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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Not For New Designs
Core Processor	8052
Core Size	8-Bit
Speed	40MHz
Connectivity	EBI/EMI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	36
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1.25K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/nuvoton-technology-corporation-america/w78e365a40pl

4. PIN DESCRIPTION

SYMBOL	TYPE	DESCRIPTIONS
$\overline{EA}$	I	EXTERNAL ACCESS ENABLE: This pin forces the processor to execute the external ROM. The ROM address and data will not be presented on the bus if the $\overline{EA}$ pin is high.
$\overline{PSEN}$	O H	PROGRAM STORE ENABLE: $\overline{PSEN}$ enables the external ROM data in the Port 0 address/data bus. When internal ROM access is performed, no $\overline{PSEN}$ strobe signal outputs originate from this pin.
ALE	O H	ADDRESS LATCH ENABLE: ALE is used to enable the address latch that separates the address from the data on Port 0. ALE runs at 1/6th of the oscillator frequency.
RST	I L	RESET: A high on this pin for two machine cycles while the oscillator is running resets the device.
XTAL1	I	CRYSTAL 1: This is the crystal oscillator input. This pin may be driven by an external clock.
XTAL2	O	CRYSTAL 2: This is the crystal oscillator output. It is the inversion of XTAL1.
V_{SS}	I	GROUND: ground potential.
V_{DD}	I	POWER SUPPLY: Supply voltage for operation.
P0.0 – P0.7	I/O D	PORT 0: Function is the same as that of standard 8052. This port also provides a multiplexed low order address/data bus during accesses to external memory. Port 0 has internal pull-up resisters enabled by software.
P1.0 – P1.7	I/O H	PORT 1: Function is the same as that of standard 8052.
P2.0 – P2.7	I/O H	PORT 2: Port 2 is a bi-directional I/O port with internal pull-ups. This port also provides the upper address bits for accesses to external memory. The P2.6 and P2.7 also provide the alternate function $\overline{REBOOT}$ which is H/W reboot from LD flash.
P3.0 – P3.7	I/O H	PORT 3: Function is the same as that of the standard 8052.
P4.0 – P4.7	I/O H	PORT 4: A bi-directional I/O. The P4.3 also provides the alternate function $\overline{REBOOT}$ which is H/W reboot from LD flash.

*** Note: TYPE** I: input, O: output, I/O: bi-directional, H: pull-high, L: pull-low, D: open drain

6. FUNCTIONAL DESCRIPTION

The W78E365 architecture consists of a core controller surrounded by various registers, four general purpose I/O ports, one special purpose programmable 4-bits I/O port, 256+1K bytes of RAM, three timer/counters, a serial port. The processor supports 111 different opcodes and references both a 64K program address space and a 64K data storage space.

6.1 RAM

The internal data RAM in the W78E365 is 256+1K bytes. It is divided into two banks: 256 bytes of scratchpad RAM and 1K bytes of AUX-RAM. These RAMs are addressed by different ways.

- RAM 0H – 7FH can be addressed directly and indirectly as the same as in 8051. Address pointers are R0 and R1 of the selected register bank.
- RAM 80H – FFH can only be addressed indirectly as the same as in 8051. Address pointers are R0, R1 of the selected registers bank.
- AUX-RAM 0H – 3FFH is addressed indirectly as the same way to access external data memory with the MOVX instruction. Address pointer are R0 and R1 of the selected register bank and DPTR register. An access to external data memory locations higher than 3FFH will be performed with the MOVX instruction in the same way as in the 8051. The AUX-RAM is **enabled** after a reset. Clearing the bit 4 in CHPCON register will disable the access to AUX-RAM. When executing from internal program memory, an access to AUX-RAM will not affect the Ports P0, P2, $\overline{WR}$ and $\overline{RD}$.

Example:

```
CHPENR    REG     F6H
CHPCON    REG     BFH
XRAMAH    REG     A1H

MOV     CHPENR, #87H
MOV     CHPENR, #59H
ORL     CHPCON, #00010000B  ; enable AUX-RAM
MOV     CHPENR, #00H
MOV     XRAMAH, #01H        ; internal high address
MOV     R0, #23H
MOV     A, #55H
MOVX    @R0, A              ; Write 55h data to 0123h AUX-RAM address.
MOV     XRAMAH, #02H
MOV     R1, #FFH            ; Read data from 02FFh AUX-RAM address.
MOVX    A, @R1
MOV     DPTR, #0134H
MOV     A, #78H
MOVX    @DPTR, A            ; Write 78h data to 0134h AUX-RAM address.
MOV     DPTR, #7FFFH
MOVX    A, @DPRT            ; Read data from the external 7FFFh address SRAM
```

6.2 Timers 0, 1, and 2

Timers 0, 1, and 2 each consist of two 8-bit data registers. These are called TL0 and TH0 for Timer 0, TL1 and TH1 for Timer 1, and TL2 and TH2 for Timer 2. The TCON and TMOD registers provide control functions for timers 0, 1. The T2CON register provides control functions for Timer 2. RCAP2H and RCAP2L are used as reload/capture registers for Timer 2. The operations of Timer 0 and Timer 1 are the same as in the W78C51. Timer 2 is a 16-bit timer/counter that is configured and controlled by the T2CON register. Like Timers 0 and 1, Timer 2 can operate as either an external event counter or as an internal timer, depending on the setting of bit C/T2 in T2CON. Timer 2 has three operating modes: capture, auto-reload, and baud rate generator. The clock speed at capture or auto-reload mode is the same as that of Timers 0 and 1.

6.2.1 Timer 2 Output

If set T2OE (T2MOD.1) bit and clear C/T2 (T2CON.1) bit at auto-reload mode, P1.0 will be toggled once overflow.

TIMER 2 Mode

Bit:	7	6	5	4	3	2	1	0
							T2OE	

Mnemonic: T2MOD Address: C9H

T2OE: Enable this bit to toggle P1.0 pin while Timer2 has been overflowed.

