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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPs
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	21
Program Memory Size	6KB (6K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b; D/A 2x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj06gs202-e-sp

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



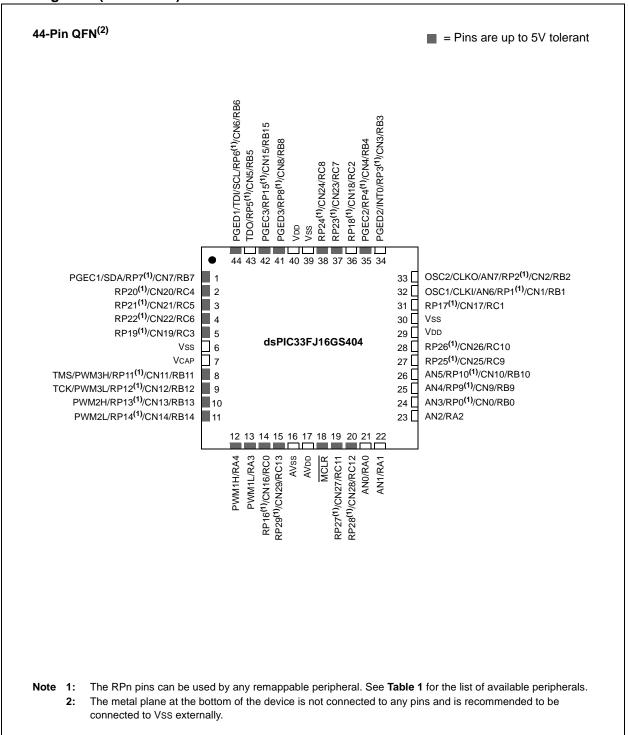


FIGURE 2-8: **OFF-LINE UPS VDC** Full-Bridge Inverter Push-Pull Converter Vour+ VBAT VOUT-GND **GND** FET Driver FET Driver FET Driver FET Driver FET Driver FET Driver ADC or **PWM PWM** ADC **PWM PWM PWM PWM** Analog Comp.  $k_3$ ADC dsPIC33FJ16GS504 ADC ADC PWM ADC FET Driver  $\mathsf{k}_6$ **Battery Charger** 

#### 4.2.5 X AND Y DATA SPACES

The core has two data spaces, X and Y. These data spaces can be considered either separate (for some DSP instructions), or as one unified linear address range (for MCU instructions). The data spaces are accessed using two Address Generation Units (AGUs) and separate data paths. This feature allows certain instructions to concurrently fetch two words from RAM, thereby enabling efficient execution of DSP algorithms, such as Finite Impulse Response (FIR) filtering and Fast Fourier Transform (FFT).

The X data space is used by all instructions and supports all addressing modes. X data space has separate read and write data buses. The X read data bus is the read data path for all instructions that view data space as combined X and Y address space. It is also the X data prefetch path for the dual operand DSP instructions (MAC class).

The Y data space is used in concert with the X data space by the MAC class of instructions (CLR, ED, EDAC, MAC, MOVSAC, MPY, MPY. N and MSC) to provide two concurrent data read paths.

Both the X and Y data spaces support Modulo Addressing mode for all instructions, subject to addressing mode restrictions. Bit-Reversed Addressing mode is only supported for writes to X data space.

All data memory writes, including in DSP instructions, view data space as combined X and Y address space. The boundary between the X and Y data spaces is device-dependent and is not user-programmable.

All Effective Addresses are 16 bits wide and point to bytes within the data space. Therefore, the data space address range is 64 Kbytes, or 32K words, though the implemented memory locations vary by device.

