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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

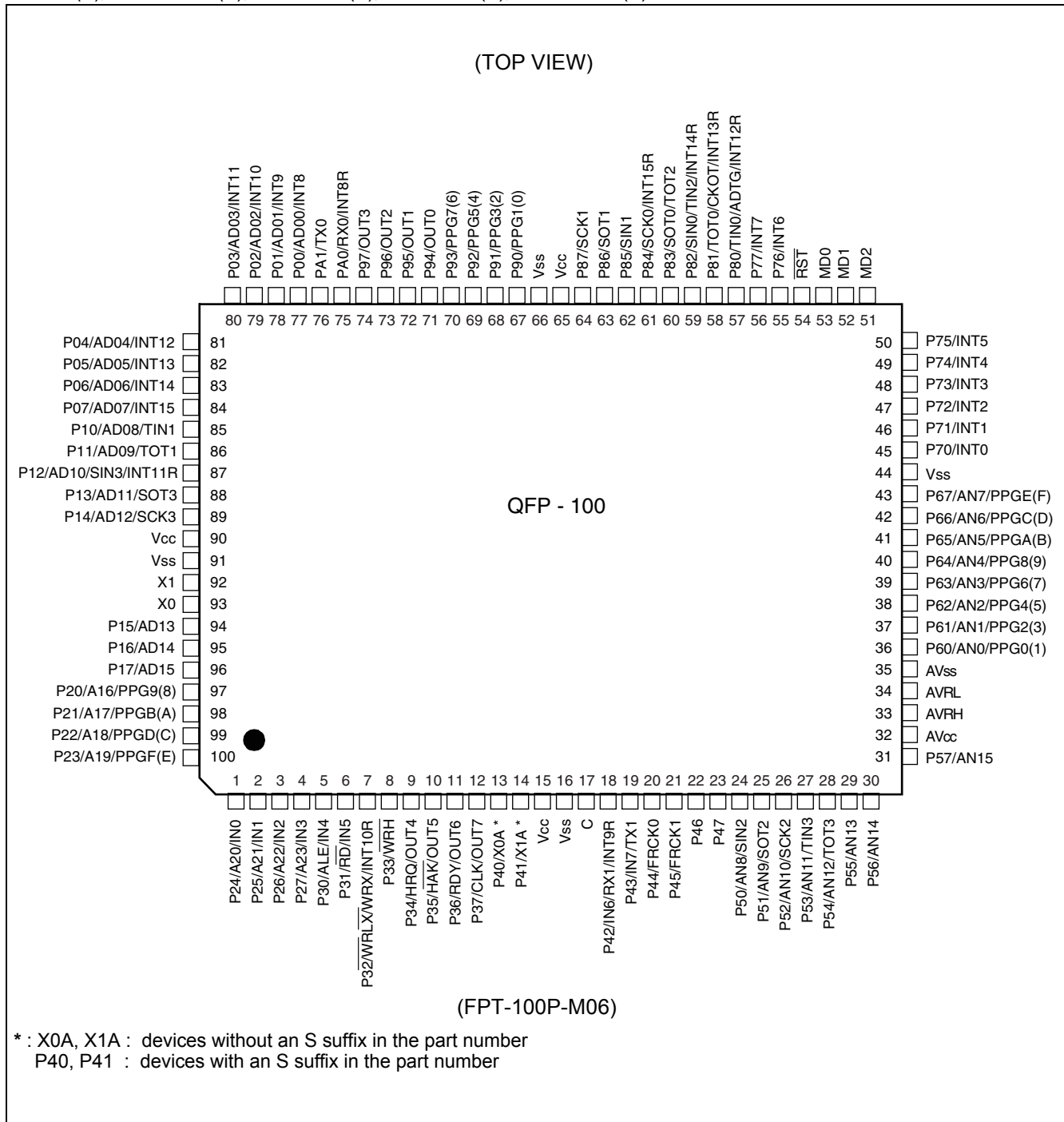
Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-g-187e1

2. Pin Assignments

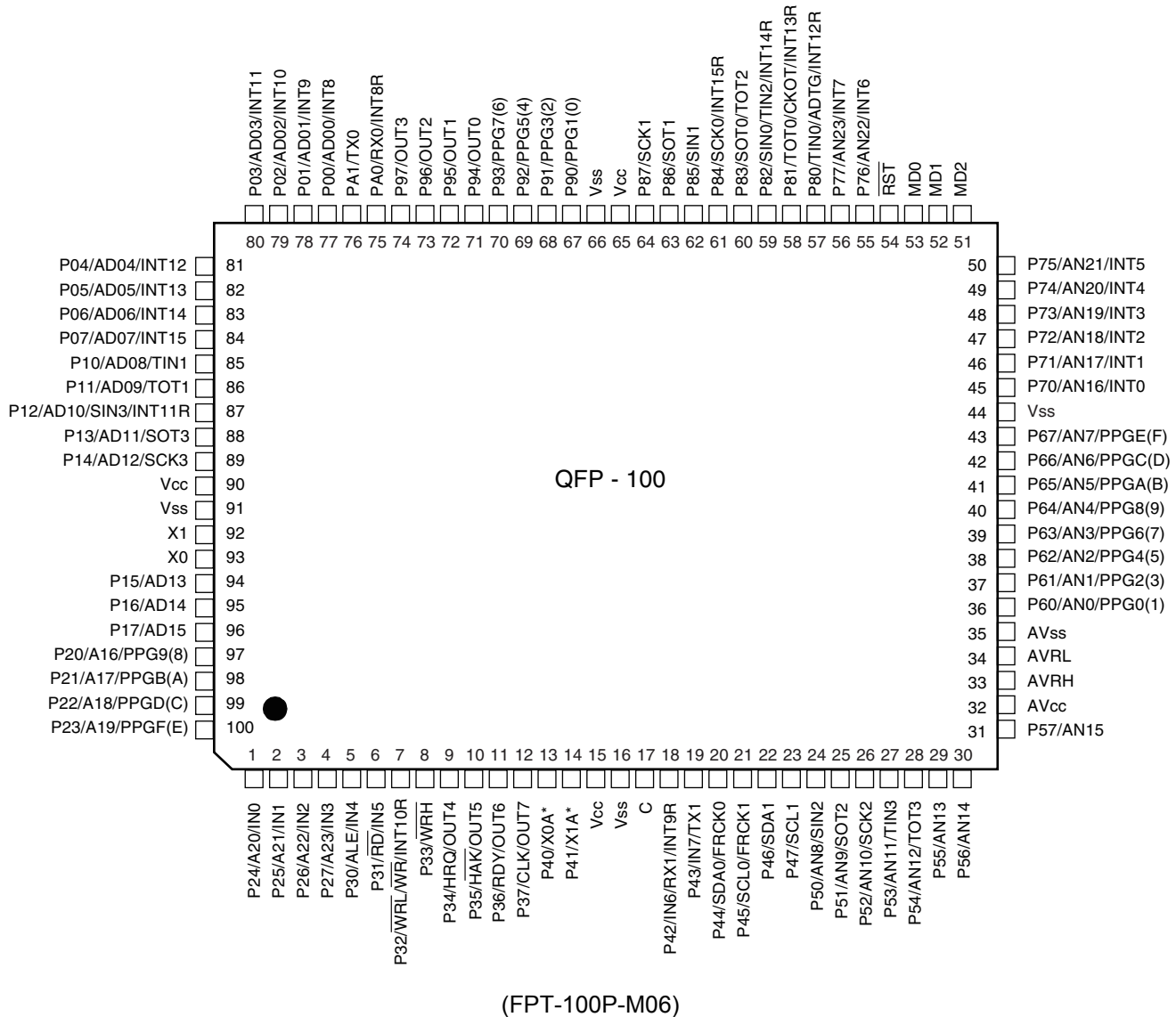
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■ MB90341CE(S), MB90342CE(S), MB90F342CE(S), MB90F345CE(S), MB90346CE(S), MB90F346CE(S), MB90347CE(S), MB90F347CE(S), MB90348CE(S), MB90349CE(S), MB90F349CE(S)

