Infineon Technologies - MB90347ESPMC-GS-411E1 Datasheet

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-411e1

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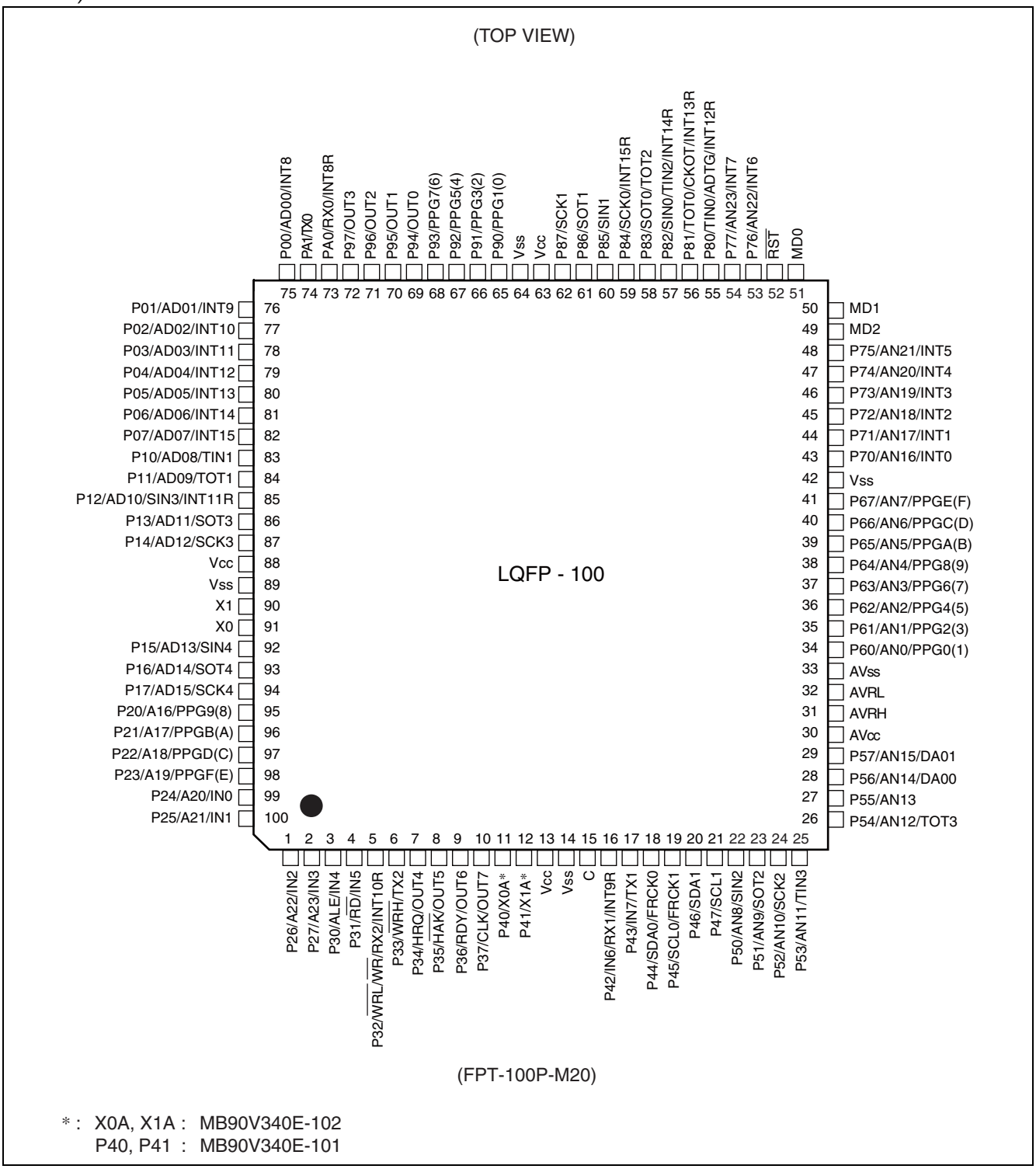


This pin assignment is for using MB90V340E-101/102 via probecable as MB90340E.

5. Handling Devices

1. Preventing latch-up

CMOS IC may suffer latch-up under the following conditions:

- A voltage higher than V_{CC} or lower than V_{SS} is applied to an input or output pin.
- A voltage higher than the rated voltage is applied between V_{CC} and V_{SS} pins.
- The AV_{CC} power supply is applied before the V_{CC} voltage.

Latch-up may increase the power supply current drastically, causing thermal damage to the device.

For the same reason, also be careful not to let the analog power-supply voltage (AV_{CC}, AVRH) exceed the digital power-supply voltage.

2. Handling unused pins

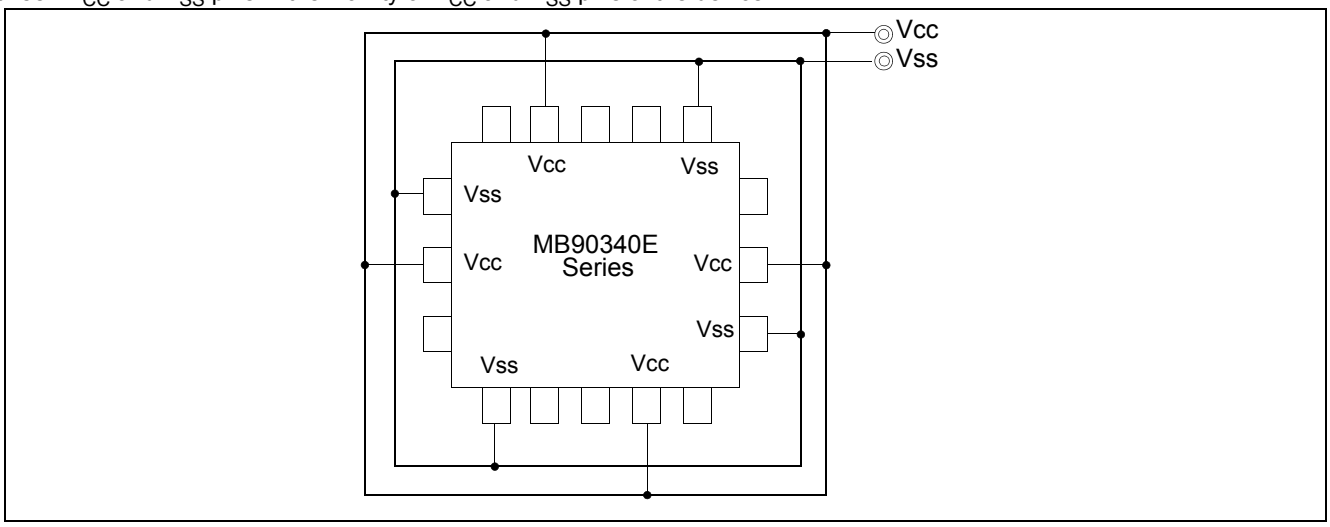
Leaving unused input terminals open may lead to permanent damage due to malfunction and latch-up; pull up or pull down the terminals through the resistors of 2 kΩ or more.

3. Power supply pins (V_{CC}/V_{SS})

- If there are multiple V_{CC} and V_{SS} pins, from the point of view of device design, pins to be of the same potential are connected inside of the device to prevent malfunction such as latch-up.

To reduce unnecessary radiation, prevent malfunctioning of the strobe signal due to the rise of ground level, and observe the standard for total output current, be sure to connect the V_{CC} and V_{SS} pins to the power supply and ground externally.
Connect V_{CC} and V_{SS} pins to the device from the current supply source at a possibly low impedance.