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TABLE 4-6:	INTERRUPT CONTROLLER	REGISTER MAP FOR	dsPIC33FJ06GS102 DEVICES ONLY	/
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File Name	SFR Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
INTCON1	0080	NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE	SFTACERR	DIV0ERR	_	MATHERR	ADDRERR	STKERR	OSCFAIL	_	0000
INTCON2	0082	ALTIVT	DISI	_	_	_	_	_	_	_	_	_	_	_	INT2EP	INT1EP	INT0EP	0000
IFS0	0084	_	_	ADIF	U1TXIF	U1RXIF	SPI1IF	SPI1EIF	_	T2IF	_	_	_	T1IF	OC1IF	_	INT0IF	0000
IFS1	0086	_	_	INT2IF	_	_	_	_		_	_	ı	INT1IF	CNIF	_	MI2C1IF	SI2C1IF	0000
IFS3	008A	_	_	_	_	_	_	PSEMIF		_	_	ı	_	_	_	_	_	0000
IFS4	008C		1	1	_	_	1	1	1	_	_	I		_		U1EIF	_	0000
IFS5	008E	PWM2IF	PWM1IF	_	_	_	_	_	_	_	_	-	_	_	_	_	_	0000
IFS6	0090	ADCP1IF	ADCP0IF	_	_	_	_	_	_	_	_	_	_	_	_	_		0000
IFS7	0092	_	_	_	_	_	_	_	_	_	_		_	_	_	_	ADCP2IF	0000
IEC0	0094	_	_	ADIE	U1TXIE	U1RXIE	SPI1IE	SPI1EIE	_	T2IE	_		_	T1IE	OC1IE	_	INT0IE	0000
IEC1	0096	_	_	INT2IE	_	_	_	_	_	_	_	_	INT1IE	CNIE	_	MI2C1IE	SI2C1IE	0000
IEC3	009A	_	_	_	_	_	_	PSEMIE	_	_	_		_	_	_	_	_	0000
IEC4	009C	_	_	_	_	_	_	_	_	_	_	_	_	_	_	U1EIE	_	0000
IEC5	009E	PWM2IE	PWM1IE	_	_	_	_	_	_	_	_	_	_	_	_	_	_	0000
IEC6	00A0	ADCP1IE	ADCP0IE	_	_	_	_	_	_	_	_		_	_	_	_	_	0000
IEC7	00A2	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	ADCP2IE	0000
IPC0	00A4	_	T1IP2	T1IP1	T1IP0	_	OC1IP2	OC1IP1	OC1IP0	_	_	_	_	_	INT0IP2	INT0IP1	INT0IP0	4404
IPC1	00A6	_	T2IP2	T2IP1	T2IP0	_	_	_	_	_	_	_	_	_	_	_	_	4000
IPC2	00A8	_	U1RXIP2	U1RXIP2	U1RXIP0	_	SPI1IP2	SPI1IP1	SPI1IP0	_	SPI1EIP2	SPI1EIP1	SPI1EIP0	_	_	_	_	4440
IPC3	00AA	_	_	_	_	_	_	_	_		ADIP2	ADIP1	ADIP0	_	U1TXIP2	U1TXIP1	U1TXIP0	0044
IPC4	00AC	_	CNIP2	CNIP1	CNIP0	_	_	_	_	_	MI2C1IP2	MI2C1IP1	MI2C1IP0	_	SI2C1IP2	SI2C1IP1	SI2C1IP0	4044
IPC5	00AE	_	_	_	_	_	_	_	_	_	_	_	_	_	INT1IP2	INT1IP1	INT1IP0	0004
IPC7	00B2	_	_	_	_	_	_	_	_	_	INT2IP2	INT2IP1	INT2IP0	_	_	_	_	0040
IPC14	00C0	_	_	_	_	_	_	_	_	_	PSEMIP2	PSEMIP1	PSEMIP0	_	_	_	_	0040
IPC16	00C4	_	_	_	_	_	_	_	_	_	U1EIP2	U1EIP1	U1EIP0	_	_	_	_	0040
IPC23	00D2	_	PWM2IP2	PWM2IP1	PWM2IP0	_	PWM1IP2	PWM1IP1	PWM1IP0	_	_		_	_	_	_	_	4400
IPC27	00DA	_	ADCP1IP2	ADCP1IP1	ADCP1IP0	_	ADCP0IP2	ADCP0IP1	ADCP0IP0	_	_	_	_	_	_	_	_	4400
IPC28	00DC	_	_	_	_	_	_	_	_	_	_		_	_	ADCP2IP2	ADCP2IP1	ADCP2IP0	0004
INTTREG	00E0	_	_	_	_	ILR3	ILR2	ILR1	ILR0	_	VECNUM6	VECNUM5	VECNUM4	VECNUM3	VECNUM2	VECNUM1	VECNUM0	0000

