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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-450ere2

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Part Number			
Parameter	MB90V340E-101, MB90V340E-102	MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
A/D Converter	24 input channels	Devices with a C suffix in the part number : 24 channels Devices without a C suffix in the part number : 16 channels	
	10-bit or 8-bit resolution Conversion time : Min 3 μs include sample time (per one channel)		
16-bit Reload Timer (4 channels)	Operation clock frequency : fsys/2 ¹ , fsys/2 ³ , fsys/2 ⁵ (fsys = Machine clock frequency) Supports External Event Count function		
16-bit Free-run Timer (2 channels)	Generates an interrupt signal on overflow Supports Timer Clear when the output compare finds a match Operation clock freq. : fsys, fsys/2 ¹ , fsys/2 ² , fsys/2 ³ , fsys/2 ⁴ , fsys/2 ⁵ , fsys/2 ⁶ , fsys/2 ⁷ (fsys = Machine clock freq.) Free-run Timer 0 (clock input FRCK0) corresponds to ICU 0/1/2/3, OCU 0/1/2/3 Free-run Timer 1 (clock input FRCK1) corresponds to ICU 4/5/6/7, OCU 4/5/6/7		
16-bit Output Compare (8 channels)	Generates an interrupt signal when one of the 16-bit free-run timer matches the output compare register A pair of compare registers can be used to generate an output signal.		
16-bit Input Capture (8 channels)	Captures the value of the 16-bit free-run timer and generates an interrupt when triggered by a pin input (rising edge, falling edge, or both rising and falling edges).		
8/16-bit Programmable Pulse Generator	8 channels (16-bit) /16 channels (8-bit) Sixteen 8-bit reload counters Sixteen 8-bit reload registers for L pulse width Sixteen 8-bit reload registers for H pulse width		
	Supports 8-bit and 16-bit operation modes A pair of 8-bit reload counters can be configured as one 16-bit reload counter or as 8-bit prescaler plus 8-bit reload counter Operating clock freq. : fsys, fsys/2 ¹ , fsys/2 ² , fsys/2 ³ , fsys/2 ⁴ or 128 μs@fosc = 4 MHz (fsys = Machine clock frequency, fosc = Oscillation clock frequency)		
CAN Interface	3 channels	2 channels : MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S) 1 channel : MB90F346E(S), MB90F346CE(S), MB90F347E(S), MB90F347CE(S), MB90F349E(S), MB90F349CE(S)	2 channels : MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S) 1 channel : MB90346E(S), MB90346CE(S), MB90347E(S), MB90347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S)
	Conforms to CAN Specification Version 2.0 Part A and B Automatic re-transmission in case of error Automatic transmission in response to Remote Frames Prioritized 16 message buffers for data and ID's Supports multiple messages Flexible configuration of acceptance filtering : Full bit compare/Full bit mask/Two partial bit masks Supports up to 1 Mbps		

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V _{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 μF .
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

