Infineon Technologies - MB90347ESPMC-GS-254E1 Datasheet

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-254e1

Part Number / Parameter	MB90V340E-101, MB90V340E-102	MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
A/D Converter	24 input channels	Devices with a C suffix in the part number : 24 channels Devices without a C suffix in the part number : 16 channels	
	10-bit or 8-bit resolution Conversion time : Min 3 μs include sample time (per one channel)		
16-bit Reload Timer (4 channels)	Operation clock frequency : fsys/2^1, fsys/2^3, fsys/2^5 (fsys = Machine clock frequency) Supports External Event Count function		
16-bit Free-run Timer (2 channels)	Generates an interrupt signal on overflow Supports Timer Clear when the output compare finds a match Operation clock freq. : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4, fsys/2^5, fsys/2^6, fsys/2^7 (fsys = Machine clock freq.) Free-run Timer 0 (clock input FRCK0) corresponds to ICU 0/1/2/3, OCU 0/1/2/3 Free-run Timer 1 (clock input FRCK1) corresponds to ICU 4/5/6/7, OCU 4/5/6/7		
16-bit Output Compare (8 channels)	Generates an interrupt signal when one of the 16-bit free-run timer matches the output compare register A pair of compare registers can be used to generate an output signal.		
16-bit Input Capture (8 channels)	Captures the value of the 16-bit free-run timer and generates an interrupt when triggered by a pin input (rising edge, falling edge, or both rising and falling edges).		
8/16-bit Programmable Pulse Generator	8 channels (16-bit) /16 channels (8-bit) Sixteen 8-bit reload counters Sixteen 8-bit reload registers for L pulse width Sixteen 8-bit reload registers for H pulse width		
	Supports 8-bit and 16-bit operation modes A pair of 8-bit reload counters can be configured as one 16-bit reload counter or as 8-bit prescaler plus 8-bit reload counter Operating clock freq. : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4 or 128 μs@fosc = 4 MHz (fsys = Machine clock frequency, fosc = Oscillation clock frequency)		
CAN Interface	3 channels	2 channels : MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S) 1 channel : MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	2 channels : MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S) 1 channel : MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
	Conforms to CAN Specification Version 2.0 Part A and B Automatic re-transmission in case of error Automatic transmission in response to Remote Frames Prioritized 16 message buffers for data and ID's Supports multiple messages Flexible configuration of acceptance filtering : Full bit compare/Full bit mask/Two partial bit masks Supports up to 1 Mbps		

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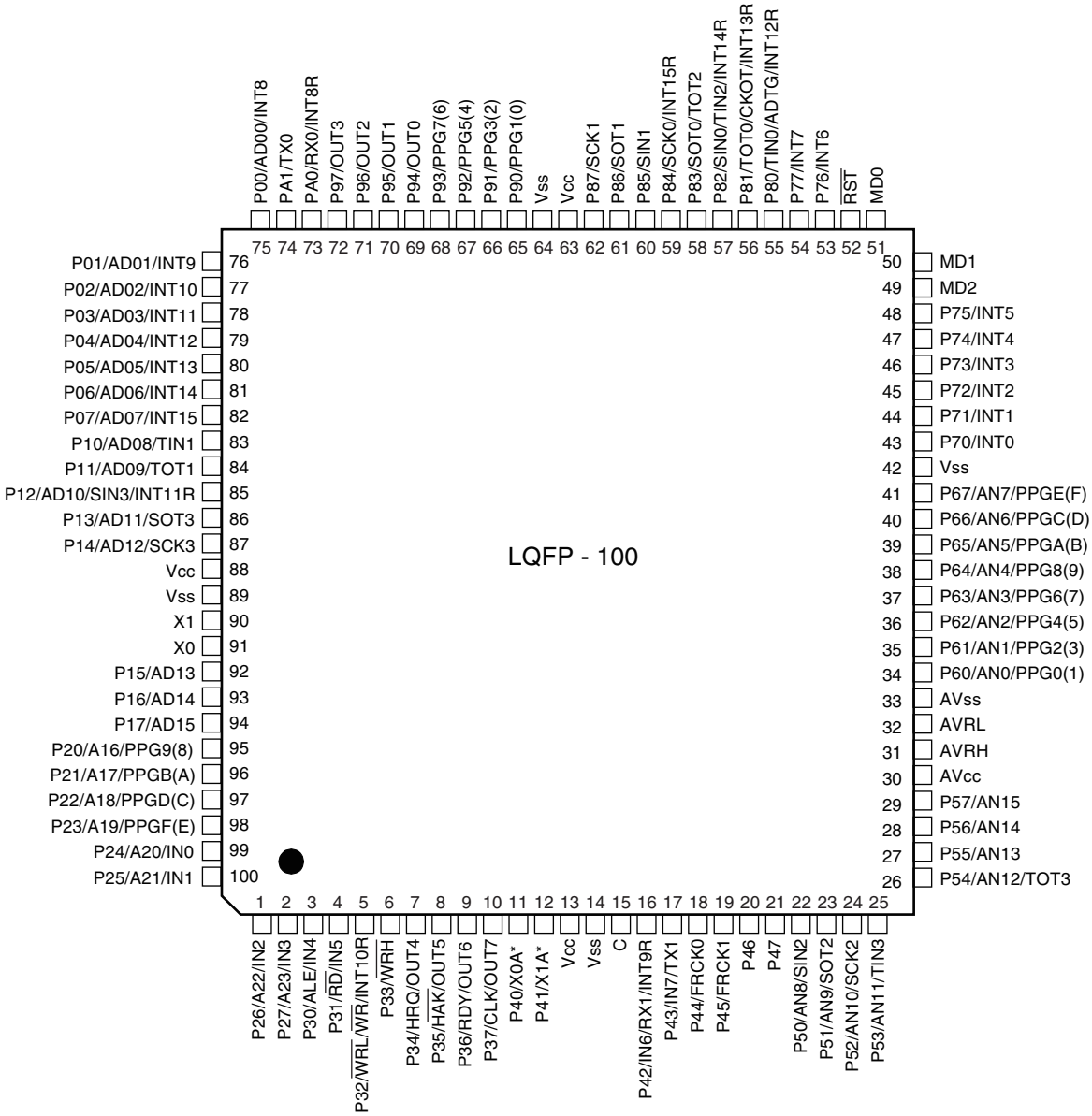
(TOP VIEW)



(FPT-100P-M20)

* : X0A, X1A : devices without an S suffix in the part number
P40, P4 : devices with an S suffix in the part number

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V_{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V_{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 µF.
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

