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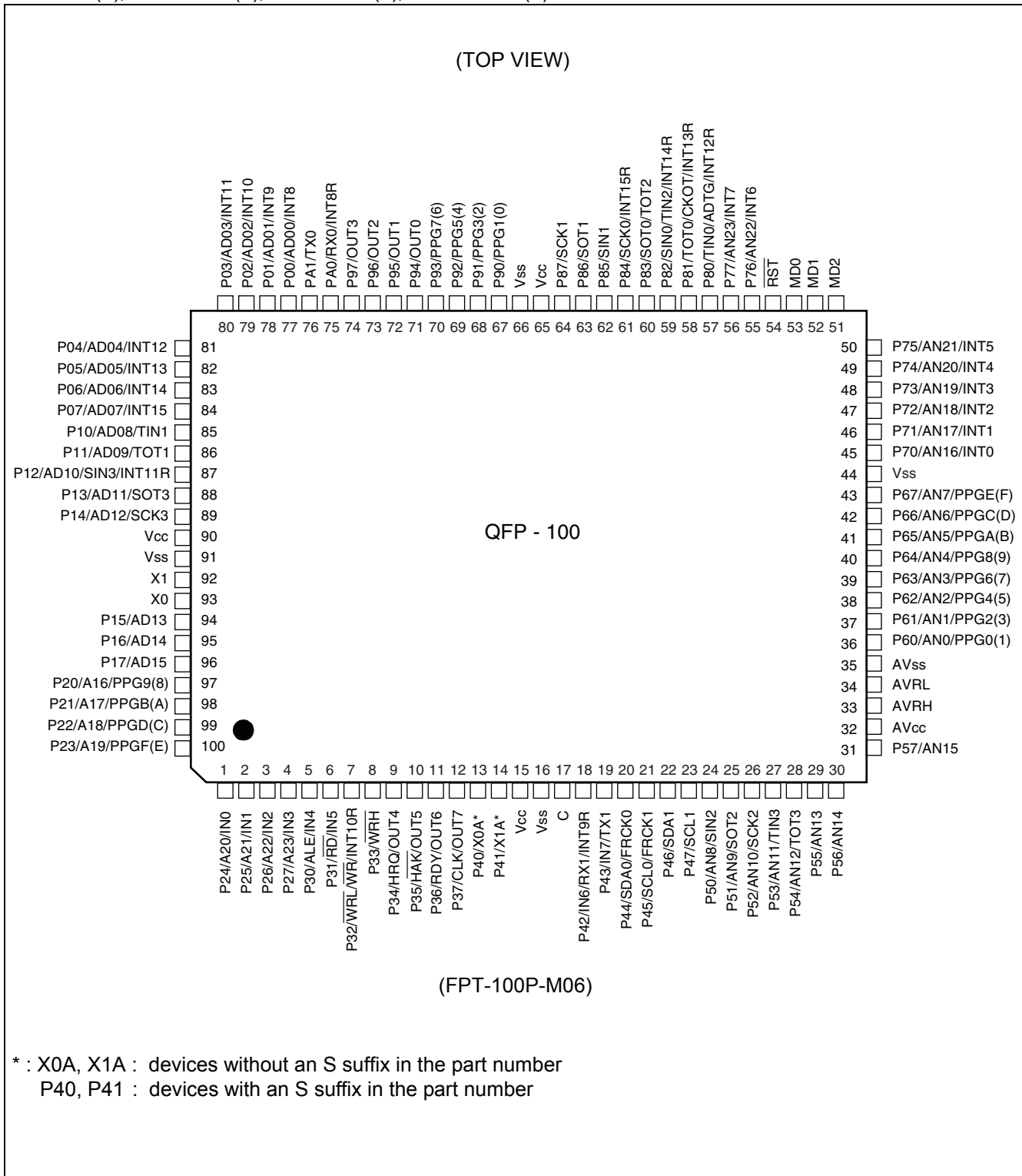
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

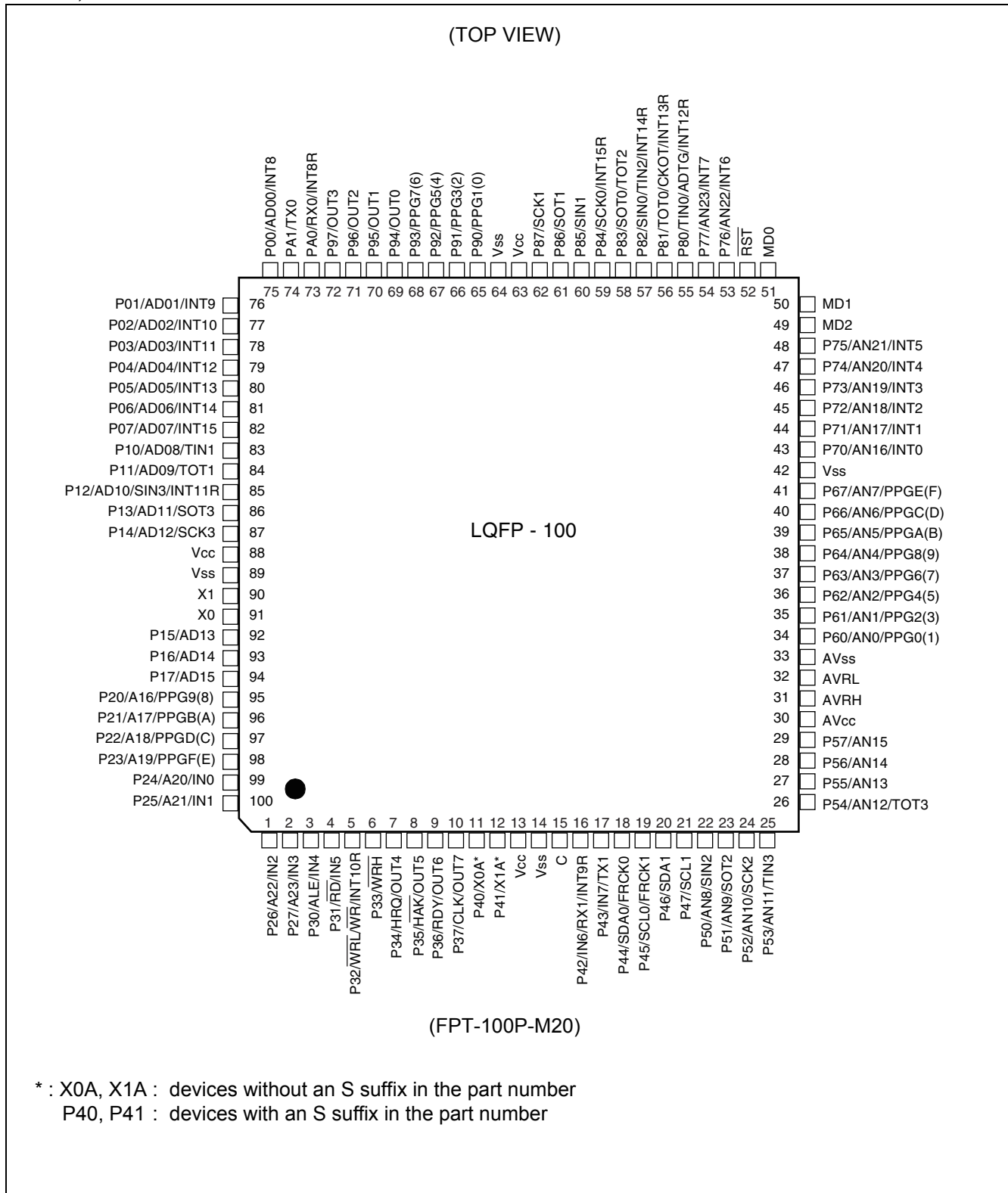
Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, LINbus, SCI, UART/USART
Peripherals	DMA, POR, WDT
Number of I/O	82
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 16x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90347espmc-gs-662e1