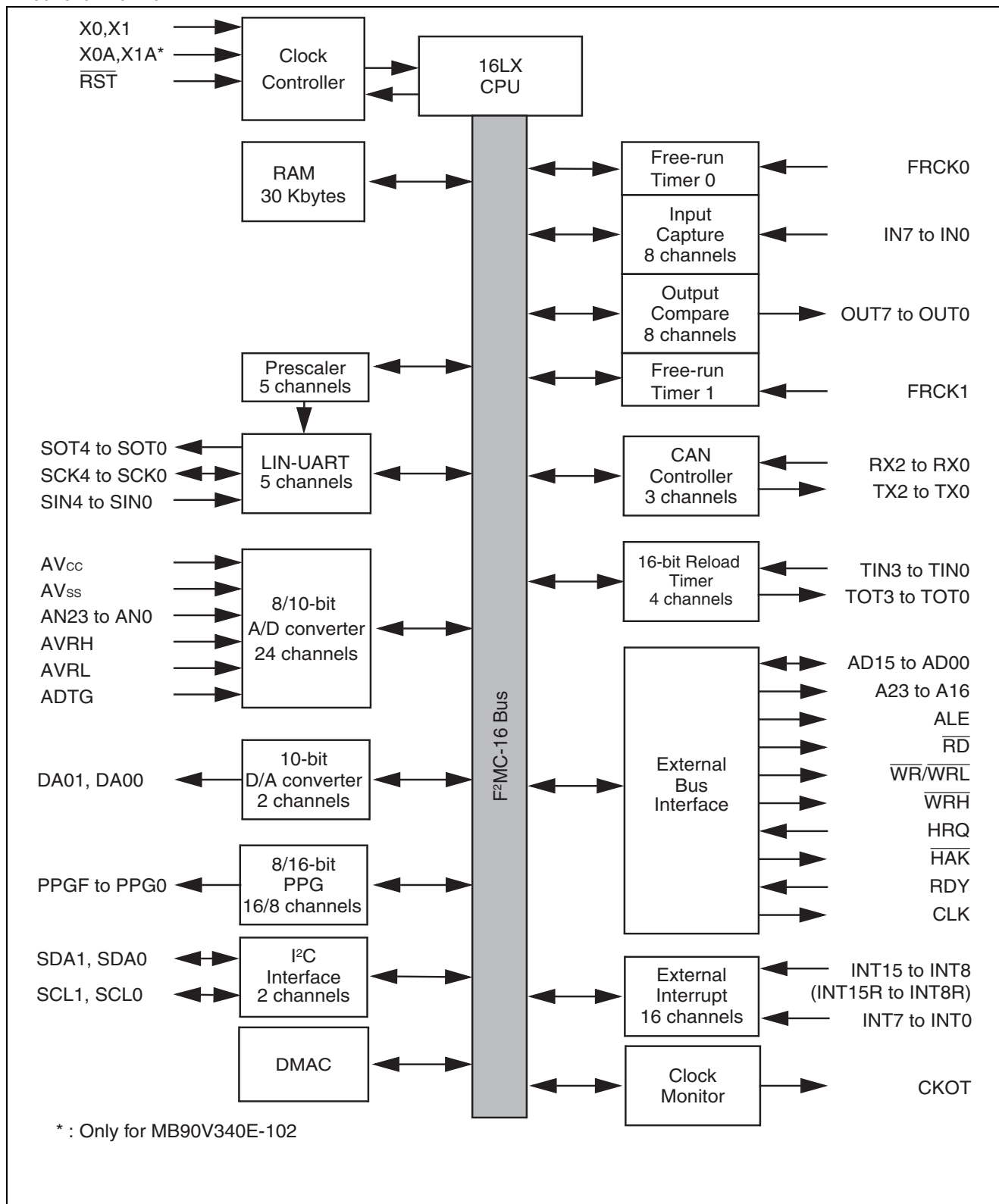
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Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
19	17	P43	F	General purpose I/O pin.
		IN7		Trigger input pin for input capture.
		TX1		TX Output pin for CAN1 (MB90341E/342E/F342E/F345E only)
20	18	P44	H	General purpose I/O pin.
		SDA0		Serial data I/O pin for I ² C (devices with a C suffix in the part number)
		FRCK0		Input pin for the 16-bit Free-run Timer 0
21	19	P45	H	General purpose I/O pin.
		SCL0		Serial clock I/O pin for I ² C (devices with a C suffix in the part number)
		FRCK1		Input pin for the 16-bit Free-run Timer
22	20	P46	H	General purpose I/O pin.
		SDA1		Serial data I/O pin for I ² C (devices with a C suffix in the part number)
23	21	P47	H	General purpose I/O pin.
		SCL1		Serial clock I/O pin for I ² C (devices with a C suffix in the part number)
24	22	P50	O	General purpose I/O pin.
		AN8		Analog input pin for the A/D converter
		SIN2		Serial data input pin for UART2
25	23	P51	I	General purpose I/O pin.
		AN9		Analog input pin for the A/D converter
		SOT2		Serial data output pin for UART2
26	24	P52	I	General purpose I/O pin.
		AN10		Analog input pin for the A/D converter
		SCK2		Clock I/O pin for UART2
27	25	P53	I	General purpose I/O pin.
		AN11		Analog input pin for the A/D converter
		TIN3		Event input pin for the reload timer
28	26	P54	I	General purpose I/O pin.
		AN12		Analog input pin for the A/D converter
		TOT3		Output pin for the reload timer
29	27	P55	I	General purpose I/O pin.
		AN13		Analog input pin for the A/D converter
30, 31	28, 29	P56, P57	J	General purpose I/O pins.
		AN14, AN15		Analog input pins for the A/D converter
32	30	AV _{CC}	K	Analog power input pin for the A/D Converter

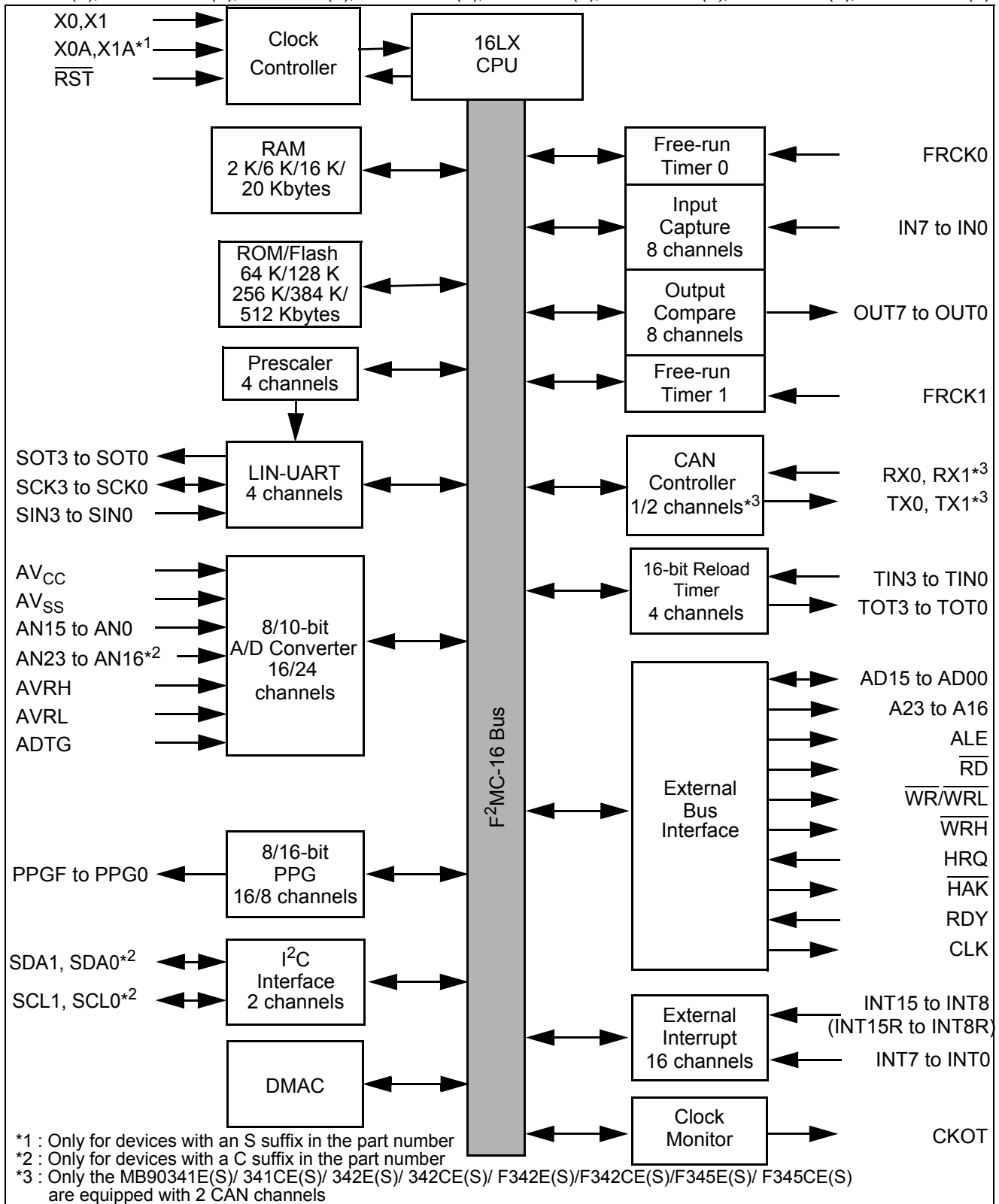
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6. Block Diagrams

