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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-301e1

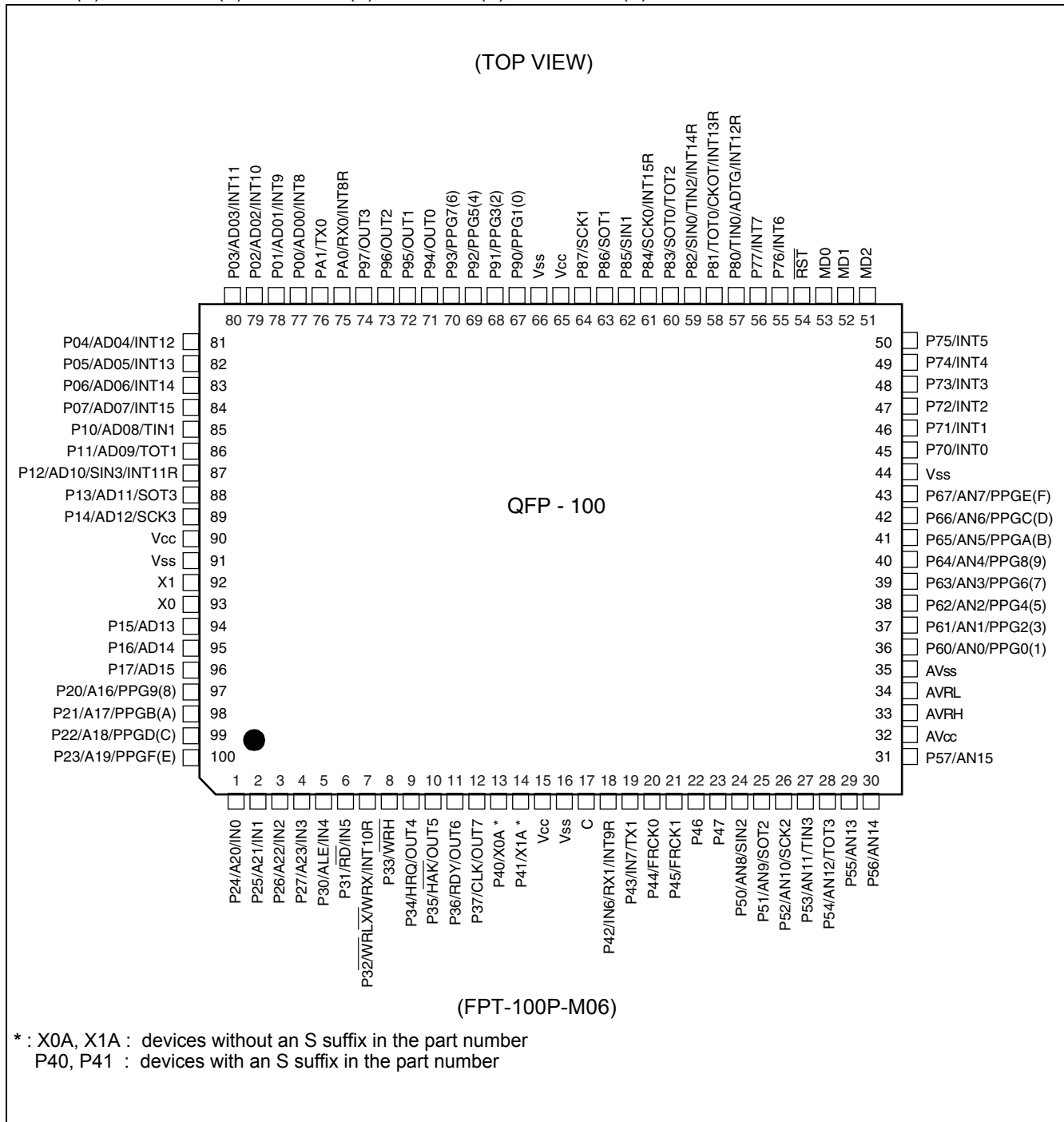
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Part Number	MB90V340E-101, MB90V340E-102	MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
Parameter			
External Interrupt (16 channels)	Can be used rising edge, falling edge, starting up by H/L level input, external interrupt, expanded intelligent I/O services (EI ² OS) and DMA		
D/A Converter	2 channels	—	
Sub clock (maximum 100 kHz)	Only for MB90V340E-102	Devices with sub clock : devices without an S suffix in the part number Devices without sub clock : devices with an S suffix in the part number	
I/O Ports	Virtually all external pins can be used as general purpose I/O port All ports are push-pull outputs Bit-wise settable as input/output or peripheral signal Can be configured 8 as CMOS schmitt trigger/ automotive inputs (in blocks of 8 pins) TTL input level settable for external bus (32-pin only for external bus)		
Flash Memory	—	Supports automatic programming, Embedded Algorithm Write/Erase/Erase-Suspend/Resume commands A flag indicating completion of the algorithm Number of erase cycles : 10000 cycles Data retention time : 20 years Boot block configuration Erase can be performed on each block Block protection with external programming voltage Flash Security Feature for protecting the content of the Flash (except for MB90F346E(S) and MB90F346CE (S))	

* : It is setting of Jumper switch (TOOL VCC) when Emulator (MB2147-01-E) is used.
Please refer to the Emulator operation manual for details.

