Infineon Technologies - MB90347ESPMC-GS-332-ERE2 Datasheet

Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

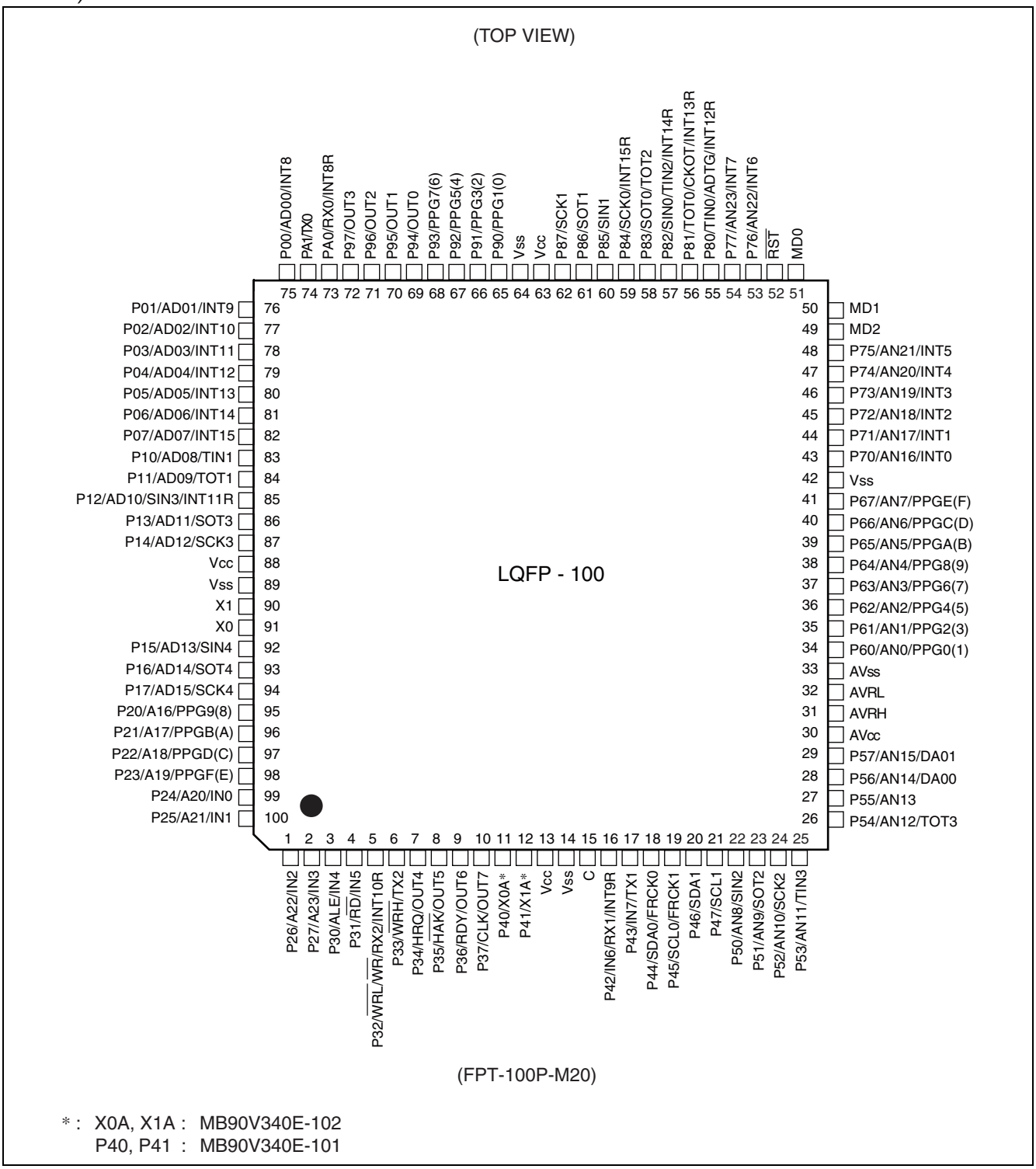
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-332-ere2

Part Number / Parameter	MB90V340E-101, MB90V340E-102	MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
A/D Converter	24 input channels	Devices with a C suffix in the part number : 24 channels Devices without a C suffix in the part number : 16 channels	
	10-bit or 8-bit resolution Conversion time : Min 3 μs include sample time (per one channel)		
16-bit Reload Timer (4 channels)	Operation clock frequency : fsys/2^1, fsys/2^3, fsys/2^5 (fsys = Machine clock frequency) Supports External Event Count function		
16-bit Free-run Timer (2 channels)	Generates an interrupt signal on overflow Supports Timer Clear when the output compare finds a match Operation clock freq. : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4, fsys/2^5, fsys/2^6, fsys/2^7 (fsys = Machine clock freq.) Free-run Timer 0 (clock input FRCK0) corresponds to ICU 0/1/2/3, OCU 0/1/2/3 Free-run Timer 1 (clock input FRCK1) corresponds to ICU 4/5/6/7, OCU 4/5/6/7		
16-bit Output Compare (8 channels)	Generates an interrupt signal when one of the 16-bit free-run timer matches the output compare register A pair of compare registers can be used to generate an output signal.		
16-bit Input Capture (8 channels)	Captures the value of the 16-bit free-run timer and generates an interrupt when triggered by a pin input (rising edge, falling edge, or both rising and falling edges).		
8/16-bit Programmable Pulse Generator	8 channels (16-bit) /16 channels (8-bit) Sixteen 8-bit reload counters Sixteen 8-bit reload registers for L pulse width Sixteen 8-bit reload registers for H pulse width		
	Supports 8-bit and 16-bit operation modes A pair of 8-bit reload counters can be configured as one 16-bit reload counter or as 8-bit prescaler plus 8-bit reload counter Operating clock freq. : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4 or 128 μs@fosc = 4 MHz (fsys = Machine clock frequency, fosc = Oscillation clock frequency)		
CAN Interface	3 channels	2 channels : MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S) 1 channel : MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	2 channels : MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S) 1 channel : MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
	Conforms to CAN Specification Version 2.0 Part A and B Automatic re-transmission in case of error Automatic transmission in response to Remote Frames Prioritized 16 message buffers for data and ID's Supports multiple messages Flexible configuration of acceptance filtering : Full bit compare/Full bit mask/Two partial bit masks Supports up to 1 Mbps		

