



Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

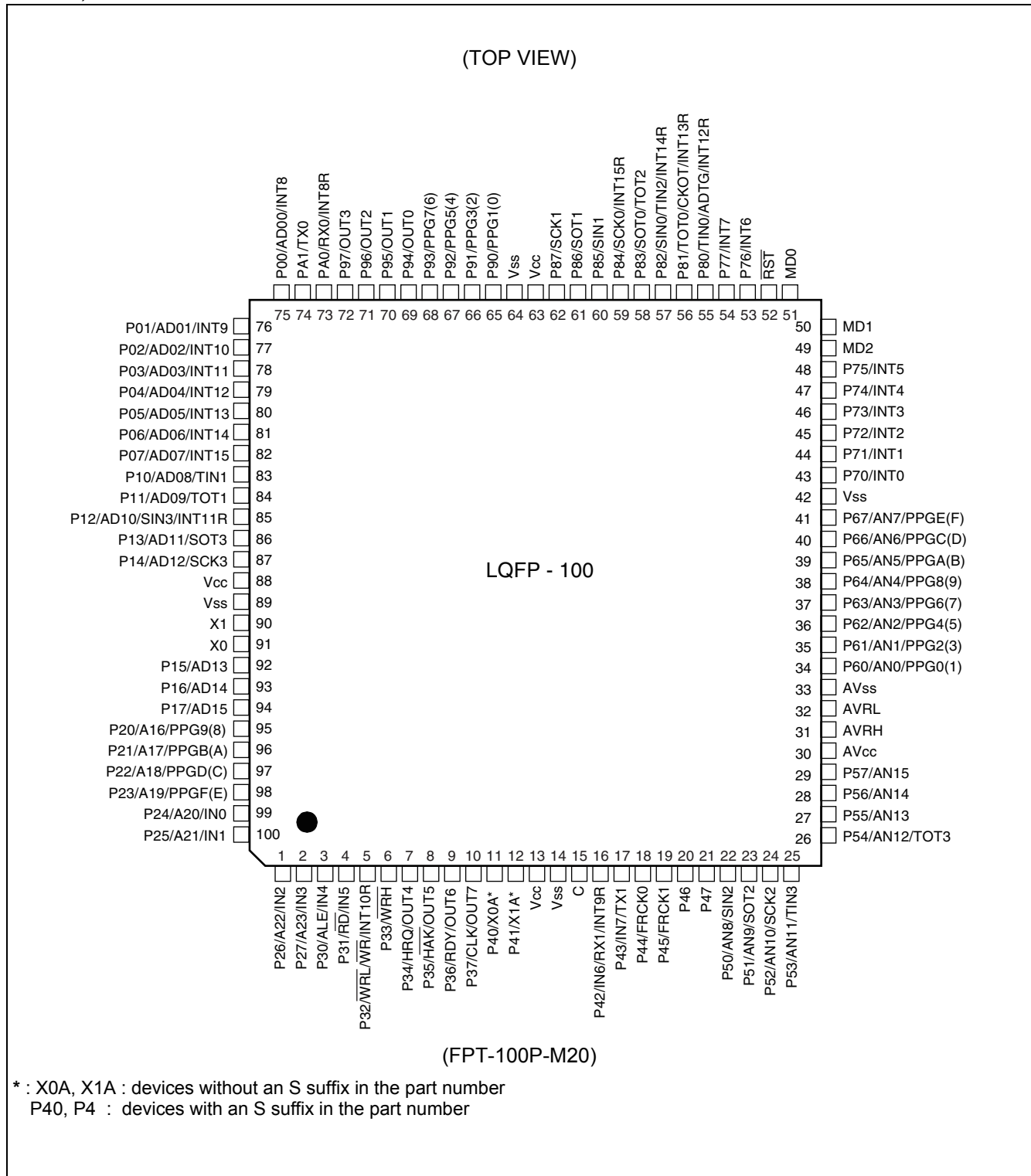
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-550e1

(Continued)

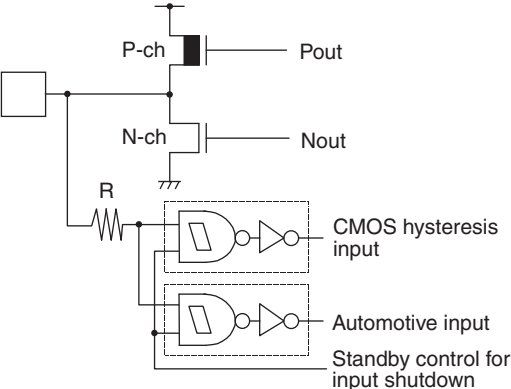
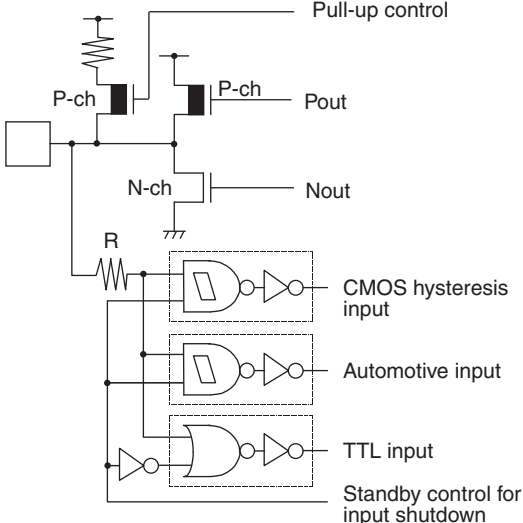
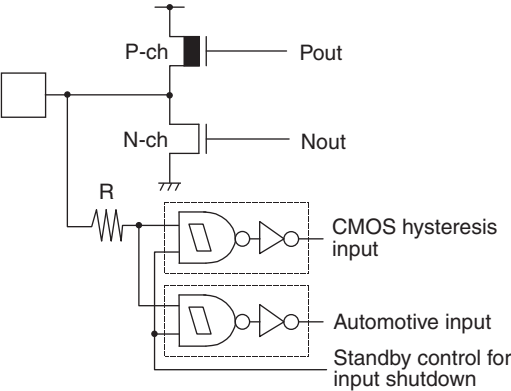


Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V _{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V _{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 μF .
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

(Continued)

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
19	17	P43	F	General purpose I/O pin.
		IN7		Trigger input pin for input capture.
		TX1		TX Output pin for CAN1 (MB90341E/342E/F342E/F345E only)
20	18	P44	H	General purpose I/O pin.
		SDA0		Serial data I/O pin for I ² C (devices with a C suffix in the part number)
		FRCK0		Input pin for the 16-bit Free-run Timer 0
21	19	P45	H	General purpose I/O pin.
		SCL0		Serial clock I/O pin for I ² C (devices with a C suffix in the part number)
		FRCK1		Input pin for the 16-bit Free-run Timer
22	20	P46	H	General purpose I/O pin.
		SDA1		Serial data I/O pin for I ² C (devices with a C suffix in the part number)
23	21	P47	H	General purpose I/O pin.
		SCL1		Serial clock I/O pin for I ² C (devices with a C suffix in the part number)
24	22	P50	O	General purpose I/O pin.
		AN8		Analog input pin for the A/D converter
		SIN2		Serial data input pin for UART2
25	23	P51	I	General purpose I/O pin.
		AN9		Analog input pin for the A/D converter
		SOT2		Serial data output pin for UART2
26	24	P52	I	General purpose I/O pin.
		AN10		Analog input pin for the A/D converter
		SCK2		Clock I/O pin for UART2
27	25	P53	I	General purpose I/O pin.
		AN11		Analog input pin for the A/D converter
		TIN3		Event input pin for the reload timer
28	26	P54	I	General purpose I/O pin.
		AN12		Analog input pin for the A/D converter
		TOT3		Output pin for the reload timer
29	27	P55	I	General purpose I/O pin.
		AN13		Analog input pin for the A/D converter
30, 31	28, 29	P56, P57	J	General purpose I/O pins.
		AN14, AN15		Analog input pins for the A/D converter
32	30	AV _{CC}	K	Analog power input pin for the A/D Converter

(Continued)

Type	Circuit	Remarks
F		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)
G		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ TTL input (with function to disconnect input during standby) ■ Programmable pull-up resistor: 50 kΩ approx.
H		■ CMOS level output ($I_{OL} = 3 \text{ mA}$, $I_{OH} = -3 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)

(Continued)

5. Sequence for Turning On the Power Supply to the A/D Converter and Analog Inputs

Make sure to turn on the A/D converter power supply (AV_{CC} , $AVRH$, $AVRL$) and analog inputs ($AN0$ to $AN23$) after turning-on the digital power supply (V_{CC}).

Turn-off the digital power after turning off the A/D converter supply and analog inputs. In this case, make sure that the voltage does not exceed $AVRH$ or AV_{CC} (turning on/off the analog and digital power supplies simultaneously is acceptable).

6. Connection of Unused A/D Converter Pins when the A/D Converter is Used

Connect unused pins of A/D converter to $AV_{CC} = V_{CC}$, $AV_{SS} = AVRH = AVRL = V_{SS}$.

7. Crystal Oscillator Circuit

The X0, X1 pins and X0A, X1A pins may be possible causes of abnormal operation. Make sure to provide bypass capacitors via the shortest distance from X0, X1 pins and X0A, X1A pins, crystal oscillator (or ceramic oscillator) and ground lines, and make sure, to the utmost effort, that the oscillation circuit lines do not cross the lines of other circuits. It is highly recommended to provide a printed circuit board art work surrounding X0, X1 pins and X0A, X1A pins with a ground area for stabilizing the operation.

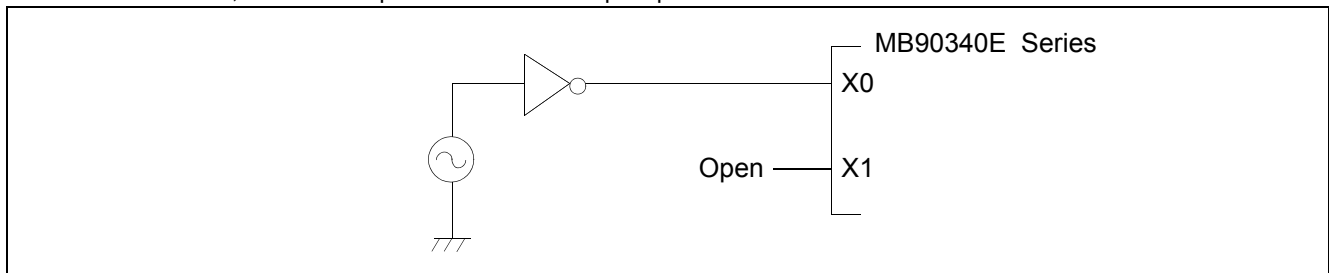
For each of the mass-production products, request an oscillator evaluation from the manufacturer of the oscillator you are using.

8. Pull-up/down resistors

The MB90340E Series does not support internal pull-up/down resistors (except for the pull-up resistors built into ports 0 to 3). Use external components where needed.

9. Using external clock

To use an external clock, drive the X0 pin and leave the X1 pin open.



10. Precautions when not using a sub clock signal

If you do not connect pins X0A and X1A to an oscillator, use pull-down handling on the X0A pin, and leave the X1A pin open.

11. Notes on operation in PLL clock mode

If PLL clock mode is selected, the microcontroller attempt to be working with the self-oscillating circuit even when there is no external oscillator or the external clock input is stopped. Performance of this operation, however, cannot be guaranteed.