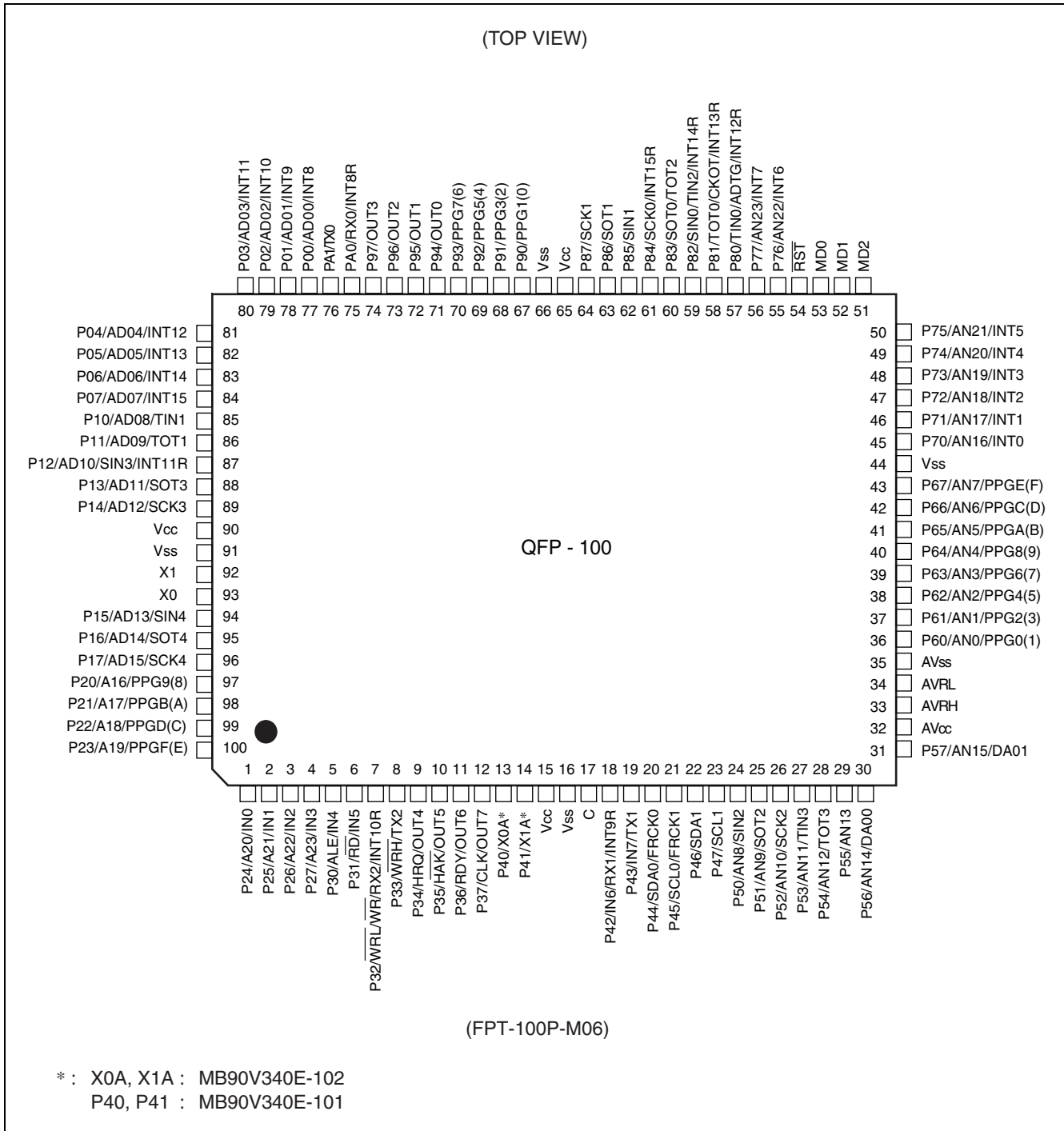
(TOP VIEW)



* : X0A, X1A : devices without an S suffix in the part number
P40, P41 : devices with an S suffix in the part number

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■ MB90V340E-101/MB90V340E-102



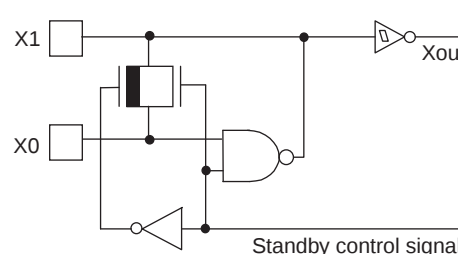
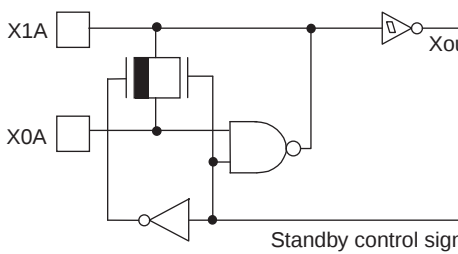
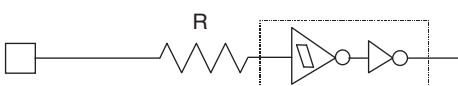
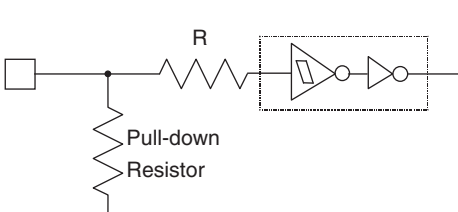
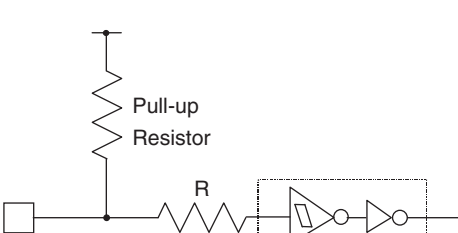
This pin assignment is for using MB90V340E-101/102 via probecable as MB90340E.