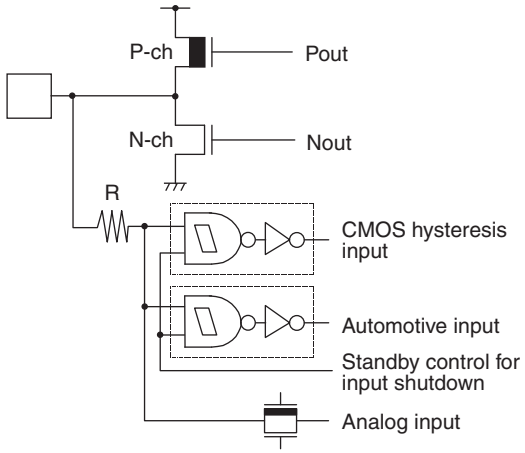
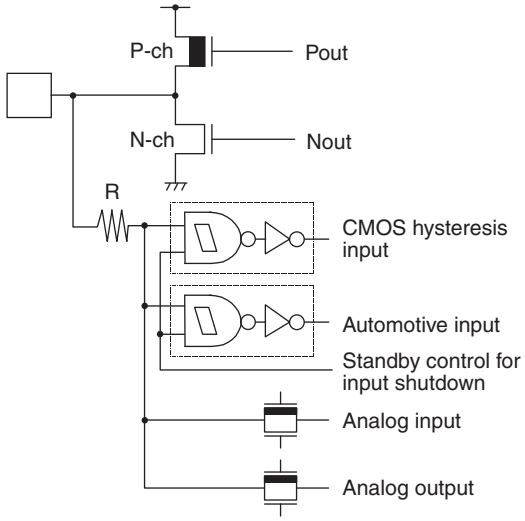
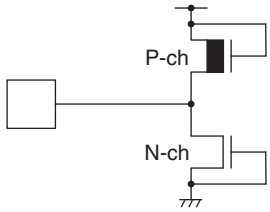
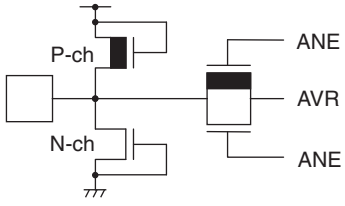
(Continued)

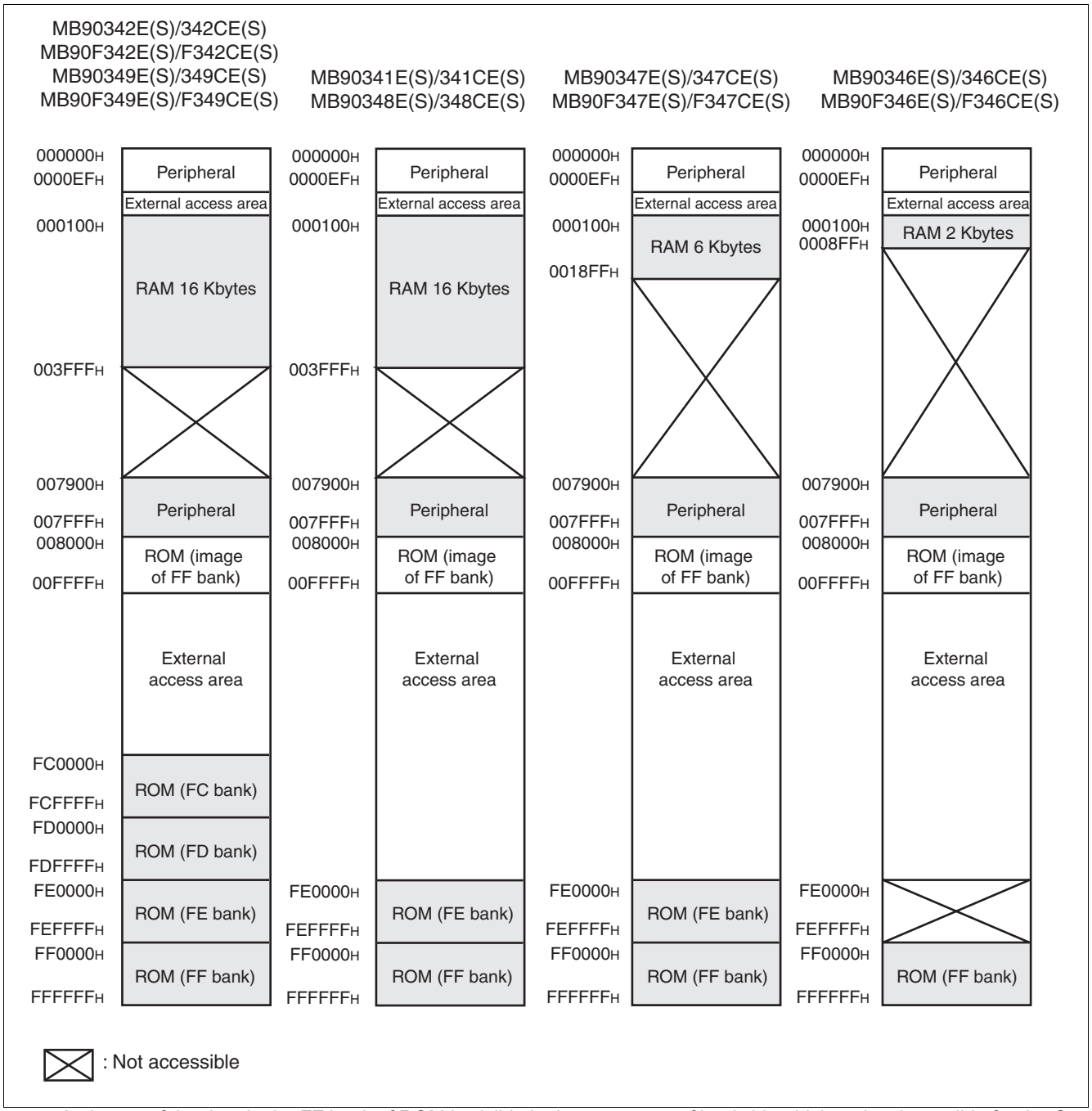


This pin assignment is for using MB90V340E-101/102 via probecable as MB90340E.

