samp}} = 7.62 \times (R_{\text{ext}} \times C_{\text{ext}} + (R_{\text{ext}} + R_{\text{VIN}}) \times C_{\text{VIN}})$$

■ Do not select a sampling time below the absolute minimum permitted value.

( $0.5\mu\text{s}$  for  $4.5\text{V} \leq AV_{\text{CC}} \leq 5.5\text{V}$ ,  $1.2\mu\text{s}$  for  $2.7\text{V} \leq AV_{\text{CC}} < 4.5\text{V}$ )

■ If the sampling time cannot be sufficient, connect a capacitor of about  $0.1\mu\text{F}$  to the analog input pin.

■ A big external driving impedance also adversely affects the A/D conversion precision due to the pin input leakage current  $I_{\text{IL}}$  (static current before the sampling switch) or the analog input leakage current  $I_{\text{AIN}}$  (total leakage current of pin input and comparator during sampling). The effect of the pin input leakage current  $I_{\text{IL}}$  cannot be compensated by an external capacitor.

■ The accuracy gets worse as  $|AV_{\text{RH}} - AV_{\text{RL}}|$  becomes smaller.

## 14.8 Flash Memory Write/Erase Characteristics

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

Parameter		Conditions	Value			Unit	Remarks
			Min	Typ	Max		
Sector erase time	Large Sector	-	-	1.6	7.5	s	Includes write time prior to internal erase.
	Small Sector	-	-	0.4	2.1	s	
	Security Sector	-	-	0.31	1.65	s	
Word (16-bit) write time		-	-	25	400	$\mu s$	Not including system-level overhead time.
Chip erase time		-	-	8.31	40.05	s	Includes write time prior to internal erase.

Note: While the Flash memory is written or erased, shutdown of the external power ( $V_{CC}$ ) is prohibited. In the application system where the external power ( $V_{CC}$ ) might be shut down while writing or erasing, be sure to turn the power off by using a low voltage detection function.

To put it concrete, change the external power in the range of change ratio of power supply voltage ( $-0.004V/\mu s$  to  $+0.004V/\mu s$ ) after the external power falls below the detection voltage ( $V_{DLX}$ )\*1.

