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## What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "Embedded - Microcontrollers"

| Details | |
|---|---|
| Product Status | Active |
| Core Processor | PIC |
| Core Size | 16-Bit |
| Speed | 32MHz |
| Connectivity | I²C, IrDA, LINbus, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, HLVD, POR, PWM, WDT |
| Number of I/O | 17 |
| Program Memory Size | 4KB (1.375K x 24) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 512 x 8 |
| Voltage - Supply (Vcc/Vdd) | 1.8V ~ 3.6V |
| Data Converters | - |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 20-SSOP (0.209", 5.30mm Width) |
| Supplier Device Package | 20-SSOP |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic24f04kl101-i-ss |

## 2.2 Power Supply Pins

### 2.2.1 DECOUPLING CAPACITORS

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, AVDD and AVSS, is required.

Consider the following criteria when using decoupling capacitors:

- **Value and type of capacitor:** A 0.1 μF (100 nF), 10-20V capacitor is recommended. The capacitor should be a low-ESR device, with a resonance frequency in the range of 200 MHz and higher. Ceramic capacitors are recommended.
- **Placement on the printed circuit board:** The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is no greater than 0.25 inch (6 mm).
- **Handling high-frequency noise:** If the board is experiencing high-frequency noise (upward of tens of MHz), add a second ceramic type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01 μF to 0.001 μF. Place this second capacitor next to each primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible (e.g., 0.1 μF in parallel with 0.001 μF).
- **Maximizing performance:** On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum, thereby reducing PCB trace inductance.

### 2.2.2 TANK CAPACITORS

On boards with power traces running longer than six inches in length, it is suggested to use a tank capacitor for integrated circuits, including microcontrollers, to supply a local power source. The value of the tank capacitor should be determined based on the trace resistance that connects the power supply source to the device, and the maximum current drawn by the device in the application. In other words, select the tank capacitor so that it meets the acceptable voltage sag at the device. Typical values range from 4.7 μF to 47 μF.

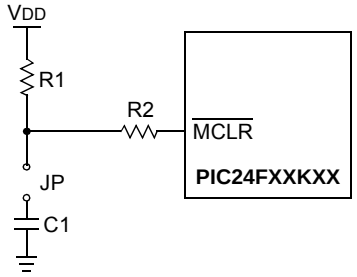
## 2.3 Master Clear ($\overline{\text{MCLR}}$) Pin

The $\overline{\text{MCLR}}$ pin provides two specific device functions: Device Reset, and Device Programming and Debugging. If programming and debugging are not required in the end application, a direct connection to VDD may be all that is required. The addition of other components, to help increase the application's resistance to spurious Resets from voltage sags, may be beneficial. A typical configuration is shown in Figure 2-1. Other circuit designs may be implemented, depending on the application's requirements.

During programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the $\overline{\text{MCLR}}$ pin. Consequently, specific voltage levels (VIH and VIL) and fast signal transitions must not be adversely affected. Therefore, specific values of R1 and C1 will need to be adjusted based on the application and PCB requirements. For example, it is recommended that the capacitor, C1, be isolated from the $\overline{\text{MCLR}}$ pin during programming and debugging operations by using a jumper (Figure 2-2). The jumper is replaced for normal run-time operations.

Any components associated with the $\overline{\text{MCLR}}$ pin should be placed within 0.25 inch (6 mm) of the pin.

**FIGURE 2-2: EXAMPLE OF $\overline{\text{MCLR}}$ PIN CONNECTIONS**




**Note 1:** R1 ≤ 10 kΩ is recommended. A suggested starting value is 10 kΩ. Ensure that the $\overline{\text{MCLR}}$ pin VIH and VIL specifications are met.

**2:** R2 ≤ 470Ω will limit any current flowing into $\overline{\text{MCLR}}$ from the external capacitor, C, in the event of $\overline{\text{MCLR}}$ pin breakdown, due to Electrostatic Discharge (ESD) or Electrical Overstress (EOS). Ensure that the $\overline{\text{MCLR}}$ pin VIH and VIL specifications are met.

**TABLE 4-3: CPU CORE REGISTERS MAP**

| File Name | Start Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| WREG0 | 0000 | Working Register 0 | | | | | | | | | | | | | | | | 0000 |
| WREG1 | 0002 | Working Register 1 | | | | | | | | | | | | | | | | 0000 |
| WREG2 | 0004 | Working Register 2 | | | | | | | | | | | | | | | | 0000 |
| WREG3 | 0006 | Working Register 3 | | | | | | | | | | | | | | | | 0000 |
| WREG4 | 0008 | Working Register 4 | | | | | | | | | | | | | | | | 0000 |
| WREG5 | 000A | Working Register 5 | | | | | | | | | | | | | | | | 0000 |
| WREG6 | 000C | Working Register 6 | | | | | | | | | | | | | | | | 0000 |
| WREG7 | 000E | Working Register 7 | | | | | | | | | | | | | | | | 0000 |
| WREG8 | 0010 | Working Register 8 | | | | | | | | | | | | | | | | 0000 |
| WREG9 | 0012 | Working Register 9 | | | | | | | | | | | | | | | | 0000 |
| WREG10 | 0014 | Working Register 10 | | | | | | | | | | | | | | | | 0000 |
| WREG11 | 0016 | Working Register 11 | | | | | | | | | | | | | | | | 0000 |
| WREG12 | 0018 | Working Register 12 | | | | | | | | | | | | | | | | 0000 |
| WREG13 | 001A | Working Register 13 | | | | | | | | | | | | | | | | 0000 |
| WREG14 | 001C | Working Register 14 | | | | | | | | | | | | | | | | 0000 |
| WREG15 | 001E | Working Register 15 | | | | | | | | | | | | | | | — | 0800 |
| SPLIM | 0020 | Stack Pointer Limit Value Register | | | | | | | | | | | | | | | | xxxx |
| PCL | 002E | Program Counter Low Word Register | | | | | | | | | | | | | | | | 0000 |
| PCH | 0030 | — | — | — | — | — | — | — | — | — | Program Counter Register High Byte | | | | | | | 0000 |
| TBLPAG | 0032 | — | — | — | — | — | — | — | — | Table Memory Page Address Register | | | | | | | | 0000 |
| PSVPAG | 0034 | — | — | — | — | — | — | — | — | Program Space Visibility Page Address Register | | | | | | | | 0000 |
| RCOUNT | 0036 | REPEAT Loop Counter Register | | | | | | | | | | | | | | | | xxxxx |
| SR | 0042 | — | — | — | — | — | — | — | DC | IPL2 | IPL1 | IPL0 | RA | N | OV | Z | C | 0000 |
| CORCON | 0044 | — | — | — | — | — | — | — | — | — | — | — | — | IPL3 | PSV | — | — | 0000 |
| DISICNT | 0052 | — | — | Disable Interrupts Counter Register | | | | | | | | | | | | | | xxxx |