6.3 Clock

The W78E365 is designed with either a crystal oscillator or an external clock. Internally, the clock is divided by two before it is used by default. This makes the W78E365 relatively insensitive to duty cycle variations in the clock.

6.3.1 Crystal Oscillator

The W78E365 incorporates a built-in crystal oscillator. To make the oscillator work, a crystal must be connected across pins XTAL1 and XTAL2. In addition, a load capacitor must be connected from each pin to ground.

6.3.2 External Clock

An external clock should be connected to pin XTAL1. Pin XTAL2 should be left unconnected. The XTAL1 input is a CMOS-type input, as required by the crystal oscillator.

6.4 Power Management

6.4.1 Idle Mode

Setting the IDL bit in the PCON register enters the idle mode. In the idle mode, the internal clock to the processor is stopped. The peripherals and the interrupt logic continue to be clocked. The processor will exit idle mode when either an interrupt or a reset occurs.

6.4.2 Power-down Mode

When the PD bit in the PCON register is set, the processor enters the power-down mode. In this mode all of the clocks are stopped, including the oscillator. To exit from power-down mode is by a hardware reset or external interrupts $\overline{INT0}$ to $\overline{INT1}$ when enabled and set to level triggered.

6.4.3 Reduce EMI Emission

The W78E365 allows user to diminish the gain of on-chip oscillator amplifier by using programmer to clear the B7 bit of security register. Once B7 is set to 0, a half of gain will be decreased. Care must be taken if user attempts to diminish the gain of oscillator amplifier, reducing a half of gain may affect the external crystal operating improperly at high frequency. The value of C1 and C2 may need some adjustment while running at lower gain.

ALE Off Function

Auxiliary Register

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	-	ALEOFF

Mnemonic: AUXR Address: 8EH

ALEOFF: Set this bit to disable ALE output.

6.5 Reset

The external RESET signal is sampled at S5P2. To take effect, it must be held high for at least two machine cycles while the oscillator is running. An internal trigger circuit in the reset line is used to deglitch the reset line when the W78E365 is used with an external RC network. The reset logic also has a special glitch removal circuit that ignores glitches on the reset line. During reset, the ports are initialized to FFH, the stack pointer to 07H, PCON (with the exception of bit 4) to 00H, and all of the other SFR registers except SBUF to 00H. SBUF is not reset.

6.5.1 W78E365 Special Function Registers (SFRs) and Reset Values

F8								
F0	+B 00000000						CHPENR 00000000	
E8								
E0	+ACC 00000000							
D8	+P4 11111111	PWMP 00000000	PWM0 00000000	PWM1 00000000	PWMCON1 00000000	PWM2 00000000	PWM3 00000000	
D0	+PSW 00000000							
C8	+T2CON 00000000	T2MOD 00000000	RCAP2L 00000000	RCAP2H 00000000	TL2 00000000	TH2 00000000	PWMCON2 00000000	PWM4 00000000
C0	+XICON 00000000		P4CONA 00000000	P4CONB 00000000	SFRAL 00000000	SFRAH 00000000	SFRFD 00000000	SFRCN 00000000

W78E365 Special Function Registers (SFRs) and Reset Values, continued

B8	+IP 00000000							CHPCON 00x11000
B0	+P3 11111111				P43AL 00000000	P43AH 00000000		
A8	+IE 00000000				P42AL 00000000	P42AH 00000000	P4CSIN 00000000	
A0	+P2 11111111	XRAMAH 00000000						
98	+SCON 00000000	SBUF xxxxxxxx						
90	+P1 11111111				P41AL 00000000	P41AH 00000000		
88	+TCON 00000000	TMOD 00000000	TL0 00000000	TL1 00000000	TH0 00000000	TH1 00000000	AUXR 00000000	WDTC 00000000
80	+P0 11111111	SP 00000111	DPL 00000000	DPH 00000000	P40AL 00000000	P40AH 00000000	POR 00000000	PCON 00110000

Notes:

1. The SFRs marked with a plus sign(+) are both byte- and bit-addressable.
2. The text of SFR with bold type characters are extension function registers.

6.6 Port 4

Port 4, address D8H, is a 8-bit multipurpose programmable I/O port. Each bit can be configured individually by software. The Port 4 has four different operation modes.

Mode 0: P4.0–P4.3 is a bi-directional I/O port which is same as port 1. P4.2 and P4.3 also serve as external interrupt $\overline{\text{PSEN}}$ and $\overline{\text{INT2}}$ if enabled.

Mode 1: P4.0–P4.3 are read strobe signals that are synchronized with $\overline{\text{RD}}$ signal at specified addresses. These signals can be used as chip-select signals for external peripherals.

Mode 2: P4.0–P4.3 are write strobe signals that are synchronized with $\overline{\text{WR}}$ signal at specified addresses. These signals can be used as chip-select signals for external peripherals.

Mode 3: P4.0–P4.3 are read/write strobe signals that are synchronized with $\overline{\text{RD}}$ or $\overline{\text{WR}}$ signal at specified addresses. These signals can be used as chip-select signals for external peripherals.

When Port 4 is configured with the feature of chip-select signals, the chip-select signal address range depends on the contents of the SFR P4xAH, P4xAL, P4CONA and P4CONB. The registers P4xAH and P4xAL contain the 16-bit base address of P4.x. The registers P4CONA and P4CONB contain the control bits to configure the Port 4 operation mode.