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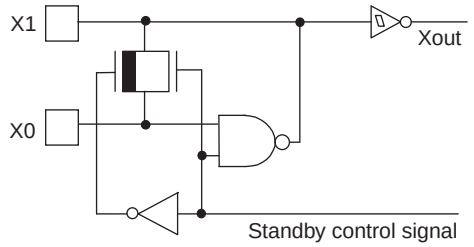
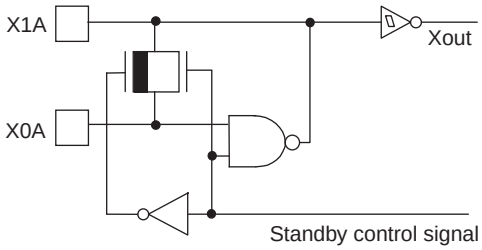
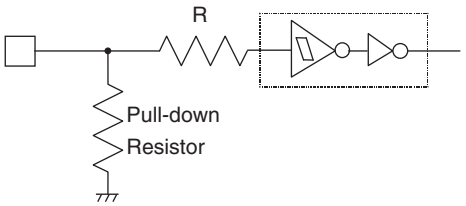
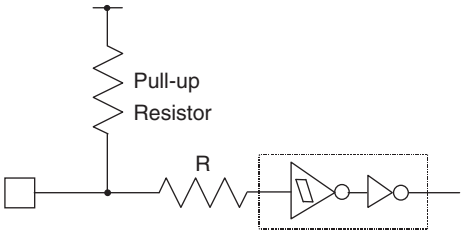
4. I/O Circuit Type

Type	Circuit	Remarks
A		Oscillation circuit High-speed oscillation feedback resistor = approx. 1 MΩ
B		Oscillation circuit Low-speed oscillation feedback resistor = approx. 10 MΩ
C		■ MASK ROM and evaluation products: CMOS hysteresis input pin ■ Flash memory products: CMOS input pin
D		MASK ROM and evaluation products: ■ CMOS hysteresis input pin ■ Pull-down resistor value: approx. 50 kΩ Flash memory products: ■ CMOS input pin ■ No pull-down
E		CMOS hysteresis input pin Pull-up resistor value: approx. 50 kΩ

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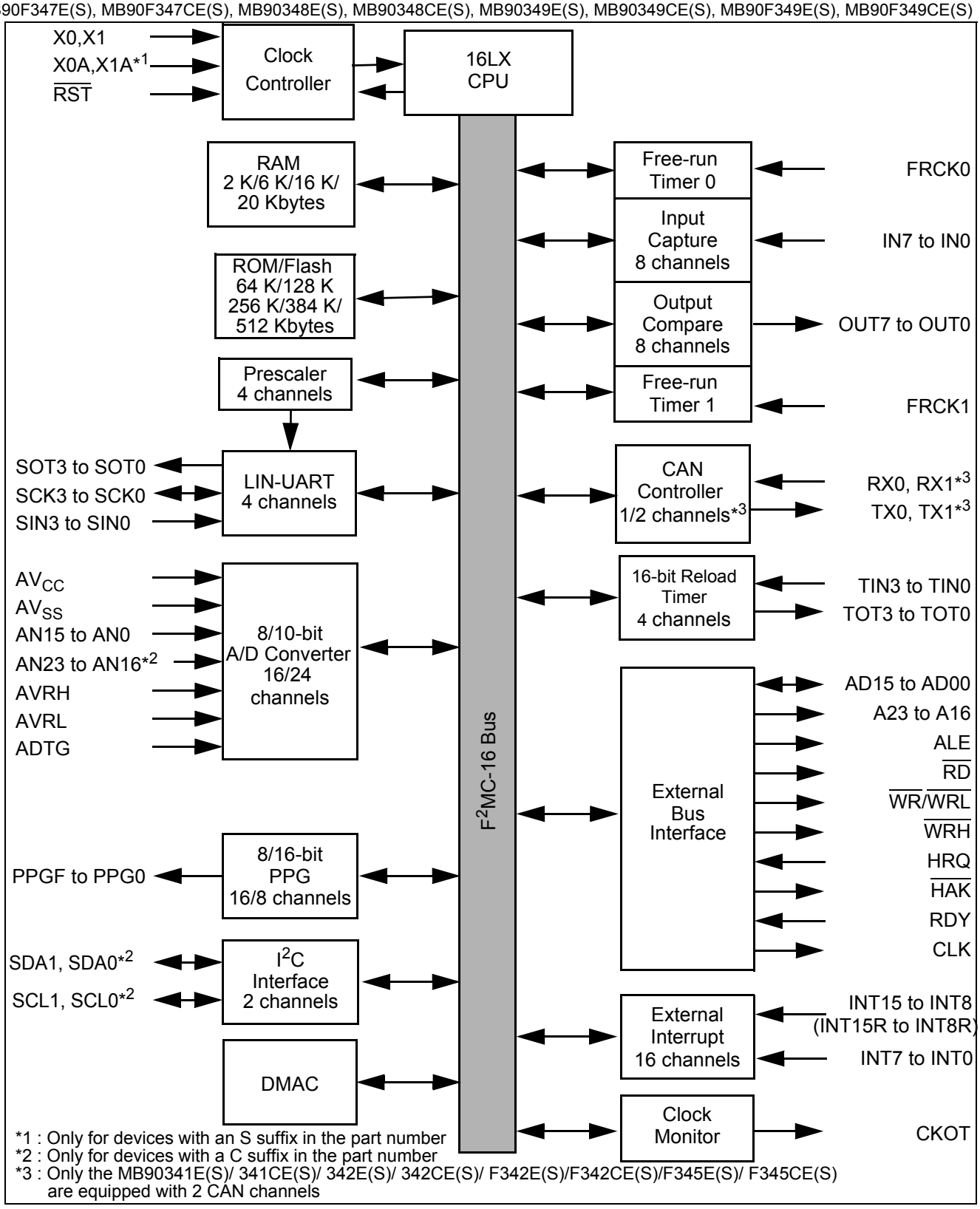
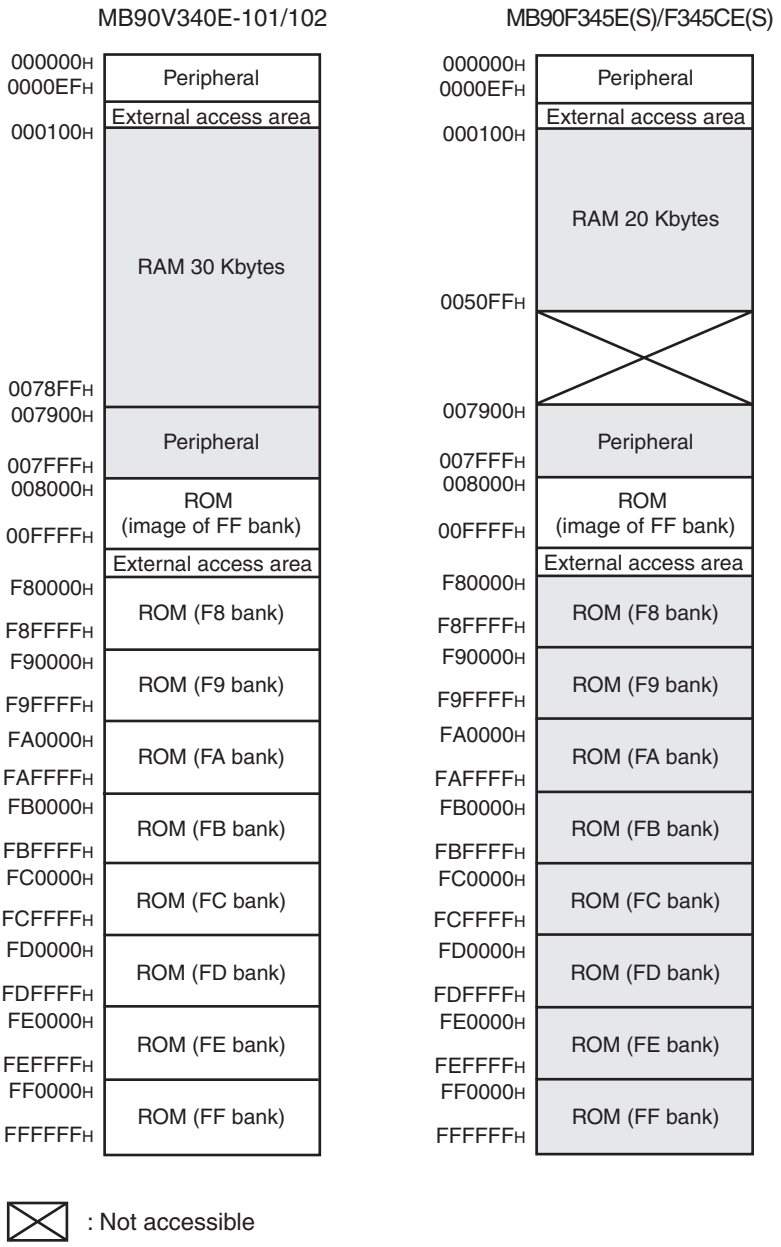
■ MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90346E(S), MB90346CE(S), MB90F346E(S), MB90F346CE(S), MB90347E(S), MB90347CE(S), MB90F347E(S), MB90F347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S), MB90F349E(S), MB90F349CE(S)