■ MB90341CE(S), MB90342CE(S), MB90F342CE(S), MB90F345CE(S), MB90346CE(S), MB90F346CE(S), MB90347CE(S), MB90F347CE(S), MB90348CE(S), MB90349CE(S), MB90F349CE(S)

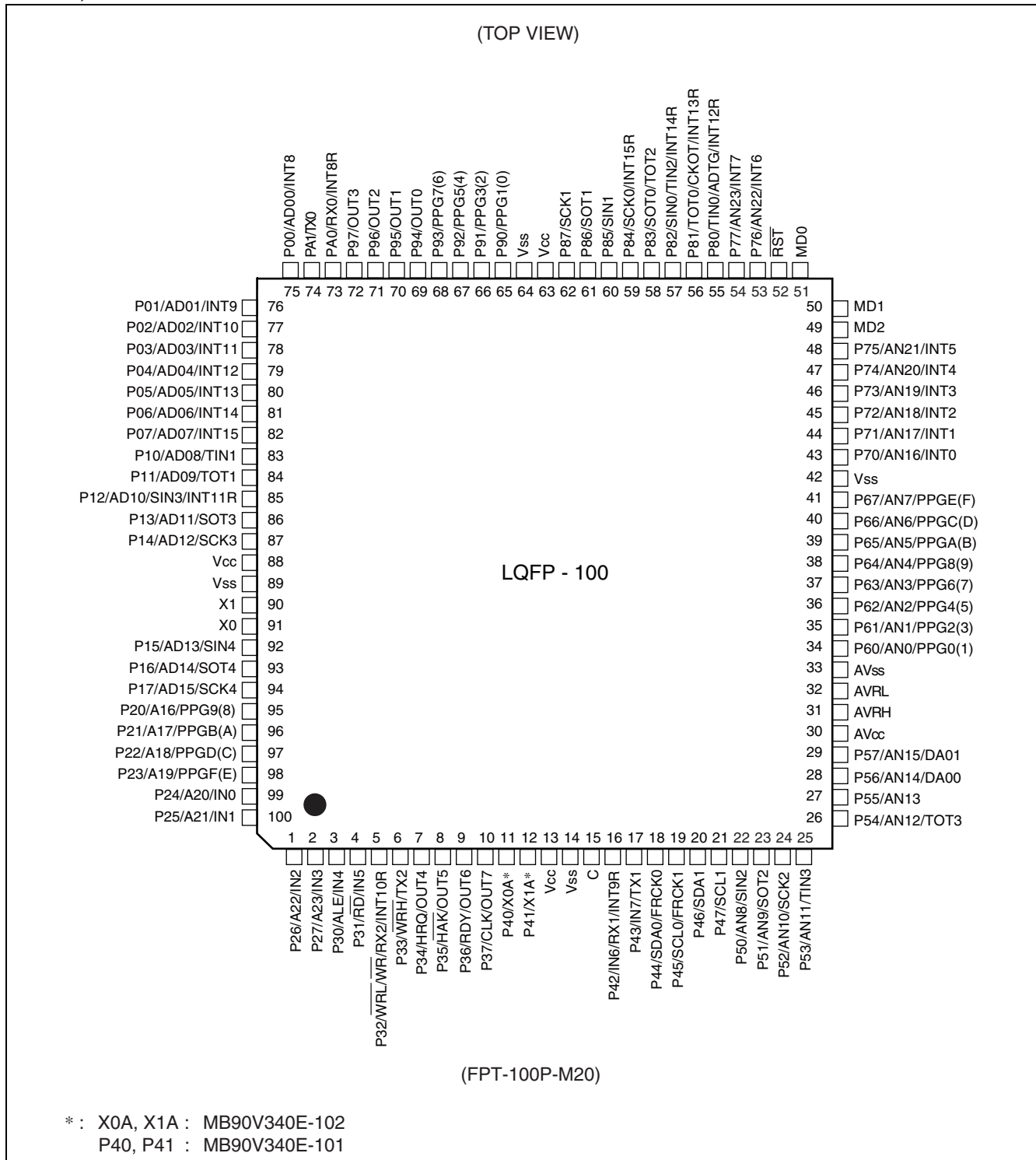


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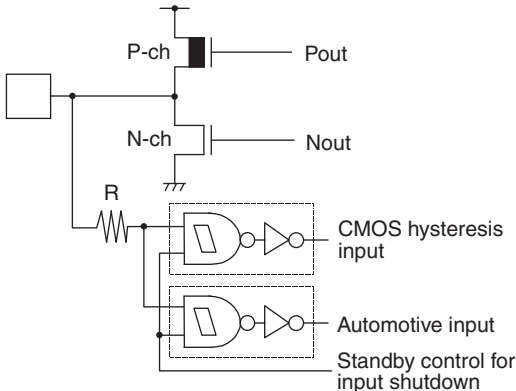
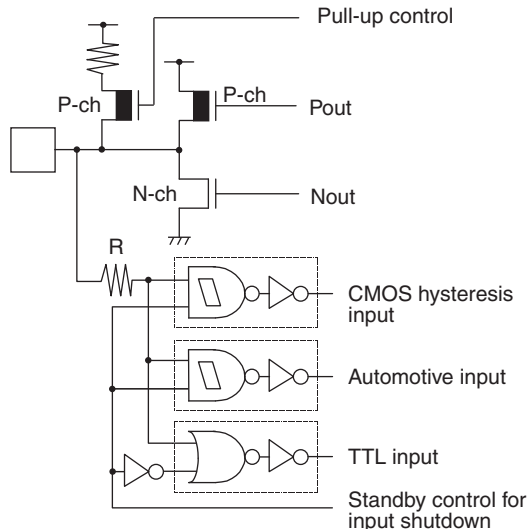
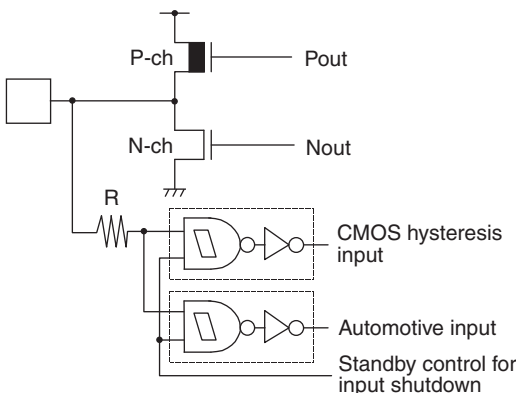
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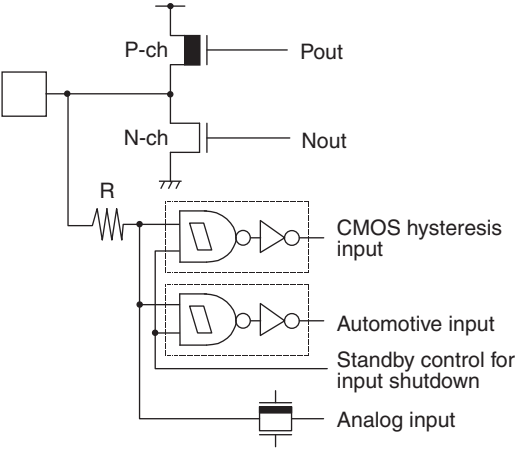
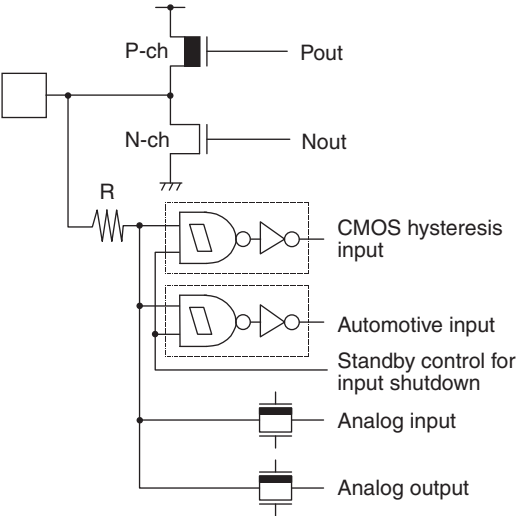
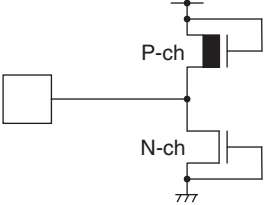
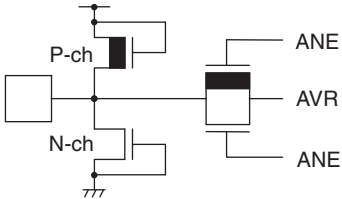
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This pin assignment is for using MB90V340E-101/102 via probecable as MB90340E.