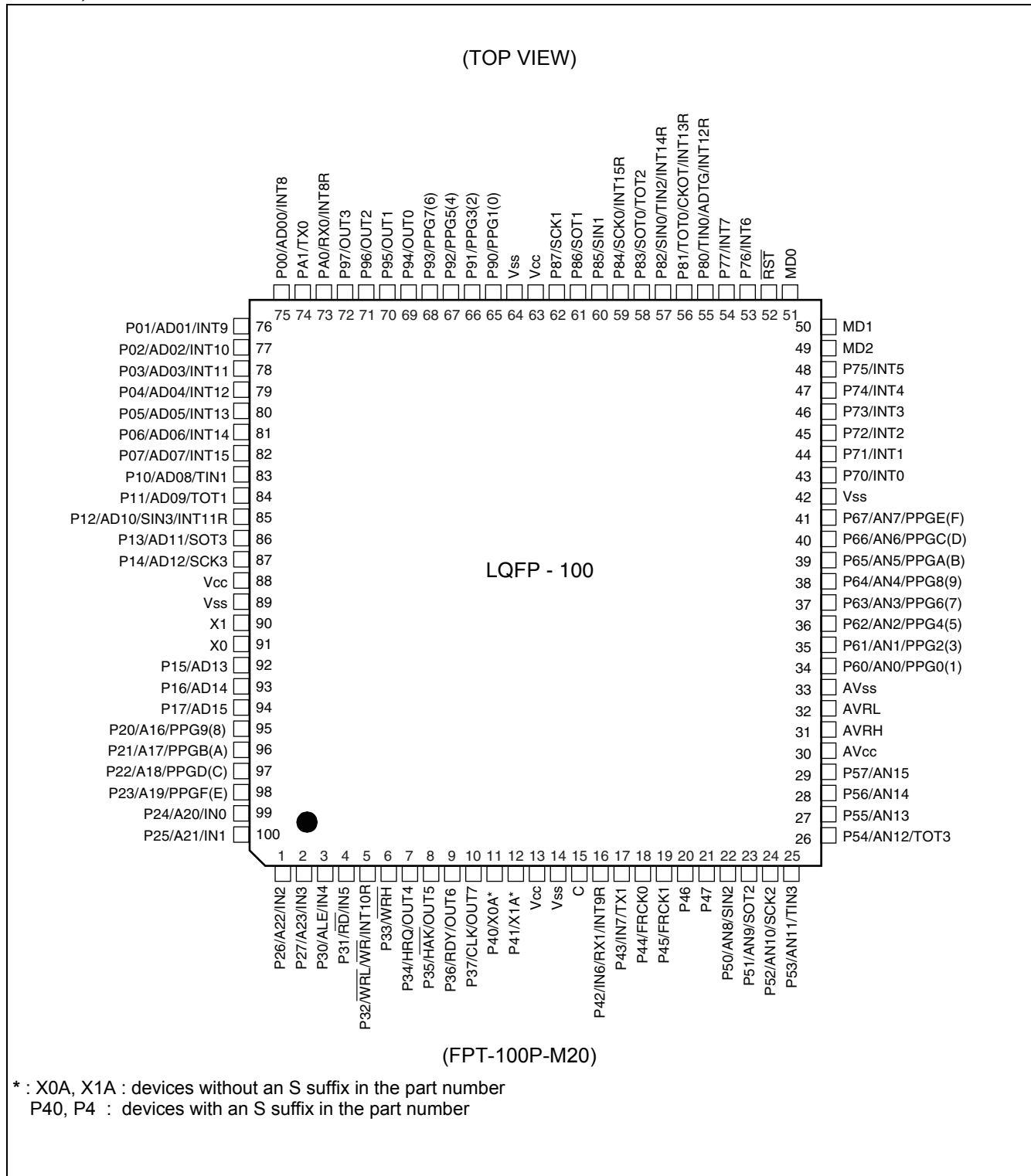
2. Pin Assignments

■ MB90341E(S), MB90342E(S), MB90F342E(S), MB90F345E(S), MB90346E(S), MB90F346E(S), MB90347E(S), MB90F347E(S), MB90348E(S), MB90349E(S), MB90F349E(S)

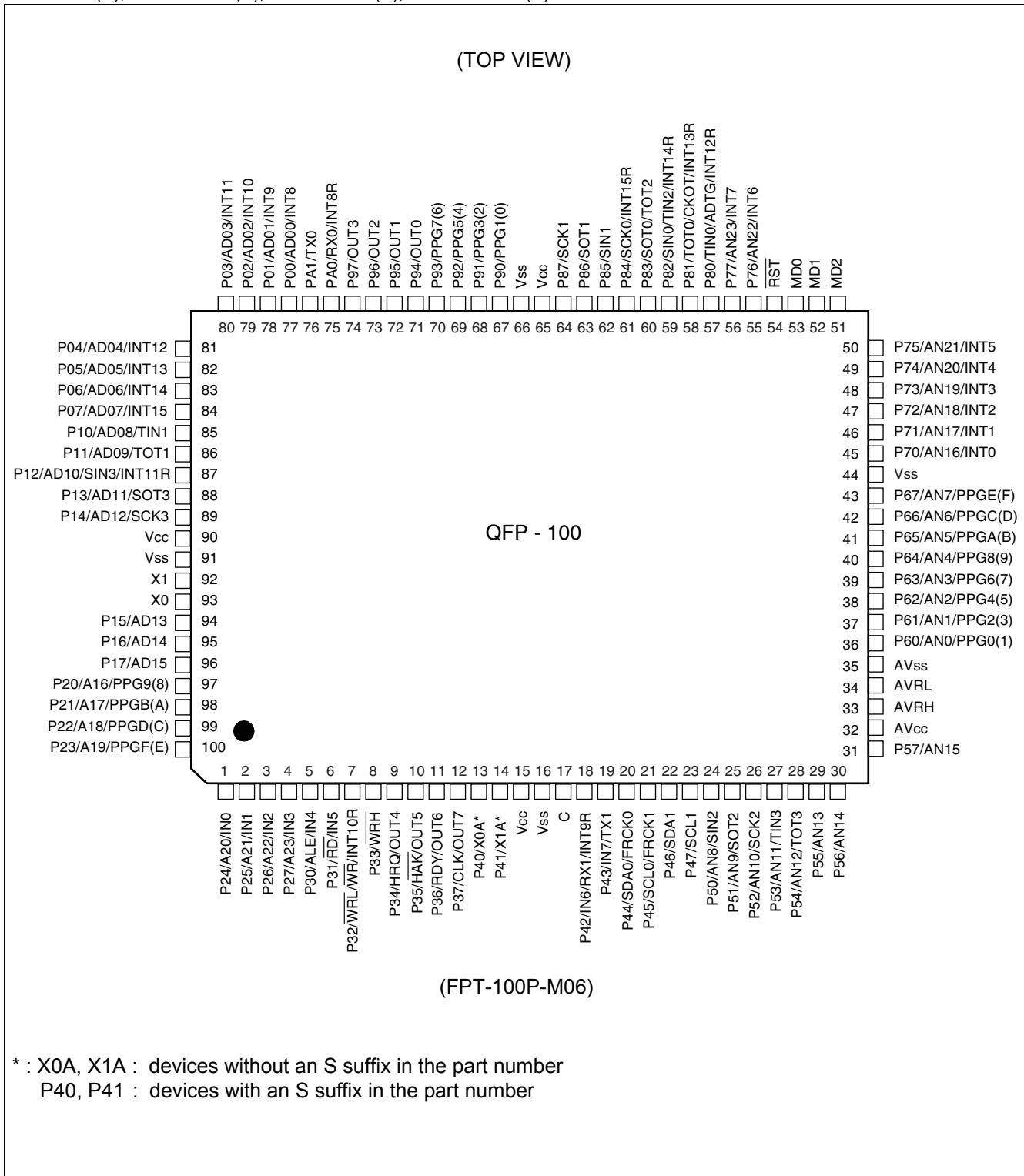


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■ MB90341CE(S), MB90342CE(S), MB90F342CE(S), MB90F345CE(S), MB90346CE(S), MB90F346CE(S), MB90347CE(S), MB90F347CE(S), MB90348CE(S), MB90349CE(S), MB90F349CE(S)