7. Memory Map


MB90V340E-101/102
000000H
0000EFH
Peripheral
External access area
000100H
RAM 30 Kbytes
0078FFH
007900H
Peripheral
007FFFH
008000H
ROM
(image of FF bank)
00FFFFH
External access area
F80000H
ROM (F8 bank)
F8FFFFH
F90000H
ROM (F9 bank)
F9FFFFH
FA0000H
ROM (FA bank)
FAFFFFH
FB0000H
ROM (FB bank)
FBFFFFH
FC0000H
ROM (FC bank)
FCFFFFH
FD0000H
ROM (FD bank)
FDFFFFH
FE0000H
ROM (FE bank)
FEFFFFH
FF0000H
ROM (FF bank)
FFFFFFH
MB90F345E(S)/F345CE(S)
000000H
0000EFH
Peripheral
External access area
000100H
RAM 20 Kbytes
0050FFH
007900H
Peripheral
007FFFH
008000H
ROM
(image of FF bank)
00FFFFH
External access area
F80000H
ROM (F8 bank)
F8FFFFH
F90000H
ROM (F9 bank)
F9FFFFH
FA0000H
ROM (FA bank)
FAFFFFH
FB0000H
ROM (FB bank)
FBFFFFH
FC0000H
ROM (FC bank)
FCFFFFH
FD0000H
ROM (FD bank)
FDFFFFH
FE0000H
ROM (FE bank)
FEFFFFH
FF0000H
ROM (FF bank)
FFFFFFH
: Not accessible

Address	Register	Abbreviation	Access	Resource name	Initial value
000020_H	Serial Mode Register 0	SMR0	W,R/W	UART0	00000000_B
000021_H	Serial Control Register 0	SCR0	W,R/W		00000000_B
000022_H	Reception/Transmission Data Register 0	RDR0/TDR0	R/W		00000000_B
000023_H	Serial Status Register 0	SSR0	R,R/W		00001000_B
000024_H	Extended Communication Control Register 0	ECCR0	R,W, R/W		$000000XX_B$
000025_H	Extended Status/Control Register 0	ESCR0	R/W		00000100_B
000026_H	Baud Rate Generator Register 00	BGR00	R/W		00000000_B
000027_H	Baud Rate Generator Register 01	BGR01	R/W		00000000_B
000028_H	Serial Mode Register 1	SMR1	W,R/W	UART1	00000000_B
000029_H	Serial Control Register 1	SCR1	W,R/W		00000000_B
$00002A_H$	Reception/Transmission Data Register 1	RDR1/TDR1	R/W		00000000_B
$00002B_H$	Serial Status Register 1	SSR1	R,R/W		00001000_B
$00002C_H$	Extended Communication Control Register 1	ECCR1	R,W, R/W		$000000XX_B$
$00002D_H$	Extended Status/Control Register 1	ESCR1	R/W		00000100_B
$00002E_H$	Baud Rate Generator Register 10	BGR10	R/W		00000000_B
$00002F_H$	Baud Rate Generator Register 11	BGR11	R/W		00000000_B
000030_H	PPG 0 Operation Mode Control Register	PPGC0	W,R/W	16-bit PPG 0/1	$0X000XX1_B$
000031_H	PPG 1 Operation Mode Control Register	PPGC1	W,R/W		$0X000001_B$
000032_H	PPG 0/PPG 1 Count Clock Select Register	PPG01	R/W		$000000X0_B$
000033_H	Reserved				
000034_H	PPG 2 Operation Mode Control Register	PPGC2	W,R/W	16-bit PPG 2/3	$0X000XX1_B$
000035_H	PPG 3 Operation Mode Control Register	PPGC3	W,R/W		$0X000001_B$
000036_H	PPG 2/PPG 3 Count Clock Select Register	PPG23	R/W		$000000X0_B$
000037_H	Reserved				
000038_H	PPG 4 Operation Mode Control Register	PPGC4	W,R/W	16-bit PPG 4/5	$0X000XX1_B$
000039_H	PPG 5 Operation Mode Control Register	PPGC5	W,R/W		$0X000001_B$
$00003A_H$	PPG 4/PPG 5 Clock Select Register	PPG45	R/W		$000000X0_B$
$00003B_H$	Address Detect Control Register 1	PACSR1	R/W	Address Match Detection 1	00000000_B
$00003C_H$	PPG 6 Operation Mode Control Register	PPGC6	W,R/W	16-bit PPG 6/7	$0X000XX1_B$
$00003D_H$	PPG 7 Operation Mode Control Register	PPGC7	W,R/W		$0X000001_B$
$00003E_H$	PPG 6/PPG 7 Count Clock Control Register	PPG67	R/W		$000000X0_B$
$00003F_H$	Reserved				