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
33	31	AVRH	L	Reference voltage input pin for the A/D Converter. This power supply must be turned on or off while a voltage higher than or equal to AVRH is applied to AV_{CC}.
34	32	AVRL	K	Lower reference voltage input pin for the A/D Converter
35	33	AV_{SS}	K	Analog GND pin for the A/D Converter
36 to 43	34 to 41	P60 to P67	I	General purpose I/O pins.
		AN0 to AN7		Analog input pins for the A/D converter
		PPG0, 2, 4, 6, 8, A, C, E		Output pins for PPGs
44	42	V_{SS}	—	GND pin
45 to 50	43 to 48	P70 to P75	I	General purpose I/O pins.
		AN16 to AN21		Analog input pins for the A/D converter (devices with a C suffix in the part number)
		INT0 to INT5		External interrupt request input pins
51	49	MD2	D	Input pin for specifying the operating mode.
52, 53	50, 51	MD1, MD0	C	Input pins for specifying the operating mode.
54	52	$\overline{RST}$	E	Reset input pin
55, 56	53, 54	P76, P77	I	General purpose I/O pins.
		AN22, AN23		Analog input pins for the A/D converter (devices with a C suffix in the part number)
		INT6, INT7		External interrupt request input pins
57	55	P80	F	General purpose I/O pin.
		TIN0		Event input pin for the reload timer
		ADTG		Trigger input pin for the A/D converter
		INT12R		External interrupt request input pin
58	56	P81	F	General purpose I/O pin.
		TOT0		Output pin for the reload timer
		CKOT		Output pin for the clock monitor
		INT13R		External interrupt request input pin
59	57	P82	M	General purpose I/O pin.
		SIN0		Serial data input pin for UART0
		TIN2		Event input pin for the reload timer
		INT14R		External interrupt request input pin
60	58	P83	F	General purpose I/O pin.
		SOT0		Serial data output pin for UART0
		TOT2		Output pin for the reload timer

(Continued)

Type	Circuit	Remarks
I		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = –4 mA) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ A/D converter analog input
J		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = –4 mA) ■ D/A analog output ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ A/D converter analog input
K		Power supply input protection circuit
L		■ A/D converter reference voltage power supply input pin, with the protection circuit ■ Flash memory devices do not have a protection circuit against V_{CC} for pin AVRH



Note: :An image of the data in the FF bank of ROM is visible in the upper part of bank 00, which makes it possible for the C compiler to use the small memory model. The lower 16 bits of addresses in the FF bank are the same as the lower 16 bits of addresses in the 00 bank so that tables stored in the ROM can be accessed without using the far specifier in the pointer declaration.
For example, when the address $00C000_H$ is accessed, the data at $FFC000_H$ in ROM is actually accessed.
The ROM area in bank FF exceeds 32 Kbytes, and its entire image cannot be shown in bank 00.
As a result, the image between $FF8000_H$ and $FFFFFF_H$ is visible in bank 00, while the image between $FF0000_H$ and $FF7FFF_H$ is visible only in bank FF.

Address	Register	Abbreviation	Access	Resource name	Initial value
000020_H	Serial Mode Register 0	SMR0	W,R/W	UART0	00000000_B
000021_H	Serial Control Register 0	SCR0	W,R/W		00000000_B
000022_H	Reception/Transmission Data Register 0	RDR0/TDR0	R/W		00000000_B
000023_H	Serial Status Register 0	SSR0	R,R/W		00001000_B
000024_H	Extended Communication Control Register 0	ECCR0	R,W, R/W		$000000XX_B$
000025_H	Extended Status/Control Register 0	ESCR0	R/W		00000100_B
000026_H	Baud Rate Generator Register 00	BGR00	R/W		00000000_B
000027_H	Baud Rate Generator Register 01	BGR01	R/W		00000000_B
000028_H	Serial Mode Register 1	SMR1	W,R/W	UART1	00000000_B
000029_H	Serial Control Register 1	SCR1	W,R/W		00000000_B
$00002A_H$	Reception/Transmission Data Register 1	RDR1/TDR1	R/W		00000000_B
$00002B_H$	Serial Status Register 1	SSR1	R,R/W		00001000_B
$00002C_H$	Extended Communication Control Register 1	ECCR1	R,W, R/W		$000000XX_B$
$00002D_H$	Extended Status/Control Register 1	ESCR1	R/W		00000100_B
$00002E_H$	Baud Rate Generator Register 10	BGR10	R/W		00000000_B
$00002F_H$	Baud Rate Generator Register 11	BGR11	R/W		00000000_B
000030_H	PPG 0 Operation Mode Control Register	PPGC0	W,R/W	16-bit PPG 0/1	$0X000XX1_B$
000031_H	PPG 1 Operation Mode Control Register	PPGC1	W,R/W		$0X000001_B$
000032_H	PPG 0/PPG 1 Count Clock Select Register	PPG01	R/W		$000000X0_B$
000033_H	Reserved				
000034_H	PPG 2 Operation Mode Control Register	PPGC2	W,R/W	16-bit PPG 2/3	$0X000XX1_B$
000035_H	PPG 3 Operation Mode Control Register	PPGC3	W,R/W		$0X000001_B$
000036_H	PPG 2/PPG 3 Count Clock Select Register	PPG23	R/W		$000000X0_B$
000037_H	Reserved				
000038_H	PPG 4 Operation Mode Control Register	PPGC4	W,R/W	16-bit PPG 4/5	$0X000XX1_B$
000039_H	PPG 5 Operation Mode Control Register	PPGC5	W,R/W		$0X000001_B$
$00003A_H$	PPG 4/PPG 5 Clock Select Register	PPG45	R/W		$000000X0_B$
$00003B_H$	Address Detect Control Register 1	PACSR1	R/W	Address Match Detection 1	00000000_B
$00003C_H$	PPG 6 Operation Mode Control Register	PPGC6	W,R/W	16-bit PPG 6/7	$0X000XX1_B$
$00003D_H$	PPG 7 Operation Mode Control Register	PPGC7	W,R/W		$0X000001_B$
$00003E_H$	PPG 6/PPG 7 Count Clock Control Register	PPG67	R/W		$000000X0_B$
$00003F_H$	Reserved				