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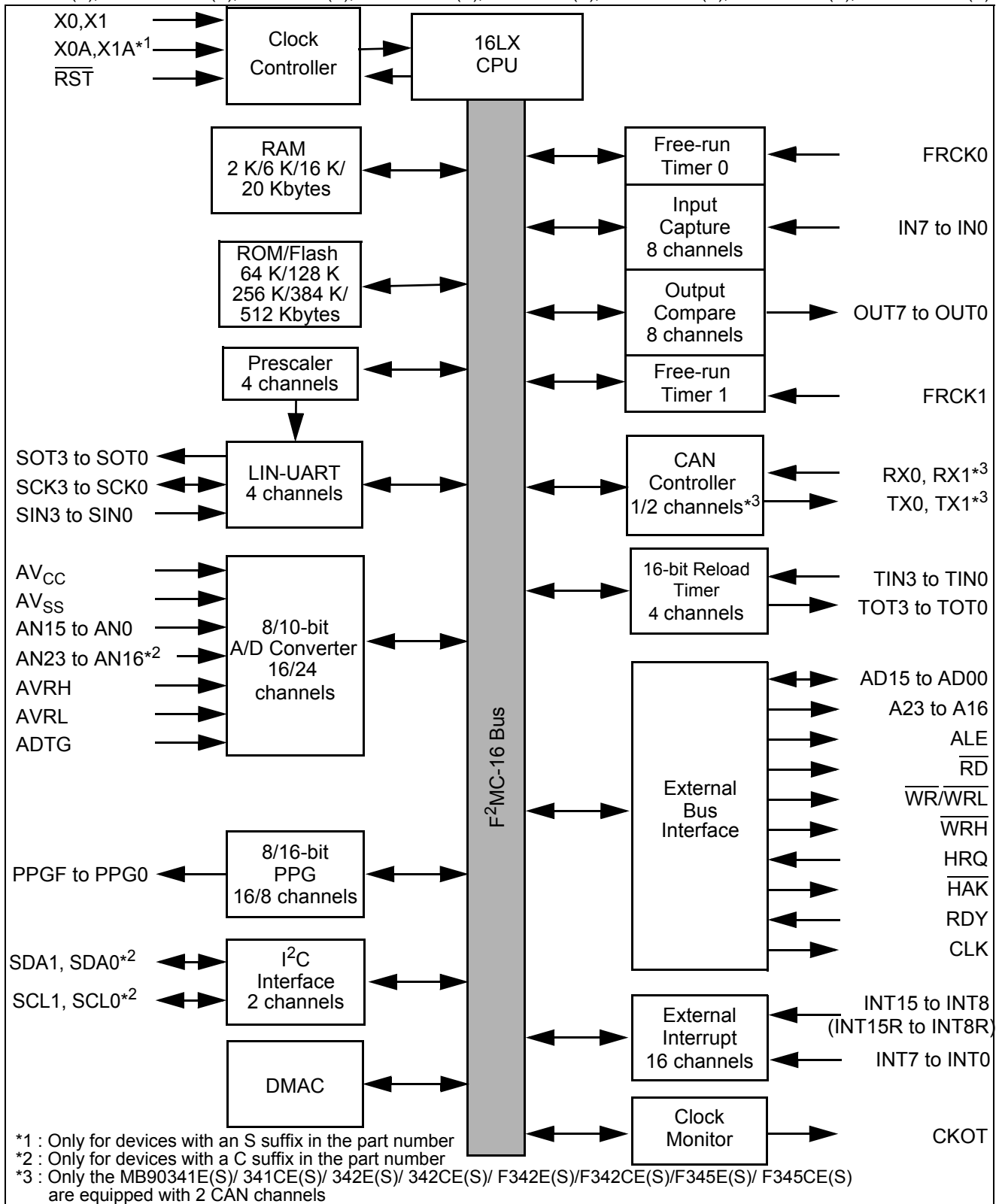
Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V _{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 μF .
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

(Continued)

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
19	17	P43	F	General purpose I/O pin.
		IN7		Trigger input pin for input capture.
		TX1		TX Output pin for CAN1 (MB90341E/342E/F342E/F345E only)
20	18	P44	H	General purpose I/O pin.
		SDA0		Serial data I/O pin for I ² C (devices with a C suffix in the part number)
		FRCK0		Input pin for the 16-bit Free-run Timer 0
21	19	P45	H	General purpose I/O pin.
		SCL0		Serial clock I/O pin for I ² C (devices with a C suffix in the part number)
		FRCK1		Input pin for the 16-bit Free-run Timer
22	20	P46	H	General purpose I/O pin.
		SDA1		Serial data I/O pin for I ² C (devices with a C suffix in the part number)
23	21	P47	H	General purpose I/O pin.
		SCL1		Serial clock I/O pin for I ² C (devices with a C suffix in the part number)
24	22	P50	O	General purpose I/O pin.
		AN8		Analog input pin for the A/D converter
		SIN2		Serial data input pin for UART2
25	23	P51	I	General purpose I/O pin.
		AN9		Analog input pin for the A/D converter
		SOT2		Serial data output pin for UART2
26	24	P52	I	General purpose I/O pin.
		AN10		Analog input pin for the A/D converter
		SCK2		Clock I/O pin for UART2
27	25	P53	I	General purpose I/O pin.
		AN11		Analog input pin for the A/D converter
		TIN3		Event input pin for the reload timer
28	26	P54	I	General purpose I/O pin.
		AN12		Analog input pin for the A/D converter
		TOT3		Output pin for the reload timer
29	27	P55	I	General purpose I/O pin.
		AN13		Analog input pin for the A/D converter
30, 31	28, 29	P56, P57	J	General purpose I/O pins.
		AN14, AN15		Analog input pins for the A/D converter
32	30	AV _{CC}	K	Analog power input pin for the A/D Converter