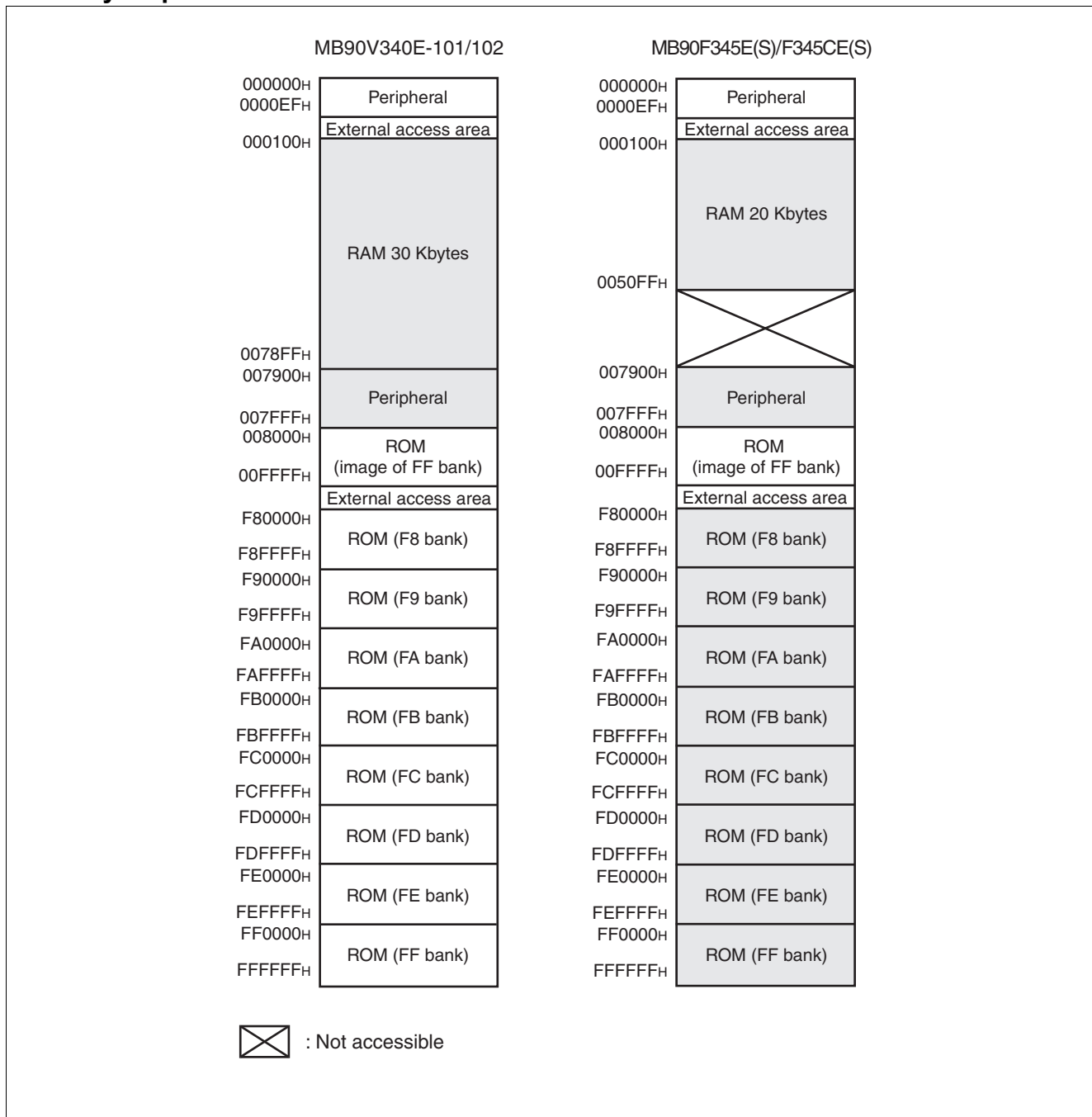
■ MB90V340E-101/102



■ MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90346E(S), MB90346CE(S), MB90F346E(S), MB90F346CE(S), MB90347E(S), MB90347CE(S), MB90F347E(S), MB90F347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S), MB90F349E(S), MB90F349CE(S)