x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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TABLE 4-41:	SYSTEM	CONTROL	REGISTER	МΔР
IADLL 4-41.	SISILIVI	CONTROL	ILLGIOILI	IVIAL

File Name	SFR Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RCON	0740	TRAPR	IOPUWR	1	_	_	_	CM	VREGS	EXTR	SWR	SWDTEN	WDTO	SLEEP	IDLE	BOR	POR	xxxx(1)
OSCCON	0742	_	COSC2	COSC1	COSC0	_	NOSC2	NOSC1	NOSC0	CLKLOCK	IOLOCK	LOCK	_	CF	-	_	OSWEN	0300(2)
CLKDIV	0744	ROI	DOZE2	DOZE1	DOZE0	DOZEN	FRCDIV2	FRCDIV1	FRCDIV0	PLLPOST1	PLLPOST0	_	PLLPRE4	PLLPRE3	PLLPRE2	PLLPRE1	PLLPRE0	3040
PLLFBD	0746	_		-	_	_	-	I				PLLI	OIV<8:0>					0030
REFOCON	074E	ROON	1	ROSSLP	ROSEL	RODIV3	RODIV2	RODIV1	RODIV0	_	_	_	_	-	-	_	_	0000
OSCTUN	0748	_	_	_	_	_	_	_	_	_	_			TUN<	:5:0>			0000
ACLKCON	0750	ENAPLL	APLLCK	SELACLK	_	_	APSTSCLR2	APSTSCLR1	APSTSCLR0	ASRCSEL	FRCSEL	_	_	_	_	_	_	2300

x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

The RCON register Reset values are dependent on the type of Reset.

The OSCCON register Reset values are dependent on the FOSCx Configuration bits and on type of Reset.

#### **TABLE 4-42: NVM REGISTER MAP**

File Name	SFR Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0760	WR	WREN	WRERR	_	_	_	_	_	_	ERASE	_	_	NVMOP3	NVMOP2	NVMOP1	NVMOP0	0000(1)
NVMKEY	0766	_	_	_	_	_	-	_	_				NVMKI	EY<7:0>				0000

dsPIC33FJ06GS101/X02 and dsPIC33FJ16GSX02/X04

x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

1: Reset value shown is for POR only. The value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset.

#### TABLE 4-43: PMD REGISTER MAP FOR dsPIC33FJ06GS101 DEVICES ONLY

File Name	SFR Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0770	_	_	_	T2MD	T1MD	-	PWMMD	_	I2C1MD	-	U1MD	_	SPI1MD	_	_	ADCMD	0000
PMD2	0772		_	_	_	-		IC2MD	IC1MD	_	_	_		_	_	OC2MD	OC1MD	0000
PMD3	0774	_	_	_	_	_	CMPMD	_	_	_	_	_	_	_	_	_	_	0000
PMD4	0776	_	_	_	_	_		ı	_	_	1	_	_	REFOMD	_	_	_	0000
PMD6	077A	_	_	_	_	PWM4MD		-	PWM1MD	-		_	_	_	-	_	-	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