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■ MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90346E(S), MB90346CE(S), MB90F346E(S), MB90F346CE(S), MB90347E(S), MB90347CE(S), MB90F347E(S), MB90F347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S), MB90F349E(S), MB90F349CE(S)



Address	Register	Abbreviation	Access	Resource name	Initial value
007900 _H	Reload Register L0	PRL0	R/W	16-bit PPG 0/1	XXXXXXXX _B
007901 _H	Reload Register H0	PRLH0	R/W		XXXXXXXX _B
007902 _H	Reload Register L1	PRL1	R/W		XXXXXXXX _B
007903 _H	Reload Register H1	PRLH1	R/W		XXXXXXXX _B
007904 _H	Reload Register L2	PRL2	R/W	16-bit PPG 2/3	XXXXXXXX _B
007905 _H	Reload Register H2	PRLH2	R/W		XXXXXXXX _B
007906 _H	Reload Register L3	PRL3	R/W		XXXXXXXX _B
007907 _H	Reload Register H3	PRLH3	R/W		XXXXXXXX _B
007908 _H	Reload Register L4	PRL4	R/W	16-bit PPG 4/5	XXXXXXXX _B
007909 _H	Reload Register H4	PRLH4	R/W		XXXXXXXX _B
00790A _H	Reload Register L5	PRL5	R/W		XXXXXXXX _B
00790B _H	Reload Register H5	PRLH5	R/W		XXXXXXXX _B
00790C _H	Reload Register L6	PRL6	R/W	16-bit PPG 6/7	XXXXXXXX _B
00790D _H	Reload Register H6	PRLH6	R/W		XXXXXXXX _B
00790E _H	Reload Register L7	PRL7	R/W		XXXXXXXX _B
00790F _H	Reload Register H7	PRLH7	R/W		XXXXXXXX _B
007910 _H	Reload Register L8	PRL8	R/W	16-bit PPG 8/9	XXXXXXXX _B
007911 _H	Reload Register H8	PRLH8	R/W		XXXXXXXX _B
007912 _H	Reload Register L9	PRL9	R/W		XXXXXXXX _B
007913 _H	Reload Register H9	PRLH9	R/W		XXXXXXXX _B
007914 _H	Reload Register LA	PRLA	R/W	16-bit PPG A/B	XXXXXXXX _B
007915 _H	Reload Register HA	PRLHA	R/W		XXXXXXXX _B
007916 _H	Reload Register LB	PRLB	R/W		XXXXXXXX _B
007917 _H	Reload Register HB	PRLHB	R/W		XXXXXXXX _B
007918 _H	Reload Register LC	PRLC	R/W	16-bit PPG C/D	XXXXXXXX _B
007919 _H	Reload Register HC	PRLHC	R/W		XXXXXXXX _B
00791A _H	Reload Register LD	PRLD	R/W		XXXXXXXX _B
00791B _H	Reload Register HD	PRLHD	R/W		XXXXXXXX _B
00791C _H	Reload Register LE	PRLLE	R/W	16-bit PPG E/F	XXXXXXXX _B
00791D _H	Reload Register HE	PRLHE	R/W		XXXXXXXX _B
00791E _H	Reload Register LF	PRLLF	R/W		XXXXXXXX _B
00791F _H	Reload Register HF	PRLHF	R/W		XXXXXXXX _B
007920 _H	Input Capture 0	IPCP0	R	Input Capture 0/1	XXXXXXXX _B
007921 _H	Input Capture 0	IPCP0	R		XXXXXXXX _B
007922 _H	Input Capture 1	IPCP1	R		XXXXXXXX _B
007923 _H	Input Capture 1	IPCP1	R		XXXXXXXX _B

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9. CAN Controllers

The CAN controller has the following features:

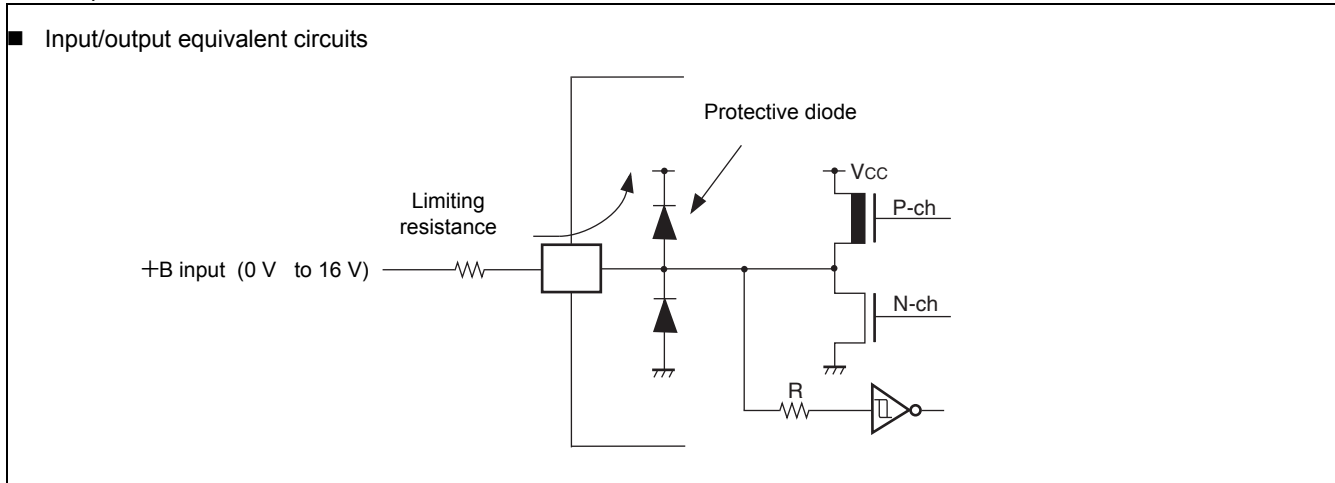
- Conforms to CAN Specification Version 2.0 Part A and B
- Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmission/reception message buffers
- 29-bit ID and 8-byte data
- Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
- Two acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 kbps to 2 Mbps (when input clock is at 16 MHz)