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List of Message Buffers (DLC Registers and Data Registers) (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A80_H$ to $007A87_H$	$007C80_H$ to $007C87_H$	Data Register 0 (8 bytes)	DTR0	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A88_H$ to $007A8F_H$	$007C88_H$ to $007C8F_H$	Data Register 1 (8 bytes)	DTR1	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A90_H$ to $007A97_H$	$007C90_H$ to $007C97_H$	Data Register 2 (8 bytes)	DTR2	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A98_H$ to $007A9F_H$	$007C98_H$ to $007C9F_H$	Data Register 3 (8 bytes)	DTR3	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AA0_H$ to $007AA7_H$	$007CA0_H$ to $007CA7_H$	Data Register 4 (8 bytes)	DTR4	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AA8_H$ to $007AAF_H$	$007CA8_H$ to $007CAF_H$	Data Register 5 (8 bytes)	DTR5	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AB0_H$ to $007AB7_H$	$007CB0_H$ to $007CB7_H$	Data Register 6 (8 bytes)	DTR6	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AB8_H$ to $007ABF_H$	$007CB8_H$ to $007CBF_H$	Data Register 7 (8 bytes)	DTR7	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AC0_H$ to $007AC7_H$	$007CC0_H$ to $007CC7_H$	Data Register 8 (8 bytes)	DTR8	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AC8_H$ to $007ACF_H$	$007CC8_H$ to $007CCF_H$	Data Register 9 (8 bytes)	DTR9	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AD0_H$ to $007AD7_H$	$007CD0_H$ to $007CD7_H$	Data Register 10 (8 bytes)	DTR10	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AD8_H$ to $007ADF_H$	$007CD8_H$ to $007CDF_H$	Data Register 11 (8 bytes)	DTR11	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AE0_H$ to $007AE7_H$	$007CE0_H$ to $007CE7_H$	Data Register 12 (8 bytes)	DTR12	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AE8_H$ to $007AEF_H$	$007CE8_H$ to $007CEF_H$	Data Register 13 (8 bytes)	DTR13	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$

10. Interrupt Factors, Interrupt Vectors, Interrupt Control Register

Interrupt cause	EI^{2}OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
Reset	N	—	#08	FFFFDC$_H$	—	—
INT9 instruction	N	—	#09	FFFFD8$_H$	—	—
Exception	N	—	#10	FFFFD4$_H$	—	—
CAN 0 RX	N	—	#11	FFFFD0$_H$	ICR00	0000B0$_H$
CAN 0 TX/NS	N	—	#12	FFFFCC$_H$		
CAN 1 RX / Input Capture 6	Y1	—	#13	FFFFC8$_H$	ICR01	0000B1$_H$
CAN 1 TX/NS / Input Capture 7	Y1	—	#14	FFFFC4$_H$		
CAN 2 RX / I^{2}C0	N	—	#15	FFFFC0$_H$	ICR02	0000B2$_H$
CAN 2 TX/NS	N	—	#16	FFFFBC$_H$		
16-bit Reload Timer 0	Y1	0	#17	FFFFB8$_H$	ICR03	0000B3$_H$
16-bit Reload Timer 1	Y1	1	#18	FFFFB4$_H$		
16-bit Reload Timer 2	Y1	2	#19	FFFFB0$_H$	ICR04	0000B4$_H$
16-bit Reload Timer 3	Y1	—	#20	FFFFAC$_H$		
PPG 0/1/4/5	N	—	#21	FFFFA8$_H$	ICR05	0000B5$_H$
PPG 2/3/6/7	N	—	#22	FFFFA4$_H$		
PPG 8/9/C/D	N	—	#23	FFFFA0$_H$	ICR06	0000B6$_H$
PPG A/B/E/F	N	—	#24	FFFF9C$_H$		
Time Base Timer	N	—	#25	FFFF98$_H$	ICR07	0000B7$_H$
External Interrupt 0 to 3, 8 to 11	Y1	3	#26	FFFF94$_H$		
Watch Timer	N	—	#27	FFFF90$_H$	ICR08	0000B8$_H$
External Interrupt 4 to 7, 12 to 15	Y1	4	#28	FFFF8C$_H$		
A/D Converter	Y1	5	#29	FFFF88$_H$	ICR09	0000B9$_H$
Free-run Timer 0 / Free-run Timer 1	N	—	#30	FFFF84$_H$		
Input Capture 4/5 / I^{2}C1	Y1	6	#31	FFFF80$_H$	ICR10	0000BA$_H$
Output Compare 0/1/4/5	Y1	7	#32	FFFF7C$_H$		
Input Capture 0 to 3	Y1	8	#33	FFFF78$_H$	ICR11	0000BB$_H$
Output Compare 2/3/6/7	Y1	9	#34	FFFF74$_H$		
UART 0 RX	Y2	10	#35	FFFF70$_H$	ICR12	0000BC$_H$
UART 0 TX	Y1	11	#36	FFFF6C$_H$		
UART 1 RX / UART 3 RX	Y2	12	#37	FFFF68$_H$	ICR13	0000BD$_H$
UART 1 TX / UART 3 TX	Y1	13	#38	FFFF64$_H$		

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Interrupt cause	EI^{2}OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
UART 2 RX / UART 4 RX	Y2	14	#39	$FFFF60_H$	ICR14	$0000BE_H$
UART 2 TX / UART 4 TX	Y1	15	#40	$FFFF5C_H$		
Flash Memory	N	——	#41	$FFFF58_H$	ICR15	$0000BF_H$
Delayed Interrupt	N	——	#42	$FFFF54_H$		

Y1 : Usable
Y2 : Usable, with EI^{2}OS stop function
N : Unusable

Note:
- The peripheral resources sharing the ICR register have the same interrupt level.
- When two peripheral resources share the ICR register, only one can use Extended Intelligent I/O Service at a time.
- When either of the two peripheral resources sharing the ICR register specifies Extended Intelligent I/O Service, the other one cannot use interrupts.

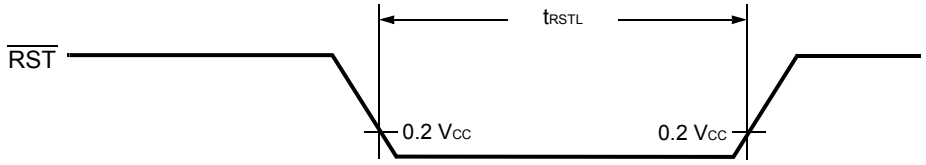
11.4.2 Reset Standby Input

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0.0 V)

