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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

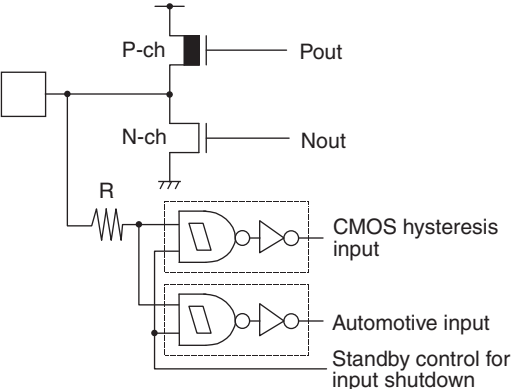
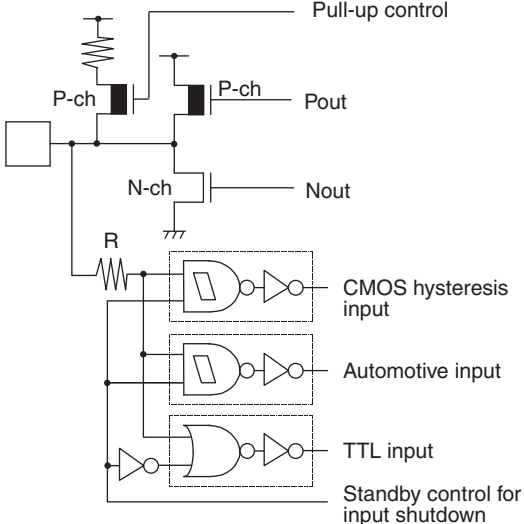
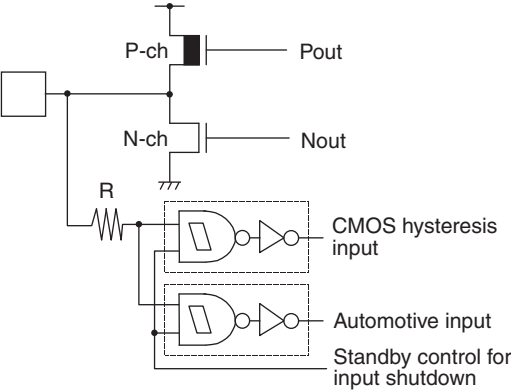
Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-309e1

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V _{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 μF .
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

(Continued)

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
33	31	AVRH	L	Reference voltage input pin for the A/D Converter. This power supply must be turned on or off while a voltage higher than or equal to AVRH is applied to AV _{CC} .
34	32	AVRL	K	Lower reference voltage input pin for the A/D Converter
35	33	AV _{SS}	K	Analog GND pin for the A/D Converter
36 to 43	34 to 41	P60 to P67	I	General purpose I/O pins.
		AN0 to AN7		Analog input pins for the A/D converter
		PPG0, 2, 4, 6, 8, A, C, E		Output pins for PPGs
44	42	V _{SS}	—	GND pin
45 to 50	43 to 48	P70 to P75	I	General purpose I/O pins.
		AN16 to AN21		Analog input pins for the A/D converter (devices with a C suffix in the part number)
		INT0 to INT5		External interrupt request input pins
51	49	MD2	D	Input pin for specifying the operating mode.
52, 53	50, 51	MD1, MD0	C	Input pins for specifying the operating mode.
54	52	RST	E	Reset input pin
55, 56	53, 54	P76, P77	I	General purpose I/O pins.
		AN22, AN23		Analog input pins for the A/D converter (devices with a C suffix in the part number)
		INT6, INT7		External interrupt request input pins
57	55	P80	F	General purpose I/O pin.
		TIN0		Event input pin for the reload timer
		ADTG		Trigger input pin for the A/D converter
		INT12R		External interrupt request input pin
58	56	P81	F	General purpose I/O pin.
		TOT0		Output pin for the reload timer
		CKOT		Output pin for the clock monitor
		INT13R		External interrupt request input pin
59	57	P82	M	General purpose I/O pin.
		SIN0		Serial data input pin for UART0
		TIN2		Event input pin for the reload timer
		INT14R		External interrupt request input pin
60	58	P83	F	General purpose I/O pin.
		SOT0		Serial data output pin for UART0
		TOT2		Output pin for the reload timer

(Continued)

Type	Circuit	Remarks
F		<ul style="list-style-type: none"> ■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)
G		<ul style="list-style-type: none"> ■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ TTL input (with function to disconnect input during standby) ■ Programmable pull-up resistor: 50 kΩ approx.
H		<ul style="list-style-type: none"> ■ CMOS level output ($I_{OL} = 3 \text{ mA}$, $I_{OH} = -3 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)

(Continued)

5. Handling Devices

1. Preventing latch-up

CMOS IC may suffer latch-up under the following conditions:

- A voltage higher than V_{CC} or lower than V_{SS} is applied to an input or output pin.
- A voltage higher than the rated voltage is applied between V_{CC} and V_{SS} pins.
- The AV_{CC} power supply is applied before the V_{CC} voltage.

Latch-up may increase the power supply current drastically, causing thermal damage to the device.

For the same reason, also be careful not to let the analog power-supply voltage (AV_{CC} , AV_{RH}) exceed the digital power-supply voltage.

2. Handling unused pins

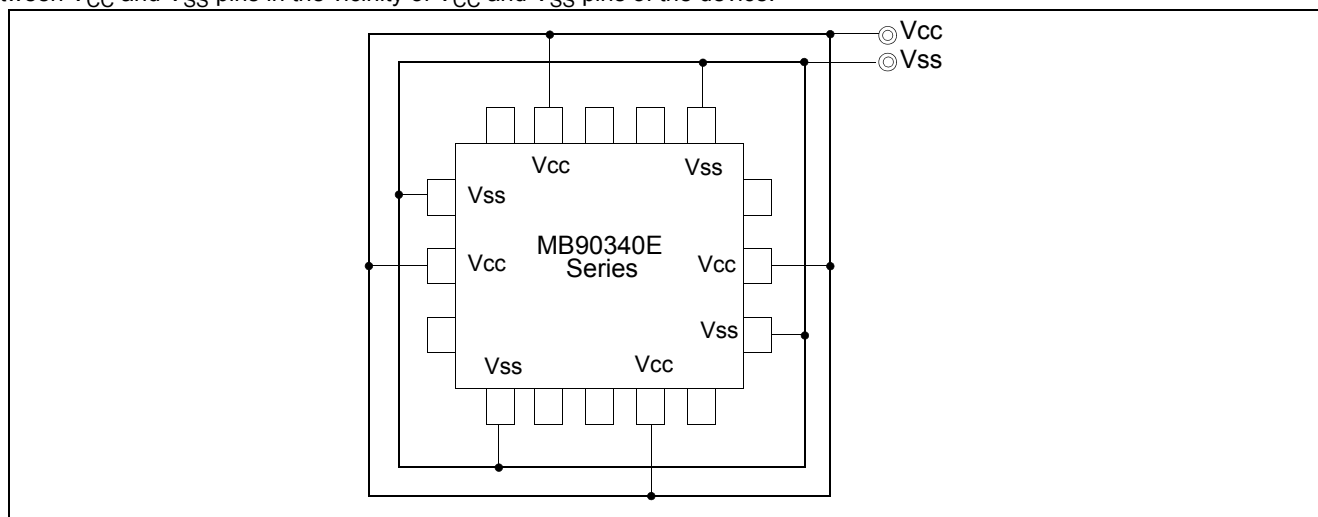
Leaving unused input terminals open may lead to permanent damage due to malfunction and latch-up; pull up or pull down the terminals through the resistors of 2 k Ω or more.