12. Notes on Power-On

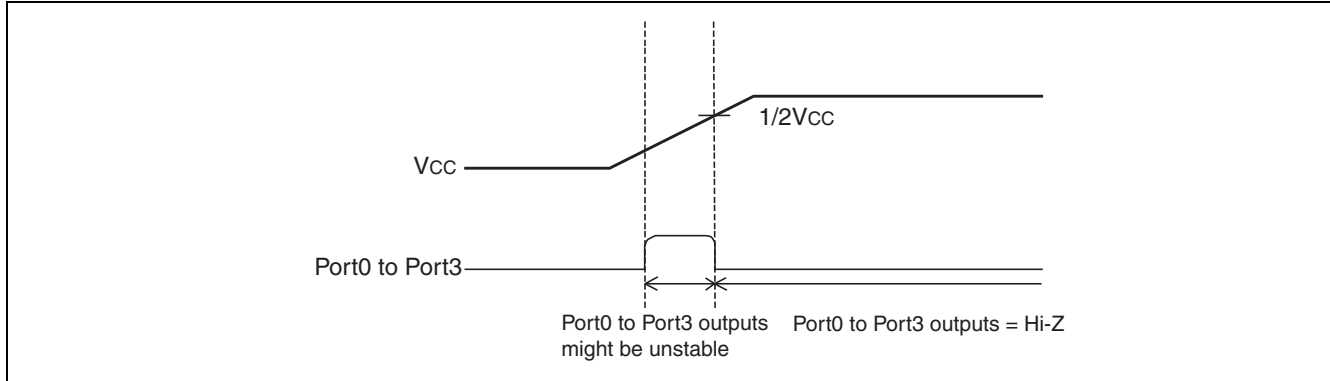
To prevent the internal regulator circuit from malfunctioning, set the voltage rise time during power-on to 50 μs or more (0.2 V to 2.7 V)

13. Stabilization of power supply voltage

A sudden change in the supply voltage may cause the device to malfunction even within the V_{CC} supply voltage operating range. Therefore, the V_{CC} supply voltage should be stabilized. For reference, the supply voltage should be controlled so that V_{CC} ripple variations (peak- to-peak values) at commercial frequencies (50 MHz/60 MHz) fall below 10% of the standard V_{CC} supply voltage and the coefficient of fluctuation does not exceed 0.1 V/ms at instantaneous power switching.

14. Port 0 to Port 3 Output During Power-on (External-bus Mode)

As shown below, when the power is turned on in External-Bus mode, there is a possibility that output signal of Port 0 to Port 3 might be unstable irrespective of the reset input.



15. Notes on Using the CAN Function

To use the CAN function, please set the DIRECT bit of the CAN Direct Mode Register (CDMR) to 1.

16. Flash Security Function (except for MB90F346E)

A security bit is located in the area of the flash memory.

If protection code 01_H is written in the security bit, the flash memory is in the protected state by security.

Therefore please do not write 01_H in this address if you do not use the security function.

Refer to following table for the address of the security bit.

	Flash memory size	Address of the security bit
MB90F347E	Embedded 1 Mbit Flash Memory	FE0001 _H
MB90F342E MB90F349E	Embedded 2 Mbits Flash Memory	FC0001 _H
MB90F345E	Embedded 4 Mbits Flash Memory	F80001 _H

17. Serial Communication

There is a possibility to receive wrong data due to the noise or other causes on the serial communication.

Therefore, design a printed circuit board so as to avoid noise.

Retransmit the data if an error occurs because of applying the checksum to the last data in consideration of receiving wrong data due to the noise.

8. I/O Map

Address	Register	Abbreviation	Access	Resource name	Initial value
000000 _H	Port 0 Data Register	PDR0	R/W	Port 0	XXXXXXXX _B
000001 _H	Port 1 Data Register	PDR1	R/W	Port 1	XXXXXXXX _B
000002 _H	Port 2 Data Register	PDR2	R/W	Port 2	XXXXXXXX _B
000003 _H	Port 3 Data Register	PDR3	R/W	Port 3	XXXXXXXX _B
000004 _H	Port 4 Data Register	PDR4	R/W	Port 4	XXXXXXXX _B
000005 _H	Port 5 Data Register	PDR5	R/W	Port 5	XXXXXXXX _B
000006 _H	Port 6 Data Register	PDR6	R/W	Port 6	XXXXXXXX _B
000007 _H	Port 7 Data Register	PDR7	R/W	Port 7	XXXXXXXX _B
000008 _H	Port 8 Data Register	PDR8	R/W	Port 8	XXXXXXXX _B
000009 _H	Port 9 Data Register	PDR9	R/W	Port 9	XXXXXXXX _B
00000A _H	Port A Data Register	PDRA	R/W	Port A	XXXXXXXX _B
00000B _H	Port 5 Analog Input Enable Register	ADER5	R/W	Port 5, A/D	1111111 _B
00000C _H	Port 6 Analog Input Enable Register	ADER6	R/W	Port 6, A/D	1111111 _B
00000D _H	Port 7 Analog Input Enable Register	ADER7	R/W	Port 7, A/D	1111111 _B
00000E _H	Input Level Select Register 0	ILSR0	R/W	Ports	XXXXXXXX _B
00000F _H	Input Level Select Register 1	ILSR1	R/W	Ports	XXXX0XXX _B
000010 _H	Port 0 Direction Register	DDR0	R/W	Port 0	0000000 _B
000011 _H	Port 1 Direction Register	DDR1	R/W	Port 1	0000000 _B
000012 _H	Port 2 Direction Register	DDR2	R/W	Port 2	0000000 _B
000013 _H	Port 3 Direction Register	DDR3	R/W	Port 3	0000000 _B
000014 _H	Port 4 Direction Register	DDR4	R/W	Port 4	0000000 _B
000015 _H	Port 5 Direction Register	DDR5	R/W	Port 5	0000000 _B
000016 _H	Port 6 Direction Register	DDR6	R/W	Port 6	0000000 _B
000017 _H	Port 7 Direction Register	DDR7	R/W	Port 7	0000000 _B
000018 _H	Port 8 Direction Register	DDR8	R/W	Port 8	0000000 _B
000019 _H	Port 9 Direction Register	DDR9	R/W	Port 9	0000000 _B
00001A _H	Port A Direction Register	DDRA	R/W	Port A	00000100 _B
00001B _H	Reserved				
00001C _H	Port 0 Pull-up Control Register	PUCR0	R/W	Port 0	0000000 _B
00001D _H	Port 1 Pull-up Control Register	PUCR1	R/W	Port 1	0000000 _B
00001E _H	Port 2 Pull-up Control Register	PUCR2	R/W	Port 2	0000000 _B
00001F _H	Port 3 Pull-up Control Register	PUCR3	W, R/W	Port 3	0000000 _B

