Infineon Technologies - MB90347ESPMC-GS-656E1 Datasheet

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

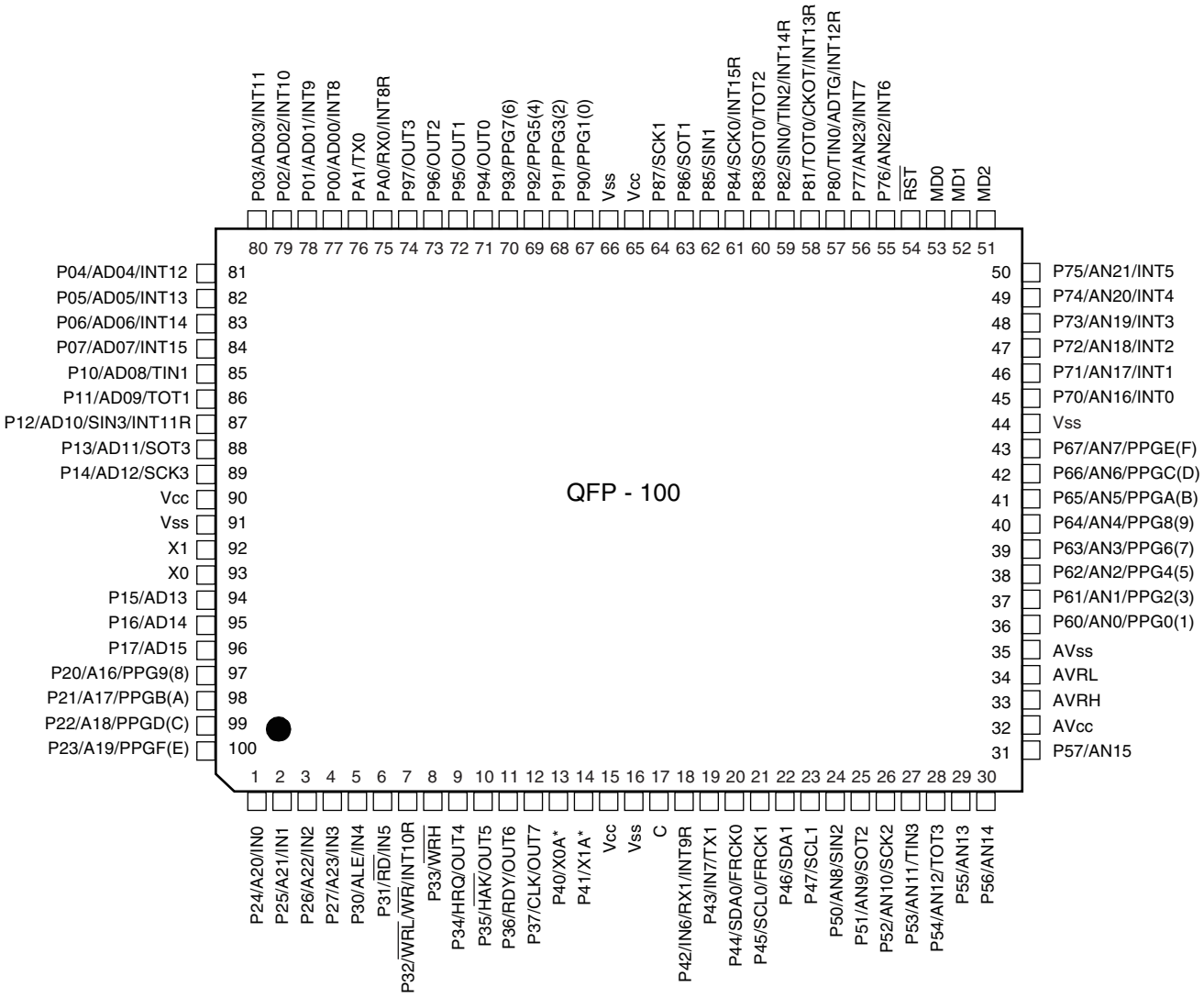
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-656e1

Contents

■ MB90341CE(S), MB90342CE(S), MB90F342CE(S), MB90F345CE(S), MB90346CE(S), MB90F346CE(S), MB90347CE(S), MB90F347CE(S), MB90348CE(S), MB90349CE(S), MB90F349CE(S)

(TOP VIEW)



(FPT-100P-M06)

* : X0A, X1A : devices without an S suffix in the part number
P40, P41 : devices with an S suffix in the part number

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Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
9	7	P34	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT4		Waveform output pin for output compare.
10	8	P35	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold function are enabled.
		OUT5		Waveform output pin for output compare.
11	9	P36	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the external ready function is disabled.
		RDY		External ready input pin. This function is enabled when both the external bus and the external ready function are enabled.
		OUT6		Waveform output pin for output compare.
12	10	P37	G	General purpose I/O pin. The register can be set to select whether to use a pull-up resistor. This function is enabled either in single-chip mode or when the clock output is disabled.
		CLK		Clock output pin. This function is enabled when both the external bus and clock output are enabled.
		OUT7		Waveform output pin for output compare
13, 14	11, 12	P40, P41	F	General purpose I/O pins. (devices with an S suffix in the part number and or MB90V340E-101)
		X0A, X1A	B	Oscillation pins for sub clock (devices without an S suffix in the part number and or MB90V340E-102)
15	13	V_{CC}	—	Power (3.5 V to 5.5 V) input pin
16	14	V_{SS}	—	GND pin
17	15	C	K	This is the power supply stabilization capacitor This pin should be connected to a ceramic capacitor with a capacitance greater than or equal to 0.1 µF.
18	16	P42	F	General purpose I/O pin.
		IN6		Trigger input pin for input capture.
		RX1		RX input pin for CAN1 Interface (MB90341E/342E/F342E/F345E only)
		INT9R		External interrupt request input pin

(Continued)