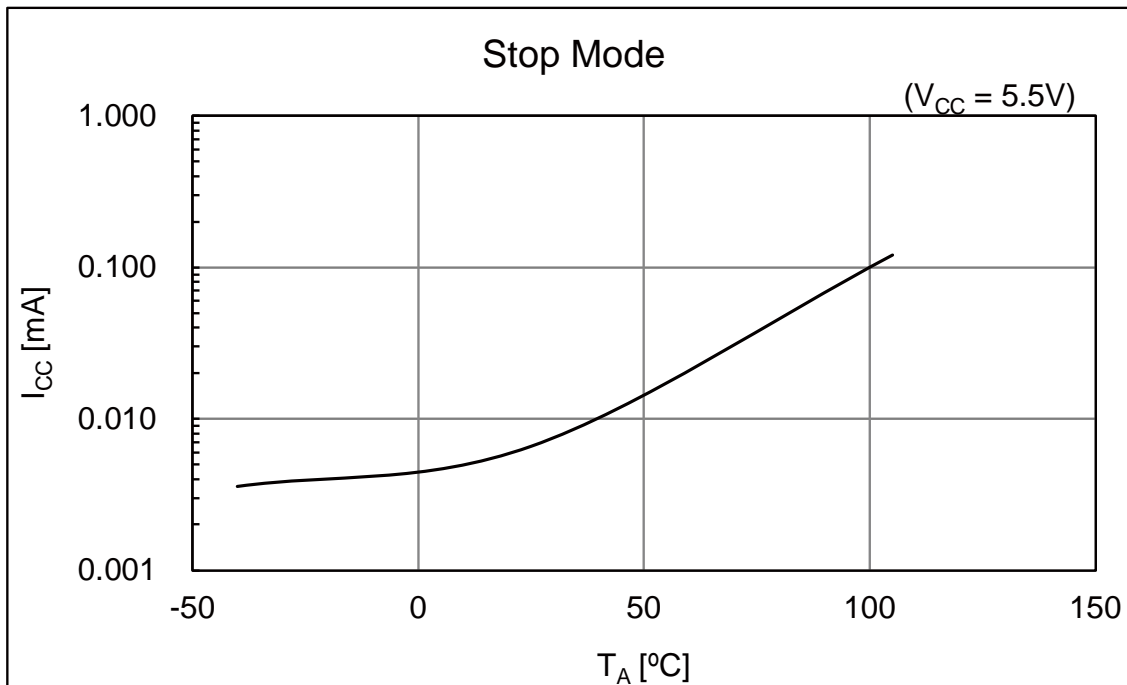
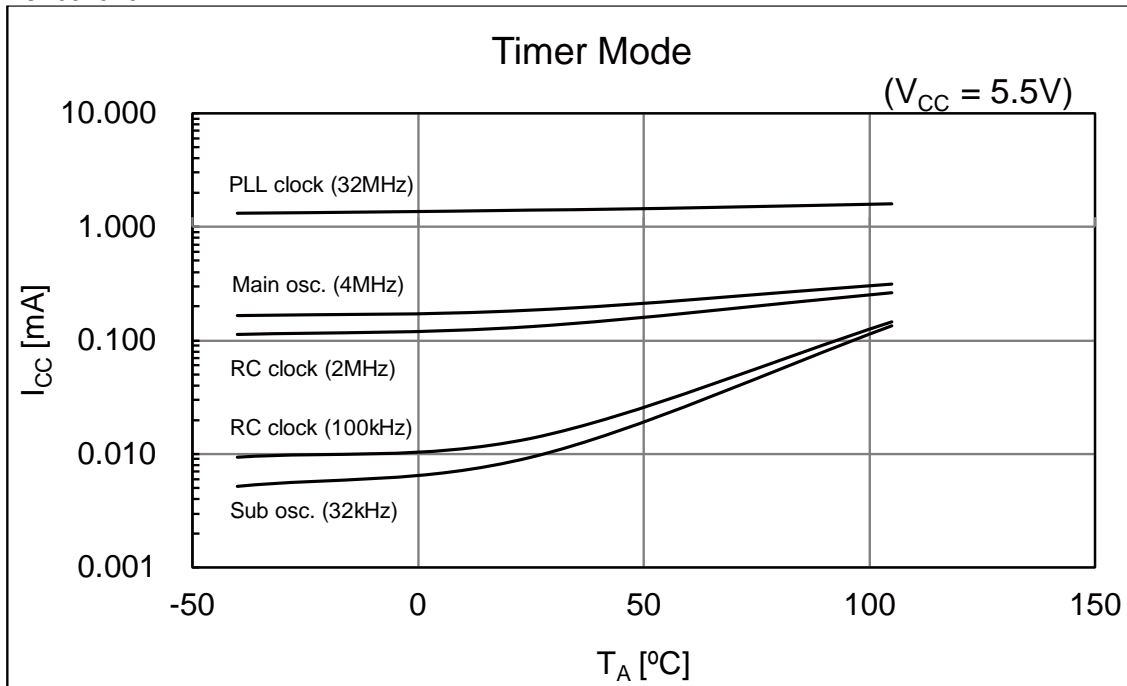
Write/Erase cycles and data hold time

Write/Erase Cycles (Cycle)	Data Hold Time (Year)
1,000	$20^{-2}$
10,000	$10^{-2}$
100,000	$5^{-2}$

\*1: See "14.7. Low Voltage Detection Function Characteristics".

\*2: This value comes from the technology qualification (using Arrhenius equation to translate high temperature measurements into normalized value at  $+85^{\circ}C$ ).