Type	Circuit	Remarks
F		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)
G		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ TTL input (with function to disconnect input during standby) ■ Programmable pull-up resistor: 50 kΩ approx.
H		■ CMOS level output ($I_{OL} = 3 \text{ mA}$, $I_{OH} = -3 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby)

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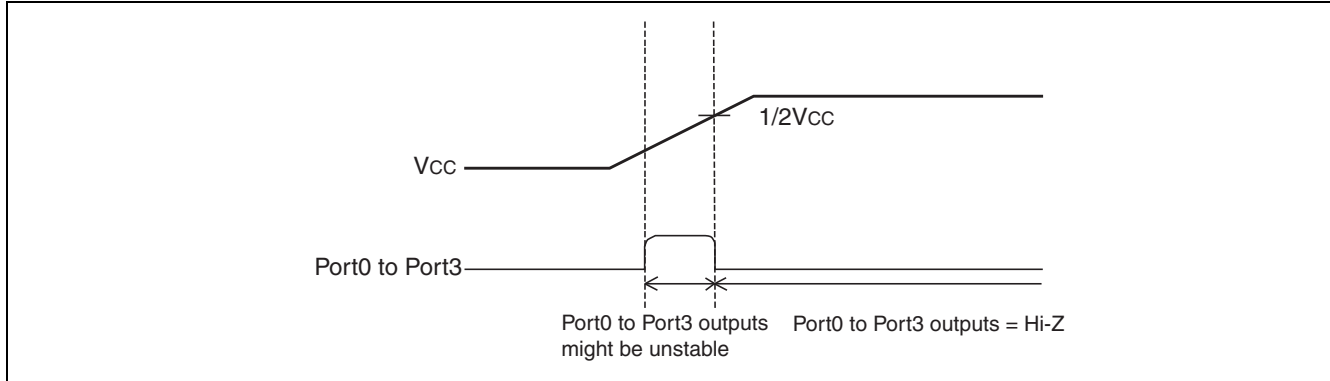
Type	Circuit	Remarks
I		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ A/D converter analog input
J		■ CMOS level output ($I_{OL} = 4 \text{ mA}$, $I_{OH} = -4 \text{ mA}$) ■ D/A analog output ■ CMOS hysteresis input (with function to disconnect input during standby) ■ Automotive input (with function to disconnect input during standby) ■ A/D converter analog input
K		Power supply input protection circuit
L		■ A/D converter reference voltage power supply input pin, with the protection circuit ■ Flash memory devices do not have a protection circuit against V_{CC} for pin AVRH

13.Stabilization of power supply voltage

A sudden change in the supply voltage may cause the device to malfunction even within the V_{CC} supply voltage operating range. Therefore, the V_{CC} supply voltage should be stabilized. For reference, the supply voltage should be controlled so that V_{CC} ripple variations (peak- to-peak values) at commercial frequencies (50 MHz/60 MHz) fall below 10% of the standard V_{CC} supply voltage and the coefficient of fluctuation does not exceed 0.1 V/ms at instantaneous power switching.

14.Port 0 to Port 3 Output During Power-on (External-bus Mode)

As shown below, when the power is turned on in External-Bus mode, there is a possibility that output signal of Port 0 to Port 3 might be unstable irrespective of the reset input.



15.Notes on Using the CAN Function

To use the CAN function, please set the DIRECT bit of the CAN Direct Mode Register (CDMR) to 1.

16.Flash Security Function (except for MB90F346E)

A security bit is located in the area of the flash memory.

If protection code 01_H is written in the security bit, the flash memory is in the protected state by security.

Therefore please do not write 01_H in this address if you do not use the security function.

Refer to following table for the address of the security bit.

	Flash memory size	Address of the security bit
MB90F347E	Embedded 1 Mbit Flash Memory	FE0001 _H
MB90F342E MB90F349E	Embedded 2 Mbits Flash Memory	FC0001 _H
MB90F345E	Embedded 4 Mbits Flash Memory	F80001 _H