List of Control Registers (1)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
000070 _H	000080 _H	Message Buffer Valid Register	BVALR	R/W	00000000 _B 00000000 _B
000071 _H	000081 _H				
000072 _H	000082 _H	Transmit Request Register	TREQR	R/W	00000000 _B 00000000 _B
000073 _H	000083 _H				
000074 _H	000084 _H	Transmit Cancel Register	TCANR	W	00000000 _B 00000000 _B
000075 _H	000085 _H				
000076 _H	000086 _H	Transmission Complete Register	TCR	R/W	00000000 _B 00000000 _B
000077 _H	000087 _H				
000078 _H	000088 _H	Receive Complete Register	RCR	R/W	00000000 _B 00000000 _B
000079 _H	000089 _H				
00007A _H	00008A _H	Remote Request Receiving Register	RRTRR	R/W	00000000 _B 00000000 _B
00007B _H	00008B _H				
00007C _H	00008C _H	Receive Overrun Register	ROVRR	R/W	00000000 _B 00000000 _B
00007D _H	00008D _H				
00007E _H	00008E _H	Reception Interrupt Enable Register	RIER	R/W	00000000 _B 00000000 _B
00007F _H	00008F _H				

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- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on reset.
- Care must be taken not to leave the +B input pin open.
- Sample recommended circuits:

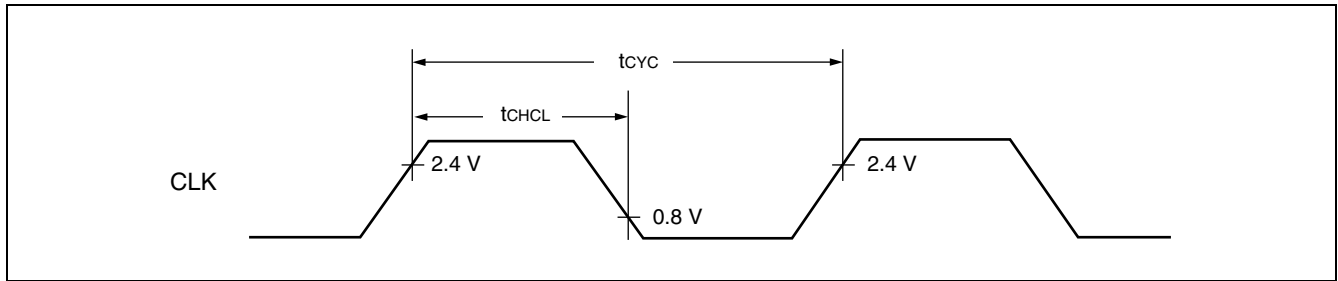


*6: The maximum output current is defined as the peak value of the current of any one of the corresponding pins.

*7: The average output current is defined as the value of the average current flowing over 100 ms at any one of the corresponding pins.

*8: The average total output current is defined as the value of the average current flowing over 100 ms at all of the corresponding pins.

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

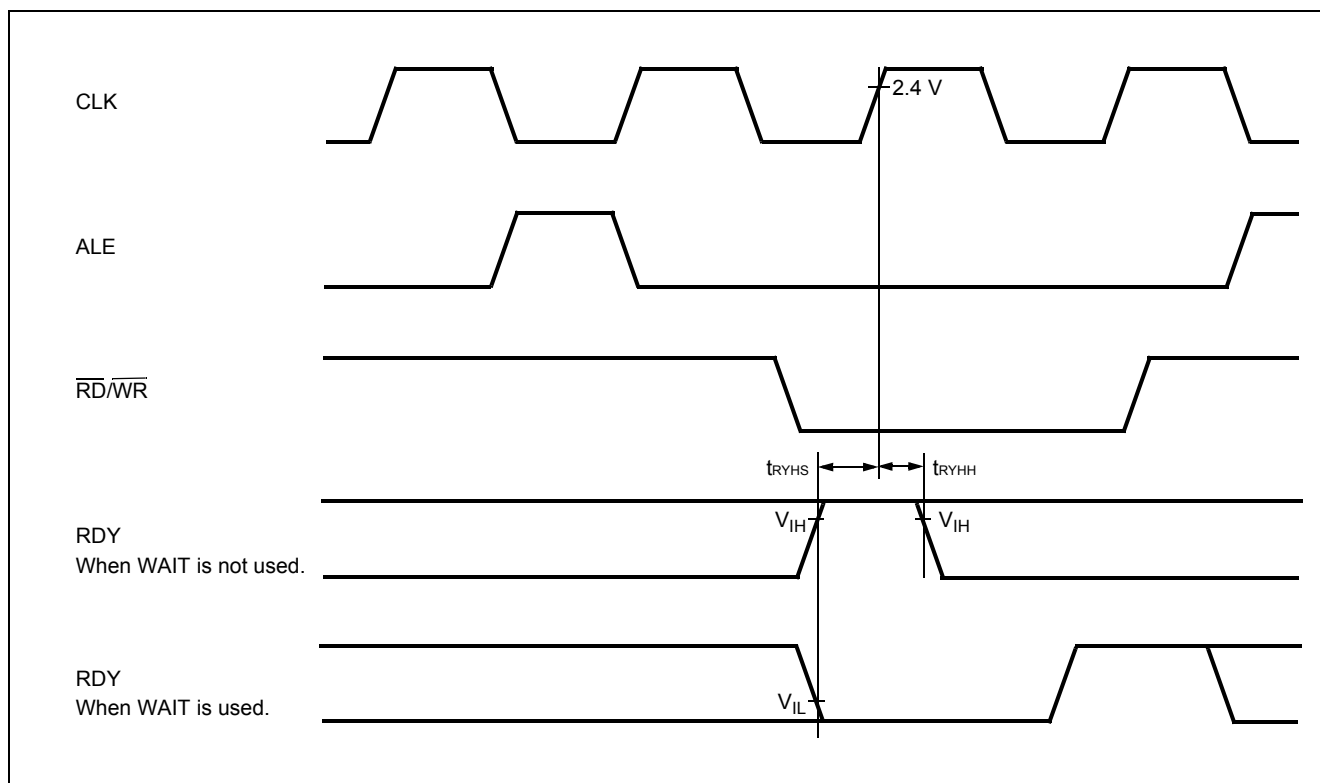


11.4.7 Ready Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Test Condition	Rated Value		Unit	Remarks
				Min	Max		
RDY setup time	t_{RYHS}	RDY	—	45	—	ns	$f_{CP} = 16\text{ MHz}$
				32	—	ns	$f_{CP} = 24\text{ MHz}$
RDY hold time	t_{RYHH}	RDY		0	—	ns	

Note: : If the RDY setup time is insufficient, use the auto-ready function.