#### PMD REGISTER MAP FOR dsPIC33FJ06GS102 DEVICES ONLY **TABLE 4-44:**

File Name	SFR Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0770	_	_	_	T2MD	T1MD	_	PWMMD	_	I2C1MD	_	U1MD	_	SPI1MD	_	_	ADCMD	0000
PMD2	0772	_	_	_	-	ı	-	IC2MD	IC1MD	_	1	_	_	_	_	OC2MD	OC1MD	0000
PMD3	0774	-	_	_	ı	I	CMPMD	ı	_		ı	_	_	_	_	_	_	0000
PMD4	0776		_	_	_	_	_	_	_	_	_	_	_	REFOMD	_	_	_	0000
PMD6	077A	_	_	_	_	_	_	PWM2MD	PWM1MD	_	-	_	_	_	_	_	_	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-48: FUNDAMENTAL ADDRESSING MODES SUPPORTED

Addressing Mode	Description
File Register Direct	The address of the file register is specified explicitly.
Register Direct	The contents of a register are accessed directly.
Register Indirect	The contents of Wn forms the Effective Address (EA).
Register Indirect Post-Modified	The contents of Wn forms the EA. Wn is post-modified (incremented or decremented) by a constant value.
Register Indirect Pre-Modified	Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA.
Register Indirect with Register Offset (Register Indexed)	The sum of Wn and Wb forms the EA.
Register Indirect with Literal Offset	The sum of Wn and a literal forms the EA.

## 4.3.3 MOVE AND ACCUMULATOR INSTRUCTIONS

Move instructions and the DSP accumulator class of instructions to provide a greater addressing flexibility than other instructions. In addition to the addressing modes supported by most MCU instructions, move and accumulator instructions also support Register Indirect with Register Offset Addressing mode, also referred to as Register Indexed mode.

Note: For the MOV instructions, the addressing mode specified in the instruction can differ for the source and destination EA. However, the 4-bit Wb (register offset) field is shared by both source and destination (but typically only used by one).

In summary, the following addressing modes are supported by move and accumulator instructions:

- Register Direct
- Register Indirect
- · Register Indirect Post-modified
- · Register Indirect Pre-modified
- Register Indirect with Register Offset (Indexed)
- · Register Indirect with Literal Offset
- 8-bit Literal
- 16-bit Literal

Note:

Not all instructions support all the addressing modes given above. Individual instructions may support different subsets of these addressing modes.

#### 4.3.4 MAC INSTRUCTIONS

The dual source operand DSP instructions (CLR, ED, EDAC, MAC, MPY, MPY.N, MOVSAC and MSC), also referred to as MAC instructions, use a simplified set of addressing modes to allow the user application to effectively manipulate the Data Pointers through register indirect tables.

The two-source operand prefetch registers must be members of the set {W8, W9, W10, W11}. For data reads, W8 and W9 are always directed to the X RAGU, and W10 and W11 are always directed to the Y AGU. The Effective Addresses generated (before and after modification) must, therefore, be valid addresses within X data space for W8 and W9 and Y data space for W10 and W11.

Note: Register Indirect with Register Offset Addressing mode is available only for W9 (in X space) and W11 (in Y space).

In summary, the following addressing modes are supported by the MAC class of instructions:

- · Register Indirect
- · Register Indirect Post-Modified by 2
- · Register Indirect Post-Modified by 4
- Register Indirect Post-Modified by 6
- Register Indirect with Register Offset (Indexed)

#### 4.3.5 OTHER INSTRUCTIONS

Besides the addressing modes outlined previously, some instructions use literal constants of various sizes. For example, BRA (branch) instructions use 16-bit signed literals to specify the branch destination directly, whereas the DISI instruction uses a 14-bit unsigned literal field. In some instructions, such as ADD Acc, the source of an operand or result is implied by the opcode itself. Certain operations, such as NOP, do not have any operands.

### REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1 (CONTINUED)

bit 2 STKERR: Stack Error Trap Status bit

bit 0

1 = Stack error trap has occurred0 = Stack error trap has not occurred

bit 1 OSCFAIL: Oscillator Failure Trap Status bit

1 = Oscillator failure trap has occurred0 = Oscillator failure trap has not occurred

Unimplemented: Read as '0'

#### 10.6.2.2 Output Mapping

In contrast to inputs, the outputs of the Peripheral Pin Select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Like the RPINRx registers, each register contains sets of 6-bit fields, with each set associated with one RPn pin (see Register 10-15 through Register 10-31). The value of the bit field corresponds to one of the peripherals, and that peripheral's output is mapped to the pin (see Table 10-2 and Figure 10-3).