3. Power supply pins (V_{CC}/V_{SS})

- If there are multiple V_{CC} and V_{SS} pins, from the point of view of device design, pins to be of the same potential are connected inside of the device to prevent malfunction such as latch-up.

To reduce unnecessary radiation, prevent malfunctioning of the strobe signal due to the rise of ground level, and observe the standard for total output current, be sure to connect the V_{CC} and V_{SS} pins to the power supply and ground externally. Connect V_{CC} and V_{SS} pins to the device from the current supply source at a possibly low impedance.

- As a measure against power supply noise, it is recommended to connect a capacitor of about 0.1 μ F as a bypass capacitor between V_{CC} and V_{SS} pins in the vicinity of V_{CC} and V_{SS} pins of the device.

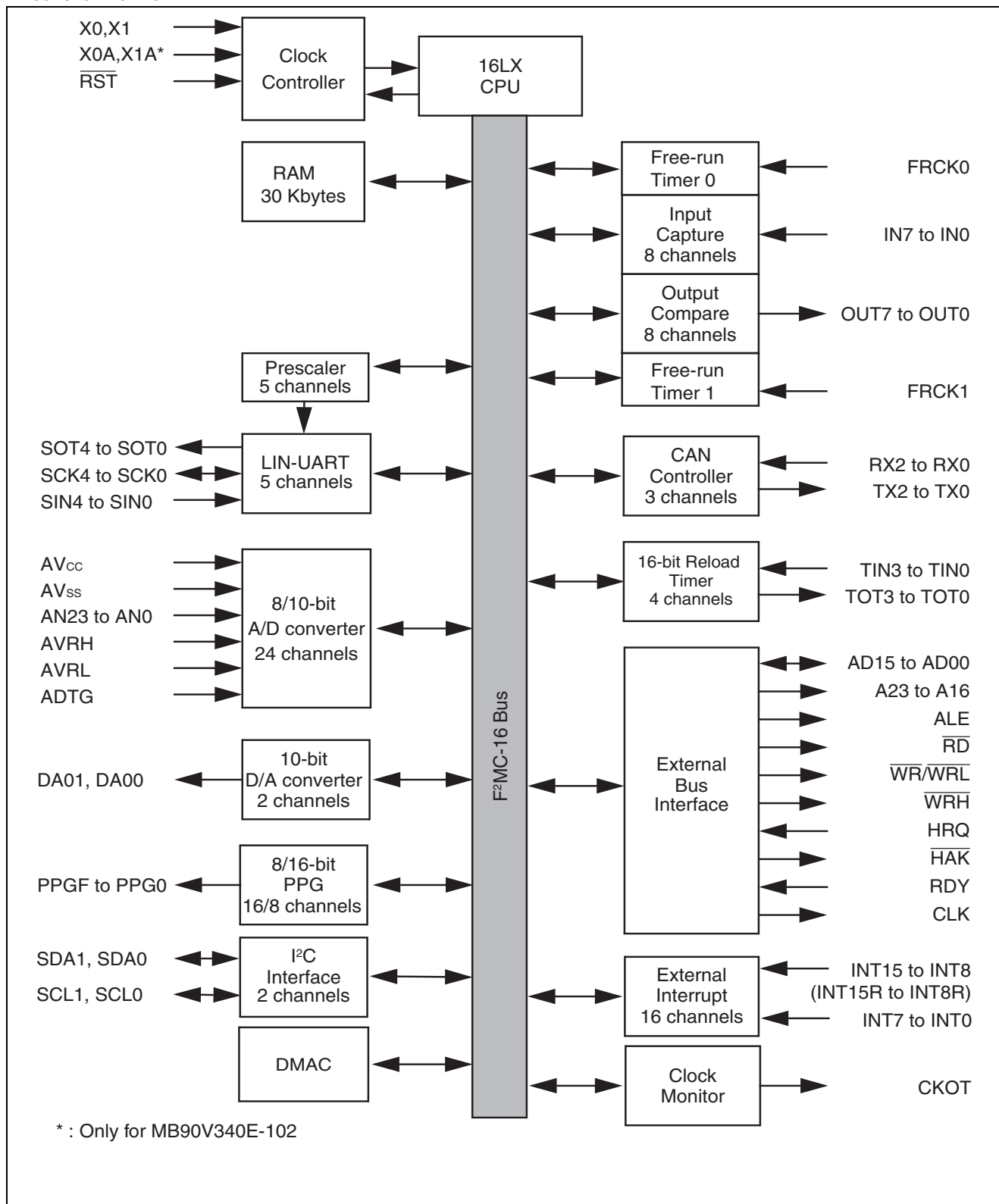


4. Mode Pins (MD0 to MD2)

Connect the mode pins directly to V_{CC} or V_{SS} pins. To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pins to V_{CC} or V_{SS} pins and to provide a low-impedance connection.