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-13: A/D REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| ADC1BUF0 | 0300 | A/D Buffer 0 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF1 | 0302 | A/D Buffer 1 | | | | | | | | | | | | | | | | xxxx |
| AD1CON1 | 0320 | ADON | — | ADSIDL | — | — | — | FORM1 | FORM0 | SSRC2 | SSRC1 | SSRC0 | — | — | ASAM | SAMP | DONE | 0000 |
| AD1CON2 | 0322 | VCFG2 | VCFG1 | VCFG0 | OFFCAL | — | CSCNA | — | — | r | — | SMPI3 | SMPI2 | SMPI1 | SMPI0 | r | ALTS | 0000 |
| AD1CON3 | 0324 | ADRC | EXTSAM | PUMPEN | SAMC4 | SAMC3 | SAMC2 | SAMC1 | SAMC0 | — | — | ADCS5 | ADCS4 | ADCS3 | ADCS2 | ADCS1 | ADCS0 | 0000 |
| AD1CHS | 0328 | CH0NB | — | — | — | CH0SB3 | CH0SB2 | CH0SB1 | CH0SB0 | CH0NA | — | — | — | CH0SA3 | CH0SA2 | CH0SA1 | CH0SA0 | 0000 |
| AD1CSSL | 0330 | CSSL15 | CSSL14 | CSSL13 | CSSL12(1) | CSSL11(1) | CSSL10 | CSSL9 | CSSL8 | CSSL7 | CSSL6 | — | CSSL4(1) | CSSL3(1) | CSSL2(1) | CSSL1 | CSSL0 | 0000 |

**Legend:** — = unimplemented, read as '0', r = reserved bit. Reset values are shown in hexadecimal.

**Note 1:** These bits are unimplemented in 14-pin devices; read as '0'.

**TABLE 4-14: ANALOG SELECT REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| ANCFG | 04DE | — | — | — | — | — | — | — | — | — | — | — | — | — | — | — | VBGEN | 0000 |
| ANSA | 04E0 | — | — | — | — | — | — | — | — | — | — | — | — | ANSA3 | ANSA2 | ANSA1 | ANSA0 | 000F |
| ANSB | 04E2 | ANSB15 | ANSB14 | ANSB13 | ANSB12(1) | — | — | — | — | — | — | — | ANSB4 | ANSB3(2) | ANSB2(1) | ANSB1(1) | ANSB0(1) | F01F(3) |

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** These bits are unimplemented in 14-pin devices; read as '0'.

**2:** These bits are unimplemented in 14-pin and 20-pin devices; read as '0'

**3:** Reset value for 28-pin devices is shown.

**TABLE 4-15: COMPARATOR REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| CMSTAT | 0630 | CMIDL | — | — | — | — | — | C2EVT(1) | C1EVT | — | — | — | — | — | — | C2OUT | C1OUT | xxxx |
| CVRCON | 0632 | — | — | — | — | — | — | — | — | CVREN | CVROE | CVRSS | CVR4 | CVR3 | CVR2 | CVR1 | CVR0 | 0000 |
| CM1CON | 0634 | CON | COE | CPOL | CLPWR | — | — | CEVT | COUT | EVPOL1 | EVPOL0 | — | CREF | — | — | CCH1 | CCH0 | xxxx |
| CM2CON(1) | 0636 | CON | COE | CPOL | CLPWR | — | — | CEVT | COUT | EVPOL1 | EVPOL0 | — | CREF | — | — | CCH1 | CCH0 | 0000 |

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** These bits and/or registers are unimplemented in PIC24FXXKL10X/20X devices; read as '0'.

**REGISTER 8-27: IPC16: INTERRUPT PRIORITY CONTROL REGISTER 16**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | U2ERIP2(1) | U2ERIP1(1) | U2ERIP0(1) |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | U1ERIP2(1) | U1ERIP1(1) | U1ERIP0(1) | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **U2ERIP<2:0>:** UART2 Error Interrupt Priority bits(1)
111 = Interrupt is Priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is Priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **U1ERIP<2:0>:** UART1 Error Interrupt Priority bits(1)
111 = Interrupt is Priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is Priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

**Note 1:** These bits are unimplemented on PIC24FXXKL10X and PIC24FXXKL20X devices.

## 8.4 Interrupt Setup Procedures

### 8.4.1 INITIALIZATION

To configure an interrupt source:

1. Set the NSTDIS Control bit (INTCON1<15>) if nested interrupts are not desired.
2. Select the user-assigned priority level for the interrupt source by writing the control bits in the appropriate IPCx register. The priority level will depend on the specific application and the type of interrupt source. If multiple priority levels are not desired, the IPCx register control bits, for all enabled interrupt sources, may be programmed to the same non-zero value.

| **Note:** | At a device Reset, the IPCx registers are initialized, such that all user interrupt sources are assigned to Priority Level 4. |
|---|---|

3. Clear the interrupt flag status bit associated with the peripheral in the associated IFSx register.
4. Enable the interrupt source by setting the interrupt enable control bit associated with the source in the appropriate IECx register.

### 8.4.2 INTERRUPT SERVICE ROUTINE

The method that is used to declare an ISR and initialize the IVT with the correct vector address depends on the programming language (i.e., C or assembler) and the language development toolsuite that is used to develop the application. In general, the user must clear the interrupt flag in the appropriate IFSx register for the source of the interrupt that the ISR handles. Otherwise, the ISR will be re-entered immediately after exiting the routine. If the ISR is coded in assembly language, it must be terminated using a `RETFIE` instruction to unstack the saved PC value, SRL value and old CPU priority level.

### 8.4.3 TRAP SERVICE ROUTINE (TSR)

A Trap Service Routine (TSR) is coded like an ISR, except that the appropriate trap status flag in the INTCON1 register must be cleared to avoid re-entry into the TSR.

### 8.4.4 INTERRUPT DISABLE

All user interrupts can be disabled using the following procedure:

1. Push the current SR value onto the software stack using the `PUSH` instruction.
2. Force the CPU to Priority Level 7 by inclusive ORing the value, OEh, with SRL.

To enable user interrupts, the `POP` instruction may be used to restore the previous SR value.

Only user interrupts with a priority level of 7 or less can be disabled. Trap sources (Levels 8-15) cannot be disabled.

The `DISI` instruction provides a convenient way to disable interrupts of Priority Levels 1-6 for a fixed period. Level 7 interrupt sources are not disabled by the `DISI` instruction.

**NOTES:**

## 11.3 Input Change Notification

The Input Change Notification (ICN) function of the I/O ports allows the PIC24F16KL402 family of devices to generate interrupt requests to the processor in response to a Change-of-State (COS) on selected input pins. This feature is capable of detecting input Change-of-States, even in Sleep mode, when the clocks are disabled. Depending on the device pin count, there are up to 23 external signals that may be selected (enabled) for generating an interrupt request on a Change-of-State.