(Continued)

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
$0079E0_H$	Detect Address Setting 0	PADR0	R/W	Address Match Detection 0	$XXXXXXXX_B$
$0079E1_H$	Detect Address Setting 0	PADR0	R/W		$XXXXXXXX_B$
$0079E2_H$	Detect Address Setting 0	PADR0	R/W		$XXXXXXXX_B$
$0079E3_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E4_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E5_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E6_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E7_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E8_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E9_H$ to $0079EF_H$	Reserved				
$0079F0_H$	Detect Address Setting 3	PADR3	R/W	Address Match Detection 1	$XXXXXXXX_B$
$0079F1_H$	Detect Address Setting 3	PADR3	R/W		$XXXXXXXX_B$
$0079F2_H$	Detect Address Setting 3	PADR3	R/W		$XXXXXXXX_B$
$0079F3_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F4_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F5_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F6_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F7_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F8_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F9_H$ to $0079FF_H$	Reserved				
$007A00_H$ to $007AFF_H$	Reserved for CAN Controller 0. Refer to “CAN Controllers				
$007B00_H$ to $007BFF_H$	Reserved for CAN Controller 0. Refer to “CAN Controllers”				
$007C00_H$ to $007CFF_H$	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
$007D00_H$ to $007DFF_H$	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
$007E00_H$ to $007FFF_H$	Reserved				

Note:
- Initial value of “X” represents unknown value.
- Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results in reading “X”.

9. CAN Controllers

The CAN controller has the following features:

- Conforms to CAN Specification Version 2.0 Part A and B
- Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmission/reception message buffers
- 29-bit ID and 8-byte data
- Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
- Two acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 kbps to 2 Mbps (when input clock is at 16 MHz)

List of Control Registers (1)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
000070_H	000080_H	Message Buffer Valid Register	BVALR	R/W	00000000_B 00000000_B
000071_H	000081_H				
000072_H	000082_H	Transmit Request Register	TREQR	R/W	00000000_B 00000000_B
000073_H	000083_H				
000074_H	000084_H	Transmit Cancel Register	TCANR	W	00000000_B 00000000_B
000075_H	000085_H				
000076_H	000086_H	Transmission Complete Register	TCR	R/W	00000000_B 00000000_B
000077_H	000087_H				
000078_H	000088_H	Receive Complete Register	RCR	R/W	00000000_B 00000000_B
000079_H	000089_H				
$00007A_H$	$00008A_H$	Remote Request Receiving Register	RRTRR	R/W	00000000_B 00000000_B
$00007B_H$	$00008B_H$				
$00007C_H$	$00008C_H$	Receive Overrun Register	ROVRR	R/W	00000000_B 00000000_B
$00007D_H$	$00008D_H$				
$00007E_H$	$00008E_H$	Reception Interrupt Enable Register	RIER	R/W	00000000_B 00000000_B
$00007F_H$	$00008F_H$				

List of Message Buffers (ID Registers) (1)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A00_H$ to $007A1F_H$	$007C00_H$ to $007C1F_H$	General-Purpose RAM	——	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A20_H$	$007C20_H$	ID Register 0	IDR0	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A21_H$	$007C21_H$				
$007A22_H$	$007C22_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A23_H$	$007C23_H$				
$007A24_H$	$007C24_H$	ID Register 1	IDR1	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A25_H$	$007C25_H$				
$007A26_H$	$007C26_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A27_H$	$007C27_H$				
$007A28_H$	$007C28_H$	ID Register 2	IDR2	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A29_H$	$007C29_H$				
$007A2A_H$	$007C2A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A2B_H$	$007C2B_H$				
$007A2C_H$	$007C2C_H$	ID Register 3	IDR3	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A2D_H$	$007C2D_H$				
$007A2E_H$	$007C2E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A2F_H$	$007C2F_H$				
$007A30_H$	$007C30_H$	ID Register 4	IDR4	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A31_H$	$007C31_H$				
$007A32_H$	$007C32_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A33_H$	$007C33_H$				
$007A34_H$	$007C34_H$	ID Register 5	IDR5	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A35_H$	$007C35_H$				
$007A36_H$	$007C36_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A37_H$	$007C37_H$				
$007A38_H$	$007C38_H$	ID Register 6	IDR6	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A39_H$	$007C39_H$				
$007A3A_H$	$007C3A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A3B_H$	$007C3B_H$				
$007A3C_H$	$007C3C_H$	ID Register 7	IDR7	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A3D_H$	$007C3D_H$				
$007A3E_H$	$007C3E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A3F_H$	$007C3F_H$				

List of Message Buffers (DLC Registers and Data Registers) (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A80_H$ to $007A87_H$	$007C80_H$ to $007C87_H$	Data Register 0 (8 bytes)	DTR0	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A88_H$ to $007A8F_H$	$007C88_H$ to $007C8F_H$	Data Register 1 (8 bytes)	DTR1	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A90_H$ to $007A97_H$	$007C90_H$ to $007C97_H$	Data Register 2 (8 bytes)	DTR2	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A98_H$ to $007A9F_H$	$007C98_H$ to $007C9F_H$	Data Register 3 (8 bytes)	DTR3	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AA0_H$ to $007AA7_H$	$007CA0_H$ to $007CA7_H$	Data Register 4 (8 bytes)	DTR4	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AA8_H$ to $007AAF_H$	$007CA8_H$ to $007CAF_H$	Data Register 5 (8 bytes)	DTR5	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AB0_H$ to $007AB7_H$	$007CB0_H$ to $007CB7_H$	Data Register 6 (8 bytes)	DTR6	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AB8_H$ to $007ABF_H$	$007CB8_H$ to $007CBF_H$	Data Register 7 (8 bytes)	DTR7	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AC0_H$ to $007AC7_H$	$007CC0_H$ to $007CC7_H$	Data Register 8 (8 bytes)	DTR8	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AC8_H$ to $007ACF_H$	$007CC8_H$ to $007CCF_H$	Data Register 9 (8 bytes)	DTR9	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AD0_H$ to $007AD7_H$	$007CD0_H$ to $007CD7_H$	Data Register 10 (8 bytes)	DTR10	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AD8_H$ to $007ADF_H$	$007CD8_H$ to $007CDF_H$	Data Register 11 (8 bytes)	DTR11	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AE0_H$ to $007AE7_H$	$007CE0_H$ to $007CE7_H$	Data Register 12 (8 bytes)	DTR12	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007AE8_H$ to $007AEF_H$	$007CE8_H$ to $007CEF_H$	Data Register 13 (8 bytes)	DTR13	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$