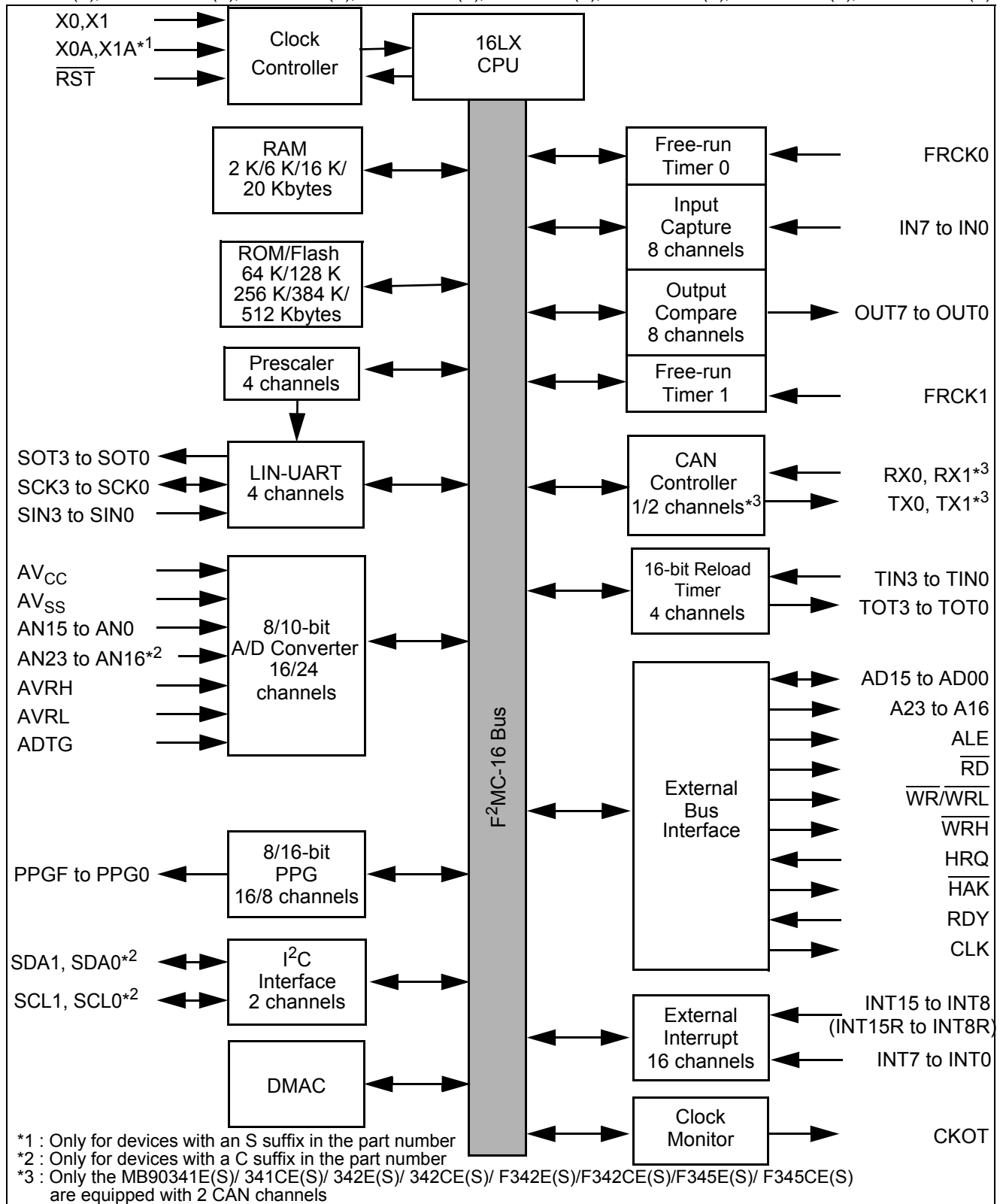
17.Serial Communication

There is a possibility to receive wrong data due to the noise or other causes on the serial communication.

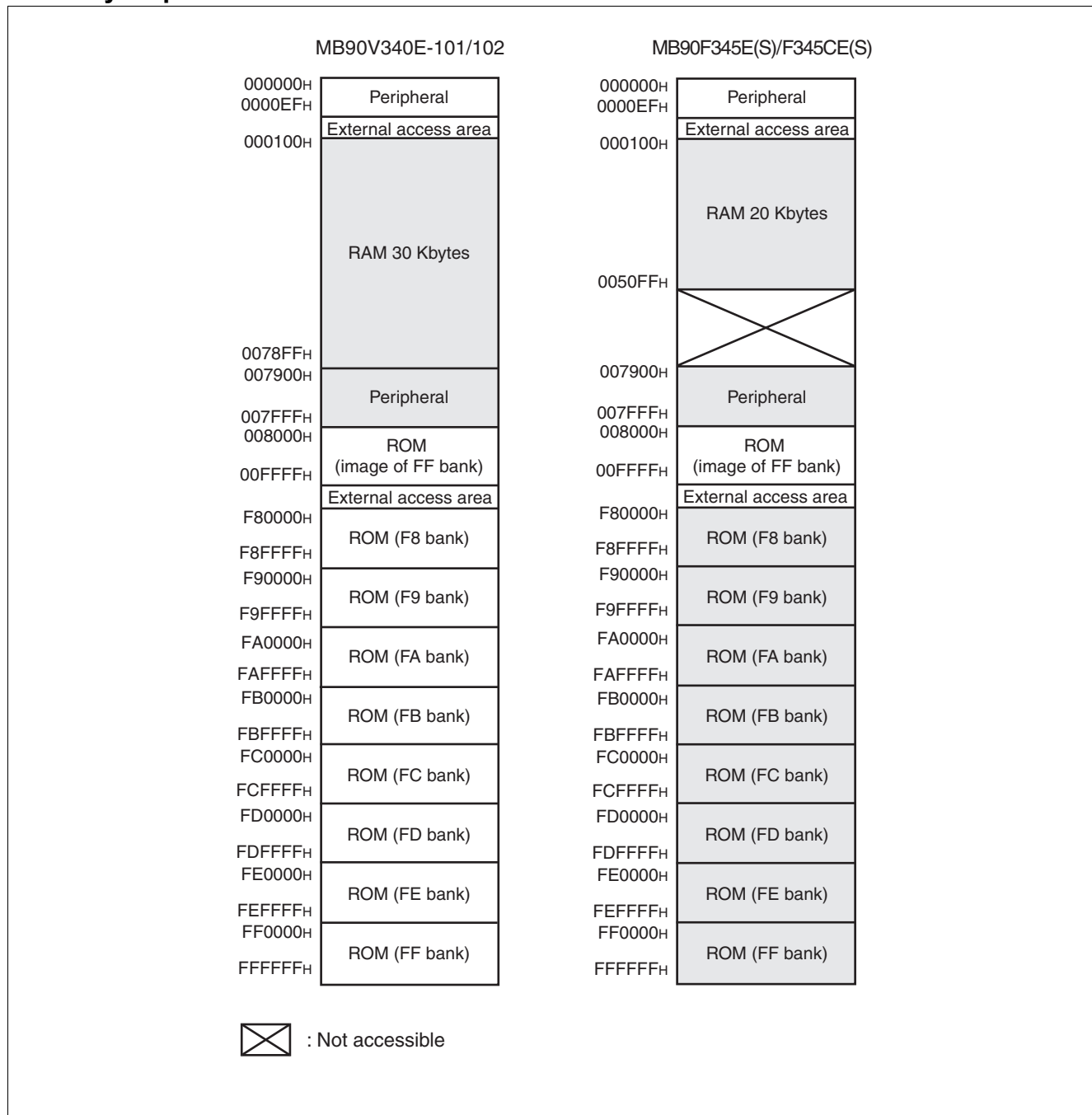
Therefore, design a printed circuit board so as to avoid noise.

Retransmit the data if an error occurs because of applying the checksum to the last data in consideration of receiving wrong data due to the noise.

■ MB90341E(S), MB90341CE(S), MB90342E(S), MB90342CE(S), MB90F342E(S), MB90F342CE(S), MB90F345E(S), MB90F345CE(S), MB90346E(S), MB90346CE(S), MB90F346E(S), MB90F346CE(S), MB90347E(S), MB90347CE(S), MB90F347E(S), MB90F347CE(S), MB90348E(S), MB90348CE(S), MB90349E(S), MB90349CE(S), MB90F349E(S), MB90F349CE(S)



7. Memory Map



Address	Register	Abbreviation	Access	Resource name	Initial value
007900 _H	Reload Register L0	PRL0	R/W	16-bit PPG 0/1	XXXXXXXX _B
007901 _H	Reload Register H0	PRLH0	R/W		XXXXXXXX _B
007902 _H	Reload Register L1	PRL1	R/W		XXXXXXXX _B
007903 _H	Reload Register H1	PRLH1	R/W		XXXXXXXX _B
007904 _H	Reload Register L2	PRL2	R/W	16-bit PPG 2/3	XXXXXXXX _B
007905 _H	Reload Register H2	PRLH2	R/W		XXXXXXXX _B
007906 _H	Reload Register L3	PRL3	R/W		XXXXXXXX _B
007907 _H	Reload Register H3	PRLH3	R/W		XXXXXXXX _B
007908 _H	Reload Register L4	PRL4	R/W	16-bit PPG 4/5	XXXXXXXX _B
007909 _H	Reload Register H4	PRLH4	R/W		XXXXXXXX _B
00790A _H	Reload Register L5	PRL5	R/W		XXXXXXXX _B
00790B _H	Reload Register H5	PRLH5	R/W		XXXXXXXX _B
00790C _H	Reload Register L6	PRL6	R/W	16-bit PPG 6/7	XXXXXXXX _B
00790D _H	Reload Register H6	PRLH6	R/W		XXXXXXXX _B
00790E _H	Reload Register L7	PRL7	R/W		XXXXXXXX _B
00790F _H	Reload Register H7	PRLH7	R/W		XXXXXXXX _B
007910 _H	Reload Register L8	PRL8	R/W	16-bit PPG 8/9	XXXXXXXX _B
007911 _H	Reload Register H8	PRLH8	R/W		XXXXXXXX _B
007912 _H	Reload Register L9	PRL9	R/W		XXXXXXXX _B
007913 _H	Reload Register H9	PRLH9	R/W		XXXXXXXX _B
007914 _H	Reload Register LA	PRLA	R/W	16-bit PPG A/B	XXXXXXXX _B
007915 _H	Reload Register HA	PRLHA	R/W		XXXXXXXX _B
007916 _H	Reload Register LB	PRLB	R/W		XXXXXXXX _B
007917 _H	Reload Register HB	PRLHB	R/W		XXXXXXXX _B
007918 _H	Reload Register LC	PRLC	R/W	16-bit PPG C/D	XXXXXXXX _B
007919 _H	Reload Register HC	PRLHC	R/W		XXXXXXXX _B
00791A _H	Reload Register LD	PRLD	R/W		XXXXXXXX _B
00791B _H	Reload Register HD	PRLHD	R/W		XXXXXXXX _B
00791C _H	Reload Register LE	PRLLE	R/W	16-bit PPG E/F	XXXXXXXX _B
00791D _H	Reload Register HE	PRLHE	R/W		XXXXXXXX _B
00791E _H	Reload Register LF	PRLLF	R/W		XXXXXXXX _B
00791F _H	Reload Register HF	PRLHF	R/W		XXXXXXXX _B
007920 _H	Input Capture 0	IPCP0	R	Input Capture 0/1	XXXXXXXX _B
007921 _H	Input Capture 0	IPCP0	R		XXXXXXXX _B
007922 _H	Input Capture 1	IPCP1	R		XXXXXXXX _B
007923 _H	Input Capture 1	IPCP1	R		XXXXXXXX _B