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
000040 _H	PPG 8 Operation Mode Control Register	PPGC8	W,R/W	16-bit PPG 8/9	0X000XX1 _B
000041 _H	PPG 9 Operation Mode Control Register	PPGC9	W,R/W		0X000001 _B
000042 _H	PPG 8/PPG 9 Count Clock Control Register	PPG89	R/W		000000X0 _B
000043 _H	Reserved				
000044 _H	PPG A Operation Mode Control Register	PPGCA	W,R/W	16-bit PPG A/B	0X000XX1 _B
000045 _H	PPG B Operation Mode Control Register	PPGCB	W,R/W		0X000001 _B
000046 _H	PPG A/PPG B Count Clock Select Register	PPGAB	R/W		000000X0 _B
000047 _H	Reserved				
000048 _H	PPG C Operation Mode Control Register	PPGCC	W,R/W	16-bit PPG C/D	0X000XX1 _B
000049 _H	PPG D Operation Mode Control Register	PPGCD	W,R/W		0X000001 _B
00004A _H	PPG C/PPG D Count Clock Select Register	PPGCD	R/W		000000X0 _B
00004B _H	Reserved				
00004C _H	PPG E Operation Mode Control Register	PPGCE	W,R/W	16-bit PPG E/F	0X000XX1 _B
00004D _H	PPG F Operation Mode Control Register	PPGCF	W,R/W		0X000001 _B
00004E _H	PPG E/PPG F Count Clock Select Register	PPGEF	R/W		000000X0 _B
00004F _H	Reserved				
000050 _H	Input Capture Control Status 0/1	ICS01	R/W	Input Capture 0/1	00000000 _B
000051 _H	Input Capture Edge 0/1	ICE01	R/W, R		XXX0X0XX _B
000052 _H	Input Capture Control Status 2/3	ICS23	R/W	Input Capture 2/3	00000000 _B
000053 _H	Input Capture Edge 2/3	ICE23	R		XXXXXXXX _B
000054 _H	Input Capture Control Status 4/5	ICS45	R/W	Input Capture 4/5	00000000 _B
000055 _H	Input Capture Edge 4/5	ICE45	R		XXXXXXXX _B
000056 _H	Input Capture Control Status 6/7	ICS67	R/W	Input Capture 6/7	00000000 _B
000057 _H	Input Capture Edge 6/7	ICE67	R/W, R		XXX000XX _B
000058 _H	Output Compare Control Status 0	OCS0	R/W	Output Compare 0/1	0000XX00 _B
000059 _H	Output Compare Control Status 1	OCS1	R/W		0XX00000 _B
00005A _H	Output Compare Control Status 2	OCS2	R/W	Output Compare 2/3	0000XX00 _B
00005B _H	Output Compare Control Status 3	OCS3	R/W		0XX00000 _B
00005C _H	Output Compare Control Status 4	OCS4	R/W	Output Compare 4/5	0000XX00 _B
00005D _H	Output Compare Control Status 5	OCS5	R/W		0XX00000 _B
00005E _H	Output Compare Control Status 6	OCS6	R/W	Output Compare 6/7	0000XX00 _B
00005F _H	Output Compare Control Status 7	OCS7	R/W		0XX00000 _B

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
007900 _H	Reload Register L0	PRL0	R/W	16-bit PPG 0/1	XXXXXXXX _B
007901 _H	Reload Register H0	PRLH0	R/W		XXXXXXXX _B
007902 _H	Reload Register L1	PRL1	R/W		XXXXXXXX _B
007903 _H	Reload Register H1	PRLH1	R/W		XXXXXXXX _B
007904 _H	Reload Register L2	PRL2	R/W	16-bit PPG 2/3	XXXXXXXX _B
007905 _H	Reload Register H2	PRLH2	R/W		XXXXXXXX _B
007906 _H	Reload Register L3	PRL3	R/W		XXXXXXXX _B
007907 _H	Reload Register H3	PRLH3	R/W		XXXXXXXX _B
007908 _H	Reload Register L4	PRL4	R/W	16-bit PPG 4/5	XXXXXXXX _B
007909 _H	Reload Register H4	PRLH4	R/W		XXXXXXXX _B
00790A _H	Reload Register L5	PRL5	R/W		XXXXXXXX _B
00790B _H	Reload Register H5	PRLH5	R/W		XXXXXXXX _B
00790C _H	Reload Register L6	PRL6	R/W	16-bit PPG 6/7	XXXXXXXX _B
00790D _H	Reload Register H6	PRLH6	R/W		XXXXXXXX _B
00790E _H	Reload Register L7	PRL7	R/W		XXXXXXXX _B
00790F _H	Reload Register H7	PRLH7	R/W		XXXXXXXX _B
007910 _H	Reload Register L8	PRL8	R/W	16-bit PPG 8/9	XXXXXXXX _B
007911 _H	Reload Register H8	PRLH8	R/W		XXXXXXXX _B
007912 _H	Reload Register L9	PRL9	R/W		XXXXXXXX _B
007913 _H	Reload Register H9	PRLH9	R/W		XXXXXXXX _B
007914 _H	Reload Register LA	PRLA	R/W	16-bit PPG A/B	XXXXXXXX _B
007915 _H	Reload Register HA	PRLHA	R/W		XXXXXXXX _B
007916 _H	Reload Register LB	PRLB	R/W		XXXXXXXX _B
007917 _H	Reload Register HB	PRLHB	R/W		XXXXXXXX _B
007918 _H	Reload Register LC	PRLC	R/W	16-bit PPG C/D	XXXXXXXX _B
007919 _H	Reload Register HC	PRLHC	R/W		XXXXXXXX _B
00791A _H	Reload Register LD	PRLD	R/W		XXXXXXXX _B
00791B _H	Reload Register HD	PRLHD	R/W		XXXXXXXX _B
00791C _H	Reload Register LE	PRLLE	R/W	16-bit PPG E/F	XXXXXXXX _B
00791D _H	Reload Register HE	PRLHE	R/W		XXXXXXXX _B
00791E _H	Reload Register LF	PRLLF	R/W		XXXXXXXX _B
00791F _H	Reload Register HF	PRLHF	R/W		XXXXXXXX _B
007920 _H	Input Capture 0	IPCP0	R	Input Capture 0/1	XXXXXXXX _B
007921 _H	Input Capture 0	IPCP0	R		XXXXXXXX _B
007922 _H	Input Capture 1	IPCP1	R		XXXXXXXX _B
007923 _H	Input Capture 1	IPCP1	R		XXXXXXXX _B