The list of peripherals for output mapping also includes a null value of '00000' because of the mapping technique. This permits any given pin to remain unconnected from the output of any of the pin selectable peripherals.

FIGURE 10-3: MULTIPLEXING OF REMAPPABLE OUTPUT

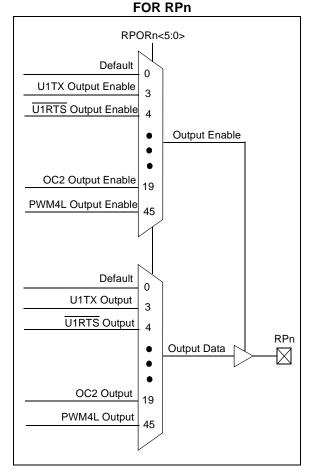


TABLE 10-2: OUTPUT SELECTION FOR REMAPPABLE PIN (RPn)

0000222	TO HOM TON NEWATT ABLE THE (INT.)
RPORn<5:0>	Output Name
000000	RPn tied to default port pin
000011	RPn tied to UART1 transmit
000100	RPn tied to UART1 Ready-to-Send
000111	RPn tied to SPI1 data output
001000	RPn tied to SPI1 clock output
001001	RPn tied to SPI1 slave select output
010010	RPn tied to Output Compare 1
010011	RPn tied to Output Compare 2
100101	RPn tied to external device synchronization signal via PWM master time base
100110	REFCLK output signal
100111	RPn tied to Analog Comparator Output 1
101000	RPn tied to Analog Comparator Output 2
101001	RPn tied to Analog Comparator Output 3
101010	RPn tied to Analog Comparator Output 4
101100	RPn tied to PWM output pins associated with PWM Generator 4
101101	RPn tied to PWM output pins associated with PWM Generator 4
	RPORn<5:0>  000000 000011 000100 000111 001000 001001

#### 10.7 Peripheral Pin Select Registers

dsPIC33FJ06GS101/X02 and dsPIC33FJ16GSX02/X04 families of devices implement 34 registers for remappable peripheral configuration:

- 15 Input Remappable Peripheral Registers
- 17 Output Remappable Peripheral Registers

Input and output register values can only be changed if OSCCON<IOLOCK> = 0. See **Section 10.6.3.1 "Control Register Lock"** for a specific command sequence.

Not all output remappable peripheral registers are implemented on all devices. See the specific register description for further details.

#### REGISTER 10-1: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
_	_	INT1R5	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 7			_	_	_		bit 0

Legend:

Note:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-8 INT1R<5:0>: Assign External Interrupt 1 (INTR1) to the Corresponding RPn Pin bits

111111 = Input tied to VSS

100011 = Input tied to RP35 100010 = Input tied to RP34

100001 = Input tied to RP33 100000 = Input tied to RP32

100000 – mpat

•

•

00000 = Input tied to RP0

bit 7-0 **Unimplemented:** Read as '0'

#### 11.0 TIMER1

Note 1: This data sheet summarizes the features of the dsPIC33FJ06GS101/X02 and dsPIC33FJ16GSX02/X04 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Timers" (DS70205) in the "dsPIC33F/PIC24H Family Reference Manual", which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer, which can serve as a time counter for the Real-Time Clock (RTC), or operate as a free-running interval timer/counter.

The Timer1 module has the following unique features over other timers:

- Can be operated from the low-power 32 kHz crystal oscillator available on the device
- Can be operated in Asynchronous Counter mode from an external clock source
- Optionally, the external clock input (T1CK) can be synchronized to the internal device clock and the clock synchronization is performed after the prescaler

The unique features of Timer1 allow it to be used for Real-Time Clock (RTC) applications. A block diagram of Timer1 is shown in Figure 11-1.