There are six control registers associated with the Change Notification (CN) module. The CNEN1 and CNEN2 registers contain the interrupt enable control bits for each of the CN input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

Each CN pin also has a weak pull-up/pull-down connected to it. The pull-ups act as a current source that is connected to the pin. The pull-downs act as a current sink to eliminate the need for external resistors when push button or keypad devices are connected.

On any pin, only the pull-up resistor or the pull-down resistor should be enabled, but not both of them. If the push button or the keypad is connected to $V_{DD}$, enable the pull-down, or if they are connected to $V_{SS}$, enable the pull-up resistors. The pull-ups are enabled separately using the CNPU1 and CNPU2 registers, which contain the control bits for each of the CN pins.

Setting any of the control bits enables the weak pull-ups for the corresponding pins. The pull-downs are enabled separately, using the CNPD1 and CNPD2 registers, which contain the control bits for each of the CN pins. Setting any of the control bits enables the weak pull-downs for the corresponding pins.

When the internal pull-up is selected, the pin uses $V_{DD}$ as the pull-up source voltage. When the internal pull-down is selected, the pins are pulled down to $V_{SS}$ by an internal resistor. Make sure that there is no external pull-up source/pull-down sink when the internal pull-ups/pull-downs are enabled.

| **Note:** | Pull-ups and pull-downs on Change Notification pins should always be disabled whenever the port pin is configured as a digital output. |
|---|---|

**EXAMPLE 11-1: PORT WRITE/READ EXAMPLE (ASSEMBLY LANGUAGE)**

```
MOV     #0xFF00, W0        ; Configure PORTB<15:8> as inputs and PORTB<7:0> as outputs
MOV     W0, TRISB
MOV     #0x00FF, W0        ; Enable PORTB<15:8> digital input buffers
MOV     W0, ANSB
NOP                        ; Delay 1 cycle
BTSS    PORTB, #13         ; Next Instruction
```

**EXAMPLE 11-2: PORT WRITE/READ EXAMPLE (C LANGUAGE)**

```
TRISB = 0xFF00;            // Configure PORTB<15:8> as inputs and PORTB<7:0> as outputs
ANSB = 0x00FF;             // Enable PORTB<15:8> digital input buffers
NOP();                     // Delay 1 cycle
if(PORTBbits.RB13 == 1)    // execute following code if PORTB pin 13 is set.
{
}
```

**REGISTER 12-1: T1CON: TIMER1 CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| TON | — | TSIDL | — | — | — | T1ECS1(1) | T1ECS0(1) |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | TGATE | TCKPS1 | TCKPS0 | — | TSYNC | TCS | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **TON:** Timer1 On bit
1 = Starts 16-bit Timer1
0 = Stops 16-bit Timer1

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Timer1 Stop in Idle Mode bit
1 = Discontinues module operation when device enters Idle mode
0 = Continues module operation in Idle mode

bit 12-10 **Unimplemented:** Read as '0'

bit 9-8 **T1ECS <1:0>:** Timer1 Extended Clock Select bits(1)
11 = Reserved; do not use
10 = Timer1 uses the LPRC as the clock source
01 = Timer1 uses the external clock from T1CK
00 = Timer1 uses the Secondary Oscillator (SOSC) as the clock source

bit 7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timer1 Gated Time Accumulation Enable bit
When TCS = 1:
This bit is ignored.
When TCS = 0:
1 = Gated time accumulation is enabled
0 = Gated time accumulation is disabled

bit 5-4 **TCKPS<1:0>:** Timer1 Input Clock Prescale Select bits
11 = 1:256
10 = 1:64
01 = 1:8
00 = 1:1

bit 3 **Unimplemented:** Read as '0'

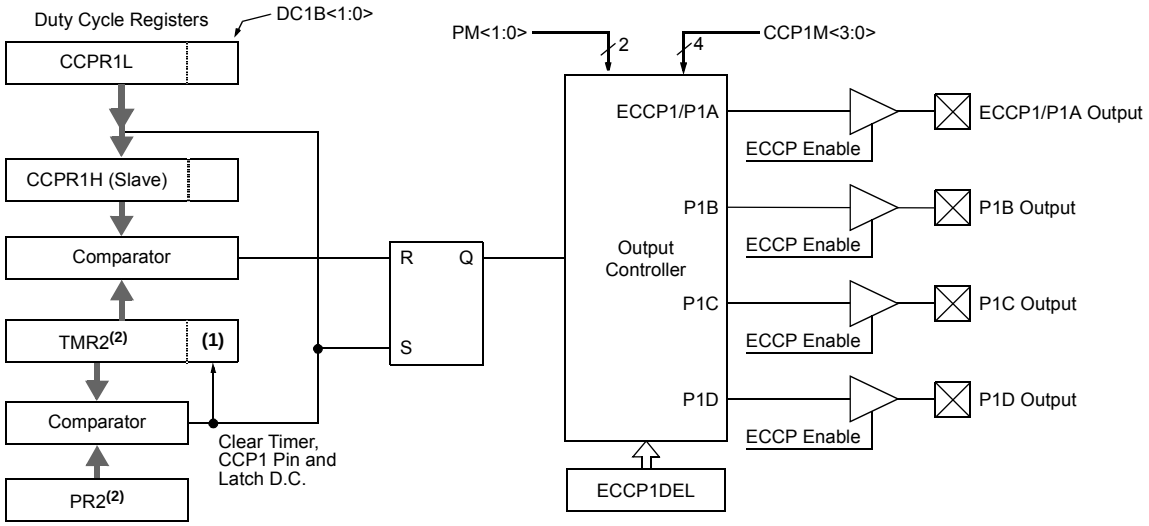
bit 2 **TSYNC:** Timer1 External Clock Input Synchronization Select bit
When TCS = 1:
1 = Synchronizes external clock input
0 = Does not synchronize external clock input
When TCS = 0:
This bit is ignored.

bit 1 **TCS:** Timer1 Clock Source Select bit
1 = Timer1 clock source is selected by T1ECS<1:0>
0 = Internal clock (FOSC/2)

bit 0 **Unimplemented:** Read as '0'