7. Memory Map



List of Message Buffers (DLC Registers and Data Registers) (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007A80 _H to 007A87 _H	007C80 _H to 007C87 _H	Data Register 0 (8 bytes)	DTR0	R/W	XXXXXXXX _B to XXXXXXXX _B
007A88 _H to 007A8F _H	007C88 _H to 007C8F _H	Data Register 1 (8 bytes)	DTR1	R/W	XXXXXXXX _B to XXXXXXXX _B
007A90 _H to 007A97 _H	007C90 _H to 007C97 _H	Data Register 2 (8 bytes)	DTR2	R/W	XXXXXXXX _B to XXXXXXXX _B
007A98 _H to 007A9F _H	007C98 _H to 007C9F _H	Data Register 3 (8 bytes)	DTR3	R/W	XXXXXXXX _B to XXXXXXXX _B
007AA0 _H to 007AA7 _H	007CA0 _H to 007CA7 _H	Data Register 4 (8 bytes)	DTR4	R/W	XXXXXXXX _B to XXXXXXXX _B
007AA8 _H to 007AAF _H	007CA8 _H to 007CAF _H	Data Register 5 (8 bytes)	DTR5	R/W	XXXXXXXX _B to XXXXXXXX _B
007AB0 _H to 007AB7 _H	007CB0 _H to 007CB7 _H	Data Register 6 (8 bytes)	DTR6	R/W	XXXXXXXX _B to XXXXXXXX _B
007AB8 _H to 007ABF _H	007CB8 _H to 007CBF _H	Data Register 7 (8 bytes)	DTR7	R/W	XXXXXXXX _B to XXXXXXXX _B
007AC0 _H to 007AC7 _H	007CC0 _H to 007CC7 _H	Data Register 8 (8 bytes)	DTR8	R/W	XXXXXXXX _B to XXXXXXXX _B
007AC8 _H to 007ACF _H	007CC8 _H to 007CCF _H	Data Register 9 (8 bytes)	DTR9	R/W	XXXXXXXX _B to XXXXXXXX _B
007AD0 _H to 007AD7 _H	007CD0 _H to 007CD7 _H	Data Register 10 (8 bytes)	DTR10	R/W	XXXXXXXX _B to XXXXXXXX _B
007AD8 _H to 007ADF _H	007CD8 _H to 007CDF _H	Data Register 11 (8 bytes)	DTR11	R/W	XXXXXXXX _B to XXXXXXXX _B
007AE0 _H to 007AE7 _H	007CE0 _H to 007CE7 _H	Data Register 12 (8 bytes)	DTR12	R/W	XXXXXXXX _B to XXXXXXXX _B
007AE8 _H to 007AEF _H	007CE8 _H to 007CEF _H	Data Register 13 (8 bytes)	DTR13	R/W	XXXXXXXX _B to XXXXXXXX _B

10. Interrupt Factors, Interrupt Vectors, Interrupt Control Register

Interrupt cause	EI ² OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
Reset	N	—	#08	FFFFDC _H	—	—
INT9 instruction	N	—	#09	FFFFD8 _H	—	—
Exception	N	—	#10	FFFFD4 _H	—	—
CAN 0 RX	N	—	#11	FFFFD0 _H	ICR00	0000B0 _H
CAN 0 TX/NS	N	—	#12	FFFFCC _H		
CAN 1 RX / Input Capture 6	Y1	—	#13	FFFFC8 _H	ICR01	0000B1 _H
CAN 1 TX/NS / Input Capture 7	Y1	—	#14	FFFFC4 _H		
CAN 2 RX / I ² C0	N	—	#15	FFFFC0 _H	ICR02	0000B2 _H
CAN 2 TX/NS	N	—	#16	FFFFBC _H		
16-bit Reload Timer 0	Y1	0	#17	FFFFB8 _H	ICR03	0000B3 _H
16-bit Reload Timer 1	Y1	1	#18	FFFFB4 _H		
16-bit Reload Timer 2	Y1	2	#19	FFFFB0 _H	ICR04	0000B4 _H
16-bit Reload Timer 3	Y1	—	#20	FFFFAC _H		
PPG 0/1/4/5	N	—	#21	FFFFA8 _H	ICR05	0000B5 _H
PPG 2/3/6/7	N	—	#22	FFFFA4 _H		
PPG 8/9/C/D	N	—	#23	FFFFA0 _H	ICR06	0000B6 _H
PPG A/B/E/F	N	—	#24	FFFF9C _H		
Time Base Timer	N	—	#25	FFFF98 _H	ICR07	0000B7 _H
External Interrupt 0 to 3, 8 to 11	Y1	3	#26	FFFF94 _H		
Watch Timer	N	—	#27	FFFF90 _H	ICR08	0000B8 _H
External Interrupt 4 to 7, 12 to 15	Y1	4	#28	FFFF8C _H		
A/D Converter	Y1	5	#29	FFFF88 _H	ICR09	0000B9 _H
Free-run Timer 0 / Free-run Timer 1	N	—	#30	FFFF84 _H		
Input Capture 4/5 / I ² C1	Y1	6	#31	FFFF80 _H	ICR10	0000BA _H
Output Compare 0/1/4/5	Y1	7	#32	FFFF7C _H		
Input Capture 0 to 3	Y1	8	#33	FFFF78 _H	ICR11	0000BB _H
Output Compare 2/3/6/7	Y1	9	#34	FFFF74 _H		
UART 0 RX	Y2	10	#35	FFFF70 _H	ICR12	0000BC _H
UART 0 TX	Y1	11	#36	FFFF6C _H		
UART 1 RX / UART 3 RX	Y2	12	#37	FFFF68 _H	ICR13	0000BD _H
UART 1 TX / UART 3 TX	Y1	13	#38	FFFF64 _H		

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Interrupt cause	EI ² OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
UART 2 RX / UART 4 RX	Y2	14	#39	FFFF60 _H	ICR14	0000BE _H
UART 2 TX / UART 4 TX	Y1	15	#40	FFFF5C _H		
Flash Memory	N	—	#41	FFFF58 _H	ICR15	0000BF _H
Delayed Interrupt	N	—	#42	FFFF54 _H		