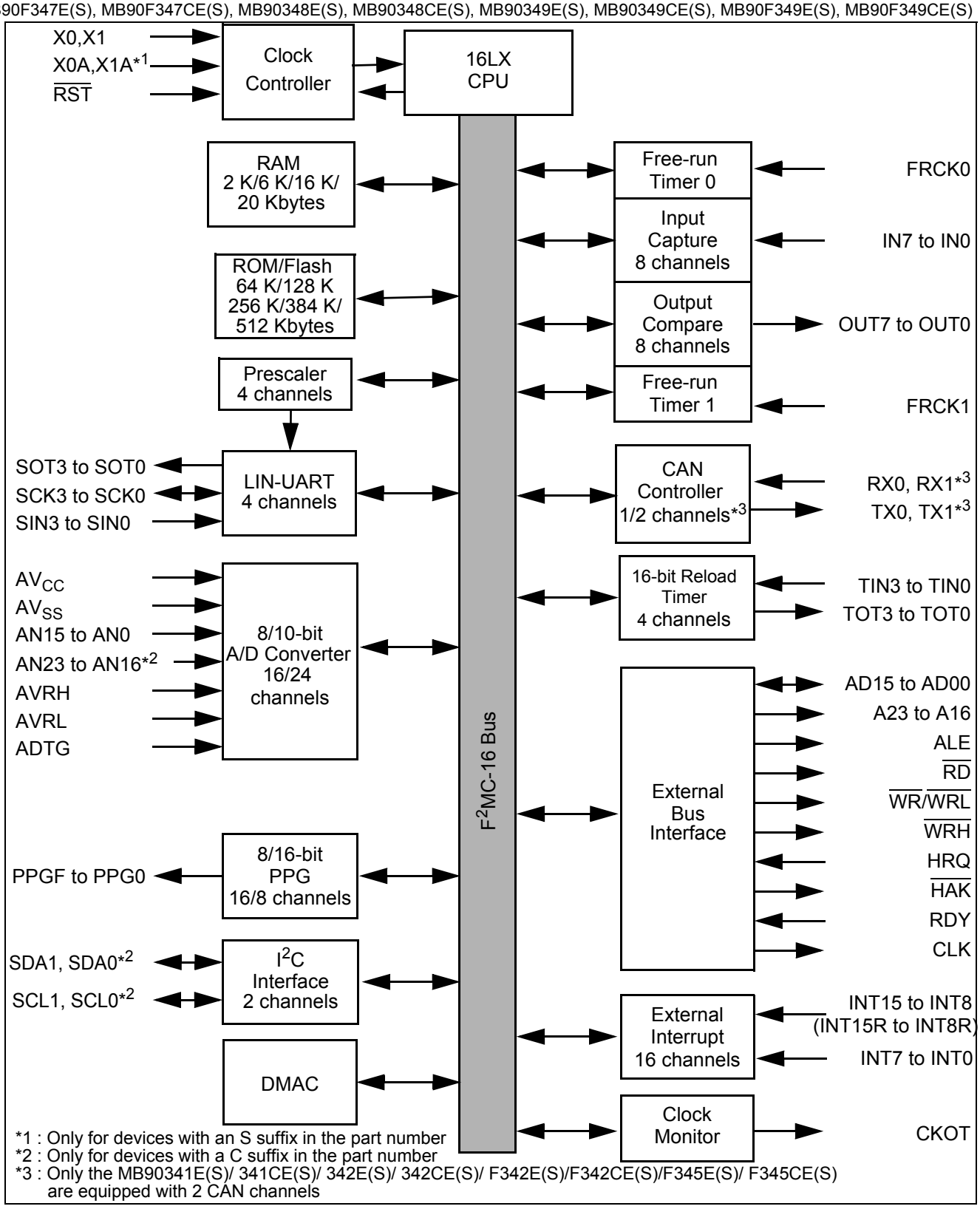
- As a measure against power supply noise, it is recommended to connect a capacitor of about 0.1 µF as a bypass capacitor between V_{CC} and V_{SS} pins in the vicinity of V_{CC} and V_{SS} pins of the device.



4. Mode Pins (MD0 to MD2)

Connect the mode pins directly to V_{CC} or V_{SS} pins. To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pins to V_{CC} or V_{SS} pins and to provide a low-impedance connection.

■ MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90346E(S), MB90346CE(S), MB90F346E(S), MB90F346CE(S), MB90347E(S), MB90347CE(S), MB90F347E(S), MB90F347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S), MB90F349E(S), MB90F349CE(S)



Address	Register	Abbreviation	Access	Resource name	Initial value
000040_H	PPG 8 Operation Mode Control Register	PPGC8	W,R/W	16-bit PPG 8/9	$0X000XX1_B$
000041_H	PPG 9 Operation Mode Control Register	PPGC9	W,R/W		$0X000001_B$
000042_H	PPG 8/PPG 9 Count Clock Control Register	PPG89	R/W		$000000X0_B$
000043_H	Reserved				
000044_H	PPG A Operation Mode Control Register	PPGCA	W,R/W	16-bit PPG A/B	$0X000XX1_B$
000045_H	PPG B Operation Mode Control Register	PPGCB	W,R/W		$0X000001_B$
000046_H	PPG A/PPG B Count Clock Select Register	PPGAB	R/W		$000000X0_B$
000047_H	Reserved				
000048_H	PPG C Operation Mode Control Register	PPGCC	W,R/W	16-bit PPG C/D	$0X000XX1_B$
000049_H	PPG D Operation Mode Control Register	PPGCD	W,R/W		$0X000001_B$
$00004A_H$	PPG C/PPG D Count Clock Select Register	PPGCD	R/W		$000000X0_B$
$00004B_H$	Reserved				
$00004C_H$	PPG E Operation Mode Control Register	PPGCE	W,R/W	16-bit PPG E/F	$0X000XX1_B$
$00004D_H$	PPG F Operation Mode Control Register	PPGCF	W,R/W		$0X000001_B$
$00004E_H$	PPG E/PPG F Count Clock Select Register	PPGEF	R/W		$000000X0_B$
$00004F_H$	Reserved				
000050_H	Input Capture Control Status 0/1	ICS01	R/W	Input Capture 0/1	00000000_B
000051_H	Input Capture Edge 0/1	ICE01	R/W, R		$XXX0X0XX_B$
000052_H	Input Capture Control Status 2/3	ICS23	R/W	Input Capture 2/3	00000000_B
000053_H	Input Capture Edge 2/3	ICE23	R		$XXXXXXXX_B$
000054_H	Input Capture Control Status 4/5	ICS45	R/W	Input Capture 4/5	00000000_B
000055_H	Input Capture Edge 4/5	ICE45	R		$XXXXXXXX_B$
000056_H	Input Capture Control Status 6/7	ICS67	R/W	Input Capture 6/7	00000000_B
000057_H	Input Capture Edge 6/7	ICE67	R/W, R		$XXX000XX_B$
000058_H	Output Compare Control Status 0	OCS0	R/W	Output Compare 0/1	$0000XX00_B$
000059_H	Output Compare Control Status 1	OCS1	R/W		$0XX00000_B$
$00005A_H$	Output Compare Control Status 2	OCS2	R/W	Output Compare 2/3	$0000XX00_B$
$00005B_H$	Output Compare Control Status 3	OCS3	R/W		$0XX00000_B$
$00005C_H$	Output Compare Control Status 4	OCS4	R/W	Output Compare 4/5	$0000XX00_B$
$00005D_H$	Output Compare Control Status 5	OCS5	R/W		$0XX00000_B$
$00005E_H$	Output Compare Control Status 6	OCS6	R/W	Output Compare 6/7	$0000XX00_B$
$00005F_H$	Output Compare Control Status 7	OCS7	R/W		$0XX00000_B$