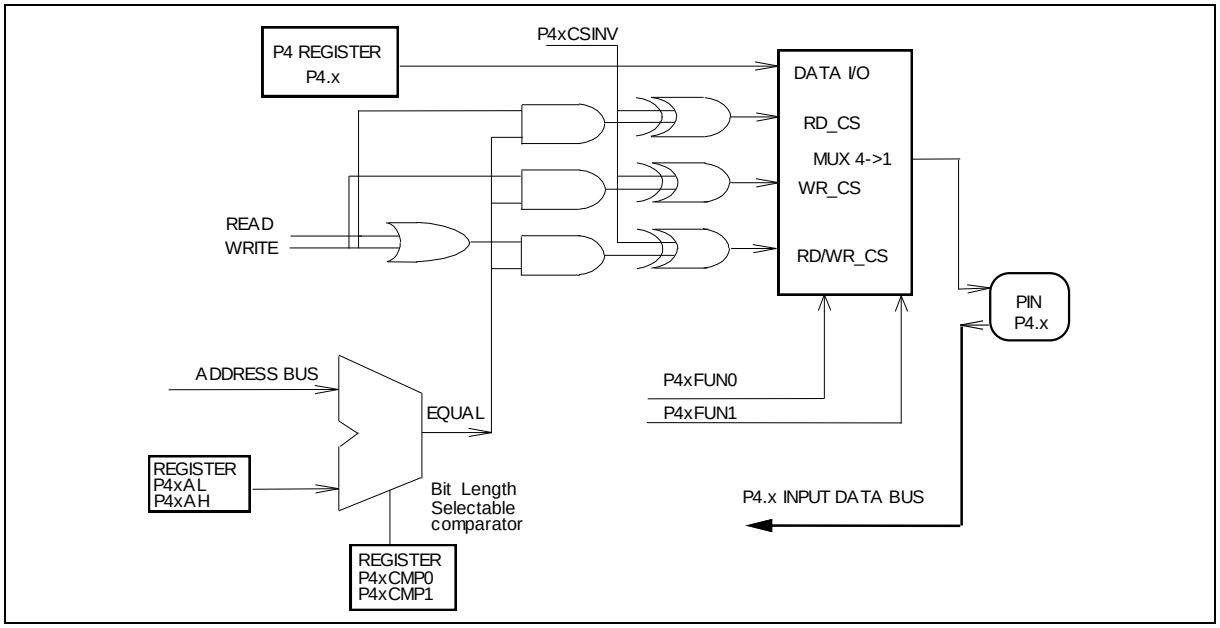
P4 (D8H)

BIT	NAME	FUNCTION
7	P47	I/O pin
6	P46	I/O pin.
5	P45	I/O pin.
4	P44	I/O pin.
3	P43	Port 4 Data bit which outputs to pin P4.3 at mode 0.
2	P42	Port 4 Data bit. which outputs to pin P4.2 at mode 0.
1	P41	Port 4 Data bit. which outputs to pin P4.1at mode 0.
0	P40	Port 4 Data bit which outputs to pin P4.0 at mode 0.

Here is an example to program the P4.0 as a write strobe signal at the I/O port address 1234H – 1237H and positive polarity, and P4.1 – P4.3 are used as general I/O ports.

```
MOV  P40AH, #12H
MOV  P40AL, #34H          ; Base I/O address 1234H for P4.0
MOV  P4CONA, #00001010B   ; P4.0 a write strobe signal and address line A0 and A1 are masked.
MOV  P4CONB, #00H         ; P4.1 – P4.3 as general I/O port which are the same as PORT1
MOV  P2ECON, #10H         ; Write the P40SINV = 1 to inverse the P4.0 write strobe polarity
                          ; default is negative.
```

Then any instruction MOVX @DPTR, A (with DPTR = 1234H – 1237H) will generate the positive polarity write strobe signal at pin P4.0. And the instruction MOV P4, #XX will output the bit3 to bit1 of data #XX to pin P4.3 – P4.1.



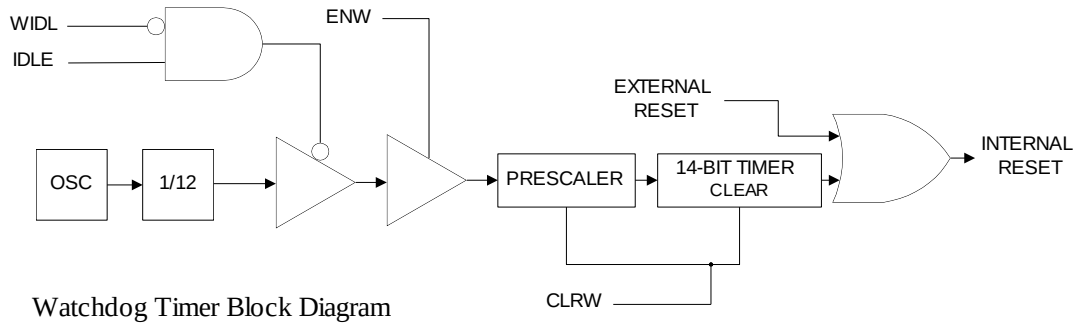
PS2, PS1, PS0: Watch-dog prescaler timer select. Prescaler is selected when set PS2–0 as follows:

PS2	PS1	PS0	PRESCALER SELECT
0	0	0	2
0	0	1	4
0	1	0	8
0	1	1	16
1	0	0	32
1	0	1	64
1	1	0	128
1	1	1	256

The time-out period is obtained using the following equation:

$$\frac{1}{OSC} \times 2^{14} \times PRESCALER \times 1000 \times 12 \text{ mS}$$

Before Watchdog time-out occurs, the program must clear the 14-bit timer by writing 1 to WDTC.6 (CLRW). After 1 is written to this bit, the 14-bit timer, prescaler and this bit will be reset on the next instruction cycle. The Watchdog timer is cleared on reset.