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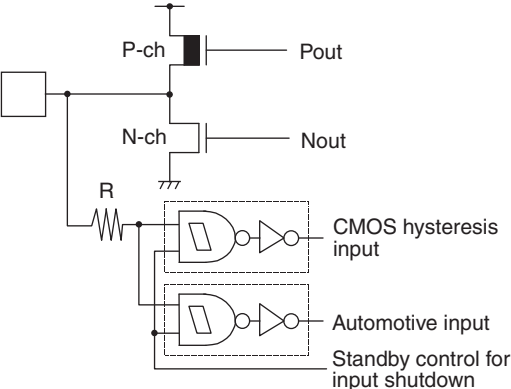
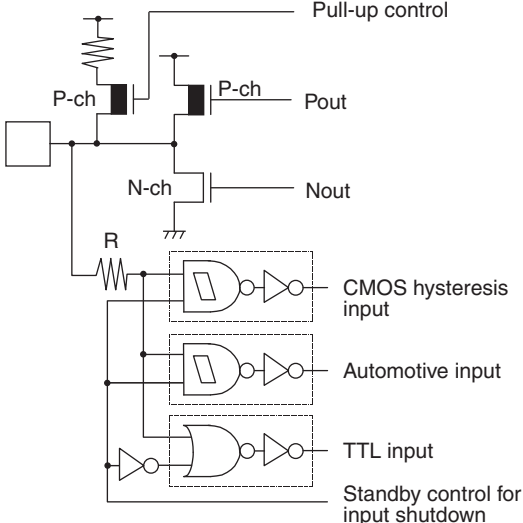
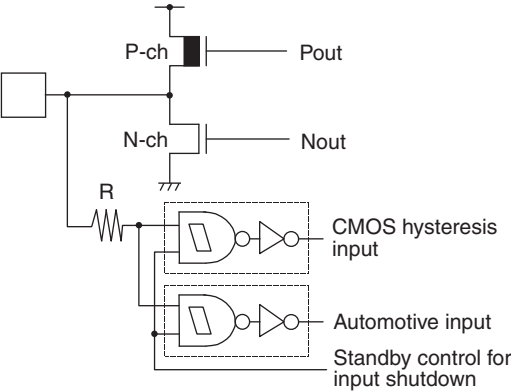
Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
61	59	P84	F	General purpose I/O pin.
		SCK0		Clock I/O pin for UART0
		INT15R		External interrupt request input pin
62	60	P85	M	General purpose I/O pin.
		SIN1		Serial data input pin for UART1
63	61	P86	F	General purpose I/O pin.
		SOT1		Serial data output pin for UART1
64	62	P87	F	General purpose I/O pin.
		SCK1		Clock I/O pin for UART1
65	63	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
66	64	V _{SS}	—	GND pin
67 to 70	65 to 68	P90 to P93	F	General purpose I/O pins
		PPG1, 3, 5, 7		Output pins for PPGs
71 to 74	69 to 72	P94 to P97	F	General purpose I/O pins
		OUT0 to OUT3		Waveform output pins for output compares. This function is enabled when the OCU enables waveform output.
75	73	PA0	F	General purpose I/O pin.
		RX0		RX input pin for CAN0 Interface
		INT8R		External interrupt request input pin
76	74	PA1	F	General purpose I/O pin.
		TX0		TX Output pin for CAN0
77 to 84	75 to 82	P00 to P07	G	General purpose I/O pins. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD00 to AD07		I/O pins for 8 lower bits of the external address/data bus. This function is enabled when the external bus is enabled.
		INT8 to INT15		External interrupt request input pins.
85	83	P10	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
		AD08		I/O pin for the external address/data bus. This function is enabled when the external bus is enabled.
		TIN1		Event input pin for the reload timer

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4. I/O Circuit Type

Type	Circuit	Remarks
A		Oscillation circuit High-speed oscillation feedback resistor = approx. 1 MΩ
B		Oscillation circuit Low-speed oscillation feedback resistor = approx. 10 MΩ
C		■ MASK ROM and evaluation products: CMOS hysteresis input pin ■ Flash memory products: CMOS input pin
D		MASK ROM and evaluation products: ■ CMOS hysteresis input pin ■ Pull-down resistor value: approx. 50 kΩ Flash memory products: ■ CMOS input pin ■ No pull-down
E		CMOS hysteresis input pin Pull-up resistor value: approx. 50 kΩ

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Type	Circuit	Remarks
F		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)
G		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ TTL input (with function to disconnect input during standby) ■ Programmable pull-up resistor: 50 kΩ approx.
H		■ CMOS level output ($I_{OL} = 3 \text{ mA}$, $I_{OH} = -3 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)

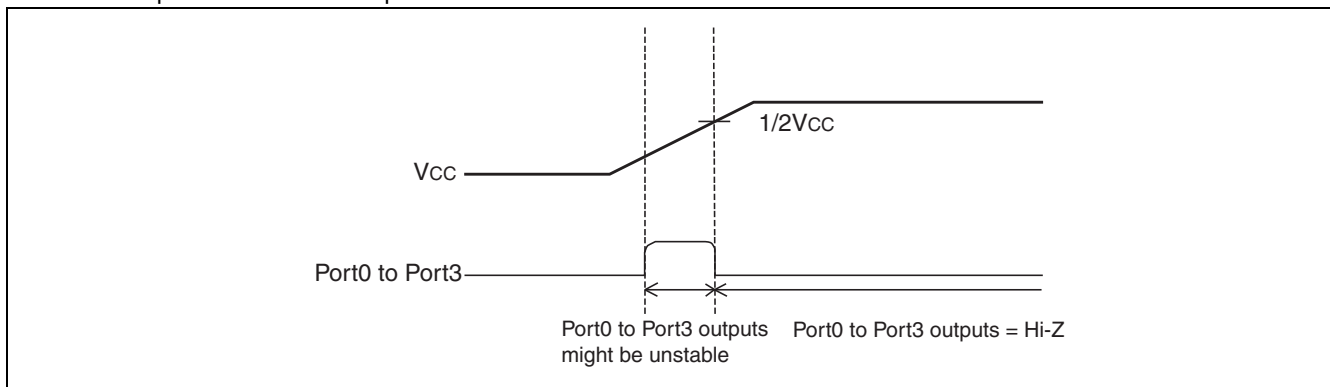
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13. Stabilization of power supply voltage

A sudden change in the supply voltage may cause the device to malfunction even within the V_{CC} supply voltage operating range. Therefore, the V_{CC} supply voltage should be stabilized. For reference, the supply voltage should be controlled so that V_{CC} ripple variations (peak- to-peak values) at commercial frequencies (50 MHz/60 MHz) fall below 10% of the standard V_{CC} supply voltage and the coefficient of fluctuation does not exceed 0.1 V/ms at instantaneous power switching.

14. Port 0 to Port 3 Output During Power-on (External-bus Mode)

As shown below, when the power is turned on in External-Bus mode, there is a possibility that output signal of Port 0 to Port 3 might be unstable irrespective of the reset input.



15. Notes on Using the CAN Function

To use the CAN function, please set the DIRECT bit of the CAN Direct Mode Register (CDMR) to 1.

16. Flash Security Function (except for MB90F346E)

A security bit is located in the area of the flash memory.

If protection code 01_H is written in the security bit, the flash memory is in the protected state by security.

Therefore please do not write 01_H in this address if you do not use the security function.

Refer to following table for the address of the security bit.