Pin No.		Pin name	I/O Circuit type*3	Function
QFP100*1	LQFP100*2			
19	17	P43	F	General purpose I/O pin.
		IN7		Trigger input pin for input capture.
		TX1		TX Output pin for CAN1 (MB90341E/342E/F342E/F345E only)
20	18	P44	H	General purpose I/O pin.
		SDA0		Serial data I/O pin for I^2C (devices with a C suffix in the part number)
		FRCK0		Input pin for the 16-bit Free-run Timer 0
21	19	P45	H	General purpose I/O pin.
		SCL0		Serial clock I/O pin for I^2C (devices with a C suffix in the part number)
		FRCK1		Input pin for the 16-bit Free-run Timer
22	20	P46	H	General purpose I/O pin.
		SDA1		Serial data I/O pin for I^2C (devices with a C suffix in the part number)
23	21	P47	H	General purpose I/O pin.
		SCL1		Serial clock I/O pin for I^2C (devices with a C suffix in the part number)
24	22	P50	O	General purpose I/O pin.
		AN8		Analog input pin for the A/D converter
		SIN2		Serial data input pin for UART2
25	23	P51	I	General purpose I/O pin.
		AN9		Analog input pin for the A/D converter
		SOT2		Serial data output pin for UART2
26	24	P52	I	General purpose I/O pin.
		AN10		Analog input pin for the A/D converter
		SCK2		Clock I/O pin for UART2
27	25	P53	I	General purpose I/O pin.
		AN11		Analog input pin for the A/D converter
		TIN3		Event input pin for the reload timer
28	26	P54	I	General purpose I/O pin.
		AN12		Analog input pin for the A/D converter
		TOT3		Output pin for the reload timer
29	27	P55	I	General purpose I/O pin.
		AN13		Analog input pin for the A/D converter
30, 31	28, 29	P56, P57	J	General purpose I/O pins.
		AN14, AN15		Analog input pins for the A/D converter
32	30	AV_{CC}	K	Analog power input pin for the A/D Converter

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Address	Register	Abbreviation	Access	Resource name	Initial value
007948_H	Timer 0/Reload 0	TMR0/TMRLR0	R/W	16-bit Reload Timer 0	$XXXXXXXX_B$
007949_H			R/W		$XXXXXXXX_B$
$00794A_H$	Timer 1/Reload 1	TMR1/TMRLR1	R/W	16-bit Reload Timer 1	$XXXXXXXX_B$
$00794B_H$			R/W		$XXXXXXXX_B$
$00794C_H$	Timer 2/Reload 2	TMR2/TMRLR2	R/W	16-bit Reload Timer 2	$XXXXXXXX_B$
$00794D_H$			R/W		$XXXXXXXX_B$
$00794E_H$	Timer 3/Reload 3	TMR3/TMRLR3	R/W	16-bit Reload Timer 3	$XXXXXXXX_B$
$00794F_H$			R/W		$XXXXXXXX_B$
007950_H	Serial Mode Register 3	SMR3	W,R/W	UART3	00000000_B
007951_H	Serial Control Register 3	SCR3	W,R/W		00000000_B
007952_H	Reception/Transmission Data Register 3	RDR3/TDR3	R/W		00000000_B
007953_H	Serial Status Register 3	SSR3	R,R/W		00001000_B
007954_H	Extended Communication Control Register 3	ECCR3	R,W, R/W		$000000XX_B$
007955_H	Extended Status Control Register	ESCR3	R/W		00000100_B
007956_H	Baud Rate Generator Register 30	BGR30	R/W		00000000_B
007957_H	Baud Rate Generator Register 31	BGR31	R/W		00000000_B
007958_H	Serial Mode Register 4	SMR4	W,R/W	UART4	00000000_B
007959_H	Serial Control Register 4	SCR4	W,R/W		00000000_B
$00795A_H$	Reception/Transmission Data Register 4	RDR4/TDR4	R/W		00000000_B
$00795B_H$	Serial Status Register 4	SSR4	R,R/W		00001000_B
$00795C_H$	Extended Communication Control Register 4	ECCR4	R,W, R/W		$000000XX_B$
$00795D_H$	Extended Status Control Register	ESCR4	R/W		00000100_B
$00795E_H$	Baud Rate Generator Register 40	BGR40	R/W		00000000_B
$00795F_H$	Baud Rate Generator Register 41	BGR41	R/W		00000000_B
007960_H to $00796B_H$	Reserved				
$00796C_H$	Clock Output Enable Register	CLKR	R/W	Clock Monitor	$XXXX0000_B$
$00796D_H$	Reserved				
$00796E_H$	CAN Direct Mode Register	CDMR	R/W	CAN Clock sync	$XXXXXXX0_B$
$00796F_H$	CAN Switch Register	CANSWR	R/W	CAN 0/1	$XXXXXX00_B$

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Address	Register	Abbreviation	Access	Resource name	Initial value
$0079E0_H$	Detect Address Setting 0	PADR0	R/W	Address Match Detection 0	$XXXXXXXX_B$
$0079E1_H$	Detect Address Setting 0	PADR0	R/W		$XXXXXXXX_B$
$0079E2_H$	Detect Address Setting 0	PADR0	R/W		$XXXXXXXX_B$
$0079E3_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E4_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E5_H$	Detect Address Setting 1	PADR1	R/W		$XXXXXXXX_B$
$0079E6_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E7_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E8_H$	Detect Address Setting 2	PADR2	R/W		$XXXXXXXX_B$
$0079E9_H$ to $0079EF_H$	Reserved				
$0079F0_H$	Detect Address Setting 3	PADR3	R/W	Address Match Detection 1	$XXXXXXXX_B$
$0079F1_H$	Detect Address Setting 3	PADR3	R/W		$XXXXXXXX_B$
$0079F2_H$	Detect Address Setting 3	PADR3	R/W		$XXXXXXXX_B$
$0079F3_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F4_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F5_H$	Detect Address Setting 4	PADR4	R/W		$XXXXXXXX_B$
$0079F6_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F7_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F8_H$	Detect Address Setting 5	PADR5	R/W		$XXXXXXXX_B$
$0079F9_H$ to $0079FF_H$	Reserved				
$007A00_H$ to $007AFF_H$	Reserved for CAN Controller 0. Refer to “CAN Controllers				
$007B00_H$ to $007BFF_H$	Reserved for CAN Controller 0. Refer to “CAN Controllers”				
$007C00_H$ to $007CFF_H$	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
$007D00_H$ to $007DFF_H$	Reserved for CAN Controller 1. Refer to “CAN Controllers”				
$007E00_H$ to $007FFF_H$	Reserved				

Note:
- Initial value of “X” represents unknown value.
- Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results in reading “X”.