6. Block Diagrams

■ MB90V340E-101/102



Address	Register	Abbreviation	Access	Resource name	Initial value
000040 _H	PPG 8 Operation Mode Control Register	PPGC8	W,R/W	16-bit PPG 8/9	0X000XX1 _B
000041 _H	PPG 9 Operation Mode Control Register	PPGC9	W,R/W		0X000001 _B
000042 _H	PPG 8/PPG 9 Count Clock Control Register	PPG89	R/W		000000X0 _B
000043 _H	Reserved				
000044 _H	PPG A Operation Mode Control Register	PPGCA	W,R/W	16-bit PPG A/B	0X000XX1 _B
000045 _H	PPG B Operation Mode Control Register	PPGCB	W,R/W		0X000001 _B
000046 _H	PPG A/PPG B Count Clock Select Register	PPGAB	R/W		000000X0 _B
000047 _H	Reserved				
000048 _H	PPG C Operation Mode Control Register	PPGCC	W,R/W	16-bit PPG C/D	0X000XX1 _B
000049 _H	PPG D Operation Mode Control Register	PPGCD	W,R/W		0X000001 _B
00004A _H	PPG C/PPG D Count Clock Select Register	PPGCD	R/W		000000X0 _B
00004B _H	Reserved				
00004C _H	PPG E Operation Mode Control Register	PPGCE	W,R/W	16-bit PPG E/F	0X000XX1 _B
00004D _H	PPG F Operation Mode Control Register	PPGCF	W,R/W		0X000001 _B
00004E _H	PPG E/PPG F Count Clock Select Register	PPGEF	R/W		000000X0 _B
00004F _H	Reserved				
000050 _H	Input Capture Control Status 0/1	ICS01	R/W	Input Capture 0/1	00000000 _B
000051 _H	Input Capture Edge 0/1	ICE01	R/W, R		XXX0X0XX _B
000052 _H	Input Capture Control Status 2/3	ICS23	R/W	Input Capture 2/3	00000000 _B
000053 _H	Input Capture Edge 2/3	ICE23	R		XXXXXXXX _B
000054 _H	Input Capture Control Status 4/5	ICS45	R/W	Input Capture 4/5	00000000 _B
000055 _H	Input Capture Edge 4/5	ICE45	R		XXXXXXXX _B
000056 _H	Input Capture Control Status 6/7	ICS67	R/W	Input Capture 6/7	00000000 _B
000057 _H	Input Capture Edge 6/7	ICE67	R/W, R		XXX000XX _B
000058 _H	Output Compare Control Status 0	OCS0	R/W	Output Compare 0/1	0000XX00 _B
000059 _H	Output Compare Control Status 1	OCS1	R/W		0XX00000 _B
00005A _H	Output Compare Control Status 2	OCS2	R/W	Output Compare 2/3	0000XX00 _B
00005B _H	Output Compare Control Status 3	OCS3	R/W		0XX00000 _B
00005C _H	Output Compare Control Status 4	OCS4	R/W	Output Compare 4/5	0000XX00 _B
00005D _H	Output Compare Control Status 5	OCS5	R/W		0XX00000 _B
00005E _H	Output Compare Control Status 6	OCS6	R/W	Output Compare 6/7	0000XX00 _B
00005F _H	Output Compare Control Status 7	OCS7	R/W		0XX00000 _B

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
0000C4 _H , 0000C5 _H	Reserved				
0000C6 _H	External Interrupt Enable 0	ENIR0	R/W	External Interrupt 0	00000000 _B
0000C7 _H	External Interrupt Source 0	EIRR0	R/W		XXXXXXXX _B
0000C8 _H	External Interrupt Level Setting 0	ELVR0	R/W		00000000 _B
0000C9 _H	External Interrupt Level Setting 0	ELVR0	R/W		00000000 _B
0000CA _H	External Interrupt Enable 1	ENIR1	R/W	External Interrupt 1	00000000 _B
0000CB _H	External Interrupt Source 1	EIRR1	R/W		XXXXXXXX _B
0000CC _H	External Interrupt Level Setting 1	ELVR1	R/W		00000000 _B
0000CD _H	External Interrupt Level Setting 1	ELVR1	R/W		00000000 _B
0000CE _H	External Interrupt Source Select	EISSR	R/W		00000000 _B
0000CF _H	PLL/Sub clock Control Register	PSCCR	W	PLL	XXXX0000 _B
0000D0 _H	DMA Buffer Address Pointer L Register	BAPL	R/W	DMA	XXXXXXXX _B
0000D1 _H	DMA Buffer Address Pointer M Register	BAPM	R/W		XXXXXXXX _B
0000D2 _H	DMA Buffer Address Pointer H Register	BAPH	R/W		XXXXXXXX _B
0000D3 _H	DMA Control Register	DMACS	R/W		XXXXXXXX _B
0000D4 _H	I/O Register Address Pointer L Register	IOAL	R/W		XXXXXXXX _B
0000D5 _H	I/O Register Address Pointer H Register	IOAH	R/W		XXXXXXXX _B
0000D6 _H	Data Counter L Register	DCTL	R/W		XXXXXXXX _B
0000D7 _H	Data Counter H Register	DCTH	R/W		XXXXXXXX _B
0000D8 _H	Serial Mode Register 2	SMR2	W,R/W	UART2	00000000 _B
0000D9 _H	Serial Control Register 2	SCR2	W,R/W		00000000 _B
0000DA _H	Reception/Transmission Data Register 2	RDR2/TDR2	R/W		00000000 _B
0000DB _H	Serial Status Register 2	SSR2	R,R/W		00001000 _B
0000DC _H	Extended Communication Control Register 2	ECCR2	R,W, R/W		000000XX _B
0000DD _H	Extended Status Control Register 2	ESCR2	R/W		00000100 _B
0000DE _H	Baud Rate Generator Register 20	BGR20	R/W		00000000 _B
0000DF _H	Baud Rate Generator Register 21	BGR21	R/W		00000000 _B
0000E0 _H to 0000EF _H	Reserved for CAN Controller 2. Refer to “CAN Controllers”				
0000F0 _H to 0000FF _H	External				