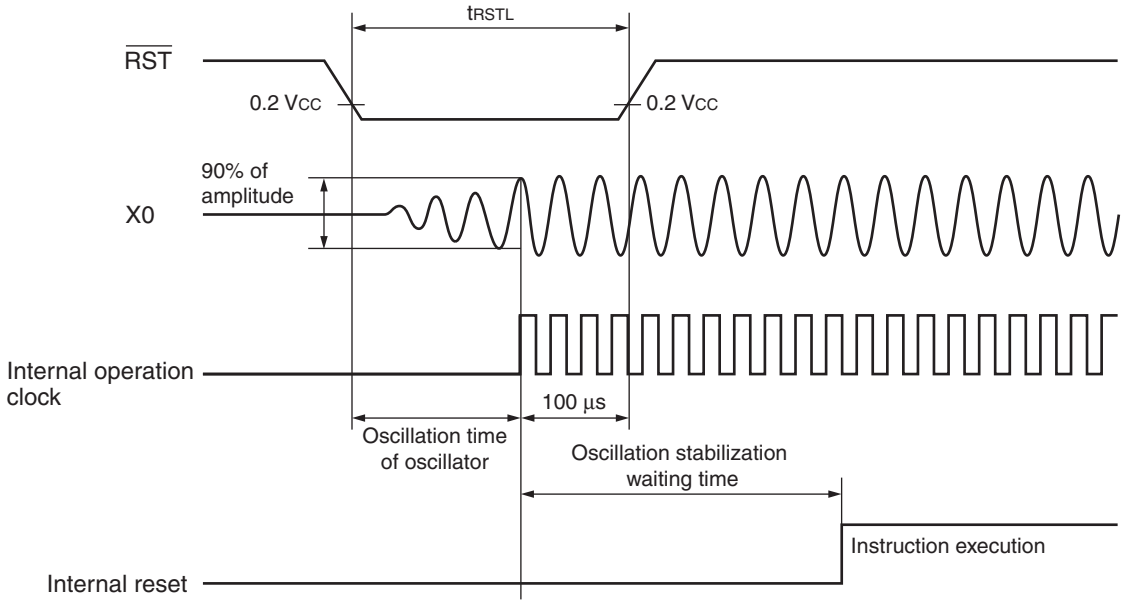
Parameter	Symbol	Pin	Value		Unit	Remarks
			Min	Max		
Reset input time	t_{RSTL}	$\overline{RST}$	500	—	ns	Under normal operation
			Oscillation time of oscillator* + 100 µs	—	µs	In Stop mode, Sub Clock mode, Sub Sleep mode and Watch mode
			100	—	µs	In Time Timer mode

* : The oscillation time of the oscillator is the time it takes for the amplitude of the oscillations to reach 90%. For crystal oscillators, this time is between several ms and several tens of ms, for ceramic oscillators the time is between several hundred µs and several ms, and for an external clock, the time is 0 ms.

- **Under normal operation:**



- **In Stop mode, Sub Clock mode, Sub Sleep mode, Watch mode:**



11.4.9 LIN-UART0/1/2/3

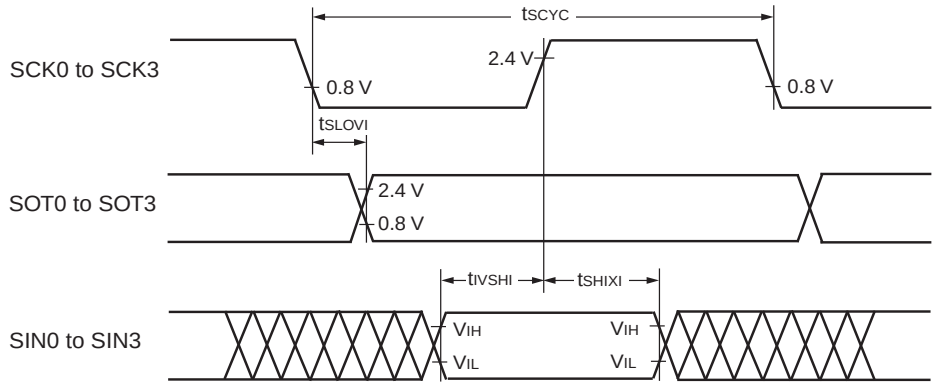
■ **Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0**

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

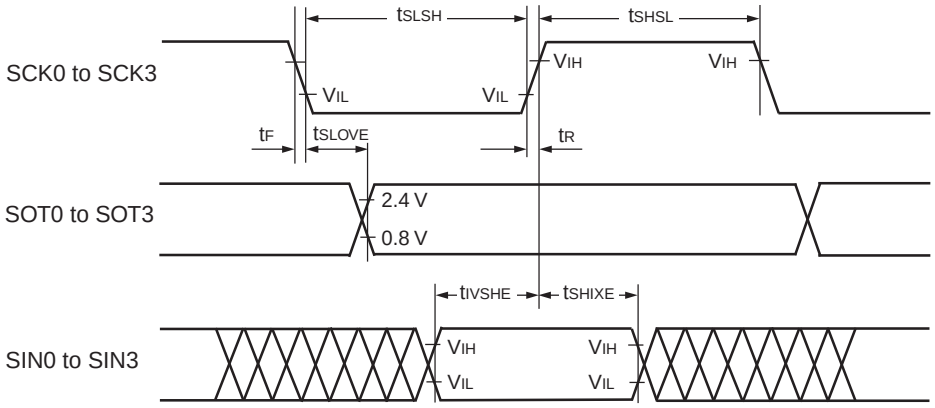
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are C_L = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		−50	+50	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock “L” pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are C_L = 80 pF + 1 TTL.	3 t_{CP} - t_R	—	ns
Serial clock “H” pulse width	t_{SLSH}	SCK0 to SCK3		t_{CP} + 10	—	ns
SCK ↓ → SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	2 t_{CP} + 60	ns
Valid SIN → SCK ↑	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXE}	SCK0, SCK1, SIN0 to SIN3		t_{CP} + 30	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

Note:
- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “ (1) Clock Timing”.

- Internal Shift Clock Mode



- External Shift Clock Mode



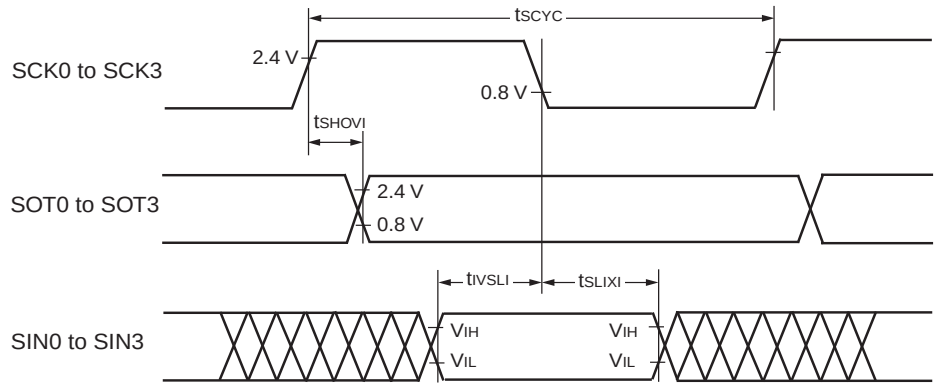
■ **Bit setting: ESCR:SCES = 1, ECCR:SCDE = 0**