List of Control Registers (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007B00_H$	$007D00_H$	Control Status Register	CSR	R/W, W R/W, R	$0XXXX0X1_B$ $00XXX000_B$
$007B01_H$	$007D01_H$				
$007B02_H$	$007D02_H$	Last Event Indicator Register	LEIR	R/W	$000X0000_B$ $XXXXXXXX_B$
$007B03_H$	$007D03_H$				
$007B04_H$	$007D04_H$	Receive And Transmit Error Counter	RTEC	R	00000000_B 00000000_B
$007B05_H$	$007D05_H$				
$007B06_H$	$007D06_H$	Bit Timing Register	BTR	R/W	11111111_B $X1111111_B$
$007B07_H$	$007D07_H$				
$007B08_H$	$007D08_H$	IDE Register	IDER	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007B09_H$	$007D09_H$				
$007B0A_H$	$007D0A_H$	Transmit RTR Register	TRTRR	R/W	00000000_B 00000000_B
$007B0B_H$	$007D0B_H$				
$007B0C_H$	$007D0C_H$	Remote Frame Receive Waiting Register	RFWTR	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007B0D_H$	$007D0D_H$				
$007B0E_H$	$007D0E_H$	Transmit Interrupt Enable Register	TIER	R/W	00000000_B 00000000_B
$007B0F_H$	$007D0F_H$				
$007B10_H$	$007D10_H$	Acceptance Mask Select Register	AMSR	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007B11_H$	$007D11_H$				
$007B12_H$	$007D12_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007B13_H$	$007D13_H$				
$007B14_H$	$007D14_H$	Acceptance Mask Register 0	AMR0	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007B15_H$	$007D15_H$				
$007B16_H$	$007D16_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007B17_H$	$007D17_H$				
$007B18_H$	$007D18_H$	Acceptance Mask Register 1	AMR1	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007B19_H$	$007D19_H$				
$007B1A_H$	$007D1A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007B1B_H$	$007D1B_H$				

List of Message Buffers (ID Registers) (1)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A00_H$ to $007A1F_H$	$007C00_H$ to $007C1F_H$	General-Purpose RAM	——	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007A20_H$	$007C20_H$	ID Register 0	IDR0	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A21_H$	$007C21_H$				
$007A22_H$	$007C22_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A23_H$	$007C23_H$				
$007A24_H$	$007C24_H$	ID Register 1	IDR1	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A25_H$	$007C25_H$				
$007A26_H$	$007C26_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A27_H$	$007C27_H$				
$007A28_H$	$007C28_H$	ID Register 2	IDR2	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A29_H$	$007C29_H$				
$007A2A_H$	$007C2A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A2B_H$	$007C2B_H$				
$007A2C_H$	$007C2C_H$	ID Register 3	IDR3	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A2D_H$	$007C2D_H$				
$007A2E_H$	$007C2E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A2F_H$	$007C2F_H$				
$007A30_H$	$007C30_H$	ID Register 4	IDR4	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A31_H$	$007C31_H$				
$007A32_H$	$007C32_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A33_H$	$007C33_H$				
$007A34_H$	$007C34_H$	ID Register 5	IDR5	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A35_H$	$007C35_H$				
$007A36_H$	$007C36_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A37_H$	$007C37_H$				
$007A38_H$	$007C38_H$	ID Register 6	IDR6	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A39_H$	$007C39_H$				
$007A3A_H$	$007C3A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A3B_H$	$007C3B_H$				
$007A3C_H$	$007C3C_H$	ID Register 7	IDR7	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A3D_H$	$007C3D_H$				
$007A3E_H$	$007C3E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A3F_H$	$007C3F_H$				

List of Message Buffers (ID Registers) (2)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
$007A40_H$	$007C40_H$	ID Register 8	IDR8	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A41_H$	$007C41_H$				
$007A42_H$	$007C42_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A43_H$	$007C43_H$				
$007A44_H$	$007C44_H$	ID Register 9	IDR9	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A45_H$	$007C45_H$				
$007A46_H$	$007C46_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A47_H$	$007C47_H$				
$007A48_H$	$007C48_H$	ID Register 10	IDR10	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A49_H$	$007C49_H$				
$007A4A_H$	$007C4A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4B_H$	$007C4B_H$				
$007A4C_H$	$007C4C_H$	ID Register 11	IDR11	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4D_H$	$007C4D_H$				
$007A4E_H$	$007C4E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A4F_H$	$007C4F_H$				
$007A50_H$	$007C50_H$	ID Register 12	IDR12	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A51_H$	$007C51_H$				
$007A52_H$	$007C52_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A53_H$	$007C53_H$				
$007A54_H$	$007C54_H$	ID Register 13	IDR13	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A55_H$	$007C55_H$				
$007A56_H$	$007C56_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A57_H$	$007C57_H$				
$007A58_H$	$007C58_H$	ID Register 14	IDR14	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A59_H$	$007C59_H$				
$007A5A_H$	$007C5A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5B_H$	$007C5B_H$				
$007A5C_H$	$007C5C_H$	ID Register 15	IDR15	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5D_H$	$007C5D_H$				
$007A5E_H$	$007C5E_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007A5F_H$	$007C5F_H$				

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Interrupt cause	EI^{2}OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
UART 2 RX / UART 4 RX	Y2	14	#39	$FFFF60_H$	ICR14	$0000BE_H$
UART 2 TX / UART 4 TX	Y1	15	#40	$FFFF5C_H$		
Flash Memory	N	——	#41	$FFFF58_H$	ICR15	$0000BF_H$
Delayed Interrupt	N	——	#42	$FFFF54_H$		

Y1 : Usable
Y2 : Usable, with EI^{2}OS stop function
N : Unusable

Note:
- The peripheral resources sharing the ICR register have the same interrupt level.
- When two peripheral resources share the ICR register, only one can use Extended Intelligent I/O Service at a time.
- When either of the two peripheral resources sharing the ICR register specifies Extended Intelligent I/O Service, the other one cannot use interrupts.

11. Electrical Characteristics

11.1 Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	
	AV_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$V_{CC} = AV_{CC}$*2
	AVRH, AVRL	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$AV_{CC} \geq$ AVRH, $AV_{CC} \geq$ AVRL, AVRH $\geq$ AVRL
Input voltage*1	V_I	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*3
Output voltage*1	V_O	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*3
Maximum Clamp Current	I_{CLAMP}	−4.0	+4.0	mA	*5
Total Maximum Clamp Current	$\Sigma\lvert I_{CLAMP}\rvert$	—	40	mA	*5
“L” level maximum output current	I_{OL}	—	15	mA	*4, *6
“L” level average output current	I_{OLAV}	—	4	mA	*4, *7
“L” level maximum overall output current	ΣI_{OL}	—	100	mA	*4
“L” level average overall output current	ΣI_{OLAV}	—	50	mA	*4, *8
“H” level maximum output current	I_{OH}	—	−15	mA	*4, *6
“H” level average output current	I_{OHAV}	—	−4	mA	*4, *7
“H” level maximum overall output current	ΣI_{OH}	—	−100	mA	*4
“H” level average overall output current	ΣI_{OHAV}	—	−50	mA	*4, *8
Power consumption	P_D	—	450	mW	
Operating temperature	T_A	−40	+105	°C	
Storage temperature	T_{STG}	−55	+150	°C	

*1: This parameter is based on $V_{SS} = AV_{SS} = 0$ V

*2: Set AV_{CC} and V_{CC} to the same voltage. Make sure that AV_{CC} does not exceed V_{CC} and that the voltage at the analog inputs does not exceed AV_{CC} when the power is switched on.