Y1 : Usable

Y2 : Usable, with EI²OS stop function

N : Unusable

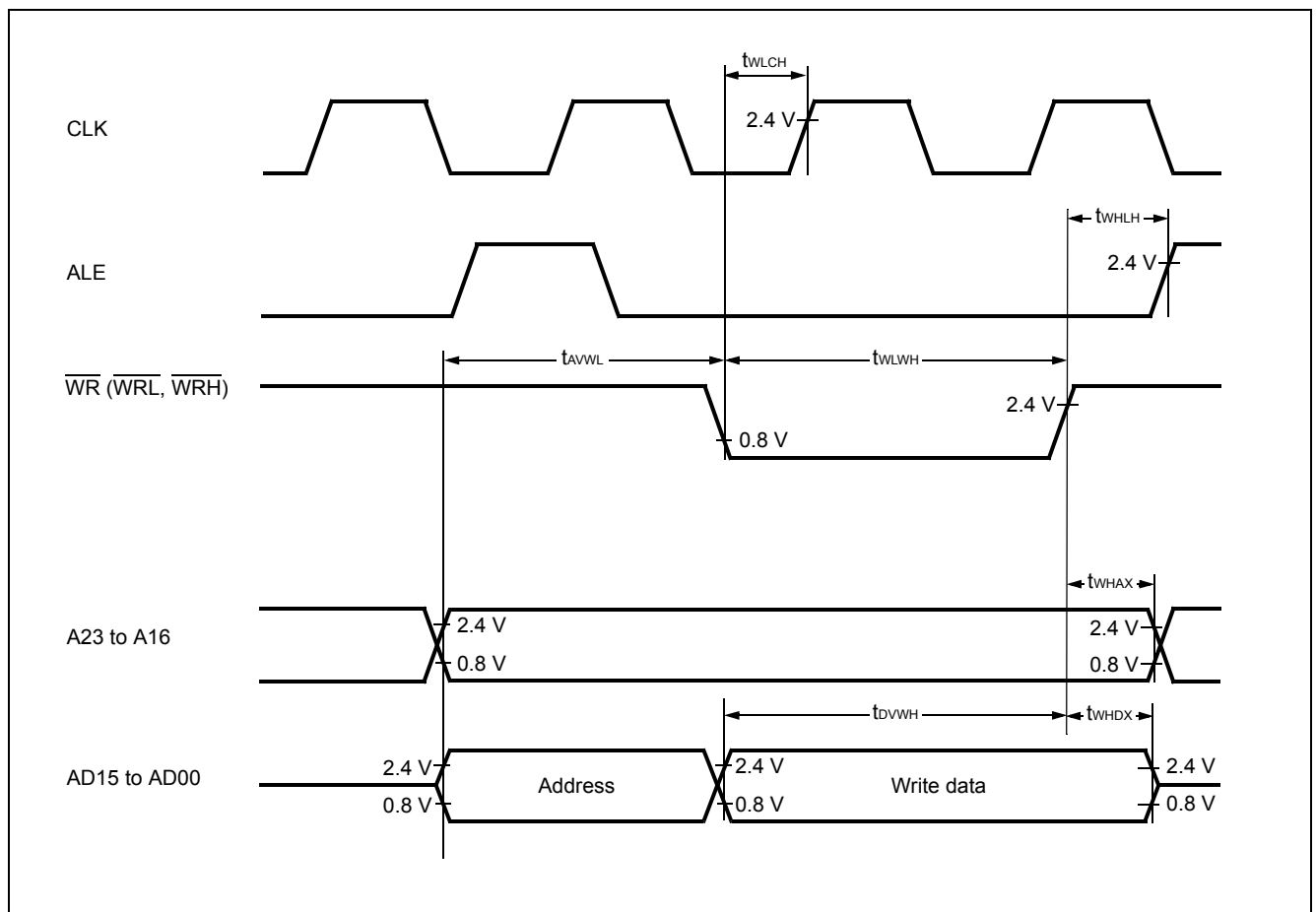
Note:

- The peripheral resources sharing the ICR register have the same interrupt level.
- When two peripheral resources share the ICR register, only one can use Extended Intelligent I/O Service at a time.
- When either of the two peripheral resources sharing the ICR register specifies Extended Intelligent I/O Service, the other one cannot use interrupts.

11.4.6 Bus Timing (Write)

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Valid address $\rightarrow \overline{\text{WR}} \downarrow$ time	t_{AVWL}	A23 to A16, AD15 to AD00, $\overline{\text{WR}}$	—	$t_{CP} - 15$	—	ns
$\overline{\text{WR}}$ pulse width	t_{WLWH}	$\overline{\text{WR}}$		$3 t_{CP}/2 - 20$	—	ns
Valid data output $\rightarrow \overline{\text{WR}} \uparrow$ time	t_{DVWH}	AD15 to AD00, $\overline{\text{WR}}$		$3 t_{CP}/2 - 20$	—	ns
$\overline{\text{WR}} \uparrow \rightarrow$ Data hold time	t_{WHDX}	AD15 to AD00, $\overline{\text{WR}}$		15	—	ns
$\overline{\text{WR}} \uparrow \rightarrow$ Address valid time	t_{WHAX}	A23 to A16, $\overline{\text{WR}}$		$t_{CP}/2 - 10$	—	ns
$\overline{\text{WR}} \uparrow \rightarrow$ ALE $\uparrow$ time	t_{WHLH}	$\overline{\text{WR}}$, ALE		$t_{CP}/2 - 15$	—	ns
$\overline{\text{WR}} \downarrow \rightarrow$ CLK $\uparrow$ time	t_{WLCH}	$\overline{\text{WR}}$, CLK		$t_{CP}/2 - 15$	—	ns