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Address	Register	Abbreviation	Access	Resource name	Initial value
$0000C4_H$, $0000C5_H$	Reserved				
$0000C6_H$	External Interrupt Enable 0	ENIR0	R/W	External Interrupt 0	00000000_B
$0000C7_H$	External Interrupt Source 0	EIRR0	R/W		$XXXXXXXX_B$
$0000C8_H$	External Interrupt Level Setting 0	ELVR0	R/W		00000000_B
$0000C9_H$	External Interrupt Level Setting 0	ELVR0	R/W		00000000_B
$0000CA_H$	External Interrupt Enable 1	ENIR1	R/W	External Interrupt 1	00000000_B
$0000CB_H$	External Interrupt Source 1	EIRR1	R/W		$XXXXXXXX_B$
$0000CC_H$	External Interrupt Level Setting 1	ELVR1	R/W		00000000_B
$0000CD_H$	External Interrupt Level Setting 1	ELVR1	R/W		00000000_B
$0000CE_H$	External Interrupt Source Select	EISSR	R/W		00000000_B
$0000CF_H$	PLL/Sub clock Control Register	PSCCR	W	PLL	$XXXX0000_B$
$0000D0_H$	DMA Buffer Address Pointer L Register	BAPL	R/W	DMA	$XXXXXXXX_B$
$0000D1_H$	DMA Buffer Address Pointer M Register	BAPM	R/W		$XXXXXXXX_B$
$0000D2_H$	DMA Buffer Address Pointer H Register	BAPH	R/W		$XXXXXXXX_B$
$0000D3_H$	DMA Control Register	DMACS	R/W		$XXXXXXXX_B$
$0000D4_H$	I/O Register Address Pointer L Register	IOAL	R/W		$XXXXXXXX_B$
$0000D5_H$	I/O Register Address Pointer H Register	IOAH	R/W		$XXXXXXXX_B$
$0000D6_H$	Data Counter L Register	DCTL	R/W		$XXXXXXXX_B$
$0000D7_H$	Data Counter H Register	DCTH	R/W		$XXXXXXXX_B$
$0000D8_H$	Serial Mode Register 2	SMR2	W,R/W	UART2	00000000_B
$0000D9_H$	Serial Control Register 2	SCR2	W,R/W		00000000_B
$0000DA_H$	Reception/Transmission Data Register 2	RDR2/TDR2	R/W		00000000_B
$0000DB_H$	Serial Status Register 2	SSR2	R,R/W		00001000_B
$0000DC_H$	Extended Communication Control Register 2	ECCR2	R,W, R/W		$000000XX_B$
$0000DD_H$	Extended Status Control Register 2	ESCR2	R/W		00000100_B
$0000DE_H$	Baud Rate Generator Register 20	BGR20	R/W		00000000_B
$0000DF_H$	Baud Rate Generator Register 21	BGR21	R/W		00000000_B
$0000E0_H$ to $0000EF_H$	Reserved for CAN Controller 2. Refer to "CAN Controllers"				
$0000F0_H$ to $0000FF_H$	External				

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Address	Register	Abbreviation	Access	Resource name	Initial value
$0079E0_H$	Detect Address Setting 0	PADR0	R/W	Address Match Detection 0	$XXXXXXXX_B$
$0079E1_H$	Detect Address Setting 0	PADR0	R/W		$XXXXXXXX_B$
$0079E2_H$	Detect Address Setting 0	PADR0	R/W		$XXXXXXXX_B$
$0079E3_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E4_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E5_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E6_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E7_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E8_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E9_H$ to $0079EF_H$	Reserved				
$0079F0_H$	Detect Address Setting 3	PADR3	R/W	Address Match Detection 1	$XXXXXXXX_B$
$0079F1_H$	Detect Address Setting 3	PADR3	R/W		$XXXXXXXX_B$
$0079F2_H$	Detect Address Setting 3	PADR3	R/W		$XXXXXXXX_B$
$0079F3_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F4_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F5_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F6_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F7_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F8_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F9_H$ to $0079FF_H$	Reserved				
$007A00_H$ to $007AFF_H$	Reserved for CAN Controller 0. Refer to “CAN Controllers				
$007B00_H$ to $007BFF_H$	Reserved for CAN Controller 0. Refer to “CAN Controllers”				
$007C00_H$ to $007CFF_H$	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
$007D00_H$ to $007DFF_H$	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
$007E00_H$ to $007FFF_H$	Reserved				

Note:
- Initial value of “X” represents unknown value.
- Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results in reading “X”.

List of Message Buffers (ID Registers) (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A40_H$	$007C40_H$	ID Register 8	IDR8	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A41_H$	$007C41_H$				
$007A42_H$	$007C42_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A43_H$	$007C43_H$				
$007A44_H$	$007C44_H$	ID Register 9	IDR9	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A45_H$	$007C45_H$				
$007A46_H$	$007C46_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A47_H$	$007C47_H$				
$007A48_H$	$007C48_H$	ID Register 10	IDR10	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A49_H$	$007C49_H$				
$007A4A_H$	$007C4A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4B_H$	$007C4B_H$				
$007A4C_H$	$007C4C_H$	ID Register 11	IDR11	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4D_H$	$007C4D_H$				
$007A4E_H$	$007C4E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4F_H$	$007C4F_H$				
$007A50_H$	$007C50_H$	ID Register 12	IDR12	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A51_H$	$007C51_H$				
$007A52_H$	$007C52_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A53_H$	$007C53_H$				
$007A54_H$	$007C54_H$	ID Register 13	IDR13	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A55_H$	$007C55_H$				
$007A56_H$	$007C56_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A57_H$	$007C57_H$				
$007A58_H$	$007C58_H$	ID Register 14	IDR14	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A59_H$	$007C59_H$				
$007A5A_H$	$007C5A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5B_H$	$007C5B_H$				
$007A5C_H$	$007C5C_H$	ID Register 15	IDR15	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5D_H$	$007C5D_H$				
$007A5E_H$	$007C5E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5F_H$	$007C5F_H$				

11.3 DC Characteristics

($T_A = -40°C$ to $+105°C$, $V_{CC} = 5.0\ V \pm 10\%$, $f_{CP} \leq 24$ MHz, $V_{SS} = AV_{SS} = 0\ V$)