(Continued)

List of Control Registers (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007B00 _H	007D00 _H	Control Status Register	CSR	R/W, W R/W, R	0XXXX0X1 _B 00XXX000 _B
007B01 _H	007D01 _H				
007B02 _H	007D02 _H	Last Event Indicator Register	LEIR	R/W	000X0000 _B XXXXXXXX _B
007B03 _H	007D03 _H				
007B04 _H	007D04 _H	Receive And Transmit Error Counter	RTEC	R	00000000 _B 00000000 _B
007B05 _H	007D05 _H				
007B06 _H	007D06 _H	Bit Timing Register	BTR	R/W	11111111 _B X1111111 _B
007B07 _H	007D07 _H				
007B08 _H	007D08 _H	IDE Register	IDER	R/W	XXXXXXXX _B XXXXXXXX _B
007B09 _H	007D09 _H				
007B0A _H	007D0A _H	Transmit RTR Register	TRTRR	R/W	00000000 _B 00000000 _B
007B0B _H	007D0B _H				
007B0C _H	007D0C _H	Remote Frame Receive Waiting Register	RFWTR	R/W	XXXXXXXX _B XXXXXXXX _B
007B0D _H	007D0D _H				
007B0E _H	007D0E _H	Transmit Interrupt Enable Register	TIER	R/W	00000000 _B 00000000 _B
007B0F _H	007D0F _H				
007B10 _H	007D10 _H	Acceptance Mask Select Register	AMSR	R/W	XXXXXXXX _B XXXXXXXX _B
007B11 _H	007D11 _H				
007B12 _H	007D12 _H				XXXXXXXX _B XXXXXXXX _B
007B13 _H	007D13 _H				
007B14 _H	007D14 _H	Acceptance Mask Register 0	AMR0	R/W	XXXXXXXX _B XXXXXXXX _B
007B15 _H	007D15 _H				
007B16 _H	007D16 _H				XXXXXXXX _B XXXXXXXX _B
007B17 _H	007D17 _H				
007B18 _H	007D18 _H	Acceptance Mask Register 1	AMR1	R/W	XXXXXXXX _B XXXXXXXX _B
007B19 _H	007D19 _H				
007B1A _H	007D1A _H				XXXXXXXX _B XXXXXXXX _B
007B1B _H	007D1B _H				

List of Message Buffers (DLC Registers and Data Registers) (1)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007A60 _H	007C60 _H	DLC Register 0	DLCR0	R/W	XXXXXXXX _B
007A61 _H	007C61 _H				
007A62 _H	007C62 _H				
007A63 _H	007C63 _H	DLC Register 1	DLCR1	R/W	XXXXXXXX _B
007A64 _H	007C64 _H				
007A65 _H	007C65 _H	DLC Register 2	DLCR2	R/W	XXXXXXXX _B
007A66 _H	007C66 _H				
007A67 _H	007C67 _H	DLC Register 3	DLCR3	R/W	XXXXXXXX _B
007A68 _H	007C68 _H				
007A69 _H	007C69 _H	DLC Register 4	DLCR4	R/W	XXXXXXXX _B
007A6A _H	007C6A _H				
007A6B _H	007C6B _H	DLC Register 5	DLCR5	R/W	XXXXXXXX _B
007A6C _H	007C6C _H				
007A6D _H	007C6D _H	DLC Register 6	DLCR6	R/W	XXXXXXXX _B
007A6E _H	007C6E _H				
007A6F _H	007C6F _H	DLC Register 7	DLCR7	R/W	XXXXXXXX _B
007A70 _H	007C70 _H				
007A71 _H	007C71 _H	DLC Register 8	DLCR8	R/W	XXXXXXXX _B
007A72 _H	007C72 _H				
007A73 _H	007C73 _H	DLC Register 9	DLCR9	R/W	XXXXXXXX _B
007A74 _H	007C74 _H				
007A75 _H	007C75 _H	DLC Register 10	DLCR10	R/W	XXXXXXXX _B
007A76 _H	007C76 _H				
007A77 _H	007C77 _H	DLC Register 11	DLCR11	R/W	XXXXXXXX _B
007A78 _H	007C78 _H				
007A79 _H	007C79 _H	DLC Register 12	DLCR12	R/W	XXXXXXXX _B
007A7A _H	007C7A _H				
007A7B _H	007C7B _H	DLC Register 13	DLCR13	R/W	XXXXXXXX _B
007A7C _H	007C7C _H				
007A7D _H	007C7D _H	DLC Register 14	DLCR14	R/W	XXXXXXXX _B
007A7E _H	007C7E _H				
007A7F _H	007C7F _H	DLC Register 15	DLCR15	R/W	XXXXXXXX _B

List of Message Buffers (DLC Registers and Data Registers) (3)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
007AF0 _H to 007AF7 _H	007CF0 _H to 007CF7 _H	Data Register 14 (8 bytes)	DTR14	R/W	XXXXXXXX _B to XXXXXXXX _B
007AF8 _H to 007AFF _H	007CF8 _H to 007CFF _H	Data Register 15 (8 bytes)	DTR15	R/W	XXXXXXXX _B to XXXXXXXX _B