The Timer1 module can operate in one of the following modes:

- Timer mode
- · Gated Timer mode
- · Synchronous Counter mode
- · Asynchronous Counter mode

In Timer and Gated Timer modes, the input clock is derived from the internal instruction cycle clock (FcY). In Synchronous and Asynchronous Counter modes, the input clock is derived from the external clock input at the T1CK pin.

The Timer modes are determined by the following bits:

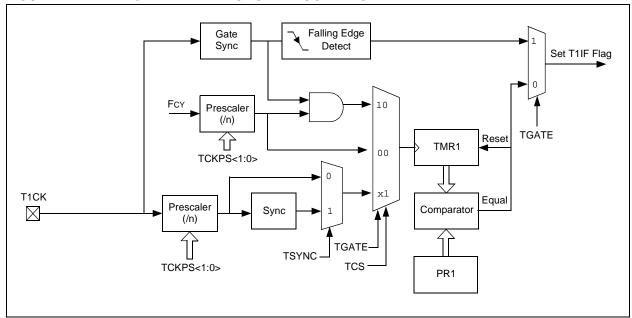
- Timer Clock Source Control bit (TCS): T1CON<1>
- Timer Synchronization Control bit (TSYNC): T1CON<2>
- Timer Gate Control bit (TGATE): T1CON<6>

The timer control bit settings for different operating modes are given in the Table 11-1.

TABLE 11-1: TIMER MODE SETTINGS

Mode	TCS	TGATE	TSYNC
Timer	0	0	х
Gated Timer	0	1	х
Synchronous Counter	1	х	1
Asynchronous Counter	1	х	0

FIGURE 11-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM



### REGISTER 16-2: SPIXCON1: SPIX CONTROL REGISTER 1 (CONTINUED)

- **Note 1:** The CKE bit is not used in the Framed SPI modes. Program this bit to '0' for the Framed SPI modes (FRMEN = 1).
  - **2:** Do not set both primary and secondary prescalers to a value of 1:1.
  - 3: This bit must be cleared when FRMEN = 1.

#### REGISTER 17-1: I2CxCON: I2Cx CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-1, HC	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	_	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0, HC				
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7							bit 0

 Legend:
 U = Unimplemented bit, read as '0'

 R = Readable bit
 W = Writable bit
 HC = Hardware Clearable bit

 -n = Value at POR
 '1' = Bit is set
 '0' = Bit is cleared
 x = Bit is unknown

bit 15 I2CEN: I2Cx Enable bit

1 = Enables the I2Cx module, and configures the SDAx and SCLx pins as serial port pins

0 = Disables the I2Cx module; all  $I^2C^{TM}$  pins are controlled by port functions.

bit 14 Unimplemented: Read as '0'

bit 13 I2CSIDL: I2Cx Stop in Idle Mode bit

1 = Discontinues module operation when device enters an Idle mode

0 = Continues module operation in Idle mode

bit 12 SCLREL: SCLx Release Control bit (when operating as I<sup>2</sup>C slave)

1 = Releases SCLx clock

0 = Holds SCLx clock low (clock stretch)

If STREN = 1

Bit is R/W (i.e., software can write '0' to initiate stretch and write '1' to release clock). Hardware clear at beginning of slave transmission. Hardware clear at end of slave reception.

If STREN = 0:

Bit is R/S (i.e., software can only write '1' to release clock). Hardware clear at beginning of slave transmission.

bit 11 IPMIEN: Intelligent Peripheral Management Interface (IPMI) Enable bit

1 = IPMI mode is enabled; all addresses are Acknowledged

0 = IPMI mode is disabled

bit 10 A10M: 10-Bit Slave Address bit

1 = I2CxADD is a 10-bit slave address 0 = I2CxADD is a 7-bit slave address

bit 9 **DISSLW**: Disable Slew Rate Control bit

1 = Slew rate control is disabled

0 = Slew rate control is enabled

bit 8 SMEN: SMBus Input Levels bit

1 = Enables I/O pin thresholds compliant with SMBus specification

0 = Disables SMBus input thresholds

bit 7 **GCEN:** General Call Enable bit (when operating as I<sup>2</sup>C slave)

1 = Enables interrupt when a general call address is received in the I2CxRSR (module is enabled for reception)

0 = General call address is disabled

bit 6 STREN: SCLx Clock Stretch Enable bit (when operating as I<sup>2</sup>C slave)

Used in conjunction with the SCLREL bit.