10. Interrupt Factors, Interrupt Vectors, Interrupt Control Register

Interrupt cause	EI^{2}OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
Reset	N	—	#08	FFFFDC$_H$	—	—
INT9 instruction	N	—	#09	FFFFD8$_H$	—	—
Exception	N	—	#10	FFFFD4$_H$	—	—
CAN 0 RX	N	—	#11	FFFFD0$_H$	ICR00	0000B0$_H$
CAN 0 TX/NS	N	—	#12	FFFFCC$_H$		
CAN 1 RX / Input Capture 6	Y1	—	#13	FFFFC8$_H$	ICR01	0000B1$_H$
CAN 1 TX/NS / Input Capture 7	Y1	—	#14	FFFFC4$_H$		
CAN 2 RX / I^{2}C0	N	—	#15	FFFFC0$_H$	ICR02	0000B2$_H$
CAN 2 TX/NS	N	—	#16	FFFFBC$_H$		
16-bit Reload Timer 0	Y1	0	#17	FFFFB8$_H$	ICR03	0000B3$_H$
16-bit Reload Timer 1	Y1	1	#18	FFFFB4$_H$		
16-bit Reload Timer 2	Y1	2	#19	FFFFB0$_H$	ICR04	0000B4$_H$
16-bit Reload Timer 3	Y1	—	#20	FFFFAC$_H$		
PPG 0/1/4/5	N	—	#21	FFFFA8$_H$	ICR05	0000B5$_H$
PPG 2/3/6/7	N	—	#22	FFFFA4$_H$		
PPG 8/9/C/D	N	—	#23	FFFFA0$_H$	ICR06	0000B6$_H$
PPG A/B/E/F	N	—	#24	FFFF9C$_H$		
Time Base Timer	N	—	#25	FFFF98$_H$	ICR07	0000B7$_H$
External Interrupt 0 to 3, 8 to 11	Y1	3	#26	FFFF94$_H$		
Watch Timer	N	—	#27	FFFF90$_H$	ICR08	0000B8$_H$
External Interrupt 4 to 7, 12 to 15	Y1	4	#28	FFFF8C$_H$		
A/D Converter	Y1	5	#29	FFFF88$_H$	ICR09	0000B9$_H$
Free-run Timer 0 / Free-run Timer 1	N	—	#30	FFFF84$_H$		
Input Capture 4/5 / I^{2}C1	Y1	6	#31	FFFF80$_H$	ICR10	0000BA$_H$
Output Compare 0/1/4/5	Y1	7	#32	FFFF7C$_H$		
Input Capture 0 to 3	Y1	8	#33	FFFF78$_H$	ICR11	0000BB$_H$
Output Compare 2/3/6/7	Y1	9	#34	FFFF74$_H$		
UART 0 RX	Y2	10	#35	FFFF70$_H$	ICR12	0000BC$_H$
UART 0 TX	Y1	11	#36	FFFF6C$_H$		
UART 1 RX / UART 3 RX	Y2	12	#37	FFFF68$_H$	ICR13	0000BD$_H$
UART 1 TX / UART 3 TX	Y1	13	#38	FFFF64$_H$		

(Continued)

11.4 AC Characteristics

11.4.1 Clock Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP}≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

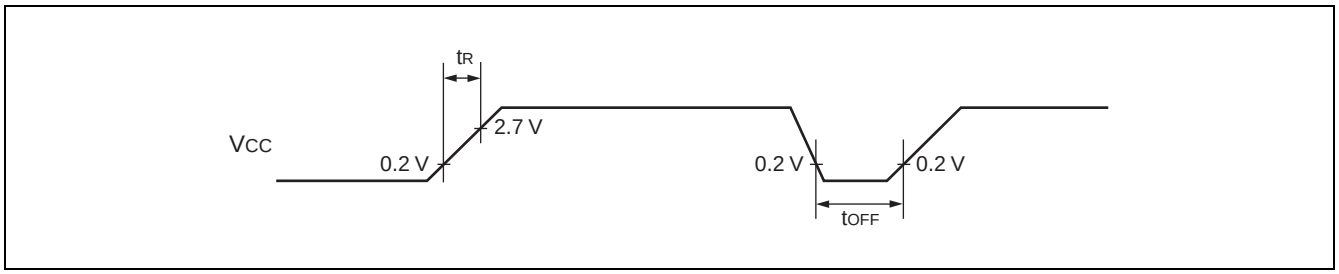
Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Clock frequency	f_C	X0, X1	3	—	16	MHz	When using an oscillation circuit
			4	—	16	MHz	PLL multiplied by 1 When using an oscillation circuit
			4	—	12	MHz	PLL multiplied by 2 When using an oscillation circuit
			4	—	8	MHz	PLL multiplied by 3 When using an oscillation circuit
			4	—	6	MHz	PLL multiplied by 4 When using an oscillation circuit
			—	—	4	MHz	PLL multiplied by 6 When using an oscillation circuit
			3	—	24	MHz	When using an external clock*
	f_{CL}	X0A, X1A	—	32.768	100	kHz	
Clock cycle time	t_{CYL}	X0, X1	62.5	—	333	ns	When using an oscillation circuit
		X0, X1	41.67	—	333	ns	When using an external clock
	t_{CYLL}	X0A, X1A	10	30.5	—	µs	
Input clock pulse width	P_{WH}, P_{WL}	X0	10	—	—	ns	Duty ratio is about 30% to 70%.
	P_{WHL}, P_{WLL}	X0A	5	15.2	—	µs	
Input clock rise and fall time	t_{CR}, t_{CF}	X0	—	—	5	ns	When using external clock
Internal operating clock frequency (machine clock)	f_{CP}	—	1.5	—	24	MHz	When using main clock
	f_{CPL}	—	—	8.192	50	kHz	When using sub clock
Internal operating clock cycle time (machine clock)	t_{CP}	—	41.67	—	666	ns	When using main clock
	t_{CPL}	—	20	122.1	—	µs	When using sub clock

* : When selecting the PLL clock, the range of clock frequency is limited. Use this product within the range as mentioned in “Relation between the external clock frequency and machine clock frequency”.