Parameter	Symbol	Pin	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Input H voltage (At V_{CC} = 5 V ± 10%)	V_{IHS}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	Port inputs if CMOS hysteresis input levels are selected (except P12, P44, P45, P46, P47, P50, P82, P85)
	V_{IHA}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	Port inputs if Automotive input levels are selected
	V_{IHT}	—	—	2.0	—	V_{CC} + 0.3	V	Port inputs if TTL input levels are selected
	V_{IHS}	—	—	0.7 V_{CC}	—	V_{CC} + 0.3	V	P12, P50, P82, P85 inputs if CMOS input levels are selected
	V_{IHI}	—	—	0.7 V_{CC}	—	V_{CC} + 0.3	V	P44, P45, P46, P47 inputs if CMOS hysteresis input levels are selected
	V_{IHR}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	$\overline{RST}$ input pin (CMOS hysteresis)
	V_{IHM}	—	—	V_{CC} − 0.3	—	V_{CC} + 0.3	V	MD input pin
Input L voltage (At V_{CC} = 5 V ± 10%)	V_{ILS}	—	—	V_{SS} − 0.3	—	0.2 V_{CC}	V	Port inputs if CMOS hysteresis input levels are selected (except P12, P44, P45, P46, P47, P50, P82, P85)
	V_{ILA}	—	—	V_{SS} − 0.3	—	0.5 V_{CC}	V	Port inputs if Automotive input levels are selected
	V_{ILT}	—	—	V_{SS} − 0.3	—	0.8	V	Port inputs if TTL input levels are selected
	V_{ILS}	—	—	V_{SS} − 0.3	—	0.3 V_{CC}	V	P12, P50, P82, P85 inputs if CMOS input levels are selected
	V_{ILI}	—	—	V_{SS} − 0.3	—	0.3 V_{CC}	V	P44, P45, P46, P47 inputs if CMOS hysteresis input levels are selected
	V_{ILR}	—	—	V_{SS} − 0.3	—	0.2 V_{CC}	V	$\overline{RST}$ input pin (CMOS hysteresis)
	V_{ILM}	—	—	V_{SS} − 0.3	—	V_{SS} + 0.3	V	MD input pin
Output H voltage	V_{OH}	Normal outputs	V_{CC} = 4.5 V, I_{OH} = −4.0 mA	V_{CC} − 0.5	—	—	V	
Output H voltage	V_{OHI}	I^2C current outputs	V_{CC} = 4.5 V, I_{OH} = −3.0 mA	V_{CC} − 0.5	—	—	V	
Output L voltage	V_{OL}	Normal outputs	V_{CC} = 4.5 V, I_{OL} = 4.0 mA	—	—	0.4	V	
Output L voltage	V_{OLI}	I^2C current outputs	V_{CC} = 4.5 V, I_{OL} = 3.0 mA	—	—	0.4	V	

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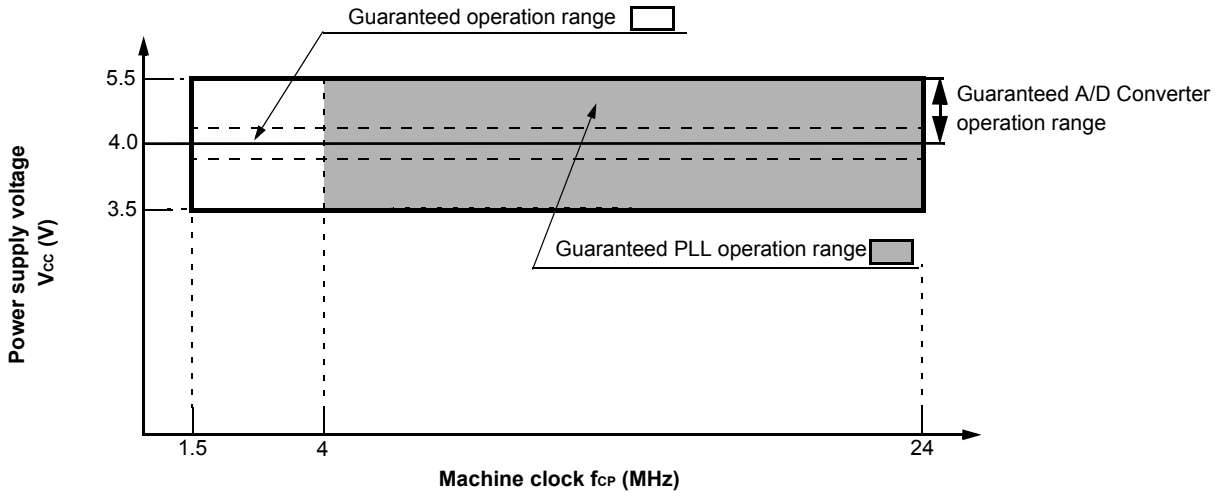
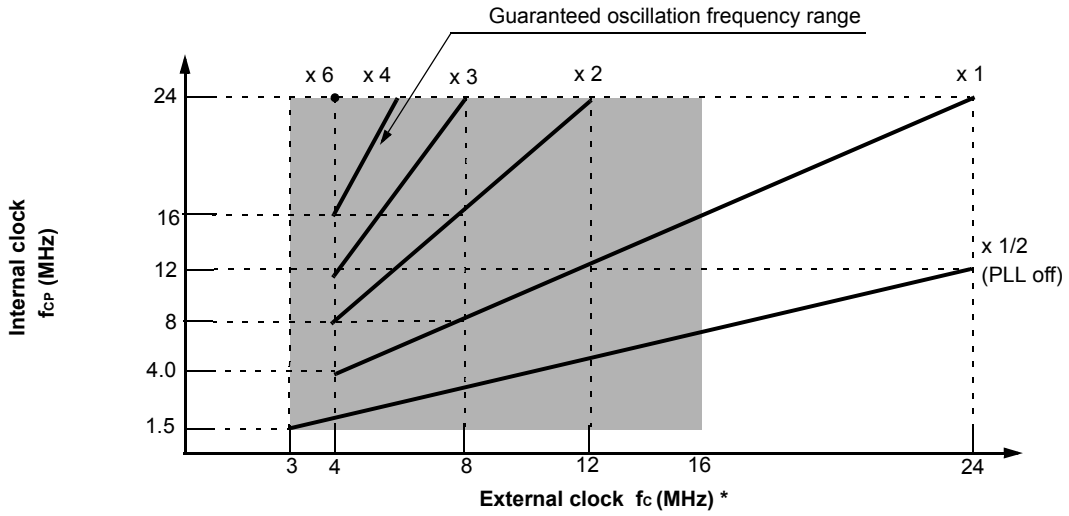
Guaranteed PLL operation range



Guaranteed operation range of MB90340E series



* : When using a crystal oscillator or ceramic oscillator, the maximum oscillation clock frequency is 16 MHz

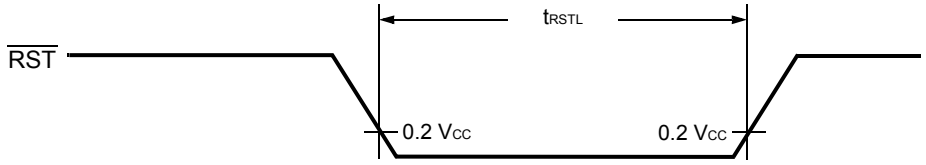
11.4.2 Reset Standby Input

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0.0 V)