11. Electrical Characteristics

11.1 Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	
	AV_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$V_{CC} = AV_{CC}$ *2
	AVRH, AVR _L	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$AV_{CC} \geq AVRH, AV_{CC} \geq AVR_L, AVRH \geq AVR_L$
Input voltage*1	V_I	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*3
Output voltage*1	V_O	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*3
Maximum Clamp Current	I_{CLAMP}	-4.0	+4.0	mA	*5
Total Maximum Clamp Current	$\sum I_{CLAMP} $	—	40	mA	*5
"L" level maximum output current	I_{OL}	—	15	mA	*4, *6
"L" level average output current	I_{OLAV}	—	4	mA	*4, *7
"L" level maximum overall output current	$\sum I_{OL}$	—	100	mA	*4
"L" level average overall output current	$\sum I_{OLAV}$	—	50	mA	*4, *8
"H" level maximum output current	I_{OH}	—	-15	mA	*4, *6
"H" level average output current	I_{OHAV}	—	-4	mA	*4, *7
"H" level maximum overall output current	$\sum I_{OH}$	—	-100	mA	*4
"H" level average overall output current	$\sum I_{OHAV}$	—	-50	mA	*4, *8
Power consumption	P_D	—	450	mW	
Operating temperature	T_A	-40	+105	°C	
Storage temperature	T_{STG}	-55	+150	°C	

*1: This parameter is based on $V_{SS} = AV_{SS} = 0$ V

*2: Set AV_{CC} and V_{CC} to the same voltage. Make sure that AV_{CC} does not exceed V_{CC} and that the voltage at the analog inputs does not exceed AV_{CC} when the power is switched on.

*3: V_I and V_O should not exceed $V_{CC} + 0.3$ V. V_I should not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_I rating.

*4: Applicable to pins: P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0, PA1

*5: ● Applicable to pins: P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57 (Evaluation device : P50 to P55), P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0 to PA1

● Use within recommended operating conditions.

● Use with DC voltage (current)

● The +B signal should always be applied by using a limiting resistance placed between the +B signal and the microcontroller.

● The value of the limiting resistance should be set so that when the +B signal is applied, the input current to the microcontroller pin does not exceed the rated value, either instantaneously or for prolonged periods.

● Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.

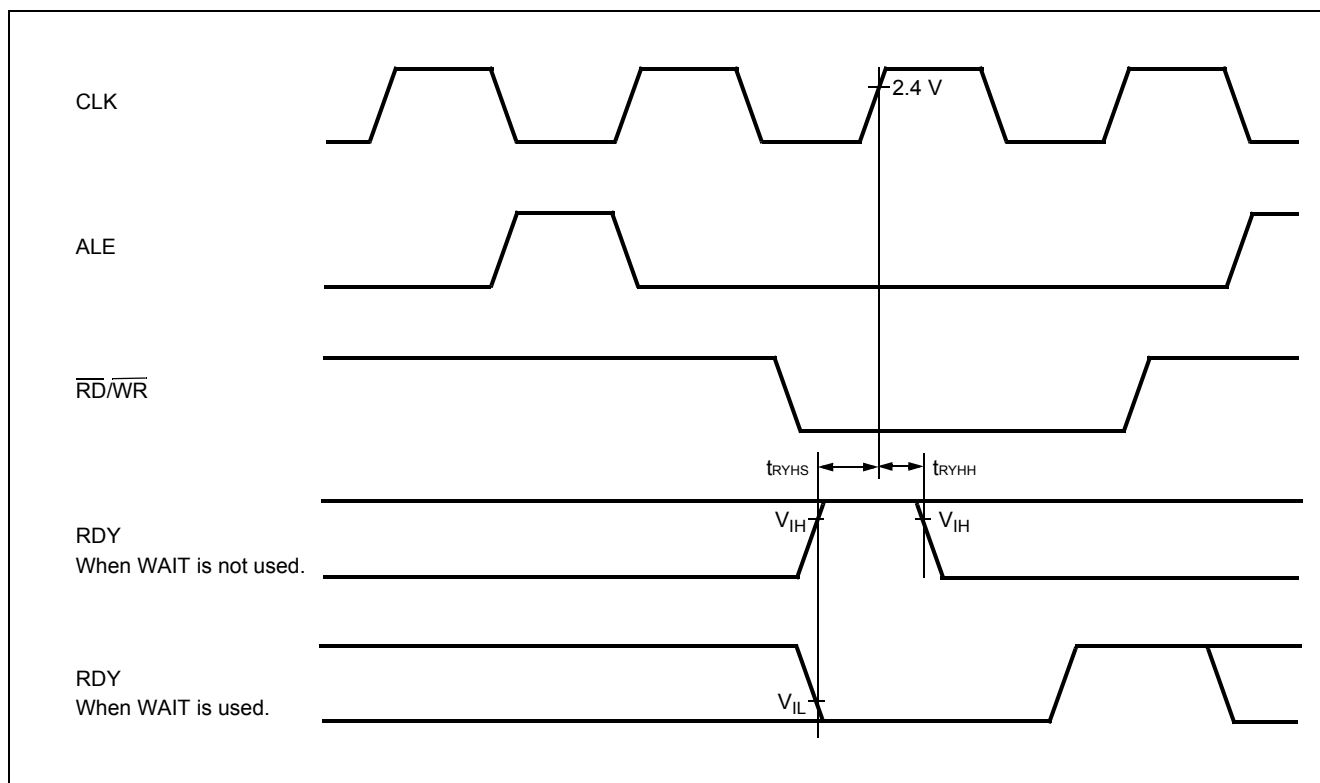
(Continued)

11.4.7 Ready Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $f_{CP} \leq 24\text{ MHz}$)

Parameter	Symbol	Pin	Test Condition	Rated Value		Unit	Remarks
				Min	Max		
RDY setup time	t_{RYHS}	RDY	—	45	—	ns	$f_{CP} = 16\text{ MHz}$
				32	—	ns	$f_{CP} = 24\text{ MHz}$
RDY hold time	t_{RYHH}	RDY		0	—	ns	

Note: : If the RDY setup time is insufficient, use the auto-ready function.