**Note 1:** The T1ECSx bits are valid only when TCS = 1.

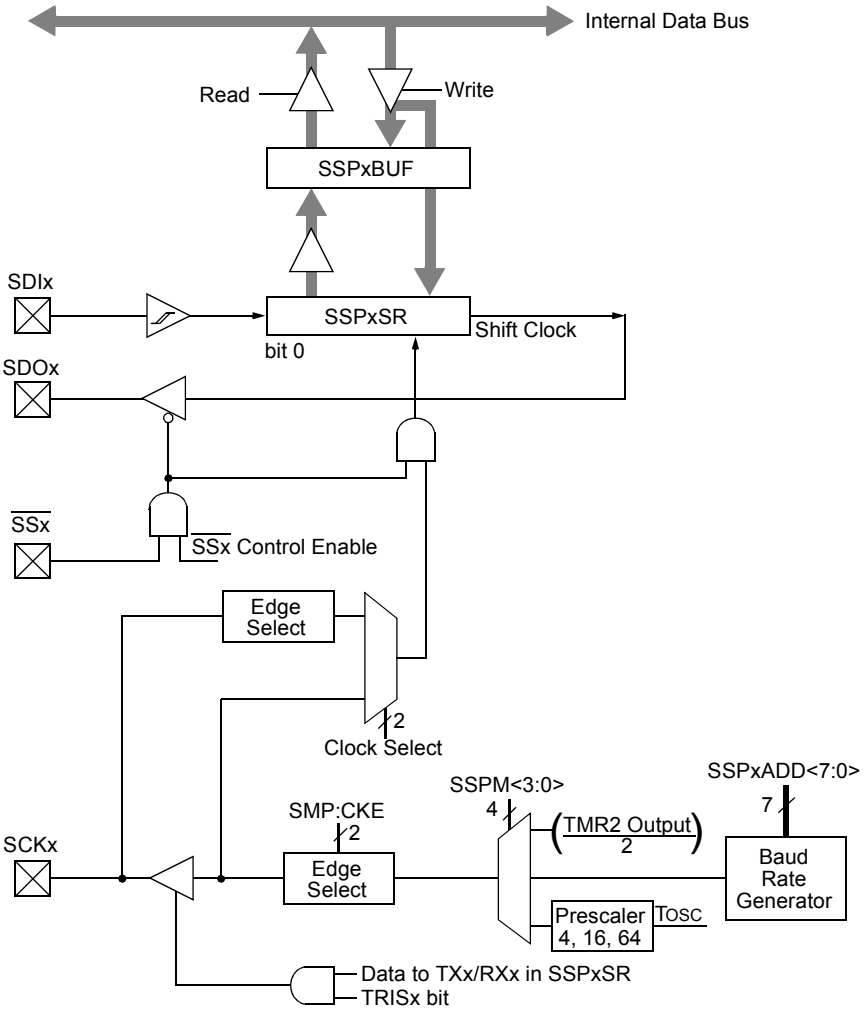
**FIGURE 16-4: SIMPLIFIED BLOCK DIAGRAM OF ENHANCED PWM MODE**




**Note 1:** The 8-bit TMR2 value is concatenated with the 2-bit internal Q clock, or 2 bits of the prescaler, to create the 10-bit time base.