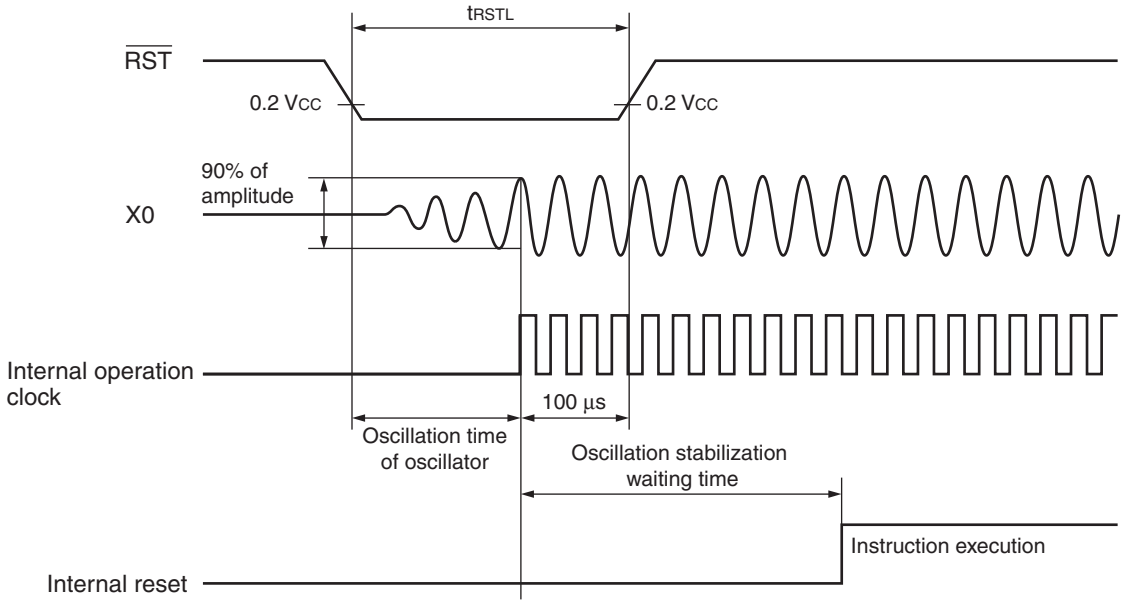
Parameter	Symbol	Pin	Value		Unit	Remarks
			Min	Max		
Reset input time	t_{RSTL}	$\overline{RST}$	500	—	ns	Under normal operation
			Oscillation time of oscillator* + 100 µs	—	µs	In Stop mode, Sub Clock mode, Sub Sleep mode and Watch mode
			100	—	µs	In Time Timer mode

* : The oscillation time of the oscillator is the time it takes for the amplitude of the oscillations to reach 90%. For crystal oscillators, this time is between several ms and several tens of ms, for ceramic oscillators the time is between several hundred µs and several ms, and for an external clock, the time is 0 ms.

- **Under normal operation:**



- **In Stop mode, Sub Clock mode, Sub Sleep mode, Watch mode:**

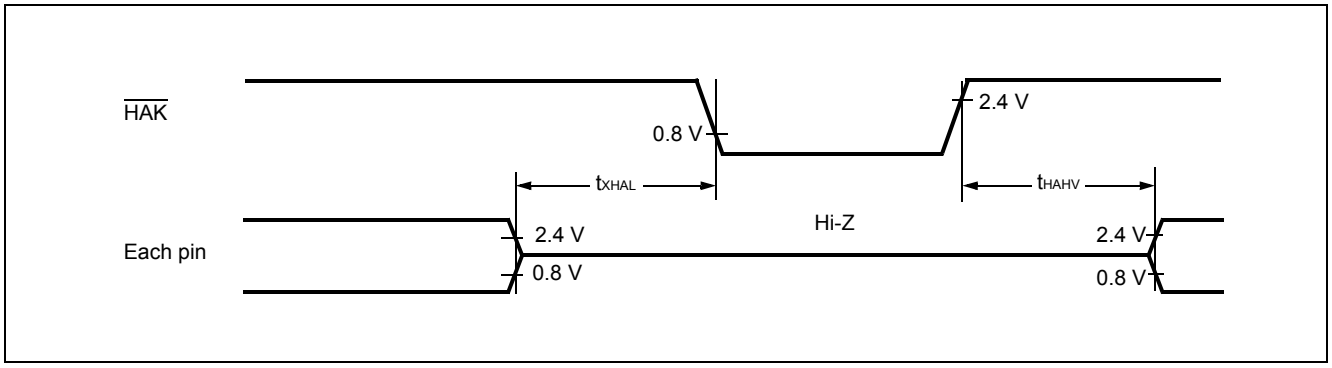


11.4.8 Hold Timing

($T_A = -40°C$ to $+105°C$, $V_{CC} = 5.0\ V \pm 10\%$, $V_{SS} = 0.0\ V$, $f_{CP} \leq 24$ MHz)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Pin floating → $\overline{HAK}$ ↓ time	t_{XHAL}	$\overline{HAK}$	—	30	t_{CP}	ns
$\overline{HAK}$ ↑ time → Pin valid time	t_{HAHV}	$\overline{HAK}$		t_{CP}	2 t_{CP}	ns

Note: : There is more than 1 cycle from when HRQ reads in until the $\overline{HAK}$ is changed.

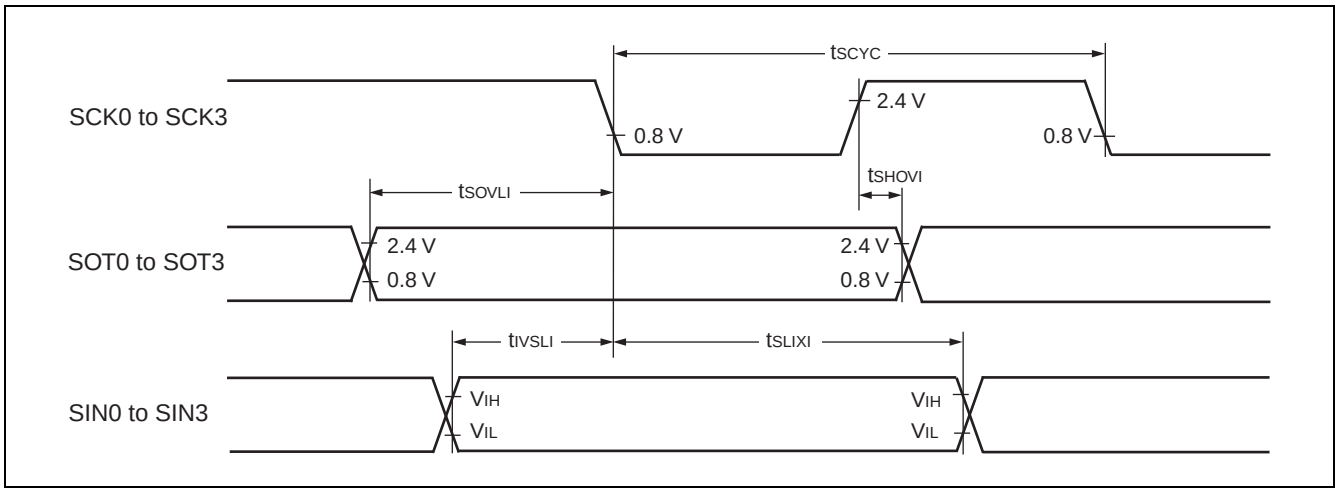


■ **Bit setting: ESCR:SCES = 0, ECCR:SCDE = 1**

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are C_L = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCK0 to SCK3, SOT0 to SOT3		−50	+50	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK0 to SCK3, SIN0 to SIN3		t_{CP} + 80	—	ns
SCK ↓ → Valid SIN hold time	t_{SLIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT → SCK ↓ delay time	t_{SOVLI}	SCK0 to SCK3, SOT0 to SOT3		3 t_{CP} − 70	—	ns

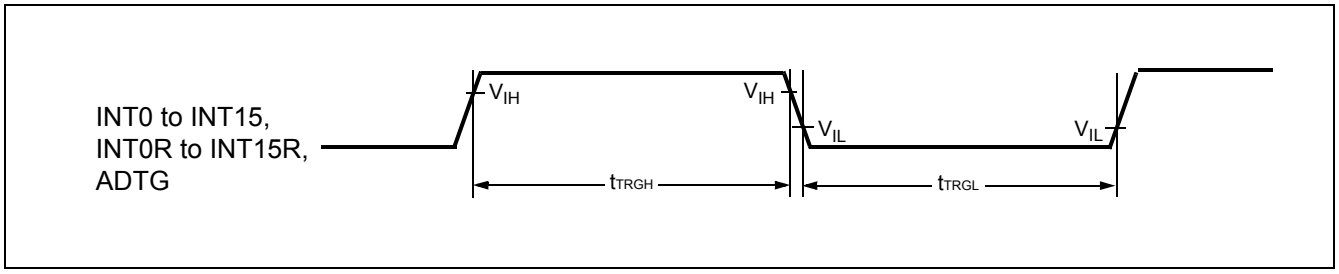
Note:
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to "Clock Timing".