	Flash memory size	Address of the security bit
MB90F347E	Embedded 1 Mbit Flash Memory	FE0001 _H
MB90F342E MB90F349E	Embedded 2 Mbits Flash Memory	FC0001 _H
MB90F345E	Embedded 4 Mbits Flash Memory	F80001 _H

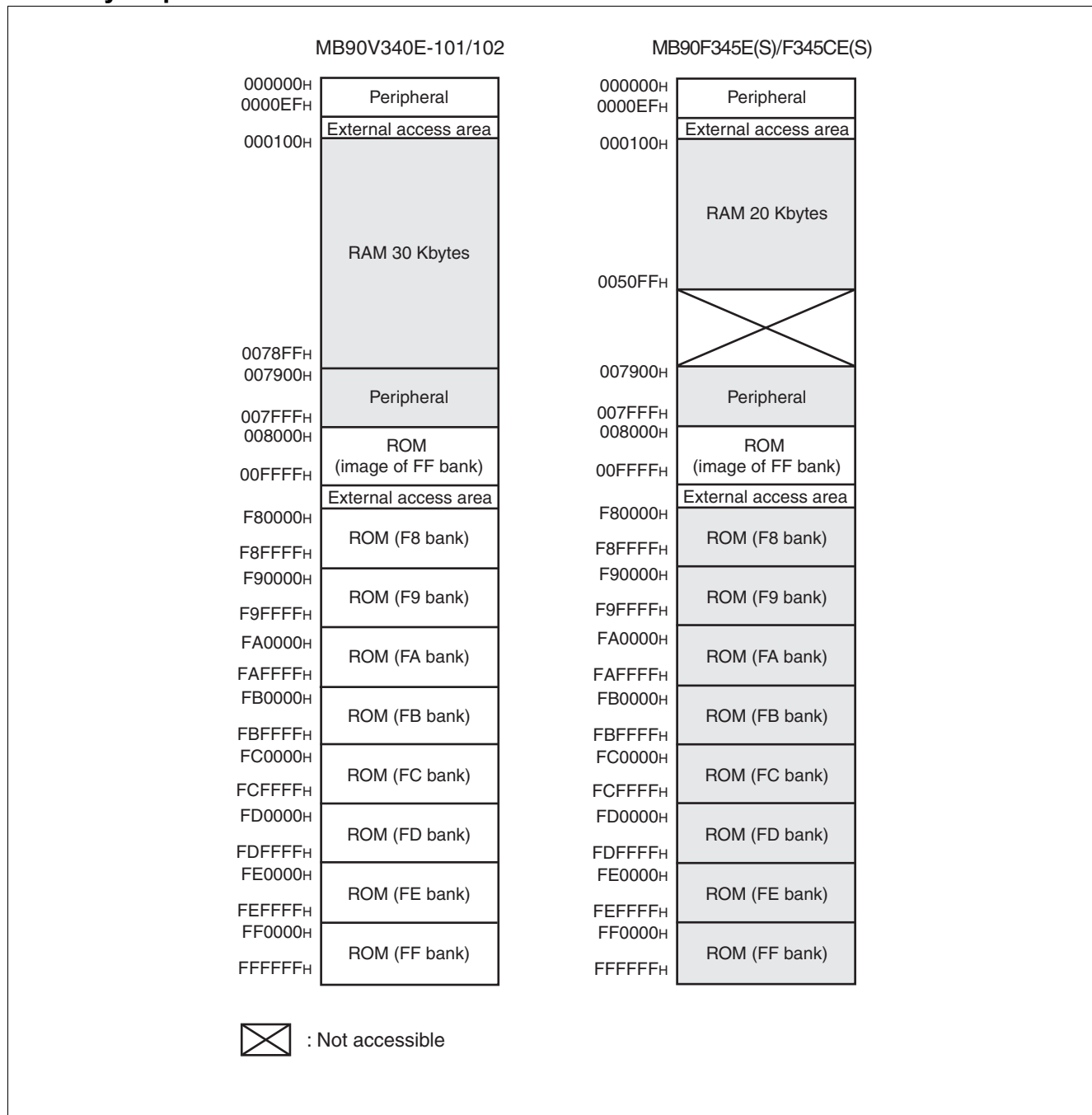
17. Serial Communication

There is a possibility to receive wrong data due to the noise or other causes on the serial communication.

Therefore, design a printed circuit board so as to avoid noise.

Retransmit the data if an error occurs because of applying the checksum to the last data in consideration of receiving wrong data due to the noise.

7. Memory Map



Address	Register	Abbreviation	Access	Resource name	Initial value
000040 _H	PPG 8 Operation Mode Control Register	PPGC8	W,R/W	16-bit PPG 8/9	0X000XX1 _B
000041 _H	PPG 9 Operation Mode Control Register	PPGC9	W,R/W		0X000001 _B
000042 _H	PPG 8/PPG 9 Count Clock Control Register	PPG89	R/W		000000X0 _B
000043 _H	Reserved				
000044 _H	PPG A Operation Mode Control Register	PPGCA	W,R/W	16-bit PPG A/B	0X000XX1 _B
000045 _H	PPG B Operation Mode Control Register	PPGCB	W,R/W		0X000001 _B
000046 _H	PPG A/PPG B Count Clock Select Register	PPGAB	R/W		000000X0 _B
000047 _H	Reserved				
000048 _H	PPG C Operation Mode Control Register	PPGCC	W,R/W	16-bit PPG C/D	0X000XX1 _B
000049 _H	PPG D Operation Mode Control Register	PPGCD	W,R/W		0X000001 _B
00004A _H	PPG C/PPG D Count Clock Select Register	PPGCD	R/W		000000X0 _B
00004B _H	Reserved				
00004C _H	PPG E Operation Mode Control Register	PPGCE	W,R/W	16-bit PPG E/F	0X000XX1 _B
00004D _H	PPG F Operation Mode Control Register	PPGCF	W,R/W		0X000001 _B
00004E _H	PPG E/PPG F Count Clock Select Register	PPGEF	R/W		000000X0 _B
00004F _H	Reserved				
000050 _H	Input Capture Control Status 0/1	ICS01	R/W	Input Capture 0/1	00000000 _B
000051 _H	Input Capture Edge 0/1	ICE01	R/W, R		XXX0X0XX _B
000052 _H	Input Capture Control Status 2/3	ICS23	R/W	Input Capture 2/3	00000000 _B
000053 _H	Input Capture Edge 2/3	ICE23	R		XXXXXXXX _B
000054 _H	Input Capture Control Status 4/5	ICS45	R/W	Input Capture 4/5	00000000 _B
000055 _H	Input Capture Edge 4/5	ICE45	R		XXXXXXXX _B
000056 _H	Input Capture Control Status 6/7	ICS67	R/W	Input Capture 6/7	00000000 _B
000057 _H	Input Capture Edge 6/7	ICE67	R/W, R		XXX000XX _B
000058 _H	Output Compare Control Status 0	OCS0	R/W	Output Compare 0/1	0000XX00 _B
000059 _H	Output Compare Control Status 1	OCS1	R/W		0XX00000 _B
00005A _H	Output Compare Control Status 2	OCS2	R/W	Output Compare 2/3	0000XX00 _B
00005B _H	Output Compare Control Status 3	OCS3	R/W		0XX00000 _B
00005C _H	Output Compare Control Status 4	OCS4	R/W	Output Compare 4/5	0000XX00 _B
00005D _H	Output Compare Control Status 5	OCS5	R/W		0XX00000 _B
00005E _H	Output Compare Control Status 6	OCS6	R/W	Output Compare 6/7	0000XX00 _B
00005F _H	Output Compare Control Status 7	OCS7	R/W		0XX00000 _B