1 = Enables software or receive clock stretching

0 = Disables software or receive clock stretching

## REGISTER 19-7: ADCPC2: ANALOG-TO-DIGITAL CONVERT PAIR CONTROL REGISTER 2<sup>(1)</sup> (CONTINUED)

```
bit 4-0
               TRGSRC4<4:0>: Trigger 4 Source Selection bits
               Selects trigger source for conversion of Analog Channels AN9 and AN8.
               11111 = Timer2 period match
               11011 = Reserved
               11010 = PWM Generator 4 current-limit ADC trigger
               11001 = PWM Generator 3 current-limit ADC trigger
               11000 = PWM Generator 2 current-limit ADC trigger
               10111 = PWM Generator 1 current-limit ADC trigger
               10110 = Reserved
               10010 = Reserved
               10001 = PWM Generator 4 secondary trigger is selected
               10000 = PWM Generator 3 secondary trigger is selected
               01111 = PWM Generator 2 secondary trigger is selected
               01110 = PWM Generator 1 secondary trigger is selected
               01101 = Reserved
               01100 = Timer1 period match
               01000 = Reserved
               00111 = PWM Generator 4 primary trigger is selected
               00110 = PWM Generator 3 primary trigger is selected
               00101 = PWM Generator 2 primary trigger is selected
               00100 = PWM Generator 1 primary trigger is selected
               00011 = PWM Special Event Trigger is selected
               00010 = Global software trigger is selected
               00001 = Individual software trigger is selected
               00000 = No conversion is enabled
```

- Note 1: This register is only implemented in the dsPIC33FJ16GS504 devices.
  - 2: The trigger source must be set as a global software trigger prior to setting this bit to '1'. If other conversions are in progress, then the conversion will be performed when the conversion resources are available.

### TABLE 24-19: AC CHARACTERISTICS: INTERNAL FRC ACCURACY

AC CHA	RACTERISTICS	Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $ -40^{\circ}C \leq TA \leq +85^{\circ}C \text{ for industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \text{ for Extended} $						
Param No.	Characteristic		Тур	Max	Units	Condi	ions	
Internal	Internal FRC Accuracy @ FRC Frequency = 7.37 MHz <sup>(1)</sup>							
F20a	FRC	-2	_	+2	%	$-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$ VDD = 3.0-3.6		
F20b	FRC	-5	_	+5	%	$-40$ °C $\leq$ TA $\leq$ $+125$ °C	VDD = 3.0-3.6V	

Note 1: Frequency calibrated at +25°C and 3.3V. TUNx bits can be used to compensate for temperature drift.

#### TABLE 24-20: AC CHARACTERISTICS: INTERNAL LPRC ACCURACY

AC CH	ARACTERISTICS	Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \le \text{TA} \le +125^{\circ}\text{C}$ for Extended						
Param No.	Characteristic	Min	Тур	Max	Units	Conditions		
LPRC @ 32.768 kHz <sup>(1)</sup>								
F21a	LPRC	-20	±6	+20	%	-40°C ≤ TA ≤ +85°C		
F21b	LPRC	-70	_	+70	%	-40°C ≤ TA ≤ +125°C	VDD = 3.0-3.6V	

Note 1: Change of LPRC frequency as VDD changes.