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
007924 _H	Input Capture 2	IPCP2	R	Input Capture 2/3	XXXXXXXX _B
007925 _H	Input Capture 2	IPCP2	R		XXXXXXXX _B
007926 _H	Input Capture 3	IPCP3	R		XXXXXXXX _B
007927 _H	Input Capture 3	IPCP3	R		XXXXXXXX _B
007928 _H	Input Capture 4	IPCP4	R	Input Capture 4/5	XXXXXXXX _B
007929 _H	Input Capture 4	IPCP4	R		XXXXXXXX _B
00792A _H	Input Capture 5	IPCP5	R		XXXXXXXX _B
00792B _H	Input Capture 5	IPCP5	R		XXXXXXXX _B
00792C _H	Input Capture 6	IPCP6	R	Input Capture 6/7	XXXXXXXX _B
00792D _H	Input Capture 6	IPCP6	R		XXXXXXXX _B
00792E _H	Input Capture 7	IPCP7	R		XXXXXXXX _B
00792F _H	Input Capture 7	IPCP7	R		XXXXXXXX _B
007930 _H	Output Compare 0	OCCP0	R/W	Output Compare 0/1	XXXXXXXX _B
007931 _H	Output Compare 0	OCCP0	R/W		XXXXXXXX _B
007932 _H	Output Compare 1	OCCP1	R/W		XXXXXXXX _B
007933 _H	Output Compare 1	OCCP1	R/W		XXXXXXXX _B
007934 _H	Output Compare 2	OCCP2	R/W	Output Compare 2/3	XXXXXXXX _B
007935 _H	Output Compare 2	OCCP2	R/W		XXXXXXXX _B
007936 _H	Output Compare 3	OCCP3	R/W		XXXXXXXX _B
007937 _H	Output Compare 3	OCCP3	R/W		XXXXXXXX _B
007938 _H	Output Compare 4	OCCP4	R/W	Output Compare 4/5	XXXXXXXX _B
007939 _H	Output Compare 4	OCCP4	R/W		XXXXXXXX _B
00793A _H	Output Compare 5	OCCP5	R/W		XXXXXXXX _B
00793B _H	Output Compare 5	OCCP5	R/W		XXXXXXXX _B
00793C _H	Output Compare 6	OCCP6	R/W	Output Compare 6/7	XXXXXXXX _B
00793D _H	Output Compare 6	OCCP6	R/W		XXXXXXXX _B
00793E _H	Output Compare 7	OCCP7	R/W		XXXXXXXX _B
00793F _H	Output Compare 7	OCCP7	R/W		XXXXXXXX _B
007940 _H	Timer Data 0	TCDT0	R/W	Free-run Timer 0	00000000 _B
007941 _H	Timer Data 0	TCDT0	R/W		00000000 _B
007942 _H	Timer Control Status 0	TCCSL0	R/W		00000000 _B
007943 _H	Timer Control Status 0	TCCSH0	R/W		0XXXXXXXX _B
007944 _H	Timer Data 1	TCDT1	R/W	Free-run Timer 1	00000000 _B
007945 _H	Timer Data 1	TCDT1	R/W		00000000 _B
007946 _H	Timer Control Status 1	TCCSL1	R/W		00000000 _B
007947 _H	Timer Control Status 1	TCCSH1	R/W		0XXXXXXXX _B

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List of Control Registers (2)

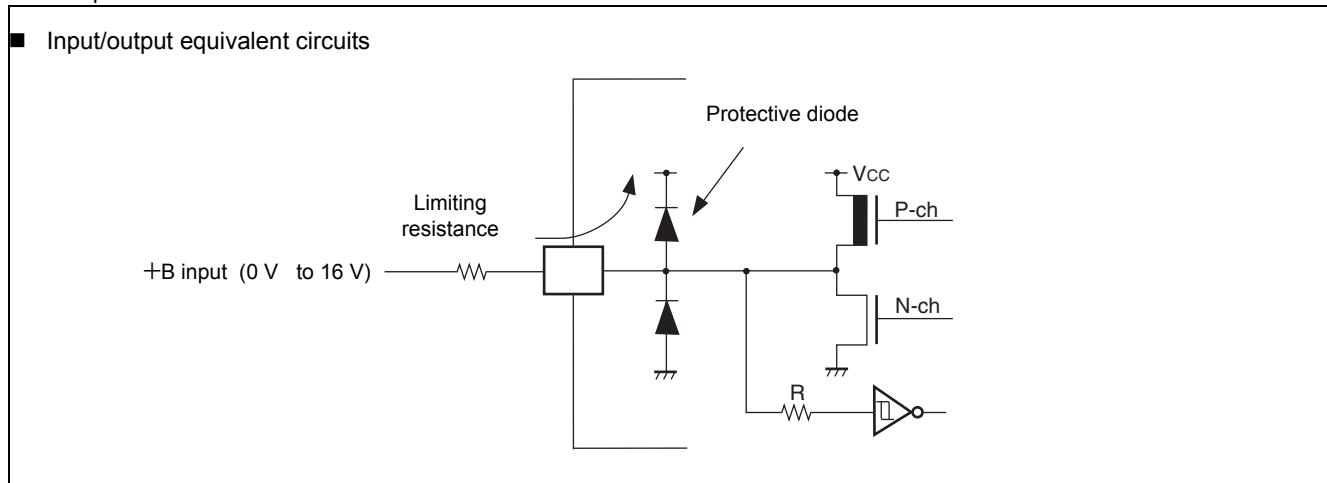
Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007B00 _H	007D00 _H	Control Status Register	CSR	R/W, W R/W, R	0XXXX0X1 _B 00XXX000 _B
007B01 _H	007D01 _H				
007B02 _H	007D02 _H	Last Event Indicator Register	LEIR	R/W	000X0000 _B XXXXXXXX _B
007B03 _H	007D03 _H				
007B04 _H	007D04 _H	Receive And Transmit Error Counter	RTEC	R	00000000 _B 00000000 _B
007B05 _H	007D05 _H				
007B06 _H	007D06 _H	Bit Timing Register	BTR	R/W	11111111 _B X1111111 _B
007B07 _H	007D07 _H				
007B08 _H	007D08 _H	IDE Register	IDER	R/W	XXXXXXXX _B XXXXXXXX _B
007B09 _H	007D09 _H				
007B0A _H	007D0A _H	Transmit RTR Register	TRTRR	R/W	00000000 _B 00000000 _B
007B0B _H	007D0B _H				
007B0C _H	007D0C _H	Remote Frame Receive Waiting Register	RFWTR	R/W	XXXXXXXX _B XXXXXXXX _B
007B0D _H	007D0D _H				
007B0E _H	007D0E _H	Transmit Interrupt Enable Register	TIER	R/W	00000000 _B 00000000 _B
007B0F _H	007D0F _H				
007B10 _H	007D10 _H	Acceptance Mask Select Register	AMSR	R/W	XXXXXXXX _B XXXXXXXX _B
007B11 _H	007D11 _H				
007B12 _H	007D12 _H				XXXXXXXX _B XXXXXXXX _B
007B13 _H	007D13 _H				
007B14 _H	007D14 _H	Acceptance Mask Register 0	AMR0	R/W	XXXXXXXX _B XXXXXXXX _B
007B15 _H	007D15 _H				
007B16 _H	007D16 _H				XXXXXXXX _B XXXXXXXX _B
007B17 _H	007D17 _H				
007B18 _H	007D18 _H	Acceptance Mask Register 1	AMR1	R/W	XXXXXXXX _B XXXXXXXX _B
007B19 _H	007D19 _H				
007B1A _H	007D1A _H				XXXXXXXX _B XXXXXXXX _B
007B1B _H	007D1B _H				