**2:** Either Timer2 or Timer4 may be used as the Enhanced PWM time base.

**FIGURE 17-1: MSSPx BLOCK DIAGRAM (SPI MODE)**




**Note:** Refer to the device data sheet for pin multiplexing.

**FIGURE 17-2: SPI MASTER/SLAVE CONNECTION**

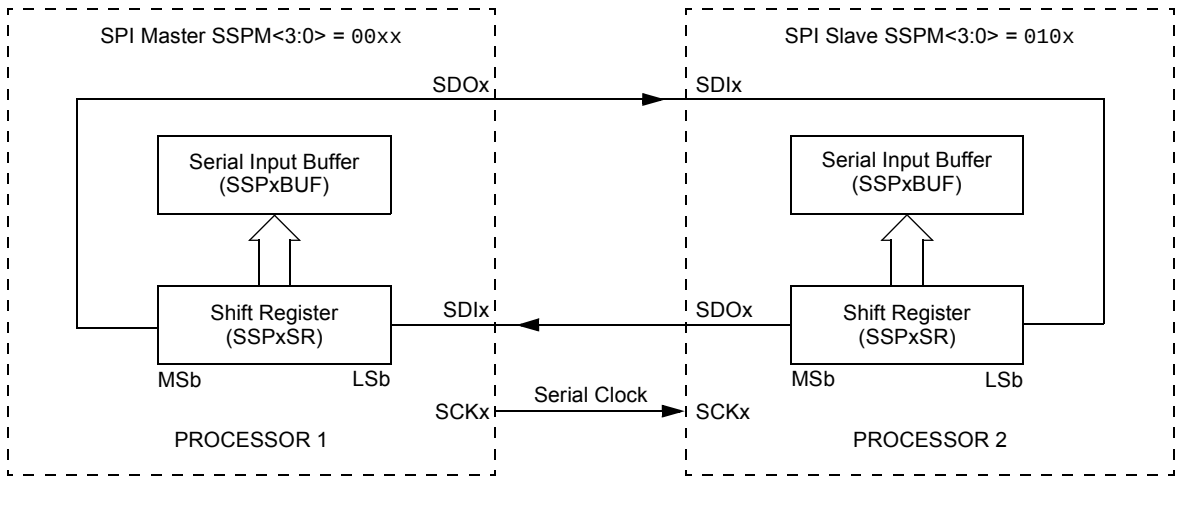
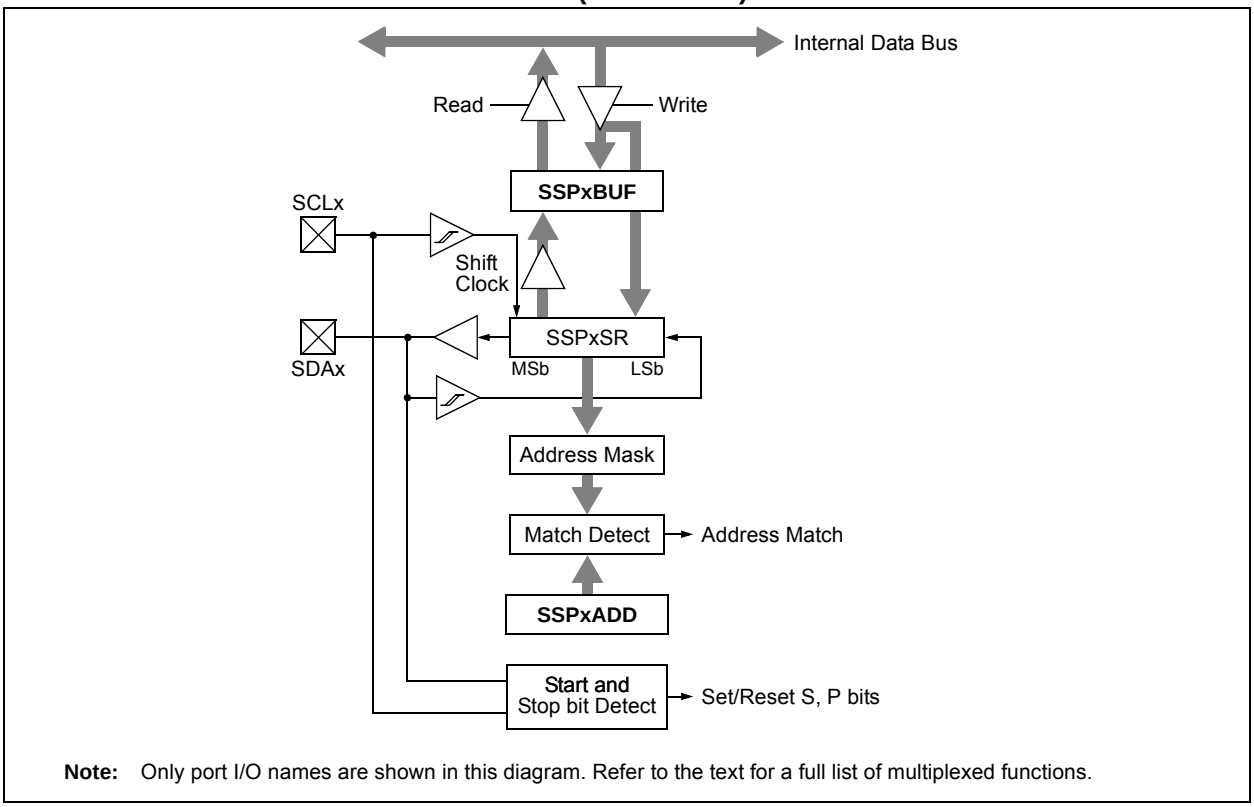
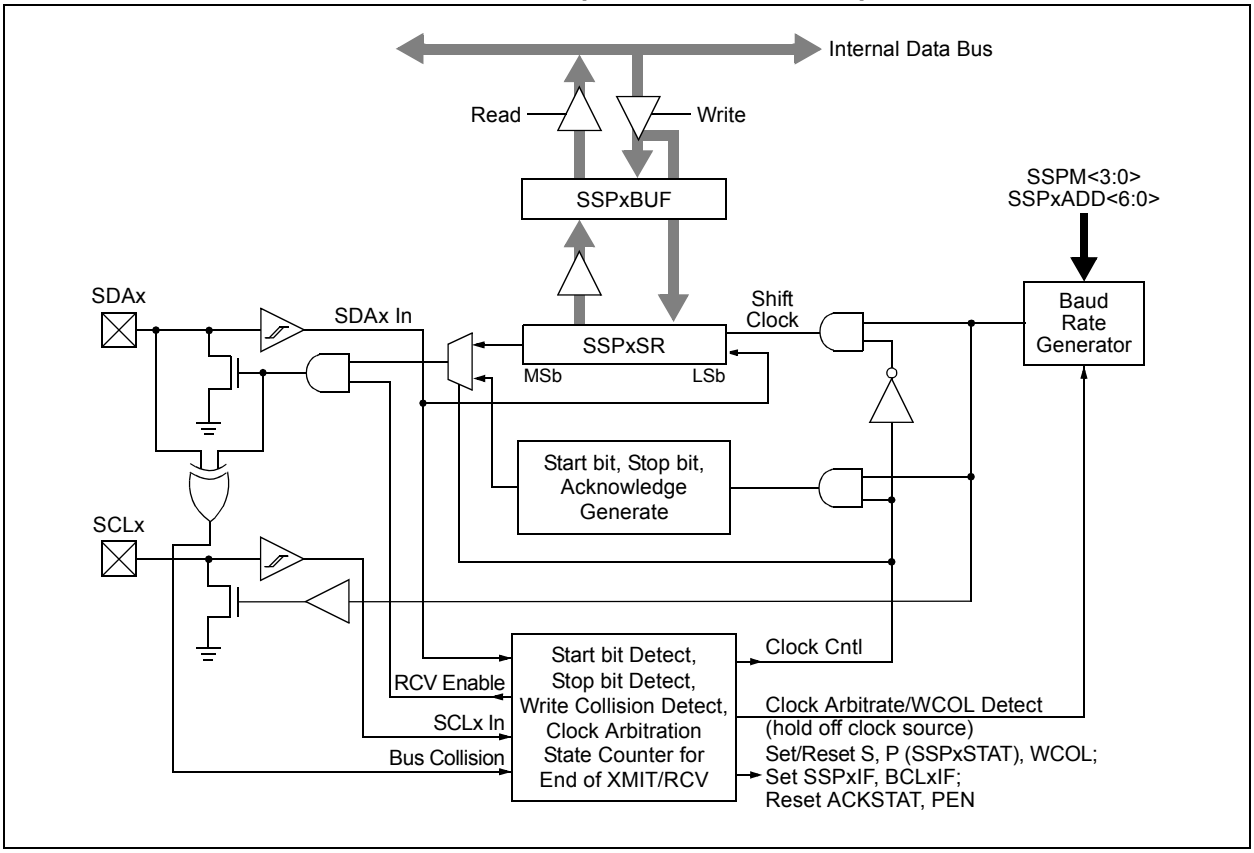


**FIGURE 17-3: MSSPx BLOCK DIAGRAM (I²C™ MODE)**




**Note:** Only port I/O names are shown in this diagram. Refer to the text for a full list of multiplexed functions.

**FIGURE 17-4: MSSPx BLOCK DIAGRAM (I²C™ MASTER MODE)**



**REGISTER 18-1: UxMODE: UARTx MODE REGISTER**

| R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0(2) | R/W-0(2) |
|---|---|---|---|---|---|---|---|
| UARTEN | — | USIDL | IREN(1) | RTSMD | — | UEN1 | UEN0 |
| bit 15 | | | | | | | bit 8 |

| R/C-0, HC | R/W-0 | R/W-0, HC | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| WAKE | LPBACK | ABAUD | RXINV | BRGH | PDSEL1 | PDSEL0 | STSEL |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | C = Clearable bit | HC = Hardware Clearable bit | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **UARTEN:** UARTx Enable bit
- 1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>
- 0 = UARTx is disabled; all UARTx pins are controlled by port latches, UARTx power consumption is minimal

bit 14 **Unimplemented:** Read as '0'

bit 13 **USIDL:** UARTx Stop in Idle Mode bit
- 1 = Discontinues module operation when device enters Idle mode
- 0 = Continues module operation in Idle mode

bit 12 **IREN:** IrDA® Encoder and Decoder Enable bit(1)
- 1 = IrDA encoder and decoder are enabled
- 0 = IrDA encoder and decoder are disabled

bit 11 **RTSMD:** Mode Selection for $\overline{\text{UxRTS}}$ Pin bit
- 1 = $\overline{\text{UxRTS}}$ pin is in Simplex mode
- 0 = $\overline{\text{UxRTS}}$ pin is in Flow Control mode

bit 10 **Unimplemented:** Read as '0'

bit 9-8 **UEN<1:0>:** UARTx Enable bits(2)
- 11 = UxTX, UxRX and UxBCLK pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by port latches
- 10 = UxTX, UxRX, $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins are enabled and used
- 01 = UxTX, UxRX and $\overline{\text{UxRTS}}$ pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by port latches
- 00 = UxTX and UxRX pins are enabled and used; $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$/UxBCLK pins are controlled by port latches

bit 7 **WAKE:** Wake-up on Start Bit Detect During Sleep Mode Enable bit
- 1 = UARTx will continue to sample the UxRX pin; interrupt is generated on the falling edge, bit is cleared in hardware on the following rising edge
- 0 = No wake-up is enabled

bit 6 **LPBACK:** UARTx Loopback Mode Select bit
- 1 = Enables Loopback mode
- 0 = Loopback mode is disabled

bit 5 **ABAUD:** Auto-Baud Enable bit
- 1 = Enables baud rate measurement on the next character – requires reception of a Sync field (55h); cleared in hardware upon completion
- 0 = Baud rate measurement is disabled or completed

bit 4 **RXINV:** Receive Polarity Inversion bit
- 1 = UxRX Idle state is '0'
- 0 = UxRX Idle state is '1'

**Note 1:** This feature is is only available for the 16x BRG mode (BRGH = 0).
**2:** Bit availability depends on pin availability.