FIGURE 24-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING CHARACTERISTICS

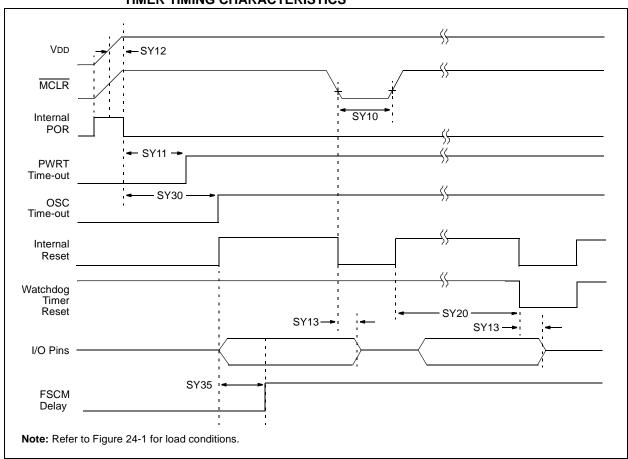


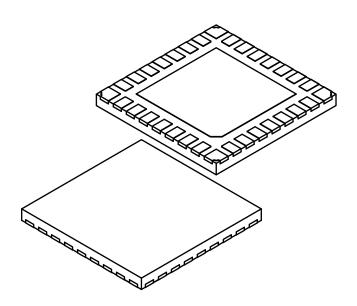
TABLE 24-37: SPIX SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING REQUIREMENTS

AC CHA	AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)  Operating temperature $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \le \text{TA} \le +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min Typ <sup>(2)</sup> Max		Units	Conditions		
SP70	TscP	Maximum SCKx Input Frequency			11	MHz	See Note 3	
SP72	TscF	SCKx Input Fall Time	_	_	_	ns	See Parameter DO32 and <b>Note 4</b>	
SP73	TscR	SCKx Input Rise Time	_	-	_	ns	See Parameter DO31 and <b>Note 4</b>	
SP30	TdoF	SDOx Data Output Fall Time		-	ı	ns	See Parameter DO32 and <b>Note 4</b>	
SP31	TdoR	SDOx Data Output Rise Time	_		_	ns	See Parameter DO31 and <b>Note 4</b>	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	_	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	_	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	_	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	_	_	ns		
SP50	TssL2scH, TssL2scL	SSx ↓ to SCKx ↑ or SCKx Input	120	-	_	ns		
SP51	TssH2doZ	SSx ↑ to SDOx Output High-Impedance	10	_	50	ns	See Note 4	
SP52	TscH2ssH TscL2ssH	SSx after SCKx Edge	1.5 Tcy + 40	—	_	ns	See Note 4	

- Note 1: These parameters are characterized, but are not tested in manufacturing.
  - 2: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated.
  - 3: The minimum clock period for SCKx is 91 ns. Therefore, the SCKx clock generated by the Master must not violate this specification.
  - 4: Assumes 50 pF load on all SPIx pins.

## 28-Lead Plastic Quad Flat, No Lead Package (MX) - 6x6x0.5mm Body [UQFN] Ultra-Thin with 0.40 x 0.60 mm Terminal Width/Length and Corner Anchors

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units			S	
Dimension	Limits	MIN	NOM	MAX	
Number of Pins	N	28			
Pitch	е		0.65 BSC		
Overall Height	Α	0.40	0.50	0.60	
Standoff	A1	0.00	0.02	0.05	
Terminal Thickness	(A3)	0.127 REF			
Overall Width	Е	6.00 BSC			
Exposed Pad Width	E2	4.00			
Overall Length	D		6.00 BSC		
Exposed Pad Length	D2		4.00		
Terminal Width	b	0.35 0.40 0.45			
Corner Pad	b2	0.25 0.40 0.45			
Terminal Length	L	0.55 0.60 0.65			
Terminal-to-Exposed Pad	K	0.20	-	-	

#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated
- 3. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.

4. Outermost portions of corner structures may vary slightly.

Microchip Technology Drawing  $\,$  C04-0209B Sheet 2 of 2