List of Message Buffers (ID Registers) (1)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007A00 _H to 007A1F _H	007C00 _H to 007C1F _H	General- Purpose RAM	—	R/W	XXXXXXXX _B to XXXXXXXX _B
007A20 _H	007C20 _H	ID Register 0	IDR0	R/W	XXXXXXXX _B XXXXXXXX _B
007A21 _H	007C21 _H				XXXXXXXX _B XXXXXXXX _B
007A22 _H	007C22 _H				XXXXXXXX _B XXXXXXXX _B
007A23 _H	007C23 _H				XXXXXXXX _B XXXXXXXX _B
007A24 _H	007C24 _H	ID Register 1	IDR1	R/W	XXXXXXXX _B XXXXXXXX _B
007A25 _H	007C25 _H				XXXXXXXX _B XXXXXXXX _B
007A26 _H	007C26 _H				XXXXXXXX _B XXXXXXXX _B
007A27 _H	007C27 _H				XXXXXXXX _B XXXXXXXX _B
007A28 _H	007C28 _H	ID Register 2	IDR2	R/W	XXXXXXXX _B XXXXXXXX _B
007A29 _H	007C29 _H				XXXXXXXX _B XXXXXXXX _B
007A2A _H	007C2A _H				XXXXXXXX _B XXXXXXXX _B
007A2B _H	007C2B _H				XXXXXXXX _B XXXXXXXX _B
007A2C _H	007C2C _H	ID Register 3	IDR3	R/W	XXXXXXXX _B XXXXXXXX _B
007A2D _H	007C2D _H				XXXXXXXX _B XXXXXXXX _B
007A2E _H	007C2E _H				XXXXXXXX _B XXXXXXXX _B
007A2F _H	007C2F _H				XXXXXXXX _B XXXXXXXX _B
007A30 _H	007C30 _H	ID Register 4	IDR4	R/W	XXXXXXXX _B XXXXXXXX _B
007A31 _H	007C31 _H				XXXXXXXX _B XXXXXXXX _B
007A32 _H	007C32 _H				XXXXXXXX _B XXXXXXXX _B
007A33 _H	007C33 _H				XXXXXXXX _B XXXXXXXX _B
007A34 _H	007C34 _H	ID Register 5	IDR5	R/W	XXXXXXXX _B XXXXXXXX _B
007A35 _H	007C35 _H				XXXXXXXX _B XXXXXXXX _B
007A36 _H	007C36 _H				XXXXXXXX _B XXXXXXXX _B
007A37 _H	007C37 _H				XXXXXXXX _B XXXXXXXX _B
007A38 _H	007C38 _H	ID Register 6	IDR6	R/W	XXXXXXXX _B XXXXXXXX _B
007A39 _H	007C39 _H				XXXXXXXX _B XXXXXXXX _B
007A3A _H	007C3A _H				XXXXXXXX _B XXXXXXXX _B
007A3B _H	007C3B _H				XXXXXXXX _B XXXXXXXX _B
007A3C _H	007C3C _H	ID Register 7	IDR7	R/W	XXXXXXXX _B XXXXXXXX _B
007A3D _H	007C3D _H				XXXXXXXX _B XXXXXXXX _B
007A3E _H	007C3E _H				XXXXXXXX _B XXXXXXXX _B
007A3F _H	007C3F _H				XXXXXXXX _B XXXXXXXX _B

(Continued)

- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on reset.
- Care must be taken not to leave the +B input pin open.
- Sample recommended circuits:



*6: The maximum output current is defined as the peak value of the current of any one of the corresponding pins.

*7: The average output current is defined as the value of the average current flowing over 100 ms at any one of the corresponding pins.

*8: The average total output current is defined as the value of the average current flowing over 100 ms at all of the corresponding pins.

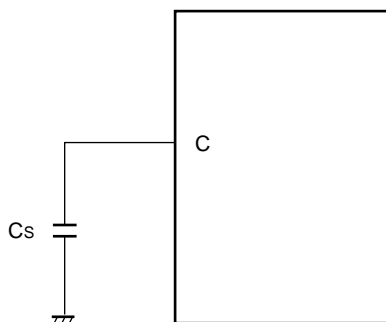
WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

11.2 Recommended Operating Conditions

($V_{SS} = AV_{SS} = 0\text{ V}$)

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Power supply voltage	V_{CC}, AV_{CC}	4.0	5.0	5.5	V	Under normal operation
		3.5	5.0	5.5	V	Under normal operation, when not using the A/D converter and not Flash programming.
		4.5	5.0	5.5	V	When External bus is used.
		3.0	—	5.5	V	Maintains RAM data in stop mode
Smoothing capacitor	C_S	0.1	—	1.0	μF	Use a ceramic capacitor or capacitor of better AC characteristics. Capacitor at the V_{CC} should be greater than this capacitor.
Operating temperature	T_A	-40	—	+105	$^{\circ}\text{C}$	

C Pin Connection Diagram



WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

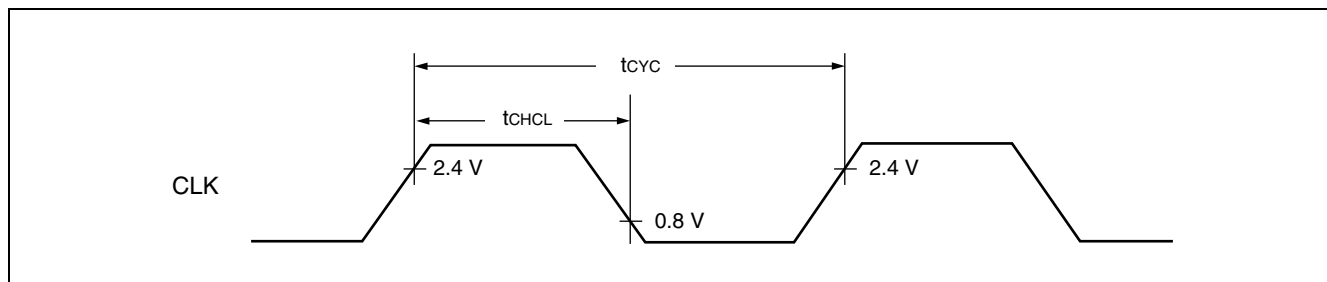
No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