Watchdog Timer Block Diagram

Typical Watch-Dog time-out period when OSC = 20 MHz

PS2	PS1	PS0	WATCHDOG TIME-OUT PERIOD
0	0	0	19.66 mS
0	0	1	39.32 mS
0	1	0	78.64 mS
0	1	1	157.28 mS
1	0	0	314.57 mS
1	0	1	629.14 mS
1	1	0	1.25 S
1	1	1	2.50 S

MODE	WFWIN	CTRL<3:0>	OEN	CEN	SFRAH, SFRAL	SFRFD
Erase 64KB APROM	0	0010	1	0	X	X
Program 64KB APROM	0	0001	1	0	Address in	Data in
Read 64KB APROM	0	0000	0	0	Address in	Data out
Erase 4KB LDROM	1	0010	1	0	X	X
Program 4KB LDROM	1	0001	1	0	Address in	Data in
Read 4KB LDROM	1	0000	0	0	Address in	Data out

6.9.1 In-System Programming Control Register (CHPCON)

CHPCON (BFH)

BIT	NAME	FUNCTION
7	SWRESET	When this bit is set to 1, and both FBOOTSL and FPROGEN are set to 1. It will enforce microcontroller reset to initial condition just like power on reset.
6	-	Reserve.
5	LD/AP	This bit is read only. 1: CPU is running LDROM program. 0: CPU is running APROM program.
4	ENAUXRAM	1: Enable on-chip AUX-RAM. 0: Disable the on-chip AUX-RAM
3	1	Must be 1
2	-	Reserve.
1	FBOOTSL	When this bit is set to 1, and both SWRESET and FPROGEN are set to 1. It will enforce microcontroller reset to initial condition just like power on reset.
0	FPROGEN	When this bit is set to 1, and both SWRESET and FBOOTSL are set to 1. It will enforce microcontroller reset to initial condition just like power on reset.

This register is protected by CHPENR register. Please write as below procedures while you would like to write CHPCON register.

```
Mov CHPENR, #87h
Mov CHPENR, #59h
Anl CHPCON, #EFh    ; Disable AUX-RAM
Mov CHPENR, #0h
```

6.10 Software Reset

Set CHPCON = 0X83, timer and enter IDLE mode. CPU will reset and restart from APFLASH after time out.

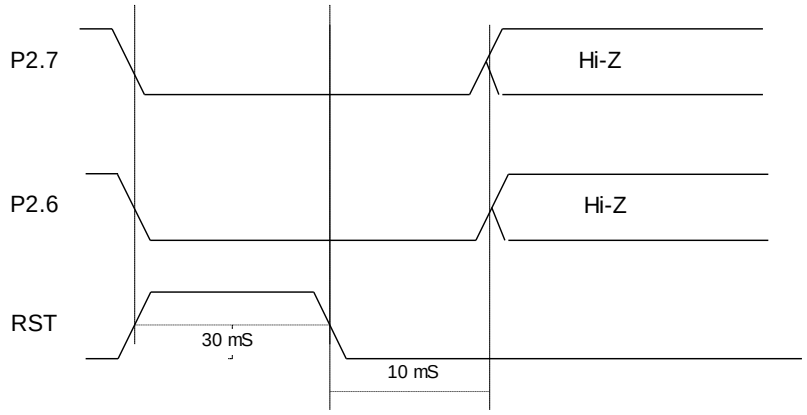
6.11 H/W Reboot Mode (Boot from LDROM)

By default, the W78E365 boots from APROM program after a power on reset. On some occasions, user can force the W78E365 to boot from the LDROM program via following settings. The possible situation that you need to enter H/W REBOOT mode when the APROM program can not run properly and device can not jump back to LDROM to execute in-system programming function. Then you can use this H/W REBOOT mode to force the W78E365 jumps to LDROM and executes in-system programming procedure. When you design your system, you may reserve the pins P2.6, P2.7 to switches or jumpers. For example in a CD-ROM system, you can connect the P2.6 and P2.7 to PLAY and EJECT buttons on the panel. When the APROM program fails to execute the normal application program. User can press both two buttons at the same time and then turn on the power of the personal computer to force the W78E365 to enter the H/W REBOOT mode. After power on of personal computer, you can release both buttons and finish the in-system programming procedure to update the APROM code. In application system design, user must take care of the P2, P3, ALE, $\overline{EA}$ and $\overline{PSEN}$ pin value at reset to prevent from accidentally activating the programming mode or H/W REBOOT mode. It is necessary to add 10K resistor on these P2.6, P2.7 and P4.3 pins.

H/W Reboot Mode

P4.3	P2.7	P2.6	MODE
X	L	L	REBOOT
L	X	X	REBOOT

The Reset Timing For Entering F04KBOOT Mode



Encryption

This bit is used to enable/disable the encryption logic for code protection. Once encryption feature is enabled, the data presented on port 0 will be encoded via encryption logic. Only whole chip erase will reset this bit.

Oscillator Control

W78E365/E516 allow user to diminish the gain of on-chip oscillator amplifier by using programmer to set the bit B7 of security register. Once B7 is set to 0, a half of gain will be decreased. Care must be taken if user attempts to diminish the gain of oscillator amplifier, reducing a half of gain may improperly affect the external crystal operation at high frequency above 24 MHz. The value of R and C1, C2 may need some adjustment while running at lower gain.

7. ELECTRICAL CHARACTERISTICS

7.1 Absolute Maximum Ratings

PARAMETER	SYMBOL	MIN.	MAX.	UNIT
DC Power Supply	V_{DD}–V_{SS}	-0.3	+6.0	V
Input Voltage	V_{IN}	V_{SS} -0.3	V_{DD} +0.3	V
Operating Temperature	T_A	0	70	°C
Storage Temperature	T_{ST}	-55	+150	°C

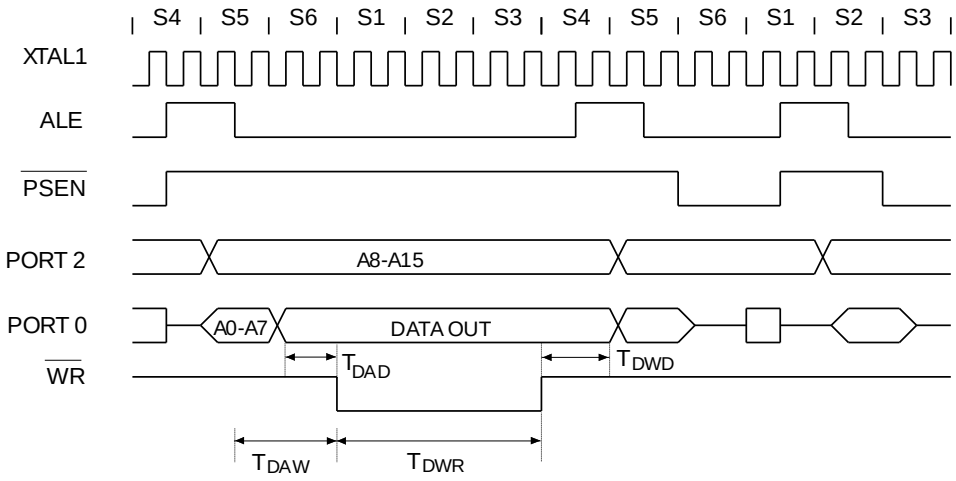
Note: Exposure to conditions beyond those listed under Absolute Maximum Ratings may adversely affect the life and reliability of the device.