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

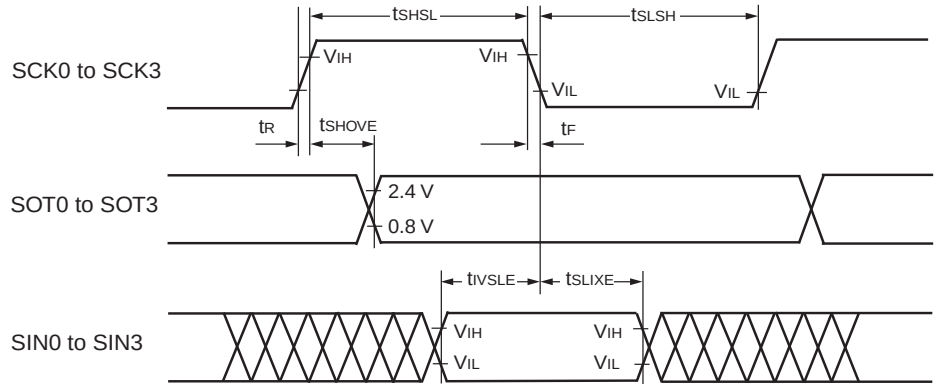
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are C_L = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		−50	+50	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↓ → Valid SIN hold time	t_{SLIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock “H” pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are C_L = 80 pF + 1 TTL.	3 t_{CP} - t_R	—	ns
Serial clock “L” pulse width	t_{SLSH}	SCK0 to SCK3		t_{CP} + 10	—	ns
SCK ↑ → SOT delay time	t_{SHOVE}	SCK0 to SCK3, SOT0 to SOT3		—	2 t_{CP} + 60	ns
Valid SIN → SCK ↓	t_{IVSLE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK ↓ → Valid SIN hold time	t_{SLIXE}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 30	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

Note:
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.

- Internal Shift Clock Mode



- External Shift Clock Mode

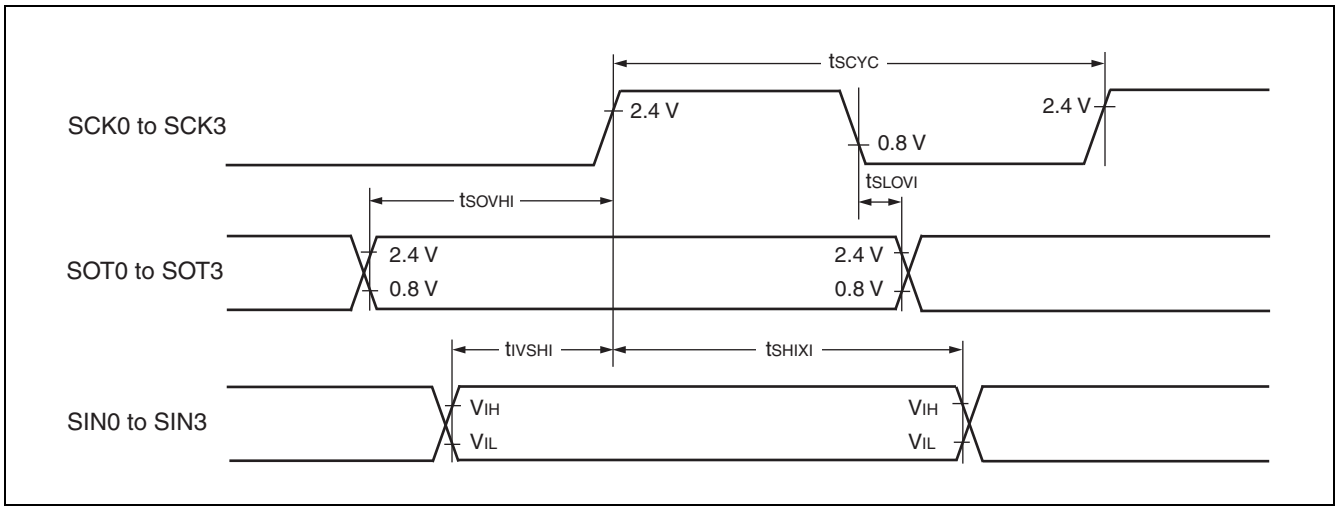


■ **Bit setting: ESCR:SCES = 1, ECCR:SCDE = 1**

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are C_L = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		−50	+50	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT → SCK ↑ delay time	t_{SOVHI}	SCK0 to SCK3, SOT0 to SOT3		3 t_{CP} − 70	—	ns

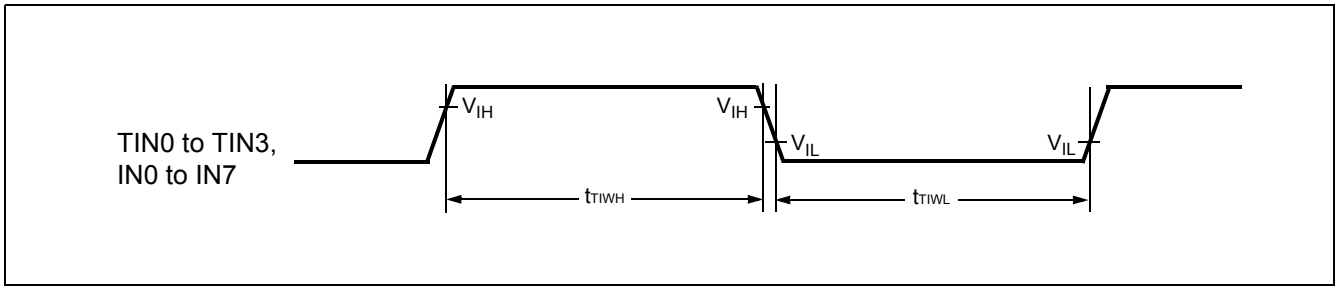
Note:
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to "Clock Timing".



11.4.11 Timer Related Resource Input Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

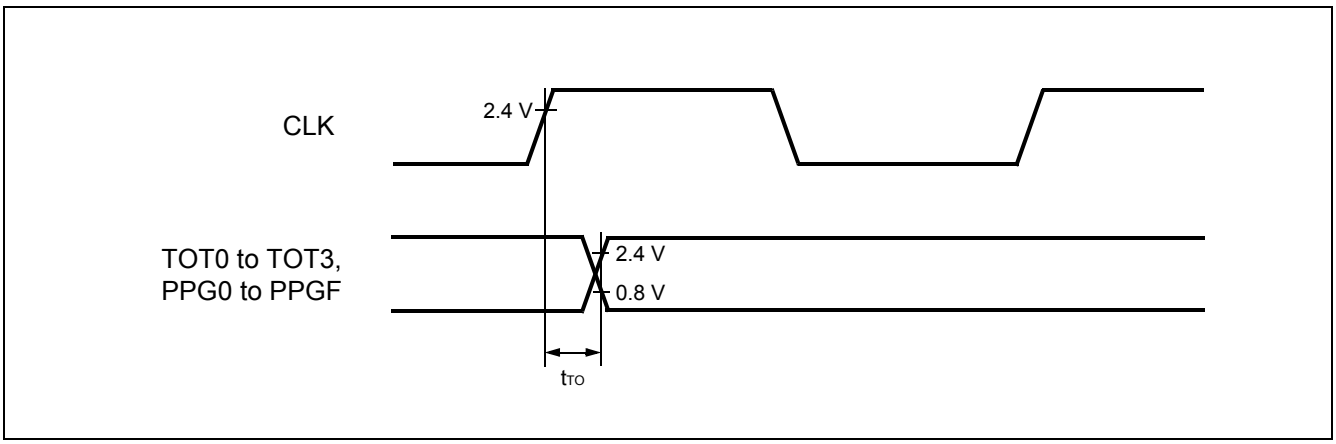
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TIWH} t_{TIWL}	TIN0 to TIN3, IN0 to IN7	—	4 t_{CP}	—	ns