## 19.0 10-BIT HIGH-SPEED A/D CONVERTER

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information on the 10-Bit High-Speed A/D Converter, refer to the *"dsPIC33/PIC24 Family Reference Manual"*, **"10-Bit A/D Converter"** (DS39705).

The 10-bit A/D Converter has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 500 ksps
- Up to 12 analog input pins
- External voltage reference input pins
- Internal band gap reference input
- Automatic Channel Scan mode
- Selectable conversion trigger source
- Two-word conversion result buffer
- Selectable Buffer Fill modes
- Four result alignment options
- Operation during CPU Sleep and Idle modes

Depending on the particular device, PIC24F16KL402 family devices implement up to 12 analog input pins, designated AN0 through AN4 and AN9 through AN15. In addition, there are two analog input pins for external voltage reference connections ($V_{REF}$+ and $V_{REF}$-). These voltage reference inputs may be shared with other analog input pins.

A block diagram of the A/D Converter is displayed in Figure 19-1.

To perform an A/D conversion:

1. Configure the A/D module:
   a) Configure port pins as analog inputs and/or select band gap reference inputs (ANSA<3:0>, ANSB<15:12,4:0> and ANCFG<0>).
   b) Select the voltage reference source to match the expected range on analog inputs (AD1CON2<15:13>).
   c) Select the analog conversion clock to match the desired data rate with the processor clock (AD1CON3<7:0>).
   d) Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>).
   e) Select how conversion results are presented in the buffer (AD1CON1<9:8>).
   f) Select interrupt rate (AD1CON2<5:2>).
   g) Turn on A/D module (AD1CON1<15>).
2. Configure A/D interrupt (if required):
   a) Clear the AD1IF bit.
   b) Select A/D interrupt priority.

**REGISTER 20-1: CMxCON: COMPARATOR x CONTROL REGISTER**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | R/W-0 | R-0 |
|---|---|---|---|---|---|---|---|
| CON | COE | CPOL | CLPWR | — | — | CEVT | COUT |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | U-0 | R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| EVPOL1(1) | EVPOL0(1) | — | CREF | — | — | CCH1 | CCH0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **CON:** Comparator Enable bit
1 = Comparator is enabled
0 = Comparator is disabled

bit 14 **COE:** Comparator Output Enable bit
1 = Comparator output is present on the CxOUT pin
0 = Comparator output is internal only

bit 13 **CPOL:** Comparator Output Polarity Select bit
1 = Comparator output is inverted
0 = Comparator output is not inverted

bit 12 **CLPWR:** Comparator Low-Power Mode Select bit
1 = Comparator operates in Low-Power mode
0 = Comparator does not operate in Low-Power mode

bit 11-10 **Unimplemented:** Read as '0'

bit 9 **CEVT:** Comparator Event bit
1 = Comparator event defined by EVPOL<1:0> has occurred; subsequent triggers and interrupts are disabled until the bit is cleared
0 = Comparator event has not occurred

bit 8 **COUT:** Comparator Output bit
When CPOL = 0:
1 = VIN+ > VIN-
0 = VIN+ < VIN-
When CPOL = 1:
1 = VIN+ < VIN-
0 = VIN+ > VIN-

bit 7-6 **EVPOL<1:0>:** Trigger/Event/Interrupt Polarity Select bits(1)
11 = Trigger/event/interrupt is generated on any change of the comparator output (while CEVT = 0)
10 = Trigger/event/interrupt is generated on the high-to-low transition of the comparator output
01 = Trigger/event/Interrupt is generated on the low-to-high transition of the comparator output
00 = Trigger/event/interrupt generation is disabled

bit 5 **Unimplemented:** Read as '0'

bit 4 **CREF:** Comparator Reference Select bits (non-inverting input)
1 = Non-inverting input connects to the internal CVREF voltage
0 = Non-inverting input connects to the CxINA pin

**Note 1:** If EVPOL<1:0> is set to a value other than '00', the first interrupt generated will occur on any transition of COUT, regardless of if it is a rising or falling edge. Subsequent interrupts will occur based on the EVPOLx bits setting.

**2:** Unimplemented on 14-pin (PIC24FXXKL100/200) devices.

## 23.3 Unique ID

A read-only Unique ID value is stored at addresses, 800802h through 800808h. This factory programmed value is unique to each microcontroller produced in the PIC24F16KL402 family. To access this region, use Table Read instructions or Program Space Visibility.

To ensure a globally Unique ID across other Microchip microcontroller families, the “Unique ID” value should be further concatenated with the family and Device ID values stored at address, FF0000h.

**REGISTER 23-8: DEVID: DEVICE ID REGISTER**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 23 | | | | | | | bit 16 |

| R | R | R | R | R | R | R | R |
|---|---|---|---|---|---|---|---|
| FAMID7 | FAMID6 | FAMID5 | FAMID4 | FAMID3 | FAMID2 | FAMID1 | FAMID0 |
| bit 15 | | | | | | | bit 8 |

| R | R | R | R | R | R | R | R |
|---|---|---|---|---|---|---|---|
| DEV7 | DEV6 | DEV5 | DEV4 | DEV3 | DEV2 | DEV1 | DEV0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 23-16 **Unimplemented:** Read as ‘0’

bit 15-8 **FAMID<7:0>:** Device Family Identifier bits
01001011 = PIC24F16KL402 family