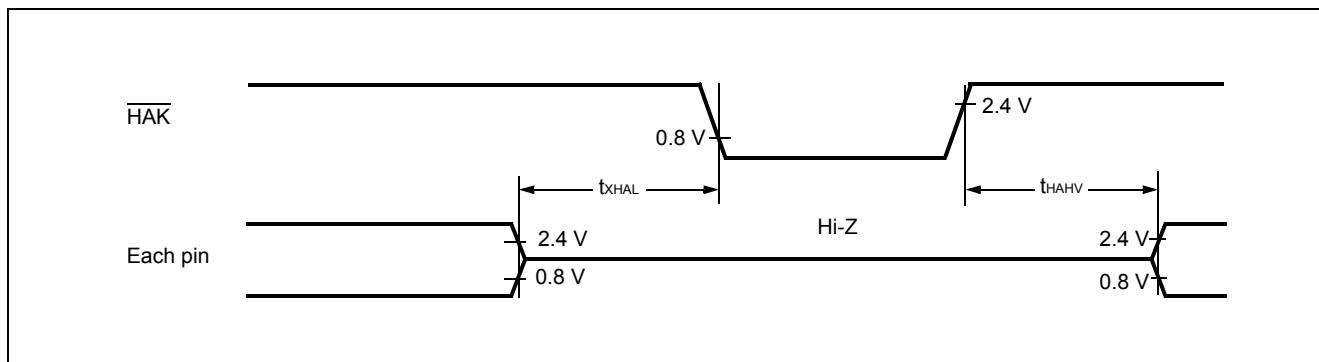


11.4.8 Hold Timing

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Pin floating $\rightarrow \overline{\text{HAK}} \downarrow$ time	t_{XHAL}	$\overline{\text{HAK}}$	—	30	t_{CP}	ns
$\overline{\text{HAK}} \uparrow$ time $\rightarrow$ Pin valid time	t_{HAHV}	$\overline{\text{HAK}}$	—	t_{CP}	$2 t_{CP}$	ns

Note: : There is more than 1 cycle from when HRQ reads in until the $\overline{\text{HAK}}$ is changed.



11.4.9 LIN-UART0/1/2/3

■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0

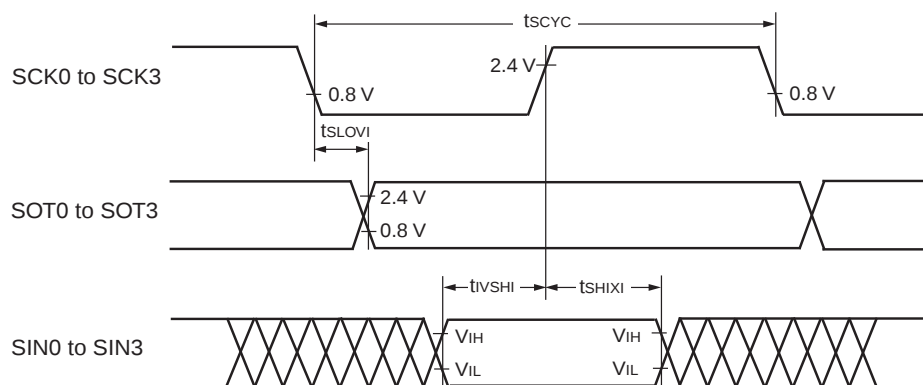
($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock "L" pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$3 t_{CP} - t_R$	—	ns
Serial clock "H" pulse width	t_{SLSH}	SCK0 to SCK3		$t_{CP} + 10$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	$2 t_{CP} + 60$	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXE}	SCK0, SCK1, SIN0 to SIN3		$t_{CP} + 30$	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

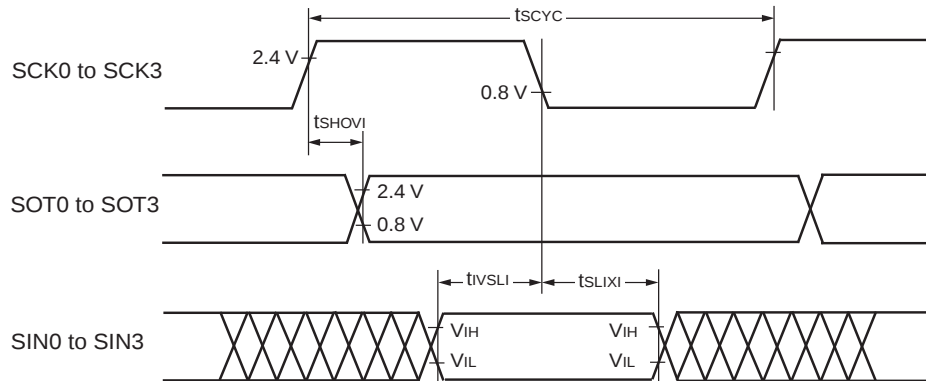
Note:

- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “(1) Clock Timing”.