11.4.9 LIN-UART0/1/2/3

■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0

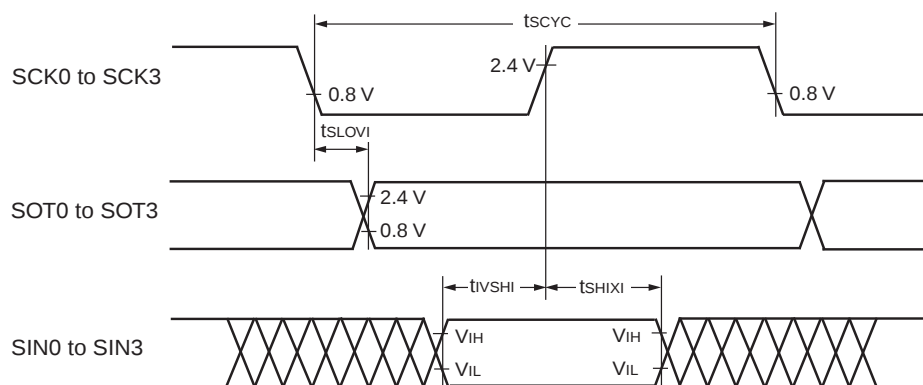
($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock "L" pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$3 t_{CP} - t_R$	—	ns
Serial clock "H" pulse width	t_{SLSH}	SCK0 to SCK3		$t_{CP} + 10$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	$2 t_{CP} + 60$	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXE}	SCK0, SCK1, SIN0 to SIN3		$t_{CP} + 30$	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

Note:

- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “(1) Clock Timing”.

• Internal Shift Clock Mode



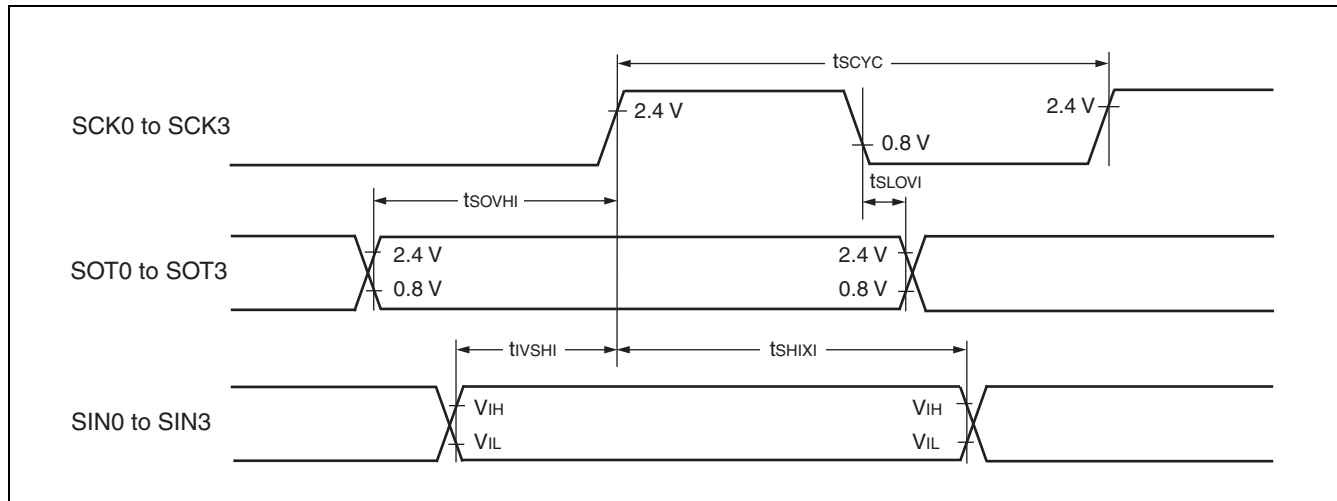
■ Bit setting: ESCR:SCES = 1, ECCR:SCDE = 1

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT $\rightarrow$ SCK $\uparrow$ delay time	t_{SOVHI}	SCK0 to SCK3, SOT0 to SOT3		$3 t_{CP} - 70$	—	ns

Note:

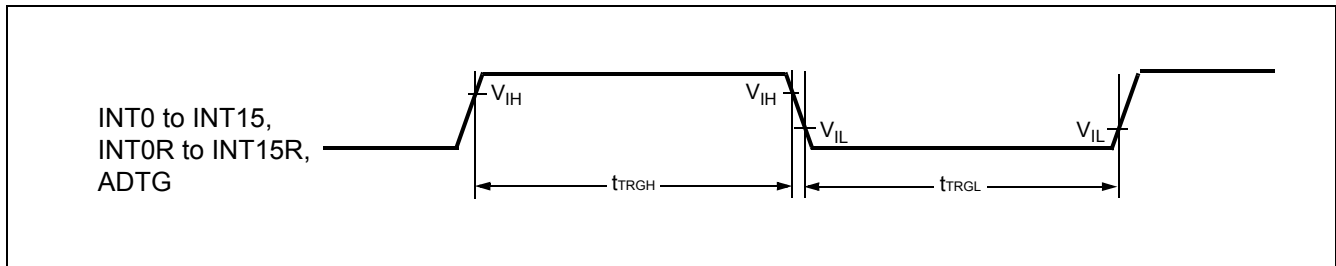
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.