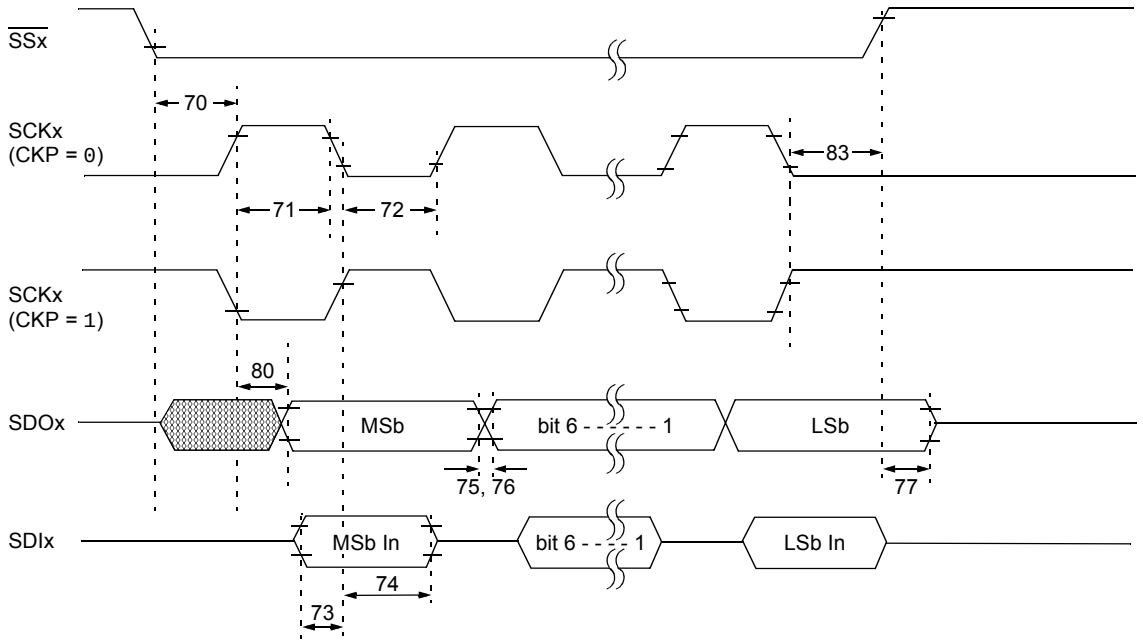
bit 7-0 **DEV<7:0>:** Individual Device Identifier bits
00000001 = PIC24F04KL100
00000010 = PIC24F04KL101

00000101 = PIC24F08KL200
00000110 = PIC24F08KL201

00001010 = PIC24F08KL301
00000000 = PIC24F08KL302

00001110 = PIC24F08KL401
00000100 = PIC24F08KL402
00011110 = PIC24F16KL401
00010100 = PIC24F16KL402

**FIGURE 26-9: EXAMPLE SPI SLAVE MODE TIMING (CKE = 0)**




**Note:** Refer to Figure 26-3 for load conditions.

**TABLE 26-29: EXAMPLE SPI MODE REQUIREMENTS (SLAVE MODE TIMING, CKE = 0)**

| Param No. | Symbol | Characteristic | | Min | Max | Units | Conditions |
|---|---|---|---|---|---|---|---|
| 70 | TssL2scH, TssL2scL | $\overline{SSx}$ ↓ to SCKx ↓ or SCKx ↑ Input | | 3 Tcy | — | ns | |
| 70A | TssL2WB | $\overline{SSx}$ to Write to SSPxBUF | | 3 Tcy | — | ns | |
| 71 | TscH | SCKx Input High Time (Slave mode) | Continuous | 1.25 Tcy + 30 | — | ns | |
| 71A | | | Single Byte | 40 | — | ns | **(Note 1)** |
| 72 | TscL | SCKx Input Low Time (Slave mode) | Continuous | 1.25 Tcy + 30 | — | ns | |
| 72A | | | Single Byte | 40 | — | ns | **(Note 1)** |
| 73 | TdiV2scH, TdiV2scL | Setup Time of SDIx Data Input to SCKx Edge | | 20 | — | ns | |
| 73A | Tb2b | Last Clock Edge of Byte 1 to the First Clock Edge of Byte 2 | | 1.5 Tcy + 40 | — | ns | **(Note 2)** |
| 74 | TscH2diL, TscL2diL | Hold Time of SDIx Data Input to SCKx Edge | | 40 | — | ns | |
| 75 | TdoR | SDOx Data Output Rise Time | | — | 25 | ns | |
| 76 | TdoF | SDOx Data Output Fall Time | | — | 25 | ns | |
| 77 | TssH2doZ | $\overline{SSx}$ ↑ to SDOx Output High-Impedance | | 10 | 50 | ns | |
| 80 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | | — | 50 | ns | |
| 83 | TscH2ssH, TscL2ssH | $\overline{SSx}$ ↑ after SCKx Edge | | 1.5 Tcy + 40 | — | ns | |
| | Fsck | SCKx Frequency | | — | 10 | MHz | |

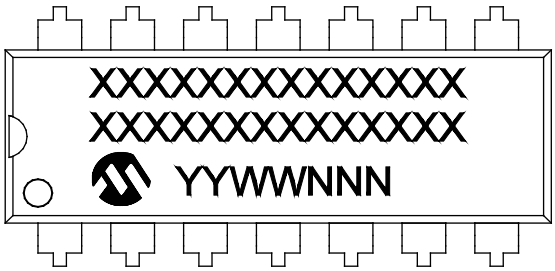
**Note 1:** Requires the use of Parameter 73A.

**2:** Only if Parameters 71A and 72A are used.

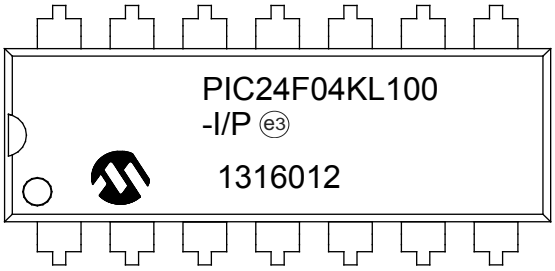
## 27.0 PACKAGING INFORMATION

### 27.1 Package Marking Information

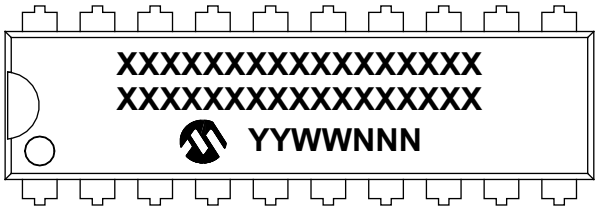
14-Lead PDIP (300 mil)



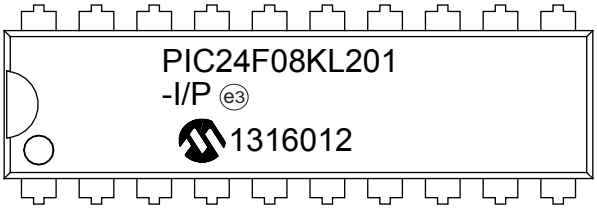

Example



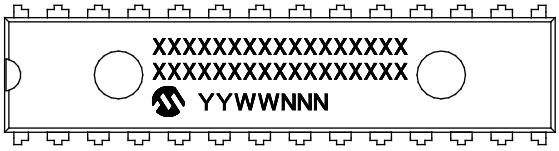

20-Lead PDIP (300 mil)



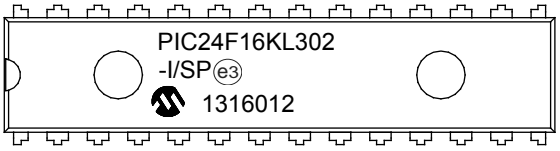

Example




28-Lead SPDIP (.300")