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
007924 _H	Input Capture 2	IPCP2	R	Input Capture 2/3	XXXXXXXX _B
007925 _H	Input Capture 2	IPCP2	R		XXXXXXXX _B
007926 _H	Input Capture 3	IPCP3	R		XXXXXXXX _B
007927 _H	Input Capture 3	IPCP3	R		XXXXXXXX _B
007928 _H	Input Capture 4	IPCP4	R	Input Capture 4/5	XXXXXXXX _B
007929 _H	Input Capture 4	IPCP4	R		XXXXXXXX _B
00792A _H	Input Capture 5	IPCP5	R		XXXXXXXX _B
00792B _H	Input Capture 5	IPCP5	R		XXXXXXXX _B
00792C _H	Input Capture 6	IPCP6	R	Input Capture 6/7	XXXXXXXX _B
00792D _H	Input Capture 6	IPCP6	R		XXXXXXXX _B
00792E _H	Input Capture 7	IPCP7	R		XXXXXXXX _B
00792F _H	Input Capture 7	IPCP7	R		XXXXXXXX _B
007930 _H	Output Compare 0	OCCP0	R/W	Output Compare 0/1	XXXXXXXX _B
007931 _H	Output Compare 0	OCCP0	R/W		XXXXXXXX _B
007932 _H	Output Compare 1	OCCP1	R/W		XXXXXXXX _B
007933 _H	Output Compare 1	OCCP1	R/W		XXXXXXXX _B
007934 _H	Output Compare 2	OCCP2	R/W	Output Compare 2/3	XXXXXXXX _B
007935 _H	Output Compare 2	OCCP2	R/W		XXXXXXXX _B
007936 _H	Output Compare 3	OCCP3	R/W		XXXXXXXX _B
007937 _H	Output Compare 3	OCCP3	R/W		XXXXXXXX _B
007938 _H	Output Compare 4	OCCP4	R/W	Output Compare 4/5	XXXXXXXX _B
007939 _H	Output Compare 4	OCCP4	R/W		XXXXXXXX _B
00793A _H	Output Compare 5	OCCP5	R/W		XXXXXXXX _B
00793B _H	Output Compare 5	OCCP5	R/W		XXXXXXXX _B
00793C _H	Output Compare 6	OCCP6	R/W	Output Compare 6/7	XXXXXXXX _B
00793D _H	Output Compare 6	OCCP6	R/W		XXXXXXXX _B
00793E _H	Output Compare 7	OCCP7	R/W		XXXXXXXX _B
00793F _H	Output Compare 7	OCCP7	R/W		XXXXXXXX _B
007940 _H	Timer Data 0	TCDT0	R/W	Free-run Timer 0	00000000 _B
007941 _H	Timer Data 0	TCDT0	R/W		00000000 _B
007942 _H	Timer Control Status 0	TCCSL0	R/W		00000000 _B
007943 _H	Timer Control Status 0	TCCSH0	R/W		0XXXXXXXX _B
007944 _H	Timer Data 1	TCDT1	R/W	Free-run Timer 1	00000000 _B
007945 _H	Timer Data 1	TCDT1	R/W		00000000 _B
007946 _H	Timer Control Status 1	TCCSL1	R/W		00000000 _B
007947 _H	Timer Control Status 1	TCCSH1	R/W		0XXXXXXXX _B

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Interrupt cause	EI ² OS Support	DMA channel number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
UART 2 RX / UART 4 RX	Y2	14	#39	FFFF60 _H	ICR14	0000BE _H
UART 2 TX / UART 4 TX	Y1	15	#40	FFFF5C _H		
Flash Memory	N	—	#41	FFFF58 _H	ICR15	0000BF _H
Delayed Interrupt	N	—	#42	FFFF54 _H		

Y1 : Usable

Y2 : Usable, with EI²OS stop function

N : Unusable

Note:

- The peripheral resources sharing the ICR register have the same interrupt level.
- When two peripheral resources share the ICR register, only one can use Extended Intelligent I/O Service at a time.
- When either of the two peripheral resources sharing the ICR register specifies Extended Intelligent I/O Service, the other one cannot use interrupts.

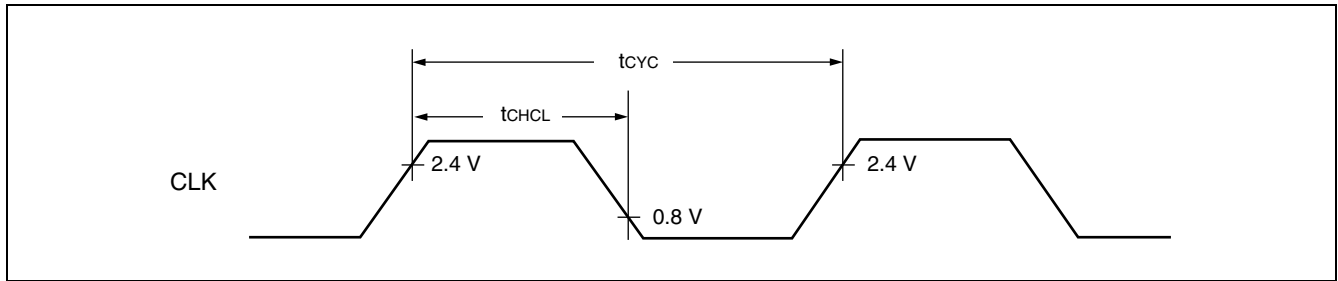
11.4 AC Characteristics

11.4.1 Clock Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = AV_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Clock frequency	f_C	X0, X1	3	—	16	MHz	When using an oscillation circuit
			4	—	16	MHz	PLL multiplied by 1 When using an oscillation circuit
			4	—	12	MHz	PLL multiplied by 2 When using an oscillation circuit
			4	—	8	MHz	PLL multiplied by 3 When using an oscillation circuit
			4	—	6	MHz	PLL multiplied by 4 When using an oscillation circuit
			—	—	4	MHz	PLL multiplied by 6 When using an oscillation circuit
			3	—	24	MHz	When using an external clock*
	f_{CL}	X0A, X1A	—	32.768	100	kHz	
Clock cycle time	t_{CYL}	X0, X1	62.5	—	333	ns	When using an oscillation circuit
		X0, X1	41.67	—	333	ns	When using an external clock
	t_{CYLL}	X0A, X1A	10	30.5	—	μs	
Input clock pulse width	P_{WH}, P_{WL}	X0	10	—	—	ns	Duty ratio is about 30% to 70%.
	P_{WHL}, P_{WLL}	X0A	5	15.2	—	μs	
Input clock rise and fall time	t_{CR}, t_{CF}	X0	—	—	5	ns	When using external clock
Internal operating clock frequency (machine clock)	f_{CP}	—	1.5	—	24	MHz	When using main clock
	f_{CPL}	—	—	8.192	50	kHz	When using sub clock
Internal operating clock cycle time (machine clock)	t_{CP}	—	41.67	—	666	ns	When using main clock
	t_{CPL}	—	20	122.1	—	μs	When using sub clock

* : When selecting the PLL clock, the range of clock frequency is limited. Use this product within the range as mentioned in "Relation between the external clock frequency and machine clock frequency".