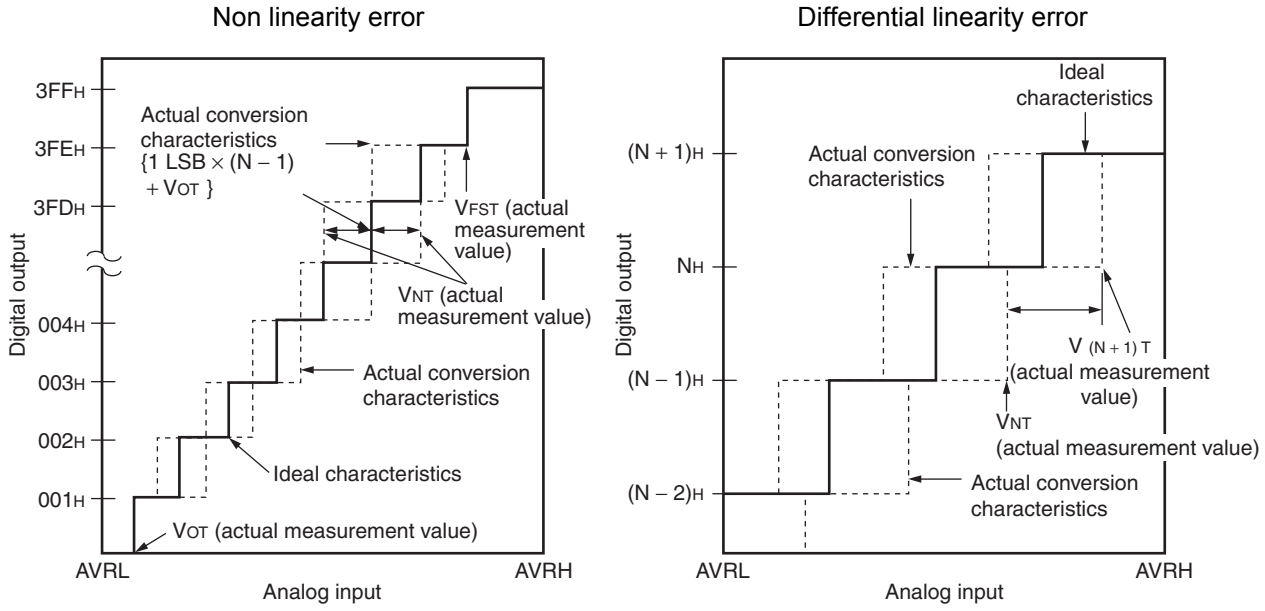
11.4.12 Timer Related Resource Output Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0.0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
CLK ↑ → T_{OUT} change time	t_{TO}	TOT0 to TOT3, PPG0 to PPGF	—	30	—	ns



(Continued)



$$\text{Non linearity error of digital output N} = \frac{V_{NT} - \{1\ \text{LSB} \times (N - 1) + V_{OT}\}}{1\ \text{LSB}}\ [\text{LSB}]$$

$$\text{Differential linearity error of digital output N} = \frac{V_{(N+1)T} - V_{NT}}{1\ \text{LSB}} - 1\ \text{LSB}\ [\text{LSB}]$$

$$1\ \text{LSB} = \frac{V_{FST} - V_{OT}}{1022}\ [\text{V}]$$

N : Value of the digital output from the A/D converter
V_{OT} : Voltage at which digital output transits from "000_H" to "001_H."
V_{FST} : Voltage at which digital output transits from "$3FE_H$" to "$3FF_H$."

11.7 Notes on A/D Converter Section

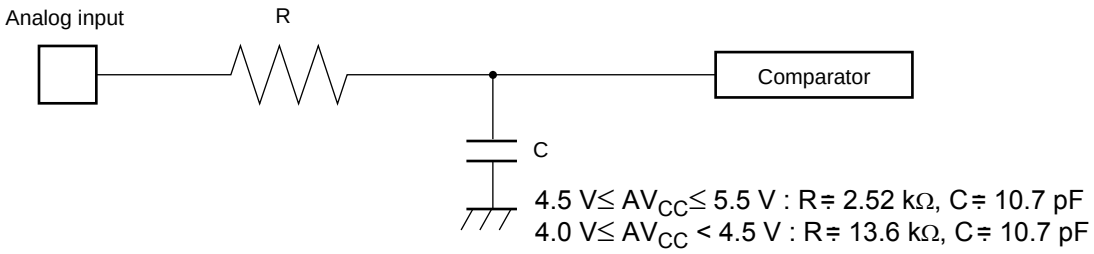
Use the device with external circuits of the following output impedance for analog inputs :

Recommended output impedance of external circuits are : Approx. 1.5 kΩ or lower (4.0 V≤ AV_{CC}≤ 5.5 V, sampling period = 0.5 µs)

If an external capacitor is used, in consideration of the capacitive voltage dividing effect between the external capacitor and the internal on-chip capacitor, it is recommended that the capacitance of the external capacitor be several thousand times greater than the capacitance of the internal capacitor.

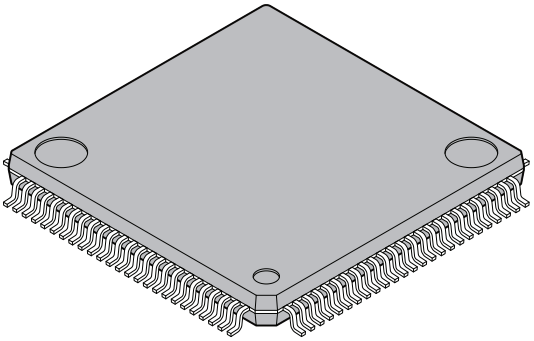
If the output impedance of the external circuit is too high, a sampling period for an analog voltage may be insufficient.