11.3 DC Characteristics

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = AV_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Input H voltage (At $V_{CC} = 5\text{ V} \pm 10\%$)	V_{IHS}	—	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	Port inputs if CMOS hysteresis input levels are selected (except P12, P44, P45, P46, P47, P50, P82, P85)
	V_{IHA}	—	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	Port inputs if Automotive input levels are selected
	V_{IHT}	—	—	2.0	—	$V_{CC} + 0.3$	V	Port inputs if TTL input levels are selected
	V_{IHS}	—	—	$0.7 V_{CC}$	—	$V_{CC} + 0.3$	V	P12, P50, P82, P85 inputs if CMOS input levels are selected
	V_{IHI}	—	—	$0.7 V_{CC}$	—	$V_{CC} + 0.3$	V	P44, P45, P46, P47 inputs if CMOS hysteresis input levels are selected
	V_{IHR}	—	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	$\overline{\text{RST}}$ input pin (CMOS hysteresis)
	V_{IHM}	—	—	$V_{CC} - 0.3$	—	$V_{CC} + 0.3$	V	MD input pin
Input L voltage (At $V_{CC} = 5\text{ V} \pm 10\%$)	V_{ILS}	—	—	$V_{SS} - 0.3$	—	$0.2 V_{CC}$	V	Port inputs if CMOS hysteresis input levels are selected (except P12, P44, P45, P46, P47, P50, P82, P85)
	V_{ILA}	—	—	$V_{SS} - 0.3$	—	$0.5 V_{CC}$	V	Port inputs if Automotive input levels are selected
	V_{ILT}	—	—	$V_{SS} - 0.3$	—	0.8	V	Port inputs if TTL input levels are selected
	V_{ILS}	—	—	$V_{SS} - 0.3$	—	$0.3 V_{CC}$	V	P12, P50, P82, P85 inputs if CMOS input levels are selected
	V_{ILI}	—	—	$V_{SS} - 0.3$	—	$0.3 V_{CC}$	V	P44, P45, P46, P47 inputs if CMOS hysteresis input levels are selected
	V_{ILR}	—	—	$V_{SS} - 0.3$	—	$0.2 V_{CC}$	V	$\overline{\text{RST}}$ input pin (CMOS hysteresis)
	V_{ILM}	—	—	$V_{SS} - 0.3$	—	$V_{SS} + 0.3$	V	MD input pin
Output H voltage	V_{OH}	Normal outputs	$V_{CC} = 4.5\text{ V}$, $I_{OH} = -4.0\text{ mA}$	$V_{CC} - 0.5$	—	—	V	
Output H voltage	V_{OHI}	I ² C current outputs	$V_{CC} = 4.5\text{ V}$, $I_{OH} = -3.0\text{ mA}$	$V_{CC} - 0.5$	—	—	V	
Output L voltage	V_{OL}	Normal outputs	$V_{CC} = 4.5\text{ V}$, $I_{OL} = 4.0\text{ mA}$	—	—	0.4	V	
Output L voltage	V_{OLI}	I ² C current outputs	$V_{CC} = 4.5\text{ V}$, $I_{OL} = 3.0\text{ mA}$	—	—	0.4	V	

(Continued)

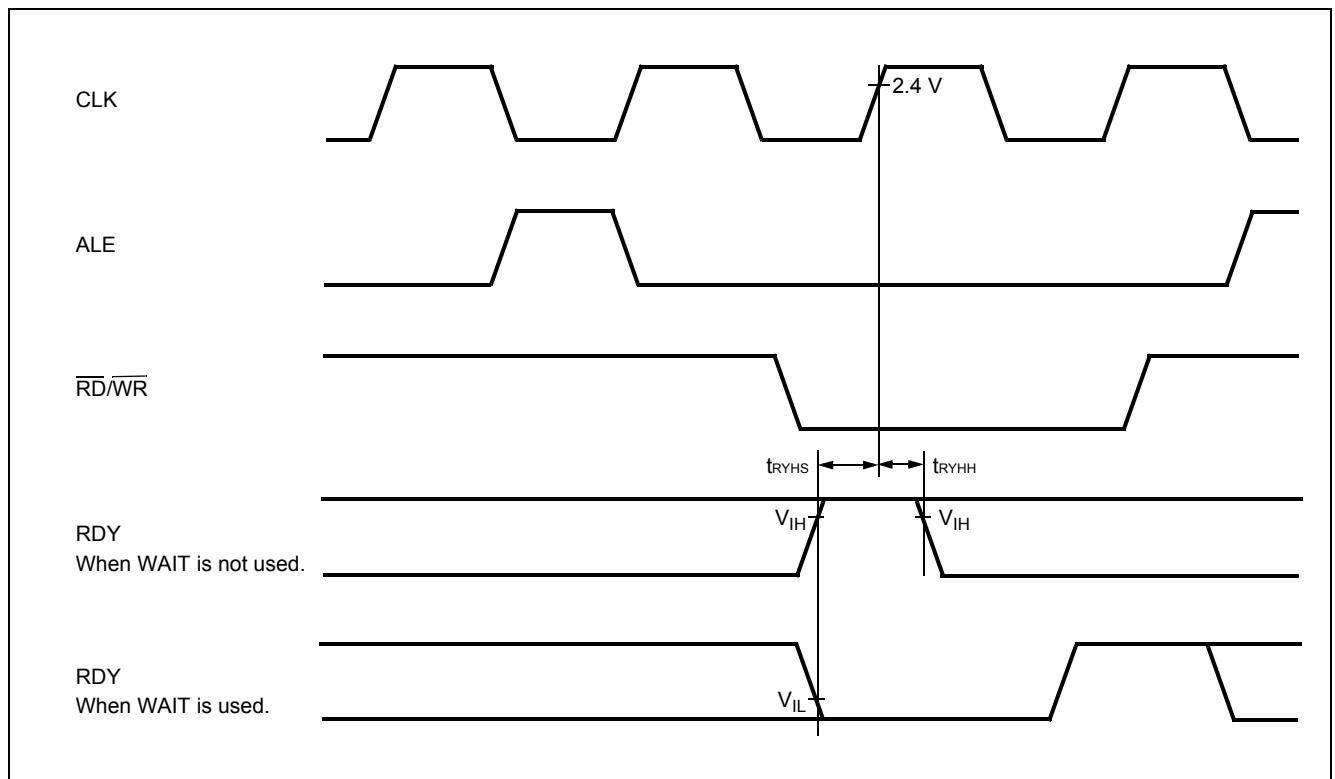


11.4.7 Ready Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Test Condition	Rated Value		Unit	Remarks
				Min	Max		
RDY setup time	t_{RYHS}	RDY	—	45	—	ns	$f_{CP} = 16\text{ MHz}$
				32	—	ns	$f_{CP} = 24\text{ MHz}$
RDY hold time	t_{RYHH}	RDY		0	—	ns	

Note: : If the RDY setup time is insufficient, use the auto-ready function.