11.4.9 LIN-UART0/1/2/3

■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0

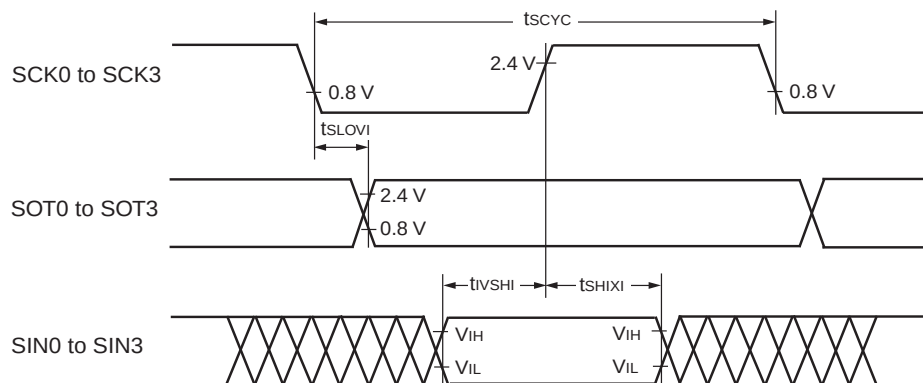
($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK0 to SCK3	Internal shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$5 t_{CP}$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCK0 to SCK3, SOT0 to SOT3		-50	+50	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHI}	SCK0 to SCK3, SIN0 to SIN3		$t_{CP} + 80$	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXI}	SCK0 to SCK3, SIN0 to SIN3		0	—	ns
Serial clock "L" pulse width	t_{SHSL}	SCK0 to SCK3	External shift clock mode output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$3 t_{CP} - t_R$	—	ns
Serial clock "H" pulse width	t_{SLSH}	SCK0 to SCK3		$t_{CP} + 10$	—	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVE}	SCK0 to SCK3, SOT0 to SOT3		—	$2 t_{CP} + 60$	ns
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{IVSHE}	SCK0 to SCK3, SIN0 to SIN3		30	—	ns
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIXE}	SCK0, SCK1, SIN0 to SIN3		$t_{CP} + 30$	—	ns
SCK fall time	t_F	SCK0 to SCK3		—	10	ns
SCK rise time	t_R	SCK0 to SCK3		—	10	ns

Note:

- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “(1) Clock Timing”.

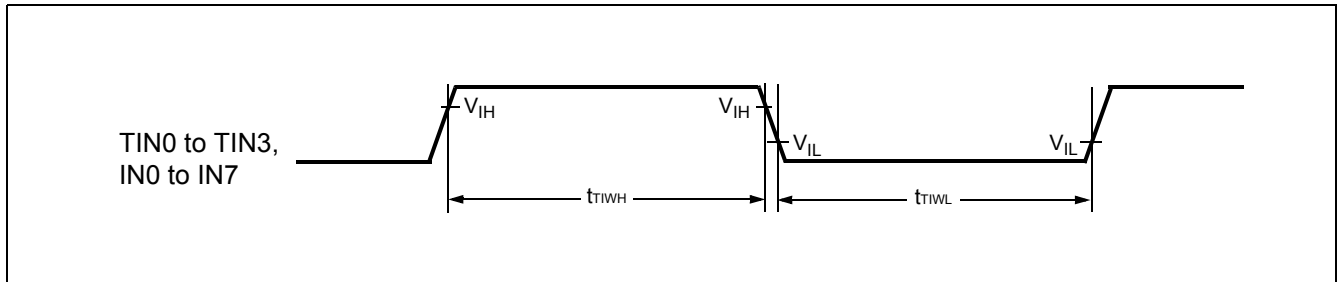
• Internal Shift Clock Mode



11.4.11 Timer Related Resource Input Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0\text{ V}$)

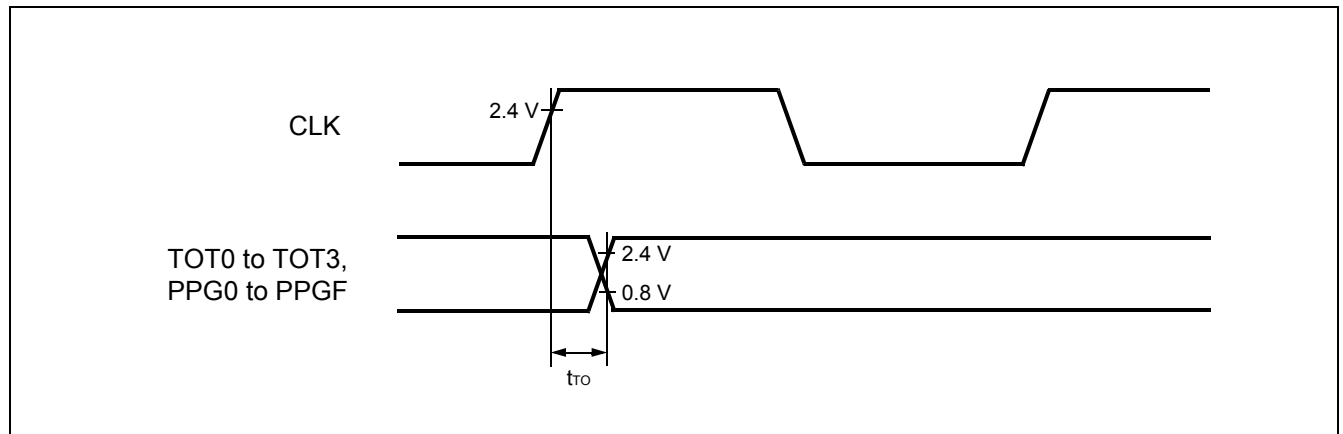
Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Input pulse width	t_{TIWH}	TIN0 to TIN3, IN0 to IN7	—	$4 t_{CP}$	—	ns
	t_{TIWL}					



11.4.12 Timer Related Resource Output Timing

($T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
CLK $\uparrow \rightarrow T_{OUT}$ change time	t_{TO}	TOT0 to TOT3, PPG0 to PPGF	—	30	—	ns