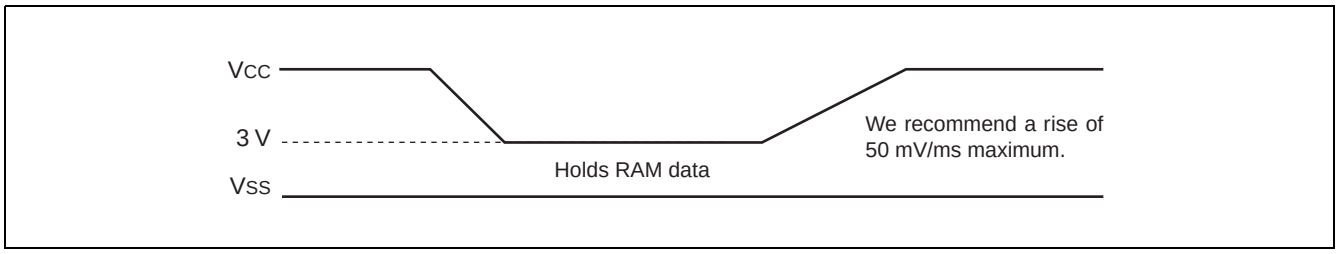
11.4.3 Power On Reset

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0.0 V)

Parameter	Symbol	Pin	Condition	Value		Unit	Remarks
				Min	Max		
Power on rise time	t_R	V_{CC}	—	0.05	30	ms	
Power off time	t_{OFF}	V_{CC}		1	—	ms	Waiting time until power-on



Note: : If you change the power supply voltage too rapidly, a power on reset may occur. We recommend that you startup smoothly by restraining voltages when changing the power supply voltage during operation, as shown in the figure below. Perform while not using the PLL clock. However, if voltage drops are within 1 V/s, you can operate while using the PLL clock.



11.4.4 Clock Output Timing

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V, f_{CP} ≤ 24 MHz)

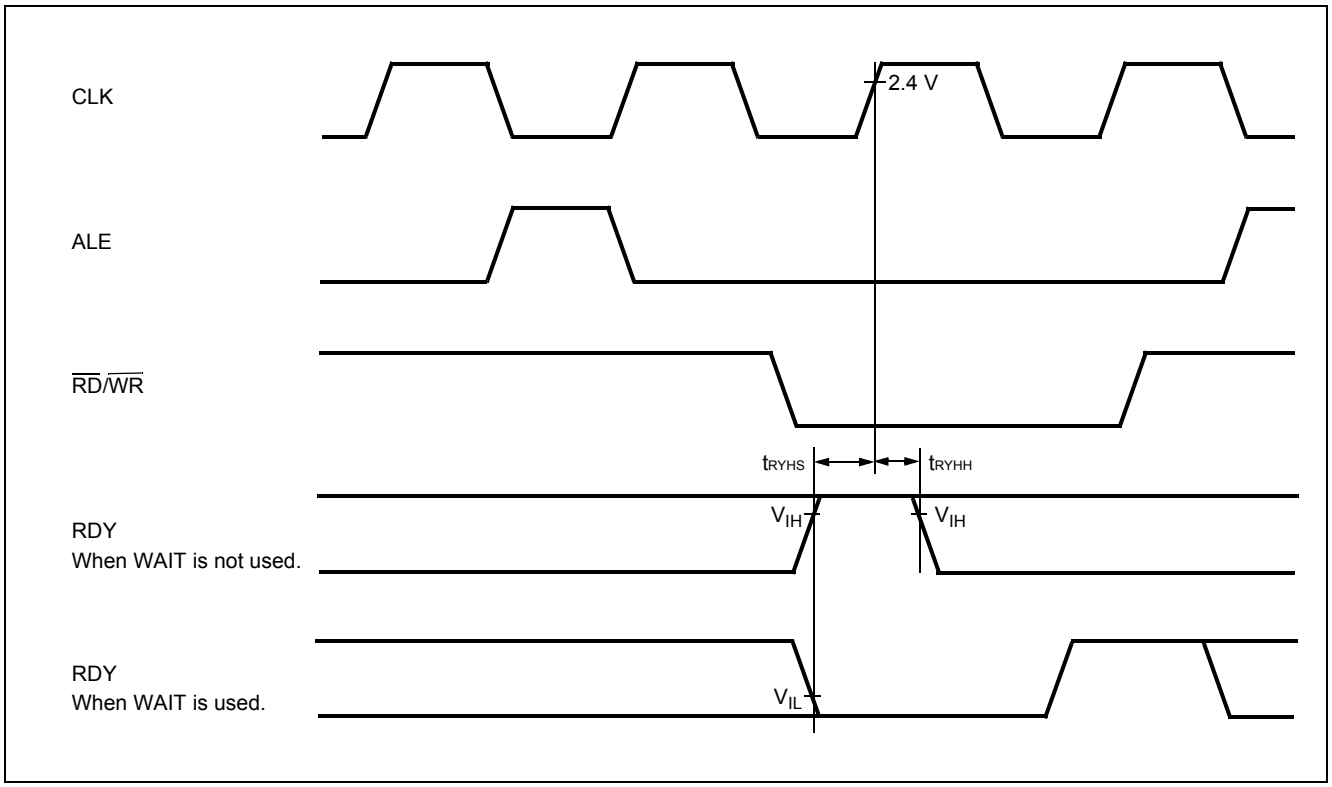
Parameter	Symbol	Pin	Condition	Value		Unit	Remarks
				Min	Max		
Cycle time	t_{CYC}	CLK	—	62.5	—	ns	f_{CP} = 16 MHz
				41.67	—	ns	f_{CP} = 24 MHz
CLK ↑ → CLK ↓	t_{CHCL}	CLK	—	20	—	ns	f_{CP} = 16 MHz
				13	—	ns	f_{CP} = 24 MHz