■ CY96F6A6





Page	Section	Change Results
		<p>Changed the annotation *4            Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the Power reset (except devices with persistent low voltage reset in internal vector mode).</p> <p>→            Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the Power reset.</p> <p>Added the annotation *4            The DEBUG I/F pin has only a protective diode against <math>V_{SS}</math>. Hence it is only permitted to input a negative clamping current (4mA). For protection against positive input voltages, use an external clamping diode which limits the input voltage to maximum 6.0V.</p>
39	Recommended Operating Conditions	<p>Added the Value and Remarks to "Power supply voltage"            Min: 2.0V            Typ: -            Max: 5.5V            Remarks: Maintains RAM data in stop mode</p> <p>Changed the Value of "Smoothing capacitor at C pin"            Typ: 1.0<math>\mu</math>F → 1.0<math>\mu</math>F to 3.9<math>\mu</math>F            Max: 1.5<math>\mu</math>F → 4.7<math>\mu</math>F</p> <p>Changed the Remarks of "Smoothing capacitor at C pin"            Deleted "(Target value)"            Added "3.9<math>\mu</math>F (Allowance within <math>\pm 20\%</math>)"</p>
40	DC Characteristics Current Rating	<p>Deleted "(Target value)"</p> <p>Added the Symbol to "Power supply current in Run modes"  <math>I_{CCRCH}</math>, <math>I_{CCRCL}</math></p> <p>Changed the Conditions of <math>I_{CCPLL}</math>, <math>I_{CCMAIN}</math>, <math>I_{CCSUB}</math> in "Power supply current in Run modes"            "Flash 0 wait" is added</p> <p>Changed the Value of "Power supply current in Run modes"  <math>I_{CCPLL}</math>            Typ: 28.5mA → 28mA (<math>T_A = +25^\circ\text{C}</math>)  <math>I_{CCMAIN}</math>            Typ: 5mA → 3.5mA (<math>T_A = +25^\circ\text{C}</math>)            Max: 10mA → 8mA (<math>T_A = +105^\circ\text{C}</math>)  <math>I_{CCSUB}</math>            Typ: 0.5mA → 0.1mA (<math>T_A = +25^\circ\text{C}</math>)            Max: 6mA → 3.3mA (<math>T_A = +105^\circ\text{C}</math>)</p>
41		<p>Added the Symbol to "Power supply current in Sleep modes"  <math>I_{CCSRCH}</math>, <math>I_{CCSRCL}</math></p> <p>Changed the Conditions of <math>I_{CCSMAIN}</math> in "Power supply current in Sleep modes"            "SMCR:LPMSS=0" is added</p> <p>Changed the Value of "Power supply current in Sleep modes"  <math>I_{CCSPLL}</math>            Typ: 10mA → 9.5mA (<math>T_A = +25^\circ\text{C}</math>)  <math>I_{CCSMAIN}</math>            Typ: 3mA → 1.1mA (<math>T_A = +25^\circ\text{C}</math>)            Max: 8mA → 4.7mA (<math>T_A = +105^\circ\text{C}</math>)  <math>I_{CCSSUB}</math>            Typ: 0.3mA → 0.04mA (<math>T_A = +25^\circ\text{C}</math>)            Max: 4.5mA → 2.7mA (<math>T_A = +105^\circ\text{C}</math>)</p> <p>Added the Symbol to "Power supply current in Timer modes"  <math>I_{CCTPLL}</math></p> <p>Changed the Conditions of <math>I_{CCTMAIN}</math>, <math>I_{CCTRCH}</math> in "Power supply current in Timer modes"            "SMCR:LPMSS=0" is added</p>