11.5 A/D Converter

($T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $3.0\text{ V} \leq \text{AVRH} - \text{AVRL}$, $V_{CC} = \text{AV}_{CC} = 5.0\text{ V} \pm 10\%$, $f_{CP} \leq 24\text{ MHz}$, $V_{SS} = \text{AV}_{SS} = 0\text{ V}$)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	—	—	± 3.0	LSB	
Nonlinearity error	—	—	—	—	± 2.5	LSB	
Differential nonlinearity error	—	—	—	—	± 1.9	LSB	
Zero reading voltage	V_{OT}	AN0 to AN23	$\text{AVRL} - 1.5 \times \text{LSB}$	$\text{AVRL} + 0.5 \times \text{LSB}$	$\text{AVRL} + 2.5 \times \text{LSB}$	V	
Full scale reading voltage	V_{FST}	AN0 to AN23	$\text{AVRH} - 3.5 \times \text{LSB}$	$\text{AVRH} - 1.5 \times \text{LSB}$	$\text{AVRH} + 0.5 \times \text{LSB}$	V	
Compare time	—	—	1.0	—	16500	μs	$4.5\text{ V} \leq \text{AV}_{CC} \leq 5.5\text{ V}$
			2.0				$4.0\text{ V} \leq \text{AV}_{CC} < 4.5\text{ V}$
Sampling time	—	—	0.5	—	∞	μs	$4.5\text{ V} \leq \text{AV}_{CC} \leq 5.5\text{ V}$
			1.2				$4.0\text{ V} \leq \text{AV}_{CC} < 4.5\text{ V}$
Analog port input current	I_{AIN}	AN0 to AN23	-0.3	—	+0.3	μA	
Analog input voltage range	V_{AIN}	AN0 to AN23	AVRL	—	AVRH	V	
Reference voltage range	—	AVRH	$\text{AVRL} + 2.7$	—	AV_{CC}	V	
	—	AVRL	0	—	$\text{AVRH} - 2.7$	V	
Power supply current	I_A	AV_{CC}	—	3.5	7.5	mA	
	I_{AH}	AV_{CC}	—	—	5	μA	*
Reference voltage current	I_R	AVRH	—	600	900	μA	
	I_{RH}	AVRH	—	—	5	μA	*
Offset between input channels	—	AN0 to AN23	—	—	4	LSB	

*: If the A/D convertor is not operating, a current when CPU is stopped is applicable ($V_{CC} = \text{AV}_{CC} = \text{AVRH} = 5.0\text{ V}$).

Note: : The accuracy gets worse as $|\text{AVRH} - \text{AVRL}|$ becomes smaller.

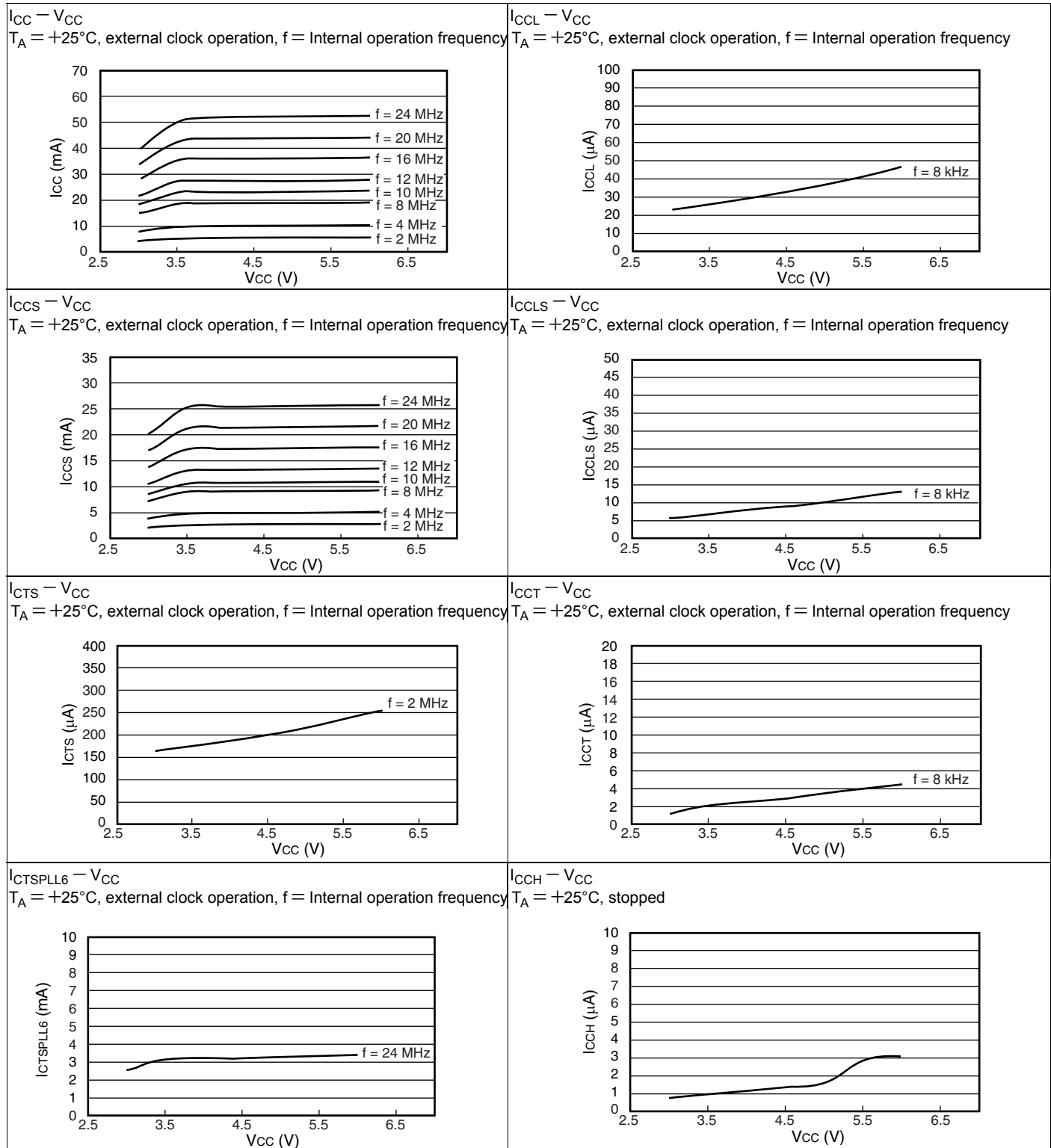
11.8 Flash Memory Program/Erase Characteristics

Parameter	Conditions	Value			Unit	Remarks
		Min	Typ	Max		
Sector erase time	$T_A = +25^{\circ}\text{C}$ $V_{CC} = 5.0\text{ V}$	—	1	15	s	Excludes programming prior to erasure
Chip erase time		—	9	—	s	Excludes programming prior to erasure
Word (16-bit width) programming time		—	16	3600	μs	Except for the over head time of the system
Program/Erase cycle	—	10000	—	—	cycle	
Flash Data Retention Time	Average $T_A = +85^{\circ}\text{C}$	20	—	—	year	*