7.2 D.C. Characteristics

(V_{DD} – V_{SS}= 5V ±10%, T_A = 25°C, Fosc = 20 MHz, unless otherwise specified.)

SYMBOL	PARAMETER	SPECIFICATION			TEST CONDITIONS
		MIN.	MAX.	UNIT	
V_{DD}	Operating Voltage	4.5	5.5	V	RST = 1, P0 = V_{DD}
I_{DD}	Operating Current	-	20	mA	No load V_{DD} = 5.5V
I_{IDLE}	Idle Current	-	6	mA	Idle mode V_{DD} = 5.5V
I_{PWDN}	Power Down Current	-	10	µA	Power-down mode V_{DD} = 5.5V
I_{IN1}	Input Current P1, P2, P3, P4	-50	+10	µA	V_{DD} = 5.5V V_{IN} = 0V or V_{DD}
I_{IN2}	Input Current RST	-10	+300	µA	V_{DD} = 5.5V 0<V_{IN}<V_{DD}
I_{LK}	Input Leakage Current P0, $\overline{EA}$	-10	+10	µA	V_{DD} = 5.5V 0V<V_{IN}<V_{DD}
I_{TL} [*4]	Logic 1 to 0 Transition Current P1, P2, P3, P4	-500	-200	µA	V_{DD} = 5.5V V_{IN} = 2.0V
VIL1	Input Low Voltage P0, P1, P2, P3, P4, $\overline{EA}$	0	0.8	V	VDD = 4.5V
V IL2	Input Low Voltage RST	0	0.8	V	VDD = 4.5V

8.3 Data Write Cycle



PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT
ALE Low to $\overline{WR}$ Low	TDAW	3 TCP-Δ	-	3 TCP+Δ	nS
Data Valid to $\overline{WR}$ Low	TDAD	1 TCP-Δ	-	-	nS
Data Hold from $\overline{WR}$ High	TDWD	1 TCP-Δ	-	-	nS
$\overline{WR}$ Pulse Width	TDWR	6 TCP-Δ	6 TCP	-	nS

Note: "Δ" (due to buffer driving delay and wire loading) is 20 nS.

9. TYPICAL APPLICATION CIRCUIT

9.1 External Program Memory and Crystal

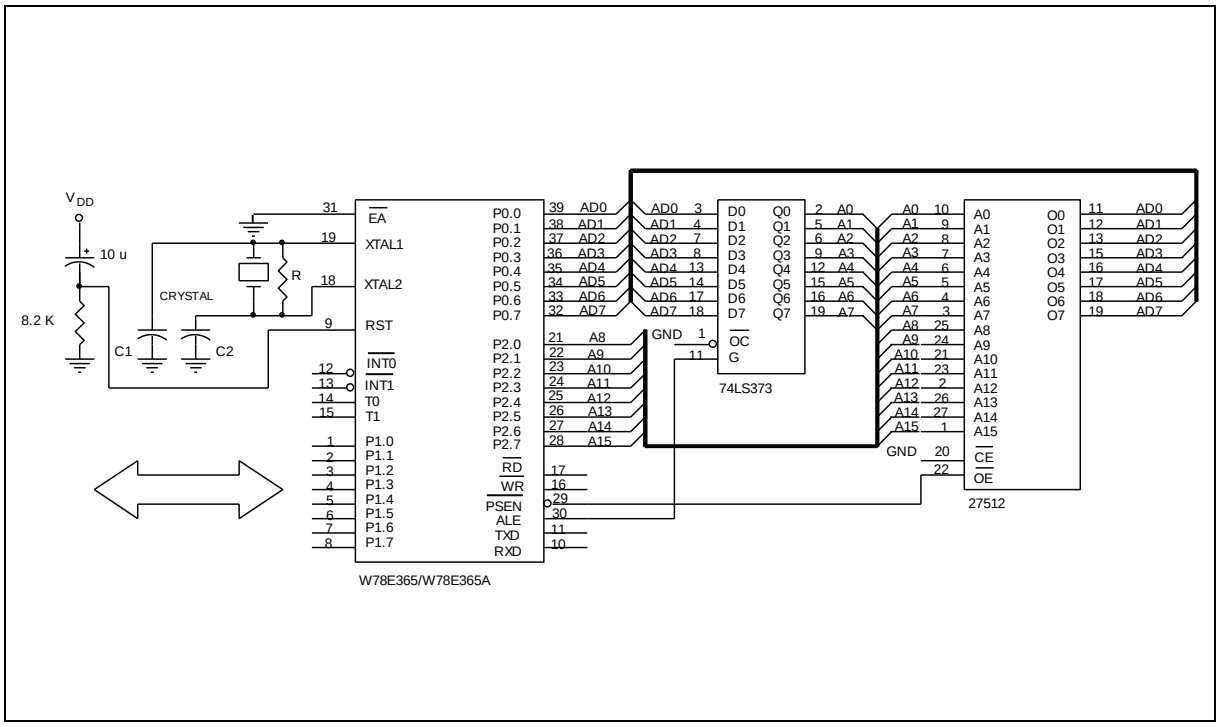


Figure A

CRYSTAL	C1	C2	R
6 MHz	47P	47P	-
16 MHz	30P	30P	-
24 MHz	15P	15P	-
32 MHz	10P	10P	6.8K
40 MHz	5P	5P	4.7K

Above table shows the reference values for crystal applications.