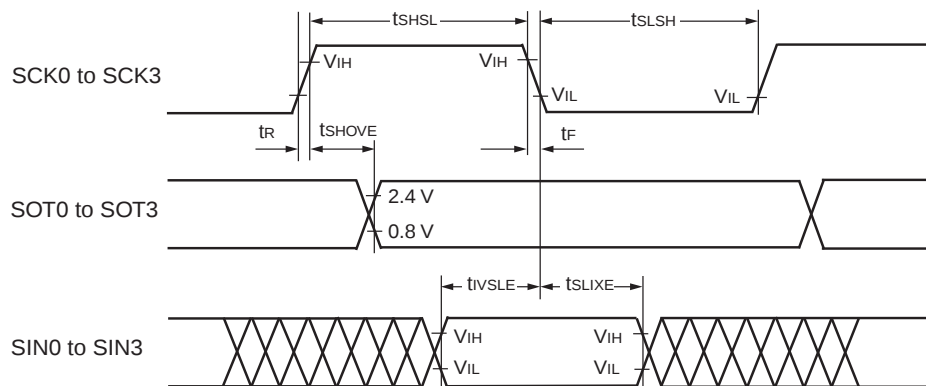
• Internal Shift Clock Mode



• Internal Shift Clock Mode



• External Shift Clock Mode



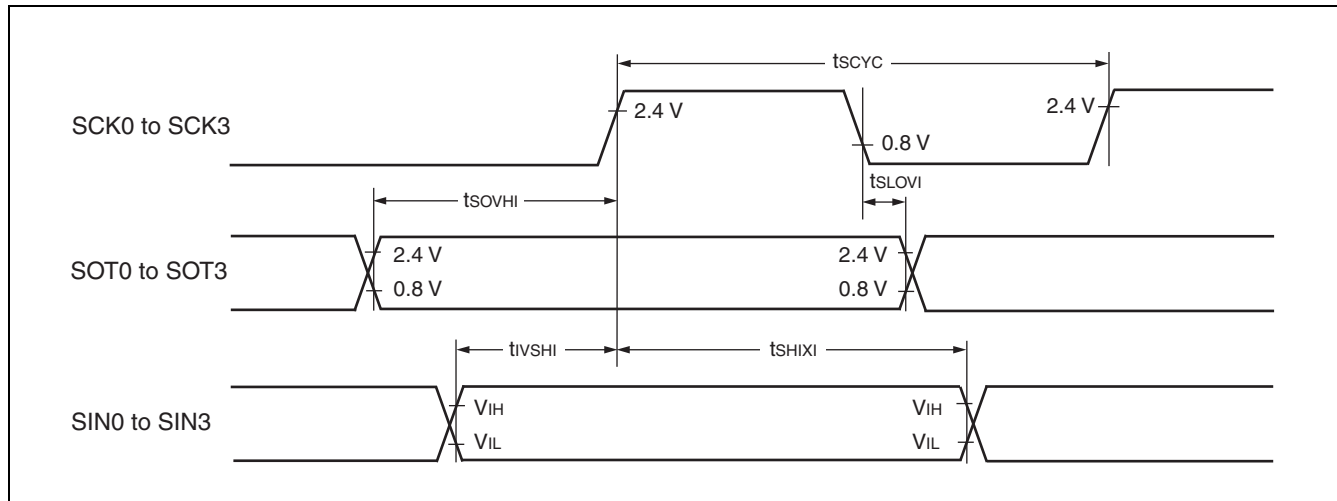
■ Bit setting: ESCR:SCES = 1, ECCR:SCDE = 1

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT $\rightarrow$ SCK $\uparrow$ delay time	t_{SOVHI}	SCK0 to SCK3, SOT0 to SOT3		$3 t_{CP} - 70$	—	ns

Note:

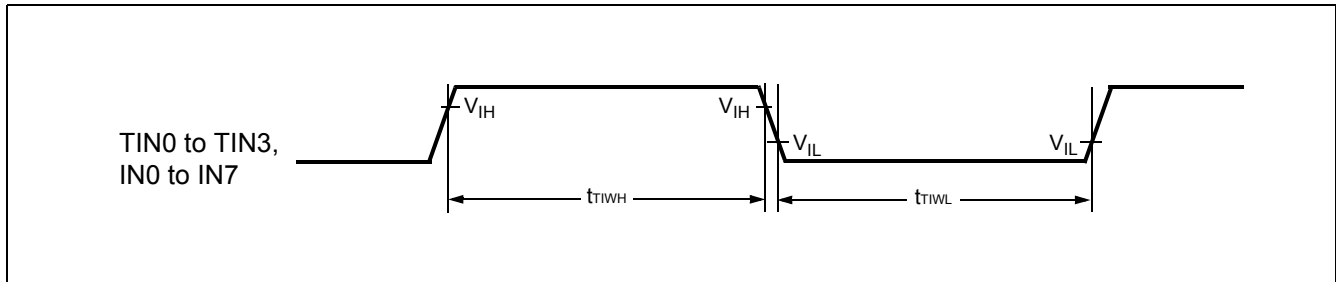
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.



11.4.11 Timer Related Resource Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

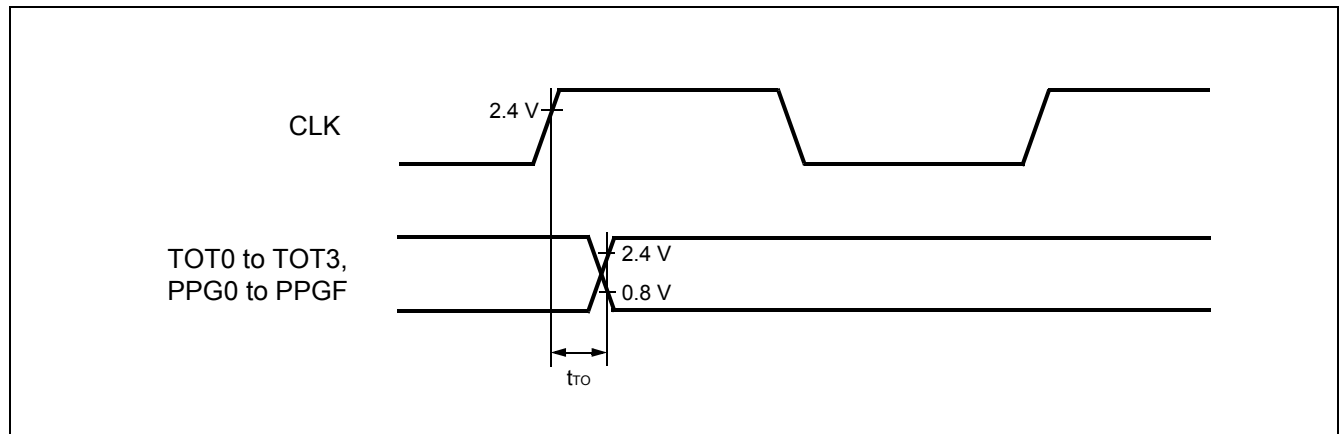
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TIWH}	TIN0 to TIN3, IN0 to IN7	—	$4 t_{CP}$	—	ns
	t_{TIWL}					



11.4.12 Timer Related Resource Output Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
CLK $\uparrow \rightarrow T_{OUT}$ change time	t_{TO}	TOT0 to TOT3, PPG0 to PPGF	—	30	—	ns