*3: V_I and V_O should not exceed $V_{CC} + 0.3$ V. V_I should not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_I rating.

*4: Applicable to pins: P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0, PA1

*5:
- Applicable to pins: P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57 (Evaluation device : P50 to P55) , P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0 to PA1
- Use within recommended operating conditions.
- Use with DC voltage (current)
- The +B signal should always be applied by using a limiting resistance placed between the +B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the +B signal is applied, the input current to the microcontroller pin does not exceed the rated value, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.

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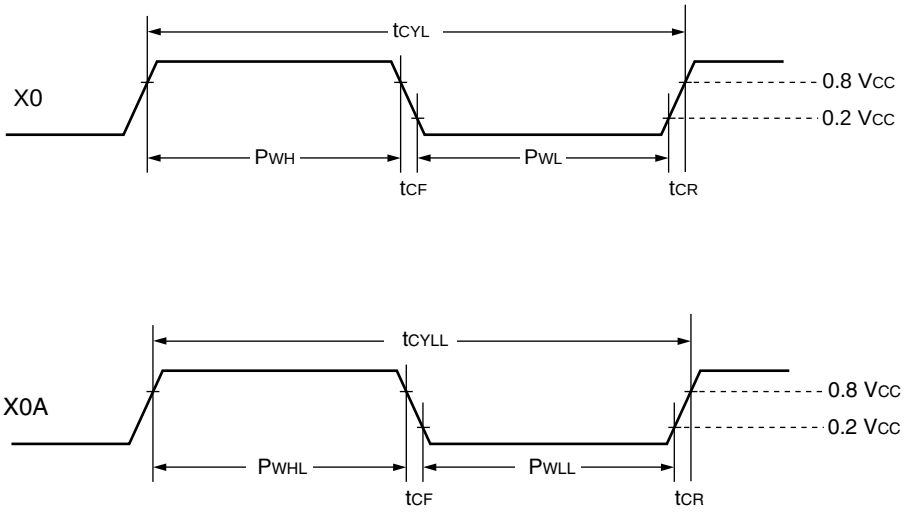
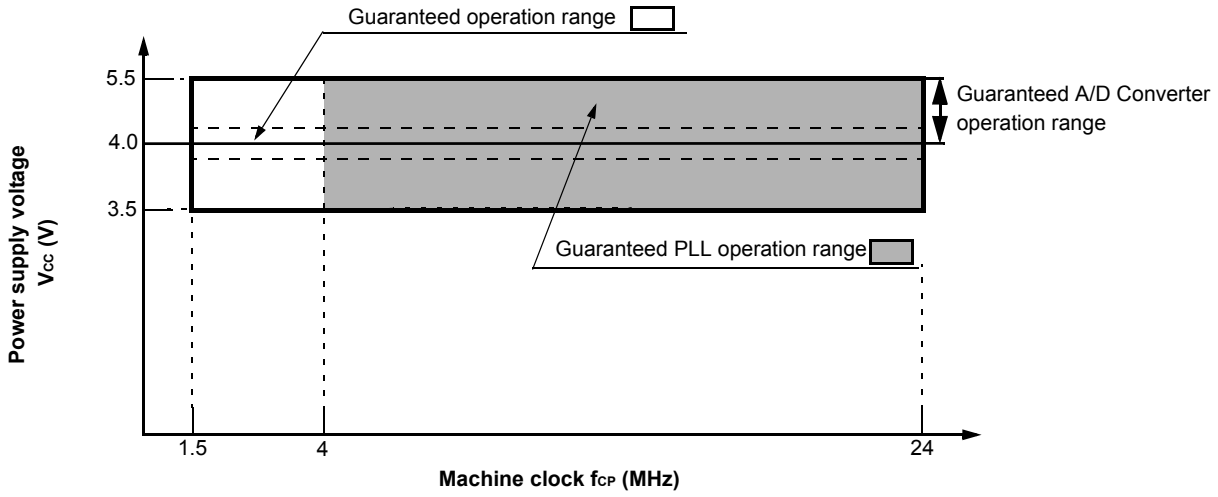
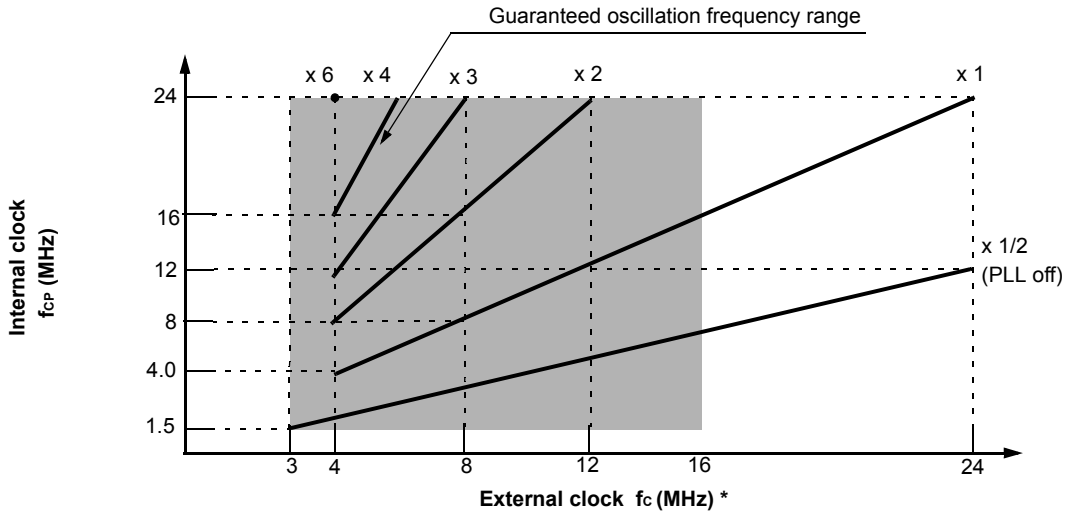
Clock Timing