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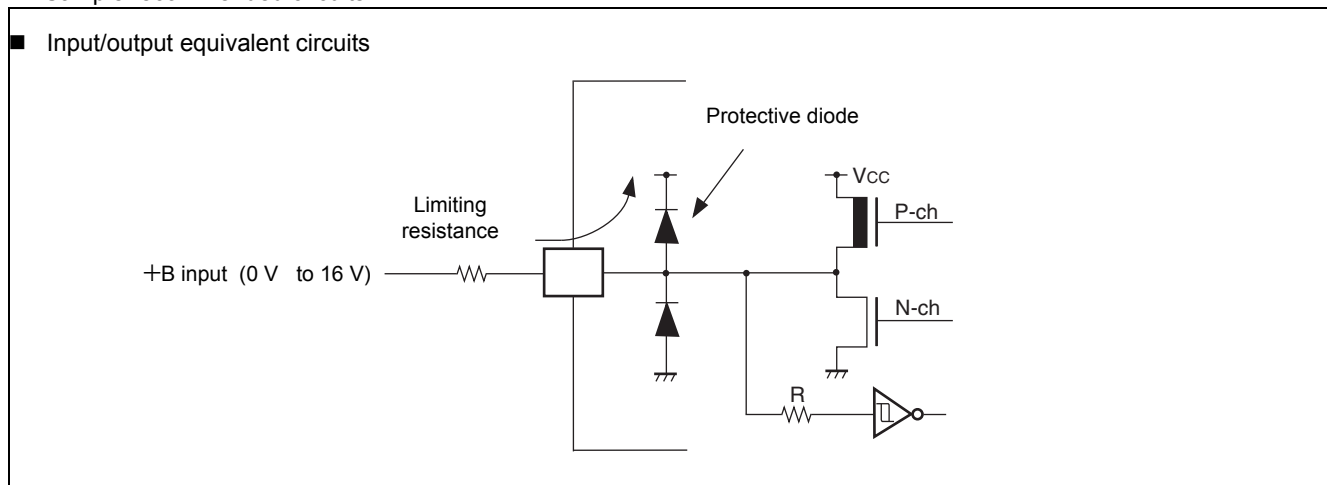
10. Interrupt Factors, Interrupt Vectors, Interrupt Control Register

Interrupt cause	EI ² OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
Reset	N	—	#08	FFFFDC _H	—	—
INT9 instruction	N	—	#09	FFFFD8 _H	—	—
Exception	N	—	#10	FFFFD4 _H	—	—
CAN 0 RX	N	—	#11	FFFFD0 _H	ICR00	0000B0 _H
CAN 0 TX/NS	N	—	#12	FFFFCC _H		
CAN 1 RX / Input Capture 6	Y1	—	#13	FFFFC8 _H	ICR01	0000B1 _H
CAN 1 TX/NS / Input Capture 7	Y1	—	#14	FFFFC4 _H		
CAN 2 RX / I ² C0	N	—	#15	FFFFC0 _H	ICR02	0000B2 _H
CAN 2 TX/NS	N	—	#16	FFFFBC _H		
16-bit Reload Timer 0	Y1	0	#17	FFFFB8 _H	ICR03	0000B3 _H
16-bit Reload Timer 1	Y1	1	#18	FFFFB4 _H		
16-bit Reload Timer 2	Y1	2	#19	FFFFB0 _H	ICR04	0000B4 _H
16-bit Reload Timer 3	Y1	—	#20	FFFFAC _H		
PPG 0/1/4/5	N	—	#21	FFFFA8 _H	ICR05	0000B5 _H
PPG 2/3/6/7	N	—	#22	FFFFA4 _H		
PPG 8/9/C/D	N	—	#23	FFFFA0 _H	ICR06	0000B6 _H
PPG A/B/E/F	N	—	#24	FFFF9C _H		
Time Base Timer	N	—	#25	FFFF98 _H	ICR07	0000B7 _H
External Interrupt 0 to 3, 8 to 11	Y1	3	#26	FFFF94 _H		
Watch Timer	N	—	#27	FFFF90 _H	ICR08	0000B8 _H
External Interrupt 4 to 7, 12 to 15	Y1	4	#28	FFFF8C _H		
A/D Converter	Y1	5	#29	FFFF88 _H	ICR09	0000B9 _H
Free-run Timer 0 / Free-run Timer 1	N	—	#30	FFFF84 _H		
Input Capture 4/5 / I ² C1	Y1	6	#31	FFFF80 _H	ICR10	0000BA _H
Output Compare 0/1/4/5	Y1	7	#32	FFFF7C _H		
Input Capture 0 to 3	Y1	8	#33	FFFF78 _H	ICR11	0000BB _H
Output Compare 2/3/6/7	Y1	9	#34	FFFF74 _H		
UART 0 RX	Y2	10	#35	FFFF70 _H	ICR12	0000BC _H
UART 0 TX	Y1	11	#36	FFFF6C _H		
UART 1 RX / UART 3 RX	Y2	12	#37	FFFF68 _H	ICR13	0000BD _H
UART 1 TX / UART 3 TX	Y1	13	#38	FFFF64 _H		

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- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on reset.
- Care must be taken not to leave the +B input pin open.
- Sample recommended circuits:

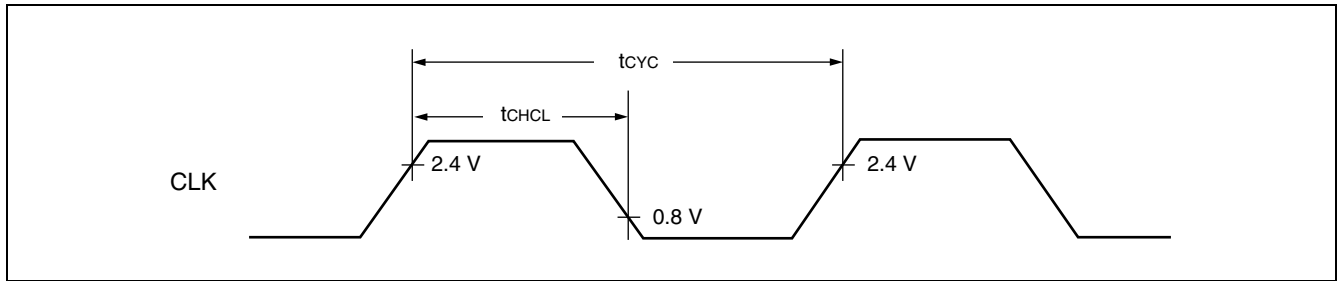


*6: The maximum output current is defined as the peak value of the current of any one of the corresponding pins.