11.4.10 Trigger Input Timing

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0.0 V)

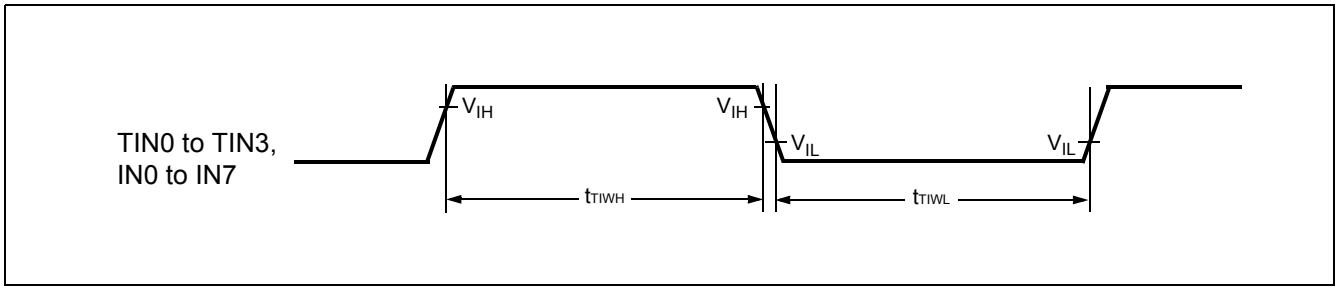
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TRGH} t_{TRGL}	INT0 to INT15, INT0R to INT15R, ADTG	—	5 t_{CP}	—	ns



11.4.11 Timer Related Resource Input Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

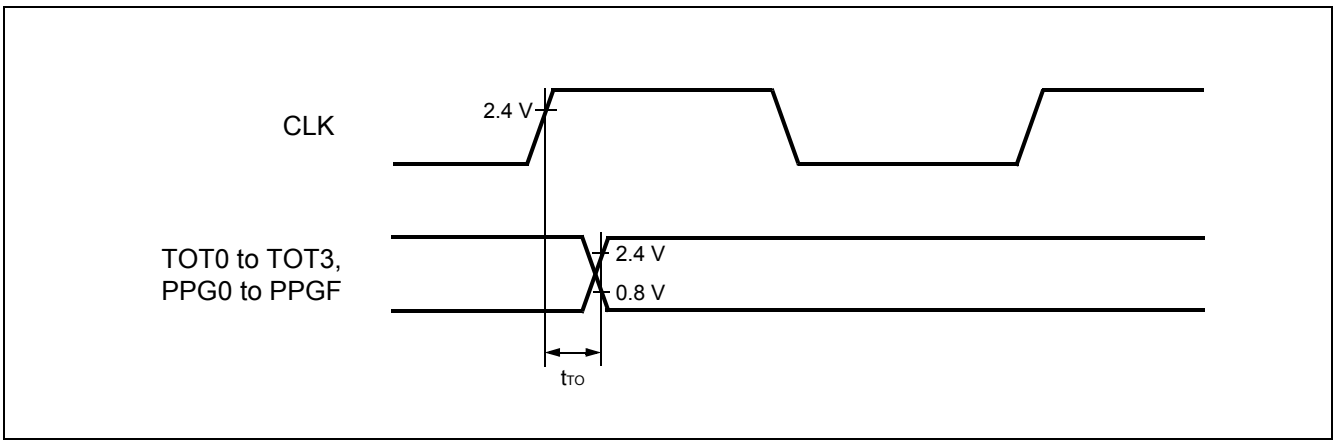
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TIWH} t_{TIWL}	TIN0 to TIN3, IN0 to IN7	—	4 t_{CP}	—	ns



11.4.12 Timer Related Resource Output Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0.0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
CLK ↑ → T_{OUT} change time	t_{TO}	TOT0 to TOT3, PPG0 to PPGF	—	30	—	ns



11.4.13 I^2C Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

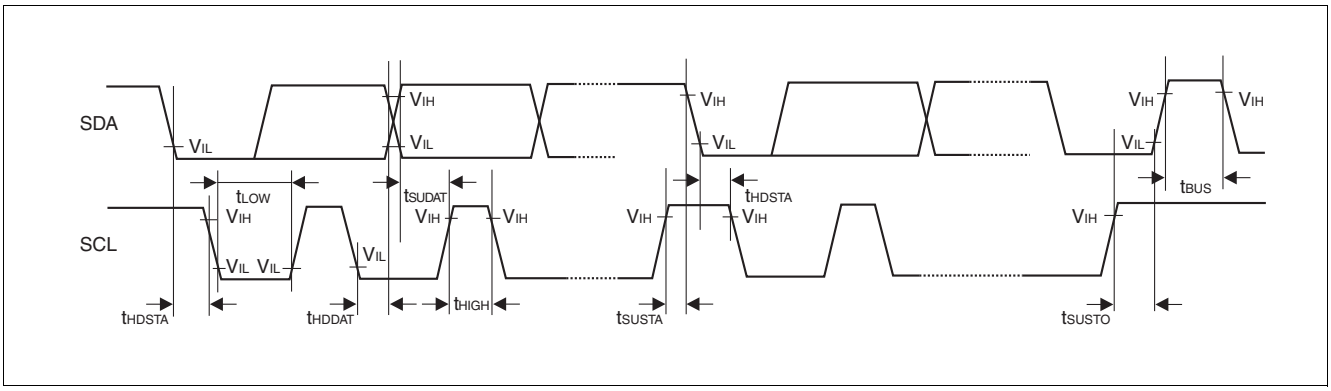
Parameter	Symbol	Condition	Standard-mode		Fast-mode*1		Unit
			Min	Max	Min	Max	
SCL clock frequency	f_{SCL}	R = 1.7 kΩ, C = 50 pF*2	0	100	0	400	kHz
Hold time (repeated) START condition SDA↓ → SCL ↓	t_{HDSTA}		4.0	—	0.6	—	µs
"L" width of the SCL clock	t_{LOW}		4.7	—	1.3	—	µs
"H" width of the SCL clock	t_{HIGH}		4.0	—	0.6	—	µs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t_{SUSTA}		4.7	—	0.6	—	µs
Data hold time SCL ↓ → SDA ↓ ↑	t_{HDDAT}		0	3.45*3	0	0.9*4	µs
Data set-up time SDA ↓ ↑ → SCL ↑	t_{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t_{SUSTO}		4.0	—	0.6	—	µs
Bus free time between a STOP and START condition	t_{BUS}		4.7	—	1.3	—	µs

*1:For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2:R,C: Pull-up resistor and load capacitor of the SCL and SDA lines.

*3:The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4:A Fast-mode I^2C-bus device can be used in a Standard-mode I^2C-bus system, but the requirement $t_{SUDAT} \geq 250$ ns must then be met.