Page	Section	Change Results
41	DC Characteristics Current Rating	<p>Changed the Value of "Power supply current in Timer modes"</p> <p><math>I_{CCTMAIN}</math>            Max: 355<math>\mu</math>A <math>\rightarrow</math> 330<math>\mu</math>A (<math>T_A = +25^\circ\text{C}</math>)            Max: 1320<math>\mu</math>A <math>\rightarrow</math> 1200<math>\mu</math>A (<math>T_A = +105^\circ\text{C}</math>)</p> <p><math>I_{CCTRCH}</math>            Max: 245<math>\mu</math>A <math>\rightarrow</math> 215<math>\mu</math>A (<math>T_A = +25^\circ\text{C}</math>)            Max: 1230<math>\mu</math>A <math>\rightarrow</math> 1110<math>\mu</math>A (<math>T_A = +105^\circ\text{C}</math>)</p> <p><math>I_{CCTRCL}</math>            Max: 105<math>\mu</math>A <math>\rightarrow</math> 75<math>\mu</math>A (<math>T_A = +25^\circ\text{C}</math>)            Max: 1030<math>\mu</math>A <math>\rightarrow</math> 910<math>\mu</math>A (<math>T_A = +105^\circ\text{C}</math>)</p> <p><math>I_{CCTSUB}</math>            Typ: 90<math>\mu</math>A <math>\rightarrow</math> 65<math>\mu</math>A (<math>T_A = +25^\circ\text{C}</math>)            Max: 1000<math>\mu</math>A <math>\rightarrow</math> 885<math>\mu</math>A (<math>T_A = +105^\circ\text{C}</math>)</p>
42		<p>Changed the Value of "Power supply current in Stop modes"</p> <p><math>I_{CCH}</math>            Max: 90<math>\mu</math>A <math>\rightarrow</math> 60<math>\mu</math>A (<math>T_A = +25^\circ\text{C}</math>)            Max: 1000<math>\mu</math>A <math>\rightarrow</math> 880<math>\mu</math>A (<math>T_A = +105^\circ\text{C}</math>)</p> <p>Added the Symbol  <math>I_{CCFLASHPD}</math></p> <p>Changed the Value and condition of "Power supply current for active Low Voltage detector"</p> <p><math>I_{CCLVD}</math>            Typ: 5<math>\mu</math>A, Max: 15<math>\mu</math>A, Remarks: nothing  <math>\rightarrow</math>            Typ: 5<math>\mu</math>A, Max: -, Remarks: <math>T_A = +25^\circ\text{C}</math>            Typ: -, Max: 12.5<math>\mu</math>A, Remarks: <math>T_A = +105^\circ\text{C}</math></p> <p>Changed the condition of "Flash Write/Erase current"</p> <p><math>I_{CCFLASH}</math>            Typ: 12.5mA, Max: 20mA, Remarks: nothing  <math>\rightarrow</math>            Typ: 12.5mA, Max: -, Remarks: <math>T_A = +25^\circ\text{C}</math>            Typ: -, Max: 20mA, Remarks: <math>T_A = +105^\circ\text{C}</math></p> <p>Changed the annotation *2            The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32kHz external clock connected to the Sub oscillator.  <math>\rightarrow</math>            The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32kHz external clock connected to the Sub oscillator. The current for "On Chip Debugger" part is not included.</p>
44	DC Characteristics Pin Characteristics	<p>Added the Symbol for DEBUG I/F pin  <math>V_{OLD}</math></p>