11.4.9 LIN-UART0/1/2/3

■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0

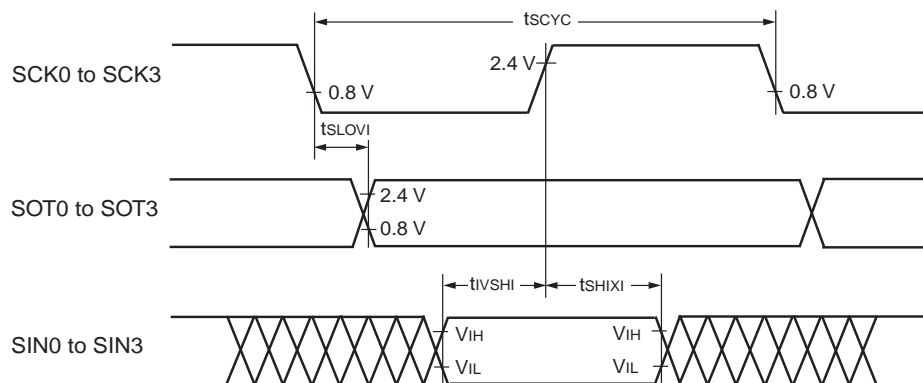
($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN \rightarrow SCK \uparrow	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock "L" pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$3 t_{CP} - t_R$	—	ns
Serial clock "H" pulse width	t_{SLSH}	SCK0 to SCK3		$t_{CP} + 10$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	$2 t_{CP} + 60$	ns
Valid SIN \rightarrow SCK \uparrow	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXE}	SCK0, SCK1, SIN0 to SIN3		$t_{CP} + 30$	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

Note:

- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “(1) Clock Timing”.

• Internal Shift Clock Mode



11.4.13 I²C Timing

(T_A = -40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

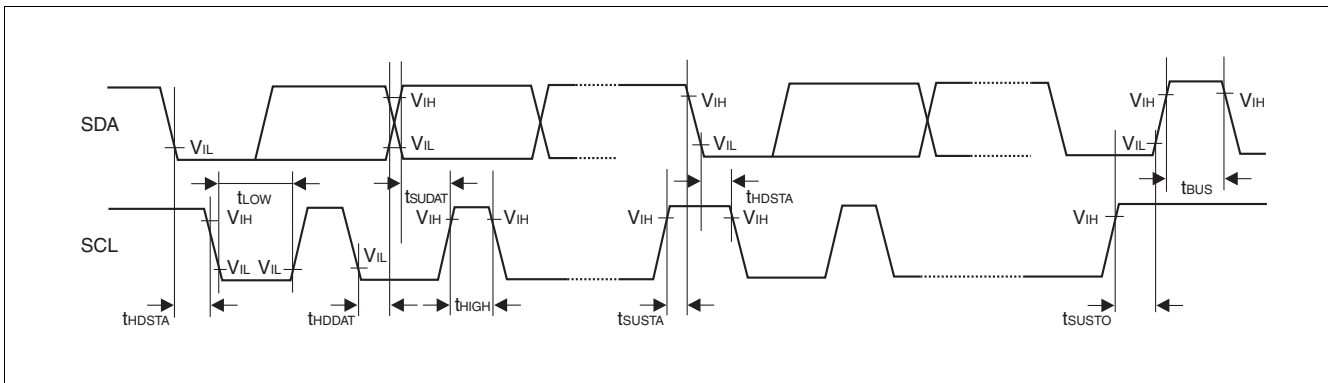
Parameter	Symbol	Condition	Standard-mode		Fast-mode* ¹		Unit
			Min	Max	Min	Max	
SCL clock frequency	f _{SCL}	R = 1.7 kΩ ₂ C = 50 pF* ²	0	100	0	400	kHz
Hold time (repeated) START condition SDA ↓ → SCL ↓	t _{HDSTA}		4.0	—	0.6	—	μs
"L" width of the SCL clock	t _{LOW}		4.7	—	1.3	—	μs
"H" width of the SCL clock	t _{HIGH}		4.0	—	0.6	—	μs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t _{SUSTA}		4.7	—	0.6	—	μs
Data hold time SCL ↓ → SDA ↓ ↑	t _{HDDAT}		0	3.45* ³	0	0.9* ⁴	μs
Data set-up time SDA ↓ ↑ → SCL ↑	t _{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t _{SUSTO}		4.0	—	0.6	—	μs
Bus free time between a STOP and START condition	t _{BUS}		4.7	—	1.3	—	μs

*1: For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.