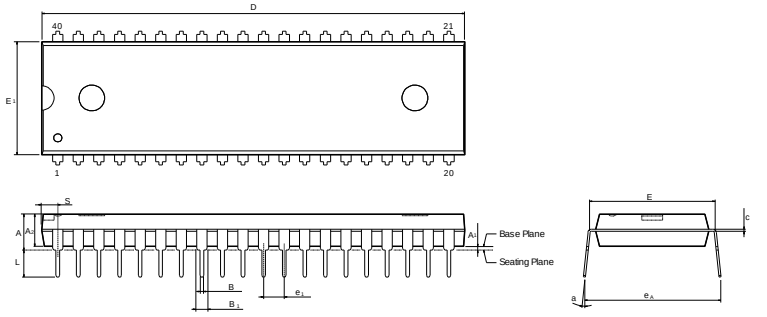
Notes:

1. C1, C2, R components refer to Figure A
2. Crystal layout must get close to XTAL1 and XTAL2 pins on user's application board.

Typical Application Circuit, continued

10. PACKAGE DIMENSIONS

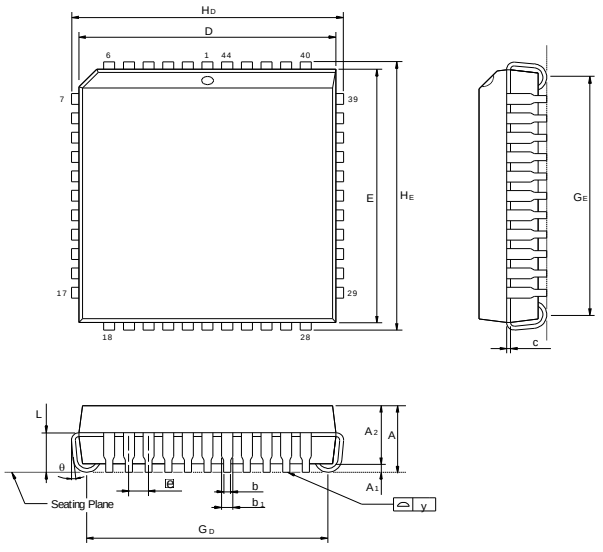
10.1 40-pin DIP



Symbol	Dimension in inch			Dimension in mm		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	—	—	0.210	—	—	5.334
A_1	0.010	—	—	0.254	—	—
A_2	0.150	0.155	0.160	3.81	3.937	4.064
B	0.016	0.018	0.022	0.406	0.457	0.559
B_1	0.048	0.050	0.054	1.219	1.27	1.372
c	0.008	0.010	0.014	0.203	0.254	0.356
D	—	2.055	2.070	—	52.20	52.58
E	0.590	0.600	0.610	14.986	15.24	15.494
E_1	0.540	0.545	0.550	13.72	13.84	13.97
e_1	0.090	0.100	0.110	2.286	2.54	2.794
L	0.120	0.130	0.140	3.048	3.302	3.556
a	0	—	15	0	—	15
e_A	0.630	0.650	0.670	16.00	16.51	17.01
S	—	—	0.090	—	—	2.286

Notes:
1. Dimension D Max. & S include mold flash or tie bar burrs.
2. Dimension E1 does not include interlead flash.
3. Dimension D & E1 include mold mismatch and are determined at the mold parting line.
4. Dimension B1 does not include dambar protrusion/intrusion.
5. Controlling dimension: Inches.
6. General appearance spec. should be based on final visual inspection spec.

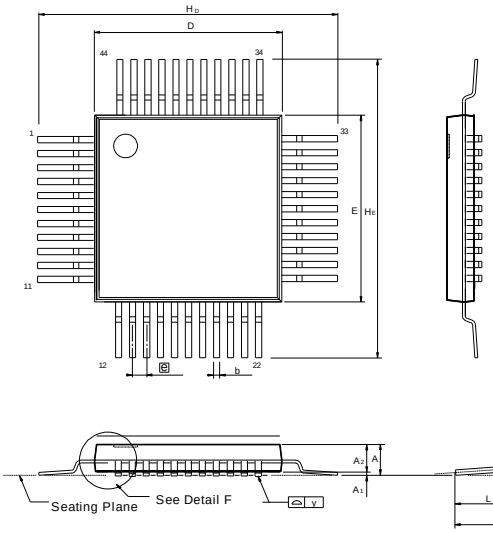
10.2 44-pin PLCC



Symbol	Dimension in inch			Dimension in mm		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	—	—	0.185	—	—	4.699
A_1	0.020	—	—	0.508	—	—
A_2	0.145	0.150	0.155	3.683	3.81	3.937
b_1	0.026	0.028	0.032	0.66	0.711	0.813
b	0.016	0.018	0.022	0.406	0.457	0.559
c	0.008	0.010	0.014	0.203	0.254	0.356
D	0.648	0.653	0.658	16.46	16.59	16.71
E	0.648	0.653	0.658	16.46	16.59	16.71
e	0.050 BSC			1.27 BSC		
G_D	0.590	0.610	0.630	14.99	15.49	16.00
G_E	0.590	0.610	0.630	14.99	15.49	16.00
H_D	0.680	0.690	0.700	17.27	17.53	17.78
H_E	0.680	0.690	0.700	17.27	17.53	17.78
L	0.090	0.100	0.110	2.296	2.54	2.794
y	—	—	0.004	—	—	0.10

Notes:
1. Dimension D & E do not include interlead flash.
2. Dimension b1 does not include dambar protrusion/intrusion.
3. Controlling dimension: Inches
4. General appearance spec. should be based on final visual inspection spec.