11.4.10 Trigger Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TRGH} t_{TRGL}	INT0 to INT15, INT0R to INT15R, ADTG	—	$5 t_{CP}$	—	ns



11.4.13 I²C Timing

(T_A = -40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

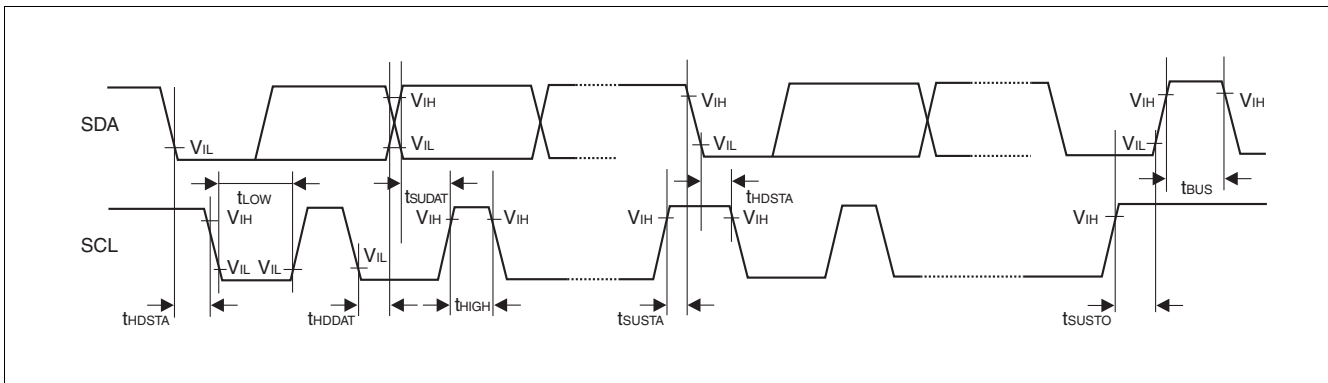
Parameter	Symbol	Condition	Standard-mode		Fast-mode* ¹		Unit
			Min	Max	Min	Max	
SCL clock frequency	f _{SCL}	R = 1.7 kΩ ₂ C = 50 pF* ²	0	100	0	400	kHz
Hold time (repeated) START condition SDA ↓ → SCL ↓	t _{HDSTA}		4.0	—	0.6	—	μs
"L" width of the SCL clock	t _{LOW}		4.7	—	1.3	—	μs
"H" width of the SCL clock	t _{HIGH}		4.0	—	0.6	—	μs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t _{SUSTA}		4.7	—	0.6	—	μs
Data hold time SCL ↓ → SDA ↓ ↑	t _{HDDAT}		0	3.45* ³	0	0.9* ⁴	μs
Data set-up time SDA ↓ ↑ → SCL ↑	t _{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t _{SUSTO}		4.0	—	0.6	—	μs
Bus free time between a STOP and START condition	t _{BUS}		4.7	—	1.3	—	μs

*1: For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.

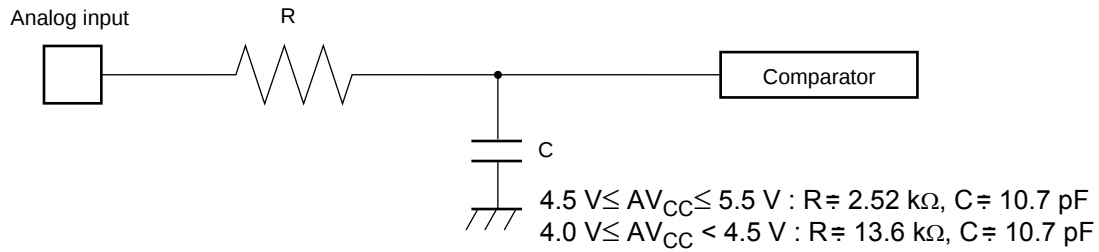
*3: The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4: A Fast-mode I²C-bus device can be used in a Standard-mode I²C-bus system, but the requirement t_{SUDAT} ≥ 250 ns must then be met.



If the output impedance of the external circuit is too high, a sampling period for an analog voltage may be insufficient.

● Analog input circuit model



Note: : Use the values in the figure only as a guideline.

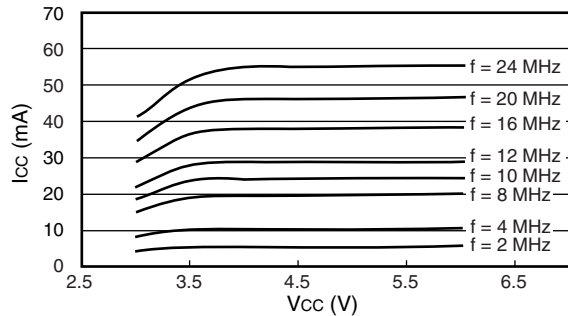
11.8 Flash Memory Program/Erase Characteristics

Parameter	Conditions	Value			Unit	Remarks
		Min	Typ	Max		
Sector erase time	$T_A = +25^{\circ}\text{C}$ $V_{CC} = 5.0\text{ V}$	—	1	15	s	Excludes programming prior to erasure
Chip erase time		—	9	—	s	Excludes programming prior to erasure
Word (16-bit width) programming time		—	16	3600	μs	Except for the over head time of the system
Program/Erase cycle	—	10000	—	—	cycle	
Flash Data Retention Time	Average $T_A = +85^{\circ}\text{C}$	20	—	—	year	*

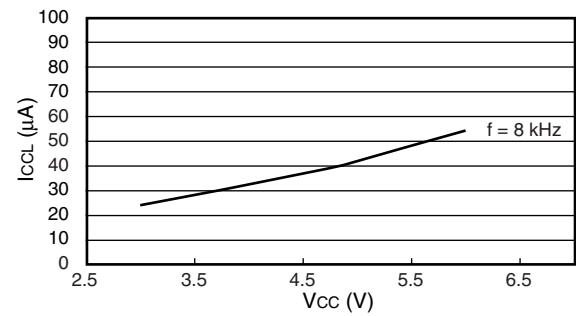
* : This value was converted from the results of evaluating the reliability of the technology (using Arrhenius equation to translate high temperature measurements into normalized value at $+85^{\circ}\text{C}$) .