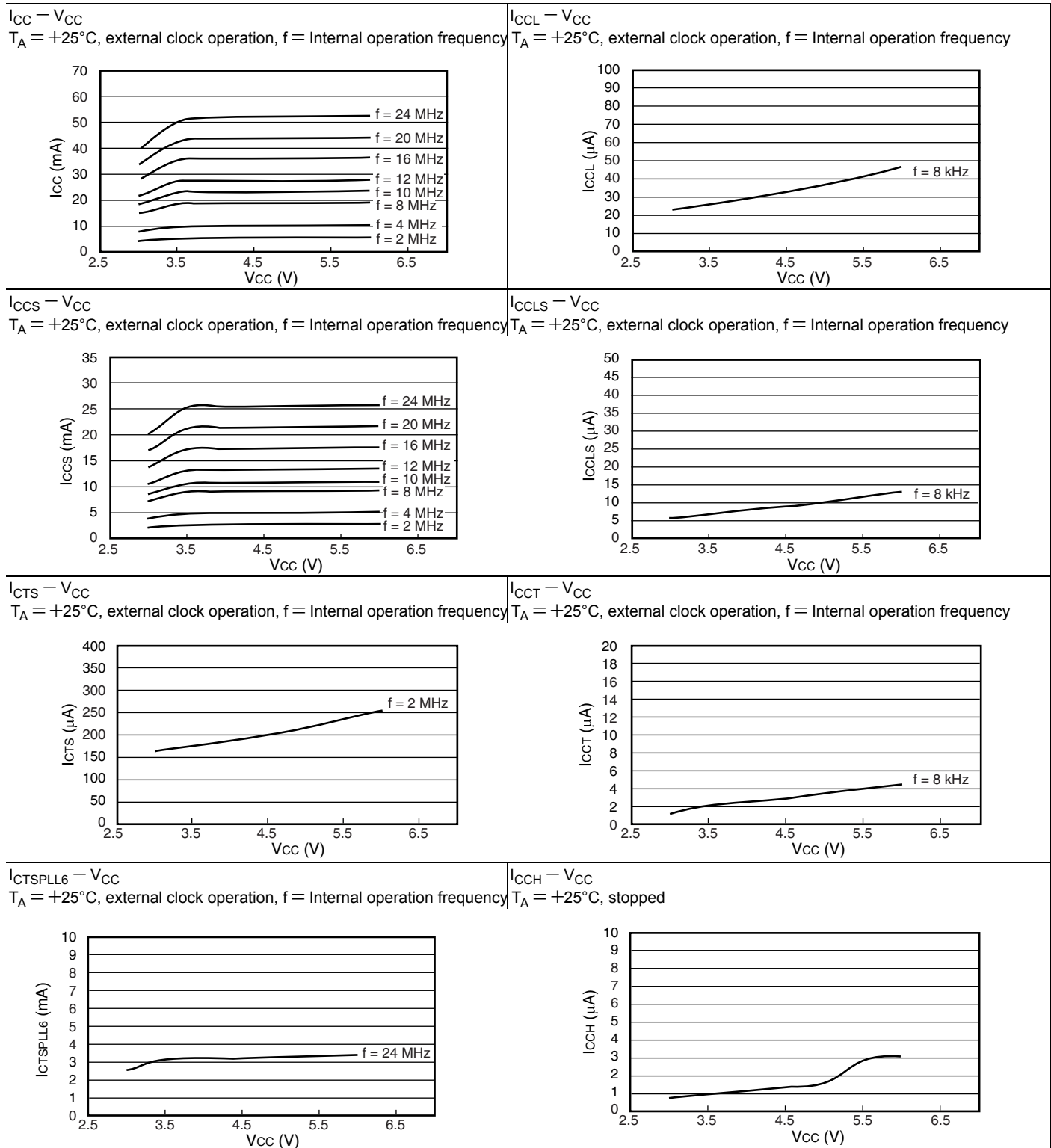
*3: The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4: A Fast-mode I²C-bus device can be used in a Standard-mode I²C-bus system, but the requirement t_{SUDAT} ≥ 250 ns must then be met.

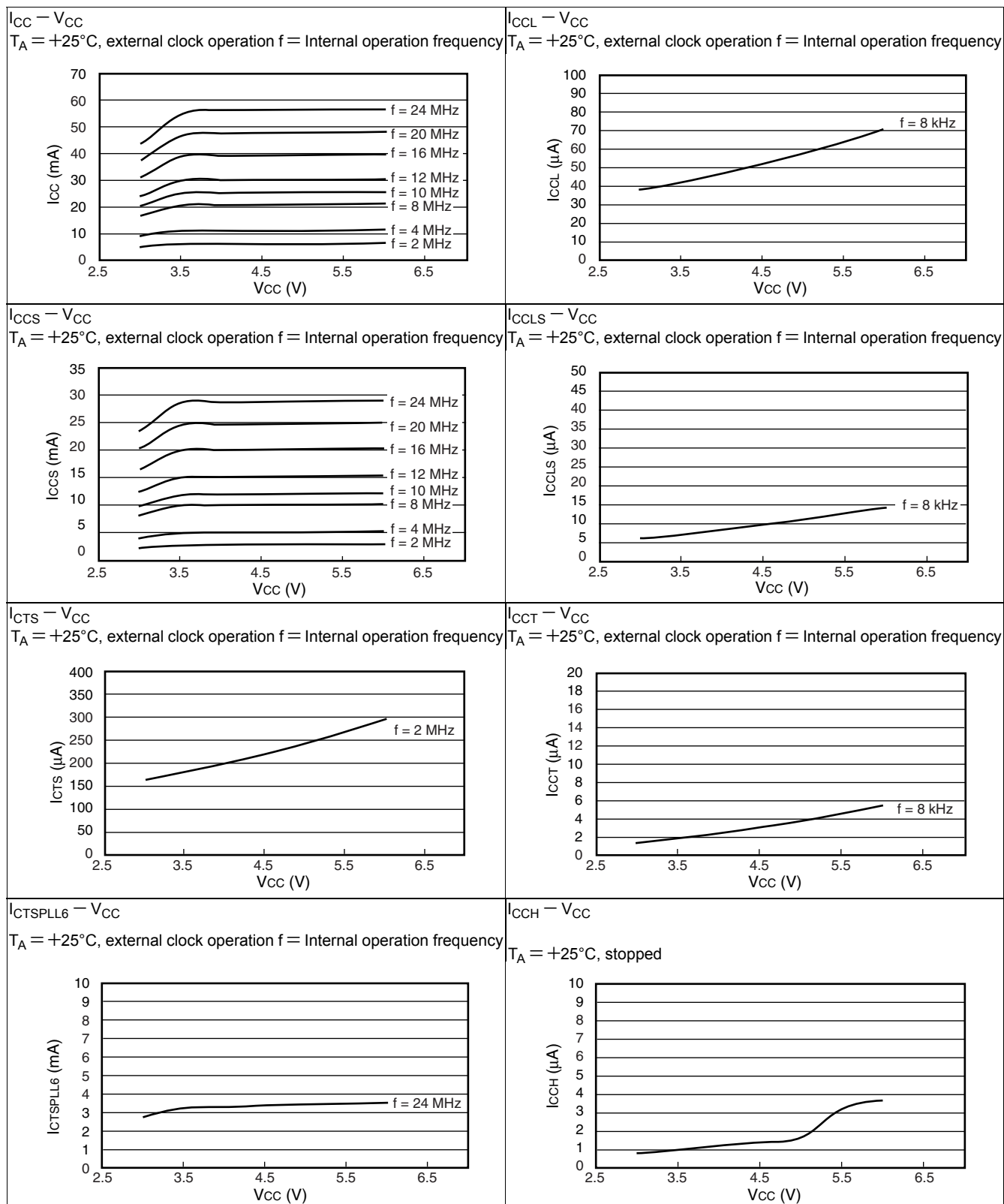


12. Example Characteristics

■ MB90F346E, MB90F346ES, MB90F346CE, MB90F346CES



■ MB90F349E, MB90F349ES, MB90F349CE, MB90F349CES



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