10.3 44-pin PQFP

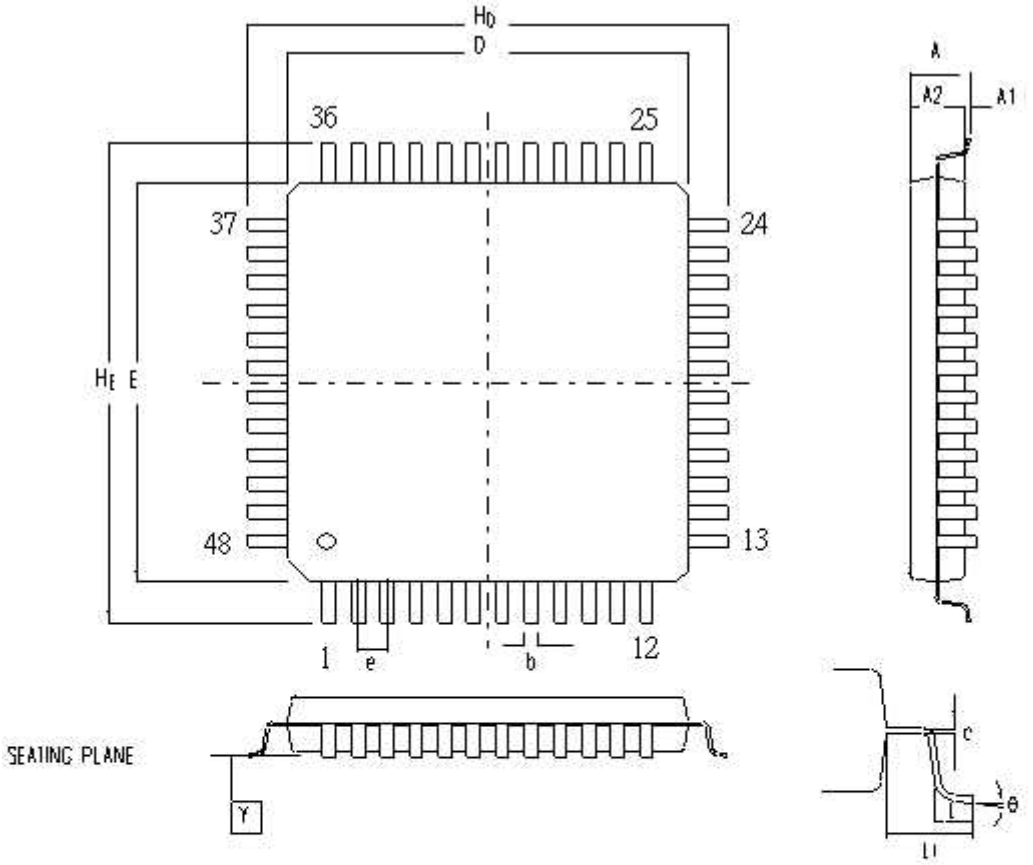


Symbol	Dimension in inch			Dimension in mm		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	---	---	---	---	---	---
A_1	0.002	0.01	0.02	0.05	0.25	0.5
A_2	0.075	0.081	0.087	1.90	2.05	2.20
b	0.01	0.014	0.018	0.25	0.35	0.45
c	0.004	0.006	0.010	0.101	0.152	0.254
D	0.390	0.394	0.398	9.9	10.00	10.1
E	0.390	0.394	0.398	9.9	10.00	10.1
e	0.025	0.031	0.036	0.635	0.80	0.952
H_D	0.510	0.520	0.530	12.95	13.2	13.45
H_E	0.510	0.520	0.530	12.95	13.2	13.45
L	0.025	0.031	0.037	0.65	0.8	0.95
L_1	0.051	0.063	0.075	1.295	1.6	1.905
y	—	—	0.003	—	—	0.08
θ	0°	—	7°	0°	—	7°

Notes:

1. Dimension D & E do not include interlead flash.
2. Dimension b does not include dambar protrusion/intrusion.
3. Controlling dimension: Millimeter
4. General appearance spec. should be based on final visual inspection spec.

10.4 48-pin LQFP



Controlling dimension : Millimeters

Symbol	Dimension in inch			Dimension in mm		
	Min	Nom	Max	Min	Nom	Max
A	—	—	0.063	—	—	1.60
A1	0.002	0.004	0.006	0.05	0.10	0.15
A2	0.053	0.055	0.057	1.35	1.40	1.45
b	0.006	0.008	0.010	0.15	0.20	0.25
c	0.004	0.006	0.008	0.10	0.15	0.20
D	0.272	0.276	0.280	6.90	7.00	7.10
E	0.272	0.276	0.280	6.90	7.00	7.10
e	0.014	0.020	0.026	0.35	0.50	0.65
HD	0.350	0.354	0.358	8.90	9.00	9.10
HE	0.350	0.354	0.358	8.90	9.00	9.10
L	0.018	0.024	0.030	0.45	0.60	0.75
L1	—	0.039	—	—	1.00	—
Y	—	—	0.004	—	—	0.10
θ	0°	—	7°	0°	—	7°

11. APPLICATION NOTE

11.1 In-system Programming Software Examples

This application note illustrates the in-system programmability of the Nuvoton W78E365 ROM microcontroller. In this example, microcontroller will boot from 64KB APROM bank and waiting for a key to enter in-system programming mode for re-programming the contents of 64KB APROM. While entering in-system programming mode, microcontroller executes the loader program in 4KB LDROM bank. The loader program erases the 64KB APROM then reads the new code data from external SRAM buffer (or through other interfaces) to update the 64KB APROM.