*7: The average output current is defined as the value of the average current flowing over 100 ms at any one of the corresponding pins.

*8: The average total output current is defined as the value of the average current flowing over 100 ms at all of the corresponding pins.

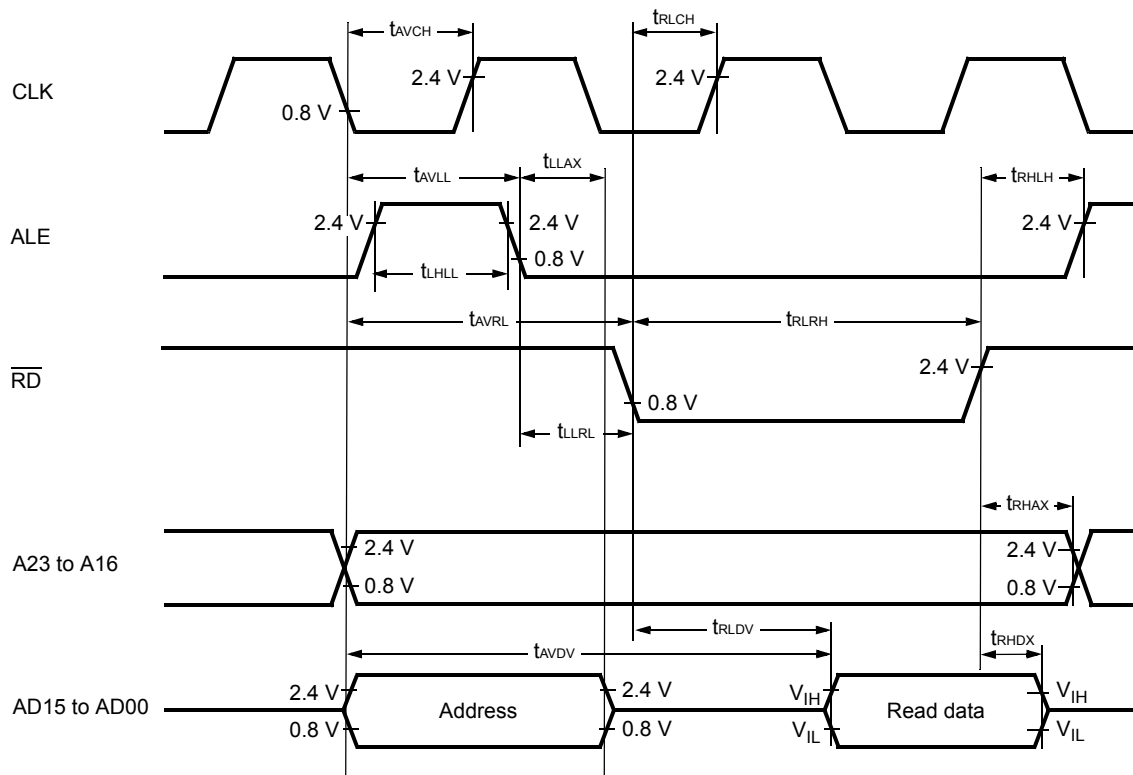
WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.



11.4.5 Bus Timing (Read)

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
ALE pulse width	t_{LHLL}	ALE	—	$t_{CP}/2 - 10$	—	ns
Valid address $\rightarrow$ ALE $\downarrow$ time	t_{AVLL}	ALE, A23 to A16, AD15 to AD00		$t_{CP}/2 - 20$	—	ns
ALE $\downarrow \rightarrow$ Address valid time	t_{LLAX}	ALE, AD15 to AD00		$t_{CP}/2 - 15$	—	ns
Valid address $\rightarrow$ RD $\downarrow$ time	t_{AVRL}	A23 to A16, AD15 to AD00, $\overline{\text{RD}}$		$t_{CP} - 15$	—	ns
Valid address $\rightarrow$ Valid data input	t_{AVDV}	A23 to A16, AD15 to AD00		—	$5 t_{CP}/2 - 60$	ns
$\overline{\text{RD}}$ pulse width	t_{RLRH}	$\overline{\text{RD}}$		$3 t_{CP}/2 - 20$	—	ns
$\overline{\text{RD}} \downarrow \rightarrow$ Valid data input	t_{RLDV}	$\overline{\text{RD}}$, AD15 to AD00		—	$3 t_{CP}/2 - 50$	ns
$\overline{\text{RD}} \uparrow \rightarrow$ Data hold time	t_{RHDX}	$\overline{\text{RD}}$, AD15 to AD00		0	—	ns
$\overline{\text{RD}} \uparrow \rightarrow$ ALE $\uparrow$ time	t_{RHLH}	$\overline{\text{RD}}$, ALE		$t_{CP}/2 - 15$	—	ns
$\overline{\text{RD}} \uparrow \rightarrow$ Address valid time	t_{RHAX}	$\overline{\text{RD}}$, A23 to A16		$t_{CP}/2 - 10$	—	ns
Valid address $\rightarrow$ CLK $\uparrow$ time	t_{AVCH}	A23 to A16, AD15 to AD00, CLK		$t_{CP}/2 - 16$	—	ns
$\overline{\text{RD}} \downarrow \rightarrow$ CLK $\uparrow$ time	t_{RLCH}	$\overline{\text{RD}}$, CLK		$t_{CP}/2 - 15$	—	ns
ALE $\downarrow \rightarrow$ $\overline{\text{RD}} \downarrow$ time	t_{LLRL}	ALE, $\overline{\text{RD}}$		$t_{CP}/2 - 15$	—	ns

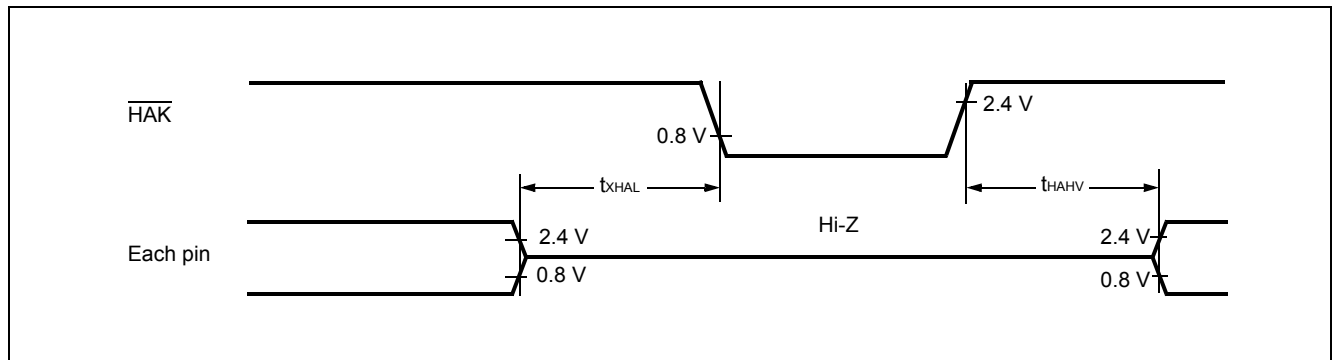


11.4.8 Hold Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Pin floating $\rightarrow \overline{\text{HAK}} \downarrow$ time	t_{XHAL}	$\overline{\text{HAK}}$	—	30	t_{CP}	ns
$\overline{\text{HAK}} \uparrow$ time $\rightarrow$ Pin valid time	t_{HAHV}	$\overline{\text{HAK}}$	—	t_{CP}	$2 t_{CP}$	ns

Note: : There is more than 1 cycle from when HRQ reads in until the $\overline{\text{HAK}}$ is changed.