11.5 A/D Converter

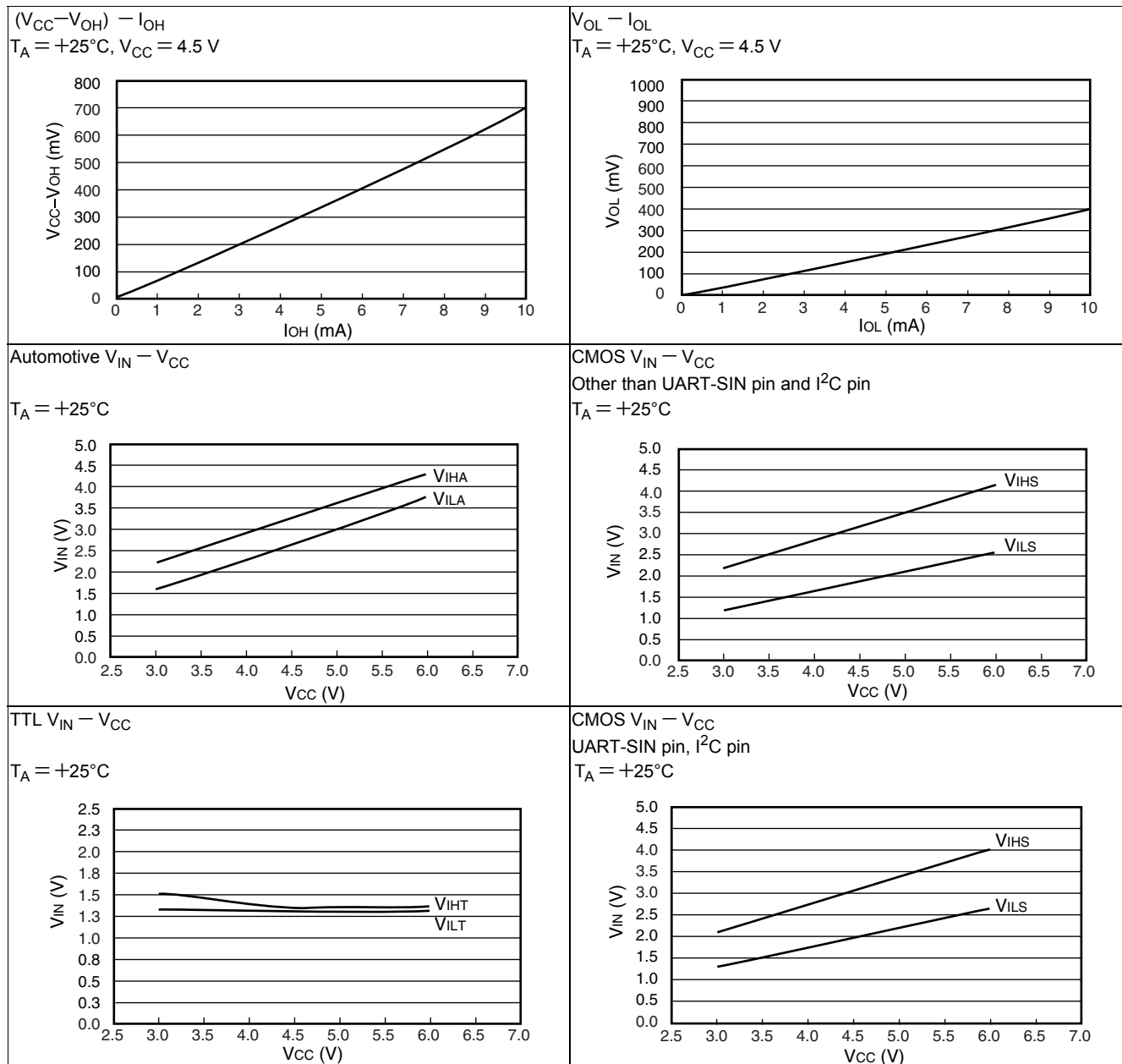
($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $3.0\text{ V} \leq \text{AVRH} - \text{AVRL}$, $V_{CC} = \text{AV}_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = \text{AV}_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	—	—	± 3.0	LSB	
Nonlinearity error	—	—	—	—	± 2.5	LSB	
Differential nonlinearity error	—	—	—	—	± 1.9	LSB	
Zero reading voltage	V_{OT}	AN0 to AN23	$\text{AVRL} - 1.5 \times \text{LSB}$	$\text{AVRL} + 0.5 \times \text{LSB}$	$\text{AVRL} + 2.5 \times \text{LSB}$	V	
Full scale reading voltage	V_{FST}	AN0 to AN23	$\text{AVRH} - 3.5 \times \text{LSB}$	$\text{AVRH} - 1.5 \times \text{LSB}$	$\text{AVRH} + 0.5 \times \text{LSB}$	V	
Compare time	—	—	1.0	—	16500	μs	$4.5\text{ V} \leq \text{AV}_{CC} \leq 5.5\text{ V}$
			2.0				$4.0\text{ V} \leq \text{AV}_{CC} < 4.5\text{ V}$
Sampling time	—	—	0.5	—	∞	μs	$4.5\text{ V} \leq \text{AV}_{CC} \leq 5.5\text{ V}$
			1.2				$4.0\text{ V} \leq \text{AV}_{CC} < 4.5\text{ V}$
Analog port input current	I_{AIN}	AN0 to AN23	-0.3	—	+0.3	μA	
Analog input voltage range	V_{AIN}	AN0 to AN23	AVRL	—	AVRH	V	
Reference voltage range	—	AVRH	$\text{AVRL} + 2.7$	—	AV_{CC}	V	
	—	AVRL	0	—	$\text{AVRH} - 2.7$	V	
Power supply current	I_A	AV_{CC}	—	3.5	7.5	mA	
	I_{AH}	AV_{CC}	—	—	5	μA	*
Reference voltage current	I_R	AVRH	—	600	900	μA	
	I_{RH}	AVRH	—	—	5	μA	*
Offset between input channels	—	AN0 to AN23	—	—	4	LSB	

*: If the A/D convertor is not operating, a current when CPU is stopped is applicable ($V_{CC} = \text{AV}_{CC} = \text{AVRH} = 5.0\text{ V}$).

Note: : The accuracy gets worse as $|\text{AVRH} - \text{AVRL}|$ becomes smaller.

■ I/O characteristics



13. Ordering Information

Part number	Package	Remarks
MB90F342EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F342ESPF		
MB90F342CEPF		
MB90F342CESPF		
MB90F342EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F342ESPMC		
MB90F342CEPMC		
MB90F342CESPMC		
MB90F345EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F345ESPF		
MB90F345CEPF		
MB90F345CESPF		
MB90F345EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F345ESPMC		
MB90F345CEPMC		
MB90F345CESPMC		
MB90F346EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F346ESPF		
MB90F346CEPF		
MB90F346CESPF		
MB90F346EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F346ESPMC		
MB90F346CEPMC		
MB90F346CESPMC		

(Continued)