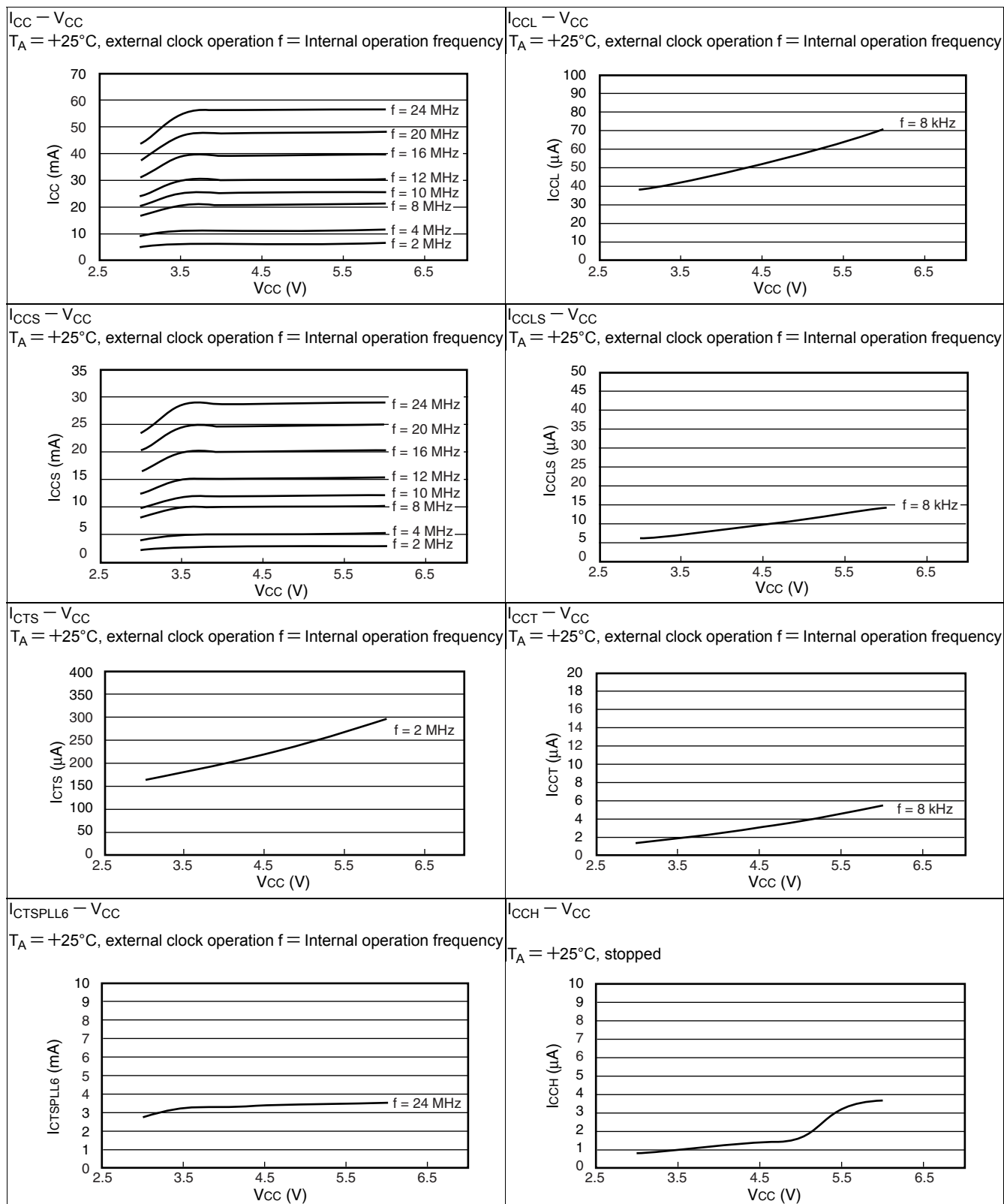
* : This value was converted from the results of evaluating the reliability of the technology (using Arrhenius equation to translate high temperature measurements into normalized value at $+85^{\circ}\text{C}$) .

12. Example Characteristics

■ MB90F346E, MB90F346ES, MB90F346CE, MB90F346CES

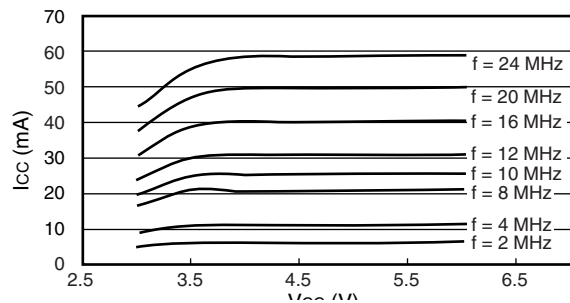


■ MB90F342E, MB90F342ES, MB90F342CE, MB90F342CES

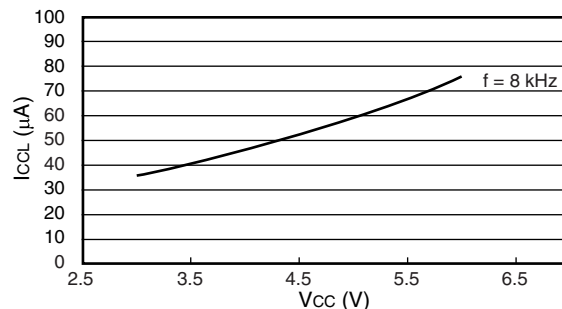


■ MB90F345E, MB90F345ES, MB90F345CE, MB90F345CES

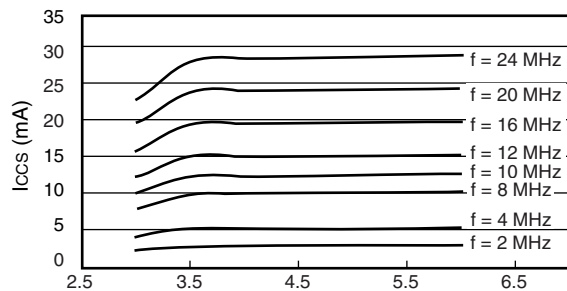
$I_{CC} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



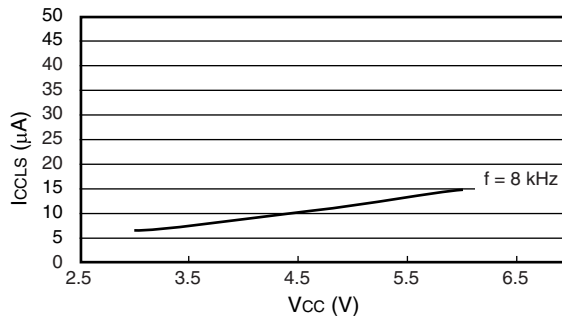
$I_{CCL} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



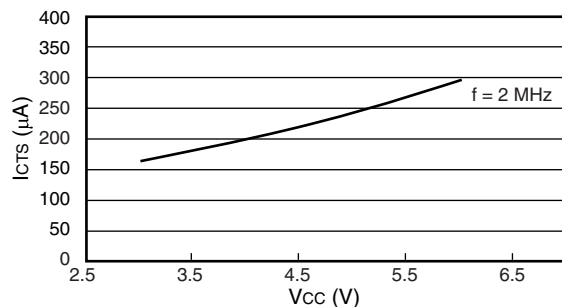
$I_{CCS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



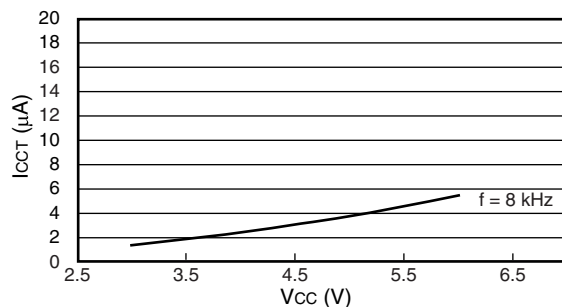
$I_{CCLS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



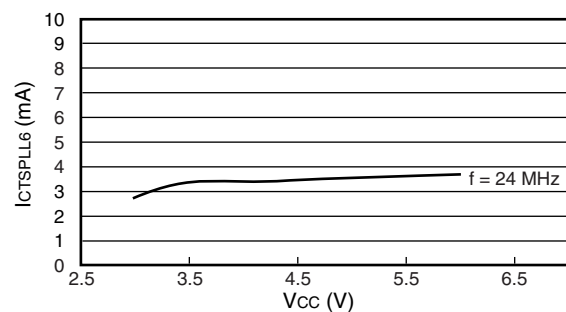
$I_{CTS} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



$I_{CCT} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



$I_{CTSPLL6} - V_{CC}$
 $T_A = +25^\circ\text{C}$, external clock operation f = Internal operation frequency



$I_{CCH} - V_{CC}$
 $T_A = +25^\circ\text{C}$, stopped