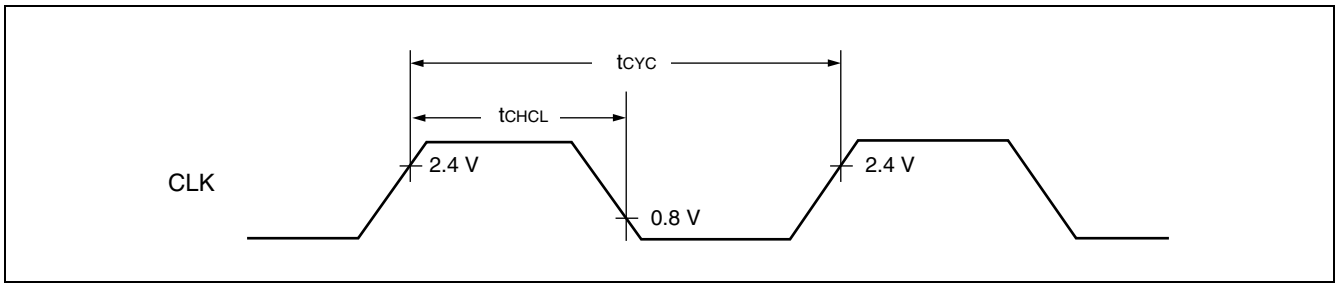
Guaranteed PLL operation range



Guaranteed operation range of MB90340E series



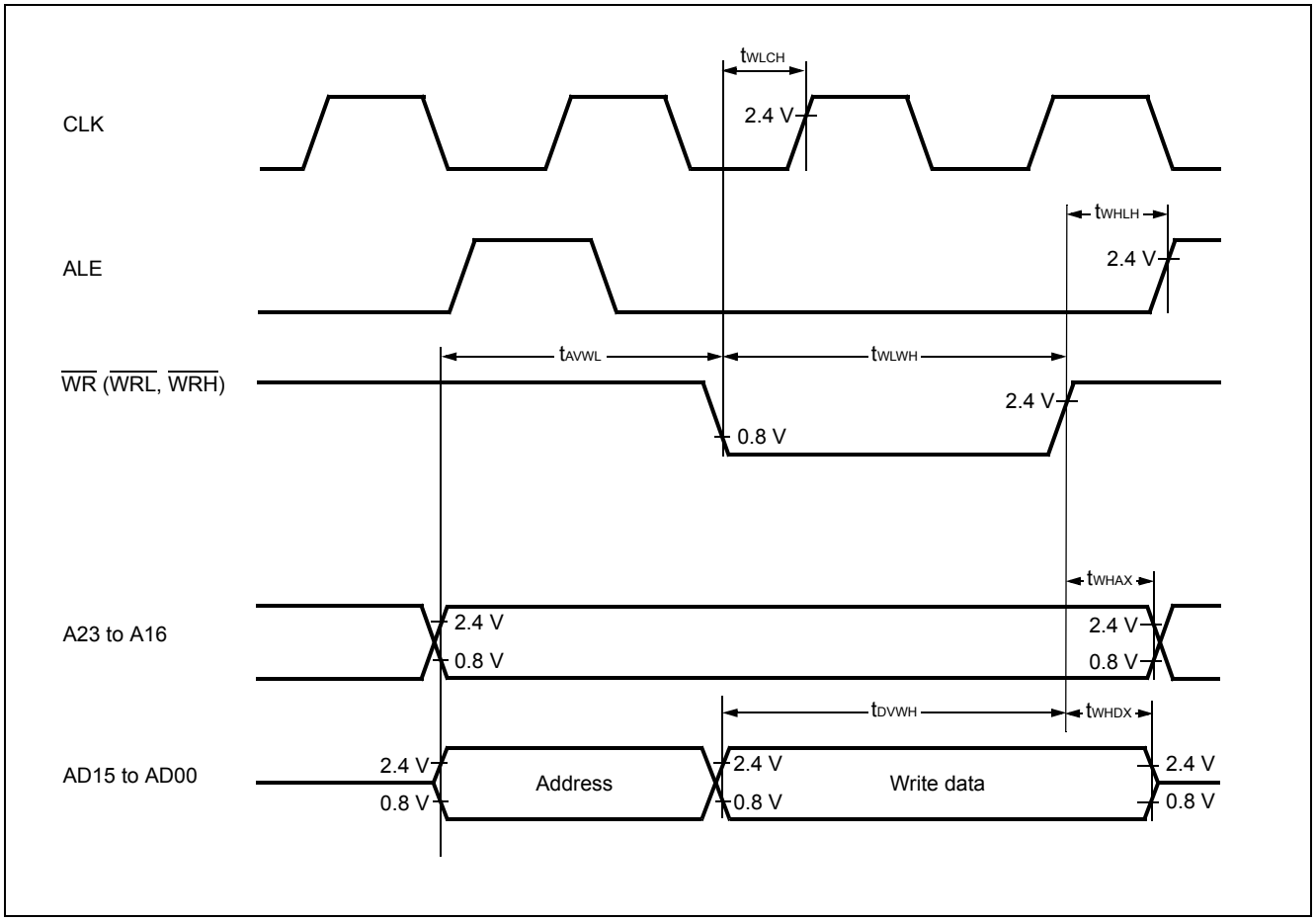
* : When using a crystal oscillator or ceramic oscillator, the maximum oscillation clock frequency is 16 MHz


tCYC
tCHCL
CLK
2.4 V
2.4 V
0.8 V

11.4.6 Bus Timing (Write)

(T_A = −40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V, f_{CP} ≤ 24 MHz)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Valid address → $\overline{WR}$ ↓ time	t_{AVWL}	A23 to A16, AD15 to AD00, $\overline{WR}$	—	t_{CP}−15	—	ns
$\overline{WR}$ pulse width	t_{WLWH}	$\overline{WR}$		3 t_{CP}/2 − 20	—	ns
Valid data output → $\overline{WR}$ ↑ time	t_{DVWH}	AD15 to AD00, $\overline{WR}$		3 t_{CP}/2 − 20	—	ns
$\overline{WR}$ ↑ → Data hold time	t_{WHDX}	AD15 to AD00, $\overline{WR}$		15	—	ns
$\overline{WR}$ ↑ → Address valid time	t_{WHAX}	A23 to A16, $\overline{WR}$		t_{CP}/2 − 10	—	ns
$\overline{WR}$ ↑ → ALE ↑ time	t_{WHLH}	$\overline{WR}$, ALE		t_{CP}/2 − 15	—	ns
$\overline{WR}$ ↓ → CLK ↑ time	t_{WLCH}	$\overline{WR}$, CLK		t_{CP}/2 − 15	—	ns