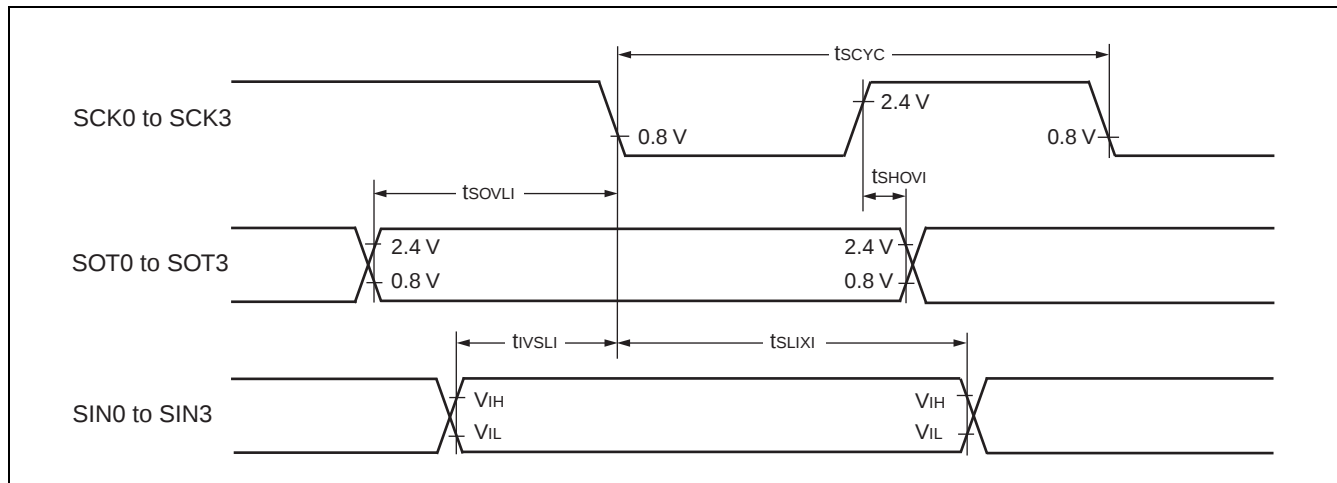
■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 1

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\uparrow \rightarrow$ SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\downarrow$	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\downarrow \rightarrow$ Valid SIN hold time	t_{SLIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT $\rightarrow$ SCK $\downarrow$ delay time	t_{SOVLI}	SCK0 to SCK3, SOT0 to SOT3		$3 t_{CP} - 70$	—	ns

Note:

- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.



11.4.13 I²C Timing

(T_A = -40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

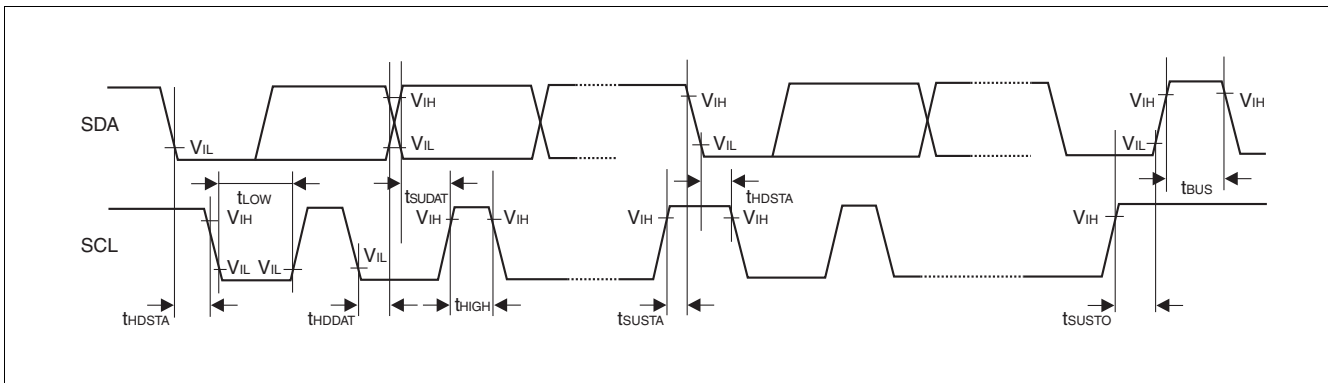
Parameter	Symbol	Condition	Standard-mode		Fast-mode* ¹		Unit
			Min	Max	Min	Max	
SCL clock frequency	f _{SCL}	R = 1.7 kΩ ₂ C = 50 pF* ²	0	100	0	400	kHz
Hold time (repeated) START condition SDA ↓ → SCL ↓	t _{HDSTA}		4.0	—	0.6	—	μs
"L" width of the SCL clock	t _{LOW}		4.7	—	1.3	—	μs
"H" width of the SCL clock	t _{HIGH}		4.0	—	0.6	—	μs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t _{SUSTA}		4.7	—	0.6	—	μs
Data hold time SCL ↓ → SDA ↓ ↑	t _{HDDAT}		0	3.45* ³	0	0.9* ⁴	μs
Data set-up time SDA ↓ ↑ → SCL ↑	t _{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t _{SUSTO}		4.0	—	0.6	—	μs
Bus free time between a STOP and START condition	t _{BUS}		4.7	—	1.3	—	μs

*1: For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.

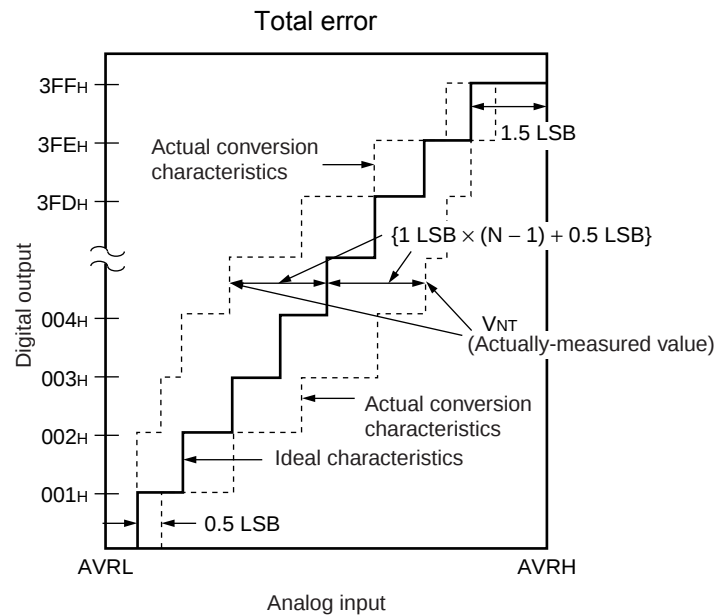
*3: The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4: A Fast-mode I²C-bus device can be used in a Standard-mode I²C-bus system, but the requirement t_{SUDAT} ≥ 250 ns must then be met.