■ MB90347E, MB90347ES, MB90347CE, MB90347CES

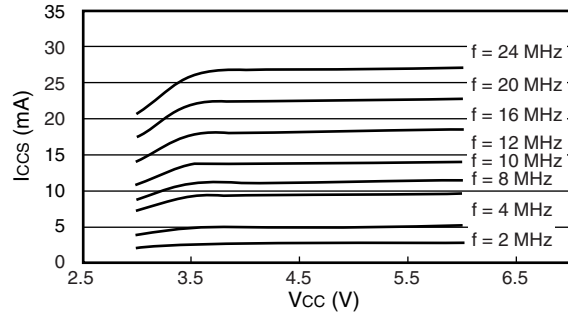
$I_{CC} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



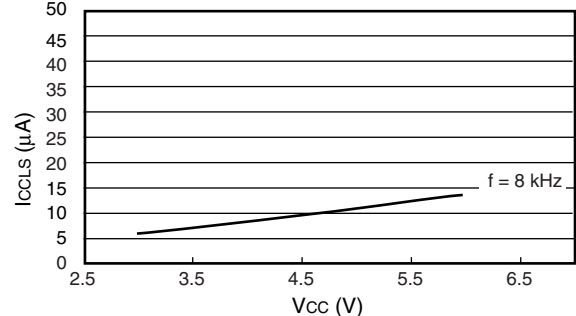
$I_{CCL} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



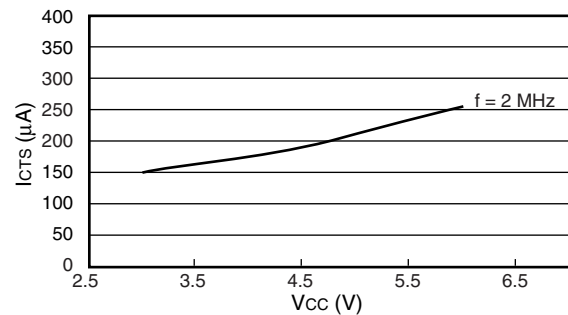
$I_{CCS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



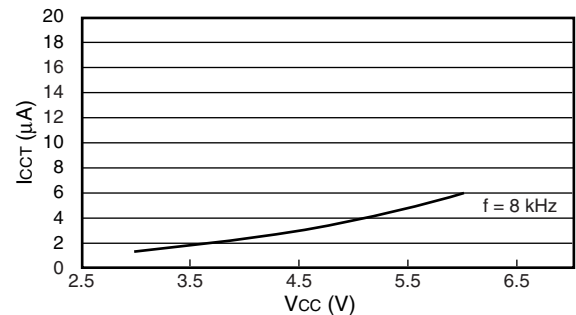
$I_{CCLS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



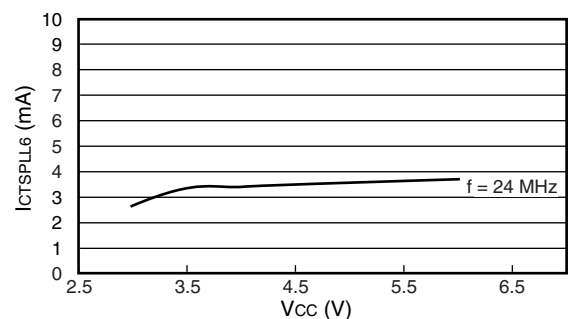
$I_{CTS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



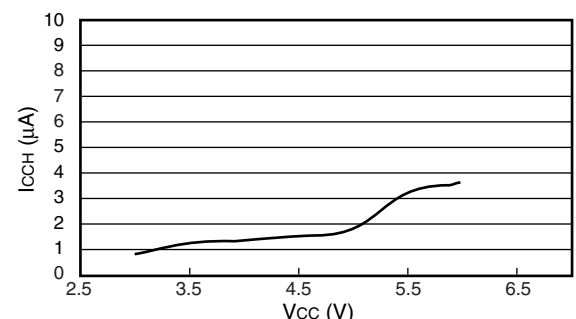
$I_{CCT} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



$I_{CTSPLL6} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



$I_{CCH} - V_{CC}$
 $T_A = +25^\circ\text{C}$, stopped

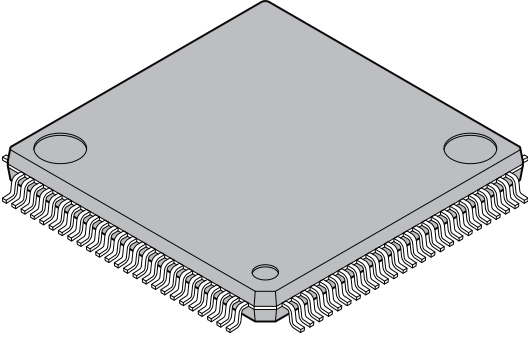


13. Ordering Information

Part number	Package	Remarks
MB90F342EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F342ESPF		
MB90F342CEPF		
MB90F342CESPF		
MB90F342EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F342ESPMC		
MB90F342CEPMC		
MB90F342CESPMC		
MB90F345EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F345ESPF		
MB90F345CEPF		
MB90F345CESPF		
MB90F345EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F345ESPMC		
MB90F345CEPMC		
MB90F345CESPMC		
MB90F346EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90F346ESPF		
MB90F346CEPF		
MB90F346CESPF		
MB90F346EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90F346ESPMC		
MB90F346CEPMC		
MB90F346CESPMC		

(Continued)

14. Package Dimensions

 100-pin plastic LQFP (FPT-100P-M20)	Lead pitch	0.50 mm
	Package width × package length	14.0 mm × 14.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm Max
	Weight	0.65 g
	Code (Reference)	P-LFQFP100-14×14-0.50