Example

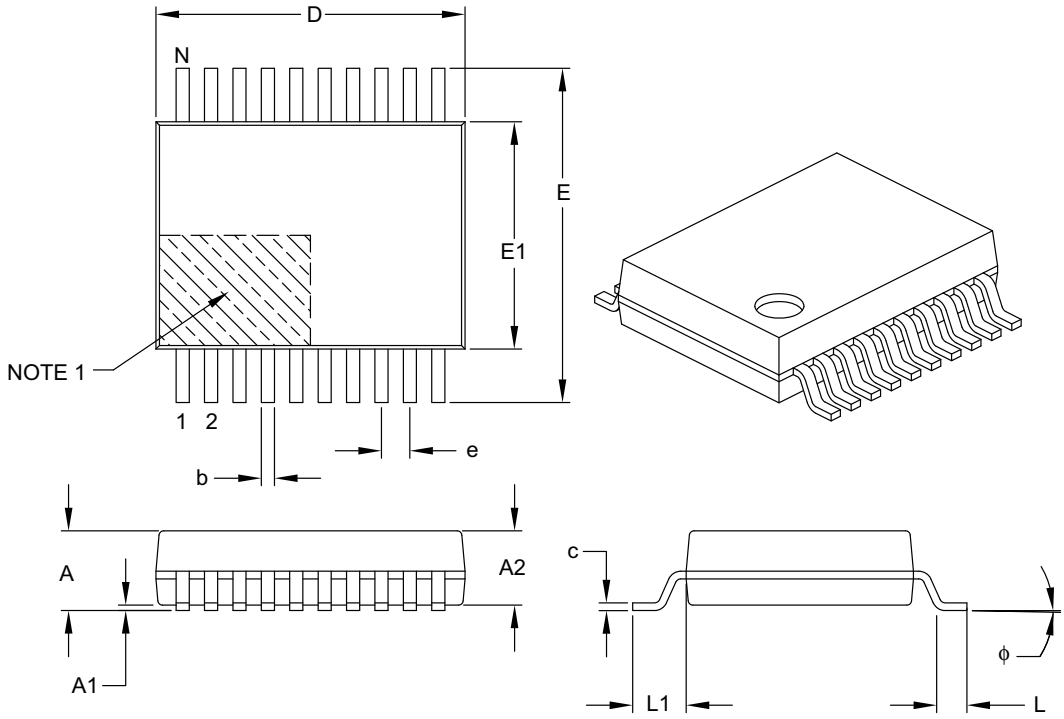



| | | |
|---|---|---|
| **Legend:** | XX...X | Product-specific information |
| | Y | Year code (last digit of calendar year) |
| | YY | Year code (last 2 digits of calendar year) |
| | WW | Week code (week of January 1 is week '01') |
| | NNN | Alphanumeric traceability code |
| | (e3) | Pb-free JEDEC designator for Matte Tin (Sn) |
| | * | This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package. |

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

### 20-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 20 | |
| Pitch | e | | 0.65 BSC | |
| Overall Height | A | – | – | 2.00 |
| Molded Package Thickness | A2 | 1.65 | 1.75 | 1.85 |
| Standoff | A1 | 0.05 | – | – |
| Overall Width | E | 7.40 | 7.80 | 8.20 |
| Molded Package Width | E1 | 5.00 | 5.30 | 5.60 |
| Overall Length | D | 6.90 | 7.20 | 7.50 |
| Foot Length | L | 0.55 | 0.75 | 0.95 |
| Footprint | L1 | | 1.25 REF | |
| Lead Thickness | c | 0.09 | – | 0.25 |
| Foot Angle | ϕ | 0° | 4° | 8° |
| Lead Width | b | 0.22 | – | 0.38 |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
3. Dimensioning and tolerancing per ASME Y14.5M.

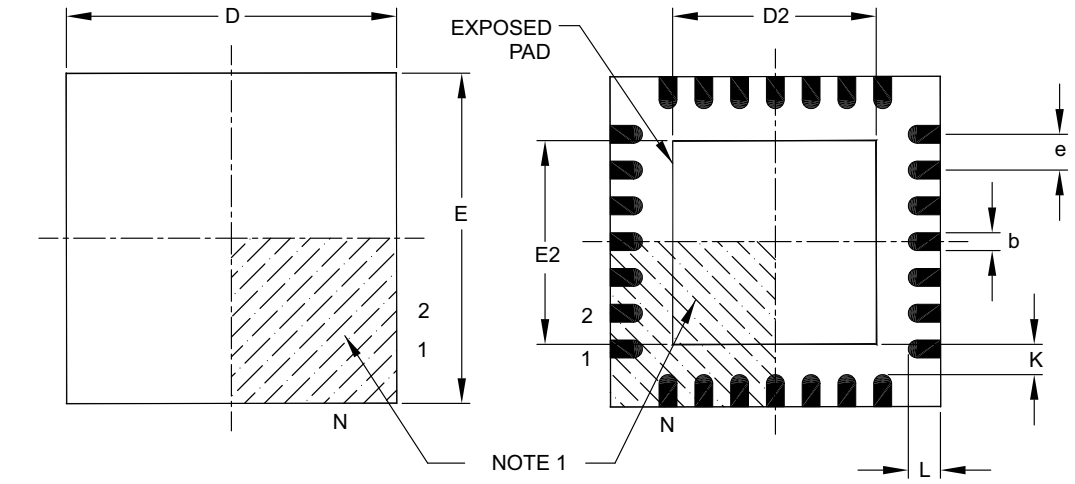
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

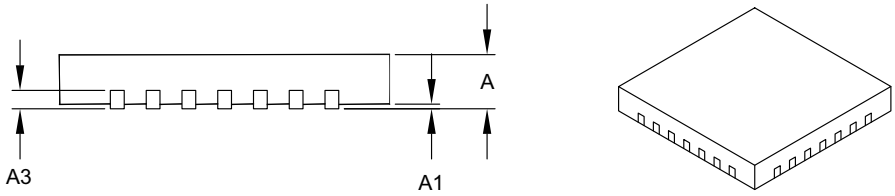
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-072B

### 28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 28 | |
| Pitch | e | | 0.65 BSC | |
| Overall Height | A | 0.80 | 0.90 | 1.00 |
| Standoff | A1 | 0.00 | 0.02 | 0.05 |
| Contact Thickness | A3 | | 0.20 REF | |
| Overall Width | E | | 6.00 BSC | |
| Exposed Pad Width | E2 | 3.65 | 3.70 | 4.20 |
| Overall Length | D | | 6.00 BSC | |
| Exposed Pad Length | D2 | 3.65 | 3.70 | 4.20 |
| Contact Width | b | 0.23 | 0.30 | 0.35 |
| Contact Length | L | 0.50 | 0.55 | 0.70 |
| Contact-to-Exposed Pad | K | 0.20 | – | – |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-105B

## R



## S