11.6 Definition of A/D Converter Terms

- Resolution : Analog variation that is recognized by the A/D converter.
- Non linearity error : The deviation between the actual conversion characteristics and a line that joins the zero-transition line ("00 0000 0000" $\leftrightarrow$ "00 0000 0001") to the full-scale transition line ("11 1111 1110" $\leftrightarrow$ "11 1111 1111").
- Differential linearity error : Deviation of input voltage, which is required for changing output code by 1 LSB, from an ideal value.
- Total error : Difference between the actual value and the ideal value. The total error includes zero transition error, full-scale transition error, and linear error.



$$\text{Total error of digital output "N"} = \frac{V_{NT} - \{1 \text{ LSB} \times (N - 1) + 0.5 \text{ LSB}\}}{1 \text{ LSB}} \text{ [LSB]}$$

$$1 \text{ LSB (Ideal value)} = \frac{AVRH - AVRL}{1024} \text{ [V]}$$

N : Value of the digital output from the A/D converter

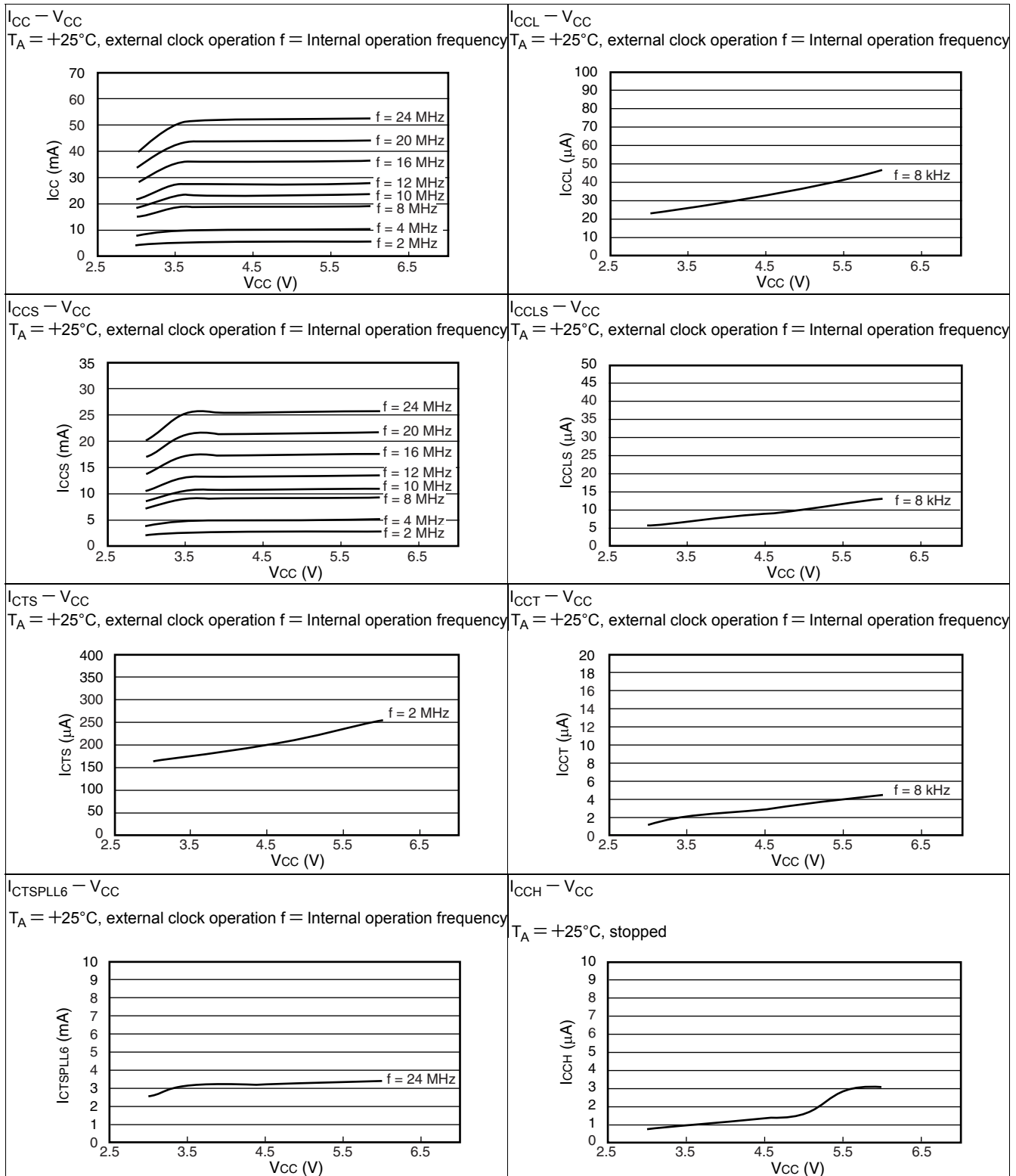
$$V_{OT} \text{ (Ideal value)} = AVRL + 0.5 \text{ LSB [V]}$$

$$V_{FST} \text{ (Ideal value)} = AVRH - 1.5 \text{ LSB [V]}$$

V_{NT} : A voltage at which the digital output transitions from $(N - 1)_H$ to N_H .

(Continued)

■ MB90F347E, MB90F347ES, MB90F347CE, MB90F347CES



13. Ordering Information

Part number	Package	Remarks
MB90F342EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F342ESPF		
MB90F342CEPF		
MB90F342CESPF		
MB90F342EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F342ESPMC		
MB90F342CEPMC		
MB90F342CESPMC		
MB90F345EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F345ESPF		
MB90F345CEPF		
MB90F345CESPF		
MB90F345EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F345ESPMC		
MB90F345CEPMC		
MB90F345CESPMC		
MB90F346EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F346ESPF		
MB90F346CEPF		
MB90F346CESPF		
MB90F346EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F346ESPMC		
MB90F346CEPMC		
MB90F346CESPMC		

(Continued)

15. Major Changes

Spanision Publication Number: DS07-13747-4E

Page	Section	Change Results
—	—	Deleted the part numbers; MB90F343E(S), MB90F343CE(S)
51	Electrical Characteristics Absolute Maximum Ratings	Added “*6” in remark for “L” level maximum output current and “H” level maximum output current. Added “*7” in remark for “L” level average output current and “H” level average output current. Added “*8” in remark for “L” level average overall output current and “H” level average overall output current.
52		Added as follows. “*6: The maximum output current is defined as the peak value of the current of any one of the corresponding pins.” “*7: The average output current is defined as the value of the average current flowing over 100 ms at any one of the corresponding pins.” “*8: The average total output current is defined as the value of the average current flowing over 100 ms at all of the corresponding pins.”

NOTE: Please see “Document History” about later revised information.

Document History

Document Title: MB90340E Series F2MC-16LX 16-bit Microcontroller Datasheet Document Number: 002-04498				
Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	—	AKIH	08/23/2010	Migrated to Cypress and assigned document number 002-04498. No change to document contents or format.
*A	5221535	AKIH	05/04/2016	Updated to Cypress template