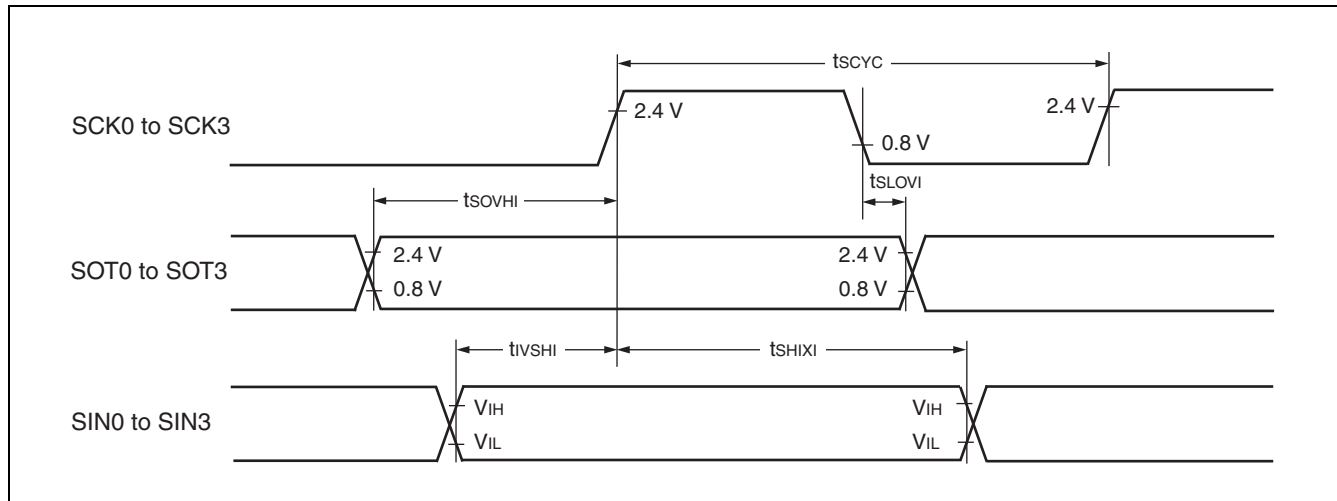
■ Bit setting: ESCR:SCES = 1, ECCR:SCDE = 1

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal clock operation output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
SOT $\rightarrow$ SCK $\uparrow$ delay time	t_{SOVHI}	SCK0 to SCK3, SOT0 to SOT3		$3 t_{CP} - 70$	—	ns

Note:

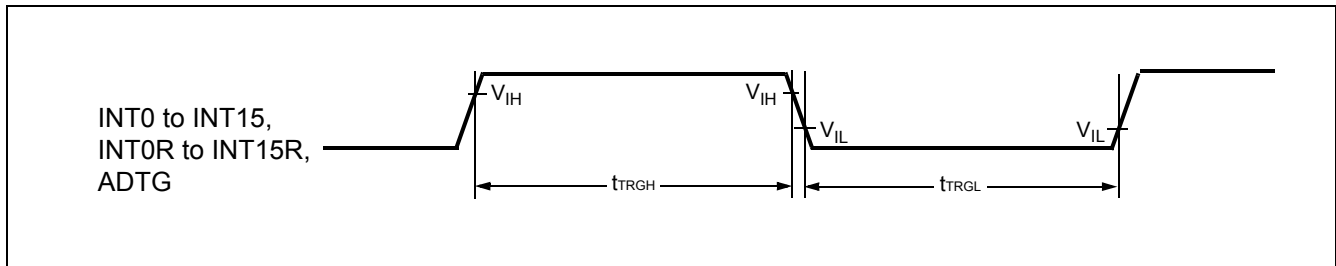
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.



11.4.10 Trigger Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TRGH} t_{TRGL}	INT0 to INT15, INT0R to INT15R, ADTG	—	$5 t_{CP}$	—	ns



11.4.13 I²C Timing

(T_A = -40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

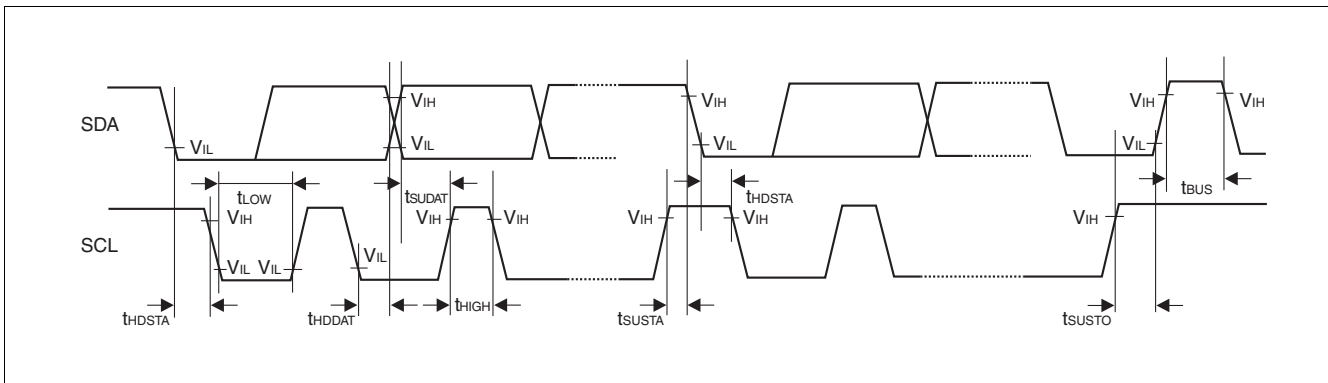
Parameter	Symbol	Condition	Standard-mode		Fast-mode* ¹		Unit
			Min	Max	Min	Max	
SCL clock frequency	f _{SCL}	R = 1.7 kΩ ₂ C = 50 pF* ²	0	100	0	400	kHz
Hold time (repeated) START condition SDA ↓ → SCL ↓	t _{HDSTA}		4.0	—	0.6	—	μs
"L" width of the SCL clock	t _{LOW}		4.7	—	1.3	—	μs
"H" width of the SCL clock	t _{HIGH}		4.0	—	0.6	—	μs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t _{SUSTA}		4.7	—	0.6	—	μs
Data hold time SCL ↓ → SDA ↓ ↑	t _{HDDAT}		0	3.45* ³	0	0.9* ⁴	μs
Data set-up time SDA ↓ ↑ → SCL ↑	t _{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t _{SUSTO}		4.0	—	0.6	—	μs
Bus free time between a STOP and START condition	t _{BUS}		4.7	—	1.3	—	μs

*1: For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.