11.4.13 I^2C Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10%, V_{SS} = 0.0 V)

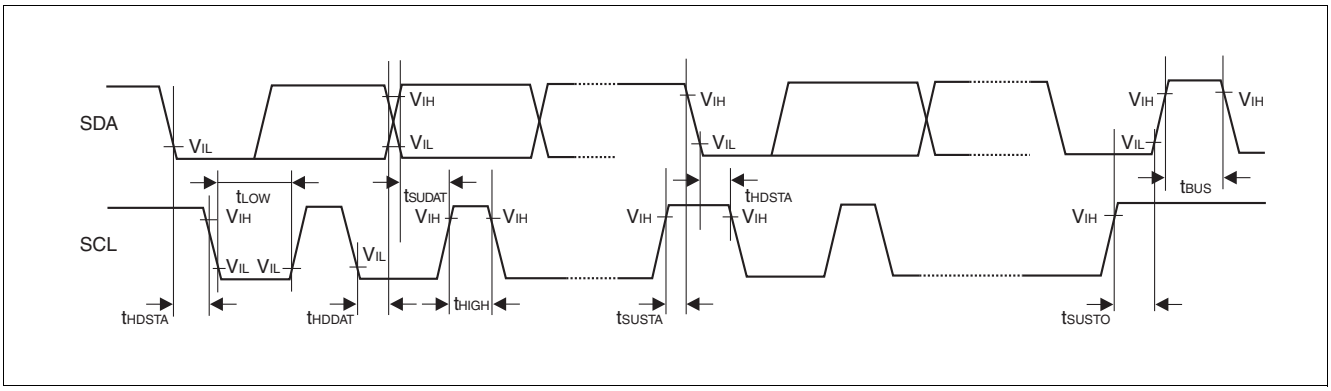
Parameter	Symbol	Condition	Standard-mode		Fast-mode*1		Unit
			Min	Max	Min	Max	
SCL clock frequency	f_{SCL}	R = 1.7 kΩ, C = 50 pF*2	0	100	0	400	kHz
Hold time (repeated) START condition SDA↓ → SCL ↓	t_{HDSTA}		4.0	—	0.6	—	µs
"L" width of the SCL clock	t_{LOW}		4.7	—	1.3	—	µs
"H" width of the SCL clock	t_{HIGH}		4.0	—	0.6	—	µs
Set-up time (repeated) START condition SCL ↑ → SDA ↓	t_{SUSTA}		4.7	—	0.6	—	µs
Data hold time SCL ↓ → SDA ↓ ↑	t_{HDDAT}		0	3.45*3	0	0.9*4	µs
Data set-up time SDA ↓ ↑ → SCL ↑	t_{SUDAT}		250	—	100	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t_{SUSTO}		4.0	—	0.6	—	µs
Bus free time between a STOP and START condition	t_{BUS}		4.7	—	1.3	—	µs

*1:For use at over 100 kHz, set the machine clock to at least 6 MHz.

*2:R,C: Pull-up resistor and load capacitor of the SCL and SDA lines.

*3:The maximum t_{HDDAT} meets the requirement that it does not extend the "L" width (t_{LOW}) of the SCL signal.

*4:A Fast-mode I^2C-bus device can be used in a Standard-mode I^2C-bus system, but the requirement $t_{SUDAT} \geq 250$ ns must then be met.



11.6 Definition of A/D Converter Terms

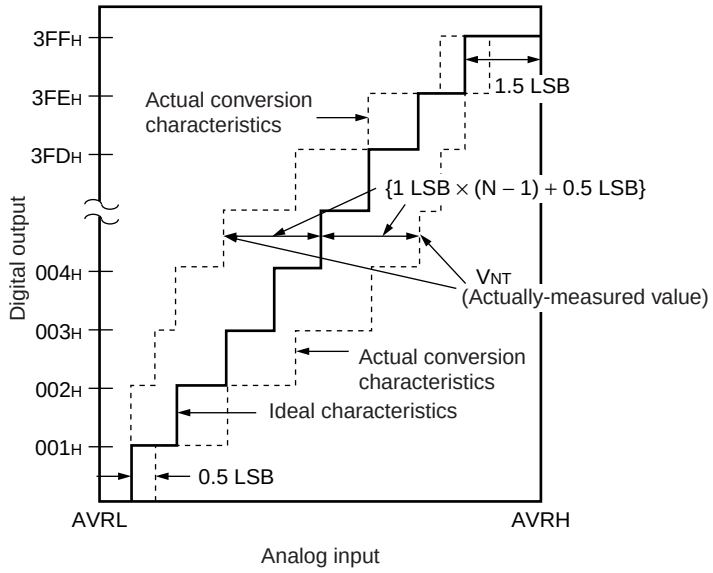
Resolution : Analog variation that is recognized by the A/D converter.

Non linearity error : The deviation between the actual conversion characteristics and a line that joins the zero-transition line (“00 0000 0000” ← → “00 0000 0001”) to the full-scale transition line (“11 1111 1110” ← → “11 1111 1111”) .

Differential linearity error : Deviation of input voltage, which is required for changing output code by 1 LSB, from an ideal value.

Total error : Difference between the actual value and the ideal value. The total error includes zero transition error, full-scale transition error, and linear error.

Total error



$$\text{Total error of digital output “N”} = \frac{V_{NT} - \{1\ \text{LSB} \times (N - 1) + 0.5\ \text{LSB}\}}{1\ \text{LSB}}\ [\text{LSB}]$$

$$1\ \text{LSB (Ideal value)} = \frac{\text{AVRH} - \text{AVRL}}{1024}\ [\text{V}]$$

N : Value of the digital output from the A/D converter

V_{OT} (Ideal value) = AVRL + 0.5 LSB [V]

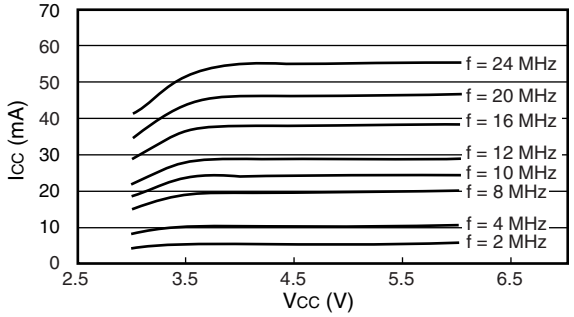
V_{FST} (Ideal value) = AVRH − 1.5 LSB [V]

V_{NT} : A voltage at which the digital output transitions from $(N - 1)_H$ to N_H.