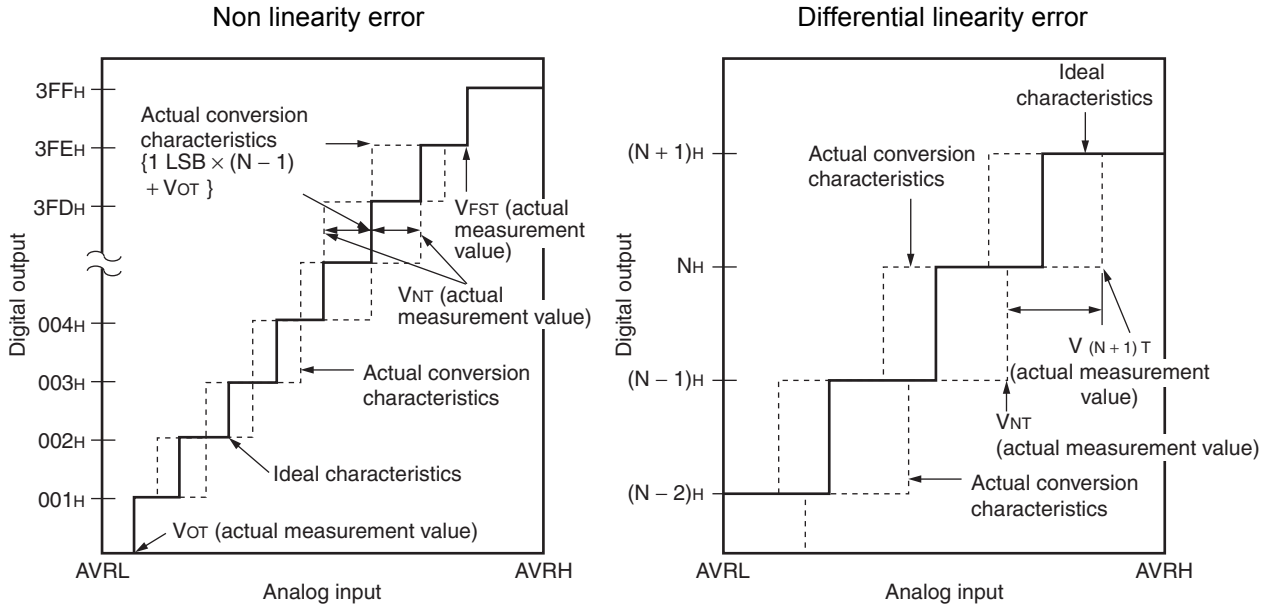
11.5 A/D Converter

(T_A = −40°C to +105°C, 3.0 V≤ AVRH − AVRL, V_{CC} = AV_{CC} = 5.0 V ± 10%, f_{CP}≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	—	—	±3.0	LSB	
Nonlinearity error	—	—	—	—	±2.5	LSB	
Differential nonlinearity error	—	—	—	—	±1.9	LSB	
Zero reading voltage	V_{OT}	AN0 to AN23	AVRL − 1.5 × LSB	AVRL + 0.5 × LSB	AVRL + 2.5 × LSB	V	
Full scale reading voltage	V_{FST}	AN0 to AN23	AVRH − 3.5 × LSB	AVRH − 1.5 × LSB	AVRH + 0.5 × LSB	V	
Compare time	—	—	1.0	—	16500	µs	4.5 V≤ AV_{CC}≤ 5.5 V
			2.0				4.0 V≤ AV_{CC} < 4.5 V
Sampling time	—	—	0.5	—	∞	µs	4.5 V≤ AV_{CC}≤ 5.5 V
			1.2				4.0 V≤ AV_{CC} < 4.5 V
Analog port input current	I_{AIN}	AN0 to AN23	−0.3	—	+0.3	µA	
Analog input voltage range	V_{AIN}	AN0 to AN23	AVRL	—	AVRH	V	
Reference voltage range	—	AVRH	AVRL + 2.7	—	AV_{CC}	V	
	—	AVRL	0	—	AVRH − 2.7	V	
Power supply current	I_A	AV_{CC}	—	3.5	7.5	mA	
	I_{AH}	AV_{CC}	—	—	5	µA	*
Reference voltage current	I_R	AVRH	—	600	900	µA	
	I_{RH}	AVRH	—	—	5	µA	*
Offset between input channels	—	AN0 to AN23	—	—	4	LSB	

*: If the A/D convertor is not operating, a current when CPU is stopped is applicable (V_{CC} = AV_{CC} = AVRH = 5.0 V) .
Note: : The accuracy gets worse as |AVRH − AVRL| becomes smaller.

(Continued)



$$\text{Non linearity error of digital output N} = \frac{V_{NT} - \{1\ \text{LSB} \times (N - 1) + V_{OT}\}}{1\ \text{LSB}}\ [\text{LSB}]$$

$$\text{Differential linearity error of digital output N} = \frac{V_{(N+1)T} - V_{NT}}{1\ \text{LSB}} - 1\ \text{LSB}\ [\text{LSB}]$$

$$1\ \text{LSB} = \frac{V_{FST} - V_{OT}}{1022}\ [\text{V}]$$

N : Value of the digital output from the A/D converter
V_{OT} : Voltage at which digital output transits from "000_H" to "001_H."
V_{FST} : Voltage at which digital output transits from "$3FE_H$" to "$3FF_H$."

11.7 Notes on A/D Converter Section

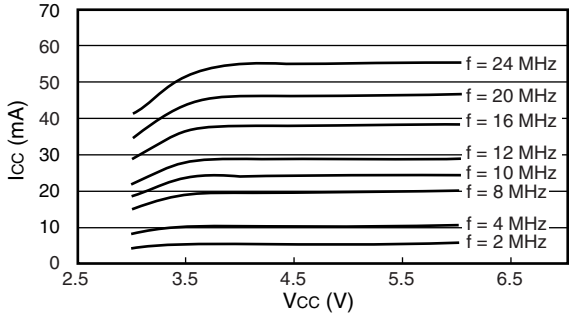
Use the device with external circuits of the following output impedance for analog inputs :

Recommended output impedance of external circuits are : Approx. 1.5 kΩ or lower (4.0 V≤ AV_{CC}≤ 5.5 V, sampling period = 0.5 µs)

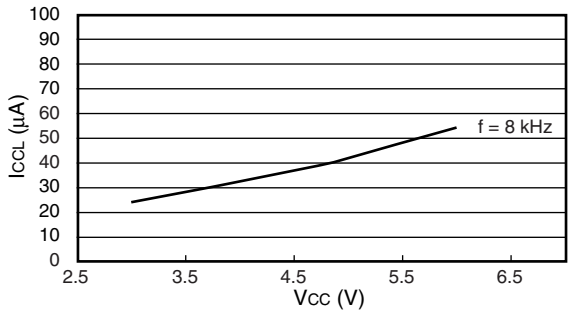
If an external capacitor is used, in consideration of the capacitive voltage dividing effect between the external capacitor and the internal on-chip capacitor, it is recommended that the capacitance of the external capacitor be several thousand times greater than the capacitance of the internal capacitor.