Example 1:

```
;*****************************************************************************************************************
;* Example of 64K APROM program: Program will scan the P1.0. if P1.0 = 0, enters in-system
;* programming mode for updating the content of APROM code else executes the current ROM code.
;* XTAL = 16 MHz
;*****************************************************************************************************************
        .chip 8052
        .RAMCHK OFF
        .symbols

        CHPCON    EQU     BFH
        CHPENR    EQU     F6H
        SFRAL     EQU     C4H
        SFRAH     EQU     C5H
        SFRFD     EQU     C6H
        SFRCN     EQU     C7H

        ORG     0H
        LJMP    100H                    ; JUMP TO MAIN PROGRAM
    ;*************************************************************************
    ;*  TIMER0 SERVICE VECTOR ORG = 000BH
    ;*************************************************************************
        ORG     00BH
        CLR     TR0                     ; TR0 = 0, STOP TIMER0
        MOV     TL0, R6
        MOV     TH0, R7
        RETI
    ;*************************************************************************
    ;*  64K APROM MAIN PROGRAM
    ;*************************************************************************
       ORG 100H

MAIN_64K:
        MOV A,P1                        ; SCAN P1.0
        ANL A, #01H
        CJNE A, #01H,PROGRAM_64K ; IF P1.0 = 0, ENTER IN-SYSTEM PROGRAMMING MODE
        JMP NORMAL_MODE

PROGRAM_64K:
        MOV CHPENR, #87H                ; CHPENR = 87H, CHPCON REGISTER WRTE ENABLE
        MOV CHPENR, #59H                ; CHPENR = 59H, CHPCON REGISTER WRITE ENABLE
        MOV CHPCON, #03H                ; CHPCON = 03H, ENTER IN-SYSTEM PROGRAMMING MODE
        MOV TCON, #00H                  ; TR = 0 TIMER0 STOP
```

```
        MOV IP, #00H                ; IP = 00H
        MOV IE, #82H                ; TIMER0 INTERRUPT ENABLE FOR WAKE-UP FROM IDLE MODE
        MOV R6, #F0H                ; TL0 = F0H
        MOV R7, #FFH                ; TH0 = FFH
        MOV TL0, R6
        MOV TH0, R7
        MOV TMOD, #01H              ; TMOD = 01H, SET TIMER0 A 16-BIT TIMER
        MOV TCON, #10H              ; TCON = 10H, TR0 = 1,GO
        MOV PCON, #01H              ; ENTER IDLE MODE FOR LAUNCHING THE IN-SYSTEM
                                    ; PROGRAMMING
;*****************************************************************************
;* Normal mode 64KB APROM program: depending user's application
;*****************************************************************************
NORMAL_MODE:
            .                       ; User's application program
            .
            .
            .
```

Example 2:

```
;*************************************************************************************************************************
Example of 4 KB LDROM program: This loader program will erase the 64KB APROM first, then reads the new ;*
code from external SRAM and program them into 32 KB APROM bank. XTAL = 16 MHz
;*************************************************************************************************************************
    .chip 8052
    .RAMCHK OFF
    .symbols

    CHPCON     EQU    BFH
    CHPENR     EQU    F6H
    SFRAL      EQU    C4H
    SFRAH      EQU    C5H
    SFRFD      EQU    C6H
    SFRCN      EQU    C7H

       ORG    000H
       LJMP   100H                  ; JUMP TO MAIN PROGRAM
  ;*************************************************************************
  ;* 1. TIMER0 SERVICE VECTOR ORG = 0BH
  ;*************************************************************************
       ORG 000BH
       CLR  TR0                     ; TR0 = 0, STOP TIMER0
       MOV TL0, R6
       MOV TH0, R7
       RETI
```

```
;*******************************************************************************
;*  4KB LDROM MAIN PROGRAM
;*******************************************************************************
        ORG 100H
MAIN_4K:
        MOV SP, #C0H
        MOV CHPENR, #87H      ; CHPENR = 87H, CHPCON WRITE ENABLE.
        MOV CHPENR, #59H      ; CHPENR = 59H, CHPCON WRITE ENABLE.
        MOV CHPCON, #03H      ; CHPCON = 03H, ENABLE IN-SYSTEM PROGRAMMING.
        MOV CHPENR, #00H      ; DISABLE CHPCON WRITE ATTRIBUTE

        MOV TCON, #00H        ; TCON = 00H, TR = 0 TIMER0 STOP
        MOV TMOD, #01H        ; TMOD = 01H, SET TIMER0 A 16BIT TIMER
        MOV IP, #00H          ; IP = 00H
        MOV IE, #82H          ; IE = 82H, TIMER0 INTERRUPT ENABLED
        MOV R6, #F0H
        MOV R7, #FFH
        MOV TL0, R6
        MOV TH0, R7
        MOV TCON, #10H        ; TCON = 10H, TR0 = 1, GO
        MOV PCON, #01H        ; ENTER IDLE MODE

UPDATE_64K:
        MOV TCON, #00H        ; TCON = 00H, TR = 0 TIM0 STOP
        MOV IP, #00H          ; IP = 00H
        MOV IE, #82H          ; IE = 82H, TIMER0 INTERRUPT ENABLED
        MOV TMOD, #01H        ; TMOD = 01H, MODE1
        MOV R6, #E0H          ; SET WAKE-UP TIME FOR ERASE OPERATION, ABOUT 15 mS. DEPENDING
                              ; ON USER'S SYSTEM CLOCK RATE.
        MOV R7, #B1H
        MOV TL0, R6
        MOV TH0, R7

ERASE_P_4K:
        MOV SFRCN, #22H     ; SFRCN(C7H) = 22H  ERASE 64K
        MOV TCON, #10H      ; TCON = 10H, TR0 = 1,GO
        MOV PCON, #01H      ; ENTER IDLE MODE (FOR ERASE OPERATION)

;*******************************************************************************
;* BLANK CHECK
;*******************************************************************************
        MOV SFRCN, #0H      ; READ 64KB APROM MODE
        MOV SFRAH, #0H      ; START ADDRESS = 0H
        MOV SFRAL, #0H
        MOV R6, #FEH        ; SET TIMER FOR READ OPERATION, ABOUT 1.5 μS.
        MOV R7, #FFH
        MOV TL0, R6
        MOV TH0, R7

BLANK_CHECK_LOOP:
        SETB TR0            ; ENABLE TIMER 0
        MOV PCON, #01H      ; ENTER IDLE MODE
        MOV A, SFRFD        ; READ ONE BYTE
        CJNE A, #FFH, BLANK_CHECK_ERROR
        INC SFRAL           ; NEXT ADDRESS
        MOV A, SFRAL
```