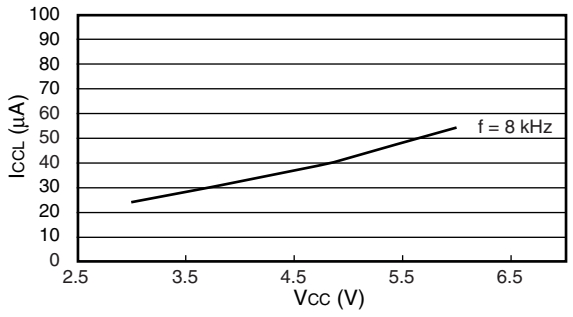
(Continued)

■ MB90347E, MB90347ES, MB90347CE, MB90347CES

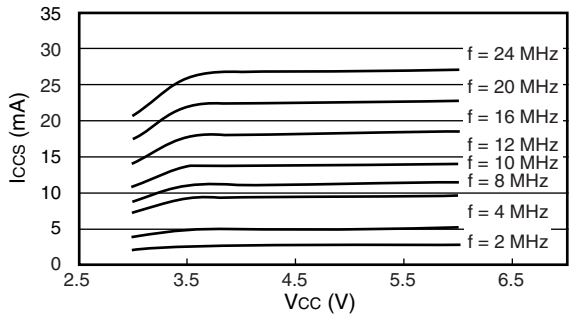
$I_{CC} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



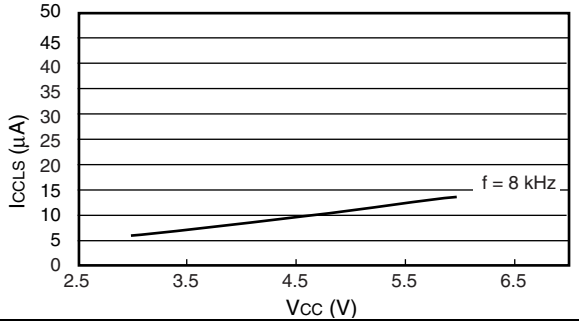
$I_{CCL} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



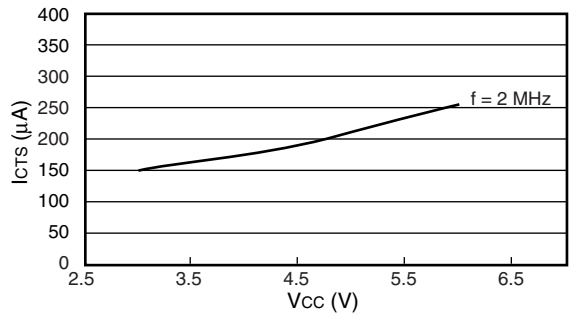
$I_{CCS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



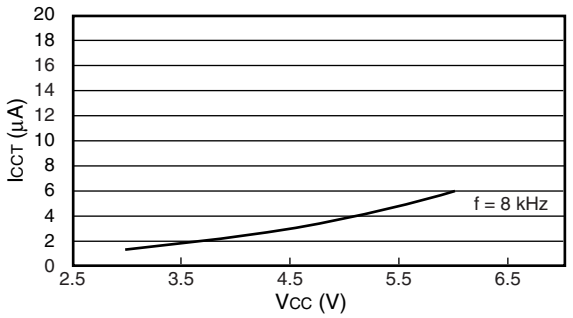
$I_{CCLS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



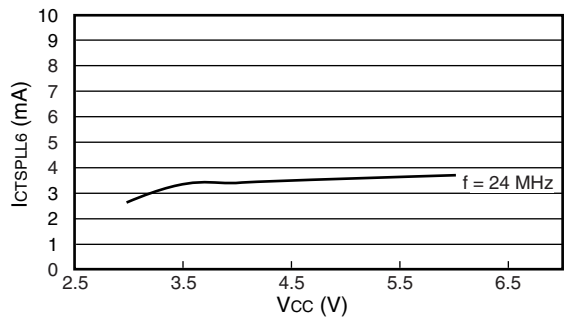
$I_{CTS} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



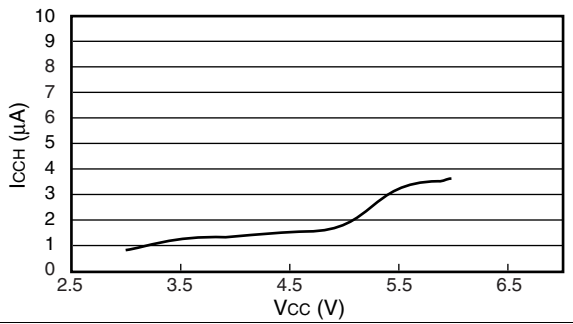
$I_{CCT} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency



$I_{CTSPLL6} - V_{CC}$
$T_A = +25°C$, external clock operation f = Internal operation frequency