■ MB90347E, MB90347ES, MB90347CE, MB90347CES

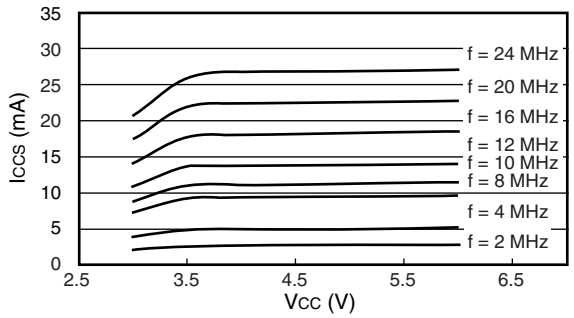
$I_{CC} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



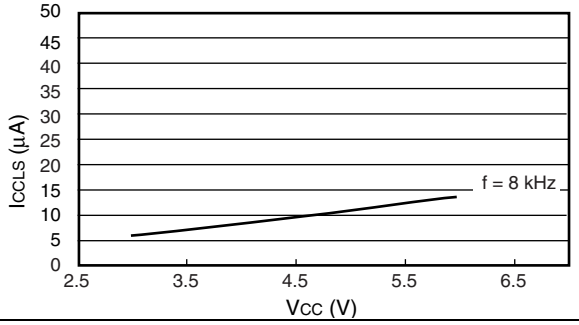
$I_{CCL} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



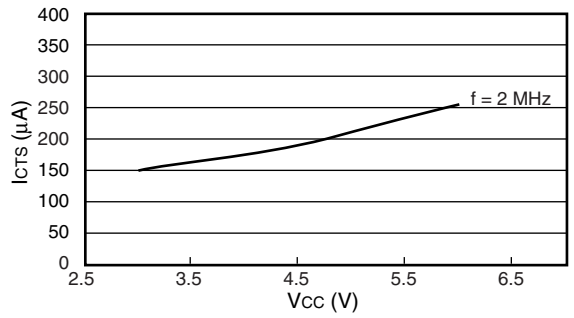
$I_{CCS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



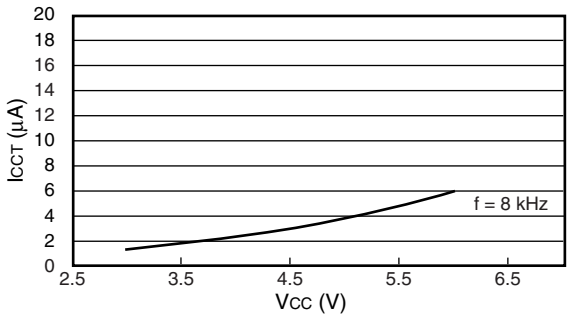
$I_{CCLS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



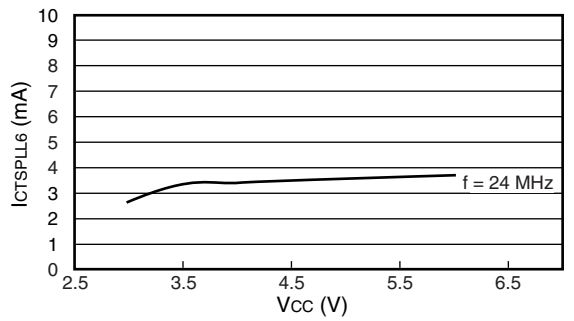
$I_{CTS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



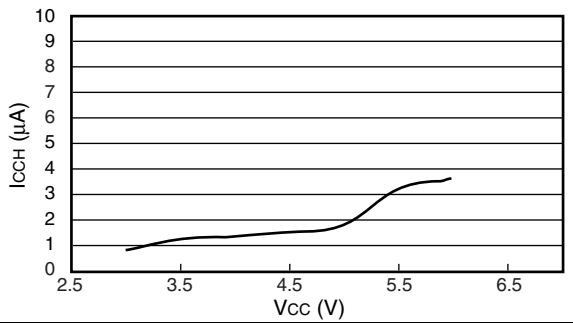
$I_{CCT} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



$I_{CTSPLL6} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



$I_{CCH} - V_{CC}$
$T_A = +25°C$, stopped



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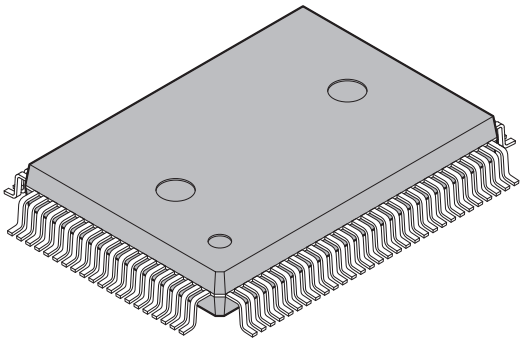
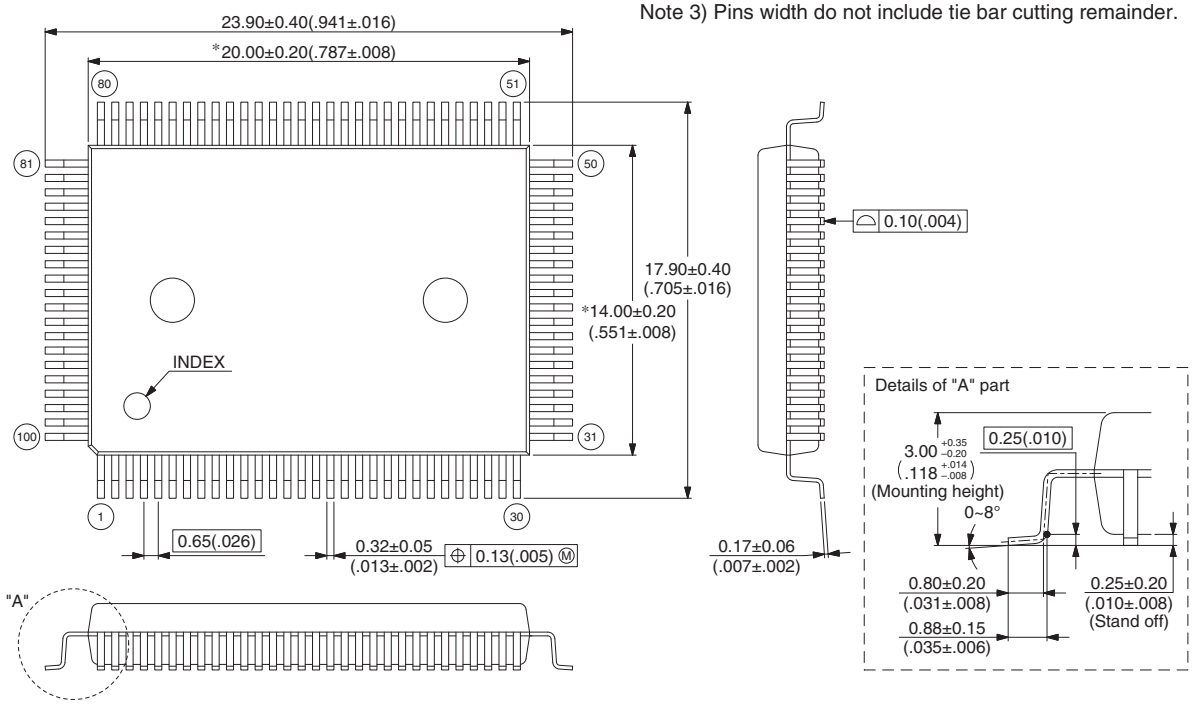
100-pin plastic QFP		
	Lead pitch	0.65 mm
	Package width × package length	14.00 × 20.00 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	3.35 mm MAX
	Code (Reference)	P-QFP100-14×20-0.65
(FPT-100P-M06)		

100-pin plastic QFP
(FPT-100P-M06)

Note 1) * : These dimensions do not include resin protrusion.
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.



Dimensions in mm (inches).
Note: The values in parentheses are reference values.

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