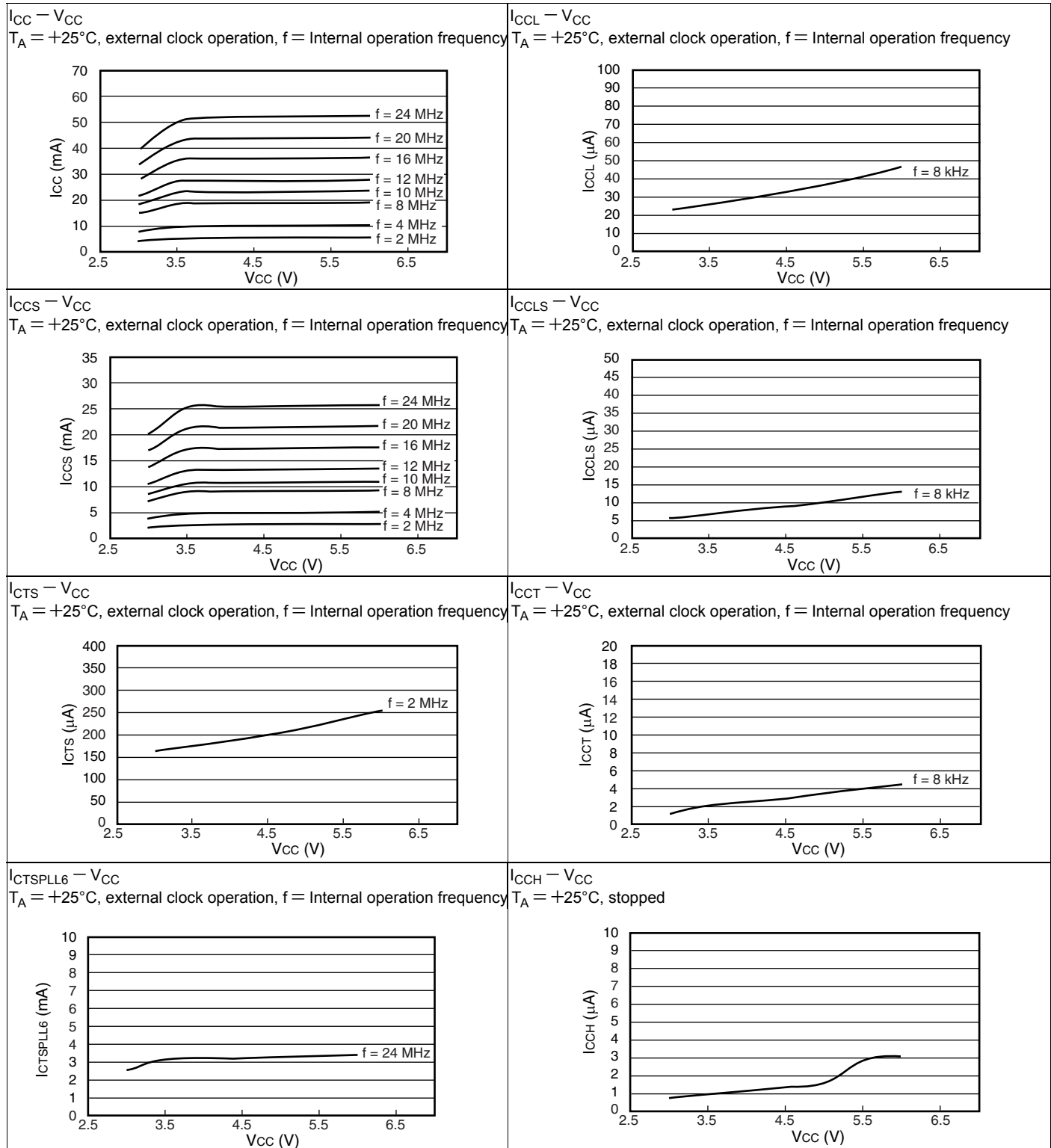
*3: The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4: A Fast-mode I²C-bus device can be used in a Standard-mode I²C-bus system, but the requirement t_{SUDAT} ≥ 250 ns must then be met.



12. Example Characteristics

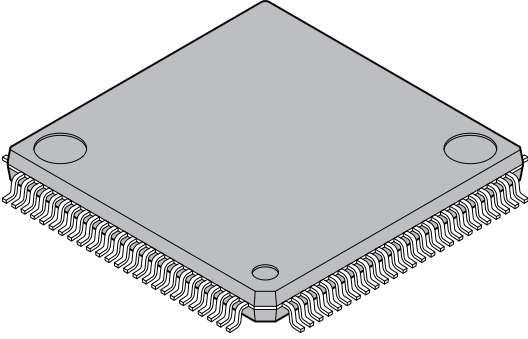
■ MB90F346E, MB90F346ES, MB90F346CE, MB90F346CES



(Continued)

Part number	Package	Remarks
MB90346EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90346ESPF		
MB90346CEPF		
MB90346CESPF		
MB90346EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90346ESPMC		
MB90346CEPMC		
MB90346CESPMC		
MB90347EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90347ESPF		
MB90347CEPF		
MB90347CESPF		
MB90347EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90347ESPMC		
MB90347CEPMC		
MB90347CESPMC		
MB90348EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90348ESPF		
MB90348CEPF		
MB90348CESPF		
MB90348EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90348ESPMC		
MB90348CEPMC		
MB90348CESPMC		
MB90349EPF	100-pin plastic QFP (FPT-100P-M06)	
MB90349ESPF		
MB90349CEPF		
MB90349CESPF		
MB90349EPMC	100-pin plastic LQFP (FPT-100P-M20)	
MB90349ESPMC		
MB90349CEPMC		
MB90349CESPMC		
MB90V340E-101CR	299-pin ceramic PGA (PGA-299C-A01)	For evaluation
MB90V340E-102CR		

14. Package Dimensions

 100-pin plastic LQFP (FPT-100P-M20)	Lead pitch	0.50 mm
	Package width × package length	14.0 mm × 14.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm Max
	Weight	0.65 g
	Code (Reference)	P-LFQFP100-14×14-0.50