- Analog input circuit model



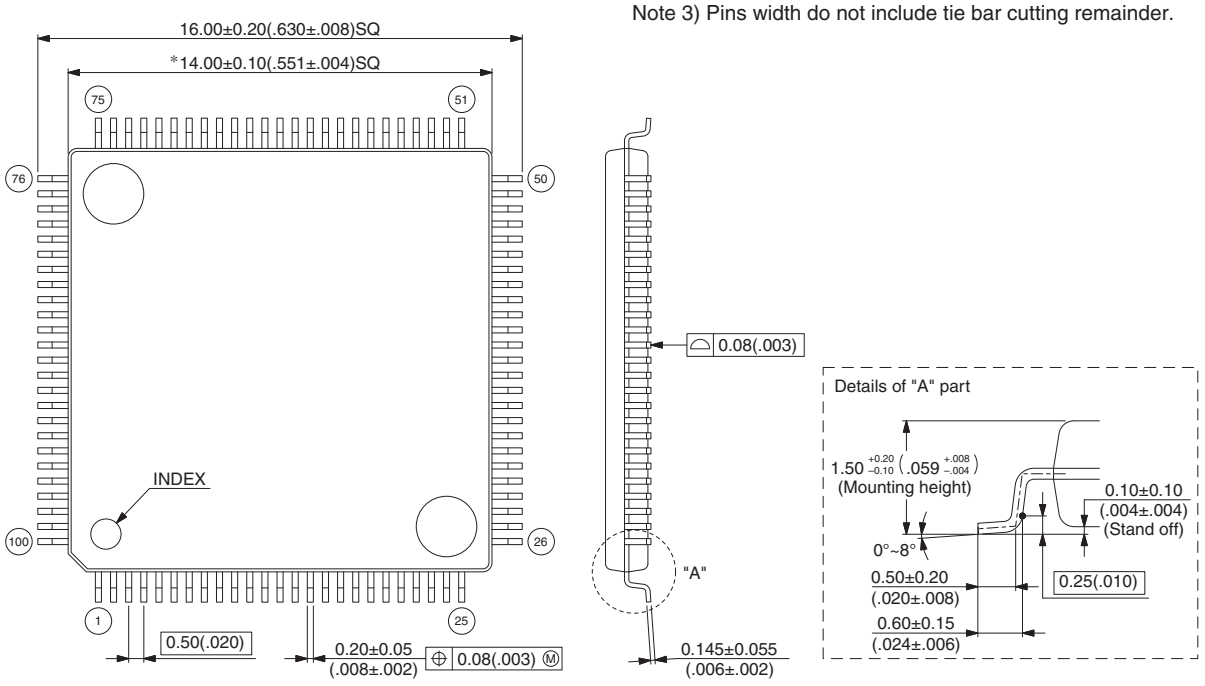
Note: : Use the values in the figure only as a guideline.

14. Package Dimensions

100-pin plastic LQFP		
	Lead pitch	0.50 mm
	Package width × package length	14.0 mm × 14.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm Max
	Weight	0.65 g
(FPT-100P-M20)	Code (Reference)	P-LFQFP100-14×14-0.50

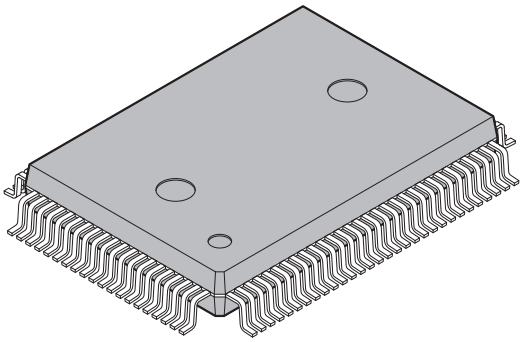
100-pin plastic LQFP
(FPT-100P-M20)

Note 1) * : These dimensions do not include resin protrusion.
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.



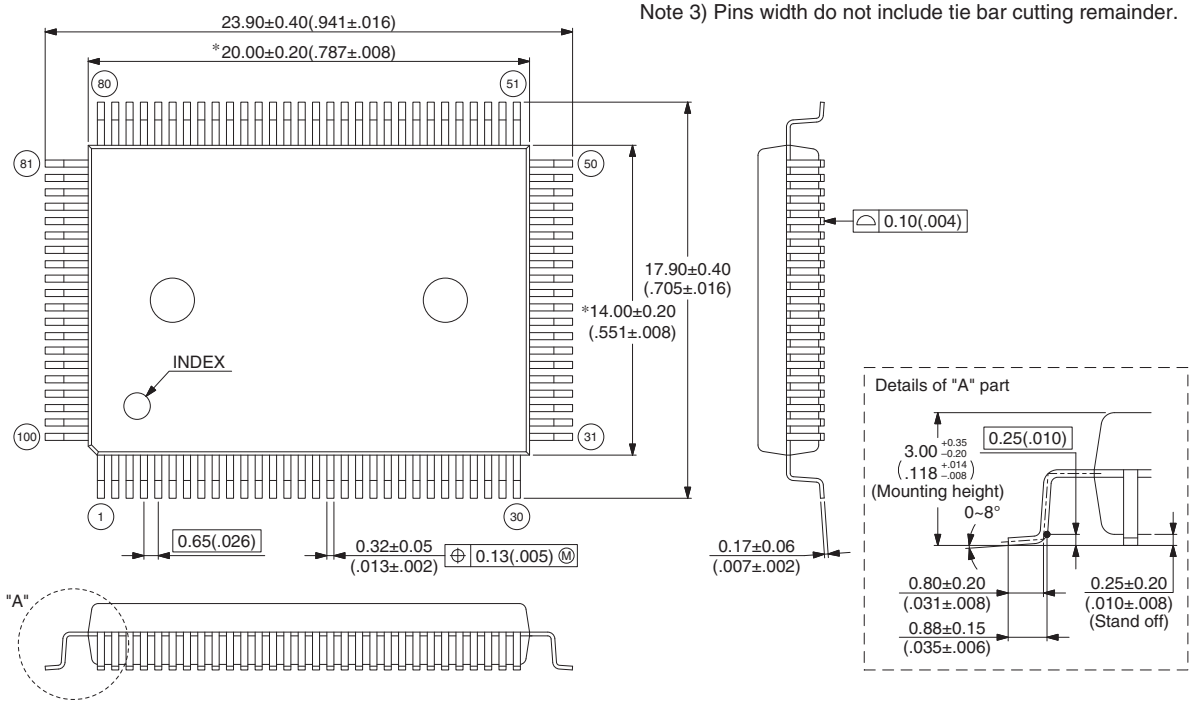
Dimensions in mm (inches).
Note: The values in parentheses are reference values

(Continued)

100-pin plastic QFP		
	Lead pitch	0.65 mm
	Package width × package length	14.00 × 20.00 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	3.35 mm MAX
	Code (Reference)	P-QFP100-14×20-0.65
(FPT-100P-M06)		

100-pin plastic QFP
(FPT-100P-M06)

Note 1) * : These dimensions do not include resin protrusion.
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.



Dimensions in mm (inches).
Note: The values in parentheses are reference values.