Page	Section	Change Results
45	DC Characteristics Pin Characteristics	Changed the Pin name of "Input capacitance" Other than V <sub>CC</sub> , V <sub>SS</sub> , AV <sub>CC</sub> , AV <sub>SS</sub> , AV <sub>RH</sub> , AV <sub>RL</sub> , P08_m, P09_m, P10_m → Other than C, V <sub>CC</sub> , V <sub>SS</sub> , DV <sub>CC</sub> , DV <sub>SS</sub> , AV <sub>CC</sub> , AV <sub>SS</sub> , AV <sub>RH</sub> , AV <sub>RL</sub> , P08_m, P09_m, P10_m
		Deleted the annotation "I <sub>OH</sub> and I <sub>OL</sub> are target value."
		Added the annotation "In the case of driving stepping motor directly or high current outputs, set "1" to the bit in the Port High Drive Register (PHDRnn:HDx="1")."
46	AC Characteristics Main Clock Input Characteristics	Changed MAX frequency for f <sub>FCI</sub> in all conditions 16 → 8 Changed MIN frequency for t <sub>CY<sub>LH</sub></sub> 62.5 → 125 Changed MIN, MAX and Unit for P <sub>WH</sub> , P <sub>WL</sub> MIN: 30 → 55 MAX: 70 → - Unit: % → ns
		Added the figure (t <sub>CY<sub>LH</sub></sub> ) when using the external clock
47	AC Characteristics Sub Clock Input Characteristics	Added the figure (t <sub>CY<sub>LL</sub></sub> ) when using the crystal oscillator clock
48	AC Characteristics Built-in RC Oscillation Characteristics	Added "RC clock stabilization time"
49	AC Characteristics Operating Conditions of PLL	Changed the Value of "PLL input clock frequency" Max: 16MHz → 8MHz
		Changed the Symbol of "PLL oscillation clock frequency" f <sub>PLLO</sub> → f <sub>CLKVCO</sub>
		Added Remarks to "PLL oscillation clock frequency"
		Added " PLL phase jitter" and the figure
	AC Characteristics Reset Input	Added the figure for reset input time (t <sub>RSTL</sub> )
51	AC Characteristics USART Timing	Changed the condition (V <sub>CC</sub> = AV <sub>CC</sub> = DV <sub>CC</sub> = 2.7V to 5.5V, V <sub>SS</sub> = AV <sub>SS</sub> = DV <sub>SS</sub> = 0V, T <sub>A</sub> = -40°C to + 105°C) → (V <sub>CC</sub> = AV <sub>CC</sub> = DV <sub>CC</sub> = 2.7V to 5.5V, V <sub>SS</sub> = AV <sub>SS</sub> = DV <sub>SS</sub> = 0V, T <sub>A</sub> = -40°C to + 105°C, C <sub>L</sub> = 50pF)
		Changed the HARDWARE MANUAL "MB966A0 series HARDWARE MANUAL" → "MB96600 series HARDWARE MANUAL"
		Changed the figure for "Internal shift clock mode"
52		
54	AC Characteristics I <sup>2</sup> C timing	Added parameter, "Noise filter" and an annotation *5 for it
		Added t <sub>SP</sub> to the figure

Page	Section	Change Results
55	A/D Converter Electrical Characteristics for the A/D Converter	Added "Analog impedance"
		Added "Variation between channels"
		Added the annotation
56	A/D Converter Accuracy and Setting of the A/D Converter Sampling Time	Deleted the unit "[Min]" from approximation formula of Sampling time
57	A/D Converter Definition of A/D Converter Terms	Changed the Description and the figure "Linearity" → "Nonlinearity" "Differential linearity error" → "Differential nonlinearity error"
		Changed the Description Linearity error: Deviation of the line between the zero-transition point (0b0000000000 ←→ 0b0000000001) and the full-scale transition point (0b1111111110 ←→ 0b1111111111) from the actual conversion characteristics. → Nonlinearity error: Deviation of the actual conversion characteristics from a straight line that connects the zero transition point (0b0000000000 ←→ 0b0000000001) to the full-scale transition point (0b1111111110 ←→ 0b1111111111).
		Added the Description "Zero transition voltage" "Full scale transition voltage"
59	High Current Output Slew Rate	Changed the Symbol and figure $t_{R2}, t_{F2}, V_{OL2}$ → $t_{R30}, t_{F30}, V_{OL30}$
60	Low Voltage Detection Function Characteristics	Added the Value of " Power supply voltage change rate" Max: +0.004 V/μs
		Added "Hysteresis width" ( $V_{HYS}$ )
		Added "Stabilization time" ( $T_{LVDSTAB}$ )
		Added "Detection delay time" ( $t_d$ )
		Deleted the Remarks
61		Added the annotation *1, *2
		Added the figure for "Hysteresis width"
		Added the figure for "Stabilization time"
62	Flash Memory Write/Erase Characteristics	Changed the Value of "Sector erase time"
		Added "Security Sector" to "Sector erase time"
		Changed the Parameter "Half word (16 bit) write time" → "Word (16-bit) write time"
		Changed the Value of "Chip erase time"
		Changed the Remarks of "Sector erase time" Excludes write time prior to internal erase → Includes write time prior to internal erase
		Added the Note and annotation *1
		Deleted "(targeted value)" from title " Write/Erase cycles and data hold time"
63 to 65	Example Characteristics	Added a section
66	Ordering information	Changed part number MCU with CAN controller MB96F6A6RAPMC-GSE1* → MB96F6A6RBPMC-GSE1 MB96F6A6RAPMC-GSE2* → MB96F6A6RBPMC-GSE2

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