11.4.7 Ready Input Timing

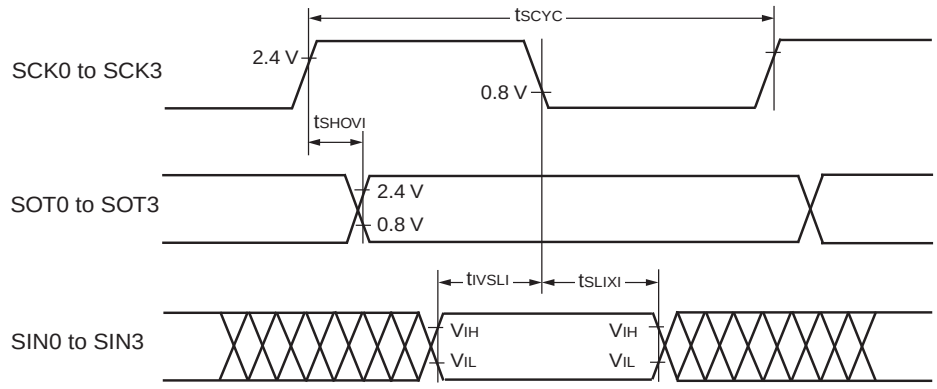
(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V, f_{CP} ≤ 24 MHz)

Parameter	Symbol	Pin	Test Condition	Rated Value		Unit	Remarks
				Min	Max		
RDY setup time	t_{RYHS}	RDY	—	45	—	ns	f_{CP} = 16 MHz
				32	—	ns	f_{CP} = 24 MHz
RDY hold time	t_{RYHH}	RDY		0	—	ns	

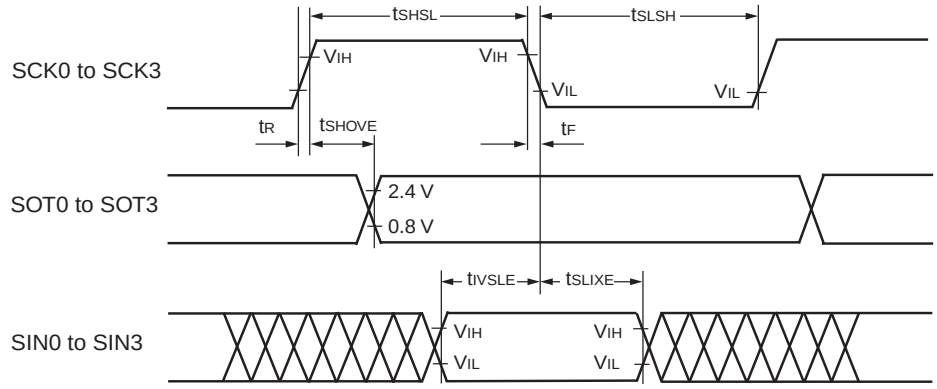
Note: : If the RDY setup time is insufficient, use the auto-ready function.



- Internal Shift Clock Mode



- External Shift Clock Mode

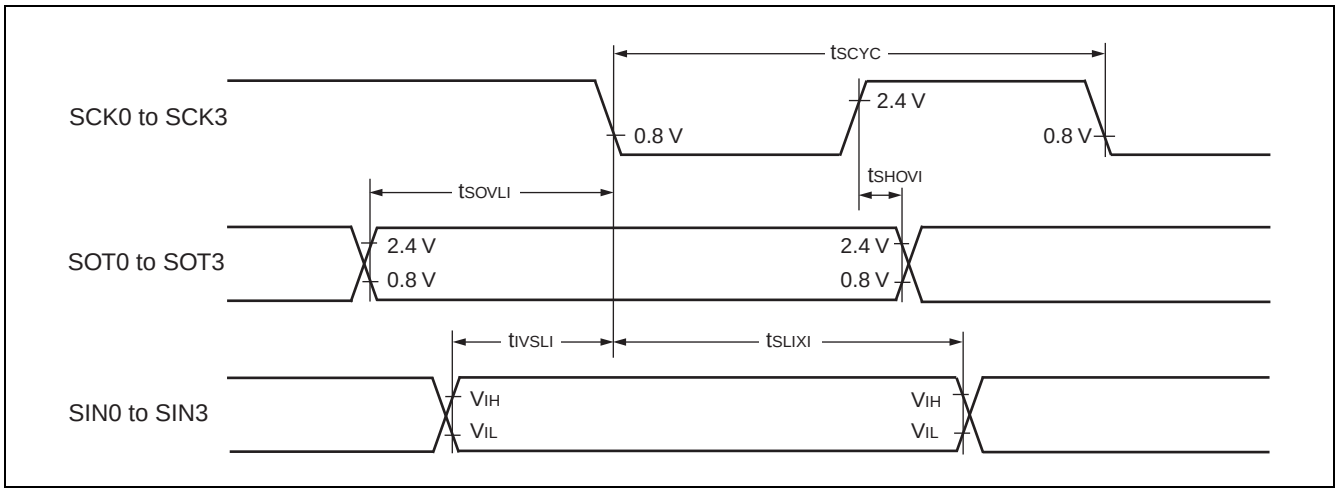


■ **Bit setting: ESCR:SCES = 0, ECCR:SCDE = 1**

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are C_L = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		−50	+50	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↓ → Valid SIN hold time	t_{SLIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT → SCK ↓ delay time	t_{SOVLI}	SCK0 to SCK3, SOT0 to SOT3		3 t_{CP} − 70	—	ns

Note:
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to "Clock Timing".