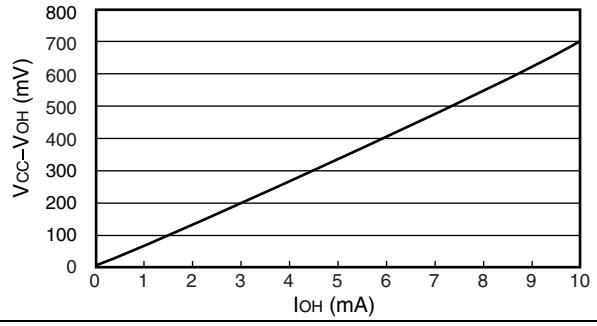


$I_{CCH} - V_{CC}$
$T_A = +25°C$, stopped

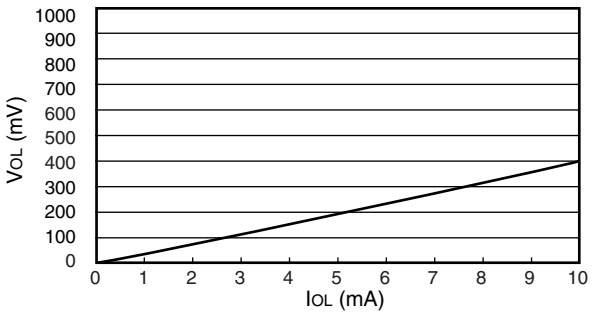


■ I/O characteristics

$(V_{CC}-V_{OH})$ – I_{OH}
T_A = +25°C, V_{CC} = 4.5 V

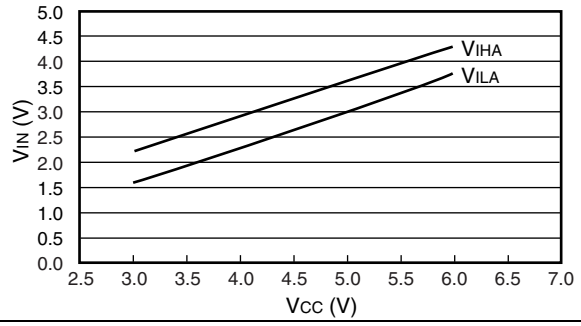


V_{OL} – I_{OL}
T_A = +25°C, V_{CC} = 4.5 V

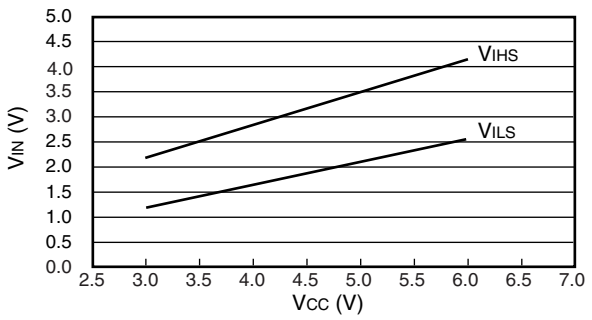


Automotive V_{IN} – V_{CC}

T_A = +25°C

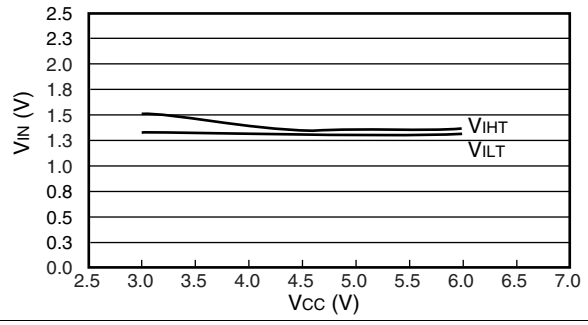


CMOS V_{IN} – V_{CC}
Other than UART-SIN pin and I^2C pin
T_A = +25°C

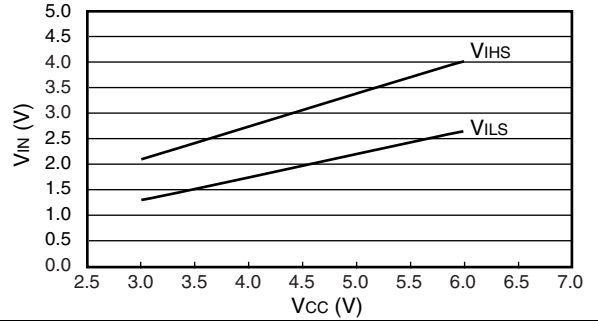


TTL V_{IN} – V_{CC}

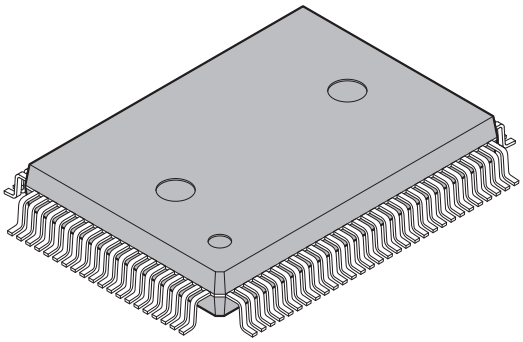
T_A = +25°C



CMOS V_{IN} – V_{CC}
UART-SIN pin, I^2C pin
T_A = +25°C

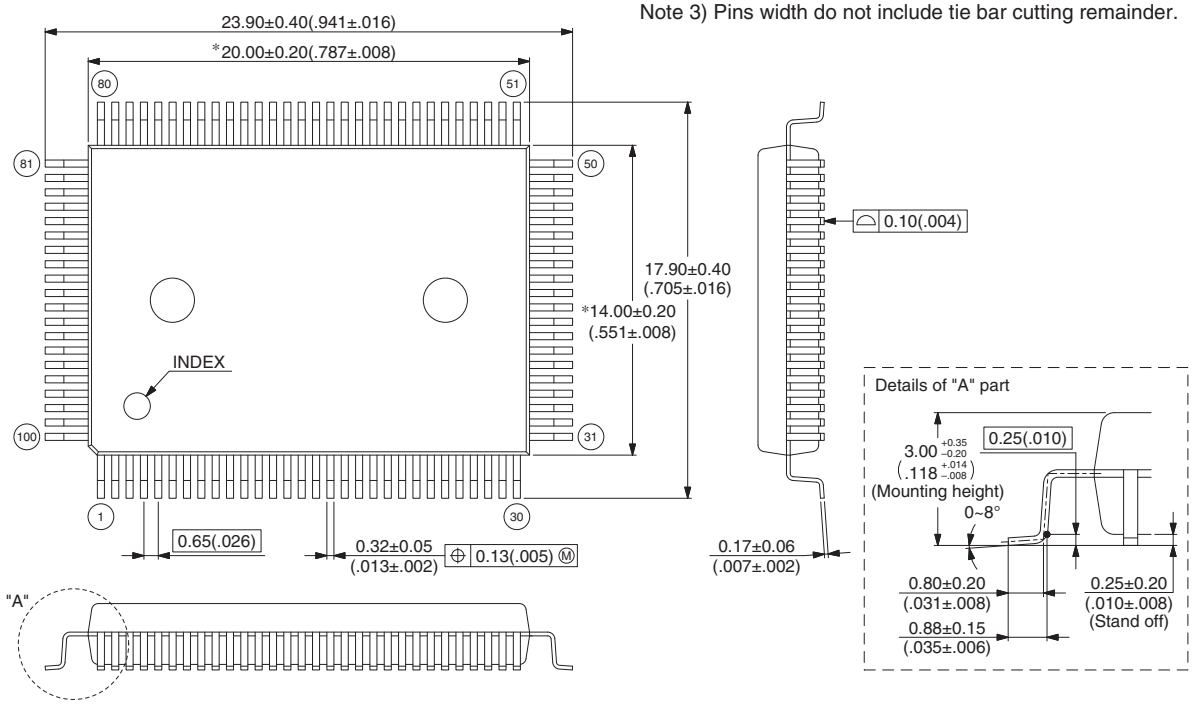


(Continued)

100-pin plastic QFP		
	Lead pitch	0.65 mm
	Package width × package length	14.00 × 20.00 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	3.35 mm MAX
	Code (Reference)	P-QFP100-14×20-0.65
(FPT-100P-M06)		

100-pin plastic QFP
(FPT-100P-M06)

Note 1) * : These dimensions do not include resin protrusion.
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.



Dimensions in mm (inches).
Note: The values in parentheses are reference values.