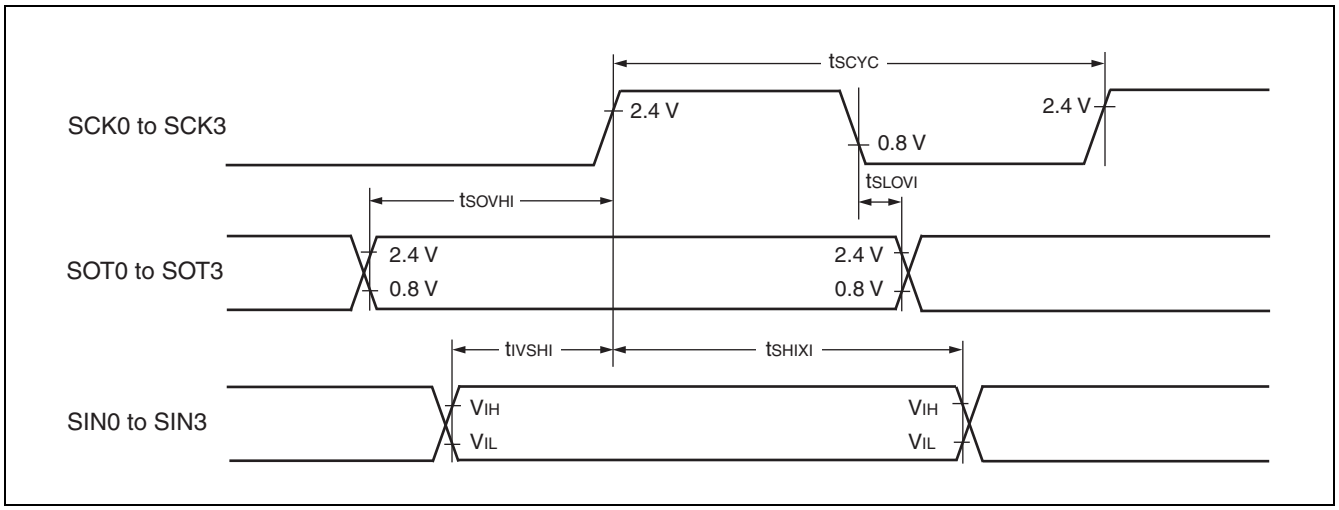


■ **Bit setting: ESCR:SCES = 1, ECCR:SCDE = 1**

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are C_L = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		−50	+50	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT → SCK ↑ delay time	t_{SOVHI}	SCK0 to SCK3, SOT0 to SOT3		3 t_{CP} − 70	—	ns

Note:
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to "Clock Timing".



11.5 A/D Converter

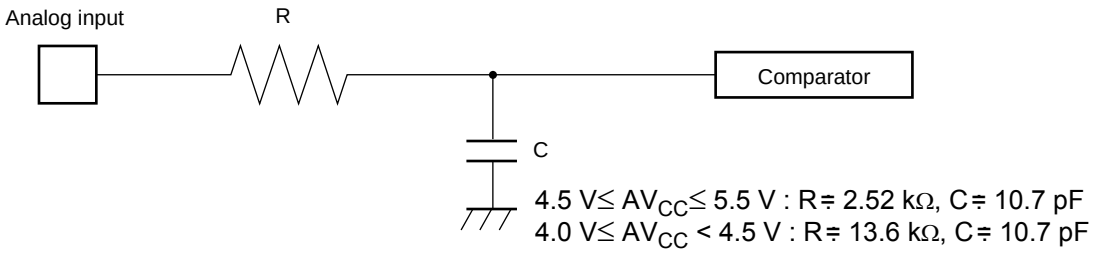
(T_A = −40°C to +105°C, 3.0 V≤ AVRH − AVRL, V_{CC} = AV_{CC} = 5.0 V ± 10%, f_{CP}≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	—	—	±3.0	LSB	
Nonlinearity error	—	—	—	—	±2.5	LSB	
Differential nonlinearity error	—	—	—	—	±1.9	LSB	
Zero reading voltage	V_{OT}	AN0 to AN23	AVRL − 1.5 × LSB	AVRL + 0.5 × LSB	AVRL + 2.5 × LSB	V	
Full scale reading voltage	V_{FST}	AN0 to AN23	AVRH − 3.5 × LSB	AVRH − 1.5 × LSB	AVRH + 0.5 × LSB	V	
Compare time	—	—	1.0	—	16500	µs	4.5 V≤ AV_{CC}≤ 5.5 V
			2.0				4.0 V≤ AV_{CC} < 4.5 V
Sampling time	—	—	0.5	—	∞	µs	4.5 V≤ AV_{CC}≤ 5.5 V
			1.2				4.0 V≤ AV_{CC} < 4.5 V
Analog port input current	I_{AIN}	AN0 to AN23	−0.3	—	+0.3	µA	
Analog input voltage range	V_{AIN}	AN0 to AN23	AVRL	—	AVRH	V	
Reference voltage range	—	AVRH	AVRL + 2.7	—	AV_{CC}	V	
	—	AVRL	0	—	AVRH − 2.7	V	
Power supply current	I_A	AV_{CC}	—	3.5	7.5	mA	
	I_{AH}	AV_{CC}	—	—	5	µA	*
Reference voltage current	I_R	AVRH	—	600	900	µA	
	I_{RH}	AVRH	—	—	5	µA	*
Offset between input channels	—	AN0 to AN23	—	—	4	LSB	

*: If the A/D convertor is not operating, a current when CPU is stopped is applicable (V_{CC} = AV_{CC} = AVRH = 5.0 V) .
Note: : The accuracy gets worse as |AVRH − AVRL| becomes smaller.

If the output impedance of the external circuit is too high, a sampling period for an analog voltage may be insufficient.

- Analog input circuit model



Note: : Use the values in the figure only as a guideline.

15. Major Changes

Spansiion Publication Number: DS07-13747-4E

Page	Section	Change Results
___	___	Deleted the part numbers; MB90F343E(S), MB90F343CE(S)
51	Electrical Characteristics Absolute Maximum Ratings	Added “*6” in remark for “L" level maximum output current and “H” level maximum output current. Added “*7” in remark for “L" level average output current and “H” level average output current. Added “*8” in remark for “L"level average overall output current and “H” level average overall output current.
52		Added as follows. “*6:The maximum output current is defined as the peak value of the current of any one of the corresponding pins.” “*7:The average output current is defined as the value of the average current flowing over 100 ms at any one of the corresponding pins.” “*8:The average total output current is defined as the value of the average current flowing over 100 ms at all of the corresponding pins.”

NOTE: Please see “Document History” about later revised information.

Document History

Document Title: MB90340E Series F2MC-16LX 16-bit Microcontroller Datasheet Document Number: 002-04498				
Revision	**ECN**	**Orig. of Change**	**Submission Date**	**Description of Change**
**	—	AKIH	08/23/2010	Migrated to Cypress and assigned document number 002-04498. No change to document contents or format.
*A	5221535	AKIH	05/04/2016	Updated to Cypress template